

# Serial

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## Getting Started with Your AT Serial Hardware and Software for Windows Me/9x

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# Compliance

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## FCC/Canada Radio Frequency Interference Compliance\*

### Determining FCC Class

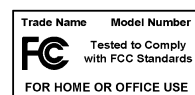
The Federal Communications Commission (FCC) has rules to protect wireless communications from interference. The FCC places digital electronics into two classes. These classes are known as Class A (for use in industrial-commercial locations only) or Class B (for use in residential or commercial locations). Depending on where it is operated, this product could be subject to restrictions in the FCC rules. (In Canada, the Department of Communications (DOC), of Industry Canada, regulates wireless interference in much the same way.)

Digital electronics emit weak signals during normal operation that can affect radio, television, or other wireless products. By examining the product you purchased, you can determine the FCC Class and therefore which of the two FCC/DOC Warnings apply in the following sections. (Some products may not be labeled at all for FCC; if so, the reader should then assume these are Class A devices.)

FCC Class A products only display a simple warning statement of one paragraph in length regarding interference and undesired operation. Most of our products are FCC Class A. The FCC rules have restrictions regarding the locations where FCC Class A products can be operated.

FCC Class B products display either a FCC ID code, starting with the letters **EXN**, or the FCC Class B compliance mark that appears as shown here on the right.

Consult the FCC web site <http://www.fcc.gov> for more information.



### FCC/DOC Warnings

This equipment generates and uses radio frequency energy and, if not installed and used in strict accordance with the instructions in this manual and the CE Mark Declaration of Conformity\*\*, may cause interference to radio and television reception. Classification requirements are the same for the Federal Communications Commission (FCC) and the Canadian Department of Communications (DOC).

Changes or modifications not expressly approved by National Instruments could void the user's authority to operate the equipment under the FCC Rules.

### Class A

#### Federal Communications Commission

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

#### Canadian Department of Communications

This Class A digital apparatus meets all requirements of the Canadian Interference-Causing Equipment Regulations.

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- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.

- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

## **Canadian Department of Communications**

This Class B digital apparatus meets all requirements of the Canadian Interference-Causing Equipment Regulations.

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## **European Union - Compliance to EEC Directives**

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\* Certain exemptions may apply in the USA, see FCC Rules §15.103 **Exempted devices**, and §15.105(c). Also available in sections of CFR 47.

\*\* The CE Mark Declaration of Conformity will contain important supplementary information and instructions for the user or installer.

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# About This Manual

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This manual contains instructions to help you install and configure the National Instruments serial hardware and the NI-Serial software for Windows Me/9x. This manual includes information about the AT-232/2, AT-232/4, AT-485/2, and AT-485/4 boards in both isolated and non-isolated versions.

This manual assumes that you are already familiar with Windows Me/9x.

## Conventions

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The following conventions appear in this manual:

»

The » symbol leads you through nested menu items and dialog box options to a final action. The sequence **File»Page Setup»Options** directs you to pull down the **File** menu, select the **Page Setup** item, and select **Options** from the last dialog box.



This icon denotes a note, which alerts you to important information.



This icon denotes a caution, which advises you of precautions to take to avoid injury, data loss, or a system crash.

**bold**

Bold text denotes items that you must select or click on in the software, such as menu items and dialog box options. Bold text also denotes parameter names.

DTR

Signal names with an overscore, such as DTR, indicate that the signal is active low.

*italic*

Italic text denotes variables, emphasis, a cross reference, or an introduction to a key concept. This font also denotes text that is a placeholder for a word or value that you must supply.

monospace

Text in this font denotes text or characters that you should enter from the keyboard, sections of code, programming examples, and syntax examples. This font is also used for the proper names of disk drives, paths, directories, programs, subprograms, subroutines, device names, functions, operations, variables, filenames and extensions, and code excerpts.

**monospace bold** Bold text in this font denotes the messages and responses that the computer automatically prints to the screen. This font also emphasizes lines of code that are different from the other examples.

AT serial boards *AT serial boards* refers to all port versions of the AT serial boards.

## Related Documentation

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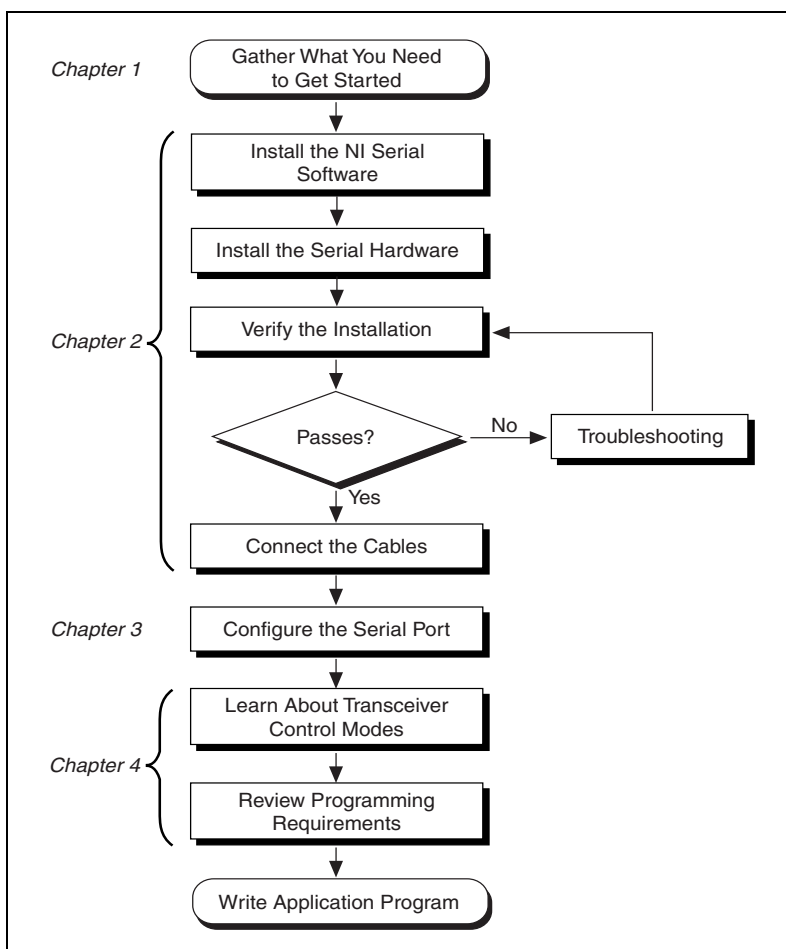
The following documents contain information that you might find helpful as you read this manual:

- ANSI/EIA-232-D Standard, *Interface Between Data Terminal Equipment and Data Circuit-Terminating Equipment Employing Serial Binary Data Interchange*
- EIA/RS-422-A Standard, *Electrical Characteristics of Balanced Voltage Digital Interface Circuits*
- EIA-485 Standard, *Standard for Electrical Characteristics of Generators and Receivers for Use in Balanced Digital Multipoint Systems*
- *Microsoft Win32 Software Developer Kit*, Online Documentation for *Win32 Overviews*, *Win32 Reference*, and *Microsoft Programmer's Guide to Windows 98/95*, Microsoft Corporation
- *NS16550AF Universal Asynchronous Receiver/Transmitter with FIFOs*, National Semiconductor
- *ST16C654 Asynchronous Receiver/Transmitter with FIFOs*, EXAR Corporation

# Introduction

This chapter explains how to use this manual, lists what you need to get started and optional equipment you can order, and briefly describes the serial hardware and the NI-Serial software.

## How to Use This Manual



## What You Need to Get Started

---

Before you install your serial hardware and the NI-Serial software, make sure you have all of the following items:

- Windows Me/9x installed on your computer
- One of the following serial boards, which is included in your kit:
  - AT-232 (two or four port)
  - AT-485 (two or four port)
  - AT-232 (two or four port) isolated
  - AT-485 (two or four port) isolated
- CD, *NI-Serial Software for Windows 2000/NT/Me/9x*, which is included in your kit

If you have a four-port interface, you also need a 10-position modular jack to DB-9 cable.

## Optional Equipment

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For more information about ordering the following optional equipment, contact National Instruments:

- DB-9 RS-485 termination connector (AT-485 only)
- 10-position modular jack to DB-9 cable (four-port boards only)
- 10-position modular jack to DB-25 cable (four-port boards only)
- RS-232 9-pin to 9-pin null modem cable
- RS-232 9-pin to 25-pin null modem cable
- RS-485 9-pin to 9-pin null modem cable

## Serial Hardware Overview

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The serial hardware gives you a variety of solutions for serial communications. The AT-232 boards work with the RS-232 protocols, and the AT-485 boards work with the RS-422 and RS-485 protocols. You can use the AT-232 hardware for serial communication up to distances of 50 ft. You can connect the AT-485 hardware with up to 31 devices using serial cable lengths up to 4,000 ft.

The AT boards are available in three different versions:

- Shared IRQ: All ports on the board share the same IRQ.
- Isolated: All ports on the board are isolated and share the same IRQ.
- Each port requires a separate IRQ (no longer ships with the NI-Serial software for Windows Me/9x).

Additionally, the AT serial boards are available in a two-port version (AT-232/2 and AT-485/2) or a four-port version (AT-232/4 and AT-485/4). The two-port versions use DB-9 connectors. The four-port versions use 10-position modular jacks to provide all four connections on a single back panel. Optional cable accessories convert the 10-position modular jacks to either DB-9 or DB-25 connectors with standard pinouts. Throughout this manual, references to AT serial boards generally refer to all versions of the boards.

The isolated AT-232 and AT-485 boards are designed for applications in harsh environments. Isolated ports provide reliable communication in situations involving ground loops from different ground levels or high common mode voltage induced on the lines in noisy environments. The non-isolated ports may not provide reliable communication in those situations. The isolation between each communication port and the host PC ensures safe operation of the PC and the devices connected to other ports on the same board in case of accidental high voltages on communication lines.

The AT-485 boards support four hardware transceiver control modes for reliable communication with two- and four-wire devices. For more information about transceiver control modes, refer to Chapter 4, *Using Your Serial Hardware*.

All serial hardware uses standard 16550-compatible UARTs (Universal Asynchronous Receiver/Transmitters) for complete compatibility with standard PC COM ports. The serial hardware contains FIFOs (First-In-First-Out) buffers to reduce susceptibility to interrupt latency for faster transmission rates. Full Plug and Play compatibility allows switchless configuration and installation. For more information about the serial hardware specifications and operating conditions, refer to Appendix D, *Specifications*.

## NI-Serial Software Overview

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The NI-Serial software for Windows Me/9x includes a native Windows device driver that provides full interrupt-driven, buffered I/O for multiple COM ports. You can obtain a maximum baud rate 115.2 KBaud. You can also use any number of serial ports under Windows Me/9x. The NI-Serial software also includes a configuration utility, which is fully integrated into the Windows Me/9x Device Manager. For more information about software specifications, refer to Appendix D, *Specifications*.

