#### **COMPREHENSIVE SERVICES**

We offer competitive repair and calibration services, as well as easily accessible documentation and free downloadable resources.

#### **SELL YOUR SURPLUS**

We buy new, used, decommissioned, and surplus parts from every NI series. We work out the best solution to suit your individual needs.

## **OBSOLETE NI HARDWARE IN STOCK & READY TO SHIP**

We stock New, New Surplus, Refurbished, and Reconditioned NI Hardware.



**Bridging the gap** between the manufacturer and your legacy test system.

0

1-800-915-6216



www.apexwaves.com

sales@apexwaves.com

All trademarks, brands, and brand names are the property of their respective owners.

Request a Quote



DAQCard-1200



# Getting Results with ComponentWorks™



#### **Internet Support**

E-mail: support@natinst.com FTP Site: ftp.natinst.com

Web Address: http://www.natinst.com

#### **Bulletin Board Support**

BBS United States: 512 794 5422 BBS United Kingdom: 01635 551422

BBS France: 01 48 65 15 59

#### Fax-on-Demand Support

512 418 1111

#### Telephone Support (USA)

Tel: 512 795 8248 Fax: 512 794 5678

#### **International Offices**

Australia 03 9879 5166, Austria 0662 45 79 90 0, Belgium 02 757 00 20, Brazil 011 288 3336, Canada (Ontario) 905 785 0085, Canada (Québec) 514 694 8521, Denmark 45 76 26 00, Finland 09 725 725 11, France 01 48 14 24 24, Germany 089 741 31 30, Hong Kong 2645 3186, Israel 03 6120092, Italy 02 413091, Japan 03 5472 2970, Korea 02 596 7456, Mexico 5 520 2635, Netherlands 0348 433466, Norway 32 84 84 00, Singapore 2265886, Spain 91 640 0085, Sweden 08 730 49 70, Switzerland 056 200 51 51, Taiwan 02 377 1200, United Kingdom 01635 523545

#### **National Instruments Corporate Headquarters**

6504 Bridge Point Parkway Austin, Texas 78730-5039 USA Tel: 512 794 0100

© Copyright 1996, 1998 National Instruments Corporation. All rights reserved.

## **Important Information**

#### Warranty

The media on which you receive National Instruments software are warranted not to fail to execute programming instructions, due to defects in materials and workmanship, for a period of 90 days from date of shipment, as evidenced by receipts or other documentation. National Instruments will, at its option, repair or replace software media that do not execute programming instructions if National Instruments receives notice of such defects during the warranty period. National Instruments does not warrant that the operation of the software shall be uninterrupted or error free.

A Return Material Authorization (RMA) number must be obtained from the factory and clearly marked on the outside of the package before any equipment will be accepted for warranty work. National Instruments will pay the shipping costs of returning to the owner parts which are covered by warranty.

National Instruments believes that the information in this manual is accurate. The document has been carefully reviewed for technical accuracy. In the event that technical or typographical errors exist, National Instruments reserves the right to make changes to subsequent editions of this document without prior notice to holders of this edition. The reader should consult National Instruments if errors are suspected. In no event shall National Instruments be liable for any damages arising out of or related to this document or the information contained in it.

EXCEPT AS SPECIFIED HEREIN, NATIONAL INSTRUMENTS MAKES NO WARRANTIES, EXPRESS OR IMPLIED, AND SPECIFICALLY DISCLAIMS ANY WARRANTY OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE. CUSTOMER'S RIGHT TO RECOVER DAMAGES CAUSED BY FAULT OR NEGLIGENCE ON THE PART OF NATIONAL INSTRUMENTS SHALL BE LIMITED TO THE AMOUNT THERETOFORE PAID BY THE CUSTOMER. NATIONAL INSTRUMENTS WILL NOT BE LIABLE FOR DAMAGES RESULTING FROM LOSS OF DATA, PROFITS, USE OF PRODUCTS, OR INCIDENTAL OR CONSEQUENTIAL DAMAGES, EVEN IF ADVISED OF THE POSSIBILITY THEREOF. This limitation of the liability of National Instruments will apply regardless of the form of action, whether in contract or tort, including negligence. Any action against National Instruments must be brought within one year after the cause of action accrues. National Instruments shall not be liable for any delay in performance due to causes beyond its reasonable control. The warranty provided herein does not cover damages, defects, malfunctions, or service failures caused by owner's failure to follow the National Instruments installation, operation, or maintenance instructions; owner's modification of the product; owner's abuse, misuse, or negligent acts; and power failure or surges, fire, flood, accident, actions of third parties, or other events outside reasonable control.

#### Copyright

Under the copyright laws, this publication may not be reproduced or transmitted in any form, electronic or mechanical, including photocopying, recording, storing in an information retrieval system, or translating, in whole or in part, without the prior written consent of National Instruments Corporation.

#### **Trademarks**

ComponentWorks $^{\text{\tiny{IM}}}$ , DAQ-STC $^{\text{\tiny{IM}}}$ , DataSocket $^{\text{\tiny{IM}}}$ , LabVIEW $^{\text{\tiny{IM}}}$ , LabWindows $^{\text{\tiny{IM}}}$ /CVI, NI-488.2 $^{\text{\tiny{IM}}}$ , NI-DAQ $^{\text{\tiny{IM}}}$ , NI-VISA $^{\text{\tiny{IM}}}$ , NI-VXI $^{\text{\tiny{IM}}}$ , and SCXI $^{\text{\tiny{IM}}}$  are trademarks of National Instruments Corporation.

Product and company names listed are trademarks or trade names of their respective companies.

#### WARNING REGARDING MEDICAL AND CLINICAL USE OF NATIONAL INSTRUMENTS PRODUCTS

National Instruments products are not designed with components and testing intended to ensure a level of reliability suitable for use in treatment and diagnosis of humans. Applications of National Instruments products involving medical or clinical treatment can create a potential for accidental injury caused by product failure, or by errors on the part of the user or application designer. Any use or application of National Instruments products for or involving medical or clinical treatment must be performed by properly trained and qualified medical personnel, and all traditional medical safeguards, equipment, and procedures that are appropriate in the particular situation to prevent serious injury or death should always continue to be used when National Instruments products are being used. National Instruments products are NOT intended to be a substitute for any form of established process, procedure, or equipment used to monitor or safeguard human health and safety in medical or clinical treatment.

# **Contents**

| About 7 | This Manual   |      |
|---------|---|------|
| (       | Organization of This Manual                                       | xix  |
|         | Conventions Used in This Manual                                   |      |
|         | Related Documentation   |      |
| _       | Customer Communication  |      |
| Chapte  | r 1   |      |
|         | iction to ComponentWorks  |      |
| 7       | What is ComponentWorks?   | 1-1  |
|         | nstalling ComponentWorks  |      |
|         | System Requirements   |      |
|         | Installation Instructions   |      |
|         | Installing the ComponentWorks ActiveX Controls                    | 1-4  |
|         | Installing From Floppy Disks                                      | 1-4  |
|         | Installing the Instrument Driver Factory                          | 1-5  |
|         | Installing the Instrument Drivers DLLs                            | 1-5  |
|         | Installed Files   | 1-6  |
| A       | About the ComponentWorks Controls                                 | 1-7  |
|         | Properties, Methods, and Events                                   |      |
|         | Object Hierarchy  | 1-8  |
|         | Collection Objects  |      |
| 5       | Setting the Properties of an ActiveX Control                      |      |
|         | Using Property Pages  |      |
|         | Changing Properties Programmatically                              |      |
|         | Item Method   |      |
|         | Working with Control Methods                                      |      |
|         | Developing Event Handler Routines                                 |      |
|         | Using the Analysis Library and Instrument Driver DLLs             |      |
|         | The Online Reference—Learning the Properties, Methods, and Events | 1-15 |
| Chapte  | r 2   |      |
| Getting | started with ComponentWorks                                       |      |
| I       | Installing and Configuring Driver Software                        | 2-1  |
|         | Exploring the ComponentWorks Documentation                        |      |
|         | Getting Results with ComponentWorks Manual                        |      |
|         | ComponentWorks Online Reference                                   |      |
|         | Accessing the Online Reference                                    |      |
|         | Finding Specific Information                                      | 2-4  |

| ]      | Becoming Familiar with the Examples Structure                     | 2-4  |
|--------|---|------|
| ]      | Developing Your Application                                       | 2-5  |
| ,      | Seeking Information from Additional Sources                       | 2-7  |
| Chapte | er 3  |      |
| •      |   |      |
|        | ng ComponentWorks Applications with Visual Basic                  | 2.1  |
| j      | Developing Visual Basic Applications                              |      |
|        | Loading the ComponentWorks Controls into the Toolbox              |      |
|        | Building the User Interface Using ComponentWorks                  |      |
|        | Using Property Sheets   |      |
|        | Using Your Program to Edit Properties                             |      |
|        | Working with Control Methods                                      |      |
|        | Developing Control Event Routines                                 |      |
|        | Using the ComponentWorks Instrument Driver DLLs in Visual Basic   |      |
|        | Using the Object Browser to Build Code in Visual Basic            |      |
|        | Pasting Code into Your Program                                    |      |
| 1      | Adding Code Using Visual Basic Code Completion                    |      |
| 1      | Learning to Use Specific ComponentWorks Controls                  | 3-12 |
|        | ng ComponentWorks Applications with Visual C++                    |      |
| ]      | Developing Visual C++ Applications                                |      |
|        | Creating Your Application   |      |
|        | Adding ComponentWorks Controls to the Visual C++ Controls Toolbar |      |
|        | Building the User Interface Using ComponentWorks Controls         |      |
|        | Programming with the ComponentWorks Controls                      |      |
|        | Using Properties  |      |
|        | Using Methods   |      |
| _      | Using Events  |      |
| ]      | Learning to Use Specific ComponentWorks Controls                  | 4-10 |
| Chapte | nr 5  |      |
| -      |   |      |
|        | ng ComponentWorks Applications with Delphi                        |      |
|        | Running Delphi Examples   |      |
|        | Upgrading from a Previous Version of ComponentWorks               |      |
| ]      | Developing Delphi Applications                                    |      |
|        | Loading the ComponentWorks Controls into the Component Palette    |      |
|        | Building the User Interface                                       |      |
|        | Placing Controls  |      |
|        | Using Property Sheets   | 5-5  |

| Programming with ComponentWorks                      | 5-6 |
|--|-----|
| Using Your Program to Edit Properties                |     |
| Using Methods  |     |
| Using Events   |     |
| Learning to Use Specific ComponentWorks Controls     |     |
| Chapter 6  |     |
| •  |     |
| Using the Graphical User Interface Controls          |     |
| What Are the UI Controls?                            |     |
| Object Hierarchy and Common Objects                  |     |
| The Knob and Slide Controls                          |     |
| Knob and Slide Object                                | 6-3 |
| Pointers Collection                                  | 6-4 |
| Pointer Object                                       | 6-4 |
| Axis Object  | 6-4 |
| Ticks Object   | 6-5 |
| ValuePairs Collection                                | 6-5 |
| ValuePair Object                                     | 6-6 |
| Statistics Object                                    | 6-6 |
| Events   | 6-6 |
| The Numeric Edit Box Control                         | 6-7 |
| Events   | 6-7 |
| Tutorial: Knob, Slide, and Numeric Edit Box Controls | 6-8 |
| Designing the Form                                   |     |
| Developing the Program Code                          |     |
| Testing Your Program                                 |     |
| The Button Control                                   |     |
| Events   |     |
| The Graph Control                                    |     |
| Graph Object   |     |
| Plot Methods   |     |
| Chart Methods  |     |
| Plots Collection                                     |     |
| Plot Object  |     |
| PlotTemplate Object                                  |     |
| Cursors Collection                                   |     |
| Cursor Object  |     |
| Axes Collection                                      |     |
| Axis Object  |     |
| Events   |     |
| Panning and Zooming                                  |     |

| Tutorial: Graph and Button Controls                      | 6-22 |
|--|------|
| Designing the Form                                       |      |
| Developing the Code                                      |      |
| Testing Your Program                                     |      |
|  |      |
| Chapter 7  |      |
| Using the Data Acquisition Controls                      |      |
| What Are the Data Acquisition Controls?                  | 7-1  |
| Data Acquisition Configuration                           |      |
| Object Hierarchy and Common Properties                   |      |
| Device, DeviceName, and DeviceType                       |      |
| Channel Strings  |      |
| SCXI Channel Strings                                     |      |
| ExceptionOnError and ErrorEventMask                      |      |
| AIPoint Control—Single Point Analog Input                |      |
| AIPoint Object   |      |
| Channels Collection                                      |      |
| Channel Object   |      |
| ChannelClock Object                                      |      |
| AI Control—Waveform Analog Input                         |      |
| AI Object  |      |
| Methods and Events                                       |      |
| Asynchronous Acquisition                                 |      |
| Synchronous Acquisition                                  |      |
| Error Handling   |      |
| ScanClock and ChannelClock Objects                       |      |
| StartCondition, PauseCondition and StopCondition Objects |      |
| Tutorial: Using the AIPoint and AI DAQ Controls          | 7-14 |
| Designing the Form                                       | 7-15 |
| Setting the DAQ Properties                               | 7-16 |
| Developing the Code                                      | 7-16 |
| Testing Your Program                                     | 7-18 |
| AOPoint Control—Single Point Analog Output               | 7-18 |
| AOPoint Object   |      |
| Methods  |      |
| AO Control—Waveform Analog Output                        |      |
| AO Object  |      |
| Methods and Events                                       |      |
| UpdateClock and IntervalClock Objects                    |      |
| StartCondition Object                                    | 7-23 |

| Tutorial: Using the AOPoint Control                   | 7-24 |
|---|------|
| Designing the Form                                    | 7-24 |
| Developing the Code                                   | 7-25 |
| Testing Your Program                                  | 7-27 |
| Digital Controls and Hardware                         | 7-28 |
| DIO Control—Single Point Digital Input and Output     | 7-29 |
| DIO Object  | 7-30 |
| Ports Collection and Port Object                      | 7-31 |
| Lines Collection and Line Object                      | 7-32 |
| Common Properties and Methods                         | 7-32 |
| DI Control—Buffered Waveform Digital Input            | 7-34 |
| DI Object   | 7-35 |
| UpdateClock Object                                    | 7-36 |
| Methods and Events                                    | 7-36 |
| DO Control—Buffered Waveform Digital Output           | 7-37 |
| DO Object   | 7-38 |
| UpdateClock Object                                    | 7-39 |
| Methods and Events                                    | 7-40 |
| Tutorial: Using the DIO Control                       | 7-41 |
| Designing the Form                                    | 7-42 |
| Developing the Code                                   | 7-42 |
| Testing Your Program                                  | 7-44 |
| Counter/Timer Hardware                                |      |
| Counter Control—Counting and Measurement Operations   | 7-46 |
| Counter Object  | 7-46 |
| Methods and Events                                    | 7-48 |
| Buffered Measurements                                 | 7-50 |
| Pulse Control—Digital Pulse and Pulsetrain Generation | 7-51 |
| Pulse Object  | 7-51 |
| Methods   | 7-53 |
| FSK and ETS Pulse Generation                          | 7-54 |
| Tutorial: Using the Counter and Pulse Controls        | 7-55 |
| Designing the Form                                    | 7-55 |
| Developing the Code                                   | 7-56 |
| Testing Your Program                                  | 7-59 |
| DAQTools—Data Acquisition Utility Functions           | 7-60 |
| Using DAO Tools Functions                             | 7-61 |

## **Chapter 8**

| Using the | GPIB | and Serial | <b>Controls</b> |
|-----------|------|------------|-----------------|
|-----------|------|------------|-----------------|

| What Are the GPIB and   | d Serial Controls?              | 3-1             |
|-------------------------|---------------------------------|-----------------|
| Object Hierard          | chy and Common Features         | 3-2             |
| Comr                    | mon Properties                  | 3-2             |
|                         | ng {                            |                 |
|                         | nced Parsing Features           |                 |
|                         | CWTask Object                   | 3-4             |
|                         | CWPattern Object                | 3-5             |
|                         | CWToken Object                  |                 |
| The GPIB Control        |                                 | 3-6             |
| CWGPIB Obje             | ect 8                           | 3-7             |
| Methods and E           | Events                          | 3-8             |
| Synch                   | hronous I/O                     | 3-8             |
| Asyn                    | chronous I/O                    | 3-8             |
| Other                   | GPIB Operations                 | 3-9             |
| Tutorial: Using the GPI | IB Control                      | 3-9             |
| Designing the           | Form                            | 3-10            |
| Setting the GP          | PIB Control Properties          | 8-10            |
| Developing the          | e Code                          | 3-11            |
| Testing Your I          | Program 8                       | 3-11            |
|                         |                                 |                 |
| CWSerial Obje           | ect 8                           | 3-12            |
|                         | Events                          |                 |
| Synch                   | hronous I/O                     | 3-13            |
| •                       | chronous I/O                    |                 |
|                         | ial Control8                    |                 |
|                         | Form                            |                 |
| •                       | rial Control Properties         |                 |
| 1 0                     | e Code8                         |                 |
| Testing Your I          | Program8                        | 3-17            |
| Chantar O               |                                 |                 |
| Chapter 9               |                                 |                 |
| Using the VISA Control  |                                 |                 |
| Overview of the VISA    | API9                            | <b>)</b> -1     |
| VISA Structur           | e9                              | 9-1             |
| VISA Advanta            | ages9                           | 9-2             |
| What is the VISA Cont   | rol?9                           | 9-2             |
| Object Hierard          | chy and Common Properties       | 9-2             |
| Comr                    | mon Instrument Control Features | 9-4             |
| Parsing                 |                                 | <b>}-</b> 5     |
| VISA Object             | (                               | <del>)</del> -5 |

| RdWrt Object  | 9-7   |
|---|-------|
| Serial (ASRL) Object  |       |
| GPIB Object   |       |
| VXI Object  |       |
| Methods and Events  |       |
| Message-Based Communication                                       | 9-9   |
| Synchronous I/O   | 9-10  |
| Asynchronous I/O  | 9-10  |
| Register-Based Communication                                      | 9-11  |
| Events  | 9-14  |
| Event Types   | 9-14  |
| Event Handling With The Event Queue                               | 9-15  |
| Checking Events in the Queue                                      | 9-16  |
| Discarding Events From The Queue                                  | 9-16  |
| Disabling The Event Queue   | 9-16  |
| Tutorial: Using the VISA Control for Message-Based Communicatio   | n9-17 |
| Designing the Form  | 9-17  |
| Setting the VISA Control Properties                               | 9-18  |
| Developing the Code   | 9-19  |
| Testing Your Program  | 9-19  |
| Tutorial: Using the VISA Control for Register-Based Communication | n9-20 |
| Designing the Form  | 9-20  |
| Setting the VISA Control Properties                               | 9-21  |
| Developing the Code   | 9-21  |
| Testing Your Program  | 9-22  |
| Charles 10  |       |
| Chapter 10  |       |
| Using the Analysis Controls and Functions                         |       |
| What Are the Analysis Controls?                                   | 10-1  |
| Analysis Library Versions   | 10-2  |
| Controls  | 10-12 |
| Analysis Function Descriptions                                    | 10-13 |
| Error Messages  |       |
| Tutorial: Using Simple Statistics Functions                       | 10-14 |
| Designing the Form  | 10-15 |
| Developing the Program Code                                       | 10-16 |
| Testing Your Program  | 10-17 |

## **Chapter 11**

| Usina  | the | DataS | ocket | <b>Control</b> | and  | Tools  |
|--------|-----|-------|-------|----------------|------|--------|
| OSILIG | uiu | Dutuo | OUNGL | OUIILI UI      | ullu | 1 0013 |

|       | What is DataSocket?                            |
|-------|--|
|       | DataSocket Basics                              |
|       | Locating a Data Source                         |
|       | Reading Data from a Data Source                |
|       | OnDataUpdated Event                            |
|       | Updating the Data11-5                          |
|       | Automatically Updating Data11-5                |
|       | OnStatusUpdated Event                          |
|       | Disconnecting from a Data Source               |
|       | Tutorial: Reading a Waveform                   |
|       | Designing the Form                             |
|       | Developing the Program Code                    |
|       | Testing Your Program                           |
|       | Writing Data to a Data Target                  |
|       | Updating a Data Target                         |
|       | Automatically Updating a Target11-10           |
|       | Working with CWData                            |
|       | Working with Attributes                        |
|       | Standalone CWData Objects11-12                 |
|       | Setting Up a DataSocket Server                 |
|       | Requirements for Running the DataSocket Server |
|       | Checking the Status of the DataSocket Server   |
|       | Creating Data Items on the Server              |
|       | Connecting to Data Items and Reading Them      |
|       | Tutorial: Sharing Data between Applications    |
|       | Configuring the DataSocket Server              |
| Chapt | er 12  |
| -     | ng Advanced Applications                       |
| Dunai |  |
|       | Using Advanced ComponentWorks Features         |
|       | A Virtual Oscilloscope 12-1                    |
|       | Data Acquisition Stop Condition Modes          |
|       | Data Acquisition Pretriggering                 |
|       | User Interface Value Pairs                     |
|       | Virtual Spectrum Meter                         |
|       | DSP Analysis Library                           |
|       | Cursors 12-7                                   |
|       | Lyroph Lrock Mode                              |

| A Virtual Data Logger   | 12-9  |
|---|-------|
| Multiple Graph Axes   |       |
| Graph Axes Formats  | 12-11 |
| File Input/Output   |       |
| Adding Testing and Debugging to Your Application                  | 12-12 |
| Error Checking  |       |
| Exceptions  |       |
| Return Codes  | 12-14 |
| Error and Warning Events  | 12-15 |
| GetErrorText Function   | 12-16 |
| Debugging   | 12-17 |
| Debug Print   | 12-17 |
| Breakpoint  | 12-17 |
| Watch Window  | 12-18 |
| Single Step, Step Into, and Step Over                             | 12-18 |
| Appendix A  |       |
| Using Previous Versions   |       |
| of Visual Basic, Visual C++, and Delphi with ComponentWorks       |       |
| Visual Basic 4  |       |
| Menus and Commands  |       |
| Object Browser  |       |
| Code Completion   |       |
| Creating a Default ComponentWorks Project                         |       |
| Visual C++ 4.x  |       |
| Creating Your Application   |       |
| Adding ComponentWorks Controls to the Visual C++ Controls Toolbar |       |
| Building Your User Interface and Code                             |       |
| Delphi 2  |       |
| Loading the ComponentWorks Controls into the Component Palette    | A-6   |
| Appendix B  |       |
| Background Information about Data Acquisition                     |       |
| Installation  |       |
| Configuration   |       |
| SCXI  |       |
| Device Number   |       |
| Channel Wizard  |       |
| Programming   |       |
| Device Number and Channels  |       |
| Buffers   | B-4   |

| ClocksB-5   |
|---|
| SCXI B-6  |
| Hardware B-7                                      |
| SCXIB-7   |
| RTSIB-8   |
| PFI B-9   |
| Appendix C  |
| Common Questions                                  |
|   |
| Installation and Getting Started                  |
| Visual Basic                                      |
| User Interface Controls                           |
| Data Acquisition Controls                         |
| GPIB, Serial, and VISA Controls                   |
| Analysis Controls                                 |
| Appendix E Distribution and Redistributable Files |
| Files   |
| Distribution E-1                                  |
| Automatic Installers E-2                          |
| Manual Installation                               |
| DataSocket Server E-3                             |
| Instrument Drivers E-3                            |
| ComponentWorks Evaluation E-4                     |
| Run-Time Licenses E-4                             |
| Troubleshooting E-4                               |
| Appendix F Customer Communication                 |
| Glossary  |

Index

## **Figures**

| Figure 1-1. | Slide Control Object Hierarchy                                | 1-9   |
|-------------|---|-------|
| Figure 1-2. | Visual Basic Default Property Sheets                          |       |
| Figure 1-3. | ComponentWorks Custom Property Pages                          |       |
| Figure 3-1. | Visual Basic Property Pages                                   | 3-4   |
| Figure 3-2. | ComponentWorks Custom Property Pages                          |       |
| Figure 3-3. | Selecting Events in the Code Window                           |       |
| Figure 3-4. | Viewing CWGraph in the Object Browser                         |       |
| Figure 3-5. | Viewing CWKnob in the Object Browser                          |       |
| Figure 3-6. | Visual Basic 5 Code Completion                                |       |
| Figure 4-1. | New Dialog Box  | 4-2   |
| Figure 4-2. | MFC AppWizard—Step 1  |       |
| Figure 4-3. | CWGraph Control Property Sheets                               |       |
| Figure 4-4. | MFC ClassWizard—Member Variable Tab                           | 4-6   |
| Figure 4-5. | Viewing Property Functions and Methods                        |       |
| _           | in the Workspace Window                                       | 4-7   |
| Figure 4-6. | Event Handler for the PointerValueChanged Event of a Knob     | 4-10  |
| Figure 5-1. | Delphi Import ActiveX Control Dialog Box                      | 5-3   |
| Figure 5-2. | ComponentWorks Controls on a Delphi Form                      |       |
| Figure 5-3. | Delphi Object Inspector                                       | 5-5   |
| Figure 5-4. | ComponentWorks Graph Control Property Page                    | 5-6   |
| Figure 5-5. | Delphi Object Inspector Events Tab                            | 5-8   |
| Figure 6-1. | Knob/Slide Control Object Hierarchy                           | 6-3   |
| Figure 6-2. | SimpleUI Form   | .6-9  |
| Figure 6-3. | Testing SimpleUI  | .6-11 |
| Figure 6-4. | Button Control Modes  |       |
| Figure 6-5. | Graph Control Object Hierarchy                                | 6-14  |
| Figure 6-6. | ButtonGraphExample Form                                       | 6-23  |
| Figure 7-1. | AIPoint Control Object Hierarchy (Single Point Analog Input)  | 7-6   |
| Figure 7-2. | AI Control Object Hierarchy (Waveform Analog Input)           | 7-9   |
| Figure 7-3. | AIExample Form  | .7-15 |
| Figure 7-4. | Testing AIExample   |       |
| Figure 7-5. | AOPoint Control Object Hierarchy (Single Point Analog Output) | 7-19  |
| Figure 7-6. | AOPoint Control Object Hierarchy (Waveform Analog Output)     |       |
| Figure 7-7. | AOPoint Form  |       |
| Figure 7-8. | Testing AOPoint   |       |
| Figure 7-9. | DIO Control Object Hierarchy                                  | 7-30  |
| Figure 7-10 | DI Control Object Hierarchy                                   | 7-34  |

| Figure 7-11. | DO Control Object Hierarchy                | . 7-38  |
|--------------|--|---------|
| Figure 7-12. | DIO Form                                   |         |
| Figure 7-13. | Counter Control Object Hierarchy           | . 7-46  |
| Figure 7-14. | Pulse Control Object Hierarchy             |         |
| Figure 7-15. | Counters Form                              | 7-56    |
| Figure 7-16. | Testing Counters                           | 7-59    |
| Figure 8-1.  | GPIB Control Object Hierarchy              | . 8-7   |
| Figure 8-2.  | GPIBExample Form                           | 8-10    |
| Figure 8-3.  | Serial Control Object Hierarchy            | . 8-12  |
| Figure 8-4.  | Weigh Form                                 | 8-15    |
| Figure 8-5.  | Serial Property Pages—Parsing Page         | . 8-16  |
| Figure 9-1.  | VISA Structure                             |         |
| Figure 9-2.  | VISA Control Object Hierarchy              |         |
| Figure 9-3.  | VISA Property Pages—General Page           |         |
| Figure 9-4.  | VISA Property Pages—RdWrt Page             | . 9-7   |
| Figure 9-5.  | VISA Property Pages—Serial Page            |         |
| Figure 9-6.  | VISA Property Pages—VxiMemory Page         | . 9-11  |
| Figure 9-7.  | MbasedExample Form                         |         |
| Figure 9-8.  | RbasedExample Form                         | . 9-21  |
| Figure 10-1. | Stat Form                                  |         |
| Figure 10-2. | Testing Stat                               | . 10-17 |
| Figure 11-1. | DataSocket Connection                      | 11-2    |
| Figure 11-2. | Specifying Data Source Locations           |         |
| Figure 11-3. | SimpleDS Form                              | . 11-7  |
| Figure 11-4. | DataSocket Control                         | . 11-11 |
| Figure 11-5. | DataSocket Server Tray Icon                |         |
| Figure 11-6. | DataSocket Server Status Window            | . 11-14 |
| Figure 11-7. | DataSocket Server Manager                  | . 11-17 |
| Figure 12-1. | Virtual Oscilloscope                       | 12-2    |
| Figure 12-2. | Knob Property Pages—Value Pairs Page       | . 12-4  |
| Figure 12-3. | Virtual Spectrum Meter                     |         |
| Figure 12-4. | Graph Property Pages—Cursors Property Page | . 12-7  |
| Figure 12-5. | Virtual Data Logger                        |         |
| Figure 12-6. | Visual Basic Error Messages                |         |
| Figure 12-7. | Error Message Box                          | . 12-16 |
| Figure 12-8. | Error Handling Message Box                 | 12-17   |

|      | Figure A-1. | Visual Basic 4 Object Browser                 | A-2  |
|------|-------------|---|------|
|      | Figure A-2. | Visual Basic 5 Object Browser                 |      |
|      | Figure A-3. | Visual C++ Component Gallery                  | A-5  |
|      | Figure A-4. | Delphi Import OLE Control Dialog Box          |      |
| Tabl | es          |   |      |
|      | Table 2-1.  | Chapters on Specific Programming Environments | 2-6  |
|      | Table 6-1.  | Graphical User Interface Control Styles       | 6-2  |
|      | Table 7-1.  | Measurement Types                             | 7-47 |
|      | Table 7-2.  | Pulse Type Operations                         | 7-52 |
|      | Table 10-1. | Analysis Control Function Tree                | 10-3 |
|      | Table D-1.  | Data Acquisition Control Error Codes          | D-1  |
|      | Table D-2.  | VISA Control Error Codes                      | D-17 |
|      | Table D-3.  | Analysis Error Codes                          | D-20 |
|      | Table D-4   | General ComponentWorks Error Codes            | D-24 |

## About This Manual

The *Getting Results with ComponentWorks* manual contains the information you need to get started with the ComponentWorks software package. ComponentWorks adds the instrumentation-specific tools for acquiring, analyzing, and displaying data in Visual Basic, Visual C,++, Delphi, and other ActiveX control environments.

This manual contains step-by-step instructions for building applications with ComponentWorks. You can modify these sample applications to suit your needs. This manual does not show you how to use every control or solve every possible programming problem. Use the online reference for further, function-specific information.

To use this manual, you already should be familiar with one of the supported programming environments and Windows 95 or Windows NT.

## **Organization of This Manual**

The Getting Results with ComponentWorks manual is organized as follows:

- Chapter 1, Introduction to ComponentWorks, contains an overview of ComponentWorks, lists the ComponentWorks system requirements, describes how to install the software, and explains the basics of ActiveX controls.
- Chapter 2, Getting Started with ComponentWorks, describes approaches to help you get started using ComponentWorks, depending on your application needs, your experience using ActiveX controls in your particular programming environment, and your specific goals in using ComponentWorks.
- Chapter 3, Building ComponentWorks Applications with Visual Basic, describes how you can use the ComponentWorks controls with Visual Basic 5; insert the controls into the Visual Basic environment, set their properties, and use their methods and events; and perform these operations using ActiveX controls in general. This chapter also outlines Visual Basic features that simplify working with ActiveX controls.
- Chapter 4, Building ComponentWorks Applications with Visual C++, describes how you can use ComponentWorks controls with Visual C++, explains how to insert the controls into the Visual C++ environment and create the necessary wrapper classes, shows you how

- to create an application compatible with the ComponentWorks controls using the Microsoft Foundation Classes Application Wizard (MFC AppWizard) and how to build your program using the ClassWizard with the controls, and discusses how to perform these operations using ActiveX controls in general.
- Chapter 5, Building ComponentWorks Applications with Delphi,
  describes how you can use ComponentWorks controls with Delphi;
  insert the controls into the Delphi environment, set their properties,
  and use their methods and events; and perform these operations using
  ActiveX controls. This chapter also outlines Delphi features that
  simplify working with ActiveX controls.
- Chapter 6, Using the User Interface Controls, describes how you can
  use the ComponentWorks User Interface (UI) controls to customize
  your application interface; explains the individual controls and their
  most commonly used properties, methods, and events; and includes
  tutorial exercises that give step-by-step instructions on using the
  controls in simple programs.
- Chapter 7, Using the Data Acquisition Controls, describes how you can use the ComponentWorks Data Acquisition (DAQ) controls in your application to perform input and output operations using your DAQ hardware. It explains the individual controls and their most commonly used properties, methods, and events and includes tutorials that give step-by-step instructions on using the controls in simple programs.
- Chapter 8, Using the GPIB and Serial Controls, describes how you
  can use the ComponentWorks Instrument controls in your application
  to perform input and output operations using GPIB and serial
  hardware; explains the individual controls and their most commonly
  used properties, methods, and events; and includes tutorial exercises
  that give step-by-step instructions on using the controls in simple
  programs.
- Chapter 9, Using the VISA Control, describes the basic structure of the VISA API; shows you how to use the ComponentWorks VISA control in your application to perform input and output operations using GPIB, Serial, and VXI hardware; explains the individual control and its most commonly used properties, methods, and events; and includes tutorial exercises that give step-by-step instructions on using the control in simple programs.
- Chapter 10, Using the Analysis Controls and Functions, describes how you can use the ComponentWorks Analysis controls to perform data analysis, manipulation, and simulation. It explains the individual controls and some of their functions and includes a tutorial that gives

- step-by-step instructions on using the Analysis controls in a simple program.
- Chapter 11, Using the DataSocket Control and Tools, describes how
  you can use the ComponentWorks DataSocket control to read, write,
  or share data on a single machine or between multiple machines and
  includes tutorial exercises that provide step-by-step instructions for
  using the DataSocket tools.
- Chapter 12, Building Advanced Applications, discusses how you can build applications using more advanced features of ComponentWorks, including advanced data acquisition techniques, the DSP Analysis Library, and advanced user interface controls and offers techniques for error tracking, error checking, and debugging.
- Appendix A, *Using Previous Versions of Visual Basic, Visual C++, and Delphi with ComponentWorks*, outlines differences between the current and previous version of the programming environments with respect to using the ComponentWorks controls. This revision of the *Getting Results with ComponentWorks* manual was written with the most current environments available: Visual Basic 5, Visual C++ 5, and Delphi 3. In this appendix, the most current versions are compared with Visual Basic 4, Visual C++ 4.x, and Delphi 2.
- Appendix B, Background Information about Data Acquisition, provides background information on data acquisition (DAQ) software and hardware specific to the ComponentWorks DAQ controls and describes the underlying architecture used by these controls.
- Appendix C, Common Questions, contains a list of answers to frequently asked questions. It contains general ComponentWorks questions as well as specific graphical user interface, data acquisition, instrument control, and analysis library questions.
- Appendix D, *Error Codes*, lists the error codes returned by the ComponentWorks DAQ controls, ComponentWorks VISA control, and Analysis Library functions. It also lists some general ComponentWorks error codes.
- Appendix E, *Distribution and Redistributable Files*, contains information about ComponentWorks 2.0 redistributable files and distributing applications that use ComponentWorks controls.
- Appendix F, Customer Communication, contains forms you can use to request help from National Instruments or to comment on our products and manuals.

- The Glossary contains an alphabetical list and description of terms used in this manual, including acronyms, abbreviations, metric prefixes, mnemonics, and symbols.
- The *Index* contains an alphabetical list of key terms and topics in this manual, including the page where you can find each one.

## **Conventions Used in This Manual**

Angle brackets enclose the name of a key on the keyboard—for example, <shift>.

A hyphen between two or more key names enclosed in angle brackets denotes that you should simultaneously press the named keys—for

example, <Control-Alt-Delete>.

The » symbol leads you through nested menu items and dialog box options to a final action. The sequence File»Page Setup»Options»Substitute
Fonts directs you to pull down the File menu, select the Page Setup item, select Options, and finally select the Substitute Fonts options from the

last dialog box.

This icon to the left of bold italicized text denotes a note, which alerts you

to important information.

bold Bold text denotes the names of menus, menu items, parameters, dialog

boxes, dialog box buttons or options, icons, and windows.

bold italic Bold italic text denotes an activity objective, note, caution, or warning.

<Control> Key names are capitalized.

italic Italic text denotes variables, emphasis, a cross reference, or an introduction

to a key concept.

monospace Text in this font denotes text or characters that you should literally enter

from the keyboard, sections of code, programming examples, and syntax examples. This font is also used for the proper names of disk drives, paths, directories, programs, subprograms, subroutines, device names, functions, operations, properties and methods, filenames and extensions, and for

statements and comments taken from programs.

paths

Paths in this manual are denoted using backslashes (\) to separate drive names, directories, folders, and files.

## **Related Documentation**

The following documents contain information you might find useful as you read this manual:

- Getting Results with ComponentWorks
- ComponentWorks online reference (available by selecting Start»Programs»National Instruments ComponentWorks» ComponentWorks Reference

## **Customer Communication**

National Instruments wants to receive your comments on our products and manuals. We are interested in the applications you develop with our products, and we want to help if you have problems with them. To make it easy for you to contact us, this manual contains comment and configuration forms for you to complete. These forms are in Appendix F, *Customer Communication*, at the end of this manual.

Introduction to ComponentWorks

This chapter contains an overview of ComponentWorks, lists the ComponentWorks system requirements, describes how to install the software, and explains the basics of ActiveX controls.

## What is ComponentWorks?

ComponentWorks is a collection of ActiveX controls for acquiring, analyzing, and presenting data within any compatible ActiveX control container. ActiveX controls also are known as OLE (Object Linking and Embedding) controls, and the two terms can be used interchangeably in this context. Use the online reference for specific information about the properties, methods, and events of the individual ActiveX controls. You can access this information by selecting **Programs»National Instruments ComponentWorks»ComponentWorks Reference** from the Windows **Start** menu.

With ComponentWorks, you can easily develop complex custom user interfaces to display your data, control your National Instruments Data Acquisition (DAQ) boards, and analyze data you acquired or received from some other source. The ComponentWorks package contains the following components:

- User Interface Controls—32-bit ActiveX controls for presenting your data in a technical format. These controls include a graph/strip chart control, sliders, thermometers, tanks, knobs, gauges, meters, LEDs, and switches.
- DAQ Controls—32-bit ActiveX controls for analog I/O, digital I/O, and counter/timer I/O operations using National Instruments DAQ products.
- GPIB, Serial, and VISA Controls—32-bit ActiveX controls for controlling and retrieving data from instruments or devices connected to a GPIB, serial, or VXI port in your computer. You must connect GPIB instruments with a National Instruments GPIB interface card.

- DataSocket Control and Tools (shipped only with the Standard and Full Development Systems)—32-bit ActiveX control and tools for sharing and exchanging data between an application and a number of different targets, including other applications, files, and FTP and Web servers.
- Analysis Library Controls—Functions for statistics, advanced signal processing, windowing, filters, curve-fitting, vector and matrix algebra routines, probability, and array manipulations. These functions are packaged in 32-bit ActiveX controls. Each ComponentWorks package (Base, Standard, and Full Development System) contains different options for analysis. The Base package includes functions for basic statistics and array operations; the Standard Development System includes additional Digital Signal Processing (DSP) functions for signal processing, windowing, and filtering operations; and the Full Development System adds advanced statistics and probability functions.
- Instrument Driver Factory (shipped only with the Full Development System)—Complete development environment for building, compiling, debugging, and analyzing instrument drivers, including a Visual Basic wizard to automate the steps of compiling an instrument driver.
- Instrument Drivers (shipped only with the Full Development System)—Source code and 32-bit DLLs for controlling common GPIB instruments with high-level instrument control routines. You can load and edit the source code in the Instrument Driver Factory. If you do not need to make any changes to the driver, you can use the pre-compiled DLLs.

The ComponentWorks ActiveX controls are designed for use in Visual Basic, a premier ActiveX control container application. Some ComponentWorks features and utilities have been incorporated with the Visual Basic user in mind. However, you can use ActiveX controls in any application that supports them, including Visual C++, Access, and Delphi.

## **Installing ComponentWorks**

The ComponentWorks setup program installs ComponentWorks through a process that lasts approximately five minutes. The ComponentWorks CD contains separate installers for the Instrument Driver Factory and Instrument Drivers (Full Development System only) and for various driver software (NI-DAQ, NI-488, and so on) that you might need.

#### **System Requirements**

To use the ComponentWorks ActiveX controls and Analysis Library, you must have the following:

- Microsoft Windows 95 or Windows NT (Windows NT 4.0 for DAQ controls) operating system
- Personal computer using at least a 33 MHz 80486 or higher microprocessor (National Instruments recommends a 66 MHz 80486 or higher microprocessor)
- VGA resolution (or higher) video adapter
- ActiveX control container such as Visual Basic (32-bit version),
   Visual C++, or Delphi (32-bit version)
- NI-DAQ 5.0 or later for Windows 95 or Windows NT (if you are using DAQ controls)
- Minimum of 16 MB of memory
- Minimum of 10 MB of free hard disk space
- Microsoft-compatible mouse

#### **Installation Instructions**

This section provides instructions for installing different pieces of your ComponentWorks software. You can start most of these installers directly from the startup screen that appears when you load the ComponentWorks CD.

#### **Installing the ComponentWorks ActiveX Controls**

Complete the following steps to install ComponentWorks.

Note

To install ComponentWorks on a Windows NT system, you must be logged in with Administrator privileges to complete the installation.

- 1. Make sure that your computer and monitor are turned on and that you have installed Windows 95 or Windows NT.
- Insert the ComponentWorks CD in the CD drive of your computer.
   From the CD startup screen, click on Install ComponentWorks 2.0.
   If the CD startup screen does not appear, use the Windows Explorer or File Manager to run the SETUP.EXE program in the \Setup directory on the CD.
- 3. Follow the instructions on the screen. The installer provides different options for setting the directory in which ComponentWorks is installed and choosing examples for different programming environments. Use the default settings in the installer if you are unsure about them. If necessary, you can run the installer at a later time to install additional components.

## **Installing From Floppy Disks**

If your computer does not have a CD drive, follow these instructions for installing the software.

- 1. On another computer with a CD drive and disk drive, copy the files in the individual subdirectories of the \Setup\disks directory on the CD onto individual 3.5" floppy disks. The floppy disks should not contain any directories and should be labeled disk1, disk2, and so on, following the name of the source directories.
- 2. On the target computer, insert the floppy labeled disk1 and run the setup.exe program from the floppy.
- 3. Follow the on-screen instructions to complete the installation.

#### **Installing the Instrument Driver Factory**

If you have purchased the ComponentWorks Full Development System, you can install the Instrument Driver Factory (IDF) and LabWindows/CVI development environment. Use the following procedure to install the IDF.

- Make sure that your computer and monitor are turned on and that you have installed Windows 95 or Windows NT.
- 2. Insert the ComponentWorks CD in the CD drive of your computer. From the CD startup screen, click on **Install Instrument Driver Factory**. If the CD startup screen does not appear, use the Windows Explorer or File Manager to run SETUP.EXE in the \CVI\DISK1 directory and SETUP.EXE in the \Instrument Driver Factory directory on the CD.
- 3. Follow the instructions on the screen to install the LabWindows/CVI environment and the Instrument Driver Factory for compiling instrument drivers from Visual Basic.

#### **Installing the Instrument Drivers DLLs**

If you have purchased the ComponentWorks Full Development System, you can install any of more than 600 instrument drivers and their source code. Use the following procedure to install an instrument driver.

- 1. Make sure that your computer and monitor are turned on and that you have installed Windows 95 or Windows NT.
- Insert the ComponentWorks CD in the CD drive of your computer.
   From the CD startup screen, click on Install Instrument Drivers. If
   the CD startup screen does not appear, use the Windows Explorer or
   File Manager to run SETUP.EXE in the \Instrument Drivers
   directory on the CD.
- 3. Following the instructions in the installation program, select the drivers you want to install. You can install additional drivers later by running the setup program again.
- 4. Follow the installer instructions to complete the installation.

#### **Installed Files**

The ComponentWorks setup program installs the following groups of files on your hard disk.

ActiveX Controls, Documentation, and other associated files

Directory: \Windows\System\

Files: cwdaq.ocx, cwdaq.dep, cwui.ocx, cwui.dep,

cwanalysis.ocx, cwanalysis.dep,
cwinstr.ocx, cwinstr.dep, cwvisa.ocx,
cwvisa.dep, cwds.ocx, cwds.dep, cwref.hlp,
cwref.cnt

Example Programs and Applications

Directory: \ComponentWorks\samples\...

• Tutorial Programs

Directory: \ComponentWorks\tutorials\...

• DataSocket Server (Standard and Full Development Systems only)

Directory: \ComponentWorks\DataSocket Server

Miscellaneous Files

Directory: \ComponentWorks\

If you have purchased the ComponentWorks Full Development System, you can install the following components.

• LabWindows/CVI Development Environment

Directory: \CVI

Instrument Driver Factory

Instrument Driver Files

Directory: \Instrument Drivers\...

Note You select the location of the \ComponentWorks\... and \CVI\... directories during installation.

## **About the ComponentWorks Controls**

Before learning how to use ComponentWorks, you should be familiar with using ActiveX controls. This section outlines some background information about ActiveX controls, in particular the ComponentWorks controls. If you are not already familiar with the concepts outlined in this section, make sure you understand them before continuing. You also might want to refer to your programming environment documentation for more information on using ActiveX (OLE) controls in your particular environment.

#### **Properties, Methods, and Events**

ActiveX controls consist of three different parts—properties, methods, and events—used to implement and program the controls.

*Properties* are the attributes of a control. These attributes describe the current state of the control and affect the display and behavior of the control. The values of the properties are stored in variables that are part of the control.

*Methods* are functions defined as part of the control. Methods are called with respect to a particular control and usually have some effect on the control itself. The operation of most methods also is affected by the current property values of the control.

*Events* are notifications generated by a control in response to some particular occurrence. The events are passed to the control container application to execute a particular subroutine in the program (event handler).

For example, the ComponentWorks Graph control has a wide variety of properties that determine how the graph looks and operates. To customize the graph appearance and behavior, set properties for color, axes, scaling, tick marks, cursors, and labels.

The Graph control also has a series of high-level methods, or functions, that you can invoke to set several properties at once and to perform a particular operation. For example, you can use the PlotY method to pass an array of data to the Graph control.

The Graph control generates events when particular operations take place. For example, when you drag a cursor on the graph, the control passes an event to your program so you can respond to cursor movements. This might be useful if you might want to retrieve the X- and Y-coordinate positions of a cursor as it is being dragged and display the coordinates in text boxes.

Note

Use the ComponentWorks online reference for specific information about the properties, methods, and events of the ActiveX controls. You can access the online reference by selecting Programs»National Instruments ComponentWorks» ComponentWorks Reference from the Windows Start menu.

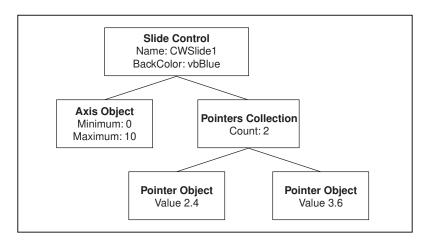
#### **Object Hierarchy**

As described in the previous section, each ActiveX control has properties, methods, and events. These three parts are stored in a *software object*, which is the piece of software that makes up the ActiveX control and contains all its parts. Certain ActiveX controls are very complex, containing many different parts (properties). For this reason, complex ActiveX controls are often subdivided into different software objects, the sum of which make up the ActiveX control. Each individual object in a control contains some specific parts (properties) and functionality (methods and events) of the ActiveX control. The relationships between different objects of a control are maintained in an object hierarchy. At the top of the hierarchy is the actual control itself.

This top-level object contains its own properties, methods, and events. Some of the top-level object properties are actually references to other objects that define specific parts of the control. Objects below the top-level have their own methods and properties, and their properties can be references to other objects. The number of objects in this hierarchy is not limited.

Another advantage of subdividing controls is the re-use of different objects between different controls. One object might be used at different places in the same object hierarchy or in several different controls/object hierarchies.

Figure 1-1 shows part of the object hierarchy of the ComponentWorks Slide control.



Chapter 1

Figure 1-1. Slide Control Object Hierarchy

The Slide object contains some of its own properties, such as Name and BackColor. It also contains properties such as Axis and Pointers, which are separate objects from the Slide object. The Axis object contains all the information about the axis used on the slide and has properties such as Maximum and Minimum. The Pointers Collection object contains several Pointer objects of its own, each describing one pointer on the Slide control. Each Pointer object has properties, such as Value, while the Pointers Collection object has the property Count. The Pointers Collection object is a special type of object referred to as a collection, which is described in the Collection Objects section.

#### **Collection Objects**

One object can contain several objects of the same type. For example, a Graph object contains several Axis objects, each representing one of the axes on the graph. Additionally, the number of objects in the group of objects might not be defined and might change while the program is running (that is, you can add or remove axes as part of your program). To handle these groups of objects more easily, an object called a *Collection* is created.

A collection is an object that contains or stores a varying number of objects of the same type. It also can be regarded as an array of objects. The name of a collection object is usually the plural of the name of the object type contained within the collection. For example, a collection of Pointer objects is referred to as Pointers, a collection of Plot objects as Plots, and a collection of Axis objects as Axes. In the ComponentWorks software, the terms *object* and *collection* are not used, only the type names Pointer and Pointers.

Each collection object contains an Item method that you can use to access any particular object stored in the collection. Refer to *Changing Properties Programmatically* later in this chapter for information about the Item method and how to access particular objects stored in the collection.

## Setting the Properties of an ActiveX Control

You can set the properties of an ActiveX control from its property pages or from within your program.

#### **Using Property Pages**

Property pages are common throughout the Windows 95 and Windows NT interface. When you want to change the appearance or options of a particular object, right click on the object and select **Properties**. A property page or tabbed dialog box appears with a variety of properties that you can set for that particular object. You customize ActiveX controls in exactly the same way. Once you place the control on a form in your programming environment, right click on the control and select **Properties...** to customize the appearance and operation of the control.

Use the property pages to set the property values for each ActiveX control while you are creating your application. The property values you select at this point represent the state of the control at the beginning of your application. You can change the property values from within your program, as shown in the next section, *Changing Properties Programmatically*.

In some programming environments (such as Visual Basic and Delphi), you have two different property pages. The property page common to the programming environment is called the *default property sheet*; it contains the most basic properties of a control.

Your programming environment assigns default values for some of the basic properties, such as the control name and the tab order. You must edit these properties through the default property sheet.

Chapter 1

The following illustration shows the Visual Basic default property sheet for the CWGraph control.

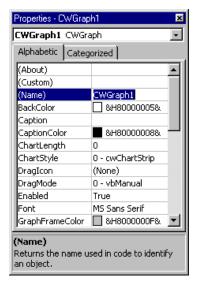


Figure 1-2. Visual Basic Default Property Sheets

The second property sheet is called the *custom property page*. The layout and functionality of the custom property pages vary for different controls. The following illustration shows the custom property page for the CWGraph control.

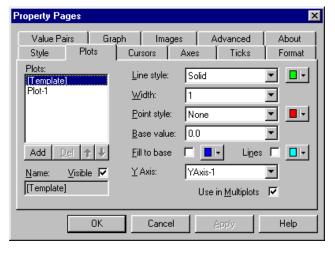


Figure 1-3. ComponentWorks Custom Property Pages

### **Changing Properties Programmatically**

You also can set or read the properties of your controls programmatically. For example, if you want to change the state of an LED control during program execution, change the Value property from True to False or from False to True. The exact syntax for reading and writing property values depends on your programming language, so consult the appropriate chapter for using your programming environment. In this discussion, properties are set with Visual Basic syntax, which is similar to most implementations.

Each control you create in your program has a name (like a variable name) which you use to reference the control in your program. You can set the value of a property on a top-level object with the following syntax.

```
name.property = new_value
```

For example, you can change the Value property of an LED control to off using the following line of code, where CWButton1 is the default name of the LED control. An LED is one style of the CWButton control.

```
CWButton1.Value = False
```

To access properties of sub-objects referenced by the top-level object, use the control name, followed by the name of the sub-object and the property name. For example, consider the following code for the ComponentWorks data acquisition analog input (CWAI) control.

```
CWAI1.ScanClock.Frequency = 10000
```

In the above code, ScanClock is a property of the CWAI control and refers to a CWAIClock object. Frequency is one of several CWAIClock properties. The CWAI control also has a ChannelClock property that refers to a different CWAIClock object.

You can retrieve the value of control properties from your program in the same way. For example, you can print the value of the LED control.

```
Print CWButton1.Value
```

You can display the frequency used by the CWAI control in a Visual Basic text box with the following code.

```
Text1.Text = CWAI1.ScanClock.ActualFrequency
```

To access an object or its properties in a collection, use the Item method of the collection object. For example, set the value of the second pointer on a slide with the following code.

Chapter 1

```
CWSlide1.Pointers.Item(2).Value = 5.0
```

The term CWSlidel.Pointers.Item(2) refers to the second Pointer object in the Pointers collection of the Slide object. The parameter of the Item method is either an integer representing the (one-based) index of the object in the collection or a string with the name of one of the objects in the collection.

```
CWSlide1.Pointers.Item("TemperaturePointer")
```

Because the Item method is the most commonly used method on a collection, it is referred to as the *default method*. Therefore, some programming environments do not require you to specify the .Item method. For example, in Visual Basic

```
CWSlide1.Pointers(2).Value = 5.0
```

is programmatically equivalent to

CWSlide1.Pointers.Item(2).Value = 5.0

#### **Working with Control Methods**

ActiveX controls and objects have their own methods, or functions, that you can call from your program. Methods can have parameters that are passed to the method and return values that pass information back to your program.

For example, the PlotY method for the ComponentWorks Graph control has a required parameter—the array of data to be plotted—that you must include when you call the method. If you want to plot the data returned from an Analog Input control, use the following line of code (the array ScaledData is automatically generated by the CWAI control).

CWGraph1.PlotY ScaledData

The PlotY method has additional parameters that are optional in some programming environments. For example, in addition to the first parameter representing the data to be plotted, you can pass a second parameter to represent the initial value for the X axis, a third parameter for an incremental change on the X axis corresponding to each data point, and a fourth parameter that determines how the graph should handle two-dimensional data.

```
CWGraph1.PlotY ScaledData, 0.0, 1.0, True
```

Depending on your programming environment, the parameters might be enclosed in parentheses. Visual Basic does not use parentheses to pass parameters if the function or method is not assigned a return variable. The AcquireData method in the DAQ Analog Input control has the following form when used with a return variable 1Err.

```
lErr = CWAI1.AcquireData(ScaledData, BinaryCodes, 1)
```

#### **Developing Event Handler Routines**

After you configure your controls on a form, you can create event handler routines in your program to respond to events generated by the controls. For example, the DAQ Analog Input control has an Acquired\_Data event that *fires* (occurs) when the acquired data is ready to be processed, based on the acquisition options you have configured in the control property pages.

You can configure the control to continuously collect 1,000 points of data from a particular channel at a rate of 1,000 points per second. Once every second, the data buffer is ready and the Acquired\_Data event is fired. In your Acquired\_Data event routine, you can write code to analyze the data buffer, plot it, or store it to disk.

To develop the event routine code, most programming environments generate a skeleton function to handle each event. Chapters 3, 4, and 5 of this manual outline how to generate these function skeletons to build your event handler routines. For example, the Visual Basic environment generates the following function skeleton into which you insert the functions to call when the AcquireData event occurs.

```
Private Sub CWAI1_AcquiredData(ScaledData As Variant, BinaryCodes As Variant)
```

End Sub

In most cases, the event also returns some data to the event handler, such as the ScaledData and BinaryCodes arrays in the previous example, that can be used in your event handler routine.

#### **Using the Analysis Library and Instrument Driver DLLs**

The ComponentWorks Analysis Library is packaged as a set of ActiveX controls, while the instrument drivers are packaged as 32-bit DLLs. You can add analysis functions to your project in the same way you add user interface or data acquisition controls. After adding the Analysis controls to your programming environment, use the analysis functions like any other method on a control. To use any specific function, place the appropriate Analysis control on a form. In your program, call the name of the control followed by the name of the analysis function:

MeanValue = CWStat1.Mean (Data)

Consult Chapter 10, *Using the Analysis Controls and Functions*, and the ComponentWorks online reference for more information on the individual analysis functions and their use.

To use the instrument driver DLLs, you must add a reference to the DLL in your project. After adding the appropriate reference to your project, you can use the functions included in the DLLs to control your instruments.

#### The Online Reference—Learning the Properties, Methods, and Events

The ComponentWorks online reference contains detailed information on each control and its associated properties, methods, and events. Refer to ComponentWorks online reference when you are using a control for the first time. Remember that many of the ComponentWorks controls share sub-objects and properties, so when you learn how to use one control, you also learn how to use others. You can open the online reference from within most programming environments by clicking on the **Help** button in the custom property pages, or you can open it from the Windows **Start** menu by selecting **Programs»National Instruments ComponentWorks» ComponentWorks Reference**.

Some programming environments have built-in mechanisms for detailing the available properties, methods, and events for a particular control and sometimes include automatic links to the help file. Refer to the chapter on your particular programming environment to learn about additional tools.

## Getting Started with ComponentWorks

This chapter describes approaches to help you get started using ComponentWorks, depending on your application needs, your experience using ActiveX controls in your particular programming environment, and your specific goals in using ComponentWorks.

This chapter elaborates on the following steps for getting started with ComponentWorks.

- Install and configure driver software if you plan to use hardware I/O controls.
- Explore the ComponentWorks documentation.
- 3. Become familiar with the examples structure.
- 4. Develop your application.
- 5. Seek answers to your questions from additional information sources.

So far you should have installed the ComponentWorks software following the instructions in Chapter 1, *Introduction to ComponentWorks*, as well as the programming environment you plan to use with the controls. Chapter 1 also includes basic information about ActiveX controls. If you are unfamiliar with ActiveX controls, read Chapter 1 before proceeding.

## **Installing and Configuring Driver Software**

If you need to use any of the hardware I/O controls in ComponentWorks (data acquisition, GPIB, serial, or VISA), you must install and configure the corresponding driver software before using these controls.

Driver software performs the low-level calls to your hardware. It is configured using a separate configuration utility provided with the driver software. In some cases, the configuration utility also provides parameters or values you need to use in your controls. For example, with the device number defined in the data acquisition (DAQ) configuration utility, you can select a specific piece of hardware in your controls.

Install the most current driver available. Sometimes, the ComponentWorks controls require features provided only in newest versions of the driver. The ComponentWorks CD includes installers for different drivers compatible with the ComponentWorks version on the CD. Check the \Drivers directory on the CD for these installation programs. If necessary, you can download newer versions of the drivers from the National Instruments Web or FTP sites.

To run the installation and configuration programs, follow the directions provided with each driver. Each driver includes a readme file or printed document that provides the latest information as well as any operating system details. Appendix B, *Background Information* about *Data Acquisition*, includes some commonly used information about the DAQ driver.

## **Exploring the ComponentWorks Documentation**

The printed and online manuals contain the information necessary to learn and use the ComponentWorks controls to their full capabilities. The manuals are divided into different sections. Each section addresses a specific step on the learning curve.

Use the *Getting Results with ComponentWorks* manual to learn how to develop simple applications with the ComponentWorks controls. The manual contains information you can use in specific circumstances, such as debugging particular problems or distributing applications.

After you understand the operation and organization of the controls, use the ComponentWorks online reference to obtain information about specific features of each control.

#### Getting Results with ComponentWorks Manual

The Getting Results with ComponentWorks manual contains four different sections.

Section 1—Includes Chapter 1, *Introduction to ComponentWorks*, and Chapter 2, *Getting Started with ComponentWorks*. These chapters provide introductory information about ComponentWorks, including installation procedures, a basic overview of ActiveX controls, and information about getting started with the software.

Section 2—Includes Chapter 3, *Building ComponentWorks Applications with Visual Basic*, Chapter 4, *Building ComponentWorks Applications with Visual C++*, and Chapter 5, *Building ComponentWorks Applications with Delphi*. These chapters describe how to use ActiveX controls in the most commonly used programming environments—Visual Basic, Visual C++, and Borland Delphi.

If you are familiar with using ActiveX controls in these environments, you should not need to read these chapters. If you are using the controls in another environment, consult your programming environment documentation for information about using ActiveX controls. You can check the ComponentWorks Support Web site for information about additional environments.

Section 3—Includes chapters 6 through 12. These chapters describe the basic operation of the different controls in ComponentWorks. Each chapter contains an overview of a group of controls, describing their most commonly used properties, methods, and events. The description also includes short code segments to illustrate programmatic control and a number of simple tutorials that step you through building an application with those controls.

Section 4—Includes the appendices of this manual. The appendices contain additional information about using ComponentWorks, including information about using ComponentWorks in previous versions of Visual Basic, Visual C++, and Delphi; DAQ basics; common questions; and error code descriptions. If you have a particular question when using the ComponentWorks software, remember to check the appendices as well as the other documentation for an answer.

#### ComponentWorks Online Reference

The ComponentWorks online reference includes complete reference information for all controls—all properties, methods, and events for every control—as well as the text from *Getting Results with ComponentWorks* and the *Instrument Driver Factory* manual.

To use the online reference efficiently, you should understand the material presented in the *Getting Results with ComponentWorks* manual about using ComponentWorks ActiveX controls.

After going through the *Getting Results with ComponentWorks* manual and tutorials, use the online reference as your main source of information. Refer to it when you need specific information about a particular feature in ComponentWorks.

#### **Accessing the Online Reference**

You can open the online reference from the Windows **Start** menu (**Programs»National Instruments ComponentWorks» ComponentWorks Reference**). The reference opens to the main contents page. From the contents page, you can browse the contents of the online reference or search for a particular topic.

Most programming environments support some type of automatic link to the online reference (help) file from within their environment, often the <F1> key. Try selecting the control on a form or placing the cursor in code specific to a control and pressing <F1> to evoke the online reference.

In most environments, the property pages for the ComponentWorks controls include a **Help** button that provides information about the property pages.

#### **Finding Specific Information**

To find information about a particular control or feature of a control, select the **Index** tab under the **Help Topics** page. Enter the name of the control, property, method, or event. Control names always begin with CW (for example, CWGraph, CWAI, and CWStat). Property, method, and event names are identical to those used in the code (for example, Axes, Plot, Channels, and Font).

One group of objects that frequently generates questions are the Collection objects. Search the online reference for Collections and the Item method for more information. You also can find information about collection objects in the *Collection Objects* section of Chapter 1, *Introduction to ComponentWorks*.

## **Becoming Familiar with the Examples Structure**

The examples installed with ComponentWorks show you how to use the controls in applications. You can use these examples as a reference to become more familiar with the use of the controls, or you can build your application by expanding one of the examples.

When you install ComponentWorks, you can install examples for selected programming environments. The examples are located in the \ComponentWorks\samples directory and organized by programming environment (\Visual Basic, \Visual C++, and so on) and control group (\UI, \DAQ, and so on). Within these directories, the examples are further subdivided by functionality.

The online reference includes a searchable list of all the examples included with ComponentWorks. Select **Examples** to see the list of examples.

The examples exist in the oldest commonly used version of a programming environment, such as Visual Basic 4. If you open an example in a newer version, you might see a warning message indicating that the example will be converted to the new version.

## **Developing Your Application**

Depending on your experience with your programming environment, ActiveX controls, and ComponentWorks, you can get started using ComponentWorks in some of the following ways.

#### Are you new to your particular programming environment?

Spend some time using and programming in your development environment. Check the documentation that accompanies your programming environment for getting started information or tutorials, especially tutorials that describe using ActiveX controls in the environment. If you have specific questions, search the online documentation of your development environment. After becoming familiar with the programming environment, continue with the following steps.

## Are you new to using ActiveX controls or do you need to learn how to use ActiveX controls in a specific programming environment?

Make sure you have read and understand the information regarding ActiveX controls in Chapter 1, *Introduction to ComponentWorks*, and the appropriate chapter about your specific programming environment. Refer to Table 2-1 to find out which chapter you should read for your specific programming environment.

If you use Borland C++ Builder, most of Chapter 5 pertains to you. If you use another programming environment, see the ComponentWorks Support Web site for current information about particular environments.

| Environment            | Read This Chapter  |
|------------------------|--|
| Microsoft Visual Basic | Chapter 3, Building ComponentWorks<br>Applications with Visual Basic |
| Microsoft Visual C++   | Chapter 4, Building ComponentWorks<br>Applications with Visual C++   |
| Borland Delphi         | Chapter 5, Building ComponentWorks<br>Applications with Delphi       |

**Table 2-1.** Chapters on Specific Programming Environments

Regardless of the programming environment you use, consult its documentation for information about using ActiveX controls. After becoming familiar with using ActiveX controls in your environment, continue with the following steps.

## Are you familiar with ActiveX controls but need to learn ComponentWorks controls, hierarchies, and features?

If you are familiar with using ActiveX controls, including collection objects and the Item method, read the chapters pertaining to the controls you want to use. Chapters 6 through 11 provide basic information about each ComponentWorks control and describe their most commonly used properties, methods, and events. The chapters also offer simple tutorials to help you become more familiar with using the controls. Solutions to each of the tutorials are installed with your software in the \ComponentWorks\tutorials directory.

