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The LabWindows/CVI Standard Libraries Reference Manual contains information about the LabWindows/CVI standard libraries: the Graphics Library, the Analysis Library, the Formatting and I/O Library, the GPIB Library, the GPIB-488.2 Library, the RS-232 Library, the Utility Library, and the system libraries. The LabWindows/CVI Standard Libraries Reference Manual is intended for LabWindows/CVI users who have already completed the Getting Started with LabWindows/CVI tutorial and are familiar with the LabWindows/CVI User Manual. To use this manual effectively, you should be familiar with LabWindows/CVI and Windows fundamentals.

Organization of This Manual

The *LabWindows/CVI Standard Libraries Reference Manual* is organized as follows:

- Chapter 1, *ANSI C Library*, describes the ANSI C Standard Library as implemented in LabWindows/CVI.
- Chapter 2, *Formatting and I/O Library*, describes the functions in the LabWindows/CVI Formatting and I/O Library and contains many examples of how to use them. The *Formatting and I/O Library Function Overview* section contains general information about the Formatting and I/O Library functions and panels. The *Formatting and I/O Library Function Reference* section contains an alphabetical list of the function descriptions.
- Chapter 3, *Analysis Library*, describes the functions in the LabWindows/CVI Analysis Library. The *Analysis Library Function Overview* section contains general information about the Analysis Library functions and panels. The *Analysis Library Function Reference* section contains an alphabetical list of the function descriptions.
- Chapter 4, *GPIB/GPIB-488.2 Library*, describes the functions in the LabWindows/CVI GPIB Library. The *GPIB Library Function Overview* section contains general information about the GPIB Library functions and panels, the GPIB DLL, and guidelines and restrictions you should know when using the GPIB Library. The *GPIB Function Reference* section contains an alphabetical list of descriptions for the Device Manager functions, the callback installation functions, and the functions for returning the thread-specific status variables. Refer to

your NI-488.2 or NI-488.2M function reference for detailed descriptions of the NI-488 and NI-488.2 functions.

- Chapter 5, *RS-232 Library*, describes the functions in the LabWindows/CVI RS-232 Library. The *RS-232 Library Function Overview* section contains general information about the RS-232 Library functions and panels. The *RS-232 Library Function Reference* section contains an alphabetical list of function descriptions.
- Chapter 6, *DDE Library*, describes the functions in the LabWindows/CVI DDE (Dynamic Data Exchange) Library. The *DDE Library Function Overview* section contains general information about the DDE Library functions and panels. The *DDE Library Function Reference* section contains an alphabetical list of function descriptions. This library is available for LabWindows/CVI for Windows only.
- Chapter 7, *TCP Library*, describes the functions in the LabWindows/CVI TCP (Transmission Control Protocol) Library. The *TCP Library Function Overview* section contains general information about the TCP Library functions and panels. The *TCP Library Function Reference* section contains an alphabetical list of function descriptions.
- Chapter 8, *Utility Library*, describes the functions in the LabWindows/CVI Utility Library. The Utility Library contains functions that do not fit into any of the other LabWindows/CVI libraries. The *Utility Library Function Overview* section contains general information about the Utility Library functions and panels. The *Utility Library Function Reference* section contains an alphabetical list of function descriptions.
- Chapter 9, *X Property Library*, describes the functions in the Lab/Windows CVI X Property Library. The X Property Library contains functions that read and write properties to and from X Windows. The *X Property Library Overview* section contains general information about the X Property Library functions and panels. The *X Property Library Function Reference* section contains an alphabetical list of function descriptions.
- Chapter 10, *Easy I/O for DAQ Library*, describes the functions in the Easy I/O for DAQ Library. The *Easy I/O for DAQ Library Function Overview* section contains general information about the functions and guidelines and restrictions you should know when using the Easy I/O for DAQ Library. The *Easy I/O for DAQ Function Reference* section contains an alphabetical list of function descriptions.
- Chapter 11, *ActiveX Automation Library*, describes the functions in the ActiveX Automation Library. The *ActiveX Automation Library*

Function Overview section contains general information about the functions as well as guidelines and restrictions you should know when using the ActiveX Automation Library. The *ActiveX Automation Library Function Reference* section contains an alphabetical list of function descriptions.

- Appendix A, *Customer Communication*, contains forms you can use to request help from National Instruments or to comment on our products and manuals.
- The *Glossary* contains an alphabetical list and description of terms used in this manual, including abbreviations, acronyms, metric prefixes, mnemonics, and symbols.
- The *Index* contains an alphabetical list of key terms and topics in this manual, including the page where you can find each one.

Conventions Used in This Manual

	The following conventions are used in this manual:
<>	Angle brackets enclose the name of a key on the keyboard—for example, <shift>.</shift>
-	A hyphen between two or more key names enclosed in angle brackets denotes that you should simultaneously press the named keys—for example, <control-alt-delete>.</control-alt-delete>
»	The » symbol leads you through nested menu items and dialog box options to a final action. The sequence File » Page Setup » Options » Substitute Fonts directs you to pull down the File menu, select the Page Setup item, select Options , and finally select the Substitute Fonts options from the last dialog box.
	This icon to the left of bold italicized text denotes a note, which alerts you to important information.
\triangle	This icon to the left of bold italicized text denotes a caution, which advises you of precautions to take to avoid injury, data loss, or a system crash.
bold	Bold text denotes the names of menus, menu items, parameters, or dialog box buttons.
bold italic	Bold italic text denotes a note or caution.

italic	Italic text denotes variables, emphasis, a cross reference, or an introduction to a key concept. This font also denotes text from which you supply the appropriate word or value.
monospace	Text in this font denotes text or characters that you should enter from the keyboard, sections of code, programming examples, and syntax examples. This font is also used for the proper names of disk drives, paths, directories, programs, subprograms, subroutines, functions, filenames and extensions, and for statements and comments taken from programs.
monospace italic	Italic text in this font denotes that you must enter the appropriate words or values in the place of these items.
paths	Paths in this manual are denoted using backslashes (\) to separate drive names, directories, folders, and files.
	IEEE 488 and IEEE 488.2 refer to the ANSI/IEEE Standard 488.1-1987 and the ANSI/IEEE Standard 488.2-1992, respectively, which define the GPIB.

LabWindows/CVI Documentation Set

For a detailed discussion of the best way to use the LabWindows/CVI documentation set, refer to the section *Using the LabWindows/CVI Documentation Set* in Chapter 1, *Introduction to LabWindows/CVI* of *Getting Started with LabWindows/CVI*.

Related Documentation

The following documents contain information that you might find helpful as you read this manual:

- ANSI/IEEE Standard 488.1-1987, *IEEE Standard Digital Interface* for Programmable Instrumentation.
- ANSI/IEEE Standard 488.2-1992, IEEE Standard Codes, Formats, Protocols, and Common Commands.
- Harbison, Samuel P., and Guy L. Steele, Jr., *C: A Reference Manual*, Englewood Cliffs, NJ: Prentice-Hall, Inc., 1995.

- Nye, Adrian. *Xlib Programming Manual*. Sebastopol, CA: O'Reilly & Associates, 1994.
- Gettys, James, and Robert W. Scheifler. *Xlib—C Language X Interface, MIT X Consortium Standard*. Cambridge, MA: X Consortium, 1994.

Customer Communication

National Instruments wants to receive your comments on our products and manuals. We are interested in the applications you develop with our products, and we want to help if you have problems with them. To make it easy for you to contact us, this manual contains comment and configuration forms for you to complete. These forms are in the appendix, *Customer Communication*, at the end of this manual.

ANSI C Library

This chapter describes the ANSI C Standard Library as implemented in LabWindows/CVI, as shown in Table 1-1.

Note Note

When you link your executable or DLL with an external compiler, you are using the ANSI C library of the external compiler.

Class	Header File
Character Handling Character Testing Character Case Mapping	<ctype.h></ctype.h>
Date and Time Time Operations Time Conversion Time Formatting	<time.h></time.h>
Localization	<locale.h></locale.h>
Mathematics Trigonometric Functions Hyperbolic Functions Exp and Log Functions Power Functions	<math.h></math.h>
Nonlocal Jumping	<setjmp.h></setjmp.h>
Signal Handling	<signal.h></signal.h>

Table 1-1. ANSI C Standard Library Classes

Class	Header File
Input/Output Open/Close Read/Write/Flush Line Input/Output Character Input/Output Formatted Input/Output Buffer Control File Positioning File System Operations Error Handling	<stdio.h></stdio.h>
General Utilities String to Arithmetic Expression Random Number Generation Memory Management Searching and Sorting Integer Arithmetic Multibyte Character Sets Program Termination Environment	<stdlib.h></stdlib.h>
String Handling Byte Operations String Operations String Searching Collation Functions Miscellaneous	<string.h></string.h>
Low-Level I/O	<lowlvlio.h></lowlvlio.h>

 Table 1-1.
 ANSI C Standard Library Classes (Continued)

Low-Level I/O Functions

Under UNIX, you can use the low-level I/O functions such as open, sopen, read, and write from the system library by including system header files in your program. Under Windows, you can use these functions by including cvi\include\ansi\lowlvlio.h in your program. LabWindows/CVI provides function panels for these functions.

Standard Language Additions

LabWindows/CVI does not support extended character sets that require more than 8 bits per character. As a result, the wide character type wchar_t is identical to the single-byte char type. LabWindows/CVI accepts wide character constants that you specify with the L prefix (as in L'ab'), but only the first character is significant. Furthermore, library functions that use the wchar_t type operate only on 8-bit characters.

LabWindows/CVI supports variable argument functions using the ANSI C macros, with one exception: None of the unspecified arguments can have a struct type. As a result, you should never use the macro va_arg (ap, type) when type is a structure.

LabWindows/CVI does not warn you about this error.

Under UNIX, LabWindows/CVI implements only the C locale as defined by the ANSI C standard. The native locale, which is specified by the empty string, "", is also the C locale. Table 1-2 shows the locale information values for the C locale.

Name	Туре	C locale Value	Description
decimal_point	char *	"."	Decimal point character for non-monetary values.
thousands_sep	char *		Non-monetary digit group separator character or characters.
grouping	char *		Non-monetary digit groupings.
int_curr_symbol	char *	""	Three-character international currency symbol, plus the character to separate the international symbol from the monetary quantity.
currency_symbol	char *	""	Local currency symbol for the current locale.
mon_decimal_point	char *	""	Decimal point character for monetary values.
mon_thousands_sep	char *	" "	Monetary digit group separator character or characters.

		C locale	
Name	Туре	Value	Description
mon_grouping	char *		Monetary digit groupings.
positive_sign	char *	F	Sign character or characters for non-negative monetary quantities.
negative_sign	char *		Sign character or characters for negative monetary quantities.
int_frac_digits	char	CHAR_MAX	Digits appear to the right of the decimal point for international monetary formats.
frac_digits	char	CHAR_MAX	Digits appear to the right of the decimal point for formats other than international monetary formats.
p_cs_precedes	char	CHAR_MAX	1 if currency_symbol precedes non-negative monetary values; 0 if it follows.
p_sep_by_space	char	CHAR_MAX	1 if a space separates currency_symbol from non-negative monetary values; 0 otherwise.
n_cs_precedes	char	CHAR_MAX	Like p_cs_precedes, for negative values.
n_sep_by_space	char	CHAR_MAX	Like p_sep_by_space, for negative values.
p_sign_posn	char	CHAR_MAX	Positioning of positive_sign for a non-negative monetary quantity, then its currency_symbol.
n_sign_posn	char	CHAR_MAX	Positioning of negative_sign for a negative monetary quantity, then its currency_symbol.

 Table 1-2.
 C Locale Information Values (Continued)

Under Windows, LabWindows/CVI implements the default locale by using the appropriate system settings. Under Windows 95/NT, you can access the system settings by using the Regional Settings applet in the Control Panel. Under Windows 3.1, use the International applet in the Control Panel. Anything not mentioned in this section behaves the same under the default locale as specified in the C locale.

For the LC_NUMERIC locale:

- decimal_point maps to the value of sDecimal.
- thousands_sep maps to the value of sThousand.

For the LC_MONETARY locale:

- currency_symbol maps to the value of sCurrency.
- mon_decimal_point maps to the value of sDecimal.
- mon_thousands_sep maps to the value of sThousand.
- frac_digits maps to the value of iCurrDigits.
- int_frac_digits maps to the value of iCurrDigits.
- LabWindows/CVI sets p_cs_precedes and n_cs_precedes to 1 if iCurrency equals 0 or 2, otherwise it sets them to 0.
- LabWindows/CVI sets p_sep_by_space and n_sep_by_space to 0 if iCurrency equals 0 or 1, otherwise they are set to 0.
- iNegCurr determines the value of p_sign_posn and n_sign_posn as shown in Table 1-3.

Value of iNegCurr	Value of p_sign_posn and n_sign_posn	
0, 4	0	
1, 5, 8, 9	1	
3, 7, 10	2	
6	3	
2	4	

 Table 1-3.
 p_sign_posn and n_sign_posn Values

For the LC_CTYPE locale:

- isalnum maps to the Windows function isCharAlphaNumeric.
- isalpha maps to the Windows function isCharAlpha.
- islower maps to the Windows function isCharLower.

- isupper maps to the Windows function isCharUpper.
- tolower maps to the Windows function AnsiLower.
- toupper maps to the Windows function AnsiUpper.

For the LC_TIME locale:

- strftime uses the following items from the win.ini file for the appropriate format specifiers: sTime, iTime, s1159, s2359, iTLZero, sShortDate, and sLongDate.
- The names of the weekdays and the names of the months match the language version of LabWindows/CVI.

For the LC_COLLATE locale, strcoll maps to the Windows function lstrcmp.

Because LabWindows/CVI does not support extended character sets that require more than one byte per character, a multibyte character in LabWindows/CVI is actually a single-byte character. Likewise, a multibyte sequence is a sequence of single-byte characters. Because a multibyte character is the same as a wide character, the multibyte conversion functions do little more than return their inputs as outputs.

Character Processing

LabWindows/CVI implements all the ANSI C character processing facilities as both macros and functions. When you run a program in LabWindows/CVI with the debugging level set to Standard or Extended, LabWindows/CVI uses the function versions of the character processing facilities. By using the function versions, LabWindows/CVI can perform run-time user protection on the arguments you pass to the functions.

String Processing

Under UNIX, strcoll is equivalent to strcmp, and the LC_COLLATE locale does not affect its behavior. Under Windows, strcoll is equivalent to the Windows function lstrcmp. For both platforms, strxfrm performs a string copy using strncpy and returns the length of its second argument.

Input/Output Facilities

rename fails if the target file already exists. Under Windows, rename fails if the source and target files are on different disk drives. Under UNIX, rename fails if the source and target files are on different file systems.

```
fgetpos and ftell set errno to EFILPOS on error.
```

File I/O Functions Set errno

The ANSI C file I/O functions and the low-level I/O functions set the errno global variable to indicate specific error conditions. The possible values of errno are declared in cvi\include\ansi\errno.h. A base set of values exists that is common to all platforms, and additional values are specific to particular platforms.

Under Windows 3.1, errno gives very limited information. LabWindows/CVI sets errno to E10 if the operating system returns an error.

Under Windows 95/NT, you can call the Windows SDK GetLastError function to obtain system specific information when LabWindows/CVI sets errno to one of the following values:

EACCES EBADF EIO ENOENT ENOSPC

Mathematical Functions

The macro HUGE_VAL defined in the header math.h and the macros FLT_EPSILON, FLT_MAX, FLT_MIN, DBL_EPSILON, DBL_MAX, DBL_MIN, LDBL_EPSILON, LDBL_MAX, and DBL_MIN defined in the header float.h all refer to variables. Consequently, you cannot use these macros in places where constant expressions are required, such as in global initializations.

Time and Date Functions

time returns the number of seconds since Jan. 1, 1990.

mktime and localtime require time zone information to produce correct results. LabWindows/CVI obtains time zone information from the environment variable TZ, if it exists. The value of this variable should have the format AAA[S]HH[:MM]BBB, where optional items are in square brackets.

The AAA and BBB fields specify the names of the standard and daylight savings time (DST) zones, respectively, such as EST for Eastern Standard Time and EDT for Eastern Daylight Time. The optional sign field s indicates whether the local time zone is to the west (+) or to the east (-) of UTC (Greenwich Mean Time). The hour field HH and the optional minutes field :MM specify the number of hours and minutes from UTC. For example, the string EST05EDT specifies the time zone information for the eastern part of the United States.

Configuring the DST Rules String

gmtime, localtime, and mktime make corrections for daylight savings time. By default the DST rules string in cvi\bin\cvimsgs.txt specifies the rules to determine when daylight savings time begins and ends. LabWindows/CVI does, however, honor the Windows 95/NT time zone information when it indicates that your region does not observe daylight savings time. You can override both the DST rules string in cvimsgs.txt and the Windows 95/NT time zone information by entering a modified DST rules string in the LabWindows/CVI configuration options.

In general, a DST rules string contains one or more rules, each beginning with a colon followed by a year in parentheses. The year indicates the first year to which the rule applies. You must put the rules for the more recent years first.

The following is the default value of the DST rules string:

": (1986)040102+0:110102-0: (1967)040102-0:110102-0"

The default string contains two rules. The first rule applies to years 1986 and later. The second rule applies to years 1967 to 1985.

Each rule consists of a set of descriptors that indicate when to switch between standard and daylight savings time. LabWindows/CVI assumes each year begins in standard time. Each descriptor follows the format MMDDHH+/-Wd. The MM portion identifies a month, where 01 indicates January. The DD portion indicates the day of the month. The month and day together serve as a reference point for the latter portion of the descriptor. The Wd portion is a day of the week, with 0 indicating Sunday, 1 indicating Monday, and so on. The minus sign (-) or plus sign (+) indicates whether the day of the week is the one before (-) or after (+) the month and day the MMDD portion describes. The HH portion indicates the hour of the day. Thus, 040102+0 indicates the first Sunday in April, and 110102-0 indicates the last Sunday in October.

The default DST rules string states that for the years from 1986 to the present, DST begins at 2 a.m. on the first Sunday in April and ends at 2 a.m. on the last Sunday in October. For the years from 1967 to 1985, DST began at 2 a.m. on the last Sunday in March, and ended at 2 a.m. on the last Sunday in October.

Modifying the DST Rules String

If you want to make a change to the DST rules string, you can add an entry to the configuration options for LabWindows/CVI. Set the entry name to DSTRules and set the entry value to the modified DST rules string.

For instructions on how to set configuration options for the LabWindows/CVI development environment, refer to the *How to Set the Configuration Options* section in Chapter 1, *Configuring LabWindows/CVI*, of the *LabWindows/CVI User Manual*. For instructions on how to set configuration options for the LabWindows/CVI Run-time Engine, refer to the Configuring the Run-Time Engine section in Chapter 7, Creating and Distributing Standalone Executables and DLLs, of the LabWindows/CVI Programmer Reference Manual.

LabWindows/CVI does not honor the DST rules string in the configuration options of executables or DLLs you build by selecting **Build**»**Instrument Driver Support Only** in the Project window. The instrument driver support run-time library does not contain code to read the LabWindows/CVI configuration options. To modify the DST rules string, you must do so in msgrtn.txt. Refer to the *Configuring the Run-Time Engine* section in Chapter 7, *Creating and Distributing Standalone Executables and DLLs*, of the *LabWindows/CVI Programmer Reference Manual*.

Suppressing Daylight Savings Time

You can suppress daylight savings time by modifying the DST rules string to the following:

```
":(1990)010102+0:010102-0"
```

Starting Year in Daylight Savings Time

If you start the year in daylight savings time, use the following as the first descriptor in the rule:

"010100-0"

Control Functions

The assert macro that LabWindows/CVI defines does not print diagnostics to the standard error stream when the debugging level is anything other than None. Instead, when the value of its argument evaluates to zero, LabWindows/CVI displays a dialog box with a message that contains the file name, line number, and expression that caused the assert to fail.

Under UNIX, system passes the specified command to the Bourne shell (sh) as input, as if the current process were performing a wait (2V) system call to wait until the shell terminated. LabWindows/CVI does not invoke callbacks while the command executes.

Under Windows, the executable can be an MS-DOS or Windows executable, including *.exe, *.com, *.bat, and *.pif files. The function does not return until the command terminates. The LabWindows/CVI runtime engine ignores user keyboard and mouse events until the command exits. Callbacks for asynchronous events, such as idle events, Windows messages, VXI interrupts, PostDeferredCall calls, and DAQ events are called while the command is executing.

If you need to execute a command built into command.com, such as copy, dir, and others, you can call system with the command command.com /C DosCommand args, where DosCommand is the shell command you want to execute. Refer to your DOS documentation

for more help with command.com. DOS executables (.exe, .com, and .bat files) use the settings in _default.pif in your Windows directory when they run. You can change the priority, display options, and more by editing _default.pif or by creating another .pif file. Refer to your Microsoft Windows documentation for help on creating and editing .pif files.

If you pass a NULL pointer to the system function, LabWindows/CVI returns a nonzero value only if a command processor is available. Under UNIX, if the argument is not a NULL pointer, the program returns a zero. Under Windows, if the argument is not a NULL pointer, the program returns zero if the program was successfully started; otherwise it returns one of the error codes in Table 1-4.

Error Code	Description
-1	System was out of memory, executable file was corrupt, or relocations were invalid.
-3	File was not found.
-4	Path was not found.
-6	Attempt was made to dynamically link to a task, or there was a sharing or network protection error occurred.
-7	Library required separate data segments for each task.
-9	There was insufficient memory to start the application.
-11	Windows version was incorrect.
-12	Executable file was invalid. Either it was not a Windows application or the .exe image contained an error.
-13	Application was designed for a different operating system.
-14	Application was designed for MS-DOS 4.0.
-15	Type of executable file was unknown.
-16	Attempt made to load a real-mode application developed for an earlier Windows version.
-17	Attempt was made to load a second instance of an executable file containing multiple data segments that were not marked read only.
-20	Attempt was made to load a compressed executable file. You must decompress the file before you can load it.

Table 1-4. Error Codes for the system Function under Windows

Error Code	Description
-21	Dynamic-link library (DLL) file was invalid. One of the DLLs required to run this application was corrupt.
-22	Application requires Windows 32-bit extensions.
-23	Could not find toolhelp.dll, or toolhelp.dll is corrupted.
-24	Could not allocate a GetProcUserDefinedHandle.

 Table 1-4.
 Error Codes for the system Function under Windows

The LabWindows/CVI environment does not use the argument you pass to exit. Under UNIX, standalone executables that LabWindows/CVI creates return the value of the argument you pass to exit.

The UNIX version of LabWindows/CVI works with all the ANSI C signals and the signals UNIX supports.

ANSI C Library Function Reference

For ANSI C function descriptions, consult a reference work such as *C: A Reference Manual*, which is listed in the *Related Documentation* section of *About This Manual*. Also, you can use LabWindows/CVI function panel help. The following function description is an extension of the ANSI C function set.

fdopen

FILE *fp = fdopen (int fileHandle, char *mode);

Only the Windows version of LabWindows/CVI supports fdopen.

Purpose

Creates a buffered I/O stream from a file handle, and returns a pointer to the stream. You can use the return value just as if you had obtained it from fopen.

You can obtain a file handle from one of the following functions:

open (low-level I/O) sopen (low-level I/O)

Parameters

Input

Name	Туре	Description
fileHandle	integer	File handle that open or sopen returns.
mode	string	Specifies the read/write, binary/text, and append modes.

Return Value

Name	Туре	Description
fp	FILE *	Pointer to a buffered I/O file stream.

Return Code

Code	Description
NULL (0)	Failure. More specific information is in errno.

Parameter Discussion

mode is the same as the mode parameter to fopen.

You should use a **mode** value that is consistent with the mode in which you originally opened the file. If you use write capabilities that were not enabled when the file handle was originally opened, the call to fdopen succeeds, but any attempt to write fails. For instance, if you originally opened the file for reading only, you can pass "rw" to fdopen, but any call to fwrite fails.

2

Formatting and I/O Library

This chapter describes the functions in the LabWindows/CVI Formatting and I/O Library and contains many examples of how to use them. The Formatting and I/O Library contains functions that input and output data to files and manipulate the format of data in a program.

The *Formatting and I/O Library Function Overview* section contains general information about the Formatting and I/O Library functions and panels. Because the Formatting and I/O Library differs in many respects from the other LabWindows/CVI libraries, it is very important to read the overview before you read the other sections of this chapter.

The *Formatting and I/O Library Function Reference* section contains an alphabetical list of function descriptions. This section can help you determine the syntax of the file I/O and string manipulation functions.

The *Using the Formatting and Scanning Functions* section describes in detail this special class of functions. Although the function reference section lists these functions, their versatility and complex nature require a more complete discussion.

The final section, *Formatting and I/O Library Programming Examples*, contains many examples of program code that call Formatting and I/O Library functions. Most of the examples use the formatting and scanning functions.

Formatting and I/O Library Function Overview

This section contains general information necessary for understanding the Formatting and I/O Library functions and panels.

Formatting and I/O Library Function Panels

The Formatting and I/O Library function panels are grouped in the tree structure in Table 2-1 according to the types of operations they perform.

The first- and second-level headings in the tree are the names of function classes and subclasses. Function classes and subclasses are groups of related function panels. The third-level headings are the names of individual function panels. Refer to the *Formatting and I/O Library Function Reference* section later in this chapter for more information.

Class/Panel Name	Function Name
File I/O	Function Ivanic
Open File	OpenFile
Close File	CloseFile
Read from File	ReadFile
Write to File	WriteFile
Array to File	ArrayToFile
File to Array	FileToArray
Get File Information	GetFileInfo
Set File Pointer	SetFilePtr
String Manipulation	5001110101
Get String Length	StringLength
String to Lowercase	StringLowerCase
String to Uppercase	StringUpperCase
Fill Bytes	FillBytes
Copy Bytes	CopyBytes
Copy String	CopyString
Compare Bytes	CompareBytes
Compare Strings	CompareStrings
Find Pattern	FindPattern
Read Line	ReadLine
Write Line	WriteLine
Data Formatting	
Formatting Functions	
Fmt to Memory (Sample Panel)	Fmt
Fmt to File (Sample Panel)	FmtFile
Fmt to Stdout (Sample Panel)	FmtOut
Scanning Functions	2
Scan from Mem (Sample Panel)	Scan
Scan from File (Sample Panel)	ScanFile
Scan from Stdin (Sample Panel)	ScanIn
Status Functions	
Get # Formatted Bytes	NumFmtdBytes
Get Format Index Error	GetFmtErrNdx
Get I/O Error	GetFmtIOError
Get I/O Error String	GetFmtIOErrorString
e	5

Table 2-1. Functions in the Formatting and I/O Library Function Tree

Class and Subclass Descriptions

- The File I/O function panels open, close, read, write, and obtain information about files.
- The String Manipulation function panels manipulate strings and character buffers.
- The Data Formatting function panels perform intricate formatting operations with a single function call.
 - Formatting Functions, a subclass of Data Formatting, contains function panels that combine and format one or more source items into a single target item.
 - Scanning Functions, a subclass of Data Formatting, contains function panels that transform a single source item into several target items.
 - Status Functions, a subclass of Data Formatting, contains function panels that return information about the success or failure of a formatting or scanning call.

The online help for each panel contains specific information about operating each function panel.

String Manipulation Functions

The functions in the String Manipulation class perform common operations such as copying one string to another, comparing two strings, or finding the occurrence of a string in a character buffer. These functions are similar in purpose to the standard C string functions.

Special Nature of the Formatting and Scanning Functions

The formatting and scanning functions are different in nature from the other functions in the LabWindows/CVI libraries. With few exceptions, each LabWindows/CVI library function has a fixed number of parameters, and each parameter has a definite data type. Each formatting and scanning function, however, takes a variable number of parameters, and the parameters can be of various data types. This difference is necessary to give the formatting and scanning functions versatility.

For instance, a single Scan function call performs disparate operations, such as the following:

- Find the two numeric values in the string "header: 45, -1.03e-2" and place the first value in an integer variable and the second value in a real variable.
- Take the elements from an integer array, swap the high and low bytes in each element, and place the resulting values in a real array.

To perform these operations, each formatting and scanning function takes a *format string* as one of its parameters. In effect, a format string is a mini-program that tells the formatting and scanning functions how to transform the input arguments to the output arguments. For conciseness, format strings are constructed using single-character codes. The *Using the Formatting and Scanning Functions* section later in this chapter describes these codes in detail.

You might find the formatting and scanning functions more difficult to learn than other LabWindows/CVI functions. To help you in this learning process, read the discussions in the *Formatting and I/O Library Programming Examples* section at the end of this chapter.

Formatting and I/O Library Function Reference

This section describes each function in the LabWindows/CVI Formatting and I/O Library in alphabetical order.

ArrayToFile

Purpose

Saves an array to a file using various formatting options. The function handles creating, opening, writing, and closing the file. You can use FileToArray to read back the file into an array.

Parameters

Input

Name	Туре	Description
fileName	string	File pathname.
array	void *	Numeric array.
dataType	integer	Array element data type.
numberOfElements	integer	Number of elements in the array.
numberOfGroups	integer	Number of groups in the array.
arrayDataOrder	integer	How to order groups in the file.
fileLayout	integer	Direction to write groups in the file.
colSepStyle	integer	How to separate data on one line.
fieldWidth	integer	Constant width between columns.
fileType	integer	ASCII/binary mode.
fileAction	integer	File pointer reposition location.

Return Value

Name	Туре	Description
status	integer	Indicates success/failure.

Return Codes

Code	Description
0	Success.
-1	Error attempting to open file.
-2	Error attempting to close file.
-3	An I/O error occurred.
-4	Invalid dataType parameter.
-5	Invalid numberOfElements parameter.
-6	Invalid numberOfGroups parameter.
-7	Invalid arrayDataOrder parameter.
-8	Invalid fileLayout parameter.
-9	Invalid fileType parameter.
-10	Invalid colSepStyle parameter.
-11	Invalid fieldWidth parameter.
-12	Invalid fileAction parameter.

Parameter Discussion

fileName can be an absolute pathname or a relative file name. If you use a relative file name, ArrayToFile creates the file relative to the current working directory.

dataType must be one of the following:

- VAL_CHAR
- VAL_SHORT_INTEGER
- VAL_INTEGER
- VAL_FLOAT
- VAL_DOUBLE
- VAL_UNSIGNED_SHORT_INTEGER
- VAL_UNSIGNED_INTEGER
- VAL_UNSIGNED_CHAR

If you save the array data in ASCII format, you can divide the array data into groups. ArrayToFile can write groups as columns or rows. **numberOfGroups** specifies the number of groups into which to divide the array data. If you do not want to divide your data into groups, use 1.

If you divide your array data into groups, **arrayDataOrder** specifies how the data is ordered in the array. The two choices are as follows:

- VAL_GROUPS_TOGETHER—ArrayToFile assumes that the elements of each data group are stored consecutively in the data array.
- VAL_DATA_MULTIPLEXED—ArrayToFile assumes that the first elements of all data group are stored together, followed by the second elements and so on.

If you save the array data in ASCII format, **fileLayout** specifies how the data appears in the file. The two choices are as follows.

- VAL_GROUPS_AS_COLUMNS
- VAL_GROUPS_AS_ROWS

If you have only one group, use VAL_GROUPS_AS_COLUMNS to write each array element on a separate line.

If you tell ArrayToFile to write multiple values on each line, **colSepStyle** specifies how to separate the values. The choices are as follows:

- VAL_CONST_WIDTH—constant field width for each column
- VAL_SEP_BY_COMMA—values followed by commas, except last value on line
- VAL_SEP_BY_TAB—values separated by tabs

If you specify a **colSepStyle** of VAL_CONST_WIDTH, **fieldWidth** specifies the width of the columns.

fileType specifies whether to create the file in ASCII or binary format. The choices are as follows:

- VAL_ASCII
- VAL_BINARY

fileAction specifies the location in the file to begin writing data if the named file already exists. The choices are as follows:

- VAL_TRUNCATE—Positions the file pointer to the beginning of the file and deletes its prior contents.
- VAL_APPEND—All write operations append data to file.
- VAL_OPEN_AS_IS—Positions the file pointer at the beginning of the file but does not affect the prior file contents.

CloseFile

```
int status = CloseFile (int fileHandle);
```

Purpose

Closes the file associated with **fileHandle**. You can obtain a file handle by calling OpenFile.

Parameter

Input

Name	Туре	Description
fileHandle	integer	File handle.

Return Value

Name	Туре	Description
status	integer	Result of the close file operation.

Return Codes

Code	Description
-1	Bad file handle.
0	Success.

CompareBytes

Purpose

Compares the **numberOfBytes** that start at position **buffer#1Index** of **buffer#1** to the **numberOfBytes** that start at position **buffer#2Index** of **buffer#2**.

Parameters

Input

Name	Туре	Description
buffer#1	string	String 1.
buffer#1Index	integer	Starting position in buffer#1 .
buffer#2	string	String 2.
buffer#2Index	integer	Starting position in buffer#2 .
numberOfBytes	integer	Number of bytes to compare.
caseSensitive	integer	Case-sensitivity mode.

Return Value

Name	Туре	Description
result	integer	Result of the compare operation.

Return Codes

Code	Description
-1	Bytes from buffer#1 less than bytes from buffer#2 .
0	Bytes from buffer#1 identical to bytes from buffer#2 .
1	Bytes from buffer#1 greater than bytes from buffer#2 .

Parameter Discussion

buffer#1Index and buffer#2Index are zero-based.

If **caseSensitive** is zero, CompareBytes compares alphabetic characters without regard to case. If **caseSensitive** is non-zero, CompareBytes considers alphabetic characters equal only if they have the same case.

The function returns an integer value that indicates the lexicographic relationship between the two sets of bytes.

CompareStrings

Purpose

Compares the null-terminated string that starts at position **string#1Index** of **string#1** to the null-terminated string that starts at position **string#2Index** of **string#2.string#1Index** and **string#2Index** are zero-based.

Parameters

Input

Name	Туре	Description
string#1	string	String 1.
string#1Index	integer	Starting position in string#1 .
string#2	string	String 2.
string#2Index	integer	Starting position in string#2 .
caseSensitive	integer	Case-sensitivity mode.

Return Value

Name	Туре	Description
result	integer	Result of the compare operation.

Return Code

Code	Description
-1	Bytes from string#1 less than bytes from string#2 .
0	Bytes from string#1 identical to bytes from string#2 .
1	Bytes from string#1 greater than bytes from string#2 .

Parameter Discussion

If **caseSensitive** is zero, CompareStrings compares alphabetic characters without regard to case. If **caseSensitive** is non-zero, CompareStrings considers alphabetic characters equal only if they have the same case.

The function returns an integer value that indicates the lexicographic relationship between the two strings.

CopyBytes

Purpose

Copies the **numberOfBytes** bytes that start at position **sourceIndex** of **sourceBuffer** to position **targetIndex** of **targetBuffer**.

Parameters

Input

Name	Туре	Description
targetIndex	integer	Starting position in targetBuffer .
sourceBuffer	string	Source buffer.
sourceIndex	integer	Starting position in sourceBuffer .
numberOfBytes	integer	Number of bytes to copy.

Output

Name	Туре	Description
targetBuffer	string	Destination buffer.

Return Value

None.

Parameter Discussion

sourceIndex and targetIndex are zero-based.

You can use CopyBytes even when sourceBuffer and targetBuffer overlap.

CopyString

Purpose

Copies the string that starts at position **sourceIndex** of **sourceString** to position **targetIndex** of **targetString**. CopyString stops copying when it encounters an ASCII NUL byte or **maximum#Bytes** bytes. CopyString appends an ASCII NUL if no ASCII NUL was copied.

Parameters

Input

Name	Туре	Description
targetIndex	integer	Starting position in targetString .
sourceString	string	Source buffer.
sourceIndex	integer	Starting position in sourceString .
maximum#Bytes	integer	Number of bytes to copy, excluding the ASCII NUL.

Output

Name	Туре	Description
targetString	string	Destination buffer.

Return Value

None.

Parameter Discussion

sourceIndex and **targetIndex** are zero-based. If you want to use **maximum#Bytes** to prevent writing beyond the end of **targetString**, make sure to allow room for the ASCII NUL. For example, if **maximum#Bytes** is 40, the destination buffer should contain at least 41 bytes.

If you do not want to specify a maximum number of bytes to copy, use -1 for **maximum#Bytes**.

You can use CopyString when sourceString and targetString overlap.

The value of maximum#Bytes must not exceed one less than the number of bytes in the target variable.

FileToArray

Purpose

Reads data from a file into an array. You can use FileToArray with files you create using the ArrayToFile function. FileToArray handles creating, opening, reading, and closing the file.

Parameters

Input

Name	Туре	Description
fileName	string	File pathname.
dataType	integer	Array element data type.
numberOfElements	integer	Number of elements in the array.
numberOfGroups	integer	Number of groups in the array.
arrayDataOrder	integer	How to order groups in the file.
fileLayout	integer	Direction to write groups in the file.
fileType	integer	ASCII/binary mode.

Output

Name	Туре	Description
array	void*	Numeric array.

Return Value

Name	Туре	Description
status	integer	Indicates success or failure.

Return Codes

Code	Description
0	Success.
-1	Error attempting to open the file.
-2	Error attempting to close the file.
-3	An I/O error occurred.
-4	Invalid dataType parameter.
-5	Invalid numberOfElements parameter.
-6	Invalid numberOfGroups parameter.
-7	Invalid arrayDataOrder parameter.
-8	Invalid fileLayout parameter.
-9	Invalid fileType parameter.

Parameter Discussion

fileName can be an absolute pathname or a relative file name. If you use a relative file name, FileToArray locates the file relative to the current working directory.

dataType must be one of the following:

- VAL_CHAR
- VAL_SHORT_INTEGER
- VAL_INTEGER
- VAL_FLOAT
- VAL_DOUBLE
- VAL_UNSIGNED_SHORT_INTEGER
- VAL_UNSIGNED_INTEGER
- VAL_UNSIGNED_CHAR

numberOfGroups specifies the number of groups into which the data in the file is divided. FileToArray can read columns or rows as groups. If you do not want to read your data as groups, use 1. This parameter applies only if the file type is ASCII.

If you divide your data into groups, **arrayDataOrder** specifies how to store the data in the array. The two choices are as follows:

- VAL_GROUPS_TOGETHER—FileToArray stores all elements from one data group followed by all elements from the next data group.
- VAL_DATA_MULTIPLEXED—FileToArray stores the first elements of all data groups consecutively, followed by the second elements from each group and so on.

If the file is in ASCII format, **fileLayout** specifies how the data appears in the file. The two choices are as follows:

- VAL_GROUPS_AS_COLUMNS
- VAL_GROUPS_AS_ROWS

If there is only one group, VAL_GROUPS_AS_COLUMNS specifies that each value in the file is on a separate line.

fileType specifies whether the file is in ASCII or binary format. The choices are as follows.

- VAL_ASCII
- VAL_BINARY

FillBytes

Purpose

Sets the **numberOfBytes** bytes that start at position **startingIndex** of **buffer** to the value in the lower byte of **value**. **startingIndex** is zero-based.

Parameters

Input

Name	Туре	Description
buffer	string	Destination buffer.
startingIndex	integer	Starting position in buffer .
numberOfBytes	integer	Number of bytes to fill.
value	integer	Value to place in bytes.

Return Value

None.

FindPattern

Purpose

Searches a character buffer for a pattern of bytes. The string **pattern** specifies the pattern of bytes.

Parameters

Input

Name	Туре	Description
buffer	string	Buffer to search.
startingIndex	integer	Starting position in buffer .
numberOfBytes	integer	Number of bytes to search.
pattern	string	Pattern to search for.
caseSensitive	integer	Case-sensitivity mode.
startFromRight	integer	Direction of search.

Return Value

Name	Туре	Description
ndx	integer	Index in buffer where FindPattern finds the pattern.

Return Code

Code	Description
-1	Pattern not found.

Parameter Discussion

The buffer searched is the set of **numberOfBytes** bytes that starts at position **startingIndex** of **buffer**. If **numberOfBytes** is -1, the buffer searched is the set of bytes that starts at position **startingIndex** of **buffer** up to the first ASCII NUL. **startingIndex** is zero-based.

If **caseSensitive** is zero, FindPattern compares alphabetic characters without regard to case. If **caseSensitive** is non-zero, FindPattern considers alphabetic characters equal only

if they have the same case. If **startFromRight** is zero, FindPattern finds the occurrence farthest to the left of the pattern in the buffer. If **startFromRight** is nonzero, FindPattern finds the occurrence farthest to the right of the pattern in the buffer.

If FindPattern finds the pattern, **pattern** returns the index *relative to the beginning of* **buffer**, where it found the first byte of the pattern. If FindPattern does not find the pattern, **pattern** returns -1.

The following example returns 4, which is the index of the second of the three occurrences of ab in the string lab2ab3ab4. FindPattern skips the first occurrence because **startingIndex** is 3. Of the two remaining occurrences, FindPattern finds the farthest to the left because **startFromRight** is zero:

```
ndx = FindPattern ("lab2ab3ab4", 3, -1, "AB", 0, 0);
```

On the other hand, the following line returns 7, which is the index of the last occurrence of ab because **startFromRight** is nonzero:

```
ndx = FindPattern ("lab2ab3ab4", 3, -1, "AB", 0, 1);
```

Fmt

int n = Fmt (void *target, char *formatString, source1,...,sourcen);

Purpose

Formats the **source1,..., sourcen** arguments according to descriptions in the **formatString** argument.

Parameters

Input

Name	Туре	Description
formatString	string	Refer to the Using the Formatting and
source1,,sourcen	Types must match formatString contents.	<i>Scanning Functions</i> section later in this chapter.

Output

Name	Туре	Description
target	Type must match formatString contents.	Refer to the <i>Using the Formatting and</i> <i>Scanning Functions</i> section later in this chapter.

Return Value

Name	Туре	Description
n	integer	Number of source format specifiers satisfied.

Return Code

Code	Description
-1	Format string error.

Using This Function

Fmt places the result of the formatting into the target argument, which you must pass by reference. The return value indicates how many source format specifiers were satisfied, or -1 if the format string is invalid. The *Using the Formatting and Scanning Functions* section later in this chapter includes a complete discussion of Fmt.

FmtFile

int n = FmtFile (int fileHandle, char *formatString, source1,...,sourcen);

Purpose

Formats the **source1**,..., **sourcen** arguments according to descriptions in the **formatString** argument. FmtFile writes the result of the formatting into the file that corresponds to the **fileHandle** argument, which you obtain by calling the LabWindows/CVI function OpenFile.

Parameters

Input

Name	Туре	Description
fileHandle	integer	File handle.
formatString	string	Refer to the <i>Using the Formatting and</i> <i>Scanning Functions</i> section later in this chapter.
source1,,sourcen	Types must match formatString contents	

Return Value

Name	Туре	Description
n	integer	Number of source format specifiers satisfied.

Return Codes

Code	Description
-1	Format string error
-2	I/O error.

Using This Function

The return value indicates how many source format specifiers were satisfied: -1 if the format string is invalid, or -2 if an I/O error occurs. The *Using the Formatting and Scanning Functions* section later in this chapter includes a complete discussion of FmtFile.

FmtOut

int n = FmtOut (char *formatString, source1,...,sourcen);

Purpose

Formats the **source1**,...,**source***n* arguments according to descriptions in the **formatString** argument. FmtOut writes the result of the formatting to the Standard I/O window.

Parameters

Input

Name	Туре	Description
formatString	string	Refer to the Using the Formatting and
source1,,sourcen	Types must match formatString contents.	<i>Scanning Functions</i> section later in this chapter.

Return Value

Name	Туре	Description
n	integer	Number of source format specifiers satisfied.

Return Codes

Code	Description
-1	Format string error.
-2	I/O error.

Using This Function

The return value indicates how many source format specifiers were satisfied: -1 if the format string is invalid, or -2 if an I/O error occurs. The *Using the Formatting and Scanning Functions* section later in this chapter includes a complete discussion of FmtOut.

GetFileInfo

int status = GetFileInfo (char *fileName, long *fileSize);

Purpose

Verifies whether a file exists. Returns an integer value of zero if no file exists and 1 if file exists. **fileSize** is a long variable that contains the file size in bytes or zero if no file exists.

Parameters

Input

Name	Туре	Description
fileName	string	Pathname of the file to check.
fileSize	long	File size or zero.

Return Value

Name	Туре	Description
status	integer	Indicates whether the file exists.

Return Codes

Code	Description	
1	File exists.	
0	File does not exist.	
-1	Maximum number of files already open.	

Example

```
/* Check for presence of file A:\DATA\TEST1.DAT.*/
/* Print its size if file exists or message that states file does not
exist. */
int n;
long size;
n = GetFileInfo("a:\\data\\test1.dat",&size);
if (n == 0)
    FmtOut("File does not exist.");
else
    FmtOut("File size = %i[b4]",size);
```

GetFmtErrNdx

```
int n = GetFmtErrNdx (void);
```

Purpose

Returns the zero-based index into the format string where an error occurred in the last formatting or scanning call.

Parameters

None.

Return Value

Name	Туре	Description
n	integer	Position of error in format string.

Return Code

Code	Description	
-1	No error.	

Using This Function

If the format string of the preceding call contains an error, such as an invalid format or an inappropriate modifier, the return value indicates the position within the format string, beginning with position zero, where the error was found. The function can report only one error per call, even if several errors exist within the string.

Example

```
int i, n;
Scan ("1234", "%s>%d", &i);
n = GetFmtErrNdx ();
/* n will have the value -1, indicating that */
/* no error exists in the format string. */
```

GetFmtIOError

```
int status = GetFmtIOError (void);
```

Purpose

This function returns specific I/O information for the last call to a Formatting and I/O function that performs file I/O. If the last function was successful, GetFmtIOError returns zero (no error). If the last function that performs I/O encountered an I/O error, GetFmtIOError returns a nonzero value.

Parameters

None.

Return Value

Name	Туре	Description
status	integer	Indicates success or failure of last function that performed file I/O.

Return Codes

String	Code	Description
FmtIONoErr	0	No error.
FmtIONoFileErr	1	File not found.
FmtIOGenErr	2	General I/O error.
FmtIOBadHandleErr	3	Invalid file handle.
FmtIOInsuffMemErr	4	Not enough memory.
FmtIOFileExistsErr	5	File already exists.
FmtIOAccessErr	6	Permission denied.
FmtIOInvalArgErr	7	Invalid argument.
FmtIOMaxFilesErr	8	Maximum number of files open.
FmtIODiskFullErr	9	Disk is full.
FmtIONameTooLongErr	10	Filename is too long.

GetFmtIOErrorString

```
char *message = GetFmtIOErrorString (int errorNum);
```

Purpose

Converts the error number GetFmtIOError returns into a meaningful error message.

Parameter

Input

Name	Туре	Description
errorNum	integer	Error code you obtain from GetFmtIOError.

Return Value

Name	Туре	Description
message	string	Explanation of error.

NumFmtdBytes

```
int n = NumFmtdBytes (void);
```

Purpose

Returns the number of bytes formatted or scanned by the previous formatting or scanning call.

Parameters

None.

Return Value

Name	Туре	Description
n	integer	Number of bytes formatted or scanned.

Using This Function

If the previous call was a formatting call, NumFmtdBytes returns the number of bytes placed into the target. If the previous call was a scanning call, NumFmtdBytes returns the number of bytes scanned from the source. The return value is undefined if there are no preceding formatting or scanning calls.

Example

```
double f; int n;
Scan ("3.1416", "%s>%f", &f);
n = NumFmtdBytes ();
/* n will have the value 6, indicating that */
/* 6 bytes were scanned from the source string. */
```

OpenFile

Purpose

Opens a file for input and/or output.

Parameters

Input

Name	Туре	Description
fileName	string	Pathname.
read/writeMode	integer	Read/write mode.
action	integer	File pointer reposition location.
fileType	integer	ASCII/binary mode.

Return Value

Name	Туре	Description
handle	integer	File handle to be used in subsequent ReadFile/WriteFile calls.

Return Code

Code	Description
-1	Function failed, unable to open file, or bad argument to function.

Parameter Discussion

fileName is a pathname that specifies the file to open. If the **read/writeMode** argument is write or read/write, OpenFile creates the file if it does not already exist. Use GetFileInfo to determine whether a file already exists. OpenFile creates files with full read and write permissions.

read/writeMode specifies how to open the file:

- VAL_READ_WRITE—Open file for reading and writing.
- VAL_READ_ONLY—Open file for reading only.
- VAL_WRITE_ONLY—Open file for writing only.

action specifies whether to delete the old contents of the file and whether to force the file pointer to the end of the file before each write operation. **action** is meaningful only if **read/writeMode** is VAL_READ_WRITE or VAL_WRITE_ONLY. After you perform read operations, the file pointer points to the byte that follows the last byte read. **action** values are as follows:

- VAL_TRUNCATE—Truncate file; delete its old contents and position the file pointer at the beginning of the file.
- VAL_APPEND—Do not truncate file; append all write operations to end of file.
- VAL_OPEN_AS_IS—Do not truncate file; position the file pointer at the beginning of the file.

fileType specifies whether to treat the file as ASCII or binary. When you perform I/O on a file in binary mode, carriage returns (CR) and linefeeds (LF) receive no special treatment. When you open the file in ASCII mode, CR LF combination translates to LF when reading, and LF translates to CR LF when writing. **fileType** values are as follows:

- VAL_BINARY—binary
- VAL_ASCII—ASCII

ReadFile

int n = ReadFile (int fileHandle, char buffer[], int count);

Purpose

Reads up to **count** bytes of data from a file or the Standard Input into **buffer**. Reading starts at the current position of the file pointer. When ReadFile completes, the file pointer points to the next unread character in the file.

Parameters

Input

Name	Туре	Description
fileHandle	integer	File handle.
count	integer	Number of bytes to read.

Output

Name	Туре	Description
buffer	string	Input buffer.

Return Value

Name	Туре	Description
n	integer	Number of bytes read.

Return Codes

Code	Description	
-1	Error, possibly a bad handle.	
0	Tried to read past end-of-file.	

Parameter Discussion

To read from a file, first call OpenFile to obtain a **fileHandle**. To read from the Standard Input, pass 0 for **fileHandle**. **buffer** is the buffer into which you read data. You must allocate space for this buffer before you call this function. **count** specifies the number of bytes to read. **count** must not be greater than **buffer** size.

Using This Function

The return value can be less than the number of bytes requested if ReadFile reaches the end of the file before the byte count is satisfied. If you open the file in ASCII mode, ReadFile counts each CR LF combination read as one character, because the pair is translated into LF when ReadFile stores it in the buffer.

Note ReadFile *does not terminate the buffer with an ASCII NUL.*

ReadLine

int n = ReadLine (int fileHandle, char lineBuffer[],int maximum#Bytes);

Purpose

Reads bytes from a file until it encounters a linefeed.

Parameters

Input

Name	Туре	Description
fileHandle	integer	File handle.
maximum#Bytes	integer	Maximum number of bytes to read into line, excluding the ASCII NUL.

Output

Name	Туре	Description
lineBuffer	string	Input buffer.

Return Value

Name	Туре	Description
n	integer	Number of bytes read, excluding linefeed.

Return Codes

Code	Description
-2	End of file.
-1	I/O error.

Parameter Discussion

ReadLine places up to **maximum#Bytes** bytes, excluding LF, into **lineBuffer** and appends an ASCII NUL to **lineBuffer**. If there are more than **maximum#Bytes** bytes before LF, ReadLine discards the extra bytes.

Call OpenFile to obtain **fileHandle**. You should open the file in ASCII mode so that ReadLine treats a CR LF combination as LF. If **fileHandle** is zero, ReadLine reads the line from the Standard Input.

lineBuffer is a character buffer that should be large enough to contain **maximum#Bytes** bytes plus an ASCII NUL.

ReadLine returns the number of bytes read from the file, including discarded bytes, but excluding LF. Hence, the return value exceeds **maximum#Bytes** if bytes are discarded.

If ReadLine reads no bytes because it has already reached the end of the file, it returns -2. If an I/O error occurs, ReadLine returns -1.

Scan

int n = Scan (void *source, char *formatString, targetptr1,...,targetptrn);

Purpose

Scans a single source item in memory and breaks it into component parts according to format specifiers found in a **formatString**. Scan then places the components into the target parameters.

Parameters

Input

Name	Туре	Description
source	string	Refer to the Using the Formatting and
formatString	Types must match formatString contents.	<i>Scanning Functions</i> section later in this chapter.

Output

Name	Туре	Description
targetptr1,, targetptr <i>n</i>	Types must match formatString contents.	Refer to the Using the Formatting and Scanning Functions section later in this chapter.

Return Value

Name	Туре	Description
n	integer	Number of target format specifiers satisfied.

Return Code

Code	Description
-1	Format string error.

Using This Function

The return value indicates how many target format specifiers were satisfied or -1 if the format string is invalid. The *Using the Formatting and Scanning Functions* section later in this chapter includes a complete discussion of Scan.

ScanFile

Purpose

Performs the same basic operation as the Scan function, except that ScanFile reads the source data from the file you specify in the **fileHandle** argument. You obtain **fileHandle** by calling the LabWindows/CVI function OpenFile.

Parameters

Input

Name	Туре	Description
fileHandle	integer	Refer to the Using the Formatting and
formatString	Types must match formatString contents.	<i>Scanning Functions</i> section later in this chapter.

Output

Name	Туре	Description
targetptr1,, targetptr <i>n</i>	Types must match formatString contents.	Refer to the Using the Formatting and Scanning Functions section later in this chapter.

Return Value

Name	Туре	Description
n	integer	Number of target format specifiers satisfied.

Return Codes

Code	Description
-1	Format string error.
-2	I/O error.

Using This Function

The amount of data ScanFile reads from the file depends on the amount needed to fulfill the target format specifiers in the format string. The return value indicates how many target format specifiers were satisfied; -1 if the format string is invalid or -2 if an I/O error occurs. The *Using the Formatting and Scanning Functions* section later in this chapter includes a complete discussion of ScanFile.

ScanIn

int n = ScanIn (char *formatString, targetptr1,...,targetptrn);

Purpose

Performs the same basic operation as ScanFile, except that ScanIn obtains the source data from the Standard Input.

Parameters

Input

Name	Туре	Description
formatString	string	Refer to the <i>Using the Formatting and</i> <i>Scanning Functions</i> section later in this chapter.

Output

Name	Туре	Description
targetptr1,, targetptr <i>n</i>	Types must match formatString contents.	Refer to the <i>Using the Formatting and</i> <i>Scanning Functions</i> section later in this chapter.

Return Value

Name	Туре	Description
n	integer	Number of target format specifiers satisfied.

Return Codes

Code	Description
-1	Format string error.
-2	I/O error.

Using This Function

ScanIn requires no argument for the source item. The return value indicates how many target format specifiers were satisfied; -1 if the format string is invalid or -2 if an I/O error occurs. The *Using the Formatting and Scanning Functions* section later in this chapter includes a complete discussion of ScanIn.

SetFilePtr

long position = SetFilePtr (int fileHandle, long offset, int origin);

Purpose

Moves the file pointer for the file specified by **fileHandle** to a location that is **offset** bytes from **origin**. Returns the offset of the new file pointer position from the beginning of the file.

Parameters

Input

Name	Туре	Description
fileHandle	integer	File handle you obtain from OpenFile.
offset	long integer	Number of bytes from origin to position of file pointer.

Output

Name	Туре	Description
origin	integer	Position in file from which to base offset.

Return Value

Name	Туре	Description
position	long integer	Offset of the new file pointer position from the beginning of the file.

Return Code

Code	Description
-1	An invalid file handle, an invalid origin value, or an offset value that is before the beginning of the file.

Parameter Discussion

The valid values of **origin** are as follows:

- 0 = beginning of file
- 1 = current position of file pointer
- 2 =end of file

Using This Function

You can use SetFilePtr to obtain the file size by setting offset to 0 and origin to 2. In this case, the return value indicates the file size, and the file pointer points to at the end of the file.

You can position the file pointer beyond the end of the file. Intermediate bytes, bytes between the old end of file and the new end of file, contain values that might vary. An attempt to position the file pointer before the beginning of the file causes the function to return an error.

If the file is a device that does not support random access, such as the Standard Input, the function returns a value that might vary.

Example

```
/* Open or create the file c:\TEST.DAT, move 10 bytes into the file,
   and write a string to the file. */
/* Note: Use \\ in pathname in C instead of \. */
int handle, result;
long position;
handle = OpenFile("c:\\TEST.DAT", 0, 2, 1);
if (handle == -1) {
   FmtOut("error opening file");
   exit(1);
}
position = SetFilePtr(handle, 10L, 0);
if (position == 10) {
   result = WriteFile(handle, "Hello, World!", 13);
   if (result == -1)
      FmtOut("error writing to file");
}
else
   FmtOut("error positioning file pointer");
CloseFile (handle);
```

StringLength

```
int n = StringLength (char *string);
```

Purpose

Returns the number of bytes in the string before the first ASCII NUL.

Parameter

Input

Name	Туре	Description
string	string	Null-terminated string.

Return Value

Name	Туре	Description
n	integer	Number of bytes in string before ASCII NUL.

Example

```
char s[100];
int nbytes;
nbytes = StringLength (s);
```

StringLowerCase

```
void StringLowerCase (char string[]);
```

Purpose

Converts all uppercase alphabetic characters in the null-terminated **string** to lowercase.

Parameter

Input/Output

Name	Туре	Description
string	string	String to convert to lowercase.

Return Value

None.

StringUpperCase

```
void StringUpperCase (char string[]);
```

Purpose

Converts all lowercase alphabetic characters in the null-terminated string to uppercase.

Parameter

Input/Output

Name	Туре	Description
string	string	String to convert to uppercase.

Return Value

None.

WriteFile

int n = WriteFile (int fileHandle, char *buffer, unsigned int count);

Purpose

Writes up to **count** bytes of data from **buffer** to a file or to the Standard Output. WriteFile starts writing at the current position of the file pointer. When WriteFile completes, it increments the file pointer by the number of bytes written.

Parameters

Input

Name	Туре	Description
fileHandle	integer	File handle.
buffer string		Data buffer.
count integer		Number of bytes to write.

Return Value

Name	Туре	Description
n	integer	Number of bytes written to the file.

Return Code

Code	Description
-1	Error. An error can indicate a bad file handle, an attempt to access a protected file, an attempt to write to a file opened as read only, or no more space left on disk.

Parameter Discussion

To write data to a file, first call OpenFile to obtain a **fileHandle**. To write to the Standard Output, pass 1 for **fileHandle**.

buffer is the buffer from which to write data.

count specifies the number of bytes to write. The **count** parameter overrides the buffer size in determining the number of bytes to write. Buffers that contain embedded ASCII NUL bytes are written in full. **count** must not be greater than **buffer** size.

Using This Function

For files you open in ASCII mode, WriteFile replaces each LF character with a CR LF combination in the output. The return value does not include the CR characters WriteFile inserts before the LF characters.

WriteLine

int n = WriteLine (int fileHandle, char *lineBuffer,int numberOfBytes);

Purpose

Writes numberOfBytes bytes from lineBuffer to a file and then writes a linefeed to the file.

Parameters

Input

Name	Туре	Description
fileHandle	integer	File handle.
lineBuffer	string	Data buffer.
numberOfBytes	integer	Number of bytes to write.

Return Value

Name	Туре	Description
n	integer	Number of bytes written, including linefeed.

Return Code

Code	Description
-1	I/O error.

Parameter Discussion

If **numberOfBytes** is -1, WriteLine writes only the bytes in **lineBuffer** before the first ASCII NUL, followed by LF.

Call OpenFile to obtain a **fileHandle**. You should open the file in ASCII mode so that WriteLine writes CR before LF. If **fileHandle** is 1, WriteLine writes the line to the Standard Output.

Using This Function

WriteLine returns the number of bytes written to the file, excluding LF. If an I/O error occurs, WriteLine returns -1.

Using the Formatting and Scanning Functions

You use data formatting functions to translate or reformat data items into other forms. Typical uses might be to translate between data stored on external files and the internal forms the program can manipulate, or to reformat a foreign binary representation into one on which the program can operate.

Three subclasses of data formatting functions exist in the LabWindows/CVI Formatting and I/O Library:

- Formatting functions
- Scanning functions
- Status functions

You use formatting functions to combine and format one or more source items into a single target item, and you use scanning functions to break apart a single source item into several target items. The status functions return information regarding the success or failure of the formatting or scanning functions.

Introductory Formatting and Scanning Examples

To introduce you to the formatting and scanning functions, consider the following examples.

Convert the integer value 23 to its ASCII representation and place the contents in a string variable:

```
char a[5];
int b,n;
b = 23;
n = Fmt (a, "%s<%i", b);</pre>
```

After the Fmt call, a contains the string 23.

In this example, a is the target argument, b is the source argument, and the string %s<%i is the format string. The Fmt call uses the format string to determine how to convert the source argument into the target argument.

With Scan, you can convert the string 23 to an integer:

```
char *a;
a = "23";
n = Scan (a$, "%s>%i", b%);
```

After the Scan call, b = 23.

In this example, a is the source argument, b is the target argument, and %s>%i is the format string. In both the formatting and the scanning functions, the format string defines the variable types of the source and target arguments and the method by which the source arguments are transformed into the target arguments.

Formatting Functions

The following information is a brief description of the three formatting functions:

• n = Fmt (target, formatstring, source1, ..., sourcen);

The Fmt function formats the source1, ..., sourcen arguments according to descriptions in the formatstring argument. Fmt places the result of the formatting into the target argument.

• n = FmtFile (handle, formatstring, source1, ..., sourcen);

The FmtFile function formats the source1, ..., sourcen arguments according to descriptions in the formatstring argument. FmtFile writes the result of the formatting into the file corresponding to the handle argument.

n = FmtOut (formatstring, source1, ..., sourcen);

The FmtOut function formats the source1, ..., source*n* arguments according to descriptions in the formatstring argument. FmtOut writes the result of the formatting to the Standard Output.

Each of these formatting functions returns the number of source format specifiers satisfied. If an error exists in the format string, the functions return -1.

The formatting functions format and combine multiple source items into a single target item. The only difference in the workings of the three functions is the location of the target data. For Fmt, the target is a data item in memory that you pass to the function by reference. You must pass the target parameter for Fmt by reference. For FmtFile, the target is a file whose handle you pass as the first argument. Call OpenFile to obtain a file handle. For FmtOut, the target is the Standard Output, typically the display. FmtOut omits the target argument present in the other two functions. Except for these differences, the following descriptions apply to all the formatting functions.

Formatting Functions—Format String

Consider the following formatting function:

```
n = Fmt(target, formatstring, source1, ..., sourcen);
```

where formatstring contains the information to transform the source arguments to the target argument.

Format strings for all the formatting functions are of the form:

```
"target_spec < source_specs_and_literals"
```

where target_spec is a format specifier that describes the nature of the target data item, and source_specs_and_literals is a sequence of format specifiers and literal characters that indicate how to combine the source material into the target.

Examples of format strings for the formatting functions are as follows:

"%s < RANGE %i" "%s < %s; %i"

The character '<' serves as a visual reminder of the direction of the data transformation from the sources to the target and separates the single target format specifier from the source format specifiers and literals. You can omit the target format specifier, in which case the functions assume a %s string format. If you omit the target format specifier, you can omit the '<' character or retain it for clarity.

Notice that the target format specifier is located to the left of the '<' symbol, just as the target parameter is located to the left of the format string. Likewise, the source format specifiers are located to the right of the '<' symbol, just as the source parameters are located to the right of the format string.

Format specifiers describe the inputs and outputs of data transformations. Each format specifier has the following form:

% [rep] formatcode [[modifiers]]

The character '%' introduces all format specifiers. rep indicates how many times the format repeats with respect to the arguments. formatcode is a code character that indicates the nature of the data items you want to format. modifiers is an optional bracket-enclosed sequence of codes that further describe the data format.

Examples of format specifiers are as follows:

```
%s %100f %i[b2u]
```

Note rep *is not allowed when* formatcode *is* s (*string*).

formatcode is specified with one of the following codes in Table 2-2.

formatcode	Meaning	Description
S	String	As a source or target specifier, this indicates that the corresponding parameter is a character string. As a target specifier, this can mean that numeric source parameters become converted into an ASCII form for inclusion in the target string. Refer to the individual numeric formats, such as %i and %f, for details of these conversions. s is the default if no target specifier exists. The functions do not work on arrays of strings. For example, %10s is not a valid format string.
		Note : When the functions fill in a target string, they always place an ASCII NUL in the string after the last byte.
i	Integer	This source or target specifier indicates that the corresponding parameter is an integer or, if rep is present, an integer array. The function performs conversions to ASCII digits when converting to or from the string format %s. A modifier is available to specify the radix to use in such a conversion. The default is decimal.
x	Integer (hexadecimal)	This source or target specifier indicates that the corresponding parameter is an integer or, if rep is present, an integer array. The function performs conversions to ASCII hexadecimal digits (0123456789abcdef) when converting to or from the string format %s.
0	Integer (octal)	This source or target specifier indicates that the corresponding parameter is an integer or, if rep is present, an integer array. The function performs conversions to ASCII octal digits (01234567) when converting to or from the string format %s.
d	Integer (decimal)	This format specifier is identical to %i and is included for compatibility with the C printf family of functions.

formatcode	Meaning	Description
f	Real number	This source or target specifier indicates that the corresponding parameter is a real number or, if rep is present, a real array. The functions perform conversions to ASCII when converting to or from the string format %s.
С	Character	This source or target specifier indicates that the corresponding parameter is an integer with one significant byte or, if rep is present, an array of 1-byte integers. The functions do <i>not</i> perform conversion to ASCII when converting to or from the string format %s. The functions copy <i>directly</i> to or from the string.

 Table 2-2.
 Codes That Specify formatcode (Continued)

Formatting Modifiers

modifiers are optional codes you use to describe the nature of the source or target data. If you use them, you must enclose the modifiers in square brackets and place them immediately after the format code they modify. If one format specifier requires more than one modifier, enclose all modifiers in the same set of brackets.

A different set of modifiers exists for each possible format specifier as shown in Table 2-3, Table 2-4, and Table 2-5.

Modifier	Meaning	Description
bn	Specify length	The b integer modifier specifies the length of the integer argument, or the length of an individual integer array element, in bytes. The default length is 4 bytes; therefore, simple 4-byte integers do not need this modifier. The modifier b2 represents short integers. The modifier b1 represents single-byte integers.
in	Specify array offset	The <i>i</i> integer modifier specifies an offset within an integer array argument. It indicates the location within the array where processing begins. <i>n</i> is the zero-based index of the first element to process. Thus, $10d[i2]$ applied to a source integer array processes the 10 integer values from the third–12th elements of the array. The <i>i</i> modifier is valid only if rep is present. If you use the <i>i</i> modifier with the <i>z</i> modifier, <i>n</i> is in terms of bytes.
Z	Treat string as integer array	The z integer modifier indicates that the data type of the corresponding argument is a string. Nevertheless, the functions treat the data in the string as an integer array. The z modifier is valid only if rep is present.
rn	Specify radix	The r integer modifier specifies the radix of the integer argument, which is important if the functions convert the integer into string format. Legal radixes are 8 (octal), 10 (decimal, the default), 16 (hexadecimal), and 256 (a special radix that represents single 8-bit ASCII characters).
wn	Specify string size	The w integer modifier specifies the exact number of bytes in which to store a string representation of the integer argument, in the event that the functions convert the integer to a string format. You can enter any non-negative value here. If n is less than the number of digits required to represent the integer, the functions insert an asterisk (*) into the string to signify an overflow. The default for n is zero, which indicates that the integer can occupy whatever space is necessary.

Modifier	Meaning	Description
pc	Specify padding	The p integer modifier specifies a padding character c , which fills the space to the left of an integer in the event it does not require the entire width you specify with the wn modifier. The default padding character is a blank.
s	Specify as two's complement	The s integer modifier indicates that the functions consider the integer argument a signed two's complement number. This is the default interpretation of integers, so the functions do not require the s modifier.
u	Specify as unsigned	The u integer modifier indicates that the functions consider the integer an unsigned integer.
onnnn	Specify byte ordering	You use the \circ integer modifier to describe the byte ordering of raw data so that LabWindows/CVI can map it to the byte order appropriate for the Intel (PC) or Motorola (SPARCstation) architecture. The number of <i>n</i> 's must be equal to the byte size of the integer argument as specified by the b <i>n</i> modifier, which must precede the \circ modifier. In the case of a four-byte integer, $\circ 0123$ indicates that the bytes are in ascending order of precedence (Intel style), and $\circ 3210$ indicates that the bytes are in descending order of precedence (Motorola style).

Table 2-3. Formatting Integer Modifiers (%i, %d, %x, %o, %c) (Continued)

When using the Fmt function to transfer raw instrument data to or from a C integer or integer array, you must use the \circ modifier on the buffer that contains the raw instrument data. Do not use the \circ modifier on the buffer that contains the C integer or integer array. LabWindows/CVI determines the byte ordering of the buffer without the \circ modifier based on the architecture on which your program is running.

For example, if your GPIB instrument sends 2-byte binary data in Intel byte order, your code should appear as follows:

```
short int instr_buf[100];
short int prog_buf[100];
status = ibrd (ud, instr_buf, 200);
Fmt (prog_buf, "%100d<%100d[b2001]", instr_buf);</pre>
```

If, instead, your GPIB instrument sends two-byte binary data in Motorola byte order, Fmt should appear as follows:

Fmt (prog_buf, "%100d<%100d[b2o10]", prog_buf);</pre>

In either case, you use the o modifier only on the buffer that contains the raw data from the instrument (instr_buf). LabWindows/CVI ensures that the program buffer (prog_buf) is in the proper byte order for the host processor.

Note When you use both the bn and on modifiers on an integer specifier, the bn modifier must be first.

Modifier	Meaning	Description
bn	Specify length	The b floating-point modifier specifies the length of the floating-point argument, or the length of an individual array element, in bytes. The default length is 8 bytes; therefore, double-precision values do not need this modifier. Single-precision, floating-point values are indicated by b4. The only valid values for n are 8 and 4.
in	Specify array offset	The <i>i</i> floating-point modifier specifies an offset within a floating-point array argument. It indicates the location within the array where processing begins. <i>n</i> is the zero-based index of the first element to process. Thus, $10f[i2]$ applied to a source floating-point array processes the 10 floating-point values from the third–12th elements of the array. The <i>i</i> modifier is valid only if rep is present. If you use the <i>i</i> modifier with the <i>z</i> modifier, <i>n</i> is in terms of bytes.
Z	Treat string as floating-point array	The z floating-point modifier indicates that the data type of the corresponding argument is a string. Nevertheless, the functions treat the data in the string as a floating-point array. The z modifier is valid only if rep is present.
wn	Specify string size	The w floating-point modifier specifies the exact number of bytes in which to store a string representation of the floating-point argument, in the event that the functions convert the value to a string format. You can enter any non-negative value here. If n is less than the number of digits required to represent the floating-point number, the functions insert an asterisk (*) into the string to signify an overflow. The default for n is zero, which indicates that the value can occupy whatever space is necessary.

Table 2-4. Formatting Floating-Point Modifiers (%f)

Modifier	Meaning	Description
pn	Specify precision	The p floating-point modifier specifies the number of digits to the right of the decimal point in a string representation of the floating-point number. You can lose significant digits by attempting to conform to the precision specification. If you omit the pn modifier, the default value is p6.
en	Specify as scientific notation	The e floating-point modifier instructs the functions to convert a value to string format in scientific notation. If you omit the en modifier, the functions use the floating-point notation. <i>n</i> is optional and specifies the number of digits in the exponent. For example, $f[e2]$ formats 10.0 as 1.0e+01. If you omit <i>n</i> , the functions use a default of three.
		Note : The functions can represent the value in scientific notation even when the e modifier is absent. This occurs when the absolute value of the argument is greater than 1.0e40 or less than 1.0e40, or when the absolute value of the argument is greater than 1.0e20 or less than 1.0e-4 and neither the p modifier nor the w modifier is present.
f	Specify as floating-point notation	The f floating-point modifier instructs the functions to convert a value to string format in floating-point notation. This is the default.
t	Truncate	The t floating-point modifier indicates that in floating-point to integer transformations, the functions truncate instead of round the floating-point value. This is the default.
r	Round	The r floating-point modifier indicates that in floating-point to integer transformations, the functions round instead of truncate the floating-point value. The default method is truncation.

Table 2-4.	Formatting	Floating-Point	Modifiers	(%f)	(Continued))
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Modifier	Meaning	Description
in	Specify array offset	The i string modifier specifies an offset within a string. It indicates the location within the string where processing begins. <i>n</i> is the zero-based index of the first byte to process. Thus, %s[i2] applied to a target string begins placing data in the third byte of the string.
a	Append	When applied to a target format specifier, the a string modifier specifies that all formatted data be appended to the target string, beginning at the first occurrence of an ASCII NUL in the target string.
wn	Specify string size	When applied to a source format specifier, the w string modifier specifies the maximum number of bytes to consume from the string argument. You can enter any non-negative value here. The default is zero, which indicates that the entire string should be consumed.
		When modifying a target format specifier, the w string modifier specifies the exact number of bytes to store in the string, excluding the terminating ASCII NUL. If <i>n</i> is zero or omitted, the functions store as many bytes as the sources call for. When <i>n</i> is greater than the number of bytes available from the source, the remaining bytes are filled with ASCII NULs if you use the q modifier or blanks if you do not use the q modifier.
		When you use the w string modifier in conjunction with the a string modifier, n indicates the number of bytes to append to the string excluding the terminating ASCII NUL.
đ	Append NULs	When applied to a target string in conjunction with the w string modifier, the q string modifier specifies that unfilled bytes at the end of the target string be set to ASCII NULs instead of blanks.

Modifier	Meaning	Description
tn	Terminate on character	When applied to a source string, the t string modifier specifies that the source string terminates on the first occurrence of the character n, where n is the ASCII value of the character. Thus, %s[t44] stops the reading of the source string on an ASCII comma. Using %s[t44] and the source string Hello, World! as an example, the functions place Hello into the target. More than one t modifier can occur in the same specifier, in which case the string terminates when any of the terminators occur. If not modifier exists, reading of the source string stops on an ASCII NUL. This modifier has no effect when you apply it to the target specifier.
t-	Terminate when full	This is similar to tn except that it specifies that there are <i>no</i> terminating characters. Reading of the source string terminates when the target is full or when the functions have read the number of bytes specified with the w modifier.
t#	Terminate on number	This is equivalent to repeating the t modifier with the ASCII values of the characters +, -, and 0–9. It instructs the functions to stop the reading of the source string on occurrence of a numeric expression. If you use $ss[t#]$ with the source string ab567, the functions place ab in the target.

 Table 2-5.
 Formatting String Modifiers (%s) (Continued)

Fmt, FmtFile, FmtOut—Asterisks (*) Instead of Constants in Format Specifiers

Often, a format specifier requires one or more integer values. The format specifier for an integer array, for example, requires the number of elements (rep). You can use constants for these integer values in format specifiers. Also, you can specify an integer value using an argument in the argument list. When you use this method, substitute an asterisk (*) for the constant in the format specifier.

Use the asterisk in the following format specifier elements:

- rep For integer or floating-point arrays
- in For integer or floating-point arrays, or strings
- wn For any format specifier
- pn For floating-point specifiers only
- en For floating-point specifiers only
- rn For integer specifiers only

When you use one or more asterisks instead of constants in a *target* specifier, the arguments that correspond to the asterisks must appear *after* the format string in the same order as the corresponding asterisks appear in the format specifier.

When you use one or more asterisks instead of constants in a *source* specifier, the arguments that correspond to the asterisks must *precede* the source argument and must be in the same order as the corresponding asterisks in the format specifier.

Fmt, FmtFile, FmtOut-Literals in the Format String

Literal characters that appear in a formatting function format string indicate that the literal characters are to be combined with the source parameters in the appropriate positions. They do not correspond to any source parameters but are copied directly into the target item.

Because the left side of the < symbol must be a single format specifier, literal characters must be on the right side of the symbol. Literals on the left side or more than one format specifier on the left side result in a -1 error, indicating a faulty format string. You then can use GetFmtErrNdx to determine exactly where the error lies in the format string.

The characters , [,], <, and > have special meaning in the format strings. To specify that these characters be taken literally, precede them with .

Scanning Functions

The following information is a brief description of the three scanning functions.

- n = Scan (source, formatstring, targetptr1, ..., targetptrn); Scan inspects the source argument and applies transformations to it according to descriptions in the formatstring argument. Scan places the results of the transformations into the targetptr1 ... targetptrn arguments.
- n = ScanFile (handle, formatstring, targetptr1, ..., targetptrn);

ScanFile reads data from the file that corresponds to the handle argument and applies transformations to it according to descriptions in the formatstring argument. ScanFile places the results of the transformations into the targetptr1 ... targetptrn arguments.

• n = ScanIn (formatstring, targetptr1, ..., targetptrn);

ScanIn reads data from the Standard Input and applies transformations to it according to descriptions in the formatstring argument. ScanIn places the results of the transformations into the targetptr1 ... targetptrn arguments.

Each of these scanning functions returns the number of target format specifiers satisfied. If an error exists in the format string, the functions return -1.

The scanning functions break apart a source item into component parts and store the parts into parameters passed to the function. The only difference among the three functions is the location of the source data. For Scan, the source item is a data item in memory that you pass to the function. For ScanFile, the source item is a file, whose handle you pass as the first argument. Call OpenFile to obtain a file handle. For ScanIn, the function takes the source from the Standard Input, typically the keyboard, and omits the source argument present in the other two functions.

You must pass all target parameters for Scan by reference.

Scanning Functions—Format String

Consider the following scanning function:

n = Scan(source, formatstring, targetptr1, ..., targetptrn);

where formatstring contains the information to transform the source argument to the targetptr arguments.

Format strings for the scanning functions follow the form:

```
"source_spec > target_specs_and_literals"
```

where source_spec is a format specifier that describes the nature of the source parameter and target_specs_and_literals is a sequence of format specifiers and literal characters that indicate how to divide and reformat the source argument into the desired target.

Examples of format strings for the scanning functions are as follows:

```
"%s > %i"
"%s > %20f[w10x]"
```

The character '>' serves as a visual reminder of the direction of the data transformation and separates the single source format specifier from the target format specifiers and literals. You can omit the source format specifier, in which case the functions assume a %s string format. If you omit the source format specifier, you can omit the '>' character or retain it for clarity.

Notice that the source format specifier is located to the left of the '>' symbol, just as the source parameter is located to the left of the format string. Likewise, the target format specifiers are located to the right of the '>' symbol, just as the target parameters are located to the right of the format string.

Format specifiers describe the inputs and outputs of data transformations. Each format specifier is of the following form:

% [rep] formatcode [[modifiers]]

The character % introduces all format specifiers. rep indicates how many times the format repeats with respect to the arguments. formatcode is a code character that indicates the nature of the data items the functions format. modifiers is an optional bracket-enclosed sequence of codes that further describe the data format.

Examples of format specifiers are a follows:

%s[t59] %100i[z] %f

T Note rep *is not allowed when* formatcode *is* s *or* 1 (*string*).

formatcode is specified with one of the following codes in Table 2-6:

formatcode	Meaning	Description
S	String	As a source or target specifier, this indicates that the corresponding parameter is a character string. As a source specifier, the number of bytes of the source parameter that the functions consume depends on the target specifier. If the target specifier is $\$s$, the functions consume bytes until they encounter a termination character. Refer to the t modifier for strings for more information on termination characters. If the target specifier is one of the numeric formats, the functions consume bytes as long as the bytes correspond to the pattern for the particular numeric item the functions are converting. The functions skip leading spaces and tabs unless you use the y modifier. Note: When the functions fill in a target string, they always place an ASCII NUL in the string after the
		last byte.
1	String	This is allowed only as a source specifier. It is the same as the %s specifier, except that the function consumes bytes from the source argument only until it encounters a linefeed. You can modify with c, as in %l[c], to tell the functions to use a comma as the target string terminator in place of white space characters.

 Table 2-6.
 Codes That Specify formatcode

formatcode	Meaning	Description
i	Integer	This source or target specifier indicates that the corresponding parameter is an integer or, if rep is present, an integer array. As a source specifier in conversions to string formats, the functions convert the integer into digits of the specified radix. The default is decimal. As a target specifier in conversions from string format, the functions consume bytes of the source parameter as long as they match the pattern of integer ASCII numbers in the appropriate radix or until the functions encounter the end of the string. The functions convert the scanned characters to integer values and place them into the corresponding target parameter, which is an integer array or integer you pass by reference. The pattern for integer ASCII numbers consists of an optional sign (+ or -), followed by a series of one or more digits in the appropriate radix. The decimal digits are 01234 56789. The octal digits are 01234567. The
		hexadecimal digits are 0123456789ABCDEFabcdef.
x	Integer (hexadecimal)	This specifier indicates a %i format with hexadecimal radix.
0	Integer (octal)	This specifier indicates a %i format with octal radix.
d	Integer (decimal)	This specifier is identical to %i and is included for compatibility with the C scanf family of functions.