The NI-Serial software includes the following components:

- Device driver
- Diagnostic utility
- Configuration utility
- Product manuals

The NI-Serial software supports all National Instruments serial hardware, including the AT, PCI, PXI/CompactPCI, and PCMCIA versions.

## Time-Saving Development Tools

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Your kit includes the NI-Serial software for Windows Me/9x. In addition, you can order the LabWindows/CVI or LabVIEW software from National Instruments to speed your application development time and make it easier to communicate with your instruments.

LabVIEW is an easy-to-use, graphical programming environment you can use to acquire data from thousands of different instruments, including IEEE 488.2 devices, VXI devices, serial devices, PLCs, and plug-in data acquisition boards. After you have acquired raw data, you can convert it into meaningful results using the powerful data analysis routines in LabVIEW. LabVIEW also comes with hundreds of instrument drivers, which dramatically reduce software development time, because you do not have to spend time programming the low-level control of each instrument.

LabWindows/CVI is similar to LabVIEW, except that it combines an interactive, easy-to-use development approach with the programming power and flexibility of compiled ANSI C code.

For ordering information, or to request free demonstration software, contact National Instruments.

# Using Your Serial Hardware with LabVIEW and LabWindows/CVI

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After you install your serial hardware and the NI-Serial software, you can use standard serial I/O functions in LabVIEW and LabWindows/CVI with your serial interface. If you already have LabVIEW or LabWindows/CVI and want to use it with your serial hardware, refer to your LabVIEW or LabWindows/CVI documentation for information about serial I/O functions.



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# Installation and Verification

This chapter describes how to install the NI-Serial software, serial hardware, and cables, and how to verify the installation.

## Install the Software

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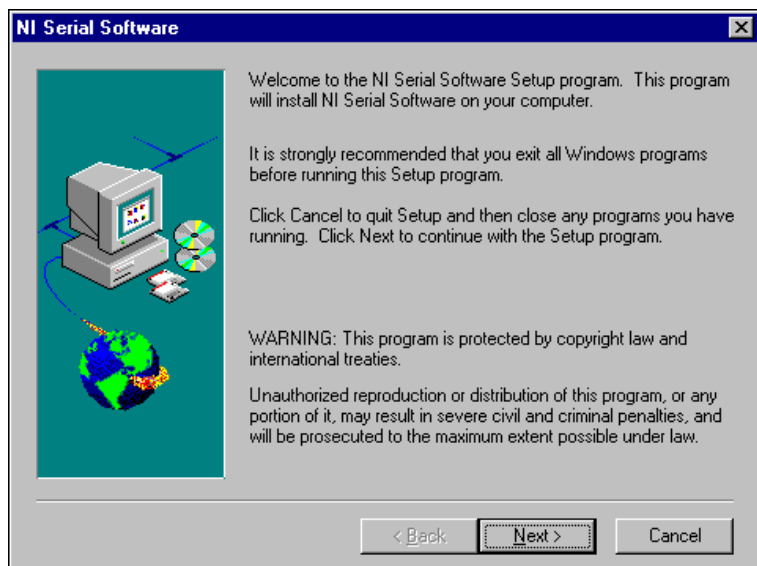
Install the NI-Serial software for Windows Me/9x before you install the hardware.

1. Select **Start»Settings»Control Panel**.
2. Double-click on the **Add/Remove Programs** icon in the Control Panel to launch the Add/Remove Programs applet. A dialog box similar to the one in Figure 2-1 appears.



**Figure 2-1.** Add/Remove Programs Properties Dialog Box

3. Click on the **Install** button.
4. When prompted, insert the *NI-Serial Software for Windows 2000/NT/Me/9x* CD, and click on the **Next** button to proceed. The software installation wizard begins with the screen shown in Figure 2-2.



**Figure 2-2.** NI-Serial Setup Screen

The setup wizard guides you through the necessary steps to install the NI-Serial software. You can go back and change values where appropriate by clicking on the **Back** button. You can exit the setup where appropriate by clicking on the **Cancel** button.

5. If you need to install your hardware, or if this is your first time to install the NI-Serial software for Windows Me/9x, skip to the next section, [Install the Hardware](#). Otherwise, continue to Step 6.
6. If your hardware is already installed, restart Windows Me/9x.

Windows Me/9x should automatically detect your hardware and display one or more **New Hardware Found** dialog boxes, but you must make sure **Windows Default Driver** is selected and click on **OK**. When you finish, continue to the [Verify the Installation](#) section.

If no **New Hardware Found** dialog box appears, refer to the [Forcing Windows to Detect Your Hardware](#) section in Appendix C, [Troubleshooting and Common Questions](#).

# Install the Hardware

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This section describes how to install your AT serial hardware.



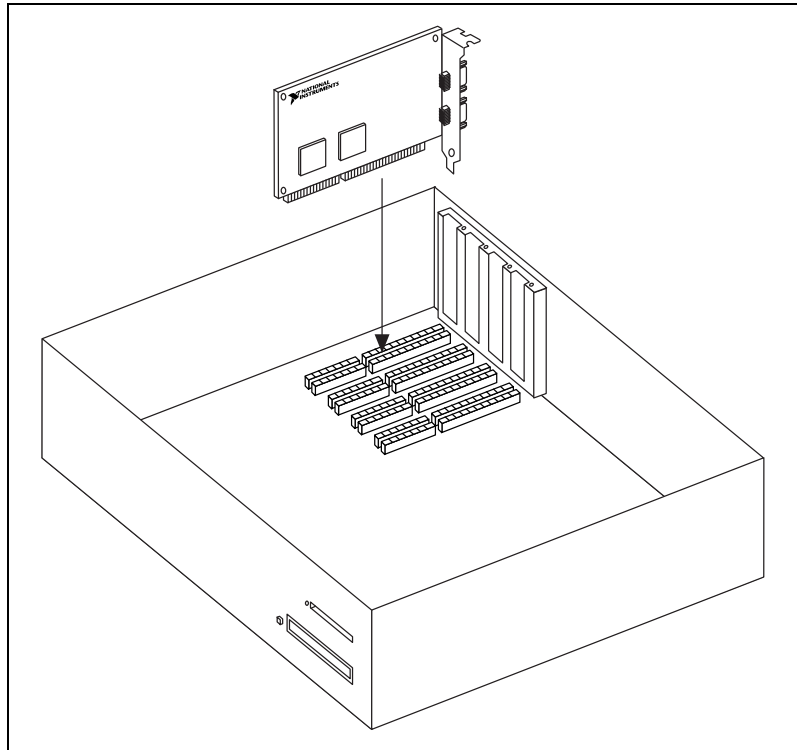
**Note** If you are installing a AT-485, you might need to adjust the value of the bias resistors, depending on your application. For more information, refer to Appendix A, [Serial Port Information](#).



**Caution** Before you remove your board from the package, touch the antistatic plastic package to a metal part of your system chassis to discharge electrostatic energy, which can damage several components on your serial board.

To install your AT serial board, complete the following steps:

1. Turn off your computer. Keep the computer plugged in so that it remains grounded while you install the AT serial board.
2. Remove the top or side cover of the computer.
3. Find an unused AT expansion slot in your computer.
4. Remove the corresponding expansion slot cover on the back panel of the computer.
5. Touch a metal part on your chassis to discharge any static electricity.
6. Insert the AT serial board into the slot with the serial connectors toward the opening on the back panel. Make sure that you insert the board all the way into the slot. The board might seem to click firmly into place, even though it is only part of the way in. Figure 2-3 shows how to install the AT serial board into an expansion slot.



**Figure 2-3.** AT Serial Board Installation

7. Screw the AT serial board mounting bracket to the back panel mounting rail of the computer.
8. Replace the cover.
9. Turn on your computer and start Windows Me/9x.
10. Watch for Windows Me/9x to display one or more **New Hardware Found** dialog boxes. In the dialog box, select **Windows Default Driver** and click on **OK**.

If no **New Hardware Found** dialog box appears, refer to the *Forcing Windows to Detect Your Hardware* section in Appendix C, *Troubleshooting and Common Questions*.

The serial hardware installation is complete. Continue to the next section, *Verify the Installation*.

## Verify the Installation

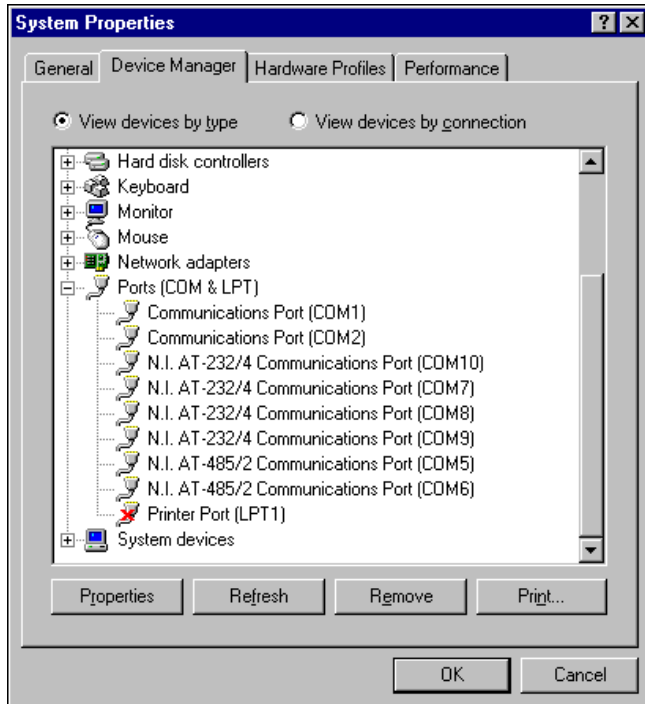
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When you begin to verify the installation, keep in mind that the serial ports built into the computer are typically named from COM1 to COM4. Windows Me/9x typically issues port names to the ports on NI serial hardware starting with COM5, COM6, and so on. If not enough resources are available to assign to all the NI serial ports, the port with the higher COMx name is left unconfigured.

Double-click on the **System** icon in the Control Panel. In the **System Properties** window that appears, select the **Device Manager** tab, and click on the **View devices by type** button at the top of the page. If necessary, double-click on the **Ports (COM & LPT)** icon to view all of the ports.

The shared IRQ AT serial boards are configured as devices belonging to the “multi-function adapters” class. The multi-function parent device is listed under the **Multi-function adapters** icon, and each child device is listed as a port under the **Ports (COM & LPT)** icon. If you have installed one of these interfaces, double-click on the **Multi-function adapters** icon as well as the **Ports (COM & LPT)** icon to look at the ports resources. To modify the hardware resources, double-click on the **Multi-Function adapters** icon.

If a circled exclamation point appears through the port icon, the serial port is not installed properly. A problem with the port may have occurred because Windows Me/9x could not acquire resources for the port, or because an interrupt request resource conflict exists. If no circled exclamation point appears, the serial hardware is installed correctly. Figure 2-4 shows an example of NI serial hardware that is installed properly and Figure 2-5 shows an example of NI serial hardware that is *not* working properly.