After becoming familiar with the information in these chapters, try building applications with the ComponentWorks controls. You can find detailed information about all properties, methods, and events for every control in the online reference.

## Do you want to develop applications quickly or modify existing examples?

If you are very familiar with using ActiveX controls, including collections and the Item method, and have some experience using ComponentWorks or other National Instruments products, you can get started more quickly by looking at the examples.

Most examples demonstrate how to perform operations with a particular control or group of controls. Generally, the examples avoid presenting complex operations on more than one group of controls, such as UI and DAQ. To become familiar with an individual group of controls, look at the

example for that particular group. Then, you can combine different programming concepts from the different groups in your application.

The examples include comments to provide more information about the steps performed in the example. The examples avoid performing complex programming tasks specific to one programming environment; instead, they focus on showing you how to perform operations using the ComponentWorks controls. When developing applications with ActiveX controls, you do a considerable amount of programming by setting properties in the property pages. Check the value of the control properties in the examples because the values greatly affect the operation of the example program. In some cases, the actual source code used by an example might not greatly differ from other examples; however, the values of the properties change the example significantly.

## **Seeking Information from Additional Sources**

After working with the ComponentWorks controls, you might need to consult other sources if you have questions. The following sources can provide you with more specific information.

- Getting Results with ComponentWorks Appendices—The appendices include information about using previous versions of development tools, DAQ basics, common questions, and error descriptions.
- ComponentWorks Instrument Driver Manual—If you are using the Instrument Driver Factory (ComponentWorks Full Development system only), you have received a separate manual detailing this tool and its use.
- ComponentWorks Online Reference—The online reference includes
  the complete reference documentation, text of the *Getting Results with*ComponentWorks manual as well as additional information. If you are
  not able to find a particular topic in the index, choose the **Find** tab in
  the **Help Topics** page and search the complete text of the online
  reference.
- ComponentWorks Support Web Site—The ComponentWorks Support Web site, as part of the National Instruments Support Web site (www.natinst.com/support), contains support information, updated continually. You can find application and support notes and information about using ComponentWorks in additional programming environments. The Web site also contains the KnowledeBase, a searchable database containing thousands of entries answering common questions related to the use of ComponentWorks and other National Instruments products.

# Building ComponentWorks Applications with Visual Basic

This chapter describes how you can use the ComponentWorks controls with Visual Basic 5; insert the controls into the Visual Basic environment, set their properties, and use their methods and events; and perform these operations using ActiveX controls in general. This chapter also outlines Visual Basic features that simplify working with ActiveX controls.

At this point you should be familiar with the general structure of ActiveX controls described in Chapter 1, *Introduction to ComponentWorks*. The individual ComponentWorks controls are described later in this manual.

Note

The descriptions and figures in this chapter apply specifically to the Visual Basic 5 environment. Although most of this information applies to Visual Basic 4 as well, some menu and option names and environment components are different. See Appendix A, Using Previous Versions of Visual Basic, Visual C++, and Delphi with ComponentWorks, for a description of key differences between these versions of Visual Basic as they apply to ComponentWorks.

### **Developing Visual Basic Applications**

The following procedure explains how you can start developing Visual Basic applications with ComponentWorks.

- 1. Select the type of application you want to build. Initially select a Standard EXE for your application type.
- Design the form. A form is a window or area on the screen on which you can place controls and indicators to create the user interface for your program. The toolbox in Visual Basic contains all of the controls available for developing the form.

- 3. After placing each control on the form, configure the properties of the control using the default and custom property pages.
  - Each control on the form has associated code (event handler routines) in your Visual Basic program that automatically executes when the user operates that control.
- 4. To create this code, double click on the control while editing your application and the Visual Basic code editor opens to a default event handler routine.

#### Loading the ComponentWorks Controls into the Toolbox

Before building an application using the ComponentWorks controls and libraries, you must add them to the Visual Basic toolbox. The ComponentWorks ActiveX controls are divided into different groups including user interface controls (CWUI.OCX), data acquisition controls (CWDAQ.OCX), and analysis library controls (CWANALYSIS.OCX). The exact list of controls depends on the ComponentWorks package you use.

Use the following procedure to add ComponentWorks controls to the project toolbox.

- 1. In a new Visual Basic project, right click on the toolbox and select **Components...**.
- 2. Scroll down to the ComponentWorks controls, which you can find in the Controls list, beginning with National Instruments.
- 3. Place a checkmark in the box next to the control groups to select the controls you want to use in your project. If the ComponentWorks controls are not in the list, select the control files from the \Windows\System(32) directory by pressing the **Browse** button.

If you need to use the ComponentWorks controls in several projects, create a new default project in Visual Basic 5 to include the ComponentWorks controls and serve as a template.

- Create a new Standard EXE application in the Visual Basic environment.
- 2. Add the ComponentWorks controls to the project toolbox as described in the preceding procedure.
- 3. Save the form and project in the \Template\Projects directory under your Visual Basic directory.
- 4. Give the form and project a descriptive name, such as CWForm and CWProject.

After creating this default project, you have a new option, CWProject, that includes the ComponentWorks controls in the **New Project** dialog by default. You can create additional project templates with different combinations of controls.

#### **Building the User Interface Using ComponentWorks**

After you add the ComponentWorks controls to the Visual Basic toolbox, use them to create the front panel of your application. To place the controls on the form, select the corresponding icon in the toolbox and click and drag the mouse on the form. This step creates the corresponding control. After you create controls, move and size them by using the mouse. To move a control, click and hold the mouse on the control and drag the control to the desired location. To resize a control, select the control and place the mouse pointer on one of the hot spots on the border of the control. Drag the border to the desired size. Notice that the icons for all but the user interface controls cannot be resized and will not be visible at run time.

Once ActiveX controls are placed on the form, you can edit their properties using their property sheets. You can also edit the properties from within the Visual Basic program at run time.

#### **Using Property Sheets**

After placing a control on a Visual Basic form, configure the control by setting its properties in the Visual Basic property pages (see Figure 3-1) and ComponentWorks custom control property pages (see Figure 3-2). Visual Basic assigns some default properties, such as the control name and the tab order. When you create the control, you can edit these stock properties in the Visual Basic default property sheet. To access this sheet, select a control and select **Properties Window** from the **View** menu, or press <F4>. To edit a property, highlight the property value on the right side of the property sheet and type in the new value or select it from a pull down menu. The most important property in the default property sheet is Name, which is used to reference the control in the program.

Edit all other properties of an ActiveX control in the custom property sheets. To open the custom property sheets, right click on the control on the form and select **Properties...** or select the controls and press <Shift-F4>.



Figure 3-1. Visual Basic Property Pages

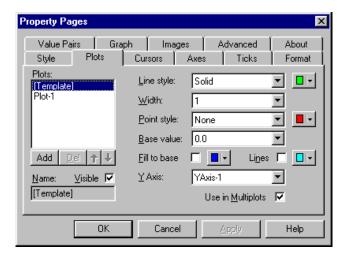


Figure 3-2. ComponentWorks Custom Property Pages

#### **Using Your Program to Edit Properties**

You can set and read the properties of your controls programmatically in Visual Basic. Use the name of the control with the name of the property as you would with any other variable in Visual Basic. The syntax for setting a property in Visual Basic is name.property = new value.

For example, if you want to change the state of an LED control during program execution, change the Value property from True to False or False to True.

CWButton1.Value = False

Some properties of a control can be objects that have their own properties. In this case, specify the name of the control, sub-object, and property separated by periods. For example, consider the following code for the DAQ analog input (CWAI) control.

CWAI1.ScanClock.Frequency = 10000

In the above code, ScanClock is a property of the AI control and refers to a CWAIClock object. Frequency is a property of the CWAIClock object.

You can retrieve the value of control properties from your program in the same way. For example, you can print the value of an LED control.

Print CWButton1.Value

In Visual Basic most controls have a default property such as Value for the Knob, Button, and Slide controls. You can access the default property of a control by using its control name (without the property name attached).

CWSlide1 = 5.0

is programmatically equivalent to

CWSlide1.Value = 5.0

Consult the Setting the Properties of an ActiveX Control section of Chapter 1, Introduction to ComponentWorks, for information on setting properties programmatically, specifically with objects and properties in collections. The Object Browser, a Visual Basic tool that is helpful with using properties in your code, is described in detail in the Using the Object Browser to Build Code in Visual Basic section of this chapter.

#### **Working with Control Methods**

Calling the methods of an ActiveX control in Visual Basic is similar to working with the control properties. To call a method, add the name of the method after the name of the control (and sub-object if applicable). For example, you can call the Start method on the DAQ analog input control.

CWAI1.Start

Methods can have parameters that you pass to the method, and return values that pass information back to your program. For example, the PlotY method for the ComponentWorks Graph control has a required parameter—the array of data to be plotted—that you must include when you call the method. If you want to plot the data returned from an Analog Input control, use the following line of code.

```
CWGraph1.PlotY ScaledData
```

The PlotY method has some additional parameters that are optional. These are added after the data parameter, separated by commas, if desired.

In Visual Basic if you call a method without assigning a return variable, any parameters passed to the method are listed after the method name, separated by commas without parentheses.

```
CWAI1.AcquireData Voltages, BinaryCodes, 1.0
```

If you assign the return value of a method to a return variable, enclose the parameters in parentheses.

```
lErr = CWAI1.AcquireData(Voltages, BinaryCodes, 1.0)
```

You can use the Visual Basic Object Browser to add method calls to your program.

#### **Developing Control Event Routines**

After you configure your controls in the forms editor, write Visual Basic code to respond to events on the controls. The controls generate these events in response to user interactions with the controls or in response to some other occurrence in the control. To develop the event handler routine code for an ActiveX control in Visual Basic, double click on the control to open the code editor, which automatically generates a default event handler routine for the control. The event handler routine skeleton includes the control name, the default event, and any parameters that are passed to the event handler routine. The following code is an example of the event routine generated for the Slide control. This event routine (PointerValueChanged) is called when the value of the slide is changed by the user or by some other part of the program.

```
Private Sub CWSlide1_PointerValueChanged(ByVal
    Pointer As Long, Value As Variant)
End Sub
```

To generate an event handler for a different event of the same control, double click the control to generate the default handler, and select the desired event from the right pull-down menu in the code window, as shown in the following illustration.

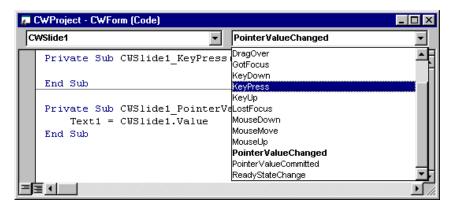


Figure 3-3. Selecting Events in the Code Window

Use the left pull-down menu in the code window to change to another control without going back to the form window.

#### Using the ComponentWorks Instrument Driver DLLs in Visual Basic

The ComponentWorks Full Development System comes with a library of instrument drivers and the Instrument Driver Factory. An instrument driver is software that handles the details of control and communications with a specific instrument.

An instrument driver consists of a set of high-level functions that controls a specific programmable instrument. Each function corresponds to a programmatic operation such as initialization, configuration, and measurement. If you did not purchase the ComponentWorks Full Development Kit and find that you need instrument drivers, contact National Instruments for information on ordering drivers.

The ComponentWorks instrument drivers are compiled to 32-bit DLLs in the Instrument Driver Factory. Before you can use any of the instrument driver functions in your program, you must add a reference to the instrument driver DLL to your project.

To add an instrument driver DLL to your project, select **References...** from the **Project** menu. In the References dialog window, press the **Browse** button and then move to the directory that contains the instrument driver DLL—the default is ...\ComponentWorks\Instrument Drivers\....

Select the instrument driver DLL you wish to add to your project.

After you have added the reference to the DLL, you can use any of the functions in the instrument driver without having to do any more declarations. An example of a typical instrument driver function is the initialization function for the Fluke 45 multimeter.

```
lerr = fl45_init(2, 1, 1, InstrID)
```

All the functions in each instrument driver are listed and described in the corresponding help file that is installed with each driver. After you add the appropriate reference to your project for using an instrument driver DLL, use the object browser to view the functions and parameters available in each instrument driver. Refer to the *Using the Object Browser to Build Code in Visual Basic* section for more information on using the object browser to help you build your program.

For more information about the instrument drivers and related development tools, see the *Instrument Driver Factory* manual.

#### Using the Object Browser to Build Code in Visual Basic

Visual Basic includes a tool called the Object Browser that you can use to work with ActiveX controls and instrument driver DLLs while creating your program. The Object Browser displays a detailed list of the available properties, methods, and events for a particular control, as well as the functions of an instrument driver. It presents a three-step hierarchical view of controls or libraries and their properties, methods, functions, and events. To open the Object Browser, select **Object Browser** from the **View** menu, or press <F2>.

In the Object Browser, use the top left pull-down menu to select a particular ActiveX control file, library, or instrument driver. You can select any currently loaded control or driver. The Classes list on the left side of the object browser displays a list of controls, objects, and function classes available in the selected control file or driver.

Figure 3-4 shows the ComponentWorks User Interface (UI) control file selected in the Object Browser. The Classes list shows all the UI controls and associated object types. Each time you select an item from the Classes list in the Object Browser, the Members list on the right side displays the properties, methods, and events for the selected object or class.

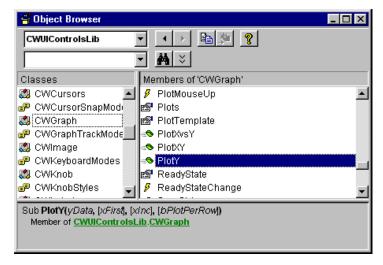


Figure 3-4. Viewing CWGraph in the Object Browser

When you select an item in the Members list, the prototype and description of the selected property, method, or function are displayed at the bottom of the Object Browser dialog box. In Figure 3-4, the CWGraph control is selected from the list of available UI objects. For this control, the PlotY method is selected and the prototype and description of the method appear in the dialog box. The prototype of a method or function lists all parameters, required and optional.

When you select a property of a control or object in the Members list which is an object in itself, the description of the property includes a reference to the object type of the property. For example, Figure 3-5 shows the Knob control (CWKnob) selected in the Classes list and its Axis property selected in the Members list.

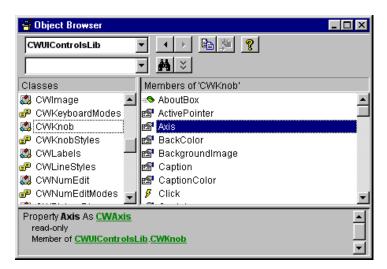


Figure 3-5. Viewing CWKnob in the Object Browser

The Axis on the Knob control is a separate object, so the description at the bottom of the dialog window lists the Axis property as CWAxis. CWAxis is the type name of the Axis object, and you can select CWAxis in the Classes list to see its properties and methods. Move from one level of the object hierarchy to the next level using the Object Browser to explore the structure of different controls.

The question mark (?) button at the top of the Object Browser opens the help file to a description of the currently selected item. To find more information about the CWGraph control, select the control in the window and press the ? button.

#### **Pasting Code into Your Program**

If you open the Object Browser from the Visual Basic code editor, you can copy the name or prototype of a selected property, method, or function to the clipboard and then paste it into your program. To perform this task, select the desired Member item in the Object Browser. Press the **Copy to Clipboard** button at the top of the Object Browser or highlight the prototype at the bottom and press <Ctrl-C> to copy it to the clipboard. Paste

it into your code window by selecting **Paste** from the **Edit** menu or pressing <Ctrl-V>.

Use this method repeatedly to build a more complex reference to a property of a lower-level object in the object hierarchy. For example, you can create a reference to

```
CWGraph1.Axes.Item(1).ValuePairs.Item(3).Name
```

by typing in the name of the control (CWGraph1) and then using the Object Browser to add each section of the property reference. Refer to the *Item Method* section of Chapter 1, *Introduction to ComponentWorks*, for more information about the Item method and collections.

#### **Adding Code Using Visual Basic Code Completion**

Visual Basic 5 supports automatic code completion in the code editor. As you enter the name of a control, the code editor prompts you with the names of all appropriate properties and methods. Try placing a control on the form and then entering its name in the code editor. After typing the name, add a period as the delimiter to the property or method of the control. As soon as you type the period, Visual Basic drops down a menu of available properties and methods, as shown in Figure 3-6.



Figure 3-6. Visual Basic 5 Code Completion

You can select from the list or properties and events by scrolling through the list and selecting one or by typing in the first few letters of the desired item. Once you have selected the correct item, type the next logical character such as a period, space, equal sign, or carriage return to enter the selected item in your code and continue editing the code.

## **Learning to Use Specific ComponentWorks Controls**

Each ComponentWorks control and its use are described in more detail in later chapters in this manual. However, these chapters do not discuss every property, method, and feature of every control. The ComponentWorks online reference contains detailed information about each control and all its associated properties, events, and methods. Refer to the online reference to find descriptions of the different features of a particular control. Remember that many of the ComponentWorks controls share properties. When you learn how to use one control, you are learning how to use others as well.

# Building ComponentWorks Applications with Visual C++

This chapter describes how you can use ComponentWorks controls with Visual C++, explains how to insert the controls into the Visual C++ environment and create the necessary wrapper classes, shows you how to create an application compatible with the ComponentWorks controls using the Microsoft Foundation Classes Application Wizard (MFC AppWizard) and how to build your program using the ClassWizard with the controls, and discusses how to perform these operations using ActiveX controls in general.

At this point you should be familiar with the general structure of ActiveX controls described in Chapter 1, *Introduction to ComponentWorks*, as well as C++ programming and the Visual C++ environment. The individual ComponentWorks controls are described later in this manual.

Note

The descriptions and figures in this chapter apply specifically to the Visual C++ 5 environment. Although most of this information applies to Visual C++ 4.x as well, some menu and option names and other environment components are different. See Appendix A, Using Previous Versions of Visual Basic, Visual C++, and Delphi with ComponentWorks, for a description of key differences between these versions of Visual C++ as they apply to ComponentWorks.

### **Developing Visual C++ Applications**

The following procedure explains how you can start developing Visual C++ applications with ComponentWorks.

- 1. Create a new workspace or project in Visual C++.
- 2. To create a project compatible with the ComponentWorks ActiveX controls, use the Visual C++ MFC AppWizard to create a skeleton project and program.
- 3. After building the skeleton project, add the ActiveX controls you need to the controls toolbar. From the toolbar, you can add the controls to the application itself.

- 4. After adding a control to your application, configure its properties using its property pages.
- While developing your program code, use the control properties and methods and create event handlers to process different events generated by the control.

Create the necessary code for these different operations using the ClassWizard in the Visual C++ environment.

#### **Creating Your Application**

When developing new applications, use the MFC AppWizard to create new project workspace so the project is compatible with ActiveX controls. The MFC AppWizard creates the project skeleton and adds the necessary code that enables you to add ActiveX controls to your program.

1. Create a new project by selecting **New...** from the **File** menu. The **New** dialog box opens (see Figure 4-1).

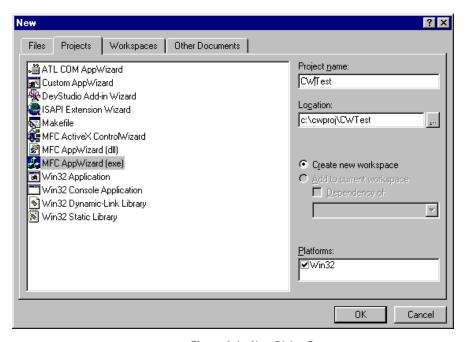


Figure 4-1. New Dialog Box

- 2. On the **Projects** tab, select the MFC AppWizard (exe) and enter the project name in the Project name field and the directory in the Location field.
- 3. Click on **OK** to setup your project.

- Complete the next series of dialog windows in which the MFC AppWizard prompts you for different project options. If you are a new Visual C++ or the MFC AppWizard user, accept the default options unless otherwise stated in this documentation.
- 4. In the first step, select the type of application you want to build. For this example, select a Dialog based application, as shown in Figure 4-2, to make it easier to become familiar with the ComponentWorks controls.

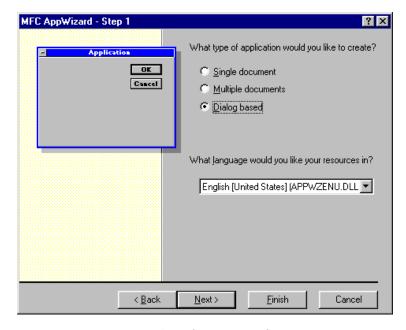


Figure 4-2. MFC AppWizard—Step 1

- 5. Click on the **Next>** button to continue.
- 6. Enable ActiveX controls support. If you have selected a Dialog based application, step two of the MFC AppWizard enables **ActiveX Controls** support by default.
- 7. Continue selecting desired options through the remainder of the MFC AppWizard. When you finish the MFC AppWizard, it builds a project and program skeleton according to the options you specified. The skeleton includes several classes, resources, and files, all of which can be accessed from the Visual C++ development environment.
- 8. Use the Workspace window, which you can select from the **View** menu, to see the different components in your project.

#### Adding ComponentWorks Controls to the Visual C++ Controls Toolbar

Before building an application using the ComponentWorks controls, you must load the controls into the Controls toolbar in Visual C++ from the Component Gallery in the Visual C++ environment. When you load the controls using the Component Gallery, a set of C++ wrapper classes automatically generate in your project. You must have wrapper classes to work with the ComponentWorks controls.

The Controls toolbar is visible in the Visual C++ environment only when the Visual C++ dialog editor is active. Use the following procedure to open the dialog editor.

- Open the Workspace window by selecting Workspace from the View menu.
- 2. Select the Resource View (second tab along the bottom of the Workspace window).
- 3. Expand the resource tree and double click on one of the Dialog entries.
- 4. If necessary, right click on any existing toolbar and enable the Controls option.

By adding controls to your project, you create the necessary wrapper classes for the control in your project and add the control to the toolbox. Use the following procedure to add new controls to the toolbar.

- Select Project»Add To Project...»Components and Controls and, in the following dialog, double click on Registered ActiveX Controls.
- 2. Select and insert registered ActiveX controls into your project and control toolbox.
- 3. Select the controls you need and click the **Insert** button. All ComponentWorks controls start with CW.
- 4. Click on **OK** in the following dialog windows.
- When you have inserted all controls, click Close in the Components and Controls Gallery.

#### **Building the User Interface Using ComponentWorks Controls**

After adding the controls to the Controls toolbar, use the controls in the design of the application user interface. Place the controls on the dialog form using the dialog editor. You can size and move individual controls in the form to customize the interface. Use the custom property sheets to configure control representation on the user interface and control behavior at run time.

To add ComponentWorks controls to the form, open the dialog editor by selecting the dialog form from the Resource View of the Workspace window. If the Controls toolbar is not displayed in the dialog editor, open it by right clicking on any existing toolbar and enabling the Controls option.

To place a ComponentWorks control on the dialog form, select the desired control in the Controls toolbar and click and drag the mouse on the form to create the control. After placing the controls, move and resize them on the form as needed.

After you add a ComponentWorks control to a dialog form, configure the default properties of the control by right clicking the control and selecting **Properties** to display its custom property sheets. Figure 4-3 shows the CWGraph control property sheets.

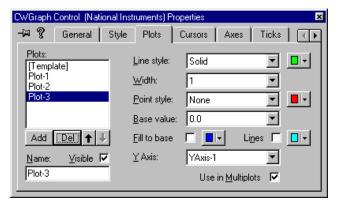


Figure 4-3. CWGraph Control Property Sheets

So you can see immediately how different properties affect the control, a separate window displays a sample copy of the control that reflects the property changes as you make them in the property sheets.

#### **Programming with the ComponentWorks Controls**

To program with ComponentWorks controls, use the properties, methods, and events of the controls as defined by the wrapper classes in Visual C++.

Note

Later chapters in this manual provide more information on the most commonly used properties, methods, and events of the individual controls.

All the properties, methods, and events of the different controls are described in detail in the ComponentWorks online reference, which you can access from Programs»National Instruments ComponentWorks»ComponentWorks Reference from the Windows Start menu.

Before you can use the properties or methods of a control in your Visual C++ program, assign a member variable name to the control. This member variable becomes a variable of the application dialog class in your project.

To create a member variable for a control on the dialog form, right click on the control and select **ClassWizard**. In the **MFC Class Wizard** window, activate the **Member Variables** tab, as shown in Figure 4-4.

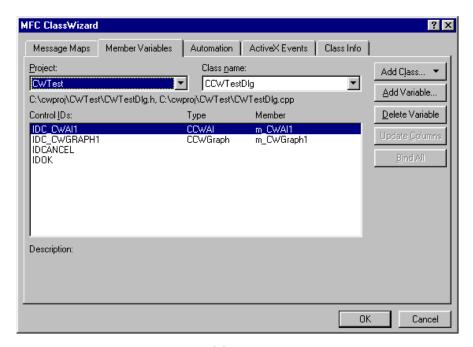


Figure 4-4. MFC ClassWizard—Member Variable Tab

Select the new control in the Control IDs field and press the **Add Variable...** button. In the dialog window that appears, complete the member variable name and press **OK**. Most member variable names start with m\_, and you should adhere to this convention. After you create the member variable, use it to access a control from your source code. Figure 4-4 shows the MFC Class Wizard after member variables have been added for a graph and analog input control.

#### **Using Properties**

Unlike Visual Basic, you do not read or set the properties of ComponentWorks controls directly in Visual C++. Instead, the wrapper class of each control contains functions to read and write the value of each property. These functions are named starting with either Get or Set

followed by the name of the property. For example, to set the Value property of a slide, use the SetValue function of the wrapper class for the Slide control. In the source code, the function call is preceded by the member variable name of the control to which it applies.

```
m_Slide.SetValue(COleVariant(5.0));
```

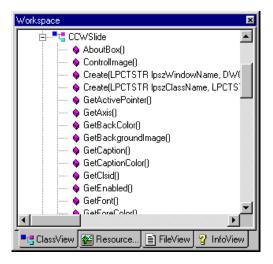
All values passed to properties need to be of variant type. Convert the value passed to the Value property to a variant using COleVariant ().

Use the GetValue() function to read the value of a control or to pass a value of a control to another part of your program. For example, pass the value of a Slide control to a Meter control.

```
m Meter.SetValue(m Slide.GetValue());
```

Because the GetValue function returns its value as a variant in the previous line of code, conversion to a variant type is not necessary.

You can view the names of all the property functions (and other functions) for a given control in the ClassView of the Workspace window. In the Workspace window, select **ClassView** and then the control for which you want to view property functions and methods. Figure 4-5 shows the functions for the Slide object as listed in the Workspace. These are created automatically when you add a control to the Controls toolbar in you project.



**Figure 4-5.** Viewing Property Functions and Methods in the Workspace Window

If you need to access a property of a control which is in itself another object, use the appropriate property function to return the sub-object of the control. Make a call to access the property of the sub-object. Include the header file in your program for any new objects. For example, use the following code to configure the Axis object of a Slide control.

```
#include cwaxis.h
CCWAxis Axis1;
Axis1 = m_Slide.GetAxis();
Axis1.SetMaximum(COleVariant(5.0));
```

You can chain this operation into one function call without having to declare another variable.

```
#include cwaxis.h
m_Slide.GetAxis().SetMaximum (COleVariant(5.0));
```

If you need to access an object in a collection property, use the Item method with the index of the object. Remember to include the header file for the collection object. For example, to set the maximum of the first y-axis on a graph, use the following code.

```
#include cwaxes.h
#include cwaxis.h
m_Graph.GetAxes().Item(COleVariant(2.0)).SetMaximum
    (COleVariant(5.0));
```

#### **Using Methods**

Use the control wrapper classes to extract all methods of the control. To call a method, append the method name to the member variable name and pass the appropriate parameters. If the method does not require parameters, use a pair of empty parentheses.

```
m_CWAI1.Start();
```

Most methods take some parameters as variants. You must convert any such parameter to a variant if you have not already done so. You can convert most scalar values to variants with COleVariant(). For example, the PlotY method of the graph control requires three scalar values as variants.

```
m_Graph.PlotY (*Voltages, COleVariant(0.0),
COleVariant(1.0), COleVariant(1.0));
```

Note Consult Visual C++ documentation for more information about variant data types.

If you need to call a method on a sub-object of a control, follow the conventions outlined in the *Using Properties* section earlier in this chapter. For example, a single plot on a graph is an object in the Plots collection, which is an object itself in the graph control. To call PlotY on one particular plot of your graph, use the following line of code.

```
m_Graph.GetPlots().Item(COleVariant(2.0)).PlotY
  (*Voltages, COleVariant(0.0), COleVariant(1.0));
```

#### **Using Events**

After placing a control on your form, you can start defining event handler functions for the control in your code. Events generate automatically at run time when different controls respond to conditions, such as a user clicking a button on the form or the data acquisition process acquiring a specified number of points.

Use the following procedure to create an event handler.

- 1. Right click on a control and select **ClassWizard**.
- 2. Select the **Message Maps** tab and the desired control in the Object IDs field. The Messages field displays the available events for the selected control. (See Figure 4-6, *Event Handler for the PointerValueChanged Event of a Knob*).
- 3. Select the event and press the **Add Function...** button to add the event handler to your code.
- 4. To switch directly to the source code for the event handler, click on the Edit Code button. The cursor appears in the event handler, and you can add the functions to call when the event occurs. You can use the Edit Code button at any time by opening the class wizard and selecting the event for the specific control.

The following figure is an example of an event handler generated for the PointerValueChanged event of a knob. Insert your own code in the event handler:

```
void CTestDlg::OnPointerValueChangedCwknob1(long
Pointer, VARIANT FAR* Value)
{
// TODO: Add your control notification handler code here
}
```

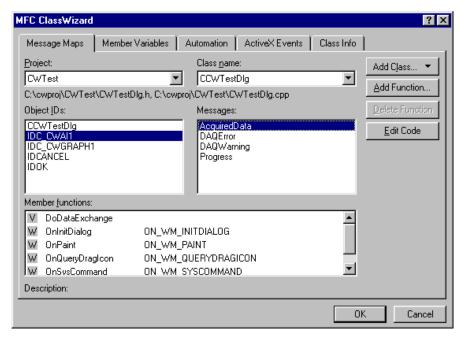


Figure 4-6. Event Handler for the PointerValueChanged Event of a Knob

## **Learning to Use Specific ComponentWorks Controls**

Each ComponentWorks control and its use are described in more detail in later chapters in this manual. However, these chapters do not discuss every property, method, and feature of every control. The ComponentWorks online reference contains detailed information about each control and all its associated properties, events, and methods. Refer to the online reference to find descriptions of the different features of a particular control. Remember that many of the ComponentWorks controls share properties and sub-objects. When you learn how to use one control, you are learning how to use others.

# Building ComponentWorks Applications with Delphi

This chapter describes how you can use ComponentWorks controls with Delphi; insert the controls into the Delphi environment, set their properties, and use their methods and events; and perform these operations using ActiveX controls. This chapter also outlines Delphi features that simplify working with ActiveX controls.

At this point you should be familiar with the general structure of ActiveX controls described in Chapter 1, *Introduction to ComponentWorks*. The individual ComponentWorks controls are described later in this manual.

Note

The descriptions and figures in this chapter apply specifically to the Delphi 3 environment. Although most of this information applies to Delphi 2 as well, some menu and option names and other environment components are different. See Appendix A, Using Previous Versions of Visual Basic, Visual C++, and Delphi with ComponentWorks, for a description of key differences between these versions of Delphi as they apply to ComponentWorks.

If you have the original release of Delphi 3, you might experience significant problems with ActiveX controls, but Borland offers a newer version of Delphi that corrects most of these problems. Before using ComponentWorks with Delphi 3, contact Borland to receive the Delphi 3 patch or a newer version.

## Running Delphi Examples

To run the Delphi examples installed with ComponentWorks, you need to import the appropriate controls into the Delphi environment. See the section on *Loading the ComponentWorks Controls into the Component Palette* for more information about loading the controls.

## **Upgrading from a Previous Version of ComponentWorks**

When you upgrade ComponentWorks, you must remove the current controls from the Delphi environment and reinsert the controls in the Delphi environment to update the support files.

- 1. From the Component menu select Install Packages....
- 2. In the Design packages list, select **Delphi User's Components**.
- Click on Edit... and Yes in the following dialog boxes to edit the user's
  component package. The package editor lists all the components
  currently installed in the user's components package, including the
  ComponentWorks controls.
- 4. Select each of the ComponentWorks entries and click on **Remove**.
- 5. Click on **Compile** to rebuild the package.
- 6. Close the package editor.

## **Developing Delphi Applications**

You start developing applications in Delphi using a *form*. A form is a window or area on the screen on which you can place controls and indicators to create the user interface for your programs. The Component palette in Delphi contains all of the controls available for building applications. After placing each control on the form, configure the properties of the control with the default and custom property pages. Each control you place on a form has associated code (event handler routines) in the Delphi program that automatically executes when the user operates the control or the control generates an event.

#### **Loading the ComponentWorks Controls into the Component Palette**

Before you can use the ComponentWorks controls in your Delphi applications, you must add them to the Component palette in the Delphi environment. You need to add the controls to the palette only once because the controls remain in the Component palette until you explicitly remove them. When you add controls to the palette, you create Pascal import units (header files) that declare the properties, methods, and events of a control. When you use a control on a form, a reference to the corresponding import unit is automatically added to the program.

🧊 Note

Before adding a new control to the Component palette, make sure to save all your work in Delphi, including files and projects. After loading the controls, Delphi closes any open projects and files to complete the loading process.

Use the following procedure to add ActiveX controls to the Component palette.

1. Select **Import ActiveX Control...** from the **Component** menu in the Delphi environment. The Import ActiveX Control window displays a list of currently registered controls.

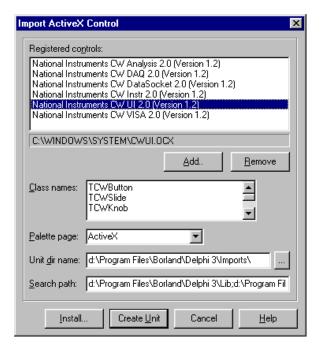


Figure 5-1. Delphi Import ActiveX Control Dialog Box

- 2. Select the control group you want to add to the Component palette.
  All ComponentWorks controls start with National Instruments.
- 3. After selecting the control group, click **Install...**.

Delphi generates a Pascal import unit file for the selected .OCX file, which is stored in the Delphi \Imports directory. If you have installed the same .OCX file previously, Delphi prompts you to overwrite the existing import unit file.

- 4. In the **Install** dialog box, click on **OK** to add the controls to the Delphi user's components package.
- 5. In the following dialog, click on **Yes** to rebuild the user's components package with the added controls. Another dialog box acknowledges the changes you have made to the user's components package, and the package editor displays the components currently installed.

At this point, you can add additional ActiveX controls with the following procedure.

- Click on the Add button.
- b. Select the **Import ActiveX** tab.
- c. Select the ActiveX control you want to add.
- Click on OK.
- e. After adding the ActiveX controls, compile the user's components package.

If your control does not appear in the list of registered controls, click the **Add...** button. To register a control with the operating system and add it to the list of registered controls, browse to and select the OCX file that contains the control. Most OCX files reside in the \Windows\System (32) directory.

New controls are added to the **ActiveX** tab in the Components palette. You can rearrange the controls or add a new tab to the Components palette by right clicking on the palette and selecting **Properties...**.

#### **Building the User Interface**

After you add the ComponentWorks controls to the Component palette, use them to create the user interface. Open a new project, and place different controls on the form. These controls, as part of the program user interface, add specific functionality to the application. After placing the controls on the form, configure their default property values through the stock and custom property sheets.

#### **Placing Controls**

To place a control on the form, select the control from the Component palette and click and drag the mouse on the form. Use the mouse to move and resize controls to customize the interface, as in the following figure. After you place the controls, you can change their default property values by using the default property sheet (Object Inspector) and custom property sheets.

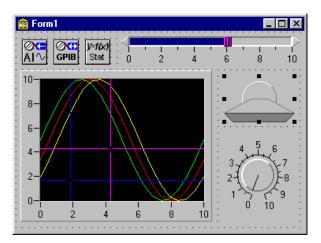


Figure 5-2. ComponentWorks Controls on a Delphi Form

#### **Using Property Sheets**

Set property values such as Name in the Object Inspector of Delphi. To open the Object Inspector, select **Object Inspector** from the **View** menu or press <F11>. Under the **Properties** tab of the Object Inspector, you can set different properties of the selected control.



Figure 5-3. Delphi Object Inspector

To open the custom property pages of a control, double click on the control or right click on the control and select **Properties...**. You can edit most

control properties from the custom property pages. The following figure shows the ComponentWorks Graph control property page.

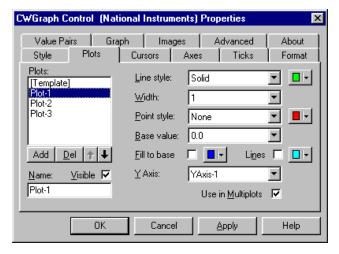


Figure 5-4. ComponentWorks Graph Control Property Page

For more information about specific control properties, see the ComponentWorks online reference.

#### **Programming with ComponentWorks**

The code for each form in Delphi is listed in the Associated Unit (code) window. You can toggle between the form and Associated Unit window by pressing <F12>. After placing controls on the form, use their methods in your code and create event handler routines to process events generated by the controls at run time.

#### **Using Your Program to Edit Properties**

You can set or read control properties programmatically by referencing the name of the control with the name of the property, as you would any variable name in Delphi. The name of the control is set in the Object Inspector.

If you want to change the state of an LED control during program execution, change the Value property from True to False or from False to True. The syntax for setting the Value property in Delphi is name.property: = new\_value.

CWButton1.Value := True;

A property can be an object itself that has its own properties. To set properties in this case, combine the name of the control, sub-object, and property. For example, consider the following code for the DAQ CWAI control. ScanClock is both a property of the DAQ control and an object itself. Frequency is a property of the ScanClock object. As an object of the DAQ control, ScanClock itself has several additional properties.

```
CWAI1.ScanClock.Frequency := 10000;
```

You can retrieve the value of a control property from your program in the same way. For example, you can assign the scan rate of a CWAI control to a text box on the user interface.

```
Edit1.Text := CWAI1.ScanClock.Frequency;
```

To use the properties or methods of an object in a collection, use the Item method to extract the object from the collection. Once you extract the object, use its properties and methods as you usually would.

```
CWGraph1.Axes.Item(2).Maximum := 5;
```

In some cases, an object can be assigned as a property to another object. The following code assigns a Plot object of a graph to a Cursor object in order to specify the plot the cursor is tracking.

```
CWGraph1.Cursors.Item(1).Plot := CWGraph1.Plots.Item(2);
```

Consult the *Setting the Properties of an ActiveX Control* section in Chapter 1, *Introduction to ComponentWorks*, for more information about setting properties programmatically.

#### **Using Methods**

Each control has defined methods that you can use in your program. To call a method in your program, use the control name followed by the method name.

```
CWAI1.Start;
```

Some methods require parameters, as does the following method.

```
CWGraph1.PlotY (data, 0.0, 1.0, True);
```

In most cases, parameters passed to a method are of type variant. Simple scalar values can be automatically converted to variants and, therefore, might be passed to methods. Arrays, however, must be explicitly declared as variant arrays.

The following example plots data using the graph PlotY method. Consult your Delphi documentation for more information about the variant data type.

```
var
    vData:Variant;
begin
    // Create array in Variant
    vData := VarArrayCreate([0, 99], varDouble);
    for i := 0 to 99 do
    begin
        vData[i] := Random;
    end;
    // Plot Variant Array
    CWGraph1.PlotY (vData, 0.0, 1.0, True);
end;
```

#### **Using Events**

Use event handler routines in your source code to respond to and process events generated by the different ComponentWorks controls. Events are generated by user interaction with an object such as a knob or by other controls (such as the DAQ controls) in response to internal conditions (for example, completed acquisition or an error). You can create a skeleton for an event handler routine using the Object Inspector in the Delphi environment.

To open the Object Inspector, press <F11> or select **Object Inspector** from the **View** menu. In the Object Inspector, select the **Events** tab. This tab, as shown in the following figure, lists all the events for the selected control. To create a skeleton function in your code window, double click on the empty field next to the event name. Delphi generates the event handler routine in the code window using the default name for the event handler.

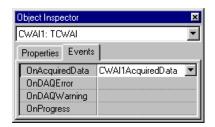


Figure 5-5. Delphi Object Inspector Events Tab

To specify your own event handler name, click in the empty field in the Object Inspector next to the event, and enter the function name. After the event handler function is created, insert the code in the event handler.

# **Learning to Use Specific ComponentWorks Controls**

Each ComponentWorks control and its use is described in more detail in later chapters in this manual. However, these chapters do not discuss every property, method, and feature of every control. The ComponentWorks online reference contains detailed information about each control and all its associated properties, methods, and events. Refer to the online reference to find descriptions of the different features of a particular control. Remember that many of the ComponentWorks controls share properties. When you learn how to use one control, you are learning how to use others.

# Using the User Interface Controls

This chapter describes how you can use the ComponentWorks User Interface (UI) controls to customize your application interface; explains the individual controls and their most commonly used properties, methods, and events; and includes tutorial exercises that give step-by-step instructions on using the controls in simple programs.

The UI controls include features commonly used in instrumentation and data acquisition. You can use them to create the front end for virtually any type of application, including finance, systems management, and many others.

In this chapter, all examples are presented in Visual Basic. Consult the appropriate chapter in this manual for information on using the ComponentWorks controls in another environment. The software includes solutions for the tutorials in Visual Basic, Visual C++, and Delphi. You can find additional information in the online reference, available by selecting Programs»National Instruments ComponentWorks» ComponentWorks Reference from the Windows Start menu.

## What Are the UI Controls?

ComponentWorks includes five separate ActiveX controls with instrumentation-style interface objects. Each of the ActiveX controls represents a family of individual control styles. Table 6-1 lists the controls and their associated styles. You can set the individual control style from the property pages during design or through properties and methods at run time.

**Control Control Style CWKnob** Knob Dial Horizontal and Vertical Meter **CWSlide** Horizontal and Vertical Slide Horizontal and Vertical Fill **ThermometerTank CWNumEdit** Numeric Edit Box **CWButton** Slide Switch Toggle Switch **Push Button Command Button Custom Bitmap Button LED CWGraph** Graph Strip Chart Scope Chart

Table 6-1. User Interface Control Styles

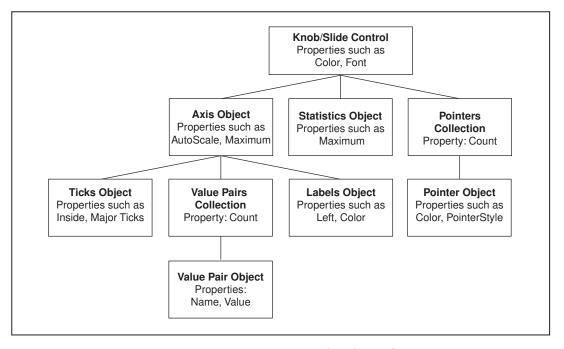
# **Object Hierarchy and Common Objects**

Most of the ComponentWorks User Interface controls are made up of a hierarchy of less complex objects. Understanding the relationship among the objects in a control is the key to properly programming with the control. Dividing a control into individual objects makes it easier to work with because each individual component has fewer parts.

## The Knob and Slide Controls

The Knob and Slide controls are similar to each other. The Knob control represents different types of circular displays, such as a knob, gauge, or different types of meters. The Slide control represents different types of linear displays, such as thermometers and tank displays. With the Knob and Slide controls, users can input or output (display) individual or multiple scalar values. A knob or slide can have multiple pointers on the control, each pointer representing one scalar value.

Like other controls, the Knob and Slide are made up of a hierarchy of objects, as shown in Figure 6-1.



**Figure 6-1.** Knob/Slide Control Object Hierarchy

#### **Knob and Slide Object**

The Knob and Slide objects maintain the basic attributes of the control, such as background color and the caption. However, its most important property is Value, which contains the value of the currently active pointer. Although the control might have more than one pointer value (each stored in an individual Pointer object), the Value property can hold only the value of the selected pointer. You can select a pointer with the ActivePointer

property or with your mouse. You access the Value property with the following code.

```
CWKnob1.Value = 5.0 x = CWSlide1.Value
```

#### **Pointers Collection**

The Pointers collection contains the individual Pointer objects of the knob or slide object. It has one read-only property, Count, which returns the number of Pointer objects in the collection.

```
NumPointers = CWSlide1.Pointers.Count
```

Like all collections, the Pointers collection also has an Item method that you use to access a specific pointer in the collection. To retrieve a pointer, call the Item method and specify the (one-based) index of the pointer in the collection.

```
CWKnob1.Pointers.Item(2)
```

Because each pointer also has a name property, you can retrieve an individual pointer with its name rather than the index.

```
CWSlide1.Pointers.Item("BoilerPressure")
```

#### **Pointer Object**

The Pointer object, which is stored in the Pointers collection, represents a single value displayed on either a knob or a slide control. The Pointer object contains properties, such as Style and FillStyle, that affect the graphical representation of the pointer. Usually, these properties are set through the property pages during design, and they do not change during program execution. If the pointer is not currently active, use its Value property to read or set its value.

```
MaxLimit = CWKnob1.Pointers.Item(3).Value
CWSlide1.Pointers.Item("BoilerPressure").Value =
   AcquiredPressure
```

#### **Axis Object**

The Axis object contains information about the axis scale used for a knob (circular scale) or a slide (straight scale) and properties, such as AutoScale, Maximum, and Minimum, that you can set and read directly.

```
CWKnob1.Axis.AutoScale = True
MaxValue = CWKnob1.Axis.Maximum
```

Use the SetMinMax method to specify a new minimum and a new maximum for the axis in one function call.

```
CWSlide1.Axis.SetMinMax newMin, newMax
```

The Axis object contains three objects—Ticks object, Labels object, and the ValuePairs collection—described in the following sections.

#### **Ticks Object**

Use the Ticks object to specify how tick marks appear on a particular axis. You can set properties to specify the spacing between ticks as well as major and minor tick selection. The Tick object also controls any grid displayed for a particular axis on the graph. Usually, Tick properties are set during design though the property pages. If necessary, you can change them at run time with simple property calls.

```
CWSlide1.Axis.Ticks.AutoDivision = False
CWKnob1.Axis.Ticks.MinorUnitsInterval = 2.0
CWGraph1.Axes.Item(1).Ticks.MajorGrid = True
```

#### **Labels Object**

The Labels object determines how axis labels are drawn. Labels are the numbers displayed next to the ticks. The Label object properties specify where to draw the labels (right, left, above, or below) and the color of the labels.

```
CWSlide1.Axis.Labels.Color = vbBlue
CWKnob1.Axis.Lables.Radial = True
CWGraph1.Axes.Item(1).Labels.Above = True
```

#### ValuePairs Collection

Use the ValuePairs collection and ValuePair objects to mark specific points on any axis with a custom label. The ValuePairs collection contains a variable number of ValuePair objects on an axis. The Count property, along with several other properties, define how value pairs appear on the axis.

```
NumMarkers = CWSlide1.Axis.ValuePairs.Count
CWKnob1.Axis.ValuePairs.LabelType = cwVPLabelName
```

The ValuePairs collection has an Item method, which you can use to access a specific ValuePair in the collection, and several other methods (Add, Remove, RemoveAll) to dynamically manipulate the collection. The

RemoveAll method deletes all objects in the collection, and the Add and Remove methods add or remove only one value pair at a time. Specify the index of the value pair to be deleted on the Remove method.

```
CWSlide1.Axis.ValuePairs.Item(2)
CWKnob1.Axis.ValuePairs.RemoveAll
CWGraph1.Axes.Item(2).ValuePairs.Remove 2
```

#### ValuePair Object

A value pair associates a symbolic name with a value and marks a specific point on an axis. You can specify whether the value pair's value or the value pair's index in the collection determines the position of the value pair on the axis and whether the graphical representation of the value pair on the axis is its name or value.

```
CWSlide1.Axis.ValuePairs.Add
n = CWSlide1.Axis.ValuePairs.Count
CWSlide1.Axis.ValuePairs.Item(n).Name = "Max"
CWSlide1.Axis.ValuePairs.Item(n).Value = 7.0
```

#### **Statistics Object**

The Statistics object provides access to statistical values stored by the Knob and Slide controls. The three calculated statistics—minimum, maximum, and mean—are updated each time a pointer value changes graphically or programmatically. Use the Reset method to reset the minimum, maximum, and mean values. After a reset, minimum and maximum values are calculated using only those values collected since the last reset. The mean is the average of the last ten values.

```
AverageMeasurement = CWSlide1.Statistics.Mean
CWKnob1.Statistics.Reset
```

Use the property pages or the Pointer mode property to continuously display any of the statistics values for a specific pointer.

#### **Events**

When the value of a pointer on the control changes from the user interface or the program, the PointerValueChanged event is fired. Usually, this event updates values in the application in response to changes on the user interface. For example, the following event handler uses a numeric edit box to digitally display the value of a slide.

```
Chapter 6
```

```
Private Sub CWSlide1_PointerValueChanged(ByVal Pointer
As Long, Value As Variant)
   NumEdit1.Value = CWSlide1.Value
End Sub
```

The Pointer specifies the index of the pointer that has a changed value. You also can use the PointerValueCommitted event to process changed values after the user moves the mouse off the control.

Consult the online reference for more information about individual properties, methods, or events.

# The Numeric Edit Box Control

Use the Numeric Edit Box control to display numbers as you would display text in a text box. Because the control includes increment and decrement buttons, you can change the value of the control with a mouse or touch screen. With range checking, you can preset a valid range for the control so the application is notified if the value is set outside of the limits. The Numeric Edit Box control has no other objects in its hierarchy. All properties and methods are contained in the control itself.

Value, the most commonly used property, reads and sets the value of the Numeric Edit Box control.

```
CWNumEdit1.Value = 5.0 x = CWNumEdit1.Value
```

With the Minimum, Maximum, and RangeChecking properties, you can configure the range checking process.

```
CWNumEdit1.Maximum = 5.0
CWNumEdit1.RangeChecking = True
```

Use the SetMinMax method to set the upper and lower limit of the range.

```
CWNumEdit1.SetMinMax -10,10
```

#### **Events**

The Numeric Edit Box control has three key events: ValueChanged, ValueChanging, and IncDecButtonClicked.

ValueChanged is fired every time the value of the control has been changed from the program or user interface.

ValueChanging is fired when the value of the control changes, before the new value is set in the control. The event returns parameters for the new value with range checking, the attempted value, and the previous value. NewValue is passed by reference so the code in the event routine can revise the value before it is set in the control. You only need to set NewValue if you want to change the value stored in the control.

```
Private Sub CWNumEdit1_ValueChanging(NewValue As Variant, ByVal AttemptedValue As Variant, ByVal PreviousValue As Variant, ByVal OutOfRange As Boolean)

If NewValue > 100 Then NewValue = NewValue + 10

End Sub
```

IncDecButtonClicked is fired when a user presses either the increment or decrement button on the numeric edit box. The event returns a Boolean parameter indicating which button was pressed.

Consult the online reference for more information about individual properties, methods, or events.

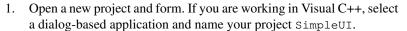
# Tutorial: Knob, Slide, and Numeric Edit Box Controls

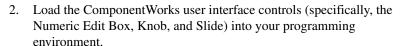
This tutorial shows you how to use the Knob, Slide, and Numeric Edit Box controls in an application. Most often, these control are used to display information or to input simple data into an application. The tutorial lists the steps necessary to integrate the controls with the program.

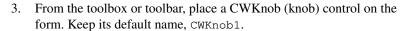
The Knob and Slide controls each have several different display styles. For example, you can display a knob as a meter or dial, and the slide as a fill, thermometer, or tank. Although each style changes the display of the control, the programmatic functionality of the control remains constant. Continue to use property sheets, event functions, and the properties and methods the same way.

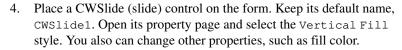
This tutorial uses Visual Basic syntax, but the discussion is in general terms so you can follow it in any compatible programming environment. Remember to adjust any code to your specific programming language. Refer to the *Building ComponentWorks Applications* chapters for information about implementing any step in different programming environments. You also can refer to the tutorial examples installed with ComponentWorks for a completed version of this example in several different programming environments.

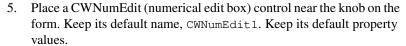
## **Designing the Form**

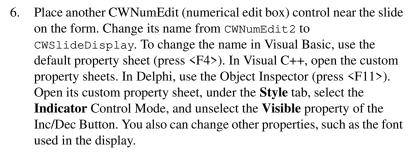












Your form should look similar to the one shown below.

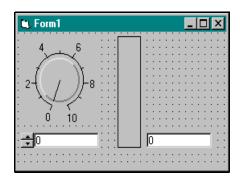


Figure 6-2. SimpleUI Form







## **Developing the Program Code**

This program uses the numeric edit box next to the slide (without the increment or decrement arrows) to display the value of the slide control. The knob is used to change the value of the slide, and the other numeric edit box is used to change the value of the knob, thereby changing the value of the slide.

To have your program respond when the slide value changes, add the PointerValueChanged event for the slide. Use the Value property to retrieve or set the current value of the controls.

- Create a skeleton event handler for the PointerValueChanged event of CWSlide1.
  - In Visual Basic, double click on the slide control on the form to create the CWKnobl\_PointerValueChanged subroutine.
  - In Visual C++, use the MFC ClassWizard to create the event handler routine. Right click on the slide control and select ClassWizard.
  - In Delphi, use the Object Inspector to create the event handler routine. Select the slide control, press <F11> to open the Object Inspector, select the **Events** tab, and double click the empty field next to the PointerValueChanged event.
- 2. Add the following code inside the event handler routine. If you are working in Visual C++, first add a member variable for each control to the application dialog class.
  - Visual Basic:
     CWSlideDisplay.Value = CWSlide1.Value
  - Visual C++:
     m\_CWSlideDisplay.SetValue(m\_CWSlide1.GetValue());
  - Delphi: CWSlideDisplay.Value:= CWSlide1.Value;
- 3. Repeat step 1 for the knob control.
- 4. Add the following code to the CWKnob1\_PointerValueChanged event routine, adjusting for your programming language:

```
CWSlide1.Value = CWKnob1.Value
```

5. Repeat step 1 for the numeric edit box (CWNumEdit1) control.

6. Add the following to the CWNumEdit1\_PointerValueChanged event routine, adjusting for your programming language:

```
CWKnob1.Value = CWNumEdit1.Value
```

7. Save the project and associated files as SimpleUI.

#### **Testing Your Program**

Run the program. Notice that the slide display and associated numeric edit box change as you turn the knob. Notice that when you change the value of the other numeric edit box (with the increment or decrement arrows), both the knob and slide value change.

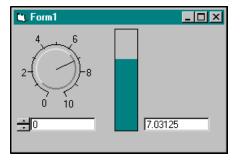


Figure 6-3. Testing SimpleUI

The program calls the CWKnob1\_PointerValueChanged function and updates the slide control every time the value of the knob changes while the mouse button is pressed. Because the slide control has its own PointerValueChanged routine, the associated numeric edit box is always updated when the value of the slide control changes. Finally, when you change the value of the other numeric edit box, its PointerValueChanged routine updates the value of the knob, calling the PointerValueChanged routine of the knob, and so on.

To call the event handler routines after releasing the mouse button from the newly selected value, use the PointerValueCommitted or MouseUp event, rather than PointerValueChanged.

## The Button Control

The Button control is a simple control you can use to input or output Boolean information or to initiate an action in your program. Because this control is simple, it is made of only one object. Like the Knob and Slide controls, the Button control has several different styles, including toggle switches, LEDs, push buttons, slides, on/off buttons and custom bitmap buttons.

The Mode property allows the button, regardless of its style, to act as a command button, switching state when you press the button with your mouse. Use this mode to initiate action in your program without changing the state of the button permanently.

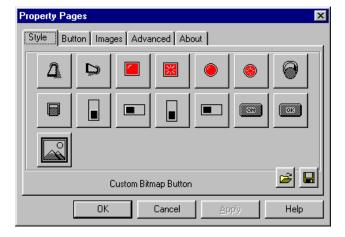


Figure 6-4. Button Control Modes

The most commonly used property on the button control is Value, which you can use to set the state of the control, such as for an LED, or to read the state of the control.

```
CWAlarmLED.Value = AlarmState
If (CWButton1.Value = True) Then...
```

Set other properties, such as OnColor, OffColor, OnText and OffText, in the property pages during development. In the property pages, you can select your own bitmaps to represent the on and off states of a custom Boolean control. For example, you can create representations of valves or heaters to depict industrial processes.

The Button control does not have any methods.

#### **Events**

The most important event generated by the Button control is ValueChanged, which notifies the application that the button value has changed. This event is generated if the button is in switch mode (switch value when clicked on) or in command mode (switch value until released).

Private Sub CWButton1\_ValueChanged(ByVal Value As Boolean)
'insert code to run when button is pressed
End Sub

# The Graph Control

The Graph control is a flexible control used for plotting and charting data. It can display multiple traces and support multiple cursors and Y axes. *Plotting* data refers to the process of taking a large number of points and updating one or more plots on the graph with new data. The old plot is replaced with the new plot. *Charting* data appends new data points to an existing plot over time. Charting is used with slow processes where only few data points per second are added to the graph. When more data points are added than can be displayed on the graph, the graph scrolls so that new points are added to the right side of the graph while old points disappear to the left. You can use the same Graph control for both charting and plotting. Select between the two operations by using different methods for displaying the data.

The Graph control is made up of a hierarchy of objects, as illustrated in Figure 6-5, used to interact with the control programmatically. At design time, you can manipulate properties of the individual objects through the property pages.

The objects in the Graph control hierarchy represent the different parts displayed on the physical representation of the graph. The three main parts are the Axes collection and Axis objects, Plots collection and Plot objects, and Cursors collection and Cursor objects. Additionally, the PlotTemplate object serves as a template for new Plot objects created in the Plots collection.

The Graph object contains the basic properties of the control, such as name, graph frame color, plot area color, and track mode.

The Axes collection and Axis objects control the different axes on the graph. The graph contains one X axis and a varying number of Y axes, all of which are contained in the Axes collection.

The Cursors collection and Cursor objects control the cursors on the graph. Usually, cursors are created at design time with the property pages. You can use cursors to mark a specific point or region on the graph or highlight something programmatically.

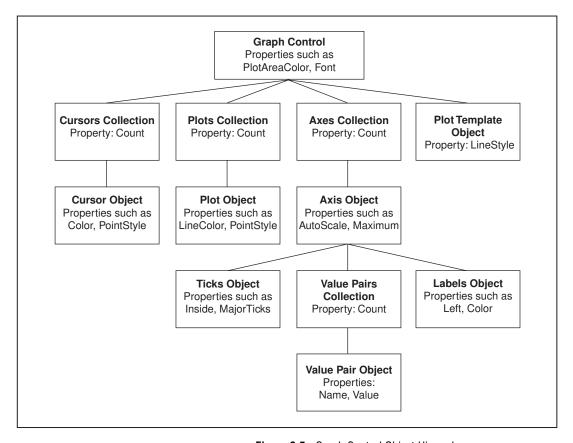


Figure 6-5. Graph Control Object Hierarchy

#### **Graph Object**

The Graph object has several simple properties, such as its name and colors, that are usually set in the property pages during design time. The Graph object also contains other properties that affect the behavior of the graph, generation of events, and some of its parts (such as the cursors), including TrackMode, ChartStyle, and ChartLength. The TrackMode property specifically determines how mouse interaction with the graph is interpreted, and it is used to implement cursors, zooming, and panning.

Several Graph control methods are called directly on the Graph object, including the Plot and Chart methods. These methods are called on the Graph object to send data to multiple plots at once and on individual Plot objects to send new data to one specific plot at a time. Use the Plot methods to update and replace all data on the plots, and use the Chart methods to append new data to the plots.

#### Plot Methods

The following three Plot methods accept data in slightly different formats:

- PlotY (yData, xFirst, xInc, bPlotPerRow) plots Y data evenly spaced on the X axis relative to the index in the array. Using the xFirst and xInc parameters, you can specify the X value at the first data point and the incremental X value between data points. yData can be a one-dimensional array that updates the first plot on the graph or a two-dimensional array that updates the first n plots on the graph. If bPlotPerRow is true, each row of the yData array is equivalent to one plot; if bPlotPerRow is false, each column of the yData array is equivalent to one plot.
- PlotXY (xyData, bPlotPerRow) plots a two-dimensional array
  of data. If bPlotPerRow is true, the first row in the data array
  contains the X data and subsequent rows contain plots of Y data.
  If bPlotPerRow is false, the first column in the data array contains
  the X data and subsequent columns contain plots of Y data.
- PlotXvsY (xData, yData, bPlotPerRow) plots a one-dimensional or two-dimensional array of Y data against a one-dimensional array of X data. If bPlotPerRow is true, each row of the yData array is equivalent to one plot; if bPlotPerRow is false, each column of the yData array is equivalent to one plot.

Depending on the programming environment, some of these parameters might be optional. If not explicitly specified, these parameters use a default value.

```
Visual Basic (Some parameters optional):
CWGraph1.PlotY Voltages

Visual C++ (All parameters required):
m_CWGraph1.PlotY (VariantArray, COleVariant(0.0),
COleVariant(1.0), COleVariant(1.0));

Delphi (All parameters required):
CWGraph1.PlotY (Voltages, 0.0, 1.0, True);
```

#### **Chart Methods**

The following three Chart methods accept data in slightly different formats:

• Charty (yData, xInc, bChartPerRow) charts Y data on one or more plots relative to the index of the data. The xInc parameter determines the X spacing between points passed to a plot. yData can be a scalar value adding one point to the first plot, a one-dimensional array adding n points to the first plot or one point to n plots, or a two-dimensional array adding multiple points to multiple plots.

If <code>bPlotPerRow</code> is true and the <code>yData</code> array is one-dimensional, all the values in the <code>yData</code> array are appended to a single plot; if <code>bPlotPerRow</code> is <code>false</code> and the <code>yData</code> array is one-dimensional, each value in the <code>yData</code> array is appended to its own plot. If <code>bPlotPerRow</code> is true and the <code>yData</code> array is two-dimensional, each <code>row</code> of the <code>yData</code> array is appended to its own plot; if <code>bPlotPerRow</code> is false and the <code>yData</code> array is two-dimensional, each <code>column</code> of the <code>yData</code> array is appended to its own plot.

- of data. If bPlotPerRow is true, the first row in the data array contains the X data and subsequent rows contain plots of Y data. If bPlotPerRow is false, the first column in the data array contains the X data and subsequent columns of Y data.
- ChartXvsY (xData, yData, bChartPerRow) charts a one- or two-dimensional array of Y data against a one-dimensional array of X data. If bPlotPerRow is true, each row of the yData array is equivalent to one plot; if bPlotPerRow is false, each column of the yData array is equivalent to one plot.

Depending on the programming environment, some of these parameters might be optional. If not explicitly specified, these parameters use a default value.

CWGraph1.ChartY VariantArray,, False

#### **Plots Collection**

The Plots collection is a standard collection containing Plot objects. The collection contains one property, Count, that returns the number of Plot objects in the collection.

NumPlots = CWGraph1.Plots.Count

Usually, all plots and their properties are defined during design in the property pages. You can use the Add, Remove, and RemoveAll methods to programmatically change the number of plots on the graph. When you add

a plot to the collection, the new plot assumes the properties of the PlotTemplate object (see *PlotTemplate Object* later in this chapter). The Remove method requires the index of the plot you are removing.

```
CWGraph1.Plots.Add
CWGraph1.Plots.Remove 3
```

Use the Item method of the Plots collection to access a particular Plot object in the collection.

```
Dim Plot1 as CWPlot
Set Plot1 = CWGraph1.Plots.Item(1)
```

## **Plot Object**

The Plot object represents an individual plot on the graph. The object contains a number of different properties that determine the display of the plot, including LineColor, LineStyle, PointColor, and FillToBase. You can set these properties during design in the property pages and change them programmatically.

```
CWGraph1.Plots.Item(1).LineColor = vbBlue
CWGraph1.Plots.Item(1).PointStyle = cwPointAsterisk
```

The following code fills the space between the first and second plot on the graph red.

```
CWGraph1.Plots.Item(1).FillToBase = True
Set CWGraph1.Plots.Item(1).BasePlot =
    CWGraph1.Plots.Item(2)
CWGraph1.Plots.Item(1).FillColor = vbRed
```

Each Plot object has a set of Plot and Chart methods similar to those of the Graph object. Calling these methods directly on the Plot object allows you to update one individual plot on the graph without affecting the other plots. For the Ploty, PlotXvsy, Charty, and ChartXvsy methods, the data arrays must be one-dimensional.

```
CWGraph1.Plots.Item(4).PlotY Voltages
CWGraph1.Plots.Item(2).ChartXvsY xData, yData
```

The protoypes for the PlotXY and ChartXY methods are as follows:

```
ChartXY (xyData, bXInFirstRow)
PlotXY (xyData, bXInFirstRow)
```

With these methods, use a two-dimensional data array with exactly two rows or two columns. If bXInFirstRow is true, the first row of the array contains the X data and the second row of the array contains a plot of Y data. If bXInFirstRow is false, the first column of the array contains the X data and the second column of the array contains a plot of Y data.

```
CWGraph1.Plots.Item(4).PlotXY xyData, True
```

For detailed descriptions of these methods, see *Plot Methods* and *Chart Methods* earlier in this chapter.