Table 2-6.	Codes	That Specify	y formatcode	(Continued))
	00000	That opcom	y ioiiiiacooao	(continuou)	

formatcode	Meaning	Description
f	Real number	As a source or target specifier, this indicates that the corresponding parameter is a real number, or if rep is present, a real array. As a source specifier in conversions to string formats, the functions convert the floating-point value into ASCII form. As a target specifier in conversions from string format, the function consumes bytes of the source parameter as long as they match the pattern of floating-point ASCII numbers or until the functions encounter the end of the string. The functions convert the scanned characters to a floating-point value and place them into the corresponding floating-point or floating-point array target parameter.
		The pattern for floating-point ASCII numbers is an optional sign (+ or –), a series of one or more decimal digits that can contain a decimal point, and an optional exponent that consists of an E or e followed by an optionally signed decimal integer value.
с	Character	As a source specifier, this indicates that the source parameter is an integer with one significant byte or, if rep is present, an array of 1-byte integers. As a target specifier, this indicates that the functions consume a byte of the source parameter and place the scanned character directly into the corresponding target parameter, which is an integer you pass by reference.

 Table 2-6.
 Codes That Specify formatcode (Continued)

Scanning Modifiers

modifiers are optional codes you use to describe the nature of the source or target data. If you use them, you must enclose the modifiers in square brackets and place them immediately after the format code they modify. If one format specifier requires more than one modifier, enclose all modifiers in the same set of brackets. A different set of modifiers exists for each possible format specifier as shown in Table 2-7, Table 2-8, and Table 2-9.

Modifier	Meaning	Description
bn	Specify length	The b integer modifier specifies in bytes the length of the integer argument or the length of an individual integer array element. The default length is 4 bytes; therefore, simple 4-byte integers do not need this modifier. The modifier b2 represents short integers. The modifier b1 represents single-byte integers.
in	Specify array offset	Use the <i>i</i> integer modifier to specify an offset within an integer array argument. It indicates the location within the array where processing begins. <i>n</i> is the zero-based index of the first element to process. Thus, $10d[i2]$ applied to a source integer array processes the 10 integer values from the third–12th elements of the array. The <i>i</i> modifier is valid only if rep is present. If you use the <i>i</i> modifier with the <i>z</i> modifier, <i>n</i> is in terms of bytes.
Z	Treat string as integer array	The z integer modifier indicates that the data type of the corresponding argument is a string. Nevertheless, the functions treat the data in the string as an integer array. The z modifier is valid only if rep is present.
rn	Specify radix	The r integer modifier specifies the radix of the integer argument, which is important if the functions convert the integer from a string format. Legal radixes are 8 (octal), 10 (decimal, the default), 16 (hexadecimal), and 256 (a special radix that represents single 8-bit ASCII characters).
wn	Specify string size	The w integer modifier specifies the exact number of bytes occupied by a string representation of the integer argument, in the event that the functions convert the integer from a string format. You can enter any non-negative value here. If n is less than the number of digits required to represent the integer, the functions insert an asterisk (*) into the string to signify an overflow. The default for n is zero, which indicates that the integer can occupy as much room as necessary.

Table 2-7. Scanning Integer Modifiers (%i, %d, %x, %o, %c)

Modifier	Meaning	Description
S	Specify as two's complement	The s integer modifier indicates that the functions consider the integer argument a signed two's complement number. This is the default interpretation of integers, so the functions do not require the s modifier.
u	Specify as non-negative	The u integer modifier indicates that the functions consider the integer to be a non-negative integer.
x	Discard terminator	The x integer causes the functions to discard the character that terminated the numeric data. In this way, the functions can skip the terminator characters when reading lists of numeric input. Thus, $3i [x]$ reads three integer numbers, disregarding the terminator character that appears after each one. You can use this specifier to scan the string 3, 7, -32.
d	Discard data	When applied to a target specifier, the d integer modifier indicates that no target argument exists to correspond to the target specifier. The data the functions would place in the target argument is discarded instead. The count the functions return <i>includes</i> the target specifier even if you use the d modifier.
onnnn	Specify byte ordering	You use the \circ integer modifier to describe the byte ordering of raw data so that LabWindows/CVI can map it to the byte order appropriate for the Intel (PC) or Motorola (SPARCstation) architecture. The number of <i>n</i> 's must be equal to the byte size of the integer argument as specified by the b <i>n</i> modifier, which must precede the \circ modifier. In the case of a four-byte integer, $\circ 0123$ indicates that the bytes are in ascending order of precedence (Intel style), and $\circ 3210$ indicates that the bytes are in descending order of precedence (Motorola style).

 Table 2-7.
 Scanning Integer Modifiers (%i, %d, %x, %o, %c) (Continued)

When using the Scan function to transfer raw instrument data to or from a C integer or integer array, you must use the \circ modifier on the buffer that contains the raw instrument data. Do not use the \circ modifier on the buffer that contains the C integer or integer array. LabWindows/CVI determines the byte ordering of the buffer without the \circ modifier based on the architecture on which your program is running.

For example, if your GPIB instrument sends 2-byte binary data in Intel-byte order, your code should appear as follows:

```
short int instr_buf[100];
short int prog_buf[100];
status = ibrd (ud, instr_buf, 200);
Scan (instr_buf, "%100d[b2o01]>%100d", prog_buf);
```

If, instead, your GPIB instrument sends 2-byte binary data in Motorola-byte order, Scan should appear as follows:

Scan (instr_buf, "%100d[b2o10]>%100d", prog_buf);

In either case, you use the o modifier only on the buffer that contains the raw data from the instrument (instr_buf). LabWindows/CVI ensures that the program buffer (prog_buf) is in the proper byte order for the host processor.

Note When you use both the bn and on modifiers on an integer specifier, the bn modifier must be first.

Modifier	Meaning	Description
bn	Specify length	The b floating-point modifier specifies the length of the floating-point argument, or the length of an individual array element, in bytes. The default length is 8 bytes; therefore, double-precision values do not need this modifier. Single-precision floating-point values are indicated by b4. The only valid values for n are 8 and 4.
in	Specify array offset	The i floating-point modifier specifies an offset within a floating-point array argument. It indicates the location within the array where processing begins. <i>n</i> is the zero-based index of the first element to process. Thus, $\$10f[i2]$ applied to a source floating-point array processes the 10 floating-point values from the third–12th elements of the array. The i modifier is valid only if rep is present. If you use the i modifier with the <i>z</i> modifier, <i>n</i> is in terms of bytes.

Table 2-8	Scanning	Floating-Point	Modifiers	(%f)
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1 7

Modifier	Meaning	Description
Z	Treat string as floating point	The z floating-point modifier indicates that the data type of the corresponding argument is a string. Nevertheless, the functions treat the data in the string as a floating-point array. The z modifier is valid only if rep is present.
wn	Specify string size	The w floating-point modifier specifies the exact number of bytes occupied by a string representation of the floating-point argument, in the event that the functions convert the value from a string format. You can enter any non-negative value here. If n is less than the number of digits required to represent the floating-point number, the functions insert an asterisk (*) into the string to signify an overflow. The default for n is zero, which indicates that the value can occupy whatever space is necessary.
pn	Specify precision	The p floating-point modifier specifies the number of digits to the right of the decimal point in a string representation of the floating-point number. You can lose significant digits by attempting to conform to the precision specification. If you omit the pn modifier, the default is p6. The p modifier is valid for sources only.
en	Specify as scientific notation	The e floating-point modifier indicates that the string representation of the floating-point value is in scientific notation. If you omit the modifier, the functions use non-scientific notation. n is optional and specifies the number of digits to use in the exponent. For example, f[e2] causes the functions to format 10.0 as 1.0e+01. If you omit n , the functions use a default of three. The e modifier is valid for sources only.
f	Specify as floating point	The f floating-point modifier indicates that the string representation of the floating-point value is not in scientific notation. This is the default even when the f modifier is absent.

 Table 2-8.
 Scanning Floating-Point Modifiers (%f) (Continued)

Modifier	Meaning	Description
x	Discard terminator	The x floating-point modifier causes the functions to discard the character that terminated the numeric data. In this way, the functions can skip terminator characters when reading lists of numeric input. Thus, $3f[x]$ reads three floating-point numbers, disregarding the terminator character that appears after each one. You can use this specifier to scan the string 3.5, 7.6, -32.4.
d	Discard data	When applied to a target specifier, the d modifier indicates no target argument exists to correspond to the target specifier. The data the functions would place in the target argument is discarded instead. The count the functions return <i>includes</i> the target specifier even if you use the d modifier.

Table 2-9.	Scanning	Strina	Modifiers ((%s)
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Modifier	Meaning	Description
in	Specify array offset	The i string modifier specifies an offset within a string. It indicates the location within the string where processing begins. <i>n</i> is the zero-based index of the first byte to process. Thus, $ss[i2]$ applied to a target string begins placing data in the third byte of the string.
a	Append	When applied to a target format specifier, the a string modifier specifies that all formatted data be <i>appended</i> to the target string, beginning at the first occurrence of an ASCII NUL in the target string.

Modifier	Meaning	Description
wn	Specify string size	When applied to a source format specifier, the w string modifier specifies the maximum number of bytes from the source string to use for filling the target arguments. You can enter any non-negative value here. The default is zero, which indicates that the entire string can be used. In this case, the ScanFile and ScanIn functions consume the entire source string even if the w modifier restricts the number of bytes used to fill in the target arguments.
		When modifying a target format specifier, the w modifier specifies the exact number of bytes to store in the string, excluding the terminating ASCII NUL. If n is zero or omitted, the functions store as many bytes as are called for by the sources. When n is greater than the number of bytes available from the source, the remaining bytes are filled with ASCII NULs if you use the q modifier or blanks if you do not use the q modifier.
		When you use the w modifier in conjunction with the a modifier, n indicates the number of bytes to append to the string excluding the terminating ASCII NUL.
q	Append NULs	When applied to a target string in conjunction with the w string modifier, the q string modifier specifies that the functions set unfilled bytes at the end of the target string to ASCII NULs instead of blanks.
У	Append with spacing	When the source is a string and you apply the y modifier to a target string format specifier, the functions fill the target string with bytes from the source string without skipping leading spaces or tabs.

 Table 2-9.
 Scanning String Modifiers (%s) (Continued)

Modifier	Meaning	Description
tn	Terminate on character	When applied to a source string, the t modifier specifies that the source string terminates on the first occurrence of the character <i>n</i> , where <i>n</i> is the ASCII value of the character. Thus, $s [t44]$ stops the reading of the source string on an ASCII comma. More than one t modifier can occur in the same specifier, in which case the string terminates when any of the terminators occur. If no t modifier exists, the functions stop reading the source string on an ASCII NUL.
		When applied to a target string that the functions fill from a source string, the t modifier specifies that the functions stop filling the target on the first occurrence of the character n, where n is the ASCII value of the character. Thus, $ss[t59]$ causes the functions to stop reading the source string on an ASCII semicolon. More than one t modifier can occur in the same specifier, in which case the functions stop filling the target when any of the terminators occur. If no t modifier exists, the functions stop filling the target on any whitespace character.
t-	Terminate when full	This is similar to tn except that it specifies that there are no terminating characters. When applied to a source string, $t-$ specifies that the functions stop reading the source string when all the targets are full or when the functions have read the number of bytes you specify with the w modifier. When applied to a target string, t- specifies that the functions stop filling the target string when the source is exhausted or when the functions have placed into the target the number of bytes you specify with the w modifier.
t#	Terminate on number	This is equivalent to repeating the t modifier with the ASCII values of the characters +, -, and 0–9. When applied to a source (target), it specifies that the functions stop reading the source string, or filling the target string, upon occurrence of a numeric expression. If you use $ss>ss[t#]$ %d with the source string "ab567", the functions place "ab" in the first target and the integer 567 in the second target.

Table 2-9.	Scanning	String	Modifiers	(%S)	(Continued)
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Modifier	Meaning	Description
x	Discard terminator	When applied to a target string, the x modifier specifies that the functions discard the terminating character before the next target is filled in. Using %s>%s[xt59]%s[xt59] with the source string "abc; XYZ; ", the functions place "abc" in the first target and "XYZ" in the second target.
d	Discard data	When applied to a target specifier, the d modifier indicates that no target argument corresponds to the target specifier. The data that the functions otherwise place in the target argument is discarded instead. The count the functions return <i>includes</i> the target specifier even if you use the d modifier.

 Table 2-9.
 Scanning String Modifiers (%s) (Continued)

Scan, ScanFile, ScanIn—Asterisks (*) Instead of Constants in Format Specifiers

Often, a format specifier requires one or more integer values. The format specifier for an integer array, for example, requires the number of elements (rep). You can use constants for these integer values in format specifiers. You can also specify an integer value using an argument in the argument list. When you use this method, substitute an asterisk (*) for the constant in the format specifier

Use the asterisk in the following format specifier elements:

- rep For integer or floating-point arrays
- in For integer or floating-point arrays, or strings
- wn For any format specifier
- pn For floating-point specifiers only
- en For floating-point specifiers only
- rn For integer specifiers only

When you use one or more asterisks instead of constants in a *source* specifier, the arguments that correspond to the asterisks must appear *after* the format string in the same order as the corresponding asterisks appear in the format specifier.

When you use one or more asterisks instead of constants in a *target* specifier, the arguments that correspond to the asterisks must *precede* the target argument and must be in the same order as the corresponding asterisks in the format specifier.

Scan, ScanFile, ScanIn-Literals in the Format String

Literal characters that appear in a scanning function format string indicate that the functions expect the literal characters in the source parameter. The functions do not store them in any target parameter but skip over them when encountered. If a literal character you specify in the format string fails to appear in the source in the expected position, the scanning function returns without processing the target specifiers that appear to the right of the unmatched literal. The scanning functions return the number of target parameters the input actually fulfilled. NumFmtdBytes returns the number of bytes consumed from the source parameter.

Because the left side of the > symbol must be a single format specifier, literal characters, if present, must be on the right side of the symbol. Literals on the left side, or more than one format specifier on the left side, result in a -1 error, indicating a faulty format string. If you receive this error, you can use GetFmtErrNdx to determine exactly where in the format string the error lies.

The characters , [,], <, and > have special meaning in the format strings. To specify that these characters be taken literally, precede them with .

Formatting and I/O Library Programming Examples

This section contains examples of program code that use the Formatting and I/O Library functions. The formatting and scanning functions are the basis of most of the examples.

The Fmt/FmtFile/FmtOut examples are logically organized as shown:

Integer to string Short integer to string Real to string in floating-point notation Real to string in scientific notation Integer and real to string with literals Two integers to ASCII file with error checking Real array to ASCII file in columns and with comma separators Integer array to binary file, assuming a fixed number of elements Real array to binary file, assuming a fixed number of elements Real array to binary file, assuming a variable number of elements Variable portion of a real array to a binary file Concatenating two strings Appending to a string Creating an array of filenames Writing a line that contains an integer with literals to the standard output Writing to the standard output without a linefeed or carriage return

The Scan/ScanFile/ScanIn examples are logically organized as shown:

String to integer String to short integer String to real String to integer and real String to string String to integer and string String to real, skipping over non-numeric characters in the string String to real, after finding a semicolon in the string String to real, after finding a substring in the string String with comma-separated ASCII numbers to real array Scanning strings that are not null-terminated Integer array to real array Integer array to real array with byte swapping Integer array that contains 1-byte integers to real array Strings that contain binary integers to integer array Strings that contain an IEEE-format real number to a real variable ASCII file to two integers with error checking ASCII file with comma-separated numbers to real array, with the number of elements at the beginning of file Binary file to integer array, assuming a fixed number of elements Binary file to real array, assuming a fixed number of elements Binary file to real array, assuming a variable number of elements Reading an integer from the standard input Reading a string from the standard input Reading a line from the standard input

Fmt/FmtFile/FmtOut Examples in C

This section contains examples of program code that use Fmt, FmtFile, and FmtOut from the Formatting and I/O Library. To eliminate redundancy, error checking on I/O operations has been omitted from all the examples in this section except the *Two Integers to ASCII File with Error Checking* example.

Integer to String

```
char buf[10];
int a;
a = 16;
Fmt (buf, "%s<%i", a); /* result: "16" */
a = 16;
Fmt (buf, "%s<%x", a); /* result: "10" */
a = 16;
```

```
Fmt (buf, "%s<%o", a); /* result: "20" */
a = -1;
Fmt (buf, "%s<%i", a); /* result: "-1" */
a = -1;
Fmt (buf, "%s<%i[u]", a); /* result: "4294967295" */
a = 1234;
Fmt (buf, "%s<%i[w6]", a); /* result: "1234" */
a = 1234;
Fmt (buf, "%s<%i[w6p0]", a); /* result: "001234" */
a = 1234;
Fmt (buf, "%s<%i[w2]", a); /* result: "*4" */</pre>
```

The results shown are the contents of buf after each call to Fmt. The last call demonstrates what occurs when the w modifier specifies a width that is too small.

Short Integer to String

```
char buf[20];
short a;
a = 12345;
Fmt (buf, "%s<%i[b2]", a); /* result: "12345" */
a = -1;
Fmt (buf, "%s<%i[b2]", a); /* result: "-1" */
a = -1;
Fmt (buf, "%s<%i[b2u]", a); /* result: "65535" */
a = 12345;
Fmt (buf, "%s<%i[b2w7]", a); /* result: "12345" */
a = 12345;
Fmt (buf, "%s<%i[b2w7p0]", a); /* result: "0012345" */
a = 12345;
Fmt (buf, "%s<%i[b2w7p0]", a); /* result: "0012345" */
a = 12345;
Fmt (buf, "%s<%i[b2w4]", a); /* result: "*345" */</pre>
```

The results shown are the contents of buf after each call to Fmt. The last call demonstrates what occurs when the w modifier specifies a width that is too small.

Real to String in Floating-Point Notation

```
char buf[30];
double x;
x = 12.3456789;
Fmt (buf, "%s<%f", x); /* result: "12.345679" */
x = 12.3456789;
Fmt (buf, "%s<%f[p2]", x); /* result: "12.35" */
x = 12.3456789;
Fmt (buf, "%s<%f[p10]", x); /* result: "12.3456789000" */
x = 12.345;
Fmt (buf, "%s<%f", x); /* result: "12.345" */
x = 12.345;
Fmt (buf, "%s<%f[p0]", x); /* result: "12" */</pre>
x = 12.345;
Fmt (buf, "%s<%f[p6]", x); /* result: "12.345000" */</pre>
x = -12.345;
Fmt (buf, "%s<%f[w12]", x); /* result: " -12.345" */</pre>
x = -12.3456789;
Fmt (buf, "%s<%f[w6]", x); /* result: "-12.3*" */</pre>
x = 0.0000012;
Fmt (buf, "%s<%f[p8]", x); /* result: "0.00000012" */</pre>
x = 0.0000012;
Fmt (buf, "%s<%f", x); /* result: "1.2e-007" */
x = 4.5e050;
Fmt (buf, "%s<%f", x); /* result: "4.5e050" */
```

The results shown are the contents of buf after each call to Fmt. The last two calls demonstrate that Fmt sometimes forces very large and very small values into scientific notation even when the e modifier is absent.

Real to String in Scientific Notation

```
char buf[20];
double x;
x = 12.3456789;
Fmt (buf, "%s<%f[e]", x); /* result: "1.234568e+001" */
x = 12.3456789;
Fmt (buf, "%s<%f[ep2]", x); /* result: "1.23e+001" */
x = 12.3456789;
Fmt (buf, "%s<%f[e2p2]", x); /* result: "1.23e+01" */
x = 12.345;
Fmt (buf, "%s<%f[e]", x); /* result: "1.2345e+001" */
x = 12.345;
Fmt (buf, "%s<%f[ep2w12]", x); /* result: "1.23e+001" */</pre>
```

```
x = 12.345;
Fmt (buf, "%s<%f[ep2w6]", x); /* result: "1.23e*" */</pre>
```

The results shown are the contents of buf after each call to Fmt. The last call demonstrates what occurs when the w modifier specifies a width that is too small.

Integer and Real to String with Literals

```
char buf[20];
int f, r;
double v;
f = 4;
r = 3;
v = 1.2;
Fmt (buf, "%s<F%iR%i; V%f;", f, r, v);</pre>
```

After the Fmt call, buf contains "F4R3; V1.2;".

Two Integers to ASCII File with Error Checking

```
int a, b, n, file_handle;
a = 12;
b = 456;
file_handle = OpenFile ("FILE.DAT", 2, 0, 1);
if (file_handle < 0) {
    FmtOut ("Error opening file\n");
    exit (1);
}
n = FmtFile (file_handle, "%s<%i %i", a, b);
if (n != 2) {
    FmtOut ("Error writing file\n");
    exit (1);
}
CloseFile (file_handle);
```

OpenFile opens the file FILE.DAT as an ASCII file for writing only. If OpenFile succeeds, it returns a file handle with a positive integer value. FmtFile writes the ASCII representation of two integer values to the file. If FmtFile succeeds, it returns 2 because the format string contains two source specifiers.

Real Array to ASCII File in Columns and with Comma Separators

```
double x[100];
int file_handle, i;
file_handle = OpenFile ("FILE.DAT", 2, 0, 1);
```

```
for (i=0; i < 100; i++) {
    FmtFile (file_handle, "%s<%f[w15],", x[i]);
    if ((i % 5) == 4)
        WriteFile (file_handle, "\n", 1);
}
CloseFile (file_handle);</pre>
```

The FmtFile call writes the ASCII representation of a real array element to the file, followed by a comma. The w modifier specifies that the number be right-justified in a 15-character field. The WriteFile call writes a linefeed to the file after every fifth call to FmtFile. Because the file is opened in ASCII mode, FmtFile automatically writes the linefeed as a linefeed/carriage return combination.

Note

If the format string is "%s[w15]<%f, ", FmtFile left-justifies the number and the comma together in a 15-character field.

Integer Array to Binary File, Assuming a Fixed Number of Elements

```
int readings[100];
int file_handle, nbytes;
file_handle = OpenFile ("FILE.DAT", 2, 0, 0);
FmtFile (file_handle, "%100i<%100i", readings);
nbytes = NumFmtdBytes ();
CloseFile (file_handle);
```

The FmtFile call writes all 100 elements of the readings integer array to a file in binary form. If the FmtFile call succeeds, nbytes = 200 (100 integers, 2 bytes per integer).

Real Array to Binary File, Assuming a Fixed Number of Elements

```
double waveform[100];
int file_handle, nbytes;
file_handle = OpenFile ("FILE.DAT", 2, 0, 0);
FmtFile (file_handle, "%100f<%100f", waveform);
nbytes = NumFmtdBytes ();
CloseFile (file_handle);
```

The FmtFile call writes all 100 elements of the waveform real array to a file in binary form. If the FmtFile call succeeds, nbytes = 800 (100 integers, 8 bytes per real number).

Real Array to Binary File, Assuming a Variable Number of Elements

```
void StoreArray (double x[], int count, char filename[])
{
    int file_handle;
    file_handle = OpenFile (filename, 2, 0, 0);
    FmtFile (file_handle, "%*f<%*f", count, count, x);
    CloseFile (file_handle);
}</pre>
```

This example shows how you can use a function to write an array of real numbers to a binary file. The function parameters are a real array, the number of elements to be written, and the filename.

The FmtFile call writes the first count elements of x to a file in binary form. FmtFile matches the two asterisks (*) in the format string to count. For instance, if count is 100, the format string is equivalent to 100f<100f.

Variable Portion of a Real Array to a Binary File

```
void StoreSubArray (double x[], int start, int count, char filename[])
{
    int file_handle;
    file_handle = OpenFile (filename, 2, 0, 0);
    FmtFile (file_handle, "%*f<%*f[i*]", count, count, start, x);
    CloseFile (file_handle);
}</pre>
```

This example is an extension of the previous example. The function writes a variable number of elements of a real array to a file. Instead of beginning at the first element of the array, you pass a starting index to the function.

The FmtFile call writes count elements of x, starting from x[start], to a file in binary form. FmtFile matches the first two asterisks (*) in the format string to count. FmtFile matches the third asterisk to start. For instance, if count is 100 and start is 30, the format string is equivalent to %100f<%100f[i30]. Because the i modifier specifies a zero-based index into the real array, FmtFile writes the array elements from x[30] through x[129] to the file.

Concatenating Two Strings

```
char buf[30];
int wave_type, signal_output;
char *wave_str, *signal_str;
int nbytes;
wave_type = 1;
signal_output = 0;
switch (wave_type) {
   case 0:
      wave_str = "SINE;"
      break;
   case 1:
      wave_str = "SQUARE;"
      break;
   case 2:
       wave_str = "TRIANGLE;"
      break;
}
switch (signal_output) {
   case 0:
       signal_str = "OUTPUT OFF;"
      break;
   case 1:
       signal_str = "OUTPUT ON;"
       break;
}
Fmt (buf, "%s<%s%s", wave_str, signal_str);</pre>
nbytes = NumFmtdBytes ();
```

The two switch constructs assign constant strings to the string variables wave_str and signal_str. The Fmt call concatenates the contents of wave_str and signal_str into buf. After the call, buf contains "SQUARE;OUTPUT OFF;". NumFmtdBytes returns the number of bytes in the concatenated string.

Appending to a String

```
char buf[30];
int wave_type, signal_output;
int nbytes;
switch (wave_type) {
   case 0:
       Fmt (buf, "%s<SINE;");</pre>
       break;
   case 1:
       Fmt (buf, "%s<SQUARE;");</pre>
       break;
   case 2:
       Fmt (buf, "%s<TRIANGLE;");</pre>
       break;
}
switch (signal_output) {
   case 0:
       Fmt (buf, "%s[a]<OUTPUT OFF;");</pre>
       break;
   case 1:
       Fmt (buf, "%s[a]<OUTPUT ON;");</pre>
       break;
}
nbytes = StringLength (buf);
```

This example shows how to append characters to a string without writing over the existing contents of the string. The first switch construct writes one of three strings into buf. The second switch construct appends one of two strings to the string already in buf. After the call, buf contains "SQUARE; OUTPUT OFF; ". Notice that the a modifier applies to the target specifier.

StringLength returns the number of bytes in the resulting string. In this case, Fmt uses StringLength instead of NumFmtdBytes, because NumFmtdBytes returns only the number of bytes appended.

Creating an Array of Filenames

```
char *fname_array[4];
int i;
for (i=0; i < 4; i++) {
    frame_array[i] = malloc(14);
    Fmt (fname_array[i], "%s<FILE%i[w4p0].DAT", i);
}
```

To allocate the space for each filename in the array, you must assign a separate constant string to each array element. Use Fmt to format each filename. The resulting filenames are FILE0000.DAT, FILE0001.DAT, FILE0002.DAT, and FILE0003.DAT.

Writing a Line That Contains an Integer with Literals to the Standard Output

```
int a, b;
a = 12;
b = 34;
FmtOut ("%s<A = %i\n", a);
FmtOut ("%s<B = %i\n", b);</pre>
```

In this example, the output is as follows:

```
\begin{array}{rcl} A &=& 12 \\ B &=& 34 \end{array}
```

Writing to the Standard Output without a Linefeed or Carriage Return

```
char *s;
int b;
double c;
a = "One";
FmtOut ("%s<%s", a);
b = 2;
FmtOut ("%s<%i", b);
c = 3.4;
FmtOut ("%s<%f", c);</pre>
```

This example demonstrates how to write to the Standard Output without a linefeed or carriage return by omitting the 'n' from the format string. The output in this example is as follows:

One 2 3.4

```
The following code produces the same output:
```

```
a = "One";
b = 2;
c = 3.4;
FmtOut ("%s<%s %i %f", a, b, c);</pre>
```

Scan/ScanFile/ScanIn Examples in C

This section contains examples of program code that use Scan, ScanFile, and ScanIn from the Formatting and I/O Library. To eliminate redundancy, the examples include no error checking on I/O operations in this section except for the *ASCII File to Two Integers with Error Checking* example.

String to Integer

When locating an integer in a string, Scan skips over white space characters such as spaces, tabs, linefeeds, and carriage returns. If Scan finds a non-numeric character other than a white space character, +, or – before the first numeric character, the Scan call fails. Thus, Scan fails on the x in x32; it leaves the value unmodified in a and returns zero, indicating that no target specifiers were satisfied.

When you use the %i specifier, Scan interprets numeric characters as decimal, even when they might appear to be octal (as in 032) or hexadecimal (as in 32a). When you use the %o specifier, Scan always interprets the numeric characters (01234567) as octal. When you

use the %x specifier, Scan always interprets the numeric characters (0123456789abcdef) as hexadecimal.

Scan considers the occurrence of a non-numeric character (such as the x in 32x1) to mark the end of the integer.

The w3 modifier specifies that the function only scans the first 3 bytes of the string.

String to Short Integer

```
char *s;
short a;
int n;
s = "9999";
n = Scan (s, "%s>%i[b2]", &a);  /* result: a = 9999, n = 1 */
s = "23417";
n = Scan (s, "%s>%o[b2]", &a);  /* result: a = 9999, n = 1 */
s = "ffff";
n = Scan (s, "%s>%x[b2]", &a);  /* result: a = 65535, n = 1 */
```

Scan extracts short integers from strings in the same way it extracts integers. The only differences are that you must use the b2 modifier and specify the target argument as a short integer. Refer to the *String to Integer* example earlier in this section for more information on using Scan to extract integers and short integers from strings.

String to Real

When locating a real number in a string, Scan accepts either floating-point notation or scientific notation.

When locating a real number in a string, Scan skips over white space characters. If Scan finds a non-numeric character other than a white space character, +, or - before the first numeric character, the Scan call fails. Thus, Scan fails on the p in p12.3; it leaves the value in x unmodified and returns zero, indicating that no target specifiers were satisfied.

Scan considers the occurrence of a non-numeric character (such as the m in 12.3m) to mark the end of the real number. A second decimal point also marks the end of the number. However, Scan fails on "1.23e" because the value of the exponent is missing.

```
s = "1.2345";
n = Scan (s, "%s>%f[w4]", &x); /* result: x = 1.23, n = 1 */
```

The w4 modifier specifies that the function scans only the first 4 bytes of the string.

String to Integer and Real

After each of the first two calls to Scan, a = 32, x = 1.23, and n = 2, indicating that two target specifiers were satisfied. In the second call, Scan uses the x modifier is used to discard the separating comma.

In the third call, a comma separator appears after the integer, but the x modifier is absent. Consequently, Scan fails when attempting to find the real number. x remains unmodified, and n = 1, indicating that only one target specifier was satisfied.

String to String

When extracting a substring from a string, Scan skips leading spaces and tabs unless the y modifier is present.

When Scan extracts a substring from a string and the t modifier is absent, Scan considers the substring to be terminated by a white space character. To include embedded white space in the target string, use the t modifier to change the target string termination character. In the second call to Scan, [t59] changes the termination character to a semicolon (ASCII 59).

The w modifier can be used to prevent Scan from writing beyond the end of a target string. The width specified does not include the ASCII NUL that Scan places at the end of the target string. Therefore, the width you specify should be at least one less than the width of the target character buffer.

When you use the w modifier and the string extracted is smaller than the width specified, Scan fills the remaining bytes in the target string with blanks. However, if you also use the q modifier, ASCII NULs fill the remaining bytes.

String to Integer and String

After the first call to Scan, a = 32, buf = "abc", and n = 2. Notice there are no spaces in the format string between the two target specifiers. In the second call, there is a space between %i and %s. Consequently, Scan expects a space to occur in s immediately after the integer. Because there is no space in s, Scan fails at that point. It leaves buf unmodified and returns 1, indicating that only one target specifier is satisfied.

📬 Note

Do not put spaces between specifiers in Scan, ScanFile, or ScanIn format strings.

String to Real, Skipping over Non-Numeric Characters in the String

```
char *s;
double x;
int n;
s = "VOLTS = 1.2";
n = Scan (s, "%s>%s[dt#]%f", &x); /* result: x = 1.2, n = 2 */
s = "VOLTS = 1.2";
n = Scan (s, "%s[i8]>%f", &x); /* result: x = 1.2, n = 1 */
s = "VOLTS = 1.2";
n = Scan (s, "%s>VOLTS = %f", &x); /* result: x = 1.2, n = 1 */
```

The three different format strings represent different methods for skipping over non-numeric characters. In the first call, the format string contains two target specifiers. In the first specifier (%s[dt#]), the t# modifier instructs Scan to read bytes from s until it encounters a number. The d modifier tells Scan to discard the bytes because no argument corresponds to the specifier. When the Scan call succeeds, it returns 2, indicating that two target specifiers were satisfied, even though only one target argument exists.

In the second call, the source specifier <code>%s[i8]</code> instructs <code>Scan</code> to ignore the first 8 bytes of s. This method works only if the location of the number within s is always the same.

In the third call, the format string contains the non-numeric characters literally. This method works only if the non-numeric characters in s are always the same.

String to Real, after Finding a Semicolon in the String

```
char *s;
double x;
int n;
s = "TIME 12:45:00; 7.34";
n = Scan (s, "%s>%s[xdt59]%f", &x); /* result: x = 7.34, n = 2 */
```

Some programmable instruments return strings that contain headers that contain both numeric and non-numeric data and are terminated by a particular character, such as a semicolon. This example shows how you can skip such a header.

The format string contains two target specifiers. In the first specifier (s[xdt#]), the t# modifier instructs Scan to read bytes from s until it encounters a number. The d modifier indicates that Scan must discard the bytes because no argument corresponds to the specifier. The x modifier indicates that the semicolon should also be discarded.

When the Scan call succeeds, it returns 2, indicating that two target specifiers were satisfied, even though only one target argument exists.

String to Real, after Finding a Substring in the String

This example is similar to the previous one except that the portion of the string to skip is terminated by a substring (DATA) rather than by a single character. FindPattern finds the index where DATA begins in s. You add four to the index so that it points to the first byte after DATA. You then pass the index to Scan and match it with the asterisk (*) in the format string.

In this example, FindPattern returns 15, and index is 19. When you match index to the asterisk in the format string in the Scan call, Scan interprets the format string as %s[i19]>%f. The i19 indicates that Scan should ignore the first 19 bytes of s. Scan then

extracts the real number from the remaining string, 3.71E+2, and assigns it to x. Scan returns 1, indicating that one target specifier is satisfied.

String with Comma-Separated ASCII Numbers to Real Array

The x modifier causes Scan to discard the comma separators.

Scan considers an array target to be satisfied when at least one element of the array is filled in. If the source string in this example were 12.3, only the first element of a would be filled in, the other elements would remain unmodified, and Scan would return 1.

Scanning Strings That Are Not Null-Terminated

```
int bd;
double x;
char s[20];
ibrd (bd, s, 15);
Scan (s, "%s[w*]>%f", ibcnt, &x);
```

All the previous examples assume that s is a null-terminated string. However, when reading data from programmable instruments using the GPIB and RS-232 Library functions, the data transferred is not null-terminated. This example uses ibrd to read up to 15 bytes from a GPIB instrument. The global variable ibcnt contains the actual number of bytes transferred. Scan uses the value in ibcnt in conjunction with the w modifier to specify the width of the source string.

For example, if ibent is 12, the format string is interpreted as s[w12], causing Scan to use only the first 12 bytes of s.

The following example is an alternative method for handling strings that are not null-terminated:

This code shows how to insert an ASCII NUL at the end of the transferred bytes. After the assignment, s is null-terminated.

Integer Array to Real Array

```
int ivals[100];
double dvals[100];
Scan (ivals, "%100i>%100f", dvals);
```

Scan converts each integer in ivals to a real number and writes it into dvals.

Integer Array to Real Array with Byte Swapping

```
int ivals[100];
double dvals[100];
Scan (ivals, "%100i[o10]>%100f", dvals);
```

For each integer in ivals, Scan byte-swaps it, converts it to a real number, and writes it into dvals.

Byte swapping is useful when a programmable instrument sends back 2-byte integers with the high byte first, followed by the low byte. When Scan reads this data into an integer array, the placement of the bytes is such that Scan interprets the high byte as the low byte. The o10 modifier specifies that Scan interprets the bytes in the opposite order.

Integer Array That Contains 1-Byte Integers to Real Array

Sometimes, Scan uses each element in an integer array to store two 1-byte integers. This example shows how to unpack the 1-byte integers and store them in a real array. The b1 indicates that each binary integer is only 1 byte long.

The first call to Scan treats the 1-byte integers as signed values, from -128 to +127. The second call includes a u in the format string, which causes Scan to treat the 1-byte integers as unsigned values, from 0 to 255.

Strings That Contain Binary Integers to Integer Array

Sometimes Scan reads data from a programmable instrument into a character buffer even though it contains binary data. This example shows how to treat a character buffer as an integer array. The format string in each Scan call specifies that the source s contains an array of 100 integers. The z modifier indicates that the source is actually a character buffer.

In some cases, the integer data might not start at the beginning of the character buffer. For instance, the data in the buffer can begin with an ASCII header. In the second call to Scan, the i6 modifier indicates that Scan should ignore the first 6 bytes of s.

Note When you use the *i* modifier in conjunction with a character buffer, the number that follows the *i* specifies the number of bytes within the buffer to ignore. This is true even when the *z* modifier is also present. On the other hand, when you use the *i* modifier in conjunction with an array variable, the number that follows the *i* indicates the number of array elements to ignore.

Strings That Contain an IEEE-Format Real Number to a Real Variable

```
char s[100];
double x;
Scan (s, "%1f[z]>%f", &x);
Scan (s, "%1f[zi5]>%f", &x);
```

This example is similar to the previous example except that s contains a single binary real number (in IEEE format) rather than an array of binary integers. The format string in each Scan call indicates that Scan treats the source s as a one-element array of real numbers. The z modifier indicates that the source is actually a character buffer. The repetition count of 1 in the format string is required; otherwise, Scan does not accept the z modifier.

The first call to Scan assumes that the real number is at the beginning of s. The second call assumes that the real number starts at the sixth byte of s. The i5 modifier causes Scan to ignore the first 5 bytes of s.

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ASCII File to Two Integers with Error Checking

```
int file_handle, n, a, b;
file_handle = OpenFile ("FILE.DAT", 1, 2, 1);
if (file_handle < 0) {
    FmtOut ("Error opening file\n");
    exit (1);
}
n = ScanFile (file_handle, "%s>%i%i", &a, &b);
if (n != 2) {
    FmtOut ("Error reading file\n");
    exit (1);
}
CloseFile (file_handle);
```

OpenFile opens the file FILE.DAT as an ASCII file for reading only. If OpenFile succeeds in opening the file, it returns a file handle with a positive integer value. ScanFile reads the ASCII representation of two integer values from the file. If ScanFile succeeds, it returns 2, indicating that two target specifiers were satisfied.

ASCII File with Comma-Separated Numbers to Real Array, with Number of Elements at Beginning of File

```
double values[1000];
int file_handle, count;
file_handle = OpenFile ("FILE.DAT", 1, 2, 1);
ScanFile (file_handle, "%s>%i", &count);
if (count > 1000) {
    FmtOut ("Count too large\n");
    exit(1);
}
ScanFile (file_handle, "%s>%*f[x]", count, values);
CloseFile (file_handle);
```

The first ScanFile call reads the number of elements into the integer variable count. If the value in count exceeds the number of elements in the real array values, ScanFile reports an error. Otherwise, the second ScanFile call matches count to the asterisk (*) in the format string. It then reads the correct number of elements into values. The x modifier causes ScanFile to discard the comma separators.

Binary File to Integer Array, Assuming a Fixed Number of Elements

```
int readings[100];
int file_handle, nbytes;
file_handle = OpenFile ("FILE.DAT", 1, 2, 0);
ScanFile (file_handle, "%100i>%100i", readings);
nbytes = NumFmtdBytes ();
CloseFile (file_handle);
```

The ScanFile call reads 100 integers from a binary file and stores them in the integer array readings. If the ScanFile call is successful, nbytes = 400 (100 integers, 4 bytes per integer).

Binary File to Real Array, Assuming a Fixed Number of Elements

```
double waveform[100];
int file_handle, nbytes;
file_handle = OpenFile ("FILE.DAT", 1, 2, 0);
ScanFile (file_handle, "%100f>%100f", waveform);
nbytes = NumFmtdBytes ();
CloseFile (file_handle);
```

The ScanFile call reads 100 real numbers from a binary file and stores them in the real array waveform. If the ScanFile call is successful, nbytes = 800 (100 integers, 8 bytes per real number).

Binary File to Real Array, Assuming a Variable Number of Elements

```
void StoreArray (double x[], int count, char filename[])
{
    int file_handle;
    file_handle = OpenFile (filename, 1, 2, 0);
    ScanFile (file_handle, "%*f>%*f", count, count, x);
    CloseFile (file_handle);
}
```

This example shows how you can use a subroutine to read an array of real numbers from a binary file. The subroutine takes as parameters a real array, the number of elements to be read, and the filename.

The ScanFile call reads the first count elements of x from a binary file. ScanFile matches the two asterisks (*) in the format string to count. For instance, if count is 100, the format string is equivalent to %100f>100f.

Reading an Integer from the Standard Input

```
int n, num_readings;
n = 0;
while (n != 1) {
    FmtOut ("Enter number of readings: ");
    n = ScanIn ("%1>%i", &num_readings);
}
```

This example shows how to get user input from the keyboard. The FmtOut call writes the prompt string to the screen without a linefeed or carriage return. The ScanIn call attempts to read an integer value from the keyboard and place it in num_readings. If ScanIn succeeds, it returns 1, and FmtOut exits the loop. Otherwise, FmtOut repeats the prompt string.

The format string in the ScanIn call contains a source specifier of %1. This has two consequences. First, ScanIn returns whenever the user presses <Enter>, even if the input line is empty. This allows the prompt string to repeat at the beginning of each line until the user enters an integer value. ScconIn discards any characters entered after the integer value.

Reading a String from the Standard Input

```
char filename[41];
int n;
n = 0;
while (n != 1) {
    FmtOut ("Enter file name: ");
    n = ScanIn ("%1>%s[w40q]", filename);
}
```

This example is similar to the previous example except that ScanIn reads a string from the keyboard instead of an integer. The w modifier prevents ScanIn from writing beyond the end of filename. Notice that the width specified is one less than the size of filename. This allows room for the ASCII NUL that ScanIn appends at the end of filename. The q modifier causes ScanIn to fill any unused bytes at the end of filename with ASCII NULs. Without the q modifier, all unused bytes are filled with spaces, except for the ASCII NUL at the end.

The call to ScanIn in this example skips over leading spaces and tabs and terminates the string on an embedded space. For other options, refer to the *String to String* example earlier in this section.

Reading a Line from the Standard Input

```
char buf[81];
nbytes = ReadLine (0, buf, 80);
```

The previous two examples show how to read single items from the keyboard. When you are prompted to enter several items on one line, it is often easier to read the entire line into a buffer before parsing it. You can do this using ReadLine.

The first parameter to ReadLine is a file handle. In this case, the file handle is zero, which is the handle reserved for the Standard Input. The other two parameters are a buffer and the maximum number of bytes to place in the buffer. ReadLine always appends an ASCII NUL at the end of the bytes read. Thus, the maximum number of bytes passed to ReadLine must be one less than the size of the buffer.

ReadLine transfers every character from the input line to the buffer, including leading spaces, embedded spaces, and trailing spaces, until ReadLine transfers the maximum number of bytes (for example, 80). ReadLine discards any remaining characters at the end of the line. ReadLine never transfers the linefeed to the buffer.

ReadLine returns the number of bytes read, including the bytes discarded but excluding the linefeed.

Analysis Library

This chapter describes the functions in the LabWindows/CVI Analysis Library. The *Analysis Library Function Overview* section contains general information about the Analysis Library functions and panels. The *Analysis Library Function Reference* section contains an alphabetical list of the function descriptions.

Analysis Library Function Overview

The Analysis Library includes functions for 1D and 2D array manipulation, complex operations, matrix operations, and statistics. This section contains general information about the Analysis Library functions and panels.

Analysis Library Function Panels

The Analysis Library function panels are grouped in the tree structure in Table 3-1 according to the types of operations they perform.

The first- and second-level headings in the tree are the names of function classes and subclasses. Function classes and subclasses are groups of related function panels. The third-level headings are the names of individual function panels. Each analysis function panel generates one analysis function call.

Class/Panel Name	Function Name
Array Operations	
1D Operations	
Clear Array	Clear1D
Set Array	Set1D
Copy Array	Copy1D
1D Array Addition	Add1D
1D Array Subtraction	Sub1D
1D Array Multiplication	Mul1D
1D Array Division	Div1D
1D Absolute Value	Abs1D
1D Negative Value	Neg1D
1D Linear Evaluation	LinEv1D
1D Maximum & Minimum	MaxMin1D

Table 3-1. Functions in the Analysis Library Function Tree

Class/Panel Name	Function Name
Array Operations (continued)	
1D Operations (continued)	
1D Array Subset	Subset1D
1D Sort Array	Sort
2D Operations	
2D Array Addition	Add2D
2D Array Subtraction	Sub2D
2D Array Multiplication	Mul2D
2D Array Division	Div2D
2D Linear Evaluation	LinEv2D
2D Maximum & Minimum	MaxMin2D
Complex Operations	
Complex Numbers	
Complex Addition	CxAdd
Complex Subtraction	CxSub
Complex Multiplication	CxMul
Complex Division	CxDiv
Complex Reciprocal	CxRecip
Rectangular to Polar	ToPolar
Polar to Rectangular	ToRect
1D Complex Operations	
1D Complex Addition	CxAdd1D
1D Complex Subtraction	CxSub1D
1D Complex Multiplication	CxMullD
1D Complex Division	CxDiv1D
1D Complex Linear Evaluation	CxLinEv1D
1D Rectangular to Polar	ToPolar1D
1D Polar to Rectangular	ToRect1D
Statistics	
Mean	Mean
Standard Deviation	StdDev
Histogram	Histogram
Vector & Matrix Algebra	
Dot Product	DotProduct
Transpose	Transpose
Determinant	Determinant
Invert Matrix	InvMatrix
Multiply Matrix	MatrixMul
Get Error String	GetAnalysisErrorString

 Table 3-1.
 Functions in the Analysis Library Function Tree (Continued)

Class and Subclass Descriptions

- The Array Operations function panels perform arithmetic operations on 1D and 2D arrays.
 - 1D Operations, a subclass of Array Operations, contains function panels that perform 1D array arithmetic.
 - 2D Operations, a subclass of Array Operations, contains function panels that perform 2D array arithmetic.
- The Complex Operations function panels perform complex arithmetic operations. The Complex Operations function panels can operate on complex scalars or 1D arrays. The functions process the real and imaginary parts of complex numbers separately.
 - Complex Numbers, a subclass of Complex Operations, contains function panels that perform scalar complex arithmetic.
 - 1D Complex Operations, a subclass of Complex Operations, contains function panels that perform complex arithmetic on 1D complex arrays.
- The Statistics function panels perform basic statistics functions.
- The Vector & Matrix Algebra function panels perform vector and matrix operations. Vectors and matrices are represented by 1D and 2D arrays, respectively.
- The Array Utilities function panels copy, initialize, and clear arrays.
- Miscellaneous is a class of function panels for miscellaneous Analysis Library functions.

The online help with each panel contains specific information about using each function panel.

Hints for Using Analysis Function Panels

With the analysis function panels, you can manipulate scalars and arrays of data interactively. You might find it helpful to use the Analysis Library function panels in conjunction with the User Interface Library function panels to view the results of analysis routines. When using the Analysis Library function panels, remember the following:

- The computer on which you run LabWindows/CVI affects the processing speed of the analysis functions. A numeric coprocessor, especially, increases the speed of floating-point computations. If you are using an Analysis Library function panel and nothing seems to happen for an unusually long time, remember the constraints of your hardware.
- Many analysis routines for arrays run in place. That is, the functions can store the input and output data in the same array. This point is important to keep in mind when you process large amounts of data. Large double-precision arrays consume a lot of memory. If the results you want do not require that you keep the original array or intermediate arrays of data, perform analysis operations in place where possible.
- The Interactive window maintains a record of generated code. If you forget to keep the code from a function panel, you can cut and paste code between the Interactive and Program windows.

The online help with each panel contains specific information about operating each function panel.

Reporting Analysis Errors

The functions in the Analysis Library return status information through a return value.

If the return value **status** is zero after an Analysis Library function call, the function properly executed with no errors. Otherwise, the functions set **status** to the appropriate error value. Table 3-2 at the end of this chapter lists error messages that correspond to the possible **status** values.

Analysis Library Function Reference

This section describes each function in the LabWindows/CVI Analysis Library in alphabetical order.

Abs1D

int status = Abs1D (double x[], int n, double y[]);

Purpose

Finds the absolute value of the x input array. Abs1D can perform the operation in place; that is, x and y can be the same array.

Parameters

Input

Name	Туре	Description
x	double-precision array	Input array.
n	integer	Number of elements.

Output

Name	Туре	Description
У	double-precision array	Absolute value of input array.

Return Value

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Add1D

```
int status = Add1D (double x[], double y[], int n, double z[]);
```

Purpose

Adds 1D arrays. Add1D obtains the i^{th} element of the output array using the following formula:

 $z_i = x_i + y_i$

Add1D can perform the operation in place; that is, z can be the same array as either x or y.

Parameters

Input

Name	Туре	Description
x	double-precision array	Input array.
У	double-precision array	Input array.
n	integer	Number of elements to add.

Output

Name	Туре	Description
Z	double-precision array	Result array.

Return Value

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Add2D

int status = Add2D (void *x, void *y, int n, int m, void *z);

Purpose

Adds 2D arrays. Add2D obtains the (i, j)th element of the output array using the following formula:

$$z_{i,j} = x_{i,j} + y_{i,j}$$

Add2D can perform the operation in place; that is, z can be the same array as either x or y.

Parameters

Input

Name	Туре	Description
X	double-precision 2D array	Input array.
У	double-precision 2D array	Input array.
n	integer	Number of elements in first dimension.
m	integer	Number of elements in second dimension.

Output

Name	Туре	Description
Z	double-precision 2D array	Result array.

Return Value

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Clear1D

```
int status = Clear1D (double x[], int n);
```

Purpose

Sets the elements of the \mathbf{x} array to 0.0.

Parameters

Input

Name	Туре	Description
n	integer	Number of elements in x .

Output

Name	Туре	Description
x	double-precision array	Cleared array.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Copy1D

int status = Copy1D (double x, int n, double y[]);

Purpose

Copies the elements of the x array. Use Copy1D to duplicate arrays for in place operations.

Parameters

Input

Name	Туре	Description
X	double-precision array	Input array.
n	integer	Number of elements in x .

Output

Name	Туре	Description
У	double-precision array	Duplicated array.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

CxAdd

Purpose

Adds two complex numbers, x and y. CxAdd obtains the resulting complex number, z, using the following formulas:

$$zr = xr + yr$$
$$zi = xi + yi$$

Parameters

Input

Name	Туре	Description
xr	double-precision	Real part of <i>x</i> .
xi	double-precision	Imaginary part of <i>x</i> .
yr	double-precision	Real part of <i>y</i> .
yi	double-precision	Imaginary part of <i>y</i> .

Output

Name	Туре	Description
zr	double-precision pointer	Real part of <i>z</i> .
zi	double-precision pointer	Imaginary part of <i>z</i> .

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

CxAdd1D

Purpose

Adds two 1D complex arrays, **x** and **y**. CxAdd1D obtains the i^{th} element of the resulting complex array, **z**, using the following formulas:

$$zr_i = xr_i + yr_i$$
$$zi_i = xi_i + yi_i$$

CxAdd1D can perform the operations in place; that is, the input and output complex arrays can be the same.

Parameters

Input

Name	Туре	Description
xr	double-precision array	Real part of x .
xi	double-precision array	Imaginary part of x .
yr	double-precision array	Real part of y .
yi	double-precision array	Imaginary part of y .
n	integer	Number of elements.

Output

Name	Туре	Description
zr	double-precision array	Real part of z .
zi	double-precision array	Imaginary part of z .

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

CxDiv

Purpose

Divides two complex numbers, *x* and *y*. CxDiv obtains the resulting complex number, *z*, using the following formulas:

$$zr = \frac{(xr \times yr + xi \times yi)}{yr^2 + yi^2}$$
$$zi = \frac{(xi \times yr - xr \times yi)}{yr^2 + yi^2}$$

Parameters

Input

Name	Туре	Description
xr	double-precision	Real part of <i>x</i> .
xi	double-precision	Imaginary part of <i>x</i> .
yr	double-precision	Real part of <i>y</i> .
yi	double-precision	Imaginary part of <i>y</i> .

Output

Name	Туре	Description
zr	double-precision	Real part of <i>z</i> .
zi	double-precision	Imaginary part of <i>z</i> .

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

CxDiv1D

Purpose

Divides two 1D complex arrays, **x** and **y**. CxDiv1D obtains the i^{th} element of the resulting complex array, **z**, using the following formulas:

$$zr_{i} = \frac{(xr_{i} \times yr_{i} + xi_{i} \times yi_{i})}{yr_{i}^{2} + yi_{i}^{2}}$$
$$zi_{i} = \frac{(xi_{i} \times yr_{i} - xr_{i} \times yi_{i})}{yr_{i}^{2} + yi_{i}^{2}}$$

zr can be in place with xr; zi can be in place with xi.

Parameters

Input

Name	Туре	Description
xr	double-precision array	Real part of x .
xi	double-precision array	Imaginary part of x .
yr	double-precision array	Real part of y .
yi	double-precision array	Imaginary part of y .
n	integer	Number of elements.

Output

Name	Туре	Description
zr	double-precision array	Real part of z .
zi	double-precision array	Imaginary part of z .

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

CxLinEv1D

Purpose

Performs a complex linear evaluation of a 1D complex array, \mathbf{x} and \mathbf{y} . CxLinEv1D obtains the *i*th element of the resulting complex array, \mathbf{z} , using the following formulas:

$$yr_i = ar \times xr_i - ai \times xi_i + br$$

 $yi_i = ar \times xi_i + ai \times xr_i + bi$

CxLinEv1D can perform the operations in place; that is, the input and output complex arrays can be the same.

Parameters

Input

Name	Туре	Description
xr	double-precision array	Real part of x .
xi	double-precision array	Imaginary part of x .
n	integer	Number of elements.
ar	double-precision	Real part of <i>a</i> .
ai	double-precision	Imaginary part of <i>a</i> .
br	double-precision	Real part of <i>b</i> .
bi	double-precision	Imaginary part of <i>b</i> .

Output

Name	Туре	Description
yr	double-precision array	Real part of y .
yi	double-precision array	Imaginary part of y .

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

CxMul

Purpose

Multiplies two complex numbers, x and y. CxMul obtains the resulting complex number, z, using the following formulas:

$$zr = xr \times yr - xi \times yi$$
$$zi = xr \times yi + xi \times yr$$

Parameters

Input

Name	Туре	Description
xr	double-precision	Real part of <i>x</i> .
xi	double-precision	Imaginary part of <i>x</i> .
yr	double-precision	Real part of <i>y</i> .
yi	double-precision	Imaginary part of <i>y</i> .

Output

Name	Туре	Description
zr	double-precision	Real part of <i>z</i> .
zi	double-precision	Imaginary part of <i>z</i> .

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

CxMul1D

Purpose

Multiplies two 1D complex arrays, **x** and **y**. CxMul1D obtains the i^{th} element of the resulting complex array, **z**, using the following formulas:

$$zr_i = xr_i \times yr_i - xi_i \times yi_i$$
$$zi_i = xr_i \times yi_i + xi_i \times yr_i$$

CxMullD can perform the operations in place; that is, the input and output complex arrays can be the same.

Parameters

Input

Name	Туре	Description
xr	double-precision array	Real part of x .
xi	double-precision array	Imaginary part of x .
yr	double-precision array	Real part of y .
yi	double-precision array	Imaginary part of y .
n	integer	Number of elements.

Output

Name	Туре	Description
zr	double-precision array	Real part of z .
zi	double-precision array	Imaginary part of z .

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

CxRecip

int status = CxRecip (double xr, double xi, double *yr, double *yi);

Purpose

Finds the reciprocal of a complex number, *x*. CxRecip obtains the resulting complex number, *y*, using the following formulas:

$$yr = \frac{xr}{xr^2 + xi^2}$$
$$yi = \frac{-xi}{xr^2 + xi^2}$$

Parameters

Input

Name	Туре	Description
xr	double-precision	Real part of <i>x</i> .
xi	double-precision	Imaginary part of <i>x</i> .

Output

Name	Туре	Description
yr	double-precision	Real part of <i>y</i> .
yi	double-precision	Imaginary part of <i>y</i> .

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

CxSub

Purpose

Subtracts two complex numbers, x and y. The resulting complex number, z, is obtained using the following formulas:

$$zr = xr - yr$$
$$zi = xi - yi$$

Parameters

Input

Name	Туре	Description
xr	double-precision	Real part of <i>x</i> .
xi	double-precision	Imaginary part of <i>x</i> .
yr	double-precision	Real part of <i>y</i> .
yi	double-precision	Imaginary part of <i>y</i> .

Output

Name	Туре	Description
zr	double-precision	Real part of <i>z</i> .
zi	double-precision	Imaginary part of <i>z</i> .

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

CxSub1D

Purpose

Subtracts two 1D complex arrays, **x** and **y**. CxSub1D obtains the i^{th} element of the resulting complex array, **z**, using the formulas:

$$zr_i = xr_i - yr_i$$
$$zi_i = xi_i - yi_i$$

CxSub1D can perform the operations in place; that is, the input and output complex arrays can be the same.

Parameters

Input

Name	Туре	Description
xr	double-precision array	Real part of x .
xi	double-precision array	Imaginary part of x .
yr	double-precision array	Real part of y .
yi	double-precision array	Imaginary part of y .
n	integer	Number of elements.

Output

Name	Туре	Description
zr	double-precision array	Real part of z .
zi	double-precision array	Imaginary part of z .

Name	Туре	Description
status	integer	Refer toTable 3-2 for error codes.

Determinant

int status = Determinant (void *x, int n, double *det);

Purpose

Finds the determinant of an **n**-by-**n** 2D input matrix.

Parameters

Input

Name	Туре	Description
X	double-precision 2D array	Input matrix.
n	integer	Dimension size of input matrix.

Output

Name	Туре	Description
det	double-precision	Determinant.

The input matrix must be an n-by-n square matrix.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Div1D

int status = Div1D (double x[], double y[], int n, double z[]);

Purpose

Divides two 1D arrays, **x** and **y**. Div1D obtains the i^{th} element of the output array, **z**, using the following formula:

$$z_i = \frac{x_i}{y_i}$$

Div1D can perform the operation in place; that is, z can be the same array as either x or y.

Parameters

Input

Name	Туре	Description
x	double-precision array	x input array.
У	double-precision array	y input array.
n	integer	Number of elements to divide.

Output

Name	Туре	Description
Z	double-precision array	Result array.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Div2D

int status = Div2D (void *x, void *y, int n, int m, void *z);

Purpose

Divides two 2D arrays. Div2D obtains the (i, j)th element of the output array using the following formula:

$$z_{i,j} = \frac{x_{i,j}}{y_{i,j}}$$

Div2D can perform the operation in place; that is, z can be the same array as either x or y.

Parameters

Input

Name	Туре	Description
x	double-precision 2D array	x input array.
У	double-precision 2D array	y input array.
n	integer	Number of elements in first dimension.
m	integer	Number of elements in second dimension.

Output

Name	Туре	Description
Z	double-precision 2D array	Result array.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

DotProduct

int status = DotProduct (double x[], double y, int n, double *dotProd);

Purpose

Calculates the dot product of the x and y input arrays. DotProduct obtains the dot product using the following formula:

$$dotProd = x \bullet y = \sum_{i=0}^{n-1} x_i \times y_i$$

Parameters

Input

Name	Туре	Description
X	double-precision array	x input vector.
У	double-precision array	y input vector.
n	integer	Number of elements.

Output

Name	Туре	Description
dotProd	double-precision	Dot product.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

GetAnalysisErrorString

char *message = GetAnalysisErrorString (int errorNum)

Purpose

Converts the error number an Analysis Library function returns into a meaningful error message.

Parameter

Input

Name	Туре	Description
errorNum	integer	Status an Analysis Library function returns.

Name	Туре	Description
message	string	Explanation of error.

Histogram

Purpose

Calculates the histogram of the input Array. If the input sequence is

 $X = \{0, 1, 3, 3, 4, 4, 4, 5, 5, 8\}$

the Histogram: h(X) of X for eight **intervals** is

$$h(x) = \{h_0, h_1, h_2, h_3, h_4, h_5, h_6, h_7\} = \{1, 1, 0, 2, 3, 2, 0, 1\}$$

Notice that the histogram of the input sequence X is a function of X.

The function obtains Histogram: h(X) as follows: Histogram scans the input sequence X to determine the range of values in it. Then the function establishes the interval width, Δx , according to the specified number of **intervals**,

$$\Delta x = \frac{max - min}{m}$$

where max is the maximum value found in the input sequence X min is the minimum value found in the input sequence X m is the specified number of **intervals**

Let χ represent the output sequence *X* because the histogram is a function of *X*. The function evaluates elements of χ using

$$\chi_i = min + 0.5 \times \Delta x + i \times \Delta x$$
 for $i = 0, 1, 2, ..., m - 1$

Histogram defines the *i*th interval Δ_i to be the range of values from $\chi_i - 0.5 \times \Delta x$ up to but not including $\chi_i + 0.5 \times \Delta x$

$$\Delta_i = [\chi_i - 0.5 \times \Delta x : \chi_i + 0.5 \times \Delta x)$$
 for $i = 0, 1, 2, ..., m - 1$

and defines the function $y_i(x)$ to be

$$y_i(x) = \begin{cases} 1 & \text{if } x \in \text{union of } \Delta_i \\ 0 & \text{elsewhere} \end{cases}$$

Histogram has unity value if the value of x falls within the specified interval. Otherwise it is zero. Notice that the interval Δ_i is centered about χ_i , and its width is Δ_x .

The last interval, Δ_{m-1} , is defined as $[\chi_{m-i} - 0.5 \times \Delta x : \chi_{m-i} + 0.5 \times \Delta x]$. In other words, if a value equals *max*, it is counted as belonging to the last interval.

Finally, Histogram evaluates the histogram sequence *h* using

$$h_i = \sum_{j=0}^{n-1} y_i(x_j)$$
 for $i = 0, 1, 2, ..., m-1$

where h_i represents the elements of the output sequence Histogram: h(X)*n* is the number of elements in the input sequence *X*

Histogram obtains the histogram by counting the number of times the elements in the input array fall in the i^{th} interval.

Parameters

Input

Name	Туре	Description
inputArray	double-precision array	Input array.
numberOfElements	integer	Number of elements in inputArray .
base	double-precision	Lower range.
top	double-precision	Upper range.
intervals	integer	Number of intervals.

Output

Name	Туре	Description
histogramArray	integer array	Histogram of inputArray .
axisArray	double-precision array	Histogram axis array; contains the midpoint values of the intervals.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

InvMatrix

int status = InvMatrix (void *x, int n, void *y);

Purpose

Finds the inverse matrix of an input matrix. InvMatrix can perform the operation in place; that is, **x** and **y** can be the same matrices.

Parameters

Input

Name	Туре	Description
x	double-precision 2D array	Input matrix.
n	integer	Dimension size of matrix.

Output

Name	Туре	Description
У	double-precision 2D array	Inverse matrix.

The input matrix must be an n-by-n square matrix.

Name	Туре	Description	
status	integer	Refer to Table 3-2 for error codes.	

LinEv1D

int status = LinEv1D (double x[], int n, double a, double b, double y[]);

Purpose

Performs a linear evaluation of a 1D array, **x**. LinEv1D obtains the i^{th} element of the output array, **y**, using the formula:

$$y_i = a \times x_i + b$$

LinEv1D can perform the operation in place; that is, x and y can be the same array.

Parameters

Input

Name	Туре	Description
X	double-precision array	Input array.
n	integer	Number of elements.
a	double-precision	Multiplicative constant.
b	double-precision	Additive constant.

Output

Name	Туре	Description
У	double-precision array	Linearly evaluated array.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

LinEv2D

int status = LinEv2D (void *x, int n, int m, double a, double b, void *y);

Purpose

Performs a linear evaluation of a 2D array, **x**. LinEv2D obtains the (i, j)th element of the output array, **y**, using the formula:

$$y_{i,j} = a \times x_{i,j} + b$$

LinEv2D can perform the operation in place; that is, **x** and **y** can be the same array.

Parameters

Input

Name	Туре	Description
x	double-precision 2D array	Input array.
n	integer	Number of elements in first dimension.
m	integer	Number of elements in second dimension.
a	double-precision	Multiplicative constant.
b	double-precision	Additive constant.

Output

Name	Туре	Description
У	double-precision 2D array	Linearly evaluated array.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

MatrixMul

int status = MatrixMul (void *X, void *Y, int n, int k, int m, void *Z);

Purpose

Multiplies two 2D input matrices, **X** and **Y**. MatrixMul obtains the (i, j)th element of the output matrix, **Z**, using the formula:

$$Z_{i,j} = \sum_{p=0}^{k-1} x_{i,p} \times y_{p,j}$$

Parameters

Input

Name	Туре	Description
X	double-precision 2D array	X input matrix.
Y	double-precision 2D array	Y input matrix.
n	integer	First dimension of X .
k	integer	Second dimension of X ; first dimension of Y .
m	integer	Second dimension of Y .

Output

Name	Туре	Description
Z	double-precision 2D array	Output matrix.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Parameter Discussion

Confirm that the array sizes are correct. You must meet the following array sizes:

- X must be **n** by **k**.
- Y must be k by m.
- Z must be **n** by **m**.

Example

```
/* Multiply two matrices. Note: A x B - B x A, in general. */
double x[10][20], y[20][15], z[10][15];
int n, k, m;
n = 10;
k = 20;
m = 15;
MatrixMul (x, y, n, k, m, z);
```

MaxMin1D

Purpose

Finds the maximum and minimum values in the input array and the respective indices of the first occurrence of the maximum and minimum values.

Parameters

Input

Name	Туре	Description
X	double-precision array	Input array.
n	integer	Number of elements.

Output

Name	Туре	Description
max	double-precision	Maximum value.
imax	integer	Index of max in x array.
min	double-precision	Minimum value.
imin	integer	Index of min in x array.

Return Value

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Example

```
/* Generate an array with random and find the maximum and minimum
values. */
double x[20], y[20];
double max, min;
int n, imax, imin;
n = 20;
Uniform (n, 17, x);
MaxMinlD (x, n, &max, &imax, &min, &imin);
```

MaxMin2D

Purpose

Finds the maximum and the minimum values in the 2D input array and the respective indices of the first occurrence of the maximum and minimum values. MaxMin2D scans the X array by rows.

Parameters

Input

Name	Туре	Description
X	double-precision 2D array	Input array.
n	integer	Number of elements in first dimension of X .
m	integer	Number of elements in second dimension of X .

Output

Name	Туре	Description
max	double-precision	Maximum value.
imax	integer	Index of max in X array (first dimension).
jmax	integer	Index of max in X array (second dimension).
min	double-precision	Minimum value.
imin	integer	Index of min in X array (first dimension).
jmin	integer	Index of min in X array (second dimension).

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Example

```
/* This example finds the maximum and minimum values as well as their
location within the array. */
double x[5][10], max, min;
int n, m, imax, jmax, imin, jmin;
n = 5;
m = 10;
MaxMin2D (x, n, m, &max, &imax, &jmax, &min, &imin, &jmin);
```

Mean

int status = Mean (double x[], int n, double *meanval);

Purpose

Calculates the mean, or average, value of the input array. Mean calculates the mean using the following formula:

$$meanval = \frac{\sum_{i=0}^{n-1} x_i}{n}$$

Parameters

Input

Name	Туре	Description
x	double-precision array	Input array.
n	integer	Number of elements in x .

Output

Name	Туре	Description
meanval	double-precision	Mean value.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Mul1D

int status = Mul1D (double x[], double y[], int n, double z[]);

Purpose

Multiplies two 1D arrays. Mul1D obtains the i^{th} element of the output array using the following formula:

```
z_i = x_i \times y_i
```

MullD can perform the operation in place; that is, z can be the same array as either x or y.

Parameters

Input

Name	Туре	Description
x	double-precision array	x input array.
У	double-precision array	y input array.
n	integer	Number of elements to multiply.

Output

Name	Туре	Description
Z	double-precision array	Result array.

	Name	Туре	Description
ĺ	status	integer	Refer to Table 3-2 for error codes.

Mul2D

int status = Mul2D (void *X, void *Y, int n, int m, void *Z);

Purpose

Multiplies two 2D arrays, **X** and **Y**. Mul2D obtains the (i, j)th element of the output array, **Z**, using the following formula:

$$z_{i,j} = x_{i,j} + y_{i,j}$$

Mul2D can perform the operation in place; that is, \mathbf{Z} can be the same array as either \mathbf{X} or \mathbf{Y} .

Parameters

Input

Name	Туре	Description
X	double-precision 2D array	X input array.
Y	double-precision 2D array	Y input array.
n	integer	Number of elements in first dimension.
m	integer	Number of elements in second dimension.

Output

Name	Туре	Description
Z	double-precision 2D array	Result array.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Neg1D

int status = Neg1D (double x[], int n, double y[]);

Purpose

Negates the elements of the input array. Neg1D can perform the operation in place; that is, ${\bf x}$ and ${\bf y}$ can be the same array.

Parameters

Input

Name	Туре	Description
x	double-precision array	Input array.
n	integer	Number of elements.

Output

Name	Туре	Description
У	double-precision array	Negated values of the x input array.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Set1D

int status = Set1D (double x[], int n, double a);

Purpose

Sets the elements of the **x** array to a constant value.

Parameters

Input

Name	Туре	Description
n	integer	Number of elements in x .
a	double-precision	Constant value.

Output

Name	Туре	Description
x	double-precision array	Result array; set to the value of a .

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Sort

int status = Sort (double x[], int n, int direction, double y[]);

Purpose

Sorts the **x** input array in ascending or descending order. Sort can perform the operation in place; that is, **x** and **y** can be the same array.

Parameters

Input

Name	Туре	Description
x	double-precision array	Input array.
n	integer	Number of elements to sort.
direction	integer	0 = ascending nonzero = descending

Output

Name	Туре	Description
У	double-precision array	Sorted array.

Return Value

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Example

/* Generate a random array of numbers and sort them in ascending
order. */
double x[200], y[200];
int n;
int dir;
n = 200;
dir = 0;
Uniform (n, 17, x);
Sort (x, n, dir, y);

StdDev

int status = StdDev (double x[], int n, double *meanval, double *sDev);

Purpose

Calculates the standard deviation and the mean, or average, values of the input array. StdDev uses the following formulas to find the mean and the standard deviation:

$$meanval = \frac{\sum_{i=0}^{n-1} x_i}{n}$$
$$sDev = \sqrt{\frac{\sum_{i=0}^{n-1} (x_i - meanval)^2}{n}}$$

Parameters

Input

Name	Туре	Description
X	double-precision array	Input array.
n	integer	Number of elements in x .

Output

Name	Туре	Description
meanval	double-precision	Mean value.
sDev	double-precision	Standard deviation.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Sub1D

int status = Sub1D (double x[], double y[], int n, double z[]);

Purpose

Subtracts two 1D arrays. Sub1D can obtain the i^{th} element of the output array using the following formula:

 $z_i = x_i - y_i$

Sub1D can perform the operation in place; that is, z can be either x or y.

Parameters

Input

Name	Туре	Description
x	double-precision array	x input array.
У	double-precision array	y input array.
n	integer	Number of elements to subtract.

Output

Name	Туре	Description
Z	double-precision array	Result array.

	Name	Туре	Description
ĺ	status	integer	Refer to Table 3-2 for error codes.

Sub2D

int status = Sub2D (void *X, void *Y, int n, int m, void *Z);

Purpose

Subtracts two 2D arrays. Sub2D obtains the (i, j)th element of the output array using the formula:

 $z_{i,j} = x_{i,j} - y_{i,j}$

Sub2D can perform the operation in place; that is, Z can be either X or Y.

Parameters

Input

Name	Туре	Description
X	double-precision 2D array	X input array.
Y	double-precision 2D array	Y input array.
n	integer	Number of elements in first dimension.
m	integer	Number of elements in second dimension.

Output

Name	Туре	Description
Z	double-precision 2D array	Result array.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Subset1D

int status = Subset1D (double x[], int n, int index, int length, double y[]);

Purpose

Extracts a subset of the input array. The output array contains the number of elements you specify by the **length**. Subset1D starts copying from **x** to **y** at the **index** element of **x**.

Parameters

Input

Name	Туре	Description
X	double-precision array	Input array.
n	integer	Number of elements in x .
index	integer	Initial index for the subset.
length	integer	Number of elements to copy to the subset.

Output

Name	Туре	Description
У	double-precision array	Subset array.

Return Value

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Example

```
/* The following example generates y = {0.0, 1.0, 2.0, 3.0}. */
double x[11], y[4], first, last;
int n, index, length;
n = 11;
index = 5;
length = 4;
first = -5.0;
last = 5.0;
Ramp (n, first, last, x);
Subset1D (x, n, index, length, y);
```

ToPolar

int status = ToPolar (double x, double y, double *mag, double *phase);

Purpose

Converts the rectangular coordinates (x, y) to polar coordinates (mag, phase). ToPolar obtains the polar coordinates using the following formulas:

$$mag = \sqrt{x^2 + y^2}$$

$$phase = \arctan\left(\frac{y}{x}\right)$$

The **phase** value is in the range $[-\pi : \pi]$.

Parameters

Input

Name	Туре	Description
x	double-precision	x coordinate.
У	double-precision	y coordinate.

Output

Name	Туре	Description
mag	double-precision	Magnitude.
phase	double-precision	Phase, in radians.

Return Value

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Example

```
/* Convert the rectangular coordinates to polar coordinates. */
double x, y, mag, phase;
x = 1.5;
y = -2.5;
ToPolar (x, y, &mag, &phase);
```

ToPolar1D

Purpose

Converts the set of rectangular coordinate points (\mathbf{x}, \mathbf{y}) to a set of polar coordinate points (**mag**, **phase**). ToPolar1D obtains the *i*th element of the polar coordinate set using the following formulas:

$$mag_{i} = \sqrt{x_{i}^{2} + y_{i}^{2}}$$
$$phase_{i} = \arctan\left(\frac{y_{i}}{x_{i}}\right)$$

The **phase** value is in the range $[-\pi : \pi]$.

ToPolar1D can perform the operations in place; that is, **x** and **mag**, and **y** and **phase**, can be the same arrays, respectively.

Parameters

Input

Name	Туре	Description
x	double-precision array	x coordinate.
у	double-precision array	y coordinate.
n	integer	Number of elements.

Output

Name	Туре	Description
mag	double-precision array	Magnitude.
phase	double-precision array	Phase, in radians.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

ToRect

int status = ToRect (double mag, double phase, double *x, double *y);

Purpose

Converts the polar coordinates (mag, phase) to rectangular coordinates (x, y). ToRect obtains the rectangular coordinates using the following formulas:

 $x = mag \times \cos(phase)$

```
y = mag \times sin(phase)
```

Parameters

Input

Name	Туре	Description
mag	double-precision	Magnitude.
phase	double-precision	Phase, in radians.

Output

Name	Туре	Description
x	double-precision	x coordinate.
У	double-precision	y coordinate.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

ToRect1D

Purpose

Converts the set of polar coordinate points (**mag**, **phase**) to a set of rectangular coordinate points (\mathbf{x} , \mathbf{y}). ToRect1D obtains the *i*th element of the rectangular set using the following formulas:

$$x_i = mag_i \times \cos(phase_i)$$
$$y_i = mag_i \times \sin(phase_i)$$

TORECt1D can perform the operations in place; that is, **x** and **mag**, and **y** and **phase**, can be the same arrays, respectively.

Parameters

Input

Name	Туре	Description
mag	double-precision array	Magnitude.
phase	double-precision array	Phase, in radians.
n	integer	Number of elements.

Output

Name	Туре	Description
x	double-precision array	x coordinate.
У	double-precision array	y coordinate.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Transpose

int status = Transpose (void *x, int n, int m, void *y);

Purpose

Finds the transpose of a 2D input matrix. Transpose obtains the (i, j)th element of the resulting matrix using the following formula:

$$y_{i,j} = x_{j,i}$$

Parameters

Input

Name	Туре	Description
X	double-precision 2D array	Input matrix.
n	integer	Size of first dimension.
m	integer	Size of second dimension.

Output

Name	Туре	Description
У	double-precision 2D array	Transpose matrix.

If the input matrix has n-by-m dimensions, the output matrix must have m-by-n dimensions.

Name	Туре	Description
status	integer	Refer to Table 3-2 for error codes.

Error Conditions

If an error condition occurs during a call to any of the functions in the Analysis Library, the status return value contains the error code. This code is a value that specifies the type of error that occurred. Table 3-2 shows the currently defined error codes and the associated meanings.

Symbolic Name	Code	Error Message
BaseGETopAnlysErr	-20101	Base must be less than Top.
DivByZeroAnlysErr	-20060	Divide by zero error.
IndexLengthAnlysErr	-20018	The following condition must be met: $0 \le (index + length) < samples.$
NoAnlysErr	0	No error; the call was successful.
OutOfMemAnlysErr	-20001	There is not enough space left to perform the specified routine.
SamplesGEZeroAnlysErr	-20004	The number of samples must be greater than or equal to zero.
SamplesGTZeroAnlysErr	-20003	The number of samples must be greater than zero.
SingularMatrixAnlysErr	-20041	The input matrix is singular. The system of equations cannot be solved.

Table 3-2. Analysis Library Error Codes

4

GPIB/GPIB-488.2 Library

This chapter describes the functions in the LabWindows/CVI GPIB Library. The *GPIB Library Function Overview* section contains general information about the GPIB Library functions and panels, the GPIB DLL, and guidelines and restrictions you should know when using the GPIB Library. The *GPIB Function Reference* section contains an alphabetical list of descriptions for the Device Manager functions, the callback installation functions, and the functions for returning the thread-specific status variables. Refer to your NI-488.2 or NI-488.2M function reference for detailed descriptions of the NI-488 and NI-488.2 functions.

GPIB Library Function Overview

This section describes the functions in the LabWindows/CVI GPIB Library. These functions are arranged alphabetically according to their names in C. For detailed function descriptions, refer to the NI-488.2 function reference manual that accompanied your GPIB interface.

GPIB Functions Library Function Panels

The GPIB Functions Library function panels are grouped in the tree structure in Table 4-1 according to the types of operations they perform.

The first- and second-level headings in the function tree are names of the function classes. Function classes are groups of related function panels. The third-level headings are the names of individual function panels. Each GPIB function panel generates a GPIB function call.