**Figure 2-4.** Device Manager Ports List for AT Serial Board Correctly Installed

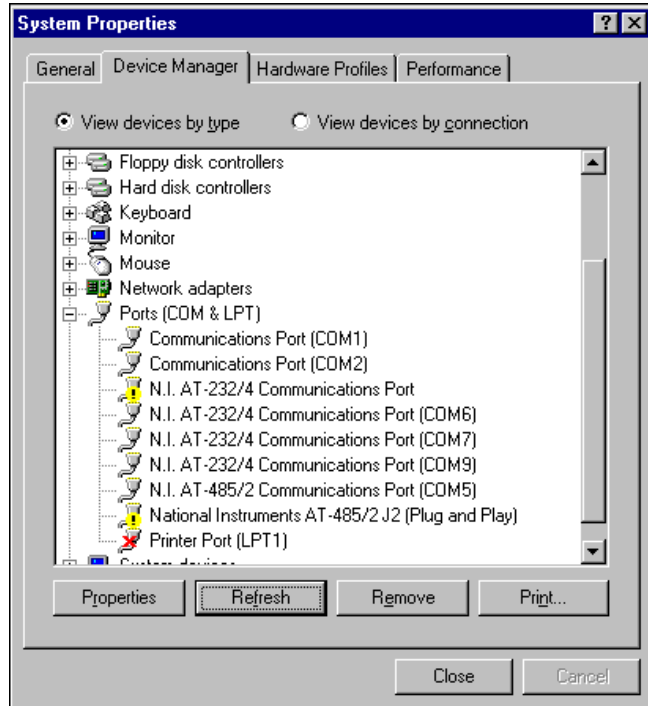


Figure 2-5. Device Manager Ports List for AT Serial Board Incorrectly Installed

## Verify the Hardware Resources

For every port of the newly installed serial interface, double-click on the name of the serial port in the Device Manager. Then, click on the **Resources** tab. If the resources were assigned correctly, the **Resources** page shows which resources are assigned to your serial ports.

If Windows Me/9x did not assign any resources to the port, the **Resources** page shows only a **Set Configuration Manually** button. Click on the **Set Configuration Manually** button and try to assign conflict-free resources to your serial hardware. For instructions, refer to the [Selecting Conflict-Free Resources](#) section of Appendix C, [Troubleshooting and Common Questions](#). You may have to free an interrupt request level so that one can be assigned to your serial hardware. For instructions, refer to the [Freeing an Interrupt Request Level](#) section in Appendix C, [Troubleshooting and Common Questions](#).

When you have finished verifying the hardware resources, proceed to the next section.

## Determine Which Physical Port Is Associated with COMx

For every port of the newly installed serial interface, double-click on the name of the serial port in the Device Manager. Then, click on the **Port Settings** tab. The top of this page displays the serial number of the serial hardware, and the physical port number starting at 1. On all serial hardware, PORT1 refers to the top port, PORT2 refers to the next port down, and so on.

When you have finished verifying the driver installation and physical port, proceed to the next section.

## Run the Diagnostic Test

To verify and test the installation, run the diagnostic program that came with your NI-Serial software. The diagnostic program verifies that your serial driver is installed properly, that the configuration of your hardware does not conflict with anything else in your system, and that the serial driver can communicate with your hardware correctly.

To run the test, select the **diagnostics** item under **Start»Programs»National Instruments Serial**.

If the diagnostic test completes with no failures, your serial hardware and software are installed properly. If it fails, refer to Appendix C, [Troubleshooting and Common Questions](#), for troubleshooting instructions.

## Connect the Cables

---

For the two-port AT serial boards, you can use the standard DB-9 connector found on most serial cables. To use the DB-9 connector with the four-port AT serial boards, you need the 10-position modular jack to DB-9 cable, which is available from National Instruments. (This cable is included with the isolated four-port kits.) You can also use a DB-25 connector with the four-port AT serial boards by ordering the 10-position modular jack to DB-25 converter cable from National Instruments.

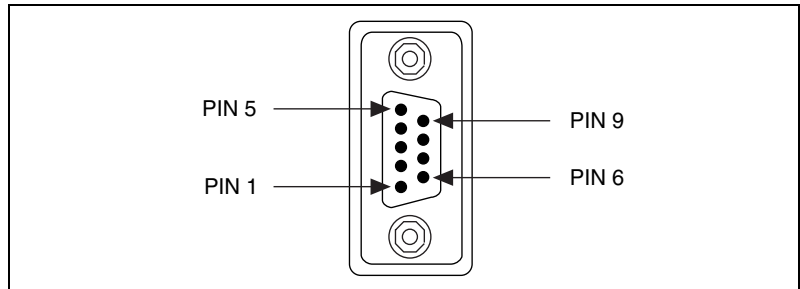


**Note** To achieve the specified isolation voltage for four-port isolated AT serial boards, use *only* the 10-position modular jack to DB-9 cable that is included in your four-port isolated AT serial board kit.



## DB-9 Connector

Figure 2-6 and Table 2-1 give the pin locations and descriptions of the DB-9 connector, which is on the two-port AT serial board, and the 10-position modular jack to DB-9 cable.



**Figure 2-6.** DB-9 Connector Pin Locations

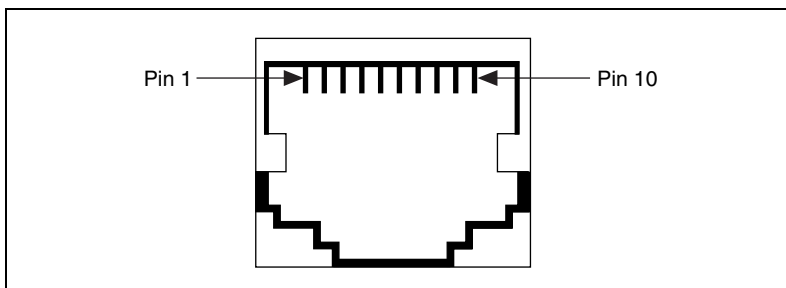
**Table 2-1.** DB-9 Pin Descriptions

DB-9 Pin	232 Signal	485 Signal
1	DCD*	GND
2	$\overline{\text{RXD}}$	CTS+ (HSI+)
3	$\overline{\text{TXD}}$	RTS+ (HSO+)
4	DTR*	RXD+
5	GND	RXD-
6	DSR*	CTS- (HSI-)
7	RTS	RTS- (HSO-)
8	CTS	TXD+
9	RI*	TXD-

\* These signals are not supported by the isolated 232 boards or ports 9-16 of the RS-232 sixteen-port board.

## Modular Jack Connector

Figure 2-7 and Table 2-2 give the pin locations and descriptions of the 10-position modular jack, which is on the four-port AT serial board.



**Figure 2-7.** 10-Position Modular Jack Pin Locations

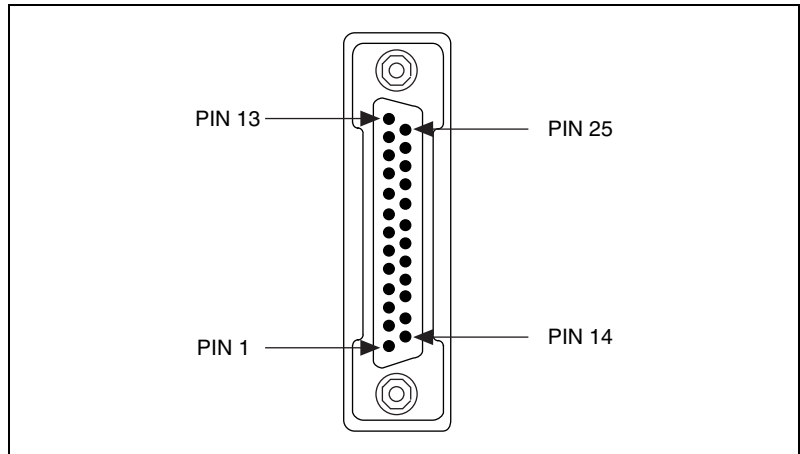
**Table 2-2.** 10-Position Modular Jack Pin Descriptions

10-Position Modular Jack Pin	232 Signal	485 Signal
10	DCD*	GND
9	$\overline{\text{RXD}}$	CTS+ (HSI+)
8	$\overline{\text{TXD}}$	RTS+ (HSO+)
7	DTR*	RXD+
6	GND	RXD-
5	DSR*	CTS- (HSI-)
4	RTS	RTS- (HSO-)
3	CTS	TXD+
2	RI*	TXD-
1	No Connect	No Connect

\* These signals are not supported by the isolated 232 ports.

## DB-25 Connector

Figure 2-8 and Table 2-3 give the pin locations and descriptions of the DB-25 connector, which is on the optional 10-position modular jack to DB-25 cable.



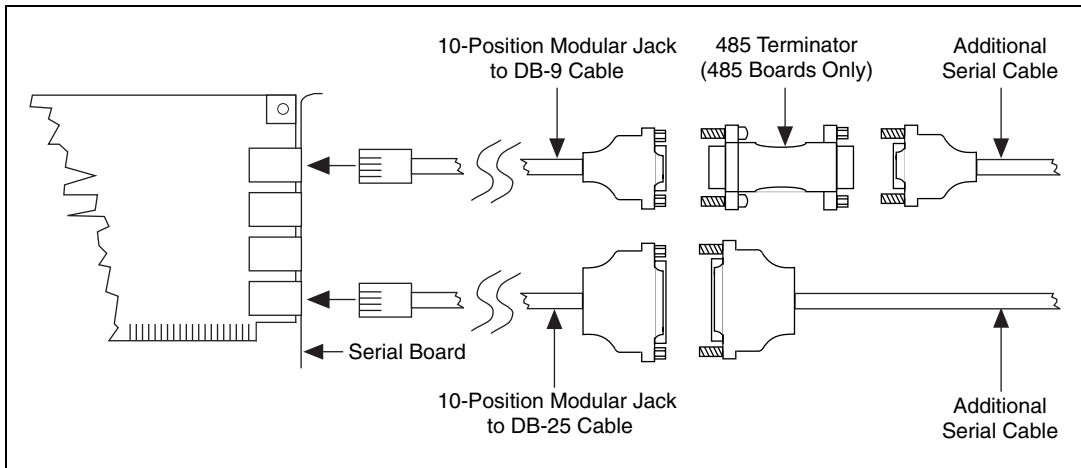
**Figure 2-8.** DB-25 Connector Pin Locations

**Table 2-3.** DB-25 Pin Descriptions

DB-25 Pin	232 Signal	485 Signal
2	$\overline{\text{TXD}}$	RTS+ (HSO+)
3	$\overline{\text{RXD}}$	CTS+ (HSI+)
4	RTS	RTS- (HSO-)
5	CTS	TXD+
6	DSR*	CTS- (HSI-)
7	GND	RXD-
8	DCD*	GND
20	DTR*	RXD+
22	RI*	TXD-

Pins not listed in this table are No Connect.  
 \* These signals are not supported by the isolated 232 ports.