#### PlotTemplate Object

The PlotTemplate object is a special instance of a Plot object used to specify the default property values of new plots. The PlotTemplate object properties are the identical to those of the Plot object and are set through the property pages or programmatically.

The PlotTemplate property values are used as default property values for newly created plots when the Add method is called on the Plots collection. If you call the Chart or Plot method on CWGraph and pass in data for more plots than are defined in the Plots collection, the CWGraph automatically creates enough plots for all the data. For example, if you have defined only two plots and you call the PlotY method with data for five plots, the previously defined two plots receive data from the first and second rows of the array (or columns, if bPlotPerRow is false) and the three automatically created plots receive data from the remaining three rows of the array (or columns, if bPlotPerRow is false).

CWGraph1.PlotTemplate.LineColor = vbRed

#### **Cursors Collection**

The Cursors collection is a standard collection containing Cursor objects. To move the cursors with your mouse while running an application, the TrackMode property of the graph must be set to a value that supports this operation. You can find valid values in the online reference under the TrackMode topic.

The Cursors collection contains one property, Count, that returns the number of Cursor objects in the collection.

NumCursors = CWGraph1.Cursors.Count

Usually, you define all cursors and their properties during design time in the property pages. If necessary, you can use the Add, Remove, and RemoveAll methods to programmatically change the number of cursors on the graph. The Remove method requires the index of the cursor you are removing.

```
CWGraph1.Cursors.Add
CWGraph1.Cursors.Remove 3
```

Use the Item method of the Cursors collection to access a particular Cursor object in the collection.

```
Dim FirstCursor as CWCursor
Set FirstCursor = CWGraph1.Cursors.Item(1)
```

## **Cursor Object**

The Cursor object controls the position and other attributes of the individual cursors on the graph. Two frequently used Cursor object properties are XPosition and YPosition, which return or set the position of the cursor on the graph.

```
x = CWGraph1.Cursors.Item(2).XPosition
CWGraph1.Cursors.Item(1).YPosition = YLimit
```

A cursor can be associated with a specific plot on a graph. Set this association in the property pages or programmatically using the SnapMode and Plot properties of the cursor. If a cursor is associated with a specific plot, you can use the PointIndex property to set the cursor at any specific index on the plot or to return the position of the cursor on the plot. Set the SnapMode property with a predefined ComponentWorks constant.

In Visual C++ and Delphi, this constant is defined in a separate header file that you must include in your program.

#### **Axes Collection**

The Axes collection is a standard collection containing all the Axis objects of the graph. A graph has one X axis and a varying number of Y axes. You can determine the number of Y axes at design time and can change them programmatically at run time. These different Axis objects are contained in the Axes collection and can be referenced by index. Usually, the X axis is at index one, and the Y axes are at subsequent indices.

The Axes collection has the property Count, which returns the number of Axis objects in the collection.

```
NumAxes = CWGraph1.Axes.Count
```

Usually, you define all axes and their properties at design time in the property pages. If necessary you can use the Add, Remove, and RemoveAll methods to programmatically change the number of axes on the graph. The Remove method requires the index of the axis you are removing.

```
CWGraph1.Axes.Add
CWGraph1.Axes.Remove 3
```

Use the Item method of the Axes collection to access a particular Axis object in the collection.

```
Dim xAxis as CWAxis
Set xAxis = CWGraph1.Axes.Item(1)
```

## **Axis Object**

The Axis object contains all the properties of the individual axes on the graph and is identical to the Axis object used on the Knob and Slide controls. The Axis object and its parts are described in detail in the *The Knob and Slide Controls* section earlier in this chapter.

#### **Events**

The graph generates a number of different events that enable your application to react to user interaction with the graph. The graph automatically processes certain mouse actions such as panning and zooming, for which you do not need to develop any event handler routines.

The TrackMode property, which you can set through the property pages or programmatically, determines the type of events generated and other automatic processing. Some common modes on the graph generate events for mouse interaction with cursors, plots, and the plot area, as well as moving cursors and panning and zooming the graph.

To move the cursors with the mouse during program execution, set the TrackMode property to a compatible value using either the property pages or your program.

```
CWGraph1.TrackMode = cwGTrackDragCursor
```

In track mode, the graph generates the CursorChange event when any cursor moves. This event can initiate a response action in your application.

```
Private Sub CWGraph1_CursorChange(CursorIndex As Long,
   XPos As Variant, YPos As Variant, bTracking As Boolean)
   xDisplay = XPos
   yDisplay = YPos
End Sub
```

#### **Panning and Zooming**

You can use the TrackMode property to specify panning and zooming modes on the graph. Panning is useful when the graph displays only a subset of the data that has been plotted. If you enable panning, the user can scroll through all data plotted on the graph, essentially shifting the graph's display to different portions of the plot. You can enable panning for both or either of the X and Y axes.

```
CWGraph1.TrackMode = cwGTrackPanPlotAreaXY
```

Users can use zooming to enlarge or diminish a portion of the plot displayed by the graph. For example, if the user zooms on a section of a plot, the graph displays a smaller portion of the plot in the same amount of display area, which enlarges the detail of that section.

```
CWGraph1.TrackMode = cwGTrackZoomRectXY
```

# **Tutorial: Graph and Button Controls**

This tutorial shows you how to integrate the Button and Graph controls in a simple application.

The button control has several different display styles but maintains a single set of property sheets, event functions, and style of interaction with the program. You can use the Button control as an input or output. When using it as an input, create a push button or a switch to initiate an action or switch between actions. For an output, create an LED to indicate a Boolean condition.

The Graph is the most complex of the user interface objects. You can use it in two basic modes—Plot or Chart. You can select the mode by using different methods in your program to pass data to the graph.

This tutorial uses Visual Basic syntax, but the discussion is in general terms so you can follow it in any compatible programming environment. Remember to adjust any code to your specific programming language. Refer to the *Building ComponentWorks Applications* chapters for information about implementing any step in different programming environments. You also can refer to the tutorial examples installed with ComponentWorks for a completed version of this example in several different programming environments.

## **Designing the Form**

- Open a new project and form. If you are working in Visual C++, select a dialog-based application and name your project ButtonGraphExample.
- 2. Load the ComponentWorks user interface controls (specifically the Button and Graph) into your programming environment.
- 3. Place a ComponentWorks Graph control (shown at left) on the form. Keep its default name, CWGraph1. Open the Graph control property page and, in the **Axes** tab, disable autoscaling and change the X-axis range to 0 (minimum) and 20 (maximum). Examine other tabs.

For more information about some of the advanced features, refer to Chapter 12, *Building Advanced Applications*, and the online reference.





4. Place two ComponentWorks buttons (shown at left) on the form. Change their name property to Chart and Plot in the default property sheets in Visual Basic and Delphi Object Inspector or the custom property pages in Visual C++.

Chapter 6

- In the custom property pages, change each of their styles to Command Button. In the **Button** tab of the property sheets, change the On Text and Off Text to Chart for the first button and Plot for the second button.
- 5. Place another ComponentWorks button on the form. Change its name to ChartSelect. Leave its style as Vertical Toggle.
- 6. Place two Visual Basic labels next to the toggle button and change their caption properties so that the up state of the switch is labeled Scope Chart and the down state Strip Chart.

Your form should look similar to the one shown below.

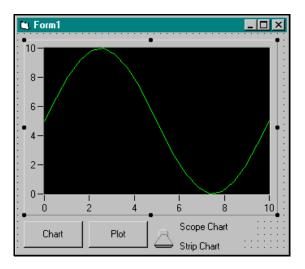


Figure 6-6. ButtonGraphExample Form



#### **Developing the Code**

Develop the code so that data is either plotted or charted on the graph in response to pressing the appropriate buttons.

1. Define an event handler routine for the **Plot** button to be called when the button is pressed. In the event handler the program creates an array of 20 points and plots it on the graph.

Generate the event handler routine for the Click event of the **Plot** button. Add the following code to the Plot\_Click subroutine. In Visual C++, remember to generate member variables for any controls referenced in the program. See the online tutorial programs for Visual C++ and Delphi code examples.

```
Private Sub Plot_Click()
   Dim data(0 To 20) As Double
   CWGraph1.Axes.Item(1).Maximum = 20
   CWGraph1.Axes.Item(1).Minimum = 0
   For i = 0 To 20
        data(i) = Rnd * 10#
   Next i
   CWGraph1.PlotY data, 0, 1, True
End Sub
```

This code generates an array of 20 random numbers. The PlotY method then replaces any data on the plot and plots the new data starting at zero on the X axis. To ensure that the new data appears on the graph, the minimum and maximum values of the X axis (CWGraph1.Axes.Item(1)) are reset to 0 and 20. This routine uses a one-dimensional array with the PlotY method to generate one trace. You also can use a two-dimensional array to generate multiple traces.

 Generate the event handler routine for the Click event of the Chart button, which charts some random data on the graph when pressed.
 Add the following code to the Chart\_Click subroutine:

```
Private Sub Chart_Click()
   Dim data As Double
For i = 0 To 59
    data = Rnd * 10#
    CWGraph1.ChartY data, 1, True
   Next i
End Sub
```

The Chart\_Click subroutine performs a similar action to Plot\_Click, except that Chart\_Click generates random points and charts them individually. When the ChartY method is called, it appends the new data to the data already on the graph. If you add only one point at a time, you can use a scalar value or a one-dimensional array to pass multiple points to the trace. Use a two-dimensional array to chart multiple traces.

3. The ChartStyle property on the graph sets the charting style. This example uses the toggle switch to switch between the two charting styles. To have your program respond when the user switches styles, add the ChartSelect\_ValueChanged event handler routine for the switch. Use the Value property of the switch to retrieve or set the current value of the control.

Generate the event handler routine for the ValueChanged event of the switch. Add the following code. In Visual C++ and Delphi, include the appropriate header files to define the constant values.

```
Private Sub ChartSelect_ValueChanged(ByVal Value
As Variant)
   If ChartSelect.Value = True Then
        CWGraph1.ChartStyle = cwChartScope
   Else
        CWGraph1.ChartStyle = cwChartStrip
   End If
End Sub
```

4. Save the project and form as ButtonGraphExample.

#### **Testing Your Program**

Run and test the program. Notice the difference between the Plot, Strip Chart, and Scope Chart options.

Ploty and Charty are the two most common methods for passing data to the graph. However, there are two more Plot methods (PlotXY and PlotXvsY) and two more Chart methods (ChartXY and ChartXvsY) that affect how data is displayed on the graph. For more information about these methods, see *The Graph Control* earlier in this chapter or the online reference. Refer to Chapter 12, *Building Advanced Applications*, for more information about advanced graph features such as cursors and multiple axes.

7

# Using the Data Acquisition Controls

This chapter describes how you can use the ComponentWorks Data Acquisition (DAQ) controls in your application to perform input and output operations using your DAQ hardware. It explains the individual controls and their most commonly used properties, methods, and events and includes tutorials that give step-by-step instructions on using the controls in simple programs.

Refer to the *Building ComponentWorks Applications* chapters for information about using the ComponentWorks controls in different programming environments. Use the online reference (available by selecting **Programs»National Instruments ComponentWorks» ComponentWorks Reference** from the Windows **Start** menu) to find information about each control and its properties, methods, and events.

# What Are the Data Acquisition Controls?

Use the DAQ controls to program your DAQ hardware. ComponentWorks includes nine ActiveX controls for performing DAQ operations as well as a utility control that contains other DAQ support functions. Each control is

used for one specific type of operation such as analog input, analog output, and so on. The following is a list of the DAQ controls:

| DAQ Control | Operation                                   |
|-------------|---|
| CWAIPoint   | Single Point Analog Input                   |
| CWAI        | Waveform Analog Input                       |
| CWAOPoint   | Single Point Analog Output                  |
| CWAO        | Waveform Analog Output                      |
| CWDIO       | Single Point Digital Input/Output           |
| CWDI        | Waveform Digital Input                      |
| CWDO        | Waveform Digital Output                     |
| CWCounter   | Data Acquisition Counter Functions          |
| CWPulse     | Data Acquisition Pulse Generation Functions |
| CWDAQTools  | Data Acquisition Utilities                  |

You can set most properties through property pages as you design your program. Property pages are the best place to become familiar with the different properties of a control. In certain cases, you might need to change the value of one or more properties in your program code. Throughout this chapter, examples demonstrate how to change property values programmatically.

# **Data Acquisition Configuration**

Before you can use your National Instruments data acquisition hardware with the ComponentWorks DAQ controls you must configure your DAQ device using the NI-DAQ driver configuration utility. Make sure that you follow the directions in the NI-DAQ driver documentation (online) to properly configure the hardware. You also can test the hardware and perform simple input/output operations with the configuration utility. Once a data acquisition device is configured, it is assigned a device number that you use to reference the device in your application. Select the device and device number in the property pages of each control.

# **Object Hierarchy and Common Properties**

Some of the ComponentWorks Data Acquisition controls are made up of a hierarchy of less complex individual objects. Understanding the relationship among the objects in a control is the key to properly programming with the control. Dividing a control into individual objects makes it easier to work with because each individual component has fewer parts.

The top-level object of each DAQ control shares common properties, as described in the following sections.

# Device, DeviceName, and DeviceType

Each control has a Device property that you use to select the hardware device used by the control. You can set this property from a pulldown menu in the property pages of each control, or you can set it programmatically.

```
CWAI1.Device = 2
```

DeviceName and DeviceType are read-only properties that return the name and type number of the selected device. The name of a device is its descriptive name, such as AT-MIO-64E-3. The type number is a unique number assigned to each hardware device type in the NI-DAQ driver. You can use these properties to control the execution of your application.

```
If CWAI1.DeviceType = 16 Then...
```

#### **Channel Strings**

Most DAQ controls have a channel string property in their object hierarchy. Use the channel string to specify which channels on a data acquisition device are used by a particular operation. If you use only one channel, enter the channel number in the string.

```
CWAOPoint1.ChannelString = "1"
```

In many cases, you must specify more than one channel in a channel string. If you want to specify a series of consecutive channels, specify the first and last channel in your list separated by a colon.

```
CWAI1.Channels.Item(1).ChannelString = "1:4"
'Specifies channel 1, 2, 3, and 4
```

You also can specify a reverse list of consecutive channels.

```
CWAI1.Channels.Item(1).ChannelString = "6:3"
'Specifies channels 6, 5, 4, and 3
```



Certain DAQ devices require that a multiple channel acquisition use a reverse list of consecutive channels ending with channel 0. These devices include all 500-, 700-, and 1200-series devices, as well as the Lab and LPM series cards.

```
CWAI1.Channels.Item(1).ChannelString = "3:0"
```

You can specify non-consecutive channels in a channel string by listing each channel separated by commas.

```
CWAIPoint1.Channels.Item(1).ChannelString = "0,1,3,5"
```

## **SCXI Channel Strings**

By using a different channel string to specify your channels, you can use the ComponentWorks DAQ controls with SCXI signal conditioning hardware. To configure channels on an SCXI module, set the <code>Device</code> property to the number of the DAQ board directly or indirectly connected to the desired SCXI module. The channel string(s) of your controls include information about the DAQ device channel, SCXI chassis number, SCXI module number, and SCXI channel number. The string has the following format.

```
oba!scx!mdy!z
```

In the SCXI channel string, a represents the DAQ device (onboard) channel used for the acquisition (with analog input channels only),  $\times$  represents the chassis number, y the module number, and z the channel number on the SCXI module. The onboard channel number usually is one less than the chassis number.

```
CWAIPoint1.Channels.Item(1).ChannelString =
  "ob0!sc1!md1!0"
'Specifies channel 0 on module 1 in chassis 1
```

You can specify multiple channels on an SCXI module in a consecutive list.

```
CWAI1.Channels(1).ChannelString = "ob0!sc1!md3!1:5"
'Specifies channel 1 through 5 on module 3 in chassis 1
```

Other combinations are listed in the following table.

| String Syntax     | Description   |
|-------------------|---|
| ob0!sc1!md2!5     | Channel 5 on module 2 of SCXI chassis 1 read through onboard Channel 0.         |
| ob0!sc1!md2!0:7   | Channels 0 through 7 on module 2 read through onboard Channel 0.                |
| ob1!sc2!md1!20:24 | Channels 20 through 24 of module 1 on chassis 2 read through onboard Channel 1. |

Note 🕝

All lines on a digital SCXI module are grouped into a single port. The SCXI channel string for digital lines refer to this port 0 only. For example, sc1!md3!0.

#### **ExceptionOnError and ErrorEventMask**

DAQ controls handle error checking in a number of different ways. By default, each DAQ control generates an exception that your programming environment handles when an error occurs. You can disable the generation of exceptions by setting the <code>ExceptionOnError</code> property to false. If exceptions are disabled, each call to a DAQ control method returns an error code. If the code is equal to zero, the operation completed normally. If the value is non-zero, either a warning or error occurred and the application should handle the condition.

Another type of error notification is the generation of error and warning events in response to error conditions. Each event calls a corresponding event handler routine that processes the error information. Use the ErrorEventMask property on each DAQ control to limit the error and warning event generation to specific operations (contexts) of the DAQ controls. For example, by default the AI control generates an error event only during the following contexts: cwaiReadingData, cwaiReadingDataContinuous, and cwaiReadingDataSWAnalog.

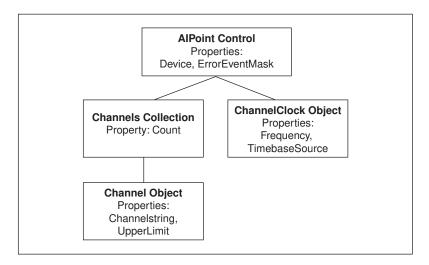
These contexts refer to asynchronous operations, which mean the AI control is in the process of acquiring data and returning it to the application. Other contexts, such as <code>cwaiStartingAcquisition</code> or <code>cwaiConfiguringChannels</code>, do not generate error events by default. To select which contexts generate error events, add the values of the <code>CWAIErrorContexts</code> constants and assign the sum to the <code>ErrorEventMask</code> property.

CWAI1.ErrorEventMask = cwaiReadingData +
cwaiReadingDataContinuous + cwaiReadingDataSWAnalog +
cwaiStartingAcquisition

Error handling is discussed in more detail in Chapter 12, *Building Advanced Applications*.

# **AlPoint Control—Single Point Analog Input**

Use the AIPoint control to acquire one point of data from one or more analog input channels at a time to monitor slowly changing processes, such as temperature. After you set the properties of the control, the application can acquire a single scan of data using a simple method call to the AIPoint control. A *scan* is defined as an acquisition of one point from each channel in the channel list.



**Figure 7-1.** AlPoint Control Object Hierarchy (Single Point Analog Input)

The object hierarchy of the AIPoint control contains a Channels collection with Channel objects and a ChannelClock object.

#### **AlPoint Object**

In addition to the default properties of each DAQ control, the AIPoint object has one more property, ReturnDataType, that determines whether the acquired data is returned to the application as voltage data, binary values, or both.

The AIPoint object has two methods, SingleRead and Reset. The SingleRead method performs a single scan using the values set in the control properties. The SingleRead method has two variant parameters: data and an optional parameter, TimeLimit, which specifies the time limit for the acquisition.

```
Dim data as Variant CWAIPoint1.SingleRead data, 1.0
```

The data variable must be a variant and is assigned the values read. The data is returned in the format specified by the ReturnDataType property, either as a scalar or one-dimensional array.

When you call the SingleRead method, the hardware is configured using the values set in the control's properties. This configuration is done only when necessary, such as calling SingleRead the first time or after changing any of the properties. You also can unconfigure the control manually using the Reset method. The control then configures the hardware on the next acquisition.

CWAIPoint1.Reset

#### **Channels Collection**

The Channels collection exists on all analog input and analog output DAQ controls, except the CWAOPoint control. This collection contains the individual Channel objects that determine which hardware channels are used by the control. The collection has a read-only property, Count, that returns the number of Channel objects in the collection.

```
NumChanObjects = CWAIPoint1.Channels.Count
```

You can get the value of the read-only property NChannels after a control has been configured. NChannels returns the total number of channels used by the control. The value returned from this property is valid only when the control is configured, which you can do using the Configure or SingleRead method of the respective control.

```
NumChannels = CWAIPoint1.Channels.NChannels
```

Like all collections, the Channels collection has an Item method you use to access a particular Channel object in the collection. To retrieve a Channel object, call the Item method and specify the (one-based) index of the channel in the collection.

```
CWAIPoint1.Channels.Item(2)
```

In this way, you can programmatically change properties of individual Channel objects. The Channels collection contains several methods that you can use to modify the number of Channel objects in the collection. The RemoveAll method clears the collection of all Channel objects. Use the Remove method to delete individual Channel objects. The Add method adds a new Channel object to the collection.

```
CWAIPoint1.Channels.Remove 1
CWAIPoint1.Channels.Add "1", 10, -10, cwaiDIFF, cwaiDC
```

## **Channel Object**

Each Channel object contains information about one or more channels used by a DAQ control. The individual Channel object contains properties such as ChannelString, InputMode, UpperLimit, and LowerLimit. For example, the ChannelString property specifies which channels are affected by the Channel object, while the remaining properties determine how the channels are used. You can read and set these properties programmatically.

```
CWAIPoint1.Channels.Item(1).ChannelString = "0,1"
MaxVolts = CWAIPoint1.Channels.Item(1).UpperLimit
```

## **ChannelClock Object**

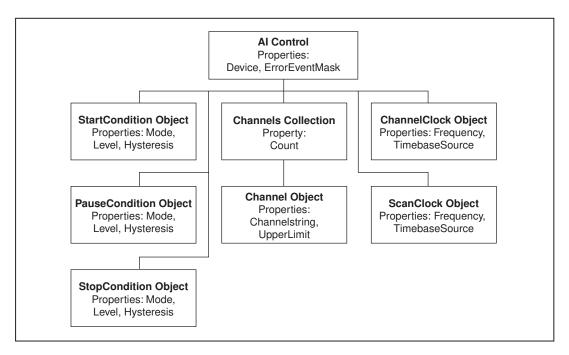
The ChannelClock object determines the timing that the AIPoint control uses in the actual analog-to-digital conversions within a scan. Use it to increase the delay between the acquisitions of different channels or to synchronize conversions with an external signal. The ChannelClock object directly affects the conversions by allowing you to select either an internal source and frequency or an external source and exact description of the signal source, such as an I/O pin or RTSI pin.

By default, ComponentWorks chooses channel clock settings that should work for most applications. You usually configure the ChannelClock in the property pages, but you might need to change its settings from your program. For example, you can switch to frequency mode and change the frequency setting.

```
CWAIPoint1.ChannelClock.ClockSourceType =
   cwaiInternalCS
CWAIPoint1.ChannelClock.Frequency = 10000
```

Use the AI control to perform waveform analog input operations including single shot and continuous acquisitions. With the AI control, you can acquire data from one or more channels at a time and configure many different modes, such as start and stop triggers, pause conditions, and different channel and scan clocks. Use this control for any application that requires fast acquisition of multiple points per channel, such as frequency analysis. After the properties of the control are set, the application can perform acquisitions using a number of simple method calls.

The object hierarchy of the AI control separates the functionality of the control into individual objects. The Channels collection and Channel objects specify the channels and channel attributes used for the acquisition. The condition objects specify when an acquisition starts, pauses, or stops. The clock objects specify the rate of the acquisition.



**Figure 7-2.** Al Control Object Hierarchy (Waveform Analog Input)

### Al Object

Along with the default properties of the DAQ controls, the AI object has other properties. One property is ReturnDataType, which determines whether the acquired data is returned to the application as voltage data, binary values, or both. The NScans property (number of scans to acquire) specifies the number of scans acquired in a single-shot acquisition or the number of scans returned at a time in a continuous acquisition.

CWAI1.NScans = 5000

If the UseDefaultBufferSize property is set to False, the NScansPerBuffer property determines the size of the acquisition buffer; otherwise ComponentWorks automatically selects the buffer size.

The AI control uses the Channels collection and Channel object in the same manner as the AIPoint control. See the *AIPoint* section earlier in this chapter for more information about these objects. Consult the online reference for more information about the individual properties, methods, or events of the AI object or any of its underlying objects.

### **Methods and Events**

The AI control has a number of simple methods for running the different acquisition processes. The normal and recommended acquisition type is an asynchronous acquisition, which is controlled using four different method calls and offers the most flexibility and control over the acquisition. Alternatively, in environments that do not support event handler routines, you can use an additional method to perform a synchronous acquisition.

### **Asynchronous Acquisition**

The methods to perform an asynchronous acquisition are Configure, Start, Stop, and Reset. Use these methods to control the acquisition. These methods do not require any parameters because acquisition parameters are set through the control properties.

Use the Configure method to configure the DAQ driver and hardware with the acquisition parameters. Configure must be called before the Start method. Use the Start method to start the acquisition. Use the Stop method only during a continuous acquisition to stop such an acquisition. Use the Reset method to unconfigure the AI control and free any resources reserved during configuration. You also must call the Configure method after you change any of the control properties so that they can take effect and after you call the Reset method so that you can restart the acquisition.

```
Private Sub StartAcquisition_Click()
        CWAI1.Configure
        CWAI1.Start
End Sub
Private Sub StopAcquisition_Click()
        CWAI1.Stop
End Sub
Private Sub ResetAcquisition_Click()
        CWAI1.Reset
End Sub
```

The AI control returns data from an asynchronous acquisition by generating an AcquiredData event. The acquired data is returned as arrays, ScaledData and/or BinaryCodes, passed to the event handler. You can process the data inside the event handler by displaying it on a graph or writing it to a file.

```
Private Sub CWAI1_AcquiredData(ScaledData As Variant,
BinaryCodes As Variant)
    CWGraph1.PlotY ScaledData
End Sub
```

You also can use the Read method on the AI control to read data from an ongoing acquisition without events. Specify how many points to read from the acquisition and supply a variant variable to return the data. You also can use another variable of type CWAIReadSpec to specify and return additional information about the acquisition.

```
Private Sub Start_Click()
    CWAI1.Configure
    CWAI1.Start

End Sub

Private Sub Read_Click()
    Dim ReadSpec As New CWAIReadSpec
    Dim data As Variant
    CWAI1.Read 100, data, ReadSpec
End Sub
```

### **Synchronous Acquisition**

Certain programming environments do not support event handler functions and are therefore not suited for running an asynchronous acquisition. In such cases, the AI control can perform a synchronous acquisition using the AcquireData method. The AcquireData method requires you to pass in

two variables for the scaled and binary data, which are used to return the acquired data at the completion of the acquisition.

You must call the Configure method before calling AcquireData, and you cannot run a continuous acquisition using this method. Because the AcquireData method takes control of the program until the acquisition is completed, you also can specify a timeout parameter in seconds that forces the method to return in the time limit specified.

```
Private Sub RunAcquisition_Click()

Dim Voltages As Variant

Dim BinaryCodes As Variant

CWAI1.Configure

CWAI1.AcquireData Voltages, BinaryCodes, 5

'timeout is 5 seconds

CWGraph1.Ploty Voltages

End Sub
```

### **Error Handling**

The AI control also has DAQError and DAQWarning events that can be used for error handling.

```
Private Sub CWAI1_DAQError(ByVal StatusCode As Long,
   ByVal ContextID As Long, ByVal ContextDescription As
   String)
   MsgBox "DAQ Error: " + CStr(StatusCode)
End Sub
```

## ScanClock and ChannelClock Objects

The AI control contains both a ScanClock and ChannelClock object to specify the scan rate and interchannel delay. These two settings apply if you acquire multiple points of data from more than one channel. In this type of operation, the data acquisition device performs repeated scans, in which one scan is an acquisition of one data point from each channel in the channel list. The timing within one scan is called the *interchannel delay*, and the ChannelClock object automatically selects it. The rate at which scans are acquired is called the *scan rate* and is set in the ScanClock object. The effective acquisition rate per channel (the rate at which points on one channel are acquired) is also the scan rate.

The ScanClock object is critical to the operation of the AI control and you must set it for most applications. In common operations, specify an internal frequency and set the acquisition (scan) rate in the property pages. More complex operations can include specifying an external source for the

ScanClock to synchronize the acquisition with another process. You can specify these settings in the property pages or programmatically. After the control is configured, you can read back the actual frequency or period used for the acquisition.

```
CWAI1.ScanClock.Frequency = 200
CWAI1.Configure
ScanPeriod = CWAI1.ScanClock.ActualPeriod
```

### StartCondition, PauseCondition and StopCondition Objects

The StartCondition, PauseCondition, and StopCondition objects control when an acquisition starts, pauses, and stops. The main property of the Condition object is Type, which sets the overall operation of the object. The value of the Type property determines which of the remaining properties on the Condition object are used.

Certain condition types are supported only by specific hardware. Verify that your data acquisition device supports the desired operation. For example, all hardware analog conditions require specific analog trigger circuitry on the acquisition device.

The StartCondition object controls when an acquisition is started. By default (Type set to cwaiNoActiveCondition) the acquisition is started immediately after the corresponding method call.

```
CWAI1.StartCondition.Type = cwaiNoActiveCondition
```

You can set the StartCondition to start the acquisition on a digital or analog trigger. In such cases, the hardware is set to start on the corresponding software call, but actual conversions do not start until the digital or analog trigger arrives. You can set trigger conditions either in the property pages or programmatically.

```
CWAI1.StartCondition.Type = cwaiHWAnalog
CWAI1.StartCondition.Level = 5
CWAI1.StartCondition.Hysteresis = 0.1
CWAI1.StartCondition.Source = 1
CWAI1.StartCondition.Mode = cwaiRising
```

The PauseCondition object controls when an ongoing acquisition is paused, which might be done in response to an external digital or analog signal with a limited number of data acquisition devices. The Type property can have the following settings: None, Hardware Digital Gate, and Hardware Analog Gate. The remaining properties of the PauseCondition specify

specific pause conditions. You can pause the acquisition while above or below a specific analog level (high and low for digital) or while inside or outside a specific analog window.

```
CWAI1.PauseCondition.Type = cwaiHWAnalog
CWAI1.PauseCondition.Mode = cwaiInside
```

The StopCondition object controls when the acquisition is stopped. The default mode is to stop after the acquisition buffer, set by the NScans property on the AI control, has been filled once. You also can select to run a continuous acquisition so the acquisition stops only on a user command or when an error occurs. Other advanced options include stopping on a hardware digital or analog signal or a software analog condition (single shot or continuous). These last three types also support pretrigger scans, which means you can specify to acquire a number of points before the stop condition and the remainder after the stop conditions. The remaining properties are similar to the StartCondition and PauseCondition objects.

The software analog trigger type on the StopCondition supports analog triggering on devices that do not have an explicit hardware analog trigger circuit. In this mode, data is continuously acquired from the data acquisition device but returned only when it matches the specified conditions. This mode behaves similarly to a hardware analog start trigger, and you can run it, either as a one-shot or continuous acquisition. The continuous software analog trigger makes it easy for you to duplicate the operation of an oscilloscope in your application.

## Tutorial: Using the AlPoint and Al DAQ Controls

This tutorial shows you how to use the AIPoint and AI controls in a simple program to acquire one scan of data from several channels using the AIPoint controls, how to perform a simple waveform acquisition using the AI control, and how to display the data on a graph.

This tutorial uses Visual Basic syntax, but the discussion is in general terms so you can follow it in any compatible programming environment. Remember to adjust any code to your specific programming language. Refer to the *Building ComponentWorks Applications* chapters for information about implementing any step in different programming environments. You also can refer to the tutorial examples installed with ComponentWorks for a completed version of this example in several different programming environments.

- 1. Open a new project and form. If you are working in Visual C++, select a dialog-based application and name your project AIExample.
- 2. Load the ComponentWorks User Interface controls (specifically, the Graph, Button, and Numeric Edit Box) and the Data Acquisition controls (specifically, the AIPoint and AI controls) into your programming environment.
- 3. Place an AIPoint and AI control on your form. You configure their properties in the next section.
- 4. Place a ComponentWorks Graph control on the form. Keep its default name CWGraph1.
  - For information about advanced features of the Graph control, refer to Chapter 12, *Building Advanced Applications*, and the online reference.
- 5. Place two ComponentWorks Numeric Edit Boxes on the form. Keep their default names, CWNumEdit1 and CWNumEdit2.
- 6. Place two ComponentWorks buttons on the form. Change their Name property to Acquire and Start in the default property sheets in Visual Basic and Delphi or the custom property pages in Visual C++.
  - In the custom property pages, change the style of both buttons to Command Button. Also, in the **Button** tab of the property pages, change the **On Text** and **Off Text** to Acquire for the first button and Start for the second button.

Your form should look similar to the one shown below.

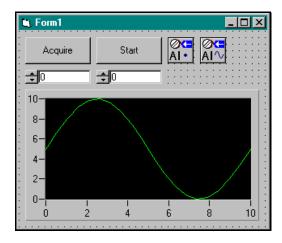


Figure 7-3. AlExample Form







### **Setting the DAQ Properties**

You normally configure the default property values of the different controls before you develop your program code. When using the DAQ controls, most or all properties are set during design and do not change during program execution. Method calls in your program start and stop the acquisition processes. If necessary, you can set the properties of the DAQ controls at run time.

- Open the custom property pages for the AIPoint control on the form by right clicking on the control and selecting **Properties...**. In the **Channels** tab, select your data acquisition device from the pulldown menu. Click the **New** button to add a new Channel object and set it to channels 0 and 1. Do this by entering "0, 1" in the **Channels** field. The new channels are displayed in the channel list on the left side. Close the AIPoint property pages. If necessary, reverse the order of the channels for your DAQ device. See the *Channel Strings* section earlier in this chapter for more information.
- 2. Open the custom property pages for the AI control on the form. In the Channels tab, select your data acquisition device from the pulldown menu. Click the New button to add a new Channel object and set it to channel 1. Do this by entering "1" in the Channels field. The new channels are displayed in the channel list on the left side. In the Clocks tab, change the scan rate (Scans/second) to 1000. Close the AI property pages.

### **Developing the Code**

Next, you develop the code so that data is acquired and displayed when the buttons are pushed.

1. For the **Acquire** button, define an event handler routine to be called when the **Acquire** button is pressed. In the event handler, acquire one scan of data (one point each from Channel 0 and 1) and display the two points in the numeric edit boxes.

Generate the event handler routine for the Click event of the Acquire button. In the event handler, declare a variable as a Variant. Pass this variable to the SingleRead method of the AIPoint control. Then display the data returned in the first variable in the numeric edit boxes. Add the following code to the Acquire\_Click subroutine. In Visual C++, remember to generate member variables for any controls referenced in the program. See the tutorials folder for Visual C++ and Delphi code examples.

The following code acquires a scan from Channels 0 and 1 using the SingleRead method and returns the data in a one-dimensional array (Volts). The two values are copied to the numeric edit boxes to be displayed.

```
Private Sub Acquire_Click()
    Dim Volts As Variant
    CWAIPoint1.SingleRead Volts, 1
    CWNumEdit1.Value = Volts(0)
    CWNumEdit2.Value = Volts(1)
End Sub
```

2. For the **Start** button, define an event handler routine to be called when the **Start** button is pressed. In the event handler, start an asynchronous acquisition on the AI control. Because the acquisition is asynchronous, the program regains control immediately after the acquisition is started, while the acquisition continues to run in the background.

Generate the event handler routine for the Click event of the **Start** button. In the event handler, call the Configure and Start methods of the AI control. Add the following code to the Start\_Click subroutine. In Visual C++, remember to generate member variables for any controls referenced in the program. See the Tutorial folder for Visual C++ and Delphi code examples.

The following code starts the acquisition and then returns control to the program.

```
Private Sub Start_Click
    CWAI1.Configure
    CWAI1.Start
End Sub
```

3. The AI control fires an AcquiredData event when it is ready to return the acquired data. You must generate the corresponding event handler to receive and process the data. In this example, plot the data on a graph. Use the PlotY method of the Graph control to display the returned ScaledData array.

Generate the event handler for the AcquiredData event of the AI control and add the following line of code.

```
Private Sub CWAI1_AcquiredData(ScaledData As
  Variant, BinaryCodes As Variant)
    CWGraph1.PlotY ScaledData, 0, 1, 1
    CWAI1.Reset
End Sub
```

4. Save the project and form as AIExample.

### **Testing Your Program**

Run and test the program. Click on the **Acquire** and **Start** buttons to perform the acquisitions. Your application should look similar to the following figure. The exact data displayed on the graph depends on the signal connected to your data acquisition board.

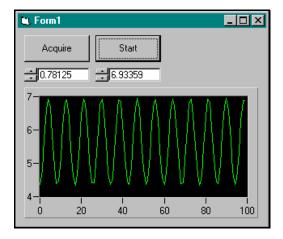


Figure 7-4. Testing AlExample

You can enhance the waveform acquisition performed in this example by defining more properties of the AI control. For example, you can perform a continuous acquisition by setting the Type property of the AI control StopCondition object to Continuous on the Conditions tab of the AI control property pages. In continuous mode, the acquisition continues and repeatedly returns the specified number of points in the DataAcquired event. The AI control has a Stop method you can call to stop a continuous acquisition.

## AOPoint Control—Single Point Analog Output

Use the AOPoint control to update one or more analog output channels for slow process control systems, such as setting a control output (for example, the power of a heater or throughput of a valve). After you set the properties of the control, the application can update the configured channels using a simple method call to the AOPoint control.

#### **AOPoint Control**

Properties: Device, ErrorEventMask, ChannelString

Figure 7-5. AOPoint Control Object Hierarchy (Single Point Analog Output)

The AOPoint control contains no other objects. All properties of the control are part of the top-level object.

### **AOPoint Object**

The AOPoint object has several unique properties that determine the operation of the control.

The ChannelString property, together with the UpperLimit, LowerLimit, Reference Source, and ChannelType properties, control the AOPoint output. You usually configure these properties through the property pages, but you also can set them programmatically.

```
CWAOPoint1.ChannelString = "0,1"
CWAOPoint1.UpperLimit = 10.0
```

#### Methods

The AOPoint object has two methods: SingleWrite and Reset. The SingleWrite method performs a single update on channels configured for the control. The SingleWrite method has two variant parameters, Values and Scaled.

Use the Values parameter to pass the analog values to the method to be generated by the analog output channels. Use the optional Scaled parameter to specify whether the analog values are passed as scaled or binary data. By default, the information is interpreted as voltage data.

```
'Update one channel
CWAOPoint1.ChannelString = "0"
CWAOPoint1.SingleWrite 5.0, True
'Update two channels
Dim VoltsArrayData(0 to 1)
CWAOPoint2.ChannelString = "0,1"
VoltsArrayData(0) = 3.2
VoltsArrayData(1) = 6.5
CWAOPoint2.SingleWrite VoltsArrayData, True
```

You can send the output data to the SingleWrite method as a scalar value for updating one channel or as a one-dimensional array of values for updating more than one channel.

When you call the SingleWrite method, the hardware is configured using the values set in the control properties. This configuration is done only when necessary, such as when SingleWrite is called the first time or after changing any of the properties. You also can unconfigure the control manually using the Reset method, which causes the control to configure the hardware on the next SingleWrite method call.

CWAOPoint1.Reset

## **AO Control—Waveform Analog Output**

Use the AO control to perform waveform generation operations from one or more analog output channels on a data acquisition device. The waveform generation can be run in a continuous or finite mode. You can configure properties on the control such as the channels used for the waveform generation, the frequency (update clock), and the start condition or trigger. This control is used for applications that require dynamic analog signals, such as testing of analog devices. After you set the properties of the control, the application can perform output operations using a number of simple method calls.

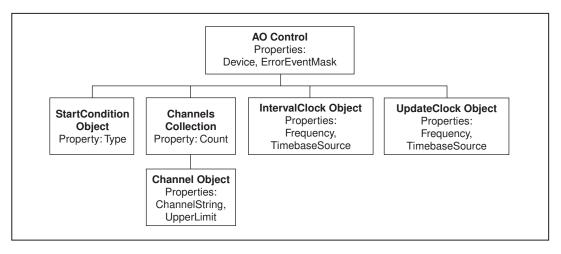


Figure 7-6. AOPoint Control Object Hierarchy (Waveform Analog Output)

The object hierarchy of the AO control separates the functionality of the control into individual objects. The Channels collection and Channel

objects specify the channels and channel attributes used for the signal generation. The StartCondition object specifies when a signal generation starts, and the Clock objects specify the rate of the output.

## **AO Object**

Use the AO object to set default properties for the DAQ controls as well as other properties. The generated waveform data is stored in a buffer in memory. The NUpdates property specifies how many updates are stored in the buffer. The Infinite property is a Boolean that selects whether a waveform generation runs continuously or stops after a finite number of buffer outputs. In a finite generation, the NIterations property specifies how often the data in the buffer is generated.

```
CWA01.Infinite = False
CWA01.NIterations = 10
```

The data buffer usually is stored in computer memory. With certain data acquisition devices, you might be able to store the data in memory on the DAQ device itself to enable faster output of the waveform. You can select this type of operation using the AllocationMode property.

While a waveform generation is running, the AO control can generate events to notify you of the progress of the output operation. Use the ProgressInterval property to specify the frequency at which these events are generated in number of updates.

The AO control uses the Channels collection and Channel object the same way as the AIPoint control.

### **Methods and Events**

The AO control has a number of methods for performing waveform generation operations, including Configure, Write, Start, and Reset. These methods control the output operations. Only the Write method requires parameters.

Use the Configure method to configure the DAQ driver and hardware with the operation parameters. Use the Write method to write an array of voltage data to the buffer in memory before the data can be generated from the analog output channels. Set all other parameters through the properties of the control.

You must call Configure before the Write and Start methods. Use the Start method to start the waveform generation that proceeds indefinitely

or stops after the specified number of buffer generations. Use the Reset method to stop a continuous generation, unconfigure the AO control, and free any resources reserved during configuration.

You must call the Configure method after any of the control properties are changed before they can take effect and after the Reset method is used before restarting a waveform generation.

```
Private Sub Start_Click()
    Dim WaveData(0 to 99) As Double
    For i = 0 To 99
        WaveData(i) = Sin(i / 100 * 6.28)
    Next i
    CWAO1.Configure
    CWAO1.Write WaveData
    CWAO1.Start
End Sub
Private Sub Stop_Click()
    CWAO1.Reset
End Sub
```

The AO control fires the Progress event while the output operation is running. The event notifies your application that a specific number of updates has been performed on the output. Set the frequency at which the event is generated in the ProgressInterval property. You can use the event to update your front panel to check the progress of the waveform generation.

```
Private Sub CWAO1_Progress(ByVal ScansGenerated As Long)
    Text1.Text = ScansGenerated
End Sub
```

The AO control also has DAQError and DAQWarning events you can use for error handling.

```
Private Sub CWA01_DAQError(ByVal StatusCode As Long,
   ByVal ContextID As Long, ByVal ContextDescription
   As String)
   MsgBox "DAQ Error: " + CStr(StatusCode)
End Sub
```

### UpdateClock and IntervalClock Objects

The AO control contains both an UpdateClock (commonly used) and IntervalClock (rarely used) object to specify the update rate and optional interval delay. The UpdateClock object specifies the rate at which data

points are generated by the boards. Because each output channel has its own digital-to-analog (DAC) converter, there is no delay between updates from different channels and all channels are updated simultaneously.

You can set the update clock to use an internal frequency, a signal from another component on the DAQ device, or an external signal. The choices of UpdateClock sources depend on the specific DAQ device.

```
CWA01.UpdateClock.ClockSourceType = cwaoInternalCS
CWA01.UpdateClock.Frequency = 10000
```

The IntervalClock object is used in a limited number of applications and is supported only on a small number of DAQ devices. When the data is stored completely in FIFO memory on the DAQ device, the IntervalClock object is used in a waveform generation to add a time delay in the output between generations of the waveform data stored in the buffer. With the IntervalClock object, you can store one cycle of a sine wave in the buffer and generate repeated cycles of a sine wave with delays between each. You can examine the properties of the IntervalClock object and their possible settings in the property page.

### **StartCondition Object**

Use the StartCondition object to specify when the waveform generation is started. In most cases, the generation starts immediately after the Start method is called. You can use the StartCondition object on some DAQ devices to trigger the generation in response to an external signal or a signal coming from another component on the device. You can use this functionality to synchronize a waveform generation with an input operation or other external process.

The Type property selects the overall operation of the object. The value of the Type property determines which of the remaining properties on the condition object are used. If the StartCondition object is set to use another signal as the start trigger, the Source property specifies the source of the signal. You can use other properties to specify trigger parameters, such as the slope of the signal to trigger on or the conditions of an analog trigger.

You also can set the values of the different StartCondition properties programmatically.

```
CWA01.StartCondition.Type = cwaoAIStartTrigger
CWA01.StartCondition.Source = "PFI0"
CWA01.StartCondition.Level = 5
CWA01.StartCondition.Mode = cwaoRising
```

If you use a start trigger, the hardware is set to start the waveform generation after the Start method is called. The actual output conversions do not start until the specified trigger signal arrives.

## **Tutorial: Using the AOPoint Control**

This tutorial shows how to develop a program using the AOPoint control. To complete this tutorial, your DAQ device must have one or more analog output channels. You can use an analog input channel of your DAQ device to read the output voltage. If your device does not have analog inputs, you can use an external voltmeter or oscilloscope.

This tutorial uses Visual Basic syntax, but the discussion is in general terms so you can follow it in any compatible programming environment. Remember to adjust any code to your specific programming language. Refer to the *Building ComponentWorks Applications* chapters for information about implementing any step in different programming environments. You also can refer to the tutorial examples installed with ComponentWorks for a completed version of this example in several different programming environments.

## **Designing the Form**

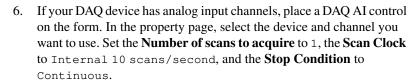
- 1. Open a new project and form. If you are working in Visual C++, select a dialog-based application and name your project AOPoint.
- 2. Load the ComponentWorks User Interface controls (specifically, the Graph and Slide controls) and the Data Acquisition controls (specifically, the AOPoint and AI controls) into your programming environment.
- 3. Place a ComponentWorks button on the form. In the custom property page change the button style to On/Off Toggle Button, its On Text to Stop, and its Off Text to Start. In the default property page, change the Name property to Start.
- 4. Place a ComponentWorks Slide control on the form and change its name to UpdateValue. On the **Numeric** tab of the custom property page, change the **Min** and **Max** properties to -10 and 10.
- 5. Place a ComponentWorks graph on the form. On the **Axis** tab of the custom property page, set the X axis range from 0 to 30 and the Y axis range from -10 to 10.











Chapter 7



7. Place a DAQ AOPoint control on the form. In the custom property page of the AOPoint control, select the device and output channel you want to use.

Your form should look similar to the one shown below.

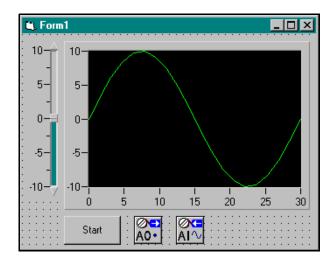


Figure 7-7. AOPoint Form

### **Developing the Code**

The next step is to add the necessary code to generate the analog output and acquire the signal using your analog input channel. If you do not have an analog input channel on your DAQ device, exclude all calls relating to the analog input (starting with CWAI) and use an external voltmeter to measure your analog output.

The program updates the selected analog output channel with the value of the slide when the slide pointer is moved. Use the **Start/Stop** button to start and stop a continuous analog input operation that measures the generated voltage.

1. Use the PointerValueChanged event of the Slide control to detect any changes and update the analog output value. Use the SingleWrite method of the AOPoint control to update the output.

Create the event handler routine for the PointerValueChanged event of the Slide control and add the following code to it. In Visual C++, you first need to create a member variable for the AOPoint control using the ClassWizard.

```
Private Sub UpdateValue_PointerValueChanged(ByVal
   Pointer As Long, ByVal Value As Variant)
   lerr = AOPoint1.SingleWrite(Value, True)
End Sub
```

 To monitor the voltage being generated, run a continuous analog input operation and chart the acquired voltage on a graph. Start and stop the acquisition with the **Start/Stop** button in response to its ValueChanged event.

Create the event handler routine for the ValueChanged event of the button and add the following code to it. In Visual C++ you first need to create a member variable for the AI control using the ClassWizard. Depending on the state (Value) of the button, the event handler either starts or stops the acquisition.

```
Private Sub Start_ValueChanged(ByVal Value As Boolean)

If Value Then

CWAI1.Configure

CWAI1.Start

Else

CWAI1.Stop

End If

End Sub
```

3. While running continuously, the acquisition returns data through the AcquiredData event of the AI control. In this event handler routine, chart the data on the graph. The ChartY method of the graph acts like the PlotY method, except that data is appended to the data already displayed on the graph.

Create the event handler routine for the AcquiredData event of the AI control and add the following code to it. In Visual C++, you first need to create a member variable for the graph control using the ClassWizard.

```
Private Sub CWAI1_AcquiredData(ScaledData As Variant, BinaryCodes As Variant)
    CWGraph1.ChartY ScaledData, 1, True
End Sub
```

4. You usually reset hardware operations before quitting the application, which means stopping any ongoing acquisition and resetting the analog output to 0 volts.

Add the following code to an event handler routine that you call when your application is terminated. The exact name of the event varies depending on your programming environment. In Visual Basic, you can use the Terminate event of the Form object.

```
Private Sub Form_Terminate()
        CWAOPoint1.SingleWrite 0, True
End Sub
```

5. Save your project and form as AOPoint.

### **Testing Your Program**

- 1. Run the program. Remember to physically connect the analog output to your analog input. When you toggle the **Start** button, the continuous input operation starts and displays its measurement on the graph.
- 2. Change the value of the analog output by moving the slide. When you move the slide, the analog output is updated and you can see the change on the graph.

Your completed running program should look similar to the one shown below.

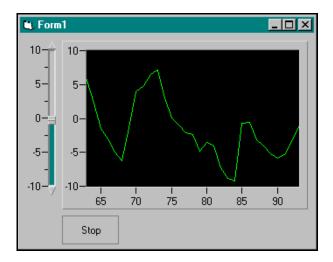


Figure 7-8. Testing AOPoint

When you end the program, the analog output is automatically reset to zero volts.

# **Digital Controls and Hardware**

Three ComponentWorks DAQ controls perform digital input and output operations. Use the DIO control for both input and output single point operations to update the state of any output lines or read the state of any input lines. Use the DI control to perform buffered digital waveform input operations, and use the DO control to perform buffered digital waveform output (pattern generation) operations.

The digital I/O lines on each data acquisition device are grouped into logical units called *ports*. Although they can have as few as two and as many as 32 lines, most devices have eight lines per port. When referencing digital lines on different controls, always specify a port number (starting with zero per device) to select the lines you want to use. On the DIO control, you can select individual lines of a given port to update or read.

### DIO Control—Single Point Digital Input and Output

Use the DIO control to perform single-point updates or reads on the digital lines of a data acquisition device. Typical applications using the DIO control include controlling the state of a physical device such as a valve, relay, or LED or reading the current state of a similar device, such as a switch or light gate. You also can use the DIO control to generate slow pulses to activate other parts of your system. After you set the properties of the DIO control, your program can perform the different operations using simple method calls to the DIO control.

The DIO control consists of a top-level object and a set of Ports and Lines collections and objects. The Ports collection contains a number of Port objects that represent the logical ports on the DAQ device selected in the DIO object. After you select a device in the DIO object, all ports of the device are represented by the control. The Lines collections contains a Line object for each physical digital line on the device. You usually access the Lines collection through one of the Port objects, but you also can access it directly from the DIO object.

Depending on the device you are using, you configure all lines in a given port for input or output operations or you might be able to configure individual lines of a digital port for input and output operations. Devices that allow for line configuration include all E-Series devices (except the extended ports on the MIO-16DE-10), the PC-TIO-10, and DIO-32HS devices.

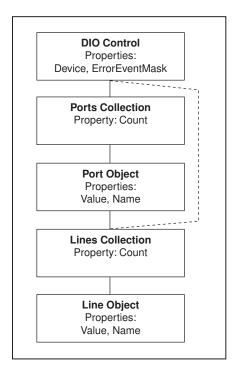


Figure 7-9. DIO Control Object Hierarchy

### DIO Object

The DIO object contains an SCXIChannelString property. If you use the DIO control with one of the SCXI-116x digital modules, enter an SCXI channel string for this property to select the SCXI module. The string must follow the convention for SCXI channel strings as described in the SCXI Channel Strings section at the beginning of this chapter. Each SCXI digital module has only one logical port (port 0) that contains all the digital lines of the module. Therefore the port number is always zero.

CWDIO1.SCXIChannelString = "sc1!md3!0"

The DIO object also contains the Ports collection, which contains individual Port objects. Use the Port object to configure the individual ports on a device, including programmatic configuration of the direction of the digital lines. Each Port object contains a Lines collection with Line objects that you can use to access the individual digital lines of the DAQ device. You also can access the Lines collection directly from the DIO control. Configure the direction of individual ports and lines using the DIO control property pages.

The DIO, Port, and Line objects contain a set of common methods to perform operations using the DIO control.

### **Ports Collection and Port Object**

The Ports collection contains the common properties and methods of a collection such as Count and Item. Use the Item method to access the individual Port objects.

```
CWDIO1.Ports.Item(1)
```

Use the Port object to configure the individual digital ports on a DAQ device. Port objects include properties such as Assignment and LineDirection. Use these two properties to configure the direction of the port or the lines in the port programmatically. The Assignment property specifies whether a port is configured for input or output operations or is line configured. In line configuration, use the LineDirection property to specify the direction of each individual line in the port. Each bit in the LineDirection property corresponds to a digital line. For example, bit 0 corresponds to line 0. A bit value of 1 indicates an output line and a 0 indicates an input line.

```
'Configure port 2 for output

CWDIO1.Ports.Item(2).Assignment = cwdioPortOutput

'Configure port 0, lines 0-3 for output, lines 4-7 for input, binary 00001111 = decimal 15

CWDIO1.Ports.Item(0).Assignment = cwdioPortLineConfigured

CWDIO1.Ports.Item(0).LineDirection = 15
```

#### Note The MIO-16DE-10 is a hybrid DIO board:

- Port 0 is 8 bits wide and line configurable.
- Port 1 does not exist.
- Ports 2, 3, and 4 are each 8 bits wide and port configurable.

Each Port object also contains a reference to a Lines collection containing individual Line objects. Use these to configure and operate the individual digital lines of the data acquisition device.

### **Lines Collection and Line Object**

The Lines collection has the same properties as the Ports collection and with it you can select individual Line objects. The Line object has a Name property that you can use to identify individual lines by name.

```
CWDIO1.Ports.Item(0).Lines.Item(0).Name = "Switch1"
```

The Assignment property of the Line object is read only. Use it to check the current direction of a particular line.

```
LineOisOutput =
   CWDIO1.Ports.Item(0).Lines.Item(0).Assignment
```

### **Common Properties and Methods**

The DIO, Port, and Line objects have a set of common methods (SingleRead, SingleWrite, and Update) to perform input and output operations. In addition, the Port and Line objects include a Value property that you use in conjunction with the Update method.

Use either the SingleRead or SingleWrite method to read or write the current state of the digital I/O lines. SingleRead requires as a parameter a variant that returns the value or values from the read operation. Performing SingleRead on the DIO object returns an array of integers where each array element represents the state of one port. The integer represents the state of the digital lines in a port by bit, where the lowest bit in the integer represents the state of line 0 in the port and so on. For example an integer of value 25 (binary 00011001) indicates that the state of lines 0, 3, and 4 are high and all the remaining lines are low. Performing SingleRead on a Port object returns a single integer representing the state of the port and performing SingleRead on a Line object returns a Boolean value indicating the state of the line.

```
Dim vData As Variant
CWDIO1.SingleRead vData
'Returns an array of integers
CWDIO1.Ports.Item(0).SingleRead vData
'Returns an integer
CWDIO1.Ports.Item(0).Lines.Item(0).SingleRead vData
'Returns a Boolean
```

You also can access the Lines collection directly from the DIO object. If you have assigned a name to a specific digital line, you can use it as a reference.

```
CWDI01.Lines.Item("Switch1").SingleRead bState CWDI01.Lines.Item(14).SingleRead bState
```

To write to the digital output lines, use the SingleWrite method on the DIO, Port, or Line object. This method requires you to write a parameter containing the data to the digital lines. The form of the parameters is the same as it would be returned from a corresponding SingleRead call.

As an alternative to reading and writing using the digital lines, use the Value property of the Port or Line object and the Update method on the DIO, Port, or Line object.

In the output direction, use the Value property to specify the value of a port or line that will be written to the hardware the next time you call the Update method. On the input side, the Value property represents the state of the hardware lines the last time the Update method was called.

#### Note The Value property does not represent the current state of the digital lines.

The Value property represents a cached state of either the last input operation or the data that will be written on the next output operation. Use the Update method to synchronize the cached values with the hardware. This allows you to assign new values to individual output lines and update

all of them at once. You can cache the current state of a set of input lines once and then read the values from the individual lines.

```
'Input Operation
CWDIO1.Update
portVal = CWDIO1.Ports.Item(0).Value
lineVal = CWDIO1.Ports.Item(0).Lines.Item(4).Value
'Output Operation
CWDIO1.Ports.Item(0).Lines.Item(6).Value = False
CWDIO1.Ports.Item(0).Value = newPortVal
CWDIO1.Update
```

### DI Control—Buffered Waveform Digital Input

Use the DI control to perform buffered waveform digital input operations. You can acquire data from your digital inputs quickly, at a rate specified by an external signal or internal frequency. Typical applications using the DI control include transferring digital data from an external device or monitoring a quickly changing system. Advanced applications might include network analyzers. After the properties of the DI control are set, your program can perform the digital acquisition using simple method calls to the DI control.

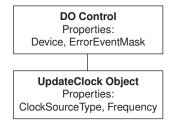


Figure 7-10. DI Control Object Hierarchy

The DI control consists of a top-level object and the UpdateClock object. Most properties that determine the actions of the DI control are set on the control itself, while the UpdateClock object determines the source for the rate of acquisition.

Many DAQ devices do not support buffered digital acquisition, and the DI control does not work with these devices. Other devices support only single buffered acquisition. For these devices, you cannot use the continuous mode. Most of these devices also require an external signal to set the acquisition rate, and you cannot just specify an internal frequency. Devices in the DIO-32 series support both continuous acquisitions and internal frequency sources and can take advantage of the full range of the DI control

features. Check the hardware manual of your data acquisition device for detailed information about its capabilities.

### DI Object

After setting the default DAQ properties of the DI object (such as Device), configure the ChannelString property to specify which digital ports are used by the DI control. You can enter the number of the port to be used or list the ports separated by commas. Make sure the ports you specify support the desired operation. Not all ports on a device support buffered digital input. For example, the DIO-24 devices have three ports, but only ports 0 and 1 can be used with the DI control. Consult your hardware manual for specific information.

You can run the DI control in either continuous or single buffer mode. In continuous mode, data is acquired until the operation is explicitly stopped. The single buffered operation acquires a preset number of points and stops. Use the Continuous property to select between these two different modes.

```
CWDI1.Continuous = True
```

The NPatterns property specifies the size of the acquisition buffer, which also equals the number of patterns acquired per port in a single buffer acquisition. A *pattern* is a value acquired from a digital port that is a numeric representation of the state of the digital lines in the port.

NPatterns is specified in number of patterns per port in the channel list. For example, if NPatterns is set to 1000 and there are two ports in ChannelString, the buffer contains 2000 pattern values. When the control is ready to return data to the application, it fires the AcquiredData event and returns the patterns in an array.

While the acquisition is running, you have the option to receive progress events from the DI control. Set the frequency of the Progress event in the ProgressInterval property as number of patterns acquired. ProgressInterval must be less than or equal to NPatterns. A zero value disables the Progress event generation. You can have the acquired patterns returned with the event using the ProgressReturnData Boolean property.

```
CWDI1.NPatterns = 1000
CWDI1.ProgressInterval = 100
CWDI1.ProgressReturnData = False
```

### UpdateClock Object

Use the UpdateClock object to set the rate used to acquire the digital pattern into the buffer. Depending on the data acquisition device you are using, you might need to supply a clock signal to the device, or you might be able to select an internal rate by frequency or period. Check your hardware manual to see what clock sources are available for your device.

The ClockSourceType property sets the source for the clock signal, which might be the I/O connector of the device, the RTSI bus, or an internal clock. Depending on this value, you can use other properties to further specify the clock. If you are using an internal clock, set the acquisition rate with the InternalClockMode and Frequency or Period properties.

```
CWDI1.UpdateClock.ClockSourceType = cwdioCSInternalClock
CWDI1.UpdateClock.InternalClockMode = cwdioFrequency
CWDI1.UpdateClock.Frequency = 1000
```

If you use the I/O connector or RTSI bus, you do not need to set any other properties.

#### **Methods and Events**

You normally operate the DI control using its Configure, Start, and Reset methods. None of these methods require any parameters. After you set the properties of the control, call the Configure method to program the driver and hardware with the current property values. Next, call the Start method to initiate the acquisition.

Use the Reset method during a continuous acquisition to stop the acquisition and to release any resource assigned in the Configure call. If the control was not reset since the last acquisition, you can perform another acquisition without calling Configure again. If any property values are changed, you need to call Configure to implement those changes.

```
Private Sub DigStart_Click()
    CWDI1.Configure
    CWDI1.Start
End Sub
Private Sub DigStop_Click()
    CWDI1.Reset
End Sub
```

If the digital acquisition requires an external signal as a clock, you must physically connect this signal to the proper line of the I/O connector of your data acquisition card. Consult your hardware manual to determine where to connect this signal.

The acquisition can generate two types of events. The AcquiredData event is generated at the completion of a single buffer acquisition or at NPatterns/2 intervals of a continuous acquisition. The AcquiredData event is the main mechanism for returning the acquired data to the application. Data from a one-port acquisition is returned in a one-dimensional array; data from a multiport acquisition is returned in a two-dimensional array.

Chapter 7

```
Private Sub CWDI1_AcquiredData(Waveform As Variant)
        CWGraph1.PlotY Waveform, 0, 1, True
End Sub
```

If the ProgressInterval property has a value other than zero and it returns data if you set the ProgressReturnData property to True, the Progress event is generated. Use the Progress event to retrieve data during an acquisition or to show the progress of an acquisition on the user interface.

In programming environments that do not support event handler routines, you can call the AcquireData method to perform a synchronous acquisition with single buffered operations.

```
Private Sub SynchAcq_Click()

Dim waveform As Variant

CWDI1.Configure

CWDI1.AcquireData waveform, 5

CWGraph1.PlotY waveform, 0, 1, True

End Sub
```

## **DO Control—Buffered Waveform Digital Output**

Use the DO control to perform buffered waveform digital output operations. With the DO control, you can generate a digital stream from the digital outputs at a rate specified by an external signal or internal frequency. Typical applications using the DO control include generating digital test

signals for testing of electronic devices, systems, and networks. You also can use the DO control to transfer binary data from a computer to another computer or other device. By building your application after setting the properties of the DO control, your program can perform the digital waveform generation using method calls to the DO control.

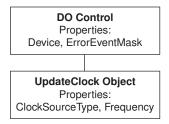


Figure 7-11. DO Control Object Hierarchy

The DO control consists of a top-level object and UpdateClock object. You can set most properties that determine the actions of the DO control in the control itself, while the UpdateClock object determines the source for the rate of generation.

Many DAQ devices do not support buffered digital generation and the DO control does not work with these devices. Other devices support only single buffered generation, and you cannot use the continuous mode in the DO control. Most of these devices also require an external signal to set the update rate, and you cannot simply specify an internal frequency. Devices in the DIO-32 series support both continuous acquisitions and internal frequency sources and can take advantage of the full range of the DO control features. Check the hardware manual of your data acquisition device for detailed information about its capabilities.

### DO Object

After setting the default DAQ properties of the DO object, configure the ChannelString property, which specifies the digital ports used by the DO control. Enter the number of the port to be used or list the ports separated by commas. Make sure the ports you specify support the desired operation. Not all ports on a device support buffered digital input. For example, the DIO-24 devices have three ports, but only ports 0 and 1 can be used with the DO control. Port 2 is used to connect the timing signals required for these operations. Consult your hardware manual for specific information.

You can run the DO control in either continuous or single buffer mode. In the continuous mode, data is generated until you explicitly stop the

operation. The single buffer operation generates a preset number of data values stored in the control buffer once and stops. Use the Continuous property to select between these two different modes.

```
CWDO1.Continuous = True
```

The NPatterns property specifies the size of the control buffer used to store the output data. A *pattern* is a value generated from a digital port numerically representing the state of the digital lines in the port.

NPatterns is specified in number of patterns per port in the channel list. For example, if NPatterns is set to 1000 and there are two ports in ChannelString, the buffer contains 2000 pattern values.