Class/Panel Name	Function Name
Open/Close	
Open Device	OpenDev
Close Device	CloseDev
Close Instrument Devices	CloseInstrDevs
Find Board/Device	ibfind
Find Unused Device	ibdev
Offline/Online	ibonl
Configuration	
Change Primary Address	ibpad
Change Secondary Address	ibsad
Change Access Board	ibbna
Change Time Out Limit	ibtmo

Table 4-1. Functions in the GPIB/GPIB-488.2 Library Function Tree

Class/Panel Name	Function Name
Configuration (continued)	
Set EOS Character	ibeos
Enable/Disable END	ibeot
Enable/Disable DMA	ibdma
System Control	ibrsc
Change Config Parameter	ibconfig
Get Config Parameter	ibask
I/O	
Read	ibrd
Read Asynchronously	ibrda
Read to File	ibrdf
Write	ibwrt
Write Asynchronously	ibwrta
Write from File	ibwrtf
Stop Asynchronous I/O	ibstop
Device Control	-
Get Serial Poll Byte	ibrsp
Clear Device	ibclr
Trigger device	ibtrg
Check for Listeners	ibln
Wait for Event (Dev)	ibwait
Go to Local (Dev)	ibloc
Parallel Poll Cfg (Dev)	ibppc
Pass Control	ibpct
Bus Control	
Send Interface Clear	ibsic
Become Active Controller	ibcac
Go to Standby	ibgts
Set/Clear Remote Enable	ibsre
Send Commands	ibcmd
Send Commands (Async)	ibcmda
Parallel Poll	ibrpp
Read Control Lines	iblines
Board Control	
Wait for Board Event	ibwait
Dequeue Board Event	ibevent
Set UNIX Signal Request	ibsgnal
Go to Local Mode	ibloc
Parallel Poll Configuration	ibppc
Request Service	ibrsv
Set/Clear IST	ibist
Write to Board Key	ibwrtkey
Read from Board Key	ibrdkey

 Table 4-1.
 Functions in the GPIB/GPIB-488.2 Library Function Tree (Continued)

Class/Panel Name	Function Name
Callbacks (Windows only)	
Install Synchronous Callback	ibInstallCallback
Install Asynchronous Callback	ibnotify
Locking (GPIB-ENET Only)	
Lock	iblock
Unlock	ibunlock
Thread-Specific Status	
Get Ibsta for Thread	ThreadIbsta
Get Iberr for Thread	ThreadIberr
Get Ibcnt for Thread	ThreadIbcnt
Get Ibcntl for Thread	ThreadIbcntl
GPIB-488.2 Functions	
Device I/O	
Send	Send
Send to Multiple Device	SendList
Receive	Receive
Trigger and Clear	
Trigger Device	Trigger
Trigger Multiple Devices	TriggerList
Clear Device	DevClear
Clear Multiple Devices	DevClearList
SRQ and Serial Polls	
Test SRQ Line	TestSRQ
Wait for SRQ	WaitSRQ
Find Requesting Device	FindRQS
Read Status Byte	ReadStatusByte
Serial Poll All Devices	AllSpoll
Parallel Polls	Ŧ
Parallel Poll	PPoll
Parallel Poll Config	PPollConfig
Parallel Poll Unconfig	PPollUnconfig
Remote/Local	
Enable Remote Operation	EnableRemote
Enable Local Operation	EnableLocal
Set Remote with Lockout	SetRWLS
Send Local Lockout	SendLLO
System Control	20110220
Reset System	ResetSys
Send Interface Clear	SendlFC
Conduct Self-Tests	TestSys
Find All Listeners	FinsLstn
Pass Control	PassControl
Low-Level I/O	1 4000000000000000000000000000000000000
Send Commands	SendCmds
Setup for Sending	SendSetup
Setup for Sending	Senabecup

Table 4-1. Functions in the GPIB/GPIB-488.2 Library Function Tree (Continued)

Table 4-1. Functions in the GPIB/GPIB-488.2 Library Function Tree (Continued)

Class/Panel Name	Function Name
GPIB-488.2 Functions (continued)	
Low-Level I/O (continued)	
Send Data Bytes	SendDataBytes
Setup for Receiving	ReceiveSetup
Receive Response Message	RcvRespMsg

Class and Subclass Descriptions

- The Open/Close function panels open and close GPIB interfaces and devices.
- The Configuration function panels alter configuration parameters you set during installation of the GPIB handler or during the execution of previous program statements.
- The I/O function panels read and write data over the GPIB. You can use these functions at the board or the device level.
- The Device Control function panels provide high-level, commonly-used GPIB services for instrument control applications.
- The Bus Control function panels provide low-level control of the GPIB bus.
- The Board Control function panels provide low-level control of the GPIB interface. Normally, you use these functions when the GPIB interface is not Controller-In-Charge.
- The Callbacks function panels install callback functions to invoke when certain GPIB events occur. The functions in this class are available only under Windows. Under UNIX, you can use the ibsgnl function.
- The Locking function panels allow you to control simultaneous access to the GPIB-ENET from multiple applications or computers.
- The Thread-Specific Status function panels return the value of the thread-specific GPIB status variables for the current thread. The functions in this class are necessary only for multithreaded applications. They are available only on Windows 95/NT.
- The GPIB 488.2 Functions function panels directly adhere to the IEEE-488.2 standard for communicating with and controlling GPIB devices.
 - The Device I/O function panels read data from and write data to devices on the GPIB.
 - The Trigger and Clear function panels trigger and clear GPIB devices.
 - The SRQ and Serial Polls function panels handle service requests and perform serial polls.
 - The Parallel Polls function panels conduct parallel polls and configure devices to respond to them.
 - The Remote/Local function panels enable and disable operation of devices remotely through the GPIB or locally through the front panel of the device.

- The System Control function panels perform system-wide functions, obtain system-wide status information, and pass system control to other devices.
- The Low-Level I/O function panels perform I/O functions at a lower-level than the function panels in the other classes.

The online help with each panel contains specific information about operating each function panel.

GPIB Library Concepts

This section contains general information about the GPIB Library, the GPIB device driver, guidelines and restrictions you should know when using the GPIB Library, and descriptions of the types of GPIB functions the GPIB Library contains.

GPIB Libraries and the GPIB Dynamic Link Library/Device Driver

LabWindows/CVI for Windows uses the National Instruments standard GPIB DLL for Windows. LabWindows/CVI for Sun uses the standard Sun Solaris-installed GPIB device drivers. These drivers are packaged with your GPIB interface and are not included with LabWindows/CVI. LabWindows/CVI does not require any special procedures for installing and using the device driver. Follow the directions outlined in your interface documentation.

You can use a software utility called *ibconf*, included with your GPIB software, to specify configuration parameters for devices on the GPIB. If your device has special configuration parameters, such as a secondary address or a special termination character, you can specify these using *ibconf*. When you use the LabWindows/CVI GPIB Library function panels, parameters you specified using *ibconf* are still in effect. You can modify configuration parameters directly from one of the LabWindows/CVI configuration function panels or from your program.

If you use a LabWindows/CVI Instrument Driver module, you do not need to make any changes using *ibconf*. The module takes into account any special configuration requirements for the instrument. If special parameters must be specified, the module sets them programmatically.

Guidelines and Restrictions for Using the GPIB Libraries

Follow these guidelines when using the GPIB Libraries:

- Before performing any other operations, open the device. You must use OpenDev, ibfind, or ibdev. Instrument modules must use OpenDev. When you open a device, an integer value that represents a device descriptor is returned. All subsequent operations that involve a particular device require that you specify this device descriptor.
- If you use OpenDev, you should use CloseDev to close the device at the end of the program.
- Each GPIB Library function panel has three global controls labeled Status, Error, and Count. These controls show the values of the GPIB status (ibsta), error (iberr), and byte count (ibent1) variables.
 - The Status control displays in hexadecimal format. The help information for Status explains the meaning of each bit in the status word. If the most significant bit is set, a GPIB error has occurred.
 - When an error occurs, the Error control displays an error number. The help information for Error describes the type of error associated with each error number.
 - Count displays the number of bytes transferred over the GPIB during the most recent bus transfer.

Note When writing instrument modules, you must use the Device Manager functions (OpenDev and CloseDev) instead of ibfind or ibdev. You also must use the Device Manager functions in application programs that make calls to instrument modules. The Device Manager functions allow instrument modules to open devices without specific device names, thereby preventing device name conflicts. They also help the LabWindows/CVI interactive program ensure that devices are closed when no longer needed.

Device and Board Functions

Device functions are high-level functions that execute command sequences to handle bus management operations required for operations such as reading from and writing to devices or polling them for status. Device functions access a specific device and handle the addressing and bus management protocol for that device. You do not need to know any GPIB protocol or bus management details. A descriptor of the accessed device is one of the arguments of the function.

In contrast, board functions are low-level functions that perform rudimentary GPIB operations. They are necessary because high-level functions might not always meet the requirements of applications. In such cases, low-level functions offer the flexibility to meet your application needs.

Board functions access the GPIB interface directly and require you to configure the addressing and bus management protocol for the bus. A descriptor of the accessed board is one of the arguments of the function.

Automatic Serial Polling

Automatic Serial Polling relieves you of the burden of sorting out occurrences of SRQ and obtaining status bytes from devices. To enable Automatic Serial Polling, (or *autopolling*), use the configuration utility ibconf or the configuration function ibconfig. If you enable autopolling, the handler automatically conducts serial polls when SRQ is asserted.

As part of the autopoll procedure, the handler stores each positive serial poll response in a queue associated with each device. A positive response has the RQS or hex 40 bit set in the device status byte. The handler stores the positive responses in a queue because some devices can send multiple positive status bytes before your program can act on them. When the handler receives a positive response from a device, the handler sets the RQS bit of the status word (ibsta). The polling continues until the device unasserts SRQ or the handler detects an error condition.

If the handler cannot locate the device that requests service because no known device responds positively to the poll, or if SRQ is stuck in the asserted state because of a faulty instrument or cable, a GPIB system error exists that interferes with the proper evaluation of the RQS bit in the status words of devices. The handler reports the ESRQ error to you when you issue an *ibwait* call with the RQS bit included in the wait mask. Aside from the difficulty ESRQ causes in waiting for RQS, the error has no detrimental effects on other GPIB operations.

If you call the serial poll function ibrsp and have received one or more responses previously through the automatic serial poll feature, the ibrsp function returns the first queued response. Other responses are read in FIFO (first-in-first-out) fashion. If the RQS bit of the status word is not set when you call ibrsp, the function conducts a serial poll and returns whatever response it receives.

If your application requires that requests for service be noticed, call the *ibrsp* function whenever the RQS bit appears in the status word. The serial poll response queue of a device can overflow with old status bytes when you neglect to call *ibrsp*. *ibrsp* returns the error condition ESTB when status bytes are discarded because the queue is full. If your application has no interest in SRQ or status bytes, you can ignore the occurrence of the automatic polls.

Note

If the RQS bit of the device status word remains set after you call ibrsp, the response byte queue has at least one more response byte remaining. You should continue to call ibrsp until RQS clears.

Autopolling Compatibility

You cannot detect the SRQI bit in device status words (ibsta) if you enable autopolling. The goal of autopolling is to remove the SRQ from the IEEE 488 bus, thus preventing visibility of the SRQI bit in status words for board calls and device calls. If you choose to look for SRQI in your program, you must disable autopolling.

Board functions also are incompatible with autopolling. The handler disables autopolling whenever you make a board call and re-enables it at the end of a subsequent device call.

Hardware Interrupts and Autopolling

If you disable the interrupts of the GPIB interface using ibconf or the ibconfig function, the handler detects SRQ only during calls to the handler, and autopolling can occur only at the following events:

- During a device ibwait for RQS
- Immediately after a device function completes and prepares to return to the application program.

If you enable hardware interrupts, the handler can respond to SRQI interrupts and perform autopolling even when the handler is not performing a function. However, the handler does not conduct an autopoll if any of the following conditions exist:

- The last GPIB call was a board call. The handler reinstates autopolling after a subsequent device call.
- GPIB I/O is in progress. In particular, during asynchronous GPIB I/O, autopolling does not occur until the asynchronous I/O completes.
- The stuck SRQ condition exists.
- You disabled autopolling by using ibconf or ibconfig.

Read and Write Termination

The IEEE 488 specification defines two methods of identifying the last byte of device-dependent (data) messages. The two methods permit a talker to send data messages of any length without the listener(s) knowing in advance the number of bytes in the transmission. The two methods are as follows:

- END message. The talker asserts the EOI (End Or Identify) signal simultaneously with transmission of the last data byte. By design, the listener stops reading when it detects a data message accompanied by EOI, regardless of the value of the byte.
- End of String (EOS) character. The talker uses a special character at the end of its data string. You can configure the listener to stop receiving data when it detects that character. You can use either a 7-bit ASCII character or a full 8-bit binary byte.

You can use these methods individually or in combination. However, you must properly configure the listener to unambiguously detect the end of a transmission.

Using the ibconf configuration program, you can accommodate all permissible forms of read and write termination. You can change the default configuration settings for read and write termination at run time using ibeos and ibeot. In accordance with the IEEE 488 specification, you cannot force the handler to ignore END on read operations.

Timeouts

A timeout mechanism regulates the GPIB routines that transfer command sequences or data messages. All I/O must complete within the timeout period to avoid a timeout error. The handler uses a default timeout period of 10 seconds. You can change the default timeout value with ibconf. In addition, you can use the function ibtmo to programmatically alter the timeout period.

Regardless of the I/O and wait timeout period, GPIB enforces a much shorter timeout for reading responses to serial polls. This shorter timeout period takes effect whenever you conduct a serial poll. Because devices normally respond quickly to polls, you do not need to wait the relatively lengthy I/O timeout period for a nonresponsive device.

Global Variables for the GPIB Library

The GPIB Library and the GPIB-488.2 Library use the following global variables:

- Status Word (ibsta)
- Error (ibcnt, ibcntl)

These variables update after each NI-488 or NI-488.2 routine to reflect the status of the device or board just accessed. Refer to your NI-488.2 user manual for detailed information on the GPIB global variables.

Multithreading under Windows 95/NT

If you use multithreading in a standalone executable, you can call GPIB functions from more than one thread at the same time under Windows 95/NT. To be truly multithreaded safe, you must use one of the following versions of the NI-488.2M driver:

- For Windows 95: Version 1.1 or later
- For Windows NT: Version 1.2 or later

Although previous versions of the drivers support multithreading, they do not support ThreadIbsta, ThreadIberr, ThreadIbent, or ThreadIbent1. You need these functions to obtain thread-specific status values when calling GPIB functions from more than one thread. The global status variables ibsta, iberr, ibent, and ibent1 are not reliable in this case because the GPIB Library maintains them on a *per process* basis.

Notification of SRQ and Other GPIB Events under Windows

Synchronous Callbacks

Under Windows 3.1, you can use ibInstallCallback to specify a function to call when an SRQ is asserted on the GPIB or when an asynchronous I/O operation completes. It is a board-level function only.

If you use Windows 95/NT, you can use ibInstallCallback to specify functions to invoke on the occurrence of any board-level or device-level condition on which you can wait using ibwait.

Callback functions you install with ibInstallCallback are *synchronous* callbacks; that is, LabWindows/CVI can invoke them only when it processes events. LabWindows/CVI processes events when you call ProcessSystemEvents or GetUserEvent or when RunUserInterface is active and you are not in a callback function. Consequently, the latency between the occurrence of the GPIB event and the invocation of the callback can be large. On the other hand, you are not restricted in what you can do in the callback function.

Asynchronous Callbacks

If you use Windows 95/NT, you can use ibnotify to install *asynchronous* callbacks. LabWindows/CVI can call your asynchronous callbacks at any time with respect to the rest of your program. Consequently, the latency between the occurrence of the GPIB event and the invocation of the callback is smaller than with synchronous callbacks, but you are restricted in what you can do in the callback function. Refer to the ibnotify function description later in this chapter for more details.

Driver Version Requirements

If you use Windows NT, you must have version 1.2 or later of the NI-488.2M driver to use ibInstallCallback and ibnotify.

If you use Windows 95, you must have version 1.1 or later of the NI-488.2M driver to use ibInstallCallback and ibnotify.

If you use Windows 3.1, you can use the limited version of ibInstallCallback, but you cannot use ibnotify.

GPIB Function Reference

The software reference manual you receive with your GPIB interface describes most of the functions in the GPIB/GPIB-488.2 Library. This section contains descriptions, in alphabetical order, only for the Device Manager functions, the callback installation functions, and the functions for returning the thread-specific status variables.

Note

ResetDevs is not available in LabWindows/CVI. This function was available in a previous LabWindows version.

CloseDev

```
int result = CloseDev (int Device);
```

Purpose

Closes a device.

Parameter

Input

Name	Туре	Description
Device	integer	The device to close.

Return Value

Name	Туре	Description
result	integer	Result of the close device operation.

Return Codes

Code	Description	
-1	Error—cannot find device.	
0	Success.	

Using This Function

Takes a device offline. CloseDev first calls ibloc and then calls ibon1 with a value of zero. **Device** is the device descriptor you obtain when you open the device with OpenDev. If CloseDev cannot find the device descriptor in its table, it returns a -1. You should use CloseDev only in conjunction with OpenDev. Never call CloseDev with a device descriptor you obtain by calling ibfind.

CloseInstrDevs

int result = CloseInstrDevs (char *instrumentPrefix);

Purpose

Closes all devices associated with an instrument module.

Parameter

Input

Name	Туре	Description
instrumentPrefix	string	Must be null-terminated.

Return Value

Name	Туре	Description
result	integer	Result of the close instrument devices operation.

Return Code

Code	Description	
0	Success.	

Using This Function

instrumentPrefix specifies the prefix of the instrument module to close. CloseInstrDevs always returns zero. You should use CloseInstrDevs only in conjunction with OpenDev.

ibInstallCallback

Note ibInstallCallback *is available only under Windows. Under UNIX, use* ibsgnl. *Under Windows 3.1, the data type of the return value and the first two parameters is* short *rather than* int. ibInstallCallback *does not work with GPIB-ENET.*

Purpose

Allows you to install a synchronous callback function for a specified interface or device. If you want to install an asynchronous callback, use <code>ibnotify</code> instead.

The callback function is called when any of the GPIB events you specify in **eventMask** have occurred on the interface or device, but only while you allow the system to process events. The system can process events when you call ProcessSystemEvents or GetUserEvent, or when you call RunUserInterface and none of your callback functions are currently active. The callbacks are called "synchronous" because you can invoke them only in the context of normal event processing.

Unlike asynchronous callbacks, no restrictions exist on what you can do in a synchronous callback. On the other hand, the latency between the occurrence of a GPIB event and the invocation of the callback function is greater and more unbounded with synchronous callbacks than with asynchronous callbacks.

You can install only one callback function for each interface or device. Each call to ibInstallCallback for the same interface or device supersedes the previous call.

To disable callbacks for an interface or device, pass 0 for eventMask.

To use ibInstallCallback under Windows 95/NT, you must have one of the following versions of the NI-488.2M driver:

- For Windows 95: Version 1.1 or later
- For Windows NT: Version 1.2 or later

If you use Windows 3.1, you must pass a board index for the first parameter, and you can use only SRQI or CMPL for **eventMask**.

Parameters

Input

Name	Туре	Description
boardOrDevice	integer (short integer on Windows 3.1)	Board index, or board or device descriptor you obtain from OpenDev, ibfind, or ibdev. (Under Windows 3.1, must be a board index).
eventMask	integer (short integer on Windows 3.1)	Specifies the events upon which the callback function is called. Pass 0 to disable callbacks. Refer to the following <i>Parameter Discussion</i> .
callbackFunction	GPIBCallbackPtr	Name of the user function to call when the specified events occur. Refer to the following <i>Parameter Discussion</i> .
callbackData	void pointer	Pointer to a user-defined, 4-byte value to pass to the callback function.

Return Value

Name	Туре	Description
status	integer (short integer on Windows 3.1)	Same value as the ibsta status variable. Refer to your NI-488.2 or NI-488.2M user manual for a description of the values of ibsta.

Parameter Discussion

eventMask

You specify the conditions upon which LabWindows/CVI invokes the callback function as bits in **eventMask**. The bits correspond to the bits of the ibsta status word. This value reflects a sum of one or more events. If any one of the conditions occur, the callback is called.

If, when you install the callback, one of the bits you set in the mask is already TRUE, LabWindows/CVI invokes the callback immediately. For example, if you pass CMPL as the **eventMask**, and ibwait would currently return a status word with CMPL set, LabWindows/CVI calls the callback immediately.

If you use Windows 95/NT, the following mask bits are valid:

- At the board level, you can specify any of the status word bits that you can specify in the **waitMask** parameter to ibwait for a board, other than ERR. This includes SRQI, END, CMPL, TIMO, CIC, and others.
- At the device level, you can specify any of the status word bits that you can specify in the **waitMask** parameter to ibwait for a device, other than ERR. This includes RQS, END, CMPL, and TIMO.

If you use Windows 3.1, the only valid mask bits are SRQI or CMPL but not both.

SRQI, RQS, and Auto Serial Polling

If you want to install a callback for the SRQI (board-level) event, you must disable autopolling. You can disable autopolling with the following function call:

```
ibconfig (boardIndex, IbcAUTOPOLL, 0);
```

If you want to install a callback for the RQS (device-level) event, you must enable autopolling for the board. You can enable autopolling with the following function call:

```
ibconfig (boardIndex, IbcAUTOPOLL, 1);
```

callbackFunction

The callback function must have the following form:

mask and callbackData are the same values you pass to ibInstallCallback.

If invoked because of an SRQI or RQS condition, the callback function must call *ibrsp* to read the status byte. For an SRQI (board-level) condition, calling the *ibrsp* function is necessary to cause the requesting device to turn off the SRQ line.

```
char statusByte;
ibrsp (device, &statusByte);
```

If invoked because of a completed asynchronous I/O operation that ibrda, ibwrta, or ibcmda started, the callback function must make the following call:

```
ibwait (boardOrDevice, TIMO | CMPL);
```

The ibent and ibent1 status variables are not updated until you call ibwait.

See Also

ibnotify

iblock

int status = iblock (int boardDevice);

Purpose

Blocks other processes from accessing the specified GPIB-ENET board or device. You can release the lock by calling ibunlock with the same board or device descriptor.

By default, a process returns an ELCK (21) error when it attempts to use a board or device locked by another process. You can cause your process to block instead of returning an error by making the following function call:

```
ibconfig (boardOrDevice, IbcBlockIfLocked, 1);
```

There is no timeout on the process that remains in a blocked state.

In general, you should use iblock to gain critical access to a GPIB-ENET board or device when multiple processes might be accessing it at the same time. When the GPIB-ENET is locked, the GPIB driver guarantees that subsequent calls you make to the GPIB-ENET are completed without interruption.

Parameters

Input

Name	Туре	Description
boardDevice	integer	Device descriptor you obtain from OpenDev, ibfind, or ibdev.

Return Value

Name	Туре	Description
status	integer	Indicates whether the function succeeded.

See Also

ibunlock

ibnotify

Note ibn

ibnotify is available only under Windows 95/NT. Under UNIX, use ibsgnl. ibnotify does not work with GPIB-ENET.

Purpose

Allows you to install an asynchronous callback function for a specified board or device. If you want to install a synchronous callback, use ibInstallCallback instead.

LabWindows/CVI calls the callback function when any of the GPIB events you specify in **eventMask** occur on the specified interface or device. LabWindows/CVI can call asynchronous callbacks at any time while your program is running. You do not have to allow the system to process events. Because of this, you are restricted in what you can do in the callback. Refer to the following *Restrictions on Operations in Asynchronous Callbacks* discussion.

You can install only one callback function for each interface or device. Each call to ibnotify for the same interface or device supersedes the previous call.

To disable callbacks for a interface or device, pass 0 for eventMask.

Parameters

Input

Name	Туре	Description
boardOrDevice	integer	Board index, or board or device descriptor you obtain from OpenDev, ibfind, or ibdev.
eventMask	integer	Specifies the events upon which the callback function is called. Pass 0 to disable callbacks. Refer to the <i>Parameter Discussion</i> .
callbackFunction	GpibNotifyCallback_t	Name of the function LabWindows/CVI calls when the specified events occur. Refer to the <i>Parameter Discussion</i> .
callbackData	void pointer	Pointer to a user-defined, 4-byte value to pass to the callback function.

Return Value

Name	Туре	Description
status	integer	Same value as the ibsta status variable. Refer to your NI-488.2M user manual for a description of the values of ibsta.

Parameter Discussion

eventMask

You specify the conditions upon which LabWindows/CVI invokes the callback function as bits in **eventMask**. The bits correspond to the bits of the ibsta status word. This value reflects a sum of one or more events. If any one of the conditions occur, the callback is called.

If, when you install the callback, one of the bits you set in the mask is already TRUE, LabWindows/CVI invokes the callback immediately. For example, if you pass CMPL as the **eventMask**, and ibwait would currently return a status word with CMPL set, LabWindows/CVI calls the callback immediately.

At the board level, you can specify any of the status word bits that you can specify in the **waitMask** parameter to ibwait for a board, other than ERR. This includes SRQI, END, CMPL, TIMO, CIC, and others.

At the device level, you can specify any of the status word bits that you can specify in the **waitMask** parameter to ibwait for a device, other than ERR. This includes RQS, END, CMPL, and TIMO.

SRQI, RQS, and Auto Serial Polling

If you want to install a callback for the SRQI (board-level) event, you must disable autopolling. You can disable autopolling with the following function call:

```
ibconfig (boardIndex, IbcAUTOPOLL, 0);
```

If you want to install a callback for the RQS (device-level) event, you must enable autopolling for the board. You can enable autopolling with the following function call:

```
ibconfig (boardIndex, IbcAUTOPOLL, 1);
```

callbackFunction

The callback function must have the following form:

callbackData is the same callbackData value you pass to ibInstallCallback. sta, err, and cntl contain the information that you normally obtain using the ibsta, iberr, and ibcntl global variables or ThreadIbsta, ThreadIberr, and ThreadIbcntl. The global variables and thread status functions return undefined values within the callback function. So you must use sta, err and cntl instead.

The value you return from the callback function is very important. It is the event mask that is used to *rearm* the callback. Returning 0 disarms the callback; that is, it is not called again until you make another call to ibnotify. If you return an event mask different than the one you originally passed to ibnotify, ibnotify uses the new event mask. Normally, you want to return the same event mask that you originally passed to ibnotify.

If you return an invalid event mask or if there is an operating system error in rearming the callback, the callback is called with the **sta** set to ERR, **err** set to EDVR, and **cntl** set to IBNOTIFY_REARM_FAILED.

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Caution Because the callback can be called as the result of a rearming error, you should always check the value of the sta parameter to make sure that one of the requested events has in fact occurred.

If invoked because of an SRQI or RQS condition, the callback function should call *ibrsp* to read the status byte. For an SRQI (board-level) condition, calling *ibrsp* is necessary to cause the requesting device to turn off the SRQ line.

```
char statusByte;
ibrsp (device, &statusByte);
```

If invoked because of a completed asynchronous I/O operation that ibrda, ibwrta, or ibcmda started, the callback function must make the following call:

```
ibwait (boardOrDevice, TIMO | CMPL);
```

The ibent and ibent1 status variables are not updated until you call ibwait.

Restrictions on Operations in Asynchronous Callbacks

LabWindows/CVI can call callbacks you install with ibnotify at any time with respect to the rest of your program. You do not have to allow the system to process events. Because of this, you are restricted in what you can do in the callback. You can do the following:

- Call any GPIB function, except ibnotify or ibInstallCallback.
- Manipulate global variables, but only if you know that the callback has not been called at a point when the main part of your program is modifying or interrogating the same global variables.
- In a standalone executable, you can use any of the other LabWindows/CVI libraries, subject to the multithreading restrictions described in the documentation for each library.
- When running in the LabWindows/CVI development environment, you can use the other LabWindows/CVI libraries only in the following ways:
 - Call the User Interface Library PostDeferredCall function, which schedules a different callback function for *synchronous* invocation.
 - Call ANSI C functions such as stropy and sprintf, which have no side effects and affect only the arguments you pass in. You cannot call printf or file I/O functions.
 - Call malloc, calloc, realloc, or free.

If you need to perform operations that fall outside these restrictions, do the following:

- 1. Perform the time-critical operations in the asynchronous callback and call PostDeferredCall to schedule a synchronous callback.
- 2. In the synchronous callback, perform the other operations.

See Also

ibInstallCallback

ibunlock

int status = ibunlock (int boardDevice);

Purpose

Releases a lock on a GPIB-ENET board or device. Refer to the *iblock* function for more information. In general, you should release your lock on a GPIB-ENET connection immediately after you make your critical access.

Parameters

Input

Name	Туре	Description
boardDevice	integer	Device descriptor you obtain from OpenDev, ibfind, or ibdev.

Return Value

Name	Туре	Description
status	integer	Indicates whether the function succeeded.

See Also

ibunlock

OpenDev

int bd = OpenDev (char *deviceName, char *instrumentPrefix);

Purpose

Opens a GPIB device.

Parameters

Input

Name	Туре	Description
deviceName	string	Must be null-terminated.
instrumentPrefix	string	Must be null-terminated.

Return Value

Name	Туре	Description
bd	integer	Result of the open device operation.

Return Code

Code	Description
-1	Device table is full, or no more devices are available.

Parameter Discussion

deviceName is a string that specifies a device name that appears in the ibconf device table. If **deviceName** is not "", OpenDev acts identically to ibfind. If **deviceName** is "", OpenDev acts identically to ibdev by opening the first available unopened device.

instrumentPrefix is a string that specifies the instrument prefix associated with the instrument module. The instrument prefix must be identical to the prefix you enter when creating the function tree for the instrument module. If the instrument module has no prefix or you are not using OpenDev in an instrument module, pass the string "" for **instrumentPrefix**.

Using This Function

OpenDev attempts to find an unused device in the GPIB handler device table and open the device. If successful, OpenDev returns a device descriptor. Otherwise, it returns a negative number.

Threadlbcnt

int threadSpecificCount = ThreadIbcnt (void);

Note ThreadIbnct *is available only under Windows 95/NT*.

Purpose

Returns the value of the thread-specific ibont variable for the current thread.

The global variables ibsta, iberr, ibent, and ibent1 are maintained on a process-specific rather than a thread-specific basis. If you call GPIB functions in more than one thread, the values in these global variables are not always reliable.

Status variables analogous to ibsta, iberr, ibcnt, and ibcntl are maintained for each thread. ThreadIbcnt returns the value of the thread-specific ibcnt variable.

If you do not use multiple threads, ThreadIbent returns a value identical to the value of the ibent global variable.

Parameters

None.

Return Value

Name	Туре	Description
threadSpecificCount	integer	Number of bytes actually transferred by the most recent GPIB read, write, or command operation for the current thread of execution. If an error occurred loading the GPIB DLL, ThreadIbcnt returns a Windows error code.

See Also

ThreadIbsta, ThreadIberr, ThreadIbcntl

Threadlbcntl

long threadSpecificCount = ThreadIbcntl (void);

Note ThreadIbcntl *is available only under Windows 95/NT*.

Purpose

Returns the value of the thread-specific ibentl variable for the current thread.

The global variables ibsta, iberr, ibent, and ibent1 are maintained on a process-specific rather than a thread-specific basis. If you call GPIB functions in more than one thread, the values in these global variables are not always reliable.

Status variables analogous to ibsta, iberr, ibcnt, and ibcntl are maintained for each thread. ThreadIbcntl returns the value of the thread-specific ibcntl variable.

If you do not use multiple threads, ThreadIbentl returns a value identical to the value of the ibentl global variable.

Parameters

None.

Return Value

Name	Туре	Description
threadSpecificCount	long integer	Number of bytes actually transferred by the most recent GPIB read, write, or command operation for the current thread of execution. If an error occurred loading the GPIB DLL, ThreadIbcntl returns a Windows error code.

See Also

ThreadIbsta, ThreadIberr, ThreadIbcnt

Threadlberr

int threadSpecificError = ThreadIberr (void);

Note ThreadIberr *is available only under Windows 95/NT*.

Purpose

Returns the value of the thread-specific iberr variable for the current thread.

The global variables ibsta, iberr, ibent, and ibent1 are maintained on a process-specific rather than a thread-specific basis. If you call GPIB functions in more than one thread, the values in these global variables are not always reliable.

Status variables analogous to ibsta, iberr, ibcnt, and ibcntl are maintained for each thread. ThreadIberr returns the value of the thread-specific iberr variable.

If you do not use multiple threads, ThreadIberr returns a value identical to the value of the iberr global variable.

Parameters

None.

Return Value

Name	Туре	Description
threadSpecificError	integer	Most recent GPIB error code for the current thread of execution. The value is meaningful only when ThreadIbsta returns a value with the ERR bit set.

Return Codes

Defined Constant	Value	Description
EDVR	0	Operating system error. ThreadIbcntl returns the system-specific error code.
ECIC	1	Function requires GPIB-PC to be Controller-In-Charge (CIC).
ENOL	2	No listener on write function.
EADR	3	GPIB-PC addressed incorrectly.
EARG	4	Invalid function call argument.

Defined Constant	Value	Description
ESAC	5	GPIB-PC not system controller as required.
EABO	6	I/O operation aborted.
ENEB	7	Non-existent GPIB-PC interface.
EDMA	8	Virtual DMA device error.
EOIP	10	I/O started before previous operation completed.
ECAP	11	Unsupported feature.
EFSO	12	File system error.
EBUS	14	Command error during device call.
ESTB	15	Serial poll status byte lost.
ESRQ	16	SRQ stuck in the asserted state.
ETAB	20	Device list error during a FindLstn or FindRQS call.
ELCK	21	Address or board is locked.
ELNK	200	The GPIB library was not linked. Dummy functions were linked instead.
EDLL	201	Error loading gpib-32.dll. ThreadIbcntl returns the Windows error code.
EFNF	203	Unable to find the function in gpib-32.dll. ThreadIbcntl returns the Windows error code.
EGLB	205	Unable to find globals in gpib-32.dll. ThreadIbcntl returns the Windows error code.
ENNI	206	Not a National Instruments gpib-32.dll.
EMTX	207	Unable to acquire mutex for loading DLL. ThreadIbcntl returns the Windows error code.

Defined Constant	Value	Description
EMSG	210	Unable to register callback function with Windows.
ECTB	211	The callback table is full.

See Also

ThreadIbsta, ThreadIbcnt, ThreadIbcntl

Threadlbsta

int threadSpecificStatus = ThreadIbsta (void);

ThreadIbsta *is available only under Windows 95/NT*.

Purpose

Returns the value of the thread-specific ibsta variable for the current thread.

The global variables ibsta, iberr, ibent, and ibent1 are maintained on a process-specific rather than a thread-specific basis. If you call GPIB functions in more than one thread, the values in these global variables are not always reliable.

Status variables analogous to ibsta, iberr, ibcnt, and ibcntl are maintained for each thread. ThreadIbsta returns the value of the thread-specific ibsta variable.

If you do not use multiple threads, ThreadIbsta returns a value identical to the value of the ibsta global variable.

Parameters

None.

Return Value

Name	Туре	Description
threadSpecificStatus	integer	Status value for the current thread of execution. The status value describes the state of the GPIB and the result of the most recent GPIB function call in the thread. Any value with the ERR bit set indicates an error. Call ThreadIberr for a specific error code.

Return Codes

The return value is a sum of the following bits.

Defined Constant	Hex Value	Description
ERR	8000	GPIB error.
END	2000	END or EOS detected.
SRQI	1000	SRQ is on.

Defined Constant	Hex Value	Description
RQS	800	Device requesting service.
CMPL	100	I/O completed.
LOK	80	GPIB-PC in lockout state.
REM	40	GPIB-PC in remote state.
CIC	20	GPIB-PC is Controller-In-Charge.
ATN	10	Attention is asserted.
TACS	8	GPIB-PC is talker.
LACS	4	GPIB-PC is listener.
DTAS	2	GPIB-PC in device trigger state.
DCAS	1	GPIB-PC in device clear state.

See Also

ThreadIberr, ThreadIbcnt, ThreadIbcntl

RS-232 Library

This chapter describes the functions in the LabWindows/CVI RS-232 Library. The *RS-232 Library Function Overview* section contains general information about the RS-232 Library functions and panels. The *RS-232 Library Function Reference* section contains an alphabetical list of function descriptions.

In order to use the RS-232 Library under UNIX, your UNIX kernel must support asynchronous I/O functions, for example, aioread and aiowrite. You can enable this by building your UNIX kernel as Generic instead of Generic Small.

RS-232 Library Function Overview

This section contains general information about the RS-232 Library functions and panels. The RS-232 Library also can be used with a National Instruments RS-485 serial board.

RS-232 Library Function Panels

The RS-232 Library function panels are grouped in the tree structure in Table 5-1 according to the types of operations they perform.

The first- and second-level headings in the tree are the names of function classes and subclasses. Function classes and subclasses are groups of related function panels. The third-level headings are the names of individual function panels. Each RS-232 function panel generates one or more RS-232 function calls.

Class/Panel Name	Function Name
Open/Close	
Open COM and Configure	OpenComConfig
Close COM	CloseCom
Open COM—Current State	OpenCom
Input/Output	
Read Buffer	ComRd
Read Terminated Buffer	ComRdTerm
Read Byte	ComRdByte
Read To File	ComToFile
Write Buffer	ComWrt
Write Byte	ComWrtByte
Write From File	ComFromFile

Table 5-1. Functions in the RS-232 Library Function Tree

Class/Panel Name	Function Name
XModem	
XModem Send File	XModemSend
XModem Receive File	XModemReceive
XModem Configure	XModemConfig
Control	
Set Timeout Limit	SetComTime
Set XON/XOFF Mode	SetXMode
Set CTS Mode	SetCTSMode
Flush Input Queue	FlushInQ
Flush Output Queue	FlushOutQ
Send Break Signal	ComBreak
Set Escape Code	ComSetEscape
Status	
Get COM Status	GetComStat
Get Input Queue Length	GetInQLen
Get Output Queue Length	GetOutQLen
Return RS-232 Error	ReturnRS232Err
Get Error String	GetRS232ErrorString
Callbacks	-
Install COM Callback	InstallComCallback

Table 5-1. Functions in the RS-232 Library Function Tree (Continued)

Class Descriptions

- The Open/Close function panels open, close, and configure a COM port.
- The Input/Output function panels read from and write to a COM port.
- The XModem function panels transfer files using the XModem protocol.
- The Control function panels set the timeout limit, set communication modes, flush the I/O queues, and send the break signal.
- The Status function panels return the COM port status and the length of the I/O queues.
- The Callbacks function panel installs callback functions for COM events.

The online help with each panel contains specific information about operating each function panel.

Using RS-485

You can use all the functions in the RS-232 Library with the National Instruments RS-485 AT-Serial board. ComSetEscape allows you to control the transceiver mode of the board.

Reporting RS-232 Errors

The functions in the RS-232 Library return negative values when an error occurs. In addition, the global variable rs232err is updated after each function call to the RS-232 Library. If the function executes properly, it sets rs232err to zero. Otherwise, it sets rs232err to the same error code that it returns.

When an aynchronous write operation fails, the function sets rs232err to an error code unless it already contains a negative value. ReturnRS232Error returns the same value as rs232err except that it keeps track of separate error codes for each thread in your application. In a multithreaded application on Windows 95/NT, use ReturnRS232Error rather than rs232err.

GetRS232ErrorString translates each possible error code into a meaningful error string.

Table 5-10 at the end of this chapter lists the possible error conditions that can occur when you use the RS-232 Library functions.

XModem File Transfer Functions

With the XModem functions, you can transfer files using a data transfer protocol. The protocol uses a generally accepted technique for serial file transfers with error-checking. The XModem functions transfer packets that contain data from the files plus error-checking and synchronization information.

You do not need to understand the protocol to use the functions. To transfer a file, open the COM port, use XModemSend on the sender side of the transfer or XModemReceive on the receiver side of the transfer, and then close the COM port. The XModem functions handle all aspects of the transfer protocol.

You can treat the XModem functions as higher-level functions that perform a more precisely defined task than the functions ComToFile and ComFromFile. Use ComToFile and ComFromFile if you need finer control over the file operations. Remember that the XModem functions calculate the checksum and retransmit when they detect an error, whereas ComToFile and ComFromFile do not do so.

Troubleshooting

Establishing communication between two RS-232 devices can be difficult because of the many different possible configurations. When using this library, you must know the device requirements, such as baud rate, parity, number of data bits, and number of stop bits. These configurations must match between the two parties of communication.

If you encounter difficulty in establishing initial communication with the device, refer to an elementary RS-232 communications handbook for information about cable requirements and

general RS-232 communication. Refer also to the *RS-232 Cable Information* section later in this chapter.

You must call <code>OpenCom</code> or <code>OpenComConfig</code> to open a COM port before using any of the other functions.

If the program writes data to the output queue and then immediately closes the COM port, the data in the queue might be lost if LabWindows/CVI did not have time to send it over the port. To guarantee that all bytes are written before the port closes, monitor the length of the output queue with GetOutQLen. When the output queue length becomes zero, it is safe to close the port.

If XModemReceive fails to complete properly, verify that the input queue length is greater than or equal to the packet size. Refer to OpenComConfig and XModemConfig for more information.

If the receiver appears to lose data the sender transmits, the input queue of the receiver might be overflowing. This means that the library does not empty the input queue of the receiver as quickly as data is coming in. You can solve this problem using handshaking, provided both devices offer the same handshaking support. Refer to the *Handshaking* section of this chapter for more information.

If an XModem file transfer with a large packet size and a low baud rate fails, you might need to increase the wait period. Ten seconds is sufficient for most transfers.

RS-232 Cable Information

An RS-232 cable consists of wires, or lines, that join two connectors. The connectors plug into the serial ports of each device to form a communications link over which data and control signals flow. Each serial port consists of numbered pins that have the meanings shown in Table 5-2.

Pin	Meaning
2	TxD—Transmit Data *
3	RxD—Receive Data
4	RTS—Request to Send *
5	CTS—Clear to Send
6	DSR—Data Set Ready

Table 5-2. PC Cable Configuration

Pin	Meaning	
20	DTR—Data Terminal Ready *	
7	Common	

Table 5-2. PC Cable Configuration (Continued)

The items with an asterisk (*) indicate the lines that the PC drives. All other items indicate the lines the PC monitors.

The type of all serial devices is either Data Communication Equipment (DCE) or Data Transmission Equipment (DTE). IBM-compatible PCs are DTE type devices. The difference between the two types is in the meaning assigned to the pins. A DCE device reverses the meaning of pins 2 and 3, 4 and 5, and 6 and 20. In the simplest scenario, a DTE device attaches to a DCE device, such as a modem. Table 5-3 shows the cable required to connect a PC (or DTE) to a DCE device.

(PC)	Connect pins as indicated:	(Device)
TxD*	22	RxD
RxD	33	TxD*
RTS*	44	CTS
CTS	55	RTS*
DSR	66	DTR
DTR*	2020	DSR*
common	77	common

Table 5-3. DTE to DCE Cable Configuration

You need a different cable for the PC to talk to a DTE device because both devices transmit data over pin 2. A *null modem cable* connects a PC to a DTE. Table 5-4 shows the configuration of a null modem cable.

(PC)	Connect pins as indicated:	(Device)
TxD*	23	RxD
RxD	32	TxD*

Table 5-4. PC to DTE Cable Configuration

(PC)	Connect pins as indicated:	(Device)
RTS*	45	CTS
CTS	54	RTS*
DSR	620	DTR
DTR*	206	DSR*
common	77	common

Table 5-4. PC to DTE Cable Configuration (Continued)

For more information on the meaning of DTE and DCE, refer to a reference book on RS-232 communication.

In the simplest case, a serial cable needs lines 2, 3, and 7 for basic communication to take place. Hardware handshaking and modem control can require other lines, depending on your application. Refer to the *Hardware Handshaking* section later in this chapter for more information about using the lines 4, 5, 6, and 20.

Another area that requires special attention is the *gender* of the connectors of your serial cable. The serial cable plugs into sockets in the PC and the serial device, just as a lamp cord plugs into a wall socket. Both the connector and the socket can be male, with pins (like a lamp plug), or female, with holes (like an outlet). If your serial cable connector and PC socket are the same gender, you cannot plug the cable into the socket. You can change this by attaching a small device called a *gender changer* to your cable. One type of gender changer converts a female connector to a male connector, and the other type converts a male connector to a female connector.

The size of the connector on your serial cable also can differ from the size of the socket. Most serial ports require a 25-pin connector. However, some serial ports require a 9-pin connector. To resolve this incompatibility, you must either change the connector on your serial cable or attach a small device that converts from a 25-pin connector to a 9-pin connector.

Handshaking

A common error condition in RS-232 communications is that the receiver appears to lose data the sender transmits. This condition typically results because the receiver cannot empty its input queue quickly enough.

Handshaking prevents overflow of the input queue that occurs when the receiver cannot empty its input queue as quickly as the sender is able to fill it. The RS-232 Library has two types of handshaking: software handshaking and hardware handshaking. You should enable one or the other if you want to ensure that your application program synchronizes its data transfers with other serial devices that perform handshaking.

Software Handshaking

SetXMode enables software handshaking. You can use software handshaking to transfer ASCII data or text to or from a serial device that also uses software handshaking. The RS-232 Library performs software handshaking by sending and monitoring incoming data for special data bytes (XON and XOFF, or decimal 17 and 19). These bytes indicate whether the receiver is ready to receive data.

Do not enable software handshaking when you transmit binary data because the special XON/XOFF characters can occur as part of the data stream and the receiver can mistake them as control codes. However, you can enable hardware handshaking regardless of the type of data you transfer.

Software Handshaking requires no special cable configuration.

Hardware Handshaking

SetCTSMode enables hardware handshaking. For hardware handshaking to work, two conditions must exist. First, the serial devices must follow the same or similar hardware handshake protocols; they must use the same lines for the handshake and assign the same meanings to those lines. Second, the serial cable that connects the two devices must include the lines required to support the protocol. Because no single well-defined hardware handshake protocol exists, you must resolve any differences between the LabWindows/CVI hardware handshake protocol and the one your device uses.

Most serial devices primarily rely on the CTS and RTS lines to perform hardware handshaking and use the DTR line to signal its online presence to the other device. Some serial devices also use the DTR line for hardware handshaking, similar to the CTS line. SetCTSMode has two different modes to handle either case.

SetCTSMode employs the following line behaviors for each mode:

Im Note Under UNIX, changes to the DTR line have no effect on the communication port.

LWRS_HWHANDSHAKE_OFF

The library raises the RTS and DTR lines when opening the port and lowers them when closing the port. The library sends data out the port regardless of the status of CTS.

Image: The state of the RTS and DTR lines.

LWRS_HWHANDSHAKE_CTS_RTS

- When the PC is the receiver:
 - If the port is opened, the library raises RTS and DTR.
 - If the input queue of the port is nearly full, the library lowers RTS.
 - If the input queue of the port is nearly empty, the library raises RTS.
 - If the port is closed, the library lowers RTS and DTR.
- When the PC is the sender, the RS-232 library must detect that its CTS line is high before it sends data out the port.

LWRS_HWHANDSHAKE_CTS_RTS_DTR

- When the PC is the receiver:
 - If the port is opened, the library raises RTS and DTR.
 - If the input queue of the port is nearly full, the library lowers RTS and DTR.
 - If the input queue of the port is nearly empty, the library raises RTS and DTR.
 - If the port is closed, the library lowers RTS and DTR.
- When the PC is the sender, the RS-232 library must detect that its CTS line is high before it sends data out the port.

Note The only difference between LWRS_HWHANDSHAKE_CTS_RTS and LWRS_HWHANDSHAKE_CTS_RTS_DTR is the behavior of the DTR line.

If the handshaking mechanism of your device uses the CTS and RTS lines, refer to Table 5-3 and Table 5-4 in the previous *RS-232 Cable Information* section for information on how to configure your cable. Your cable can omit the connection between pins 6 and 20 if your device does not monitor DSR when it sends data. Notice that the RTS pin of the receiver translates to the CTS pin of the sender and that the DSR pin of the receiver translates to the DTR pin of the sender.

If you want to use hardware handshaking but your device uses a different hardware handshake protocol than the ones described here, you can build a cable that overcomes the differences. You can construct a cable to serve your special needs by referencing the pin description in Table 5-2 in the previous *RS-232 Cable Information* section.

Multithreading under Windows 95/NT

Under Windows 95/NT, you can call RS-232 Library functions from different threads in the same process, even if the functions operate on the same port. The following limitations apply:

- Do not use the rs232err global variable in a multithreaded application. Use ReturnRS232Err instead.
- Do not call XModemReceive or ComToFile from two threads at the same time if the target file in both calls is the Standard Output.

RS-232 Library Function Reference

This section describes each function in the LabWindows/CVI RS-232 Library in alphabetical order.

CloseCom

```
int result = CloseCom (int COMPort);
```

Purpose

Closes a COM port.

Parameter

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.

Return Value

Name	Туре	Description
result	integer	Refer to Table 5-10 for error codes.

Parameter Discussion

CloseCom does nothing if the port is not open.

ComBreak

int result = ComBreak (int COMPort, int breakTimeMsec);

Purpose

Generates a break signal.

Parameters

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.
breakTimeMsec	integer	Range 1–255, or 0 to select 250.

Return Value

Name	Туре	Description
result	integer	Refer to Table 5-10 for error codes.

Using This Function

ComBreak generates a break signal for the number of milliseconds you indicate or for 250 ms if the **breakTimeMsec** parameter is zero. For most applications, 250 ms is adequate.

A break signal is the transmission of a special character on the communication line for a period longer than the transmission time for one character and its framing bits. You can use a break signal to convey any special condition as long as the sender and receiver agree on the meaning.

ComBreak returns an error if you have not opened the port or if you pass an invalid parameter value.

ComFromFile

Purpose

Reads from the specified file and writes to the output queue of a COM port.

Parameters

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.
fileHandle	integer	File handle you obtain from OpenFile.
count	integer	If O, ComFromFile ignores this value.
terminationByte	integer	If -1, ComFromFile ignores this value.

Return Values

Name	Туре	Description
nbytes	integer	Number of bytes written to the output queue. <0 = error; refer to Table 5-10 for error codes

Parameter Discussion

ComFromFile reads **count** bytes from the file unless it encounters **terminationByte**, reaches EOF, or encounters an error. ComFromFile returns the number of bytes it writes successfully to the output queue. ComFromFile returns immediately after it places all bytes in the output queue, not when it sends all bytes out the COM port.

If count is zero, ComFromFile terminates on terminationByte, EOF, or error.

If **terminationByte** is -1, ComFromFile ignores it, and ComFromFile terminates on **count** bytes written, EOF, or error. If **terminationByte** is not -1, ComFromFile stops reading from the file when it encounters **terminationByte**. It does not write **terminationByte** to the output queue. If **terminationByte** is CR or LF, ComFromFile treats CR-LF and LF-CR combinations just as ComRdTerm does.

If count is 0 and terminationByte is -1, ComFromFile terminates on EOF or error.

Using This Function

ComFromFile times out whenever the library does not write any bytes from the output queue to the COM port during an entire timeout period. This can occur if you enable XON/XOFF, the device sends an XOFF character without sending the follow-on XON character, and the output queue is full. It also can occur if you enable hardware handshaking and the CTS line is not asserted. On a timeout, ComFromFile returns the number of bytes actually read from the COM port and sets rs232err to -99. You can set the timeout period by calling SetComTime.

To guarantee that ComFromFile removes all bytes from the output queue before it closes the port, call GetOutQLen to determine the number of bytes left in the output queue. If you close the port before ComFromFile sends every byte, you lose the bytes left in the queue.

ComFromFile returns an error code if you have not opened the port, if you pass an invalid parameter value, or if a file read error occurs.

ComRd

int nbytes = ComRd (int COMPort, char buffer[], int count);

Purpose

Reads **count** bytes from the input queue of the port you specify and stores them in **buffer**. Returns on timeout or when **count** bytes have been read. Returns an integer value that indicates the number of bytes read from queue.

Parameters

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.
count	integer	0 value takes no bytes from queue.

Output

Name	Туре	Description
buffer	string	Buffer in which to store the data.

Return Value

Name	Туре	Description
nbytes	integer	Number of bytes read from the input queue. <0 = error; refer to Table 5-10 for error codes

Using This Function

ComRd times out whenever the input queue remains empty for an entire timeout period. On a timeout, ComRd returns the number of bytes actually written and sets rs232err to -99. You can set the timeout period by calling SetComTime.

ComRd returns an error code if you have not opened the port or if you pass an invalid parameter value.

Example

```
/* Read 100 bytes from input queue of COM1 into buf.*/
int n;
char buf[100];
.
.
.
n = ComRd (1, buf, 100);
if (n != 100)
    /* Timeout or error occurred before read completed. */;
```

ComRdByte

int byte = ComRdByte (int COMPort);

Purpose

Reads a byte from the input queue of the port you specify. Returns an integer whose low-order byte contains the byte read. Returns on timeout, when the byte is read, or when an error occurs. If an error or a timeout occurs, ComRdByte returns a negative error code. Refer to Table 5-10 at the end of this chapter for error codes. This is the only case in which the high-order byte of the return value is nonzero.

Parameter

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.

Return Value

Name	Туре	Description
byte	integer	Low order byte contains the byte read. <0 = error; refer to Table 5-10 for error codes

Using This Function

ComRdByte times out whenever the input queue remains empty for an entire timeout period. On a timeout, ComRdByte returns -99. You can set the timeout period by calling SetComTime.

ComRdByte returns an error code if you have not opened the port, if you pass an invalid parameter value, or if a timeout occurs.

ComRdTerm

Purpose

Reads from the input queue until **terminationByte** occurs in **buffer**, **count** is met, or a timeout occurs. Returns integer value that indicates the number of bytes read from the queue.

Parameters

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.
count	integer	If 0, ComRdTerm removes no bytes from queue.
terminationByte	integer	Low byte contains the numeric equivalent of the terminating character.

Output

Name	Туре	Description
buffer	string	Buffer in which to store the data.

Return Value

Name	Туре	Description
nbytes	integer	Number of bytes read from the input queue. <0 = error; refer to Table 5-10 for error codes

Using This Function

ComRdTerm times out whenever the input queue remains empty during an entire timeout period. This occurs when no data has been received during one timeout period. On a timeout, ComRdTerm returns the number of bytes read and sets rs232err to -99. You can set the timeout period by calling SetComTime.

If the read terminates on the termination byte, ComRdTerm neither writes the byte to the buffer nor includes it in **count**.

If the termination character is a carriage return (CR or decimal 13) or a linefeed (LF or decimal 10), the function handles it as follows:

- If terminationByte = CR, and if the character immediately following CR is LF, ComRdTerm discards the LF in addition to the CR.
- If **terminationByte** = LF, and if the character immediately following LF is CR, ComRdTerm discards the CR in addition to the LF.

ComRdTerm includes in the return count only the bytes placed in buffer. If ComRdTerm discards CR or LF because it follows an LF or CR, the function does not count it toward satisfying **count**.

ComRdTerm returns an error if you have not opened the port or you pass an invalid parameter value.

ComSetEscape

int result = ComSetEscape (int COMPort, int escapeCode);

Purpose

Directs a COM port to carry out an extended function such as clearing or setting the RTS signal line or setting the transceiver mode for RS-485. The serial device driver defines the extended functions.

Not all device drivers support all escape codes. ComSetEscape returns Unknown System Error (-1) when the device driver does not support a particular escape code.

Parameters

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.
escapeCode	integer	Specifies the escape code of the extended function.

Return Value

Name	Туре	Description
result	integer	Refer to Table 5-10 for error codes.

Parameter Discussion

You can use the following values for escape code:

CLRDTR—Clears the DTR (data-terminal-ready) signal.

CLRRTS—Clears the RTS (request-to-send) signal.

GETMAXCOM—Returns the maximum COM port identifier the system supports. This value ranges from 0x00 to 0x7F, such that 0x00 corresponds to COM1, 0x01 to COM2, 0x02 to COM3, and so on.

SETDTR—Sends the DTR signal.

SETRTS—Sends the RTS signal.

SETXOFF—Causes the port to act as if it has received an XOFF character.

SETXON—Causes the port to act as if it has received an XON character.

You can use the following values only with the National Instruments RS-485 serial driver:

WIRE_4—Sets the transceiver to four-wire mode.

WIRE_2_ECHO—Sets the transceiver to two-wire DTR controlled with echo mode.

WIRE_2_CTRL—Sets the transceiver to two-wire DTR controlled without echo.

WIRE_2_AUTO—Sets the transceiver to two-wire auto TXRDY controlled mode.

ComToFile

Purpose

Reads from the input queue of a COM port and writes the data to a file. Returns the number of bytes successfully written to the file. ComToFile reads bytes from the input queue until it satisfies **count**, encounters **terminationByte**, a timeout occurs, or an error occurs.

Parameters

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.
fileHandle	integer	File handle you obtain from OpenFile.
count	integer	If O, ComToFile ignores this value.
terminationByte	integer	If -1, ComToFile ignores this value.

Return Value

Name	Туре	Description
nbytes	integer	Number of bytes written to the file. <0 = error; refer to Table 5-10 for error codes

Parameter Discussion

If count is zero, ComToFile ignores it and terminates on terminationByte or error.

If **terminationByte** is -1, ComToFile ignores it and terminates on **count** bytes read or an error. If **terminationByte** is valid, the function stops when it encounters a byte that has the value of **terminationByte**; ComToFile removes the termination byte from the input queue and does not write it to the file. If **terminationByte** is CR or LF, ComToFile treats CR LF and LF CR combinations just as ComRdTerm does. If **count** is 0 and **terminationByte** is -1, ComToFile terminates on error or timeout.

Using This Function

ComToFile times out whenever the input queue remains empty for an entire timeout period. On a timeout, ComToFile returns the number of bytes actually written to the COM port and sets rs232err to -99. You can set the timeout period by calling SetComTime.

ComToFile returns an error code if you have not opened the port, if you pass an invalid parameter value, or if a file write error occurs.

ComWrt

int nbytes = ComWrt (int COMPort, char buffer[], int count);

Purpose

Writes **count** bytes to the output queue of the port you specify. Returns an integer value that indicates the number of bytes placed in the queue. Returns immediately without waiting for the bytes to be sent out of the serial port.

Parameters

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.
buffer	string	Buffer that contains data to write or the actual string.
count	integer	0 value places no bytes in queue.

Return Values

Name	Туре	Description
nbytes	integer	Number of bytes placed in the output queue. <0 = error; refer to Table 5-10 for error codes

Using This Function

ComWrt times out whenever the library does not write any bytes from the output queue to the COM port during an entire timeout period. This can occur if you enable XON/XOFF, the device sends an XOFF character without sending the follow-on XON character, and the output queue is full. It also can occur if you enable hardware handshaking and the CTS line is not asserted. On a timeout, ComWrt returns the number of bytes actually written and sets rs232err to -99.

ComWrt sends bytes from the output queue to the serial device under interrupt control without program intervention. If you close the port before all bytes are sent, you lose the bytes that remain in the queue. To guarantee that all bytes are removed from the output queue before you close the port, call GetOutQLen. GetOutQLen returns the number of bytes that remain in the output queue.

ComWrt returns an error if you have not opened the port or if you pass an invalid parameter value.

Example

```
/* Place the string "Hello, world!" in the output queue of */
/* COM2 and check if operation was successful. */
if (ComWrt (2, "Hello, World!", 13) != 13)
/* Operation was unsuccessful. */;
```

or

```
char buf[100];
Fmt(buf,"%s","Hello, World!");
if (ComWrt (2, buf, 13) != 13)
/* Operation was unsuccessful. */;
```

ComWrtByte

int status = ComWrtByte (int COMPort, int byte);

Purpose

Writes a byte to the output queue of a COM port. The byte written is the low-order byte of the integer. Returns a 1 to indicate the operation is successful or a negative error code to indicate the operation failed. Returns immediately without waiting for the byte to be transmitted out through the serial port.

Parameters

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.
byte	integer	Only the low-order byte is significant.

Return Values

Name	Туре	Description
status	integer	Result of the write operation. <0 = error; refer to Table 5-10 for error codes 0 = a timeout occurred 1 = one byte placed in the output queue

Parameter Discussion

ComWrtByte times out whenever the library does not write any bytes from the output queue to the COM port during an entire timeout period. This can occur if you enable XON/XOFF, the device sends an XOFF character without sending the follow-on XON character, and the output queue is full. It also can occur if you enable hardware handshaking and the CTS line is not asserted. On a timeout, ComWrtByte returns 0 and sets rs232err to -99.

ComWrtByte sends bytes from the output queue to the serial device under interrupt control without program intervention. If you close the port before all bytes are sent, you lose the bytes left in the queue. To guarantee that all bytes are removed from the output queue before you close the port, call GetOutQLen. GetOutQLen returns the number of bytes left in the output queue.

ComWrtByte returns an error if you have not opened the port or if you pass an invalid parameter value.

FlushInQ

```
int status = FlushInQ (int COMPort);
```

Purpose

Removes all characters from the input queue of a COM port.

Parameter

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.

Return Value

Name	Туре	Description
status	integer	Refer to Table 5-10 for error codes.

Using This Function

You can use FlushInQ to flush a flawed transmission in preparation for re-transmission. It alleviates the need to read bytes into a buffer to empty the queue. If the queue is already empty, FlushInQ does nothing.

FlushInQ returns a negative error code if you have not opened the port of if you pass an invalid value for **COMPort**.

FlushOutQ

```
int status = FlushOutQ (int COMPort);
```

Purpose

Removes all characters from the output queue of a COM port.

Parameter

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.

Return Value

Name	Туре	Description
status	integer	Refer to Table 5-10 for error codes.

Using This Function

FlushOutQ returns an error if you have not opened the port of if you pass an invalid value for **COMPort**.

GetComStat

```
int status = GetComStat (int COMPort);
```

Purpose

Returns information about the status of a COM port. The library accumulates COM port conditions until you call GetComStat.

Parameter

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.

Return Values

Name	Туре	Description
status	integer	Bits indicate COM port status. <0 = error; refer to Table 5-10 for error codes

Using This Function

Table 5-5 lists definitions of specific bits in the return value. Several bits can indicate the presence of more than one condition.

Hex Value	Mnemonic	Description
0001	INPUT LOST	Input queue filled and input characters lost; you did not remove characters fast enough.
0002	ASYNCH ERROR	Problem determining number of characters in input queue. This is an internal error and normally should not occur.
0010	PARITY	Parity error detected.
0020	OVERRUN	Overrun error detected; a character was received before the receiver data register was emptied.
0040	FRAMING	Framing error detected; stop bits were not received when expected.

Table 5-5. Bit Definitions for the GetComStat Function

Hex Value	Mnemonic	Description
0080	BREAK	Break signal detected.
1000	REMOTE XOFF	XOFF character received. If you enabled XON/XOFF, no characters are removed from the output queue and sent to the other device until that device sends an XON character. Refer to SetXMode.
4000	LOCAL XOFF	XOFF character sent to the other device. If you enabled XON/XOFF, XOFF is transmitted when the input queue is 50%, 75%, and 90% full. If the other device is sensitive to XON/XOFF protocol, it transmits no more characters until it receives an XON character. You use this process to avoid the INPUT LOST error.

Table 5-5. Bit Definitions for the GetComStat Function (Continued)

Notice the ambiguity in this status information. If an error occurs on the indicated port, your application program knows that one or more bytes are invalid. Your program cannot determine from the status word which byte read is invalid.

GetComStat returns a negative error code if you have not opened the port of if you pass an invalid value for **COMPort**.

GetInQLen

```
int len = GetInQLen (int COMPort);
```

Purpose

Returns the number of characters in the input queue of a COM port. GetIngLen does not change the input queue.

Parameter

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.

Return Value

Name	Туре	Description
len	integer	Number of characters in the input queue.

Parameter Discussion

GetInQLen returns an error if you have not opened the port of if you pass an invalid value for **COMPort**.

GetOutQLen

int len = GetOutQLen (int COMPort);

C Note Only the Windows versions of LabWindows/CVI support GetOutQLen.

Purpose

Returns the number of characters in the output queue of a COM port.

Parameter

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.

Return Value

Name	Туре	Description
len	integer	Number of characters in the output queue.

Using This Function

You can use GetOutQLen to ensure the output queue empties before you close the port. This function has no effect on the output queue.

GetOutQLen returns an error if you have not opened the port of if you pass an invalid value for **COMPort**.

GetRS232ErrorString

char *message = GetRS232ErrorString (int errorNum);

Purpose

Converts the error number an RS-232 Library function returns into a meaningful error message.

If **errorNum** is -1 (Unknown System Error) and you are running under Windows 95/NT, GetRS232ErrorString calls the Windows SDK GetLastError function and translates the return value to a Windows message string.

Parameter

Input

Name	Туре	Description
errorNum	integer	Error code an RS-232 function returns.

Return Value

Name	Туре	Description
message	string	Explanation of error.

InstallComCallback

Note Only the Windows version of LabWindows/CVI supports InstallComCallback.

Purpose

Allows you to install a callback function for a particular COM port. The callback function is called whenever any of the events you specify in **eventMask** occur on the COM port and you allow the system to process events. The system can process events in the following situations:

- You call RunUserInterface and none of your callback functions is currently executing.
- You call GetUserEvent.
- You call ProcessSystemEvents.

You can install only one callback function for each COM port. Each call to this function for the same COM port supersedes the previous call.

To disable callbacks for a board or device, pass 0 for the **eventMask** and/or **callbackFunction**.

Image: NoteThe callback function can receive more than one event at a time. When using this
function at higher baud rates, the library might miss some LWRS_RXCHAR events.
Use LWRS_RECEIVE or LWRS_RXFLAG instead.

Note Once the LWRS_RECEIVE event occurs, it does not occur again until the input queue falls below and then rises back above notifyCount bytes.

Parameters

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.
eventMask	integer	Events upon which the callback function is called. Refer to the following <i>Parameter Discussion</i> for a list of valid events. If you want to disable callbacks, pass 0.
notifyCount	integer	Minimum number of bytes the input queue must contain before it sends the LWRS_RECEIVE event to the callback function. Valid range = 0 to size of input queue
eventCharacter	integer	Specifies the character or byte value that triggers the LWRS_RXFLAG event. Valid range = 0 to 255
callbackPtr	ComCallbackPtr	Name of the user function that processes the event callback.
callbackData	void *	A 4-byte value the library passes to the callback function.

Return Value

Name	Туре	Description
status	integer	Refer to Table 5-10 for error codes.

Parameter Discussion

The callback function must have the following form:

eventMask and callbackData are the same values you pass to InstallComCallback. You can use callbackData as a pointer to a data object you want to access in the callback function. In this way, you do not have to declare the data object as a global variable.

You specify the events using bits in **eventMask**, and you can specify multiple event bits. Table 5-6 lists valid event bits.

Bit	Hex Value	COM Port Event	Constant Name	Description
0	0x0001	Any character received.	LWRS_RXCHAR	Set when a character is received and placed in the input queue.
1	0x0002	Received certain character.	LWRS_RXFLAG	Set when the event character is received and placed in the input queue. The event character is specified in eventCharacter .
2	0x0004	Transmit queue empty.	LWRS_TXEMPTY	Set when the last character in the output queue is sent.
3	0x0008	CTS changed state.	LWRS_CTS	Set when the CTS (clear-to-send) line changes state.
4	0x0010	DSR changed state.	LWRS_DSR	Set when the DSR (data-set-ready) line changes state.
5	0x0020	RLSD changed state.	LWRS_RLSD	Set when the RLSD (receive-line-signal-detect) line changes state.
6	0x0040	BREAK received.	LWRS_BREAK	Set when a break is detected on input.
7	0x0080	Line status error occurred.	LWRS_ERR	Set when a line-status error occurs. Line-status errors are CE_FRAME, CE_OVERRUN, and CE_RXPARITY.

 Table 5-6.
 Valid Event Bits and Descriptions

Bit	Hex Value	COM Port Event	Constant Name	Description
8	0x0100	Ring signal detected.	LWRS_RING	Set to indicate that a ring indicator was detected.
15	0x8000	notifyCount bytes in input queue.	LWRS_RECEIVE	Set to detect when at least notifyCount bytes are in the input queue. Once this event has occurred, it does not trigger again until the input queue falls below and then rises back above notifyCount bytes.

Example

```
notifyCount = 50; /* Wait for at least 50 bytes in queue. */
eventChar = 13; /* Wait for LF. */
eventMask = LWRS_RXFLAG | LWRS_TXEMPTY | LWRS_RECEIVE;
InstallComCallback (comport, eventMask, notifyCount,
                    eventChar, ComCallback, NULL);
.
/* Callback Function */
void ComCallback(int portNo, int evnetMask, void *data)
{
   if (eventMask & LWRS_RXFLAG)
      printf("Received specified character\n");
   if (eventMask & LWRS_TXEMPTY)
      printf("Transmit queue now empty\n");
   if (eventMask & LWRS_RECEIVE)
      printf("50 or more bytes in input queue\n");
}
```

OpenCom

int result = OpenCom (int COMPort, char deviceName[]);

Purpose

Opens a COM port using the default settings for the port parameters. If you want to set port settings, call <code>OpenComConfig</code> instead.

Parameters

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.
deviceName	string	Name of the COM port.

Return Value

Name	Туре	Description
result	integer	Refer to Table 5-10 for error codes.

Parameter Discussion

deviceName is the name of the COM port in ASCII string format; for example, "COM1" for COM port 1 under Windows using com.drv and "/dev/ttya" for COM port 1 under UNIX using the Zilog 8530 SCC serial comm driver.

If you pass a NULL pointer or an empty string for **deviceName**, the library uses the following device names depending on the COM port number you specify. Table 5-7 shows the syntax for opening ports one through four. You can follow this model exemplified in the table to open higher-numbered ports.

Table 5-7. Syntax for Opening Port	able 5-7.	Syntax for	Opening Por
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Port Number	deviceName under Windows	deviceName under UNIX
1	"COM1"	"/dev/ttya"
2	"COM2 "	"/dev/ttyb"
3	"СОМЗ"	"/dev/ttys1"
4	"COM4"	"/dev/ttys2"

Using This Function

OpenCom uses 512 bytes of the buffer for the input queue, and 512 bytes for the output. OpenCom assumes the default baud rate, parity, stop bits, data bits, port address, and handshake mode established through the *COM port* configuration of the operating system. The timeout for I/O operations is 5 seconds. Refer to SetXMode, SetCTSMode, SetComTime, and OpenComConfig if you want to change these defaults.

If the specified port is already open, OpenCom closes the port and then opens it again.

OpenComConfig

Purpose

Opens a COM port and sets port parameters. If **inputQueueSize** or **outputQueueSize** is between 1 and 29, OpenComConfig forces it to 30.

Parameters

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.
deviceName	string	Name of the COM port.
baudRate	long	110, 150, 300, 600, 1,200, 2,400, 4,800, 9,600, 14,400, 19,200, 28,800, 38,400, 56,000, 57,600, 115,200, 128,000, or 256,000
		SPARCstations do not support 14,400, 28,800, 56,000, 57,600, 115,200, 128,000, and 256,000. PCs do not support 150. Some PC serial drivers do not support 115,200, 128,000, and 256,000.
parity	integer	0 = no parity 1 = odd parity 2 = even parity 3 = mark parity 4 = space parity
dataBits	integer	5, 6, 7, or 8
stopBits	integer	1 or 2
inputQueueSize	integer	0 selects 512. Refer to the following <i>Parameter Discussion</i> .
outputQueueSize	integer	0 selects 512. Refer to the following <i>Parameter Discussion</i> .

Return Value

Name	Туре	Description
result	integer	Refer to Table 5-10 for error codes.

Parameter Discussion

deviceName is the name of the COM port in ASCII string format; for example, "COM1" for COM port 1 under Windows using comm.drv and "/dev/ttya" for COM port 1 under UNIX using the Zilog 8530 SCC serial comm driver.

If you pass a NULL pointer or an empty string for **deviceName**, the library uses the following device names depending on the COM port number you specify. Table 5-8 shows the syntax for opening ports one through four. You can follow this model to open higher-numbered ports.

Port Number	deviceName on Windows	deviceName on UNIX
1	"СОМ1"	"/dev/ttya"
2	"COM2"	"/dev/ttyb"
3	"СОМЗ"	"/dev/ttys1"
4	"COM4 "	"/dev/ttys2"

Table 5-8. Syntax for Opening Ports

Under UNIX, OpenComConfig ignores inputQueueSize and outputQueueSize. The serial driver determines the queue size.

Under Windows, if you specify 0 for **inputQueueSize** or **outputQueueSize**, OpenComConfig uses 512. If you specify a value between 0 and 30, OpenComConfig uses 30. Under Windows 95/NT, there is no maximum limitation on the queue size. Under Windows 3.1, the maximum queue size is 65,535. However, some serial drivers have a maximum of 32,767 and give undefined behavior when you use a larger queue size. National Instruments recommends that you use a queue size no greater than 32,767.

If you pass an odd number for **inputQueueSize** under Windows NT, LabWindows/CVI rounds it to the next highest even number. The Microsoft serial driver for Windows NT requires an even number for the input queue size.

On all Windows platforms, LabWindows/CVI passes **inputQueueSize** to the Windows serial driver, which might use a different number. For example, the Windows NT serial driver imposes a minimum input queue size of 4096.

Under Windows 3.1, the **baudRate** value can range from 0 to 0xffff. The COM driver interprets values below 0xff00 literally. Values from 0xff00 to 0xffff are codes the particular COM driver defines to represent rates higher than 0xfeff.

Under Windows 95/NT, the comm driver interprets all baudRate values literally.

Using This Function

OpenComConfig disables XON/XOFF mode and CTS hardware handshaking. The default timeout for I/O operations is 5 seconds. Refer to the SetXMode, SetCTSMode, and SetComTime function descriptions if you want to change these defaults.

If the specified port is already open, OpenComfig closes the port and then opens it again. Refer to the CloseCom function description for more information.

ReturnRS232Err

int status = ReturnRS232Err (void);

Purpose

Returns the error code from the most recent function call in the current thread. If the most recent function call was successful, ReturnRS232Err returns zero.

C Note

If the most recent function call was successful but an asynchronous write operation failed, ReturnRS232Err returns the error code from the asynchronous operation. If you want to make sure that a particular function call succeeded, use the return value from that function call.

ReturnRS232Err is multithread safe. Using the rs232err global variable is not multithread safe.

If this function returns -1 and you are running under Windows 95/NT, you can call GetRS232ErrorString to obtain a Windows system message.

Parameters

None.

Return Value

Name	Туре	Description
status	integer	Refer to Table 5-10 for error codes.

SetComTime

int result = SetComTime (int COMPort, double timeoutSeconds);

Purpose

Sets timeout limit for input/output operations.

Parameters

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.
timeoutSeconds	double-precision	Timeout period for all read/write functions.

Return Value

Name	Туре	Description
result	integer	Refer to Table 5-10 for error codes.

Using This Function

SetComTime sets the timeout parameters for all read and write operations. The default value of **timeoutSeconds** is 5 seconds.

For an RS-232 read operation, **timeoutSeconds** specifies the time the library allows from the start of the transfer to the arrival of the first byte. It also specifies the time the library allows to elapse between the arrival of any two consecutive bytes. An RS-232 read operation waits for at least the amount of time you specify for the next incoming byte before it returns a timeout error.

For an RS-232 write operation, **timeoutSeconds** specifies the time the library allows before the first byte is transferred to the output queue. It also specifies the time the library allows between the transfer of any two consecutive bytes to the output queue. The transfer of bytes to the output queue can stall if the output queue is full and hardware or software handshaking is held off. If the holdoff is not resolved within the timeout period, the RS-232 write operation returns a timeout error.

If **timeoutSeconds** is zero, it disables timeouts, and the read or write functions wait indefinitely for the operation to complete.

SetComTime returns an error if you have not opened the port or if you pass an invalid parameter value.

SetCTSMode

int result = SetCTSMode (int COMPort, int mode);

Purpose

Enables or disables hardware handshaking as described in the *Hardware Handshaking* section of the *RS-232 Library Function Overview* section at the beginning of this chapter.

Parameters

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.
mode	integer	0 to disable hardware handshaking; nonzero to enable hardware handshaking. Refer to the following <i>Parameter</i> <i>Discussion</i> .

Return Value

Name	Туре	Description
result	integer	Refer to Table 5-10 for error codes.

Parameter Discussion

Table 5-9 shows the valid values for **mode**.

Value	Defined Constant	Description
0	LWRS_HWHANDSHAKE_OFF	Hardware handshaking is disabled. The library ignores the CTS line, and raises the RTS and DTR lines the entire time the port is open.
1	LWRS_HWHANDSHAKE_CTS_RTS_DTR	Hardware handshaking is enabled. The library monitors the CTS line and uses the RTS and DTR lines for handshaking.
2	LWRS_HWHANDSHAKE_CTS_RTS	Hardware handshaking is enabled. The library monitors the CTS line, uses the RTS for handshaking, and raises the DTR line the entire time the port is open.

Table 5-9.	Valid Mode Values
------------	-------------------

Using This Function

By default, hardware handshaking is not used.

SetCTSMode returns an error if you have not opened the port or if you pass an invalid parameter value.

SetXMode

int result = SetXMode (int COMPort, int mode);

Purpose

Enables or disables software handshaking by enabling or disabling XON/XOFF sensitivity on transmission and reception of data.

Parameters

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.
mode	integer	0 to disable; nonzero to enable.

Return Value

Name	Туре	Description
result	integer	Refer to Table 5-10 for error codes.

Using This Function

By default, XON/XOFF sensitivity is disabled. Refer to the *Software Handshaking* section of the *RS-232 Library Function Overview* section at the beginning of this chapter for more information.

SetXMode returns an error if you have not opened the port of if you pass an invalid parameter value.

XModemConfig

Purpose

Sets the XModem configuration parameters for a COM port.

Parameters

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.
startDelay	double-precision	0.0 selects the default value 10.0 seconds.
maximum#ofRetries	integer	0 selects the default value 10.
waitPeriod	double-precision	0.0 selects the default value 10.0 seconds. National Instruments recommends >5.0.
packetSize	integer	0 selects the default value 128.

Return Values

Name	Туре	Description
result	integer	Refer to Table 5-10 for error codes. 0 = success

Parameter Discussion

XModemSend and XModemReceive use the baud rate and the input/output queue sizes you specify when you call OpenComConfig. They ignore the data bits, the parity, and the stop bits settings of OpenComConfig and always use 8 bits, no parity, and one stop bit. Instead of using the timeout value you set by calling SetComTime, XModem functions use a 1-second timeout between data bytes.

A zero input for any parameter except **COMPort** sets the parameter to its default value.

startDelay sets the timing for the initial connection between the two communication parties. When a LabWindows/CVI program assumes the role of receiver, **startDelay** specifies the interval, in seconds, during which to send the initial negative acknowledgment character to the transmitter. XModemConfig sends that character every **startDelay** seconds, up to **maximum#ofRetries** times. When a LabWindows/CVI program assumes the role of

transmitter, **startDelay** specifies the interval, in seconds, during which the transmitter waits for the initial negative acknowledgment. The transmitter waits up to **startDelay** × **maximum#ofRetries** seconds. The default value of **startDelay** is 10.0.

maximum#ofRetries sets the maximum number of times the transmitter retries sending a packet to the receiver on the occurrence of an error condition. The default value of **maximum#ofRetries** is 10.

waitPeriod sets the period of time between the transfers of two packets. When a LabWindows/CVI program assumes the role of transmitter, it waits for up to **waitPeriod** seconds for an acknowledgment before it re-sends the current packet. When LabWindows/CVI plays the role of receiver, it waits for up to **waitPeriod** seconds for the next packet after it sends out an acknowledgment for the current packet. If it does not receive the next packet within **delayPeriod** seconds, it re-sends the acknowledgment and waits again, up to **maximum#ofRetries** times. The default value of **waitPeriod** is 10.0.

packetSize sets the packet size in bytes. The value must be less than or equal to the input and output queue sizes. The standard XModem protocol defines packet sizes as 128 or 1,024. If you use any other size, make sure the two communication parties understand each other. The default value of **packetSize** is 128.

Using This Function

For transfers with a large packet size and a low baud rate, a large delay period is recommended.

XModemReceive

```
int result = XModemReceive (int COMPort, char fileName[]);
```

Purpose

Receives packets of information over a COM port and writes the packets to a file.

Parameters

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.
fileName	string	Contains the pathname.

Return Value

Name	Туре	Description
result	integer	Refer to Table 5-10 for error codes. 0 = success

Using This Function

XModemReceive uses the XModem file transfer protocol. The transmitter also must follow this protocol for this function to work properly.

The Xmodem protocol requires that the sender and receiver agree on the error checking protocol. The sender and receiver negotiate this agreement at the beginning of the transfer, which can cause a significant delay. **XModemReceive** tries (**maximum#ofTries** + 1)/2 times to negotiate a CRC error check transfer. If there is no response, it tries to negotiate a check sum transfer up to (**maximum#ofTries** – 1)/2 times.

XModemReceive opens the file in binary mode and does not treat carriage returns and linefeeds as special characters. The function writes them to the RS-232 line untouched.

If the size of the file being sent is not an even multiple of the packet size, the file received is padded with ASCII NUL (0) bytes. For example, if the file being sent contains only the string HELLO, the file written to disk contains the letters HELLO followed by (packet size -5) NUL bytes. If the packet size is 128, the file contains the five letters in HELLO and 123 NUL bytes.

The standard XModem protocol supports only 128 and 1,024 as packet sizes. The sender sends an SOH ASCII character (0x01) to indicate that the packet size is 128 or an STX ASCII character (0x02) to indicate that the packet size is 1,024. LabWindows/CVI attempts to support any packet size. As a receiver, when LabWindows/CVI receives an STX character from the sender, it switches to 1,024 packet size regardless of what you specify. When it receives an SOH character from the sender, it uses the packet size you specify. You can specify the packet size by calling XModemConfig.

For transfers with a large packet size and a low baud rate, National Instruments recommends a large delay period.

Example

```
/* Receive the file c:\test\data from COM1. */
/* NOTE: use \\ in pathname in C instead of \. */
int n;
OpenComConfig(1, "", 9600, 1, 8, 1, 256, 256);
n = XModemReceive (1, "c:\\test\\data");
if (n != 0)
    FmtOut ("Error %d in receiving file",rs232err);
else
    FmtOut ("File successfully received.");
```

XModemSend

int result = XModemSend (int COMPort, char fileName[]);

Purpose

Reads data from a file and sends it in packets over a COM port.

Parameters

Input

Name	Туре	Description
COMPort	integer	Range 1–1,000.
fileName	string	Contains the pathname.

Return Values

Name	Туре	Description
result	integer	Refer to Table 5-10 for error codes. 0 = success

Using This Function

XModemSend opens the file in binary mode and does not treat carriage returns and linefeeds as special characters. The function sends them to the receiver untouched.

XModemSend uses the XModem file transfer protocol. The receiver also must follow this protocol for this function to work properly.

If the size of the file being sent is not an even multiple of the packet size, the last packet is padded with ASCII NUL (0) bytes. For example, if the file being sent contains only the string HELLO and the packet size is 128, the packet of data sent contains the letters HELLO followed by 123 (packet size -5) NUL bytes.

The standard XModem protocol supports only 128 and 1,024 as packet sizes. The sender sends an SOH ASCII character (0x01) to indicate that the packet size is 128 or an STX ASCII character (0x02) to indicate that the packet size is 1,024. LabWindows/CVI attempts to support any packet size. As a sender, LabWindows/CVI sends an STX character when you specify packet size as 1,024. For any other packet size, it sends an SOH character. You can specify the packet size by calling XModemConfig.