Figure 2-9 shows how to connect the cables when you install a four-port AT serial board.



**Figure 2-9.** Connecting the Cables to Your Four-Port AT Serial Board

## Connecting Two-Wire Devices

The AT-485 boards are designed to work with either two- or four-wire devices. If you are using a two-wire device, refer to the device documentation for specific wiring instructions.

In general, half-duplex networks use a single twisted pair of wires for communication in both directions, so you must connect both the transmitter and the receiver at each end of the same pair of wires. For example, to connect an RS-485 data acquisition device to a port on your AT-485 using half-duplex communication, you need a single twisted pair of wires. At the AT-485, connect the TXD+ and RXD+ signals (pins 8 and 4 on a DB-9 connector, pins 5 and 20 on a DB-25 connector) together and to one wire. Connect the other end of this wire to both the TXD+ and RXD+ signals on the data acquisition device. Use the same method to connect the TXD- and RXD- signals (pins 9 and 5 on a DB-9 connector, pins 22 and 7 on a DB-25 connector) to the second wire.

For information about setting the transceiver mode for two-wire communication, refer to Chapter 4, *Using Your Serial Hardware*. For more information about duplex architectures, refer to Appendix A, *Serial Port Information*.

---

# Configuration

This chapter describes how to view or change the communication port settings.

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## View or Change Communication Port Settings

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The serial configuration utility is fully integrated into the Windows Me/9x Device Manager. You can use it to view or change the configuration of your serial ports.

Follow these steps to configure the serial port. Repeat the configuration procedure for each serial port in your system.

1. Select **Start»Settings»Control Panel** and double-click on the **System** icon. The **System Properties** window appears.
2. Select the **Device Manager** tab, and click on the **View devices by type** button at the top of the page.
3. Double-click on the **Ports (COM & LPT)** icon.
4. Double-click on the name of the port you want to configure.

You can now view or change information about your serial port in the following ways:

- To view the hardware resources assigned to the serial port, click on the **Resources** tab.
- To view or change the port settings, click on the **Port Settings** tab. For more information about the settings, refer to the next section, *Port Settings Tab*.
- To change the RS-485 transceiver mode, or to enable or disable the FIFOs on the serial hardware, in the **Port Settings** tab, click on the **Advanced** button. For more information about the settings, refer to the next section, *Port Settings Tab*.



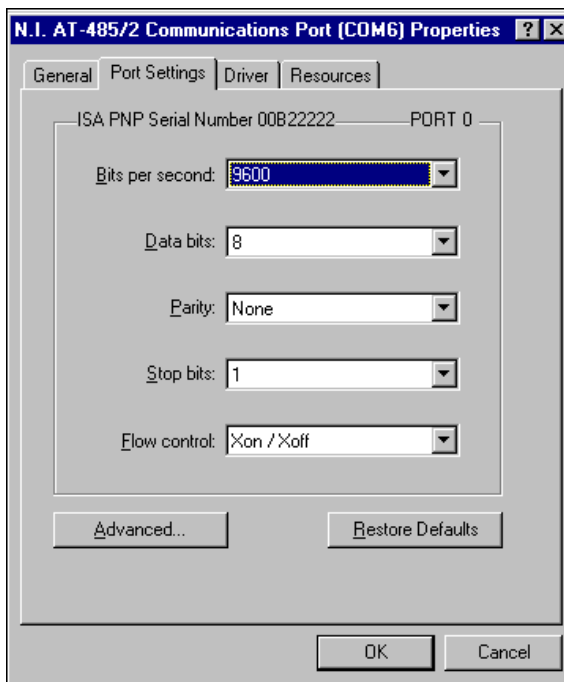
**Note** If you use two-wire TXRDY mode, FIFOs must be enabled. Transceiver modes apply to RS-485 interfaces only. For more information about transceiver modes, refer to Chapter 4, *Using Your Serial Hardware*.

5. To save your changes, click on the **OK** button. To exit without saving the changes, click on the **Cancel** button.

## Port Settings Tab

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On the **Port Settings** tab, you can change any of the settings by clicking on the arrow button to the right of the setting. When you click on the arrow button, a list of valid values for that setting appears. Select the desired setting from the list. Figure 3-1 shows the **Port Settings** tab.



**Figure 3-1.** Port Settings Tab

The following sections describe the options you can set in the Device Manager **Port Settings** tab.

### Bits per Second

**Bits per second**, or baud rate, is the speed for a serial port.

### Data Bits

**Data bits** is the number of data bits in a single serial byte.

## Parity

**Parity** is the specification for even, odd, or no parity bits in each transmitted byte.

## Stop Bits

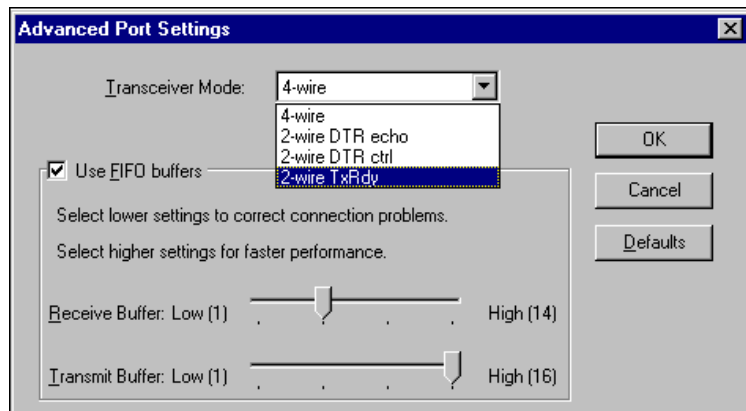
**Stop bits** is the number of terminating bits on the end of each transmitted serial byte.

## Flow Control

**Flow control** is a method for temporarily halting the stream of serial bytes to prevent overflow.

## Advanced Port Settings

You can view or change the advanced port settings by clicking on the **Advanced** button on the **Port Settings** tab. Figure 3-2 shows the **Advanced Port Settings** dialog box.



**Figure 3-2.** Advanced Port Settings Dialog Box

The following sections describe the advanced settings options.

### Transceiver Mode

The transceiver mode selection is available by clicking on the **Advanced** button on the **Port Settings** tab. It shows the transceiver mode in use, and applies only to AT-485 boards. For more information about transceiver modes, refer to Chapter 4, *Using Your Serial Hardware*.

## Use FIFO Buffers

The FIFO buffer control is available by clicking on the **Advanced** button on the **Port Settings** tab. FIFO buffers are present on the 16550-compatible UARTs—one for the transmitter and one for the receiver. The receiver FIFO trigger denotes the number of characters received in the FIFO before the PC is interrupted to read the data. The transmit FIFO trigger denotes the maximum number of bytes written to the FIFO in a block when the PC is interrupted to write the data. Consider the following points when selecting FIFO settings:

- You can select larger FIFO settings to reduce the number of interrupts and therefore minimize system overhead.
- If transfer rates are high, you can lower receive FIFO settings to prevent overrun errors due to interrupt latency.
- If data transfer sizes are small, selecting receive FIFO settings just above data sizes can reduce efficiency, so select lower settings.



**Note** If you want your serial hardware ports to use the names *COM1*, *COM2*, *COM3*, or *COM4*, refer to the [Common Questions](#) section of Appendix C, [Troubleshooting and Common Questions](#).



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# Using Your Serial Hardware

This chapter describes how to set the hardware transceiver control mode for your RS-485 interfaces and lists some general programming requirements.

## General Programming Requirements

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The NI-Serial software is fully integrated into the standard Windows Me/9x communications software. NI serial ports are used like any other Windows Me/9x communications (COM) port. Windows Me/9x has standard communication functions for use within either Win16 or Win32 applications.

When you develop your application, remember that you must use the standard Microsoft Windows serial communication functions. For information about Microsoft Windows serial communication functions, refer to the *Win32 Software Development Kit* and to the *Win32 Overviews and Win32 Reference* online help.

If you have LabVIEW or LabWindows/CVI and want to use it with your serial hardware, refer to your LabVIEW or LabWindows/CVI documentation for information about serial I/O functions.

## Advanced Transceiver Control for the AT-485

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**Note** Transceiver modes apply only to the AT-485 boards.

The AT-485 boards support four modes of hardware transceiver control. You can use hardware flow control to enable and disable your transmitters and receivers so that they function on different bus topologies. Table 4-1 lists the status of the transmitters and receivers under each of the transceiver control modes.

**Table 4-1.** Transceiver Control Modes

Mode	Transmitter	Receiver
Four-wire mode	Always enabled	Always enabled
Two-wire mode: $\overline{\text{DTR}}$ with echo	Enabled with $\overline{\text{DTR}}$ unasserted	Always enabled
Two-wire mode: $\overline{\text{DTR}}$ controlled	Enabled with $\overline{\text{DTR}}$ unasserted	Enabled with $\overline{\text{DTR}}$ asserted
Two-wire mode: $\overline{\text{TXRDY}}$ auto control	Enabled with $\overline{\text{TXRDY}}$ asserted	Enabled with $\overline{\text{TXRDY}}$ unasserted



**Note** Signal names with an overscore, such as  $\overline{\text{DTR}}$ , indicate that the signal is active low.

## Four-Wire Mode

Use the four-wire mode for most full-duplex systems. In this mode, the transmitter and receiver are always enabled. This mode is the default.

## Two-Wire Mode: $\overline{\text{DTR}}$ with Echo

Use this mode in half-duplex systems where the  $\overline{\text{DTR}}$  (Data Terminal Ready) line must control the transmitter. In the  $\overline{\text{DTR}}$ -with-echo mode, the transmitter is tri-stated when the  $\overline{\text{DTR}}$  signal of the UART (Universal Asynchronous Receiver/Transmitter) is asserted. To transmit, your application must first clear the  $\overline{\text{DTR}}$  bit to enable the transmitter. After the data is fully transmitted, your application once again sets the  $\overline{\text{DTR}}$  bit to disable the transmitter. Because the receiver is always enabled in this mode, you not only receive packets from other devices, you also receive the packets sent from your transmitter.

## Two-Wire Mode: $\overline{\text{DTR}}$ Controlled

This mode is similar to the two-wire,  $\overline{\text{DTR}}$ -with-echo mode. Use this mode in half-duplex systems where the  $\overline{\text{DTR}}$  line must control the transmitter. Although this mode uses the same method as the  $\overline{\text{DTR}}$ -with-echo mode to control the transmitter, the hardware automatically disables the receiver whenever the transmitter is enabled. Thus, you do not receive the packets sent from your transmitter.

## Two-Wire Mode: $\overline{\text{TXRDY}}$ Auto Control

In this mode, the serial hardware transparently enables the transmitter and receiver in a two-wire system. Use this mode to remove the burden of flow control from your application. By connecting the transmitter to the  $\overline{\text{TXRDY}}$  (Transmit Ready) line, the hardware enables the transmitter for each byte to be transmitted. Also, the hardware disables the receiver whenever the transmitter is enabled, so you do not receive the packets sent from your transmitter.