While the generation occurs, the control fires the Progress event to indicate the status of the operation. By default, the Progress event is only generated at the completion of a single buffer operation or at the end of every completed half-buffer in a continuous operation. You can set the frequency of the Progress event by disabling the AutoSelectProgressInterval property and specifying the ProgressInterval property in number of patterns acquired. ProgressInterval must be less than NPatterns, and a zero value disables the progress event generation.

```
CWD01.NPatterns = 1000
CWD01.AutoSelectProgressInterval = False
CWD01.ProgressInterval = 100
```

### **UpdateClock Object**

Use the UpdateClock object to set the update rate of the digital waveform generation. Depending on the data acquisition device, you might need to supply a clock signal to the device or you might be able to select an internal rate by frequency or period. Check your hardware manual to see what clock sources are available on your device.

The ClockSourceType property sets the source for the clock signal, which might be the I/O connector of the device, the RTSI bus, or an internal clock. Depending on this value, you can use other properties to further specify the clock. If you are using an internal clock, use the InternalClockMode and Frequency, Period, or Timebase properties to set the update rate.

```
CWDI1.UpdateClock.ClockSourceType = cwdioCSInternalClock
CWDI1.UpdateClock.InternalClockMode = cwdioFrequency
CWDI1.UpdateClock.Frequency = 1000
```

If you use the I/O connector or RTSI bus, you do not need to set any other properties.

#### Methods and Events

You normally operate the DO control using its Configure, Write, Start, and Reset methods. Only the Write method requires parameters. After you set the properties of the control, call the Configure method to program the driver and hardware with the current property values. Next, call the Write method to send data to the control buffer for output. Data should be passed as a one-dimensional array of pattern values for a single port output and a two-dimensional array of patterns for a multiport output. You then call the Start method to initiate the output operation.

In a single buffer output, the generation stops after it completes the buffer. In a continuous generation, use the Reset method to stop the output and release any resource assigned in the Configure call. If the control was not reset since the last generation, you can perform another output without calling Configure again. You must call Configure to implement any changes you make to the property values.

```
Private Sub DigStart_Click()
   Dim data(0 to 1, 0 to 99) '2-port output
   For i = 0 To 99
        data(0, i) = i 'Port 1 data
        data(1, i) = Int(Rnd * 256) 'Port 2 data
        Next i
        CWDO1.Configure
        CWDO1.Write data
        CWDO1.Start
End Sub
Private Sub DigStop_Click()
        CWDO1.Reset
End Sub
```

Note

If your digital waveform generation requires an external signal as a clock, you must physically connect this signal to the proper line of the I/O connector of your data acquisition card. Consult your hardware manual to determine where to connect this signal.

You also use the Write method during a continuous output to send new data to the buffer so that it can be output from the digital lines. This new data is usually written in half buffer sizes to the control. Use the Progress event to determine when to write new data to the DO control. In continuous mode, set the AllowRegeneration property to False to prevent the DO control from generating the same data in the buffer twice.

During the digital output operation, the DO control generates a Progress event to notify you of the completion of an output or to allow you to monitor its progress. In a continuous generation, the Progress event is set to fire after half the buffer is generated to prompt you to send new data to the control. Although only half the buffer is updated at a time, data is written to the control using the Write method.

```
Private Sub CWDO1_Progress(ByVal TotalPatterns As Long)
   Dim data(0 to 1, 0 to 49)
   For i = 0 To 49
      data(0, i) = i
      data(1, i) = Int(Rnd * 256)
   Next i
   CWDO1.Write data
End Sub
```

## **Tutorial: Using the DIO Control**

This tutorial shows you how to develop a simple program that uses the DIO control to perform single point digital inputs and outputs. Your DAQ device must have one or more digital ports to use this example. You also need a way to apply signals to the digital lines if you want to perform an input or a way to display the state of any output lines. If you have two digital ports, you can connect all the lines from one to the other so that the input can read the state of the output lines.

This tutorial uses Visual Basic syntax, but the discussion is in general terms so you can follow it in any compatible programming environment. Remember to adjust any code to your specific programming language. Refer to the *Building ComponentWorks Applications* chapters for information about implementing any step in different programming environments. You also can refer to the tutorial examples installed with ComponentWorks for a completed version of this example in several different programming environments.

### **Designing the Form**

- 1. Open a new project and form. If you are working in Visual C++, select a dialog-based application and name your project DIO.
- Load the ComponentWorks User Interface controls (specifically, the Numeric Edit Box) and the Data Acquisition controls (specifically, the DIO control) into your programming environment.
- 3. Place two buttons on the form. Change their captions and names according to the following table.

| Button    | Name   | Caption    |
|-----------|--------|------------|
| CWButton1 | Input  | Read Port  |
| CWButton2 | Output | Write Port |





- 4. Place two ComponentWorks Numeric Edit Box controls on the form and change their names to InputNum and OutputNum.
- 5. Place two DIO controls on the form. Use the first one (CWDIO1) for your input operations, and the second (CWDIO2) for any output operations. You configure the DIO controls in the next section of this tutorial.

Your form should look similar to the one shown below.

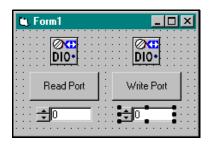


Figure 7-12. DIO Form

## **Developing the Code**

Configure the DIO controls and add the necessary code to write an update to the output lines or read the state of the input lines. If you use only the input control or only the output control, follow the directions for the appropriate task. Although there are ports on some boards that can be configured only as one or the other, most digital ports can be configured for either input or output.

1. Configure one DIO control for input and one for output.

**Input**: In the custom property page of the first DIO control, CWDIO1, select the appropriate DAQ device. Then select (highlight) one digital port in the list and set its direction (Port assignment) to Input. Set the port assignment for all other ports to Unused.

**Output:** In the custom property page of the second DIO control, CWDIO2, select the appropriate DAQ device. Then select one digital port in the list and set its direction (Port assignment) to Output. Set the port assignment for all other ports to Unused.

Depending on your device, you might be able to select the same port for both controls. You can write to the port using one control and read back a value with the other control without making any external connections.

2. Use the **Read Input** button to read the state of the digital input port and display the pattern value in the numeric edit control. You can read the state of all ports at once or you can read a specific port using the DIO control. In this example, read only the selected port to make the code more independent of the hardware you are using.

Create an event handler for the Click event of the **Input** button and add the following code. In the Item method, use the number of the digital port you configured for input. In this example, port 1 is used. The first port on most boards is port 0.

```
Private Sub Input_Click()
    Dim data As Variant
    CWDIO1.Ports.Item(1).SingleRead data
    InputNum.Value = data
End Sub
```

Note If you read all ports at once, the data is returned as an array and you must access individual array elements for the information, as in the following code. Do not add this code to your example.

```
Dim data As Variant
CWDIO1.SingleRead data
InputNum.Value = data(1)
```

3. Use the **Write Output** button to set the state of the digital output port and display the pattern value in the numeric edit control. You can write the state of all the ports at once or you can write to a specific port using the DIO control. In this example, write only to the selected port to make the code more independent of the hardware you are using.

Create an event handler for the Click event of the **Output** button and add the following code. In the Item method, use the number of the digital port you configured for output. In this example, port 0 is used, which is the first port on most boards.

```
Private Sub Output_Click()
    Dim data As Variant
    data = OutputNum.Value
    CWDIO2.Ports.Item(0).SingleWrite data
End Sub
```

Note

If you want to write to all ports at once, you must pass in an array of data with a value for each port on the device, as in the following code. Do not add this code to your example.

```
Dim data As Variant

'For a device with one port
data = OutputNum.Value

'For a device with three ports
data = Array(OutputNum.Value, 0, 0)

CWDIO2.Ports.Item(0).SingleWrite data
```

4. Save your project and form as DIO.

### **Testing Your Program**

Before you can run your program, connect a signal source to your input port and a display or sensor to the output port. You can connect the output lines to the input lines and use the input to measure the output.

- 1. Run the program. Write a value to the output port by setting a value in the corresponding numeric edit box and pressing the **Write Output** button. The value in the numeric edit box represents the pattern written to the port. The pattern is a numeric (integer) representation of the bits in the digital port. A value of zero means all lines are written low. A value of 22 (binary 00010110) means lines 1, 2 and 4 are written high. Most ports have 8 digital lines, and a value of 255 corresponds to all lines high.
- 2. Read the value of the input port by pressing the **Read Input** button. The pattern value is read from the port and displayed in the corresponding numeric edit box. If you have connected all lines of the output port to the input port, you should read the same value you wrote out. If you read input lines that are not connected to anything (floating), their values are not necessarily low. An open port might read any value, not always 0.

#### 3. Quit the program.

Instead of using the SingleRead and SingleWrite methods, you also can use the Value property and Update method of the DIO control to implement the functionality of this tutorial. The Update method can be called on the DIO control as a whole or on the individual port.

```
Private Sub Input_Click()
    Dim data As Variant
    CWDIO1.Update
    data = CWDIO1.Ports.Item(1).Value
    InputNum.Value = data
End Sub
Private Sub Output_Click()
    Dim data As Variant
    data = OutputNum.Value
    CWDIO2.Ports.Item(0).Value data
    CWDIO2.Ports.Item(0).Update
End Sub
```

## **Counter/Timer Hardware**

The hardware component on the DAQ device used by the Counter and Pulse controls is called a counter/timer. Use this component to count or measure incoming digital pulses or to generate digital pulses and pulse trains on its output.

Each counter/timer has two inputs labeled *Source* and *Gate* and one output labeled *Out*. The Source is also referred to as *Clock*. The counter counts the number of digital pulses coming in on the source input. The counting operation can be gated by a digital signal applied to the gate input. The output of the counter generates a pulse when the counter reaches its maximum count or zero, depending on whether it is counting up or down. Vary parameters, such as the signals applied to the source and gate, and the initial count of the counter and the mode used in gating to use this simple component in a variety of different applications.

The ComponentWorks Counter and Pulse controls allow you to select from a number of standard operations and specify applicable properties. The properties in the controls are grouped by the I/O point of the counter that they affect, such as source, gate, and output.

## **Counter Control—Counting and Measurement Operations**

Use the Counter control to perform counting and other measurement operations using the counter/timer components on a data acquisition device. Typical operations include counting a number of events, measuring the period of an unknown pulse, or measuring the frequency of a signal. After the properties of the control are set, the application can perform the operation using a simple method call to the Counter control. The operation of the Counter control is measurement-oriented, and the behavior of the control depends on the type of measurement selected.

Counter Control
Properties such as
Device, Counter,
MeasurementType

Figure 7-13. Counter Control Object Hierarchy

The Counter control consists of only one object—the Counter object—which contains all the properties and methods necessary to use the control.

## **Counter Object**

The Counter object contains all the properties necessary to configure a counting or measurement operation.

The Counter and MeasurementType properties affect the Counter control as a whole. The Counter property specifies which counter/timer on the DAQ device will be used by the control. The available counter numbers depend on the DAQ device. The MeasurementType property selects the type of operation the control will perform and affects the interpretation of the remaining properties. The InitialCount property sets the value of the counter at the start of an operation.

7

Table 7-1 describes different measurement types. **Table 7-1.** Measurement Types

| Measurement<br>Type              | Description   | Units | One<br>Point | Buffered<br>(DAQ-STC<br>Only) |
|----------------------------------|---|-------|--------------|-------------------------------|
| Event Count                      | Counts the number of pulses on the source input.  | Count | X            | X                             |
| Time                             | Measures time by counting a known clock input.  | Sec   | X            | X                             |
| Frequency                        | Measures frequency on source input by counting the number of pulses in a known period of time.  | Hertz | X            |                               |
| Pulse Width,<br>High             | AM9513: Measures the length of the high pulse until the next falling edge. A partial measurement is possible if the pulse is initially high.  DAQ-STC: Measure first pulse after next falling edge.   | Sec   | X            | Х                             |
| Pulse Width,<br>Low              | AM9513: Measures the length of the low pulse until the next rising edge. A partial measurement is possible if the pulse is initially low.  DAQ-STC: Measures the first pulse after the next rising edge.  | Sec   | X            | X                             |
| Pulse Width,<br>High Single-Shot | AM9513: Measures the length of the high pulse until the next falling edge. A partial measurement is possible if the pulse is initially high.  DAQ-STC: Measures the first complete pulse and generates an error if the pulse is in a high state at the start. | Sec   | X            |                               |
| Pulse Width,<br>Low Single-Shot  | AM9513: Measures the length of the low pulse until the next rising edge. A partial measurement is possible if the pulse is initially low.  DAQ-STC: Measures the first complete pulse and generates an error if the pulse is in a low state at the start.     | Sec   | X            |                               |
| Period, Rising<br>Edge           | Measures the period between two rising edges on gate input by counting a known clock.   | Sec   | X            | X                             |
| Period, Falling<br>Edge          | Measures the period between two falling edges on gate input by counting a known clock.  | Sec   | X            | X                             |
| Semi-Periods                     | Measures the length of consecutive high and low pulses.   | Sec   |              | X                             |

Frequency and Single-Shot Pulse Width measurements can be performed as one point (unbuffered) operations only, but the Semi-Period measurement must be buffered.

The remaining Counter object properties directly affect one of the inputs or outputs of the control. Properties affecting the source input include TimebaseSource, TimebaseSignal, SourceEdge and CountDirection.

- TimebaseSignal—Selects either a specific input pin of your board or the internal frequency used for the source of the counter, depending on the TimebaseSource property.
- SourceEdge—Selects whether to count rising or falling edges on the source
- CountDirection—Determines whether the counter counts up or down.

Gate properties are GateMode, GateSource, GateSignal, and GateWidth.

- GateMode—Selects the type of gating used in an operation such as No Gating, High Level Gating, and so on.
- GateSource and GateSignal—Select the source of the gate signal.
- GateWidth—Sets the sample width of the measurement in Frequency measurements.

Output properties are OutputMode and Polarity.

- OutputMode—Determines whether the counter output pulses or toggles when the counter reaches its limit.
- Polarity—Determines if the output is high (active high) or low (active low) polarity.

To become familiar with different types of measurements and properties, browse through the custom property pages and study the different settings. Some properties are disabled depending on the state of other properties.

#### Methods and Events

The Counter control has a set of simple methods to control the operation of the counter. Call the Configure method to configure the data acquisition driver and hardware with the current properties before starting any operation. Call the Start method to start the measurement. If needed, you can call the Stop method to stop the counter and the Reset method to unconfigure the counter and release its resources for other operations. After stopping a counter, you can restart it using just the Start method if you

have not called the Reset method. After resetting the counter, you must call Configure again before restarting.

Depending on the measurement, the control might fire an AcquiredData event to indicate the completion of a measurement and return the data. The data is returned in the Measurement parameter that is passed to the AcquiredData event and scaled to the units indicated in the previous table. Measurements that fire an AcquireData event are Frequency, Pulse Width, Period, and Semi-Period.

```
Private Sub CWCounter1_AcquiredData(Measurement As
   Variant, ByVal Overflow As Boolean)
   txtPulseWidth.Text = Measurement
End
```

Event Count and Time measurements do not fire an event to return data. Therefore, use the ReadCounter and ReadMeasurement methods to read the value of your measurement. ReadCounter returns the actual count value of the counter and usually is used in event counting operations. ReadMeasurement returns the value scaled to the appropriate units, such as time. Both methods require one parameter to return the measurement and another to indicate an overflow condition in the counter.

```
Private Sub Timer1_Timer()
   Dim lVal As Long
   Dim vVal As Variant
   Dim bOverflow As Boolean
   CWCounter1.ReadCounter lVal, bOverflow
   txtCount.Text = lVal
   CWCounter1.ReadMeasurement vVal, bOverflow
   txtMeas.Text = vVal
End Sub
```

#### **Buffered Measurements**

All measurements acquire and return a single value of the selected type. On specific data acquisition devices such as the E-Series devices, you can perform a buffered measurement for most of the measurement types. A buffered measurement acquires multiple values and stores the individual values in a buffer for later analysis and processing. After they are started, measurements are stored in the buffer asynchronously. When all data points have been acquired, the AcquiredData event is fired and the buffer is returned to the application. Measurements are stored in the buffer at the completion of a period or pulse for Period and Pulse measurements or at a conversion signal on the gate input for Event Count and Time measurements.

The Counter object has two properties to enable buffered measurements. UseBuffering is a Boolean property that enables the buffered mode. NMeasurements specifies the number of measurements. While a buffered measurement is running, no data can be read from the counter or the buffer, and all data is returned when the measurement is complete. The same methods used for a one-point operation also are used to control buffered measurements. When data is returned in the Measurement parameter of the AcquiredData event, it is formatted as an array.

```
Private Sub BufferedStart_Click()
    CWCounter1.MeasurementType = cwctrHiPulseWidth
    CWCounter1.UseBuffering = True
    CWCounter1.NMeasurements = 10
    CWCounter1.Configure
    CWCounter1.Start
End Sub
Private Sub CWCounter1_AcquiredData(Measurement As
    Variant, ByVal Overflow As Boolean)
    CWGraph1.PlotY Measurement, 0, 1, True
End Sub
```

## Pulse Control—Digital Pulse and Pulsetrain Generation

Use the Pulse control to generate individual pulses and pulse trains with the counter/timer component on a data acquisition device. Typical operations include generating a digital test signal or driving a stepper motor. After you set the properties of the control, the application can perform operations using simple method calls to the Pulse control. The operation of the Pulse control is task-oriented, and the behavior of the control depends on the type of task selected in the properties.

#### **Pulse Control**

Properties such as Device, Counter, PulseType

Figure 7-14. Pulse Control Object Hierarchy

The Pulse control consists of only one object—the Pulse object—which contains all the properties and methods necessary to use the control.

## **Pulse Object**

The Pulse object contains the properties necessary to configure the pulse operations.

The Counter and PulseType properties affect the Pulse control as a whole. The Counter property specifies the counter/timer on the DAQ device used by the control. The available counter numbers depend on the type of DAQ device. The PulseType property selects the type of operation the control performs and affects the interpretation of the remaining properties.

Table 7-2 describes the different pulse type operations.

**Table 7-2.** Pulse Type Operations

| Pulse Type                        | Description   |  |  |
|-----------------------------------|---|--|--|
| Single Pulse                      | Generates one pulse according to the specifications.  |  |  |
| Continuous Pulse Chain            | Generates a continuous pulse train according to the specifications.   |  |  |
| Finite Pulse Chain                | Generates a finite set of pulses. This requires two counters.   |  |  |
| FSK Pulse                         | Frequency Shift Keying, generates one of two different pulse trains dependent on a digital input. The selector is applied to the gate of counter.                       |  |  |
| Incremental Delay Pulse (ETS)     | Equivalent Time Sampling pulse. Generates a series of individual pulses with increasing offset from the digital trigger. The trigger is applied to the gate of counter. |  |  |
| Retriggerable Pulse, Rising Edge  | Retriggered single pulse. The trigger is applied to the gate, triggered off the rising edge.  |  |  |
| Retriggerable Pulse, Falling Edge | Retriggered single pulse. The trigger is applied to the gate, triggered off the falling edge.   |  |  |

The remaining properties of the Pulse object directly affect the pulse generation or the gate of the counter. Properties affecting pulse generation include ClockMode, CountDirection, DutyCycle, Frequency, Period, Period2, Phase1, Phase2, Frequency2, Count, Phase1Inc, PulseDelay, PulseWidth, SourceEdge, TimebaseSource, and TimebaseSignal.

The parameters that are used for the actual pulse generation depend on the settings of the PulseType and ClockMode properties. The PulseType settings select the general operation of the Pulse control, such as single pulse or continuous pulse generation, while the ClockMode settings determine how the output is characterized. Settings for ClockMode include Frequency and Period, which means the output is characterized by its frequency or by the period of the pulse.

Gate properties include GateMode, GateSource, GateSignal. GateMode selects the type of gating used in an operation such as No Gating, High Level Gating, and so on. GateSource and GateSignal select the source of the gate signal.

To become familiar with different types of pulse generation and their corresponding properties, browse through the custom property pages and study the different settings. Some properties are disabled depending on the state of other properties.

#### Methods

The Pulse control has a set of simple methods to control the operation of the pulse generation. Use the Configure method to configure the data acquisition driver and hardware with the current properties before starting any operation. Use the Start method to start the generation. If needed, you can call the Stop method to stop the counter and the Reset method to unconfigure the counter and release its resources for other operations. After stopping a pulse generation, you can restart it using just the Start method if you have not called the Reset method. After resetting the counter, you must call Configure again before restarting.

While running a pulse generation operation, you can change some parameters without stopping the operation. For example, you can change the frequency of continuous pulse generation in mid-stream by updating the relevant property of the pulse control and calling the Reconfigure method.

Reconfigure can be called only when an operation is running because it updates all properties that have changed since the last call to Configure or Reconfigure. Use this method with the PointerValueChanged event of the Slide control to set the pulse frequency to the value of the slide.

```
Private Sub CWSlide1_PointerValueChanged(ByVal Pointer
As Long, Value As Variant)
    CWPulse1.Frequency = Value
    If OutputRunning Then CWPulse1.Reconfigure
End Sub
```

#### **FSK and ETS Pulse Generation**

On data acquisition devices that use the DAQ-STC counter/timer, the Pulse control supports two specialized pulse generation modes, which you can select in the PulseType property. Use these modes in conjunction with analog input operations to perform special acquisitions.

Use FSK (frequency shift keying) to generate a continuous pulse with one of two different frequencies, depending on a separate digital signal. Apply the digital signal that selects between the two different frequencies to the gate input of the counter used by the pulse control. Using the Frequency and Frequency2, Period and Period2, or Phase1 and Phase2 properties, you can select the two different frequencies to generate. You can combine this type of pulse generation with an analog input to build a Rate-Change-on-the-Fly acquisition.

To change the acquisition rate dynamically with a digital signal, use the output of the counter as the scan clock of the acquisition. If you have a hardware analog trigger on your device, you can enhance this application by using the analog trigger to convert an analog signal, such as the one being acquired, into a digital signal, which you then use to control the pulse generation. This means you can use two different acquisition rates on your analog signal and the acquisition automatically changes rates above and below the specified analog voltage value.

ETS (equivalent time sampling) is an acquisition technique that combines an analog input operation, hardware analog trigger, and pulse generation on a repetitive signal to achieve an effective acquisition rate that is significantly higher than the actual acquisition rate of the device.

The analog trigger is used to generate a repeating digital trigger signal from the repetitive analog signal. This digital signal is routed to the gate of a counter that generates another digital pulse with an increasing amount of delay in response to the trigger. This pulse is used as the scan clock of the acquisition. By triggering off the same point of the analog signal with an exact and varying delay, you can sample the entire signal waveform using many cycles. Because the change in the delay is much smaller than the minimum acquisition period of the device, the effective acquisition rate is significantly increased.

In the Pulse control, specify the input of the gate to be AlTrigger and set the change in delay using the ETSIncrement property. The ETS increment is always specified in number of cycles of the clock source and can range between 0 and 255.

# **Tutorial: Using the Counter and Pulse Controls**

This tutorial shows you how to develop a program that uses the Counter and Pulse controls. The example generates a continuous pulse of varying frequency using the Pulse control and counts the number of pulses generated using the Counter control. To complete this tutorial, your DAQ device must have two available counters. If you use just one counter with either the Counter or Pulse control, you need an external mechanism to display the output from the Pulse control or apply an input to the Counter control.

This tutorial uses Visual Basic syntax, but the discussion is in general terms so you can follow it in any compatible programming environment. Remember to adjust any code to your specific programming language. Refer to the *Building ComponentWorks Applications* chapters for information about implementing any step in different programming environments. You also can refer to the tutorial examples installed with ComponentWorks for a completed version of this example in several different programming environments.

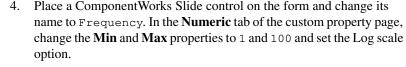
## **Designing the Form**

- 1. Open a new project and form. If you are working in Visual C++, select a dialog-based application and name your project Counters.
- 2. Load the ComponentWorks User Interface controls (specifically the Slide controls) and the Data Acquisition controls (specifically the Counter and Pulse controls) into your programming environment.
- 3. Place five buttons on the form. Change their captions and names to the ones listed in the following table.

| Button    | Name           | Caption         |  |
|-----------|----------------|-----------------|--|
| CWButton1 | ConfigurePulse | Configure Pulse |  |
| CWButton2 | StartPulse     | Start Pulse     |  |
| CWButton3 | StopPulse      | Stop Pulse      |  |
| CWButton4 | StartCounter   | Start Counter   |  |
| CWButton5 | ReadCounter    | Read Counter    |  |









5. Place a text box on the form.



6. Place a DAQ Pulse control on the form. In the custom property page of the Pulse control, select the device and counter you want to use. If you have an E-Series device, use counter 0. If you have an older MIO device, use counter 5. Otherwise, use an available counter. You set the remaining properties in the following section.



7. Place a DAQ Counter control on the form. In the property page, select the device and counter you want to use. If you have an E-Series or older MIO device, use counter 1. Otherwise, use an available counter.



8. If your environment has a timer control, place one on the form. In the property page, set its **Enabled** property to False and its **Interval** property to 100 (ms).

Your form should look similar to the one shown below.

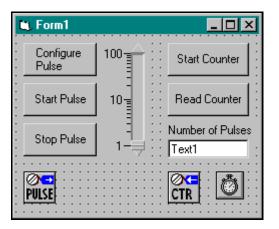


Figure 7-15. Counters Form

## **Developing the Code**

Configure the DAQ controls and add the necessary code to generate the continuous pulse train and count the pulses. If you are using one counter, follow the directions for either the Counter or Pulse control. The next section describes how you can connect your signals in either case.

- 1. Configure the Pulse control to generate a continuous pulse train. On the **General** tab of the property page, set **Pulse Mode** to Continuous pulse train. On the **Clock** tab, set **Clock Mode** to Use frequency settings, **Frequency** to 1.0, and **duty cycle** to 0.50 (50%). On the **Gate** tab, set **Gate Mode** to Ungated.
- 2. Three buttons on the form control the operation of the Pulse control. Generate event handlers for the Click event of each button and add the following code. You also need to declare a Boolean variable, Running, which is global to the module containing the code for the form. This declaration might vary among different programming languages. In Visual C++, you must create a member variable for the Pulse control.

```
Dim Running as Boolean
Private Sub ConfigurePulse_Click()
    CWPulse1.Configure
End Sub
Private Sub StartPulse_Click()
    CWPulse1.Start
    Running = True
End Sub
Private Sub StopPulse_Click()
    CWPulse1.Stop
    Running = False
End Sub
```

Use the **Stop** and **Start** buttons to halt the pulse generation and restart it without having to reconfigure the Pulse control.

The Slide control changes the frequency of the pulse train. If the pulse
generation is running, the output updates immediately. Create an event
handler for the PointerValueChanged event of the slide, and add
the following code.

```
Private Sub Frequency_PointerValueChanged(ByVal
Pointer As Long, Value As Variant)
    CWPulse1.Frequency = Value
    If Running Then
        CWPulse1.Reconfigure
    Else
        CWPulse1.Configure
    End If
End Sub
```

If the pulse generation is running, the Reconfigure method updates the output immediately. Otherwise, the Configure method reprograms the hardware for the next start.

- 4. Configure the Counter control to count events, which are the pulses generated by the pulse control. On the **General** tab of the property page, set **Measurement Type** to Event count. On the **Clock** tab, set **Timebase source** to Counter's source. On the **Gate** tab, set the **Gate Mode** to Ungated.
- 5. Two buttons on the form control the operation of the Pulse control. Generate event handlers for the Click event of each button and add the following code. In Visual C++, you must create a member variable for the Counter control. Add the following code to the two event handlers.

```
Private Sub StartCounter_Click()
    CWCounter1.Configure
    CWCounter1.Start
End Sub
Private Sub ReadCounter_Click()
    Dim CountValue As Long
    Dim Overflow As Boolean
    CWCounter1.ReadCounter CountValue, Overflow
    Text1.Text = CountValue
End Sub
```

After the counter starts, you can use the **Read** button to interactively read the value of the counter and display it in the textbox.

6. If you have a timer control on your form, you can program it to automatically read the value of the counter once it has been started. If you are working in Visual C++, create a member variable for the timer control.

To activate the timer, add the following line to the end of the code in the StartCounter\_Click subroutine.

```
Timer1.Enabled = True
```

Create an event handler for the Timer event of the timer control and add a call to the ReadCounter\_Click() subroutine.

```
Private Sub Timer1_Timer()
    ReadCounter_Click
End Sub
```

7. Save your project and form as Counters.

## **Testing Your Program**

- 1. Before you can run your program, you must connect the output of the counter running the pulse generation to the source input of the counter counting events, which is an external connection. If you are using only one counter, you need other external hardware. If you are using the DAQ Pulse control, you should have a device to measure the output of the counter, such as an oscilloscope or external counter. If you are using the DAQ Counter control, you must connect an external pulse source to the source input of the counter.
- Run the program. Start the pulse generation by clicking on the Configure Pulse and Start Pulse buttons. Start the counter. If you have the timer control enabled, the textbox displays the value of the event count. Without the timer control, you can use the Read Counter button to update the textbox.
- 3. Change the value of the slide to modify the frequency of the pulse generation. Notice that the count value in the textbox changes faster or slower accordingly. You also can stop and restart the pulse generation, which affects the count value.

Your completed running program should look similar to the one shown below.

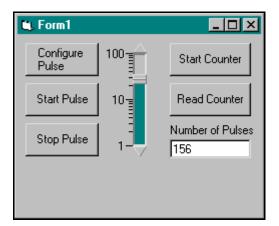


Figure 7-16. Testing Counters

4. Quit the program (click on the **X** button in the window title bar).

# **DAQTools—Data Acquisition Utility Functions**

The ComponentWorks DAQ controls include a DAQTools control that contains a set of utility functions for data acquisition. Although the control itself has no properties or events, these utility functions are all methods of the DAQTools control. Use these functions with different data acquisition devices to implement functionality that is not part of any other DAQ control. The function groups in the DAQ Tools control include the following:

- GetErrorText function—Converts a ComponentWorks error number to a descriptive string. Use this in error handling to convert the return code from a DAQ method call to an error message.
- Configure functions—Configure specific devices or parts of devices such as the hardware analog trigger circuit on specific E-Series devices.
- Conversion functions—Convert measurement units to physical units for certain transducers, such as thermocouples, thermistors, RTDs, and strain gauges.
- Get and Set functions—Read and set different properties of data acquisition and SCXI (signal conditioning) devices.
- Reset functions—Reset DAQ and SCXI devices.
- ICtr functions—Perform operations using the interval counter (ICounter) on some data acquisition devices. Devices that include this counter are the 500, 700, 1200, LPM-16, and Lab-PC series devices. The functions are ResetICtr, StartICtr, and ReadICtr.
- FOUT functions—Generate a simple continuous pulse train from the FOUT pin of different DAQ devices. The functions are StartFOUT and ResetFOUT.
- Calibration functions—Perform software calibration on different data acquisition devices.

🦙 Note

Because all devices are calibrated before shipping and do not need to be calibrated before their first use, you probably do not need to calibrate your device. Read all hardware documentation describing calibration and calibration functions before attempting to perform any calibration.

You must place the DAQTools control on your form to use the DAQTools functions. To call a function, use the standard convention for calling any method of a control; that is, prepend the name of the control to the function name.

The following example converts an error code number to a text description and displays it in a message box.

```
MsgBox "DAQ Error: " +
   CWDAQTools1.GetErrorText(ErrorCode)
```

To configure the hardware analog trigger circuit, you can use the ConfigureATCOut function.

```
'Prototype: ConfigureATCOut (Device:=, Enable:=,
   TriggerMode:=, Level:=, Hysteresis:=, strSource:=,
   ActualLevel:=, ActualHysteresis:=)

Dim Level as Variant, Hysteresis as Variant

CWDAQTools1.ConfigureATCOut 1, True, 1, 0#, 0.1, "0",
   Level, Hysteresis
```

# Using the GPIB and Serial Controls

This chapter describes how you can use the ComponentWorks Instrument controls in your application to perform input and output operations using GPIB and serial hardware; explains the individual controls and their most commonly used properties, methods, and events; and includes tutorial exercises that give step-by-step instructions on using the controls in simple programs.

Refer to the *Building ComponentWorks Applications* chapters for information about using the ComponentWorks controls in different programming environments. You can find additional information in the online reference, available by selecting **Programs»National Instruments ComponentWorks»ComponentWorks Reference** from the Windows **Start** menu.

## What Are the GPIB and Serial Controls?

Use the GPIB and Serial controls to perform instrument communication and control and integrate these operations into your application. ComponentWorks includes two ActiveX controls for performing GPIB and Serial (RS-232) operations, CWGPIB and CWSerial.

You can set most properties for these controls through property pages as you design your program. In certain cases, you might need to change the value of one or more properties in your program code. Throughout this chapter, examples demonstrate how to change property values programmatically.

## **Object Hierarchy and Common Features**

The ComponentWorks Instrument controls are made up of a hierarchy of objects. Understanding the relationship among the objects in a control is the key to properly programming with the control. Dividing a control into individual objects makes it easier to work with because each individual component has fewer parts.

The Instrument controls share a very similar object hierarchy (compare Figure 8-1, *GPIB Control Object Hierarchy*, and Figure 8-3, *Serial Control Object Hierarchy*). The hierarchy consists of a simple series of objects from the top-level control through three sets of collections and associated objects. A collection is the property of an object that stores multiple instances of the same type of object. For example, a Tasks collection object contains multiple Task objects.

## **Common Properties**

The top-level object of each Instrument control share some common properties.

DataAsString—Use the DataAsString property to specify whether data is returned in a string or byte array format. If this property is True, data is returned as a string. If this property is False, data is returned as an array of bytes. You can set this property from the property pages of each control or programmatically as in the following example.

CWGPIB1.DataAsString = True

SwapBytes—Some instruments return data in which the least significant byte appears first. This format is known as Little Endian. Other instruments return data starting with the most significant byte of the word, or in Big Endian format. Check your instrument documentation to determine if the instrument returns data in Big or Little Endian format. If your instrument returns data in Big Endian format, set SwapBytes to True.

ExceptionOnError—The Instrument controls handle error checking in two different ways. When an error occurs, each Instrument control generates an exception that your programming environment handles (default action). You can disable the generation of exceptions using the ExceptionOnError property of each Instrument control. If you disable exceptions on errors, the control fires an OnError event in response to an error condition and passes the error information to the OnError event handler. For some error conditions, such as those that occur during asynchronous operations, the control fires OnError events regardless of the value of ExceptionOnError.

## **Parsing**

With the Instrument control parsing features, you can parse data into formats more easily used by your application. Both Instrument controls support multiple parsing tasks. Use tasks to specify the way in which the data is parsed, and you can invoke different tasks at different times in your application.

Each task contains a group of patterns. These patterns are made up of one or more tokens, which are the basic building blocks of parsing. For example, a token might be a number, a 4-byte word, or a comma. A pattern might consist of a number token followed by a comma token. A parsing task might consist of this particular pattern repeated several times.

Parsed data is returned as an array of tokens. The control returns parsed data as an array of tokens. You can configure the control to ignore specific types of tokens and not return them in the array. For example, you might not want the commas returned in certain patterns. If you specify commas as ignored, only the numbers are returned in the array. Use the built-in task Number Parser to automatically extract all numbers from the data and return them in an array. If only one number is present, it returns the number as a scalar (simple non-array variable).

## **Advanced Parsing Features**

This section describes advanced parsing features. Refer to *Tutorial: Using the Serial Control* later in this chapter to learn how to use simple parsing features.

You perform a parsing task by calling the task's Read method. The ReadAsynch method performs an asynchronous read and returns the parsed data in the DataReady event. The task number is also passed to the event handler. The Run method of the Task object performs an automated asynchronous task, writing the output string specified for the task (either programmatically or on the **Parsing** property page) and then performs an asynchronous read. The Parse method parses an argument passed to the method rather than performing a read and then parsing the read data.

```
CWGPIB1.Tasks.Item(1).Read CWGPIB1.Tasks.Item(1).Run
```

You can build a parsing task through property pages at design time. By creating and manipulating CWTask objects programmatically, you also can build parsing tasks at run time.

#### **CWTask Object**

To add a parsing task to a control, call the Add method of the Tasks collection property of the control, as in the following example.

```
CWGPIB1.Tasks.Add
```

The new CWTask object is added to the end of the Tasks collection. You can reference it by using the Count property of the Tasks collection. In Visual Basic, use the Set statement to assign an object to a variable.

```
Dim NewTask as CWTask 'create a CWTask variable
CWGPIB1.Tasks.Add
Set NewTask = CWGPIB1.Tasks(CWGPIB1.Tasks.Count)
```

In environments other than Visual Basic, use the Item method on the Tasks collection to reference a specific Task object in the collection, as in the following block of code.

```
Dim NewTask as CWTask 'create a CWTask variable
CWGPIB1.Tasks.Add
Set NewTask = CWGPIB1.Tasks.Item(CWGPIB1.Tasks.Count)
```

The CWTask object has two properties previously mentioned. Name is an identifier used to select a specific task in the Tasks collection. To programmatically set the Name property of the task added above use the following syntax.

```
NewTask.Name = "Waveform"
```

OutputString contains a string that is written to the instrument when the Run method is invoked.

```
NewTask.OutputString = "val1?"
```

#### Methods and Events

The CWTask object has four methods, Read, ReadAsynch, Run, and Parse, which are described earlier in this parsing section. The Task object also contains a Patterns collection which contains the individual Pattern object that defines the parsing task.

You add and manipulate pattern objects in the same manner that you add Task objects. The CWPattern object has several properties that define its parsing description. To access a Pattern object, reference it through the Task object in which it is contained.

Chapter 8

NewTask.Patterns.Add

Name is an identifier used to select the pattern in the Patterns collection.

NewTask.Patterns(NewTask.Patterns.Count).Name = "Header"

RepetitionFactor is the number of times the pattern is to be repeated. Set this property to -1 if the pattern is to be repeated an undefined number of times.

If you are programming in environments other than Visual Basic, use the Item method.

NewTask.Patterns.Item(NewTask.Patterns.Count).Name = "Header"

You also can use the complete syntax to access the Pattern object from the Instrumentation control.

CWGPIB1.Tasks.Item(CWGPIB1.Tasks.Count).Patterns(CWGPIB1.Tasks.Item(CWGPIB1.Tasks.Count).Patterns.Count).Name = "Header"

The Type property of the Pattern object is set to one of two values—
cwNumberParser or cwUserDefined—which are constants defined by
ComponentWorks. Set the pattern type to cwNumberParser (only built-in
pattern type) to pull all of the numbers from the input string and return
them. Use the cwUserDefined type to define a pattern using tokens.

Dim NewPattern as CWPattern

Set NewPattern = NewTask.Patterns.Item(NewTask.Patterns.Count)
NewPattern.Type = cwUserDefined

The Pattern object contains a Tokens collection and associated Token objects that define the individual pattern.

#### **CWToken Object**

You add and manipulate Token objects in the same manner that you work with Task and Pattern objects. The CWToken object has several properties that define its parsing description.

Value is a string defining the type of token. For example, the value can be "<number>", "<stringX>" (where X is the number of bytes that make up the token), or a literal string to match, such as "FLUKE" or ",".

RepetitionFactor is the number of times the token is to be repeated. Set this property to -1 if the token is to be repeated an undefined number of times. Ignore is a boolean property that determines whether the token should be ignored or returned with the data. For example, you might set the Ignore property to True so that commas are not returned to the application.

```
NewPattern.Tokens.RemoveAll
NewPattern.Tokens.Add
NewPattern.Tokens.Item(1).InputType = cwString
NewPattern.Tokens.Item(1).Value = ","
NewPattern.Tokens.Item(1).Ignore = True
```

The RemoveAll method used in the code segment above is available on all collections such as Tasks, Patterns, and Tokens. It removes all objects from the collection. A subsequent call to the Add method adds the first object in the collection; therefore, you know the exact index of any objects you add. Calling RemoveAll on the Tasks collection also removes the predefined number parsing task. You can recreate this task by adding a new task and new pattern and setting the Type property of the new pattern to cwNumberParser.

## The GPIB Control

Use the GPIB control to control GPIB instruments. After setting the properties of the control, you can acquire data using method calls to the GPIB control and perform automated parsing of the returned data. To configure the properties of the control during design, right click on the control and select **Properties...** from the popup menu to open the property pages for the control.

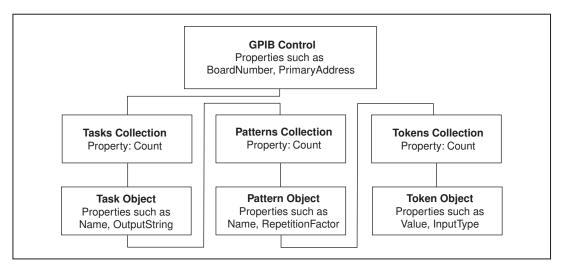


Figure 8-1. GPIB Control Object Hierarchy

The object hierarchy of the GPIB control contains a Tasks collection and objects for parsing. See *Advanced Parsing Features* earlier in this chapter for more information about accessing Pattern and Token objects.

## **CWGPIB Object**

The GPIB object has GPIB-specific properties, such as BoardNumber, PrimaryAddress, and SecondaryAddress, that you use to specify the instrument. You can set these properties through the property pages or in your program, as in the following code.

```
CWGPIB1.BoardNumber = 0
CWGPIB1.PrimaryAddress = 2
CWGPIB1.SecondaryAddress = 0
```

Other properties include Timeout, EOTMode, EOSCharacter, Compare8Bits, EOSEndsRead, EOIWithEOS, Unaddressing, and NotifyMask, although not all instruments require you to set these properties. See the online reference for all properties and their uses.

#### **Methods and Events**

To control a GPIB instrument, use the Configure method. This method initializes the GPIB instrument and configures it with the settings you specified for the control. You must call the Configure method in the following cases:

- Before calling any other control methods
- After changing any properties (for new properties to take effect)
- After calling the Reset method, before performing any GPIB I/O

```
Private Sub ConfigureDevice_Click()
    CWGPIB1.Configure
End Sub

Private Sub ResetDevice_Click()
    CWGPIB1.Reset
End Sub
```

## Synchronous I/O

You perform synchronous I/O using the Read and Write methods of the CWGPIB control. Read accepts an optional parameter that specifies the buffer size. Unlike the Read method on CWTask, the Read method on CWGPIB does not perform any parsing of the data.

The following example displays the identification string returned by many GPIB instruments. The control first writes the command \*IDN? to the instrument and then reads back and displays the response in a text box in the program.

```
CWGPIB1.Write "*IDN?"
Text1.Text = CWGPIB1.Read
```

## Asynchronous I/O

You use the ReadAsynch and WriteAsynch methods to perform asynchronous I/O operations. These methods start a read or write operation, respectively, and then return immediately. When an asynchronous read is complete, the control generates a DataReady event and passes the data to your event handler. When an asynchronous write is complete, the control generates a WriteComplete event.

```
CWGPIB1.ReadAsynch
Private Sub CWGPIB1_DataReady(taskNumber as Short,
  data As Variant)
    Text1.Text = data
End Sub
```

Unlike the ReadAsynch and WriteAsynch methods on CWTask, the ReadAsynch and WriteAsynch methods on CWGPIB do not perform any parsing of the data.

## **Other GPIB Operations**

The GPIB control has methods to perform basic operations such as serial polling, parallel polling, triggering, and clearing the instrument. You can perform these methods with the following syntax.

```
CWGPIB1.SerialPoll
CWGPIB1.ParallelPoll
CWGPIB1.Trigger
CWGPIB1.Clear
```

# **Tutorial: Using the GPIB Control**

This tutorial shows you an example of using the GPIB control in a simple program to control a Fluke 45 multimeter. While the Fluke 45 and this example use a specific command set, you can control most other GPIB instruments in a similar manner. Substitute commands for your particular instrument in place of the Fluke 45-specific commands.

This tutorial uses Visual Basic syntax, but the discussion is in general terms so you can follow it in any compatible programming environment. Remember to adjust any code to your specific programming language. Refer to the *Building ComponentWorks Applications* chapters for information about implementing any step in different programming environments. You also can refer to the tutorial examples installed with ComponentWorks for a completed version of this example in several different programming environments.

## **Designing the Form**

- 1. Open a new project and form. If you are working in Visual C++, select a dialog-based application and name your project GPIBExample.
- 2. Load the ComponentWorks Instrument controls (specifically, the GPIB control) into your programming environment.
- 3. Place a GPIB control on the form. You configure its properties in the next section.
- 4. Place a text edit box control on the screen. Leave the Name property for the text edit box set to Text1.
- 5. Place a button control on the form. Change the Name and Caption properties of the button to FREQ.

Your form should look similar to the one show below.



Figure 8-2. GPIBExample Form

## **Setting the GPIB Control Properties**

You normally configure the default property values of the Instrument controls before you develop your program code. Most or all properties are set during design and do not change during program execution; however, you can edit the properties of the Instrument controls at run time, if necessary.

- 1. Open the custom property pages for the GPIB control on the form by right clicking on the control and selecting **Properties...**.
- In the General tab, select your GPIB instrument from the **Device** combobox. If it is not present, make sure that the GPIB driver software is properly installed and configuration software recognizes the instrument. Alternatively, you can manually select the GPIB board number and instrument address.
- 3. Select other communication parameters in the **Advanced** tab.
- 4. Open the **Test** property page for the GPIB control. To ensure that the control is properly communicating with the instrument, enter "\*IDN?" in the Send String box and press the **Execute** button. If your instrument







receives this command a string similar to "FLUKE, 45, 5005161, 1.6 D1.0" appears in the output window. You can send any string to the instrument from this property page. For example, for the Fluke 45 enter "val1?" in the Send String box and press the **Execute** button. A value appears in the output window. The **Execute** button performs both send and read operations.

## **Developing the Code**

Develop the code so that data is acquired and displayed in response to a user pressing the button. In the following steps, you define an event handler routine to be called when the **FREQ** button is pressed. In the event handler, you send a command to the Fluke 45 to read the frequency and display it in the text box on the user interface.

 Generate the event handler routine for the Click event of the FREQ button. The following code configures the GPIB control and sends a command to the Fluke 45 to switch it into frequency mode, reads the current value from the multimeter, and finally displays the value in the text edit box.

Add the following code to the FREQ\_Click subroutine. In Visual C++, remember to generate member variables for any controls referenced in the program. See the \Tutorial folder for Visual C++ and Delphi code examples.

```
Private Sub FREQ_Click()
    CWGPIB1.Configure
    CWGPIB1.Write "FREQ"
    CWGPIB1.Write "val1?"
    Text1.Text = CWGPIB1.Read
End Sub
```

2. Save the project as GPIBExample.

## **Testing Your Program**

Run and test the program. Click on the **FREQ** button. The value displayed in the text edit box should match the value displayed on the Fluke. By selecting a different mode of the instrument, you can perform other types of measurements using the Fluke 45. Change the "FREQ" command sent to the instrument with a corresponding command.

## The Serial Control

Use the Serial control to control serial instruments, such as scales and calipers, or to communicate with other devices connected to your serial port, including modems and fieldbus networks, using a serial connection and other computers. After setting the properties of the control, you can acquire data or send commands using method calls to the serial control and perform automated parsing of the returned data. To configure the properties of the control during design, right click on the control and select **Properties...** from the popup menu to open the property pages for the control.

The object hierarchy of the Serial control contains a Tasks collection and objects for parsing. Refer to *Advanced Parsing Features* earlier in this chapter for more information about accessing Pattern and Token objects.

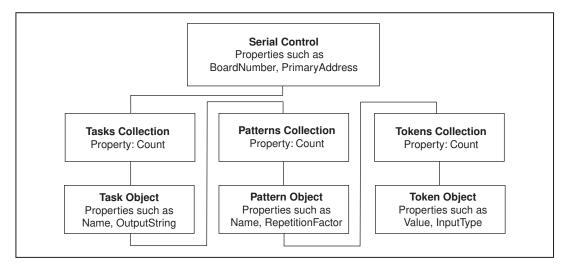


Figure 8-3. Serial Control Object Hierarchy

## **CWSerial Object**

The Serial object has serial-specific properties—ComPort, Parity, StopBits, DataBits, BaudRate, and EOSChar—that you use to specify and configure the communications port.

CWSerial1.ComPort = 2 'Instrument connected to COM port 2

The following settings must match the settings used by your instrument.

```
CWSerial1.Parity = cwParityEven
CWSerial1.BaudRate = 9600
CWSerial1.StopBits = cwStopBitsTwo
CWSerial1.DataBits = cwDataBitsEight
CWSerial1.EOSChar = "\10"
```

Other communication properties you can set include FlowControl, XonChar, and DTR.

#### **Methods and Events**

To begin communication with a serial instrument, use the Configure method. This method initializes a communication process with the serial instrument and configures it with the settings you specified for the control. You must call the Configure method in the following cases:

- Before calling any other control methods
- After changing any properties (for new properties to take effect)
- After calling the Reset method, before performing any serial I/O

```
Private Sub ConfigureDevice_Click()
        CWSerial1.Configure
End Sub
Private Sub ResetDevice_Click()
        CWSerial1.Reset
End Sub
```

## Synchronous I/O

You perform synchronous I/O using the Read and Write methods of the CWSerial control. Read accepts an optional parameter that specifies the buffer size. Unlike the Read method on CWTask, the Read method on CWSerial does not perform any parsing of the data.

The following example displays a string returned by a serial scale.

```
CWSerial1.Write "P\13"
Text1.Text = CWSerial1.Read
```

Many serial instruments require some termination character or characters, such as the carriage return or line feeds. In Visual Basic you can enter these unprintable characters using the backslash symbol (\) followed by the ASCII value of the character you want to send.

## Asynchronous I/O

You use the ReadAsynch and WriteAsynch methods to perform asynchronous I/O operations. These methods start a read or write operation, respectively, and then return immediately. When an asynchronous read is complete, the control generates a DataReady event and passes the data to your event handler. When an asynchronous write is complete, the control generates a WriteComplete event.

```
CWSerial1.ReadAsynch
Private Sub CWSerial1_DataReady(taskNumber as Short,
   data As Variant)
   Text1.Text = data
End Sub
```

Unlike the ReadAsynch and WriteAsynch methods on CWTask, the ReadAsynch and WriteAsynch methods on CWSerial do not perform any parsing of the data.

# **Tutorial: Using the Serial Control**

This tutorial shows you an example of using the Serial control in a simple program to control a serial scale. Other serial instruments behave differently and use different commands, but this tutorial provides a good illustration of how to use the Serial control and its parsing ability.

This tutorial uses Visual Basic syntax, but the discussion is in general terms so you can follow it in any compatible programming environment. Remember to adjust any code to your specific programming language. Refer to the *Building ComponentWorks Applications* chapters for information about implementing any step in different programming environments. You also can refer to the tutorial examples installed with ComponentWorks for a completed version of this example in several different programming environments.

## **Designing the Form**

- Open a new project and form. If you are working in Visual C++, select a dialog-based application and name your project SerialExample.
- Load the ComponentWorks instrument controls (specifically, the Serial control) into your programming environment.
- 3. Place a Serial control on the form. You configure its properties in the next section.





- 4. Place a text edit box control on the screen. Leave the Name property for the text edit box set to Text1.
- 5. Place a button control on the form. Change the Name and Caption properties of the button to Weigh.

Your form should look similar to the one show below.



Figure 8-4. Weigh Form

## **Setting the Serial Control Properties**

You normally configure the default property values of the Instrument controls before you develop your program code. Most or all properties are set during design and do not change during program execution; however, you can edit the properties of the Instrument controls at run time.

- 1. Open the custom property pages for the Serial control on the form by right clicking on the control and selecting **Properties...**.
- In the General tab, select the communications port to which your serial instrument is connected.
- On the General and the Flow Control property pages, adjust the
  properties of the control to match the setting of your instrument. These
  settings vary by instrument. Refer to your instrument documentation
  for details on specific instrument settings.
- 4. Open the **Test** property page for the Serial control. To ensure that the control is properly communicating with the instrument, enter "P\13" or another string compatible with your instrument in the Send String box and press the **Execute** button. A value, similar to "1.0040 Lbs 02" appears in the output window. The **Execute** button performs both send and read operations. Each instrument has a different command interface, which should be documented in your instrument manual.

Add a custom parsing task to the control in order to extract the number from the string.

- 5. Open the **Parsing** property page and press the **Task** button.
- 6. Click on the string New Task1 and change its name to Weight.

7. Add a pattern to the new parsing task by clicking the **Pattern** button.

Add the tokens that make up the parsing tasks.

- 8. Add a token to the pattern by clicking the **Token** button.
- 9. Change its value to a number by selecting <number> in the **Token** combobox at the top right.

Add a token to grab the rest of the string.

- 10. Click the **Token** button.
- 11. Change the value of the token to <string1>.
- 12. Select **Many** from the **Token Repeat** options and select the **Ignore Token** box. This token matches the rest of the string but is not returned as data.

Your **Parsing** page should look like the following figure.

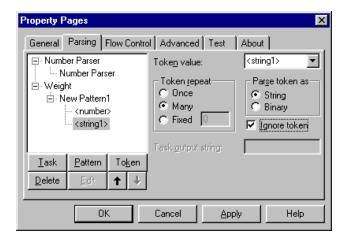


Figure 8-5. Serial Property Pages—Parsing Page

13. Click on **Apply** and **OK**.

Develop the code so that data is acquired and displayed in response to the button. In the following steps, you define an event handler routine to be called when the **Weigh** button is pressed. In the event handler, you send a command to the scale to read the weight and display the parsed and returned data in the text edit box.

Chapter 8

1. Generate the event handler routine for the Click event of the Weigh button. The following code calls the Configure method of the Serial control, sends the command "P\13" to prompt the scale to send back its current reading, and reads back the value from the scale using the Read method of the defined task. The returned information is automatically parsed by the corresponding Task object. Finally, it displays the returned value in the text edit box.

Add the following code to the Weigh\_Click subroutine. In Visual C++, remember to generate member variables for any controls referenced in the program. See the \tutorials folder for Visual C++ and Delphi code examples.

```
Private Sub Weigh_Click()
    CWSerial1.Configure
    CWSerial1.Write "P\13"
    Text1.Text = CWSerial1.Tasks.Item("Weight").Read
End Sub
```

Note

Because the weight task is the second task in the collection (after the built-in number parser task at index 1), you can specify the value 2 as an index to the Tasks collection instead of Weight.

2. Save the project as SerialExample.

## **Testing Your Program**

Run and test the program. Click on the **Weigh** button. The value displayed in the text edit box should match the value displayed on the scale. You can further enhance this example by making the read asynchronous. Change the Read method call to a ReadAsynch call, and display the value returned in the CWSerial1\_DataReady event handler.

# **Using the VISA Control**

This chapter describes the basic structure of the VISA API; shows you how to use the ComponentWorks VISA control in your application to perform input and output operations using GPIB, Serial, and VXI hardware; explains the control and its most commonly used properties, methods, and events; and includes tutorial exercises that give step-by-step instructions on using the control in simple programs.

Refer to the *Building ComponentWorks Applications* chapters for information about using the ComponentWorks controls in different programming environments. You can find additional information in the online reference, available by selecting **Programs»National Instruments ComponentWorks»ComponentWorks Online Reference** from the Windows **Start** menu.

## Overview of the VISA API

VISA is a standard I/O API for instrumentation programming. By itself, VISA does not provide instrumentation programming capability.

#### **VISA Structure**

VISA is a high-level driver that calls lower-level drivers. VISA can control VXI, GPIB, and serial instruments, as the hierarchy in Figure 9-1 indicates.

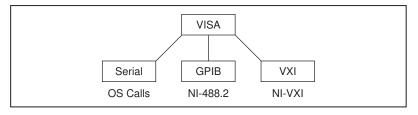


Figure 9-1. VISA Structure

When debugging VISA problems, remember that this hierarchy exists. Although VISA appears to be causing your problem, you might have a bug or installation problem with one of the drivers into which VISA is calling.

## **VISA Advantages**

VISA provides interface independence. Regardless of the interface type, VISA uses many of the same methods to communicate with instruments. For example, the VISA command to write an ASCII string to a message-based instrument is the same for Serial, GPIB, and VXI. This feature allows you to switch interfaces and use a single language to work with different interfaces for instruments.

VISA is an object-oriented language that can easily adapt to new instrumentation interfaces as they are developed in the future, which will enable programmers to easily move to new interfaces.

As an object-oriented language, VISA and its operations are intuitive. VISA provides the most frequently used functionality for instrumentation programming in a very compact command set.

## What is the VISA Control?

Use the VISA control to program your instruments and integrate these operations with the rest of the application. The VISA control, CWVISA, is an implementation of the VISA API. After setting the properties of the control, you can acquire data using simple method calls to the VISA control and perform automated parsing of the returned data. To configure the properties of a control during design, right click on the control and select **Properties...** from the popup menu to open the property pages for the control. From the property pages, you can intuitively set property values.

You can set most properties through the property pages as you design and create the program. In certain cases, you might need to change the value of one or more properties in your program code. Throughout this chapter, examples demonstrate how to change property values programmatically.

## **Object Hierarchy and Common Properties**

The ComponentWorks VISA control is made up of a hierarchy of simple objects. Understanding the relationship among the objects in a control is the key to properly programming with the control. Dividing a control into individual objects makes it easier to work with because each individual component has fewer parts.

Figure 9-2 shows the object hierarchy of the CWVISA control.

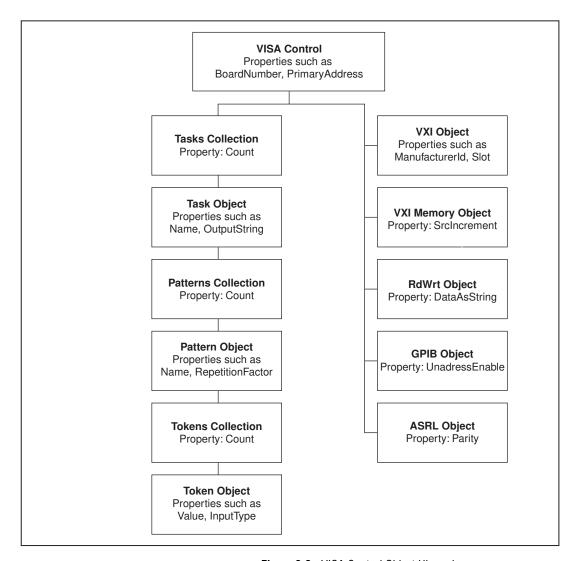


Figure 9-2. VISA Control Object Hierarchy

The VISA control contains a Tasks collection and underlying objects for parsing, an ASRL (Serial) object for serial properties, a RdWrt object for message-based I/O properties, a VXI Memory object for VXI register-access properties, a GPIB object for GPIB properties, and a VXI object for VXI specific properties.

A *collection* is a property of an object, which stores multiple instances of the same type of object. For example, the VISA control contains a Tasks collection object that contains multiple Task objects.

## **Common Instrument Control Features**

The VISA control uses the same parsing sub-objects as the GPIB and Serial controls. The Instrument controls share certain common properties.

SwapBytes—Some instruments return data in which the least significant byte appears first. This format is known as Little Endian format. Other instruments return data in which the address points to the most significant byte of the word, or in Big Endian format. Check your instrument documentation to determine if the instrument returns data in Big or Little Endian format. If your instrument returns data in Big Endian format, set the SwapBytes property of the RdWrt object to True, as in the following example:

CWVisa1.RdWrt.SwapBytes = True

ExceptionOnError—The Instrument controls handle error checking in two different ways. When an error occurs, each Instrument control generates an exception that your programming environment handles (default action). You can disable the generation of exceptions using the ExceptionOnError property of each Instrument control. If you disable exceptions on errors, the control fires an OnError event in response to an error condition and passes the error information to the OnError event handler. For some error conditions, such as those that occur during asynchronous operations, the control fires OnError events regardless of the value of ExceptionOnError.

DataAsString—Use the DataAsString property to specify if data is returned as a string or an array of bytes. If you set this property to True, the data is returned as a string. If you set this property to False, the data is returned as an array of bytes. You can set this property from the RdWrt page of the VISA property pages or in your program:

CWVisa1.RdWrt.DataAsString=True

# **Parsing**

As with the GPIB and Serial controls, you can use the VISA control to parse data into formats more easily used by your application. The VISA control supports multiple parsing tasks. Use these tasks to specify the way in which the data is parsed, and you can invoke different tasks at different times in your application.

Each task contains a group of patterns. These patterns are made up of one or more tokens, which are the basic building blocks for parsing. For example, a token might be a number, a 4-byte word, or a comma. A pattern might consist of a number token followed by a comma token. A parsing task might consist of this particular pattern repeated several times.

Parsed data is returned as an array of tokens. The control returns parsed data as an array of tokens. You can configure the control to ignore specific types of tokens and not return them in the array. For example, you might not want the commas returned in certain patterns. If you specify commas as ignored, only the numbers are returned in the array. Use the built-in pattern type Number Parser to automatically extract all numbers from the data and return them in an array. If only one number is present, it returns the number as a scalar (simple non-array variable).

For more detailed information about parsing objects, see *Advanced Parsing Features* in Chapter 8, *Using the GPIB and Serial Controls*. To use the parsing features in a tutorial, see *Tutorial: Using the Serial Control* in Chapter 8, *Using the GPIB and Serial Controls*.

# VISA Object

The VISA object has several properties for performing I/O with any interface (GPIB, Serial, or VXI). The most important is the resource name (RsrcName) property, which you can use to select the instrument being addressed by the VISA control. RsrcName specifies the exact name and location of a VISA resource, with the following format.

Interface Type[Board Index]::Address::VISA Class

- Interface Type—Specifies the I/O interface to which the device is connected (GPIB, ASRL (Serial), or VXI).
- Board Index—Specifies the index of the board. Use Board Index only if the system has more than one interface type. For example, if the system contains two GPIB plug-in boards, you can refer to one as GPIBO and the other as GPIBI.

- Address—For VXI instruments, the Address parameter is the logical address of the instrument. For GPIB instruments, Address is the GPIB primary address.
  - For GPIB communication with secondary addressing, add the secondary address to the resource name. For example, to communicate with a GPIB instrument with primary address 4 and secondary address 2, use the resource name GPIB::4::2::INSTR.
  - Do not use Address for serial instruments. For example, ASRL1::INSTR is the descriptor for the COM 1 serial port on a personal computer.
- VISA Class—Specifies the grouping that encapsulates some or all of the VISA methods. INSTR is the general class that encompasses all VISA methods. In the future, other classes might be added to the VISA specification. Currently, you are not required to include VISA Class, but you should include it to ensure future compatibility. Most applications use the INSTR class.

The VISA control can search the system for available resources. From the **General** property page, you can view all available resources in the **Resource Name** list box, as shown in Figure 9-3.

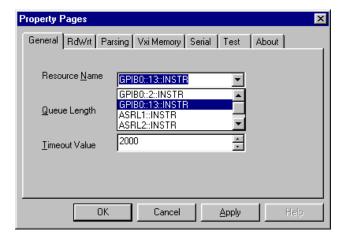


Figure 9-3. VISA Property Pages—General Page

Other general attributes include Queue Length and the Timeout Value.

- **Queue Length**—The length of the queue, used only with a synchronous method of event handling.
- **Timeout Value**—The value in milliseconds used for Input/Output (IO) operations.

You also can set these properties programmatically.

```
CWVisa1.RsrcName = "GPIB::2::INSTR"
CWVisa1.MaxQueueLength = 100
CWVisa1.Timeout = 1000
```

Other properties include InterfaceInstanceName, InterfaceType, InterfaceNumber, ResourceImplVersion, ResourceSpecVersion, and ResourceManufacturerName.

# **RdWrt Object**

The RdWrt object contains properties that apply to general message-based communication for any type of interface—GPIB, Serial, or VXI. Figure 9-4 shows the RdWrt object properties.

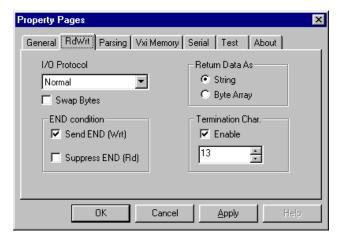


Figure 9-4. VISA Property Pages—RdWrt Page

- I/O Protocol—Usually left at Normal, but other options are available depending on the interface.
- **END condition**—Specifies whether the end condition is sent at the end of write operations.
- **Return Data As**—Specifies whether to return data as a string or byte array. You also can set this property programmatically.

Use the DataAsString property to specify the format of returned data. If you set this property to True, the data returns as a string. If you set this property to False, the data returns as an array of bytes. You can set this property from the **RdWrt** tab of VISA property page or programmatically.

CWVisa1.RdWrt.DataAsString = True

• **Termination Character**—Use the **Enable** feature to set a termination character for terminating read operations.

# Serial (ASRL) Object

The Serial object contains properties pertaining to VISA communication with a serial device. Use the settings to configure the serial port for serial communication, to check the state of serial hardware lines, and to check the number of bytes available in the serial input buffer. These properties include BaudRate, DataBits, StopBits, and FlowControl. You can set most of these properties on the **Serial** page of the VISA control property pages, as shown in the following figure.

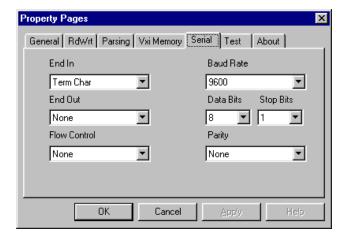


Figure 9-5. VISA Property Pages—Serial Page

# **GPIB Object**

The GPIB object contains properties pertaining to VISA communication with a GPIB resource. Two of these properties, PrimaryAddess and SecondaryAddress, are read only. Use the other two properties, ReaddressEnable and UnaddressEnable, to enable readressing or unaddressing after GPIB read and write operations. By default, ReaddressEnable is enabled and UnaddressEnable is disabled.