For transfers with a large packet size and a low baud rate, National Instruments recommends a large delay period.

Error Conditions

If an error condition occurs during a call to any of the functions in the LabWindows/CVI RS-232 Library, the function returns an error code. This code is a negative value that specifies the type of error that occurred.

You can call ReturnRS232Err to obtain the error code, either zero or negative, from the most recent function call in the current thread. If the most recent call was successful but an asynchronous write operation failed, ReturnRS232Err returns the error code from the asynchronous operation. To make sure that a particular function call succeeded, use the return value from that function call.

The rs232err global variable is the error code from the most recent function call or failed asynchronous write operation in your application, regardless of thread. In multithreaded applications, use ReturnRS232Err rather than rs232err.

Table 5-10 lists the currently defined error codes and their meanings.

Code	Error Message
-1	Unknown system error. Refer to the following discussion.
-2	Invalid port number.
-3	Port is not open.
-4	Unknown I/O error.
-5	Unexpected internal error.
-6	No serial port found.
-7	Cannot open port.
-11	Memory allocation error in creating buffers.
-12	Unable to allocate system resources.
-13	Invalid parameter.
-14	Invalid baud rate.
-24	Invalid parity.
-34	Illegal number of data bits.
-44	Illegal number of stop bits.

 Table 5-10.
 RS-232 Library Error Codes

Code	Error Message
-90	Bad file handle.
-91	Error in performing file I/O.
-94	Invalid count; must be greater than or equal to 0.
-97	Invalid interrupt level.
-99	I/O operation timed out.
-104	Value must be between 0 and 255.
-114	Requested input queue size must be 0 or greater.
-124	Requested output queue size must be 0 or greater.
-151	General I/O error.
-152	Buffer parameter is NULL.
-257	Packet was sent, but no acknowledgment was received.
-258	Packet not sent within retry limit.
-259	Packet not received within retry limit.
-260	End of transmission character encountered when start of data character expected.
-261	Packet number could not be read.
-262	Packet number inconsistency.
-263	Packet data could not be read.
-264	Checksum could not be read.
-265	Checksum received did not match computed checksum.
-269	Packet size exceeds input queue size.
-300	Error opening file.
-301	Error reading file.
-302	Did not receive the initial negative acknowledgment character.
-303	Did not receive acknowledgment after the end of transmission character was sent.

Table 5-10. RS-232 Library Error Codes (Continued)

Code	Error Message
-304	Error while writing to file.
-305	Did not receive either a start of data or end of transmission character when expected.
-402	Transfer was canceled because the CAN ASCII character was received.
-503	Invalid start delay.
-504	Invalid maximum number of retries.
-505	Invalid wait period.
-506	Invalid packet size.
-507	Unable to read Cyclical Redundancy Check.
-508	Cyclical Redundancy Check error.

 Table 5-10.
 RS-232 Library Error Codes (Continued)

Errors above 200 occur only on XModem function calls. The library records errors 261 through 265 when the maximum number of retries has been exhausted in trying to receive an XModem function packet.

For error code -1 (UnknownSystemError) on Windows 95/NT, call the GetRS232ErrorString function to obtain a specific Window message string.

DDE Library

This chapter describes the functions in the LabWindows/CVI DDE (Dynamic Data Exchange) Library. The *DDE Library Function Overview* section contains general information about the DDE Library functions and panels. The *DDE Library Function Reference* section contains an alphabetical list of function descriptions. This library is available for LabWindows/CVI for Windows only.

DDE Library Function Overview

The DDE Library includes functions specifically for Windows DDE support. This section contains general information about the DDE Library functions and panels.

DDE Library Function Panels

The DDE Library function are grouped in the tree structure in Table 6-1 according to the types of operations they perform.

The first- and second-level headings in the tree are the names of function classes and subclasses. Function classes and subclasses are groups of related function panels. The third-level headings are the names of individual function panels. Each DDE function panel generates one or more DDE function calls.

Class/Panel Name	Function Name
Server Functions	
Register DDE Server	RegisterDDEServer
Server DDE Write	ServerDDEWrite
Advise DDE Data Ready	AdviseDDEDataReady
Broadcast DDE Data Ready	BroadcastDDEDataReady
Unregister DDE Server	UnregisterDDEServer
Client Functions	
Connect to DDE Server	ConnectToDDEServer
Client DDE Read	ClientDDERead
Client DDE Write	ClientDDEWrite
Client DDE Execute	ClientDDEExecute
Set Up DDE Hot Link	SetUpDDEHotLink
Set Up DDE Warm Link	SetUpDDEWarmLink
Terminate DDE Link	TerminateDDELink

Table 6-1. Functions in the DDE Library Function Tree

h

Class/Panel Name Client Functions (continued)	Function Name
Disconnect from DDE Server	DisconnectFromDDEServer
Get Error String	GetDDEErrorString

Table 6-1. Functions in the DDE Library Function Tree (Continued)

The online help with each panel contains specific information about operating each function panel.

DDE Clients and Servers

Interprocess communication with DDE involves a client and a server in each DDE conversation. A DDE server can execute commands another application sends, and send and receive information to and from a client application under Windows. A DDE client can send commands to a server application to execute and can request data from a server application.

With the LabWindows/CVI DDE Library, you can write programs that act as a DDE client or server. Refer to the *DDE Library Example Using Microsoft Excel and LabWindows/CVI* section later in this chapter for information on how to use the DDE Library functions.

To connect to a DDE server from a LabWindows/CVI program, you must know some information about the application to which you want to connect. All DDE server applications have a name and a topic that defines the connection. For example, you can connect to Microsoft Excel in two ways with the ConnectToDDEServer function. If you want Excel to perform tasks, such as opening worksheets and creating charts when you send commands, you should specify excel as the server name and system as the topic name in the call to the ConnectToDDEServer function. However, if you want to send data to an Excel spreadsheet, you should specify excel as the server name and the filename of the worksheet that is already loaded in Excel as the topic name.

If your program acts as a DDE server, to which other Windows applications will send and receive commands and data, you need to call RegisterDDEServer in your program. RegisterDDEServer establishes your program as a valid DDE server so that other applications can connect to it and exchange information. The server callback function is then invoked as discussed in the following section.

DDE Callback Function

Callback functions provide the mechanism for sending and receiving data to and from other applications through DDE. Similar to the method in which a callback function responds to user interface events from your User Interface Library objects, a DDE callback function responds to incoming DDE information.

A callback function in a client application can respond to only two types of DDE messages: DDE_DISCONNECT and DDE_DATAREADY. If you set up a warm link or hot link, also called an advisory loop, the callback function you specify in ConnectToDDEServer is called with the DDE_DATAREADY message whenever the data values change in the server application.

A DDE callback function used in a server application can be triggered in a number of ways. Whenever a client application attempts to connect to your server program or requests information from your program, the callback function in your program is executed to process the request. The parameter prototypes for the DDE callback functions in LabWindows/CVI are defined as follows:

Name	Туре	Description
handle	integer	Conversation handle that uniquely identifies the client-server connection.
topicName	char pointer	Server application that triggers the callback.
itemName	char pointer	Data item within the server application that triggers the callback. Exception: When xType is DDE_EXECUTE, itemName represents the command string from the client program.
хТуре	integer	Transaction type; refer to Table 6-2 in the following <i>Transaction Types</i> section.
dataFmt	integer	Format of the data being transmitted.
dataSize	integer	Number of bytes in the data. Might actually be greater than the number of bytes transmitted. You should encode size information in your data.
dataPtr	void pointer	Points to the transmitted data.
callbackData	void pointer	User-defined data value.

Parameters

Input

	callbackData		vo
No	ote	The value of the	data

the value of the dataSize parameter is greater than or equal to the actual size of the data. You should encode more exact size information in your data.

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Return Value

The callback function should return 1 to indicate success or 0 to indicate failure or rejection of the requested action.

Transaction Types

Table 6-2 lists all the DDE transaction types, **xType**, that can trigger a callback function.

хТуре	Server	Client	When?
DDE_CONNECT	Y	N	When a new client requests a connection.
DDE_DISCONNECT	Y	Y	When conversation partner quits.
DDE_DATAREADY	Y	Y	When conversation partner sends data.
DDE_REQUESTDATA	Y	Ν	When client requests data.
DDE_ADVISELOOP	Y	Ν	When client requests advisory loop.
DDE_ADVISESTOP	Y	N	When client terminates request for advisory loop.
DDE_EXECUTE	Y	N	When client requests execution of a command.

 Table 6-2.
 DDE Transaction Types (xType)

Refer to the description for RegisterDDEServer and ConnectToDDEServer for more information about the DDE callback function.

DDE Links

You need a DDE data link whenever a client program needs to know about changes to the value of a particular data item in the server application. You can establish a DDE data link in LabWindows/CVI by calling SetUpDDEWarmLink or SetUpDDEHotLink. Whenever the data value changes, the client callback function is invoked with the DDE_DATAREADY message, and the data is available in the **dataPtr** parameter.

Within one client-server connection, multiple data links can exist, each applying to a different data item. For example, you can establish a link between your LabWindows/CVI program and a particular cell in Excel. You specify the data item to which the link applies in the **itemName** parameter to SetUpDDEWarmLink or SetUpDDEHotLink.

As defined in Windows, warm and hot links differ in that under a warm link, the client is merely alerted when the data value changes, and under a hot link, the data is actually sent.

LabWindows/CVI makes no distinction between warm links and hot links. In both cases, your client application receives the data through the client callback function when the data value changes. If a warm link is in effect, LabWindows/CVI requests and receives the data from the server before the callback function is called. SetUpDDEWarmLink and SetUpDDEHotLink are provided because some DDE server applications offer only one type of link.

DDE Library Example Using Microsoft Excel and LabWindows/CVI

LabWindows/CVI includes a sample program called ddedemo.prj that uses DDE to send data to Microsoft Excel. The example program is located in the samples\dde directory. The following discussion outlines the process required to open an Excel worksheet file, send data over DDE, and set up a DDE link with one of the cells in the worksheet from a LabWindows/CVI program.

Start Excel and load the worksheet file called *lwcvi.xls*. The sample program performs the following operations:

1. Connects to the Microsoft Excel worksheet as a client.

ConnectToDDEServer, with excel as the server name and lwcvi.xls as the topic name, establishes a connection with the worksheet. The client callback function ClientCallback identifies the function that processes the DDE transactions this particular conversation generates.

2. Establishes a DDE warm link with a particular cell in the Excel worksheet.

SetUpDDEWarmLink, with the cell address R5C2 as the item name, establishes a DDE link with the cell in the worksheet. Thereafter, whenever the value of cell B5—row 5, column 2—changes, Excel sends information to LabWindows/CVI by invoking the clientCallback function.

3. Sends data to the Excel worksheet from LabWindows/CVI.

The program formats the data as a string and sends it to Excel using ClientDDEWrite with the Excel cell region R1C2:R50C2 as the item name and a character array that contains 50 elements as the buffer pointer.

4. The callback function responds to DDE transactions from the Excel worksheet.

The callback function automatically returns the following information:

handle—Conversation that triggered the callback. One callback function can process multiple DDE conversations.

item name—Cell(s) involved.

topic name—Excel system or Excel file.

transaction type—Either DDE_DATAREADY or DDE_DISCONNECT.

data format—CF_TEXT in this case.

data size—Number of bytes in the data.

data pointer—Pointer to the data.

callback data—User defined; NULL in this case.

When the callback function receives the DDE_DATAREADY transaction, it updates a numeric display by passing the data pointer value to a numeric control on the .uir file. When the DDE event is DDE_DISCONNECT, DisconnectFromDDEServer ends the DDE conversation.

Multithreading under Windows 95/NT

Although it is safe to use DDE Library functions in a multithreaded executable, you must observe a few restrictions. The following restrictions stem from limitations in the Windows implementation of DDE:

- After you call RegisterDDEServer to register your program as a server, you must make all subsequent function calls that apply to the server in the same thread in which you called RegisterDDEServer.
- After you call ConnectToDDEServer to create a client connection, you must make all subsequent functions calls that apply to the connection in the same thread in which you called ConnectToDDEServer.

DDE Library Function Reference

This section describes each function in the LabWindows/CVI DDE Library in alphabetical order.

AdviseDDEDataReady

Purpose

This server function writes data to a DDE client application. Call AdviseDDEDataReady in your server program only when the value of a data item changes and a warm or hot link has been established for the data item.

Parameters

Name	Туре	Description
conversationHandle	unsigned integer	Uniquely identifies the conversation.
itemName	string	Uniquely identifies the output item; for example, an Excel cell name.
dataFormat	unsigned integer	Valid data format; for example, CF_TEXT.
dataPointer	void pointer	Pointer to buffer that holds data.
dataSize	unsigned integer	Number of bytes in data. Must be 0 if dataPointer is NULL. Limited to 64 KB under Windows 3.1 and Windows 95.
timeout	unsigned integer	Timeout in milliseconds.

Input

Return Value

Name	Туре	Description
nbytes	integer	Number of bytes written to the client. <0 = error; refer to Table 6-3 for error codes

Parameter Discussion

dataFormat must be a valid data format Windows recognizes. Windows supports the following valid data formats:

CF_TEXT	CF_PALETTE
CF_BITMAP	CF_PENDATA
CF_METAFILEPICT	CF_RIFF
CF_SYLK	CF_WAVE
CF_DIF	CF_OWNERDISPLAY
CF_TIFF	CF_DSPTEXT
CF_OEMTEXT	CF_DSPBITMAP
CF_DIB	CF_DSPMETAFILEPICT

Refer to Microsoft programmer's documentation for Windows for an in-depth discussion of DDE programming and the meaning of each data format type.

Using This Function

AdviseDDEDataReady allows your program, acting as a DDE server, to send data to a client that has a hot or warm link.

When a client sets up a hot or warm link, your server callback function receives a DDE_ADVISELOOP message for a particular data object that corresponds to **itemName**. When the hot or warm link is terminated, your server callback function receives a DDE_ADVISESTOP message for the data object.

During the period when the hot or warm link is in effect, your server program is responsible for notifying the client whenever the value of the data object changes. When the data object value changes, you can call AdviseDDEDataReady or BroadcastDDEDataReady.

AdviseDDEDataReady differs from BroadcastDDEDataReady in that you specify a particular conversation with a client. AdviseDDEDataReady sends the data only to the client you specify with **conversationHandle**, even if other clients have hot or warm links to the same item. AdviseDDEDataReady sends the data without invoking your server callback function. However, if other clients have warm links to the same item, the function notifies them all that new data is available. If the clients request the new data, the DDE_REQUESTDATA message invokes your server callback function. If you do not want to send the data to those other clients, you must write your server callback function so that it does not call ServerDDEWrite in this case.

If you pass NULL (0) as **dataPointer** and 0 as **dataSize**, AdviseDDEDataReady sends no data to the client you specify with **conversationHandle**. Instead, the function notifies all clients with warm links to the item. If the clients request the new data, the DDE_REQUESTDATA message invokes your server callback function, and you can use ServerDDEWrite to send the data in response.

If successful, AdviseDDEDataReady returns the number of bytes sent. Otherwise, AdviseDDEDataReady returns a negative error code. Refer to Table 6-3 at the end of this chapter for error codes.

Note Your program should not call AdviseDDEDataReady in a tight loop because the iterations compete with user interface events for the CPU time. You should use AdviseDDEDataReady sparingly, and only when the value of the hot- or warm-linked data object changes. In cases when the server returns large data objects, your program should call AdviseDDEDataReady only when the user interface is not busy.

See Also

RegisterDDEServer, SetUpDDEHotLink, SetUpDDEWarmLink, BroadcastDDEDataReady

BroadcastDDEDataReady

Purpose

This server function sends data to all clients that have set up hot or warm links on **topicName** and **itemName**.

Parameters

Input

Name	Туре	Description
serverName	string	Identifies the server from which to send the data.
topicName	string	Identifies the topic with which the data is associated.
itemName	string	Identifies the item with which the data is associated.
dataFormat	unsigned integer	Valid data format; for example, CF_TEXT.
dataPointer	void pointer	Pointer to buffer that holds data.
dataSize	unsigned integer	Number of bytes in data. Limited to 64 KB on Windows 3.1 and Windows 95.

Return Value

Name	Туре	Description
nbytes	integer	Number of bytes written to the client. <0 = error; refer to Table 6-3 for error codes

Parameter Discussion

serverName, **topicName**, and **itemName** must be strings of length from 1 to 255. You can use them without regard to case.

Using This Function

BroadcastDDEDataReady allows your program, acting as a DDE server, to send data to all clients that have hot or warm links on the topic and item you specify.

When a client sets up a hot or warm link, your server callback function receives a DDE_ADVISELOOP message for a particular data object that corresponds to **itemName**. When the hot or warm link is terminated, your server callback function receives a DDE_ADVISESTOP message for the data object.

During the period when the hot or warm link is in effect, your server program is responsible for notifying the client whenever the value of the data object changes. When the data object value changes, your server program should call BroadcastDDEDataReady or AdviseDDEDataReady.

BroadcastDDEDataReady differs from AdviseDDEDataReady in that it is not restricted to a particular client. BroadcastDDEDataReady sends the data automatically to all clients with hot links to the item. BroadcastDDEDataReady notifies all clients with warm links to the item. For each warm-linked client that requests the data, the DDE_REQUESTDATA message invokes your server callback function. You must call ServerDDEWrite in the callback to send the data.

When successful, BroadcastDDEDataReady returns the number of bytes sent. Otherwise, BroadcastDDEDataReady returns a negative error code. Refer to Table 6-3 at the end of this chapter for error codes.

Note Your program should not call BroadcastDDEDataReady in a tight loop because the iterations compete with user interface events for the CPU time. You should use BroadcastDDEDataReady sparingly and only when the value of the hot- or warm-linked data object changes. In cases when the server returns large data objects, your program should call BroadcastDDEDataReady only when the user interface is not busy.

See Also

RegisterDDEServer, SetUpDDEHotLink, SetUpDDEWarmLink, AdviseDDEDataReady

ClientDDEExecute

Purpose

This client function sends a command for a DDE server application to execute.

Parameters

Input

Name	Туре	Description
conversationHandle	unsigned integer	Uniquely identifies the conversation.
commandString	string	Command for the server application to execute.
timeout	unsigned integer	Timeout in milliseconds.

Return Value

Name	Туре	Description
status	integer	Refer to Table 6-3 for error codes.

Parameter Discussion

commandString represents a valid command sequence for the server application to execute. Refer to the command function reference manual for the application to which you are connecting for more information on the commands supported.

See Also

ConnectToDDEServer, ClientDDERead, ClientDDEWrite

ClientDDERead

Purpose

This client function reads data from a DDE server application.

Parameters

Input

Name	Туре	Description
conversationHandle	unsigned integer	Uniquely identifies the conversation.
itemName	string	Uniquely identifies the output item; for example, an Excel cell name.
dataFormat	unsigned integer	Valid data format; for example, CF_TEXT.
dataSize	unsigned integer	Number of bytes to read. Limited to 64 KB under Windows 3.1 and Windows 95.
timeout	unsigned integer	Timeout in milliseconds.

Output

Name	Туре	Description
dataBuffer	void pointer	Buffer in which to receive data.

Return Value

Name	Туре	Description
nbytes	integer	Number of bytes read from the server. <0 = error; refer to Table 6-3 for error codes

Parameter Discussion

dataFormat must be a valid data format Windows recognizes. Windows supports the following data types:

CF_TEXT	CF_PALETTE
CF_BITMAP	CF_PENDATA
CF_METAFILEPICT	CF_RIFF
CF_SYLK	CF_WAVE
CF_DIF	CF_OWNERDISPLAY
CF_TIFF	CF_DSPTEXT
CF_OEMTEXT	CF_DSPBITMAP
CF_DIB	CF_DSPMETAFILEPICT

Refer to Microsoft programmer's documentation for Windows for an in-depth discussion of DDE programming and the meaning of each data format type.

status returns a positive number that represents the number of bytes that were successfully read. A negative number is an error code.

See Also

ConnectToDDEServer, ClientDDEWrite

ClientDDEWrite

Purpose

This client function writes data to a DDE server application.

Parameters

Input

Name	Туре	Description
conversationHandle	unsigned integer	Uniquely identifies the conversation.
itemName	string	Uniquely identifies the output item; for example, an Excel cell name.
dataFormat	unsigned integer	Valid data format; for example, CF_TEXT.
dataPointer	void pointer	Buffer that holds data.
dataSize	unsigned integer	Number of bytes to write. Limited to 64 KB under Windows 3.1 and Windows 95.
timeout	unsigned integer	Timeout in milliseconds.

Return Value

Name	Туре	Description
nbytes	integer	Number of bytes written to the server. <0 = error; refer to Table 6-3 for error codes

Parameter Discussion

dataFormat must be a valid data format Windows recognizes. Windows supports the following valid data formats:

CF_TEXT	CF_PALETTE
CF_BITMAP	CF_PENDATA
CF_METAFILEPICT	CF_RIFF
CF_SYLK	CF_WAVE
CF_DIF	CF_OWNERDISPLAY
CF_TIFF	CF_DSPTEXT
CF_OEMTEXT	CF_DSPBITMAP
CF_DIB	CF_DSPMETAFILEPICT

Refer to Microsoft programmer's documentation for Windows for an in-depth discussion of DDE programming and the meaning of each data format type.

status returns a positive number that represents the number of bytes that were successfully read. A negative number is an error code.

See Also

ConnectToDDEServer, ClientDDERead

ConnectToDDEServer

Purpose

Establishes a connection, or conversation, between your program and a named server on a topic name you specify.

Parameters

Input

Name	Туре	Description
serverName	string	Name of the server application.
topicName	string	Specifies the type of conversation with the server.
clientCallbackFunction	DDE function pointer	Pointer to the callback function that processes messages for the client.
callbackData	void pointer	User-defined data.

Output

Name	Туре	Description
conversationHandle	unsigned integer	Uniquely identifies the conversation.

Return Value

Name	Туре	Description
status	integer	Refer to Table 6-3 for error codes.

Parameter Discussion

conversationHandle returns an integer value that uniquely represents a conversation between a server and a client.

serverName and **topicName** must be strings of length from 1 to 255. You can use them without regard to case.

Each server application defines its own set of valid topic names. Refer to the command function reference manual for the server application. A client and a server can have multiple connections as long as they are under different topic names.

clientCallbackFunction is the name of a callback function to which the DDE Library sends messages from the server.

The callback function must be of the following form:

xType specifies the type of message the server sends.

clientCallbackFunction can receive only two transaction types: DDE_DISCONNECT and DDE_DATAREADY.

DDE_DISCONNECT—Received when a server requests the termination of a connection or when Windows terminates the connection because of an internal error.

DDE_DATAREADY—Received when you have already set up a hot or warm link by calling SetUpDDEHotLink or SetUpDDEWarmLink and the server notifies you that new data is available. If the server program uses the LabWindows/CVI DDE Library, it notifies you by calling AdviseDDEDataReady or BroadcastDDEDataReady. The callback receives the data in **dataPtr**. **topicName**, **itemName**, **dataFmt**, **dataSize**, and **dataPtr** contain significant data. The server to which you are connecting assigns its own meaning to **topicName**. **itemName** can specify an object to which the data refers. For example, in Excel, the item name specifies a cell. **dataFmt** is one of the Windows-defined data types, for example, CF_TEXT. **dataSize** specifies the number of bytes in the data **dataPtr** points to.

 $\square \qquad \text{Note} \qquad The \ \text{dataSize value is the value LabWindows/CVI receives from Windows. This} \\ value \ can \ be \ larger \ than \ the \ actual \ number \ of \ bytes \ the \ client \ writes. \\ \end{tabular}$

Note Return TRUE from the callback function if it can process the message successfully. Otherwise, return FALSE. The callback function should be short and return as soon as possible.

callbackData is a 4-byte value the DDE Library passes to the callback function each time the DDE Library invokes the callback for the same client.

It is your responsibility to define the meaning of the callback data. For example, you can use the callback data as a pointer to a data object that you need to access in the callback function. In this way, you do not need to declare the data object as a global variable.

If you do not want to use the callback data, you can pass zero.

In the case of DDE_DISCONNECT, the value of callbackData is undefined.

See Also

DisconnectFromDDEServer, RegisterDDEServer

DisconnectFromDDEServer

int status = DisconnectFromDDEServer (unsigned int conversationHandle);

Purpose

Disconnects your client program from a server application.

Parameter

Input

Name	Туре	Description
conversationHandle	unsigned integer	Uniquely identifies the conversation.

Return Value

Name	Туре	Description
status	integer	Refer to Table 6-3 for error codes.

Note DisconnectFromDDEServer ends only the client-server conversation that conversationHandle identifies. Multiple, concurrent conversations can exist between a client and a server.

See Also

ConnectToDDEServer, RegisterDDEServer

GetDDEErrorString

char *message = GetDDEErrorString (int errorNum)

Purpose

Converts the error number that a DDE Library function returns into a meaningful error message.

Parameter

Input

Name	Туре	Description
errorNum	integer	Error code a DDE function returns.

Name	Туре	Description
message	string	Explanation of error.

RegisterDDEServer

Purpose

Registers your program as a valid DDE server, allowing other Windows applications to connect to it for interprocess communication.

Parameters

Input

Name	Туре	Description
serverName	string	Name of the server.
serverCallbackFunction	DDE function pointer	Pointer to the callback function that processes messages for the server.
callbackData	void pointer	Pointer to the user data.

Return Value

Name	Туре	Description
status	integer	Refer to Table 6-3 for error codes.

Parameter Discussion

serverName must be a string of length from 1 to 255. You can use it without regard to case.

serverCallbackFunction is the name of a callback function that the DDE Library calls to process client requests.

The callback function must be of the following form:

xType specifies the type of request the client sent. **serverCallbackFunction** can receive the following transaction types:

DDE_CONNECT—Received when a client requests a connection. **topicName** specifies the connection topic. The server defines the set of valid topic names and uses them in different ways. For example, Excel uses the topic name to specify the file the client asks to operate on.

A client can have multiple connections to the same server as long as a different topic name exists for each connection.

DDE_DISCONNECT—Received when a client requests the termination of a connection or when Windows terminates the connection because of an internal error.

DDE_DATAREADY—Received when the client sends data through DDE to the server. topicName, itemName, dataFmt, dataSize, and dataPtr contain significant data. itemName can specify an object to which the data refers. For example, in Excel, the item name specifies a cell. dataFmt is one of the Windows-defined data types, for example, CF_TEXT. dataSize specifies the number of bytes in the data dataPtr points to.

Note The dataSize value is the value LabWindows/CVI receives from Windows. This value can be larger than the actual number of bytes the client writes.

DDE_REQUEST—Received when the client requests that you send data to it through DDE. **itemName** can specify an object to which the data refers. For example, in Excel, the item name specifies a cell. **dataFmt** is one of the Windows-defined data types, for example, CF_TEXT.

DDE_ADVISELOOP—Received when the client requests a hot or warm link, or advisory loop, on a specific item. When a hot or warm link is in effect, the server is supposed to notify the client whenever the item you specify changes value. The server notifies the client of the change in value by calling AdviseDDEDataReady or BroadcastDDEDataReady. **itemName** and **dataFmt** contain significant values. **itemName** can specify an object to which the data item refers. For example, in Excel, the item name specifies a cell. **dataFmt** is one of the Windows-defined data types, for example, CF_TEXT.

DDE_ADVISESTOP—Received when the client requests the termination of an advisory loop. **itemName** contains the same value that the client used to set up the advisory loop.

DDE_EXECUTE—Received when the client requests the execution of a command. **itemName** contains the command string. The server defines the set of valid command strings. For example, Excel uses "[Save()]" to save a file.

Using This Function

RegisterDDEServer registers your program as a DDE server with the name you specify. Clients that attempt to connect to your program must use the specified name. Thereafter, RegisterDDEServer routes all client requests through the **serverCallbackFunction** you specify.

You can register your program as a DDE server multiple times as long as you specify different server names.

Note Return TRUE from the callback function if the request is successful. Otherwise, return FALSE. The callback function should be short and should return as soon as possible.

callbackData is a 4-byte value the DDE Library passes to the callback function each time the DDE Library invokes the callback for the same server.

It is your responsibility to define the meaning of the callback data. The following examples show you how you can use the callback data:

- You can register your program as a DDE server multiple times under different names. For instance, you can use the same callback function for all the server instances by using the callback data to differentiate between them.
- You can use the callback data as a pointer to a data object that you need to access in the callback function. In this way, you do not need to declare the data object as a global variable.

If you do not want to use the callback data, you can pass zero.

In the case of DDE_DISCONNECT, the value of callbackData is undefined.

See Also

ConnectToDDEServer, UnregisterDDEServer

ServerDDEWrite

Purpose

Writes data to a DDE client application when the client requests data.

Parameters

Input

Name	Туре	Description
conversationHandle	unsigned integer	Uniquely identifies the conversation.
itemName	string	Uniquely identifies the output item; for example, an Excel cell name.
dataFormat	unsigned integer	Valid data format; for example, CF_TEXT.
dataPointer	void pointer	Buffer that holds data.
dataSize	unsigned integer	Number of bytes to write. Limited to 64 KB under Windows 3.1 and Windows 95.
timeout	unsigned integer	Timeout in milliseconds.

Name	Туре	Description
nbytes	integer	Number of bytes written to the server. <0 = error; refer to Table 6-3 for error codes

Parameter Discussion

dataFormat must be a valid data format Windows recognizes. Windows supports the following valid data formats:

CF_TEXT	CF_PALETTE
CF_BITMAP	CF_PENDATA
CF_METAFILEPICT	CF_RIFF
CF_SYLK	CF_WAVE
CF_DIF	CF_OWNERDISPLAY
CF_TIFF	CF_DSPTEXT
CF_OEMTEXT	CF_DSPBITMAP
CF_DIB	CF_DSPMETAFILEPICT

Refer to Microsoft programmer's documentation for Windows for an in-depth discussion of DDE programming and the meaning of each data format type.

Using This Function

ServerDDEWrite allows your program, acting as a DDE server, to send data to a client. You should call this function only when your **serverCallbackFunction** receives a DDE_REQUESTDATA transaction.

If you call the function at any other time, ServerDDEWrite stores the data until the client requests it. If you call the function multiple times on the same conversation before the client requests the data, ServerDDEWrite appends each new data set to the buffer that contains the stored data.

If the client has a hot or warm link and you need to send data *other than* in response to a DDE_REQUESTDATA transaction, use AdviseDDEDataReady or BroadcastDDEDataReady.

If successful, ServerDDEWrite returns the number of bytes written. Otherwise, ServerDDEWrite returns a negative error code.

See Also

RegisterDDEServer, AdviseDDEDataReady

SetUpDDEHotLink

Purpose

This client function sets up a hot link, or advisory loop, between the client and the server. SetUpDDEHotLink returns zero for success and a negative error code for failure.

Parameters

Input

Name	Туре	Description
conversationHandle	unsigned integer	Uniquely identifies the conversation.
itemName	string	Uniquely identifies the output item; for example, an Excel cell name.
dataFormat	unsigned integer	Valid data format; for example, CF_TEXT.
timeout	unsigned integer	Timeout in milliseconds.

Return Value

Name	Туре	Description
status	integer	Refer to Table 6-3 for error codes.

Parameter Discussion

itemName identifies the information in the server application to which the DDE link applies. For example, the item name can represent an Excel range of cells by using the range description R1C1:R10C10.

Note

To the client, LabWindows/CVI does not distinguish between a hot link and a warm link. For both types of links, the DDE Library calls the client callback function with a transaction type of DDE_DATAREADY when the data item changes at the server site. The new data is available in the dataPtr parameter of the callback function. LabWindows/CVI has two different functions for setting up a warm link or hot link in case some applications accept only one or the other kind of link.

See Also

RegisterDDEServer, SetUpDDEWarmLink

SetUpDDEWarmLink

Purpose

This client function sets up a warm link, or advisory loop, between the client and the server. SetUpDDEWarmLink returns zero for success and a negative error code for failure.

Parameters

Input

Name	Туре	Description
conversationHandle	unsigned integer	Uniquely identifies the conversation.
itemName	string	Uniquely identifies the output item; for example, an Excel cell name.
dataFormat	unsigned integer	Valid data format; for example, CF_TEXT.
timeout	unsigned integer	Timeout in milliseconds.

Return Value

Name	Туре	Description
status	integer	Refer to Table 6-3 for error codes.

Parameter Discussion

itemName identifies the information in the server application to which the DDE link applies. For example, the item name can represent an Excel range of cells by using the range description R1C1:R10C10.

Note To the client, LabWindows/CVI does not distinguish between a hot link and a warm link. For both types of links, the DDE Library calls the client callback function with a transaction type of DDE_DATAREADY when the data item changes at the server site. The new data is available in the dataPtr parameter of the callback function. LabWindows/CVI has two different functions for setting up a warm link or hot link in case some applications accept only one or the other kind of link.

See Also

RegisterDDEServer, SetUpDDEHotLink

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TerminateDDELink

Purpose

Lets your program, acting as a DDE client, terminate an advisory loop you previously established with the server through SetUpDDEWarmLink or SetUpDDEHotLink.

TerminateDDELink returns zero for success or a negative error code for failure.

Parameters

Input

Name	Туре	Description
conversationHandle	unsigned integer	Uniquely identifies the conversation.
itemName	string	Uniquely identifies the output item; for example, an Excel cell name.
dataFormat	unsigned integer	Valid data format; for example, CF_TEXT.
timeout	unsigned integer	Timeout in milliseconds.

Name	Туре	Description
status	integer	Refer to Table 6-3 for error codes.

UnregisterDDEServer

int status = UnregisterDDEServer (char serverName[]);

Purpose

Unregisters your application program as a DDE server.

Parameter

Input

Name	Туре	Description
serverName	string	Name of the server.

Return Value

Name	Туре	Description
status	integer	Refer to Table 6-3 for error codes.

See Also

RegisterDDEServer

Error Conditions

If an error condition occurs during a call to any of the functions in the LabWindows/CVI DDE Library, the status return value contains the error code. This code is a nonzero value that specifies the type of error that occurred. Error codes are negative numbers. Table 6-3 lists the currently defined error codes and the associated meanings.

Code	Error Message
0	kDDE_NoError
-1	-kDDE_UnableToRegisterService
-2	-kDDE_ExistingServer
-3	-kDDE_FailedToConnect
-4	-kDDE_ServerNotRegistered
-5	-kDDE_TooManyConversations
-9	-kDDE_InvalidParameter
-10	-kDDE_OutOfMemory
-12	-kDDE_NoConnectionEstablished
-13	-kDDE_NotThreadOfServer
-14	-kDDE_NotThreadOfClient
-16	-kDDE_AdvAckTimeOut
-17	-kDDE_Busy
-18	-kDDE_DataAckTimeOut
-19	-kDDE_DllNotInitialized
-20	-kDDE_D11Usage
-21	-kDDE_ExecAckTimeOut
-22	-kDDE_DataMismatch
-23	-kDDE_LowMemory
-24	-kDDE_MemoryError
-25	-kDDE_NotProcessed
-26	-kDDE_NoConvEstablished

Table 6-3. DDE Library Error Codes

Code	Error Message
-27	-kDDE_PokeAckTimeOut
-28	-kDDE_PostMsgFailed
-30	-kDDE_ServerDied
-31	-kDDE_SysError
-32	-kDDE_UnadvAckTimeOut
-33	-kDDE_UnfoundQueueId

Table 6-3. DDE Libra	ry Error Codes (Continued)
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🕞 Note

Error codes -16 to -33 correspond to native Windows DDE error codes that start from 0x4000.

TCP Library

This chapter describes the functions in the LabWindows/CVI TCP (Transmission Control Protocol) Library. The *TCP Library Function Overview* section contains general information about the TCP Library functions and panels. The *TCP Library Function Reference* section contains an alphabetical list of function descriptions.

To use this library under Windows, you must have a version of winsock.dll. The DLL comes with the program that drives the network card.

TCP Library Function Overview

This section contains general information about the TCP Library functions and network communication using TCP. TCP Library functions provide a platform-independent interface to the reliable, connection-oriented, byte-stream, network communication protocol.

TCP Library Function Panels

The TCP Library function panels are grouped in the tree structure in Table 7-1 according to the types of operations they perform.

The first- and second-level headings in the tree are the names of function classes and subclasses. Function classes and subclasses are groups of related function panels. The third-level headings are the names of individual function panels. Each TCP Library function panel generates one TCP Library function call.

Function Name
RegisterTCPServer
ServerTCPRead
ServerTCPWrite
UnregisterTCPServer
DisconnectTCPClient
ConnectToTCPServer
ClientTCPRead
ClientTCPWrite
DisconnectFromTCPServer

Table 7-1. Functions in the TCP Library Function Tree

Table 7-1.	Functions in th	e TCP Library Function	Tree (Continued)
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Class/Panel Name	Function Name
Support Functions	
Get Host IP Address	GetTCPHostAddr
Get Host Machine Name	GetTCPHostName
Get Peer IP Address	GetTCPPeerAddr
Get Peer Machine Name	GetTCPPeerName
Get System Socket Handle	GetHostTCPSocketHandle
Set Disconnect Mode	SetTCPDisconnectMode
Get Error String	GetTCPErrorString
Get System Error String	GetTCPSystemErrorString

The online help with each panel contains specific information about operating each function panel.

TCP Clients and Servers

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Network communication using the TCP Library involves a client and a server in each connection. A TCP server can send and receive information to and from a client application through a network. A TCP client can send and request data to and from a server application. Once registered, a server waits for clients to request connection to it. A client, however, can request connection only to a pre-existing server.

With the LabWindows/CVI TCP Library, you can write programs to act as a TCP client or server. Under Windows, you cannot run both a server and a client on the same computer. The procedure for writing a program using TCP is similar to the procedure you follow for using DDE. Refer to the sample program discussion in Chapter 6, *DDE Library*. Two additional sample programs, tcpserv.prj and tcpclnt.prj, provide some guidelines on structuring your TCP programs as a server or a client. These programs are provided as templates only and require modification for operation on your computer.

To connect to a TCP server from a LabWindows/CVI program, you must have some information about the application to which you would like to connect. All TCP server applications must run on a specified host, which has a known host name, for example, aaa.bbb.ccc, or a known IP address, for example, 123.456.78.90, associated with it. In addition, each server has a unique port number on the host computer. These two pieces of information identify different servers on the same computer or on different computers. Before any client program can connect to a server, it must know the host name and server port number.

If you want your program to act as a TCP server, you must call RegisterTCPServer in your program. RegisterTCPServer establishes your program as the server associated with a port number on the local host. Client applications can connect to your program by using the port number associated with the server and either the host name or the IP address of the computer

on which the server application is currently running. The TCP Library calls your server callback function whenever the conversation partner requests communication.

TCP Callback Function

Callback functions provide the mechanism for receiving notification of connection, connection termination, and data availability. Similar to the method in which a callback function responds to user interface events from your User Interface Library object files, a TCP callback function responds to incoming TCP messages and information.

A callback function can respond to three types of TCP messages: TCP_CONNECT, TCP_DISCONNECT, and TCP_DATAREADY.

If your program acts as a TCP server, client applications can trigger your TCP callback function in a number of ways. Whenever a client application attempts to connect to your server program or requests information from your program, the TCP Library invokes your callback function to process the request.

The parameter prototype for the TCP callback function in LabWindows/CVI is defined as follows:

where handle represents the conversation handle
 xType represents the transaction type; refer to Table 7-2 in this section
 errCode for TCP_DISCONNECT is negative if the connection terminates
 because of an error
 callbackData is a user-defined data value

Table 7-2 lists the TCP transaction types, **xType**, that can trigger a callback function.

хТуре	Server	Client	When?
TCP_CONNECT	Y	Ν	When a new client requests connection.
TCP_DISCONNECT	Y	Y	When conversation partner quits.
TCP_DATAREADY	Y	Y	When conversation partner sends data.

 Table 7-2.
 TCP Transaction Types (xType)

Refer to RegisterTCPServer and ConnectToTCPServer for more information about the TCP callback function.

Multithreading under Windows 95/NT

It is safe to use TCP Library in a multithreaded executable. No restrictions exist.

TCP Library Function Reference

This section describes each function in the LabWindows/CVI TCP Library in alphabetical order.

ClientTCPRead

Purpose

Reads data from a TCP server application.

Parameters

Input

Name	Туре	Description
conversationHandle	unsigned integer	Uniquely identifies the conversation.
dataBuffer	void pointer	Buffer in which to receive data.
dataSize	unsigned integer	Maximum number of bytes to read.
timeout	unsigned integer	Timeout in milliseconds.

Return Value

Name	Туре	Description
nbytes	integer	Number of bytes read from the server. <0 = error; refer to Table 7-3 for error codes

See Also

ConnectToTCPServer, ClientTCPWrite

ClientTCPWrite

Purpose

Writes data to a TCP server application.

Parameters

Input

Name	Туре	Description
conversationHandle	unsigned integer	Uniquely identifies the conversation.
dataPointer	void pointer	Buffer that holds data.
dataSize	unsigned integer	Number of bytes to write.
timeout	unsigned integer	Timeout in milliseconds.

Return Value

Name	Туре	Description
nbytes	integer	Number of bytes written to the server. <0 = error; refer to Table 7-3 for error codes

See Also

ConnectToTCPServer, ClientTCPRead

ConnectToTCPServer

Purpose

Establishes a conversation between your program and a pre-existing server. Your program becomes a client.

Parameters

Input

Name	Туре	Description
portNumber	unsigned integer	Uniquely identifies a server on a single computer.
serverHostName	string	Host name or IP address of the server computer; for example, aaa.bbb.ccc or 123.456.78.90.
clientCallbackFunction	TCP function pointer	Pointer to the callback function that processes messages for the client.
callbackData	void pointer	User-defined data.
timeout	unsigned integer	Timeout in milliseconds.

Output

Name	Туре	Description
conversationHandle	unsigned integer	Uniquely identifies the conversation.

Name	Туре	Description
status	integer	Refer to Table 7-3 for error codes.

Parameter Discussion

clientCallbackFunction is the name of the function the TCP Library calls to process messages your program receives as a TCP client.

The callback function must be of the following form:

xType specifies the type of message the server sends. The client callback function can receive the following transaction types:

TCP_DISCONNECT TCP_DATAREADY

Use errCode only when the transaction type is TCP_DISCONNECT.

TCP_DISCONNECT—Received when a server requests the termination of a connection or when a connection terminates because of an error. If the connection terminates because of an error, the **errCode** parameter contains a negative error code. Refer to Table 7-3 at the end of this chapter for the list of error codes.

TCP_DATATREADY—Received when the server sends data through TCP to the client. Your program, acting as the client, calls ClientTCPRead to obtain the data.

Note *Return TRUE for the client callback function if it can process the message successfully. Otherwise, return FALSE. The callback function should be short and should return as soon as possible.*

callbackData is a 4-byte value the TCP Library passes to the callback function each time the TCP Library invokes the callback for the same client.

It is your responsibility to define the meaning of the callback data. One way to use **callbackData** is as a pointer to a data object that you need to access in the callback function. By doing this, you can avoid declaring the data object as a global variable.

If you do not want to use callbackData, you can pass zero.

See Also

RegisterTCPServer, DisconnectFromTCPServer

DisconnectFromTCPServer

int status = DisconnectFromTCPServer (unsigned int conversationHandle);

Purpose

Disconnects your client program from a server application.

Parameter

Input

Name	Туре	Description
conversationHandle	unsigned integer	Uniquely identifies the conversation.

Return Value

Name	Туре	Description
status	integer	Refer to Table 7-3 for error codes.

Note DisconnectFromTCPServer terminates only the connection conversationHandle identifies. There can be more than one conversation between a client and a server.

See Also

ConnectToTCPServer, RegisterTCPServer, SetTCPDisconnectMode

DisconnectTCPClient

int status = DisconnectTCPClient (unsigned int conversationHandle);

Purpose

This TCP server function terminates a connection with a client.

Parameter

Input

Name	Туре	Description
conversationHandle	unsigned integer	Uniquely identifies the connection.

Return Value

Name	Туре	Description
status	integer	Refer to Table 7-3 for error codes.

Note DisconnectTCPClient *terminates only the connection* conversationHandle *identifies. There can be more than one conversation between a client and a server.*

See Also

RegisterTCPServer, SetTCPDisconnectMode

GetHostTCPSocketHandle

Purpose

Obtains the system socket handle that corresponds to a TCP Library connection.

Parameters

Input

Name	Туре	Description
connectionHandle	unsigned integer	TCP Library conversation handle you obtain from ConnectToTCPServer or receive in a server callback as the handle parameter of a TCP_DISCONNECT message.

Output

Name	Туре	Description
systemSocket	unsigned integer	System socket handle for the connection connectionHandle identifies.

Name	Туре	Description
status	integer	Refer to Table 7-3 for error codes.

GetTCPErrorString

char *message = GetTCPErrorString (int errorNum);

Purpose

Converts the error number a TCP Library function returns into a meaningful error message.

Parameter

Input

Name	Туре	Description
errorNum	integer	Status value a TCP function returns.

Return Value

Name	Туре	Description
message	string	Explanation of error.

See Also

GetTCPSystemErrorString

GetTCPHostAddr

```
int status = GetTCPHostAddr (char buffer[], int bufferSize);
```

Purpose

Obtains the IP address of the computer on which your program is currently running.

Parameters

Input

Name	Туре	Description
bufferSize	integer	Number of bytes in buffer , including space for the ASCII NUL byte.

Output

Name	Туре	Description
buffer	character array	Buffer GetTCPHostAddr fills with the IP address of the computer your program is currently running on.

Parameter Discussion

GetTCPHostAddr fills in **buffer** with the IP address of your computer. The IP address is in the dot format, as in "130.164.1.1".

Name	Туре	Description
status	integer	Refer to Table 7-3 for error codes.

GetTCPHostName

```
int status = GetTCPHostName (char buffer[], int bufferSize);
```

Purpose

Obtains the name of the computer on which your program is currently running.

Parameters

Input

Name	Туре	Description
bufferSize	integer	Number of bytes in buffer , including space for the ASCII NUL byte.

Output

Name	Туре	Description
buffer	character array	Buffer GetTCPHostName fills with the name of the computer your program is currently running on.

	Name	Туре	Description
status	5	integer	Refer to Table 7-3 for error codes.

GetTCPPeerAddr

Purpose

Obtains the IP address of the computer on which a remote client or server is currently running.

Parameters

Input

Name	Туре	Description
connectionHandle	unsigned integer	TCP Library conversation handle you obtain from ConnectToTCPServer or receive in a server callback as the handle parameter of a TCP_CONNECT message.
bufferSize	integer	Number of bytes in buffer , including space for the ASCII NUL byte.

Output

Name	Туре	Description
buffer	character array	Buffer GetTCPPeerAddr fills with the IP address of the computer the remote client or server program is currently running on.

Return Value

Name	Туре	Description
status	integer	Refer to Table 7-3 for error codes.

Parameter Discussion

GetTCPPeerAddr fills in **buffer** with the IP address of the remote client or server computer. The IP address is in the dot format, as in "130.164.1.1".

GetTCPPeerName

Purpose

Obtains the name of the computer on which a remote client or server is currently running.

Parameters

Input

Name	Туре	Description
connectionHandle	unsigned integer	TCP Library conversation handle you obtain from ConnectToTCPServer or receive in a server callback as the handle parameter of a TCP_CONNECT message.
bufferSize	integer	Number of bytes in buffer , including space for the ASCII NUL byte.

Output

Name	Туре	Description
buffer	character array	Buffer GetTCPPeerName fills with the name of the computer the remote client or server program is currently running on.

Name	Туре	Description
status	integer	Refer to Table 7-3 for error codes.

GetTCPSystemErrorString

char *errorMsgString = GetTCPSystemErrorString (void);

Image: NoteOnly the Windows versions of LabWindows/CVI supportGetTCPSystemErrorString.

Purpose

Obtains a system message that describes the error that caused a TCP Library function to fail. The messages GetTCPSystemErrorString returns are sometimes more descriptive than the error codes the TCP Library functions return.

To obtain the correct system error message, you must call GetTCPSystemErrorString immediately after you call the TCP Library function that failed.

Parameters

None.

Return Value

Name	Туре	Description
errorMsgString	string	System error message string.

See Also

GetTCPErrorString

RegisterTCPServer

Purpose

Registers your program as a valid TCP server and allows other applications to connect to it for network communication.

Parameters

Input

Name	Туре	Description
portNumber	unsigned integer	Uniquely identifies a server on a single computer.
serverCallbackFunction	TCP function pointer	Pointer to the callback function that processes messages for the server.
callbackData	void pointer	Pointer to the user data.

Return Value

Name	Туре	Description
status	integer	Refer to Table 7-3 for error codes.

Parameter Discussion

serverCallbackFunction is the name of the function the TCP Library calls to process client requests.

The callback function must be of the following form:

xType specifies the type of message the server sends. The server callback function can receive the following transaction types:

TCP_CONNECT—Received when a client requests a connection.

TCP_DISCONNECT—Received when a client requests the termination of a connection or when a connection terminates because of an error. If the connection terminates because of an error,

the **errCode** parameter contains a negative error code. Refer to Table 7-3 at the end of this chapter for error codes.

TCP_DATATREADY—Received when the client sends data through TCP to the server. Your program, acting as the server, calls ServerTCPRead to obtain the data.

Use **errCode** only when the transaction type is TCP_DISCONNECT.

Note Return TRUE for the server callback function if the request is successful. Otherwise, return FALSE. Server callbacks should be short and should return as soon as possible.

callbackData is a 4-byte value the TCP Library passes to the callback function each time the TCP Library invokes the callback for the same server.

It is your responsibility to define the meaning of the callback data. The following examples show you how you can use the callback data:

- You can register your program as a TCP server multiple times under different port numbers. You can use the same callback function for all the server instances by using the callback data to differentiate between them.
- You can use the callback data as a pointer to a data object that you need to access in the callback function. By doing this, you can avoid declaring the data object as a global variable.

If you do not want to use the callback data, you can pass zero.

See Also

ConnectToTCPServer, UnregisterTCPServer

ServerTCPRead

Purpose

Reads data from a TCP client application.

Parameters

Input

Name	Туре	Description
conversationHandle	unsigned integer	Uniquely identifies the conversation.
dataBuffer	void pointer	Buffer in which to receive data.
dataSize	unsigned integer	Number of bytes to read.
timeout	unsigned integer	Timeout in milliseconds.

Return Value

Name	Туре	Description
nbytes	integer	Number of bytes read from the client. <0 = error; refer to Table 7-3 for error codes

See Also

RegisterTCPServer, ServerTCPWrite

ServerTCPWrite

Purpose

Writes data to a TCP client application.

Parameters

Input

Name	Туре	Description
conversationHandle	unsigned integer	Uniquely identifies the conversation.
dataPointer	void pointer	Buffer that holds data.
dataSize	unsigned integer	Number of bytes to write.
timeout	unsigned integer	Timeout in milliseconds.

Return Value

Name	Туре	Description
nbytes	integer	Number of bytes written to the client. <0 = error; refer to Table 7-3 for error codes

See Also

RegisterTCPServer, ServerTCPRead

SetTCPDisconnectMode

Purpose

Tells the TCP Library whether to close the local conversation handle when a remote client or server terminates a connection. There are two modes: auto disconnect and manual disconnect.

In the auto disconnect mode (TCP_DISCONNECT_AUTO), the TCP Library closes the local conversation handle after it invokes your client or server callback with the TCP_DISCONNECT message. If, however, the library invokes the TCP_DISCONNECT message while your program is already nested in a ServerTCPRead or ClientTCPRead call on the same conversation handle, the library does not close the conversation handle until the ServerTCPRead or ClientTCPRead function completes.

In the manual disconnect mode (TCP_DISCONNECT_MANUAL), the TCP Library never closes the local conversation handle automatically. You must call DisconnectFromTCPServer or DisconnectTCPClient to close the conversation handle. This method allows you to read data from the connection after you receive a TCP_DISCONNECT for the connection. You should close the handle to the connection after you have read all the data.

If you do not call ${\tt SetTCPDisconnectMode},$ the TCP Library uses the auto disconnect method.

Parameters

Input

Name	Туре	Description
conversationHandle	unsigned integer	TCP Library conversation handle you obtain from ConnectToTCPServer or receive in a server callback as the handle parameter of a TCP_CONNECT message.
disconnectMode	integer	Tells the TCP Library whether to close the conversation handle automatically. Use TCP_DISCONNECT_AUTO or TCP_DISCONNECT_MANUAL.

Return Value

Name	Туре	Description
status	integer	Refer to Table 7-3 for error codes.

See Also

DisconnectFromTCPServer, DisconnectTCPClient

UnregisterTCPServer

int status = UnregisterTCPServer (unsigned int portNumber);

Purpose

Unregisters your server application program as a TCP server.

Parameter

Input

Name	Туре	Description
portNumber	unsigned integer	Uniquely identifies a server on a single computer.

Return Value

Name	Туре	Description
status	integer	Refer to Table 7-3 for error codes.

See Also

RegisterTCPServer

Error Conditions

If an error condition occurs during a call to any of the functions in the LabWindows/CVI TCP Library, the status return value contains the error code. This code is a nonzero value that specifies the type of error that occurred. Error codes are negative numbers. Table 7-3 lists the currently defined error codes and the associated meanings.

Code	Error Message
0	kTCP_NoError
-1	-kTCP_UnableToRegisterService
-2	-kTCP_UnableToEstablishConnection
-3	-kTCP_ExistingServer
-4	-kTCP_FailedToConnect
-5	-kTCP_ServerNotRegistered
-6	-kTCP_TooManyConnections
-7	-kTCP_ReadFailed
-8	-kTCP_WriteFailed
-9	-kTCP_InvalidParameter
-10	-kTCP_OutOfMemory
-11	-kTCP_TimeOutErr
-12	-kTCP_NoConnectionEstablished
-13	-kTCP_GeneralIOErr
-14	-kTCP_ConnectionClosed
-15	-kTCP_UnableToLoadWinsockDLL
-16	-kTCP_IncorrectWinsockDLLVersion
-17	-kTCP_NetworkSubsystemNotReady
-18	-kTCP_ConnectionsStillOpen

Table 7.2	TOD	Library	Error	Codoo
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Utility Library

This chapter describes the functions in the LabWindows/CVI Utility Library. The Utility Library contains functions that do not fit into any of the other LabWindows/CVI libraries. The *Utility Library Function Overview* section contains general information about the Utility Library functions and panels. The *Utility Library Function Reference* section contains an alphabetical list of function descriptions.

Utility Library Function Overview

The Utility Library function panels are grouped in the tree structure in Table 8-1 according to the type of operations they perform.

The first- and second-level headings in the tree are the names of function classes and subclasses. Function classes and subclasses are groups of related function panels. The third-level headings are the names of individual function panels.

The following shows the structure of the ActiveX Automation Library function tree.

Timer/Wait Date/Time Keyboard File Utilities **Directory Utilities** External Modules Port I/O Standard Input/Output Window Run-Time Error Reporting **Old-Style Functions** Interrupts Physical Memory Access Persistent Variable Task Switching Launching Executables **Extended Functions** Miscellaneous

Class/Panel Name	Function Name
Timer/Wait	
Timer	Timer
Delay	Delay
Synchronized Wait	SyncWait
Date/Time	
Date in ASCII Format	DateStr
Time in ASCII Format	TimeStr
Get System Date	GetSystemDate
Set System Date	SetSystemDate
Get System Time	GetSystemTime
Set System Time	SetSystemTime
Keyboard	
Key Hit?	KeyHit
Get a Keystroke	GetKey
File Utilities	
Delete File	DeleteFile
Rename File	RenameFile
Copy File	CopyFile
Get File Size	GetFileSize
Get File Date	GetFileDate
Set File Date	SetFileDate
Get File Time	GetFileTime
Set File Time	SetFileTime
Get File Attributes	GetFileAttrs
Set File Attributes	SetFileAttrs
Get First File	GetFirstFile
Get Next File	GetNextFile
Make Pathname	MakePathname
Split Path	SplitPath
Directory Utilities	
Get Directory	GetDir
Get Project Directory	GetProjectDir
Get Module Directory	GetModuleDir
Get Full Path from Project	GetFullPathFromProject
Set Directory	SetDir
Make Directory	MakeDir
Delete Directory	DeleteDir
Get Drive	GetDrive
Set Drive	SetDrive
External Modules	Deebiive
Load External Module	LoadExternalModule
Load External Module Ex	LoadExternalModuleEx
Run External Module	RunExternalModule
Get External Module Address	GetExternalModuleAddr
Get External Would Address	SCEENCETHAIMOUUTEAUUI

Table 8-1. Functions in the Utility Library Function Tree

Class/Panel Name	Function Name
External Modules (continued)	
Unload External Module	UnloadExternalModule
Release External Module	ReleaseExternalModule
Port I/O	Refeabelineernatiioaare
Input Byte from Port	inp
Input Word from Port	inpw
Output Byte to Port	outp
Output Word to Port	outpw
Standard Input/Output Window	oucpw
Clear Screen	Cls
Get Stdio Window Options	GetStdioWindowOptions
Set Stdio Window Options	SetStdioWindowOptions
Get Stdio Window Position	GetStdioWindowPosition
Set Stdio Window Position	SetStdioWindowPosition
Get Stdio Window Fostion	GetStdioWindowSize
Set Stdio Window Size	SetStdioWindowSize
Get Stdio Window Visibility	GetStdioWindowVisibility
Set Stdio Window Visibility	SetStdioWindowVisibility
Get Stdio Port	GetStdioPort
Set Stdio Port	SetStdioPort
Run-Time Error Reporting	Seesediorore
Set Break on Library Errors	SetBreakOnLibraryErrors
Get Break on Library Errors	GetBreakOnLibraryErrors
Set Break on Protection Errors	SetBreakOnProtectionErrors
Get Break on Protection Errors	GetBreakOnProtectionErrors
Old-Style Functions	Geebreakoni roceccroniiriors
Enable Break on Library Errors	DisableBreakOnLibraryErrors
Disable Break on Library Errors	EnableBreakOnLibraryErrors
Interrupts	Inabiebreakonbibiarybriots
Disable Interrupts	DisableInterrupts
Enable Interrupts	EnableInterrupts
Get Interrupt State	GetInterruptState
Physical Memory Access	Geeineerrapebeate
Read from Physical Memory	ReadFromPhysicalMemory
Read from Physical Memory Ex	ReadFromPhysicalMemoryEx
Write to Physical Memory	WriteToPhysicalMemory
Write to Physical Memory Ex	WriteToPhysicalMemoryEx
Map Physical Memory	MapPhysicalMemory
Unmap Physical Memory	UnMapPhysicalMemory
Persistent Variable	onnaprnysteathemory
Set Persistent Variable	SetPersistentVariable
Get Persistent Variable	GetPersistentVariable
Task Switching	
Disable Task Switching	DisableTaskSwitching
Enable Task Switching	EnableTaskSwitching
Lhabe task Switching	LINGDICIASKOWICCILLING

Table 8-1. Functions in the Utility Library Function Tree (Continued)
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Class/Panel Name Launching Executables	Function Name
Launch Executable	LaunchExecutable
Extended Functions	
Launch Executable Extended	LaunchExecutableEx
Has Executable Terminated?	ExecutableHasTerminated
Terminate Executable	TerminateExecutable
Retire Executable Handle	RetireExecutableHandle
Miscellaneous	
System Help	SystemHelp
Get CVI Version	GetCVIVersion
Get Current Platform	GetCurrentPlatform
In Standalone Executable?	InStandaloneExecutable
Run-Time Engine Detached?	CVIRTEHasBeenDetached
Initialize CVI Run-Time Engine	InitCVIRTE
Close CVI Run-Time Engine	CloseCVIRTE
Low-Level Support Driver Loaded	CVILowLevelSupportDriverLoaded
Beep	Веер
Breakpoint	Breakpoint
Round Real to Nearest Integer	RoundRealToNearestInteger
Truncate Real Number	TruncateRealNumber
Get Window Display Setting	GetWindowDisplaySetting
Check for Duplicate Instance	CheckForDuplicateAppInstance

Table 8-1. Functions in the Utility Library Function Tree (Continued)

Class Descriptions

- Timer/Wait functions use the system timer, including functions that wait on a timed basis.
- Date/Time functions return the date or time in ASCII or integer formats and set the date or time.
- Keyboard functions provide access to user keystrokes.
- File Utilities functions manipulate files.
- Directory Utilities functions manipulate directories and disk drives.
- External Modules functions load, execute, and unload files that contain compiled code.
- Port I/O functions read and write data from I/O ports; available only under Windows.
- Standard Input/Output Window functions control various attributes of the Standard Input/Output window.
- Run-Time Error Reporting functions enable and disable the features that break execution when certain types of errors occur.
- Interrupts functions disable and enable the occurrence of interrupts.
- Physical Memory Access functions read and write data from and to physical memory addresses; supported only under Windows.
- Persistent Variable functions store and retrieve an integer value across multiple builds and executions of a project in the LabWindows/CVI development environment.
- Task Switching functions control whether a user can switch to another task when running your program under Windows.
- Launching Executables functions start another executable, check whether it is still running, and terminate it.
- Miscellaneous functions perform a variety of operations that do not fit into any of the other function classes.

The online help with each panel contains specific information about operating each function panel.

Utility Library Function Reference

This section describes each of the functions in the LabWindows/CVI Utility Library in alphabetical order.

Beep

void Beep (void);

Purpose

Sounds the speaker.

Parameters

None.

Return Value

Breakpoint

void Breakpoint (void);

Purpose

Suspends program operation. While the program is suspended, you can inspect or modify variables and use many other features of the LabWindows/CVI interactive program.

Calling Breakpoint with the debugging level set to None or from a compiled module has no effect.

Parameters

None.

Return Value

CheckForDuplicateAppInstance

Purpose

Determines if another copy of the same executable is running, but only if the other copy has already called this function. You can pass ACTIVATE_OTHER_INSTANCE in **activateOtherInstance** to bring the other copy to the front.

Use CheckForDuplicateAppInstance to prevent two instances of your application from running at the same time.

For other platforms, CheckForDuplicateAppInstance always returns -1.

Parameters

Input

Name	Туре	Description
activateOtherInstance	integer	Specifies whether to bring the other application instance to the front. Valid values are ACTIVATE_OTHER_INSTANCE or DO_NOT_ACTIVATE_OTHER_INSTANCE

Output

Name	Туре	Description
thereIsAnotherInstance	integer	1 if another instance of this executable exists; otherwise, 0. If CheckForDuplicateAppInstance returns an error code, this variable is always set to zero.

Return Value

Name	Туре	Description
status	integer	Indicates whether the function succeeded.

Image: Solution of the second secon

Return Codes

Code	Description
0	Success.
-1	You are running on a platform other than Windows 95/NT.
-2	Could not allocate system resources needed to check for a duplicate application instance.

Example

CloseCVIRTE

void CloseCVIRTE (void);

Purpose

Releases memory that InitCVIRTE allocated in the LabWindows/CVI Run-time Engine for a particular DLL.

If you call InitCVIRTE from DllMain, you also should call CloseCVIRTE from DllMain. You should call it in response to the DLL_PROCESS_DETACH message just before you return from DllMain.

Parameters

None.

Return Value

Cls

void Cls (void);

Purpose

Clears the Standard I/O window.

Parameters

None.

Return Value

CopyFile

```
int result = CopyFile (char sourceFileName[], char targetFileName[]);
```

Purpose

Copies the contents of an existing file to another file.

Parameters

Input

Name	Туре	Description
sourceFileName	string	File to copy.
targetFileName	string	Copy of the original file.

Return Value

Name	Туре	Description
result	integer	Result of the copy operation.

Return Codes

Code	Description	
0	Success.	
-1	File not found or directory in path not found.	
-3	General I/O error occurred.	
-4	Insufficient memory to complete operation.	
-5	Invalid path for either of the filenames.	
-6	Access denied.	
-7	Specified path is a directory, not a file.	
-8	Disk is full.	

Parameter Discussion

sourceFileName and **targetFileName** can contain wildcard characters '?' and '*'. If **sourceFileName** has wildcards, CopyFile copies all matching files. If **targetFileName** has wildcards, the function matches it to **sourceFileName**. If the target file is a directory, CopyFile copies the existing file or group of files into the directory.

sourceFileName also can be the empty string "", in which case CopyFile copies the file found by the most recent call to GetFirstFile or GetNextFile.

CVILowLevelSupportDriverLoaded

int	loaded	=	CVILowLevelSupportDriverLoaded	(void);
-----	--------	---	--------------------------------	---------

Note Only the Windows 95/NT versions of Lab Windows/CVI support CVILowLevelSupportDriverLoaded.

Purpose

Returns an indication of whether the LabWindows/CVI low-level support driver was loaded at startup. Table 8-2 lists Utility Library functions that require the LabWindows/CVI low-level driver.

Function	Platforms
inp	Windows NT
inpw	Windows NT
outp	Windows NT
outpw	Windows NT
ReadFromPhysicalMemory	Windows 95/NT
ReadFromPhysicalMemoryEx	Windows 95/NT
WriteToPhysicalMemory	Windows 95/NT
WriteToPhysicalMemoryEx	Windows 95/NT
MapPhysicalMemory	Windows 95/NT
UnMapPhysicalMemory	Windows 95/NT
DisableInterrupts	Windows 95
EnableInterrupts	Windows 95
DisableTaskSwitching	Windows 95

Table 8-2. Functions That Require Low-Level Driver

🕼 Note

Most of these functions do not return an error if the low-level support driver is not loaded. To make sure your calls to these functions can execute correctly, call CVILowLevelSupportDriverLoaded at the beginning of your program.

Both the LabWindows/CVI development environment and run-time engine automatically load the low-level support driver at startup if it is on disk. The low-level support driver ships with LabWindows/CVI. The Create Distribution Kit command in the Project window gives you an option to include it with your standalone executables or DLLs.

Parameters

None.

Return Value

Name	Туре	Description
loaded	integer	Indicates whether the LabWindows/CVI low-level support driver was loaded at startup.

Return Codes

Code	Description	
1	Low-level support driver was loaded at startup.	
0	Low-level support driver was not loaded at startup.	

CVIRTEHasBeenDetached

int hasBeenDetached = CVIRTEHasBeenDetached (void);

 Note
 Only the Windows 95/NT versions of LabWindows/CVI support

 CVIRTEHasBeenDetached.

Purpose

Indicates whether Windows 95/NT has detached the LabWindows CVI Run-time Engine from your standalone executable process. The operating system detaches the run-time engine from a process in the following cases:

- The process terminates.
- The process dynamically unloads a DLL that uses the run-time engine, and the process does not directly link to the run-time engine.

You might need to use CVIRTEHasBeenDetached if you call LabWindows/CVI library functions in response to a PROCESS_DETACH message in the DllMain function of a DLL. In some cases, Windows 95/NT sends a PROCESS_DETACH message to the LabWindows/CVI Run-time Engine before it sends a PROCESS_DETACH message to your DLL. When the LabWindows/CVI Run-time Engine receives a PROCESS_DETACH message, it releases all the system resources it has acquired. When, in response to the PROCESS_DETACH message, your DLL calls LabWindows/CVI library functions that assume the system resources are still present, a general protection fault occurs.

A similar problem can occur when you call the atexit function in a DLL to register a routine for the ANSI C library to execute when your DLL unloads. The ANSI C library calls your routine when the DLL receives a PROCESS_DETACH message. This can occur after the LabWindows/CVI Run-time Engine receives a PROCESS_DETACH message. If your registered function calls LabWindows/CVI library functions that assume the system resources are still present, a general protection fault occurs.

To prevent such problems, call LabWindows/CVI functions from the PROCESS_DETACH code and registered functions in your DLL only if CVIRTEHasBeenDetached returns 0.

Note CVIRTEHasBeenDetached always returns 0 when you call it in the LabWindows/CVI development environment or on platforms other than Windows 95/NT.

Parameters

Name	Туре	Description
hasBeenDetached	integer	 1 = The run-time engine has already received the PROCESS_DETACH message. Do not call LabWindows/CVI library functions. 0 = The run-time engine has not yet received a PROCESS_DETACH message. You can safely call LabWindows/CVI library functions.

Return Value

Example:

```
int myPanel = 0;
static void CleanupPanels (void)
{
    if ( ! CVIRTEHasBeenDetached())
        if (myPanel > 0)
            DiscardPanel (myPanel);
}
int CreatePanel (void)
{
    if ((myPanel = LoadPanel (0, "my.uir", MY_PANEL) < 0)
        return 0;
    atexit (CleanupPanels)
    return 1;
}
```

DateStr

char *s = DateStr (void);

Purpose

Returns a 10-character string in the form *MM-DD-YYYY*, where *MM* is the month, *DD* is the day, and *YYYY* is the year.

Parameters

None.

Return Value

Name	Туре	Description
s	10-character string	Date in <i>MM-DD-YYYY</i> format.

Delay

void Delay (double numberOfSeconds);

Purpose

Waits the number of seconds **numberOfSeconds** indicates. The resolution under Windows is normally 1 ms. If, however, you set the useDefaultTimer configuration option to True, the resolution is 55 ms.

The resolution on Sun Solaris is 1 ms.

Parameter

Input

Name	Туре	Description
numberOfSeconds	double-precision	Number of seconds to wait.

Return Value

DeleteDir

```
int result = DeleteDir (char directoryName[]);
```

Purpose

Deletes an existing directory.

Parameter

Input

Name	Туре	Description
directoryName	string	Name of directory to delete.

Return Value

Name	Туре	Description
result	integer	Result of the operation.

Return Codes

Code	Description
0	Success.
-1	Directory not found.
-3	General I/O error occurred.
-4	Insufficient memory to complete operation.
-6	Access denied, or directory not empty.
-7	Path is a file, not a directory.

DeleteFile

int result = DeleteFile (char fileName[]);

Purpose

Deletes an existing file from disk.

Parameter

Input

Name	Туре	Description
fileName	string	File to delete.

Return Value

Name	Туре	Description
result	integer	Result of the delete operation.

Return Codes

Code	Description
0	Success.
-1	File not found or directory in path not found.
-3	General I/O error occurred.
-4	Insufficient memory to complete operation.
-5	Invalid path; for example, c:filename in Windows.
-6	Access denied.
-7	Specified path is a directory, not a file.

Parameter Discussion

fileName can contain wildcard characters '?' and '*', in which case DeleteFile deletes all matching files.

fileName also can be the empty string "", in which case DeleteFile deletes the file found by the most recent call to GetFirstFile or GetNextFile.

DisableBreakOnLibraryErrors

void DisableBreakOnLibraryErrors (void);

Purpose

DisableBreakOnLibraryErrors directs LabWindows/CVI not to display a run-time error dialog box when a National Instruments library function reports an error.

In general, you should use the Break on Library Errors checkbox in the **Run Options** command of the Project window to disable this option. However, you can use this function in conjunction with EnableBreakOnLibraryErrors to temporarily suppress the Break on Library Errors feature around a segment of code. DisableBreakOnLibraryErrors does not affect the state of the Break on Library Errors checkbox in the **Run Options** command of the Project window.

Note SetBreakOnLibraryErrors *obsoletes* DisableBreakOnLibraryErrors.

Parameters

None.

Return Value

DisableInterrupts

void DisableInterrupts (void);

Purpose

Uses the CLI instruction to turn off all maskable 80x86 interrupts under Windows 3.1 and Windows 95. Under UNIX, DisableInterrupts uses sigblock to block all blockable signals.

Note	Under Windows 95, DisableInterrupts requires the LabWindows/CVI
	low-level support driver. LabWindows/CVI loads the driver at startup if it is on disk. You can check whether LabWindows/CVI loaded the driver at startup by
	calling CVILowLevelSupportDriverLoaded.

Note Under Windows NT, EnableInterrupts and DisableInterrupts have no effect. Interrupts are always enabled while your program is running at the user level, as opposed to the kernel level.

Parameters

None.

Return Value

None.

See Also

CVILowLevelSupportDriverLoaded

DisableTaskSwitching

void DisableTaskSwitching (void);

NoteOnly the Windows versions of LabWindows/CVI supportDisableTaskSwitching.

Purpose

Prevents the user from using one of the following Windows features to switch another task:

- The <Alt-Tab>, <Alt-Esc>, or <Ctrl-Esc> key combination under Windows 3.1 or Windows 95.
- The **Switch To** item in the system menu under Windows 3.1.

DisableTaskSwitching affects the behavior of these keys only while LabWindows/CVI or a LabWindows/CVI standalone executable is the active application under Windows.

If you configure Windows 95 to hide the taskbar, DisableTaskSwitching also prevents the user from using the mouse to bring the taskbar back up.

DisableTaskSwitching has no effect in Windows NT. Refer to the *Alternatives under Windows NT* section in this function description for instructions on how to achieve the desired effect.

Note Under Windows 95, DisableTaskSwitching requires the LabWindows/CVI low-level support driver. LabWindows/CVI loads the driver at startup if it is on disk. You can check whether LabWindows/CVI loaded the driver at startup by calling CVILowLevelSupportDriverLoaded.

Parameters

None.

Return Value

None.

See Also

CVILowLevelSupportDriverLoaded

Disabling the Task List

DisableTaskSwitching does not prevent the user from clicking on the desktop to get the task list under Windows 3.1 or from clicking on the taskbar under Windows 95. You can prevent the user from clicking on the desktop by forcing your window to cover the entire screen.

Forcing Window to Cover Entire Screen

You can force your window to cover the entire screen by making the following calls to functions in the User Interface Library.

```
SetPanelAttribute (panel, ATTR_SIZABLE, FALSE);
SetPanelAttribute (panel, ATTR_CAN_MINIMIZE, FALSE);
SetPanelAttribute (panel, ATTR_CAN_MAXIMIZE, FALSE);
SetPanelAttribute (panel, ATTR_SYSTEM_MENU_VISIBLE, FALSE);
SetPanelAttribute (panel, ATTR_MOVABLE, FALSE);
SetPanelAttribute (panel, ATTR_WINDOW_ZOOM, VAL_MAXIMIZE);
```

In these calls, panel is the panel handle for your top-level window. These calls work under Windows 3.1, Windows 95, and Windows NT.

Alternatives under Windows 3.1

Under Windows 3.1, you can prevent the user accessing the task list by disabling the Task Manager. You can do this by changing the following line in your system.ini [boot] section from:

```
taskman.exe = taskman.exe
to:
taskman.exe =
```

Forcing your window to cover the entire screen or disabling the Task Manager does not prevent the user from task switching using the <Alt-Tab> and <Alt-Esc> key combinations. You also must call DisableTaskSwitching to disable the <Alt-Tab> and <Alt-Esc> key combinations. As an alternative to calling DisableTaskSwitching, you can arrange for Windows to open your standalone application in place of the Program Manager when Windows boots. You can do this by changing the following line in your system.ini [boot] section from:

```
shell = progman.exe
to:
shell = full-path-of-your-executable
```

Alternatives under Windows 95

Under Windows 95, you can arrange for your standalone application to appear in place of the desktop when Windows boots.

You can do this by changing the following line in your system.ini [boot] section from:

```
shell = Explorer.exe
to:
shell = full-path-of-your-executable
```

Alternatives under Windows NT

Under Windows NT, you can achieve the same results as DisableTaskSwitching by arranging for your LabWindows/CVI application to be brought up in place of the Program Manager and by disabling the Task Manager. You can do this by making the following changes to the registry entry for the key name:

KEY_LOCAL_MACHINE\Software\Microsoft\Windows NT
\CurrentVersion\Winlogon

- Change the value for shell to the pathname of your application executable.
- Add a value with the name taskman. Set the data to an empty string.

Preventing Interference with Real-Time Processing

Under Windows, many user actions can interfere with real-time processing. The following actions suspend the processing of events:

- Moving and sizing top-level windows
- Bringing down the System menu
- Pressing the <Alt-Tab> key combination

You can prevent these user actions from interfering with event processing by:

- Calling DisableTaskSwitching or using the alternative this section mentions for Windows NT.
- Making all your top-level panels non-movable and non-sizable.
- Not using the Standard I/O Window in your final application.
- Making the following calls if you use any of the built-in pop-ups in the User Interface Library:

```
SetSystemPopupsAttribute (ATTR_MOVABLE, 0);
SetSystemPopupsAttribute (ATTR_SYSTEM_MENU_VISIBLE, 0);
```

An alternative approach is available on Windows 95/NT. You can enable timer control callbacks while the user presses <Alt-Tab>, pulls down the **System** menu, or, in some cases, moves or sizes a window. You can do this by using the following function call:

SetSystemAttribute (ATTR_ALLOW_UNSAFE_TIMER_EVENTS, 1);

This alternative approach is incomplete and can be unsafe. Refer to the discussion on *Unsafe Timer Events* in the *Using the System Attributes* section of Chapter 3, *Programming with the User Interface Library*, of the *LabWindows/CVI User Interface Reference Manual*.

See Also

EnableTaskSwitching

EnableBreakOnLibraryErrors

void EnableBreakOnLibraryErrors (void);

Purpose

EnableBreakOnLibraryErrors directs LabWindows/CVI to display a run-time error dialog box when a National Instruments library function reports an error. If you disable debugging, EnableBreakOnLibraryErrors has no effect.

In general, you should check the Break on Library Errors checkbox in the **Run Options** command of the Project window to enable this feature. However, you can use EnableBreakOnLibraryErrors in conjunction with DisableBreakOnLibraryErrors to temporarily suppress the Break on Library Errors feature around a segment of code. EnableBreakOnLibraryErrors does not affect the state of the Break on Library Errors checkbox.

Note SetBreakOnLibraryErrors *obsoletes* EnableBreakOnLibraryErrors.

Parameters

None.

Return Value

EnableInterrupts

void EnableInterrupts (void);

Purpose

Uses the STI instruction to turn on all maskable 80x86 interrupts under Windows 3.1 and Windows 95. Under UNIX, EnableInterrupts reverses the effect of the last call to DisableInterrupts. It restores the signal processing state to the condition prior to the DisableInterrupts call.

Note Note

Under Windows 95, EnableInterrupts requires the Lab Windows/CVI low-level support driver. Lab Windows/CVI loads the driver at startup if it is on disk. You can check whether Lab Windows/CVI loaded the driver at startup by calling CVILowLevelSupportDriverLoaded.

Note Under Windows NT, EnableInterrupts and DisableInterrupts have no effect. Interrupts are always enabled while your program is running at the user level, as opposed to the kernel level.

Parameters

None.

Return Value

None.

See Also

CVILowLevelSupportDriverLoaded

EnableTaskSwitching

void EnableTaskSwitching (void);

Note Only the Windows versions of LabWindows/CVI support EnableTaskSwitching.

Purpose

Lets the user switch to another task by using the <Alt-Tab>, <Alt-Esc>, and <Ctrl-Esc> key combinations, and the **Switch To** item in the **Control/System** menu. EnableTaskSwitching affects the behavior of these keys only while LabWindows/CVI or a LabWindows/CVI standalone executable is the active application.

Parameters

None.

Return Value

None.

See Also

DisableTaskSwitching

ExecutableHasTerminated

int status = ExecutableHasTerminated (int executableHandle);

Purpose

Determines whether an application you started with LaunchExecutableEx has terminated.

Parameter

Input

Name	Туре	Description
executableHandle	integer	Executable handle you obtain from LaunchExecutableEx.

Return Value

Name	Туре	Description
status	integer	Result of the operation.

Return Codes

Note

Code	Description
-1	Handle is invalid.
0	Executable is still running.
1	Executable has been terminated.

If you launch a LabWindows/CVI executable under Windows 3.x, the launched executable process terminates itself after it launches a copy of the LabWindows/CVI Run-time Engine. ExecutableHasTerminated then always returns 1 because it cannot track the process identification for the second run-time engine. Refer to LaunchExecutableEx for more information.

GetBreakOnLibraryErrors

int state = GetBreakOnLibraryErrors (void);

Purpose

Returns the state of the Break on Library Errors option. It returns a 1 if you enable the Break on Library Errors option. If you disable debugging, GetBreakOnLibraryErrors always returns 0.

You can change the state of the Break on Library Errors option interactively using the **Run Options** command of the Project window. You can change the state of the Break on Library Errors option programmatically using SetBreakOnLibraryErrors.

Parameters

None.

Return Value

Name	Туре	Description
state	integer	Current state of the Break on Library Errors option.

Return Codes

Code	Description
1	Break on Library Errors option is enabled.
0	Break on Library Errors option is disabled or debugging is disabled.

See Also

SetBreakOnLibraryErrors

GetBreakOnProtectionErrors

int state = GetBreakOnProtectionErrors (void);

Purpose

Returns the state of the Break on Protection Errors feature. It returns a 1 if you enable the option. If you disable debugging GetBreakOnProtectionErrors always returns 0.

For more information, refer to SetBreakOnProtectionErrors.

Parameters

None.

Return Value

Name	Туре	Description
state	integer	Current state of the Break on Protection Errors option.

Return Codes

Code	Description
1	Break on Protection Errors option is enabled.
0	Break on Protection Errors option is disabled or debugging is disabled.