**Note** When you are communicating with a two-wire device, National Instruments recommends that you use the two-wire  $\overline{\text{TXRDY}}$  auto control mode. Because this mode handles the transmitter/receiver enabling for a two-wire connection in your hardware, it reduces the software overhead required to perform this operation in your application program.

For more information about serial communication in two- or four-wire modes, refer to the [Serial Communication Issues](#) section in Appendix A, [Serial Port Information](#).

## Setting the Transceiver Control Mode

The recommended method for setting the transceiver control mode is with the serial configuration utility located in the Windows Me/9x Device Manager. For more information, refer to the [View or Change Communication Port Settings](#) section in Chapter 3, [Configuration](#). The mode you select in the Device Manager is automatically configured when you open a port on a serial interface. You can also set the hardware transceiver control mode from within a DOS application. For each port you want to control, write the control byte for the mode you want to select to the scratch register of the UART. Table 4-2 shows the control bytes for each mode.

**Table 4-2.** Transceiver Mode Control Bytes

Transceiver Mode	Control Byte
Four-wire mode	0x00
Two-wire mode: $\overline{DTR}$ with echo	0x01
Two-wire mode: $\overline{DTR}$ controlled	0x02
Two-wire mode: $\overline{TXRDY}$ auto control	0x03

The scratch register is located at offset 7 from the base address of the port. For example, if COM2 were located at base address 0x3F8, and you wanted to set the AT-485 board to two-wire mode with  $\overline{DTR}$  control, you would write a 0x02 to I/O address 0x3FF. The AT-485 board would immediately switch to the two-wire mode with  $\overline{DTR}$  control.

## Setting the Transceiver Mode with DeviceIoControl

The NI-Serial software extends the `DeviceIoControl` Windows function for programming the transceiver control mode. To program the transceiver control mode using `DeviceIoControl`, complete the following steps:

1. Add the following lines to your source code:
 

```
#include <winioctl.h>

#define IOCTL_SERIAL_SET_TRANSCIEVER_MODE
CTL_CODE(FILE_DEVICE_SERIAL_PORT, 37,
METHOD_BUFFERED, FILE_ANY_ACCESS)
```
2. Use the Win32 function `DeviceIoControl`, as follows:
  - a. Use the defined control code value listed in step 1 to set the transceiver mode.
  - b. Use the input buffer values (unsigned long) listed in Table 4-3 for programming different transceiver modes.

**Table 4-3.** DeviceIoControl Function Input Values

<b>Transceiver Mode</b>	<b>DeviceIoControl Function Input Value</b>
Four-wire mode	128
Two-wire mode: $\overline{\text{DTR}}$ with echo	129
Two-wire mode: $\overline{\text{DTR}}$ controlled	130
Two-wire mode: $\overline{\text{TXRDY}}$ auto control	131

For example, to set  $\overline{\text{TXRDY}}$  two-wire auto control mode, use the following code:

```
ULONG TranceiverMode = 131;
DeviceIoControl(hDevice,
IOCTL_SERIAL_SET_TRANSCEIVER_MODE, (PVOID)
&TranceiverMode, sizeof(ULONG), lpOutBuffer,
nOutBufferSize, lpBytesReturned, lpOverlapped);
```

# Serial Port Information

This appendix describes the RS-232, RS-422, and RS-485 standards and explains some of the issues involved with these types of serial communication.

Table A-1 lists the features of the RS-232, RS-422, and RS-485 standards.

**Table A-1.** RS-232, RS-422, and RS-485 Features

Feature	RS-232	RS-422	RS-485
Type of transmission lines	Single ended	Differential	Differential
Maximum number of drivers	1	1	32
Maximum number of receivers	1	10	32
Maximum cable length	50 ft	4,000 ft	4,000 ft
Maximum data rate	20 kbytes/s	10 Mbytes/s	10 Mbytes/s
Maximum CMV	$\pm 25$ V	$\pm 7$ V	+12 to $-7$ V
Driver output	5 to 25 V	2 to 6 V	1.5 to 6 V
Driver load	$> 3$ k $\Omega$	100 $\Omega$	60 $\Omega$

## RS-232

As specified in the ANSI/EIA-232-D Standard, *Interface Between Data Terminal Equipment and Data Circuit-Terminating Equipment Employing Serial Binary Data Interchange*, RS-232 standardizes serial communication between computers, and between computer terminals and modems. Most applications use the RS-232 standard to interface peripherals to personal computers. RS-232 uses transmission lines in which the state of each signal is represented by referencing the voltage level of a single line to ground. RS-232 was designed for serial communication up to

distances of 50 ft. and with data rates up to 20 kbytes/s. However, because of improvements in line drivers and cabling, you can usually increase the actual performance of the bus past the limitations on speed and distance recommended in the specification.

## RS-422

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As specified in the EIA/RS-422-A Standard, *Electrical Characteristics of Balanced Voltage Digital Interface Circuits*, RS-422 defines a serial interface much like RS-232. However, RS-422 uses balanced (or differential) transmission lines. Balanced transmission lines use two transmission lines for each signal. The state of each signal is represented, not by a voltage level on one line referenced to ground as in RS-232, but rather by the relative voltage of the two lines to each other. For example, the TX signal is carried on two wires, wire A and wire B. A logical 1 is represented by the voltage on line A being greater than the voltage on line B. A logical 0 is represented by the voltage on line A being less than the voltage on line B. Differential voltage transmission creates a signal that is more immune to noise as well as voltage loss due to transmission line effects. Thus, you can use RS-422 for longer distances (up to 4,000 ft.) and greater transmission speeds (up to 10 Mbytes/s) than RS-232.

## RS-485

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As specified in the EIA-485 Standard, *Standard for Electrical Characteristics of Generators and Receivers for Use in Balanced Digital Multipoint Systems*, RS-485 expands on the RS-422 standard by increasing the number of devices you can use from 10 to 32 and by working with half-duplex bus architectures. Unlike the RS-422 standard, RS-485 addresses the issue of using multiple transmitters on the same line. RS-485 defines the electrical characteristics necessary to ensure adequate signal voltages under maximum load, short-circuit protection. RS-485 can also withstand multiple drivers driving conflicting signals at the same time.

# Serial Communication Issues

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This section explains some serial communication issues, including duplex architectures, termination methods, bias resistors, and types of connecting equipment.

## Duplex Architectures

*Duplex* refers to the means of bandwidth usage in a serial system. The two common means of bi-directional serial communication are full duplex and half duplex. Half-duplex communication involves a transmitter and a receiver connected to each end of the same wire or pair of wires. Because the same transmission line both sends and receives data, devices cannot send data in both directions at the same time. First, one device transmits over the wire(s) to the receiver of the second device. When the first device finishes transmitting, both devices switch the connections from their transmitter to their receiver, or vice versa. The device that was receiving data can then transmit over the line.

In full-duplex communication, the devices use a separate wire (or pair of wires) for simultaneous transmission in each direction. Thus, the devices do not switch between transmitting and receiving.

In a differential serial bus (such as RS-422 or RS-485), a half-duplex system transmits and receives over the same twisted pair of wires. Thus, half-duplex communication is often referred to as *two-wire* communications. Likewise, full-duplex communication is often referred to as *four-wire* communications, because the full-duplex system uses a separate pair of wires for communication in each direction.

## Full Duplex

A typical full-duplex multidrop bus architecture involves a master-slave protocol. Only one device, the master, can control access to the bus. All other devices are slaves. Slave devices must wait for the master to give them access to the bus. In a typical full-duplex system, one transmission line connects the bus master transmitter to all of the slave receivers. A second transmission line connects all of the slave transmitters to the bus master receiver. Because each transmission line has two separate wires, a full-duplex system is often referred to as a four-wire system. Figure A-1 shows a typical full-duplex system.



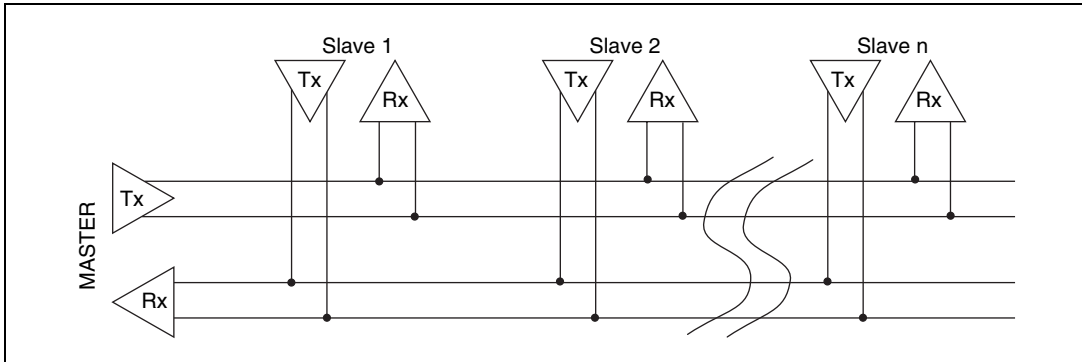


Figure A-1. Typical Full-Duplex System

## Half Duplex

A typical half-duplex multidrop bus architecture also involves a master-slave protocol. However, in a half-duplex system, all transmitters and receivers are connected to the same transmission line. A half-duplex system is often referred to as a two-wire system. Figure A-2 shows a typical half-duplex system.

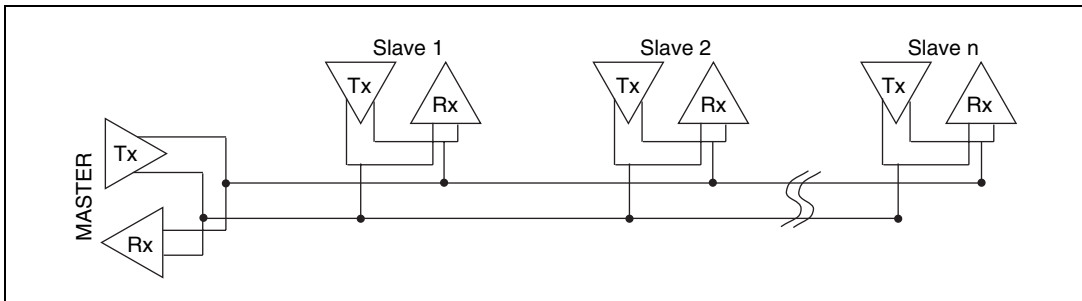
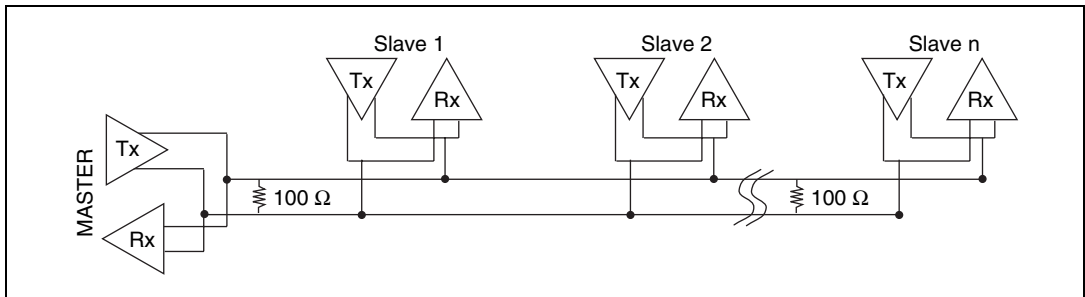


Figure A-2. Typical Half-Duplex System

## Termination

Because each differential pair of wires is a transmission line, you must properly terminate the line to prevent reflections. A common method of terminating a two-wire multidrop RS-485 network is to install terminating resistors at each end of the multidrop network. If you daisy-chained multiple instruments together, you need a terminating resistor at only the first and last instruments. The terminating resistor should match the characteristic impedance of the transmission line (typically 100 to 120  $\Omega$ ). You can order an optional DB-9 RS-485 termination connector that contains embedded terminating resistors for easy termination from National Instruments. For ordering information, contact National Instruments.