# VXI Object

The VXI object contains properties pertaining to VISA communication with a VXI device. All properties, including ManufacturerId, Slot, and ModelCode, are read only. Use the properties to access information obtained by the VXI Resource Manager utility when it configures the VXI system.

### **Methods and Events**

To begin controlling a resource with the VISA control, use the <code>Open</code> method. This method initializes the resource and configures it with the settings that you specified for the control. You must call <code>Open</code> before you can call any other methods of the control. If you call the <code>Close</code> method at any point in the program, you must call <code>Open</code> again before performing any I/O.

```
Private Sub OpenDevice_Click()
    CWVisal.Open
End Sub
Private Sub CloseDevice_Click()
    CWVisal.Close
End Sub
```

# **Message-Based Communication**

All serial and GPIB devices, and many VXI devices, recognize a variety of message-based command strings. With the VISA control, the actual protocol used to send a command string to an instrument is transparent. You need to specify only whether you want to write a message or read a message from a message-based device.

Note

The same methods are used to write message-based commands to GPIB, serial, and message-based VXI instrument. VISA automatically knows which functions to call based on the type of resource being used.

## Synchronous I/O

You perform synchronous message-based I/O using the Read and Write methods of the CWVisa control. Read accepts an optional parameter that specifies the buffer size. If you omit this parameter, the buffer size is specified by the DefaultBufferSize property. Unlike the Read method on CWTask, the Read method on CWVisa does not perform any parsing of the data.

The following example displays the identification string returned by many message-based instruments. The control first writes the command \*IDN? to the instrument and then reads back and displays the response in a text box in the program.

```
CWVisal.Write "*IDN?"
Text1.Text = CWVisal.Read
```

## Asynchronous I/O

You use the ReadAsynch and WriteAsynch methods to perform asynchronous message-based I/O operations. These methods start a read or write operation, respectively, and then return immediately. When an asynchronous read is complete, the control generates a DataReady event and passes the data to your event handler. When an asynchronous write is complete, the control generates a WriteComplete event.

```
Private Sub CWVisa2_DataReady(ByVal taskNumber As
  Integer, ByVal Data As Variant)
   Text1.Text = Data
End Sub
```

Both of these operations also generate the IOCompletion event when they finish. You can use these events when you want your program to continue executing other tasks during a long write or read operation.

Unlike the ReadAsynch and WriteAsynch methods on CWTask, the ReadAsynch and WriteAsynch methods on CWVisa do not perform any parsing of the data.

### **Register-Based Communication**

Some VXI instruments do not support message-based commands. To communicate with these instruments, use register accesses. The VISA control contains a set of register access methods that you can use with VXI instruments.

Because all VXI instruments have configuration registers in the upper 16 kilobytes of A16 memory space, you can use register access functions to read from and write to the configuration registers for message-based devices. To read a value from a register, use the basic VISA In method. Three different versions of the In operation exist so you can read 8-, 16-, or 32-bit values.

You can set the properties related to VXI register accesses in the **VXI Memory** page of the VISA property pages, as shown in the following figure.

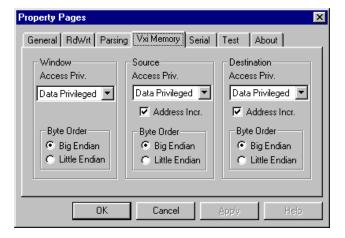


Figure 9-6. VISA Property Pages—VxiMemory Page

The Access Privilege property specifies the VME access privilege. The Byte Order property specifies the byte order used in performing register accesses. The Source and Destination attributes apply to the high-level register access operations. The Address Increment properties apply to the MoveIn and MoveOut methods only. The Window attributes apply to lower-level register access methods only.

#### High-Level Register Accesses with the In and Out Methods

The parameters for the In16 method, space and offset, specify the address space and the offset. The address space is an enumeration indicating whether the A16, A24, or A32 space is being accessed. The following list includes the constants for the different address spaces.

| Constant Name | Description |
|---------------|-------------|
| cwVxiA16Space | A16         |
| cwVxiA24Space | A24         |
| cwVxiA32Space | A32         |

The **offset** parameter is a long integer specifying the address in the indicated address space. Remember that VISA keeps track of the base memory address that a device requests in each address space. The **offset** input is relative to this base address. For example, suppose that you have a device at logical address 1 and want to use the In16 method to read its ID/Logical Address configuration register. This register is at absolute address 0xC040 in A16 space and the configuration registers for the device at logical address 1, range from 0xC040 to 0xC07F. Because VISA also holds this information, you only need to specify the offset in the region you want to access. In this case, that offset is zero.

The Out 16 method uses the address space and offset parameters in addition to a third integer parameter, which specifies the value to be written to the register. Do not use the VISA Out methods on read-only registers.

#### Moving Blocks of Data with the Moveln and MoveOut Methods

Use the MoveIn and MoveOut methods to move large blocks of 8-, 16-, or 32-bit data from a VXI address space to local memory or from local memory to a VXI address space. The Move methods are efficient operations, and you should use them for block transfers of data. If you do not select the Address Increment property, the block of data moves to a single location (FIFO) rather than to a corresponding block.

In addition to the MoveIn and MoveOut methods, you can use the Move and MoveAsync methods with a special resource of the MEMACC class (instead of INSTR class). This resource has access to all VXI address spaces via absolute addresses (instead of relative offsets for a particular resource). Move and MoveAsync can move data from one VXI memory range to another as well as to or from local memory.

#### Low-Level Register Accesses with the Peek and Poke Methods

If the high-level In and Out methods cannot sufficiently perform register accesses, you can use the lower-level methods. Low-level register access methods use the User Window specified in the controller's VXI Configuration utility to access the VXI/VMEbus. The Peek XX method reads registers, and the PokeXX method writes to registers, where XX specifies the corresponding size in bits of the access (8, 16, or 32). The Peek and Poke methods are generally faster than the corresponding In and Out methods.

Before you can use these methods, map a part of the VXI memory space to local memory with the MapAddress method. The MapAddress method takes the following input: address space, base VXI address, size of memory (in bytes), and a suggested local address to which the memory can be mapped. MapAddress returns the actual local address to which the specified base VXI address was mapped. If the MapAddress method completes without an error, check the WinBaseAddr and WinSize properties under the VxiMemory object to verify the actual size of the window that was mapped.

Note

Before attempting to use the Peek and Poke methods, verify that the MapAddress method executed successfully. If the operation did not successfully execute, the system can crash.

Use the following steps as a guideline for developing a program that performs low-level register accesses.

- 1. Set the property pages for the resource that you want to access.
- 2. Call the Open method.
- 3. Use the MapAddress method to map a region of a VXI address space to local memory.
- Check the mapped window size and window base to make sure you do not access an area outside this window.
- 5. Perform Peek and Poke operations.
- 6. Call the UnMapAddress method to free the window.
- 7. Call the Close method.

If you want to access another VXI address space using low-level register access functions, unmap your current window and remap it to the region that you want to peek or poke.

#### **Events**

In VISA, events provide communication between VISA resources and a VISA application. Events are generated when certain conditions occur in the system. When the specified conditions occur, the corresponding event handler routine is called. To respond to an event, place the code that you want to execute into the event handler routine. Some events return additional information in the form of a VisaEvent object, but most events simply indicate that a specific condition occurred.

When should you use events? Consider the following situation. Suppose that you have a sophisticated message-based VXI device in your chassis that can perform a variety of different measurement operations, but some measurements require several minutes for the device to obtain a stable reading. After writing the command to the device to get the measurement, you cannot be sure when the measurement is complete. After performing the write operation, you can continuously attempt to perform VISA reads from the device until one is successful. Alternatively, you might attempt to read the result infrequently until it is available or wait a long time before checking to see if the result is available.

Several problems arise with these solutions. Continuous polling interferes with concurrent operations, such as controlling other instruments, writing data to disk, or updating the screen display. Also, these methods do not provide timely solutions. This scenario illustrates the need for other means of communication between VISA resources and a VISA application. Events provide this alternate means of communication.

# **Event Types**

In addition to the events produced by asynchronous I/O operations, the VISA control generates the following events.

- ServiceRequest—Notifies the application when a device requests service from its controller. This event returns the status byte that was obtained by serial polling the device generating the request. This event is primarily produced by GPIB devices asserting the GPIB SRQ line and message-based VXI devices.
- Trigger—Notifies the application when a device asserts a trigger line
  on the VXI backplane. The returned VisaEvent object contains a
  TriggerId property specifying the trigger line with which the event
  is associated. When you set the TriggerId property of the VISA
  control, the Trigger event is sensitized to a single trigger line each
  time. You must set the line before you can start responding to trigger

events on that trigger line. For example, you can receive trigger events for triggers on TTL Trigger Line 5 with the following code.

```
CWVisa1.TriggerId = cwTrigTTL5
CWVisa1.EnableEvent CWVisaEventTrigger
```

To detect triggers on two different trigger lines at the same time, use a second VISA control.

• VxiSignalProc—Notifies the application when a device asserts an interrupt on the VXI backplane or produces a VXI signal. When a VXI interrupt or signal occurs, there is a StatusId value associated with the event. This value is returned by the VxiSignalProc event. Unlike triggers, a VXI interrupt on any of the interrupt levels produces a VxiSignalProc event. The lower 8 bits of this StatusId are set to the logical address of the device creating the signal or interrupt. VISA checks this StatusId value and generates an event only if the device creating the event is the device specified by the resource name property.

The following code fragment checks the StatusId value associated with a VxiSignalProc event.

```
Text1.Text = VisaEvent.StatusId
End Sub
```

The VxiSignalProc event does not return the actual interrupt line that was asserted on the backplane. If you need the actual interrupt line, use the VxiVmeInterrupt event.

VxiVmeInterrupt—Notifies the application when a device asserts
an interrupt on the VXI backplane. This event is similar to the
VxiSignalProc event except it is produced only for VXI or VME
interrupts, not signals. It also returns the interrupt line on which the
interrupt occurred and the StatusId.

# **Event Handling With The Event Queue**

The VISA control provides an alternative mechanism for responding to events. Instead of implementing event handlers in your program code, you can configure the VISA control to place events in a queue from which you can later retrieve them. Use the EnableEvent method to specify the VISA events that the control should place in a queue. Set the VISA event type in the parameter for this method.

CWVisa1.EnableEvent cwVisaEventVXIVMEInterrupt

After this call, events are placed in the event queue as they occur. The maximum size of the queue is determined by the Queue Length property. The default size is 50 entries. If more than 50 entries are received before any are removed from the queue, the entries are discarded.

Note

The VISA control automatically calls the EnableEvent on all event types except Trigger when a VISA session is opened. If you are concerned with events that occur at certain points in your program, use commands to empty the queue or disable the queuing of events. See the following sections, Discarding Events From The Queue, and Disabling The Event Queue, for more information.

# **Checking Events in the Queue**

In your program code, use the WaitOnEvent method to check the queue for events. The WaitOnEvent parameters specify the event type for which to wait, the timeout for waiting, and a return parameter for the event (if one is received). To determine if any events are currently in the event queue, specify a timeout of zero.

The following code fragment checks the event queue to determine if a VXIVMEInterrupt is available in the queue, and if one is available, it obtains the StatusId value of the interrupt.

If the  ${\tt WaitOnEvent}$  method is successful, it removes the oldest event from the queue.

# **Discarding Events From The Queue**

To empty the event queue of all of its current events, use the DiscardEvents method.

CWVisa1.DiscardEvents cwVisaEventVXIVMEInterrupt

# **Disabling The Event Queue**

To stop events from being placed in the queue, use the DisableEvent method.

CWVisa1.DisableEvent cwVisaEventVXIVMEInterrupt

To continue queuing events, call the EnableEvent method again. If you call DisableEvent and then call EnableEvent later in the program, all events present in the queue when you called DisableEvent are still present in the queue.



When the event queue fills up, subsequent events are discarded.

# Tutorial: Using the VISA Control for Message-Based Communication

This tutorial shows you an example of using the VISA control in a simple program to control a GPIB Fluke 45 multimeter. While the Fluke 45 and this example use a specific command set, you can control most other message-based instruments in a similar manner. Substitute commands for your particular instrument in place of the Fluke 45-specific commands.

This tutorial uses Visual Basic syntax, but the discussion is in general terms so you can follow it in any compatible programming environment. Remember to adjust any code to your specific programming language. Refer to the Building ComponentWorks Applications chapters for information about implementing any step in different programming environments. You also can refer to the tutorial examples installed with ComponentWorks for a completed version of this example in several different programming environments.

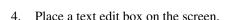
# **Designing the Form**

Open a new project and form. If you are working in Visual C++, select a dialogue-based application and name your project MbasedExample.

3. Place a VISA control on your form. You configure its properties in the

Load the ComponentWorks VISA control into your programming environment.





next section.



5. Set the Name property for the text box to Text1.



- Place a button control on the form.
- Change the Name and Caption properties to FREQ.

Your form should look similar to the one shown below.

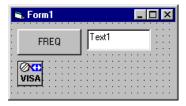


Figure 9-7. MbasedExample Form

# **Setting the VISA Control Properties**

You normally configure the default property values of the VISA control before you develop your program code. When using the VISA control, most or all properties are set during design and do not change during program execution. If necessary, you can edit the properties of the VISA control at run time.

- 1. Open the custom property pages for the VISA control on the form by right clicking on the control and selecting **Properties...**.
- 2. In the General tab, select the resource name for your GPIB instrument from the Resource Name pull-down menu. If it is not present, make sure that the GPIB and VISA driver software is installed properly. Alternately, you can manually enter a resource name. For more information about manually entering resource names, see the VISA Object section earlier in this chapter.
- 3. Open the **RdWrt** property page for the VISA control. If your instrument uses a termination character or needs some other property change, enter the settings.
- 4. Open the **Test** property page for the VISA control.
- 5. To ensure that the control is properly communicating with the instrument, enter "\*IDN?" in the Send String box and press the Execute button. If your instrument understands this command, a string similar to "FLUKE, 45, 5005161, 1.6 D1.0" appears in the output window. You can send any string to the instrument from this property page. For example, for the Fluke 45, enter "vall?" in the Send String box and press the Execute button. A value appears in the output window. The Execute button performs both write and read operations.

# **Developing the Code**

Develop the code so that data is acquired and displayed in response to a user pressing the button. In the following steps, you define an event handler routine to be called when the **FREQ** button is pressed. In the event handler, you send a command to the Fluke 45 to read the frequency and display it in the text edit box.

Generate the event handler routine for the Click event of the FREQ button. The following code opens the VISA control and sends a command to the Fluke 45 to switch it into the frequency mode, reads the current value from the multimeter, and displays the value in the text box.

Add the following code to the FREQ\_Click subroutine. In Visual C++, remember to generate member variables for any controls referenced in the program.

```
Private Sub FREQ_Click ()
    CWVisal.Open
    CWVisal.Write "FREQ"
    CWVisal.Write "vall?"
    Text1.Text = CWVisal.Read
End Sub
```

2. Save the project as MbasedExample.

# **Testing Your Program**

Run and test the program. Click on the **FREQ** button. The value displayed in the text edit box should match the value displayed on the Fluke. By selecting different modes, you can perform other types of measurements using the Fluke 45. Change the "FREQ" command sent to the instrument with a corresponding command, such as "VDC" for volts.

A very similar project can be used to communicate with a message-based serial or VXI device. Set the serial port configuration on the **Serial** property page to match the necessary settings for the serial instrument.

# Tutorial: Using the VISA Control for Register-Based Communication

This tutorial shows you an example of using the VISA control to read the value of configuration registers for a VXI device.

This tutorial uses Visual Basic syntax, but the discussion is in general terms so you can follow it in any compatible programming environment. Remember to adjust any code to your specific programming language. Refer to the *Building ComponentWorks Applications* chapters for information about implementing any step in different programming environments. You also can refer to the tutorial examples installed with ComponentWorks for a completed version of this example in several different programming environments.

# **Designing the Form**

- Open a new project and form. If you are working in Visual C++, select a dialogue-based application and name your project RbasedExample.
- 2. Load the ComponentWorks VISA control and the ComponentWorks User Interface controls into your programming environment.
- 3. Place a VISA control on your form. You configure its properties in the next section.
- Place a numeric edit box on the screen. Set the Name property for the numeric edit box to Offset.

Right click on the Offset object and select **Properties...**.

On the Numeric page, set Maximum range checking to 64, Values to Discrete, Base to 0, Interval to 2, and the Increment value of the Inc/Dec button to 2.

5. Place a second numeric edit box on the form. Set the Name property of the second numeric edit box to Val.

Select the Val object.

On the **Style** page, set **Control mode** to Indicator and uncheck the **Visible** box of the **Inc/Dec button** setting.

Add labels with the appropriate names for the two numeric edit controls.







Your form should look similar to the one shown below.

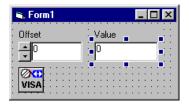


Figure 9-8. RbasedExample Form

# **Setting the VISA Control Properties**

You normally configure the default property values of the VISA control before you develop your program code. Most or all properties are set during design and do not change during program execution. If necessary, you can edit the properties of the VISA control at run time.

- 1. Open the custom property pages for the VISA control on the form by right clicking on the control and selecting **Properties...**.
- 2. In the General tab, select the resource name for your VXI instrument from the Resource Name pull-down menu. If it is not present, make sure that the VXI and VISA driver software is installed properly. Alternately, you can manually enter a resource name. For more information about entering resource names, see the VISA Object section earlier in this chapter.

# **Developing the Code**

Develop the code so that a configuration register is read and displayed in response to a user entering an offset value. For the Offset numeric edit control, define an event handler routine to be called when the offset value changes. In the event handler, read and display the configuration register at the specified offset in the numeric edit box on the user interface.

 Generate the event handler routine for the ValueChanged event of the Offset control. In the event handler, open the VISA control, read a configuration register, and display the value in the numeric edit box in hexadecimal format.

Add the following code to the Offset\_ValueChanged subroutine. In Visual C++, remember to generate member variables for any controls referenced in the program.

2. Add the following line to the Form\_Load subroutine.

3. Save the project as RbasedExample.

# **Testing Your Program**

Run and test the program. Try reading the value of configuration registers at various offsets. Keep in mind that all VXI devices are required to implement at least four basic configuration registers (offsets 0, 2, 4, and 6).

# Using the Analysis Controls and Functions

This chapter describes how you can use the ComponentWorks Analysis controls to perform data analysis, manipulation, and simulation. It explains the individual controls and some of their functions and includes a tutorial that gives step-by-step instructions on using the Analysis controls in a simple program.

With the ComponentWorks analysis controls, you can perform operations such as matrix and array calculations, frequency analysis, statistical analysis and signal generation. The analysis functions are methods on different Analysis controls that are organized by functionality.

Refer to the *Building ComponentWorks Applications* chapters for information about using the ComponentWorks controls in different programming environments. You can find a detailed description of each individual analysis function in the online reference, which is available by selecting **Programs»National Instruments ComponentWorks» ComponentWorks Reference** from the Windows **Start** menu.

# What Are the Analysis Controls?

ComponentWorks includes five ActiveX controls with more than 200 analysis functions. The functions are grouped into controls according to their functionality.

| Control   | Functionality   |
|-----------|---|
| CWArray   | Array manipulation functions                              |
| CWComplex | Complex scalars and array manipulation functions          |
| CWMatrix  | Vector and matrix algebra functions                       |
| CWStat    | Statistical functions                                     |
| CWDSP     | Digital signal processing and signal generation functions |

# **Analysis Library Versions**

ComponentWorks is distributed with one of three different versions of the analysis library. Each version contains a different set of functions in the library. The functions available to you depend on the package of ComponentWorks you purchased.

- Base Analysis Library, ComponentWorks Base Package—Includes simple matrix algebra, array and complex number functions, and simple statistics functions.
- Digital Signal Processing (DSP) Analysis Library, *ComponentWorks Standard Development System*—Includes the functions of the Base Analysis Library plus DSP functions (time and frequency domain analysis, filters, windows), curve fitting functions, advanced array and complex number functions, and measurement functions.
- Advanced Analysis Library (AAL), ComponentWorks Full
   Development System—Includes the functions of the DSP analysis
   library plus advanced statistics and matrix algebra functions.

Although specific analysis functions or controls might not be part of your analysis library, every function and control is shown in your development environment, such as the Visual Basic Object Browser or the Visual C++ Component Gallery. When you attempt to use a function that is not included in your analysis library, an error message appears to notify you that the function is not supported. See *Adding Testing and Debugging to Your Application* section in Chapter 12, *Using the Analysis Controls and Functions*, for more information.

Table 10-1, *Analysis Control Function Tree*, lists all the analysis functions, grouped by control. The last column specifies the ComponentWorks version that includes the specific function.

- Base—Base Package (also in Standard and Full Development System)
- Standard—Standard Development System (also in Full Development System)
- Full—Full Development System

Table 10-1. Analysis Control Function Tree

| Control | Function                     | Function Name | Development<br>System |
|---------|------------------------------|---------------|-----------------------|
| CWArray | 1D 2D Operations             |               |                       |
|         | 1D Maximum & Minimum         | MaxMin1D      | Base                  |
|         | 1D Array Subset              | Subset1D      | Base                  |
|         | 1D Array Reverse             | Reverse1D     | Standard              |
|         | 1D Array Shift               | Shift1D       | Standard              |
|         | 1D Array Sort                | Sort1D        | Base                  |
|         | 1D Array Interleave          | Interleave1D  | Base                  |
|         | 2D Array Transpose           | Transpose2D   | Base                  |
|         | MultiDimensional Element Ope | erations      | -                     |
|         | Array Addition               | AddArray      | Base                  |
|         | Array Subtraction            | SubArray      | Base                  |
|         | Array Multiplication         | MulArray      | Base                  |
|         | Array Division               | DivArray      | Base                  |
|         | Absolute Value               | AbsArray      | Base                  |
|         | Negative Value               | NegArray      | Base                  |
|         | Linear Evaluation            | LinEvArray    | Base                  |
|         | Polynomial Evaluation        | PolEvArray    | Standard              |
|         | Scaling                      | ScaleArray    | Standard              |
|         | Quick Scaling                | QScaleArray   | Standard              |
|         | Array Clipping               | ClipArray     | Standard              |
|         | Array Clearing               | ClearArray    | Base                  |

**Table 10-1.** Analysis Control Function Tree (Continued)

| Control     | Function                                  | Function Name  | Development<br>System |  |
|-------------|---|----------------|-----------------------|--|
| CWArray     | Array Setting                             | SetArray       | Base                  |  |
| (continued) | Array Copying                             | CopyArray      | Base                  |  |
|             | Array Normalizing                         | NormalizeArray | Standard              |  |
|             | Variant Conversion                        | VarToDblArray  | Base                  |  |
|             | MultiDimensional Array Operatio           | ons            |                       |  |
|             | Array Size                                | ArraySize      | Base                  |  |
|             | Sum of Elements                           | SumArray       | Standard              |  |
|             | Product of Elements                       | ProArray       | Standard              |  |
|             | Extract complete dimensions(s) from array | IndexArray     | Base                  |  |
|             | Array Subset                              | SubsetArray    | Base                  |  |
|             | Maximum and Minimum of Array              | MaxMinArray    | Base                  |  |
|             | Search Array                              | SearchArray    | Base                  |  |
|             | Build/Concatenate Array                   | BuildArray     | Base                  |  |
|             | Reshape Array                             | ReshapeArray   | Base                  |  |
| CWComplex   | Complex Numbers                           |                |                       |  |
|             | Complex Addition                          | CxAdd          | Base                  |  |
|             | Complex Subtraction                       | CxSub          | Base                  |  |
|             | Complex Multiplication                    | CxMul          | Base                  |  |
|             | Complex Division                          | CxDiv          | Base                  |  |
|             | Complex Reciprocal                        | CxRecip        | Base                  |  |

**Table 10-1.** Analysis Control Function Tree (Continued)

| Control     | Function                    | Function Name | Development<br>System |
|-------------|-----------------------------|---------------|-----------------------|
| CWComplex   | Complex Square Root         | CxSqrt        | Standard              |
| (continued) | Complex Logarithm           | CxLog         | Standard              |
|             | Complex Natural Log         | Cxlon         | Standard              |
|             | Complex Power               | CxPow         | Standard              |
|             | Complex Exponential         | CxExp         | Standard              |
|             | Rectangular to Polar        | ToPolar       | Base                  |
|             | Polar to Rectangular        | ToRect        | Base                  |
|             | MultiDimensional Complex Op | erations      |                       |
|             | Complex Addition            | CxAddArray    | Base                  |
|             | Complex Subtraction         | CxSubArray    | Base                  |
|             | Complex Multiplication      | CxMulArray    | Base                  |
|             | Complex Division            | CxDivArray    | Base                  |
|             | Complex Linear Evaluation   | CxLinEvArray  | Base                  |
|             | Rectangular to Polar        | ToPolarArray  | Base                  |
|             | Polar to Rectangular        | ToRectArray   | Base                  |
| CWMatrix    | Vector & Matrix Algebra     | •             |                       |
|             | Dot Product                 | DotProduct    | Base                  |
|             | Matrix Multiplication       | MatrixMul     | Base                  |
|             | Matrix Inversion            | InvMatrix     | Base                  |
|             | Transpose                   | Transpose     | Base                  |
|             | Determinant                 | Determinant   | Base                  |

**Table 10-1.** Analysis Control Function Tree (Continued)

| Control     | Function                       | Function Name    | Development<br>System |
|-------------|--------------------------------|------------------|-----------------------|
| CWMatrix    | Unit Vector                    | UnitVector       | Base                  |
| (continued) | Trace                          | Trace            | Full                  |
|             | Solution of Linear Equations   | LinEqs           | Full                  |
|             | LU Decomposition               | LU               | Full                  |
|             | Forward Substitution           | ForwSub          | Full                  |
|             | Backward Substitution          | BackSub          | Full                  |
| CWStat      | Statistics                     | ·                |                       |
|             | Mean                           | Mean             | Base                  |
|             | Standard Deviation             | StdDev           | Base                  |
|             | Variance                       | Variance         | Full                  |
|             | Mean Squared Error             | MeanSquaredError | Full                  |
|             | RootMean Squared Value         | RMS              | Full                  |
|             | Moments about the Mean         | Moment           | Full                  |
|             | Median                         | Median           | Full                  |
|             | Mode                           | Mode             | Full                  |
|             | Histogram                      | Histogram        | Base                  |
|             | Probability Distributions      | •                |                       |
|             | Normal Distribution Function   | N_Dist           | Full                  |
|             | TDistribution Function         | T_Dist           | Full                  |
|             | FDistricution Function         | F_Dist           | Full                  |
|             | $\chi^2$ Distribution Function | XX_Dist          | Full                  |

**Table 10-1.** Analysis Control Function Tree (Continued)

| Control               | Function                                | Function Name     | Development<br>System |
|-----------------------|---|-------------------|-----------------------|
| CWStat<br>(continued) | Normal Distribution Inverse<br>Function | InvN_Dist         | Full                  |
|                       | TDistribution Inverse Function          | InvF_Dist         | Full                  |
|                       | FDistribution Inverse Function          | InvF_Dist         | Full                  |
|                       | $\chi^2$ Distribution Inverse Function  | InvXX_Dist        | Full                  |
|                       | Analysis of Variance                    |                   |                       |
|                       | One-way Analysis of Variance            | ANOVA1Way         | Full                  |
|                       | Two-way Analysis of Variance            | ANOVA2Way         | Full                  |
|                       | Three-way Analysis of Variance          | ANOVA3Way         | Full                  |
|                       | Nonparametric Statistics                |                   |                       |
|                       | Contingency Table                       | Contingency_Table | Full                  |
|                       | Curve Fitting                           |                   |                       |
|                       | Linear Fit                              | LinFit            | Standard              |
|                       | Exponential Fit                         | ExpFit            | Standard              |
|                       | Polynomial Fit                          | PolyFit           | Standard              |
|                       | General Least Squares Linear Fit        | GenLSFit          | Standard              |
|                       | Interpolation                           | •                 | •                     |
|                       | Polynomial Interpolation                | PolyInterp        | Full                  |
|                       | Rational Interpolation                  | RatInterp         | Full                  |
|                       | Spline Interpolation                    | SpInterp          | Full                  |
|                       | Spline Interpolant                      | Spline            | Full                  |

**Table 10-1.** Analysis Control Function Tree (Continued)

| Control | Function                    | Function Name | Development<br>System |
|---------|-----------------------------|---------------|-----------------------|
| CWDSP   | Signal Generation           |               |                       |
|         | Impulse                     | Impulse       | Standard              |
|         | Pulse                       | Pulse         | Standard              |
|         | Ramp                        | Ramp          | Standard              |
|         | Triangle                    | Triangle      | Standard              |
|         | Sine Pattern                | SinePattern   | Standard              |
|         | Uniform Noise               | Uniform       | Standard              |
|         | White Noise                 | WhiteNoise    | Standard              |
|         | Gaussian Noise              | GaussianNoise | Standard              |
|         | Arbitary Wave               | ArbitaryWave  | Standard              |
|         | Chirp                       | Chirp         | Standard              |
|         | Sawtooth Wave               | SawtoothWave  | Standard              |
|         | Sinc Waveform               | Sinc          | Standard              |
|         | Sine Waveform               | SineWave      | Standard              |
|         | Square Wave                 | SquareWave    | Standard              |
|         | Triangle Wave               | TriangleWave  | Standard              |
|         | Frequency Domain Signal Pro | ocessing      |                       |
|         | FFT                         | FFT           | Standard              |
|         | Inverse FFT                 | InvFFT        | Standard              |
|         | Real Valued FFT             | ReFFT         | Standard              |
|         | Real Value Inverse FFT      | ReInvFFT      | Standard              |

**Table 10-1.** Analysis Control Function Tree (Continued)

| Control     | Function                      | Function Name | Development<br>System |
|-------------|-------------------------------|---------------|-----------------------|
| CWDSP       | Power Spectrum                | Spectrum      | Standard              |
| (continued) | FHT                           | FHT           | Standard              |
|             | Inverse FHT                   | InvFHT        | Standard              |
|             | Cross Spectrum                | CrossSpectrum | Standard              |
|             | Time Domain Signal Processing |               |                       |
|             | Convolution                   | Convolve      | Standard              |
|             | Correlation                   | Correlate     | Standard              |
|             | Integration                   | Integrate     | Standard              |
|             | Differentiate                 | Difference    | Standard              |
|             | Pulse Parameters              | PulseParam    | Standard              |
|             | Decimate                      | Decimate      | Standard              |
|             | Deconvolve                    | Deconvolve    | Standard              |
|             | UnWrap Phase                  | UnWrapID      | Standard              |
|             | IIR Digital Filters           |               |                       |
|             | Lowpass Butterworth           | Bw_LPF        | Standard              |
|             | Highpass Butterworth          | Bw_HPF        | Standard              |
|             | Bandpass Butterworth          | Bw_BPF        | Standard              |
|             | Bandstop Butterworth          | Bw_BSF        | Standard              |
|             | Butterworth Coefficients      | BwCoef        | Standard              |
|             | Lowpass Chebyshev             | Ch_LPF        | Standard              |
|             | Highpass Chebyshev            | Ch_HPF        | Standard              |
|             | Bandpass Chebyshev            | Ch_BPF        | Standard              |

**Table 10-1.** Analysis Control Function Tree (Continued)

| Control     | Function                       | Function Name | Development<br>System |
|-------------|--------------------------------|---------------|-----------------------|
| CWDSP       | Bandstop Chebyshev             | Ch_BSF        | Standard              |
| (continued) | Chebyshev Coefficients         | ChCoef        | Standard              |
|             | Lowpass Inverse Chebyshev      | InvCh_LPF     | Standard              |
|             | Highpass Inverse Chebyshev     | InvCh_HPF     | Standard              |
|             | Bandpass Inverse Chebyshev     | InvCh_BPF     | Standard              |
|             | Bandstop Inverse Chebyshev     | InvCh_BSF     | Standard              |
|             | Inverse Chebyshev Coefficients | InvChCoef     | Standard              |
|             | Lowpass Elliptic               | Elp_LPF       | Standard              |
|             | Highpass Elliptic              | Elp_HPF       | Standard              |
|             | Bandpass Elliptic              | Elp_BPF       | Standard              |
|             | Bandstop Elliptic              | Elp_BSF       | Standard              |
|             | Elliptical Coefficients        | ElpCoef       | Standard              |
|             | IIR Filtering                  | IIRFiltering  | Standard              |
|             | FIR Digital Filters            |               |                       |
|             | Lowpass Window                 | Wind_LPCoef   | Standard              |
|             | Highpass Window                | Wind_HPCoef   | Standard              |
|             | Bandpass Window                | Wind_BPCoef   | Standard              |
|             | Bandstop Window                | Wind_BSCoef   | Standard              |
|             | Lowpass Kaiser Window          | Ksr_LPCoef    | Standard              |
|             | Highpass Kaiser Window         | Ksr_HPCoef    | Standard              |
|             | Bandpass Kaiser Window         | Ksr_BPCoef    | Standard              |
|             | Bandstop Kaiser Window         | Ksr_BSCoef    | Standard              |

**Table 10-1.** Analysis Control Function Tree (Continued)

| Control     | Function                | Function Name  | Development<br>System |
|-------------|-------------------------|----------------|-----------------------|
| CWDSP       | General EquiRipple FIR  | Equi_Ripple    | Standard              |
| (continued) | Lowpass EquiRipple FIR  | EquiRpl_LPCoef | Standard              |
|             | Highpass EquiRipple FIR | EquiRpl_HPCoef | Standard              |
|             | Bandpass EquiRipple FIR | EquiRpl_BPCoef | Standard              |
|             | Bandstop EquiRipple FIR | EquiRpl_BSCoef | Standard              |
|             | Windows                 |                |                       |
|             | Triangle Window         | TriWin         | Standard              |
|             | Hanning Window          | HanWin         | Standard              |
|             | Hamming Window          | HamWin         | Standard              |
|             | Blackman Window         | BkmanWin       | Standard              |
|             | Kaiser Window           | KsrWin         | Standard              |
|             | BlackmanHarris Window   | BlkHarrisWin   | Standard              |
|             | Tapered Cosine Window   | CosTaperedWin  | Standard              |
|             | Exact Blackman Window   | ExBkmanWin     | Standard              |
|             | Exponential Window      | ExpWin         | Standard              |
|             | Flat Top Window         | FlatTopWin     | Standard              |
|             | Force Window            | ForceWin       | Standard              |
|             | General Cosine Window   | GenCosWin      | Standard              |

**Table 10-1.** Analysis Control Function Tree (Continued)

| Control     | Function                 | Function Name              | Development<br>System |
|-------------|--------------------------|----------------------------|-----------------------|
| CWDSP       | Measurement              |                            |                       |
| (continued) | AC/DC Estimator          | ACDCEstimator              | Standard              |
|             | Amplitude/Phase Spectrum | AmpPhaseSpectrum           | Standard              |
|             | Auto Power Spectrum      | AutoPowerSpectrum          | Standard              |
|             | Cross Power Spectrum     | CrossPowerSpectrum         | Standard              |
|             | Impulse Response         | ImpulseResponse            | Standard              |
|             | Network Functions        | NetworkFunctions           | Standard              |
|             | Peak Detector            | PeakDetector               | Standard              |
|             | Power Frequency Estimate | PowerFrequency<br>Estimate | Standard              |
|             | Scaled Window            | ScaledWindow               | Standard              |
|             | Spectrum Unit Conversion | SpectrumUnit<br>Conversion | Standard              |
|             | Threshold Peak Detector  | ThresholdPeak<br>Detector  | Standard              |
|             | Transfer Function        | TransferFunction           | Standard              |

# **Controls**

Each analysis function is a method of its corresponding control. Parameters are passed to analysis functions like any other functions. In many cases, the calculated value or data is returned as a result from the function, rather than in an output variable. This allows you to directly assign the result of the function to another part of the program, such as the user interface, or as the parameter of another function.

Text1.Text = CWStat1.Mean(Data)

Because each function is a method of a control, you must place the corresponding control in your application to use the function. You must include the name of the control in each call to an analysis function. For example, a call to the AddArray function, which is part of the CWArray control, might look like this:

```
SumArray = CWArray1.AddArray(Array1, Array2)
```

Do not assign a return variable for functions from which the information is not returned. For example, the AutoPowerSpectrum method returns results in the Spectrum and deltaF parameters.

```
CWDSP1.AutoPowerSpectrum Data, 0.001, Spectrum, deltaF
```

Many parameters passed to the analysis functions are of variant data type. When passing these parameters for output or return, you only need to declare them as a variant.

```
Dim Data as Variant
Data = CWDSP1.SinePattern(1024, 5, 0, 4.5)
```

# **Analysis Function Descriptions**

Because there are many functions in the analysis libraries, individual functions are not described in this manual. Each function, with its purpose and parameters, is described in detail in the ComponentWorks online reference. The online reference also includes code examples for each function. You can access the online reference directly from most programming environments. See the chapter in this manual specific to your programming environment for more information.

# **Error Messages**

If any analysis function encounters an error, it sends an exception back to the application, which displays a dialog box with the error number and description. The analysis functions do not return the error code from the function. Consult the Appendix D, *Error Codes*, for more information about individual error messages and how to resolve them. Error handling and debugging is described in more detail in Chapter 12, *Building Advanced Applications*.

# **Tutorial: Using Simple Statistics Functions**

This tutorial shows you how to use some of the CWStat control statistical functions. The functions in this tutorial are part of the Base Analysis Library, which is supported by all versions of ComponentWorks.

By placing the Analysis control containing the functions you are using in your application, you can use the functions by adding them to your code manually or with the tools provided by your development environment. The Analysis controls do not have any properties that need to be edited. The only property you use with an Analysis control is the Name property, which you use when calling any function. For example, the default name of the CWStat controls is CWStatl and a call to the Mean function is CWStatl. Mean.

Although this tutorial uses the Graph control to display data arrays, you can still complete this tutorial if you do not have the user interface tools. Disregard references to the Graph control, and use your own method for displaying data arrays.

This tutorial uses Visual Basic syntax, but the discussion is in general terms so you can follow it in any compatible programming environment. Remember to adjust any code to your specific programming language. Refer to the *Building ComponentWorks Applications* chapters for information about implementing any step in different programming environments. You also can refer to the tutorial examples installed with ComponentWorks for a completed version of this example in several different programming environments.

# **Designing the Form**

- 1. Open a new project and form. If you are working in Visual C++, select a dialog-based application and name your project Stat.
- 2. Load the ComponentWorks User Interface control, CWGraph, and the CWStat Analysis controls into your programming environment.
- 3. From the toolbox or toolbar, place a CWStat control on the form. Keep its default name, CWStat1.
- 4. From the toolbox or toolbar, place a CWArray control on the form. Name the control CWArray1.
- 5. Place a CWGraph control on the form. Keep its default name, CWGraph1. You can open its property page to change any of its properties.
- 6. Place a button on the form. Change its name and caption property to Go.
- 7. Create six text boxes on the form and name them Max, MaxIndex, Min, MinIndex, Mean, and StdDev.
- Add a label to each text box with the following descriptions: Maximum, Max Index, Minimum, Min Index, Mean, and Standard Deviation.

Your form should look similar to the one shown below.

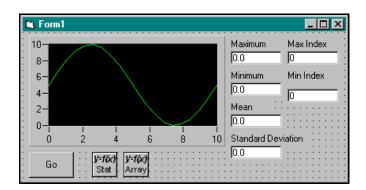


Figure 10-1. Stat Form













# **Developing the Program Code**

When you press the **Go** button, the program generates an array of random numbers. It displays the data on the graph and also calculates and displays the following statistics of the data set: maximum, array index at maximum, minimum, array index at minimum, mean, and standard deviation.

- 1. Create a skeleton event handler for the Click event of the **Go** button.
  - In Visual Basic, double click on the button on the form to create the Go\_Click subroutine.
  - In Visual C++, use the MFC ClassWizard to create the event handler routine. Right click on the button and select ClassWizard.
  - In Delphi, use the Object Inspector to create the event handler routine. Select the **Go** button, then press <F11> to open the Object Inspector. Select the **Events** tab. Double click the empty field next to the Click event.
- Add code inside the event handler routine to generate an array, fill it
  with random data and display it on the graph. If you are working in
  Visual C++, you first need to add a member variable for the graph
  control using the MFC Class Wizard.

```
Dim data(0 To 99)
For i = 0 To 99
    data(i) = Rnd
Next i
CWGraph1.PlotY data
```

3. Add the function to calculate the statistics of the data set. Use the StdDev function of the CWStat control to calculate the standard deviation and mean of the dataset, and the MaxMin1D function of the CWArray control for the remaining values. You also need to declare a number of variables to store the different calculated values. Add the following code to the program, placing the variable declarations at the top of the event handler routine and the analysis functions after the call to the Ploty method from the Step 2.

```
Dim MeanVal as Variant, StdDevVal as Variant
Dim MaxVal as Variant, MaxIndexVal as Variant
Dim MinVal as Variant, MinIndexVal as Variant
CWStatl.StdDev data, MeanVal, StdDevVal
CWArray1.MaxMin1D data, MaxVal, MaxIndexVal,
    MinVal, MinIndexVal
```

4. Add the necessary code after the analysis functions to display the calculated values in the textboxes on the user interface.

```
Mean.Text = MeanVal
StdDev.Text = StdDevVal
Max.Text = MaxVal
Min.Text = MinVal
MaxIndex.Text = MaxIndexVal
MinIndex.Text = MinIndexVal
```

5. Save the project and associated files as Stat.

### **Testing Your Program**

Run the program. Click on the **Go** button to generate a data set and calculate the statistical values. The result should be similar to the following illustration.

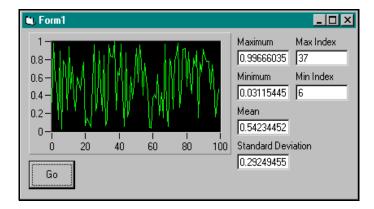


Figure 10-2. Testing Stat

When the statistical values are displayed in the text boxes, all digits of precision are displayed by default. You can edit the code that displays these values to limit the number of digits displayed. Consult your programming reference manual for information about limiting the degree of precision.

You also can use the Numeric Edit Box control to display the values and use its format string to limit the number of digits displayed.

11

# Using the DataSocket Control and Tools

This chapter describes how you can use the ComponentWorks DataSocket control to read, write, or share data on a single machine or between multiple machines and includes tutorial exercises that provide step-by-step instructions for using the DataSocket tools.

Refer to the *Building ComponentWorks Applications* chapters for information about using the ComponentWorks controls in different programming environments. The software includes solutions for the tutorials in Visual Basic, Visual C++, and Delphi.



The DataSocket control is part of the ComponentWorks Standard and Full Development Systems.

### What is DataSocket?

DataSocket, both a technology and a group of tools, facilitates the exchange of data and information between an application and a number of different data sources and targets. These sources and targets include files and HTTP/FTP servers. Often, these sources and targets are located on a different computer. You can specify DataSocket sources and targets (connections) using URLs (uniform resource locators) that adhere to the familiar URL model.

DataSocket uses an enhanced data format for exchanging instrumentation style data, including data attributes and the actual data. Data attributes might include information such as an acquisition rate, test operator name, time stamp, quality of data, and so on.

Although you can use general purpose file I/O functions, TCP/IP functions, and FTP/HTTP requests to transfer data between different applications, applications and files, and different computers, you must write a significant amount of program code to do so. DataSocket greatly simplifies this task by providing a unified API for these low-level communication protocols. Transferring data across computers with DataSocket is as simple as using a browser to read Web pages on the Internet.

### **DataSocket Basics**

To bring data into your application, connect the DataSocket control to the data source with the Connect method. The Connect method uses a URL to identify the source to which you want to connect.

Although it is not visible at run time, the DataSocket can be thought of as a connector on an application, as depicted by the following figure. When you connect to a data source, it is like plugging in a wire from the source. Because the DataSocket control parses the raw data and passes the value to your application, you can connect to different sources without having to support different data formats and protocols. If the DataSocket is connected to a dynamic source, new values are passed to the application when the value at the source changes.

When the DataSocket control has a new value loaded from the source, it stores the value in a local CWData object, which holds the data value and attributes associated with the data. For example, you can use DataSocket to convert a wave file automatically into an array of numbers that can be plotted or processed.

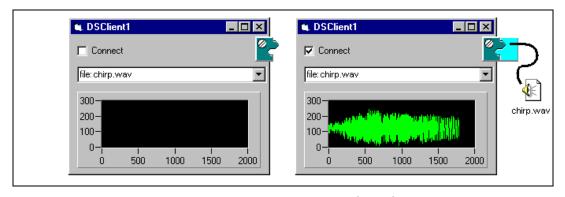


Figure 11-1. DataSocket Connection

### **Locating a Data Source**

Specify a URL to point the DataSocket to the data source location. Like URLs you use in a Web browser, the data source locator can point to many different types of sources depending on the prefix. The prefix is called the *URL scheme*. DataSocket supports several existing schemes, including http: (hypertext transfer protocol), ftp: (file transfer protocol), and file: (local files). The DataSocket also supports a new scheme, dstp: (DataSocket transfer protocol), for connecting to DataSocket Servers. After the URL scheme, enter the data-source-path. The format of the path depends on the scheme you use.

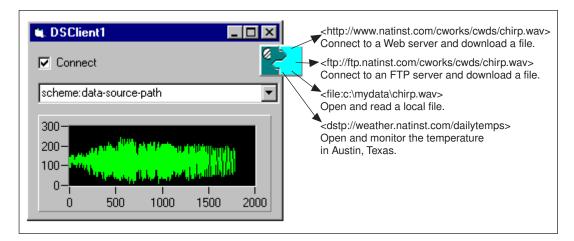


Figure 11-2. Specifying Data Source Locations

# **Reading Data from a Data Source**

To read, load, or download data using the DataSocket control, call the ConnectTo method and pass in the URL and access mode. The access mode specifies whether the connection is reading or writing data. To read from a source, use the access mode cwdsRead.

'Connect to a new data source to read from. CWDataSocket1.ConnectTo "http://host/path" cwdsRead

When you use the ConnectTo method, the URL and access mode values are saved in the URL and AccessMode properties of the DataSocket control. If you have already set these properties, you can use the Connect method instead.

```
' Connect using the current URL and ' Access mode property settings.
CWDataSocket1.Connect
```

As it connects and loads data, the DataSocket control can generate two events to notify your application of progress: OnDataUpdated and OnStatusUpdated.

### **OnDataUpdated Event**

The DataSocket control generates an OnDataUpdated event when it receives a data value. The event passes a reference to the DataSocket CWData object.

You can use the DataSocket control Data property to access the currently stored value. The Data property returns a reference to the same CWData object that is passed to the event. From the CWData object, you can get the value or attributes associated with the current data. The data value is returned as a variant (the specific type of variant depends on the source to which the DataSocket is connected).

```
x = CWDataSocket1.Data.Value
```

Instead of waiting for an event, you might find it more convenient to check for new data. To determine if the DataSocket data has been updated since it was last read, query the value of the DataUpdated property. When a new value is loaded, DataUpdated becomes true. When the data value or any attribute is checked, DataUpdated reverts to false.

Use the DataUpdated property to check for updates in conjunction with another periodic operation, such as an operation initiated by a timer event.

```
Sub Timer1_OnTimer

' DataUpdated is true only if the data
' has been reloaded.

If DataSocket1.DataUpdated then

' Reading the data property resets the
' DataUpdated property.

MySub DataSocket1.Data

End If
' Other timer event code.

End sub
```

### **Updating the Data**

To reload data from the source, call the Update method. When the new data is loaded, the DataUpdated property is set to true and the OnDataUpdated event is fired.

```
' Update the data that DataSocket is holding. CWDataSocket1.Update
```

If you read the Data property before the event occurs, you get the previous data.

### **Automatically Updating Data**

Some data sources, such as the DataServer, support automatic notification of value changes. For example, the DataSocket Server can automatically download updates when another client changes the data item to which it is connected. When the DataSocket control receives an update, it generates an OnDataUpdated event and sets the DataUpdated property to true. To receive updates automatically, connect using the cwdsReadAutoUpdate access mode.

CWDataSocket1.ConnectTo sourceURL, cwdsReadAutoUpdate

### OnStatusUpdated Event

The OnStatusUpdated event occurs every time you try to connect to the data source specified by the URL. The event returns parameters for the status, a system error code, and a string describing the most recent progress or error. You can use these parameters to identify the cause of a problem or to report the progress. The OnStatusUpdated event can occur a number of times, depending on the data source to which you are trying to connect.

```
Private Sub CWDataSocket1_OnStatusUpdated(ByVal Status
As Long, ByVal Error As Long, Message As String)
' Display the current status in the form
   Text1.Text = Message
End Sub
```

### **Disconnecting from a Data Source**

When you finish retrieving data from the data source, call the Disconnect method to release system resources that are used by the data source to which you connected. If you call the Connect method while connected to

another source; delete the control; or unload the form it is on, the DataSocket control automatically calls Disconnect.

CWDataSocket1.Disconnect

Once disconnected, the DataSocket retains the last data loaded so you can continue to use it after the connection terminates. The Update method does not work after you disconnect.

# **Tutorial: Reading a Waveform**

This tutorial shows you how to use the DataSocket to load a wave from several different data sources, some of which are installed with ComponentWorks and others are on the National Instruments's Web and FTP sites. To use the Internet sources, your computer must be connected to the Internet.

This tutorial uses Visual Basic syntax, but the discussion is in general terms so you can follow it in any compatible programming environment. Remember to adjust any code to your specific programming language. Refer to the *Building ComponentWorks Applications* chapters for information about implementing any step in different programming environments. You also can refer to the tutorial examples installed with ComponentWorks for a completed version of this example in several different programming environments.

### **Designing the Form**

- 1. Open a new project and form. If you are working in Visual C++, select a dialog-based application and name your project SimpleDSRead.
- 2. Load the ComponentWorks DataSocket and ComponentWorks UI controls (specifically the graph) into your programming environment.
- Place a CWDataSocket control on the form. Keep its default name, CWDataSocket1.
- 4. Place a CWGraph control on the form. Keep its default name, CWGraph1.









5. Place a CommandButton control on the form. Keep its default name, Command1.

Chapter 11

- 6. Change the CommandButton caption to Connect.
- 7. Place a TextBox control on the form. Keep its default name Text1.
- 8. Place another TextBox control on the form. Keep its default name, Text2.

Your form should look similar to the one shown below.

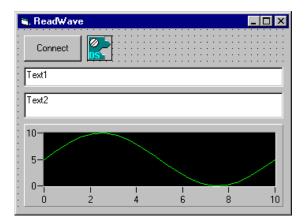


Figure 11-3. SimpleDS Form

### **Developing the Program Code**

After completing the following steps, you can press the **Connect** button to connect the DataSocket to the data source. The DataSocket loads the data, and the graph displays the data.

You can specify the data source by typing the URL in the text box. Each time the DataSocket connects to a new source, it disconnects from the previous source.

- Create a skeleton event handler for the OnDataUpdated event of CWDataSocket1.
  - In Visual Basic, double click on the DataSocket control that you placed on the form.
  - In Visual C++, use the MFC ClassWizard to create the event handler routine. Right click on the DataSocket control and select ClassWizard.
  - In Delphi, use the Object Inspector to create the event handler routine. Select the Slide control, press <F11> to open the object inspector, select the Events tab, and double click on the empty field next to the OnDataUpdated event.
- 2. Add the following code inside the event handler routine. If you are working in Visual C++, first add a member variable for each control to the application dialog class.
  - Visual Basic: CWGraph1.PlotY Data.Value

  - Delphi: CWGraph1.PlotY(Data.GetValue(), 0, 1, TRUE);
- $3. \quad Add \ the \ following \ code \ to \ the \ {\tt CWDataSocket1\_OnStatusUpdated} \\ event. \ Remember \ to \ adjust \ the \ syntax \ for \ your \ programming \ language.$

```
Text2.Text = message
```

Add the following code to the Command1\_Click event routine.
 Remember to adjust the syntax for your programming language.
 CWDataSocket1.ConnectTo Text1.Text, cwdsReadAutoUpdate

5. Save the project and associated files as SimpleDSRead.

### **Testing Your Program**

Run the program. Initially, the graph does not display any data because the DataSocket is not connected to a source. To connect to a data source, enter a URL in the text box and press **Connect**.



You must establish a network connection before you can connect to an Internet data source. If you normally dial into an Internet service provider over a phone line, do so before attempting to connect to a data source on the Internet.

You do not need an Internet connection to read data from local files or connect to DataSocket Servers on the same computer.

The following list contains URLs you can use to test the program.

To connect to and load data from a local file, enter a file URL.
 ComponentWorks includes sample files in the ComponentWorks installation directory.

file:c:\Program Files\National Instruments
\ComponentWorks\tutorials\Visual Basic\chirp.wav

- The following list specifies URLs to which you can connect with the DataSocket. If the URLs do not work, use your Web browser to locate new URLs at www.natinst.com/cworks/datasocket.
  - To connect to and load data from an http (Web) server, enter
     http://www.natinst.com/cworks/datasocket/chirp.dsd
  - To connect to and load data from an ftp server, enter ftp://ftp.natinst.com/support/compworks/datasocket /chirp.dsd
  - To connect to and load data from a DataSocket, enter dstp://weather.natinst.com/weather/windspeed
     This site has live weather information from our corporate headquarters in Austin, Texas.

# **Writing Data to a Data Target**

When you connect to a URL with one of the read modes, the URL identifies a data source. When you connect to a URL with a write mode, the URL identifies a data target. That is, you read data from a data source and write data to a data target.

To connect to a data target, use the Connect method with the cwdsWrite access mode. Once connected, the DataSocket writes the data it is currently holding.

CWDataSocket1.Data.Value = x
CWDataSocket1.ConnectTo targetURL, cwdsWrite

When the connection is complete and the data is written to the target, the DataSocket fires the OnDataUpdated event and sets the DataUpdated property to true. DataUpdated reverts to false once the Data value or attributes are modified or checked.

Note

Some data sources, such as DataSocket Servers and local files, can be either a data source or a data target, determined by the access mode used to connect to it. Other data sources, especially http: and ftp: sources, are read only and cannot be used as a data target.

### **Updating a Data Target**

The DataSocket rewrites data to the data target with the Update method. When the new data has been written, the OnDataUpdated event is fired and the DataUpdated property is set to true.

```
'Update the data target with a new value.

CWDataSocket1.Data.Value = x

CWDataSocket1.Update
```

Use the Update method to write new data to a DataSocket Server or a local file each time you run an experiment or acquire data. When a data target is updated, the existing value is replaced completely with the new value and attributes. The DataSocket control completely replaces the existing value with the new value and attributes.

### **Automatically Updating a Target**

When you connect to the data target using the cwdsWriteAutoUpdate access mode, the DataSocket updates the target every time the data value or attributes are set.

```
CWDataSocket1.ConnectTo targetURL, cwdsWriteAutoUpdate
```

If you want to set the value and attributes in one operation, use a second CWData object to prepare the data, and then use the CopyFrom method to copy the value and attributes.

```
' Set the value and attributes in a
' second CWData object.

Dim cwd as New CWData
cwd.Value = x
cwd.SetAttribute "SampleRate", 10000
' Copy the data from the second object.
' into the CWData owned by the DataSocket.
' After the copy is done the target will be updated.
CWDataSocket1.Data.CopyFrom cwd
```

# **Working with CWData**

The DataSocket control consists of two objects. The first is the CWDataSocket object. The top-level object manages the process of connecting to data sources or targets, transferring and parsing data, and firing events. The second object, CWData, holds the data that has been read or that will be written.

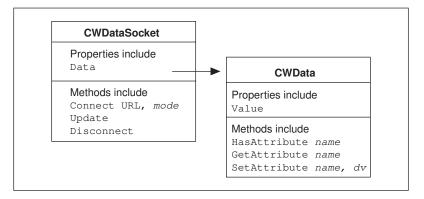


Figure 11-4. DataSocket Control

Because the CWData object is part of the CWDataSocket control, operations that read or modify the data value or attributes notify the DataSocket. Therefore, the DataSocket knows when data loaded from a source has been read or when a data target needs to be updated. When the DataSocket control is connected to a Read source, it prohibits modifications to the CWData objects it owns.

As shown in the proceeding figure, the Data property on the DataSocket returns a reference to a CWData object, which holds the value and attributes. CWData contains a property for the primary value of the data and methods to access attributes of the data. If the DataSocket is connected to a data source, the CWData object it owns is read only. For example, if cwd is a reference to a CWData object owned by a CWDataSocket that is connected to a data target with the cwdsWriteAutoUpdate mode, setting its value; calling CopyFrom; or setting its attributes causes the DataSocket to write the new value to the data target.

x = CWDataSocket1.Data.Value

### **Working with Attributes**

You can use attributes to provide information such as the time the value was calculated or acquired, the units in which the value is expressed, the equipment used to generate the value, or any other properties that you want to define.

Use the SetAttribute method to change an existing attribute value or, if the attribute is not present in the data, add the attribute.

```
CWDataSocket1.Data.SetAttribute "Units", "volts"
```

To determine if existing data has a specific attribute, use the HasAttribute method.

```
x = CWDataSocket1.Data.HasAttribute ("Units")
' x is true if the attribute has a "Units" attribute,
' false otherwise.
```

To get the value of an attribute, use the GetAttribute method. GetAttribute accepts an optional parameter, Default. If the attribute you are trying to get is not present in the data, Default is returned.

```
x = CWDataSocket1.Data.GetAttribute ("Units", "volts")
' x is the value for the "Units" attribute or "volts"
' if the attribute is not present.

x = CWDataSocket1.Data.GetAttribute ("Units", "")
' x is the value for the "Units" attribute or an empty 'string if the attribute is not present.

x = CWDataSocket1.Data.GetAttribute ("Units", Empty)
' x is the value for the "Units" attribute or an empty 'variant if the attribute is not present.
' "Empty" is a predefined value in VB that 'has the value of an empty variant.
```

To delete an attribute, use the DeleteAttribute method.

```
CWDataSocket1.DeleteAttribute "Units"
```

### Standalone CWData Objects

You can create a CWData object and use it independently of the DataSocket control. To preserve the data value and attributes, use standalone CWData objects to hold copies of the data loaded by a DataSocket control.

```
' Store a copy of the CWData value in a variant.
' Attributes are not copied.

Dim v as Variant
v = CWDataSocket1.Data.Value

' Store a copy of the value and all attributes in a
' CWData object.

Dim cwd as new CWData
cwd.CopyFrom CWDataSocket1.Data
```

You can use CWData on its own as a variable that can hold both a regular value and attributes.

```
Dim cwd as new CWData
cwd.Value = 50.0
cwd.SetAttribute "Units", "volts"
```

Use the CopyFrom method to copy the value and attributes from one CWData object to another.

Note

Each CWData object knows if it is owned by a CWDataSocket control or if it is created as a standalone object. If it is owned, the control is notified of changes made to the data or attributes. For example, if cwd is a reference to a CWData object owned by a CWDataSocket that is connected to a data target with the cwdsWriteAutoUpdate mode, setting its value, calling CopyFrom, or setting its attributes causes the DataSocket to write the new value to the data target.

# Setting Up a DataSocket Server

The DataSocket Server is a separate executable used to communicate and exchange data between two applications using DSTP (DataSocket transfer protocol). When you run it on your computer, you make data easily accessible to other DataSocket applications on the same computer or other computers connected though a TCP network, such as the Internet.

To launch the DataSocket Server, run **DataSocket Server** from the **National Instruments ComponentWorks** group in the Windows **Start** menu. Alternatively, you can run DataSocketServer.exe located in the \ComponentWorks\DataSocketServer directory. To make the DataSocket Server run every time you launch your computer, place a link to DataSocketServer.exe in your Startup folder.

### Requirements for Running the DataSocket Server

The DataSocket Server requires support for TCP/IP networking on your machine. To check your configuration, launch the DataSocket Server. If you have a working Web browser on your computer, the TCP/IP driver should be installed.

### Checking the Status of the DataSocket Server

When the server is running, you see a tray icon indicating that the server is up and running. To check on its status, double click on the icon or right click and choose **Show DataSocket Server** from the popup menu.



Figure 11-5. DataSocket Server Tray Icon

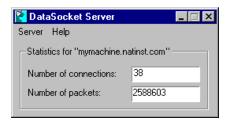


Figure 11-6. DataSocket Server Status Window

### **Creating Data Items on the Server**

The default configuration of the server allows the local machine to create new data items and to change the data in these data items. Remote machines can connect to the server and read items. To create an item, run a client that uses a DataSocket control to write items to the server on your machine. When a DataSocket writes data to a data server using a new DataItem path, the server automatically creates a new entry and stores the value in that new entry. Your line of code should look similar to the following.

'A DataSocket client that writes to a DataSocket Server. CWDataSocket1.ConnectTo "dstp://localhost/DataItem", cwdsWrite

### **Connecting to Data Items and Reading Them**

You can connect to data items and read them just as you create data items or write to them. However, use the read access mode instead of the write access mode.

'A DataSocket client that reads from a DataSocket Server. CWDataSocket1.ConnectTo "dstp://localhost/DataItem", cwdsReadAutoUpdate

If the reading client connects using <code>cwdsRead</code>, it gets updates only after calling the <code>Update</code> method on the DataSocket. If it uses <code>cwdsReadAutoUpdate</code>, it gets updates automatically when another client changes the value. If a reading client attempts to connect to a data item that does not exist, the connection completes, but no data is returned. Furthermore, the <code>OnDataUpdated</code> event does not fire until a writing client connects to the same data item and actually writes a value to it. You can start reading clients before launching the writing clients. When a writing client is launched, data is sent to the waiting reading clients.

# **Tutorial: Sharing Data between Applications**

This tutorial shows you how to use the DataSocket Server to share data between different applications. The application is included in the ComponentWorks directory.

### Note

The host name localhost in this tutorial tells the DataSocket to connect to a server on the same machine. Use localhost when you do not want to hard code the local host name into applications.

- Launch the application \ComponentWorks\tutorials\Visual Basic\ch11DSSReader.exe.
- 2. Enter the URL dstp://localhost/wave.
- 3. Press the **Connect** button. The DataSocket connects to the server. Because the item is not yet created, no data is returned.
- 4. Launch the application tutorials\Visual Basic\ch11DSSWriter.exe.
- Move the slide pointers to change the wave displayed in the graph. Because ch11DSSWriter has not connected to the server, ch11DSSReader is not affected.
- 6. Enter the URL dstp://localhost/wave in ch11DSSWriter and press **Connect**. ch11DSSReader gets the wave data item value each time it is set by the other client.

- 7. Launch another copy of ch11DSSReader, enter the same URL, and press **Connect**. This application immediately gets a copy of the data because the server already has a value for the item.
- 8. Move the slide pointer on the chllDSSWriter application again. Notice that both applications show the same wave.

If you have another machine with ComponentWorks installed, you can run the ChllDssReader application on them. On other machines, you need to enter the actual host name of the server, not localhost. To determine the host name of the server, display the status window on the DataSocket Server.

### **Configuring the DataSocket Server**

The default configuration of the DataSocket Server works for many intranet applications. By default, only programs running on the same computer as the server can create items or write to items, whereas applications on the same computer or other computers can read items. Items exist only as long as there is at least one DataSocket client connected to read or write the item's value. When no connections to the item remain, the DataSocket Server releases the item and its value.

Use the DataSocket Server Manager to change the default settings. You can specify which machines can create items, write items, and read items. You can specify items that should be automatically created and given an initial value when the server is started. The DataSocket Server never releases predefined items, so their values exist even when no DataSocket client is connected to them. Predefined items can have special read and write access groups so different machines can have different access to different items. Changes that you make to the server take affect the next time that you launch the DataSocket Server.

Items created dynamically can be read by hosts in the **Default Readers** group and modified by hosts in the **Default Writers** group.

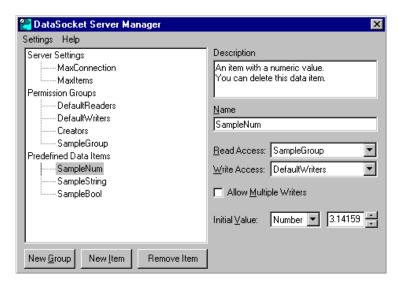


Figure 11-7. DataSocket Server Manager

# **Building Advanced Applications**

This chapter discusses how you can build applications using more advanced features of ComponentWorks, including advanced data acquisition techniques, the DSP Analysis Library, and advanced user interface controls and offers techniques for error tracking, error checking, and debugging.

# Using Advanced ComponentWorks Features

This section illustrates advanced data acquisition techniques, such as pretriggering and using start, stop, and pause conditions through real application examples. The examples demonstrate how to incorporate the DSP Analysis Library and use the spectrum functions. Finally, advanced user interface control features, such as graph cursors and multiple axes and pointers, are presented.

This chapter concentrates on the key features of sample applications located in the \ComponentWorks\tutorials directory. You can customize these examples to implement the advanced features in your own applications.

### A Virtual Oscilloscope

The Virtual Oscilloscope application uses the ComponentWorks User Interface and Data Acquisition analog input controls and a DAQ board to build a simple one-channel oscilloscope. Load the sample program from \ComponentWorks\tutorials into your development environment to follow the discussion.