See Also

SetBreakOnProtectionErrors

GetCurrentPlatform

int platformCode = GetCurrentPlatform (void);

Purpose

Returns a code that represents the operating system under which a project or standalone executable is running.

Do not confuse the return value of GetCurrentPlatform with the predefined macros such as _NI_mswin_, _NI_unix_, and others, which specify the platform on which you compile a source file.

GetCurrentPlatform is useful when you have a program that can run under multiple operating systems but must take different actions on the different systems. For example, consider a standalone executable that can run under Sun Solaris 2 and Windows 95/ NT. If the program must behave differently on the two platforms, you can use GetCurrentPlatform to determine the platform at run time.

Parameters

None.

Return Value

Name	Туре	Description
platformCode	integer	Indicates the current operating system.

Return Codes

Message	Code	Platform
kPlatformWin16	1	Windows 3.1
kPlatformWin95	2	Windows 95
kPlatformWinnt	3	Windows NT
kPlatformSunos4	4	Sun Solaris 1
kPlatformSunos5	5	Sun Solaris 2
kPlatformHPUX9	6	HP-UX 9.x
kPlatformHPUX10	7	HP-UX 10.x

L F

Note

GetCurrentPlatform returns kPlatformWin16 when you call it from a program that is running under Windows 95 but that was built using LabWindows/CVI for Windows 3.1.

GetCVIVersion

int versionNum = GetCVIVersion (void);

Purpose

Returns the version of LabWindows/CVI you are running. In a standalone executable, this tells you which version of the LabWindows/CVI Run-time Libraries you are using.

The value is in the form Nnn, where the N.nn is the version number the About LabWindows/CVI dialog box shows.

For example, for LabWindows/CVI version 5.0, GetCVIVersion returns 500. For version 4.0.1, it returns 401. The values always increase with each new version of LabWindows/CVI.

Do not confuse the return value of GetCVIVersion with the predefined macro_CVI_, which specifies the version of LabWindows/CVI in which you compile the source file that contains the macro.

Parameters

None.

Return Value

Name	Туре	Description
versionNum	integer	Version number of LabWindows/CVI or the Run-time Libraries.

Return Code

Code	Description
Nnn	Where N. nn is the LabWindows/CVI version.

GetDir

int result = GetDir (char currentDirectory[]);

Purpose

Gets the current working directory on the default drive.

Parameter

Output

Name	Туре	Description
currentDirectory	string	Current directory.

Return Value

Name	Туре	Description
result	integer	Result of the operation.

Return Codes

Code	Description
0	Success.
-3	General I/O error occurred.
-4	Insufficient memory to complete operation.

Parameter Discussion

currentDirectory must be at least MAX_PATHNAME_LEN bytes long.

GetDrive

int result = GetDrive (int *currentDriveNumber, int *numberOfDrives);

Note Only the Windows versions of Lab Windows/CVI support GetDrive.

Purpose

Gets the current default drive number and the total number of logical drives in the system.

Parameters

Output

Name	Туре	Description
currentDriveNumber	integer	Current default drive number.
numberOfDrives	integer	Number of logical drives.

Return Value

Name	Туре	Description
result	integer	Result of the operation.

Return Codes

Code	Description
0	Success.
-1	Current directory is on a network drive that is not mapped to a local drive. currentDriveNumber is set correctly, but numberOfDrives is set to -1.
-3	General I/O error occurred.
-4	Insufficient memory to complete the operation.
-6	Access denied.

Parameter Discussion

The mapping between the drive number and the logical drive letter is 0 = A, 1 = B, and so on.

The total number of logical drives includes floppy-disk drives, hard-disk drives, RAM disks, and networked drives.

GetExternalModuleAddr

Purpose

Obtains the address of an identifier in a module you loaded using LoadExternalModule or LoadExternalModuleEx.

Parameters

Input

Name	Туре	Description
name	string	Name of the identifier.
moduleID	integer	ID of the loaded module.

Output

Name	Туре	Description
status	integer	Zero or error code.

Return Value

Name	Туре	Description
address	void pointer	Address of the identifier.

Return Codes

Code	Description
0	Success.
-1	Out of memory.
-4	Invalid file format.
-5	Undefined references.
-8	Cannot open file.
-9	Invalid module ID.
-10	Identifier not defined globally in the module.
-25	DLL initialization failed, for example, DLL file not found.

Parameter Discussion

moduleID is the value LoadExternalModule returns.

name is the name of the identifier, the address of which you obtain from the external module. The identifier must be a variable or function name defined globally in the external module.

status is zero if the function is a success or a negative error code if it fails.

If GetExternalModuleAddr succeeds, it returns the address of the variable or function in the module. If GetExternalModuleAddr fails, it returns NULL.

If the return value is the address of a function that has a calling convention different from the default calling convention, you must include the calling convention in the declaration of the function pointer. For example, if the function is declared in the external module as

```
int __stdcall SetADouble (double d);
```

and the default calling convention is __cdecl, you should declare the function pointer as int (__stdcall * SetADouble_FnPtr)(double d) = NULL;.

Select **Options**»**Compiler Options** in the Project window to determine the default calling convention.

Example

```
void (*funcPtr) (char buf[], double dval, int *ival);
int module_id;
int status;
char buf[100];
double dval;
int ival;
char *pathname;
char *funcname;
pathname = "EXTMOD.OBJ";
funcname = "my_function";
module_id = LoadExternalModule (pathname);
if (module_id < 0)</pre>
   FmtOut ("Unable to load %s\n", pathname);
else
   {
   funcPtr = GetExternalModuleAddr (module_id, funcname, &status);
   if (funcPtr == NULL)
       FmtOut ("Could not get address of %s\n", funcname);
   else
       (*funcPtr) (buf, dval, &ival);
   }
```

GetFileAttrs

I Note Only the Windows versions of Lab Windows/CVI support GetFileAttrs.

Purpose

Gets the read-only, system, hidden, and archive attributes of a file.

The **read-only** attribute makes it impossible to write to the file or create a file with the same name.

The **system** attribute and **hidden** attribute both prevent the file from appearing in a directory list and exclude it from normal searches.

The operating system sets the **archive** attribute whenever you modify the file. The DOS backup command clears the **archive** attribute.

Parameters

Input

Name	Туре	Description
fileName	string	File to get the attributes of.

Output

Name	Туре	Description
read-only	integer	Read-only attribute.
system	integer	System attribute.
hidden	integer	Hidden attribute.
archive	integer	Archive attribute.

Return Value

Name	Туре	Description
result	integer	Result of the operation.

Return Codes

Code	Description
0	Success.
1	Specified file is a directory.
-1	File not found.

Parameter Discussion

Each attribute parameter contains one of the following values:

0-attribute is not set

1—attribute is set

fileName can be the empty string "", in which case GetFileAttrs returns the attributes of the file that the most recent call to GetFirstFile or GetNextFile found.

Example

```
/* Get the attributes of WAVEFORM.DAT. */
int read_only, system, hidden, archive;
GetFileAttrs ("WAVEFORM.DAT",&read_only,&system,&hidden,&archive);
if (read_only)
    FmtOut("WAVEFORM.DAT is a read-only file!");
```

GetFileDate

```
int result = GetFileDate (char fileName[], int *month, int *day, int *year);
```

Purpose

Gets the date of a file.

Parameters

Input

Name	Туре	Description
fileName	string	File to get the date of.

Output

Name	Туре	Description
month	integer	Month; 1–12.
day	integer	Day of month; 1–31.
year	integer	Year; 1980–2099.

Return Value

Name	Туре	Description
result	integer	Result of the operation.

Return Codes

Code	Description
0	Success.
-1	File not found or directory in path not found.
-3	General I/O error occurred.
-4	Insufficient memory to complete operation.
-5	Invalid path, for example, c:filename in Windows.
-6	Access denied.

Parameter Discussion

fileName can be the empty string "", in which case GetFileDate returns the date of the file that the most recent call to GetFirstFile or GetNextFile found.

Example

```
/* Get the date of WAVEFORM.DAT. */
int month, day, year;
GetFileDate ("WAVEFORM.DAT", &month, &day, &year);
```

GetFileSize

```
int result = GetFileSize (char fileName[], long *fileSize);
```

Purpose

Returns the size of a file.

Parameters

Input

Name	Туре	Description
fileName	string	Name of the file.

Output

Name	Туре	Description
fileSize	long	Size of the file in bytes.

Return Value

Name	Туре	Description
result	integer	Result of the operation.

Return Codes

Code	Description
0	Success.
-1	File not found or directory in path not found.
-3	General I/O error occurred.
-4	Insufficient memory to complete the operation.
-5	Invalid path; for example, c:filename in Windows.
-6	Access denied.

Parameter Discussion

fileName can be the empty string "", in which case GetFileSize returns the size of the file that the most recent call to GetFirstFile or GetNextFile found.

Example

```
/* Get the size of WAVEFORM.DAT. */
long size;
if (GetFileSize ("WAVEFORM.DAT",&size) == 0)
FmtOut("The size of WAVEFORM.DAT is %i[b4]",size);
```

GetFileTime

Purpose

Gets the time of a file.

Parameters

Input

Name	Туре	Description
fileName	string	File to get the date of.

Output

Name	Туре	Description
hours	integer	Hours; 0–23.
minutes	integer	Minutes; 0–59.
seconds	integer	Seconds; 0–58, odd values are rounded down.

Return Value

Name	Туре	Description
result	integer	Result of the operation.

Return Codes

Code	Description
0	Success.
-1	File not found or directory in path not found.
-3	General I/O error occurred.
-4	Insufficient memory to complete the operation.
-5	Invalid path; for example, c:filename in Windows.
-6	Access denied.

Parameter Discussion

fileName can be the empty string "", in which case GetFileTime returns the time of the file the most recent call to GetFirstFile or GetNextFile found.

Example

```
/* Get the time of WAVEFORM.DAT. */
int hours, minutes, seconds;
GetFileTime ("WAVEFORM.DAT", &hours, &minutes, &seconds);
```

GetFirstFile

Purpose

Conducts a search for files with specified attributes and returns the first matching file. Call GetNextFile to get the names of other matching files.

If you select multiple attributes, a match occurs on the first file for which one or more of the specified attributes are set and that matches the pattern in **searchPath**. The search attributes are **normal**, **read-only**, **system**, **hidden**, **archive**, and **directory**.

Under UNIX, GetFirstFile honors only the **directory** attribute. If you pass 1 for the **directory** attribute, only directories match. If you pass 0 for the **directory** attribute, only non-directories match.

Under Windows, GetFirstFile honors all the attributes. The **normal** attribute specifies files with no attributes set or with only the archive bit set. The **archive** attribute specifies files that have been modified because they were last backed up using the DOS backup command. The **read-only** attribute specifies files that are protected from modification or overwriting. The **system** and **hidden** attributes specify files that normally do not appear in a directory listing. The **directory** attribute specifies directories.

If you use only the **normal** attribute, GetFirstFile can return any file that is not read only, not a system file, not hidden, and not a directory. Normal files can have the **archive** attribute on or off.

If you specify the **read-only** attribute, GetFirstFile can return any file that is read only unless the file is a system, or hidden, file and you did not specify the **system**, or **hidden** attribute.

If you specify the **system** attribute, GetFirstFile can return any system file unless the file is also a hidden file and you did not specify the **hidden** attribute. If you do not specify the **system** attribute, a system file cannot match regardless of its other attributes.

If you specify the **hidden** attribute, GetFirstFile can return any hidden file unless the file is also a system file and you did not specify the **system** attribute. If you do not specify the **hidden** attribute, a hidden file cannot match regardless of its other attributes.

If you use more than one attribute, the effect is additive. GetFirstFile returns any file that meets only one of the attributes you specify regardless of the additional attributes you specify.

Parameters

Input

Name	Туре	Description
searchPath	string	Path to search.
normal	integer	Normal attribute.
read-only	integer	Read-only attribute.
system	integer	System attribute.
hidden	integer	Hidden attribute.
archive	integer	Archive attribute.
directory	integer	Directory attribute.

Output

Name	Туре	Description
fileName	string	First file found.

Return Value

Name	Туре	Description
result	integer	Result of search.

Return Codes

Code	Description
0	Success.
-1	No files found that match criteria.
-3	General I/O error occurred.
-4	Insufficient memory to complete the operation.
-5	Invalid path, for example, c:filename in Windows.
-6	Access denied.

Parameter Discussion

searchPath can contain the wildcard characters '*' and '?'.

Each attribute parameter can have one of the following values:

- 0— do not search for files with the attribute
- 1— search for files with the attribute

fileName contains the basename and extension of the first matching file and must be at least MAX_FILENAME_LEN characters in length.

GetFullPathFromProject

int result = GetFullPathFromProject (char fileName[], char fullPathName[]);

Purpose

Gets the full pathname for the file you specify, if the file is in the currently loaded project.

Parameters

Input

Name	Туре	Description
fileName	string	Name of the file in the project.

Output

Name	Туре	Description
fullPathName	string	Full pathname of the file.

Return Value

Name	Туре	Description
result	integer	Result of the operation.

Return Codes

Code	Description
0	Success.
-1	File is not in the project.

Parameter Discussion

fileName is the name of a file that is in the currently loaded project. The name must be a simple filename and should not contain any directory paths. For example, file.c is a simple filename, whereas dir\file.c is not.

fullPathName must be at least MAX_PATHNAME_LEN bytes long.

Using This Function

GetFullPathFromProject is useful when your program needs to access a file in the project and you do not know what directory the file is in.

Example

```
char *fileName;
char fullPath[MAX_PATHNAME_LEN];
fileName = "myfile.c";
if (GetFullPathFromProject (fileName, fullPath) < 0)
    FmtOut ("File %s is not in the project\n", fileName);
```

Note LabWindows/CVI does not report run-time errors for

GetFullPathFromProject.

GetInterruptState

int interruptstate = GetInterruptState (void);

Note Only the Windows versions of Lab Windows/CVI support GetInterruptState.

Purpose

Returns the state of the interrupt bit of the 80x86 CPU status flag.

Under Windows NT, GetInterruptState always returns 1. Interrupts are always enabled while your program is running at the user level, as opposed to the kernel level.

Parameters

None.

Return Value

Name	Туре	Description
interruptstate	integer	Interrupt bit of 80x86 CPU status flag.

GetKey

int k = GetKey (void);

Purpose

Waits for the user to press a key and returns the key code as an integer value.

Note GetKey detects keystrokes only in the Standard I/O window. It does not detect keystrokes in windows you create with the User Interface Library or in the console window in a Windows Console Application.

Parameters

None.

Return Value

Name	Туре	Description
k	integer	Key code.

Using This Function

The values GetKey returns are the same as the key values the User Interface Library uses. Refer to userint.h. Table 8-3 shows examples of keystrokes and the values GetKey returns for them.

Keystroke	Return Value
	'b'
<ctrl-b></ctrl-b>	(VAL_MENUKEY_MODIFIER 'B')
<f4></f4>	VAL_F4_VKEY
<shift-f4></shift-f4>	(VAL_SHIFT_MODIFIER VAL_F4_VKEY)

Table 8-3. Example Keystrokes and GetKey Return Values

C Note

GetKey returns -1 if you are running under UNIX and have done one of the following:

- Selected Options»Environment»Use hosts system's Standard Input/Output in the Project window
- **Called** SetStdioPort to set the port to HOST_SYSTEM_STDIO

Example

```
/* Give the user a chance to quit the program. */
int k;
FmtOut ("Enter 'q' to quit, any other key to continue");
k = GetKey ();
if ((k == 0x0051) || (k == 0x0071)) /* q or Q */
exit (0);
```

GetModuleDir

int result = GetModuleDir (void *moduleHandle, char directoryPathname[]);

Note Only the Windows 95/NT versions of LabWindows/CVI support GetModuleDir.

Purpose

Obtains the name of the directory of the DLL module you specify.

GetModuleDir is useful when you distribute a DLL and its related files to multiple users who might place them in different directories. If your DLL needs to access a file that is in the same directory as the DLL, you can use GetModuleDir and MakePathname to construct the full pathname.

If the moduleHandle you specify is zero, GetModuleDir returns the same result as GetProjectDir.

Parameters

Input

Name	Туре	Description
moduleHandle	void pointer	Module handle of DLL, or zero for the project.

Output

Name	Туре	Description
directoryPathname	string	Directory of the module.

Return Value

Name	Туре	Description
result	integer	Result of the operation.

Return Codes

Code	Description
0	Success.
-1	Current project has no pathname; that is, it is untitled.
-2	There is no current project.
-3	Out of memory.
-4	Operating system is unable to determine the module directory; moduleHandle is probably invalid.

Parameter Discussion

directoryPathname must be at least MAX_PATHNAME_LEN bytes long.

If you want to obtain the directory name of the DLL in which the call to GetModuleDir resides, then pass __CVIUserHInst as the **moduleHandle**. You can pass any valid Windows module handle. If you pass 0 for the **moduleHandle**, GetModuleDir obtains the directory of the project or standalone executable.

GetNextFile

int result = GetNextFile (char fileName[]);

Purpose

Gets the next file found in the search that GetFirstFile starts.

Parameter

Output

Name	Туре	Description
fileName	string	Next file found.

Return Value

Name	Туре	Description
result	integer	Result of the search.

Return Codes

Code	Description
0	Success.
-1	No more files found that match criteria.
-2	GetFirstFile must initiate search.

Parameter Discussion

fileName contains the basename and extension of the next matching file and must be at least MAX_FILENAME_LEN characters in length.

GetPersistentVariable

void GetPersistentVariable (int *value);

Purpose

Returns the value SetPersistentVariable sets. However, if you unloaded the project since you last called SetPersistentVariable, the function returns zero.

In a standalone executable, GetPersistentVariable returns zero if you have not called SetPersistentVariable since the start of execution.

Parameter

Output

Name	Туре	Description
value	integer	Current value of the persistent variable.

Return Value

GetProjectDir

```
int result = GetProjectDir (char directoryName[]);
```

Purpose

Gets the name of the directory that contains the currently loaded project file.

Parameter

Output

Name	Туре	Description
directoryName	string	Directory of project.

Return Value

Name	Туре	Description
result	integer	Result of the operation.

Return Codes

Code	Description
0	Success.
-1	Current project has no pathname; it is untitled.

Parameter Discussion

directoryName must be at least MAX_PATHNAME_LEN bytes long.

Using This Function

GetProjectDir is useful when you distribute a project and its related files to multiple users who might place them in a different directory on each computer. If your program needs to access a file that is in the same directory as the project, you can use GetProjectDir and MakePathname to construct the full pathname.

Example

```
/* Get the name of the directory that contains myfile. */
char *fileName;
char projectDir[MAX_PATHNAME_LEN];
char fullPath[MAX_PATHNAME_LEN];
fileName = "myfile";
if (GetProjectDir (projectDir) < 0)
    FmtOut ("Project is untitled\n");
else
    MakePathname (projectDir, fileName, fullPath);</pre>
```

GetStdioPort

void GetStdioPort (int *stdioPort);

C Note Only the UNIX versions of LabWindows/CVI support GetStdioPort.

Purpose

Gets a value that indicates the current destination for data you write to the Standard Output and the source of data you read from the Standard Input.

The Standard I/O port can be either the LabWindows/CVI Standard Input/Output window or the Standard Input/Output of the host system.

Parameter

Output

Name	Туре	Description
stdioPort	integer	0 = LabWindows/CVI Standard Input/Output window
		1 = Standard Input/Output of host system

Return Value

GetStdioWindowOptions

Purpose

Gets the current value of the following Standard Input/Output window options:

- Maximum number of lines
- Bring to front when modified
- Show line numbers

Parameters

Output

Name	Туре	Description
maxNumLines	integer	Maximum number of lines you can store in the Standard Input/Output window. If this amount is exceeded, lines are discarded from the top.
bringToFrontWhenModified	integer	Indicates whether to bring the Standard Input/Output window to the front each time you add a string or character. 1 = Yes 0 = No
showLineNumbers	integer	Indicates whether to show line numbers in the Standard Input/Output window. 1 = Yes 0 = No

Return Value

None.

Parameter Discussion

If you do not want to obtain any of these values, you can pass NULL.

GetStdioWindowPosition

void GetStdioWindowPosition (int *top, int *left);

Purpose

Gets the current position, in pixels, of the client area of the Standard Input/Output window relative to the upper left corner of the screen. The client area begins under the title bar and to the right of the frame.

Parameters

Output

Name	Туре	Description
top	integer	Current distance, in pixels, from the top of client area of the Standard Input/Output window to the top of the screen.
left	integer	Current distance, in pixels, from the left edge of the client area of the Standard Input/Output window to the left edge of the screen.

Return Value

GetStdioWindowSize

void GetStdioWindowSize (int *height, int *width);

Purpose

Gets the height and width, in pixels, of the client area of the Standard Input/Output window. The client area excludes the frame and the title bar.

Parameters

Output

Name	Туре	Description
height	integer	Current height, in pixels, of the client area of the Standard Input/Output window.
width	integer	Current width, in pixels, of the client area of the Standard Input/Output window.

Return Value

GetStdioWindowVisibility

```
void GetStdioWindowVisibility (int *visible);
```

Purpose

Indicates whether the Standard Input/Output window is currently visible. If the window is minimized into an icon, GetStdioWindowVisibility considers the window to be *not* visible. If the you cannot see the window merely because its position is off the screen, GetStdioWindowVisibility considers the window to be visible.

Parameters

Output

Name	Туре	Description
visible	integer	1 = Standard I/O window is visible
		0 = Standard I/O window is not visible

Return Value

GetSystemDate

int status = GetSystemDate (int *month, int *day, int *year);

Note Only the Windows versions of LabWindows/CVI support GetSystemDate.

Purpose

Obtains the system date in numeric format.

Parameters

Output

Name	Туре	Description
month	integer	Month; 1–12.
day	integer	Day of the month; 1–31.
year	integer	Year; under Windows 3.1, the year is limited to the values 1980–2099.

Return Value

Name	Туре	Description
status	integer	Success or failure.

Return Codes

Code	Description	
0	Success.	
-1	Operating system reported failure.	

GetSystemTime

int status = GetSystemTime(int *hours, int *minutes, int *seconds);

Note Only the Windows versions of LabWindows/CVI support GetSystemTime.

Purpose

Obtains the system time in numeric format.

Parameters

Output

Name	Туре	Description
hours	integer	Hours; 0–23.
minutes	integer	Minutes; 0–59.
seconds	integer	Seconds; 0–59.

Return Value

Name	Туре	Description
status	integer	Success or failure.

Return Codes

Code	Description
0	Success.
-1	Operating system reported failure.

GetWindowDisplaySetting

void GetWindowDisplaySetting (int *visible, int *zoomState);

Note Only the Windows versions of LabWindows/CVI support GetWindowDisplaySetting.

Purpose

Indicates how the user of your application wants the initial application window to display. The values GetWindowDisplaySetting returns reflect the display options the user sets for the program in Program Manager and other Windows shells.

Parameters

Output

Name	Туре	Description
visible	integer	0 = hide window 1 = display window
zoomState	integer	ATTR_NO_ZOOM = normal display ATTR_MINIMIZE ATTR_MAXIMIZE

Return Value

None.

Example

If you want to honor the user's display options, put the following code where you display your initial panel:

```
int showWindow, zoomState;
GetWindowDisplaySetting (&showWindow, &zoomState);
/* Load panel or create panel. */
if (showWindow){
    SetPanelAttribute (panel, ATTR_WINDOW_ZOOM, zoomState);
    SetPanelAttribute (panel, ATTR_VISIBLE, 1);
}
```

InitCVIRTE

int status = InitCVIRTE (void *hInstance, char *argv[], void *reserved);

Purpose

Performs initialization of the LabWindows/CVI Run-time Engine. You need InitCVIRTE only in executables or DLLs that you link using an external compiler. Otherwise, the function is harmless.

Parameters

Input

Name	Туре	Description
hInstance	void pointer	0 if called from main. hInstance if called from WinMain, first parameter. hInstDLL if called from DllMain, first parameter.
argv	string array	argv if called from main, second parameter. Otherwise, 0.
reserved	void pointer	Reserved for future use. Pass 0.

Return Value

Name	Туре	Description
status	integer	1 = success 0 = failure, probably out of memory

Using this Function

You should call InitCVIRTE in your main, WinMain, or DllMain function. Which of these three functions you use determines the parameter values you pass to InitCVIRTE. The following examples show how to use InitCVIRTE in each case:

```
int main (int argc, char *argv[])
{
   if (InitCVIRTE (0, argv, 0) == 0)
      return -1; /* out of memory */
   /* your other code */
   return 0;
}
int __stdcall WinMain (HINSTANCE hInstance, HINSTANCE hPrevInstance,
                         LPSTR lpszCmdLine, int nCmdShow)
{
   if (InitCVIRTE (hInstance, 0, 0) == 0)
      return -1; /* out of memory */
   /* your other code */
   return 0;
}
int __stdcall DllMain (void *hinstDLL, int fdwReason, void
                         *lpvReserved)
{
   if (fdwReason == DLL_PROCESS_ATTACH)
       {
      if (InitCVIRTE (hinstDLL, 0, 0) == 0)
          return 0; /* out of memory */
          /* your other ATTACH code */
   else if (fdwReason == DLL_PROCESS_DETACH)
      {
      /* your other DETACH code */
      CloseCVIRTE ();
      }
   return 1;
}
```

Note 🕞

The prototypes for InitCVIRTE and CloseCVIRTE are in cvirte.h, which is included by utility.h.

inp

```
char byteRead = inp (int portNumber);
```

Note Only the Windows versions of LabWindows/CVI support inp.

Purpose

Reads a byte from a port.

Image: NoteUnder Windows NT, inp requires the LabWindows/CVI low-level support driver.
LabWindows/CVI loads the driver at startup if it is on disk. You can check whether
LabWindows/CVI loaded the driver at startup by calling
CVILowLevelSupportDriverLoaded.

Parameter

Input

Name	Туре	Description
portNumber	integer	Port

Return Value

Name	Туре	Description
byteRead	char	Byte read from the port.

See Also

CVILowLevelSupportDriverLoaded

inpw

short wordRead = inpw (int portNumber);

Note Only the Windows versions of Lab Windows/CVI support inpw.

Purpose

Reads a word from a port.

Note Under Windows NT, inpw requires the LabWindows/CVI low-level support driver. LabWindows/CVI loads the driver at startup if it is on disk. You can check whether LabWindows/CVI loaded the driver at startup by calling CVILowLevelSupportDriverLoaded.

Parameter

Input

Name	Туре	Description
portNumber	integer	Port.

Return Value

Name	Туре	Description
wordRead	short	Word read from the port.

See Also

CVILowLevelSupportDriverLoaded

InStandaloneExecutable

int standalone = InStandaloneExecutable(void);

Purpose

Returns a nonzero value if your program is currently running as a standalone executable. If your program is currently running under the LabWindows/CVI development environment, InStandaloneExecutable returns zero.

Parameters

None.

Return Value

Name	Туре	Description
standalone	integer	 1 = program is currently running as a standalone executable 0 = program is currently running under LabWindows/CVI

KeyHit

int result = KeyHit (void);

Purpose

Indicates whether the user has pressed a key on the keyboard.

Note KeyHit detects keystrokes only in the Standard I/O window. It does not detect keystrokes in windows you create with the User Interface Library or in the console window in a Windows console application.

Parameters

None.

Return Value

Name	Туре	Description
result	integer	Indicates if a key has been pressed.

Return Codes

Code	Description	
0	Key has not been pressed.	
1	Key has been pressed.	

Using This Function

KeyHit returns 1 if a keystroke is available in the keyboard buffer; 0 otherwise. After a keystroke is available, you should make a call to GetKey to flush the keyboard buffer. Otherwise, KeyHit continues to return 1.

Note KeyHit always returns 0 if you are running under UNIX and have done one of the following:

- Selected Options»Environment»Use Host System's Standard Input/Output in the Project window
- **Called** SetStdioPort to set the port to HOST_SYSTEM_STDIO

Example

```
/* Flush any pending keystrokes. */
while (KeyHit())
    GetKey();
/* Perform loop indefinitely until the user presses key. */
while (!KeyHit()) {
}
```

LaunchExecutable

int result = LaunchExecutable (char fileName[]);

Purpose

Starts running a program and returns without waiting for it to exit. The program must be an actual executable; that is, you cannot launch commands intrinsic to a command interpreter.

Under Windows the executable can be either a DOS or Windows executable, including *.exe, *.com, *.bat, and *.pif files.

If you need to execute a command built into command.com such as copy, dir, and others, you can call LaunchExecutable with the command

command.com /C DosCommand args

where DosCommand is the shell command you want to execute. For example, the following command string copies file.tmp from the temp directory to the tmp directory:

command.com /C copy c:\\temp\\file.tmp c:\\tmp

 Note
 If you want to monitor whether the launched executable has terminated, use

 LaunchExecutableEx.

Parameter

Input

Name	Туре	Description
fileName	string	Pathname of executable file and arguments.

Return Value

Name	Туре	Description
result	integer	Result of the operation.

Return Codes under UNIX

Code	Description	
0	Command successfully started.	
-1	Launching the executable would exceed the operating system limit on the total number of processes under execution or the total number of processes per user.	
-2	Insufficient swap space for the new process.	
-3	vfork failed for unknown reason.	
-4	Search permission is denied for a directory listed in the path prefix of the new process image file, the new process image file denies execution permission, or the new process image file is not a regular file.	
-5	The length of the pathname or filename or an element of the environment variable PATH prefixed to a filename exceeds PATH_MAX, or a pathname component is longer than NAME_MAX while _POSIX_NO_TRUNC is in effect for that file. Refer to the man page for pathconf (2V).	
-6	One or more components of the pathname of the new process image file do not exist.	
-7	A component of the path prefix of the new process image file is not a directory.	
-8	Number of bytes that the new process-image-argument list and the environment list use is greater than ARG_MAX bytes. Refer to the man page for sysconf (2V).	
-9	New process image file has the appropriate access permission but is not in the proper format.	

Return Codes under Windows

Code	Description	
0	Command was successfully started.	
-1	System was out of memory, executable file was corrupt, or relocations were invalid.	
-3	File was not found.	
-4	Path was not found.	

Code	Description	
-6	Attempt was made to dynamically link to a task, or there was a sharing or network-protection error.	
-7	Library required separate data segments for each task.	
-9	There was insufficient memory to start the application.	
-11	Windows version was incorrect.	
-12	Executable file was invalid. Either it was not a Windows application or there was an error in the .exe image.	
-13	Application was designed for a different operating system.	
-14	Application was designed for MS-DOS 4.0.	
-15	Type of executable file was unknown.	
-16	You made an attempt to load a real-mode application developed for an earlier version of Windows.	
-17	You made an attempt to load a second instance of an executable file that contains multiple data segments that were not marked read only.	
-20	Attempt was made to load a compressed executable file. You must decompress the file before you can load it.	
-21	DLL file was invalid. One of the DLLs required to run this application was corrupt.	
-22	Application requires Windows 32-bit extensions.	

Parameter Discussion

fileName is the program to run.

If the program is not in one of the directories specified in the PATH environment variable, you must specify the full path. The path can include arguments to pass to the program.

Under Windows, if the program is a .pif, .bat, or .com file, you must include the extension in the pathname. For example, under Windows, the following command string launches the Edit program with the file file.dat:

c:\\dos\\edit.com c:\\file.dat

See Also

LaunchExecutableEx

LaunchExecutableEx

Purpose

Performs the same operation as LaunchExecutable with the following extended features:

- Under Windows, you can specify how the Windows application displays.
- LaunchExecutableEx returns a handle to the executable that can show whether the executable is still running and also can terminate the executable.

Parameters

Input

Name	Туре	Description
fileName	string	Pathname of executable file and arguments.
windowState	integer	Specifies how to show a Windows program. Ignored under UNIX.

Output

Name	Туре	Description
handle	integer	Handle that represents the executable launched.

Return Value

Name	Туре	Description
result	integer	Result of the operation.

Return Codes

Code	Description	
0	Success.	
(nonzero value)	Failure, refer to LaunchExecutable.	

Parameter Discussion

Table 8-4 shows valid values for **windowState**.

Table 8-4.	Valid	windowState	Values
------------	-------	-------------	--------

Value	Application window behavior	
LE_HIDE	hidden	
LE_SHOWNORMAL	shown normally and activated	
LE_SHOWMINIMIZED	displayed as an icon and activated	
LE_SHOWMAXIMIZED	displayed as a maximized window and activated	
LE_SHOWNA	shown normally but not activated	
LE_SHOWMINNOACTIVE	shown as an icon but not activated	

You can pass the handle you obtain from LaunchExecutableEx to ExecutableHasTerminated and TerminateExecutable. When you no longer need the handle, you must call RetireExecutableHandle. If you do not want to obtain a handle, you can pass NULL for the **handle** parameter.

When you launch several processes with LaunchExecutableEx but do not call RetireExecutableHandle on them, you might reach the limit for the maximum number of processes the system imposes. This happens even if the processes terminate; the program does not recognize that the processes have terminated until you call RetireExecutableHandle.

Checking Termination of LabWindows/CVI Executables under Windows 3.1

If you launch another LabWindows/CVI executable under Windows 3.1, the launched executable process terminates itself after launching a copy of the LabWindows/CVI Run-time Engine. ExecutableHasTerminated then always returns 1 because it cannot track the process identification for the second run-time engine. This behavior can also occur with non-LabWindows/CVI executables.

You can work around this problem when launching LabWindows/CVI runtime executables by executing the run-time engine directly and passing it the pathname of the executable, as shown in the following example:

c:\cvi\cvirt5.exe c:\test\myapp.exe

The pathname of the run-time engine might not be c:\cvi\cvirt5.exe. You can determine the pathname of the run-time engine by looking at the cvirt5 section in win.ini. If the run-time executable was made with a different version of CVI, look in the cvirtnn section for that version.

If you need to pass arguments to your application, create a file that contains the arguments and pass the pathname of that file as the second argument to the run-time engine, as shown in the following example:

c:\cvi\cvirt5.exe c:\test\myapp.exe myargs

The file that contains the arguments must be in the same directory as the executable. The first three characters in the file that contains the arguments must be "CVI" in uppercase, as in the following example:

CVI arg1 arg2 arg3

The run-time engine deletes the file that contains the arguments after reading it.

See Also

ExecutableHasTerminated, TerminateExecutable, RetireExecutableHandle

LoadExternalModule

int module_id = LoadExternalModule (char pathName[]);

Purpose

Loads a file that contains one or more object modules.

Parameter

Input

Name	Туре	Description
pathName	string	Relative or absolute pathname of the module to load.

Return Value

Name	Туре	Description
module_id	integer	ID of the loaded module.

Return Codes

Code	Description
-1	Out of memory.
-2	File not found.
-4	Invalid file format.
-6	Invalid pathname.
-7	Unknown file extension.
-8	Cannot open file.
-11	.pth file open error.
-12	.pth file read error.
-13	.pth file invalid contents.
-14	DLL header file contains a static function prototype.
-15	DLL function has an unsupported argument type.
-16	DLL has a variable argument function.
-17	DLL header contains a function without a proper prototype.

Code	Description
-18	DLL function has an unsupported return type.
-19	DLL function argument or return type is a function pointer.
-20	Function in the DLL header file was not found in the DLL.
-21	Could not load the DLL.
-22	Could not find the DLL header file.
-23	Could not load the DLL header file; out of memory or the file is corrupted.
-24	Syntax error in the DLL header file.
-25	DLL initialization function failed.
-26	Module already loaded with different calling module handle. Refer to LoadExternalModuleEx.
-27	Invalid calling module handle. Refer to LoadExternalModuleEx.
-28	Module you loaded in Borland mode within the LabWindows/CVI development environment contains uninitialized global variables that are also defined in other modules.

Parameter Discussion

LoadExternalModule loads an external object module file. You do not need to list the file in your project or load it as an instrument module.

Under Windows 3.1, the file can be an object file (.obj), a library file (.lib), or a dynamic link library (.dll). You must compile object and library modules with the Watcom C compiler for Windows or with the LabWindows/CVI compiler.

Under Windows 95/NT, the file can be an object file (.obj), a library file (.lib), or a DLL import library (.lib). You cannot load a DLL directly. You can compile object and library modules with LabWindows/CVI or with an external compiler.

Under UNIX, the file can be an object file $(.\circ)$ or a statically linked library (.a).

All files must conform to the rules for loadable compiled modules in the *LabWindows/CVI Programmer Reference Manual*.

By loading external object modules, you can execute code that is not in your project and not in a loaded instrument module. You can load the external modules only when you need them and unload them when you no longer need them.

After you load a module, you can execute its code in one of two ways:

- You can obtain pointers to functions in the module by calling GetExternalModuleAddr. Then, you can call the module functions through the function pointers.
- You can call RunExternalModule. This requires that the module contain a function with a pre-defined name and prototype. The function serves as the entry point to the module. Refer to RunExternalModule for more information.

You can use LoadExternalModule on a source file (.c) that is part of the current project or on a source file that you load as the program for an instrument module. This allows you to develop your module in source code form and test it using the LabWindows/CVI debugging capabilities. After you finish testing your module and compile it into an external object or library file, you must change the pathname in the call to LoadExternalModule in your application source code. You do not have to make any other modifications to load the module.

Avoid calling LoadExternalModule on a file in the project when you plan to link your program in an external compiler. The LabWindows/CVI Utility Library does not know the locations of symbols in executables or DLLs linked in external compilers. You can provide this information by using the Other Symbols section of the **External Compiler Support** dialog box in the **Build** menu of the LabWindows/CVI Project window to create an object module that contains a table of symbols you want to find using GetExternalModuleAddr. If you use this method, you should pass the empty string "" to LoadExternalModule for the module pathname.

If successful, LoadExternalModule returns an integer module ID that you can later pass to RunExternalModule, GetExternalModuleAddr, and UnloadExternalModule. If unsuccessful, LoadExternalModule returns a negative error code.

Resolving External References from Object and Static Library Files on Windows 95/NT

An important difference exists between loading an object or static library module and loading a DLL through an import library. DLLs are prelinked; that is, when you load a DLL, the loader does not need to resolve any external references. Object and static library modules, on the other hand, have unresolved external references. LoadExternalModule resolves them using symbols defined in the project or exported by object, static library, or import library modules that you have already loaded using LoadExternalModule. This is true even when you call LoadExternalModule in a DLL. LoadExternalModule does not use symbols in a DLL to resolve external references unless the DLL exports those symbols.

When you load an object or library module from a DLL, you might want to resolve external references in the object or library module through global symbols the DLL does not export. If you want to do this, you must call LoadExternalModuleEx rather than LoadExternalModule.

Using This Function

pathname can be a relative or absolute pathname. If it is a simple filename, such as module.obj, LoadExternalModule takes the following steps to find the file:

- 1. It first looks for the file in the project list.
- 2. It then looks for the file in the directory that contains the currently loaded project.
- 3. Under Windows 3.1, if the file is not found and its extension is .dll, LoadExternalModule searches for the file in the directories Windows searches to find DLLs.

If it is a relative pathname with one or more directory paths (such as dir\module.obj), LoadExternalModule creates an absolute pathname by appending the relative pathname to the directory that contains the currently loaded project.

If the **pathname** is for a DLL import library, LoadExternalModule finds the DLL using the DLL name embedded in the import library and the standard Windows DLL search algorithm.

See Also

LoadExternalModuleEx,GetExternalModuleAddr,RunExternalModule,UnloadExternalModule,ReleaseExternalModule

Example

```
void (*funcPtr) (char buf[], double dval, int *ival);
int module_id;
int status;
char buf[100];
double dval;
int ival;
char *pathname;
char *funcname;
pathname = "EXTMOD.OBJ";
funcname = "my_function";
module_id = LoadExternalModule (pathname);
if (module_id < 0)</pre>
   FmtOut ("Unable to load %s\n", pathname);
else {
       funcPtr = GetExternalModuleAddr (module_id, funcname, &status);
       if (funcPtr == NULL)
          FmtOut ("Could not get address of %s\n", funcname);
       else
          (*funcPtr) (buf, dval, &ival);
}
```

LoadExternalModuleEx

Purpose

Loads a file that contains one or more object modules. It is similar to LoadExternalModule except that under Windows 95/NT, you can resolve external references in object and library modules you load in a DLL by using symbols the DLL does not export. On platforms other than Windows 95/NT, LoadExternalModuleEx works exactly like LoadExternalModule.

Parameters

Input

Name	Туре	Description
pathName	string	Relative or absolute pathname of the module to load.
callingModuleHandle	void pointer	Usually, the module handle of the calling DLL. You can use CVIUserHInst. Zero indicates the project or executable.

Return Value

Name	Туре	Description
moduleId	integer	ID of the loaded module.

Return Codes

Same as the return codes for LoadExternalModule.

Using this Function

Refer to the function help for LoadExternalModule for more information on this function.

If you call LoadExternalModule on an object or library module, LoadExternalModule resolves external references using symbols defined in the project or exported by object, library, or DLL import library modules that you have already loaded using LoadExternalModuleEx or LoadExternalModule. This is true even if you call LoadExternalModule in a DLL.

You might want to load an object or library module in a DLL and have the module link back to symbols that you defined in, but did not export from, the DLL. You can do this using LoadExternalModuleEx. You must specify the module handle of the DLL as **callingModuleHandle**. You can do so by using the LabWindows/CVI pre-defined variable ___CVIUserHInst.

LoadExternalModuleEx first searches the global DLL symbols to resolve external references. LoadExternalModuleEx resolves any remaining unresolved references by searching the symbols defined in the project or exported by object, library, or import library modules that you have already loaded using LoadExternalModule or LoadExternalModuleEx.

LoadExternalModuleEx expects the DLL to contain a table of symbols to use to resolve references. If you create the DLL in LabWindows/CVI, the table is included automatically. If you create the DLL using an external compiler, you must arrange for the table to be included in the DLL. You can do this by creating an include file that includes all the symbols that the table must contain. You can then use the **External Compiler Support** command in the **Build** menu of the Project window to create an object file that contains the table. You must include the object file in the external compiler project you use to create the DLL.

LoadExternalModuleEx acts identically to LoadExternalModule in the following cases:

- You pass zero for callingModuleHandle.
- You pass <u>CVIUserHInst</u> for callingModuleHandle, but you call the function from a file that is in the project or your executable, rather than in a DLL.
- You are not running under Windows 95/NT.

You cannot load the same external module using two different calling module handles. The function reports an error if you attempt to load an external module when you have already loaded it under a different module handle.

MakeDir

```
int result = MakeDir (char directoryName[]);
```

Purpose

Creates a new directory with the name you specify.

Note You can create only one directory at a time.

Parameter

Input

Name	Туре	Description
directoryName	string	New directory name.

Return Value

Name	Туре	Description
result	integer	Result of the operation.

Return Codes

Code	Description
0	Success.
-1	One of the path components not found.
-3	General I/O error occurred.
-4	Insufficient memory to complete the operation.
-5	Invalid path; for example, c:filename in Windows.
-6	Access denied.
-8	Disk is full.
-9	Directory or file already exists with same pathname.

Example

```
/* Make a new directory named \DATA\WAVEFORM on drive C */
/* assuming that C:\DATA does not exist */
MakeDir ("C:\\DATA");
MakeDir ("C:\\DATA\\WAVEFORM");
```

MakePathname

void MakePathname (char directoryName[], char fileName[], char pathName[]);

Purpose

Constructs a pathname from a directory path and a filename. The subroutine ensures that a backslash separates the directory path and the filename.

Parameters

Input

Name	Туре	Description
directoryName	string	Directory path.
fileName	string	Base filename and extension.

Output

Name	Туре	Description
pathName	string	Pathname

Return Value

None.

Parameter Discussion

pathName must be at least MAX_PATHNAME_LEN bytes long. If MakePathname constructs a pathname that exceeds that size, it fills in **pathName** with an empty string instead.

Example

```
char dirname[MAX_PATHNAME_LEN];
char pathname[MAX_PATHNAME_LEN];
GetProjectDir (dirname);
MakePathname (dirname, "FILE.DAT", pathname);
```

MapPhysicalMemory

 Note
 Only the Windows 95/NT versions of LabWindows/CVI support

 MapPhysicalMemory.

Purpose

Maps a physical address to a pointer that you can use in your program like any other C pointer. For example, you can read or write an area of physical memory by incrementing the pointer after each access.

In cases where you cannot transfer all your data at once, MapPhysicalMemory provides better performance than ReadPhysicalMemory or WritePhysicalMemory. There is a significant performance penalty to mapping and unmapping physical memory. If you call ReadPhysicalMemory or WritePhysicalMemory on each access, you are mapping and unmapping the memory each time.

When you no longer need the pointer, call UnMapPhysicalMemory on the handle **mapHandle** returns.

Under Windows 95/NT, MapPhysicalMemory requires the LabWindows/CVI low-level support driver. LabWindows/CVI loads the driver at startup if it is on disk. You can check whether LabWindows/CVI loaded the driver at startup by calling CVILowLevelSupportDriverLoaded.

Parameters

Input

Name	Туре	Description
physAddress	unsigned integer	Physical address to map into user memory.
numBytes	unsigned integer	Number of bytes of physical memory to map.

Output

Name	Туре	Description
ptrToMappedAddr	any type of pointer	Contains the mapped physical address. Pass a pointer by reference as this parameter.
mapHandle	integer	Contains the handle that you pass to the UnMapPhysicalMemory function to unmap the physical memory.

Return Value

Name	Туре	Description
status	integer	Indicates whether the function succeeded.

Return Codes

Code	Description		
1	Success.		
0	numBytes is 0, memory allocation failed, the operating system reported an error, or the low-level support driver is not loaded.		

Parameter Discussion

No restrictions exist on the value of **physAddress**. It can be below or above 1 MB.

Note MapPhysicalMemory *does not check the validity of the physical address.*

Example

```
else
{
  for (i=0; i < numBytes/sizeof(int); i++)
     {
     /* <determine data to write> */
     *physMemPtr++ = data;
     }
  UnMapPhysicalMemory (mapHandle);
  }
```

See Also

UnMapPhysicalMemory, CVILowLevelSupportDriverLoaded

outp

char byteWritten = outp(int portNumber, char byteToWrite);

Note Only the Windows versions of Lab Windows/CVI support outp.

Purpose

Writes a byte to a port.

NoteUnder Windows NT, outp requires the LabWindows/CVI low-level support driver.
LabWindows/CVI loads the driver at startup if it is on disk. You can check whether
LabWindows/CVI loaded the driver at startup by calling
CVILowLevelSupportDriverLoaded.

Parameters

Input

Name	Туре	Description
portNumber	integer	Port.
byteToWrite	char	Byte to write.

Return Value

Name	Туре	Description
byteWritten char		Byte that you wrote.

See Also

CVILowLevelSupportDriverLoaded

outpw

short wordWritten = outpw (short portNumber, int wordToWrite);

Note Only the Windows versions of Lab Windows/CVI support outpw.

Purpose

Writes a word to a port.

Note Under Windows NT, outpw requires the LabWindows/CVI low-level support driver. LabWindows/CVI loads the driver at startup if it is on disk. You can check whether LabWindows/CVI loaded the driver at startup by calling CVILowLevelSupportDriverLoaded.

Parameters

Input

Name	Туре	Description
portNumber	integer	Port.
wordToWrite	short	Word to write.

Return Value

Name	Туре	Description			
wordWritten	short	Word that you wrote.			

See Also

CVILowLevelSupportDriverLoaded

ReadFromPhysicalMemory

Note Only the Windows versions of LabWindows/CVI support ReadFromPhysicalMemory.

Purpose

Copies the contents of a region of physical memory into **destinationBuffer**. ReadFromPhysicalMemory does not check whether the memory actually exists. If the memory does not exist, ReadFromPhysicalMemory returns the success value but does not read data.

Under Windows 95/NT, ReadFromPhysicalMemory requires the LabWindows/CVI low-level support driver. LabWindows/CVI loads the driver at startup if it is on disk. You can check whether LabWindows/CVI loaded the driver at startup by calling CVILowLevelSupportDriverLoaded.

Parameters

Note

Input

Name	Туре	Description
physicalAddress	unsigned integer	Physical address to read from. No restrictions exists on the address; it can be below or above 1 MB.
destinationBuffer	void pointer	Buffer into which to copy the physical memory.
numberOfBytes	unsigned integer	Number of bytes to copy from physical memory.

Return Value

Name	Туре	Description
status	integer	Indicates whether the function succeeded.

Return Codes

Code	Description		
1	Success.		
0	Operating system reported failure, or low-level support driver not loaded.		

See Also

ReadFromPhysicalMemoryEx, MapPhysicalMemory, CVILowLevelSupportDriverLoaded

ReadFromPhysicalMemoryEx

int	status	=	ReadFromPhysicalMemory	Ex (unsigned	int	physic	alAddress,	
			void *des	stina	ationBuff	er,			
			unsigned	int	numberOf	Byte	es, int	bytesAtAT	ime);

Note Only the Windows versions of LabWindows/CVI support ReadFromPhysicalMemoryEx.

Purpose

Copies the contents of a region of physical memory into the buffer you specify. It can copy the data in units of 1, 2, or 4 bytes at a time. ReadFromPhysicalMemoryEx does not check whether the memory actually exists. If the memory does not exist, ReadFromPhysicalMemoryEx returns the success value but does not read data.

C Note

Under Windows 95/NT, ReadFromPhysicalMemoryEx requires the LabWindows/CVI low-level support driver. LabWindows/CVI loads the driver at startup if it is on disk. You can check whether LabWindows/CVI loaded the driver at startup by calling CVILowLevelSupportDriverLoaded.

Parameters

Input

Name	Туре	Description
physicalAddress	unsigned integer	Physical address to read from. No restrictions exist on the address; it can be above or below 1 MB.
destinationBuffer	void pointer	Buffer into which to copy the physical memory.
numberOfBytes	unsigned integer	Number of bytes to copy from physical memory.
bytesAtATime	integer	Unit size in which to copy the data; Can be 1, 2, or 4 bytes.

Return Value

Name	Туре	Description
status	integer	Indicates whether the function succeeded.

Return Codes

Code	Description
1	Success.
0	Operating system reported failure, low-level support driver not loaded, numberOfBytes is not a multiple of bytesAtATime , or invalid value for bytesAtATime .

Parameter Discussion

numberOfBytes must be a multiple of bytesAtATime.

See Also

MapPhysicalMemory, CVILowLevelSupportDriverLoaded

ReleaseExternalModule

int status = ReleaseExternalModule (int moduleID);

Purpose

Decreases the reference count for a module you load using LoadExternalModule or LoadExternalModuleEx.

When you call LoadExternalModule successfully on a module, the module reference count increments by one. When you call ReleaseExternalModule, the module reference count decrements by one.

If the reference count decreases to zero, the module ID is invalidated and you cannot access the module through GetExternalModuleAddr or RunExternalModule. If, in addition, the module file is not in the project and not loaded as an instrument, ReleaseExternalModule removes the external module from memory.

If you want to unload the module regardless of the reference count, call UnloadExternalModule rather than ReleaseExternalModule. Use ReleaseExternalModule when multiple calls might have been made to LoadExternalModule on the same module and you do not want to unload the module in case other parts of the application still use it.

Parameter

Input

Name	Туре	Description
moduleID	integer	Module ID you obtain from
		LoadExternalModule or
		LoadExternalModuleEx.

Return Value

Name	Туре	Description
status	integer	Indicates the result of the operation.

Return Codes

Code	Description
> 0	Success, but the module was not unloaded. The value indicates the number of remaining references.
0	Success, and the module was unloaded.
-5	Module cannot be unloaded because another external module that is currently loaded references it.
-9	Invalid module ID.

RenameFile

int result = RenameFile (char existingFileName[], char newFileName[]);

Purpose

Renames an existing file.

Parameters

Input

Name	Туре	Description
existingFileName	string	Existing filename.
newFileName	string	New filename.

Return Value

Name	Туре	Description
result	integer	Result of rename operation.

Return Codes

Code	Description
0	Success.
-1	File not found or directory in path not found.
-3	General I/O error occurred.
-4	Insufficient memory to complete the operation.
-5	Invalid path, for either of the filenames.
-6	Access denied.
-7	Specified existing path is a directory, not a file.
-8	Disk is full.
-9	New file already exists.

Parameter Discussion

existingFileName and newFileName can contain DOS wildcard characters '?' and '*'. If existingFileName has wildcards, RenameFile renames all matching files. If newFileName has wildcards, RenameFile matches it to existingFileName.

existingFileName can be the empty string "", in which case RenameFile renames the file that the most recent call to GetFirstFile or GetNextFile found.

Under Windows, if the arguments to RenameFile specify files on different disk drives, RenameFile copies the source to the target and then deletes the source file.

Under UNIX, if the arguments to RenameFile specify files on different file systems, RenameFile copies the source to the target and then deletes the source file.

RetireExecutableHandle

int status = RetireExecutableHandle (int executableHandle);

Purpose

Informs the LabWindows/CVI Utility Library that you no longer intend to use the handle you acquired from LaunchExecutableEx. When you call RetireExecutableHandle, the LabWindows/CVI Utility Library can reuse the memory allocated to keep track of the state of the executable.

When you launch several processes with LaunchExecutableEx but do not call RetireExecutableHandle on them, you might reach the limit for the maximum number of processes the system imposes. This happens even if the processes terminate; the program does not recognize that the processes have terminated until you call RetireExecutableHandle.

Parameter

Input

Name	Туре	Description
executableHandle	integer	Executable handle you obtain from
		LaunchExecutableEx. -1 = handle is invalid 0 = success

Return Value

Name	Туре	Description
status	integer	Result of the operation.

RoundRealToNearestInteger

long n = RoundRealToNearestInteger (double inputRealNumber);

Purpose

Rounds its floating-point argument and returns the result as a long integer. A value with a fractional part of exactly 0.5 is rounded to the nearest even number.

Parameter

Input

Name	Туре	Description
inputRealNumber	double-precision	Real number to round.

Return Value

Name	Туре	Description
n	long	Result of the rounding operation.

Example

```
long n;
n = round (1.2); /* result: 1L */
n = round (1.8); /* result: 2L */
n = round (1.5); /* result: 2L */
n = round (0.5); /* result: 0L */
n = round (-1.2); /* result: -1L */
n = round (-1.8); /* result: -2L */
n = round (-1.5); /* result: -2L */
n = round (-0.5); /* result: 0L */
```

RunExternalModule

int result = RunExternalModule (int moduleID, char *buffer);

Purpose

Calls the pre-defined entry point function in an external module. Refer to LoadExternalModule.

Parameters

Input

Name	Туре	Description
moduleID	integer	ID of loaded module.
buffer	string	Parameter buffer.

Return Value

Name	Туре	Description
result	integer	Indicates the result of the operation.

Return Codes

Code	Description
0	Success.
-1	Out of memory.
-3	Entry point is undefined.
-4	Invalid file format.
-5	Undefined references.
-8	Cannot open file.
-9	Invalid module ID.

Parameter Discussion

moduleID is the value LoadExternalModule returns. **buffer** is a character array in which you can pass information to and from the module.

RunExternalModule requires that the module define the following function:

```
void _xxx_entry_point (char [])
```

where xxx is the base name of the file, in lowercase. For example, if the pathname of the file is C:\LW\PROGRAMS\TEST01.OBJ,

the name of the entry point must be

```
_test01_entry_point.
```

Example

```
int module_id;
int status;
char *pathname;
pathname = "EXTMOD.OBJ";
module_id = LoadExternalModule (pathname);
if (module_id <0)
    FmtOut ("Unable to load %s\n", pathname);
else {
    RunExternalModule (module_id, "");
    UnloadExternalModule (module_id);
}
```

SetBreakOnLibraryErrors

int oldState = SetBreakOnLibraryErrors (int newState);

Purpose

When you enable debugging and a National Instruments library function reports an error, LabWindows/CVI can display a runtime error dialog box and suspend execution. You can use SetBreakOnLibraryErrors to enable or disable this feature.

In general, it is best to use the Break on Library Errors checkbox in the **Run Options** command of the Project window to enable or disable this feature. You should use this function only when you want to temporarily disable the Break on Library Errors feature around a segment of code.

SetBreakOnLibraryErrors does not affect the state of the Break on Library Errors checkbox in the **Run Options** command of the Project window.

If you disable debugging, SetBreakOnLibraryErrors has no effect. LabWindows/CVI never reports run-time errors when you disable debugging.

Parameter

Input

Name	Туре	Description
newState	integer	Pass a nonzero value to enable. Pass zero to disable.

Return Value

Name	Туре	Description
oldState	integer	Previous state of the Break on Library Errors feature.

Code	Description
1	Previously enabled.
0	Previously disabled, or debugging is disabled.

Example

```
int oldValue;
oldValue = SetBreakOnLibraryErrors (0);
/* Function calls that may legitimately return errors. */
SetBreakOnLibraryErrors (oldValue);
```

See Also

GetBreakOnLibraryErrors

SetBreakOnProtectionErrors

int oldState = SetBreakOnProtectionErrors (int newState);

Purpose

If you enable debugging, LabWindows/CVI uses information it gathers from compiling your source code to make extensive run-time checks to protect your program. When it encounters a protection error at run-time, LabWindows/CVI displays a dialog box and suspends execution.

Examples of protection errors include:

- Dereferencing an invalid pointer value in source code.
- Attempting, in source code, to read or write beyond the end of an array.
- Making a function call, in source code, in which an array is smaller than the function expects.
- Performing pointer arithmetic in source code which generates an invalid address.

You can use SetBreakOnProtectionErrors to prevent LabWindows/CVI from displaying the dialog box and suspending execution when it encounters a protection error. In general, it is better not to disable the Break on Protection Errors feature. Nevertheless, you might want to disable it temporarily around a line of code for which LabWindows/CVI erroneously reports a protection error.

If you disable debugging, SetBreakOnProtectionErrors has no effect. LabWindows/CVI never reports run-time errors when you disable debugging.

Note If an invalid memory access generates a processor exception, LabWindows/CVI reports the error and terminates your program regardless of the debugging level or the state of the Break on Protection Errors feature.

Parameter

Input

Name	Туре	Description
newState	integer	Pass a nonzero value to enable. Pass zero to disable.

Return Value

Name	Туре	Description
oldState	integer	Previous state of the Break on Protection Errors feature.

Return Codes

Code	Description	
1	Previously enabled.	
0	Previously disabled, or debugging is disabled.	

Example

int oldValue; oldValue = SetBreakOnProtectionErrors (0); /* Statement that erroneously reports an error */ SetBreakOnProtectionErrors (oldValue);

See Also

GetBreakOnProtectionErrors

SetDir

int result = SetDir (char directoryName[]);

Purpose

Sets the current working directory to the directory you specify. Under Windows 3.1, SetDir can change the current working directory on any drive; however, it does not change the default drive. To change the default drive, use SetDrive.

Parameter

Input

Name	Туре	Description
directoryName	string	New current working directory.

Return Value

Name	Туре	Description
result	integer	Result of the operation.

Return Codes

Code	Description	
0	Success.	
-1	Specified directory not found or out of memory.	

Parameter Discussion

Under Windows 3.1, directoryName must not contain a drive letter.

SetDrive

```
int result = SetDrive (int driveNumber);
```

Note Only the Windows versions of Lab Windows/CVI support SetDrive.

Purpose

Sets the current default drive.

Parameter

Input

Name	Туре	Description
driveNumber	integer	New drive number; 0–25.

Return Value

Name	Туре	Description
result	integer	Result of the operation.

Return Codes

Code	Description	
0	Success.	
-1	Invalid drive number.	

Using This Function

The mapping between the drive number and the logical drive letter is 0 = A, 1 = B, and so on.

SetFileAttrs

Note Only the Windows versions of Lab Windows/CVI support SetFileAttrs.

Purpose

Sets the read-only, system, hidden and archive attributes of a file.

The **read-only** attribute protects a file from being overwritten and prevents the creation of a file with the same name.

The **system** attribute and **hidden** attribute both prevent the file from appearing in a directory list and exclude it from normal searches.

The operating system sets the **archive** attribute whenever you modify the file. The DOS backup command clears it.

Parameters

Input

Name	Туре	Description
fileName	string	File to set the attributes of.
read-only	integer	Read-only attribute.
system	integer	System attribute.
hidden	integer	Hidden attribute.
archive	integer	Archive attribute.

Return Value

Name	Туре	Description
result	return value	Result of the operation.

Code	Description	
0	Success.	
-1	File not found, or attribute cannot be changed.	

Parameter Discussion

Each attribute parameter can have one of the following values:

- 0 = clears the attribute
- 1 = sets the attribute
- -1 = leaves the attribute unchanged

fileName can be the empty string "", in which case SetFileAttrs sets the attributes of the file that the most recent call to GetFirstFile or GetNextFile found.

SetFileDate

int status = SetFileDate (char fileName[], int month, int day, int year);

Purpose

Sets the date of a file.

Parameters

Input

Name	Туре	Description
fileName	string	File to set the attributes of.
month	integer	Month; 1–12
day	integer	Day of month, 1–31
year	integer	Year; 1980–2099

Return Value

Name	Туре	Description
status	integer	Result of the operation.

Return Codes

Code	Description	
0	Success.	
-1	File not found or directory in path not found.	
-3	General I/O error occurred.	
-4	Insufficient memory to complete the operation.	
-5	Invalid date or invalid path; for example, c:filename in Windows.	
-6	Access denied.	

Parameter Discussion

fileName can be the empty string "", in which case SetFileAttrs sets the date of the file that the most recent call to GetFirstFile or GetNextFile found.

SetFileTime

Purpose

Sets the time of a file.

Parameters

Input

Name	Туре	Description
fileName	string	File to set the time of.
hours	integer	Hours; 0–23
minutes	integer	Minutes; 0–59
seconds	integer	Seconds; 0–58, odd values are rounded down.

Return Value

Name	Туре	Description
result	integer	Result of operation.

Code	Description
0	Success.
-1	File not found or directory in path not found.
-3	General I/O error occurred.
-4	Insufficient memory to complete the operation.
-5	Invalid time, or invalid path; for example, c:filename in Windows.
-6	Access denied.

Parameter Discussion

fileName can be the empty string "", in which case SetFileTime sets the time of the file that the most recent call to GetFirstFile or GetNextFile found.

If you enter an odd number for the **seconds** parameter, the operating system rounds the value down to an even number.

SetPersistentVariable

void SetPersistentVariable (int value);

Purpose

Lets you store an integer value across multiple builds and executions of your project in the LabWindows/CVI development environment. When you unload a project or load a new project, SetPersistentVariable resets the value to zero.

SetPersistentVariable is useful when your program performs an action, such as setting up your instruments, that takes a long time and that you do not want to repeat each time you run your program. LabWindows/CVI initializes global variables in your program each time you run your project. Therefore, you cannot use them to indicate that you have already taken the action once.

To get around this problem, LabWindows/CVI maintains an integer variable across multiple builds and executions of your project. SetPersistentVariable sets the value of that variable. To retrieve the variable value, call GetPersistentVariable().

Parameter

Input

Name	Туре	Description
value	integer	Value to assign to the persistent variable.

Return Value

None.

SetStdioPort

int status = SetStdioPort (int stdioPort);

Note Only the UNIX versions of LabWindows/CVI support SetStdioPort.

Purpose

Sets the current destination for data written to the Standard Output and the source of data read from Standard Input.

You can specify either the LabWindows/CVI Standard Input/Output window or the Standard Input/Output of the host system.

Parameter

Input

Name	Туре	Description
stdioPort	integer	CVI_STDIO_WINDOW (0) = LabWindows/CVI Standard Input/Output window HOST_SYSTEM_STDIO (1) = host system's Standard Input/Output

Return Value

Name	Туре	Description
status	integer	Indicates whether the function succeeded.

Code	Description	
0	Success.	
-2	Destination was not a valid range.	

Parameter Discussion

In a standalone executable, the default value for **stdioPort** is CVI_STDIO_WINDOW.

In the LabWindows/CVI development system, the default value for **stdioPort** is the current state of the Use Host System's Standard Input/Output option in the Environment dialog box of the Project window. The value you set using SetStdioPort is reflected the next time you open the Environment dialog box.

SetStdioWindowOptions

Purpose

Sets the current value of the following Standard Input/Output window options:

- Maximum number of lines
- Bring to front when modified
- Show line numbers

Parameters

Input

Name	Туре	Description
maxNumLines	integer	Maximum number of lines you can store in the Standard Input/Output window. If this amount is exceeded, lines are discarded from the top. Valid range = 100 to 1,000,000
bringToFrontWhenModified	integer	Indicates whether to bring the Standard Input/Output window to the front each time you add a string or character to it. 1 = Yes 0 = No
showLineNumbers	integer	Indicates whether to show line numbers in the Standard Input/Output window. 1 = Yes 0 = No

Return Value

Name	Туре	Description
status	integer	Indicates whether the function succeeded.

Return Codes

Code	Description
0	Success.
-1	Maximum number of lines is not within the valid range.

Parameter Discussion

In an executable, the default value of **maxNumLines** is 10,000. In the LabWindows/CVI development system, the default value is the value of the Maximum Number of Lines in Standard Input/Output Window control in the Environment dialog box of the Project window. The value you set using SetStdioWindowOptions is reflected the next time you bring up the Environment dialog box.

In an executable, the default value of **bringToFrontWhenModified** is 1. In the LabWindows/CVI development system, the default value is the state of the Bring Standard Input/Output Window to Front When Modified checkbox in the Environment dialog box of the Project window. The value you set using SetStdioWindowOptions is reflected the next time you bring up the Environment dialog box.

In an executable, the default value of **showLineNumbers** is 0. In the LabWindows/CVI development system, the default value is the current state you set by selecting **View»Line Numbers** in the Standard Input/Output Window. The value you set using SetStdioWindowOptions is reflected the next time you bring up the **View** menu.

SetStdioWindowPosition

int status = SetStdioWindowPosition (int top, int left);

Purpose

Sets the current position, in pixels, of the client area of the Standard Input/Output window relative to the upper left corner of the screen. The client area begins under the title bar and to the right of the frame.

Parameters

Input

Name	Туре	Description
top	integer	Distance, in pixels, of the top of client area of the Standard Input/Output window relative to the top of the screen. Valid range = VAL_AUTO_CENTER;
		-16,000 to +16,000
left	integer	Distance, in pixels, of the left edge of client area of the Standard Input/Output window relative to the left edge of the screen.
		Valid range = VAL_AUTO_CENTER; -16,000 to +16,000

Return Value

Name	Туре	Description
status	integer	Indicates whether the function succeeded.

Code	Description
0	Success.
-1	top is not within the valid range.
-2	left is not within the valid range.

Parameter Discussion

To vertically center the Standard Input/Output window client area within the area of the screen, pass VAL_AUTO_CENTER as the **top** parameter.

To horizontally center the Standard Input/Output window client area within the area of the screen, pass VAL_AUTO_CENTER as the **left** parameter.

SetStdioWindowSize

int status = SetStdioWindowSize (int height, int width);

Purpose

Sets the height and width, in pixels, of the client area of the Standard Input/Output window. The client area excludes the frame and the title bar.

Parameters

Input

Name	Туре	Description
height	integer	Height, in pixels, of the client area of the Standard Input/Output window. Valid range = 0 to 16,000
width	integer	Width, in pixels, of the client area of the Standard Input/Output window. Valid range = 0 to 16,000

Return Value

Name	Туре	Description
status	integer	Indicates whether the function succeeded.

Code	Description
0	Success.
-1	height is not within the valid range.
-2	width is not within the valid range.
-3	You must call this function from the main thread of your program.

SetStdioWindowVisibility

```
void SetStdioWindowVisibility (int visible);
```

Purpose

Brings to the front or hides the Standard Input/Output window.

Parameter

Input

Name	Туре	Description
visible	integer	1 = bring to front 0 = hide

Return Value

None.

SetSystemDate

int status = SetSystemDate (int month, int day, int year);

Note Only the Windows versions of Lab Windows/CVI support SetSystemDate. Under Windows NT, you must have system administrator status to use this function.

Purpose

Sets the system date.

Parameters

Input

Name	Туре	Description
month	integer	Month; 1–12.
day	integer	Day of month; 1–31.
year	integer	Year; under Windows 3.1, the year is limited to the values 1980–2099.

Return Value

Name	Туре	Description
status	integer	Success or failure.

Code	Description
0	Success.
-1	Operating system reported failure, probably because of an invalid parameter.

SetSystemTime

int status = SetSystemTime(int hours, int minutes, int seconds);

Note Only the Windows versions of Lab Windows/CVI support SetSystemTime. Under Windows NT, you must have system administrator status to use this function.

Purpose

Sets the system time.

Parameters

Input

Name	Туре	Description
hours	integer	Hours; 0–23.
minutes	integer	Minutes; 0–59.
seconds	integer	Seconds; 0–58. Odd values are rounded down.

Return Value

Name	Туре	Description
status	integer	Success or failure.

Code	Description
0	Success.
-1	Operating system reported failure, probably because of an invalid parameter.

SplitPath

Purpose

Splits a pathname into the drive name, the directory name, and the filename.

Parameters

Input

Name	Туре	Description
pathName	string	Pathname to split.

Output

Name	Туре	Description
driveName	string	Drive name.
directoryName	string	Full directory path, ending with directory separator character.
fileName	string	Simple filename.

Return Value

None.

Parameter Discussion

driveName, **directoryName**, and **fileName** can each be NULL. If not NULL, they must be buffers of the following size or greater:

driveName	MAX_DRIVENAME_LEN
directoryName	MAX_DIRNAME_LEN

fileName MAX_FILENAME_LEN

On operating systems without drive names (such as UNIX), SplitPath always fills **driveName** with the empty string.

Example

```
char pathName[MAX_PATHNAME_LEN];
char driveName[MAX_DRIVENAME_LEN];
char dirName[MAX_DIRNAME_LEN];
char fileName[MAX_FILENAME_LEN];
```

```
SplitPath (pathName, driveName, dirName, fileName);
/* If pathName contains
      c:\cvi\samples\apps\update.c
   then
      driveName contains
                                 "c:"
      dirName contains
                                 "\cvi\samples\apps\"
      fileName contains
                                 "update.c"
   If pathName is
      \\computer\share\dirname\foo.c
   then
                                  ....
      drive name is
      directory name is
                                 "\\computer\share\dirname\"
      filename is
                                 "foo.c" */
```

SyncWait

void SyncWait (double beginTime, double interval);

Purpose

Waits until interval seconds elapse since beginTime.

Parameters

Input

Name	Туре	Description
beginTime	double-precision	Value Timer returns.
interval	double-precision	Number of seconds to wait after beginTime .

Return Value

None.

Parameter Discussion

beginTime must be a value Timer returns.

The resolution on Windows is normally 1 ms. If, however, you set the useDefaultTimer configuration option to True, the resolution is 55 ms.

The resolution on Sun Solaris is 1 ms.

SystemHelp

Purpose

Under Windows, starts Windows Help, winhelp.exe, on a help file you specify. You can pass optional data that indicates the nature of the help you want to display.

For information about creating help files, refer to the Microsoft Windows programming documentation, which is not included with LabWindows/CVI.

Under UNIX, SystemHelp starts the HyperHelp help viewer on the help file you specify.

Note Although you may use the HyperHelp viewer that comes with LabWindows/CVI, you may not distribute it in an application you build unless you purchase a license from Bristol Technology, Inc.

Parameters

Input

Name	Туре	Description
helpFile	string	Points to a string that contains the name of the help file you want to display.
command	unsigned integer	Specifies the type of help you want to display.
additionalLongData	unsigned long integer	Depends on the command parameter as described in the following <i>Parameter Discussion</i> .
additionalStringData	string	Depends on the command parameter as described in the following <i>Parameter Discussion</i> .

Return Value

Name	Туре	Description
status	integer	Nonzero on success; zero on failure.

Parameter Discussion

helpFile contains the pathname of the file you want to display. The pathname can be followed by an angle bracket (>) and the name of a secondary window if you want the topic to appear in a secondary window rather than in the primary window. The [WINDOWS] section of the help project (.hpj) file must define the name of the secondary window.

command can be one of the following values:

HELP_COMMAND—Executes a help macro or macro string. In this case, **additionalStringData** is the help macro to execute.

HELP_CONTENTS—Displays the help contents topic as defined by the contents option in the [OPTIONS] section of the .hpj file. HELP_CONTENTS is for backward compatibility. New programs should provide a .cnt file and use the HELP_FINDER command.

HELP_CONTEXT—Displays help for a particular topic identified by a context number that has been defined in the [MAP] section of the .hpj file. In this case, **additionalLongData** is the context number of the topic.

HELP_CONTEXTPOPUP—Displays in a pop-up window a particular help topic identified by a context number that has been defined in the [MAP] section of the .hpj file. HELP_CONTEXTPOPUP does not display the main help window. In this case, **additionalLongData** is the context number of the topic.

HELP_FINDER—Displays the Help Topics dialog box.

HELP_HELPONHELP—Displays the contents topic of the Using Help file if it is available.

HELP_KEY—Displays the topic in the keyword list that matches the keyword passed in the **additionalStringData** parameter if one exact match exists. Under Windows 3.1, if more than one match exists, HELP_KEY displays the first topic found. If no match exists HELP_KEY displays an error message. Under Windows 95/NT, if more than one match exists, HELP_KEY displays the Topics Found dialog box.

HELP_PARTIALKEY—Displays the topic found in the keyword list that matches the keyword passed in the **additionalStringData** parameter if one exact match exists.

Under Windows 3.1, if more than one match exists, HELP_PARTIALKEY displays the Search dialog box with the topics listed in the Go To list box. If no match exists, HELP_PARTIALKEY displays the Search dialog box. If you want to bring up just the Search dialog box without passing a keyword, pass an empty string ("").

Under Windows 95/NT, if more than one match exists, HELP_PARTIALKEY displays the Topics Found dialog box. If you want to display the Index without passing a keyword, pass an empty string ("").

HELP_POPUPID—Displays in a pop-up window the topic identified by a context string. HELP_POPUPID does not display the main help window.

HELP_QUIT—Closes the help file. HELP_QUIT has no effect if another executable opens the help file.

HELP_SETCONTENTS—Determines which Contents topic help appears when the user chooses the Contents button in a help window if the help file does not have an associated .cnt file. If a help file has two or more Contents topics, you must assign one as the default. Call SystemHelp with **command** set to HELP_SETCONTENTS and the **additionalLongData** parameter specifying the corresponding context identifier.

TerminateExecutable

int status = TerminateExecutable (int executableHandle);

Purpose

Terminates an executable if it has not already terminated.

Windows 3.1 terminates an executable by sending close messages to each window in the application. If the application does not honor the close messages, the application does not terminate.TerminateExecutable gives up control for a limited time to give the application an opportunity to process the close messages. This time period should be sufficient for all applications. When you must allow more time, your program can call ProcessSystemEvents in a loop, as shown in the following example.

Example for Windows 3.1

Parameter

Input

Name	Туре	Description
executableHandle	integer	Executable handle acquired from LaunchExecutableEx.

Return Value

Name	Туре	Description
status	integer	Result of the operation.

Code	Description	
-1	Handle is invalid.	
0	Handle is valid. To determine if the function actually terminated the executable, use ExecutableHasTerminated.	

Timer

double t = Timer (void);

Purpose

Returns the number of seconds that have elapsed since the first call to Timer, Delay, or SyncWait or the first operation on a timer control. The value is never reset to zero except when you restart your program. The resolution on Windows is normally 1 ms. If, however, you set the useDefaultTimer configuration option to True, the resolution is 55 ms.

The resolution on Sun Solaris is 1 ms.

Parameters

None.

Return Value

Name	Туре	Description
t	double-precision	Number of seconds since the first call to Timer.

TimeStr

char *s = TimeStr (void);

Purpose

Returns an 8-character string in the form *HH:MM:SS*, where *HH* is the hour, *MM* is in minutes, and *SS* is in seconds.

Parameters

None.

Return Value

Name	Туре	Description
s	8-character string	Time in HH:MM:SS format.

TruncateRealNumber

double y = TruncateRealNumber (double inputRealNumber);

Purpose

Truncates the fractional part of inputRealNumber and returns the result as a real number.

Parameter

Input

Name	Туре	Description
inputRealNumber	double-precision	Real number to truncate.

Return Value

Name	Туре	Description
У	double-precision	Value of inputRealNumber without its fractional part.

UnloadExternalModule

int status_id = UnloadExternalModule (int moduleID);

Purpose

Unloads an external module file you loaded using LoadExternalModule.

Parameter

Output

Name	Туре	Description
moduleID	integer	ID of loaded module.

Return Value

Name	Туре	Description
status_id	integer	Indicates the result of the operation.

Return Codes

Code	Description
0	Success.
-9	Failure because of an invalid module_id.

Parameter Discussion

moduleID is the value LoadExternalModule returns, or -1. If **moduleID** is -1, LabWindows/CVI unloads all external modules.

Example

```
int module_id;
int status;
char *pathname;
pathname = "PROG.OBJ";
module_id = LoadExternalModule (pathname);
if (module_id <0)
    FmtOut ("Unable to load %s\n", pathname);
else {
    RunExternalModule (module_id, "");
    UnloadExternalModule (module_id);
}
```

UnMapPhysicalMemory

int status = UnMapPhysicalMemory (int mapHandle);

 Image: Note
 Only the Windows 95/NT versions of LabWindows/CVI support

 UnMapPhysicalMemory.

Purpose

Unmaps an address that you mapped using MapPhysicalMemory. You do not pass the address to this function. Instead, you pass the handle that MapPhysicalMemory returned.

Note Under Windows 95/NT, UnMapPhysicalMemory requires the LabWindows/CVI low-level support driver. LabWindows/CVI loads the driver at startup if it is on disk. You can check whether LabWindows/CVI loaded the driver at startup by calling CVILowLevelSupportDriverLoaded.

Parameters

Input

Name	Туре	Description
mapHandle	integer	Handle MapPhysicalMemory returns.

Return Value

Name	Туре	Description
status	integer	Indicates whether the function succeeded.

Return Codes

Code	Description
1	Success.
0	mapHandle is not valid, the operating system reported an error, or the low-level support driver is not loaded.

See Also

CVILowLevelSupportDriverLoaded

WriteToPhysicalMemory

Note Only the Windows versions of LabWindows/CVI support WriteToPhysicalMemory.

Purpose

Copies the contents of **destinationBuffer** into a region of physical memory. WriteToPhysicalMemory does not check whether the memory actually exists. If the memory does not exist, WriteToPhysicalMemory returns the success value but does not read any data.

C Note

Under Windows 95/NT, WriteToPhysicalMemory requires the LabWindows/CVI low-level support driver. LabWindows/CVI loads the driver at startup if it is on disk. You can check whether LabWindows/CVI loaded the driver at startup by calling CVILowLevelSupportDriverLoaded.

Parameters

Input

Name	Туре	Description
physicalAddress	unsigned integer	Physical address to write to. No restrictions exist on the address; it can be below or above 1 MB.
sourceBuffer	void pointer	Buffer from which to copy the physical memory.
numberOfBytes	unsigned integer	Number of bytes to copy to physical memory.

Return Value

Name	Туре	Description
status	integer	Indicates whether the function succeeded.

Return Codes

Code	Description
1	Success.
0	Operating system reported failure, or low-level support driver not loaded.

See Also

WriteToPhysicalMemoryEx, MapPhysicalMemory, CVILowLevelSupportDriverLoaded

WriteToPhysicalMemoryEx

🕞 Note

Only the Windows versions of LabWindows/CVI support WriteToPhysicalMemoryEx.

Purpose

Copies the contents of the buffer you specify to a region of physical memory. It can copy the data in units of 1, 2, or 4 bytes at a time. WriteToPhysicalMemoryEx does not check whether the memory actually exists. If the memory does not exist, WriteToPhysicalMemoryEx returns the success value but does not read any data.

C Note

Under Windows 95/NT, WriteToPhysicalMemoryEx requires the LabWindows/CVI low-level support driver. LabWindows/CVI loads the driver at startup if it is on disk. You can check whether LabWindows/CVI loaded the driver at startup by calling CVILowLevelSupportDriverLoaded.

Parameters

Input

Name	Туре	Description
physicalAddress	unsigned integer	Physical address to write to. No restrictions exist on the address; it can be above or below 1 MB.
sourceBuffer	void pointer	Buffer from which to copy the physical memory.
numberOfBytes	unsigned integer	Number of bytes to copy to physical memory.
bytesAtATime	integer	Unit size in which to copy the data; can be 1, 2, or 4 bytes.

Return Value

Name	Туре	Description
status	integer	Indicates whether the function succeeded.

Return Codes

Code	Description
1	Success.
0	Operating system reported failure, low-level support driver not loaded, numberOfBytes is not a multiple of bytesAtATime , or invalid value for bytesAtATime .

Parameter Discussion

numberOfBytes must be a multiple of bytesAtATime.

See Also

MapPhysicalMemory, CVILowLevelSupportDriverLoaded

X Property Library

This chapter describes the functions in the Lab/Windows CVI X Property Library. The X Property Library contains functions that read and write properties to and from X Windows. The *X Property Library Overview* section contains general information about the X Property Library functions and panels. The *X Property Library Function Reference* section contains an alphabetical list of function descriptions.