Figure A-3 shows a multidrop network using terminating resistors.

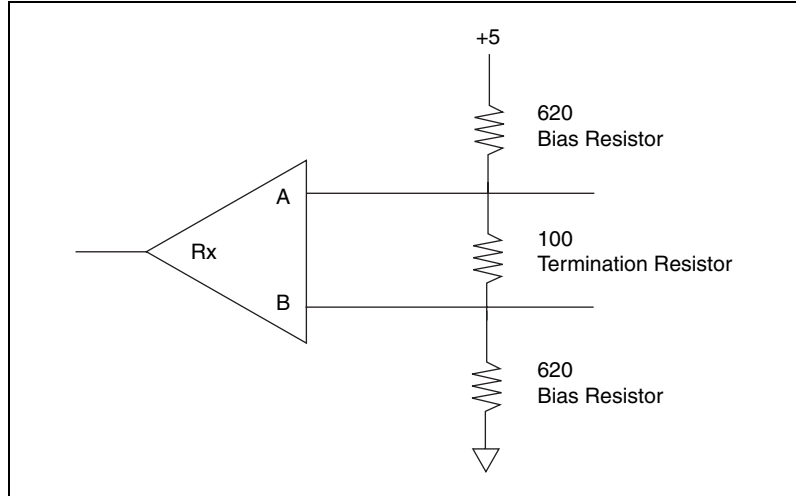


**Figure A-3.** Multidrop Network Using Terminating Resistors

## Bias Resistors

A transmission line enters an indeterminate state if no nodes are transmitting on it. This indeterminate state can cause the receivers to receive invalid data bits from noise picked up on the cable. To prevent a line from receiving these data bits, force the transmission line into a known state. To do so, install two 620  $\Omega$  bias resistors at one node on the transmission line; doing so creates a voltage divider that forces the voltage between the differential pair to be greater than 200 mV, the threshold voltage for the receiver. You should install these resistors on only one node.

Figure A-4 shows a transmission line using bias resistors.



**Figure A-4.** Transmission Line Using Bias Resistors

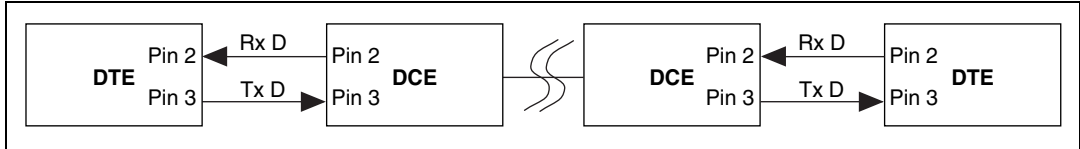
Rather than using two 620  $\Omega$  resistors at one node, you can increase the value of the resistors and put them at every node. For instance, if there are eight nodes in a system, you can use 4.7 k $\Omega$  resistors at each node to effectively achieve the same result.

## DTE vs. DCE

In the RS-232 specification, DTE (Data Terminal Equipment) and DCE (Data Communications Equipment)<sup>1</sup> refer to the types of equipment on either end of a serial connection. In general, DTE and DCE refer to computer equipment and modems, respectively. Because the RS-232 specification mainly involves connecting a DTE directly to a DCE and vice versa, the pinouts are defined so that cabling is simple. That is, a cable connected a computer to a modem by wiring pin 1 to pin 1, pin 2 to pin 2, and so on. This method is known as *straight-through* cabling.

<sup>1</sup> In Revision D of the RS-232 specification, a DCE is a Data Circuit-Terminating Equipment.

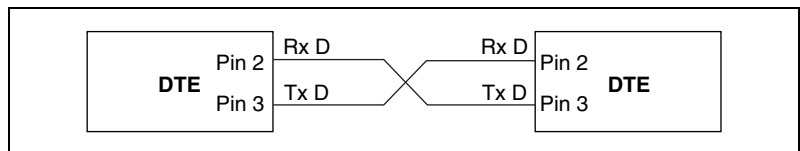
Figure A-5 shows straight-through cabling in a DTE-to-DCE interface.



**Figure A-5.** Straight-Through Cabling in a DTE-to-DCE Interface

Straight-through cabling is still the standard method to connect a modem to your PC. However, because many applications use serial communication to connect two or more DTEs without modems, the cabling becomes more complicated. If two DTEs are wired together using a straight-through cable, one transmitter is connected to the other transmitter, and one receiver is connected to the other receiver. In this setup, no transmissions can occur. Thus, these applications must use a cabling scheme that connects the transmitter on one device to the receiver on the other device and vice versa. This method is known as *null-modem* cabling, because it replaces the two modems that traditional RS-232 applications would require between the two DTEs. To communicate from one serial port to another, use a null-modem cable.

Figure A-6 shows null-modem cabling in a DTE-to-DTE interface.



**Figure A-6.** Null-Modem Cabling in a DTE-to-DTE Interface

# Uninstalling the Hardware and Software

This appendix describes how to uninstall your serial hardware and the NI-Serial software.

## Uninstall the Hardware

---

Before physically removing the serial hardware, you must remove the hardware information from the Windows Me/9x Device Manager.

Follow these steps to uninstall the hardware:

1. Double-click on the **System** icon under **Start»Settings»Control Panel**. The **System Properties** dialog box appears.
2. Select the **Device Manager** tab.
3. Click on the **View devices by type** button.
4. Double-click on the **Ports (COM & LPT)** icon.
5. Select the National Instruments port to remove from the list of ports, as shown in Figure B-1.

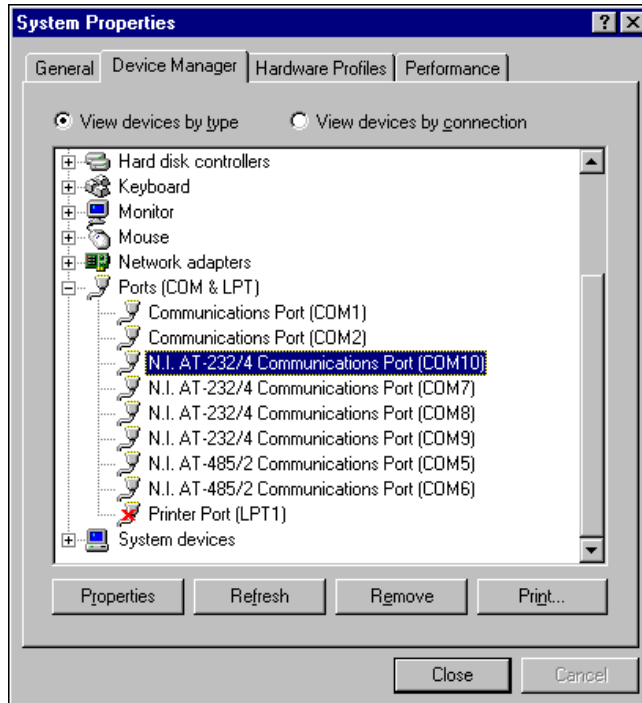


Figure B-1. Selecting an Interface to Uninstall

6. Click on the **Remove** button.



**Note** To remove ports on shared IRQ AT boards from within the Device Manager, you must open the **Multi-function adapters** class, select the name of your interface, and click on the **Remove** button.

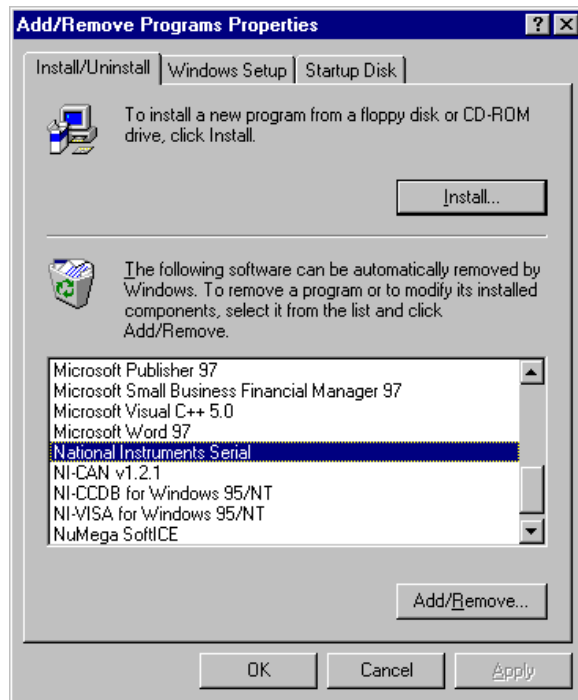
7. In the **Confirm Device Removal** dialog box, click on the **OK** button to remove this interface or click on **Cancel** to cancel your request.

# Uninstall the Software

Before uninstalling the software, remove all serial port information from the Windows Me/9x Device Manager, as described in the previous section. You do not need to shut down Windows Me/9x before uninstalling the software.