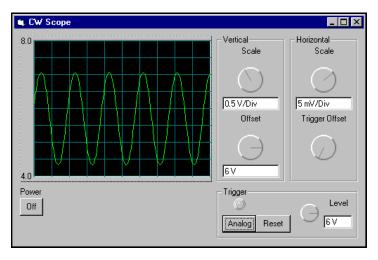


Figure 12-1. Virtual Oscilloscope

Depending on the state of the trigger mode button, the application acquires data in a single-shot, continuous, or analog trigger continuous operation. When the data is returned to the AcquiredData event, it is plotted on the graph. The vertical controls on the scope adjust the Y axis of the graph, while the horizontal and trigger settings affect the AI control. Any AI control property that the user does not control at run time, such as the device and channel number, is set directly in the AI property pages. By default, channel 1 on device 1 is used for the acquisition. Wire your signal accordingly or change these values in the property pages.

### **Data Acquisition Stop Condition Modes**

The scope can run in one of three acquisition modes—single, continuous trigger, and analog continuous software trigger—which you select by using the **Single/Cont/Analog** button in the Trigger section of the form. The first two modes work well with any input signal, while the analog trigger mode works best with a periodic dynamic input signal.

The three trigger modes correspond to three types of stop conditions on the data acquisition analog input control. For example, the event handler for the **Analog** button programmatically sets a new value for the property CWAII.StopCondition.Type according to the state of the button, as shown in the following code for the analog trigger mode.

CWAI1.StopCondition.Type = cwaiSWAnalog

The DAQ control or header file defines the constant cwaisWanalog. You can retrieve any StopCondition. Type constant value by using the Object Browser in Visual Basic, consulting the online documentation, or looking in the header file for your environment. After changing the property value, the event handler of the **Trigger** button also reconfigures and restarts the acquisition. It is important to set the analog trigger level to a value within the range of the input signal.

### **Data Acquisition Pretriggering**

When the scope is in analog trigger mode, you can move the trigger point along the horizontal axis of the graph by using the **Trigger Offset** knob. In the code, the event handler for the knob changes the PretriggerScans property of the AI control.

CWAI1.StopCondition.PreTriggerScans = TOffset.Value

Without pretriggering, the application acquires all scans after the stop condition trigger (analog trigger). When the number of pretrigger scans is greater than zero, the application acquires the number of scans specified before the trigger occurs. After the trigger occurs, the array of data returned to the CWAI1\_AcquiredData event handler contains data acquired both before and after the trigger. You can set the PretriggerScans property and all the stop trigger properties through the property pages of the DAQ AI control. Pretriggering works the same way with the analog software, the analog hardware, and digital hardware stop triggers.

### **User Interface Value Pairs**

Value pairs are User Interface control features for assigning names to specific values on a scale or axis in the graph, slide and knob controls. All the value pairs for a given axis are stored in the ValuePairs collection object of that axis. Each value pair object consists of a name and a value corresponding to a scale or axis of the particular control. Although you usually set value pairs through the property page of the control, you can add, edit, or delete them programmatically.

After you assign value pairs, such as the settings for the **Vertical Scale** knob, you can limit the allowed values for a control to the predefined value pairs. To do this, set the control to <code>ValuePairsOnly</code> on the **Style** page of the property sheet. In the Virtual Scope application, the vertical and horizontal scale knobs are **Value Pairs Only** controls. This way, the control is limited to preset settings and the program can retrieve the name, value, or index of the currently selected value pair. The application uses the value of the value pair to update the appropriate property on the graph or DAQ AI

control and uses the name of the value pair to update the appropriate text display.

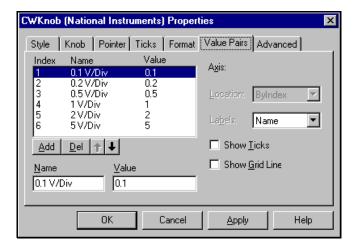


Figure 12-2. Knob Property Pages—Value Pairs Page

The following code shows how to retrieve the value, name, and index from the currently selected value pair of a knob control.

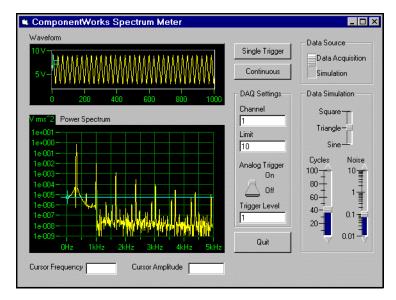
```
CWKnob1.Value
CWKnob1.Axis.ValuePairs(CWKnob1.ValuePairIndex).Name
CWKnob1.ValuePairIndex
```

You can specify multiple axes on a graph and associate value pairs with each individual axis.

### **Virtual Spectrum Meter**

The Virtual Spectrum Meter application, which you can find in \ComponentWorks\tutorials, uses the DSP analysis functions to build a simple spectrum analyzer. The data can either be acquired with a DAQ board or simulated. If you do not have a DAQ board, select Simulation with the **Data Source** switch and characterize your signal in the Data Simulation section. The UI controls are used to display the information as

well as control the operations of the program. The following screen shows the application.



**Figure 12-3.** Virtual Spectrum Meter

Once the Spectrum Meter is started, you can select either a **Single Trigger** or a **Continuous Trigger** acquisition. The single trigger takes a snapshot of the incoming signal so you can study the spectrum of the acquired signal. Use the continuous trigger to monitor changes in a signal as they occur. You can set some DAQ parameters, such as the channel, using the DAQ settings section of the user interface. The input limit specifies the maximum expected absolute voltage on the input signal and determines the optimal gain to use on the acquisition process. You also can use an analog trigger with your data acquisition. Set other DAQ parameters, such as the device number, in the AI control property pages.

Use the cursors on the graphs to measure the amplitude of the incoming waveform and the frequency of any specific point in the spectrum. When you move one of the cursors, the corresponding display at the bottom of the user interface is automatically updated.

### **DSP Analysis Library**

The digital signal processing (DSP) analysis functions are part of the ComponentWorks Standard and Full Development Systems. DSP functions include Fourier and Hartley transforms, spectrum analysis,

convolution and correlation of data sets, and digital windowing and filtering of data. If you have installed the ComponentWorks Base Package, you cannot run these functions from your development environment. However, you can examine the Spectrum Meter project and code and run the precompiled executable in the \ComponentWorks\tutorials folder. To use the DSP functions, you must load the Analysis controls into your environment, and then place the CWDSP control on your form.

The Virtual Spectrum Meter application contains all the analysis functions in the AnalyzeAndGraph subroutine, which is shown below. The application passes the data (acquired or simulated) to this routine for analysis and display.

```
Private Sub AnalyzeAndGraph (WaveformData() As Variant,
 SampleInterval As Double)
   Dim WindowedData As Variant
   Dim FreqInterval As Variant
   Dim SpectrumData As Variant
   Dim HalfSpectrumData As Variant
   WaveformGraph.PlotY WaveformData
   WindowedData = CWDSP1.HamWin(WaveformData)
   CWDSP1.AutoPowerSpectrum WindowedData,
   SampleInterval, SpectrumData, FreqInterval,
   SpectrumData, freqinterval
   HalfSpectrumData = CWArray1.Subset1D(SpectrumData,
     2, 510)
   SpectrumGraph.PlotY HalfSpectrumData, FreqInterval,
   FregInterval * 2
End Sub
```

The analysis procedure consists of the Hamming window (HamWin) and the auto power spectrum function (AutoPowerSpectrum). The Hamming window reduces the effect of spectral noise leakage in the spectrum because of the finite length sample of a continuous signal. The auto power spectrum function is a single-sided, scaled spectrum that you can graph directly. The AutoPowerSpectrum function also calculates the frequency resolution of the spectrum (FreqInterval) using the SampleInterval value passed to AnalyzeAndGraph. The frequency resolution is used in the PlotY method of the graph for scaling the X axis of the spectrum graph.

The DSP Analysis Library also includes the SpectrumUnitConversion function for scaling the calculated spectrum between different formats, including linear, dB, and dBm, combined with Vrms, Vrms<sup>2</sup>, Vpk, and Vpk<sup>2</sup>, as well as amplitude and power spectral densities.

Chapter 12

The DSP functions include FFT and inverse FFT algorithms for low-level spectrum calculations. Time domain functions, such as Convolution, Correlation, Differentiate, and Integrate, are included along with a number of different windowing, IIR (infinite impulse response), and FIR (finite impulse response) digital filtering functions.

#### Cursors

The Virtual Spectrum Meter application form has cursors on the graph for marking sections of the plots. Use the two cursors on the waveform graph to mark the minimum and maximum values of the acquisition waveform and measure the waveform amplitude. The cursor on the spectrum graph marks a particular point in the spectrum and displays the associated frequency.

To use a cursor on a graph, create and configure one or more cursors in the property pages of the graph. To create additional cursors, press the **Add** button in the **Cursors** tab and configure each cursor. The **Snap Mode** specifies whether the cursor jumps (snaps) to a point on the nearest plot or can be placed freely on the graph. When you select Point on selected plot for **Snap Mode**, you also can connect the cursor to a particular plot.

The following screen shows the property pages for the cursors on the waveform graph of the Virtual Spectrum Meter application.



Figure 12-4. Graph Property Pages—Cursors Property Page

Individual cursors are represented in the object hierarchy by Cursor objects contained in the Cursors collection of the Graph control. You can manipulate individual cursors programmatically by following the standard conventions of working with collections and their objects. For example, reference the cursors with the name of the graph, cursor index, and cursor property.

```
Max = WaveformGraph.Cursors.Item(2).YPosition
```

Use event handler subroutines associated with the graph to process any user interactions with the cursors. There are four events on the graph relating to the cursors, of which the CursorChange and CursorMouseUp routines are the most commonly used. Generate the event handler skeleton for the CursorChange event, which is similar to the following.

```
Private Sub Graph_CursorChange (CursorIndex As Long, XPos As Variant, YPos As Variant, bTracking As Boolean)
End Sub
```

The event handler provides the index of the cursor (which you use to determine the cursor that generated the event), as well as the X and Y coordinates of the cursor. For the waveform graph cursors, the Virtual Spectrum Meter application reads the Y position of the two cursors to calculate the amplitude of the waveform data, as shown below.

```
Private Sub WaveformGraph_CursorChange(CursorIndex As
Long, XPos As Variant, YPos As Variant, bTracking As
Boolean)
Dim Amplitude As Double
Amplitude =
   Abs(WaveformGraph.Cursors.Item(1).YPosition -
   WaveformGraph.Cursors.Item(2).YPosition)
CursorAmplitude = CStr(Round(Amplitude, 2)) + " V"
```

### **Graph Track Mode**

End Sub

The TrackMode property of the graph determines how the graph reacts to mouse actions and which events the graph generates at these times. By default, the TrackMode property is set to cwGTrackDragCursor, which allows the mouse to move the cursors on the graph. Moving a cursor generates the CursorChange event.

The TrackMode property generates events when the mouse interacts with the plot area as a whole or with individual plots on the graph. With these

settings, you can use the mouse to select a specific plot or detect when the user moves the mouse over the plot area.

You also can use TrackMode to select panning and zooming. When TrackMode is set to Pan, any click-and-drag action on the graph shifts the contents of the graph following the mouse movement. When TrackMode is set to ZoomRect, any click-and-drag action on the graph draws a rectangular outline on the graph. When the mouse button is released, the graph zooms to the dimensions of the outline. For these two operations, you can select X axis, Y axis, and XY axis modes, limiting the motion to the specified axes.

### A Virtual Data Logger

The Virtual Data Logger application records real time phenomena on multiple channels at slow rates over an extended period of time. It can either simulate the data being acquired or acquire data with a data acquisition card. The acquired data is logged to a serial ASCII file. Although it makes the file larger in size than binary format, ASCII format allows you to read the file in many other applications.

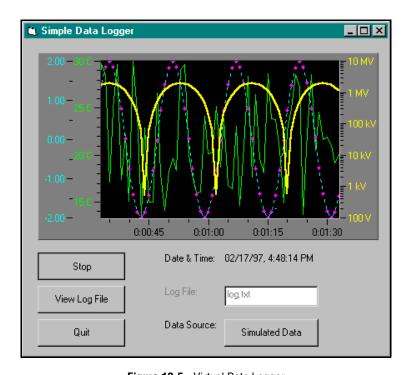


Figure 12-5. Virtual Data Logger

By default, the **Data Source** is set to simulated data, but you can acquire data from a DAQ board. If you use a DAQ board to acquire the data, remember to set the properties for the DAQ AI control accordingly.

The **Start/Stop** button is an on/off style for starting and stopping the acquisition/logging process. The **View Log File** button opens the recorded file using the Windows Notepad application. By default, the application does not clear the log file when you start the logging process. Rather, it appends the data to any existing data in the file.

### **Multiple Graph Axes**

You can configure multiple Y axes for a graph using its property pages. On the **Axes** page, use the **Add** and **Del** buttons to add and delete axes. For each axis, select the range and style you want to use. After configuring the axes, switch to the **Ticks** page. Select each axis in the pulldown ring and configure the labels and ticks for each axis.

You can predefine the properties of multiple plots on the **Plots** page. By default, each plot is assigned to the same Y axis on the graph, but you can assign plots to different Y axes of a graph. When an application plots or charts data on the graph, the Y axis specified for a particular plot determines the scaling of that plot. If you generate more plots on a graph than there are predefined plots, the template plot style and the first Y axis are used for each undefined plot.

You can set plot or axes properties in your program code. Plots and axes are individual objects (of type Plot and Axis) that are stored in corresponding collection objects (Plots and Axes, respectively). To change a property of an individual axis or plot, you must select the collection and then the individual object in the collection, followed by the property to read or write.

For example, you can reference individual Plot objects by using the Item method on the collection. The methods of the Plots collection—such as Add, Item, and Remove—make changes to the collection as a whole, while the properties of the Plot object—such as Name, AutoScale, and LineColor—are individual settings for one plot.

Objects in a collection are referenced by their one-based index using the Item method, as in the following examples.

```
' Refers to the first axis on the graph (X axis) {\tt CWGraph1.Axes.Item(1)}
```

- ' The second plot on the graph (default name Plot-2) CWGraph1.Plots.Item(2)
- ' Retrieves/sets the name of the second (first Y ) axis  ${\tt CWGraph1.Axes.Item\,(2).Name}$

To assign simple properties—properties that contain Boolean, double, integer, variant, or string values—to a plot or axis, use the property name as you would any other variable in your program. The following example changes the name of a plot on a graph.

```
CWGraph1.Plots(2).Name = "Temperature"
```

You can assign an object as a property of another object. Because each plot on a graph is assigned a specific Y axis that is used for data scaling, you can assign a new axis (an object) as a property to a plot. In most programming environments, assign the object as you would any other variable. In Visual Basic, you must use the Set keyword, which differentiates the assignment of data from the assignment of objects. The following Visual Basic code assigns the third axis as an object to the YAXIS property of the first plot.

```
Set CWGraph1.Plots.Item(1).YAxis =
   CWGraph1.Axes.Item(3)
```

### **Graph Axes Formats**

The axes on the graph, as well as the slide and knob, support special formatting modes you can use to edit the labels on the tick marks. In addition to simple formatting, such as using exponential or engineering notation, you can add alphanumeric characters such as units (for example, Hz or V) and convert to currency, percentage, or time formats. The time format includes options for time and date.

Two more advanced formatting modes are scaling and symbolic engineering. Use the scaling format mode to automatically perform simple mathematical functions (addition, subtraction, multiplication, and division) on your data before displaying it on your graph. For example, if you are using an IC temperature sensor whose output in volts corresponds to the temperature divided by 100, you can specify your axis to automatically scale the data by \*100. The data displayed on this axis is automatically multiplied by 100 without any changes in the program code.

You can use a symbolic engineering format when displaying units with your tick labels. The symbolic engineering format adds prefixes such as k for kilo and m for milli before the units. This format is useful for logarithmic scaling.

### File Input/Output

The file I/O functions in the Virtual Data Logger application demonstrate how to perform simple file I/O in a program. Because file I/O is not part of the ComponentWorks functionality, the functions vary between different programming environments. Consult the data logger example in your programming environment for an example of how to perform file I/O.

All the file I/O functions are in the LogData subroutine, which you can use as a template for other input/output routines. The application uses a sequential ASCII file to store the data and appends new data to any existing data already in the file.

# Adding Testing and Debugging to Your Application

Although they vary depending on the programming environment, debugging tools normally include features such as breakpoints, step-run modes, and watch windows.

### **Error Checking**

ComponentWorks controls can report error information to you and to the application in a number of different ways:

- Return an error code from a function or method call
- Generate an error or warning event
- Throw an exception handled by your programming environment

The type of error reporting depends on the type of application and the preference of the programmer.

By default, all ComponentWorks controls generate exceptions when errors occur, rather than returning error codes from the methods. However, the DAQ and Instrumentation controls have a property, <code>ExceptionOnError</code>, that you can set to <code>False</code> if you want methods to return error codes instead of generating exceptions. Error events are generated by these controls if an error occurs during specific contexts of an operation. The contexts for which error events are generated are set in the <code>ErrorEventMask</code> property of the controls.

### **Exceptions**

Exceptions are error messages returned directly to your programming environment. Usually, exceptions are processed by displaying a default error message. The error message allows you to end your application or to enter debug mode and perform certain debugging functions. Part of the exception returned is an error number and error description, displayed as part of the error message. For example the AI control might return the following exception to Visual Basic.

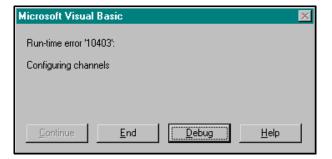


Figure 12-6. Visual Basic Error Messages

Depending on your programming environment, you might be able to insert code that can catch exceptions being sent to your application and handle them in another manner. In Visual Basic, you can do this by using the On Error statement.

• On Error Resume Next disables automatically generated error messages. The program continues running at the next line. To handle an error in this mode, you should check and process the information in the Err object in your code.

```
Private Sub Acquire_Click()
On Error Resume Next
    CWAI1.Configure
    If Err.Number <> 0 Then MsgBox "Configure: " +
        CStr(Err.Number)
    CWAI1.Start
    If Err.Number <> 0 Then MsgBox "Start: " +
        CStr(Err.Number)
End Sub
```

 On Error GoTo disables automatically generated error messages and causes program execution to continue at a specified location in the subroutine. You can define one error handler in your subroutine.

```
Private Sub Acquire_Click()
On Error GoTo ErrorHandler
    CWAI1.Configure
    CWAI1.Start
    Exit Sub
ErrorHandler:
    MsgBox "DAQ Error: " + CStr(Err.Number)
    Resume Next
End Sub
```

### **Return Codes**

If the ExceptionOnError property is set to False, the DAQ and Instrumentation control methods return a status code to indicate whether an operation completed successfully. If the return value is something other than zero, it indicates a warning or error. A positive return value indicates a warning, signifying that a problem occurred in the operation, but that you should be able to continue with your application. A negative value indicates an error—a critical problem that has occurred in the operation—and that all other functions or methods dependent on the failed operation also will fail.

You can use the specific value of the return code for more detailed information about the error or warning. The ComponentWorks DAQ controls can convert the error code into a more descriptive text message, as described in the *GetErrorText Function* section of this chapter.

To retrieve the return code from a method call, assign the value of the function or method to a long integer variable and check the value of the variable after calling the function or method. For example, the following code checks the return code of the CWAI control Start method.

```
lerr = CWAI1.Start
If lerr <> 0 Then MsgBox "Error at DAQ Start: " +
CStr(lerr)
```

In Visual Basic, you can use the **MsgBox** popup window to display error information. Normally, you can write one error handler for your application instead of duplicating it for every call to a function or method. For example, the following code creates a LogError subroutine to use with the Start method and later functions or methods.

```
Private Sub LogError(code As Long)
   If code <> 0 Then
        MsgBox "DAQ Error: " + CStr(code)
   End If
End Sub
```

To use the LogError subroutine, call LogError before every function or method call. The return code is passed to LogError and processed.

```
LogError CWAI1.Start
```

### **Error and Warning Events**

The DAQ and Instrumentation controls also include their own error and warning events—DAQError and DAQWarning. Although you normally use return codes for error checking of method calls, you cannot use return codes for error checking in asynchronous operations, such as a continuous analog input or asynchronous instrument control.

In this case, the controls generate their own error events if an error or warning occurs during an on-going process. You can develop an event handler to process these error and warning events. The following code shows the skeleton event functions for the CWAI control.

```
CWAI1_DAQError(ByVal StatusCode As Long, ByVal ContextID As Long, ByVal ContextDescription As String)

CWAI1_DAQWarning(ByVal StatusCode As Long, ByVal ContextID As Long, ByVal ContextDescription As String)
```

The StatusCode variable that is passed to the event handler contains the value of the error or warning condition. The ContextID contains a value describing the operation where the error or warning occurred, and the ContextDescription contains a string describing the operation where the error or warning occurred.

The following code, which produces the following error message box, shows an example of how you can use the AI\_DAQError event in a Visual Basic application.

```
Private Sub CWAI1_DAQError(ByVal StatusCode As Long,
   ByVal ContextID As Long, ByVal ContextDescription As
   String)
   MsgBox ContextDescription + ": CStr(StatusCode)
End Sub
```



Figure 12-7. Error Message Box

By default, only asynchronous operations call error and warning events. You can set the ErrorEventMask property to specify the operations for which the error and warning events are generated.

### **GetErrorText Function**

If you use return error codes to perform error checking, you might want to convert the error code values into more descriptive error texts. The ComponentWorks DAQ controls include a utility control that includes a method to convert error codes into descriptive error strings. To use this method, create a DAQTools control in your program and use the GetErrorText method as shown in the following example.

```
DAQError = CWAI1.Start
If DAQError <> 0 Then MsgBox
CWDAQTools.GetErrorText(DAQError)
```

The following screen shows a message box generated by using the GetErrorText function in the previous example.

Figure 12-8. Error Handling Message Box

Chapter 12

### **Debugging**

This section outlines a number of general debugging methods that you might use in your application development. If you experience some unexpected behavior in your program, use these methods to locate and correct the problem in your application.

### **Debug Print**

One of the most common debugging methods is to print out or display important variables throughout the program execution. You can monitor critical values and determine when your program varies from the expected progress. Some programming environments have dedicated debugging windows that are used to display such information without disturbing the rest of the user interface. For example, you can use the <code>Debug.Print</code> command in Visual Basic to print information directly to the debug window.

Debug.Print CWAI1.Channels.Item(1).ChannelString

### **Breakpoint**

Most development environments include breakpoint options so you can suspend program execution at a specific point in your code. Breakpoints are placed on a specific line of executable code in the program to pause program execution.

Stopping at a breakpoint confirms that your application ran to the line of code containing the breakpoint. If you are unsure whether a specific section of code is being called, place a breakpoint in the routine to find out. Once you have stopped at a specific section of your code, you can use other tools, such as a watch window or debug window, to analyze or even edit variables.

In some environments, breakpoints might also include conditions so program execution halts if certain conditions are met. These conditions usually check program variables for specific values. Once you have completed the work at the breakpoint, you can continue running your program, either in the normal run mode or in some type of single-step mode.

### **Watch Window**

Use a watch window to display the value of a variable during program execution. You can use it to edit the value of a variable while the program is paused. In some cases, you can display expressions, which are values calculated dynamically from one or more program variables.

### Single Step, Step Into, and Step Over

Use *single stepping* to execute a program one line at a time. This way, you can check variables and the output from your program during execution. Single stepping is commonly used after a breakpoint to slowly step though a questionable section of code.

If you use *step into*, the program executes any code available for subroutines or function calls and steps through it one line at a time. Use this mode if you want to check the code for each function called. The *step over* mode assumes that you do not want to go into the code for functions being called and runs them as one step.

In some cases, you might want to test a limited number of iterations of a loop but then run the rest of the iterations without stopping again. For this type of debugging, several environments include the *step to cursor* or *run to cursor* options. Under this option, you can place your cursor at a specific point in the code, such as the first line after a loop and run the program to that point.



# Using Previous Versions of Visual Basic, Visual C++, and Delphi with ComponentWorks

This appendix outlines differences between the current and previous version of the programming environments with respect to using the ComponentWorks controls. This revision of the *Getting Results with ComponentWorks* manual was written with the most current environments available: Visual Basic 5, Visual C++ 5, and Delphi 3. In this appendix, the most current versions are compared with Visual Basic 4, Visual C++ 4.x, and Delphi 2.

### Visual Basic 4

Differences between Visual Basic versions 4 and 5 include the design of the object browser, code completion in the code editor, and slightly different menu names. In addition to these environment differences, creating a default project to include ComponentWorks controls in version 5 is significantly different from creating one in version 4.

### **Menus and Commands**

The Visual Basic 4 environment uses slightly different menus and command names for different options. Use the following commands for common operations with ComponentWorks.

- To open the controls toolbox, select **Toolbox** from the **View** menu.
- To add controls to the project toolbox, right click on the toolbox and select Custom Controls....
- To add a DLL instrument driver to a project, select References... from the Tools menu.
- To open the object browser, select **Object Browser...** from the **View** menu or press <F2>.

- To open the Visual Basic properties page, select **Properties** from the **View** menu or press <F4>.
- To open custom property page for a control, right click on the control and select **Properties**.

### **Object Browser**

Although its functionality is nearly the same, the Object Browser design is different between the two versions of Visual Basic. Compare Figure A-1, *Visual Basic 4 Object Browser*, and Figure A-2, *Visual Basic 5 Object Browser*, which both have the ComponentWorks Graph control selected.

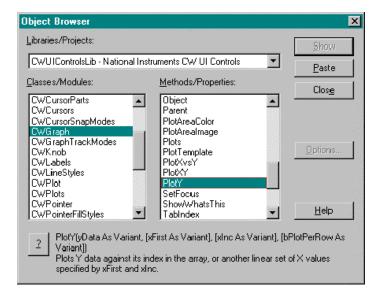


Figure A-1. Visual Basic 4 Object Browser

Notice that the Visual Basic 4 Object Browser does not list control events. The **Paste** button copies a selected item directly into the code editor; however, the button is enabled only when you open the Object Browser from the code editor.

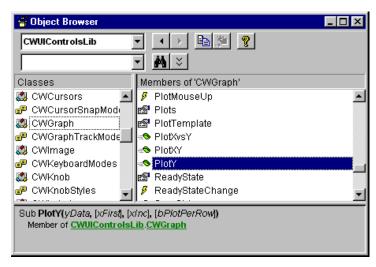


Figure A-2. Visual Basic 5 Object Browser

### **Code Completion**

The Visual Basic 4 code editor does not have code completion. When entering your program code you must completely enter the syntax or use the Object Browser to paste selected properties and methods into your code.

### **Creating a Default ComponentWorks Project**

Visual Basic 4 supports only one default project. The name of that project is AUTO32LD.VBP, and you can find it in the Visual Basic directory.

Use the following procedure to add the ComponentWorks controls to the default project or change the default controls.

- 1. Load the project AUTO32LD. VBP from the Visual Basic directory.
- 2. Add the ComponentWorks controls to the toolbox and make any other necessary changes.
- 3. Save the project in the same location.

When you create a new project, the ComponentWorks controls appear in the toolbox.

### Visual C++4.x

Visual C++ 4.x and Visual C++ 5.0 require different methods to install the ActiveX control in the controls toolbar for use in the dialog editor. For other operations, such as creating a new workspace and building your user interface and code, follow the directions in Chapter 4, *Building ComponentWorks Applications with Visual C++*. Although some of the dialog windows in Visual C++ 4.x are slightly different from the manual, the descriptions still apply.

### **Creating Your Application**

To create a new application in Visual C++ 4.x, use the MFC AppWizard as described in Chapter 4, *Building ComponentWorks Applications with Visual C*++. Initially, you see one extra dialog box, in which you should create a new **Project Workspace**. The next dialog allows you to select the **MFC AppWizard**.

In the second step of the MFC APPWizard, you must enable **OLE controls** support to use the ComponentWorks controls. This option is not automatically selected in Visual C++ 4.x. Complete the MFC AppWizard.

### Adding ComponentWorks Controls to the Visual C++ Controls Toolbar

This section explains how you can add the ComponentWorks controls to the toolbar in Visual C++4.x.

Before you can use the ComponentWorks controls in your application, you must load the controls into the Controls toolbar in Visual C++, which is done from the Component Gallery in the Visual C++ environment. When you load the controls with the Component Gallery, you automatically generate a set of C++ wrapper classes in your project, which you need to work with the ComponentWorks controls.

The Controls toolbar is visible in the Visual C++ environment only if the Visual C++ dialog editor is currently active. To open the dialog editor, open the Project Workspace window (select **Project Workspace** from the **View** menu), select **ResourceView**, and double click on one of the **Dialog** entries.

1. To add a new control, select the **Component...** option from the **Insert** menu. This opens the Component Gallery in Visual C++, as shown in the following illustration.

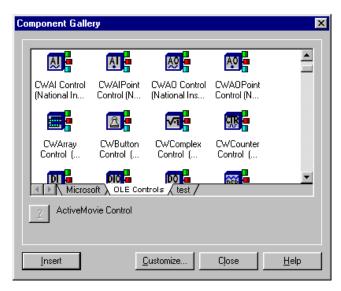


Figure A-3. Visual C++ Component Gallery

- 2. Select the **OLE Controls** tab in the gallery and look for the ComponentWorks controls. All ComponentWorks control names start with CW.
- 3. If the ComponentWorks controls are not shown in the OLE controls tab of the Component Gallery, push the **Customize...** button and the **Import** button in the following dialog. Select the OCX file on your hard drive that contains the controls you want to load. The ComponentWorks OCX files are located in the \Windows\System(32) directory and have names of the form CW\*.OCX. Repeat the import process for any additional OCX files you want to add to the Component Gallery.
- 4. From the Component Gallery, select a control you want to add to the Controls toolbar and push the **Insert** button. The dialog window that appears lists the classes generated for the ActiveX control and the file names used.
- 5. Click **OK** to continue.

With this procedure, you have added the new classes to your project and the new control to the Controls toolbar. Repeat this process for additional controls you want to add.

When you have completed adding controls, click on **Close** in the Component Gallery. The new controls should be visible in the Visual C++ environment Controls toolbar.

### **Building Your User Interface and Code**

Follow the directions in Chapter 4, *Building ComponentWorks Applications with Visual C++*, to build your user interface and use different VC++ tools, including the MFC Class Wizard, to build your code.

### Delphi 2

Delphi 2 and Delphi 3 require different methods for loading ActiveX controls into the Component palette of the environment. For all other operations, such as creating the user interface and code, refer to Chapter 5, *Building ComponentWorks Applications with Delphi*.



Remember that you must load the ComponentWorks controls into the Delphi environment before you can load and run any programs that use the ComponentWorks controls, including the examples installed with ComponentWorks.

### **Loading the ComponentWorks Controls into the Component Palette**

This section explains how you can add the ComponentWorks controls to the Component palette in Delphi 2.

Before you can use the ComponentWorks controls in your Delphi applications, you must add them to the Component palette in the Delphi environment. The controls need to be added only once to the palette because they will be available until they are explicitly removed from the Component palette. Adding the controls to the palette also creates a Pascal import unit (header file) that declares all the properties, methods, and events of a control. When you use a control on a form, a reference to the import unit is automatically added to the program.

#### Note

Before adding a new control to the Component palette, make sure to save all your work in Delphi, including files and projects. After loading the controls, Delphi closes any open projects and files to complete the loading process.

- 1. To add ActiveX controls to the Component palette, select **Install** from the **Component** menu in the Delphi environment.
- 2. In the Install Components window, press the **OCX** button.
- 3. In the Import OLE Control window, select the desired registered control that appears on the Registered Controls field. The ComponentWorks controls all start with National Instruments.

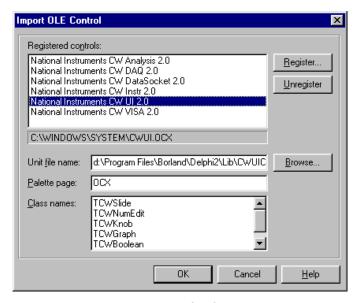


Figure A-4. Delphi Import OLE Control Dialog Box

4. After you have selected the proper control, click on **OK** to close the window. When you click the **OK** button, Delphi generates a Pascal import unit file for the selected OCX file, which is stored in the \Lib directory of Delphi. If you had previously installed the same .OCX file, it prompts you to overwrite the existing import unit file.

If your control does not appear in the Import OLE Control window it is not registered with the operating system. In this case, click on the **Register...** button to open the Register OLE Control window, find the OCX file that contains the control, and select it. This process registers the control with the operating system. Most OCX files are located in the \System (32) directory under Windows.

To load additional controls, return to the Import OLE Controls window and select more controls.

When you have finished selecting controls, click on **OK** in the Install Components window to load the new controls and add them to the **OCX** tab of the Component palette. Because this step closes any open projects in the Delphi environment, you need to reopen any projects you had open.

You can rearrange controls on the Component palette in Delphi by right clicking on the palette and selecting **Properties**.

## Background Information about Data Acquisition

This appendix provides background information on data acquisition (DAQ) software and hardware specific to the ComponentWorks DAQ controls and describes the underlying architecture used by these controls.

Chapter 7, *Using the Data Acquisition Controls*, and the online reference provide information on the ComponentWorks DAQ controls. You can access the online reference from the Windows **Start** menu by selecting **Programs»National Instruments ComponentWorks»**ComponentWorks Reference.

### Installation

Before you can use data acquisition hardware and software, you must completely install both the DAQ software and hardware and run the software configuration. To complete the installation, follow the instructions provided with your hardware and software. Usually, you first install the hardware. Verify that your computer is turned off and unplugged before opening it, and follow all other safety precautions. After installing the NI-DAQ software driver, restart your system. With most plug-in cards (AT and PCI cards), the operating system automatically detects that you have a new card installed.

If you plan to use ISA Plug-and-Play DAQ devices on Windows NT 4.0, you must install the Windows NT 4.0 ISA Plug-and-Play driver before configuring your device with the NI-DAQ Configuration Utility.

The Windows NT 4.0 ISA Plug-and-Play driver is not installed by default. Use the following steps to install the driver.

- 1. Insert your Windows NT 4.0 CD.
- 2. Access the \Drvlib\Pnpisa\X86 directory.
- 3. Right click on the Pnpisa.inf file, select the **Install** option, and follow the on-screen instructions.

- After you have installed the Pnpisa.inf file, shut down your computer.
- 5. If you have not already done so, install NI-DAQ and then shut down your computer.
- 6. Install your ISA Plug-and-Play DAQ device.
- Turn on your computer. When Windows NT 4.0 detects your ISA
   Plug-and-Play DAQ device, it specifies the necessary driver files.
   Because this results in a configuration change, you need to restart your computer.
- 8. After you have restarted your computer, run the NI-DAQ Configuration Utility to configure your device.

### Configuration

With the NI-DAQ Configuration Utility, you specify default settings for certain hardware options, such as input mode, input range, accessories, SCXI devices, and so on. Follow the directions provided with the NI-DAQ driver to configure your hardware.

Most data acquisition boards are automatically detected by the Windows operating system. If you have a board that Windows does not automatically detect, use the **Add New Hardware** option in the Windows Control Panel to manually inform Windows of the hardware.

You can use the DAQ Configuration Utility to test the operation of the device with its assigned resources (that is, the Input/Output range, Interrupt Request, and DMA channels). To run these tests, select a device in the NI-DAQ Devices list and click **Configure**. On the **System** property page, click the **Test Resources**. You also can perform simple input and output operations with your hardware by clicking **Run Test Panels...**.

#### SCXI

Configure any SCXI hardware on the **SCXI Devices** tab of the NI-DAQ Configuration Utility. Select **add new SCXI chassis and modules** and configure them according to your settings. Specify in the module configuration which module is connected to your DAQ. Save your changes.

#### **Device Number**

When configuring your hardware using the DAQ Configuration Utility, select a device number for each DAQ device. When you use the ComponentWorks AI, AIPoint, AO, and AOPoint controls, you specify the

device number as well as the channel number to use for the input and output operation. You can specify a Named Channel that you previously defined with the DAQ Channel Wizard rather than specifying the device number and channel number. Refer to the *Channel Wizard* section for more information about Named Channels.

#### **Channel Wizard**

You can use the DAQ Channel Wizard to create Named Channels. A Named Channel is a channel configuration that specifies a DAQ device; a hardware-specific channel string; channel attributes such as input limits, input mode, and actuator type; and a scaling formula for making a measurement or generating a signal in terms of your actual physical quantity. When you create a Named Channel, the DAQ Channel Wizard determines whether your DAQ device is capable of making the measurement.

You can start the Channel Wizard from the NI-DAQ Configuration Utility by selecting **File»Run Channel Wizard** or from the NI-DAQ program group in the Windows **Start** menu. Refer to the DAQ Channel Wizard help for instructions on creating Named Channels.

### **Programming**

After completing the NI-DAQ configuration, you can use the ComponentWorks DAQ controls. To become familiar with the DAQ controls, read Chapter 7, *Using the Data Acquisition Controls*, and complete the tutorials. Use the ComponentWorks online reference to obtain complete information about the DAQ controls.

The following sections describe several concepts that you might encounter when working with the ComponentWorks DAQ controls and DAQ hardware.

### **Device Number and Channels**

When you select and configure a DAQ control, first specify the device number and channel(s) you want to use with the control, or you might use named channels. See the *Channel Wizard* section for information about naming channels.

Use the Channels property of each control—Ports on the digital controls and Counter on the Counter and Pulse controls—to specify the particular channels you want to use with a specific control. A *channel* or *port* is a physical I/O location on a DAQ device. Most of the DAQ controls have a Channels or Ports collection to allow you to individually select and configure multiple channels or ports. These collections contain individual Channel and Port objects. For each Channel object, you can select one or more channels and configure additional properties to specify the operation of the hardware. For each Port object, you can select the direction (input or output) of the port.

#### **Buffers**

Buffers are memory locations used to store data, either acquired on a buffered input operation or generated on a buffered output operation. The individual control (AI, AO, DI, and DO) allocates the buffers according to the number of points it acquired. Normally, the buffer size is set equal to the number of points acquired or generated. In continuous or double buffered input operations, the buffer size is automatically set to a multiple of the number of points selected in the control. In continuous output operations, you explicitly select the buffer size.

When the buffer cannot store all the data as quickly as you can process it, you encounter an overflow condition. In such scenarios, you can increase the buffer size. The AI control allows you to disable the default buffer size and select your own value.

In single buffer operations, the buffer is written to or read from once. When the buffer is used up, the operation is completed. In continuous or double buffered operations, the same buffer is used multiple times. After using the buffer once, the operation returns to the beginning of the buffer and continues writing data to the buffer or reading data form the buffer. As the data acquisition operation writes data to the buffer or reads data from it, the application must retrieve data from the buffer or supply new data to the buffer. The application must complete this process quickly enough so unread input data is not overwritten or data is not generated twice on an output operation. On an output operation, you can allow regeneration of data.

Use the AcquiredData and Progress events with the buffers to indicate when a given number of points has been acquired or generated, which allows the application and developer to manage the data in the buffer more efficiently.

#### Clocks

Clocks are counter/timers on data acquisition devices that control the timing of operations such as a data acquisition or waveform generation. Some operations require multiple clocks.

Appendix B

The data acquisition driver programs the counter/timers that are used for clocks. Generally, the counter/timers cannot be controlled by the developer for other purposes. Configure the clocks for a particular DAQ process using the Clock objects in the ComponentWorks DAQ controls.

Typical Clock objects are the ScanClock and ChannelClock on the CWAI control. You can set properties such as a timebase source and frequency to determine the exact operation of the clocks. With this information, you can exactly configure the timing of a process to be controlled by the board with a preset frequency or to be synchronized with another onboard or external process. See the sections on *PFI* and *RTSI* for more information about routing timing signals.

#### Channel and Scan Clocks

You can acquire signals on multiple channels simultaneously. A multi-channel acquisition sometimes is referred to as a *scan*. Most data acquisition boards (for example, MIO E Series) have only one analog-to-digital converter with a multiplexor that connects only one of the analog input channels to the analog-to-digital converter at any given point in time. On these boards, the hardware cannot sample the channels in a multi-channel acquisition simultaneously. Rather, the hardware samples the channels in quick succession to approximate simultaneous sampling. The channel clock controls the interchannel daley between samplings of the channels in a multi-channel acquisition. By default, the CWAI control specifies that NI-DAQ automatically chooses the best possible interchannel delay, but you also can explicitly specify the interchannel delay using the ChannelClock property on the CWAI control.

The scan clock controls the timing between individual scans or between individual measurements in a one-channel acquisition. The scan rate is the actual acquisition rate per channel. You set the frequency of the scan clock in Hertz using the ScanClock object of the CWAI control. To synchronize the acquisition with another process, you can configure the ScanClock to take its input from another source.

### SCXI

SCXI is a set of signal conditioning hardware used with plug-in data acquisition cards. Refer to the *Hardware SCXI* section for more information.

#### **SCXI Channel String**

When using SCXI modules with your ComponentWorks DAQ control, set a special SCXI channel string to indicate which modules and channels are used with a specific process. The device number set in the DAQ control corresponds to the DAQ device connected to and controlling the SCXI chassis, which could be an SCXI-1200 module in the chassis. The SCXI channel string specifies which chassis, modules, and channels are used by your DAQ process. For analog input operations, you can specify an onboard DAQ channel to acquire all analog signals from the SCXI chassis.

The SCXI channel string is of the format "obA!scX!mdY!Z" (for example, "ob0!sc1!md1!0"). A, X, Y, and Z represent specific values that do vary.

- A is the onboard analog DAQ channel used to acquire analog input signals, and "obA!" is used only in analog input operations. The onboard channel A is usually one less than the chassis number x.
- x represents the chassis number starting with 1 and allows you to specify additional chassis in multi-chassis configurations. If you use more than one SCXI chassis, all chassis are controlled from the same DAQ board by routing a DAQ cable from the first chassis to the second and so on. Optionally, you can use additional DAQ boards to control an individual chassis.
- Y indicates which SCXI module (actually module slot) in a chassis to use. Module slots are numbered starting with 1 for the left most slot.
- z indicates which channels on an SCXI module to use.

For analog input operations, you can specify multiple channels on a module with the colon (:), but you can select only one continuous range of channels per module. For example, "3:11" specifies channels 3 through 11. For digital modules, all digital lines in a module are grouped in port 0 and you specify only "0" for your channel number.

For analog input operations, you can specify channels from multiple modules and chassis by using multiple Channel objects on your AI DAQ control.

#### **Examples**

| ob0!sc1!md3!0:4  | Analog Channels 0 through 4 on module 3 of chassis 1.                            |
|------------------|--|
| ob1!sc2!md1!5    | Analog Channel 5 on module 1 of chassis 2.                                       |
| sc1!md3!0        | Digital port 0 on module 3 of chassis1.  |
| ob0!sc1!md2!4:11 | Analog Channel 4 through 11 on module 2 and Channels 8 through 15 on module 3 of |
| ob0!sc1!md3!8:15 | chassis1.  |

#### **Hardware**

#### SCXI

SCXI is a set of signal conditioning hardware used with plug-in data acquisition cards. Signal conditioning prepares certain analog and digital signals for a plug-in DAQ card and provides functionality such as amplification, isolation, current supplies to sensors, multiplexing for higher channel counts, current to voltage conversion, and more.

An SCXI setup consists of an SCXI chassis and one or more SCXI modules selected for specific purposes and inserted in the SCXI chassis. Only one SCXI module per chassis is connected to the data acquisition board in your computer using a ribbon or shielded cable. This cable controls the chassis and all inserted modules from the DAQ board and passes signals from the chassis back to the computer. The modules in the chassis communicate with each other and route signals using the SCXI bus in the back of the chassis. All signal connections are made to the front of the individual chassis, which processes the signals and then passes them to the DAQ board using the SCXI bus and connected cable.

With analog input signals, the SCXI modules usually perform the signal conditioning and pass the conditioned signals to the DAQ card for analog-to-digital conversion. All analog input signals are multiplexed at the SCXI chassis on to one channel when transferred to the DAQ board. Analog output and digital I/O signals are directly processed on specific SCXI modules. Alternatively, you can use an SCXI-1200 module in the SCXI chassis to act as a DAQ device and perform the analog-to-digital conversion in the chassis. This module communicates with the computer using a digital connection such as a parallel cable.

Consult your SCXI hardware manual for more information about system configuration and settings. Remember that all SCXI hardware must be configured in the NI-DAQ configuration tool.

#### **RTSI**

The Real Time System Integration (RTSI) bus is an optional cable connection between multiple DAQ devices that allows you to share and exchange timing and trigger signals between devices. Use it to synchronize data acquisition processes running on multiple devices. For ISA (AT) and PCI bus cards, the RTSI connector is located along the top edge of the card and multiple cards can be connected to each other using an optional RTSI ribbon cable. PXI bus cards have the RTSI bus located on the PXI bus, and no additional cables are required.

The RTSI bus itself consists of seven signal lines (numbered 0 through 6) that can be freely defined using the DAQ software. Each DAQ device supporting RTSI contains a multiplexer that allows the card to route any available onboard signal, such as a timing or trigger signal, onto any of the seven available RTSI lines. Any board receiving a signal from the RTSI bus can route any of the seven signal lines back into one of its onboard signals. Although only one board at a time can supply a signal onto one of the RSTI lines, multiple boards can receive this signal into their onboard circuitry.

### **Programming**

When using RTSI to share signals between devices, such as synchronizing two analog input operations, always call two operations to specify both the sender and receiver of the RTSI signal. To supply a signal to a RTSI line, use the RouteSignal (all E-series cards) or RouteRTSI (other cards) method of the CWDAQTools control. On these methods, specify both the onboard signal and RTSI line. To receive a signal from a RTSI line and use it in a DAQ process, specify the RTSI line in your regular DAQ control. The different Clock and Condition objects that control the timing and triggering of the different processes include options to select a RTSI line as the signal source. For E-series cards to use a RTSI line as the scan clock of an analog input acquisition, set the ClockSourceType to one of the RTSI options (low-to-high or high-to-low) and set the RTSI line number in the ClockSourceSignal.

Programmable Function Inputs (PFI) are variable input lines on the I/O connectors of specific DAQ devices (E-series cards) that route input signals to a variety of onboard signals. They also can be used to route output signals to any of the PFI lines on the I/O connector. PFI lines are used to output onboard timing and trigger signals for external purposes, including synchronization between multiple devices when the RTSI bus is not available. Most devices have 10 PFI lines, numbered 0 through 9. When used as an input, each PFI line is mapped to a specific onboard signal and can be used only for that purpose. On the output direction, you can freely assign onboard signals to a specific PFI line.

Appendix B

Use the RouteSignal method of the CWDAQTools control to route a specific onboard signal to a PFI line. To use a signal connected to a PFI line as an input signal, specify the PFI line in the corresponding Clock or Condition object of the DAQ control.

Consult the online reference for the RouteSignal method and Clock and Condition objects for more information about using the PFI and RTSI lines.



### **Common Questions**

This appendix contains a list of answers to frequently asked questions. It contains general ComponentWorks questions as well as specific graphical user interface, data acquisition, instrument control, and analysis library questions.

### **Installation and Getting Started**

How do I run the installer? What do I do if the AutoRun screen does not appear?

The ComponentWorks CD contains a different installer for each development system. The Full Development System includes the Instrument Driver Factory and Instrument Drivers installers. You can start all installers from the ComponentWorks CD AutoRun screen.

The AutoRun screen appears automatically when you load the ComponentWorks CD in your computer. You also can open the AutoRun screen by running the SETUP program in the root directory of the CD. To manually start an individual installer, run the SETUP program in the corresponding subdirectory of the CD.



You must run the SETUP program if you copied the installer to floppy disks for installation on a system without a CD-ROM drive.

### What does it mean when I place a ComponentWorks control on my form and get an error saying that I am not licensed to use this control?

This error indicates that ComponentWorks was not installed properly. Make sure to install ComponentWorks on your computer using your installation disks or CD. Copying the OCX files from another machine or sharing them over a network does not work.

Make sure to close all other applications before running the ComponentWorks installer and restart your machine after completing the installation. If you had previously installed a demo or evaluation version of ComponentWorks, uninstall this version first and restart your computer before installing the licensed version of ComponentWorks.

#### How do I distribute an application using ComponentWorks?

To distribute an application using ComponentWorks or any ActiveX controls, you need to distribute all OCX files, DLL files, and supporting OCXs and DLLs referenced in the application. You also need to distribute any support DLLs required by your specific programming environment.

Any OCXs and OLE Automation DLLs (OLE Automation Servers) distributed with an application need to be registered in the operating system on the target computer. Usually, you can do this with an installer, which you build with the Setup Wizard/Tool provided by your programming environment. If your setup tool does not provide this functionality or if your environment does not include a setup tool, you need to manually install all necessary files and register the OCX files using the REGSVR32.EXE utility provided by Microsoft.

To install and manually register an OCX file, copy the file to the \System (for Windows 95) or \System32 (for Windows NT) subdirectory of the Windows directory on the target computer. Run the following:

regsvr32 c:\windows\system(32)\<ocxname>.ocx

To unregister a control, use the following:

regsvr32 /u c:\windows\system(32)\<ocxname>.ocx

If you distribute the ComponentWorks OCXs, you also need to make sure that all the necessary support DLLs are installed on the target machine. All the necessary support DLLs for the ComponentWorks controls are located in the \ComponentWorks\Setup\redist directory on the ComponentWorks CD.

Remember to include any files required by your programming environment, such as run-time DLLs. Check the documentation of your development environment for a list of required DLLs.

### **Visual Basic**

### I do not see any new controls in my Visual Basic toolbox. How do I load the ComponentWorks controls into Visual Basic?

To load the ComponentWorks controls in Visual Basic, right click on the toolbox and select **Components...** (**Custom Controls...** in Visual Basic 4) from the popup menu. Select the controls you want to use from the list of registered controls. If necessary, click on the **Browse** button to select a new unregistered control file. The ComponentWorks controls are located in the \Windows\System directory and start with CW. Select each of the controls and then click **OK** to return to Visual Basic. The new controls are placed in the toolbox.

### How can I have the ComponentWorks controls and libraries automatically loaded when I start Visual Basic?

In Visual Basic 5, you can have the ComponentWorks controls and libraries loaded by adding them to a template project. To do this, create a new project, load the controls, and save the project with a descriptive name in the (VB) \Template\Projects directory. When creating new projects, you have the option of including the ComponentWorks controls.

In Visual Basic 4, load the AUTO32LD project located in the Visual Basic directory, add the ComponentWorks controls and save the project.

### What is the difference in Visual Basic between using Base 0 or Base 1 to declare arrays?

Visual Basic can use either zero-based or one-based arrays. The default is Base 0. To change to the Base 1 option, use the following statement at the top of your code:

```
Option Base 1
```

You also can specify the exact range when declaring an array.

```
Dim voltBuffer(0 To 9) As Double
Dim voltBuffer(1 To 10) As Double
Dim voltBuffer(10 To 19) As Double
```

### What manuals and additional information are available for ComponentWorks?

Refer to Chapter 2, *Getting Started with ComponentWorks*, for information sources, including the online reference and Web site.

### **User Interface Controls**

#### How do I set the default value for a control such as the Knob or Slider?

To set the default value for a Knob, Slider, or Switch, open the default property page (<F4> in Visual Basic, <F11> in Delphi) and set the Value property.

In Visual C++, open the custom property pages and set the value. If the control is a ValuePairs Only control, set the ValuePairIndex property to the one-based index of the desired value pair.

#### How do I plot my data on the graph?

The easiest way to plot data is to use the PlotY method, which displays a simple plot of your values.

' dataArray can be an array or a variant containing an array

```
CWGraph1.PlotY dataArray, 0, 1, True
```

Additional methods you can use to plot or chart data include PlotXY, PlotXvsY, ChartY, ChartXY, and ChartXvsY. The Plot methods plot a whole data set at once, deleting any previous information on the same plot. You can define multiple plots on a graph in the property pages and use the Plot methods to update individual plots.

The Chart methods append data to existing plots and create scrolling charts. Refer to the online reference for more information about these methods.

### How do I display a value on a Slide, Knob, or NumEdit control and read values back from them? How do I read or set a button?

To pass a value to or read a value from one of these controls in Visual Basic and Borland Delphi, use their Value property. The Value property acts as a variable in your program, except that the value of this variable is the value of the control on the form.

```
' set the value of a slide to 5
CWSlide1.Value = 5
' read back the value from a knob
Dim ReadValue As Double
ReadValue = CWKnob1.Value
```

Buttons work in the same way, except that their values are Booleans.

```
' set a button
CWButton1.Value = True
' read a button
If CWButton1.Value = True then
' insert code here
End If
```

In Visual C++, control properties are not read or set directly (like variables). Instead, the wrapper class created for each control provide functions to read and write the value of that property. These functions are named with either Get or Set followed by the name of the property.

For example, to set the Value property of a slide, use the SetValue function. In the C code, the function call is preceded by the member variable name of the control to which it applies.

```
m_Slide.SetValue(5);
```

To read the value of a control, use the GetValue function. You can use the GetValue function to pass a value to another part of your program. For example, to pass the value of a slide to a meter use the following line of code.

```
m_Meter.SetValue(m_Slide.GetValue());
```

You can view the names of all the property functions in the ClassView of the Project Workspace in Visual C++. In the Project Workspace, select the ClassView and then the control/object to view its property functions (as well as its methods).

#### How can I change the style of my UI controls programmatically?

The Button, Knob, and Slide controls each have a number of default styles, which you can choose in the property pages of the control. In some applications, you might want to switch the style of a control while the program is running.

Use the SetBuiltinStyle method to change the style at run time to one of the predefined styles. The different styles are defined as constants in the UI controls.

```
CWSlide1.SetBuiltinStyle cwSlideStyleTank
CWKnob1.SetBuiltinStyle cwKnobStyleDial
CWButton1.SetBuiltinStyle cwButtonStyleRoundLED
```

You can use the ExportStyle and ImportStyle methods on all UI controls to save and load custom-defined styles. To save a predefined style, configure a control and click the Export Style (floppy disk icon) button in the property pages of the control (or right click on the control and select **Export Style**). Assign a file name for the new style. Using ImportStyle, you can interactively or programmatically load the settings from this file.

### How do I access or change a particular axis, plot, cursor, or value pair on one of the UI controls?

Each of these objects, with the exception of the axis on the knob and slide, is contained within a collection object on the control. A collection object is a special object on a control that is used to store multiple objects of the same type. For example a graph can have many different axes. Rather than linking each Axis object directly to the graph, one Axes collection is linked to the graph and it contains all the axes.

Other objects are contained in collections—the Plot, Cursor, ValuePair, and Channel objects on the Data Acquisition controls. The name of the collection object is the name of the contained object in plural form. For example, the collection of Axis objects is Axes, Plot is Plots, Cursor is Cursors, and so on.

The ValuePair object is contained in the ValuePairs collection, which itself is part of the Axis object contained in the Knob or Slide control or in the Axes collection of the graph.

To access one of the objects in a collection, use the Item method of the collection object. The Item method extracts a particular object in the collection using a parameter, which is the one-based index of the object in the collection. For example, to access the first plot on a graph, use the following code.

```
CWGraph1.Plots.Item(1)
```

This code segment refers to the first plot on a graph as an object. You can then access the properties of the plot object by appending the name of the property. For example to read the X position of the second cursor on a graph, use the following code.

```
x = CWGraph1.Cursors.Item(2).XPosition
```

The properties of individual objects are described in the online reference. Search for the corresponding object name, such as CWAxis, CWPlot, CWCursor, and so on, to find the description. Each of the collection objects also has a number of properties and methods, described in the online reference under the collection name, such as CWAxes, CWPlots, and so on.

Use the Count property to determine the number of objects in a collection.

```
NumAxes = CWGraph1.Axes.Count
```

Use the Add, Remove, and RemoveAll methods to programmatically change the number of objects in a collection (for example, you can add and delete axes, cursors, value pairs, and so on in your program). The Remove method requires the index of the object you want to remove.

```
CWSlide1.Axis.ValuePairs.Remove 3
CWGraph1.Cursors.RemoveAll
```

Remember that ValuePair objects are contained in the ValuePairs collection, which itself is part of an Axis object. The following code shows you how to access value pairs.

```
CWKnob1.Axis.ValuePairs.Item(1).Name = "Maximum"
CWGraph1.Axes.Item(3).ValuePairs.Item(2).Value = 7.5
```

#### How do I add labels to the ComponentWorks graph axes?

Set the Caption property of the corresponding axis interactively on the **Ticks** tab of the Graph property pages.

### How do I show gridlines on my graph without displaying the scales (similar to an oscilloscope screen)?

In the Ticks section of the Graph property pages, enable the grid lines for the selected axis and disable all the ticks and labels for the same axis. Make sure to keep the Visible property of the axis enabled.

### **Data Acquisition Controls**

### What methods and events do I need to use for the DAQ analog input control?

The DAQ AI control has four main methods—Configure, Start, Stop, Reset. The methods are listed and described in the ComponentWorks online reference.

After you set the properties of the AI control in the property pages, call the Configure method to pass the property values to the driver and hardware. Then call Start to start the actual acquisition. Use the Stop method to stop a continuous acquisition, and the Reset method to stop any acquisition and reset the driver and hardware. You need to call Configure anytime you change a property value programmatically, after you call the Reset method, or after the acquisition stops because of an error.

The AI control AcquiredData event, which is called when a set number of points is acquired, returns the data to the program. Two additional events, DAQError and DAQWarning, are generated in response to any errors or warnings that occur in the DAQ process. The ErrorEventMask property determines for which operations (contexts) of the AI control these events are called.

### How do I assign new channels dynamically or retrieve channel information from the DAQ AI control in my program?

Use the Channels collection object of the AI control to retrieve information from individual Channel objects. Use the CWAI.Channels.Item(n) syntax to access individual Channel objects.

```
Dim ChannelInfo As String
ChannelInfo = CWAI1.Channels.Item(1).ChannelString
```

Use CWAI. Channels. RemoveAll and CWAI. Channels. Add with the appropriate information in the parameter list to delete all the Channel objects in the channel list (Channels collection) and to add new Channel objects to the collection.

```
CWAI.Channels.RemoveAll
```

Refer to the properties on CWAI. Channels in the online reference manual for more information.

### Why does my EISA-A2000, AT-A2150, or AT-DSP2200 data acquisition card not work with ComponentWorks?

These three boards are not compatible with the ComponentWorks data acquisition controls.

### How do I pass an array to CWAI. AcquireData? I keep getting type mismatches on my declared arrays. What is a Variant data type?

The two data buffers (ScaledData and BinaryCodes) of the AcquireData method are defined as variant data types. Do not declare them as arrays. Select two variable names, declare them as Variant, and pass them to AcquireData. The AcquireData method re-declares these variables to the correct array data type and array size.

Variant data types are used when the resultant data type is not known ahead of time. This allows a function or method to re-declare the variant variable to the appropriate type.

```
Dim Volts As Variant
Dim BinaryBuffer As Variant
Dim Timeout As Single
Timeout = 5
CWAI1.AcquireData (Volts, BinaryBuffer, Timeout)
```

When performing a single channel acquisition, data buffers are declared as one-dimensional arrays; a multi-channel acquisition are declared with two-dimensional arrays.

#### What is a named channel? What is a hardware-specific channel string?

A named channel is a symbolic name that represents a specific channel on a data acquisition device. For analog input channels, a named channel also includes information about the input range of the signal that your are measuring, the input mode of the channel, the coupling of the channel, and the scaling formula that the data acquisition driver (NI-DAQ) uses to convert the acquired voltages into engineering units. For analog output channels, a named channel also includes information specifying the actuator to use and a scaling formula that NI-DAQ uses to convert data specified in engineering units into the units of the actuator (for example, volts or milliAmps). You create named channels using the Channel Wizard feature of the NI-DAQ Configuration Utility.

Hardware-specific channel strings identify a channel on a DAQ device and contain no information about the device, scaling, or other attributes.

Examples of hardware-specific channel string refers are "1", "2:0", and "ob0!sc1!md2!0:3".

#### What is the Channel Wizard?

The Channel Wizard is a tool that you use to define named channels. You launch the Channel Wizard from the NI-DAQ Configuration Utility, which is launched from a shortcut in the NI-DAQ program group (usually Start»Programs»NI-DAQ for Windows»NI-DAQ Configuration Utility).

#### Can I mix named channels with hardware-specific channel strings?

No. You can specify either named channels or hardware-specific channel strings within one Channels collection or channel string of your DAQ control, but not both.

### Can I mix named channels that refer to different I/O types in the same channel string, such as analog and digital input?

No. Each ComponentWorks DAQ controls can work with only named channels that refer to the I/O type corresponding to the control.

### I start my acquisition, but I get no data back and no errors. What is happening?

First, make sure that you set the ExceptionOnError property of the DAQ controls to True. If this property is set to False, you must check for non-zero return values from the methods that you call on the DAQ controls.

Second, make sure that you implement the DAQError and DAQWarning event handlers.

Third, if you are using an external clock or external triggers on the acquisition, make sure that you have wired valid signals to the data acquisition hardware.

Finally, if you are using all of the above mechanisms and you still do not receive any AcquiredData events and no errors, it is possible that the acquisition has stopped because of an overflow error or even an unexpected computer error. During an ongoing acquisition, the NI-DAQ driver only posts messages to the DAQ controls when the specified number of points has been acquired. If the acquisition has stopped because of an error,

NI-DAQ does not post a message and, as such, the DAQ control cannot fire any events notifying you of the error.

You can implement a watchdog timer using a Timer control that you reset on each AcquiredData event. If the acquisition unexpectedly stops sending events, the watchdog timer will fire an event, indicating that an error occurred.

Computer errors that can stop the acquisition include an electromagnetic pulse or power glitch that resets the data acquisition hardware without resetting the computer.

### My mouse stops responding and the computer locks up after starting my acquisition?

Your acquisition rate is too fast. The NI-DAQ driver is posting messages at a rate too fast for your system. You can increase the number of scans between events, slow the acquisition rate, or turn off events and use a synchronous method for obtaining the data such as the AcquireData or Read method.

If you have a very fast acquisition and you want to read the most recent data acquired, turn off the AcquiredData and Progress event. Call the Start method and then call the Read method, passing in a ReadSpec variable with the ReadMode property set to cwaiEndOfData.

### How do I program the counter/timer on my Lab-PC+, DAQCard-1200, or DAQCard-700 (or other 1200, 700, 500 series DAQ device)?

To program the counter/timer on these DAQ devices, use the ICtr functions in the DAQTools control. Consult the online reference for the descriptions of the StartICtr, ReadICtr, and ResetICtr functions. Do not use the CWCounter and CWPulse controls to program the counters on these devices.

### **GPIB**, Serial, and VISA Controls

#### Why doesn't my device show up in the Detected Devices list?

First, check to make sure that the cables are secure. It is possible that a properly connected device might not show up as a listener if there are errors on the bus. Try changing the address of the device or resetting the device. With GPIB, check the results of the detection by using GPIB/NI-Spy, which comes with the National Instruments GPIB board.

#### Why can't I communicate with my device or instrument?

For GPIB, check the NI-488 global variables, ibsta and iberr, in the **Test** property page to see what the status is after the function. If an error is being reported, such as ENOL (Error No Listener), your device might not be at the correct GPIB address. Also, verify that the cables are secure. The NI-488 documentation discusses other troubleshooting methods for other errors.

If no error conditions exist but you still cannot communicate as you expect, you might not have sent the right command in the sequence that the device requires or you might not have sent the correct terminating characters. Terminating characters are typically semicolon, carriage return, line feed, or combinations of characters. The GPIB driver software never appends these to your data automatically. You must include these characters, if needed by your device, in the character string passed to the control method function. Check your device programming manual for the exact protocols required.

For serial, check the error status in the **Test** property page to see what the status is after the call that does not seem to be operating correctly. If an error is being reported such as Bad Comm Port, your device might not be at the correct serial port. Also, verify that the cables are secure.

If no error condition exists but you still cannot communicate as you expect, you might not have sent the right command in the sequence that the device requires or you may not have sent the correct terminating (EOS) characters. Terminating characters are typically semicolon, carriage return, line feed, or combinations of characters. The Serial control never appends these to your data automatically. You must include these characters, if needed by your device, in the character string passed to the device. You might need to adjust other settings on the Serial control also, such as flow control, parity,

baud rate, and so on. These settings must match those of the device. Check your device programming manual for the exact protocols required.

For VISA, follow the same method as described above, corresponding to your hard interface. Make sure you have the newest version of the NI-VISA driver, version 1.2 or newer, installed.

### Why does the Test property page work with my device but my program does not?

The **Test** Property page in the Instrument controls lets users interactively type commands to be sent to the device and is an excellent place to start your development. It lets you test your commands before writing code. However, since the **Test** Property Page is interactive, you are naturally introducing very long delays between commands sent to your device. When you put the same commands in a program, the delays are gone. To solve the problem, put delays in your code where the program is failing. If this does not work, make sure you are checking for errors in the OnError event. This information can reveal details that will help troubleshoot your problem.

#### What does the Number Parser do and how do I use it?

The Number Parser is a parsing pattern that takes all of the numbers in a string and returns them as an array of doubles, ignoring all other information in the string.