These functions provide a mechanism for communication among X clients. This library provides capabilities similar to those available in the TCP Library, but differs from the TCP Library in the following significant ways:

- It conforms to a conventional method for X interclient communication.
- It works between any X clients that are connected to the same display and does not require any particular underlying communication protocol such as TCP.
- It provides a method for sharing data among X clients without explicit point-to-point connections between them.

X Property Library Overview

The X Property Library is available only in the UNIX versions of LabWindows/CVI. This section contains general information about the X Property Library functions and panels.

X Property Library Function Panels

The X Property Library function panels are grouped in the tree structure in Table 9-1 according to the types of operations they perform.

The first- and second-level headings in the tree are the names of function classes and subclasses. Function classes and subclasses are groups of related function panels. The third-level headings are the names of individual function panels. Each X Property Library function panel generates an X Property Library function call.

Function Name

Table 9-1.	Functions in the X Property Library Function Tree
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Class/Panel Name

1 unetion i junie
ConnectToXDisplay
DisconnectFromXDisplay

Class/Panel Name	Function Name
Managing Property Types	
Create New Property Type	CreateXPropType
Get Property Type Name	GetXPropTypeName
Get Property Type Size	GetXPropTypeSize
Get Property Type Unit	GetXPropTypeUnit
Destroy Property Type	DestroyXPropType
Managing Property Information	
Create New Property	CreateXProperty
Get Property Name	GetXPropertyName
Get Property Type	GetXPropertyType
Destroy Property	DestroyXProperty
Accessing Window Properties	
Get Single Window Property Item	GetXWindowPropertyItem
Put Single Window Property Item	PutXWindowPropertyItem
Get Window Property Value	GetXWindowPropertyValue
Put Window Property Value	PutXWindowPropertyValue
Remove Window Property	RemoveXWindowProperty
Handling Property Events	
Install Property Callback	InstallXPropertyCallback
Uninstall Property Callback	UninstallXPropertyCallback
· ·	
Get Error String	GetXPropErrorString

 Table 9-1.
 Functions in the X Property Library Function Tree (Continued)

The online help with each panel contains specific information about operating each function panel.

X Interclient Communication

X applications often use X properties to communicate with each other. Properties are essentially tagged data associated with a window. Applications communicate by reading and writing properties to and from windows. In addition, an X application can request that the X server notify it whenever a specific property value changes on a window.

The X applications that need to communicate with each other must first connect to the same X display. Then they must agree upon the names and types of properties and the X window IDs that they use to transfer the data. Although it is a simple matter to agree upon the names and types of properties in advance, the X applications cannot know the window IDs in advance because they are different for each invocation of the program. There must be a mechanism for transferring the window IDs from one client to another. A client usually accomplishes this by placing a property that contains the window ID on the root window, which is a window that all clients can access. The window ID refers to the window that contains the data for transfer to other clients. The other clients read this property from the root window to determine where to access the data.

With the LabWindows/CVI X Property Library functions, you can connect to X displays and obtain the root window ID, read and write properties on windows, and monitor when specific properties change.

Property Handles and Types

Before you can read or write properties on windows, you must create the property and its type. CreateXProperty takes a property name and a property type and returns a property handle you can use to access properties on windows. The property type, which CreateXPropType creates, contains the attributes that determine how data for the property are stored and retrieved. More specifically, these attributes are the size and unit. The size is the number of bytes in a single property item. The unit is the number of bytes in the basic entities that make up a property item. Refer to CreateXPropType for more information on the meanings of the size and unit attributes.

Table 9-2 lists the three predefined property types that you do not have to create. These types are useful for defining properties to store X window IDs, integers, and strings.

Property Type	Name	Size/Unit
WINDOW_X_PROP_TYPE	"WINDOW"	sizeof(WindowX)
INTEGER_X_PROP_TYPE	"INTEGER"	sizeof(int)
STRING_X_PROP_TYPE	"STRING"	sizeof(char)

Table 9-2. Predefined Property Types

Communicating with Local Applications

You can use the function ConnectToXDisplay to connect to any X server on a network. However, if your program communicates only with other applications connected to the same display as LabWindows/CVI, you do not need to connect to the display using ConnectToXDisplay. Instead, use the global variable CVIXDisplay, which is a pointer to the X display that LabWindows/CVI uses. The variable CVIXRootWindow contains the X window ID of the root window of the display that LabWindows/CVI uses.

Hidden Window

Before you can read or write property data, you need the X window IDs of the windows that store the properties.

One option is to always use the root window ID for attaching properties. The variable CVIXRootWindow holds the root window ID for the local display. To get the root window ID for a remote display, call ConnectToXDisplay. This approach has disadvantages. First, if your program adds a property to the root window and does not delete it, the property remains

there indefinitely. Second, because only one root window exists, conflicts might arise when multiple applications attempt to access the same properties.

To overcome those disadvantages, LabWindows/CVI provides a hidden window. Before it runs your program, LabWindows/CVI creates a window that never displays. The variable CVIXHiddenWindow holds the X window ID for the hidden window. This window ID is always available to your program for reading and writing properties. When your program terminates, LabWindows/CVI removes the window and all its properties.

Property Callback Functions

You can use the X Property Library to instruct LabWindows/CVI to notify your program whenever there is a change to a property/set of properties on a window/set of windows. InstallPropertyCallback registers a function that LabWindows/CVI calls whenever any of the specified properties changes. The callback function must have the type PropertyCallbackTypeX as defined in xproplib.h. LabWindows/CVI passes the X display, window, and property that changed to the callback function. The **state** parameter of the callback function can be NewValueX, if the property value changed, or DeleteX, if the property was deleted. UninstallPropertyCallback disables the callback function.

Error Codes

PropLibXErrType is the data type of all return values in the X Property Library functions. PropLibXErrType is an enumerated (enum) type that contains descriptive constant names and numeric values for the errors. PropLibXErrType and its enumerated values are all integers. All error values are negative numbers.

The function descriptions in the following section include detailed descriptions of these error types.

Using the Library Outside of LabWindows/CVI

You can use the LabWindows/CVI X Property Library in applications developed outside of LabWindows/CVI. By linking your program with the library file libxprop.a in the misc/lib directory of the LabWindows/CVI installation directory, you can use all the X Property Library functions in your program. You cannot use the libxprop.a library within LabWindows/CVI. The following two functions are available only outside of LabWindows/CVI:

 void _InitXPropertyLib(DisplayPtrX cviDisplay, WindowX rootWindow, WindowX hiddenWindow)

This function sets the global variables CVIXDisplay, CVIXRootWindow, and CVIXHiddenWindow of the X Property Library.

void HandlePropertyNotifyEvent(EventPtrX event)

This function calls the functions that you installed as property callbacks. You should call this function whenever you receive an XPropertyNotify event. The event must be a valid XPropertyEvent.

X Property Library Function Reference

This section describes each function in the LabWindows/CVI X Property Library in alphabetical order.

ConnectToXDisplay

Purpose

Connects to a remote X server.

Use ConnectToXDisplay to access an X server on a remote computer. This function returns a display pointer and the root window, which you can use to read and write properties on the root window of the remote X server.

If you want to communicate only with applications that use the same display as your application, you do not need this function. Instead, use the global variables CVIXDisplay and CVIXRootWindow, which contain the display and root window of the X server LabWindows/CVI uses.

Parameters

Input

Name	Туре	Description
displayName	string	Determines the X server connection and which communication domain to use.

Output

Name	Туре	Description
display	DisplayPtrX	Pointer to the display of the remote X server. Use this value as the argument to other library functions to communicate with the remote X server.
rootWindow	WindowX	Root window of the remote X server. Use this value as the parameter to other library functions to access properties on the root window of the remote X server.

Constant Name	Value	Description
NoXErr	0	Function was successful.
InvalidParamXErr	-1	NULL was passed to one or more parameters.
TooManyConnectionsXErr	-6	Program has already made the maximum number of connections that the constant MAX_X_DISPLAYS defines. Use DisconnectFromXDisplay to allow more connections.
CannotConnectXErr	-7	Connection could not be made to the X server. This happens for a number of reasons, including an invalid display name, a network problem, or a security problem.

Return Values

Parameter Discussion

Valid values for **displayName** include any valid arguments to the Xlib function XOpenDisplay. The format is hostname:server or hostname:server.screen, where:

- hostname specifies the name of the host computer to which the display is physically connected.
- server specifies the number of the server, usually 0, on its host computer.
- screen specifies the number of the default screen, usually 0, on the server.

See Also

Refer to the Xlib Programming Manual or to Xlib—C Language X Interface, MIT X Consortium Standard for more information about XOpenDisplay DefaultRootWindow.

CreateXProperty

Purpose

Creates X property information.

Use this function to define the attributes of the properties that you read and write on X windows. You must create properties with CreateXProperty before you can access them on X windows.

Each property has a unique name and a type, created by CreateXPropType, that you cannot change except by destroying the property and recreating it.

Note You can create a maximum of 256 different properties.

Parameters

Input

Name	Туре	Description
propertyName	string	Name of the property. Each property name is unique and has a type that you cannot change after you create the property.
propertyType	PropTypeHandleX	Type of the property. This value must be a predefined type or a value CreateXPropType returns.

Output

Name	Туре	Description
property	PropertyHandleX	Handle to the property information created. Use this value as the parameter to other library functions to access the property on X windows.

Constant Name	Value	Description
NoXErr	0	Function was successful.
InvalidParamXErr	-1	NULL was passed to one or more parameters.
InvalidPropTypeXErr	-5	propertyType argument is not a valid property type. This value must be one of the predefined property types, or must be a value CreateXPropType returns.
DupPropertyXErr	-8	Property with the same propertyName but with a different propertyType already exists.
InsuffMemXErr	-19	Insufficient memory to store the property information, or 256 properties already exist.

Return Values

Parameter Discussion

CreateXProperty sets the **propertyType** of the property the first time you write a property to a window. When you access a property on a window on which the property already exists, its type must match this value for the access to succeed.

See Also

Refer to the *Xlib Programming Manual* or to *Xlib—C Language X Interface, MIT X Consortium Standard* for more information about XInternAtom.

CreateXPropType

Purpose

Creates an X property type. You can use this function to define the attributes of the properties that you read and write on X windows. You must create property types with this function before you can create properties.

Each property type has a unique name and set of attributes that you cannot change except by destroying the property and recreating it.

Refer to Table 9-2 in the *Property Handles and Types* section of the *X Property Library Overview* section of this chapter for the three predefined property types, which you do not need to create using CreateXPropType.

Note You can create a maximum of 64 different property types.

Parameters

Input

Name	Туре	Description
typeName	string	Name of the property type. Each property type name is unique and has one set of attributes that you cannot change after you create the property type.
size	unsigned integer	Number of bytes in a single property item.
unit	unsigned integer	Number of bytes in the basic units that make up a property item.

Output

Name	Туре	Description
propertyType	PropTypeHandleX	Property type created. Use this value as the type parameter to CreateXProperty to create properties.

Constant Name	Value	Description
NoXErr	0	Function was successful.
InvalidParamXErr	-1	NULL was passed to one or more parameters; size argument is 0; unit is not 1, 2, or 4; or size is not a multiple of unit .
DupPropTypeXErr	-9	Property type with the same typeName but with a different size or unit already exists.
InsuffMemXErr	-19	Insufficient memory to store the property information or 64 property types already exist.

Return Values

Parameter Discussion

Usually, you can use the expression sizeof(type) for the **size** parameter, where type is the data type you use to store the property value. This value must be a multiple of the **unit** argument.

unit specifies how the X server views the property item, for example, as an array of 1-byte, 2-byte or 4-byte objects. **unit** is necessary to perform simple byte swapping between different types of computers. Refer to the following notes for more information.

If the property item consists of a single object, such as an integer or a character, the unit should be the size of the object. An exception is the double type, for which the default unit should be 4 bytes.

If the property item is a structure or array that contains a number of smaller objects, then the unit should be the number of bytes in the smaller objects.

- Note If you are communicating with a remote X server on a computer that uses different byte ordering than your application, CreateXPropType uses the unit you specify to perform the byte swapping. However, LabWindows/CVI cannot properly perform byte swapping for structures that contain different-sized members or for the double type. For these special cases, use a unit of one and explicitly perform byte swapping where you need to.
- **Note** The LabWindows/CVI X Property Library specifies units in the number of bytes as opposed to bits. Thus, the format values of 8, 16, and 32 that Xlib functions use correspond to units of 1, 2, and 4, respectively, in the functions of the LabWindows/CVI X Property Library.

See Also

Refer to the *Xlib Programming Manual* or to *Xlib—C Language X Interface, MIT X Consortium Standard* for more information about XInternAtom.

DestroyXProperty

PropLibXErrType status = DestroyXProperty (PropertyHandleX property);

Purpose

Destroys X property information. You can use DestroyXProperty when you no longer need to access a property. This function frees memory that CreateXProperty allocates. The property handle cannot be used after you call DestroyXProperty.

LabWindows/CVI destroys all property information when the program terminates.

NoteYou cannot destroy properties for which callbacks are installed. You must first call
UninstallXPropertyCallback on the callbacks.

Parameter

Input

Name	Туре	Description
property	PropertyHandleX	Handle to the property information to destroy. This value must be one of the predefined property types or must be a value CreateXPropType returns.

Return Values

Constant Name	Value	Description
NoXErr	0	Function was successful.
InvalidPropertyXErr	-4	property argument is not a valid property. This argument must be the value CreateXProperty returns.
PropertyInUseXErr	-10	A property callback was installed with InstallPropertyCallback for this property. It is not possible to destroy properties for which callbacks are installed.

DestroyXPropType

PropLibXErrType status = DestroyXPropType (PropTypeHandleX propertyType);

Purpose

Destroys X property type. You can use DestroyXPropType when you no longer need a property type. This function frees memory that CreateXPropType allocates. The property type cannot be used after you call DestroyXPropType.

LabWindows/CVI destroys all property types when the program terminates.

Note You cannot destroy property types if there are properties that use them. You must first call DestroyXProperty on the properties.

Parameter

Input

Name	Туре	Description
propertyType	PropertyHandleX	Handle of the property type to destroy. This value must be one of the predefined property types or must be a value CreateXPropType returns.

Return Values

Constant Name	Value	Description
NoXErr	0	Function was successful.
InvalidPropTypeXErr	-5	propertyType argument is not a valid property type. This value must be one of the predefined property types, or must be a value CreateXPropType returns.
PropTypeInUseXErr	-11	A property that CreateXProperty created has this property type. It is not possible to destroy property types if there are properties that use them.

DisconnectFromXDisplay

PropLibXErrType status = DisconnectFromXDisplay (DisplayPtrX display);

Purpose

Disconnects from a remote X server. You can use DisconnectFromXDisplay to end access to a remote X server you connected to using ConnectToXDisplay. After you call DisconnectFromXDisplay, you can no longer access the remote X server.

Parameter

Input

Name	Туре	Description
display	DisplayPtrX	A pointer to the display of the remote X server to disconnect. You must obtain the pointer from ConnectToXDisplay.

Return Values

Constant Name	Value	Description
NoXErr	0	Function was successful.
InvalidParamXErr	-1	NULL was passed to the parameter.
InvalidDisplayXErr	-2	display argument is not a valid display. You must obtain a display pointer from ConnectToXDisplay.

See Also

Refer to the *Xlib Programming Manual* or to *Xlib—C Language X Interface, MIT X Consortium Standard* for more information about XCloseDisplay.

GetXPropErrorString

char *message = GetXPropErrorString (PropLibXErrType errorNum);

Purpose

Converts the error number an X Property Library function returns into a meaningful error message.

Parameter

Input

Name	Туре	Description
errorNum	PropLibXErrType	Status that an X Property Library function returns.

Return Value

Name	Туре	Description
message	string	Explanation of error.

GetXPropertyName

Purpose

Gets a property name. This function returns a pointer to the name associated with the property handle.

Parameters

Input

Name	Туре	Description
property	PropertyHandleX	Property handle for which to obtain the name. You must obtain this handle from CreateXProperty.

Output

Name	Туре	Description
propertyName	character pointer	Pointer to the property name.



Caution The propertyName pointer points to memory allocated by CreateXProperty. You must not attempt to free this pointer or to change its contents.

Return Values

Constant Name	Value	Description
NoXErr	0	Function was successful.
InvalidParamXErr	-1	NULL was passed to the name parameter.
InvalidPropertyXErr	-4	property argument is not a valid property handle. You must obtain a property handle from CreateXProperty.

GetXPropertyType

Purpose

Gets the type of a property.

This function returns a pointer to the type associated with the property handle.

Parameters

Input

Name	Туре	Description
property	PropertyHandleX	Property handle for which to obtain the type. You must obtain this handle from CreateXProperty.

Output

Name	Туре	Description
propertyType	PropTypeHandleX	Property type. Use GetXPropTypeName, GetXPropTypeSize, and GetXPropTypeUnit to get more information about the property type.

Return Values

Constant Name	Value	Description
NoXErr	0	Function was successful.
InvalidParamXErr	-1	NULL was passed to the parameter.
InvalidPropertyXErr	-4	property argument is not a valid property handle. You must obtain a property handle from CreateXProperty.

GetXPropTypeName

Purpose

Gets a property type name. This function returns the name associated with the property type.

Parameters

Input

Name	Туре	Description
propertyType	PropTypeHandleX	Handle to property type for which to obtain the name. This value must be one of the predefined property types or a handle you obtain from CreateXPropType.

Output

Name	Туре	Description
typeName	character pointer	Property type name.



Caution The typeName pointer points to memory CreateXPropType allocates. You must not attempt to free this pointer or to change its contents.

Return Values

Constant Name	Value	Description
NoXErr	0	Function was successful.
InvalidParamXErr	-1	NULL was passed to the parameter.
InvalidPropTypeXErr	-5	propertyType argument is not a valid property type. You must use one of the predefined property types or obtain a property handle from CreateXPropType.

See Also

CreateXPropType

GetXPropTypeSize

Purpose

Gets a property type size. This function returns the size associated with the property type.

Parameters

Input

Name	Туре	Description
propertyType	PropTypeHandleX	Handle to property type for which to obtain the size. This value must be one of the predefined property types or a handle you obtain from CreateXPropType.

Output

Name	Туре	Description
size	unsigned integer	Size associated with the property type. The size is the number of bytes in a single property item.

Return Values

Constant Name	Value	Description
NoXErr	0	Function was successful.
InvalidParamXErr	-1	NULL was passed to the parameter.
InvalidPropTypeXErr	-5	propertyType argument is not a valid property type. You must use one of the predefined property types or obtain a property handle from CreateXPropType.

See Also

CreateXPropType

GetXPropTypeUnit

Purpose

Gets a property type unit.

GetXPropTypeUnit returns the unit associated with the property type.

Parameters

Input

Name	Туре	Description
propertyType	PropTypeHandleX	Handle to property type for which to obtain the unit. This value must be one of the predefined property types or a handle you obtain from CreateXPropType.

Output

Name	Туре	Description
unit	unsigned integer	unit associated with the property type. The unit is the number of bytes (1, 2 or 4) in the basic objects that make up a property item.

Return Values

Constant Name	Value	Description
NoXErr	0	Function was successful.
InvalidParamXErr	-1	NULL was passed to the parameter.
InvalidPropTypeXErr	-5	propertyType argument is not a valid property type. You must use one of the predefined property types or obtain a property handle from CreateXPropType.

See Also

CreateXPropType

GetXWindowPropertyItem

Purpose

Gets a single property item from a window.

GetXWindowPropertyItem obtains the value of the specified property on the window and copies a single item into the supplied buffer. When more than one item exists in the property value, GetXWindowPropertyItem obtains only the first one. This function does not change the property value.

If the property does not exist on the window, GetXWindowPropertyItem reports the MissingPropertyXErr error.

Use GetXWindowPropertyValue to get multiple property items.

Parameters

Input

Name	Туре	Description
display	DisplayPtrX	Pointer to the display of the X server to which the window belongs.
window	WindowX	Window from which to obtain the property item.
property	PropertyHandleX	Handle of the property to obtain. You must obtain this handle from CreateXProperty.

Output

Name	Туре	Description
propertyItem	generic pointer	Property item obtained from window.

Return Values

Constant Name	Value	Description
NoXErr	0	Function was successful.
InvalidParamXErr	-1	NULL was passed to one or more parameters.
InvalidDisplayXErr	-2	display argument is not a valid display. You must use the predefined value CVIXDisplay or obtain a display pointer from ConnectToXDisplay.
InvalidWindowXErr	-3	window argument is not a valid window.
InvalidPropertyXErr	-4	property argument is not a valid property handle. You must obtain a property handle from CreateXProperty.
TypeMismatchXErr	-12	Actual X type of the property value on the window does not match the type you specified for property .
UnitMismatchXErr	-13	Actual X format of the property value on the window does not match the unit you specified for property .
SizeMismatchXErr	-15	Number of bytes in the property value is not a multiple of the size you specified for property .
MissingPropertyXErr	-18	Property does not exist on the window.
InsuffMemXErr	-19	Insufficient memory to perform the operation.
GeneralXErr	-20	An Xlib function failed for an unknown reason.
BrokenConnectionXErr	-21	Connection to the X server was broken. This occurs if the remote server terminates.

Parameter Discussion

display must be the predefined value CVIXDisplay or must be a display pointer you obtain from ConnectToXDisplay. Use CVIXDisplay if the window is on the same display LabWindows/CVI uses.

For the **window** parameter, use CVIXRootWindow to access the default root window of the display LabWindows/CVI uses. Use CVIXHiddenWindow to access the hidden window associated with your application.

propertyItem must point to an object of the same size as the property item. You can get the size of the property item by calling the function GetXPropertySize.

See Also

Refer to the Xlib Programming Manual or to Xlib—C Language X Interface, MIT X Consortium Standard for more information about XGetWindowProperty.

GetXWindowPropertyValue

Purpose

Gets the value of a property on a window.

GetXWindowPropertyValue obtains the value of the specified property on the window and copies it into the supplied buffer.

If the property does not exist on the window, GetXWindowPropertyValue does not report an error. Instead, it sets the number of items returned to 0.

Parameters

Note

Input

Name	Туре	Description
display	DisplayPtrX	Pointer to the display of the X server to which the window belongs.
window	WindowX	Window from which to obtain the property value.
property	PropertyHandleX	Handle of the property to obtain. You must obtain this handle from CreateXProperty.
index	unsigned integer	Index into the property value where reading is to begin. Specify the number of property items to skip from the start of the property value.

Name	Туре	Description
numberOfItemsRequested	unsigned integer	Number of property items to obtain from the window.
delete	integer	Flag that indicates whether to delete the property value from the window after it is obtained. Specify 1 to delete the portion of the property value that was obtained. Specify 0 to leave the property value as it is.

Output

Name	Туре	Description
numberOfItemsReturned	unsigned integer	Number of property items that were obtained from the window.
numberOfItemsRemaining	unsigned integer	Number of property items on the window that were neither skipped nor obtained. Pass NULL for this parameter if you do not need this information.
propertyValue	generic pointer	Property value obtained from window. This parameter must point to an array of size <i>n</i> -by- <i>m</i> bytes, where <i>n</i> is the size of the property item, and <i>m</i> is the number of items requested.

Return Values

Constant Name	Value	Description
NoXErr	0	Function was successful.
InvalidParamXErr	-1	NULL was passed to one or more parameters.

Constant Name	Value	Description
InvalidDisplayXErr	-2	display argument is not a valid display. You must use the predefined value CVIXDisplay or obtain a display pointer from ConnectToXDisplay.
InvalidWindowXErr	-3	window argument is not a valid window.
InvalidPropertyError	-4	property argument is not a valid property handle. You must obtain a handle from CreateXProperty.
TypeMismatchXErr	-12	Actual X type of the property value on the window does not match the type you specified for property .
UnitMismatchXErr	-13	Actual X format of the property value on the window does not match the unit you specified for property .
InvalidIndexXErr	-14	index you specified is larger than the actual number of property items on the window.
SizeMismatchXErr	-15	Number of bytes in the property value is not a multiple of the size you specified for property .
InsuffMemXErr	-19	Insufficient memory to perform the operation.
GeneralXErr	-20	An Xlib function failed for an unknown reason.
BrokenConnectionXErr	-21	Connection to the X server was broken. This occurs if the remote server terminates.

Parameter Discussion

display must be the predefined value CVIXDisplay or must be a display pointer you obtain from ConnectToXDisplay. Use CVIXDisplay if the window is on the same display LabWindows/CVI uses.

For the **window** parameter, use CVIXRootWindow to access the default root window of the display LabWindows/CVI uses. Use CVIXHiddenWindow to access the hidden window associated with your application.

numberOfItemsReturned will be less than or equal to the number of property items you requested. If the property does not exist on the window or no property value exists, this value is 0. You must check this value to determine if any property items were read.

See Also

Refer to the *Xlib Programming Manual* or to *Xlib—C Language X Interface*, *MIT X Consortium Standard* for more information about XGetWindowProperty.

InstallXPropertyCallback

Purpose

Installs a property callback function.

The X Property Library calls the callback function whenever one of the specified properties on one of the specified windows changes in any way. If you install more than one function for the same property, the library calls the functions in the reverse order in which you installed them.

If you already installed the callback function, the window list and properties you specify in this call replace the ones you previously associated with the callback function.

Parameters

Name	Туре	Description
display	DisplayPtrX	Pointer to the display of the X server to which the window belongs.
windowList	const WindowX []	Array of windows on which the properties can exist.
numberOfWindows	unsigned integer	Number of windows in the window list; this value must be greater than 0.
propertyList	const Property CallbackTypeX []	Array of handles to properties for which the library invokes the callback.
numberOfProperties	unsigned integer	Number of properties in the property list.

Input

Name	Туре	Description
callbackData	generic pointer	Pointer to data to pass to the callback function. LabWindows/CVI passes this value to the callback function as userData .
callbackFunction	Property CallbackTypeX *	Pointer to the function to call when the properties change.

Return Values

Constant Name	Value	Description
NoXErr	0	Function was successful.
InvalidParamXErr	-1	NULL was passed to one or more parameters. The numberOfWindows argument is 0.
InvalidDisplayXErr	-2	display argument is not a valid display. You must use the predefined value CVIXDisplay or obtain a display pointer from ConnectToXDisplay.
InvalidWindowXErr	-3	One or more of the windows in the windowList argument are not valid.
InvalidPropertyXErr	-4	One or more of the property handles in the propertyList argument are not valid. These properties must be values CreateXProperty returns.
InsuffMemXErr	-19	Insufficient memory to perform the operation.
BrokenConnectionXErr	-21	Connection to the X server was broken. This occurs if the remote server terminates.

Parameter Discussion

display must be the predefined value CVIXDisplay or must be a display pointer you obtain from ConnectToXDisplay. Use CVIXDisplay if the window is on the same display LabWindows/CVI uses.

To specify a single window named win, pass the expression & win for the windowList parameter and pass 1 for the **numberOfWindows**. Use & CVIXRootWindow to access the default root window of the display LabWindows/CVI uses. Use & CVIXHiddenWindow to specify the hidden window associated with your application.

If **numberOfProperties** is 0 or the **propertyList** value is ANY_X_PROPERTY, the callback function is called whenever any property changes on any of the windows in the **windowList**.

The values in the **propertyList** array must be handles you obtain from CreateXProperty.

To specify a single property named *prop*, pass the expression *&prop* for the **propertyList** parameter and pass 1 for **numberOfProperties**. If this value is ANY_X_PROPERTY or the **numberOfProperties** is 0, the callback function is called whenever any property changes on any of the windows in the **windowList**.

See Also

Refer to the *Xlib Programming Manual* or to *Xlib—C Language X Interface*, *MIT X Consortium Standard* for more information about the PropertyNotify event.

PutXWindowPropertyItem

Purpose

Stores a single property item on a window. This value replaces any existing property value.

To store multiple property items, use PutXWindowPropertyValue.

Parameters

Input

Name	Туре	Description
display	DisplayPtrX	Pointer to the display of the X server to which the window belongs.
window	WindowX	Window on which the property item is to be stored.
property	PropertyHandleX	Handle of the property to store. You must obtain this handle from CreateXProperty.
propertyItem	generic pointer	Property item to store on the window. This parameter must point to an object of the same size as a property item. You can get the property item size by calling GetXPropertySize.

Return Values

Constant Name	Value	Description
NoXErr	0	Function was successful.
InvalidParamXErr	-1	NULL was passed to one or more parameters.

Constant Name	Value	Description
InvalidDisplayXErr	-2	display argument is not a valid display. You must use the predefined value CVIXDisplay or obtain a display pointer from ConnectToXDisplay.
InvalidWindowXErr	-3	window argument is not a valid window.
InvalidPropertyXErr	-4	property argument is not a valid property handle. You must obtain a property handle from CreateXProperty.
InsuffMemXErr	-19	Insufficient memory to perform the operation.
GeneralXErr	-20	An Xlib function failed for an unknown reason.
BrokenConnectionXErr	-21	Connection to the X server was broken. This occurs if the remote server terminates.

Parameter Discussion

display must be the predefined value CVIXDisplay or must be a display pointer you obtain from ConnectToXDisplay. Use CVIXDisplay if the window is on the same display LabWindows/CVI uses.

For the **window** parameter, use CVIXRootWindow to access the default root window of the display LabWindows/CVI uses. Use CVIXHiddenWindow to access the hidden window associated with your application.

See Also

Refer to the *Xlib Programming Manual* or to *Xlib—C Language X Interface*, *MIT X Consortium Standard* for more information about XChangeProperty.

PutXWindowPropertyValue

Purpose

Stores the value of a property on a window.

To store a single property item, you can use PutXWindowPropertyItem.

Parameters

Name	Туре	Description
display	DisplayPtrX	Pointer to the display of the X server to which the window belongs.
window	WindowX	Window on which the property value is to be stored.
property	PropertyHandleX	Handle of the property to store. You must obtain this handle from CreateXProperty.
numberOfItems	unsigned integer	Number of property items to store on the window.
mode	integer	Mode in which property value is stored.
propertyValue	generic pointer	Property value to store on the window. This parameter must be an array of size n -by- m bytes, where n is the size of a property item, and m is the number of items to write.

Input

Return Values

Constant Name	Value	Description
NoXErr	0	Function was successful.
InvalidParamXErr	-1	NULL was passed to one or more parameters; mode is not ReplaceXPropMode, PrependXPropMode or AppendXPropMode.
InvalidDisplayXErr	-2	display argument is not a valid display. You must use the predefined value CVIXDisplay or obtain a display pointer from ConnectToXDisplay.
InvalidWindowXErr	-3	window argument is not a valid window.
InvalidPropertyXErr	-4	property argument is not a valid property handle. You must obtain a property handle from CreateXProperty.
TypeMismatchXErr	-12	Actual X type of the property value on the window does not match the type you specified for property . This can occur only if you set mode to append or prepend.
UnitMismatchXErr	-13	Actual X format of the property value on the window does not match the unit you specified for property . This can occur only if you set mode to append or prepend.
OverflowXErr	-16	Arithmetic overflow occurred in calculations on the property item sizes and the number of items you specified.
InsuffMemXErr	-19	Insufficient memory to perform the operation.

Constant Name	Value	Description
GeneralXErr	-20	An Xlib function failed for an unknown reason.
BrokenConnectionXErr	-21	Connection to the X server was broken. This occurs if the remote server terminates.

Parameter Discussion

display must be the predefined value CVIXDisplay or must be a display pointer you obtain from ConnectToXDisplay. Use CVIXDisplay if the window is on the same display LabWindows/CVI uses.

For the **window** parameter, use CVIXRootWindow to access the default root window of the display LabWindows/CVI uses. Use CVIXHiddenWindow to access the hidden window associated with your application.

The following values are valid for the **mode** parameter:

ReplaceXPropMode—Replaces the existing property value with the new value. PrependXPropMode—Adds the new property value to the beginning of the existing value. AppendXPropMode—Adds the new property value to the end of the existing value.

See Also

Refer to the *Xlib Programming Manual* or to *Xlib—C Language X Interface*, *MIT X Consortium Standard* for more information about XChangeProperty.

RemoveXWindowProperty

Purpose

Deletes the property value and removes the property from the window.

Parameters

Input

Name	Туре	Description
display	DisplayPtrX	Pointer to the display of the X server to which the window belongs.
window	WindowX	Window from which the property is to be removed.
property	PropertyHandleX	Handle of the property to remove. You must obtain this handle from CreateXProperty.

Return Values

Constant Name	Value	Description
NoXErr	0	Function was successful.
InvalidParamXErr	-1	NULL was passed to one or more parameters.
InvalidDisplayXErr	-2	display argument is not a valid display. You must use the predefined value CVIXDisplay or obtain a display pointer from ConnectToXDisplay.
InvalidWindowXErr	-3	window argument is not a valid window.
InvalidPropertyXErr	-4	property argument is not a valid property handle. You must obtain a property handle from CreateXProperty.

Constant Name	Value	Description
InsuffMemXErr	-19	Insufficient memory to perform the operation.
BrokenConnectionXErr	-21	Connection to the X server was broken. This occurs if the remote server terminates.

Parameter Discussion

display must be the predefined value CVIXDisplay or must be a display pointer you obtain from ConnectToXDisplay. Use CVIXDisplay if the window is on the same display LabWindows/CVI uses.

For the **window** parameter, use CVIXRootWindow to access the default root window of the display LabWindows/CVI uses. Use CVIXHiddenWindow to access the hidden window associated with your application.

See Also

Refer to the *Xlib Programming Manual* or to *Xlib—C Language X Interface*, *MIT X Consortium Standard* for more information about XDeleteProperty.

UninstallXPropertyCallback

Purpose

Uninstalls a property callback function.

After a callback function is uninstalled, it is no longer called when properties change. LabWindows/CVI automatically uninstalls all property callback functions when the program terminates.

Parameter

Input

Name	Туре	Description
callbackFunction	Property CallbackTypeX *	Function that was installed with InstallXPropertyCallback.

Return Values

Constant Name	Value	Description
NoXErr	0	Function was successful.
InvalidCallbackXErr	-17	Function you specified is not installed as a callback.

Note Although you cannot selectively uninstall certain properties or windows associated with a callback function, you can reinstall a callback function with a new set of windows and properties using InstallXPropertyCallback.

10

Easy I/O for DAQ Library

This chapter describes the functions in the Easy I/O for DAQ Library. The *Easy I/O for DAQ Library Function Overview* section contains general information about the functions and guidelines and restrictions you should know when using the Easy I/O for DAQ Library. The *Easy I/O for DAQ Function Reference* section contains an alphabetical list of function descriptions.

Easy I/O for DAQ Library Function Overview

The functions in the Easy I/O for DAQ Library make it easier to write simple DAQ programs than if you use the Data Acquisition Library.

This library implements a subset of the functionality of the Data Acquisition Library, but it does not use the same functions as the Data Acquisition Library. Read the following advantages and limitations to see if the Easy I/O for DAQ Library is appropriate for your application.

You must have NI-DAQ for PC compatibles installed to use the Easy I/O for DAQ Library, which has been tested using version 4.6.1 and later of NI-DAQ. It has not been tested using previous versions of NI-DAQ.

The cvi\samples\easyio directory includes sample programs for the Easy I/O for DAQ Library. The EASYIO section of cvi\samples.doc includes discussions of these sample programs.

Note Do not mix calls to the Data Acquisition Library with similar types of calls to the Easy I/O for DAQ Library in the same application. For example, do not mix analog input calls to the Data Acquisition Library with analog input calls to the Easy I/O for DAQ Library in the same program.

Advantages of Using the Easy I/O for DAQ Library

If you want to scan multiple analog input channels on an MIO board using the Data Acquisition Library, you have to programmatically build a channel list and a gain list before calling SCAN_Op.

The Easy I/O for DAQ functions accept a channel string and upper and lower input limit parameters so you can easily perform a scan in one step.

In the Data Acquisition Library, you might have to use Lab_ISCAN_Op, SCAN_Op, or MDAQ_Start depending on which DAQ device you use. Also, if you use SCXI, you must call a number of SCXI-specific functions before you actually acquire data.

The Easy I/O for DAQ functions are device independent, which means that you can use the same function on a Lab series board, an MIO board, an EISA-A2000, or an SCXI module.

Limitations of Using the Easy I/O for DAQ Library

The Easy I/O for DAQ Library currently works only with analog I/O, counter/timers, and simple digital I/O.

The library does not currently work with multirate scanning.

Easy I/O for DAQ Library Function Panels

The Easy I/O for DAQ Library function panels are grouped in the tree structure in Table 10-1 according to the types of operations they perform.

The first- and second-level headings in the function tree are names of the function classes and subclasses. Function classes and subclasses are groups of related function panels. The third-level headings are the names of individual function panels. Each Easy I/O for DAQ function panel generates a function call.

Class/Panel Name	Function Name
Analog Input	
AI Sample Channel	AISampleChannel
AI Sample Channels	AISampleChannels
AI Acquire Waveform(s)	AIAcquireWaveforms
AI Acq. Triggered Waveform(s)	AIAcquireTriggeredWaveforms
Asynchronous Acquisition	
AI Start Acquisition	AIStartAcquisition
AI Check Acquisition	AICheckAcquisition
AI Read Acquisition	AIReadAcquisition
AI Clear Acquisition	AIClearAcquisition
Plot Last Waveform(s) to Popup	PlotLastAIWaveformsPopup
Analog Output	
AO Update Channel	AOUpdateChannel
AO Update Channels	AOUpdateChannels
AO Generate Waveform(s)	AOGenerateWaveforms
AO Clear Waveform(s)	AOClearWaveforms
Digital Input/Output	
Read from Digital Line	ReadFromDigitalLine
Read from Digital Port	ReadFromDigitalPort

Table 10-1. Functions in the Easy I/O for DAQ Library Function Tree

Class/Panel Name	Function Name
Digital Input/Output (continued)	
Write to Digital Line	WriteToDigitalLine
Write to Digital Port	WriteToDigitalPort
Counter/Timer	
Counter Measure Frequency	CounterMeasureFrequency
Counter Event or Time Configure	CounterEventOrTimeConfig
Continuous Pulse Gen Configure	ContinuousPulseGenConfig
Delayed Pulse Gen Configure	DelayedPulseGenConfig
Frequency Divider Configure	FrequencyDividerConfig
Pulse Width or Period Meas Conf	PulseWidthOrPeriodMeasConfig
Counter Start	CounterStart
Counter Read	CounterRead
Counter Stop	CounterStop
I Counter Control	ICounterControl
Miscellaneous	
Get DAQ Error Description	GetDAQErrorString
Get Number of Channels	GetNumChannels
Get Channel Indices	GetChannelIndices
Get Channel Name from Index	GetChannelNameFromIndex
Get AI Limits of Channel	GetAILimitsOfChannel
Group by Channel	GroupByChannel
Set Multitasking Mode	SetEasyIOMultitaskingMode

Table 10-1. Functions in the Easy I/O for DAQ Library Function Tree

Class Descriptions

- The Analog Input function class contains all the functions that perform A/D conversions.
- The Asynchronous Acquisition function class contains all the functions that perform asynchronous, or background, A/D conversions.
- The Analog Output function class contains all the functions that perform D/A conversions.
- The Digital Input/Output function class contains all the functions that perform digital input and output operations.
- The Counter/Timer function class contains all the functions that perform counting and timing operations.
- The Miscellaneous function class contains functions that do not fit into the other categories but are useful when you write programs using the Easy I/O for DAQ Library.

The online help with each panel contains specific information about operating each function panel.

Device Numbers

The first parameter to most of the Easy I/O for DAQ functions is the device number of the DAQ device you want to use for the given operation. After you have followed the installation and configuration instructions in Chapter 1, *Introduction to NI-DAQ*, of the *NI-DAQ User Manual for PC Compatibles*, the configuration utility displays the device number for each device you have installed in the system. You can use the configuration utility to verify your device numbers. To use multiple DAQ devices in one application, pass the appropriate device number to each function.

Channel String for Analog Input Functions

The second parameter to most of the analog input functions is the channel string that contains the analog input channels to sample.

Refer to Chapter 2, *Hardware Overview*, in your *NI-DAQ User Manual for PC Compatibles* to determine exactly what channels are valid for your hardware.

The following examples explain the syntax for the channel string in various cases:

• If you are using an MIO board, NEC-AI-16E-4, or NEC-AI-16XE-50, list the channels in the order in which they are to be read, as in the following example:

```
"0,2,5" /* reads channels 0, 2, and 5 in that order */
"0:3" /* reads channels 0 through 3 inclusive */
```

• If you are using AMUX-64T boards, you can address AMUX-64T channels when you attach one, two, or four AMUX-64T boards to a plug-in data acquisition board.

Refer to Chapter 2, *Hardware Overview*, in your *NI-DAQ User Manual for PC Compatibles* to determine how AMUX-64T channels are multiplexed onto onboard channels.

The onboard channel to which each block of four, eight, or 16 AMUX-64T channels are multiplexed and the scanning order of the AMUX-64T channels are fixed. To specify a range of AMUX-64T channels, you enter in the channel list the onboard channel into which the range is multiplexed. For example, if you have one AMUX-64T:

```
"0" /* reads channels 0 through 3 on each AMUX-64T board in that order */
```

To sample a single AMUX-64T channel, you also must specify the number of the AMUX-64T board, as in the following example:

"AM1!3" /* samples channel 3 on AMUX-64T board 1 */ "AM4!8" /* samples channel 8 on AMUX-64T board 4 */

• If you are using a Lab-PC+, DAQCard-500/700/1200, DAQPad-1200, or PC-LPM-16, you can sample input channels only in descending order, and you must end with channel 0, such as "3:0". If you are using a Lab-PC+ or 1200 product in differential mode, you must use even-numbered channels.

- If you are using a DAQPad-MIO-16XE-50, you can read the value of the cold junction compensation temperature sensor using "cjtemp" as the channel.
- If you are using SCXI, you can address SCXI channels when you attach one or more SCXI chassis to a plug-in data acquisition board. If you operate a module in parallel mode, you can select a SCXI channel by specifying the corresponding onboard channels or by using special channel syntax for SCXI. If you operate the modules in multiplexed mode, you must use the SCXI channel syntax. The following example describes the SCXI channel syntax:

```
"OB1!SCx!MDy!a" /* Channel a on the module in slot y of the chassis
with ID x is multiplexed into onboard channel 1. */
"OB0!SCx!MDy!a:b" /* Channels a through b inclusive on the module
in slot y of the chassis with ID x is multiplexed into onboard
channel 0. */
```

SCXI channel ranges cannot cross module boundaries and must always increase in channel number.

The following examples of the SCXI channel syntax introduce the special SCXI channels:

- "OB0!SCx!MDy!MTEMP" /* The temperature sensor configured in MTEMP mode on the multiplexed module in slot y of the chassis with ID x. */
- "OB1!SCx!MDy!DTEMP" /* The temperature sensor configured in DTEMP mode on the parallel module in slot y of the chassis with ID x. */
- "OB0!SCx!MDy!CALGND" /* (SCXI-1100 and SCXI-1122 only) The grounded amplifier of the module in slot y of the chassis with ID x. */
- "OB0!SCx!MDy!SHUNTO" /* (SCXI-1121, SCXI-1122 and SCXI-1321 only) Channel 0 of the module in slot y of the chassis with ID x, with the shunt resistor applied. */
- "OB0!SCx!MDy!SHUNT0:3" /* (SCXI-1121, SCXI-1122 and SCXI-1321 only) Channel 0 through 3 of the module in slot y of the chassis with ID x, with the shunt resistors applied at each channel. */

Command Strings

You can use command strings within the channel string to set per-channel limits and an interchannel sample rate. For example,

"cmd hi 10.0 low -10.0; 7:4; cmd hi 5.0 low -5.0; 3:0"

specifies that channels 7 through 4 should be scanned with limits of +/-10.0 volts and channels 3 through 0 should be scanned with limits of +/-5.0 volts. As you view the channel string from left to right, each high/low limit command applies to the channels that

follow it until the next high/low limit command is encountered. The **highLimit** and **lowLimit** parameters to AISampleChannels are the initial high/low limits, which apply to channels in the channel string to the left of the first high/low limit command.

The channel string

"cmd interChannelRate 1000.0; 0:3"

specifies that channels 0 through 3 should be sampled at 1,000.0 Hz. In other words, there should be 1/1,000.0 = 1 ms of delay between each channel. If you do not set an interchannel sample rate, the channels are sampled as fast as possible for your hardware to achieve pseudo-simultaneous scanning.

The following guide describes the syntax for the command string:

- Items enclosed in [] are optional.
- <number> is an integer or real number.
- <LF> is a linefeed character.
- ; | <LF> means you can use either ; or <LF> to separate command strings from channel strings.
- You can use ! as an optional command separator.
- Spaces are optional.

The following example specifies the syntax for the initial command string that appears before any channel:

The following example specifies the syntax for command strings that appear after any channel:

```
"; \LF> cmd hi <number>[!] low <number>[!] ; \LF>"
```

Channel String for Analog Output Functions

The second parameter to most of the analog output functions is the channel string that contains the analog output channels to drive.

Refer to the chapter specific to your DAQ device in the *DAQ Hardware Overview Guide* to determine what channels are valid for your hardware. The document is an Adobe Acrobat file, daqhwov.pdf, that you can view on screen or print. daqhwov.pdf is part of a set of .pdf files that National Instruments includes with every DAQ device the company sells.

The following examples explain the syntax for the channel string:

• If you are using a DAQ device without SCXI, list the channels to drive, as in the following example:

```
"0,2,5" /* drives channels 0, 2, and 5 */
"0:3" /* drives channels 0 through 3 inclusive */
```

• If you are using SCXI, you can address SCXI channels when you attach one or more SCXI chassis to a plug-in data acquisition board by using the following SCXI channel syntax:

```
"SCx!MDy!a" /* Channel a on the module in slot y of the chassis
with ID x. */
"SCx!MDy!a:b" /* Channels a through b inclusive on the module in
slot y of the chassis with ID x. */
```

SCXI channel ranges cannot cross module boundaries and must always increase in channel number.

Valid Counters for the Counter/Timer Functions

The second parameter to most of the counter/timer functions is the counter the functions use for the operation. The valid counters you can use depends on your hardware, as shown in Table 10-2.

Device Type	Valid Counters
DAQ-STC Devices	0 and 1
Am9513 MIO boards	1, 2, and 5
PC-TIO-10	1-10
EISA-A2000	2

Table 10-2. Valid Counters

Easy I/O for DAQ Function Reference

This section describes each function in the Easy I/O for DAQ Library in alphabetical order.

AIAcquireTriggeredWaveforms

Purpose

Performs a timed acquisition of voltage data from the analog channels you specify in **channelString**. The acquisition does not start until the trigger conditions are satisfied.

If you have an E Series DAQ device, you can select Equivalent Time Sampling for **triggerType** to sample repetitive waveforms at up to 20 MHz. Refer to the following *Parameter Discussion* section for more information.

Parameters

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
channelString	string	Analog input channels to sample.
numberOfScans	long integer	Number of scans to acquire. One scan involves sampling every channel in channelString once.
scansPerSecond	double	Number of scans performed per second. The function samples each channel at this rate.
highLimit	double	Maximum value to measure.
lowLimit	double	Minimum value to measure.
triggerType	unsigned short integer	Trigger type.
edgeSlope	unsigned short integer	Edge/slope condition for triggering.
triggerLevel	double	Value at which the trigger is to occur.

Input

Name	Туре	Description
triggerSource	string	Specifies which channel is the trigger source.
pretriggerScans	long integer	Specifies the number of scans to retrieve before the trigger point.
timeLimitsec	double	Maximum length of time in seconds to wait for the data.
fillMode	short integer	Specifies whether the waveforms array is in GROUP_BY_CHANNEL or GROUP_BY_SCAN mode.

Output

Name	Туре	Description
actualScanRate	double	Actual scan rate. The actual scan rate might differ slightly from the scan rate you specified, given the limitations of your particular DAQ device.
waveforms	double array	Array that contains the values acquired on the channels you specify in channelString .

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

channelString is the analog input channel to sample. Refer to the *Channel String for Analog Input Functions* section of the *Easy I/O for DAQ Library Function Overview* section of this chapter for the syntax of this string.

triggerType is the trigger type. Table 10-3 lists trigger types.

Trigger Type	Constant Name
Hardware Analog Trigger	HW_ANALOG_TRIGGER
Digital Trigger A	DIGITAL_TRIGGER_A
Digital Triggers A & B	DIGITAL_TRIGGER_AB
Scan Clock Gating	SCAN_CLOCK_GATING
Software Analog Trigger	SW_ANALOG_TRIGGER
Equivalent Time Sampling	ETS_TRIGGER

Tahle	10-3	Trigger	Types
Table	10-0.	шууы	Types

If you choose Hardware or Software Analog Trigger, AIAcquireTriggeredWaveforms retrieves data after the analog triggering parameters are satisfied. Be sure that **triggerSource** is one of the channels the channel string lists. Hardware triggering is more accurate than software triggering, but it is not available on all boards.

If you choose Digital Trigger A, the trigger starts the acquisition if **pretriggerScans** is 0. For the MIO-16, connect the digital trigger signal to the STARTTRIG input. If **pretriggerScans** is greater than 0, the trigger stops the acquisition after all posttrigger data is acquired. For the MIO-16, connect the digital trigger signal to the STOPTRIG input.

If you choose Digital Trigger A & B, **pretriggerScans** must be greater than 0. A digital trigger starts the acquisition and a digital trigger stops the acquisition after all posttrigger data is acquired. For the MIO-16, the STARTTRIG input starts the acquisition and the STOPTRIG input stops the acquisition.

If you choose Scan Clock Gating, an external signal gates the scan clock on and off. If the scan clock gate becomes FALSE, the current scan completes, and the scan clock ceases operation. When the scan clock gate becomes TRUE, the scan clock immediately begins operation again.

If you choose Equivalent Time Sampling, you use the Equivalent Time Sampling technique on an E Series DAQ device to achieve an effective acquisition rate of up to 20 MHz, with the following conditions:

- The signal that you measure must be a periodic waveform.
- The trigger conditions must be satisfied or AIAcquireTriggeredWaveforms times out.

Equivalent Time Sampling is the process of taking A/D conversions from a periodic waveform at special points in time such that when the A/D conversions are placed side by side, they represent the original waveform as if it were sampled at a high frequency.

For example, if the A/D conversions, represented by x's, on the waveform shown in Figure 10-1 are placed side by side, they represent one cycle of the waveform.

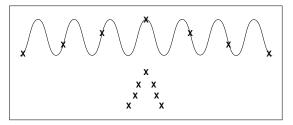


Figure 10-1. One Cycle of a Waveform

AIAcquireTriggeredWaveforms accomplishes Equivalent Time Sampling as follows:

- You set a hardware analog trigger condition for measuring your waveform using edgeSlope, triggerLevel, and triggerSource.
- Whenever a hardware analog trigger occurs, AIAcquireTriggeredWaveforms strobes the internal ATCOUT signal.
- AIAcquireTriggeredWaveforms internally routes the ATCOUT signal to the gate of GPCTR0, which is configured to generate a pulse each time it receives a rising edge at its gate input.
- The function then internally routes the output of GPCTR0 to the data acquisition sample clock to control the A/D conversion rate.
- You can achieve a very high effective scan rate through a pre-pulse delay that is programmed into GPCTR0. This delay automatically increments before each GPCTR0 pulse so that the A/D conversions occur at slightly larger intervals from the trigger condition as trigger conditions occur over time.
- Because the waveform being measured is periodic, A/D conversions that are at particular intervals from trigger conditions over time can look the same as A/D conversions at particular intervals from one unique trigger point in time, as shown in Figure 10-2 and Figure 10-3.

In Figure 10-2:

tn = nth trigger condition dn = delay between the nth trigger and the nth conversion x = an A/D conversion --- = the trigger level

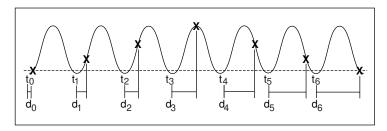


Figure 10-2. Converting a Signal at Periodic Intervals

When the A/D conversions are placed side by side, they represent the original waveform as if it were sampled at a high frequency.

Figure 10-3. Resulting Waveform That Resembles Original Waveform

edgeSlope specifies whether the trigger occurs when the trigger signal value is leading, POSITIVE_SLOPE, or trailing, NEGATIVE_SLOPE.

triggerLevel specifies the value at which the trigger is to occur. **triggerLevel** is valid only when **triggerType** is hardware or software analog trigger.

triggerSource specifies which channel the trigger source is. **triggerSource** must be one of the channels **channelString** lists. If you pass "" or NULL, the function uses the first channel in **channelString** as **triggerSource**. **triggerSource** is valid only when **triggerType** is hardware or software analog trigger.

timeLimitsec is the maximum length of time in seconds to wait for the data. If the time you set expires, AIAcquireTriggeredWaveforms returns a timeout error (timeOutErr = -10800). A value of -2.0 disables the time limit.

\triangle

Caution Disabling the time limit leaves your program in a suspended state until the trigger condition occurs.

A value of -1.0 (default) for **timeLimitsec** lets the function calculate the timeout based on the acquisition rate and number of scans you request.

fillMode specifies whether the **waveforms** array is grouped by channels or grouped by scans. Consider the following examples:

• If you scan channels A through C and **numberOfScans** is 5, the possible fill modes are as follows:

GROUP_BY_CHANNEL

A1 A2 A3 A4 A5 B1 B2 B3 B4 B5 C1 C2 C3 C4 C5

GROUP_BY_SCAN

A1 B1 C1 A2 B2 C2 A3 B3 C3 A4 B4 C4 A5 B5 C5

- If you pass the array to a graph, acquire the data grouped by channel.
- If you pass the array to a strip chart, acquire the data grouped by scan.
- You can acquire the data grouped by scan and later reorder it to be grouped by channel using GroupByChannel.

waveforms is an array that contains the values acquired on the channels you specify in the **channelString**. AIAcquireTriggeredWaveforms places the acquired values into the array in the order **fillMode** specifies. This array must be declared as large as (number of channels) \times (**numberOfScans**). You can determine the number of channels using GetNumChannels.

If you set **highLimit** and **lowLimit** to 0.0, this function uses the default limits, which are defined as follows:

- For channels you configure in the DAQ Channel Wizard, the default limits are set in the Physical Quantity section of the DAQ Channel Wizard.
- For hardware channels, the default limits are set in the AI section of NI-DAQ Configuration Utility.

AIAcquireWaveforms

Purpose

Performs a timed acquisition of voltage data from the analog channels you specify in **channelString**.

Parameters

Input

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
channelString	string	Analog input channels to sample.
numberOfScans	long integer	Number of scans to acquire. One scan involves sampling every channel in channelString once.
scansPerSecond	double	Number of scans performed per second. The function samples each channel at this rate.
highLimit	double	Maximum value to measure.
lowLimit	double	Minimum value to measure.
fillMode	short integer	Specifies whether the waveforms array is in GROUP_BY_CHANNEL or GROUP_BY_SCAN mode.

Name	Туре	Description
actualScanRate	double	Actual scan rate. The actual scan rate might differ slightly from the scan rate you specified, given the limitations of your particular DAQ device.
waveforms	double array	Array that contains the values acquired on the channels you specify in the channelString .

Output

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

channelString is the analog input channel to sample. Refer to the *Channel String for Analog Input Functions* section of the *Easy I/O for DAQ Library Function Overview* section of this chapter for the syntax of this string.

fillMode specifies whether the **waveforms** array is grouped by channels or grouped by scans. Consider the following examples:

• If you scan channels A through C and **numberOfScans** is 5, the possible fill modes are as follows:

GROUP_BY_CHANNEL

A1 A2 A3 A4 A5 B1 B2 B3 B4 B5 C1 C2 C3 C4 C5

GROUP_BY_SCAN

A1 B1 C1 A2 B2 C2 A3 B3 C3 A4 B4 C4 A5 B5 C5

- If you pass the array to a graph, acquire the data grouped by channel.
- If you pass the array to a strip chart, acquire the data grouped by scan.
- You can acquire the data grouped by scan and later reorder it to be grouped by channel using GroupByChannel.

waveforms is an array that contains the values acquired on the channels you specify in the **channelString**. AIAcquireWaveforms places the acquired values into the array in the order **fillMode** specifies. This array must be declared as large as (number of channels) \times (**numberOfScans**). You can determine the number of channels using GetNumChannels.

If you set **highLimit** and **lowLimit** to 0.0, this function uses the default limits, which are defined as follows:

- For channels you configure in the DAQ Channel Wizard, the default limits are set in the Physical Quantity section of the DAQ Channel Wizard.
- For hardware channels, the default limits are set in the AI section of NI-DAQ Configuration Utility.

AICheckAcquisition

Purpose

Determines the backlog of scans that have been acquired into the circular buffer but that you have not read using AIReadAcquisition.

If you call AIReadAcquisition with read mode set to LATEST_MODE, AICheckAcquisition resets scanBacklog to zero.

Parameters

Input

Name	Туре	Description
taskID	unsigned long integer	Task ID that AIStartAcquisition returns.

Output

Name	Туре	Description
scanBacklog	unsigned long integer	Returns the backlog of scans that have been acquired into the circular buffer but that you have not read using AIReadAcquisition.

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

AIClearAcquisition

```
short error = AIClearAcquisition (unsigned long taskID);
```

Purpose

Clears the current asynchronous acquisition that AIStartAcquisition started.

Parameter

Input

Name	Туре	Description
taskID	unsigned long integer	Task ID that AIStartAcquisition returns.

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

AIReadAcquisition

Purpose

Reads the specified number of scans from the internal circular buffer established by AIStartAcquisition.

If the specified number of scans is not available in the buffer, the function waits until the scans are available. You can call AICheckAcquisition before calling AIReadAcquisition to determine how many scans are available.

Parameters

Input

Name	Туре	Description
taskID	unsigned long integer	Task ID that AIStartAcquisition returns.
scanstoRead	long integer	Number of scans to read from the internal circular buffer.
readMode	unsigned short integer	Specifies whether to read scans from the circular buffer in CONSECUTIVE_MODE or LATEST_MODE.
fillMode	short integer	Specifies whether the waveforms array is in GROUP_BY_CHANNEL or GROUP_BY_SCAN mode.

Output

Name	Туре	Description
scanBacklog	unsigned long integer	Returns the backlog of scans that have been acquired into the circular buffer but that you have not read using AIReadAcquisition.
waveforms	double array	Array that contains the values acquired on the channels you specify in the channelString .

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

readMode specifies whether AIReadAcquisition reads scans from the circular buffer in CONSECUTIVE_MODE or LATEST_MODE. In CONSECUTIVE_MODE, the function reads scans from the internal circular buffer starting from the last scan that you read. Using this mode, you are guaranteed not to lose data unless an error occurs. In LATEST_MODE, AIReadAcquisition reads the most recently acquired *n* scans from the internal circular buffer, where *n* is **scanstoRead**. Calling AIReadAcquisition in this mode resets the **scanBacklog** to zero.

scanBacklog returns the backlog of scans that have been acquired into the circular buffer but that you have not read using AIReadAcquisition. You can call AICheckAcquisition to determine the scan backlog before you call AIReadAcquisition.

waveforms is an array that contains the values acquired on the channels you specify in the **channelString**. AIReadAcquisition places the acquired values into the array in the order **fillMode** specifies.

This array must be declared as large as (number of channels) \times (scanstoRead). You can determine the number of channels using GetNumChannels.

AlSampleChannel

Purpose

Acquires a single voltage from a single analog input channel.

Parameters

Input

Name	Туре	Description
device	short integer	Assigned by the NI-DAQ configuration utility.
singleChannel	string	Analog input channel to sample.
highLimit	double	Maximum value to measure.
lowLimit	double	Minimum value to measure.

Output

Name	Туре	Description
sample	double (passed by reference)	The measured value.

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

singleChannel is the analog input channel to sample. Refer to the *Channel String for Analog Input Functions* section of the *Easy I/O for DAQ Library Function Overview* section of this chapter for the syntax of this string.

If you set **highLimit** and **lowLimit** to 0.0, this function uses the default limits, which are defined as follows:

- For channels you configure in the DAQ Channel Wizard, the default limits are set in the Physical Quantity section of the DAQ Channel Wizard.
- For hardware channels, the default limits are set in the AI section of NI-DAQ Configuration Utility.

AISampleChannels

Purpose

Performs a single scan on a set of analog input channels.

Parameters

Input

Name	Туре	Description
device	short integer	Assigned by the NI-DAQ configuration utility.
channelString	string	Analog input channels to sample.
highLimit	double	Maximum value to measure.
lowLimit	double	Minimum value to measure.

Output

Name	Туре	Description
sampleArray	double array	Array that contains the values acquired on the channels you specify in channelString .

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

channelString is the Analog input channels to sample. Refer to the *Channel String for Analog Input Functions* section of the *Easy I/O for DAQ Library Function Overview* section of this chapter for the syntax of this string.

sampleArray is an array that contains the values acquired on the channels you specify in **channelString**. AlSampleChannels places the acquired values into the array in the order you specify in **channelString**. This array must be declared as large as the number of channels you specify in **channelString**.

You can use GetNumChannels to determine the number of channels.

If you set **highLimit** and **lowLimit** to 0.0, this function uses the default limits, which are defined as follows:

- For channels you configure in the DAQ Channel Wizard, the default limits are set in the Physical Quantity section of the DAQ Channel Wizard.
- For hardware channels, the default limits are set in the AI section of NI-DAQ Configuration Utility.

AIStartAcquisition

Purpose

Starts a continuous asynchronous acquisition on the analog input channels you specify in **channelString**. AIStartAcquisition acquires data into an internal circular buffer. Use AIReadAcquisition to retrieve scans from the internal buffer.

Parameters

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
channelString	string	Analog input channels to sample.
bufferSize	integer	Size of the internal circular buffer in scans.
scansPerSecond	double	Number of scans performed per second. The function samples each channel at this rate.
highLimit	double	Maximum value to measure.
lowLimit	double	Minimum value to measure.

Input

Output

Name	Туре	Description
actualScanRate	double	Actual scan rate. The actual scan rate might differ slightly from the scan rate you specified, given the limitations of your particular DAQ device.
taskID	unsigned long integer	Identifier for the asynchronous acquisition.

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

channelString is the Analog input channels to sample. Refer to the *Channel String for Analog Input Functions* section of the *Easy I/O for DAQ Library Function Overview* section of this chapter for the syntax of this string.

taskID is an identifier for the asynchronous acquisition that you must pass to AICheckAcquisition, AIReadAcquisition, and AIClearAcquisition.

If you set **highLimit** and **lowLimit** to 0.0, this function uses the default limits, which are defined as follows:

- For channels you configure in the DAQ Channel Wizard, the default limits are set in the Physical Quantity section of the DAQ Channel Wizard.
- For hardware channels, the default limits are set in the AI section of NI-DAQ Configuration Utility.

AOClearWaveforms

short error = AOClearWaveforms (unsigned long taskID);

Purpose

Clears the waveforms AOGenerateWaveforms generates when you pass 0 for Iterations.

Parameter

Input

Name	Туре	Description
taskID	unsigned long integer	Task ID AOGenerateWaveforms returns.

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

AOGenerateWaveforms

Purpose

Generates a timed waveform of voltage data on the analog output channels you specify in **channelString**.

Parameters

Input

Name	Туре	Description
device	short integer	Assigned by the NI-DAQ configuration utility.
channelString	string	The analog output channels to apply the voltages to.
updatesPerSecond	double	Number of updates to perform per second. The function updates each channel at this rate.
updatesPerChannel	integer	Number of D/A conversions that compose a waveform for a particular channel.
iterations	integer	Number of waveform iterations to perform before the operation is complete; 0 = continuous.

Output

Name	Туре	Description
waveforms	double array	Voltages to apply to the channels you specify in channelString .
taskID	unsigned long integer	Identifier for the waveform generation. If you pass 0 as the iterations parameter, you need to pass taskID to AOClearWaveforms to clear the waveform generation.

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

channelString is the analog output channels to apply the voltages to. Refer to the *Channel String for Analog Output Functions* section of the *Easy I/O for DAQ Library Function Overview* section of this chapter for the syntax of this string.

updatesPerChannel is the number of D/A conversions that compose a waveform for a particular channel. If **updatesPerChannel** is 10, each waveform is composed of 10 elements from the **waveforms** array.

iterations is the number of waveform iterations performed before the operation is complete. If you pass 0, AOGenerateWaveforms generates the waveform(s) continuously and you need to call AOClearWaveforms to clear waveform generation.

waveforms is the array that contains the voltages to apply to the channels you specify in **channelString**. The voltages are applied to the analog output channels in the order you specify in **channelString**. For example, if **channelString** is

"0:3,5",

the array contains the voltages in the following order:

```
waveforms[0]
                 /* the 1st update on channel 0 */
waveforms[1]
                 /* the 1st update on channel 1 */
                /* the 1st update on channel 2 */
waveforms[2]
                 /* the 1st update on channel 3 */
waveforms[3]
waveforms[4]
                 /* the 1st update on channel 5 */
waveforms[5]
                 /* the 2nd update on channel 0 */
waveforms[6]
                /* the 2nd update on channel 1 */
                /* the 2nd update on channel 2 */
waveforms[7]
                /* the 2nd update on channel 3 */
waveforms[8]
waveforms[9]
                 /* the 2nd update on channel 5 */
waveforms[n-5]
               /* the last update on channel 0 */
                /* the last update on channel 1 */
waveforms[n-4]
waveforms[n-3]
                /* the last update on channel 2 */
                /* the last update on channel 3 */
waveforms[n-2]
waveforms[n-1]
                /* the last update on channel 5 */
```

AOUpdateChannel

Purpose

Applies the voltage you specify to a single analog output channel.

Parameters

Input

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
singleChannel	string	Analog output channel to which the voltage is applied.
voltage	double	Voltage applied to the analog output channel.

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

singleChannel is the analog output channel to which the voltage is applied. Refer to the *Channel String for Analog Output Functions* section of the *Easy I/O for DAQ Library Function Overview* section of this chapter for the syntax of this string.

AOUpdateChannels

Purpose

Applies the voltages you specify in **voltageArray** to the analog output channel you specify in **channelString**.

Parameters

Input

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
channelString	string	Analog output channels to which the voltages are applied.
voltageArray	double array	Voltages applied to the analog output channels you specify.

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

channelString is the analog output channels to which the voltages are applied. Refer to the *Channel String for Analog Output Functions* section of the *Easy I/O for DAQ Library Function Overview* section of this chapter for the syntax of this string.

voltageArray is

the voltages that are applied to the analog output channels you specify. This array contains the voltages to apply to the analog output channels in the order that you specify in **channelString**. For example, if **channelString** contains:

"0,1,3"

then:

```
voltage[0] = 1.2; /* 1.2 volts applied to channel 0 */
voltage[1] = 2.4; /* 2.4 volts applied to channel 1 */
voltage[2] = 3.6; /* 3.6 volts applied to channel 3 */
```

ContinuousPulseGenConfig

Purpose

Configures a counter to generate a continuous Transistor-Transistor Logic (TTL) pulse train on its OUT pin.

ContinuousPulseGenConfig creates the signal by repeatedly decrementing the counter twice, first for the delay to the pulse, phase 1, then for the pulse itself, phase 2. The function selects the highest resolution timebase to achieve the desired characteristics.

You can gate or trigger the operation with a signal on the counter GATE pin. Call CounterStart to start the operation or to enable the gate or trigger action.

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility
counter	string	Counter to use for the counting operation.
frequency	double	Desired repetition rate of the continuous pulse train.
dutyCycle	double	Desired ratio of the duration of the pulse phase, phase 2, to the period, (phase 1 + phase 2).
gateMode	unsigned short integer	Specifies how to use the signal on the counter GATE pin.
pulsePolarity	unsigned short integer	Polarity of phase 2 of each cycle.

Parameters

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Name	Туре	Description
actualFrequency	double	Achieved frequency based on the resolution and range of your hardware.
actualDutyCycle	double	Achieved duty cycle based on the resolution and range of your hardware.
taskID	unsigned long integer	Reference number assigned to this operation. You pass taskID to CounterStart, CounterRead, and CounterStop.

Output

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

counter is the counter to use for the counting operation. For valid counters, refer to Table 10-2 in the *Valid Counters for the Counter/Timer Functions* section of the *Easy I/O for DAQ Library Function Overview* section of this chapter.

dutyCycle is the desired ratio of the duration of the pulse phase, phase 2, to the period, phase 1 + phase 2. The default of 0.5 generates a square wave.

- If **dutyCycle** = 0.0, ContinuousPulseGenConfig computes the closest achievable duty cycle using a minimum pulse phase, phase 2, of three timebase cycles.
- If **dutyCycle** = 1.0, ContinuousPulseGenConfig computes the closest achievable duty cycle using a minimum delay phase, phase 1, of three timebase cycles.
- A duty cycle very close to 0.0 or 1.0 might not be possible.

gateMode specifies how to use the signal on the counter GATE pin. You can use the following options:

- UNGATED_SOFTWARE_START—Ignore the gate signal and start when you call CounterStart.
- COUNT_WHILE_GATE_HIGH—Count while the gate signal is TTL high after you call CounterStart.
- COUNT_WHILE_GATE_LOW—Count while the gate signal is TTL low after you call CounterStart.

- START_COUNTING_ON_RISING_EDGE—Start counting on the rising edge of the TTL gate signal after you call CounterStart.
- START_COUNTING_ON_FALLING_EDGE—Start counting on the falling edge of the TTL gate signal after you call CounterStart.

pulsePolarity is the polarity of phase 2 of each cycle. You can use the following options:

- POSITIVE_POLARITY—The delay, phase 1, is a low TTL level, and the pulse, phase 2, is a high level.
- NEGATIVE_POLARITY—The delay, phase 1, is a high TTL level, and the pulse, phase 2, is a low level.

CounterEventOrTimeConfig

Purpose

Configures one or two counters to count edges in the signal on the counter SOURCE pin you specify or the number of cycles of an internal timebase signal you specify.

When you use CounterEventOrTimeConfig with the internal timebase and in conjunction with CounterStart and CounterRead, your program can make more precise timing measurements than with Timer.

You can gate or trigger the operation with a signal on the counter GATE pin. Call CounterStart to start the function or to enable the gate or trigger action.

Parameters

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
counter	string	Counter to use for the counting operation.
counterSize	unsigned short integer	Determines the size of the counter used to perform the operation.
sourceTimebase	double	Use USE_COUNTER_SOURCE to count TTL edges at the counter SOURCE pin or supply a valid internal timebase frequency to count the TTL edges of an internal clock.
countLimitAction	unsigned short integer	Action to take when the counter reaches terminal count.
sourceEdge	short integer	Edge of the counter source or timebase signal on which it increments.
gateMode	unsigned short integer	Specifies how to use the signal on the counter GATE pin.

Input

Name	Туре	Description
taskID	unsigned long integer	Reference number assigned to this counter operation. You pass taskID to CounterStart, CounterRead, and CounterStop.

Output

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

counter is the counter to use for the counting operation. For valid counters, refer to Table 10-2 in the *Valid Counters for the Counter/Timer Functions* section of the *Easy I/O for DAQ Library Function Overview* section of this chapter.

counterSize determines the size of the counter CounterEventOrTimeConfig uses to perform the operation. For a device with DAQ-STC counters, **counterSize** must be ONE_COUNTER (24-bit). For a device with Am9513 counters, **counterSize** can be ONE_COUNTER (16-bit) or TWO_COUNTERS (32-bit). If you use TWO_COUNTERS, **counter**+1 is cascaded with the counter you specify. Table 10-4 defines **counter**+1.

counter	counter+1
1	2
2	3
3	4
4	5
5	1
6	7
7	8
8	9
9	10
10	6

Table 10-4. Definition of Am9513: Counter+1

sourceTimebase determines whether the counter uses its SOURCE pin or an internal timebase as its signal source. Pass USE_COUNTER_SOURCE to count TTL edges at the counter SOURCE pin or pass a valid internal timebase frequency to count the TTL edges of an internal clock.

Table 10-5 shows valid internal timebase frequencies are:

Frequency	Chip Type on DAQ Board
1,000,000	Am9513
100,000	Am9513
10,000	Am9513
1,000	Am9513
100	Am9513
20,000,000	DAQ-STC
100,000	DAQ-STC

 Table 10-5.
 Valid Internal Timebase Frequencies

countLimitAction is the action to take when the counter reaches terminal count and accepts the following attributes:

- COUNT_UNTIL_TC—Count until terminal count and set the overflow status when it is reached. This mode is not available on the DAQ-STC.
- COUNT_CONTINUOUSLY—Count continuously. The Am9513 does not set the overflow status at terminal count, but the DAQ-STC does.

sourceEdge is the edge of the counter source or timebase signal on which it increments and accepts COUNT_ON_RISING_EDGE and COUNT_ON_FALLING_EDGE as values.

gateMode specifies how to use the signal on the counter GATE pin. You can use the following options:

- UNGATED_SOFTWARE_START—Ignore the gate signal and start when you call CounterStart.
- COUNT_WHILE_GATE_HIGH—Count while the gate signal is TTL high after you call CounterStart.
- COUNT_WHILE_GATE_LOW—Count while the gate signal is TTL low after you call CounterStart.

- START_COUNTING_ON_RISING_EDGE—Start counting on the rising edge of the TTL gate signal after you call CounterStart.
- START_COUNTING_ON_FALLING_EDGE—Start counting on the falling edge of the TTL gate signal after you call CounterStart.

CounterMeasureFrequency

Purpose

Measures the frequency of a TTL signal on the counter SOURCE pin you specify by counting rising edges of the signal during a period of time you specify. In addition to this connection, you also must wire the counter GATE pin to the OUT pin of **counter**–1. Table 10-6 defines **counter**, **counter**–1 and **counter**+1.

Chip	counter-1	counter	counter+1
Am9513	5	1	2
	1	2	3
	2	3	4
	3	4	5
	4	5	1
	10	6	7
	6	7	8
	7	8	9
	8	9	10
	9	10	6
DAQ-STC	1	0	1
	0	1	0

Table 10-6. Adjacent Counters

CounterMeasureFrequency is useful for relatively high frequency signals when many cycles of the signal occur during the timing period. Use

PulseWidthOrPeriodMeasConfig for relatively low-frequency signals. Remember that

period = 1/frequency

CounterMeasureFrequency configures **counter** and **counter**+1 (optional) to be event counters that count rising edges of the signal on the counter SOURCE pin. The function also configures **counter**-1 to generate a minimum-delayed pulse to gate the event counter, starts the event counter and then the gate counter, waits the expected gate period, and reads the gate counter until its output state is low. CounterMeasureFrequency then reads the event counter and computes the signal frequency, number of events/actual gate pulse width, and stops the counters. You can also gate or trigger the operation with a signal on the **counter**-1 GATE pin.

Parameters

Input

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
counter	string	Counter to use for the counting operation.
counterSize	unsigned short integer	Determines the size of the counter to use to perform the operation: ONE_COUNTER or TWO_COUNTERS.
gateWidthSampleTimeinSec	double	Desired length of the pulse to use to gate the signal. The lower the signal frequency, the longer the gate width must be.
maxDelayBeforeGateSec	double	Maximum expected delay between the time you call the function and the start of the gating pulse. If the gate signal does not start in this time, a timeout occurs.
counterMinus1GateMode	unsigned short integer	Gate mode for counter –1.

Name	Туре	Description
actualGateWidthSec	double	Achieved length in seconds of the gating pulse.
overflow	short integer	 1 = counter rolled past terminal count 0 = counter did not roll past terminal count. If overflow is 1, the value of frequency is inaccurate.
valid	short integer	Set to 1 if the measurement completes without a counter overflow. A timeout and a valid measurement can occur at the same time. A timeout does not produce an error.
timeout	short integer	Set to 1 if the time limit expires during the function call. A timeout and a valid measurement can occur at the same time. A timeout does not produce an error.
frequency	double	Frequency of the signal, it is computed as (number of rising edges) / (actualGateWidthSec).

Output

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

counter is the counter to use for the counting operation. For valid counters, refer to Table 10-2 in the *Valid Counters for the Counter/Timer Functions* section of the *Easy I/O for DAQ Library Function Overview* section of this chapter.

counterSize determines the size of the counter to use to perform the operation. For a device with DAQ-STC counters, **counterSize** must be ONE_COUNTER (24-bit). For a device with Am9513 counters, **counterSize** can be ONE_COUNTER (16-bit) or TWO_COUNTERS (32-bit). If you use TWO_COUNTERS, **counter**+1 is cascaded with the specified counter. **counter**+1 is defined as shown in Table 10-6 in this function description.

counterMinus1GateMode is the gate mode for **counter**-1. The possible values are UNGATED_SOFTWARE_START, COUNT_WHILE_GATE_HIGH, COUNT_WHILE_GATE_LOW, and START_COUNTING_ON_RISING_EDGE

CounterMeasureFrequency uses **counter**-1 to gate **counter** so that rising edges are counted over a precise sample time. For a specified **counter**, **counter**-1 is defined as shown in Table 10-6 in this function description.

CounterRead

Purpose

Reads the counter taskID identifies.

Parameters

Input

Name	Туре	Description
taskID	unsigned long integer	Reference number assigned to the counting operation by one of the counter configuration functions.

Output

Name	Туре	Description
overflow	short integer	1 = counter rolled past terminal count 0 = counter did not roll past terminal count
count	long integer	Value of the counter at the time it is read.

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

overflow indicates whether the counter rolled over past its terminal count. If **overflow** is 1, the value of **count** is inaccurate.

CounterStart

short error = CounterStart (unsigned long taskID);

Purpose

Starts the counter **taskID** identifies.

Parameter

Input

Name	Туре	Description
taskID	unsigned long integer	Reference number assigned to the counting operation by one of the counter configuration functions.

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

CounterStop

short error = CounterStop (unsigned long taskID);

Purpose

Stops a count operation immediately.

Parameter

Input

Name	Туре	Description
taskID	unsigned long integer	Reference number assigned to the counting operation by one of the counter configuration functions.

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

DelayedPulseGenConfig

Purpose

Configures a counter to generate a delayed TTL pulse or triggered pulse train on its OUT pin.

DelayedPulseGenConfig creates the signal by decrementing the counter twice, first for the delay to the pulse, phase 1, then for the pulse itself, phase 2. DelayedPulseGenConfig selects the highest resolution timebase to achieve the desired characteristics.

You can gate or trigger the operation with a signal on the counter GATE pin. Call CounterStart to start the operation or to enable the gate or trigger action.

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
counter	string	Counter to use for the counting operation.
pulseDelay	double	Desired duration of the delay, phase 1, before the pulse.
pulseWidth	double	Desired duration of the pulse, phase 2, after the delay.
timebaseSource	unsigned short integer	Signal that causes the counter to count.
gateMode	unsigned short integer	Specifies how to use the signal on the counter GATE pin.
pulsePolarity	unsigned short integer	Polarity of phase 2 of each cycle.

Parameters

Input

Name	Туре	Description
actualDelay	double	Achieved delay based on the resolution and range of your hardware.
actualPulseWidth	double	Achieved pulse width based on the resolution and range of your hardware.
taskID	unsigned long integer	Reference number assigned to this operation. You pass taskID to CounterStart, CounterRead, and CounterStop.

Output

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

counter is the counter to use for the counting operation. For valid counters, refer to Table 10-2 in the *Valid Counters for the Counter/Timer Functions* section of the *Easy I/O for DAQ Library Function Overview* section of this chapter.

pulseDelay is the desired duration of the delay, phase 1, before the pulse. The unit is seconds if **timebaseSource** is USE_INTERNAL_TIMEBASE or cycles if **timebaseSource** is USE_COUNTER_SOURCE. If **pulseDelay** = 0.0 and **timebaseSource** is internal, DelayedPulseGenConfig selects a minimum delay of three cycles of the timebase you use.

pulseWidth is the desired duration of the pulse, phase 2, after the delay.

timebaseSource is the signal that causes the counter to count and can be one of the following values:

- USE_INTERNAL_TIMEBASE—DelayedPulseGenConfig selects an internal timebase based on the pulse delay and width, in units of seconds.
- USE_COUNTER_SOURCE—DelayedPulseGenConfig uses the signal on the counter SOURCE pin; the units of pulse delay and width are cycles of that signal.

gateMode specifies how to use the signal on the counter GATE pin. You can use the following options:

- UNGATED_SOFTWARE_START—Ignore the gate signal and start when you call CounterStart.
- COUNT_WHILE_GATE_HIGH—Count while the gate signal is TTL high after you call CounterStart.
- COUNT_WHILE_GATE_LOW—Count while the gate signal is TTL low after you call CounterStart.
- START_COUNTING_ON_RISING_EDGE—Start counting on the rising edge of the TTL gate signal after you call CounterStart.
- START_COUNTING_ON_FALLING_EDGE—Start counting on the falling edge of the TTL gate signal after you call CounterStart.
- RESTART_ON_EACH_RISING_EDGE—Restart counting on each rising edge of the TTL gate signal after you call CounterStart.
- RESTART_ON_EACH_FALLING_EDGE—Restart counting on each falling edge of the TTL gate signal after you call CounterStart.

pulsePolarity is the polarity of phase 2 of each cycle. You can use the following options:

- POSITIVE_POLARITY—The delay, phase 1, is a low TTL level, and the pulse, phase 2, is a high level.
- NEGATIVE_POLARITY—The delay, phase 1, is a high TTL level; and the pulse, phase 2, is a low level.