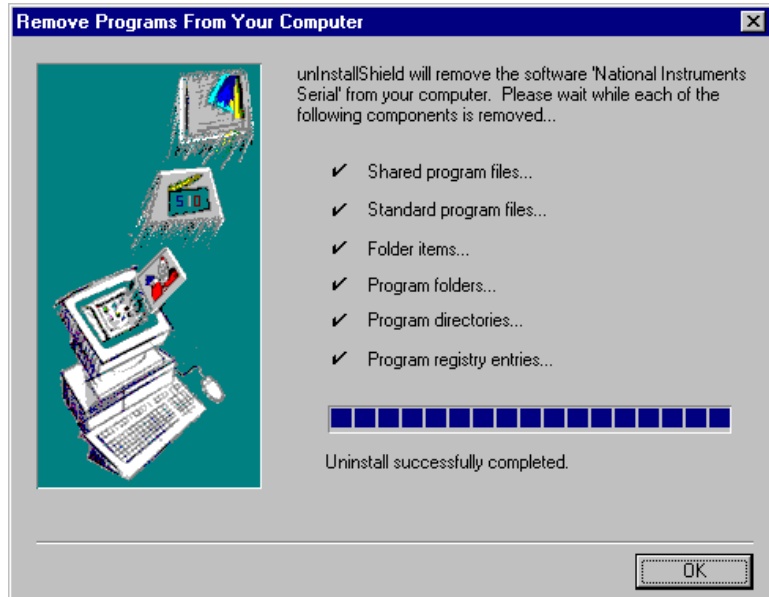
Complete the following steps to remove the NI-Serial software:

1. Select **Start»Settings»Control Panel**.
2. Double-click on the **Add/Remove Programs** icon in the Control Panel to launch the Add/Remove Programs applet. A dialog box similar to the one in Figure B-2 appears. This dialog box lists the software available for removal.



**Figure B-2.** Add/Remove Programs Properties Dialog Box

3. Select the serial software you want to remove, and click on the **Add/Remove** button. The uninstall program runs and removes all folders, programs, VxDs, DLLs, and registry entries associated with the NI-Serial software. Figure B-3 shows the results of a successful uninstallation.



**Figure B-3.** Successful Uninstallation

4. Shut down Windows Me/9x, turn off your computer, and physically remove the serial interfaces from your system.

If you want to reinstall the hardware and software, refer to Chapter 2, [Installation and Verification](#).





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# Troubleshooting and Common Questions

This appendix describes how to troubleshoot problems and answers some common questions.

## Freeing an Interrupt Request Level

---

To free an interrupt request level for your serial port, you must disable the device that is using the interrupt request level. To view the system-wide allocation of interrupt request resources and remove a device, complete the following steps:

1. Select **Start»Settings»Control Panel** and double-click on the **System** icon.
2. Click on the **Device Manager** tab.
3. Double-click on the **Computer** icon and click on the **View Resources** tab.
4. Click on the **Interrupt Request (IRQ)** button. Scan through the list of IRQ settings to determine which devices are using which interrupt request levels.
5. When you locate a device that you are not currently using, click on the **Cancel** button.
6. In the **Device Manager** tab, double-click on the icon for that device.
7. In the **Device usage** field, a checkmark appears to the left of the current configuration, usually **Original Configuration (Current)**. Click on the checkbox to remove the checkmark.
8. Click on the **Resources** tab and make sure that **Use automatic settings** is unchecked.
9. Repeat steps 7 through 9 for each unused device.
10. Click on the **OK** button to save your changes.
11. Restart Windows Me/9x to assign resources to your serial port. Then, complete step 6 in the *Verify the Hardware Resources* section of Chapter 2, *Installation and Verification*.

## Selecting Conflict-Free Resources

---

When the Device Manager indicates a conflict with another device, you can usually correct the problem by manually selecting conflict-free resources. To do so, complete the following steps:

1. Select **Start»Settings»Control Panel**.
2. Double-click on the **System** icon.
3. Select the **Device Manager** tab, and click on the **View devices by type** button at the top of the page.
4. Double-click on the **Ports (COM & LPT)** icon. A list of installed ports appears.
5. Double-click on the name of the serial port you want to change, then click on the **Resources** tab.



**Note** To change the resources of ports on shared IRQ AT boards from within the Device Manager, you must open the **Multi-function adapters** class and double-click on the name of your interface. Use the **Resources** page to change the resources. Any resource changes are automatically reflected to the child devices.

6. Uncheck the **Use automatic settings** checkbox and click on the **Change Setting** button. If the system does not allow you to change the settings, select the configuration that gives you a conflict-free base address and interrupt level from the **Setting based on** list box.
7. Click on the **OK** button to save your changes.

## Troubleshooting Diagnostic Messages

---

This section lists possible error messages returned by the diagnostic utility, along with solutions.

### No National Instruments Serial Port Found

If the **No National Instruments serial port found** error message appears, complete the following steps:

1. Verify the hardware resources, as follows:
  - a. In the **Device Manager** tab, under **Multi-function adapters**, double-click on a serial board.
  - b. If a serial board is missing from the **Multi-function adapters** list, reinstall the hardware and software. For instructions on how to do so, refer to Chapter 2, *Installation and Verification*.

- c. Click on the **Resources** tab. If the resources were assigned properly, the **Resources** tab shows which resources are assigned to your serial ports.
  - d. Check the hardware resources. If they are in conflict, refer to the previous section, *Selecting Conflict-Free Resources*.
2. In some versions of Windows Me/9x, in the Device Manager, the **Driver** tab shows information about the installed driver. Make sure that the National Instruments serial driver is installed for the port.  
If the serial driver is a Microsoft driver, reinstall the NI-Serial software. For instructions on how to do so, refer to Chapter 2, *Installation and Verification*.
  3. Make sure that the National Instruments serial driver is installed, as follows:
    - a. Locate the `niserial.vxd` file in the `\Windows\system` directory.
    - b. If the `niserial.vxd` file is missing, reinstall the hardware and software. For instructions on how to do so, refer to Chapter 2, *Installation and Verification*.

## Diagnostic Utility Does Not Show All Installed Ports

If the diagnostic utility does not show all the ports you installed, complete the following steps:

1. Verify the hardware resources, as follows:
  - a. In the **Device Manager** tab, under **Multi-function adapters**, double-click on a serial board.
  - b. If a serial board is missing from the **Multi-function adapters** list, reinstall the hardware and software. For instructions on how to do so, refer to Chapter 2, *Installation and Verification*.
  - c. Click on the **Resources** tab. If the resources were assigned properly, the **Resources** tab shows which resources are assigned to your serial ports.
  - d. Check the hardware resources. If they are in conflict, refer to the previous section, *Selecting Conflict-Free Resources*.
2. In some versions of Windows Me/9x, in the Device Manager, the **Driver** tab shows information about the installed driver. Make sure that the National Instruments serial driver is installed for the port.  
If the serial driver is a Microsoft driver, reinstall the NI-Serial software. For instructions on how to do so, refer to Chapter 2, *Installation and Verification*.

3. Physically make sure the correct number of boards/ports are installed.

## Address Test Failed

If the **address test failed, Interrupt test cannot be performed** error message appears, you might have an address conflict with legacy boards in your system. To solve this problem, change the base addresses assigned to your legacy boards and refer to the [Resolving Resource Conflicts with Legacy Boards](#) section later in this appendix.

## Interrupt Test Failed

If the **Interrupt test failed** error message appears, you might have an IRQ conflict with legacy boards in your system. To solve this problem, change the IRQ level assigned to your legacy boards and refer to the next section, *Resolving Resource Conflicts with Legacy Boards*.

## Resolving Resource Conflicts with Legacy Boards

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Resource conflicts typically occur if your system contains legacy boards that use resources that are not reserved properly. If a resource conflict exists, write down the resource that caused the conflict and refer to the Microsoft Windows Me/9x user's guide for instructions on how to use the Device Manager to reserve I/O and IRQ resources for legacy boards.

## Forcing Windows to Detect Your Hardware

---

If Windows does not detect your serial hardware correctly, or you have been using your serial hardware with the default Windows Me/9x serial driver or an older version of the NI-Serial software, Windows Me/9x does not display the **New Hardware Found** dialog box. To fix this problem, follow these steps:

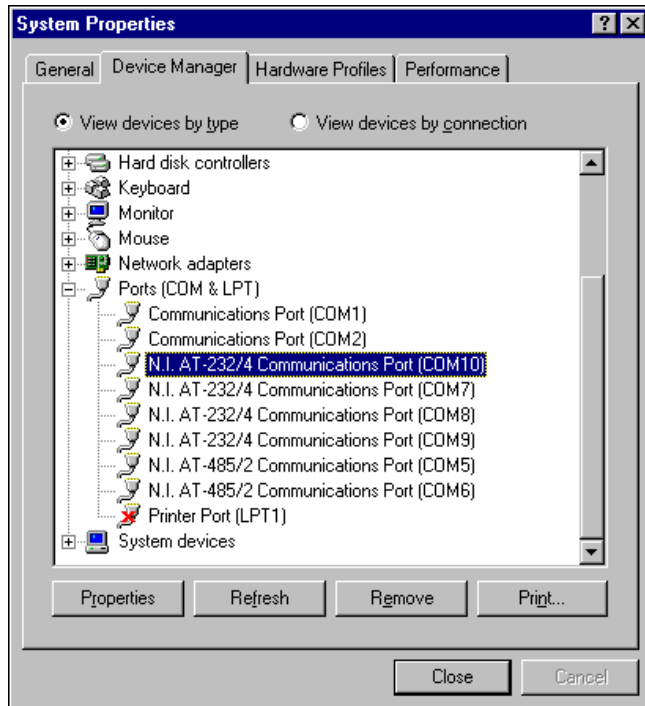
1. Select **Start»Settings»Control Panel**.
2. Double-click on the **System** icon.
3. Select the **Device Manager** tab.
4. Click on the **View devices by type** button.
5. Double-click on the **Ports (COM & LPT)** icon to display a list of all ports that Windows Me/9x recognizes.

If you have already installed the hardware, double-click on **Other Devices** to display where Windows Me/9x lists the ports it does not recognize.

- Select a National Instruments port name from the list of ports that corresponds to a serial port (for example, COM 5, COM 6, COM 7, or COM 8). Figure C-1 shows the **Ports** list in the **Device Manager** with a port selected.



**Note** To remove ports on shared IRQ cards, you must open the **Multifunction adapter** class, select the name of the interface, and click on the **Remove** button.



**Figure C-1.** Ports List in Device Manager

- Click on the **Remove** button, and click on **OK** to confirm the removal of the serial hardware information.

Repeat steps 6 and 7 until all serial board entries are removed. Then, click on **Refresh** to force Windows Me/9x to detect the serial hardware and display the **New Hardware Found** dialog box.

## Common Questions

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### How can I determine which type of serial hardware I have installed?

1. Select **Start»Settings»Control Panel** and double-click on the **System** icon.
2. Click on the **Device Manager** tab and click on the **View devices by type** button.
3. Double-click on the **Ports (COM & LPT)** icon to display a list of installed ports.

### How can I determine which version of the NI-Serial software I have installed?

The **Read Me** file gives the version of the software. To open the file, select **Start»Programs»National Instruments Serial»Read Me**.

### What do I do if the diagnostic test fails with an error?

Refer to the [Troubleshooting Diagnostic Messages](#) section earlier in this appendix.

### How can I determine which port is associated with COMx?

To determine which physical port is associated with COM $x$ , complete the following steps:

1. In the **Device Manager** tab, under **Ports (COM & LPT)**, double-click on a serial port.
2. Click on the **Port Settings** tab to display the serial number of the serial hardware and the physical port number starting at 1. For all serial hardware, PORT1 refers to the top port, PORT2 refers to the next port down, and so on.