#### Where can I learn more about how to use the parsing tools included in the Serial, GPIB, and VISA controls?

There are several parsing examples provided in the \ComponentWorks\
samples\programming language>\Instrument Drivers
directory, in addition to the online reference.

### **Analysis Controls**

#### How do I call an analysis function?

All ComponentWorks analysis functions are methods of the different Analysis controls. To use a specific function, place the corresponding control in your program. Then call the function as a method of the control in your program, passing any necessary parameters and assigning the return value to a variable if appropriate. For example, calling the Mean function on the CWStat control has the following syntax in Visual Basic.

MeanVal = CWStat1.Mean(data)

Consult the online reference manual for complete documentation of each analysis function.

### My analysis functions seem to have no effect. What does the return code –30008 mean?

The analysis functions are licensed in three different levels of the analysis library corresponding to the three different levels of ComponentWorks packages. If you attempt to call a function that is not in your level of the analysis library, you get an error –30008.

See Chapter 10, *Using the Analysis Controls and Functions*, for a list of the analysis functions and their corresponding license level.



### **Error Codes**

This appendix lists the error codes returned by the ComponentWorks DAQ controls, ComponentWorks VISA control, and Analysis Library functions. It also lists some general ComponentWorks error codes.

Table D-1 lists the negative error codes returned by the DAQ controls. Each DAQ control returns an error code that indicates whether it executed successfully. When a control returns a code that is negative, the control did not execute.

Table D-1. Data Acquisition Control Error Codes

| Error Code | Description  |
|------------|--|
| -10001     | An error was detected in the input string; the arrangement or ordering of the characters in the string is not consistent with the expected ordering.                                   |
| -10002     | An error was detected in the input string; the syntax of the string is correct, but certain values specified in the string are inconsistent with other values specified in the string. |
| -10003     | The value of a numeric parameter is invalid.   |
| -10004     | The value of a numeric parameter is inconsistent with another one, and therefore the combination is invalid.   |
| -10005     | The device is invalid.   |
| -10006     | The line is invalid.   |
| -10007     | A channel, port, or counter is out of range for the device type or device configuration; or the combination of channels is not allowed; or the scan order must be reversed (0 last).   |
| -10008     | The group is invalid.  |
| -10009     | The counter is invalid.  |
| -10010     | The count is too small or too large for the specified counter, or the given I/O transfer count is not appropriate for the current buffer or channel configuration.                     |

 Table D-1.
 Data Acquisition Control Error Codes (Continued)

| Error Code | Description   |
|------------|---|
| -10011     | The analog input scan rate is too fast for the number of channels and the channel clock rate; or the given clock rate is not supported by the associated counter channel or I/O channel.  |
| -10012     | The analog input or analog output voltage range is invalid for the specified channel, or you are writing an invalid voltage to the analog output.   |
| -10013     | The driver returned an unrecognized or unlisted error code.   |
| -10014     | The group size is too large for the board.  |
| -10015     | The time limit is invalid.  |
| -10016     | The read count is invalid.  |
| -10017     | The read mode is invalid.   |
| -10018     | The offset is unreachable.  |
| -10019     | The frequency is invalid.   |
| -10020     | The timebase is invalid.  |
| -10021     | The limits are beyond the range of the board.   |
| -10022     | Your data array contains an incomplete update, or you are trying to write past the end of the internal buffer, or your output operation is continuous and the length of your array is not a multiple of one half of the internal buffer size.   |
| -10023     | The write mode is out of range or is disallowed.  |
| -10024     | Adding the write offset to the write mark places the write mark outside the internal buffer.  |
| -10025     | The requested input limits exceed the board's capability or configuration. Alternative limits were selected.  |
| -10026     | The requested number of buffers or the buffer size is not allowed. For example, the buffer limit for Lab and 1200 devices is 64K samples, or the board does not support multiple buffers.   |
| -10027     | For DAQEvents 0 and 1 general value A must be greater than 0 and less than the internal buffer size. If DMA is used for DAQEvent 1, general value A must divide the internal buffer size evenly, with no remainder. If the TIO-10 is used for DAQEvent 4, general value A must be 1 or 2. |

 Table D-1.
 Data Acquisition Control Error Codes (Continued)

| Error Code | Description  |
|------------|--|
| -10028     | The cutoff frequency specified is not valid for this device.   |
| -10029     | The function you are calling is no longer supported in this version of the driver.   |
| -10030     | The specified baud rate for communicating with the serial port is not valid on this platform.  |
| -10031     | The specified SCXI chassis does not correspond to a configured SCXI chassis.   |
| -10032     | The SCXI module slot that was specified is invalid or corresponds to an empty slot.  |
| -10033     | The window handle passed to the function is invalid.   |
| -10034     | No configured message matches the one you tried to delete.   |
| -10035     | The specified attribute is not relevant.   |
| -10036     | The specified year is invalid.   |
| -10037     | The specified month is invalid.  |
| -10038     | The specified day is invalid.  |
| -10039     | The specified input string is too long. For instance, DAQScope 5102 devices can only store a string up to 32 bytes in length on the calibration EEPROM. In that case, please shorten the string. |
| -10080     | The gain is invalid.   |
| -10081     | The pretrigger sample count is invalid.  |
| -10082     | The posttrigger sample count is invalid.   |
| -10083     | The trigger mode is invalid.   |
| -10084     | The trigger count is invalid.  |
| -10085     | The trigger range or trigger hysteresis window is invalid.   |
| -10086     | The external reference is invalid.   |
| -10087     | The trigger type is invalid.   |
| -10088     | The trigger level is invalid.  |

Table D-1. Data Acquisition Control Error Codes (Continued)

| Error Code | Description   |
|------------|---|
| -10089     | The total count is inconsistent with the buffer size and pretrigger scan count or with the board type.  |
| -10090     | The individual range, polarity, and gain settings are valid but the combination is not allowed.   |
| -10091     | You have attempted to use an invalid setting for the iterations parameter. The iterations value must be 0 or greater. Your device might be limited to only two values, 0 and 1.   |
| -10092     | Some devices require a time gap between the last sample in a scan and the start of the next scan. The scan interval you have specified does not provide a large enough gap for the board. See your documentation for an explanation.            |
| -10093     | FIFO mode waveform generation cannot be used because at least one condition is not satisfied.   |
| -10094     | The calDAC constant passed to the function is invalid.  |
| -10095     | The calibration stimulus passed to the function is invalid.   |
| -10100     | The requested digital port width is not a multiple of the hardware port width or is not attainable by the DAQ hardware.   |
| -10120     | Invalid application used.   |
| -10121     | Invalid counterNumber used.   |
| -10122     | Invalid paramValue used.  |
| -10123     | Invalid paramID used.   |
| -10124     | Invalid entityID used.  |
| -10125     | Invalid action used.  |
| -10200     | Unable to read data from EEPROM.  |
| -10201     | Unable to write data to EEPROM.   |
| -10202     | You cannot write into this location or area of your EEPROM because it is write-protected. You may be trying to store calibration constants into a write-protected area; if this is the case, you should select user area of the EEPROM instead. |
| -10240     | The driver interface could not locate or open the driver.   |

 Table D-1.
 Data Acquisition Control Error Codes (Continued)

| Error Code | Description   |
|------------|---|
| -10241     | One of the driver files or the configuration utility is out of date, or a particular feature of the Channel Wizard is not supported in this version of the driver.  |
| -10242     | The specified function is not located in the driver.  |
| -10243     | The driver could not locate or open the configuration file, or the format of the configuration file is not compatible with the currently installed driver.  |
| -10244     | The driver encountered a hardware-initialization error while attempting to configure the specified device.  |
| -10245     | The driver encountered an operating system error while attempting to perform an operation, or the operating system does not support an operation performed by the driver.   |
| -10246     | The driver is unable to communicate with the specified external device.   |
| -10247     | The CMOS configuration-memory for the device is empty or invalid, or the configuration specified does not agree with the current configuration of the device, or the EISA system configuration is invalid.  |
| -10248     | The base addresses for two or more devices are the same; consequently, the driver is unable to access the specified device.   |
| -10249     | The interrupt configuration is incorrect given the capabilities of the computer or device.  |
| -10250     | The interrupt levels for two or more devices are the same.  |
| -10251     | The DMA configuration is incorrect given the capabilities of the computer/DMA controller or device.   |
| -10252     | The DMA channels for two or more devices are the same.  |
| -10253     | Unable to find one or more jumperless boards you have configured using the NI-DAQ Configuration Utility.  |
| -10254     | Cannot configure the DAQCard because 1) the correct version of the card and socket services software is not installed; 2) the card in the PCMCIA socket is not a DAQCard; or 3) the base address and/or interrupt level requested are not available according to the card and socket services resource manager. Try different settings or use AutoAssign in the NI-DAQ Configuration Utility. |

 Table D-1.
 Data Acquisition Control Error Codes (Continued)

| Error Code | Error Code Description   |  |
|------------|--|--|
| -10255     | •  |  |
|            | There was an error in initializing the driver for Remote SCXI.   |  |
| -10256     | There was an error in opening the specified COM port.  |  |
| -10257     | Bad base address specified in the configuration utility.   |  |
| -10258     | Bad DMA channel 1 specified in the configuration utility or by the operating system.   |  |
| -10259     | Bad DMA channel 2 specified in the configuration utility or by the operating system.   |  |
| -10260     | Bad DMA channel 3 specified in the configuration utility or by the operating system.   |  |
| -10261     | The user mode code failed when calling the kernel mode code.   |  |
| -10340     | No RTSI signal/line is connected, or the specified signal and the specified line are not connected.                                    |  |
| -10341     | The RTSI signal/line cannot be connected as specified.   |  |
| -10342     | The specified RTSI signal is already being driven by a RTSI line, or the specified RTSI line is already being driven by a RTSI signal. |  |
| -10343     | The specified SCXI configuration parameters are invalid, or the function cannot be executed with the current SCXI configuration.       |  |
| -10344     | The Remote SCXI unit is not synchronized with the host. Reset the chassis again to resynchronize it with the host.                     |  |
| -10345     | The required amount of memory cannot be allocated on the Remote SCXI unit for the specified operation.                                 |  |
| -10346     | The packet received by the Remote SCXI unit is invalid. Check your serial port cable connections.                                      |  |
| -10347     | There was an error in sending a packet to the remote chassis. Check your serial port cable connections.                                |  |
| -10348     | The Remote SCXI unit is in reprogramming mode and is waiting for reprogramming commands from the host (NI-DAQ Configuration Utility).  |  |
| -10349     | The module ID read from the SCXI module conflicts with the configured module type.   |  |

 Table D-1.
 Data Acquisition Control Error Codes (Continued)

| Error Code | Description   |
|------------|---|
| -10360     | The DSP driver was unable to load the kernel for its operating system.  |
| -10370     | The scan list is invalid; for example, you are mixing AMUX-64T channels and onboard channels, scanning SCXI channels out of order, or have specified a different starting channel for the same SCXI module. Also, the driver attempts to achieve complicated gain distributions over SCXI channels on the same module by manipulating the scan list and returns this error if it fails. |
| -10400     | The specified resource is owned by the user and cannot be accessed or modified by the driver.   |
| -10401     | The specified device is not a National Instruments product, the driver does not support the device (for example, the driver was released before the device was supported), or the device has not been configured using the NI-DAQ Configuration Utility.  |
| -10402     | No device is located in the specified slot or at the specified address.   |
| -10403     | The specified device does not support the requested action (the driver recognizes the device, but the action is inappropriate for the device).  |
| -10404     | No line is available.   |
| -10405     | No channel is available.  |
| -10406     | No group is available.  |
| -10407     | The specified line is in use.   |
| -10408     | The specified channel is in use.  |
| -10409     | The specified group is in use.  |
| -10410     | A related line, channel, or group is in use; if the driver configures the specified line, channel, or group, the configuration, data, or handshaking lines for the related line, channel, or group will be disturbed.   |
| -10411     | The specified counter is in use.  |
| -10412     | No group is assigned, or the specified line or channel cannot be assigned to a group.   |
| -10413     | A group is already assigned, or the specified line or channel is already assigned to a group.   |

Table D-1. Data Acquisition Control Error Codes (Continued)

| Error Code | Description  |
|------------|--|
| -10414     | The selected signal requires a pin that is reserved and configured only by NI-DAQ. You cannot configure this pin yourself.   |
| -10415     | This function does not support your DAQ device when an external multiplexer (such as an AMUX-64T or SCXI) is connected to it.  |
| -10440     | The specified resource is owned by the driver and cannot be accessed or modified by the user.  |
| -10441     | No memory is configured to support the current data transfer mode, or<br>the configured memory does not support the current data transfer mode.<br>(If block transfers are in use, the memory must be capable of performing<br>block transfers.)   |
| -10442     | The specified memory is disabled or is unavailable given the current addressing mode.  |
| -10443     | The transfer buffer is not aligned properly for the current data transfer mode. For example, the buffer is at an odd address, is not aligned to a 32-bit boundary, is not aligned to a 512-bit boundary, and so on. Alternatively, the driver is unable to align the buffer because the buffer is too small. |
| -10444     | No more system memory is available on the heap, or no more memory is available on the device, or insufficient disk space is available.   |
| -10445     | The transfer buffer cannot be locked into physical memory. On PC AT machines, portions of the DMA data acquisition buffer may be in an invalid DMA region, for example, above 16 megabytes.  |
| -10446     | The transfer buffer contains a page break; system resources may require reprogramming when the page break is encountered.  |
| -10447     | The operating environment is unable to grant a page lock.  |
| -10448     | The driver is unable to continue parsing a string input due to stack limitations.  |
| -10449     | A cache-related error occurred, or caching is not supported in the current mode.   |
| -10450     | A hardware error occurred in physical memory, or no memory is located at the specified address.  |

 Table D-1.
 Data Acquisition Control Error Codes (Continued)

| Error Code | Description   |
|------------|---|
| -10451     | The driver is unable to make the transfer buffer contiguous in virtual memory and therefore cannot lock it into physical memory; thus, the buffer cannot be used for DMA transfers.   |
| -10452     | No interrupt level is available for use.  |
| -10453     | The specified interrupt level is already in use by another device.  |
| -10454     | No DMA controller is available in the system.   |
| -10455     | No DMA channel is available for use.  |
| -10456     | The specified DMA channel is already in use by another device.  |
| -10457     | DMA cannot be configured for the specified group because it is too small, too large, or misaligned. Consult the device user manual to determine group ramifications with respect to DMA.  |
| -10458     | The storage disk you specified is full.   |
| -10459     | The NI-DAQ DLL could not be called due to an interface error.   |
| -10460     | You have mixed VIs from the DAQ library and the _DAQ compatibility library (LabVIEW 2.2 style VIs). You may switch between the two libraries only by running the DAQ VI Device Reset before calling _DAQ compatibility VIs or by running the compatibility VI Board Reset before calling DAQ VIs. |
| -10461     | The specified resource is unavailable because it has already been reserved by another entity.   |
| -10462     | The specified resource has not been reserved, so the action is not allowed.   |
| -10480     | The scan list is too large to fit into the mux-gain memory of the board.  |
| -10481     | You must provide a single buffer of interleaved data, and the channels must be in ascending order. You cannot use DMA to transfer data from two buffers; however, you may be able to use interrupts.  |
| -10540     | At least one of the SCXI modules specified is not supported for the operation.  |
| -10541     | CTRB1 will drive COUTB1, however CTRB1 will also drive TRIG1. This may cause unpredictable results when scanning the chassis.   |
| -10560     | The DSP handle input is not valid.  |

 Table D-1. Data Acquisition Control Error Codes (Continued)

| Error Code | Description   |
|------------|---|
| -10561     | Either DAQ or WFM can use a PC memory buffer, but not both at the same time.  |
| -10600     | No setup operation has been performed for the specified resources. Or, some resources require a specific ordering of calls for proper setup.  |
| -10601     | The specified resources have already been configured by a setup operation.  |
| -10602     | No output data has been written into the transfer buffer.   |
| -10603     | The output data associated with a group must be for a single channel or must be for consecutive channels.   |
| -10604     | Once data generation has started, only the transfer buffers originally written to may be updated. If DMA is active and a single transfer buffer contains interleaved channel data, new data must be provided for all output channels currently using the DMA channel. |
| -10605     | No data was written to the transfer buffer because the final data block has already been loaded.  |
| -10606     | The specified resource is not armed.  |
| -10607     | The specified resource is already armed.  |
| -10608     | No transfer is in progress for the specified resource.  |
| -10609     | A transfer is already in progress for the specified resource, or the operation is not allowed because the device is in the process of performing transfers, possibly with different resources.  |
| -10610     | A single output channel in a group may not be paused if the output data for the group is interleaved.   |
| -10611     | Some of the lines in the specified channel are not configured for the transfer direction specified. For a write transfer, some lines are configured for input. For a read transfer, some lines are configured for output.   |
| -10612     | The specified line does not support the specified transfer direction.   |
| -10613     | The specified channel does not support the specified transfer direction.  |
| -10614     | The specified group does not support the specified transfer direction.  |
| -10615     | The clock configuration for the clock master is invalid.  |

 Table D-1.
 Data Acquisition Control Error Codes (Continued)

| Error Code | Description  |
|------------|--|
| -10616     | The clock configuration for the clock slave is invalid.  |
| -10617     | No source signal has been assigned to the clock resource.  |
| -10618     | The specified source signal cannot be assigned to the clock resource.  |
| -10619     | A source signal has already been assigned to the clock resource.   |
| -10620     | No trigger signal has been assigned to the trigger resource.   |
| -10621     | The specified trigger signal cannot be assigned to the trigger resource.   |
| -10622     | The pretrigger mode is not supported or is not available in the current configuration, or no pretrigger source has been assigned.  |
| -10623     | No posttrigger source has been assigned.   |
| -10624     | The delayed trigger mode is not supported or is not available in the current configuration, or no delay source has been assigned.  |
| -10625     | The trigger configuration for the trigger master is invalid.   |
| -10626     | The trigger configuration for the trigger slave is invalid.  |
| -10627     | No signal has been assigned to the trigger resource.   |
| -10628     | A signal has already been assigned to the trigger resource.  |
| -10629     | The specified operating mode is invalid, or the resources have not been configured for the specified operating mode.   |
| -10630     | The parameters specified to read data were invalid in the context of the acquisition. For example, an attempt was made to read 0 bytes from the transfer buffer, or an attempt was made to read past the end of the transfer buffer. |
| -10631     | Continuous input or output transfers are not allowed in the current operating mode, or continuous operation is not allowed for this type of device.  |
| -10632     | Certain inputs were ignored because they are not relevant in the current operating mode.   |
| -10633     | The specified analog output regeneration mode is not allowed for this board.   |
| -10634     | No continuous (double buffered) transfer is in progress for the specified resource.  |

Table D-1. Data Acquisition Control Error Codes (Continued)

| Error Code | Description   |
|------------|---|
| -10635     | Either the SCXI operating mode specified in a configuration call is invalid, or a module is in the wrong operating mode to execute the function call. |
| -10636     | You cannot start a continuous (double-buffered) operation with a synchronous function call.   |
| -10637     | Attempted to configure a buffer after the buffer had already been configured. You can configure a buffer only once.                                   |
| -10680     | All channels of this board must have the same gain.   |
| -10681     | All channels of this board must have the same range.  |
| -10682     | All channels of this board must be the same polarity.   |
| -10683     | All channels of this board must have the same coupling.   |
| -10684     | All channels of this board must have the same input mode.   |
| -10685     | The clock rate exceeds the board's recommended maximum rate.  |
| -10686     | A configuration change has invalidated the scan list.   |
| -10687     | A configuration change has invalidated the acquisition buffer, or an acquisition buffer has not been configured.                                      |
| -10688     | The number of total scans and pretrigger scans implies that a triggered start is intended, but triggering is not enabled.                             |
| -10689     | Digital trigger B is illegal for the number of total scans and pretrigger scans specified.  |
| -10690     | This board does not allow digital triggers A and B to be enabled at the same time.  |
| -10691     | This board does not allow an external sample clock with an external scan clock, start trigger, or stop trigger.                                       |
| -10692     | The acquisition cannot be started because the channel clock is disabled.  |
| -10693     | You cannot use an external scan clock when doing a single scan of a single channel.   |
| -10694     | The sample frequency exceeds the safe maximum rate for the hardware, gains, and filters used.   |

 Table D-1.
 Data Acquisition Control Error Codes (Continued)

| Error Code | Description   |
|------------|---|
| -10695     | You have set up an operation that requires the use of interrupts. DMA is not allowed. For example, some DAQ events, such as messaging and LabVIEW occurrences, require interrupts.        |
| -10696     | Multi-rate scanning cannot be used with the AMUX-64, SCXI, or pretriggered acquisitions.  |
| -10697     | Unable to convert your timebase/interval pair to match the actual hardware capabilities of this board.  |
| -10698     | You cannot use this combination of scan and sample clock timebases for this board.  |
| -10699     | You cannot use this combination of scan and sample clock source polarities for this operation and board.  |
| -10700     | You cannot use this combination of scan and convert clock signal sources for this operation and board.  |
| -10701     | The call had no effect because the specified channel had not been set for later internal update.  |
| -10702     | Pretriggering and posttriggering cannot be used simultaneously on the Lab and 1200 series devices.  |
| -10710     | The specified port has not been configured for handshaking.   |
| -10720     | The specified counter is not configured for event-counting operation.   |
| -10740     | A signal has already been assigned to the SCXI track-and-hold trigger line, or a control call was inappropriate because the specified module is not configured for one-channel operation. |
| -10780     | When you have an SC2040 attached to your device, all analog input channels must be configured for differential input mode.  |
| -10781     | The polarity of the output channel cannot be bipolar when outputting currents.  |
| -10782     | The specified operation cannot be performed with the SC-2040 configured in hold mode.   |
| -10783     | Calibration constants in the load area have a different polarity from the current configuration. Therefore, you should load constants from factory.                                       |
| -10800     | The operation could not complete within the time limit.   |

 Table D-1. Data Acquisition Control Error Codes (Continued)

| Error Code | Description   |
|------------|---|
| -10801     | An error occurred during the calibration process. Possible reasons for this error include incorrect connection of the stimulus signal, incorrect value of the stimulus signal, or malfunction of your DAQ device.   |
| -10802     | The requested amount of data has not yet been acquired.   |
| -10803     | The ongoing transfer has been stopped. This is to prevent regeneration for output operations, or to reallocate resources for input operations.  |
| -10804     | The transfer stopped prior to reaching the end of the transfer buffer.  |
| -10805     | The clock rate is faster than the hardware can support. An attempt to input or output a new data point was made before the hardware could finish processing the previous data point. This condition may also occur when glitches are present on an external clock signal. |
| -10806     | No trigger value was found in the input transfer buffer.  |
| -10807     | The trigger occurred before sufficient pretrigger data was acquired.  |
| -10808     | An error occurred in the parallel port communication with the DAQ device.   |
| -10809     | Attempted to start a pulse width measurement with the pulse in the phase to be measured (e.g., high phase for high-level gating).   |
| -10810     | An unexpected error occurred inside the driver when performing this given operation.  |
| -10840     | The contents or the location of the driver file was changed between accesses to the driver.   |
| -10841     | The firmware does not support the specified operation, or the firmware operation could not complete due to a data integrity problem.  |
| -10842     | The hardware is not responding to the specified operation, or the response from the hardware is not consistent with the functionality of the hardware.  |
| -10843     | Because of system limitations, the driver could not write data to the device fast enough to keep up with the device throughput. This error may be returned erroneously when an overRunErr has occurred.   |
| -10844     | New data was not written to the output transfer buffer before the driver attempted to transfer the data to the device.  |

 Table D-1.
 Data Acquisition Control Error Codes (Continued)

| Error Code | Description  |
|------------|--|
| -10845     | Because of system limitations, the driver could not read data from the device fast enough to keep up with the device throughput; the onboard device memory reported an overflow error.   |
| -10846     | The driver wrote new data into the input transfer buffer before the previously acquired data was read.   |
| -10847     | New buffer information was not available at the time of the DMA chaining interrupt; DMA transfers will terminate at the end of the currently active transfer buffer.   |
| -10848     | The driver could not obtain a valid reading from the transfer-count register in the DMA controller.  |
| -10849     | The configuration file or DSP kernel file could not be opened.   |
| -10850     | Unable to close a file.  |
| -10851     | Unable to seek within a file.  |
| -10852     | Unable to read from a file.  |
| -10853     | Unable to write to a file.   |
| -10854     | An error occurred accessing a file.  |
| -10855     | NI-DAQ does not support the current operation on this particular version of the operating system.  |
| -10856     | An unexpected error occurred from the operating system while performing the given operation.   |
| -10857     | An unexpected error occurred inside the kernel of the device while performing this operation.  |
| -10858     | The system has reconfigured the device and has invalidated the existing configuration. The device requires reinitialization to be used again.  |
| -10880     | A change to the update rate is not possible at this time because 1) when waveform generation is in progress, you cannot change the interval timebase or 2) when you make several changes in a row, you must give each change enough time to take effect before requesting further changes. |
| -10881     | You cannot do another transfer after a successful partial transfer.  |

 Table D-1.
 Data Acquisition Control Error Codes (Continued)

| Error Code | Description  |
|------------|--|
| -10882     | The data collected on the Remote SCXI unit was overwritten before it could be transferred to the buffer in the host. Try using a slower data acquisition rate if possible.               |
| -10883     | New data could not be transferred to the waveform buffer of the Remote SCXI unit to keep up with the waveform update rate. Try using a slower waveform update rate if possible.          |
| -10884     | Could not rearrange data after a pretrigger acquisition completed.   |
| -10920     | One or more data points may have been lost during buffered GPCTR operations due to speed limitations of your system.   |
| -10940     | No response was received from the Remote SCXI unit within the specified time limit.  |
| -10941     | Reprogramming the Remote SCXI unit was unsuccessful. Please try again.   |
| -10942     | An invalid reset signature was sent from the host to the Remote SCXI unit.   |
| -10943     | The interrupt service routine on the remote SCXI unit is taking longer than necessary. You do not need to reset your remote SCXI unit, however, clear and restart your data acquisition. |

Table D-2 lists the error codes returned from the VISA control.

Table D-2. VISA Control Error Codes

| Error Code | Description  |
|------------|--|
| -30500     | Unknown system error (miscellaneous error).  |
| -30514     | The given session or object reference is invalid.  |
| -30515     | Specified type of lock cannot be obtained, or specified operation cannot be performed, because the resource is locked. |
| -30516     | Invalid expression specified for search.   |
| -30517     | Insufficient location information or the device or resource is not present in the system.                              |
| -30518     | Invalid resource reference specified. Parsing error.   |
| -30519     | Invalid access mode.   |

Table D-2. VISA Control Error Codes (Continued)

| Error Code | Description  |
|------------|--|
| -30521     | Timeout expired before operation completed.  |
| -30522     | Unable to deallocate the previously allocated data structures corresponding to this session or object reference. |
| -30527     | Specified degree is invalid.   |
| -30528     | Specified job identifier is invalid.   |
| -30529     | The specified attribute is not defined or supported by the referenced resource.                                  |
| -30530     | The specified state of the attribute is not valid, or is not supported as defined by the resource.               |
| -30531     | The specified attribute is read only.  |
| -30532     | The specified type of lock is not supported by this resource.  |
| -30533     | The access key to the specified resource is invalid.   |
| -30538     | Specified event type is not supported by the resource.   |
| -30539     | Invalid mechanism specified.   |
| -30540     | A handler was not installed.   |
| -30541     | The given handler reference is either invalid or was not installed.  |
| -30542     | Specified event context is invalid.  |
| -30548     | User abort occurred during transfer.   |
| -30552     | Violation of raw write protocol occurred during transfer.  |
| -30553     | Violation of raw read protocol occurred during transfer.   |
| -30554     | Device reported an output protocol error during transfer.  |
| -30555     | Device reported an input protocol error during transfer.   |
| -30556     | Bus error occurred during transfer.  |
| -30558     | Unable to start operation because setup is invalid (due to attributes being set to an inconsistent state).       |
| -30559     | Unable to queue the asynchronous operation.  |
| -30560     | Insufficient system resources to perform necessary memory allocation.  |

 Table D-2.
 VISA Control Error Codes (Continued)

| Error Code | Description  |
|------------|--|
| -30561     | Invalid buffer mask specified.   |
| -30562     | Could not perform operation because of I/O error.  |
| -30563     | A format specifier in the format string is invalid.  |
| -30565     | A format specifier in the format string is not supported.  |
| -30566     | The specified trigger line is currently in use.  |
| -30574     | Service request has not been received for the session.   |
| -30578     | Invalid address space specified.   |
| -30581     | Invalid offset specified.  |
| -30584     | Specified offset is not accessible from this hardware.   |
| -30587     | The specified session is not currently mapped.   |
| -30595     | No listeners condition is detected (both NRFD and NDAC are de-asserted).   |
| -30596     | The interface associated with this session is not currently the controller in charge.                                    |
| -30603     | The given session or object reference does not support this operation.   |
| -30606     | A parity error occurred during transfer.   |
| -30607     | A framing error occurred during transfer.  |
| -30608     | An overrun error occurred during transfer. A character was not read from the hardware before the next character arrived. |
| -30618     | Specified width is not supported by this hardware.   |
| -30620     | The value of some parameter (which parameter is not known) is invalid.   |
| -30621     | The protocol specified is invalid.   |
| -30623     | Invalid size of window specified.  |
| -30628     | The specified session currently contains a mapped window.  |
| -30629     | The given operation is not implemented.  |
| -30631     | Invalid length specified.  |
| -30656     | The current session did not have a lock on the resource.   |

Table D-2. VISA Control Error Codes (Continued)

| Error Code | Description   |
|------------|---|
| -30582     | Invalid access width specified.   |
| -30585     | Cannot support source and destination widths that are different.                    |
| -30612     | The specified offset is not properly aligned for the access width of the operation. |
| -30613     | A specified user buffer is not valid or cannot be accessed for the required size.   |
| -30614     | The resource is valid, but VISA cannot currently access it.                         |
| -30547     | You must be enabled for events of the specified type in order to receive them.      |
| -30658     | A code library required by VISA could not be located or loaded.                     |
| -30589     | A previous response is still pending, causing a multiple query error.               |
| -30597     | The interface associated with this session is not the system controller.            |
| -30645     | Invalid mode specified.   |

If an error occurs during a call to any of the functions in the ComponentWorks Analysis controls, the exception contains the error code. This code is a value that specifies the type of error that occurred. You can find the currently defined error codes and their associated meanings in Table D-3.

**Table D-3.** Analysis Error Codes

| Error Code | Description  |
|------------|--|
| -20001     | There is not enough memory to perform the specified routine.                         |
| -20002     | The input sequences must be the same size.   |
| -20003     | The number of samples must be >0.  |
| -20004     | The number of samples must be $\geq 0$ .   |
| -20006     | The number of samples must be $\geq 2$ .   |
| -20007     | The number of samples must be $\geq 3$ .   |
| -20008     | The input arrays do not contain the correct number of data values for this function. |
| -20009     | The size of the input array must be a power of two: $size = 2^m, 0 \le m \le 23$ .   |

 Table D-3.
 Analysis Error Codes (Continued)

| Error Code | Description  |  |  |
|------------|--|--|--|
| -20010     | The maximum allowable transform size has been exceeded.                                    |  |  |
| -20011     | The duty cycle must be equal to or fall between 0 and 100: $0 \le duty \ cycle \le 100$ .  |  |  |
| -20012     | The number of cycles must be > 0 and <= the number of samples.                             |  |  |
| -20013     | The width must meet: 0 < width < samples.  |  |  |
| -20014     | The following conditions must be met: $0 \le (delay + width) \le samples$ .                |  |  |
| -20015     | dt must be $\geq 0$ .  |  |  |
| -20016     | dt must be > 0.  |  |  |
| -20017     | The following condition must be met: $0 \le index \le samples$ .                           |  |  |
| -20018     | The following condition must be met: $0 \le (index + length) \le samples$ .                |  |  |
| -20019     | The upper value must be >= the lower value.  |  |  |
| -20020     | The cut-off frequency, $fc$ , must meet: $0 \le fc \le fs/2$ .                             |  |  |
| -20021     | The order must be > 0.   |  |  |
| -20022     | The decimating factor must meet: 0 < decimating factor <= samples.                         |  |  |
| -20023     | The following conditions must be met: $0 < f\_low \le f\_high \le fs/2$ .                  |  |  |
| -20024     | The ripple amplitude must be > 0.  |  |  |
| -20025     | The attenuation must be > 0.   |  |  |
| -20026     | The width must be > 0.   |  |  |
| -20027     | The final value must be > 0.   |  |  |
| -20028     | The attenuation value must be greater than the ripple amplitude.                           |  |  |
| -20029     | The step-size, u, must meet: $0 \le u \le 0.1$ .   |  |  |
| -20030     | The leakage coefficient, leak, and step-size parameter, u, must meet: $0 \le leak \le u$ . |  |  |
| -20031     | The filter cannot be designed with the specified input values.                             |  |  |
| -20032     | The rank of the filter must meet: $1 \le (2*rank + 1) \le size$ .                          |  |  |
| -20033     | The number of coefficients must be odd for this filter.                                    |  |  |

Table D-3. Analysis Error Codes (Continued)

| Error Code | Description  |  |  |
|------------|--|--|--|
| -20034     | The number of coefficients must be even for this filter.   |  |  |
| -20035     | The standard deviation must be greater than zero for normalization.  |  |  |
| -20036     | The elements of the Y Values array must be nonzero and either all positive or all negative.                  |  |  |
| -20037     | The number of data points in the Y Values array must be greater than the order.                              |  |  |
| -20038     | The number of intervals must be > 0.   |  |  |
| -20039     | The number of columns in the first matrix is not equal to the number of rows in the second matrix or vector. |  |  |
| -20040     | The input matrix must be a square matrix.  |  |  |
| -20041     | The system of equations cannot be solved because the input matrix is singular.                               |  |  |
| -20042     | The number of levels is out of range.  |  |  |
| -20043     | The level of factors is outside the allowable range of some data.  |  |  |
| -20044     | Zero observations were made at some level of a factor.   |  |  |
| -20045     | The total number of data points must be equal to the product of levels/each factor * observations/cell.      |  |  |
| -20046     | There is an overflow in the calculated F-value for the ANOVA Fit function.                                   |  |  |
| -20047     | The data is unbalanced. All cells must contain the same number of observations.                              |  |  |
| -20048     | The Random Effect model was requested when the Fixed Effect model is required.                               |  |  |
| -20049     | The x-values must be distinct.   |  |  |
| -20050     | The interpolating function has a pole at the requested value.  |  |  |
| -20051     | All values in the first column of X matrix must be one.  |  |  |
| -20052     | The degrees of freedom must be one or more.  |  |  |
| -20053     | The probability must be between zero and one.  |  |  |
| -20054     | The probability must be greater than or equal to zero and less than one.                                     |  |  |

 Table D-3.
 Analysis Error Codes (Continued)

| Error Code | Description   |  |
|------------|---|--|
| -20055     | The number of categories or samples must be greater than one.             |  |
| -20056     | The contingency table has a negative number.                              |  |
| -20057     | The parameter to the beta function should be $0 \le p \le 1$ .            |  |
| -20058     | Invalid number of dimensions or dependent variables.                      |  |
| -20059     | Negative number error.  |  |
| -20060     | Divide by zero error.   |  |
| -20061     | The selection is invalid.   |  |
| -20062     | The maximum number of iterations was exceeded.                            |  |
| -20063     | The coefficients of the polynomial are invalid.                           |  |
| -20064     | The internal memory state of this function was not initialized correctly. |  |
| -20065     | The elements in the vector can not be all zero.                           |  |
| -20066     | The information in IIR filter structure is not correct.                   |  |
| -20080     | Time increment must be greater than the (window length)/16.               |  |
| -20081     | dN must be greater than zero.   |  |
| -20082     | Time increment must not be greater than dM.                               |  |
| -20083     | Window length must be > 4 and a power of 2.                               |  |
| -20084     | Time increment must not be greater than (window length)/4.                |  |
| -20085     | The size of the input array and its Hilbert transform must be equal.      |  |
| -20086     | Window length must be > 2 and a power of 2.                               |  |
| -20101     | Parameter must meet the condition: <i>Top&gt;Base</i> .                   |  |
| -20102     | The shifts must meet:  shifts  < samples.                                 |  |
| -20103     | The order must be positive.   |  |
| -20999     | Serious algorithm failure. Call National Instruments support.             |  |

Table D-4 lists the negative error codes that can be returned by any ComponentWorks operation.

 Table D-4.
 General ComponentWorks Error Codes

| Error Code | Description  |
|------------|--|
| -30000     | An unexpected error has occurred.  |
| -30001     | Too many controls are configured for this DAQ device. Reset one of the other controls configured for this device before configuring any more controls for this device.   |
| -30002     | You have passed an invalid value for one of the parameters to the function, method or property.  |
| -30003     | You have passed an invalid type into a parameter of a VARIANT type.  |
| -30004     | A divide by zero error has occurred.   |
| -30005     | The result of a calculation is an imaginary number.  |
| -30006     | An overflow error has occurred.  |
| -30007     | Out of memory.   |
| -30008     | You have called a function or method requiring a ComponentWorks product that you do not have a license for. For example, you may be using a method that is not supported in the base, (or standard) Analysis package. To upgrade your product, contact National Instruments. |
| -30009     | Cannot reconfigure when PulseType has changed.   |
| -30010     | DAQ operation cannot be started because it is not configured or is currently active.   |
| -30011     | The type of counter/timer on the device cannot perform the requested operation.  |
| -30013     | Newer version of NI-DAQ required.  |
| -30014     | Invalid ReturnDataType property. Scaled data will be returned.   |
| -30015     | CWAI.ProgressInterval must divide evenly into CWAI.NScans.   |
| -30016     | CWAI.NScans must divide evenly into CWAI.NScansPerBuffer.  |
| -30017     | ProgressInterval must divide evenly into NPatterns.  |
| -30018     | Invalid trigger source.  |
| -30019     | Current PulseType cannot be reconfigured.  |

 Table D-4.
 General ComponentWorks Error Codes (Continued)

| Error Code | Description   |
|------------|---|
| -30020     | DAQ operation not active.                                 |
| -30021     | DAQ operation not configured.                             |
| -30100     | The data type is not correct.                             |
| -30101     | Array cannot be locked.                                   |
| -30102     | Array cannot be unlocked.                                 |
| -30103     | The argument is not an array.                             |
| -30104     | The input parameters must all contain the same data type. |
| -30301     | Operation Timed out.                                      |
| -30302     | No more data.   |
| -30303     | Could not parse character.                                |
| -30304     | IO Operation in Progress.                                 |
| -30305     | Cannot Add Token to non User-Defined Pattern.             |
| -30307     | Cannot load GPIB DLL.                                     |
| -30308     | Cannot load VISA DLL.                                     |
| -30312     | Invalid COM Port.   |
| -30315     | Access denied: Specified resource is already in use.      |
| -30316     | Specified Device is Not Configured.                       |
| -30317     | Specified Device is Not Opened.                           |
| -30322     | File Not Found.   |
| -30324     | Cannot open file: Too Many Open Files.                    |
| -30325     | Cannot Open File: Access Denied.                          |
| -30330     | Invalid GPIB Board Number.                                |
| -30331     | The GPIB Board is not the Controller In Charge (CIC).     |
| -30332     | No Listeners on the GPIB are addressed.                   |
| -30333     | GPIB Board is not properly addressing itself.             |
| -30334     | Invalid Parameter.  |

 Table D-4.
 General ComponentWorks Error Codes (Continued)

| Error Code | Description  |
|------------|--|
| -30335     | The GPIB Board is not the System Controller.                                       |
| -30336     | I/O operation timed out.   |
| -30337     | Invalid GPIB IO Address.   |
| -30338     | GPIB DMA Error.  |
| -30340     | I/O In Progress.   |
| -30341     | GPIB Board or device does not have the ability to perform the requested operation. |
| -30342     | File System Error.   |
| -30344     | Error on the GPIB Bus.   |
| -30345     | Serial Poll Overflow: Too many status bytes received.                              |
| -30346     | The SRQ line is stuck asserting.   |
| -30350     | Problem with GPIB Listening Table.   |
| -30400     | The value or attribute cannot be set because the CWData object is read only.       |
| -30401     | The data read is corrupt or in an unrecognized format.                             |
| -30402     | You are initializing too many cluster elements.                                    |
| -30403     | You are trying to create an array with too many dimensions.                        |
| -30404     | You are using an element index that is out of range.                               |
| -30405     | You cannot index the current value because it is not a vector or cluster.          |
| -30420     | The URL prefix (http:, ftp:, file:, and so on) is not recognized.                  |
| -30421     | The URL syntax could not be recognized.  |



# Distribution and Redistributable Files

This chapter contains information about ComponentWorks 2.0 redistributable files and distributing applications that use ComponentWorks controls.

## **Files**

The files in the \Setup\redist directory of the ComponentWorks CD are necessary for distributing applications and programs that use ComponentWorks controls. You need to distribute only those files needed by the controls you are using in your application.

# Distribution

When installing an application using ComponentWorks controls on another computer, you also must install the necessary control files and supporting libraries on the target machine. In addition to installing all necessary OCX files on a target computer, you must register each of these files with the operating system. This allows your application to find the correct OCX file and create the controls.

If your application performs any I/O operations requiring separate driver software, such as data acquisition or GPIB, you must install and configure the driver software and corresponding hardware on the target computer. For more information, consult the hardware documentation for the specific driver used.

When distributing applications with the ComponentWorks controls, do not violate the license agreement (section 5) provided with the software. If you have any questions about the licensing conditions, contact National Instruments.

#### **Automatic Installers**

Many programming environments include some form of a setup or distribution kit tool. This tool automatically creates an installer for your application so that you can easily install it on another computer. To function successfully, this tool must recognize which control files and supporting libraries are required by your application and include these in the installer it creates. The resulting installer also must register the controls on the target machine.

Some of these tools, such as the Visual Basic 5 Setup Wizard, use dependency files to determine which libraries are required by an OCX file. Each of the ComponentWorks OCX files includes a corresponding dependency file located in the \Windows\System directory (\Windows\System32 for Windows\T) after you install the ComponentWorks software.

Some setup tools might not automatically recognize which files are required by an application but provide an option to add additional files to the installer. In this case, verify that all necessary OCX files (corresponding to the controls used in your application) as well as all the DLL and TLB files from the \redist directory are included. You also should verify that the resulting installer does not copy older versions of a file over a newer version on the target machine.

If your programming environment does not provide a tool or wizard for building an installer, you may use third-party tools, such as InstallShield. Some programming environments provide simplified or trial versions of third-party installer creation tools on their installation CDs.

#### **Manual Installation**

If your programming environment does not include a setup or distribution kit tool, you must build your own installer and perform the installation task manually. To install your application on another computer, follow these steps:

- 1. Copy the application executable to the target machine.
- Copy all required ComponentWorks OCX files (corresponding to the controls used in your application) to the System directory (\Windows\System for Windows 95 or \Windows\System32 for WindowsNT) on the target machine.

- 3. Copy all DLL and TLB files in the \redist directory to the System directory on the target machine.
- 4. Copy any other DLLs and support files required by your application to the System directory on the target machine.

Some of these files might already be installed on the target machine. If the file on the target machine has an earlier version number than the file in the \redist directory, copy the newer file to the target machine.

After copying the files to the target machine, you must register all OCX files with the operating system. To register an OCX file, you need a utility such as REGSVR32.EXE. You must copy this utility to the target machine to register the OCX files, but you can delete it after completing the installation. Use this utility to register each OCX file with the operating system, as in the following example.

regsvr32 c:\windows\system\cwui.ocx

## **DataSocket Server**

If your application uses the DataSocket Server, you also might need to distribute the server with your application. The server executable can be easily copied to the target machine and does not need to be registered. It requires the same support libraries as the ComponentWorks controls. With the DataSocket server, you also should distribute the server configuration file (CWDSSINI.DSS) to start the server on the target in the same state as configured on your development machine. You can distribute multiple configuration files to switch between different setups of the server.

In rare cases, you might want to distribute the DataSocket Server Manager utility with your application. In general, this should not be necessary. Contact National Instruments technical support for information about distributing the DataSocket Server Manager.

# **Instrument Drivers**

If you are using any instrument drivers in your applications, you must distribute the instrument driver DLL file with your application. Copy the instrument driver DLL and necessary support DLL (INSTRSUP.DLL) to the target machine. Make sure to install and configure any required driver software, such as NI-488.2, on the target machine.

# **ComponentWorks Evaluation**

Once the ComponentWorks OCX files are installed and registered on a target computer, your application can create the controls as necessary. You or your customer also can use the same OCX files in any compatible development environment as an evaluation version of the controls. If desired, you may distribute the ComponentWorks reference files (from the \redist directory) with your application, which provide complete documentation of the ComponentWorks controls when used in evaluation mode.

If you would like to use the ComponentWorks controls as a development tool on this target machine, you must purchase another ComponentWorks development system. Contact National Instruments to purchase additional copies of the ComponentWorks software.

## **Run-Time Licenses**

For each copy of your ComponentWorks-based application that you distribute, you must have a valid run-time license. A limited number of run-time licenses are provided with the ComponentWorks development systems. National Instruments driver software also provides you with ComponentWorks run-time licenses. You can purchase additional ComponentWorks run-time licenses from National Instruments. Consult the license agreement (section 5) provided with the software for more detailed information. If you have any questions about the licensing conditions, contact National Instruments.

# **Troubleshooting**

Try the following suggestions if you encounter problems after installing your application on another computer.

# The application is not able to find an OCX file or is not able to create a control.

- The control file or one of its supporting libraries is not copied on the computer. Verify that the correct OCX files and all their supporting libraries are copied on the machine. If one control was built using another, you might need multiple OCX files for one control.
- The control is not properly registered on the computer. Make sure you run the registration utility and that it registers the control.

#### Controls in the application run in evaluation (demo) mode.

The application does not contain the correct run-time license. When
developing your application, verify that the controls are running in a
fully licensed mode. Although most programming environments
include a run-time license for the controls in the executable, some
do not.

If you are developing an application in Visual C++ using SDI (single document interface) or MDI (multiple document interface), you must include the run-time license in the program code for each control you create. Consult the ComponentWorks documentation, National Instruments Knowledgebase (www.natinst.com/support) or technical support if you are not familiar with this operation.



# **Customer Communication**

For your convenience, this appendix contains forms to help you gather the information necessary to help us solve your technical problems and a form you can use to comment on the product documentation. When you contact us, we need the information on the Technical Support Form and the configuration form, if your manual contains one, about your system configuration to answer your questions as quickly as possible.

National Instruments has technical assistance through electronic, fax, and telephone systems to quickly provide the information you need. Our electronic services include a bulletin board service, an FTP site, a fax-on-demand system, and e-mail support. If you have a hardware or software problem, first try the electronic support systems. If the information available on these systems does not answer your questions, we offer fax and telephone support through our technical support centers, which are staffed by applications engineers.

#### **Electronic Services**

#### **Bulletin Board Support**

National Instruments has BBS and FTP sites dedicated for 24-hour support with a collection of files and documents to answer most common customer questions. From these sites, you can also download the latest instrument drivers, updates, and example programs. For recorded instructions on how to use the bulletin board and FTP services and for BBS automated information, call 512 795 6990. You can access these services at:

United States: 512 794 5422

Up to 14,400 baud, 8 data bits, 1 stop bit, no parity

United Kingdom: 01635 551422

Up to 9,600 baud, 8 data bits, 1 stop bit, no parity

France: 01 48 65 15 59

Up to 9,600 baud, 8 data bits, 1 stop bit, no parity

#### **FTP Support**

To access our FTP site, log on to our Internet host, ftp.natinst.com, as anonymous and use your Internet address, such as joesmith@anywhere.com, as your password. The support files and documents are located in the /support directories.

#### **Fax-on-Demand Support**

Fax-on-Demand is a 24-hour information retrieval system containing a library of documents on a wide range of technical information. You can access Fax-on-Demand from a touch-tone telephone at 512 418 1111.

#### E-Mail Support (Currently USA Only)

You can submit technical support questions to the applications engineering team through e-mail at the Internet address listed below. Remember to include your name, address, and phone number so we can contact you with solutions and suggestions.

support@natinst.com

### **Telephone and Fax Support**

National Instruments has branch offices all over the world. Use the list below to find the technical support number for your country. If there is no National Instruments office in your country, contact the source from which you purchased your software to obtain support.

| Country          | Telephone       | Fax              |
|------------------|-----------------|------------------|
| Australia        | 03 9879 5166    | 03 9879 6277     |
| Austria          | 0662 45 79 90 0 | 0662 45 79 90 19 |
| Belgium          | 02 757 00 20    | 02 757 03 11     |
| Brazil           | 011 288 3336    | 011 288 8528     |
| Canada (Ontario) | 905 785 0085    | 905 785 0086     |
| Canada (Quebec)  | 514 694 8521    | 514 694 4399     |
| Denmark          | 45 76 26 00     | 45 76 26 02      |
| Finland          | 09 725 725 11   | 09 725 725 55    |
| France           | 01 48 14 24 24  | 01 48 14 24 14   |
| Germany          | 089 741 31 30   | 089 714 60 35    |
| Hong Kong        | 2645 3186       | 2686 8505        |
| Israel           | 03 6120092      | 03 6120095       |
| Italy            | 02 413091       | 02 41309215      |
| Japan            | 03 5472 2970    | 03 5472 2977     |
| Korea            | 02 596 7456     | 02 596 7455      |
| Mexico           | 5 520 2635      | 5 520 3282       |
| Netherlands      | 0348 433466     | 0348 430673      |
| Norway           | 32 84 84 00     | 32 84 86 00      |
| Singapore        | 2265886         | 2265887          |
| Spain            | 91 640 0085     | 91 640 0533      |
| Sweden           | 08 730 49 70    | 08 730 43 70     |
| Switzerland      | 056 200 51 51   | 056 200 51 55    |
| Taiwan           | 02 377 1200     | 02 737 4644      |
| United Kingdom   | 01635 523545    | 01635 523154     |
| United States    | 512 795 8248    | 512 794 5678     |

# **Technical Support Form**

Photocopy this form and update it each time you make changes to your software or hardware, and use the completed copy of this form as a reference for your current configuration. Completing this form accurately before contacting National Instruments for technical support helps our applications engineers answer your questions more efficiently.

If you are using any National Instruments hardware or software products related to this problem, include the configuration forms from their user manuals. Include additional pages if necessary. Company Fax ( \_\_\_ ) \_\_\_\_\_Phone ( \_\_\_ ) \_\_\_\_\_ Computer brand Model Processor Operating system (include version number) Clock speed \_\_\_\_\_MHz RAM \_\_\_\_MB Display adapter \_\_\_\_\_ Mouse \_\_\_yes \_\_\_no Other adapters installed\_\_\_\_\_\_ Hard disk capacity \_\_\_\_\_MB Brand\_\_\_\_\_ Instruments used \_\_\_\_\_ National Instruments hardware product model \_\_\_\_\_\_ Revision \_\_\_\_\_ Configuration \_\_\_\_\_ National Instruments software product \_\_\_\_\_\_ Version \_\_\_\_\_ Configuration \_\_\_\_\_ The problem is: List any error messages: The following steps reproduce the problem:

# ComponentWorks Hardware and Software Configuration Form

Record the settings and revisions of your hardware and software on the line to the right of each item. Complete a new copy of this form each time you revise your software or hardware configuration, and use this form as a reference for your current configuration. Completing this form accurately before contacting National Instruments for technical support helps our applications engineers answer your questions more efficiently.

# **National Instruments Products**

| DAQ hardware                      |
|-----------------------------------|
| Interrupt level of hardware       |
| DMA channels of hardware          |
| Base I/O address of hardware      |
| Programming choice                |
| ComponentWorks and NI-DAQ version |
| Other boards in system            |
| Base I/O address of other boards  |
| DMA channels of other boards      |
| Interrupt level of other boards   |
| Other Products                    |
| Computer make and model           |
| Microprocessor                    |
| Clock frequency or speed          |
| Type of video board installed     |
| Operating system version          |
| Operating system mode             |
| Programming language              |
| Programming language version      |
| Other boards in system            |
| Base I/O address of other boards  |
| DMA channels of other boards      |
| Interrupt level of other boards   |
|                                   |

# **Documentation Comment Form**

Austin, Texas 78730-5039

Getting Results with ComponentWorks™

Title:

National Instruments encourages you to comment on the documentation supplied with our products. This information helps us provide quality products to meet your needs.

**Edition Date: April** 1998 Part Number: 321170C-01 Please comment on the completeness, clarity, and organization of the manual. If you find errors in the manual, please record the page numbers and describe the errors. Thank you for your help. Name \_\_\_\_\_ Title \_\_\_\_\_ Company \_\_\_\_\_ Address E-Mail Address Phone ( \_\_\_ ) \_\_\_\_\_ Fax ( \_\_\_ ) \_\_\_\_ **Mail to:** Technical Publications Fax to: **Technical Publications** National Instruments Corporation National Instruments Corporation 512 794 5678 6504 Bridge Point Parkway

# **Glossary**

| Prefix | Meanings | Value |
|--------|----------|-------|
| p-     | pico     | 10-12 |
| n-     | nano-    | 10-9  |
| μ-     | micro-   | 10-6  |
| m-     | milli-   | 10-3  |
| k-     | kilo-    | 103   |
| M-     | mega-    | 106   |
| G-     | giga-    | 109   |
| t-     | tera-    | 1012  |

# Numbers/Symbols

12-bit Resolution of a data acquisition device. A 12-bit device converts an analog

voltage into a 12-bit binary integer. The binary value is scaled to a voltage

representation in software.

16-bit Resolution of a data acquisition device. A 16-bit device converts an analog

voltage into a 16-bit binary integer. The binary value is scaled to a voltage

representation in software.

1D One-dimensional.

2D Two-dimensional.

9513 Counter See AM9513 Counter.

A

A Amperes.

A/D Analog-to-Digital.

AC Alternating Current.

AC signal Signal with significant frequency components.

ActiveX Set of Microsoft technologies for reusable software components. Formerly

called *OLE*.

ActiveX control Standard software tool that adds additional functionality to any compatible

ActiveX container. The DAQ, UI, and analysis tools in ComponentWorks are all ActiveX controls. An ActiveX control has properties, methods,

objects, and events.

ADC Analog-to-Digital Converter. An electronic device, often an integrated

circuit, that converts an analog voltage to a digital number.

ADC resolution Resolution of the ADC, which is measured in bits. An ADC with 16 bits

has a higher resolution than a 12-bit ADC.

AI Analog Input.

AIGND Analog Input GrouND pin on a DAQ device.

AIPoint Analog Input Single Point control.

AM 9513 Counter Counter/Timer chip used on legacy MIO and other data acquisition devices,

replaced by the DAQ-STC chip on newer devices, including the E-series DAQ boards. The AM9513 Counter does not support some of the advanced

features of the DAO-STC.

amplification Type of signal conditioning that improves accuracy in the resulting

digitized signal and reduces noise.

AMUX devices See analog multiplexer.

analog multiplexer Device that increase the number of measurement channels while still using

a single instrumentation amplifier. Also called AMUX devices.

analog trigger Trigger that occurs at a user-selected point on an incoming analog signal.

Triggering can be set to occur at a specified level either on an increasing or a decreasing signal (positive or negative slope). Analog triggering can be implemented either in software or in hardware. When implemented in software, all data is collected, transferred into system memory, and analyzed for the trigger condition. When analog triggering is implemented in hardware, no data is transferred to system memory until the trigger

condition has occurred.

ANOVA ANalysis Of VAriance.

AO Analog Output.

AOPoint Analog Output single Point control.

array Ordered, indexed set of data elements of the same type.

asynchronous Property of a function or operation that begins an operation and returns

control to the program prior to the completion or termination of the

operation.

ATC Analog Trigger Circuit; an analog trigger contained on some E-series DAQ

devices, required for any analog triggering (including ETS operations).

В

BCD Binary-Coded Decimal.

bipolar Signal range that includes both positive and negative values

(for example, -5 to 5 V).

buffer Temporary storage for acquired or generated data.

C

callback (function) User-defined function called in response to an event from an object. Also

called an event handler.

cascading Process of extending the counting range of a counter chip by connecting to

the next higher counter.

channel Pin or wire lead to which you apply or from which you read the analog or

digital signal. Analog signals can be single-ended or differential. For digital signals, group channels to form ports. Ports usually consist of either four or

eight digital channels.

channel clock Clock controlling the time interval between individual channel sampling

within a scan. Boards with simultaneous sampling do not have this clock.

channel list Collection of channel objects that specify the channels used by a control.

Channel Wizard Utility that guides you through naming and configuring your DAQ analog

and digital channels.

Chart History CWGraph property for charting that determines how many points the graph

stores before deleting old data.

Chart Style CWGraph property that specifies how a chart method updates the display

as new data is plotted.

clock Hardware component that controls timing for reading from or writing to

groups; an input pin on a counter/timer.

cm Centimeters.

code width Smallest detectable change in an input voltage of a DAQ device.

Collection Control property and object that contains a number of objects of the same

type, such as pointers, axes, and plots. The type name of the collection is the plural of the type name of the object in the collection. For example, a collection of CWAxis objects is called CWAxes. To reference an object in the collection, you must specify the object as part of the collection, usually by index. For example, CWGraph. Axes. Item (2) is the second axis in the

CWAxes collection of a graph.

column-major order Systematic way to organize the data in a 2D array by columns.

common-mode voltage Any voltage present at the instrumentation amplifier inputs with respect to

amplifier ground.

condition object Object used to specify the Start, Pause, or Stop condition on a data

acquisition process.

Control Refresh CWGraph property that determines when changes to the graph are

displayed. The property name is ImmediateUpdates.

conversion device Device that transforms a signal from one form to another. For example,

analog-to-digital converters (ADCs) for analog input, digital-to-analog converters (DACs) for analog output, digital input or output ports, and

counter/timers are conversion devices.

counter/timer group Collection of counter/timer channels. You can use this type of group for

simultaneous operation of multiple counter/timers.

coupling Manner in which a signal is connected from one location to another.

D

D/A Digital-to-Analog.

DAC Digital-to-Analog Converter. An electronic device, often an integrated

circuit, that converts a digital number into a corresponding analog voltage

or current.

DAQ Data acquisition.

DAQ-STC DAQ System Timing Controller. An ASIC developed by National

Instruments for enhanced timing control on data acquisition devices. DAQ-STC is used on E-Series and other National Instruments DAQ devices and is required for certain counter/timer operations, including buffered

counter measurements and frequency shift keying.

data acquisition Process of acquiring data, typically from A/D or digital input plug-in

boards.

DataSocket Technology that simplifies data exchange between an application and other

applications, files, FTP servers, and Web servers. It provides one common

API to a number of different communication protocols.

DataSocket control ActiveX control that implements the DataSocket client functionality.

Enables applications to exchange data with other data sources and targets.

DataSocket Server Executable that enables data exchange between multiple applications,

each of which uses a DataSocket client. The server accepts and stores

information from data sources and relays it to other data targets.

DataSocket Server

Manager

Executable to configure the default settings of the DataSocket Server, including access permission, number of connections, and predefined data

items stored in the server.

DC Direct Current.

DC signal Signal solely comprised of a non-dynamic component, steady or very

slowly changing voltage.

Delphi Borland Delphi programming environment.

device Plug-in data acquisition board that can contain multiple channels and

conversion devices.

device number Slot number or board ID number assigned to the board when configured.

DFT Discrete Fourier Transform.

DI Digital Input.

DIFF Differential. A differential input is an analog input consisting of two

terminals, both of which are isolated from computer ground and whose

difference you measure.

differential measurement Method to configure your device to read signals so you do not need to

connect either input to a fixed reference, such as the earth or a building

ground.

digital trigger TTL level signal having two discrete levels—a high and a low level used to

trigger (start or stop) another process.

DIO Digital Input/Output.

dithering Addition of Gaussian noise to an analog input signal.

DLL Dynamic Link Library.

DMA Direct Memory Access. A method by which you can transfer data to

computer memory from a device or memory on the bus (or from computer memory to a device) while the processor does something else. DMA is the

fastest method of transferring data to or from computer memory.

DO Digital Output.

down counter Performing frequency division on an internal signal.

driver Software that controls a specific hardware device, such as a data acquisition

board.

DSP Digital Signal Processing.

DSTP DataSocket Transfer Protocol. Protocol based on TCP/IP to exchange data

directly between two applications using DataSocket clients. Data is passed

through a DataSocket Server between the applications.

Ε

E-Series Device Series of enhanced data acquisition devices that include technologies such

as DAQ-STC ASIC, Plug and Play compatibility, and the NI-PGIA. Some functionality in the ComponentWorks DAQ controls can be used only by

E-Series devices.

EEPROM Electrically Erased Programmable Read-only Memory. Read-only memory

that you can erase with an electrical signal and reprogram.

EISA Extended Industry Standard Architecture.

Equivalent Time Analog input data acquisition method in which points are acquired with

Sampling (ETS) increasing delay from a fixed point on a repetitive waveform.

event Object-generated response to some action or change in state, such as a

mouse click or x number of points being acquired. The event calls an event handler (callback function), which processes the event. Events are defined

as part of an OLE control object.

event handler See callback (function) and event.

exception Error message generated by a control and sent directly to the application or

programming environment containing the control.

external trigger Voltage pulse from an external source that triggers an event such as A/D

conversion.

F

FFT Fast Fourier Transform. A method used to compute the Fourier transform

of an image.

FHT Fast Hartley Transform.

FIFO First-In, First-Out memory buffer. In a FIFO structure, the first data stored

is the first data sent to the acceptor.

File I/O Saving and loading data to and from files in an application.

filtering Type of signal conditioning that allows you to filter unwanted signals from

the signal you are trying to measure.

FIR Finite Impulse Response.

fires Occurs. An event fires in response to predefined conditions, such as the

completion of a specified interval of time with a timer control, the acquisition of a specified number of data points with a CWAI control, or a

mouse-click on a CWButton.

floating signal sources Signal sources with voltage signals that are not connected to an absolute

reference or system ground. Also called nonreferenced signal sources.

Common example of floating signal sources include batteries,

transformers, and thermocouples.

form Window or area on the screen on which you place controls and indicators

to create the user interface for your program.

Format Flexible specification that defines how a number is displayed on an axis or

on some other display. The specification is a format string for formatting all values on a specific display. You specify the format string in the property

sheet of a control.

FSR Frequency Shift Keying. An advanced pulse generation mode in which the

output frequency is switched by another digital signal.

FTP File Transfer Protocol. Protocol based on TCP/IP to exchange files between

computers.

FTP Server Application running on a computer that enables the storing and retrieving

of files by different clients via FTP. Most FTP servers allow anonymous

connections so that any networked user can exchange files.

function tree Hierarchical structure in which the functions in a library or an instrument

driver are grouped. The function tree simplifies access to a library or instrument driver by presenting functions organized according to the operation they perform, as opposed to a single linear listing of all available

functions.

G

gain Factor by which a signal is amplified, sometimes expressed in decibels.

GATE input pin Counter input pin that controls when counting in your application occurs.

GPIB General Purpose Interface bus. The standard bus used for controlling

electronic instruments with a computer. Also called IEEE 488 bus because

it is defined by ANSI/IEEE Standards 488-1978, 488.1-1987, and

488.2-1987.

grounded measurement

system

See referenced single-ended measurement system.

grounded signal sources Signal sources with voltage signals that are referenced to a system ground,

such as the earth or a building ground. Also called *referenced signal* 

sources.

GUI Graphical User Interface.

Н

handshaked digital I/O Type of digital acquisition/generation where a device or module accepts or

transfers data after a digital pulse has been received. Also called *latched* 

digital I/O.

hardware triggering Form of triggering where you set the start time of an acquisition and gather

data at a known position in time relative to a trigger signal.

hex Hexadecimal.

HTML HyperText Markup Language. Language (syntax) used to build Web pages.

HTML files are downloaded from an HTTP server and viewed in a Web

browser.

HTTP HyperText Transfer Protocol. Protocol based on TCP/IP, which is used to

download Web pages from an HTTP server to a Web browser.

HTTP Server Application running on a computer that serves Web pages and other

information to client computers using HTTP. Clients display Web pages in

Web browsers but can retrieve information using other tools, like a

DataSocket client.

Hz Hertz. The number of scans read or updates written per second.

I

I/O Input/Output. The transfer of data to or from a computer system involving

communications channels, operator interface devices, and/or data

acquisition and control interfaces.

I/O Connector Connector on a data acquisition device used to connect the device to

external signals or devices.

ICtr(82C53) Simple counter/timer chip used on 1200-, 700-, 500-, Lab-, and

LPM- series data acquisition devices. ICtr(82C53) supports limited counter pulse capabilities and can be controlled using the ICtr functions in the

ComponentWorks DAQTools control.

IDFT Inverse Discrete Fourier Transform.

IEEE Institute of Electrical and Electronic Engineers.

IEEE 488 Shortened notation for ANSI/IEEE Standards 488-1978, 488.1-1987, and

488.2-1987. See also *GPIB*.

IFFT Inverse Fast Fourier Transform.

IFHT Inverse Fast Hartley Transform.

IIR Infinite Impulse Response.

immediate digital I/O Type of digital acquisition/generation where LabVIEW updates the digital

lines or port states immediately or returns the digital value of an input line.