FrequencyDividerConfig

Purpose

Configures the counter you specify to count the number of signal transitions on its SOURCE pin or on an internal timebase signal and to strobe or toggle the signal on its OUT pin.

To divide an external TTL signal, connect it to the counter SOURCE pin and set the **sourceTimebase** parameter to USE_COUNTER_SOURCE.

To divide an internal timebase signal, set the **sourceTimebase** parameter to a desired valid frequency.

Set the **timebaseDivisor** to the desired value. For a value of n and a pulsed output, an output pulse equal to the period of the source or timebase signal appears on the counter OUT pin once for each n cycles of that signal. For a toggled output, the output toggles after each n cycles. The toggled output frequency is half that of the pulsed output.

If **gateMode** is not UNGATED_SOFTWARE_START, connect your gate signal to the counter GATE pin.

Parameters

Input

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
counter	string	Counter to use for the counting operation.
sourceTimebase	double	Use USE_COUNTER_SOURCE to count TTL edges at the counter SOURCE pin or supply a valid internal timebase frequency to count the TTL edges of an internal clock.
timebaseDivisor	double	Source frequency divisor.
gateMode	unsigned short integer	Specifies how to use the signal on the counter GATE pin.

Name	Туре	Description
outputBehavior	unsigned short integer	Behavior of the output signal when counter reaches terminal count.
sourceEdge	short integer	Edge of the counter source or timebase signal on which it decrements: COUNT_ON_RISING_EDGE or COUNT_ON_FALLING_EDGE.

Output

Name	Туре	Description
taskID	unsigned long integer	Reference number assigned to this operation. You pass taskID to
		CounterStart, CounterRead, and
		CounterStop.

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

counter is the counter to use for the counting operation. For valid counters, refer to Table 10-2 in the *Valid Counters for the Counter/Timer Functions* section of the *Easy I/O for DAQ Library Function Overview* section of this chapter.

sourceTimebase determines whether the counter uses its SOURCE pin or an internal timebase as its signal source. Pass USE_COUNTER_SOURCE to count TTL edges at the counter SOURCE pin or pass a valid internal timebase frequency to count the TTL edges of an internal clock.

Frequency	Chip Type on DAQ Board
1,000,000	Am9513
100,000	Am9513
10,000	Am9513
1,000	Am9513
100	Am9513
20,000,000	DAQ-STC
100,000	DAQ-STC

Table 10-7 shows valid internal timebase frequencies.

Table 10-7. Valid Internal Timebase Frequencies

timebaseDivisor is the source frequency divisor. For example, if the source signal is 1,000 Hz, the **timebaseDivisor** is 10, and the output is pulsed, the frequency of the counter OUT signal is 100 Hz. If the output is toggled, the frequency is 50 Hz.

gateMode specifies how to use the signal on the counter GATE pin. You can use the following options:

- UNGATED_SOFTWARE_START—Ignore the gate signal and start when you call CounterStart.
- COUNT_WHILE_GATE_HIGH—Count while the gate signal is TTL high after you call CounterStart.
- COUNT_WHILE_GATE_LOW—Count while the gate signal is TTL low after you call CounterStart.
- START_COUNTING_ON_RISING_EDGE—Start counting on the rising edge of the TTL gate signal after you call CounterStart.
- START_COUNTING_ON_FALLING_EDGE—Start counting on the falling edge of the TTL gate signal after you call CounterStart.

outputBehavior is the behavior of the output signal when counter reaches terminal count and can be one of the following values:

- HIGH_PULSE—High pulse that lasts one cycle of the source or timebase signal.
- LOW_PULSE—Low pulse that lasts one cycle of the source or timebase signal.
- HIGH_TOGGLE—High toggle that lasts until the next terminal count (TC).
- LOW_TOGGLE—Low toggle that lasting until the next TC.

For a Timebase Divisor of N and a pulsed output, an output pulse equal to the period of the source or timebase signal appears on the counter OUT pin once each N cycles of that signal For a toggled output, the output toggles after each N cycles. The toggled output frequency is thus half that of the pulsed output, in other words,

pulsedFrequency = sourceFrequency/N

and

toggledFrequency = sourceFrequency/ $(2 \times N)$

If N = 3, the OUT pin generates pulses as shown in Figure 10-4.

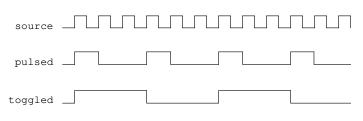


Figure 10-4. OUT Pin Pulses

GetAILimitsOfChannel

Purpose

Returns the high and low limits for a particular channel in the channel string.

Parameters

Input

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
channelString	string	Analog input channels to sample.
singleChannel	string	Single channel of the channel string.
initialHighLimit	double	Maximum value to measure for all channels that appear in the channel string before the first command string that specifies a new high limit.
initialLowLimit	double	Minimum value to measure for all channels that appear in the channel string before the first command string that specifies a new low limit.

Output

Name	Туре	Description
highLimit	double	Returns the high limit for the channel you specify.
lowLimit	double	Returns the low limit for the channel you specify.

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

channelString is the list of Analog input channels to sample. Refer to the *Channel String for Analog Input Functions* section of the *Easy I/O for DAQ Library Function Overview* section of this chapter for the syntax of this string.

singleChannel is a single channel of the channel string. For example, if the channel string is "0:3, 5" a single channel can be "2" or "5" and so on.

initialHighLimitVolts specifies the maximum voltage to measure for all channels that appear in the channel string before the first command string that specifies a new high limit. Consider the following channel string:

```
"0,1; cmd hi 10.0 low -10.0; 2,3"
```

If **initialHighLimitVolts** is 5.0, channels "0" and "1" have a high limit of 5.0 and channels "2" and "3" have a high limit of 10.0.

initialLowLimitVolts is the minimum voltage to measure for all channels that appear in the channel string before the first command string that specifies a new low limit. Consider the following channel string:

"0,1; cmd hi 10.0 low -10.0; 2,3"

If the **initialLowLimitVolts** is -5.0, channels "0" and "1" have a low limit of -5.0, and channels "2" and "3" have a low limit of -10.0.

GetChannelIndices

Purpose

Determines the indices of the channels in **channelSubString**. For example, if **channelString** is "1:6" and **channelSubString** is "1, 3, 6".

```
GetChannelIndices fills in the channelIndices array as follows:
channelIndices[0] = 0;
channelIndices[1] = 2;
channelIndices[2] = 5;
```

GetChannelIndices is useful if you want to verify that a particular channel is part of channelString.

Parameters

Input

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
channelString	string	Analog channel string.
channelSubString	string	Sub-string of channelString.
channelType	short integer	Specifies whether the channelString is ANALOG_INPUT or ANALOG_OUTPUT.

Output

Name	Туре	Description
channelIndices	long integer array	Returns the indices of the channels in the channelSubString .

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

channelString is the analog channels to sample. Refer to the *Channel String for Analog Input Functions* section of the *Easy I/O for DAQ Library Function Overview* section of this chapter for the syntax of this string.

channelSubString is a sub-string of the **channelString**. For example, if **channelString** is "0:3, 5" the sub-string can be "2" or "1, 3".

GetChannelNameFromIndex

Purpose

Determines the name of the particular channel in **channelString** that **index** indicates.

Parameters

Input

Name	Туре	Description
device	short integer	Assigned by the NI-DAQ configuration utility.
channelString	string	Analog input channels to sample.
index	long integer	Index of a particular channel in channelString .
channelType	short integer	Specifies whether the channelString is ANALOG_INPUT or ANALOG_OUTPUT.

Output

Name	Туре	Description
channelName	string	Returns the name of the particular channel in channelString that index .

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

channelString is the analog channels to sample. Refer to the *Channel String for Analog Input Functions* or *Channel String for Analog Output Functions* section of the *Easy I/O for DAQ Library Function Overview* section of this chapter for the syntax of this string.

channelName returns the name of the particular channel in **channelString** that **index** indicates. Declare this string to have MAX_CHANNEL_NAME_LENGTH bytes.

GetDAQErrorString

char *errorString = GetDAQErrorString (short errorNumber);

Purpose

Returns a string that contains the description for the numeric error code.

Parameter

Input

Name	Туре	Description
errorNumber	short integer	Error number an Easy I/O for DAQ function returns.

Name	Туре	Description
errorString	string	String that contains the description for the numeric error code.

GetNumChannels

Purpose

Determines the number of channels channelString contains.

You must know the number of channels in **channelString** so you can correctly interpret analog input waveform arrays or build analog output waveform arrays.

Parameters

Input

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
channelString	string	Analog channel string.
channelType	short integer	Specifies whether channelString is ANALOG_INPUT or ANALOG_OUTPUT.

Output

Name	Туре	Description
numberOfChannels	unsigned long integer	Returns the number of channels channelString contains.

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

channelString is the analog channels to sample. Refer to the *Channel String for Analog Input Functions* or *Channel String for Analog Output Functions* section of the *Easy I/O for DAQ Library Function Overview* section of this chapter for the syntax of this string.

GroupByChannel

Purpose

Reorders an array of data from GROUPED_BY_SCAN mode into GROUPED_BY_CHANNEL mode.

If you acquire data in GROUPED_BY_SCAN mode, you need to reorder the array into "grouped by channel" mode before you can pass it to graph plotting functions, analysis functions, and others.

Refer to the description of the **fillMode** parameter of AIAcquireWaveforms for an explanation of GROUPED_BY_SCAN versus GROUPED_BY_CHANNEL.

Parameters

Input/Output

Name	Туре	Description
array	double array	Pass in the GROUPED_BY_SCAN array. GroupByChannel groups the data by channel in place.

Input

Name	Туре	Description
numberOfScans	long integer	Number of scans the data array contains.
numberOfChannels	unsigned long integer	Specifies the number of channels that were scanned. You can use GetNumChannels to determine the number of channels your channel string contains.

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

ICounterControl

Purpose

Controls counters on devices that use the 8253 timer chip, such as Lab boards, SCXI-1200, DAQPad-1200, PC-LPM-16, and DAQCard 700.

Parameters

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
counter	short integer	Counter to control. Valid counters = 0–2.
controlCode	short integer	Determines the counter operating mode.
count	unsigned short integer	Period between output pulses.
binaryorBCD	short integer	I_BINARY = Counter operates as a 16-bit binary counter; 0–65,535 I_BCD = Counter operates as a 4-digit BCD counter; 0–9,999
outputState	short integer	I_HIGH_STATE = Output state of the counter is high I_LOW_STATE = Output state of the counter is low Matters only when controlCode = 7 (I_RESET).

Input

Output

Name	Туре	Description
readValue	unsigned short integer	Returns the value read from the counter when controlCode = 6 (I_READ).

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

controlCode determines the counter operating mode and accepts the following attributes:

- 0: I_TOGGLE_ON_TC—Counter output becomes low after the mode set operation and the counter decrements from **count** to 0 while the gate is high. The output toggles from low to high after the counter reaches 0.
- 1: I_PROGRAMMABLE_ONE_SHOT—Counter output becomes low on the count following the leading edge of the gate input and becomes high on terminal count.
- 2: I_RATE_GENERATOR—Counter output becomes low for one period of the clock input. count indicates the period between output pulses.
- 3: I_SQUARE_WAVE_RATE_GENERATOR—Counter output stays high for half the count clock pulses and stays low for the other half.
- 4: I_SOFTWARE_TRIGGERED_STROBE—Counter output is initially high, and the counter begins to count down while the gate input is high. On terminal count, the output becomes low for on clock pulse, then becomes high again.
- 5: I_HARDWARE_TRIGGERED_STROBE—Similar to mode 4 except that a rising edge at the gate input triggers the count to start.
- 6: I_READ—Reads the counter and returns the value in **readValue**.
- 7: I_RESET—Resets the counter and sets its output to **outputState**.

count is the period between output pulses and can be one of the following values:

- If **controlCode** is 0, 1, 4, or 5, **count** can be 0 through 65,535 in binary counter operation and 0 through 9,999 in binary-coded decimal (BCD) counter operation.
- If **controlCode** is 2 or 3, **count** can be 2 through 65,535 in binary counter operation and 2 through 9,999 in BCD counter operation.

Note 0 is equivalent to 65,536 in binary counter operation and 10,000 in BCD counter operation.

PlotLastAlWaveformsPopup

Purpose

Plots the last analog input (AI) waveform you acquired. It is intended for demonstration purposes.

You must group data by channel before you pass it to PlotLastAIWaveformsPopup. Use GROUP_BY_CHANNEL as **fillMode** when you acquire the data, or call GroupByChannel before you call this function.

Parameters

Input

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
waveformsBuffer	double array	Array that contains the last AI waveform acquired.

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

PulseWidthOrPeriodMeasConfig

Purpose

Configures the counter you specify to measure the pulse width or period of a TTL signal connected to its GATE pin. PulseWidthOrPeriodMeasConfig takes the measurement by counting the number of cycles of the timebase you specify between the appropriate starting and ending events.

Connect the signal you want to measure to the counter GATE pin.

To measure with an internal timebase, set sourceTimebase to the desired frequency.

To measure with an external timebase, connect that signal to the counter SOURCE pin and set **sourceTimebase** to USE_COUNTER_SOURCE.

Call CounterStart to start the measurement. Then call CounterRead to read the value. If the operation is valid, CounterRead returns a count greater than 3 in the **count** output parameter and returns 0 in the **overflow** output parameter.

Parameters

Input

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
counter	string	Counter to use for the counting operation.
typeOfMeasurement	unsigned short integer	Identifies the type of pulse width or period measurement to make.
sourceTimebase	double	Use USE_COUNTER_SOURCE to count TTL edges at the counter SOURCE pin or supply a valid internal timebase frequency to count the TTL edges of an internal clock.

Output

Name	Туре	Description
taskID	unsigned long integer	Reference number assigned to this counter operation. You pass taskID to CounterStart, CounterRead, and CounterStop.

Return Value

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

typeOfMeasurement identifies the type of pulse width or period measurement to make and accepts the following attributes:

- MEASURE_HIGH_PULSE_WIDTH—Measure high pulse width from rising to falling edge.
- MEASURE_LOW_PULSE_WIDTH—Measure low pulse width from falling to rising edge.
- MEASURE_PERIOD_BTW_RISING_EDGES—Measure period between adjacent rising edges.
- MEASURE_PERIOD_BTW_FALLING_EDGES—Measure period between adjacent falling edges.

sourceTimebase determines whether the counter uses its SOURCE pin or an internal timebase as its signal source. Pass USE_COUNTER_SOURCE to count TTL edges at the counter SOURCE pin or pass a valid internal timebase frequency to count the TTL edges of an internal clock.

Table 10-8 shows valid internal timebase frequencies and the corresponding chip types on a DAQ board.

Frequency	Chip Type on DAQ Board
1,000,000	Am9513
100,000	Am9513
10,000	Am9513
1,000	Am9513

Table 10-8. Valid Internal Timebase Frequencies

Frequency	Chip Type on DAQ Board
100	Am9513
20,000,000	DAQ-STC
100,000	DAQ-STC

 Table 10-8.
 Valid Internal Timebase Frequencies (Continued)

ReadFromDigitalLine

Purpose

Reads the logical state of a digital line on a port that you configure as input.

Parameters

Input

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
portNumber	string	Specifies the digital port ReadFromDigitalLine configures.
line	short integer	Specifies the individual bit or line within the port to use for I/O (zero-based).
portWidth	short integer	Total width in bits of the port.
configure	long integer	 1 = Configure the digital port before reading 0 = Do not configure the digital port before reading

Output

Name	Туре	Description
lineState	unsigned long integer	Returns the state of the digital line. 1 = logical high 0 = logical low

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

portNumber specifies the digital port ReadFromDigitalLine configures.

A **portNumber** value of 0 signifies port 0; a **portNumber** of 1 signifies port 1; and so on. If you use an SCXI-1160, SCXI-1161, SCXI-1162, or SCXI-1163 module, use the following syntax:

"SCx!MDy!0"

where x is the chassis ID and y is the module device number, to specify the port on a module.

portWidth is the total width in bits of the port. For example, you can combine two 4-bit ports into an 8-bit port on an MIO (non-E Series) board by setting **portWidth** to 8.

When **portWidth** is greater than the physical port width of a digital port, the following restrictions apply: The **portWidth** must be an integral multiple of the physical port width, and the port numbers in the combined port must begin with the port named by **portNumber** and must increase consecutively. For example, if **portNumber** is 3 and **portWidth** is 24 (bits), LabWindows/CVI uses ports 3, 4, and 5.

You must pass a **portWidth** of at least 8 for the 8255-based digital I/O ports, including all digital ports on Lab boards, SCXI-1200, DAQPad-1200, DAQCard-1200, DIO-24, DIO-32F, DIO-96, and AT-MIO-16DE-10/AT-MIO-16D ports 2, 3, and 4.

configure specifies whether to configure the digital port before reading.

When you call ReadFromDigitalLine in a loop, you can optimize it by configuring the digital port only on the first iteration.

When you configure a digital I/O port that is part of an 8255 PPI, including all digital ports on Lab boards, SCXI-1200, DAQPad-1200, DAQCard-1200, DIO-24, DIO-32F, DIO-96, and AT-MIO-16DE-10/AT-MIO-16D ports 2, 3, and 4, the 8255 PPI goes through a configuration phase in which all the ports within the same PPI chip are reset to logic low, regardless of the data direction. The data directions on other ports, however, are maintained.

ReadFromDigitalPort

Purpose

Reads a digital port that you configure for input.

Parameters

Input

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
portNumber	string	Specifies the digital port ReadFromDigitalPort configures.
portWidth	short integer	Total width in bits of the port.
configure	long integer	 1= Configure the digital port before reading 0 = Do not configure the digital port before reading

Output

Name	Туре	Description
pattern	unsigned long integer	Data read from the digital port.

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

portNumber specifies the digital port ReadFromDigitalPort configures.

A **portNumber** value of 0 signifies port 0; a **portNumber** of 1 signifies port 1; and so on. If you use an SCXI-1160, SCXI-1161, SCXI-1162, or SCXI-1163 module, use the following syntax:

"SCx!MDy!0"

where x is the chassis ID and y is the module device number, to specify the port on a module.

portWidth is the total width in bits of the port. For example, you can combine two 4-bit ports into an 8-bit port on an MIO (non-E Series) board by setting **portWidth** to 8.

When **portWidth** is greater than the physical port width of a digital port, the following restrictions apply: The **portWidth** must be an integral multiple of the physical port width, and the port numbers in the combined port must begin with the port named by **portNumber** and must increase consecutively. For example, if **portNumber** is 3 and **portWidth** is 24 (bits), LabWindows/CVI uses ports 3, 4, and 5.

You must pass a **portWidth** of at least 8 for the 8255-based digital I/O ports, including all digital ports on Lab boards, SCXI-1200, DAQPad-1200, DAQCard-1200, DIO-24, DIO-32F, DIO-96, and AT-MIO-16DE-10/AT-MIO-16D ports 2, 3, and 4.

configure specifies whether to configure the digital port before reading.

When you call ReadFromDigitalPort in a loop, you can optimize it by configuring the digital port only on the first iteration.

When you configure a digital I/O port that is part of an 8255 PPI, including all digital ports on Lab boards, SCXI-1200, DAQPad-1200, DAQCard-1200, DIO-24, DIO-32F, DIO-96, and AT-MIO-16DE-10/AT-MIO-16D ports 2, 3, and 4, the 8255 PPI goes through a configuration phase in which all the ports within the same PPI chip are reset to logic low, regardless of the data direction. The data directions on other ports, however, are maintained.

SetEasyIOMultitaskingMode

void SetEasyIOMultitaskingMode (int multitaskingMode);

Purpose

By default, if you call the non-timed Easy I/O for DAQ functions repetitively, LabWindows/CVI does not reconfigure the hardware unless you change the parameters. Thus, LabWindows/CVI improves the performance of these functions by reconfiguring the hardware only when necessary.

However, if you run multiple data acquisition programs simultaneously, the non-timed Easy I/O for DAQ functions do not know when the hardware has been reconfigured by another application that accesses the same DAQ device. Consequently, the functions might work incorrectly.

To get around this problem, you can force these functions to always reconfigure the hardware. You do this by setting the multitasking mode to MULTITASKING_AWARE.

You should set the multitasking mode to MULTITASK_AWARE if your program calls the non-timed Easy I/O for DAQ functions and you expect another data acquisition program to access the same board while your program runs. In this mode, the Easy I/O for DAQ functions always reconfigure the hardware on each invocation, which means they are not optimized for speed, but other applications cannot adversely affect them.

You should set the multitasking mode to MULTITASK_UNAWARE if you know no another program accesses the same DAQ device while your program runs.

Parameter

Input

Name	Туре	Description
multitaskingMode	integer	When set to a nonzero value, DAQ devices are reconfigured to default settings every time an Easy I/O for DAQ function invokes such devices.

Return Value

None.

WriteToDigitalLine

Purpose

Sets the output logic state of a digital line on a digital port.

Parameters

Input

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
portNumber	string	Specifies the digital port this function configures.
line	short integer	Specifies the individual bit or line within the port to use for I/O.
portWidth	short integer	Total width in bits of the port.
configure	long integer	 1= Configure the digital port before writing 0 = Do not configure the digital port before writing
lineState	unsigned long integer	Specifies the new state of the digital line. 1 = logical high 0 = logical low

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

portNumber specifies the digital port WriteToDigitalLine configures.

A **portNumber** value of 0 signifies port 0; a **portNumber** of 1 signifies port 1; and so on. If you use an SCXI-1160, SCXI-1161, SCXI-1162, or SCXI-1163 module, use the following syntax:

"SCx!MDy!0"

where x is the chassis ID and y is the module device number, to specify the port on a module.

portWidth is the total width in bits of the port. For example, you can combine two 4-bit ports into an 8-bit port on an MIO (non-E Series) board by setting **portWidth** to 8.

When **portWidth** is greater than the physical port width of a digital port, the following restrictions apply: the **portWidth** must be an integral multiple of the physical port width, and the port numbers in the combined port must begin with the port named by **portNumber** and must increase consecutively. For example, if **portNumber** is 3 and **portWidth** is 24 (bits), LabWindows/CVI uses ports 3, 4, and 5.

You must pass a **portWidth** of at least 8 for the 8255-based digital I/O ports, including all digital ports on Lab boards, SCXI-1200, DAQPad-1200, DAQCard-1200, DIO-24, DIO-32F, DIO-96, and AT-MIO-16DE-10/AT-MIO-16D ports 2, 3, and 4.

configure specifies whether to configure the digital port before writing.

When you call WriteToDigitalLine in a loop, you can optimized it by configuring the digital port only on the first iteration.

When you configure a digital I/O port that is part of an 8255 PPI, including all digital ports on Lab boards, SCXI-1200, DAQPad-1200, DAQCard-1200, DIO-24, DIO-32F, DIO-96, and AT-MIO-16DE-10/AT-MIO-16D ports 2, 3, and 4, the 8255 PPI goes through a configuration phase in which all the ports within the same PPI chip are reset to logic low, regardless of the data direction. The data directions on other ports, however, are maintained.

WriteToDigitalPort

Purpose

Outputs a decimal pattern to a digital port.

Parameters

Input

Name	Туре	Description
device	short integer	Assigned by NI-DAQ configuration utility.
portNumber	string	Specifies the digital port this function configures.
portWidth	short integer	Total width in bits of the port.
configure	long integer	 1 = Configure the digital port before writing 0 = Do not configure the digital port before writing
pattern	unsigned long integer	Specifies the new state of the lines in the port.

Name	Туре	Description
error	short integer	Refer to Table 10-9 for error codes.

Parameter Discussion

portNumber specifies the digital port WriteToDigitalPort configures.

A **portNumber** value of 0 signifies port 0; a **portNumber** of 1 signifies port 1; and so on. If you use an SCXI-1160, SCXI-1161, SCXI-1162, or SCXI-1163 module, use the following syntax:

"SCx!MDy!0"

where x is the chassis ID and y is the module device number, to specify the port on a module.

portWidth is the total width in bits of the port. For example, you can combine two 4-bit ports into an 8-bit port on an MIO (non-E Series) board by setting **portWidth** to 8.

When **portWidth** is greater than the physical port width of a digital port, the following restrictions apply: the **portWidth** must be an integral multiple of the physical port width, and the port numbers in the combined port must begin with the port named by **portNumber** and must increase consecutively. For example, if **portNumber** is 3 and **portWidth** is 24 (bits), LabWindows/CVI uses ports 3, 4, and 5.

You must pass a **portWidth** of at least 8 for the 8255-based digital I/O ports, including all digital ports on Lab boards, SCXI-1200, DAQPad-1200, DAQCard-1200, DIO-24, DIO-32F, DIO-96, and AT-MIO-16DE-10/AT-MIO-16D ports 2, 3, and 4.

configure specifies whether to configure the digital port before writing.

When you call WriteToDigitalPort in a loop, you can optimized it by configuring the digital port only on the first iteration.

When you configure a digital I/O port that is part of an 8255 PPI, including all digital ports on Lab boards, SCXI-1200, DAQPad-1200, DAQCard-1200, DIO-24, DIO-32F, DIO-96, and AT-MIO-16DE-10/AT-MIO-16D ports 2, 3, and 4, the 8255 PPI goes through a configuration phase in which all the ports within the same PPI chip are reset to logic low, regardless of the data direction. The data directions on other ports, however, are maintained.

Error Conditions

All the functions in the Easy I/O for DAQ Library return an error code. A negative number indicates that an error occurred. If the return value is positive, it has the same description as if it were negative, but it is considered a warning.

Code	Constant Name	Explanation
0		Success.
-10001	syntaxErr	An error was detected in the input string; the arrangement or ordering of the characters in the string is not consistent with the expected ordering.
-10002	semanticsErr	An error was detected in the input string; the syntax of the string is correct, but certain values you specify in the string are inconsistent with other values you specify in the string.
-10003	invalidValueErr	The value of a numeric parameter is invalid.
-10004	valueConflictErr	The value of a numeric parameter is inconsistent with another parameter, and the combination is therefore invalid.
-10005	badDeviceErr	Device parameter is invalid.
-10006	badLineErr	Line parameter is invalid.
-10007	badChanErr	A channel is out of range for the device type or input configuration, the combination of channels is invalid, or you must reverse the scan order so that channel 0 is last.
-10008	badGroupErr	Group parameter is invalid.
-10009	badCounterErr	Counter parameter is invalid.
-10010	badCountErr	Count parameter is too small or too large for the specified counter.

Table 10-9. Easy I/O for DAQ Library Error Codes

Code	Constant Name	Explanation
-10011	badIntervalErr	Interval parameter is too small or too large for the associated counter or I/O channel.
-10012	badRangeErr	Analog input or analog output voltage range is invalid for the specified channel.
-10013	badErrorCodeErr	Driver returned an unrecognized or unlisted error code.
-10014	groupTooLargeErr	Group size is too large for the device.
-10015	badTimeLimitErr	Time limit parameter is invalid.
-10016	badReadCountErr	Read count parameter is invalid.
-10017	badReadModeErr	Read mode parameter is invalid.
-10018	badReadOffsetErr	Offset is unreachable.
-10019	badClkFrequencyErr	Frequency parameter is invalid.
-10020	badTimebaseErr	Timebase parameter is invalid.
-10021	badLimitsErr	Limits are beyond the range of the device.
-10022	badWriteCountErr	Data array contains an incomplete update; you are trying to write past the end of the internal buffer; or your output operation is continuous and the length of your array is not a multiple of half the internal buffer size.
-10023	badWriteModeErr	Write mode is out of range or is invalid.
-10024	badWriteOffsetErr	Write offset plus the write mark is greater than the internal buffer size or it must be set to 0.
-10025	limitsOutOfRangeErr	Voltage limits are out of range for this device in the current configuration. Alternate limits were selected.

Table 10-9.	Easy I/O	for DAQ Librar	v Error Codes ((Continued)
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Code	Constant Name	Explanation
-10026	badInputBufferSpecification	Input buffer specification is invalid. This error results if, for example, you try to configure a multiple-buffer acquisition for a device that cannot perform multiple-buffer acquisition.
-10027	badDAQEventErr	For DAQEvents 0 and 1, general value A must be greater than 0 and less than the internal buffer size. If DMA is used for DAQEvent 1, general value A must divide the internal buffer size evenly, with no remainder. If the TIO-10 is used for DAQEvent 4, general value A must be 1 or 2.
-10028	badFilterCutoffErr	Cutoff frequency is not valid for this device.
-10080	badGainErr	Gain parameter is invalid.
-10081	badPretrigCountErr	Pretrigger sample count is invalid.
-10082	badPosttrigCountErr	Posttrigger sample count is invalid.
-10083	badTrigModeErr	Trigger mode is invalid.
-10084	badTrigCountErr	Trigger count is invalid.
-10085	badTrigRangeErr	Trigger range or trigger hysteresis window is invalid.
-10086	badExtRefErr	External reference value is invalid.
-10087	badTrigTypeErr	Trigger type parameter is invalid.
-10088	badTrigLevelErr	Trigger level parameter is invalid.
-10089	badTotalCountErr	Total count you specified is inconsistent with the buffer configuration and pretrigger scan count or with the device type.
-10090	badRPGErr	Individual range, polarity, and gain settings are valid but the combination you specified is invalid for this device.

Code	Constant Name	Explanation
-10091	badIterationsErr	Analog output buffer iterations count is invalid. It must be 0, for indefinite iterations, or 1.
-10100	badPortWidthErr	Requested digital port width is not a multiple of the hardware port width.
-10240	noDriverErr	Driver interface could not locate or open the driver.
-10241	oldDriverErr	Driver is out of date.
-10242	functionNotFoundErr	Specified function is not located in the driver.
-10243	configFileErr	Driver could not locate or open the configuration file, or the format of the configuration file is not compatible with the currently installed driver.
-10244	deviceInitErr	Driver encountered a hardware-initialization error while attempting to configure the specified device.
-10245	osInitErr	Driver encountered an operating system error while attempting to perform an operation, or the driver performed an operation that the operating system does not recognize.
-10246	communicationsErr	Driver is unable to communicate with the specified external device.
-10247	cmosConfigErr	CMOS configuration memory for the computer is empty or invalid, or the configuration you specified does not agree with the current configuration of the computer.
-10248	dupAddressErr	Base addresses for two or more devices are the same; consequently, the driver is unable to access the specified device.

Table 10-9. Easy I/O for DAQ Library Error Codes (Continued)

Code	Constant Name	Explanation
-10249	intConfigErr	Interrupt configuration is incorrect given the capabilities of the computer or device.
-10250	dupIntErr	Interrupt levels for two or more devices are the same.
-10251	dmaConfigErr	DMA configuration is incorrect given the capabilities of the computer/DMA controller or device.
-10252	dupDMAErr	DMA channels for two or more devices are the same.
-10253	switchlessBoardErr	NI-DAQ was unable to find one or more switchless boards you configured using WDAQCONF.
-10254	DAQCardConfigErr	Cannot configure the DAQCard because: the correct version of card and socket services software is not installed; the card in the PCMCIA socket is not a DAQCard: or the base address and/or interrupt level you requested are not available according to the card and socket services resource manager. Try different settings or use AutoAssign in the NI-DAQ configuration utility.
-10340	noConnectErr	No RTSI signal/line is connected, or the specified signal and the specified line are not connected.
-10341	badConnectErr	RTSI signal/line cannot be connected as specified.
-10342	multConnectErr	Specified RTSI signal is already being driven by a RTSI line, or the specified RTSI line is already being driven by a RTSI signal.

Table 10-9.	Easy I/O for DAQ	Library Error Codes	(Continued)
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Code	Constant Name	Explanation
-10343	SCXIConfigErr	Specified SCXI configuration parameters are invalid, or the function cannot be executed given the current SCXI configuration.
-10360	DSPInitErr	DSP driver was unable to load the kernel for its operating system.
-10370	badScanListErr	Scan list is invalid. This error can result if, for example, you mix AMUX-64T channels and onboard channels, or if you scan multiplexed SCXI channels out of order.
-10400	userOwnedRsrcErr	Specified resource is owned by the user and cannot be accessed or modified by the driver.
-10401	unknownDeviceErr	Specified device is not a National Instruments product, or the driver does not work with the device. For example, the driver was released before the features of the device existed.
-10402	deviceNotFoundErr	No device is located in the specified slot or at the specified address.
-10403	deviceSupportErr	Requested action does not work with specified device. The driver recognizes the device, but the action is inappropriate for the device.
-10404	noLineAvailErr	No line is available.
-10405	noChanAvailErr	No channel is available.
-10406	noGroupAvailErr	No group is available.
-10407	lineBusyErr	Specified line is in use.
-10408	chanBusyErr	Specified channel is in use.
-10409	groupBusyErr	Specified group is in use.

Table 10-9.	Easy I/O	for DAQ Library	/ Error Codes ((Continued)

Code	Constant Name	Explanation
-10410	relatedLCGBusyErr	A related line, channel, or group is in use. If the driver configures the specified line, channel, or group, the configuration, data, or handshaking lines for the related line, channel, or group will be disturbed.
-10411	counterBusyErr	Specified counter is in use.
-10412	noGroupAssignErr	No group is assigned, or the specified line or channel cannot be assigned to a group.
-10413	groupAssignErr	A group is already assigned, or the specified line or channel is already assigned to a group.
-10414	reservedPinErr	Selected signal indicates a pin reserved by NI-DAQ. You cannot configure this pin yourself.
-10440	sysOwnedRsrcErr	Specified resource is owned by the driver and cannot be accessed or modified by the user.
-10441	memConfigErr	No memory is configured to work with the current data transfer mode, or the configured memory does not work with the current data transfer mode. If block transfers are in use, the memory must be capable of performing block transfers.
-10442	memDisabledErr	Specified memory is disabled or is unavailable given the current addressing mode.
-10443	memAlignmentErr	Transfer buffer is not aligned properly for the current data transfer mode. For example, the memory buffer is at an odd address, is not aligned to a 32-bit boundary, is not aligned to a 512-bit boundary, and so on. Alternatively, the driver is unable to align the buffer because the buffer is too small.

Table 10-9.	Easy I/O for DAQ Librar	y Error Codes (Continued)
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Code	Constant Name	Explanation
-10444	memFullErr	No more system memory is available on the heap, or no more memory is available on the device.
-10445	memLockErr	Transfer buffer cannot be locked into physical memory.
-10446	memPageErr	Transfer buffer contains a page break. System resources might require reprogramming when the page break is encountered.
-10447	memPageLockErr	Operating environment is unable to grant a page lock.
-10448	stackMemErr	Driver is unable to continue parsing a string input because of stack limitations.
-10449	cacheMemErr	A cache-related error occurred, or caching does not work in the current mode.
-10450	physicalMemErr	A hardware error occurred in physical memory, or no memory is located at the specified address.
-10451	virtualMemErr	Driver is unable to make the transfer buffer contiguous in virtual memory and therefore cannot lock the buffer into physical memory; thus, you cannot use the buffer for DMA transfers.
-10452	noIntAvailErr	No interrupt level is available for use.
-10453	intInUseErr	Specified interrupt level is already in use by another device.
-10454	noDMACErr	No DMA controller is available in the system.
-10455	noDMAAvailErr	No DMA channel is available for use.
-10456	DMAInUseErr	Specified DMA channel is already in use by another device.

Table 10-9. Easy I/O for DAQ Library Error Codes (Continued)

Code	Constant Name	Explanation
-10457	badDMAGroupErr	DMA cannot be configured for the specified group because it is too small, too large, or misaligned. Consult the user manual for the device in question to determine group ramifications with respect to DMA.
-10459	DLLInterfaceErr	DLL could not be called because of an interface error.
-10460	interfaceInteractionErr	You have attempted to mix LabVIEW 2.2 VIs and LabVIEW 3.0 VIs. You must run an application that consists only of 2.2 VIs, then run the 2.2 Board Reset VI, before you can run any 3.0 VIs. You must run an application that consists of only 3.0 VIs, then run the 3.0 Device Reset VI, before you can run any 2.2 VIs.
-10560	invalidDSPhandleErr	DSP handle input to the VI is not a valid handle.
-10600	noSetupErr	No setup operation has been performed for the specified resources.
-10601	multSetupErr	Specified resources have already been configured by a setup operation.
-10602	noWriteErr	No output data has been written into the transfer buffer.
-10603	groupWriteErr	Output data associated with a group must be for a single channel or must be for consecutive channels.
-10604	activeWriteErr	Once data generation has started, only the transfer buffers originally written to can be updated. If DMA is active and a single transfer buffer contains interleaved channel data, all output channels currently using the DMA channel will require new data.

Table 10-9.	Easy I/O for DAQ Librar	y Error Codes ((Continued))
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Code	Constant Name	Explanation
-10605	endWriteErr	No data was written to the transfer buffer because the final data block has already been loaded.
-10606	notArmedErr	Specified resource is not armed.
-10607	armedErr	Specified resource is already armed.
-10608	noTransferInProgErr	No transfer is in progress for the specified resource.
-10609	transferInProgErr	A transfer is already in progress for the specified resource.
-10610	transferPauseErr	A single output channel in a group cannot be paused if the output data for the group is interleaved.
-10611	badDirOnSomeLinesErr	Some of the lines in the specified channel are not configured for the transfer direction specified. For a write transfer, some lines were configured for input. For a read transfer, some lines were configured for output.
-10612	badLineDirErr	Specified line does not support the specified transfer direction.
-10613	badChanDirErr	Specified channel does not support the specified transfer direction.
-10614	badGroupDirErr	Specified group does not support the specified transfer direction.
-10615	masterClkErr	Clock configuration for the clock master is invalid.
-10616	slaveClkErr	Clock configuration for the clock slave is invalid.
-10617	noClkSrcErr	No source signal has been assigned to the clock resource.
-10618	badClkSrcErr	Specified source signal cannot be assigned to the clock resource.

Table 10-9.	Easy I/O for DAQ	Library Error Codes	(Continued)
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Code	Constant Name	Explanation
-10619	multClkSrcErr	A source signal has already been assigned to the clock resource.
-10620	noTrigErr	No trigger signal has been assigned to the trigger resource.
-10621	badTrigErr	Specified trigger signal cannot be assigned to the trigger resource.
-10622	preTrigErr	Pretrigger mode is not supported or is not available in the current configuration, or no pretrigger source has been assigned.
-10623	postTrigErr	No posttrigger source has been assigned.
-10624	delayTrigErr	Delayed trigger mode is not supported or is not available in the current configuration, or no delay source has been assigned.
-10625	masterTrigErr	Trigger configuration for the trigger master is invalid.
-10626	slaveTrigErr	Trigger configuration for the trigger slave is invalid.
-10627	noTrigDrvErr	No signal has been assigned to the trigger resource.
-10628	multTrigDrvErr	A signal has already been assigned to the trigger resource.
-10629	invalidOpModeErr	Specified operating mode is invalid, or the resources have not been configured for the specified operating mode.
-10630	invalidReadErr	An attempt was made to read 0 bytes from the transfer buffer, or an attempt was made to read past the end of the transfer buffer.
-10631	noInfiniteModeErr	Continuous input or output transfers are invalid in the current operating mode.

Table 10-9.	Easy I/O for DAQ Librar	y Error Codes ((Continued)
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Code	Constant Name	Explanation
-10632	someInputsIgnoredErr	Certain inputs were ignored because they are not relevant in the current operating mode.
-10633	invalidRegenModeErr	This device does not support the specified analog output regeneration mode.
-10680	badChanGainErr	All channels must have an identical setting for this device.
-10681	badChanRangeErr	All channels of this device must have the same range.
-10682	badChanPolarityErr	All channels of this device must have the same polarity.
-10683	badChanCouplingErr	All channels of this device must have the same coupling.
-10684	badChanInputModeErr	All channels of this device must have the same input range.
-10685	clkExceedsBrdsMaxConvRate	Clock rate selected exceeds the recommended maximum rate for this device.
-10686	scanListInvalidErr	A configuration change has invalidated the scan list.
-10687	bufferInvalidErr	A configuration change has invalidated the allocated buffer.
-10688	noTrigEnabledErr	Total number of scans and pretrigger scans implies that a trigger start is intended, but no trigger is enabled.
-10689	digitalTrigBErr	Digital trigger B is illegal for the total scans and pretrigger scans specified.
-10690	digitalTrigAandBErr	With this device, you cannot enable digital triggers A and B at the same time.
-10691	extConvRestrictionErr	With this device, you cannot use an external sample clock with an external scan clock, start trigger, or stop trigger.

Table 10-9. Easy I/O for DAQ Library Error Codes (Continued)

Code	Constant Name	Explanation
-10692	chanClockDisabledErr	Cannot start the acquisition because the channel clock is disabled.
-10693	extScanClockErr	Cannot use an external scan clock when performing a single scan of a single channel.
-10694	unsafeSamplingFreqErr	Sampling frequency exceeds the safe maximum rate for the ADC, gains, and filters you are using.
-10695	DMAnotAllowedErr	You must use interrupts. DMA does not work.
-10696	multiRateModeErr	Multirate scanning can not be used with AMUX-64, SCXI, or pre-triggered acquisitions.
-10697	rateNotSupportedErr	NI-DAQ was unable to convert your timebase/interval pair to match the actual hardware capabilities of the specified board.
-10698	timebaseConflictErr	You cannot use this combination of scan and sample clock timebases for the specified board.
-10699	polarityConflictErr	You cannot use this combination of scan and sample clock source polarities for this operation for the specified board.
-10700	signalConflictErr	You cannot use this combination of scan and convert clock signal sources for this operation for the specified board.
-10740	SCXITrackHoldErr	A signal has already been assigned to the SCXI track-and-hold trigger line, or a control call was inappropriate because the specified module is not configured for one-channel operation.

Table 10-9. Easy I/O for DAQ Library Error Codes (Continued)

Code	Constant Name	Explanation
-10780	sc2040InputModeErr	When you have an SC2040 attached to your device, all analog input channels must be configured for differential input mode.
-10800	timeOutErr	Operation could not complete within the time limit.
-10801	calibrationErr	An error occurred during the calibration process.
-10802	dataNotAvailErr	Requested amount of data has not yet been acquired, or the acquisition has completed and no more data is available to read.
-10803	transferStoppedErr	Transfer has been stopped to prevent regeneration of output data.
-10804	earlyStopErr	Transfer stopped before reaching the end of the transfer buffer.
-10805	overRunErr	Clock source for the input transfer is faster than the maximum input-clock rate; the integrity of the data has been compromised. Alternatively, the clock source for the output transfer is faster than the maximum output-clock rate; a data point was generated more than once because the update occurred before new data was available.
-10806	noTrigFoundErr	No trigger value was found in the input transfer buffer.
-10807	earlyTrigErr	Trigger occurred before sufficient pretrigger data was acquired.
-10809	gateSignalErr	Attempted to start a pulse width measurement with the pulse in the active state.

Table 10-9.	Easy I/O for	DAQ Library Err	or Codes ((Continued)
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Code	Constant Name	Explanation
-10840	softwareErr	Contents or the location of the driver file was changed between accesses to the driver.
-10841	firmwareErr	Firmware does not support the specified operation, or the firmware operation could not complete because of a data-integrity problem.
-10842	hardwareErr	Hardware is not responding to the specified operation, or the response from the hardware is not consistent with the functionality of the hardware.
-10843	underFlowErr	The update rate exceeds your system capacity to supply data to the output channel.
-10844	underWriteErr	At the time of the update for the device-resident memory, insufficient data was present in the output transfer buffer to complete the update.
-10845	overFlowErr	At the time of the update clock for the input channel, the device-resident memory was unable to accept additional data. One or more data points might have been lost.
-10846	overWriteErr	New data was written into the input transfer buffer before the old data was retrieved.
-10847	dmaChainingErr	New buffer information was not available at the time of the DMA chaining interrupt; DMA transfers will terminate at the end of the currently active transfer buffer.
-10848	noDMACountAvailErr	Driver could not obtain a valid reading from the transfer-count register in the DMA controller.
-10849	openFileErr	Unable to open a file.

Table 10-9.	Easy I/O for DAQ Librar	y Error Codes	(Continued)
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Code	Constant Name	Explanation
-10850	closeFileErr	Unable to close a file.
-10851	fileSeekErr	Unable to seek within a file.
-10852	readFileErr	Unable to read from a file.
-10853	writeFileErr	Unable to write to a file.
-10854	miscFileErr	An error occurred accessing a file.
-10880	updateRateChangeErr	A change to the update rate is not possible at this time because when waveform generation is in progress, you cannot change the interval timebase; or when you make several changes in a row, you must wait long enough for each change to take effect before you request more changes.
-10920	gpctrDataLossErr	One or more data points might have been lost during buffered GPCTR operations because of speed limitations of your system.

Table 10-9. Easy I/O for DAQ Library Error Codes (Continued)

ActiveX Automation Library

This chapter describes the ActiveX Automation Library, which contains functions that control ActiveX Automation servers. The *ActiveX Automation Library Function Overview* section contains general information about the functions as well as guidelines and restrictions you should know when you use the ActiveX Automation Library. The *ActiveX Automation Library Function Reference* section contains an alphabetical list of function descriptions.

This library is available only on Windows 95/NT.

ActiveX Automation Library Function Overview

ActiveX Automation (formerly called OLE Automation) allows applications to make their unique features available to scripting tools and other applications. An ActiveX Automation server is the application that exposes its features. An ActiveX Automation controller is the application that uses the features of an ActiveX Automation server. An ActiveX Automation server exports its features as a set of ActiveX Objects. For example, Microsoft Excel exposes its workbooks, worksheets, and charts as ActiveX Objects. Each ActiveX Object provides methods and properties that other applications can access. For example, the Microsoft Excel worksheet object provides a calculate method that calculates the values in a worksheet.

The ActiveX Automation Library contains functions that facilitate calling into ActiveX server interfaces. Use the ActiveX Automation Library in conjunction with the instrument drivers the ActiveX Automation Controller Wizard generates. The ActiveX Automation Controller Instrument Drivers contain C functions to create ActiveX Objects, to call ActiveX Object methods, and to get and set ActiveX Object properties. Select **ToolsCreate ActiveX Automation Controller** to start the wizard.

The ActiveX Automation Library contains functions that:

- Help you work with the VARIANT parameters, SAFEARRAY parameters, and return values of the functions in the generated instrument drivers.
- Free resources dynamically allocated by the generated instrument drivers or by other ActiveX Automation Library functions.
- Display error information the library functions or the Automation server methods return.

The ActiveX Automation Library also contains low-level functions that the generated drivers use. These low-level functions invoke methods of server objects and get and set properties of server objects.

If you want to use the low-level functions, you should know ActiveX concepts. In particular, you should know how to browse through an ActiveX Automation server type library.

Variants and Safe Arrays

The VARIANT data type is a structure that can hold a value of any valid ActiveX Automation data type. Refer to Tables 11-1 and 11-2 for valid ActiveX Automation data types. ActiveX Automation server functions declare a parameter as a VARIANT when the parameter can take a value of more than one data type. This document uses the term *variant* to refer to parameters or variables declared with the VARIANT data type. The ActiveX Automation Library provides functions to help you pass values as variant input parameters and retrieve values from variant output parameters.

The SAFEARRAY data type is a structure that holds an array of data, the number of dimensions in the array, and the size of each dimension. ActiveX Automation server functions use the SAFEARRAY data type to pass arrays. This document uses the term *safe array* to refer to parameters or variables declared with the SAFEARRAY data type. The ActiveX Automation Library provides functions to convert between C-style arrays and safe arrays, functions to obtain the number of dimensions in a safe array and the size of each dimension, and functions to convert between C-arrays stored inside variants.

You can declare a variant structure as a local or global variable, but safe arrays are always dynamically allocated. Consequently, you must always reference safe arrays using pointers. Use the LPSAFEARRAY typedef to declare a pointer to a safe array. Microsoft adds LP at the beginning of data type names to indicate a pointer to a data type. Thus, LPSAFEARRAY signifies a pointer to a SAFEARRAY.

Events are Not Supported

The ActiveX Automation Library does not receive events from Automation servers. If you need to receive events through an Automation server event interface, you must manually create an IDispatch interface that conforms to the event interface the server provides.

ActiveX Automation Library Function Panels

The ActiveX Automation Library function panels are grouped in the tree structure in Table 11-1 according to the types of operations they perform.

The first- and second-level headings in the tree are names of function classes and subclasses. Function classes and subclasses are groups of related function panels. The third-level headings are the names of individual function panels. Each function panel generates a function call. The following shows the structure of the ActiveX Automation Library function tree.

Variant-Related Functions Passing Values as Variants Assigning Values to Variants Querying the Type of a Variant Retrieving Values from Variants Array Functions C Array-to-Safe Array Conversion Safe Array-to-C Array Conversion **Ouerving Safe Arrays BSTR** Functions Freeing Resources Error Processing Locales Low-level Functions Creating Automation Objects Calling Methods and Properties

Table 11 1	Eurotiona in the	Active V Automation	Library Eurotian Trac
		HULIVEN HULUIIIALIUII	Library Function Tree

Class/Panel Name

Variant-Related Functions Passing Values as Variants Variant From Long Variant From Short Variant From Int Variant From Bool Variant From Float Variant From Double Variant From Currency Variant From Date Variant From Error Variant From UnsignedChar Variant From Dispatch Variant From IUnknown Variant From BSTR **Empty Variant** NULL Variant Default Value Variant Assigning Values to Variants Variant Set Empty Variant Set Long Variant Set Short Variant Set Int Variant Set Bool Variant Set Float Variant Set Double

Function Name

CA_VariantLong CA VariantShort CA_VariantInt CA VariantBool CA VariantFloat CA_VariantDouble CA_VariantCurrency CA VariantDate CA VariantError CA_VariantUChar CA_VariantDispatch CA VariantIUnknown CA_VariantBSTR CA_VariantEmpty CA VariantNULL CA DefaultValueVariant CA_VariantSetEmpty CA_VariantSetLong CA VariantSetShort CA VariantSetInt

CA_VariantSetInt CA_VariantSetBool CA_VariantSetFloat CA_VariantSetDouble

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Class/Panel Name	Function Name
Variant-Related Functions (continued)	
Assigning Values to Variants (continued)	
Variant Set Safe Array	CA_VariantSetSafeArray
Variant Set 1D Array	CA_VariantSet1DArray
Variant Set 2D Array	CA_VariantSet2DArray
Variant Set BSTR	CA_VariantSetBSTR
Variant Set NULL	CA_VariantSetNULL
Variant Set Currency	CA_VariantSetCurrency
Variant Set Date	CA_VariantSetDate
Variant Set Dispatch	CA_VariantSetDispatch
Variant Set IUnknown	CA_VariantSetIUnknown
Variant Set Error	 CA VariantSetError
Variant Set Unsigned Char	 CA_VariantSetUChar
Variant Set C String	 CA_VariantSetCString
Variant Set Long Ptr	CA_VariantSetLongPtr
Variant Set Short Ptr	CA_VariantSetShortPtr
Variant Set Int Ptr	CA VariantSetIntPtr
Variant Set Bool Ptr	CA_VariantSetBoolPtr
Variant Set Float Ptr	CA VariantSetFloatPtr
Variant Set Double Ptr	CA VariantSetDoublePtr
Variant Set Safe Array Ptr	CA_VariantSetSafeArrayPtr
Variant Set BSTR Ptr	CA_VariantSetBSTRPtr
Variant Set Currency Ptr	CA_VariantSetCurrencyPtr
Variant Set Date Ptr	CA VariantSetDatePtr
Variant Set Dispatch Ptr	CA_VariantSetDispatchPtr
Variant Set IUnknown Ptr	CA VariantSetIUnknownPtr
Variant Set Error Ptr	CA VariantSetErrorPtr
Variant Set Unsigned Char Ptr	CA_VariantSetUCharPtr
Variant Set Variant Ptr	CA_VariantSetVariantPtr
Querying the Type of a Variant	
Variant Get Type	CA_VariantGetType
Variant Has Array	CA_VariantHasArray
Variant Has Pointer	CA_VariantHasPtr
Variant Has Long	CA_VariantHasLong
Variant Has Short	CA VariantHasShort
Variant Has Int	CA VariantHasInt
Variant Has Bool	CA VariantHasBool
Variant Has Float	CA VariantHasFloat
Variant Has Double	CA_VariantHasDouble
Variant Has C String	CA_VariantHasCString
Variant Has BSTR	CA VariantHasBSTR
Variant Has NULL	CA_VariantHasNull
Variant Has NOLL Variant Has Currency	CA_VariantHasCurrency
Variant Has Date	CA_VariantHasDate
Variant Has IUnknown	CA_VariantHasIUnknown
vallalit Has IUlikiluwil	CA_VALIAIICHASIUIIKIIUWII

Table 11-1. Functions in the ActiveX Automation Library Function Tree (Continued)

Class/Panel Name	Function Name
Variant-Related Functions (continued)	
Querying the Type of a Variant (continued)	
Variant Has Dispatch	CA_VariantHasDispatch
Variant Has ObjHandle	CA_VariantHasObjHandle
Variant Has Unsigned Char	CA_VariantHasUChar
Variant Has Error Code	CA_VariantHasError
Variant Is Empty	CA_VariantIsEmpty
Retrieving Values from Variants	
Convert Variant To Type	CA_VariantConvertToType
Copy Variant	CA_VariantCopy
Variant Get Long	CA_VariantGetLong
Variant Get Short	CA_VariantGetShort
Variant Get Int	CA_VariantGetInt
Variant Get Boolean	CA_VariantGetBool
Variant Get Float	CA_VariantGetFloat
Variant Get Double	CA_VariantGetDouble
Variant Get Safe Array	CA_VariantGetSafeArray
Variant Get 1D Array	CA_VariantGet1DArray
Variant Get 2D Array	CA_VariantGet2DArray
Variant Get 1D Array in Buffer	CA_VariantGet1DArrayBuf
Variant Get 2D Array in Buffer	CA_VariantGet2DArrayBuf
Variant Get Array Num Dims	CA_VariantGetArrayNumDims
Variant Get 1D Array Size	CA_VariantGet1DArraySize
Variant Get 2D Array Size	CA_VariantGet2DArraySize
Variant Get BSTR	CA_VariantGetBSTR
Variant Get Currency	CA_VariantGetCurrency
Variant Get Date	CA_VariantGetDate
Variant Get Dispatch	CA_VariantGetDispatch
Variant Get IUnknown	CA_VariantGetIUnknown
Variant Get Error	CA_VariantGetError
Variant Get Unsigned Char	CA_VariantGetUChar
Variant Get ObjHandle	CA_VariantGetObjHandle
Variant Get String Length	CA_VariantGetCStringLen
Variant Get String In Buffer	CA_VariantGetCStringBuf
Variant Get String	CA_VariantGetCString
Variant Get Long Ptr	CA_VariantGetLongPtr
Variant Get Short Ptr	CA_VariantGetShortPtr
Variant Get Int Ptr	CA_VariantGetIntPtr
Variant Get Bool Ptr	CA_VariantGetBoolPtr
Variant Get Float Ptr	CA_VariantGetFloatPtr
Variant Get Double Ptr	CA_VariantGetDoublePtr
Variant Get Safe Array Ptr	CA_VariantGetSafeArrayPtr
Variant Get BSTR Ptr	CA_VariantGetBSTRPtr
Variant Get Currency Ptr	CA_VariantGetCurrencyPtr
Variant Get Date Ptr	CA_VariantGetDatePtr

Table 11-1. Functions in the ActiveX Automation Library Function Tree (Continued)

Class/Panel Name Function Name Variant-Related Functions (continued) Retrieving Values from Variants (continued) Variant Get Dispatch Ptr CA_VariantGetDispatchPtr Variant Get IUnknown Ptr CA VariantGetIUnknownPtr Variant Get Error Ptr CA VariantGetErrorPtr Variant Get Unsigned Char Ptr CA_VariantGetUCharPtr Variant Get Variant Ptr CA VariantGetVariantPtr Array Functions C Array-to-Safe Array Conversion 1D Array to Safe Array CA_Array1DToSafeArray 2D Array to Safe Array CA_Array2DToSafeArray Safe Array-to-C Array Conversion Safe Array to 1D Array CA_SafeArrayTo1DArray Safe Array to 2D Array CA_SafeArrayTo2DArray Safe Array to 1D Array Buffer CA_SafeArrayTo1DArrayBuf Safe Array to 2D Array Buffer CA_SafeArrayTo2DArrayBuf **Ouerving Safe Arrays** Safe Array Get Number of Dims CA_SafeArrayGetNumDims Get 1D Safe Array Size CA_SafeArrayGet1DSize Get 2D Safe Array Size CA SafeArrayGet2DSize **BSTR** Functions C String To BSTR CA_CStringToBSTR BSTR Get C String CA_BSTRGetCString BSTR Get C String In Buffer CA_BSTRGetCStringBuf BSTR Get C String Length CA_BSTRGetCStringLen Freeing Resources Free Memory CA_FreeMemory Clear Variant CA VariantClear Destroy Safe Array CA SafeArrayDestroy **Discard Object Handle** CA_DiscardObjHandle Free Unused Servers CA FreeUnusedServers Error Processing **Display Error Info** CA_DisplayErrorInfo Get Automation Error String CA_GetAutomationErrorString Locales Set Locale CA_SetLocale Get Locale CA GetLocale Low-level Functions **Creating Automation Objects** Get Active Object By Class Id CA_GetActiveObjectByClassId Get Active Object By Prog Id CA GetActiveObjectByProgId Create Object By Class Id CA_CreateObjectByClassId Create Object By Prog Id CA_CreateObjectByProgId Load Object From File CA_LoadObjectFromFile Load Object From File By Class Id CA_LoadObjectFromFileByClassId

Table 11-1. Functions in the ActiveX Automation Library Function Tree (Continued)

Class/Panel Name	Function Name
Low-level Functions (continued)	
Creating Automation Objects (continued)	
Load Object From File By Prog Id	CA_LoadObjectFromFileByProgId
Create ObjHandle from Dispatch	CA_CreateObjHandleFromIDispatch
Calling Methods and Properties	
Invoke Method	CA_MethodInvoke
Invoke Method (List)	CA_MethodInvokeV
Get Property	CA_PropertyGet
Set Property	CA_PropertySet
Set Property (List)	CA_PropertySetV
Set Property By Ref	CA_PropertySetByRef
Set Property By Ref (List)	CA_PropertySetByRefV
Invoke Method/Property	CA_InvokeHelper
Invoke Method/Property (List)	CA_InvokeHelperV

Table 11-1. Functions in the ActiveX Automation Library Function Tree (Continued)

Get Dispatch From ObjHandle

CA_GetDispatchFromObjHandle

Class Descriptions

- The Variant-Related Functions class contains all the functions for assigning values to, or obtaining values from, variables or parameters declared with the VARIANT data type.
- The Passing Values as Variants class contains functions that allow you to pass variant parameters without declaring variant variables. You cannot pass strings or arrays using these functions because the conversions needed to store strings or arrays in variants might fail.
- The Assigning Values to Variants class contains functions that assign values to variant variables.
- The Querying the Type of a Variant class contains functions that allow you to query the data type of the value a variant holds.
- The Retrieving Values from Variants class contains functions that retrieve the values the variant parameters or variables hold.
- The Array Functions class contains functions that convert between C-style arrays and safe arrays and functions that can get the dimension and sizes of a safe array.
- The C Array-to-Safe Array Conversion class contains functions to create safe arrays from C-style arrays.
- The Safe Array-to-C Array Conversion class contains functions to create C-style arrays from safe arrays.
- The Querying Safe Arrays class contains functions to determine the number of dimensions and size of a safe array.

- The BSTR Functions class contains functions that convert between C-style strings and BSTR strings, which are Basic-style strings that store both text and length information.
- The Freeing Resources class contains functions to free resources that the Automation Controller Instrument Drivers or ActiveX Automation Library functions dynamically allocate.
- The Error Processing class contains functions that display error information based on error values that the ActiveX Automation Library functions or the Automation server functions return.
- The Locales class contains functions that set and get the language to use in the communication with the Automation server.
- The Low-level Functions class contains functions to create Automation server objects, invoke methods of those objects, and set and get properties of those objects.
- The Creating Automation Objects class contains functions to create Automation server objects, such as an Excel worksheet.
- The Calling Methods and Properties class contains functions to invoke methods of Automation server objects and to set and get properties of those objects.

The online help with each panel contains specific information about operating each function panel.

Using Input Variant Parameters

The ActiveX Automation Library contains two sets of functions to help you pass variant input parameters and set variants properties. The first set of functions allows you to pass values as variants without declaring VARIANT variables. The Passing Values as Variants function tree class includes these functions. You cannot pass strings or arrays using these functions because the conversions needed when storing strings or arrays in variants might fail.

Some server methods have optional variant parameters. You can tell the server to use a server-defined default value for an optional parameter by passing a variant with a special value. Use CA_DefaultValueVariant to pass a variant that contains this special value. You can use the CA_DEFAULT_VAL macro to refer to CA_DefaultValueVariant.

For strings and arrays, you must declare variables of type VARIANT and use the functions in the Assigning Values to Variants function tree class to store values in these variables. You must free the strings or arrays stored in variants when you no longer need them. Use CA_VariantClear to free the contents of variants.

Using Output Variant Parameters

The ActiveX Automation Library contains functions to query the type of value a variant contains and functions to retrieve values from a variant. CA_VariantGetType returns a constant that represents the type of value the variant contains. Other functions, such as

CA_VariantHasLong and CA_VariantHasShort, return a Boolean value that indicates whether the variant contains a value of a specific type.

CA_VariantConvertToType converts the value the variant contains to a type you specify. Other functions, such as CA_VariantGetLong, retrieve a value of a specific type from a variant and fail if the variant does not contain a value of that type.

Variants Marked as Empty by Retrieval Functions

All the functions that retrieve values from a variant mark the variant as empty and free any dynamically allocated memory the variant holds. Thus, you cannot call the retrieval functions multiple times on the same variant. If you do not retrieve the values from a variant, you can free the contents of a variant using CAVariantClear.

Data Types for Variants, Safe Arrays, and Properties

A set of fundamental data types exists that is valid for variants, safe arrays, and properties. You can apply a set of modifiers to the fundamental data types to create more data types. Not all combinations are valid in all cases. The function descriptions specify which data types are valid in particular contexts. Table 11-2 shows the fundamental data types.

Defined Constant	Data Type or Meaning	
CAVT_EMPTY	Variant contains nothing.	
CAVT_NULL	Variant contains NULL value.	
CAVT_SHORT	short	
CAVT_LONG	long	
CAVT_INT	int (same as CAVT_LONG)	
CAVT_FLOAT	float	
CAVT_DOUBLE	double	
CAVT_CY	CURRENCY (Windows SDK data type)	
CAVT_DATE	DATE (Windows SDK data type)	
CAVT_BSTR	BSTR (Windows SDK data type)	
CAVT_DISPATCH	LPDISPATCH (ActiveX data type for an automation object interface)	
CAVT_ERROR	SCODE (Windows SDK data type)	

 Table 11-2.
 Fundamental Data Types for Variants, Safe Arrays, and Properties

Defined Constant	Data Type or Meaning	
CAVT_BOOL	VBOOL, which maps to VARIANT_BOOL (ActiveX data type)	
CAVT_VARIANT	VARIANT (ActiveX data type)	
CAVT_UNKNOWN	LPUNKNOWN (ActiveX data type for an unknown interface)	
CAVT_UCHAR	unsigned char	
CAVT_CSTRING	char* (null-terminated string)	
CAVT_OBJHANDLE	CAObjHandle, which maps to void*	

 Table 11-2.
 Fundamental Data Types for Variants, Safe Arrays, and Properties (Continued)

You can bitwise OR all the constants in Table 11-2 with the data type modifiers except for CAVT_EMPTY and CAVT_NULL. Table 11-3 shows the data type modifiers.

Defined Constant	Meaning	
CAVT_ARRAY	Array of data type. For example, CAVT_SHORT CAVT_ARRAY signifies an array of short integers.	
CAVT_BYREF	Pointer to data type.	
CAVT_BYREFI	Pointer to data type. Input-only parameter you pass by reference. Defined as CAVT_BYREF CAVT_IN.	
CAVT_BYREFO	Pointer to data type. Output-only parameter you pass by reference. Defined as CAVT_BYREF CAVT_OUT.	
CAVT_BYREFIO	Pointer to data type. Input-output parameter you pass by reference. Defined as CAVT_BYREF CAVT_IN CAVT_OUT.	

Table 11-3. Data Types Modifiers for Variants, Safe Arrays, and Properties

To pass a pointer to the array address, use CAVT_ARRAY and one of the CAVT_BYREF modifiers.

Handling Dynamic Memory Variants Hold

Variants of the following data types store their values in dynamically allocated memory:

CAVT_CSTRING CAVT_OBJHANDLE <any type> | CAVT_ARRAY

The functions that retrieve values from such variants free the memory. If you do not retrieve the value stored in the variant, you can free the contents of a variant using CA_VariantClear.

ActiveX Automation Library Function Reference

This section describes each function in the LabWindows/CVI ActiveX Automation Library in alphabetical order.

CA_Array1DToSafeArray

Purpose

Creates a safe array from a 1D array.

Parameters

Input

Name	Туре	Description
array	void pointer	1D array.
arrayType	unsigned integer	Data type of the elements in array .
numElements	unsigned integer	Number of elements in array.

Output

Name	Туре	Description
safeArray	LPSAFEARRAY	Safe array CA_Array1DToSafeArray creates from the contents of array .

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **arrayType** parameter can have any of the values in Table 11-2 except for CAVT_EMPTY, CAVT_NULL, or CAVT_OBJHANDLE. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter.

CA_Array1DToSafeArray does not make copies of BSTR, VARIANT, LPUNKNOWN, or LPDISPATCH elements. It simply copies the pointers from **array** into the created **safeArray**. Therefore, when you call CA_SafeArrayDestroy, which frees all contents of the safe array, the BSTR, VARIANT, LPUNKNOWN, or LPDISPATCH elements in **array** become invalid.

CA_Array2DToSafeArray

Purpose

Creates a safe array from a 2D array.

Parameters

Input

Name	Туре	Description
array	void pointer	2D array.
arrayType	unsigned integer	Data type of the elements in array .
numElemsDim1	unsigned integer	Number of rows in array .
numElemsDim2	unsigned integer	Number of columns in array .

Output

Name	Туре	Description
safeArray	LPSAFEARRAY	Safe array CA_Array2DToSafeArray creates from the contents of array .

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **arrayType** parameter can have any of the values in Table 11-2 except for CAVT_EMPTY, CAVT_NULL, or CAVT_OBJHANDLE. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter.

CA_Array2DToSafeArray does not make copies of BSTR, VARIANT, LPUNKNOWN, or LPDISPATCH elements. It simply copies the pointers from **array** into the created **safeArray**. Therefore, when you call CA_SafeArrayDestroy, which frees all contents of the safe array, the BSTR, VARIANT, LPUNKNOWN, or LPDISPATCH elements in **array** become invalid.

CA_BSTRGetCString

HRESULT status = CA_BSTRGetCString (BSTR bString, char **cString);

Purpose

Converts a BSTR into a C-style string. A BSTR is a Basic-style string that stores both text and length information.

CA_BSTRGetCString does not free the Basic-style string.

Parameters

Input

Name	Туре	Description
bString	BSTR	Basic-style string you want to convert to a C-style string.

Output

Name	Туре	Description
cString	string	Dynamically allocated C-style string that CA_BSTRGetCString converts from the Basic-style string.

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

When you no longer need the C-style string, call CA_FreeMemory to free it.

CA_BSTRGetCStringBuf

Purpose

Converts a BSTR into a C-style string and copies it into a buffer you pass as a parameter. A BSTR is a Basic-style string that stores both text and length information.

CA_BSTRGetCStringBuf does not free the Basic-style string.

If **buffer** is not large enough to hold the string, CA_BSTRGetCStringBuf copies (**bufferSize** – 1) bytes to the **buffer**, followed by an ASCII NUL byte.

Parameters

Input

Name	Туре	Description
bString	BSTR	Basic-style string you want to convert to a C-style string.
bufferSize	unsigned long integer	Number of bytes in buffer . Must be must be large enough to hold the string text and an ASCII NUL byte.

Output

Name	Туре	Description
buffer	string	Character buffer into which the CA_BSTRGetCString copies the C-style string it converts from the Basic-style string.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_BSTRGetCStringLen

HRESULT status = CA_BSTRGetCStringLen (BSTR bString, int *len);

Purpose

Obtains the length of the C-style string you can create by calling CA_BSTRToCString on a BSTR you specify. A BSTR is a Basic-style string that stores both text and length information.

The length CA_BSTRGetCStringLen returns does not include the ASCII NUL byte.

Parameters

Input

Name	Туре	Description
bString	BSTR	Basic-style string.

Output

Name	Туре	Description
len	integer	Length of the C-style string CA_BSTRToCString can convert from the Basic-style string. Does not include the ASCII NUL byte.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_CreateObjectByClassId

Purpose

Creates a new Automation server object based on an object Class ID.

If the application that provides the Automation object is already running, CA_CreateObjectByClassId might start another copy of the application, depending on the implementation of the application.

Parameters

Input

Name	Туре	Description
classID	GUID pointer	Class ID of the Automation server object; located in the server type library.
serverMachineName	string	Name or IP address of the computer on which you want to run the Automation server.

Output

Name	Туре	Description
objHandle	CAOHandle	Handle to the server object you create.

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **serverMachineName** can be either a UNC name ("\\server") or a DNS name ("home.server.com").

If you pass NULL for the **serverMachineName** and a RemoteServerName registry entry exists for this server, the server runs on the computer the RemoteServerName entry specifies. If you pass NULL for this parameter and no RemoteServerName registry entry exists for this server, the server runs on the same computer as your program.

You can pass **objHandle** to other functions in this library to call methods of the Automation object or to get and set properties of the Automation object. When you no longer need **objHandle**, discard it by calling CA_DiscardObjHandle.

CA_CreateObjectByProgId

Purpose

Creates a new Automation server object based on the object Prog ID.

If the application that provides the Automation object is already running, CA_CreateObjectByProgId might start another copy of the application, depending on the implementation of the application.

Parameters

Input

Name	Туре	Description
progID	string	Prog ID of the Automation server object; located in the server documentation.
serverMachineName	string	Name or IP address of the computer on which you want to run the Automation server.

Output

Name	Туре	Description
objHandle	CAObjHandle	Handle to the server object you create.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **serverMachineName** can be either a UNC name ("\\server") or a DNS name ("home.server.com").

If you pass NULL for the **serverMachineName** and a RemoteServerName registry entry exists for this server, the server runs on the computer the RemoteServerName entry specifies. If you pass NULL for this parameter and no RemoteServerName registry entry exists for this server, the server runs on the same computer as your program.

You can pass **objHandle** to other functions in this library to call methods of the Automation object or to get and set properties of the Automation object. When you no longer need **objHandle**, discard it by calling CA_DiscardObjHandle.

CA_CreateObjHandleFromIDispatch

Purpose

Creates a CAObjHandle value when you already have a Dispatch pointer to an automation object.

Parameters

Input

Name	Туре	Description
dispatchPtr	LPDISPATCH	Dispatch pointer to an Automation server object.
callAddRef	integer	If nonzero, CA_CreateObjHandleFromIDispatch invokes the AddRef method of the object.

Output

Name	Туре	Description
objHandle	CAObjHandle	Handle to the server object you create.

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

You can pass **objHandle** to other functions in this library to call methods of the Automation object or to get and set properties of the Automation object. When you no longer need **objHandle**, discard it by calling CA_DiscardObjHandle.

CA_CStringToBSTR

HRESULT status = CA_CStringToBSTR (char cString[], BSTR *bString);

Purpose

Converts a C-style string into a BSTR. A BSTR is a Basic-style string that stores both text and length information.

CA_CStringToBSTR does not free the C-style string.

Parameters

Input

Name	Туре	Description
cString	string	C-style string you want to convert to a BSTR.

Output

Name	Туре	Description
bString	BSTR	Basic-style string CA_CSringToBSTR creates from cString .

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

When you no longer need the Basic-style string, call the Windows SDK function SysFreeString to free it.

CA_DefaultValueVariant

VARIANT *variant = CA_DefaultValueVariant (void);

Purpose

Some Automation server functions allow you to pass a VARIANT parameter value that means "use the default value for this parameter." CA_DefaultValueVariant returns such a variant. You can use the macro CA_DEFAULT_VAL to refer to CA_DefaultValueVariant.

You can use the returned variant only for parameters that are optional. You can tell whether a parameter is optional by checking the default value in its function panel control. If the default value is CA_DEFAULT_VAL, the parameter is optional.

CA_DefaultValueVariant sets the type field in the returned variant to VT_ERROR and the error value field to DISP_E_PARAMNOTFOUND.

Parameters

None.

Name	Туре	Description
variant	VARIANT	Variant in which LabWindows/CVI sets the type field to VT_ERROR and the error value to DISP_E_PARAMNOTFOUND.

CA_DiscardObjHandle

HRESULT status = CA_DiscardObjHandle (CAObjHandle objHandle);

Purpose

Use CA_DiscardObjHandle when you no longer need to reference an Automation server object. CA_DiscardObjHandle releases resources associated with the object and calls the Release method of the Automation server object.

If **objHandle** is the only reference to the Automation server and the Automation server is an application, the server application might shut down after you call CA_DiscardObjHandle. If you implement the Automation server as a DLL, you must call the Windows SDK function CoFreeUnusedLibraries to unload the DLL. If you do not call CoFreeUnusedLibraries, the DLL does not unload until you exit your program.

Parameters

Input

Name	Туре	Description
objHandle	CAObjHandle	ActiveX Object handle one of the object creation functions in this library or an Automation server method returns.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_DisplayErrorInfo

Purpose

Displays in a dialog box the description associated with an error code and the error information an ERRORINFO structure contains. CA_DisplayErrorInfo formats and displays the sCode, wCode, source, description, and errorParamPos fields of the ERROINFO structure, unless they are NULL.

If the helpFile of the ERROINFO structure field is not NULL, the dialog box includes a **Help** button. To display the help file, click on the **Help** button.

Parameters

Name	Туре	Description
objHandle	CAObjHandle	Object handle you pass to the Automation server function or ActiveX Automation Library function that reported the error.
title	string	Title of the dialog box. If you pass NULL, Automation Error appears as the title.
errorCode	HRESULT	Error code an Automation server function or an ActiveX Automation Library function returns.
errorInfo	ERRORINFO	Structure the ActiveX Automation Library fills in when a server method fails. You can pass NULL for this parameter.

Input

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_FreeMemory

```
void CA_FreeMemory (void *memPtr);
```

Purpose

Frees memory allocated through the following sources:

- String output parameters of functions in an Automation Instrument Driver
- Strings that the following functions allocate: CA_VariantGetCString, CA_BSTRGetCString, and CA_VariantConvertToType
- Arrays that the following functions allocate: CA_SafeArrayTolDArray, CA_SafeArrayTo2DArray, CA_VariantGet1DArray, and CA_VariantGet2DArray
- String array elements of arrays that the following functions allocate: CA_SafeArrayTo1DArray, CA_SafeArrayTo2DArray, CA_SafeArrayTo1DArrayBuf, CA_SafeArrayTo2DArrayBuf, CA_VariantGet1DArray, CA_VariantGet2DArray, CA_VariantGet1DArrayBuf, and CA_VariantGet2DArrayBuf

Parameters

Input

Name	Туре	Description
memPtr	void pointer	Address of the memory to free.

Return Value

None.

CA_FreeUnusedServers

```
void FreeUnusedServers(void)
```

Purpose

Unloads ActiveX Automation server DLLs that you are no longer using.

For each server that is in DLL form, CA_UnloadUnusedServers unloads the server DLL if you have already called CA_DiscardObjectHandle on all object handles for that server. This includes object handles that you create by calling server methods, functions in the ActiveX Automation Library, and functions in generated automation controller instrument drivers that return object handles, such as New, Open, and Active.

This function has no effect on servers that are running in separate processes.

Parameters

None.

Return Value

None.

CA_GetActiveObjectByClassId

Purpose

Obtains a handle to an active Automation server object based on the Class ID of the object.

Parameters

Input

Name	Туре	Description
classID	GUID pointer	Class ID of the Automation server object; located in the server type library.
serverMachineName	string	Name or IP address of the computer on which you want to run the Automation server.

Output

Name	Туре	Description
objHandle	CAObjHandle	Handle to the server object you create.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **serverMachineName** can be either a UNC name ("\\server") or a DNS name ("home.server.com"). If you pass NULL for the **serverMachineName**, CA_GetActiveObjectByClassId looks for the active Automation server on the same computer as your program.

了 Note

Windows 95 and Windows NT 4.0 do not allow you to access active objects on remote machines. Future versions of these operating systems might support this functionality.

You can pass **objHandle** to other functions in this library to call methods of the Automation object or to get and set properties of the Automation object. When you no longer need **objHandle**, discard it by calling CA_DiscardObjHandle.

CA_GetActiveObjectByProgId

Purpose

Obtains a handle to an active Automation server object based on the Prog ID of the object.

Parameters

Input

Name	Туре	Description
progID	string	Prog ID of the Automation server object; located in the server documentation.
serverMachineName	string	Name or IP address of the computer on which you want to run the Automation server.

Output

Name	Туре	Description
objHandle	CAObjHandle	Handle to the server object you create.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **serverMachineName** can be either a UNC name ("\\server") or a DNS name ("home.server.com"). If you pass NULL for the **serverMachineName**, CA_GetActiveObjectByProgId looks for the active Automation server on the same computer as your program.

🕼 Note

Windows 95 and Windows NT 4.0 do not allow you to access active objects on remote machines. Future versions of these operating systems might support this functionality.

You can pass **objHandle** to other functions in this library to call methods of the Automation object or to get and set properties of the Automation object. When you no longer need **objHandle**, discard it by calling CA_DiscardObjHandle.

CA_GetAutomationErrorString

Purpose

Converts an error code number into a meaningful error string.

Parameters

Input

Name	Туре	Description
errorCode	HRESULT	Error code an Automation server function or an ActiveX Automation Library function returns.

Output

Name	Туре	Description
buffer	character array	Buffer into which CA_GetAutomationErrorString copies the error string.
bufferSize	unsigned integer	Number of bytes in buffer .

Return Value

None.

Parameter Discussion

If **buffer** cannot hold the entire error string, CA_GetAutomationErrorString copies (**bufferSize**-1) bytes into **buffer**, appended by the ASCII NUL byte.

CA_GetDispatchFromObjHandle

```
HRESULT status = CA_GetDispatchFromObjHandle (CAObjHandle objHandle,
                               LPDISPATCH *dispatchPtr);
```

Purpose

Obtains the Dispatch pointer associated with the CAObjHandle for an Automation server object. You can use the Dispatch pointer to call members of the server IDispatch interface, or you can pass the Dispatch pointer to Windows SDK functions.

CA_GetDispatchFromObjHandle does not invoke the AddRef method on the Dispatch pointer.

Parameters

Input

Name	Туре	Description
objHandle	CAObjHandle	ActiveX Object handle one of the object creation functions in this library or an Automation server method returns.

Output

Name	Туре	Description
dispatchPtr	LPDISPATCH	Dispatch pointer of the Automation server object objHandle identifies.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_GetLocale

HRESULT status = CA_GetLocale (CAObjHandle objHandle, LCID *locale);

Purpose

Obtains the language the Automation server uses to interpret the arguments it receives as parameters to its functions.

Parameters

Input

Name	Туре	Description
objHandle	CAObjHandle	ActiveX Object handle one of the object creation functions in this library or an Automation server method returns.

Output

Name	Туре	Description
locale	LCID	ID that indicates the language the Automation server uses. Refer to CA_SetLocale for a list of locale IDs.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_InvokeHelper

Purpose

Gets or sets the value of an Automation server property or invokes a method of an Automation server. Unlike CA_InvokeHelperV, CA_InvokeHelper accepts arguments to the server operation as comma-separated parameters.

🕼 Note

Automation Controller Instrument Drivers you generate with the ActiveX Automation Controller Wizard use CA_InvokeHelper. You do not need to call it directly.

Parameters

Input

Name	Туре	Description
objHandle	CAObjHandle	ActiveX Object handle one of the object creation functions in this library or an Automation server method returns.
methodOrPropertyID	integer	ID of the method or property you call or access; located in the server type library.
operation	integer	Type of operation you want the server to perform.
returnType	unsigned integer	Type of the return value (if any).
parameterCount	integer	Number of arguments you pass that follow parameterTypes .
parameterTypes	unsigned integer array	Data types of each argument that follows this parameter.
parameters	depends on the values in parameterTypes	Arguments to the Automation server operation. You must separate multiple arguments with commas.

Name	Туре	Description
errorInfo	ERRORINFO	Structure CA_InvokeHelper fills in when a server method fails. You can pass NULL.
returnValue	void pointer	The value (if any) the server method or property function returns.

Output

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

When an Automation server method invoked by CA_InvokeHelper fails with the error code DISP_E_EXCEPTION, CA_InvokeHelper stores descriptive information about the error in the **errorInfo** parameter. The descriptive information includes the error code, source, and description. It also can include a help file and help file context string.