### How can I change the COM numbers of my National Instruments serial ports?

To name serial ports COM1, COM2, COM3, or COM4, change the base address of the port. To do so, refer to the [Selecting Conflict-Free Resources](#) section earlier in this appendix.

When you change the base address, Windows Me/9x automatically converts it to the corresponding COM name listed in Table C-1. You do not need to change the IRQ setting for Windows Me/9x to change the name.

**Table C-1.** Standard DOS-Based Addresses

<b>COM Port</b>	<b>Base Address</b>
COM1	3f8
COM2	2f8
COM3	3e8
COM4	2e8

**How do I change the resources assigned to the serial interface?**

Because the shared IRQ AT boards are single physical devices that support multiple ports, they are registered as “multi-function adapters” in the Device Manager. Each port is a child device listed under **Ports (COM & LPT)**. Windows Me/9x does not allow the resources of the multi-function child devices to be changed directly.

To change the resources of ports on shared IRQ AT boards from within the Device Manager, you must open the **Multi-function adapters** class and double-click on the **Multi-function Parent** item that corresponds to your National Instruments serial interface. Use the **Resources** page to change the resources. Any resource changes are automatically reflected to the child devices. Figure C-2 shows the **Multi-function adapters** class in the Device Manager.

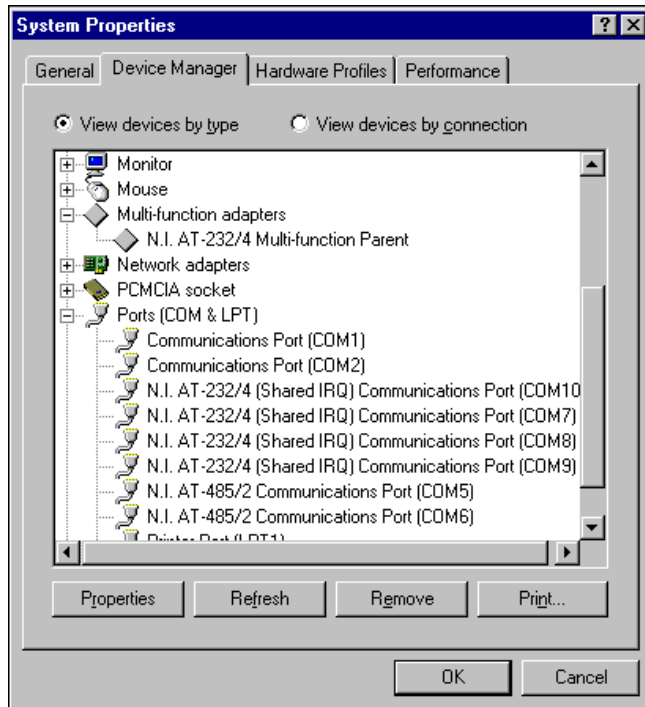


Figure C-2. Multi-Function Adapter Class in the Device Manager

### How do I remove information about serial boards from the Device Manager?

Because the shared IRQ AT boards are single physical devices that support multiple ports, they are registered as “multi-function adapters” in the Device Manager. Each port is a child device listed under **Ports (COM & LPT)**. Windows Me/9x does not allow multi-function child devices to be removed directly within the Device Manager. You must open the **Multi-function adapters** class as shown in Figure C-2, select your interface, and click on the **Remove** button.

### How many interrupts are required for my serial interface?

If you have a shared IRQ board or an isolated board, you need one interrupt per board. This is the hardware that currently ships with Windows Me/9x.

If you have an older non-shared IRQ board, you need as many interrupts as there are ports on the board.



# Specifications

This appendix describes the characteristics of the serial hardware, the NI-Serial software, along with the recommended operating conditions.

**Table D-1.** Physical Characteristics of the Two-Port AT Serial Boards (Non-Isolated)

Characteristic	Specification
Dimensions	10.67 by 16.51 cm (4.2 by 6.5 in.)
I/O Connector	DB-9
Power Requirement (from PC AT I/O channel)	
AT-485/2	+5 VDC      390 mA Typical 510 mA Maximum
AT-232/2	+5 VDC      260 mA Typical 340 mA Maximum
AT-485/2 (Shared IRQ)	+5 VDC      140 mA Typical 180 mA Maximum
AT-232/2 (Shared IRQ)	+5 VDC      70 mA Typical 100 mA Maximum

**Table D-2.** Physical Characteristics of the Two-Port Isolated AT Serial Boards

<b>Characteristic</b>	<b>Specification</b>
Dimensions	10.67 by 18.70 cm (4.2 by 7.4 in.)
I/O Connector	DB-9
Isolation Voltage	
From Port to Port	3000 Vrms/60s
From Any Port to Host Computer	2000 Vrms/60s
Power Requirement (from PC AT I/O channel)	
AT-485/2 Isolated	+5 VDC      220 mA Typical 260 mA Maximum
AT-232/2 Isolated	+5 VDC      160 mA Typical 200 mA Maximum

**Table D-3.** Physical Characteristics of the Four-Port AT Serial Boards (Non-Isolated)

<b>Characteristic</b>	<b>Specification</b>
Dimensions	10.67 by 16.51 cm (4.2 by 6.5 in.)
I/O Connector*	10-position modular jack
Power Requirement (from PC AT I/O channel)	
AT-485/4	+5 VDC      160 mA Typical 200 mA Maximum
AT-232/4	+5 VDC      110 mA Typical 150 mA Maximum
AT-485/4 (Shared IRQ)	+5 VDC      160 mA Typical 200 mA Maximum
AT-232/4 (Shared IRQ)	+5 VDC      110 mA Typical 150 mA Maximum
* The four-port AT serial board requires a cable to convert the 10-position modular jack to either DB-9 or DB-25 connectors.	

**Table D-4.** Physical Characteristics of the Four-Port Isolated AT Serial Boards

<b>Characteristic</b>	<b>Specification</b>
Dimensions	10.67 by 25.40 cm (4.2 by 10.0 in.)
I/O Connector*	10-position modular jack
Isolation Voltage	
From Port to Port	3000 Vrms/60s
From Any Port to Host Computer	2000 Vrms/60s
Power Requirement (from PC AT I/O channel)	
AT-485/4 Isolated	+5 VDC    300 mA Typical 360 mA Maximum
AT-232/4 Isolated	+5 VDC    280 mA Typical 320 mA Maximum
* The four-port isolated AT serial board requires cables, which are included in your kit, to convert the 10-position modular jack to a DB-9 connector. Use only the type of cables provided in your kit.	

**Table D-5.** Environmental Characteristics of the Serial Hardware

<b>Characteristic</b>	<b>Specification</b>
Operating Environment	
Component Temperature	0 to 70° C
Relative Humidity	10 to 90%, noncondensing
Storage Environment	
Temperature	-40 to 120° C
Relative Humidity	5 to 90%, noncondensing
EMI	
AT Serial	FCC Class B Certified
AT Serial Isolated	FCC Class A Verified

## Software Characteristics

**Table D-6.** Software Characteristics

<b>Characteristic</b>	<b>Specification</b>
Maximum Serial Transfer Rate	115,200 bps*
* Actual speed may vary considerably from speed shown due to system and instrumentation capabilities.	



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# Technical Support Resources

## Web Support

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National Instruments Web support is your first stop for help in solving installation, configuration, and application problems and questions. Online problem-solving and diagnostic resources include frequently asked questions, knowledge bases, product-specific troubleshooting wizards, manuals, drivers, software updates, and more. Web support is available through the Technical Support section of [ni.com](http://ni.com)

## NI Developer Zone

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The NI Developer Zone at [ni.com/zone](http://ni.com/zone) is the essential resource for building measurement and automation systems. At the NI Developer Zone, you can easily access the latest example programs, system configurators, tutorials, technical news, as well as a community of developers ready to share their own techniques.

## Customer Education

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National Instruments provides a number of alternatives to satisfy your training needs, from self-paced tutorials, videos, and interactive CDs to instructor-led hands-on courses at locations around the world. Visit the Customer Education section of [ni.com](http://ni.com) for online course schedules, syllabi, training centers, and class registration.

## System Integration

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If you have time constraints, limited in-house technical resources, or other dilemmas, you may prefer to employ consulting or system integration services. You can rely on the expertise available through our worldwide network of Alliance Program members. To find out more about our Alliance system integration solutions, visit the System Integration section of [ni.com](http://ni.com)

## Worldwide Support

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National Instruments has offices located around the world to help address your support needs. You can access our branch office Web sites from the Worldwide Offices section of [ni.com](http://ni.com). Branch office Web sites provide up-to-date contact information, support phone numbers, e-mail addresses, and current events.

If you have searched the technical support resources on our Web site and still cannot find the answers you need, contact your local office or National Instruments corporate. Phone numbers for our worldwide offices are listed at the front of this manual.

# Glossary

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Prefix	Meaning	Value
p-	pico-	$10^{-12}$
n-	nano-	$10^{-9}$
$\mu$ -	micro-	$10^{-6}$
m-	milli-	$10^{-3}$
k-	kilo-	$10^3$
M-	mega-	$10^6$
G-	giga-	$10^9$
t-	tera-	$10^{12}$

° degrees

$\Omega$  ohms

% percent

A amperes

ANSI American National Standards Institute

b bits

B bytes

baud bits per second

bps bits per second

C Celsius

COM Computer Output Microform; used in reference to a communication port

CTS clear to send

DB-xx subminiature D connector, where xx is the number of pins

*Glossary*

DCD	data carrier detect
DCE	data communications equipment or data circuit-terminating equipment
DLL	dynamic link library
DMA	direct memory access
DSR	data set ready
DTE	data terminal equipment
$\overline{\text{DTR}}$	data terminal ready—the overscore denotes that the signal is active low
duplex	the means of bandwidth usage in a serial system
EIA	Electronic Industries Association
EMI	electromagnetic interference
FCC	Federal Communications Commission
FIFO	First-In-First-Out
ft	feet
GND	ground
HSI	handshake input
HSO	handshake output
Hz	Hertz
IEEE	Institute of Electrical and Electronic Engineers
in.	inches
I/O	input/output
IRQ	interrupt request
ISA	Industry Standard Architecture
Kbaud	kilobits per second
m	meters



MB	megabytes of memory
PC	personal computer
PCI	Peripheral Components Interconnect
RAM	random-access memory
RI	ring indicator
RTS	request to send
RX	receive
$\overline{\text{RXD}}$	receive data—the overscore denotes that the signal is active low
s	seconds
SCSI	Small Computer Systems Interface
TX	transmit
$\overline{\text{TXD}}$	transmit data—the overscore denotes that the signal is active low
$\overline{\text{TXRDY}}$	transmit ready—the overscore denotes that the signal is active low
UART	Universal Asynchronous Receiver/Transmitter
V	volts
VDC	volts direct current
VXI	VME eXtensions for Instrumentation
Win16	describes a 16-bit Windows application
Win32	describes a 32-bit Windows application

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