Also called nonlatched digital I/O.

in. Inches.

input limits The upper and lower voltage inputs for a channel. You must use a pair of

numbers to express the input limits.

instrument driver Library of functions to control and use one specific physical instrument.

Also a set of functions that adds specific functionality to an application.

interrupt Signal indicating that the central processing unit should suspend its current

task to service a designated activity.

interval clock Clock used in a DAQ device in an analog input operation to control the

delay between samples acquired from consecutive channels in a scan.

interval delay Delay between samples acquired from consecutive channels in a scan

during an analog input operation.

interval scanning Scanning method where there is a longer interval between scans than there

is between individual channels comprising a scan.

ISA Industry Standard Architecture.

isolation Type of signal conditioning in which you isolate the transducer signals

from the computer for safety purposes. This protects you and your computer from large voltage spikes and makes sure the measurements from

the DAQ device are not affected by differences in ground potentials.

K

ksamples 1,000 samples.

Kwords 1,024 words of memory.

L

latched digital I/O Type of digital acquisition/generation where a device or module accepts or

transfers data after a digital pulse has been received. Also called

handshaked digital I/O.

LED Light-Emitting Diode.

limit settings Maximum and minimum voltages of the analog signals you are measuring

or generating.

linearization Type of signal conditioning that linearizes the voltage levels from

transducers, so the voltages can be scaled to measure physical phenomena.

LSB Least Significant Bit.

M

MB Megabytes of memory.

memory buffer See buffer.

method Function that performs a specific action on or with an object. The operation

of the method often depends on the values of the object properties.

mse Mean squared error.

multibuffered I/O Input operation for which you allocate more than one memory buffer so you

can read and process data from one buffer while the acquisition fills

another.

multiplexed mode SCXI operating mode in which analog input channels are multiplexed into

one module output so that your cabled DAQ device has access to the module's multiplexed output as well as the outputs on all other multiplexed modules in the chassis through the SCXI bus. Also called *serial mode*.

multiplexer Set of semiconductor or electromechanical switches with a common output

that can select one of a number of input signals and that you commonly use

to increase the number of signals measured by one ADC.

N

Named Channel Channel configuration that specifies a DAQ device; a hardware-specific

channel string; channel attributes such as input limits, input mode, and actuator type; and a scaling formula for making a measurement or generating a signal in terms of your actual physical quantity

NI-488 Driver-level software to control and communicate with GPIB cards and

devices.

NI-DAQ Driver-level software to control and communicate with GPIB cards and

devices.

nonlatched digital I/O Type of digital acquisition/generation where the DIO control updates the

digital lines or port states immediately or returns the digital value of an

input line. Also called *immediate digital I/O*.

nonreferenced signal Signal sources with voltage signals that are not connected to an absolute

reference or system ground. Also called *floating signal sources*. Common example of non-referenced signal sources include batteries, transformers,

and thermocouples.

nonreferenced single-ended

Measurement where the voltage can vary with respect to the measurement system ground. All measurements are made with respect to a common

reference.

NRSE Nonreferenced Single-Ended.

0

object Software tool for accomplishing tasks in different programming

environments. An object can have properties, methods, and events. You change an object's state by changing the values of its properties. An object's behavior consists of the operations (methods) that can be

performed on it and the accompanying state changes.

See property, method, event.

object browser Dialog window that displays the available properties and methods for

the controls that are loaded. The object browser shows the hierarchy within a group of objects. To activate the object browser in Visual Basic,

press <F2>.

OCX OLE Control eXtension. Another name for ActiveX controls, reflected by

the .OCX file extension of ActiveX control files.

OLE Object Linking and Embedding. See ActiveX.

OLE control See ActiveX control.

onboard channels Channels on the plug-in data acquisition board.

OUT output pin Counter output pin where the counter can generate various TTL pulse

waveforms.

output limits Upper and lower voltage or current outputs for an analog output channel.

The output limits determine the polarity and voltage reference settings for

a board.

P

parallel mode Type of SCXI operating mode in which the module sends each of its input

channels directly to a separate input channel of the device to the module.

One update (input or output) on a digital port. The number of updates on a pattern

buffered digital operation is measured in number of patterns.

pattern generation Type of handshaked (latched) digital I/O in which internal counters

> generate the handshaked signal, which in turn initiates a digital transfer. Because counters output digital pulses at a constant rate, you can generate and retrieve patterns at a constant rate because the handshaked signal is

produced at a constant rate.

pause condition Condition on a data acquisition process that determines when the

acquisition is paused. The condition can be a digital hardware signal or the

state of an analog hardware signal relative to set limits.

**PFI** Programmable Function Input. Input and output lines on the I/O controller

of E-series data acquisition devices.

**PGIA** Programmable Gain Instrumentation Amplifier.

Plot CWGraph group of methods that displays a new set of data while deleting

> any previous data on the graph. A plot also refers to one of the traces (data lines) on a graph representing the data in one row or column of an array. Each plot on the graph has its own properties, such as color, style, and

so on.

Plug and Play devices Devices that do not require dip switches or jumpers to configure resources

on the devices. Also called switchless devices.

PnP See Plug and Play devices.

Pointer Indicator on a CWSlide or CWKnob object. You can use a collection of

> pointers to display different values on the same object. In the collection, each pointer is referenced by an index in the collection and each individual

pointer has its own properties such as color, style, mode, and so on.

postriggering Technique used on data acquisition boards to acquire a programmed

number of samples after trigger conditions are met.

pretriggering Technique used on data acquisition boards to keep a continuous buffer

filled with data. When the trigger conditions are met, the sample includes

the data leading up to the trigger condition.

property Attribute that controls the appearance or behavior of an object. The

property can be a specific value or another object with its own properties and methods. For example, a value property is the color (property) of a plot (object), while an object property is a specific Y axis (property) on a graph (object). The Y axis itself is another object with properties, such as

minimum and maximum values.

pulse Physical signal generated by the Pulse control. Pulse uses TTL levels on

most data acquisition devices.

pulse delay Amount of time from the start of a pulse generation until the active phase

of the pulse, measured in seconds. In a positive polarity pulse, the output from the counter is low for the duration of the pulse delay before going high.

pulse period Period of a continuous or finite pulse train. The period is defined as the

amount of time between two consecutive rising or falling edges of the signal. The period is the inverse of the frequency of the pulse train.

pulse trains Multiple pulses.

pulse width Width of a pulse generated by a counter on a data acquisition device;

measured in seconds.

pulsed output Form of counter signal generation by which a pulse is output when a

counter reaches a certain value.

R

reference Link to an external code source in Visual Basic. References are anything

that add additional code to your program, such as OLE controls, DLLs, objects, and type libraries. You can add references by selecting the

Tools»References... menu.

referenced single-ended Measurement made with respect to a common reference (RSE) or a ground.

Also called a grounded measurement system.

RMS Root Mean Square.

row-major order Systematic way to organize the data in a 2D array by rows.

RS-232 Standard serial bus on a computer used to communicate with instruments.

Commonly referred to as serial communication.

RSE Referenced Single-Ended.

RTD Resistance Temperature Detector. A temperature-sensing device in which

resistance increases with increases in temperature.

RTSI Real-Time System Integration bus. The National Instruments timing bus

that interconnects data acquisition boards directly, by means of connectors

on top of the boards, for precise synchronization of functions.

S

sample Single (one and only one) analog or digital input or output data point.

sample counter Clock that counts the output of the channel clock (the number of samples

taken). On boards with simultaneous sampling, this counter counts the

output of the scan clock and hence the number of scans.

scan One or more analog or digital input samples. Typically, the number of input

samples in a scan is equal to the number of channels in the input group. For example, one pulse from the scan clock produces one scan that acquires one

new sample from every analog input channel in the group.

scan clock Clock controlling the time interval between scans. On boards with interval

scanning support (for example, the AT-MIO-16F-5), this clock gates the channel clock on and off. On boards with simultaneous sampling, this clock

clocks the track-and-hold circuitry.

scan rate Number of scans per second. For example, at a scan rate of 10Hz, each

channel is sampled 10 times per second.

scan width Number of channels in the channel list or number of ports in the port list

you use to configure an analog or digital input group.

SCXI Signal Conditioning eXtensions for Instrumentation. The National

Instruments product line for conditioning low-level signals within an external chassis near sensors, so only high-level signals in a noisy

environment are sent to data acquisition boards.

sec Seconds.

serial Standard serial bus on a computer used to communicate with instruments.

Also known as RS-232.

settling time Amount of time required for a voltage to reach its final value within

specified limits.

signal conditioning Manipulation of analog signals to prepare them for digitizing.

signal divider Performing frequency division on an external signal.

single-ended inputs Analog inputs that you measure with respect to a common ground.

Snap Mode Mode that controls the available coordinates for cursors to line up on a plot.

software analog

triggering

Method of triggering in which you simulate an analog trigger using

software.

SOURCE input pin Counter input pin where the counter counts the signal transitions.

start condition Condition on a data acquisition process that determines when the actual

acquisition starts. The condition can be a software trigger, an analog

hardware trigger, or a digital hardware trigger.

STC System Timing Controller. See DAQ-STC.

stop condition Condition on a data acquisition process that determines when the

acquisition stops. The condition can be none (the acquisition stops when all points have been acquired), continuous (the acquisition runs continuously), software analog trigger, hardware analog trigger, or hardware digital

trigger.

strain gauge Thin conductor attached to a material that detects stress or vibrations in that

material.

Style Display style of a GUI object. An object can have different display styles

while maintaining the same functionality. For example, the button can be an LED, toggle switch, vertical or horizontal slide, push button, command

button, and more.

switchless device Devices that do not require dip switches or jumpers to configure resources

on the devices. Also called *Plug and Play devices*.

synchronous Property or operation that begins an operation and returns control to the

program only when the operation is complete.

syntax Set of rules to which statements must conform in a particular programming

language.

T

TC Terminal Count. The highest value of a counter.

thermocouple Template-sensing device that measures temperature by the changing

electrical potential between two different metals.

toggled output Form of counter signal generation by which the output changes the state of

the output signal from high to low or from low to high when the counter

reaches a certain value.

trace Data line on a graph. Traces are generated using the Plot or Chart methods

of the graph. Also called a plot.

track-and-hold Circuit that tracks an analog voltage and holds the value on command.

Track Mode Property of a graph that specifies how the mouse interacts with the graph.

Use the Track Mode to turn on zooming and panning for the graph.

transducer excitation Type of signal conditioning that uses external voltages and currents to

excite the circuitry of a signal conditioning system into measuring physical

phenomena.

trigger Condition for starting or stopping clocks.

TTL Transistor-Transistor Logic. Specifications for digital signals.

U

UI User Interface.

unipolar Signal range that is always positive, for example, 0 to 10 V.

update One or more analog or digital output samples. Typically, the number of

output samples in an update is equal to the number of channels in the output group. For example, one pulse from the update clock produces one update that sends one new sample to every analog output channel in the group.

update clock Clock that sets the update rate for the AO, DI, and DO controls.

update rate Number of output updates per second.

update width

Number of channels in the channel list or number of ports in the port list

you use to configure an analog or digital output group.

URL Uniform Resource Locator. A standard that uses a descriptive string to

identify the source or connection for a data transfer used with DataSocket, FTP, HTTP, and file I/O. The URL includes the communication protocol (scheme), name or identifier of the computer being accessed, and scheme-specific information identifying a file, Web page, or, when using

DSTP, the data item.

V

V Volts.

Value Pairs Pair that consists of a name and a value that you can use for custom ticks,

labels, and grid lines on the axis of a knob, slide, or graph.

Value Pairs Only control Control whose only valid values are its value pairs.

VB Microsoft Visual Basic.

VC++ Microsoft Visual C++.

VDC Volts, Direct Current.

VISA Driver software architecture developed by National Instruments to unify

instrumentation software—VXI, GPIB, and serial port. It has been accepted as a standard for VXI by the VXI*plug&play* Systems Alliance.

VISA Resource String identifying a specific instrument connected to the computer and

controlled using the VISA control and driver.

Vref Voltage reference.

VXI VME eXtension for Instrumentation. Instrumentation architecture and bus

based on the VME standard. Used in high-end test applications.

## W

waveform Multiple voltage readings taken at a specific sampling rate.

Web Server See *HTTP server*.

## Index

| Numbers                                     | object hierarchy (figure), 7-6                   |
|---|--|
| 1D and 2D operations (table), 10-3          | tutorial, 7-14 to 7-18                           |
| The and 2D operations (table), 10-3         | developing code, 7-16 to 7-17                    |
|   | form design, 7-15                                |
| A   | setting DAQ properties, 7-16                     |
| AcquireData method, 7-11 to 7-12            | testing the program, 7-18                        |
| ActiveX controls. See also events; methods; | AIPoint object, 7-6 to 7-7                       |
| properties.                                 | analog input, single point. See AIPoint control. |
| getting started with using, 2-5 to 2-6      | analog output, single point. See AOPoint control |
| installing, 1-4                             | Analysis Library controls                        |
| setting properties, 1-10 to 1-15            | controls, 10-12 to 10-13                         |
| Advanced Analysis Library, 10-2             | descriptions in online reference                 |
| advanced application development. See       | manual, 10-13                                    |
| application development.                    | error codes (table), D-20 to D-23                |
| AI control, 7-9 to 7-14                     | error messages, 10-13                            |
| AI object, 7-10                             | function tree (table)                            |
| asynchronous acquisition, 7-10 to 7-11      | CWArray control, 10-3 to 10-4                    |
| ChannelClock object, 7-12 to 7-13           | CWComplex control, 10-4 to 10-5                  |
| error handling, 7-12                        | CWDSP control, 10-8 to 10-12                     |
| methods and events, 7-10 to 7-12            | CWMatrix control, 10-5 to 10-6                   |
| object hierarchy (figure), 7-9              | CWStat control, 10-6 to 10-7                     |
| PauseCondition object, 7-13 to 7-14         | list of controls (table), 10-1                   |
| ScanClock object, 7-12 to 7-13              | overview, 1-2                                    |
| StartCondition object, 7-13 to 7-14         | purpose and use, 1-15                            |
| StopCondition object, 7-13 to 7-14          | questions and answers, C-14                      |
| synchronous acquisition, 7-11 to 7-12       | statistics function tutorial, 10-14 to 10-17     |
| tutorial, 7-14 to 7-18                      | developing code, 10-16 to 10-17                  |
| developing code, 7-16 to 7-17               | form design, 10-15                               |
| form design, 7-15                           | testing the program, 10-17                       |
| setting DAQ properties, 7-16                | versions of the library, 10-2                    |
| testing the program, 7-18                   | analysis of variance functions (table), 10-7     |
| AI object, 7-10                             | AO control, 7-20 to 7-24                         |
| AIPoint control, 7-6 to 7-8                 | AO object, 7-21                                  |
| AIPoint object, 7-6 to 7-7                  | IntervalClock object, 7-22 to 7-23               |
| Channel object, 7-8                         | methods and events, 7-21 to 7-22                 |
| ChannelClock object 7-8                     | object hierarchy (figure), 7-20                  |

Channels collection, 7-7 to 7-8

| StartCondition object, 7-23 to 7-24                       | GetErrorText function, 12-16 to 12-17                     |
|---|---|
| UpdateClock object, 7-22 to 7-23                          | return codes, 12-14 to 12-15                              |
| AO object, 7-21   | single stepping, 12-18                                    |
| AOPoint control, 7-18 to 7-20                             | Step Into mode, 12-18                                     |
| AOPoint object, 7-19                                      | Step Over mode, 12-18                                     |
| methods, 7-19 to 7-20                                     | watch window, 12-18                                       |
| object hierarchy (figure), 7-19                           | Visual Basic applications, 3-1 to 3-12                    |
| tutorial, 7-24 to 7-28                                    | Visual C++ applications, 4-1 to 4-10                      |
| developing code, 7-25 to 7-27                             | array operation functions (table)                         |
| form design, 7-24 to 7-25                                 | 1D and 2D operations, 10-3                                |
| testing the program, 7-27 to 7-28                         | multidimensional array operations, 10-4                   |
| AOPoint object, 7-19                                      | multidimensional element operations,                      |
| application development                                   | 10-3 to 10-4  |
| ActiveX controls, 2-5 to 2-6                              | ASRL (Serial) object, 9-8                                 |
| advanced features of ComponentWorks, 12-1 to 12-12        | asynchronous acquisition methods and events, 7-10 to 7-11 |
| Virtual Data Logger application,                          | asynchronous I/O  |
| 12-9 to 12-12   | GPIB control, 8-8 to 8-9                                  |
| Virtual Oscilloscope application, 12-1 to 12-4            | message-based communication, 9-10<br>Serial control, 8-14 |
| Virtual Spectrum Meter application,                       | AT-A2150 data acquisition card, C-9                       |
| 12-4 to 12-9  | AT-DSP2200 data acquisition card, C-9                     |
| Delphi applications, 5-1 to 5-9                           | attributes, CWData object, 11-12                          |
| distributing applications using                           | axes, Virtual Data Logger application                     |
| ComponentWorks, C-2                                       | formats, 12-11 to 12-12                                   |
| examples included with                                    | multiple, 12-10 to 12-11                                  |
| ComponentWorks, 2-4 to 2-5                                | Axes collection, 6-20                                     |
| installing for specific programming environment, 2-5      | Axis object, 6-4 to 6-5, 6-20                             |
| learning to use controls, 2-4                             | P   |
| using as basis for applications,                          | В   |
| 2-6 to 2-7  | Base Analysis Library, 10-2                               |
| getting started, 2-5 to 2-7                               | Borland Delphi. See Delphi applications.                  |
| testing and debugging, 12-12 to 12-18                     | breakpoints, 12-17 to 12-18                               |
| breakpoints, 12-17 to 12-18<br>Debug.Print command, 12-17 | buffered measurements, Counter control, 7-50              |
| error and warning events,                                 | buffered waveform digital input. See                      |
| 12-15 to 12-16  | DI control.   |
| error checking, 12-12 to 12-14                            | buffers, data acquisition programming                     |
| exceptions, 12-13 to 12-14                                | considerations, B-4                                       |
| enceptions, 12 15 to 12 11                                | bulletin board support, F-1                               |

| Button control  | IntervalClock, 7-22 to 7-23           |
|---|---------------------------------------|
| events, 6-13  | ScanClock, 7-12 to 7-13               |
| Graph and Button control tutorial,                                    | UpdateClock                           |
| 6-22 to 6-25  | AO control, 7-22 to 7-23              |
| developing program code,  | DI control, 7-36                      |
| 6-24 to 6-25  | DO control, 7-39 to 7-40              |
| form design, 6-22 to 6-23   | Clock (Source) input, 7-45            |
| testing the program, 6-25   | clocks                                |
| purpose and use, 6-12   | channel clocks, B-4                   |
|   | data acquisition programming          |
| C   | considerations, B-4                   |
|   | scan clocks, B-5                      |
| calibration functions, 7-60   | collection objects, 1-9 to 1-10       |
| channel clocks, B-4   | collections                           |
| Channel object, 7-8   | Axes, 6-20                            |
| channel strings   | Channels, 7-7 to 7-8                  |
| devices requiring reverse list of channels                            | Cursors, 6-18 to 6-19                 |
| (note), 7-4   | definition, 1-9                       |
| purpose and use, 7-3 to 7-4   | Lines, 7-32                           |
| SCXI channel strings  | Plots, 6-16 to 6-18                   |
| data acquisition controls, 7-4 to 7-5                                 | Pointers, 6-4                         |
| data acquisition programming  | Ports, 7-31                           |
| considerations, B-6 to B-7  | ValuePairs collection, 6-5 to 6-6     |
| Channel Wizard, B-3   | common questions. See questions about |
| ChannelClock object   | ComponentWorks.                       |
| AI control, 7-12 to 7-13  | complex number functions (table),     |
| AIPoint control, 7-8  | 10-4 to 10-5                          |
| channels  | complex operation functions,          |
| data acquisition programming considerations, B-3 to B-4               | multidimensional (table), 10-5        |
|   | ComponentWorks                        |
| questions and answers, C-9 to C-10<br>Channels collection, 7-7 to 7-8 | application development overview,     |
|   | 2-5 to 2-7                            |
| charting data, 6-13. <i>See also</i> Graph control.                   | components, 1-1 to 1-2                |
| ChartXvsY method, 6-16<br>ChartXY method, 6-16                        | examples installed with, 2-4 to 2-5   |
| •   | general error codes, D-24 to D-26     |
| ChartY method, 6-16, 6-25   | information sources                   |
| clearing instruments, with GPIB control, 8-9                          | additional sources, 2-7               |
| Clock objects   | documentation, 2-2 to 2-3             |
| ChannelClock  | online reference information,         |
| Al Roint control, 7.8   | 2-3 to 2-4                            |
| AIPoint control, 7-8  |                                       |

| installing and configuring driver software,     | Cursor object, 6-19                          |
|---|--|
| 2-1 to 2-2                                      | cursors, Virtual Spectrum Meter application, |
| overview, 1-1 to 1-2                            | 12-7 to 12-8                                 |
| questions about, C-1 to C-14                    | Cursors collection, 6-18 to 6-19             |
| system requirements, 1-3                        | curve fitting functions (table), 10-7        |
| configuration, for data acquisition, B-2 to B-3 | custom property page                         |
| DAQ Channel Wizard, B-3                         | CWGraph control example (figure), 1-12       |
| device number, B-2 to B-3                       | definition, 1-11                             |
| overview, 7-2                                   | customer communication, xxiii, F-1 to F-2    |
| SCXI hardware, B-2                              | CWArray control function tree, 10-3 to 10-4  |
| Configuration method, Pulse control, 7-53       | 1D and 2D operations, 10-3                   |
| Configure functions, 7-60                       | multidimensional array operations, 10-4      |
| Configure method                                | multidimensional element operations,         |
| AO control, 7-21 to 7-22                        | 10-3 to 10-4                                 |
| asynchronous acquisition, AI control,           | CWButton control (table), 6-2                |
| 7-10 to 7-11                                    | CWComplex control function tree,             |
| Counter control, 7-48                           | 10-4 to 10-5                                 |
| DO control, 7-40                                | complex numbers, 10-4 to 10-5                |
| Connect method, DataSocket control,             | multidimensional complex                     |
| 11-2, 11-9                                      | operations, 10-5                             |
| ConnectTo method, DataSocket control, 11-3      | CWData object, 11-11 to 11-13                |
| control methods. See methods.                   | standalone CWData objects,                   |
| Conversion functions, 7-60                      | 11-12 to 11-13                               |
| CopyFrom method, 11-10                          | working with attributes, 11-12               |
| Counter control, 7-46 to 7-50                   | CWDSP control function tree, 10-8 to 10-12   |
| buffered measurements, 7-50                     | FIR digital filters, 10-10 to 10-11          |
| methods and events, 7-48 to 7-49                | frequency domain signal processing,          |
| object hierarchy (figure), 7-46                 | 10-8 to 10-9                                 |
| tutorial, 7-55 to 7-59                          | IIR digital filters, 10-9 to 10-10           |
| code development, 7-56 to 7-58                  | measurement, 10-11                           |
| form design, 7-55 to 7-56                       | signal generation, 10-8                      |
| testing the program, 7-59                       | time domain signal processing, 10-9          |
| Counter object, 7-46 to 7-48                    | windows, 10-11                               |
| buffered measurements, 7-50                     | CWGPIB object, 8-7                           |
| measurement types (table), 7-47                 | CWGraph control                              |
| counter/timer hardware                          | associated styles (table), 6-2               |
| Counter control, 7-46 to 7-50                   | custom property page (figure), 1-11          |
| Pulse control, 7-51 to 7-54                     | CWKnob control (table), 6-2                  |
| questions and answers, C-11                     | CWMatrix control function tree, 10-5 to 10-6 |
| tutorial, 7-55 to 7-59                          | CWNumEdit control (table), 6-2               |
|   | CWPattern object, 8-5                        |

| CWSerial object, 8-12 to 8-13                | Data Acquisition controls, 7-1 to 7-61 |
|--|--|
| CWSlide control (table), 6-2                 | AI control, 7-9 to 7-14                |
| CWStat control function tree, 10-6 to 10-7   | AI object, 7-10                        |
| analysis of variance, 10-7                   | asynchronous acquisition,              |
| curve fitting, 10-7                          | 7-10 to 7-11                           |
| interpolation, 10-7                          | ChannelClock object, 7-12 to 7-13      |
| nonparametric statistics, 10-7               | error handling, 7-12                   |
| probability distributions, 10-6 to 10-7      | methods and events, 7-10 to 7-12       |
| statistics, 10-6                             | PauseCondition object, 7-13 to 7-14    |
| CWTask object, 8-4                           | ScanClock object, 7-12 to 7-13         |
| CWToken object, 8-6                          | StartCondition object, 7-13 to 7-14    |
|  | StopCondition object, 7-13 to 7-14     |
| n  | synchronous acquisition,               |
| D  | 7-11 to 7-12                           |
| DAQ Channel Wizard, B-3                      | AIPoint and AI DAQ control tutorial,   |
| DAQ controls. See data acquisition controls. | 7-14 to 7-18                           |
| DAQCard-700, C-11                            | developing code, 7-16 to 7-17          |
| DAQCard-1200, C-11                           | form design, 7-15                      |
| DAQTools, 7-60 to 7-61                       | setting DAQ properties, 7-16           |
| function groups, 7-60                        | testing the program, 7-18              |
| using DAQTools functions, 7-61               | AIPoint control, 7-6 to 7-8            |
| data acquisition                             | AIPoint object, 7-6 to 7-7             |
| configuration, B-2 to B-3                    | Channel object, 7-8                    |
| DAQ Channel Wizard, B-3                      | ChannelClock object, 7-8               |
| device number, B-2 to B-3                    | Channels collection, 7-7 to 7-8        |
| overview, 7-2                                | AO control, 7-20 to 7-24               |
| SCXI hardware, B-2                           | AO object, 7-21                        |
| hardware, B-7 to B-9                         | IntervalClock object, 7-22 to 7-23     |
| PFI, B-9                                     | methods and events, 7-21 to 7-22       |
| RTSI, B-8                                    | object hierarchy (figure), 7-20        |
| SCXI, B-7 to B-8                             | StartCondition object, 7-23 to 7-24    |
| installing hardware and software,            | UpdateClock object, 7-22 to 7-23       |
| B-1 to B-2                                   | AOPoint control, 7-18 to 7-20          |
| programming considerations, B-3 to B-9       | AOPoint object, 7-19                   |
| buffers, B-4                                 | methods, 7-19 to 7-20                  |
| channel clocks, B-5                          | AOPoint control tutorial, 7-24 to 7-28 |
| clocks, B-5                                  | developing code, 7-25 to 7-27          |
| device numbers and channels,                 | form design, 7-24 to 7-25              |
| B-3 to B-4                                   | testing the program, 7-27 to 7-28      |
| scan clocks, B-5                             |  |
| SCXI channel string, B-6 to B-7              |  |

| Counter and Pulse control tutorial,    | object hierarchy and common properties,        |
|--|--|
| 7-55 to 7-59                           | 7-2 to 7-6                                     |
| code development, 7-56 to 7-58         | channel strings, 7-3 to 7-4                    |
| form design, 7-55 to 7-56              | Device, DeviceName, and                        |
| testing the program, 7-59              | DeviceType, 7-3                                |
| Counter control, 7-46 to 7-50          | ExceptionOnError and                           |
| buffered measurements, 7-50            | ErrorEventMask, 7-5 to 7-6                     |
| Counter object, 7-46 to 7-48           | SCXI channel strings, 7-4 to 7-5               |
| measurement types (table), 7-47        | overview, 1-1, 7-1 to 7-2                      |
| methods and events, 7-48 to 7-49       | Pulse control, 7-51 to 7-54                    |
| counter/timer hardware, 7-45 to 7-54   | FSK and ETS pulse generation, 7-54             |
| DAQTools, 7-60 to 7-61                 | methods, 7-53                                  |
| function groups, 7-60                  | Pulse object, 7-51 to 7-53                     |
| using DAQTools functions, 7-61         | questions and answers, C-8 to C-11             |
| data acquisition configuration, 7-2    | data acquisition utility functions (DAQTools), |
| DI control, 7-34 to 7-37               | 7-60 to 7-61                                   |
| DI object, 7-35                        | Data Logger application. See                   |
| methods and events, 7-36 to 7-37       | Virtual Data Logger application.               |
| UpdateClock object, 7-36               | data source, for DataSocket control. See       |
| digital controls and hardware,         | DataSocket control.                            |
| 7-28 to 7-41                           | DataAsString property                          |
| DIO control, 7-29 to 7-34              | GPIB control and Serial control, 8-2           |
| common properties and methods,         | VISA control, 9-4                              |
| 7-32 to 7-34                           | DataSocket control, 11-1 to 11-17              |
| DIO object, 7-30 to 7-31               | basic principles, 11-2 to 11-3                 |
| Ports collection and Port object, 7-31 | CWData object, 11-11 to 11-13                  |
| DIO control tutorial, 7-41 to 7-45     | standalone CWData objects,                     |
| developing code, 7-42 to 7-44          | 11-12 to 11-13                                 |
| form design, 7-42                      | working with attributes, 11-12                 |
| testing the program, 7-44 to 7-45      | disconnecting from data source,                |
| DO control, 7-37 to 7-41               | 11-5 to 11-6                                   |
| DO object, 7-38 to 7-39                | locating data source, 11-3                     |
| methods and events, 7-40 to 7-41       | OnDataUpdated event, 11-4 to 11-5              |
| UpdateClock object, 7-39 to 7-40       | OnStatusUpdated event, 11-5 to 11-6            |
| error codes (table), D-1 to D-16       | overview, 1-2, 11-1 to 11-2                    |
| Lines collection and Line object, 7-32 | reading data from data source,                 |
| common properties and methods,         | 11-3 to 11-6                                   |
| 7-32 to 7-34                           | setting up DataSocket Server,                  |
| list of DAQ controls, 7-2              | 11-13 to 11-15                                 |

| tutorial for reading waveform,             | Delphi 2, A-6 to A-7                        |
|--|---|
| 11-6 to 11-9                               | Delphi applications, 5-1 to 5-9             |
| code development, 11-7 to 11-8             | building user interface, 5-4 to 5-6         |
| form design, 11-6 to 11-7                  | editing properties programmatically,        |
| testing the program, 11-8 to 11-9          | 5-6 to 5-7                                  |
| updating data, 11-5                        | events, 5-8 to 5-9                          |
| automatically, 11-5                        | loading ComponentWorks controls,            |
| writing data to data target, 11-9 to 11-10 | 5-2 to 5-4                                  |
| automatically updating data                | methods, 5-7 to 5-8                         |
| target, 11-10                              | online help for learning controls, 5-9      |
| updating data target, 11-10                | placing controls, 5-4 to 5-5                |
| DataSocket Server, 11-13 to 11-15          | programming with ComponentWorks             |
| connecting to and reading data             | controls, 5-6 to 5-9                        |
| items, 11-15                               | property sheets, 5-5 to 5-6                 |
| creating data items, 11-14                 | using Delphi 2, A-6 to A-7                  |
| distributing applications, E-3             | developing applications. See                |
| requirements for running, 11-14            | application development.                    |
| status checking, 11-14                     | device numbers                              |
| tutorial for sharing data between          | configuration, B-2 to B-3                   |
| applications, 11-15 to 11-17               | programming considerations, B-3 to B-4      |
| configuring DataSocket Server,             | Device property, 7-3                        |
| 11-16 to 11-17                             | DeviceName property, 7-3                    |
| procedural steps, 11-15 to 11-16           | DeviceType property, 7-3                    |
| debugging and testing applications,        | DI control, 7-34 to 7-37                    |
| 12-12 to 12-18                             | methods and events, 7-36 to 7-37            |
| breakpoints, 12-17 to 12-18                | object hierarchy (figure), 7-34             |
| Debug.Print command, 12-17                 | UpdateClock object, 7-36                    |
| error and warning events, 12-15 to 12-16   | DI object, 7-35                             |
| error checking, 12-12 to 12-14             | digital controls and hardware, 7-28 to 7-41 |
| exceptions, 12-13 to 12-14                 | common properties and methods,              |
| GetErrorText function, 12-16 to 12-17      | 7-32 to 7-34                                |
| return codes, 12-14 to 12-15               | DI control—buffered waveform digital        |
| single stepping, 12-18                     | input, 7-34 to 7-37                         |
| Step Into mode, 12-18                      | DI object, 7-35                             |
| Step Over mode, 12-18                      | DIO control—single point digital input      |
| watch window, 12-18                        | and output, 7-29 to 7-34                    |
| default property sheet                     | DIO object, 7-30 to 7-31                    |
| definition, 1-10                           | DO control—buffered waveform digital        |
| Visual Basic example (figure), 1-11        | output, 7-37 to 7-41                        |
| DeleteAttribute method, 11-12              | DO object, 7-38 to 7-39                     |

| Lines collection and Line object, 7-32              | disconnecting from data source, 11-5 to 11-6   |
|---|--|
| methods and events                                  | distributing applications, E-1 to E-5  |
| DI control, 7-36 to 7-37                            | automatic installers, E-2  |
| DO control, 7-40 to 7-41                            | ComponentWorks evaluation mode, E-4  |
| Ports collection and Port object, 7-31              | DataSocket Server, E-3   |
| UpdateClock object                                  | general considerations, E-1  |
| DI control, 7-36                                    | instrument drivers, E-3  |
| DO control, 7-39 to 7-40                            | manual installation, E-2 to E-3  |
| Digital Signal Processing Analysis                  | questions and answers, C-2   |
| Library, 10-2                                       | required files, E-1  |
| digital signal processing and                       | run-time licenses, E-4   |
| signal generation functions                         | troubleshooting, E-4 to E-5  |
| FIR digital filters (table), 10-10 to 10-11         | DO control, 7-37 to 7-41   |
| frequency domain signal processing                  | methods and events, 7-40 to 7-41   |
| (table), 10-8 to 10-9                               | object hierarchy (figure), 7-38  |
| IIR digital filters (table), 10-9 to 10-10          | UpdateClock object, 7-39 to 7-40   |
| measurement functions (table), 10-11                | DO object, 7-38 to 7-39  |
| signal generation functions (table), 10-8           | documentation  |
| time domain signal processing functions             | conventions used in manual, xxii-xxiii   |
| (table), 10-9                                       | organization of manual, xix-xxii,  |
| Virtual Spectrum Meter application,                 | 2-2 to 2-3   |
| 12-5 to 12-7  | related documentation, xxiii   |
| windows functions (table), 10-11                    | driver software for hardware I/O controls,   |
| DIO control   | installing, 2-1 to 2-2   |
| common properties and methods, 7-32 to 7-34         | DSP functions. <i>See</i> digital signal processing and signal generation functions. |
| Lines collection and Line object, 7-32              | dstp: (DataSocket transfer protocol)   |
| object hierarchy (figure), 7-30                     | scheme, 11-3   |
| Ports collection and Port object, 7-31              |  |
| single point digital input and output, 7-29 to 7-34 | E  |
| tutorial, 7-41 to 7-45                              | EISA-A2000 data acquisition card, C-9  |
| developing code, 7-42 to 7-44                       | electronic support services, F-1 to F-2  |
| form design, 7-42                                   | e-mail support, F-2  |
| testing the program, 7-44 to 7-45                   | EnableEvent method, 9-17   |
| DIO object  | equivalent time sampling (ETS) pulse   |
| common properties and methods,                      | generation, 7-54   |
| 7-32 to 7-34  | error and warning events, 12-15 to 12-16   |
| purpose and use, 7-30 to 7-31                       | error checking/handling  |
| DisableEvent method, 9-16                           | AI control, 7-12   |
| DiscardEvent method, 9-16                           | DAQ controls, 7-5 to 7-6   |
|   |  |

| GetErrorText function, 7-60,             | Serial control, 8-13 to 8-14  |
|--|---|
| 12-16 to 12-17                           | synchronous acquisition, 7-11 to 7-12   |
| testing applications, 12-12 to 12-14     | using in applications   |
| error codes                              | Delphi applications, 5-8 to 5-9   |
| Analysis controls (table), D-20 to D-23  | Visual C++ applications, 4-9 to 4-10  |
| data acquisition controls (table),       | VISA control, 9-14 to 9-17  |
| D-1 to D-16                              | examples included with ComponentWorks,  |
| general ComponentWorks codes,            | 2-4 to 2-5  |
| D-24 to D-26                             | installing for specific programming   |
| VISA controls (table), D-17 to D-19      | environment, 2-5  |
| error messages                           | learning about controls, 2-4  |
| Analysis Library controls, 10-13         | using for application development,  |
| exceptions, 12-13 to 12-14               | 2-6 to 2-7  |
| ErrorEventMask property, 7-5 to 7-6      | ExceptionOnError property   |
| ETS (equivalent time sampling) pulse     | GPIB control and Serial control, 8-2  |
| generation, 7-54                         | purpose and use, 7-5 to 7-6   |
| event handler routines                   | VISA control, 9-4   |
| developing, 1-14 to 1-15                 | exceptions, in application testing,   |
| Visual Basic applications, 3-6 to 3-7    | 12-13 to 12-14  |
| event handling with event queue,         |   |
| VISA control, 9-15 to 9-17               | F   |
| checking events, 9-16                    | •   |
| disabling events, 9-16 to 9-17           | fax and telephone support numbers, F-2  |
| discarding events, 9-16                  | Fax-on-Demand support, F-2  |
| event types, VISA control, 9-14 to 9-15  | file: (local files) scheme, 11-3  |
| events                                   | file input/output functions, Virtual Data                                     |
| AO control, 7-21 to 7-22                 | Logger application, 12-12   |
| asynchronous acquisition, 7-10 to 7-11   | files   |
| Button control, 6-13                     | installed files, 1-6  |
| Counter control, 7-48 to 7-49            | required files for distributing applications,<br>E-4 to E-5                   |
| CWTask object, 8-4                       |   |
| definition, 1-7                          | FIR digital filters (table), 10-10 to 10-11 forms. <i>See also</i> tutorials. |
| DI control, 7-36 to 7-37                 |   |
| DO control, 7-40 to 7-41                 | Delphi applications, 5-2  |
| error and warning events, 12-15 to 12-16 | Visual Basic applications, 3-1 to 3-2 FOUT functions, 7-60                    |
| GPIB control, 8-8 to 8-9                 |   |
| Graph control, 6-21                      | frequency domain signal processing (table), 10-8 to 10-9                      |
| Knob and Slide controls, 6-6 to 6-7      |   |
| Numeric Edit Box control, 6-7 to 6-8     | FSK (frequency shift keying) pulse generation, 7-54                           |
| OnDataUpdated, 11-4 to 11-5              | generation, 1-34  |
| OnStatusUpdated, 11-5 to 11-6            |   |

| ftp: (file transfer protocol) scheme, 11-3  | Graph control, 6-13 to 6-21                  |
|---|--|
| FTP support, F-1                            | Axes collection, 6-20                        |
|   | Axis object, 6-20                            |
| C   | chart methods, 6-16                          |
| G   | Cursor object, 6-19                          |
| Gate input, 7-45                            | Cursors collection, 6-18 to 6-19             |
| Get functions, 7-60                         | events, 6-21                                 |
| GetAttribute method, 11-12                  | Graph object, 6-14 to 6-16                   |
| GetErrorText function, 7-60, 12-16 to 12-17 | hierarchy of (figure), 6-14                  |
| GPIB control, 8-6 to 8-9                    | overview, 1-7 to 1-8                         |
| common properties, 8-2                      | panning and zooming, 6-21                    |
| CWGPIB object, 8-7                          | plot methods, 6-15                           |
| methods and events, 8-8 to 8-9              | Plot object, 6-17 to 6-18                    |
| asynchronous I/O, 8-8 to 8-9                | Plots collection, 6-16 to 6-18               |
| other GPIB operations, 8-9                  | PlotTemplate object, 6-18                    |
| synchronous I/O, 8-8                        | purpose and use, 6-13 to 6-14                |
| object hierarchy, 8-2                       | tutorial, 6-22 to 6-25                       |
| object hierarchy (figure), 8-7              | Graph object, 6-14 to 6-16                   |
| overview, 1-1                               | graph track mode, Virtual Spectrum Meter     |
| parsing, 8-2 to 8-6                         | application, 12-8 to 12-9                    |
| advanced features, 8-2 to 8-6               | Graphical User Interface (GUI) controls. See |
| CWPattern object, 8-5                       | User Interface controls.                     |
| CWTask object, 8-4                          |  |
| CWToken object, 8-6                         | Н  |
| purpose and use, 8-1                        |  |
| questions and answers, C-12 to C-13         | HasAttribute method, 11-12                   |
| tutorial, 8-9 to 8-11                       | Help button, 1-15                            |
| code development, 8-11                      | help files, online. See online reference.    |
| form design, 8-10                           | http: (hypertext transfer protocol)          |
| setting properties, 8-10 to 8-11            | scheme, 11-3                                 |
| testing the program, 8-11                   |  |
| GPIB object, 9-9                            | I  |
| Graph and Button control tutorial,          | ICta functions 7.60                          |
| 6-22 to 6-25                                | ICtr functions, 7-60                         |
| developing program code, 6-24 to 6-25       | IIR digital filters (table), 10-9 to 10-10   |
| form design, 6-22 to 6-23                   | In method, 9-11, 9-12                        |
| testing the program, 6-25                   | installation, 1-3 to 1-6                     |
| graph axes, Virtual Data Logger application | ActiveX controls, 1-4                        |
| formats, 12-11 to 12-12                     | from CD-ROM, 1-3                             |
| multiple, 12-10 to 12-11                    |  |

| distributed applications, E-2 to E-3                   | Statistics object, 6-6                             |
|--|--|
| automatic installers, E-2                              | Ticks object, 6-5                                  |
| manual installation, E-2 to E-3                        | tutorial, 6-8 to 6-11                              |
| driver software for hardware I/O controls, 2-1 to 2-2  | developing program code,<br>6-10 to 6-11           |
| from floppy disks, 1-4                                 | form design, 6-9                                   |
| hardware and software for data acquisition, B-1 to B-2 | testing the program, 6-11<br>ValuePair object, 6-6 |
| installed files, 1-6                                   | variati an object, o o                             |
| instrument driver DLLs, 1-5                            | _  |
| Instrument Driver Factory, 1-5                         | L  |
| questions about ComponentWorks,                        | Labels object, 6-5                                 |
| C-1 to C-2   | Lab-PC+ card, C-11                                 |
| system requirements, 1-3                               | Line object, 7-32                                  |
| Instrument controls. See GPIB control;                 | Lines collection, 7-32                             |
| Serial control; VISA control.                          |  |
| instrument driver DLLs                                 | NA.  |
| installing, 1-5  | М  |
| using in applications, 1-15                            | MapAddress method, 9-13                            |
| Visual Basic applications, 3-7 to 3-8                  | matrix algebra functions (table), 10-5 to 10-6     |
| Instrument Driver Factory                              | measurement functions (table), 10-11               |
| installing, 1-5  | measurement types, Counter object                  |
| overview, 1-2  | (table), 7-47                                      |
| instrument drivers                                     | message-based communication, 9-9 to 9-13           |
| definition, 3-7  | asynchronous I/O, 9-10                             |
| overview, 1-2  | synchronous I/O, 9-10                              |
| interchannel delay, 7-12                               | tutorial, 9-17 to 9-19                             |
| interpolation functions (table), 10-7                  | code development, 9-19                             |
| IntervalClock object, 7-22 to 7-23                     | form design, 9-17 to 9-18                          |
| Item method, 1-13                                      | setting properties, 9-18 to 9-19                   |
|  | testing the program, 9-19                          |
| V  | methods. See also specific methods.                |
| K  | AI object, 7-10 to 7-12                            |
| Knob and Slide controls, 6-3 to 6-7                    | asynchronous acquisition,                          |
| Axis object, 6-4 to 6-5                                | 7-10 to 7-11                                       |
| events, 6-6 to 6-7                                     | synchronous acquisition,                           |
| hierarchy of (figure), 6-3                             | 7-11 to 7-12                                       |
| Knob and Slide object, 6-3 to 6-4                      | AO control, 7-21 to 7-22                           |
| Labels object, 6-5                                     | AOPoint object, 7-19 to 7-20                       |
| Pointer object, 6-4                                    | asynchronous acquisition, 7-10 to 7-11             |
| Pointers collection, 6-4                               | Counter control, 7-48 to 7-49                      |

| CWTask object, 8-4                               | tutorial, 6-8 to 6-11                     |
|--|---|
| definition, 1-7                                  | developing program code,                  |
| DI control, 7-36 to 7-37                         | 6-10 to 6-11                              |
| DIO control, 7-32 to 7-34                        | form design, 6-9                          |
| DO control, 7-40 to 7-41                         | testing the program, 6-11                 |
| functions as methods of corresponding            |   |
| control, 10-12                                   | 0   |
| GPIB control, 8-8 to 8-9                         | 0   |
| Lines collection and Line object,                | Object Browser                            |
| 7-32 to 7-34                                     | Visual Basic 4, A-2 to A-3                |
| parameters, 3-6                                  | Visual Basic 5, 3-8 to 3-10               |
| Pulse control, 7-53                              | object hierarchy                          |
| Serial control, 8-13 to 8-14                     | AI control (figure), 7-9                  |
| synchronous acquisition, 7-11 to 7-12            | AIPoint control (figure), 7-6             |
| using in applications                            | AO control (figure), 7-20                 |
| Delphi applications, 5-7 to 5-8                  | AOPoint control (figure), 7-19            |
| Visual Basic applications, 3-5 to 3-6            | Counter control (figure), 7-46            |
| Visual C++ applications, 4-8 to 4-9              | DAQ controls, 7-3 to 7-6                  |
| VISA control, 9-9 to 9-13                        | DI control (figure), 7-34                 |
| working with control methods,                    | DIO control (figure), 7-30                |
| 1-13 to 1-14                                     | DO control (figure), 7-38                 |
| MoveIn method, 9-12                              | GPIB and Serial controls, 8-2             |
| MoveOut method, 9-12                             | GPIB control (figure), 8-7                |
| multidimensional array operations                | Graph control (figure), 6-14              |
| (table), 10-4                                    | Knob and Slide controls (figure), 6-3     |
| multidimensional complex operations              | Pulse control (figure), 7-51              |
| (table), 10-5                                    | purpose and use, 1-8 to 1-9               |
| multidimensional element operations (table),     | Serial control (figure), 8-12             |
| 10-3 to 10-4                                     | similarity in different controls, 6-2     |
| multiple graph axes, Virtual Data Logger         | Slide object example, 1-9                 |
| application, 12-10 to 12-11                      | VISA control, 9-2 to 9-3                  |
|  | OnDataUpdated event, 11-4 to 11-5         |
| N  | one dimensional operations (table), 10-3  |
|  | online reference, 2-3 to 2-4              |
| NI-DAQ driver configuration utility, 7-2         | accessing, 2-4                            |
| nonparametric statistics functions (table), 10-7 | descriptions of analysis functions, 10-13 |
| Numeric Edit Box control, 6-7 to 6-8             | finding specific information, 2-4         |
| events, 6-7 to 6-8                               |   |
| purpose and use 6-7                              |   |

| learning about ComponentWorks                | Pointer object, 6-4                           |
|--|---|
| controls, 1-15                               | Pointers collection, 6-4                      |
| Delphi applications, 5-9                     | PokeXX method, 9-13                           |
| Visual Basic applications, 3-12              | polling, with GPIB control, 8-9               |
| Visual C++ applications, 4-10                | Port object, 7-31                             |
| Web Site support, 2-7                        | ports, definition, 7-29                       |
| OnStatusUpdated event, 11-5 to 11-6          | Ports collection, 7-31                        |
| Oscilloscope application. See                | pretriggering modes, Virtual Oscilloscope     |
| Virtual Oscilloscope application.            | application, 12-3                             |
| Out method, 9-12                             | probability distribution functions (table),   |
| Out output, 7-45                             | 10-6 to 10-7                                  |
|  | Programmable Function Inputs (PFI), B-9       |
| п  | programming considerations,                   |
| P  | for data acquisition, B-3 to B-9. See also    |
| panning and zooming graphs, 6-21             | application development.                      |
| parallel polling, with GPIB control, 8-9     | buffers, B-4                                  |
| parameters for methods, 3-6                  | channel clocks, B-5                           |
| Parse method, 8-3                            | clocks, B-5                                   |
| parsing                                      | device numbers and channels, B-3 to B-4       |
| GPIB control, 8-2 to 8-6                     | scan clocks, B-5                              |
| advanced features, 8-2 to 8-6                | SCXI channel string, B-6 to B-7               |
| CWPattern object, 8-5                        | properties. See also specific property names. |
| CWTask object, 8-4                           | channel strings, 7-3 to 7-4                   |
| CWToken object, 8-6                          | definition, 1-7                               |
| questions and answers, C-13                  | Device, DeviceName, and                       |
| VISA control, 9-5                            | DeviceType, 7-3                               |
| PauseCondition object, 7-13 to 7-14          | DIO control, 7-32 to 7-34                     |
| PeekXX method, 9-13                          | editing programmatically                      |
| PFIs (Programmable Function Inputs), B-9     | Delphi applications, 5-6 to 5-7               |
| Plot object, 6-17 to 6-18                    | Visual Basic applications, 3-4 to 3-5         |
| Plots collection, 6-16 to 6-18               | ExceptionOnError and ErrorEventMask,          |
| PlotTemplate object, 6-18                    | 7-5 to 7-6                                    |
| plotting data, 6-13. See also Graph control. | GPIB control, 8-2                             |
| PlotXvsY method, 6-15                        | Instrument controls, 8-2                      |
| PlotXY method, 6-15                          | Lines collection and Line object,             |
| PlotY method                                 | 7-32 to 7-34                                  |
| changing properties programmatically         | Port object, 7-32 to 7-34                     |
| (example), 1-13 to 1-14                      | SCXI channel strings, 7-4 to 7-5              |
| format for accepting data, 6-15              | Serial control, 8-2                           |
| Graph and Button control tutorial, 6-25      |   |

| setting, 1-10 to 1-15. See also tutorials.   | ĸ  |
|--|--|
| Analysis Library and instrument              | RdWrt object, 9-7 to 9-8                   |
| driver DLLs, 1-15                            | Read method                                |
| changing properties                          | parsing, 8-3                               |
| programmatically, 1-12                       | synchronous I/O, message-based             |
| developing event handler routines,           | communication, 9-10                        |
| 1-14 to 1-15                                 | ReadAsynch method                          |
| help file, 1-15                              | asynchronous I/O, message-based            |
| Item method, 1-13                            | communication, 9-10                        |
| property sheets, 1-10 to 1-11                | parsing, 8-3                               |
| working with control methods,                | ReadCounter method, 7-48                   |
| 1-13 to 1-14                                 | ReadMeasurement method, 7-48               |
| VISA object, 9-5 to 9-7                      | Reconfigure method, 7-53                   |
| Visual C++ applications, 4-6 to 4-8          | register-based communication, 9-11 to 9-13 |
| property pages, 1-10 to 1-11                 | high-level register accesses, 9-12         |
| custom property page, 1-11                   | low-level register accesses, 9-13          |
| default property sheet, 1-10                 | moving blocks of data, 9-12                |
| Delphi applications, 5-5 to 5-6              | tutorial, 9-20 to 9-22                     |
| setting default values, 1-10 to 1-11         | code development, 9-21 to 9-22             |
| Visual Basic applications, 3-3 to 3-4        | form design, 9-20 to 9-21                  |
| Pulse control, 7-51 to 7-54                  | setting properties, 9-21                   |
| FSK and ETS pulse generation, 7-54           | testing the program, 9-22                  |
| methods, 7-53                                | RemoveAll method, 8-6                      |
| object hierarchy (figure), 7-51              | Reset functions, 7-60                      |
| tutorial, 7-55 to 7-59                       | Reset method                               |
| code development, 7-56 to 7-58               | AIPoint object, 7-7                        |
| form design, 7-55 to 7-56                    | AO control, 7-22                           |
| testing the program, 7-59                    | AOPoint object, 7-19, 7-20                 |
| Pulse object, 7-51 to 7-53                   | asynchronous acquisition, 7-10             |
| pulse type operations (table), 7-52          | Counter control, 7-48                      |
|  | DO control, 7-40                           |
| Q  | Pulse control, 7-53                        |
|  | return codes, testing applications,        |
| questions about ComponentWorks,              | 12-14 to 12-15                             |
| C-1 to C-14                                  | RTSI bus                                   |
| analysis controls, C-14                      | data acquisition considerations, B-8       |
| data acquisition controls, C-8 to C-11       | programming, B-8                           |
| GPIB, Serial, and VISA controls,             | run-time licenses, E-4                     |
| C-12 to C-13                                 | Tall time needless, 2 1                    |
| installation and getting started, C-1 to C-2 |  |
| user interface controls, C-4 to C-7          |  |

| 3  | signal processing functions. See digital signal                             |
|--|---|
| scan clocks, data acquisition                | processing and signal generation functions.                                 |
| programming considerations, B-4              | single point analog input. See AIPoint control.                             |
| scan rate, 7-12                              | single point analog output. See   |
| ScanClock object, 7-12 to 7-13               | AOPoint control.  |
| SCXI channel strings                         | single stepping, 12-18  |
| data acquisition controls, 7-4 to 7-5        | SingleRead method   |
| data acquisition programming                 | AIPoint object, 7-7   |
| considerations, B-6 to B-7                   | DIO, Port, and Line objects, 7-32 to 7-33                                   |
| SCXI hardware                                | SingleWrite method  |
| configuring, B-2                             | AOPoint object, 7-19 to 7-20  |
| data acquisition considerations,             | DIO, Port, and Line objects, 7-33   |
| B-7 to B-8                                   | Slide control. See Knob and Slide controls.                                 |
| Serial (ASRL) object, 9-8                    | software objects, 1-8   |
| Serial control, 8-12 to 8-14                 | Source input, 7-45  |
| common properties, 8-2                       | Spectrum Meter application. See   |
| CWSerial object, 8-12 to 8-13                | Virtual Spectrum Meter application.   |
| methods and events, 8-13 to 8-14             | Start method  |
| asynchronous I/O, 8-14                       | AO control, 7-21  |
| synchronous I/O, 8-13                        | asynchronous acquisition,   |
| object hierarchy, 8-2                        | AI control, 7-10  |
| object hierarchy (figure), 8-12              | Counter control, 7-48   |
| overview, 1-1                                | DO control, 7-40  |
| parsing, 8-2 to 8-6                          | Pulse control, 7-53   |
| advanced features, 8-2 to 8-6                | StartCondition object   |
| CWPattern object, 8-5                        | AI control, 7-13 to 7-14  |
| CWTask object, 8-4                           | AO control, 7-23 to 7-24  |
| CWToken object, 8-6                          | statistics functions  |
| purpose and use, 8-1                         | analysis of variance functions (table), 10-7                                |
| questions and answers, C-12 to C-13          |   |
| tutorial, 8-14 to 8-17                       | curve fitting functions (table), 10-7 interpolation functions (table), 10-7 |
| code development, 8-17                       | •   |
| form design, 8-14 to 8-15                    | nonparametric statistics functions (table), 10-7                            |
| setting properties, 8-15 to 8-16             | probability distribution functions (table),                                 |
| testing the program, 8-17                    | 10-6 to 10-7  |
| serial polling, with GPIB control, 8-9       | simple statistics (table), 10-6   |
| ServiceRequest event, VISA control, 9-14     | tutorial, 10-13 to 10-17  |
| Set functions, 7-60                          | developing code, 10-16 to 10-17   |
| SetAttribute method, 11-12                   | form design, 10-15  |
| setting properties. See properties, setting. | testing the program, 10-17  |
|  | testing the program, 10 17  |

| Statistics object, 6-6                          | Counter control, 7-55 to 7-59               |
|---|---|
| step into mode, 12-18                           | DataSocket control, 11-6 to 11-9            |
| step over mode, 12-18                           | DataSocket Server, 11-15 to 11-17           |
| stop condition modes, Virtual Oscilloscope      | DIO control, 7-41 to 7-45                   |
| application, 12-2 to 12-3                       | GPIB control, 8-9 to 8-11                   |
| Stop method                                     | Graph and Button control tutorial,          |
| asynchronous acquisition, 7-10                  | 6-22 to 6-25                                |
| Counter control, 7-48                           | Knob and Slide controls, 6-8 to 6-11        |
| Pulse control, 7-53                             | message-based communication,                |
| StopCondition object, 7-13 to 7-14              | 9-17 to 9-19                                |
| SwapBytes property                              | Numeric Edit Box control, 6-8 to 6-11       |
| GPIB control and Serial control, 8-2            | Pulse control, 7-55 to 7-59                 |
| VISA control, 9-4                               | register-based communication,               |
| synchronous acquisition methods and events,     | 9-20 to 9-22                                |
| 7-11 to 7-12                                    | Serial control, 8-14 to 8-17                |
| synchronous I/O                                 | statistics functions, 10-13 to 10-17        |
| GPIB control, 8-8                               | two dimensional operations (table), 10-3    |
| message-based communication, 9-10               |   |
| Serial control, 8-13                            | U   |
| system requirements, 1-3                        |   |
|   | UI Controls. See User Interface controls.   |
| Т   | Update method, 7-33 to 7-34                 |
| 1   | UpdateClock object                          |
| technical support, F-1 to F-2                   | AO control, 7-22 to 7-23                    |
| telephone and fax support numbers, F-2          | DI control, 7-36                            |
| testing applications. See debugging and testing | DO control, 7-39 to 7-40                    |
| applications.                                   | updating                                    |
| Ticks object, 6-5                               | data, 11-5                                  |
| time domain signal processing functions         | data target, 11-10                          |
| (table), 10-9                                   | URL scheme, 11-3                            |
| TrackMode property                              | URLs, for locating data source, 11-3        |
| Graph object, 6-14                              | user interface, building. See also          |
| panning and zooming, 6-21                       | Graphical User Interface controls.          |
| Virtual Spectrum Meter application,             | Delphi applications, 5-4 to 5-6             |
| 12-8 to 12-9                                    | Visual Basic applications, 3-3 to 3-5       |
| Trigger event, VISA control, 9-14 to 9-15       | Visual C++ applications, 4-4 to 4-5         |
| triggering instruments, with GPIB control, 8-9  | User Interface controls.                    |
| tutorials                                       | Button control, 6-12 to 6-13                |
| AI control, 7-14 to 7-18                        | events, 6-13                                |
| AIPoint control, 7-14 to 7-18                   | controls and associated styles (table), 6-2 |
| AOPoint control, 7-24 to 7-28                   |   |

| Graph and Button control tutorial,  | numeric edit box control, 6-7 to 6-8           |
|-------------------------------------|--|
| 6-22 to 6-25                        | events, 6-7 to 6-8                             |
| developing program code,            | object hierarchy and common objects, 6-2       |
| 6-24 to 6-25                        | overview, 1-1                                  |
| form design, 6-22 to 6-23           | questions and answers, C-4 to C-7              |
| testing the program, 6-25           | -  |
| Graph control, 6-13 to 6-21         | V  |
| Axes collection, 6-20               | V  |
| Axis object, 6-20                   | value pairs, Virtual Oscilloscope application, |
| chart methods, 6-16                 | 12-3 to 12-4                                   |
| Cursor object, 6-19                 | ValuePair object, 6-6                          |
| Cursors collection, 6-18 to 6-19    | ValuePairs collection, 6-5 to 6-6              |
| events, 6-21                        | vector and matrix algebra functions (table),   |
| Graph object, 6-14 to 6-16          | 10-5 to 10-6                                   |
| hierarchy of (figure), 6-14         | Virtual Data Logger application, 12-9 to 12-12 |
| panning and zooming, 6-21           | file input/output, 12-12                       |
| plot methods, 6-15                  | graph axes formats, 12-11 to 12-12             |
| Plot object, 6-17 to 6-18           | multiple graph axes, 12-10 to 12-11            |
| Plots collection, 6-16 to 6-18      | Virtual Oscilloscope application               |
| PlotTemplate object, 6-18           | data acquisition pretriggering, 12-3           |
| tutorial, 6-22 to 6-25              | data acquisition stop condition modes,         |
| Knob, Slide, and Numeric Edit Box   | 12-2 to 12-3                                   |
| control tutorial, 6-8 to 6-11       | user interface value pairs, 12-3 to 12-4       |
| developing program code,            | Virtual Spectrum Meter application,            |
| 6-10 to 6-11                        | 12-4 to 12-9                                   |
| form design, 6-9                    | cursors, 12-7 to 12-8                          |
| testing the program, 6-11           | DSP Analysis Library functions,                |
| Knob and Slide controls, 6-3 to 6-7 | 12-5 to 12-7                                   |
| Axis object, 6-4 to 6-5             | graph track mode, 12-8 to 12-9                 |
| events, 6-6 to 6-7                  | VISA API, 9-1 to 9-2                           |
| hierarchy of (figure), 6-3          | advantages, 9-2                                |
| Knob and Slide object, 6-3 to 6-4   | structure (figure), 9-1                        |
| Labels object, 6-5                  | VISA control, 9-1 to 9-22                      |
| Pointer object, 6-4                 | common instrument control features, 9-4        |
| Pointers collection, 6-4            | error codes (table), D-17 to D-19              |
| Statistics object, 6-6              | event handling with event queue,               |
| Ticks object, 6-5                   | 9-15 to 9-17                                   |
| tutorial, 6-8 to 6-11               | checking events, 9-16                          |
| ValuePair object, 6-6               | disabling events, 9-16 to 9-17                 |
| ValuePairs collection, 6-5 to 6-6   | discarding events, 9-16                        |
|                                     | event types, 9-14 to 9-16                      |

| events, 9-14                                  | Visual Basic applications, 3-1 to 3-12.                  |
|---|--|
| GPIB object, 9-9                              | See also Visual Basic 4.                                 |
| message-based communication,                  | automatic code completion feature, 3-11                  |
| 9-9 to 9-13                                   | building user interface, 3-3 to 3-5                      |
| asynchronous I/O, 9-10                        | default property sheet (figure), 1-11                    |
| synchronous I/O, 9-10                         | developing event handler routines,                       |
| methods, 9-9 to 9-13                          | 3-6 to 3-7   |
| object hierarchy, 9-2 to 9-3                  | development procedure, 3-1 to 3-2                        |
| overview, 1-1                                 | editing properties programmatically,                     |
| parsing, 9-5                                  | 3-4 to 3-5   |
| purpose and use, 9-2                          | instrument driver DLLs, 3-7 to 3-8                       |
| questions and answers, C-12 to C-13           | loading ComponentWorks controls into toolbox, 3-2 to 3-3 |
| RdWrt object, 9-7 to 9-8                      |  |
| register-based communication,<br>9-11 to 9-13 | Object Browser for building code, 3-8 to 3-10            |
| high-level register accesses, 9-12            | online help for learning controls, 3-12                  |
| low-level register accesses, 9-13             | pasting code into programs, 3-10 to 3-11                 |
| moving blocks of data, 9-12                   | property sheets, 3-3 to 3-4                              |
| Serial (ASRL) object, 9-8                     | questions about ComponentWorks, C-3                      |
| tutorial                                      | working with control methods, 3-5 to 3-6                 |
| message-based communication,                  | Visual C++ 4. <i>x</i> , A-4 to A-6                      |
| 9-17 to 9-19                                  | adding ComponentWorks                                    |
| register-based communication,                 | controls to toolbar, A-4 to A-5                          |
| 9-20 to 9-22                                  | building user interface and code, A-6                    |
| VISA object, 9-5 to 9-7                       | creating the application, A-4                            |
| VXI object, 9-9                               | Visual C++ applications, 4-1 to 4-10. See also           |
| VISA object, 9-5 to 9-7                       | Visual C++ 4. <i>x</i> .                                 |
| VISA Property Pages                           | adding ComponentWorks                                    |
| General Page (figure), 9-6                    | controls to toolbar, 4-4                                 |
| RdWrt Page (figure), 9-7                      | building user interface, 4-4 to 4-5                      |
| Serial Page (figure), 9-8                     | creating applications, 4-1 to 4-3                        |
| VxiMemory Page (figure), 9-11                 | events, 4-9 to 4-10                                      |
| Visual Basic 4, A-1 to A-3                    | methods, 4-8 to 4-9                                      |
| code completing lacking, A-3                  | online help for learning controls, 4-10                  |
| creating default ComponentWorks project, A-3  | programming with ComponentWorks controls, 4-5 to 4-6     |
| menus and commands, A-1 to A-2                | properties, 4-6 to 4-8                                   |
| Object Browser, A-2 to A-3                    | VXI object, 9-9  |
| Object Browser, A-2 to A-3                    | VxiSignalProc event, VISA control, 9-15                  |
|   | VxiVmeInterrupt event, VISA control, 9-15                |
|   |  |

## W

```
WaitOnEvent method, 9-16
warning events, 12-15 to 12-16
watch window, 12-18
waveform analog input. See AI control.
waveform analog output. See AO control.
waveform digital input, buffered. See
  DI control.
waveform tutorial, DataSocket control,
  11-6 to 11-9
Web site support for ComponentWorks, 2-7
windows functions (table), 10-11
Write method
    AO control, 7-21
    synchronous I/O, message-based
      communication, 9-10
    UpdateClock object, 7-40, 7-41
WriteAsynch method, 9-10
writing data to data target, DataSocket control,
  11-9 to 11-10
```

## Z

zooming graphs, 6-21