When an Automation server method invoked by CA_InvokeHelper fails with the error codes DISP_E_PARAMNOTFOUND, DISP_E_TYPEMISMATCH, or E_INVALIDARG, CA_InvokeHelper might store the parameter position of the invalid argument in the errorParamPos member of the **errorInfo** structure.

You can pass NULL for the **errorInfo** parameter.

The operation parameter must be one of the values in Table 11-4.

Defined Constant	Type of Operation
DISPATCH_METHOD	Invoke a method.
DISPATCH_PROPERTYGET	Get a property value.
DISPATCH_PROPERTYPUT	Set a property value.
DISPATCH_PROPERTYPUTREF	Set a property value (pass a pointer to the value).

Table 11-4. operation Parameter Values

The value you pass for **returnType** depends on the **operation** parameter as shown in Table 11-5.

Operation	Return Type
DISPATCH_METHOD	Return type of the server function.
DISPATCH_PROPERTYGET	Data type of the property.
DISPATCH_PROPERTYPUT	Always CAVT_EMPTY.
DISPATCH_PROPERTYPUTREF	Always CAVT_EMPTY.

Table	11-5.	Return	Type	Values
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For DISPATCH_METHOD and DISPATCH_PROPERTYGET, the **returnType** can be any of the types in Table 11-2 in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter except CAVT_NULL. You can use the CAVT_ARRAY modifier on all data types except CAVT_EMPTY, CAVT_CSTRING, and CAVT_OBJHANDLE.

The value you pass for **parameterCount** depends on the **operation** parameter as shown in Table 11-6.

Operation	Parameter Count
DISPATCH_METHOD	Number of arguments to pass to the server function.
DISPATCH_PROPERTYGET	0
DISPATCH_PROPERTYPUT	1
DISPATCH_PROPERTYPUTREF	1

Table 11-6. Parameter Count Values

The value you pass for **parameterTypes** depends on the **operation** parameter as shown in Table 11-7.

Operation	Parameter Types
DISPATCH_METHOD	Array that contains the types of the arguments to the server function.
DISPATCH_PROPERTYGET	NULL
DISPATCH_PROPERTYPUT	Single-element array that contains the data type of the property.
DISPATCH_PROPERTYPUTREF	Single-element array that contains the data type of the property.

 Table 11-7.
 Parameter Types Values

The **parameterTypes** array can contain any of the data types in Table 11-2 except CAVT_NULL or CAVT_EMPTY. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter. You can use the CAVT_ARRAY modifier on all data types except CAVT_CSTRING and CAVT_OBJHANDLE. For parameters you pass by reference using DISPATCH_METHOD, you can use the CAVT_BYREFI, CAVT_BYREFO, or CAVT_BYREFIO modifier. For DISPATCH_PROPERTYPUTREF, you should add the CAVT_BYREFI modifier, but the ActiveX Automation Library adds it for you if you forget.

The values you pass for **parameters** depends on the **operation** parameter as shown in Table 11-8.

Operation	Parameters
DISPATCH_METHOD	Arguments to the server function. You must separate multiple arguments with commas.
DISPATCH_PROPERTYGET	Do not pass any arguments.
DISPATCH_PROPERTYPUT	Value to which you want to set the property.
DISPATCH_PROPERTYPUTREF	Pointer to the value to which you want to set the property.

Table 11-8.	Parameter Values
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The value CA_InvokeHelper returns in **returnValue** depends on the **operation** parameter as shown in Table 11-9.

Operation	Return Value
DISPATCH_METHOD	Value the server function returns. Pass a pointer to a variable of the data type returnType specifies.
DISPATCH_PROPERTYGET	Value of the property. Pass a pointer to a variable of the data type returnType specifies.
DISPATCH_PROPERTYPUT	None. Always pass NULL.
DISPATCH_PROPERTYPUTREF	None. Always pass NULL.

Table 11-9. Return Values

CA_InvokeHelperV

Purpose

Gets or sets the value of an Automation server property or invokes a method of an Automation server. Unlike CA_InvokeHelper, CA_InvokeHelperV accepts arguments to the server operation as a variable argument list.

C Note

Automation Controller Instrument Drivers you generate with the ActiveX Automation Controller Wizard use CA_InvokeHelperV. You do not need to call it directly.

Parameters

The parameters to CA_InvokeHelperV are the same as the parameters to CA_InvokeHelper except that you must pass the parameters to the Automation server operation as a variable argument list (va_list) that you initialize with the va_start macro.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_LoadObjectFromFile

Purpose

Creates an Automation server object and initializes it using data CA_LoadObjectFromFile reads from a file. The extension portion of the **filename** parameter identifies the Automation server to use. The contents of the file identifies the type of object to create and its initial data.

Parameters

Input

Name	Туре	Description
filename	string	Pathname of file that contains the type of object to create and its initial data. The extension indicates the Automation server to use.
serverMachineName	string	Name or IP address of the computer on which you want to run the Automation server.

Output

Name	Туре	Description
objHandle	CAObjHandle	Handle to the server object you create.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **serverMachineName** can be either a UNC name ("\\server") or a DNS name ("home.server.com").

If you pass NULL for the **serverMachineName** and a RemoteServerName registry entry exists for this server, the server runs on the computer the RemoteServerName entry specifies. If you pass NULL for this parameter and no RemoteServerName registry entry exists for this server, the server runs on the same computer as your program.

You can pass **objHandle** to other functions in this library to call methods of the Automation object or to get and set properties of the Automation object. When you no longer need **objHandle**, discard it by calling CA_DiscardObjHandle.

CA_LoadObjectFromFileByClassId

Purpose

Creates an Automation server object and initializes it using data CA_LoadObjectFromFileByClassId reads from a file. The **classID** parameter identifies the Automation server object. **filename** specifies the file that contains the initial data.

Parameters

Input

Name	Туре	Description
filename	string	Pathname of file that contains the initial data for the object.
classID	GUID pointer	Class ID of the Automation server object; located in the server type library.
serverMachineName	string	Name or IP address of the computer on which you want to run the Automation server.

Output

Name	Туре	Description
objHandle	CAObjHandle	Handle to the server object you create.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **serverMachineName** can be either a UNC name ("\\server") or a DNS name ("home.server.com").

If you pass NULL for the **serverMachineName** and a RemoteServerName registry entry exists for this server, the server runs on the computer the RemoteServerName entry specifies. If you pass NULL for this parameter and no RemoteServerName registry entry exists for this server, the server runs on the same computer as your program.

You can pass **objHandle** to other functions in this library to call methods of the Automation object or to get and set properties of the Automation object. When you no longer need **objHandle**, discard it by calling CA_DiscardObjHandle.

CA_LoadObjectFromFileByProgld

Purpose

Creates an Automation server object and initializes it using data CA_LoadObjectFromFileByProgId reads from a file. The **progID** parameter identifies the Automation server object. **filename** specifies the file that contains the initial data.

Parameters

Input

Name	Туре	Description
filename	string	Pathname of file that contains the initial data for the object.
progID	string	ProgID of the Automation server object; located in the server documentation.
serverMachineName	string	Name or IP address of the computer on which you want to run the Automation server.

Output

Name	Туре	Description
objHandle	CAObjHandle	Handle to the server object you create.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **serverMachineName** can be either a UNC name ("\\server") or a DNS name ("home.server.com").

If you pass NULL for the **serverMachineName** and a RemoteServerName registry entry exists for this server, the server runs on the computer the RemoteServerName entry specifies. If you pass NULL for this parameter and no RemoteServerName registry entry exists for this server, the server runs on the same computer as your program.

You can pass **objHandle** to other functions in this library to call methods of the Automation object or to get and set properties of the Automation object. When you no longer need **objHandle**, discard it by calling CA_DiscardObjHandle.

CA_MethodInvoke

Purpose

Invokes an Automation server method. Unlike CA_MethodInvokeV, CA_MethodInvoke accepts arguments to the server operation as comma-separated parameters.

C Note

Automation Controller Instrument Drivers you generate with the ActiveX Automation Controller Wizard use CA_MethodInvoke. You do not need to call it directly.

Parameters

Input

Name	Туре	Description
objHandle	CAObjHandle	ActiveX Object handle one of the object creation functions in this library or an Automation server method returns.
methodID	integer	ID of the method you call; located in the server type library.
returnType	unsigned integer	Data type of the return value of the server method.
parameterCount	integer	Number of arguments you pass that follow parameterTypes .
parameterTypes	unsigned integer array	Data types of each argument that follows this parameter.
parameters	depends on the values in parameterTypes	Arguments to the Automation server method. You must separate multiple arguments with commas.

Name	Туре	Description
errorInfo	ERRORINFO	Structure CA_MethodInvoke fills in when a server method fails. You can pass NULL.
returnValue	void pointer	The value the server method returns. Pass a pointer to a variable of the data type returnType specifies.

Output

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

When an Automation server method invoked by CA_MethodInvoke fails with the error code DISP_E_EXCEPTION, CA_MethodInvoke stores descriptive information about the error in the **errorInfo** parameter. The descriptive information includes the error code, source, and description. It also can include a help file and help file context string.

When an Automation server method invoked by CA_MethodInvoke fails with the error codes DISP_E_PARAMNOTFOUND, DISP_E_TYPEMISMATCH, or E_INVALIDARG, CA_MethodInvoke might store the parameter position of the invalid argument in the errorParamPos member of the **errorInfo** structure.

You can pass NULL for the **errorInfo** parameter.

The **returnType** can be any of the types in Table 11-2 except CAVT_NULL. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter. You can use the CAVT_ARRAY modifier on all data types except CAVT_EMPTY, CAVT_CSTRING, and CAVT_OBJHANDLE.

The **parameterTypes** array can contain any of the data types in Table 11-2 except CAVT_NULL or CAVT_EMPTY. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter. You can use the CAVT_ARRAY modifier on all data types except CAVT_CSTRING and CAVT_OBJHANDLE. For parameters you pass by reference, you can use the CAVT_BYREFI, CAVT_BYREFO, or CAVT_BYREFIO modifier.

CA_MethodInvokeV

Purpose

Invokes a method of an Automation server. Unlike CA_MethodInvoke, CA_MethodInvokeV accepts arguments to the server operation as a variable argument list.

Note

Automation Controller Instrument Drivers you generate with the ActiveX Automation Controller Wizard use CA_MethodInvokeV. You do not need to call it directly.

Parameters

The parameters to CA_MethodInvokeV are the same as the parameters to CA_MethodInvoke except that you must pass the parameters to the Automation server method as a variable argument list (va_list) that you initialize with the va_start macro.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_PropertyGet

Purpose

Obtains the value of the property of an Automation server object.

 Note
 Automation Controller Instrument Drivers you generate with the ActiveX

 Automation Controller Wizard use CA_PropertyGet. You do not need to call it directly.

Parameters

Input

Name	Туре	Description
objHandle	CAObjHandle	ActiveX Object handle one of the object creation functions in this library or an Automation server method returns.
propertyID	integer	ID of the automation server property; located in the server type library.
propertyType	unsigned integer	Data type of the property.

Output

Name	Туре	Description
errorInfo	ERRORINFO	Structure CA_PropertyGet fills in when a server function fails. You can pass NULL.
propertyValue	depends on the value of propertyType	Value the server method returns. Pass a pointer to a variable of the data type propertyType specifies.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

When an Automation server method invoked by CA_PropertyGet fails with the error code DISP_E_EXCEPTION, CA_PropertyGet stores descriptive information about the error in the **errorInfo** parameter. The descriptive information includes the error code, source, and description. It also can include a help file and help file context string.

When an Automation server method invoked by CA_PropertyGet fails with the error codes DISP_E_PARAMNOTFOUND, DISP_E_TYPEMISMATCH, or E_INVALIDARG, CA_PropertyGet might store the parameter position of the invalid argument in the errorParamPos member of the **errorInfo** structure.

You can pass NULL for the errorInfo parameter.

The **propertyType** can be any of the data types in Table 11-2 except CAVT_NULL or CAVT_EMPTY. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter. You can use the CAVT_ARRAY modifier on all data types except CAVT_CSTRING and CAVT_OBJHANDLE.

CA_PropertySet

Purpose

Sets the value of the property of an Automation server object. Unlike CA_SetPropertyV, CA_PropertySet accepts the property value as a simple parameter.

Note Note

Automation Controller Instrument Drivers you generate with the ActiveX Automation Controller Wizard use CA_PropertySet. You do not need to call it directly.

Parameters

Input

Name	Туре	Description
objHandle	CAObjHandle	ActiveX Object handle one of the object creation functions in this library or an Automation server method returns.
propertyID	integer	ID of the automation server property; located in the server type library.
propertyType	unsigned integer	Data type of the property.
propertyValue	depends on the value of propertyType	Value to which you want to set the property. Pass a value with the data type propertyType specifies. If propertyType is VARIANT, you can pass a value of any type.

Output

Name	Туре	Description
errorInfo	ERRORINFO	Structure CA_PropertySet fills in when a server function fails. You can pass NULL.

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

When an Automation server method invoked by CA_PropertySet fails with the error code DISP_E_EXCEPTION, CA_PropertySet stores descriptive information about the error in the **errorInfo** parameter. The descriptive information includes the error code, source, and description. It also can include a help file and help file context string.

When an Automation server method invoked by CA_PropertySet fails with the error codes DISP_E_PARAMNOTFOUND, DISP_E_TYPEMISMATCH, or E_INVALIDARG, CA_PropertySet might store the parameter position of the invalid argument in the errorParamPos member of the **errorInfo** structure.

The **propertyType** can be any of the data types in Table 11-2 except CAVT_NULL or CAVT_EMPTY. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter. You can use the CAVT_ARRAY modifier on all data types except CAVT_CSTRING and CAVT_OBJHANDLE.

CA_PropertySetByRef

Purpose

Sets the value of the property of an Automation server object. Unlike CA_SetProperty, CA_PropertySetByRef accepts a pointer to the property value. Unlike CA_SetPropertyByRefV, it accepts the pointer as a simple parameter.

 Note
 Automation Controller Instrument Drivers you generate with the ActiveX

 Automation Controller Wizard use CA_PropertySetByRef. You do not need to call it directly.

Parameters

Input

Name	Туре	Description
objHandle	CAObjHandle	ActiveX Object handle one of the object creation functions in this library or an Automation server method returns.
propertyID	integer	ID of the automation server property; located in the server type library.
propertyType	unsigned integer	Data type of the property.
pointerToValue	pointer to the type propertyType specifies	Pointer to the value to which you want to set the property. Must point to the data type propertyType specifies. If propertyType is VARIANT, you can pass a pointer to any type. If the propertyType includes the CAVT_ARRAY modifier, you must pass the address of a pointer to an array.

Output

Name	Туре	Description
errorInfo	ERRORINFO	Structure CA_PropertySetByRef fills in when a server function fails. You can pass NULL.

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

When an Automation server method invoked by CA_PropertySetByRef fails with the error code DISP_E_EXCEPTION, CA_PropertySetByRef stores descriptive information about the error in the **errorInfo** parameter. The descriptive information includes the error code, source, and description. It also can include a help file and help file context string.

When an Automation server method invoked by CA_PropertySetByRef fails with the error codes DISP_E_PARAMNOTFOUND, DISP_E_TYPEMISMATCH, or E_INVALIDARG, CA_PropertySetByRef might store the parameter position of the invalid argument in the errorParamPos member of the **errorInfo** structure.

The **propertyType** can be any of the data types in Table 11-2 except CAVT_NULL or CAVT_EMPTY. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter. You can use the CAVT_ARRAY modifier on all data types except CAVT_CSTRING and CAVT_OBJHANDLE. You should add the CAVT_BYREFI modifier, but the ActiveX Automation Library adds it for you if you forget.

CA_PropertySetByRefV

Purpose

Sets the value of the property of an Automation server object. Unlike CA_SetPropertyV, CA_PropertySetByRefV accepts a pointer to the property value. Unlike CA_SetPropertyByRef, it accepts the pointer as the single element in a variable argument list.

Note

Automation Controller Instrument Drivers you generate with the ActiveX Automation Controller Wizard use CA_PropertySetByRefV. You do not need to call it directly.

Parameters

The parameters to CA_PropertySetByRefV are the same as the parameters to CA_PropertySetByRef except that you pass **pointerToValue** as a variable argument list (va_list) that you initialize with the va_start macro.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_PropertySetV

Purpose

Sets the value of the property of an Automation server object. Unlike CA_SetProperty, CA_PropertySetV accepts the property value as the single element in a variable argument list.

Note 🕞

Automation Controller Instrument Drivers you generate with the ActiveX Automation Controller Wizard use CA_PropertySetV. You do not need to call it directly.

Parameters

The parameters to CA_PropertySetV are the same as the parameters to CA_PropertySet except that you pass **propertyValue** as a variable argument list (va_list) that you initialize with the va_start macro.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_SafeArrayDestroy

HRESULT status = CA_SafeArrayDestroy (LPSAFEARRAY safeArray);

Purpose

Frees the memory a safe array uses.

Do not call CA_SafeArrayDestroy on a safe array if you pass the safe array to one of the Safe Array-to-C Array conversion functions. The Safe Array-to-C Array conversion functions free the safe array.

Parameter

Input

Name	Туре	Description
safeArray	LPSAFEARRAY	Safe array to free.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_SafeArrayGet1DSize

Purpose

Obtains the number of elements in a 1D safe array.

Parameters

Input

Name	Туре	Description
safeArray	LPSAFEARRAY	1D safe array.

Output

Name	Туре	Description
numElements	unsigned integer	Number of elements in the safe array.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_SafeArrayGet2DSize

Purpose

Obtains the number of elements in a 2D safe array.

Parameters

Input

Name	Туре	Description
safeArray	LPSAFEARRAY	2D safe array.

Output

Name	Туре	Description
numElemsDim1	unsigned integer	Number of elements in the first dimension of the safe array.
numElemsDim2	unsigned integer	Number of elements in the second dimension of the safe array.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_SafeArrayGetNumDims

Purpose

Obtains the number of dimensions in a safe array.

Parameters

Input

Name	Туре	Description
safeArray	LPSAFEARRAY	Safe array.

Output

Name	Туре	Description
numDims	unsigned integer	Number of dimensions in the safe array.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_SafeArrayTo1DArray

Purpose

Converts a 1D safe array into a dynamically allocated C-style array.

Upon success, CA_SafeArrayTolDArray frees the contents of the safe array and sets the safe array pointer to NULL.

Parameters

Input/Output

Name	Туре	Description
safeArray	LPSAFEARRAY	1D safe array. Pass the address of the safe array pointer. CA_SafeArrayTo1DArray frees the safe array contents and sets the safe array pointer to NULL.

Input

Name	Туре	Description
аггауТуре	unsigned integer	Data type of the array CA_SafeArrayTolDArray creates from the safe array.

Output

Name	Туре	Description
array	depends on the value of arrayType	C-style array that CA_SafeArrayTo1DArray dynamically allocates. The type of the array must be the same as arrayType . Pass the address of an array pointer.
numElements	unsigned integer	Number of elements in array . You can pass NULL for this parameter.

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **arrayType** parameter must be the same as the type of the safe array except for the following cases:

- You can create a C-style array that contains char* elements from a BSTR safe array.
- You can create a C-style array that contains CAObjHandle elements from an LPDISPATCH safe array.

arrayType can be any of the data types in Table 11-2 except CAVT_EMPTY or CAVT_NULL. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter. CA_SafeArrayTo1DArray ignores the CAVT_ARRAY modifier.

When you no longer need the C-style array, call CA_FreeMemory to discard it. If the C-style array contains elements of one of the data types in Table 11-10, use the corresponding function to free each element when you no longer need it.

Data Type	Function to Free Each Element	
char *	CA_FreeMemory	
CAObjHandle	CA_DiscardObjHandle	
BSTR	SysFreeString (a Windows SDK function)	
LPUNKNOWN	<pre>Release(array[i]->lpVtbl->Release())</pre>	
LPDISPATCH	<pre>Release(array[i]->lpVtbl->Release())</pre>	
VARIANT	CA_VariantClear	

Table 11-10. Data Types and Function	ons to Free Each Element for CA_SafeArrayTo1DArray
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Example

The following code shows you how to use CA_SafeArrayTolDarray:

CA_SafeArrayTo1DArrayBuf

Purpose

Converts a 1D safe array into a C-style array you pass as a buffer.

Upon success, CA_SafeArrayTo1DArrayBuf frees the contents of the safe array and sets the safe array pointer to NULL.

CA_SafeArrayTo1DArrayBuf returns an error if the buffer is not big enough to hold the array.

Parameters

Input/Output

Name	Туре	Description
safeArray	LPSAFEARRAY	1D safe array. Pass the address of the safe array pointer. CA_SafeArrayTo1DArrayBuf frees the safe array contents and sets the safe array pointer to NULL.

Input

Name	Туре	Description
аггауТуре	unsigned integer	Data type of the array CA_SafeArrayTo1DArrayBuf creates from the safe array.
bufferSize	unsigned integer	Number of bytes in the arrayBuffer parameter.

Name	Туре	Description
arrayBuffer	depends on the value of arrayType	Buffer to receive the C-style array elements. The type of the array must be the same as arrayType .
numElements	unsigned integer	Number of elements CA_SafeArrayTo1DArrayBuf stores in arrayBuffer . You can pass NULL for this parameter.

Output

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **arrayType** parameter must be the same as the type of the safe array except for the following cases:

- You can create a C-style array that contains char* elements from a BSTR safe array.
- You can create a C-style array that contains CAObjHandle elements from an LPDISPATCH safe array.

arrayType can be any of the data types in Table 11-2 except CAVT_EMPTY or CAVT_NULL. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter. CA_SafeArrayTo1DArrayBuf ignores the CAVT_ARRAY modifier.

If the C-style array contains elements of one of the data types in Table 11-11, use the corresponding function to free each element when you no longer need it.

Data Type	Function to Free Each Element	
char *	CA_FreeMemory	
CAObjHandle	CA_DiscardObjHandle	
BSTR	SysFreeString (a Windows SDK function)	
LPUNKNOWN	<pre>Release (array[i]->lpVtbl->Release())</pre>	

 Table 11-11.
 Data Types and Functions to Free Each CA_SafeArrayTo1DArrayBuf Element

 Table 11-11.
 Data Types and Functions to Free Each CA_SafeArrayTo1DArrayBuf Element

Data Type	Function to Free Each Element	
LPDISPATCH	<pre>Release(array[i]->lpVtbl->Release())</pre>	
VARIANT	CA_VariantClear	

Example

The following code shows you how to use CA_SafeArrayTolDArrayBuf:

CA_SafeArrayTo2DArray

Purpose

Converts a 2D safe array into a dynamically allocated C-style array.

Upon success, CA_SafeArrayTo2DArray frees the contents of the safe array and sets the safe array pointer to NULL.

Parameters

Input/Output

Name	Туре	Description
safeArray	LPSAFEARRAY	2D safe array. Pass the address of the safe array pointer. CA_SafeArrayTo2DArray frees the safe array contents and sets the safe array pointer to NULL.

Input

Name	Туре	Description
аггауТуре	unsigned integer	Data type of the array CA_SafeArrayTo2DArray creates from the safe array.

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Name	Туре	Description
array	depends on the value of arrayType	C-style array that CA_SafeArrayTo2DArray dynamically allocates. The type of the array must be the same as arrayType . Pass the address of an array pointer.
numElemsDim1	unsigned integer	Number of elements in the first dimension of array . You can pass NULL for this parameter.
numElemsDim2	unsigned integer	Number of elements in the second dimension of array . You can pass NULL for this parameter.

Output

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **arrayType** parameter must be the same as the type of the safe array except for the following cases:

- You can create a C-style array that contains char* elements from a BSTR safe array.
- You can create a C-style array that contains CAObjHandle elements from an LPDISPATCH safe array.

arrayType can be any of the data types in Table 11-2 except CAVT_EMPTY OF CAVT_NULL. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter. CA_SafeArrayTo2DArray ignores the CAVT_ARRAY modifier.

To access the elements of **array**, use the CA_Get2DArrayElement macro, which is declared in cviauto.h.

When you no longer need the C-style array, call CA_FreeMemory to discard it. If the C-style array contains elements of one of the data types in Table 11-12, use the corresponding function to free each element when you no longer need it.

Data Type	Function to Free Each Element	
char *	CA_FreeMemory	
CAObjHandle	CA_DiscardObjHandle	
BSTR	SysFreeString (a Windows SDK function)	
LPUNKNOWN	<pre>Release(array[i]->lpVtbl->Release())</pre>	
LPDISPATCH	<pre>Release(array[i]->lpVtbl->Release())</pre>	
VARIANT	CA_VariantClear	

Table 11-12. Data Types and Functions to Free Each Element for CA_SafeArrayTo2DArray

Example

The following code shows you how to use CA_SafeArrayTo2Darray:

```
double *dblArray = NULL;
LPSAFEARRAY safeArray;
unsigned numElemsDim1, numElemsDim2;
int index1, index2;
/* Call an ActiveX Automation function that returns a safe array. */
/* Convert the safe array into a C-style array. */
CA_SafeArrayTo2DArray(&safeArray, CAVT_DOUBLE, &dblArray,
                      &numElemsDim1, &numElemsDim2);
for (index1 = 0; index1 < numElemsDim1; index1++)</pre>
   for (index2 = 0; index2 < numElemsDim2; index2++)</pre>
       {
      double d;
      d = CA_Get2DArrayElement(dblArray, numElemsDim1, numElemsDim2,
                                index1, index2, double);
      printf("%f", d);
       }
/* Free the allocated array. */
CA_FreeMemory(dblArray);
```

CA_SafeArrayTo2DArrayBuf

Purpose

Converts a 2D safe array into a C-style array you pass in as a buffer.

Upon success, CA_SafeArrayTo2DArrayBuf frees the contents of the safe array and sets the safe array pointer to NULL.

CA_SafeArrayTo2DArrayBuf returns an error if the buffer is not big enough to hold the array.

Parameters

Input/Output

Name	Туре	Description
safeArray	LPSAFEARRAY	2D safe array. Pass the address of the safe array pointer. CA_SafeArrayTo2DArrayBuf frees the safe array contents and sets the safe array pointer to NULL.

Input

Name	Туре	Description
аггауТуре	unsigned integer	Data type of the array CA_SafeArrayTo2DArrayBuf creates from the safe array.
bufferSize	unsigned integer	Number of bytes in the arrayBuffer parameter.

Name	Туре	Description
arrayBuffer	depends on the value of arrayType	Buffer to receive the C-style array elements. The type of the array must be the same as arrayType .
numElemsDim1	unsigned integer	Number of elements in the first dimension of array . You can pass NULL for this parameter.
numElemsDim2	unsigned integer	Number of elements in the second dimension of array . You can pass NULL for this parameter.

Output

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **arrayType** parameter must be the same as the type of the safe array except for the following cases:

- You can create a C-style array that contains char* elements from a BSTR safe array.
- You can create a C-style array that contains CAObjHandle elements from an LPDISPATCH safe array.

arrayType can be any of the data types in Table 11-2 except CAVT_EMPTY or CAVT_NULL. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter. CA_SafeArrayTo2DArrayBuf ignores the CAVT_ARRAY modifier.

To access the elements of **array**, use the CA_Get2DArrayElement macro, which is declared in cviauto.h.

If the C-style array contains elements of one of the data types in Table 11-13, use the corresponding function to free each element when you no longer need it.

Data Type	Function to Free Each Element	
char*	CA_FreeMemory	
CAObjHandle	CA_DiscardObjHandle	
BSTR	SysFreeString (a Windows SDK function)	
LPUNKNOWN	<pre>Release (array[i]->lpVtbl->Release())</pre>	
LPDISPATCH	Release(array[i]->lpVtbl->Release())	
VARIANT	CA_VariantClear	

Table 11-13. Data Types and Functions to Free Each Element for CA_SafeArrayTo2DArrayBuf

Example

The following code shows you how to use CA_SafeArrayTo2DArrayBuf:

```
double dblArray[1024];
LPSAFEARRAY safeArray;
unsigned numElemsDim1, numElemsDim2;
int index1, index2;
/* Call an ActiveX Automation function that returns a safe array. */
/* Convert the safe array into a C-style array. */
CA_SafeArrayTo2DArrayBuf(&safeArray, CAVT_DOUBLE, dblArray,
                          sizeof(dblArray), &numElemsDim1,
                          &numElemsDim2);
for (index1 = 0; index1 < numElemsDim1; index1++)</pre>
   for (index2 = 0; index2 < numElemsDim2; index2++)</pre>
       {
      double d;
      d = CA_Get2DArrayElement(dblArray, numElemsDim1, numElemsDim2,
                                 index1, index2, double);
      printf("%f", d);
       }
```

CA_SetLocale

HRESULT status = CA_SetLocale (CAObjHandle objHandle, LCID locale);

Purpose

Sets the language the Automation server uses to interpret the arguments it receives as parameters to its functions.

If you do not call CA_SetLocale, the ActiveX Automation Library asks the Automation server to use LANG_NEUTRAL, which signifies the default language of the server.

Parameters

Input

Name	Туре	Description
objHandle	CAObjHandle	ActiveX Object handle one of the object creation functions in this library or an Automation server method returns.
locale	LCID	ID that indicates the language the Automation server uses. Refer to the following <i>Parameter Discussion</i> section.

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The locale can be any of the locales that the Automation server you are using supports. The following list shows the defined constant for locale ID:

LANG_NEUTRAL LANG_AFRIKAANS LANG_ALBANIAN LANG_BASQUE LANG_BELARUSIAN LANG_BULGARIAN LANG_CATALAN LANG_CHINESE LANG_CROATIAN LANG_CZECH LANG_DANISH LANG_DUTCH LANG_ENGLISH LANG_ESTONIAN LANG_FAEROESE LANG_FARSI LANG_FINNISH LANG_FRENCH LANG_GERMAN LANG_GREEK LANG_HEBREW LANG_HUNGARIAN LANG_ICELANDIC LANG_INDONESIAN LANG_ITALIAN LANG_JAPANESE LANG_KOREAN LANG_LATVIAN LANG_LITHUANIAN LANG_NORWEGIAN LANG_POLISH LANG_PORTUGUESE LANG_ROMANIAN LANG_RUSSIAN LANG_SERBIAN LANG_SLOVAK LANG_SLOVENIAN LANG_SPANISH LANG_SWEDISH LANG_THAI LANG_TURKISH LANG_UKRAINIAN LANG_VIETNAMESE

CA_VariantBool

VARIANT variant = CA_VariantBool (VBOOL boolValue);

Purpose

Converts a VBOOL value into a variant that contains the VBOOL value. Use CA_VariantBool to pass a VBOOL value as a variant parameter.

Parameter

Input

Name	Туре	Description
boolValue	VBOOL	Value to store in the variant.

Name	Туре	Description
variant	VARIANT	Variant that contains the value in boolValue .

CA_VariantBSTR

VARIANT variant = CA_VariantBSTR (BSTR BSTRValue);

Purpose

Converts a BSTR into a variant that contains a BSTR. Use CA_VariantBSTR to pass a BSTR value as a variant parameter.

Parameter

Input

Name	Туре	Description
BSTRValue	BSTR	Value to store in the variant.

Name	Туре	Description
variant	VARIANT	Variant that contains the value in BSTRValue .

CA_VariantClear

HRESULT status = CA_VariantClear (VARIANT *variant);

Purpose

Frees the contents of a variant and marks the variant as empty.

Although you can call CA_VariantClear on a variant that contains a value of any type, CA_VariantClear frees resources only when the variant contains a string (BSTR), an automation object interface (LPDISPATCH), or an unknown interface (LPUNKNOWN).

CA_VariantClear always sets the variant type to VT_EMPTY.

Do not call CA_VariantClear on a variant that you have not initialized. You can initialize a variant using any of the CA_VariantSet functions.

Parameter

Input

Name	Туре	Description
variant	VARIANT	Variant whose contents you want to clear.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantConvertToType

Purpose

Converts a value in a variant to a variable with a data type you specify. This can help you when you are uncertain about the data type a variant stores and when you need to work with a particular data type.

CA_VariantConvertToType converts all the fundamental types, such as numeric, string, DATE, CURRENCY, and so on. It converts from a pointer to a value by dereferencing the pointer. It cannot convert to a pointer type, and it cannot convert to or from array types unless the **desiredType** is exactly the same as the type in the variant.

Upon success, CA_VariantConvertToType frees the contents of the variant parameter, marks it as empty, and sets the type to VT_EMPTY.

Parameters

Input

Name	Туре	Description
variant	VARIANT	Variant that contains the value to convert. CA_VariantConvertToType frees the variant contents and marks the variant as empty.
desiredType	unsigned integer	Type to convert the variant value to.

Output

Name	Туре	Description
convertedValue	depends on the value of desiredType	Address of a variable large enough to hold the converted value.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

desiredType can be any of the fundamental data types in Table 11-2 except CAVT_EMPTY or CAVT_NULL. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter. You can use the CAVT_ARRAY modifier.

C Note

If you use the CAVT_ARRAY modifier, CA_VariantConvertToType returns a safe array, not a C-style array.

If the **desiredType** is one of the data types in Table 11-14, you must call the corresponding function to free the **convertedValue** when you no longer need it.

Data Type	Function to Free Converted Value
char *	CA_FreeMemory
CAObjHandle	CA_DiscardObjHandle
BSTR	SysFreeString (a Windows SDK function)
LPUNKNOWN	<pre>Release(convertedValue->lpVtbl.Release())</pre>
LPDISPATCH	Release(convertedValue->lpVtbl.Release())
any type CAVT_ARRAY	CA_SafeArrayDestroy

Table 11-14. Data Types and Functions to Free the Converted Value

CA_VariantCopy

```
HRESULT status = CA_VariantCopy (VARIANT *sourceVariant,
VARIANT *destinationVariant);
```

Purpose

Copies the contents of one variant to another variant. CA_VariantCopy makes a deep copy of the source variant by duplicating any allocated data that it contains.

Parameters

Input

Name	Туре	Description
sourceVariant	pointer to VARIANT	Pointer to the variant that contains the value to copy.

Output

Name	Туре	Description
destinationVariant	VARIANT	Variant into which CA_VariantCopy copies the sourceVariant contents.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\3sdk\winerror.h for Windows SDK error codes.

CA_VariantCurrency

VARIANT variant = CA_VariantCurrency (CURRENCY currencyValue);

Purpose

Converts a CURRENCY value into a variant that contains the CURRENCY value. Use CA_VariantCurrency to pass a CURRENCY value as a variant parameter.

Parameter

Input

Name	Туре	Description
currencyValue	CURRENCY	Value to store in the variant.

Name	Туре	Description
variant	VARIANT	Variant that contains the value in currencyValue .

CA_VariantDate

VARIANT variant = CA_VariantDate (DATE dateValue);

Purpose

Converts a DATE value into a variant that contains the DATE value. Use CA_VariantDate to pass a DATE value as a variant parameter.

Parameter

Input

Name	Туре	Description
dateValue	DATE	Value to store in the variant.

Name	Туре	Description
variant	VARIANT	Variant that contains the value in dateValue .

CA_VariantDispatch

VARIANT variant = CA_VariantDispatch (LPDISPATCH dispatchValue);

Purpose

Converts a LPDISPATCH value into a variant that contains the LPDISPATCH value. Use CA_VariantDispatch to pass a LPDISPATCH value as a variant parameter.

Parameter

Input

Name	Туре	Description
dispatchValue	LPDISPATCH	Value to store in the variant.

Name	Туре	Description
variant	VARIANT	Variant that contains the value in dispatchValue .

CA_VariantDouble

VARIANT variant = CA_VariantDouble (double doubleValue);

Purpose

Converts a double-precision value into a variant that contains the double-precision value. Use CA_VariantDouble to pass a double-precision value as a variant parameter.

Parameter

Input

Name	Туре	Description
doubleValue	double-precision	Value to store in the variant.

Name	Туре	Description
variant	VARIANT	Variant that contains the value in doubleValue .

CA_VariantEmpty

VARIANT variant = CA_VariantEmpty (void);

Purpose

Returns a variant in which the value of the type field is VT_EMPTY. Use CA_VariantEmpty to pass an empty variant as a parameter.

Parameters

None.

Name	Туре	Description
variant	VARIANT	Variant in which the value of the type field is VT_EMPTY.

CA_VariantError

VARIANT variant = CA_VariantError (SCODE errorValue);

Purpose

Converts an SCODE value into a variant that contains the SCODE value. SCODE is the data type for an error value. Use CA_VariantError to pass an SCODE value as a variant parameter.

Parameter

Input

Name	Туре	Description
errorValue	SCODE	Value to store in the variant.

Name	Туре	Description
variant	VARIANT	Variant that contains the value in errorValue .

CA_VariantFloat

VARIANT variant = CA_VariantFloat (float floatValue);

Purpose

Converts a single-precision, floating-point value into a variant that contains the single-precision value. Use CA_VariantFloat to pass a single-precision value as a variant parameter.

Parameter

Input

Name	Туре	Description
floatValue	single-precision	Value to store in the variant.

Name	Туре	Description
variant	VARIANT	Variant that contains the value in floatValue .

CA_VariantGet1DArray

Purpose

Converts a 1D safe array in a variant parameter into a dynamically allocated C-style array.

Upon success, CA_VariantGet1DArray frees the contents of the variant parameter and marks it as empty.

Parameters

Input/Output

Name	Туре	Description
variant	VARIANT	Pointer to a variant that contains a 1D safe array. CA_VariantGet1DArray frees the contents of the variant contents and marks it as empty.

Input

Name	Туре	Description
аггауТуре	unsigned integer	Data type of the array CA_VariantGet1DArray creates from the safe array.

Output

Name	Туре	Description
array	depends on the value of arrayType	C-style array that CA_VariantGet1DArray dynamically allocates. The type of the array must be the same as arrayType . Pass the address of an array pointer.
numElements	unsigned integer	Number of elements in array . You can pass NULL for this parameter.

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **arrayType** parameter must be the same as the type of the safe array except for the following cases:

- You can create a C-style array that contains char* elements from a BSTR safe array.
- You can create a C-style array that contains CAObjHandle elements from an LPDISPATCH safe array.

arrayType can be any of the data types in Table 11-2 except CAVT_EMPTY or CAVT_NULL. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter. CA_VariantGet1DArray ignores the CAVT_ARRAY modifier.

If you do not know the type of the array, you can call CA_VariantGetType and pass its return value as the **arrayType**.

When you no longer need the C-style array, call CA_FreeMemory to discard it. If the C-style array contains elements of one of the data types in Table 11-15, use the corresponding function to free each element when you no longer need it.

Data Type	Function to Free Each Element	
char *	CA_FreeMemory	
CAObjHandle	CA_DiscardObjHandle	
BSTR	SysFreeString (a Windows SDK function)	
LPUNKNOWN	<pre>Release(array[i]->lpVtbl->Release())</pre>	
LPDISPATCH	<pre>Release (array[i]->lpVtbl->Release())</pre>	
VARIANT	CA_VariantClear	

Example

The following code shows you how to use CA_VariantGet1Darray:

```
double *dblArray = NULL;
VARIANT variant;
unsigned numElements;
int index;
/* Call an ActiveX Automation function that returns a safe array in a
Variant. */
.
.
/* Convert the safe array the variant contains into a C-style array. */
CA_VariantGet1DArray(&variant, CAVT_DOUBLE, &dblArray, &numElements);
for (index = 0; index < numElements; index++)
    printf("%f", dblArray[index]);
/* Free the allocated array. */
CA_FreeMemory(dblArray);
```

CA_VariantGet1DArrayBuf

Purpose

Converts a 1D safe array in a variant parameter into a C-style array you pass as a buffer.

On success, CA_VariantGet1DArrayBuf releases the contents of the variant parameter and marks it as empty.

CA_VariantGet1DArrayBuf returns an error if the buffer is not big enough to hold the array.

Parameters

Input/Output

Name	Туре	Description
variant	VARIANT	Pointer to a variant that contains a 1D safe array. CA_VariantGet1DArrayBuf frees the contents of the variant contents and marks it as empty.

Input

Name	Туре	Description
аггауТуре	unsigned integer	Data type of the array CA_VariantGet1DArrayBuf creates from the safe array.
bufferSize	unsigned integer	Number of bytes in the arrayBuffer parameter.

Name	Туре	Description
arrayBuffer	depends on the value of arrayType	Buffer to receive the C-style array elements. The type of the array must be the same as arrayType .
numElements	unsigned integer	Number of elements CA_VariantGet1DArrayBuf stores in arrayBuffer . You can pass NULL for this parameter.

Output

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **arrayType** parameter must be the same as the type of the safe array except for the following cases:

- You can create a C-style array that contains char* elements from a BSTR safe array.
- You can create a C-style array that contains CAObjHandle elements from an LPDISPATCH safe array.

arrayType can be any of the data types in Table 11-2 except CAVT_EMPTY or CAVT_NULL.Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter. CA_VariantGet1DArrayBuf ignores the CAVT_ARRAY modifier.

If you do not know the type of the array, you can call CA_VariantGetType and pass its return value as the **arrayType**.

If the C-style array contains elements of one of the data types in Table 11-16, use the corresponding function to free each element when you no longer need it.

Data Type	Function to Free Each Element	
char *	CA_FreeMemory	
CAObjHandle CA_DiscardObjHandle		
BSTR	SysFreeString (a Windows SDK function)	
LPUNKNOWN Release(array[i]->lpVtbl->Release())		
LPDISPATCH Release (array[i]->lpVtbl->Release())		
VARIANT	CA_VariantClear	

Table 11-16. Data Types and Functions to Free Each Element for CA_VariantGet1DArrayBuf

Example

The following code shows you how to use CA_VariantGet1DArrayBuf:

CA_VariantGet1DArraySize

Purpose

Obtains the number of elements in a 1D safe array in the variant you specify.

Parameters

Input

Name	Туре	Description
variant	VARIANT	Pointer to a variant that contains a 1D safe array.

Output

Name	Туре	Description
numElements	unsigned integer	Number of elements in the safe array.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGet2DArray

Purpose

Converts a 2D safe array in a variant parameter into a dynamically allocated C-style array.

Upon success, CA_VariantGet2DArray frees the contents of the variant parameter and marks it as empty.

Parameters

Input/Output

Name	Туре	Description
variant	VARIANT	Pointer to a variant that contains a 2D safe array. CA_VariantGet2DArray frees the contents of the variant contents and marks it as empty.

Input

Name	Туре	Description
аггауТуре	unsigned integer	Data type of the array CA_VariantGet2DArray creates from the safe array.

Name	Туре	Description
array	depends on the value of arrayType	C-style array that CA_VariantGet2DArray dynamically allocates. The type of the array must be the same as arrayType . Pass the address of an array pointer.
numElemsDim1	unsigned integer	Number of elements in the first dimension of array . You can pass NULL for this parameter.
numElemsDim2	unsigned integer	Number of elements in the second dimension of array . You can pass NULL for this parameter.

Output

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **arrayType** parameter must be the same as the type of the safe array except for the following cases:

- You can create a C-style array that contains char* elements from a BSTR safe array.
- You can create a C-style array that contains CAObjHandle elements from an LPDISPATCH safe array.

arrayType can be any of the data types in Table 11-2 except CAVT_EMPTY or CAVT_NULL. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter. CA_VariantGet2Darray ignores the CAVT_ARRAY modifier.

If you do not know the type of the array, you can call CA_VariantGetType and pass its return value as the **arrayType**.

To access the elements of **array**, use the CA_Get2DArrayElement macro, which is declared in cviauto.h.

When you no longer need the C-style array, call CA_FreeMemory to discard it. If the C-style array contains elements of one of the data types in Table 11-17, use the corresponding function to free each element when you no longer need it.

Data Type Function to Free Each Element	
char *	CA_FreeMemory
CAObjHandle	CA_DiscardObjHandle
BSTR	SysFreeString (a Windows SDK function)
LPUNKNOWN	<pre>Release(array[i]->lpVtbl->Release())</pre>
LPDISPATCH	<pre>Release(array[i]->lpVtbl->Release())</pre>
VARIANT	CA_VariantClear

Table 11-17.	Data Type	s and Functions	to Free Each	Element for CA	_VariantGet2DArray
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Example

The following code shows you how to use CA_VariantGet2Darray:

```
double *dblArray = NULL;
VARIANT variant;
unsigned numElemsDim1, numElemsDim2;
int index1, index2;
/* Call an ActiveX Automation function that returns a safe array in a
Variant. */
/* Convert the safe array the variant contains into a C-style array. */
CA_VariantGet2DArray(&variant, CAVT_DOUBLE, &dblArray, &numElemsDim1,
                     &numElemsDim2);
for (index1 = 0; index1 < numElemsDim1; index1++)</pre>
   for (index2 = 0; index2 < numElemsDim2; index2++)</pre>
       double d;
       d = CA_Get2DArrayElement(dblArray, numElemsDim1, numElemsDim2,
                                 index1, index2, double);
       printf("%f", d);
       }
/* Free the allocated array. */
CA_FreeMemory(dblArray);
```

CA_VariantGet2DArrayBuf

Purpose

Converts a 2D safe array in a variant parameter into a C-style array you pass as a buffer.

On success, CA_VariantGet2DArrayBuf releases the contents of the variant parameter and marks it as empty.

CA_VariantGet2DArrayBuf returns an error if the buffer is not big enough to hold the array.

Parameters

Input/Output

Name	Туре	Description
variant	VARIANT	Pointer to a variant that contains a 2D safe array. CA_VariantGet2DArrayBuf frees the contents of the variant contents and marks it as empty.

Input

Name	Туре	Description
аггауТуре	unsigned integer	Data type of the array CA_VariantGet2DArrayBuf creates from the safe array.
bufferSize	unsigned integer	Number of bytes in the arrayBuffer parameter.

Name	Туре	Description
arrayBuffer	depends on the value of arrayType	Buffer to receive the C-style array elements. The type of the array must be the same as arrayType .
numElemsDim1	unsigned integer	Number of elements in the first dimension of array . You can pass NULL for this parameter.
numElemsDim2	unsigned integer	Number of elements in the second dimension of array . You can pass NULL for this parameter.

Output

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **arrayType** parameter must be the same as the type of the safe array except for the following cases:

- You can create a C-style array that contains char* elements from a BSTR safe array.
- You can create a C-style array that contains CAObjHandle elements from an LPDISPATCH safe array.

arrayType can be any of the data types in Table 11-2 except CAVT_EMPTY or CAVT_NULL. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter. CA_VariantGet2DArrayBuf ignores the CAVT_ARRAY modifier.

If you do not know the type of the array, you can call CA_VariantGetType and pass its return value as the **arrayType**.

To access the elements of **array**, use the CA_Get2DArrayElement macro, which is declared in cviauto.h.

If the C-style array contains elements of one of the data types in Table 11-18, use the corresponding function to free each element when you no longer need it.

Data Type	Function to Free Each Element	
char *	CA_FreeMemory	
CAObjHandle	CA_DiscardObjHandle	
BSTR	SysFreeString (a Windows SDK function)	
LPUNKNOWN	<pre>Release(array[i]->lpVtbl->Release())</pre>	
LPDISPATCH	<pre>Release(array[i]->lpVtbl->Release())</pre>	
VARIANT	CA_VariantClear	

Table 11-18. Data Types and Functions to Free Each Element for CA_VariantGet2DArrayBuf

Example

The following code shows you how to use CA_VariantGet2DArrayBuf:

```
double dblArray[1024];
VARIANT variant;
unsigned numElemsDim1, numElemsDim2;
int index1, index2;
/* Call an ActiveX Automation function that returns a safe array in a
Variant. */
/* Convert the safe array the variant contains into a C-style array. */
CA_VariantGet2DArrayBuf(&variant, CAVT_DOUBLE, dblArray,
                        sizeof(dblArray), &numElemsDim1,
&numElemsDim2);
for (index1 = 0; index1 < numElemsDim1; index1++)</pre>
   for (index2 = 0; index2 < numElemsDim2; index2++)</pre>
       {
       double d;
       d = CA_Get2DArrayElement(dblArray, numElemsDim1, numElemsDim2,
                                 index1, index2, double);
       printf("%f", d);
       }
```

CA_VariantGet2DArraySize

Purpose

Obtains the number of elements in a 2D safe array in the variant parameter you specify.

Parameters

Input

Name	Туре	Description
variant	VARIANT	Pointer to a variant that contains a 2D safe array.

Output

Name	Туре	Description
numElemsDim1	unsigned integer	Number of elements in the first dimension of the safe array.
numElemsDim2	unsigned integer	Number of elements in the second dimension of the safe array.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetArrayNumDims

Purpose

Obtains the number of dimensions in a safe array in the variant you specify.

Parameters

Input

Name	Туре	Description
variant	VARIANT	Pointer to a variant that contains a safe array.

Output

Name	Туре	Description
numDims	unsigned integer	Number of dimensions in the safe array.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetBool

HRESULT status = CA_VariantGetBool (VARIANT *variant, VBOOL *boolValue);

Purpose

Copies the value in a variant into a VBOOL variable.

CA_VariantGetBool returns an error if the variant does not contain a VBOOL value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a VBOOL value.

Output

Name	Туре	Description
boolValue	VBOOL	VBOOL value CA_VariantGetBool copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetBoolPtr

Purpose

Copies the value in a variant into a VBOOL pointer variable.

CA_VariantGetBoolPtr returns an error if the variant does not contain a pointer to a VBOOL value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a VBOOL pointer.

Output

Name	Туре	Description
boolValueP	r pointer to VBOOL	VBOOL pointer CA_VariantGetBoolPtr copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetBSTR

HRESULT status = CA_VariantGetBSTR (VARIANT *variant, BSTR *BSTRValue);

Purpose

Copies the value in a variant into a BSTR variable.

On success, CA_VariantGetBSTR marks the variant as empty.

CA_VariantGetBSTR returns an error if the variant does not contain a BSTR value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a BSTR value. CA_VariantGetBSTR marks the variant as empty on success.

Output

Name	Туре	Description
BSTRValue	BSTR	BSTR value CA_VariantGetBSTR copies from the variant.

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

When you no longer need the BSTR, call the Windows SDK function SysFreeString to free it.

CA_VariantGetBSTRPtr

```
HRESULT status = CA_VariantGetBSTRPtr (VARIANT *variant,
BSTR **BSTRValuePtr);
```

Purpose

Copies the value in a variant into a BSTR pointer variable.

CA_VariantGetBSTRPtr returns an error if the variant does not contain a pointer to a BSTR value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a BSTR pointer.

Output

Name	Туре	Description
BSTRValuePtr	pointer to BSTR	BSTR pointer CA_VariantGetBSTRPtr copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetCString

HRESULT status = CA_VariantGetCString (VARIANT *variant, char **cString);

Purpose

Converts the BSTR string in the variant you specify to a dynamically allocated C-style string.

On success, CA_VariantGetCString releases the contents of the variant and marks it as empty.

CA_VariantGetCString returns an error if the variant does not contain a BSTR value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a BSTR value. CA_VariantGetCString marks the variant as empty on success.

Output

Name	Туре	Description
cString	string	Dynamically allocated C-style string CA_VariantGetCString converts from the BSTR in the variant.

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

When you no longer need the C-style string, call CA_FreeMemory to free it.

CA_VariantGetCStringBuf

Purpose

Converts the BSTR string in the variant you specify to a C-style string and copies the string into a buffer parameter.

If **buffer** is not large enough to hold the string, CA_VariantGetCStringBuf copies (**bufferSize** -1) characters into the buffer, followed by an ASCII NUL byte.

On success, CA_VariantGetCStringBuf releases the contents of the variant and marks it as empty.

CA_VariantGetCStringBuf returns an error if the variant does not contain a BSTR value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a BSTR value. CA_VariantGetCStringBuf marks the variant as empty on success.
bufferSize	unsigned integer	Number of bytes in buffer .

Output

Name	Туре	Description
buffer	character array	Buffer into which CA_VariantGetCStringBuf copies the C-style string it converts from the BSTR in the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetCStringLen

Purpose

Obtains the length of the C string you can create by calling CA_VariantGetCString to convert the BSTR string in the variant you specify. The length does not include the ASCII NUL byte.

CA_VariantGetCStringLen returns an error if the variant does not contain a BSTR value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a BSTR value.

Output

Name	Туре	Description
len	string	Length of C-style string that CA_VariantGetCString can convert from the BSTR in the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetCurrency

Purpose

Copies the value in a variant into a CURRENCY variable.

CA_VariantGetCurrency returns an error if the variant does not contain a CURRENCY value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a CURRENCY value.

Output

Name	Туре	Description
currencyValue	CURRENCY	CURRENCY value CA_VariantGetCurrency copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetCurrencyPtr

Purpose

Copies the value in a variant into a CURRENCY pointer variable.

CA_VariantGetCurrencyPtr returns an error if the variant does not contain a pointer to a CURRENCY value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a CURRENCY pointer.

Output

Name	Туре	Description
currencyValuePtr	pointer to CURRENCY	CURRENCY pointer CA_VariantGetCurrencyPtr copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetDate

HRESULT status = CA_VariantGetDate (VARIANT *variant, DATE *dateValue);

Purpose

Copies the value in a variant into a DATE variable.

CA_VariantGetDate returns an error if the variant does not contain a DATE value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a DATE value.

Output

Name	Туре	Description
dateValue	DATE	DATE value CA_VariantGetDate copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetDatePtr

```
HRESULT status = CA_VariantGetDatePtr (VARIANT *variant,
DATE **dateValuePtr);
```

Purpose

Copies the value in a variant into a DATE pointer variable.

CA_VariantGetDatePtr returns an error if the variant does not contain a pointer to a DATE value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a DATE pointer.

Output

Name	Туре	Description
dateValuePtr	pointer to DATE	DATE pointer CA_VariantGetDatePtr copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetDispatch

```
HRESULT status = CA_VariantGetDispatch (VARIANT *variant,
LPDISPATCH *dispatchValue);
```

Purpose

Copies the value in a variant into an LPDISPATCH variable. An LPDISPATCH value is a dispatch pointer for an ActiveX Automation object interface.

On success, CA_VariantGetDispatch marks the variant parameter as empty.

CA_VariantGetDispatch returns an error if the variant does not contain an LPDISPATCH value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains an LPDISPATCH value. CA_VariantGetDispatch marks the variant as empty on success.

Output

Name	Туре	Description
dispatchValue	LPDISPATCH	LPDISPATCH value CA_VariantGetDispatch copies from the variant.

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

When you no longer need the LPDISPATCH, free it by calling its Release function, as in the following:

```
lpDispatch->lpVtbl->Release();
```

CA_VariantGetDispatchPtr

```
HRESULT status = CA_VariantGetDispatchPtr (VARIANT *variant,
LPDISPATCH **dispatchValuePtr);
```

Purpose

Copies the value in a variant into a variable that is a pointer to the LPDISPATCH type. An LPDISPATCH value is a dispatch pointer for an ActiveX Automation object interface.

CA_VariantGetDispatchPtr returns an error if the variant does not contain a pointer to an LPDISPATCH value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains an LPDISPATCH pointer.

Output

Name	Туре	Description
dispatchValuePtr	pointer to LPDISPATCH	LPDISPATCH pointer CA_VariantGetDispatchPtr copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetDouble

Purpose

Copies the value in a variant into a double-precision variable.

CA_VariantGetDouble returns an error if the variant does not contain a double-precision value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a double-precision value.

Output

Name	Туре	Description
dblValue	double-precision	Double-precision value CA_VariantGetDouble copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetDoublePtr

Purpose

Copies the value in a variant into a double-precision pointer variable.

CA_VariantGetDoublePtr returns an error if the variant does not contain a pointer to a double-precision value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a double-precision pointer.

Output

Name	Туре	Description
doubleValuePtr	pointer to double-precision	Double-precision pointer CA_VariantGetDoublePtr copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetError

Purpose

Copies the value in a variant into an SCODE variable. SCODE is the data type for an error value.

CA_VariantGetError returns an error if the variant does not contain an SCODE value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains an SCODE value.

Output

Name	Туре	Description
errorValue	SCODE	SCODE value CA_VariantGetError copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetErrorPtr

Purpose

Copies the value in a variant into an SCODE pointer variable. SCODE is the data type for an error value.

CA_VariantGetErrorPtr returns an error if the variant does not contain a pointer to an SCODE value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains an SCODE pointer.

Output

Name	Туре	Description
errorValuePtr	pointer to SCODE	SCODE pointer CA_VariantGetErrorPtr copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetFloat

Purpose

Copies the value in a variant into a single-precision, floating-point variable.

CA_VariantGetFloat returns an error if the variant does not contain a single-precision value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a single-precision value.

Output

Name	Туре	Description
floatValue	single-precision	Single-precision value CA_VariantGetFloat copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetFloatPtr

Purpose

Copies the value in a variant into a single-precision, floating-point pointer variable.

CA_VariantGetFloatPtr returns an error if the variant does not contain a pointer to a single-precision value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a single-precision pointer.

Output

Name	Туре	Description
floatValuePtr	pointer to single-precision	Single-precision pointer CA_VariantGetFloatPtr copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetInt

HRESULT status = CA_VariantGetInt (VARIANT *variant, int *intValue);

Purpose

Copies the value in a variant into an integer variable.

CA_VariantGetInt returns an error if the variant does not contain an integer value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains an integer value.

Output

Name	Туре	Description
intValue	integer	Integer value CA_VariantGetInt copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetIntPtr

Purpose

Copies the value in a variant into an integer pointer variable.

CA_VariantGetIntPtr returns an error if the variant does not contain a pointer to an integer value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains an integer pointer.

Output

Name	Туре	Description
intValuePtr	pointer to integer	Integer pointer CA_VariantGetIntPtr copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetlUnknown

```
HRESULT status = CA_VariantGetIUnknown (VARIANT *variant,
LPUNKNOWN *IUnknownValue);
```

Purpose

Copies the value in a variant into a LPUNKNOWN variable. An LPUNKNOWN value is a pointer to an unknown interface.

On success, CA_VariantGetIUnknown marks the variant parameter as empty.

CA_VariantGetIUnknown returns an error if the variant does not contain an LPUNKNOWN value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains an LPUNKNOWN value. CA_VariantGetIUnknown marks the variant as empty on success.

Output

Name	Туре	Description
IUnknownValue	LPUNKNOWN	LPUNKNOWN value CA_VariantGetIUnknown copies from the variant.

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

When you no longer need the LPUNKNOWN, free it by calling its Release function, as in the following:

```
lpUnknown->lpVtbl->Release();
```

CA_VariantGetIUnknownPtr

Purpose

Copies the value in a variant into a variable that is a pointer to the LPUNKNOWN type. An LPUNKNOWN value is a pointer to an unknown interface.

CA_VariantGetIUnknownPtr returns an error if the variant does not contain a pointer to an LPUNKNOWN value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains an LPUNKNOWN pointer.

Output

Name	Туре	Description
IUnknownValPtr	pointer to LPUNKNOWN	LPUNKNOWN pointer CA_VariantGetIUnknownPtr copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetLong

HRESULT status = CA_VariantGetLong (VARIANT *variant, long *longValue);

Purpose

Copies the value in a variant into a long integer variable.

CA_VariantGetLong returns an error if the variant does not contain a long integer value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a long integer value.

Output

Name	Туре	Description
longValue	long integer	Long integer value CA_VariantGetLong copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetLongPtr

Purpose

Copies the value in a variant into a long integer pointer variable.

CA_VariantGetLongPtr returns an error if the variant does not contain a pointer to a long integer value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a long integer pointer.

Output

Name	Туре	Description
longValuePtr	pointer to long integer	long integer pointer CA_VariantGetLongPtr copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetObjHandle

```
HRESULT status = CA_VariantGetObjHandle (VARIANT *variant,
CAObjHandle *objHandle);
```

Purpose

Converts the LPDISPATCH value in a variant to a CAObjHandle.

On success, CA_VariantGetObjHandle marks the variant parameter as empty.

CA_VariantGetObjHandle returns an error if the variant does not contain an LDISPATCH value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains an LPDISPATCH value. CA_VariantGetObjHandle marks the variant as empty on success.

Output

Name	Туре	Description
objHandle	CAObjHandle	Object handle CA_VariantGetObjHandle converts from the LPDISPATCH value in the variant.

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

When you no longer need objHandle, call CA_DiscardObjHandle to free it.

CA_VariantGetSafeArray

Purpose

Copies the safe array in a variant into a safe array variable.

On success, CA_VariantGetSafeArray marks the variant parameter as empty.

CA_VariantGetSafeArray returns an error if the variant does not contain a safe array.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a safe array. CA_VariantGetSafeArray marks the variant as empty on success.
arrayType	unsigned integer	Type of the safe array.

Output

Name	Туре	Description
safeArray	LPSAFEARRAY	Safe array CA_VariantGetSafeArray copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **arrayType** parameter can have any of the values in Table 11-2 except for CAVT_EMPTY, CAVT_NULL, and CAVT_OBJHANDLE. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter.

If you do not know the type of the safe array, call CA_VariantGetType and pass its return value as the **arrayType**. CA_VariantGetSafeArray ignores the CAVT_ARRAY modifier.

CA_VariantGetSafeArrayPtr

Purpose

Copies the value in a variant into a safe array pointer variable.

CA_VariantGetSafeArrayPtr returns an error if the variant does not contain a pointer to a safe array.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a pointer to a safe array.
arrayType	unsigned integer	Type of the safe array.

Output

Name	Туре	Description
safeArrayPtr	pointer to LPSAFEARRAY	Safe array pointer CA_VariantGetSafeArrayPtr copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **arrayType** parameter can have any of the values in Table 11-2 except for CAVT_EMPTY, CAVT_NULL, and CAVT_OBJHANDLE. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter.

If you do not know the type of the safe array, call CA_VariantGetType and pass its return value as the **arrayType**. CA_VariantGetSafeArrayPtr ignores the CAVT_ARRAY modifier.

CA_VariantGetShort

Purpose

Copies the value in a variant into a short integer variable.

CA_VariantGetShort returns an error if the variant does not contain a short integer value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a short integer value.

Output

Name	Туре	Description
shortValue	short integer	Short integer value CA_VariantGetShort copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetShortPtr

Purpose

Copies the value in a variant into a short integer pointer variable.

CA_VariantGetShortPtr returns an error if the variant does not contain a pointer to a short integer value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a short integer pointer.

Output

Name	Туре	Description
shortValuePtr	pointer to short integer	Short integer pointer CA_VariantGetShortPtr copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetType

unsigned int type = CA_VariantGetType (VARIANT *variant);

Purpose

Returns the type of value the variant you specify contains.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
type	unsigned integer	 0 if the parameter is invalid. Otherwise, one of the data types listed in Table 11-2 in the <i>Data Types for Variants, Safe Arrays, and Properties</i> section of the <i>ActiveX</i> <i>Automation Library Function Overview</i> section of this chapter, possibly bitwise OR'ed with one or more of the data type modifiers listed in Table 11-3 in the <i>Data Types for Variants, Safe Arrays, and Properties</i> section of the <i>ActiveX</i> <i>Automation Library Function Overview</i> section of the chapter, possibly bitwise

CA_VariantGetUChar

Purpose

Copies the value in a variant into an unsigned character variable.

CA_VariantGetUChar returns an error if the variant does not contain an unsigned character value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains an unsigned character value.

Output

Name	Туре	Description
uCharValue	unsigned character	unsigned character value CA_VariantGetUChar copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetUCharPtr

Purpose

Copies the value in a variant into an unsigned character pointer variable.

CA_VariantGetUCharPtr returns an error if the variant does not contain a pointer to an unsigned character value.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains an unsigned character pointer.

Output

Name	Туре	Description
uCharValuePtr	pointer to unsigned character	Unsigned character pointer CA_VariantGetUCharPtr copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantGetVariantPtr

```
HRESULT status = CA_VariantGetVariantPtr (VARIANT *variant,
VARIANT **variantPtr);
```

Purpose

Copies the value in a variant into a variant pointer variable.

CA_VariantGetVariantPtr returns an error if the variant does not contain a pointer to variant.

Parameters

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to a variant that contains a VARIANT pointer.

Output

Name	Туре	Description
variantPtr	pointer to VARIANT	VARIANT pointer CA_VariantGetVariantPtr copies from the variant.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantHasArray

HRESULT status = CA_VariantHasArray (VARIANT *variant);

Purpose

Determines whether a variant contains an array. This is true if the type field of the variant contains the VT_CAVT modifier.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if variant type is an array.
		0 if variant type is not an array.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantHasBool

```
HRESULT status = CA_VariantHasBool (VARIANT *variant);
```

Purpose

Determines whether a variant contains a VBOOL value.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if the variant contains a VBOOL value.
		0 if variant does not contain a VBOOL value.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantHasBSTR

HRESULT status = CA_VariantHasBSTR (VARIANT *variant);

Purpose

Determines whether a variant contains a BSTR value.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if the variant contains a BSTR value.
		0 if variant does not contain a BSTR value.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantHasCString

HRESULT status = CA_VariantHasCString (VARIANT *variant);

Purpose

Determines whether a variant contains a string. Variants do not contain C-style strings, but you can convert the strings they contain to C-style strings.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if the variant contains a string value.
		0 if variant does not contain a string value.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantHasCurrency

HRESULT status = CA_VariantHasCurrency (VARIANT *variant);

Purpose

Determines whether a variant contains a CURRENCY value.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if the variant contains a CURRENCY value.
		0 if variant does not contain a CURRENCY value.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantHasDate

```
HRESULT status = CA_VariantHasDate (VARIANT *variant);
```

Purpose

Determines whether a variant contains a DATE value.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if variant contains a DATE value.
		0 if variant does not contain a DATE value.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantHasDispatch

HRESULT status = CA_VariantHasDispatch (VARIANT *variant);

Purpose

Determines whether a variant contains an IDispatch interface.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if variant contains an IDispatch interface.
		0 if variant does not contain an IDispatch interface.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantHasDouble

```
HRESULT status = CA_VariantHasDouble (VARIANT *variant);
```

Purpose

Determines whether a variant contains a double-precision value.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if variant contains a double-precision value.
		0 if variant does not contain a double-precision value.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantHasError

HRESULT status = CA_VariantHasError (VARIANT *variant);

Purpose

Determines whether a variant contains an SCODE value. SCODE is the data type for an error value.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if variant contains an SCODE value.
		0 if variant does not contain an SCODE value.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantHasFloat

```
HRESULT status = CA_VariantHasFloat (VARIANT *variant);
```

Purpose

Determines whether a variant contains a single-precision, floating-point value.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if variant contains a single-precision value.
		0 if variant does not contain a single-precision value.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantHasInt

HRESULT status = CA_VariantHasInt (VARIANT *variant);

Purpose

Determines whether a variant contains an integer value.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if variant contains an integer value.
		0 if variant does not contain an integer value.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantHaslUnknown

HRESULT status = CA_VariantHasIUnknown (VARIANT *variant);

Purpose

Determines whether a variant contains an IUnknown interface.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if variant contains an IUnknown interface.
		0 if variant does not contain an IUnknown interface.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantHasLong

HRESULT status = CA_VariantHasLong (VARIANT *variant);

Purpose

Determines whether a variant contains a long integer value.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if variant contains a long integer value.
		0 if variant does not contain a long integer value.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantHasNull

```
HRESULT status = CA_VariantHasNull (VARIANT *variant);
```

Purpose

Determines whether the data type of a variant is VT_NULL.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if variant has a type of VT_NULL.
		0 if variant does not have a type of VT_NULL.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantHasObjHandle

```
HRESULT status = CA_VariantHasObjHandle (VARIANT *variant);
```

Purpose

Determines whether a variant contains a value that you can convert to a CAObjHandle using CA_VariantGetObjHandle. This is true if the variant type is CAVT_DISPATCH and the IDispatch pointer the variant contains is not NULL.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if variant contains a non-null IDispatch interface.
		0 if variant does not contain a non-null IDispatch interface.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantHasPtr

HRESULT status = CA_VariantHasPtr (VARIANT *variant);

Purpose

Determines whether a variant contains a pointer to a data value. This is true if the type field of the variant contains the VT_BYREF flag.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if variant contains a pointer to a value.
		0 if variant does not contain a pointer to a value.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantHasShort

HRESULT status = CA_VariantHasShort (VARIANT *variant);

Purpose

Determines whether a variant contains a short integer value.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if variant contains a short integer value.
		0 if variant does not contain a short integer value.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantHasUChar

```
HRESULT status = CA_VariantHasUChar (VARIANT *variant);
```

Purpose

Determines whether a variant contains an unsigned character value.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if variant contains an unsigned character value.
		0 if variant does not contain an unsigned character value.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantInt

VARIANT variant = CA_VariantInt (int intValue);

Purpose

Converts an integer value to a variant that contains the integer value. Use CA_VariantInt to pass an integer value as a variant parameter.

Parameter

Input

Name	Туре	Description
intValue	integer	Value to store in the variant.

Name	Туре	Description
variant	VARIANT	Variant that contains the value in intValue .

CA_VariantIsEmpty

```
HRESULT status = CA_VariantIsEmpty (VARIANT *variant);
```

Purpose

Determines whether the data type of a variant type is VT_EMPTY.

Parameter

Input

Name	Туре	Description
variant	pointer to VARIANT	Pointer to the variant variable to inspect.

Name	Туре	Description
status	HRESULT	1 if variant has a type of VT_EMPTY.
		0 if variant does not have a type of VT_EMPTY.
		< 0 if variant is invalid.
		Refer to Table 11-18 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantIUnknown

VARIANT variant = CA_VariantIUnknown (LPUNKNOWN IUnknownValue);

Purpose

Converts an LPUNKNOWN value to a variant that contains an LPUNKNOWN value. Use CA_VariantIUnknown to pass an LPUNKNOWN value as a variant parameter.

Parameter

Input

Name	Туре	Description
IUnknownValue	LPUNKNOWN	Value to store in the variant.

Name	Туре	Description
variant	VARIANT	Variant that contains the value in IUnknownValue .

CA_VariantLong

VARIANT variant = CA_VariantLong (long longValue);

Purpose

Converts a long integer value to a variant that contains the long integer value. Use CA_VariantLong to pass a long integer value as a variant parameter.

Parameter

Input

Name	Туре	Description
longValue	long integer	Value to store in the variant.

Name	Туре	Description
variant	VARIANT	Variant that contains the value in longValue .

CA_VariantNULL

VARIANT variant = CA_VariantNULL (void);

Purpose

Returns a variant in which the value of the type field is VT_NULL. Use CA_VariantNULL to pass a NULL variant as a parameter.

Parameters

None.

Name	Туре	Description
variant	VARIANT	Variant in which LabWindows/CVI sets the type field to VT_NULL.

CA_VariantSet1DArray

Purpose

Creates a safe array from a 1D array and stores the safe array in a variant.

Parameters

Input/Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSet1DArray assigns the safe array.

Input

Name	Туре	Description
arrayType	unsigned integer	Data type of array .
numElements	unsigned integer	Number of elements in array .
array	depends on value of arrayType	1D array that CA_VariantSet1DArray converts to a safe array.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **arrayType** parameter can contain any of the fundamental types in Table 11-2 except CAVT_EMPTY, CAVT_NULL, and CAVT_OBJHANDLE. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter.

C Note

CA_VariantSet1DArray does not make copies of BSTR, VARIANT, LPUNKNOWN, or LPDISPATCH elements. It simply copies the pointers into the created safe array. Therefore, when you call CA_VariantClear, which frees the safe array and all its contents, the BSTR, VARIANT, LPUNKNOWN, or LPDISPATCH elements of the input array parameter become invalid.

CA_VariantSet2DArray

Purpose

Creates a safe array from a 2D array and stores the safe array in a variant.

Parameters

Input/Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSet2DArray assigns the safe array.

Input

Name	Туре	Description
arrayType	unsigned integer	Data type of array .
numElemsDim1	unsigned integer	Number of elements in the first dimension of array .
numElemsDim2	unsigned integer	Number of elements in the second dimension of array .
array	depends on value of arrayType	2D array that CA_VariantSet2DArray converts to a safe array.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **arrayType** parameter can contain any of the fundamental types in Table 11-2 except CAVT_EMPTY, CAVT_NULL, and CAVT_OBJHANDLE. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter.

C Note

CA_VariantSet2DArray does not make copies of BSTR, VARIANT, LPUNKNOWN, or LPDISPATCH elements. It simply copies the pointers into the created safe array. Therefore, when you call CA_VariantClear, which frees the safe array and all its contents, the BSTR, VARIANT, LPUNKNOWN, or LPDISPATCH elements of the input array parameter become invalid.

CA_VariantSetBool

HRESULT status = CA_VariantSetBool (VARIANT *variant, VBOOL boolValue);

Purpose

Stores a VBOOL value in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
boolValue	VBOOL	Value to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetBool assigns boolValue .

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetBoolPtr

Purpose

Stores a pointer to a VBOOL value in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
boolValuePtr	pointer to VBOOL	Pointer to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetBoolPtr assigns boolValuePtr .

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetBSTR

HRESULT status = CA_VariantSetBSTR (VARIANT *variant, BSTR BSTRValue);

Purpose

Stores a BSTR in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
BSTRValue	BSTR	Value to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetBSTR assigns BSTRValue .

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetBSTRPtr

```
HRESULT status = CA_VariantSetBSTRPtr (VARIANT *variant,
BSTR *BSTRValuePtr);
```

Purpose

Stores a pointer to a BSTR in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
BSTRValuePtr	pointer to BSTR	Pointer to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetBSTRPtr assigns BSTRValuePtr .

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetCString

HRESULT status = CA_VariantSetCString (VARIANT *variant, char *cString);

Purpose

Converts a C-style string to a BSTR, stores the BSTR in a variant, and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
cString	string	Value CA_VariantSetCString converts to a BSTR.

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetCString assigns the BSTR it creates.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetCurrency

Purpose

Stores a CURRENCY value in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
currencyValue	CURRENCY	Value to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetCurrency assigns currencyValue.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetCurrencyPtr

Purpose

Stores a pointer to a CURRENCY value in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
currencyValuePtr	pointer to CURRENCY	Pointer to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetCurrencyPtr assigns currencyValuePtr.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetDate

HRESULT status = CA_VariantSetDate (VARIANT *variant, DATE dateValue);

Purpose

Stores a DATE value in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
dateValue	DATE	Value to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetDate assigns dateValue.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetDatePtr

```
HRESULT status = CA_VariantSetDatePtr (VARIANT *variant,
DATE *dateValuePtr);
```

Purpose

Stores a pointer to a DATE value in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
dateValuePtr	pointer to DATE	Pointer to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetDatePtr assigns dateValuePtr.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetDispatch

```
HRESULT status = CA_VariantSetDispatch (VARIANT *variant,
LPDISPATCH dispatchValue);
```

Purpose

Stores an LPDISPATCH value in a variant and sets the type field of the variant accordingly. An LPDISPATCH value is a dispatch pointer for an ActiveX Automation object interface.

Parameters

Input

Name	Туре	Description
dispatchValue	LPDISPATCH	Value to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetDispatch assigns dispatchValue .

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetDispatchPtr

Purpose

Stores a pointer to an LPDISPATCH value in a variant and sets the type field of the variant accordingly. An LPDISPATCH value is a dispatch pointer for an ActiveX Automation object interface.

Parameters

Input

Name	Туре	Description
dispatchValuePtr	pointer to LPDISPATCH	Pointer to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which
		CA_VariantSetDispatchPtr assigns dispatchValuePtr .

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetDouble

Purpose

Stores a double-precision value in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
doubleValue	double-precision	Value to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetDouble assigns doubleValue.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetDoublePtr

Purpose

Stores a pointer to a double-precision value in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
doubleValuePtr	pointer to double-precision	Pointer to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which
		CA_VariantSetDoublePtr assigns doubleValuePtr .

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetEmpty

HRESULT status = CA_VariantSetEmpty (VARIANT *variant);

Purpose

Marks a variant as empty by setting its type field to VT_EMPTY.

Parameter

Output

Name	Туре	Description
variant	VARIANT	Variant to mark as empty.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetError

HRESULT status = CA_VariantSetError (VARIANT *variant, SCODE errorValue);

Purpose

Stores an SCODE value in a variant and sets the type field of the variant accordingly. SCODE is the data type for an error value.

Parameters

Input

Name	Туре	Description
errorValue	SCODE	Value to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetError assigns errorValue .

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetErrorPtr

Purpose

Stores a pointer to an SCODE value in a variant and sets the type field of the variant accordingly. SCODE is the data type for an error value.

Parameters

Input

Name	Туре	Description
errorValuePtr	pointer to SCODE	Pointer to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetErrorPtr assigns errorValuePtr.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetFloat

HRESULT status = CA_VariantSetFloat (VARIANT *variant, float floatValue);

Purpose

Stores a single-precision, floating-point value in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
floatValue	single-precision	Value to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetFloat assigns floatValue .

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetFloatPtr

Purpose

Stores a pointer to a single-precision, floating-point value in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
floatValuePtr	pointer to single-precision	Pointer to store in variant .

Output

Туре	Description
VARIANT	Variant to which
	CA_VariantSetFloatPtr assigns floatValuePtr.
	<i></i>

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetInt

HRESULT status = CA_VariantSetInt (VARIANT *variant, int intValue);

Purpose

Stores an integer value in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
intValue	integer	Value to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetInt assigns intValue.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetIntPtr

HRESULT status = CA_VariantSetIntPtr (VARIANT *variant, int *intValuePtr);

Purpose

Stores a pointer to an integer value in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
intValuePtr	pointer to integer	Pointer to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetIntPtr assigns intValuePtr.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetlUnknown

```
HRESULT status = CA_VariantSetIUnknown (VARIANT *variant,
LPUNKNOWN IUnknownValue);
```

Purpose

Stores an LPUNKNOWN value in a variant and sets the type field of the variant accordingly. An LPUNKNOWN value is a pointer to an unknown interface.

Parameters

Input

Name	Туре	Description
IUnknownValue	LPDISPATCH	Value to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetIUnknown assigns IUnknownValue .

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetIUnknownPtr

```
HRESULT status = CA_VariantSetIUnknownPtr (VARIANT *variant,
                                  LPUNKNOWN *IUnknownValuePtr);
```

Purpose

Stores a pointer to an LPUNKNOWN value in a variant and sets the type field of the variant accordingly. An LPUNKNOWN value is a pointer to an unknown interface.

Parameters

Input

Name	Туре	Description
IUnknownValuePtr	pointer to LPUNKNOWN	Pointer to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetIUnknownPtr assigns IUnknownValuePtr .

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetLong

HRESULT status = CA_VariantSetLong (VARIANT *variant, long longValue);

Purpose

Stores a long integer value in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
longValue	long integer	Value to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetLong assigns longValue.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetLongPtr

Purpose

Stores a pointer to a long integer value in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
longValuePtr	pointer to long integer	Pointer to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetLongPtr assigns longValuePtr.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetNULL

HRESULT status = CA_VariantSetNULL (VARIANT *variant);

Purpose

Marks a variant as NULL by setting its type field to VT_NULL.

Parameter

Output

Name	Туре	Description
variant	VARIANT	Variant to mark as NULL.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetSafeArray

Purpose

Stores a safe array in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
arrayType	unsigned integer	Type of the safe array.
safeArray	LPSAFEARRAY	Value to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetSafeArray assigns safeArray .

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **arrayType** parameter can be any of the fundamental types in Table 11-2 except CAVT_EMPTY, CAVT_NULL, or CAVT_OBJHANDLE. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter.

CA_VariantSetSafeArrayPtr

Purpose

Stores a pointer to a safe array in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
arrayType	unsigned integer	Type of the safe array.
safeArrayPtr	pointer to LPSAFEARRAY	Pointer to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetSafeArrayPtr assigns safeArrayPtr.

Return Value

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

Parameter Discussion

The **arrayType** parameter can be any of the fundamental types in Table 11-2 except CAVT_EMPTY, CAVT_NULL, or CAVT_OBJHANDLE. Table 11-2 is in the *Data Types for Variants, Safe Arrays, and Properties* section of the *ActiveX Automation Library Function Overview* section of this chapter.

CA_VariantSetShort

HRESULT status = CA_VariantSetShort (VARIANT *variant, short shortValue);

Purpose

Stores a short integer value in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
shortValue	short integer	Value to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetShort assigns shortValue .

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetShortPtr

Purpose

Stores a pointer to a short integer value in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
shortValuePtr	pointer to short integer	Pointer to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetShortPtr assigns shortValuePtr.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetUChar

Purpose

Stores an unsigned character value in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
uCharValue	unsigned character	Value to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetUChar assigns uCharValue .

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetUCharPtr

Purpose

Stores a pointer to an unsigned character value in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
uCharValuePtr	pointer to unsigned character	Pointer to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which
		CA_VariantSetUCharPtr assigns uCharValuePtr.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantSetVariantPtr

```
HRESULT status = CA_VariantSetVariantPtr (VARIANT *variant,
VARIANT *variantPtr);
```

Purpose

Stores a pointer to a variant in a variant and sets the type field of the variant accordingly.

Parameters

Input

Name	Туре	Description
variantPtr	pointer to VARIANT	Pointer to store in variant .

Output

Name	Туре	Description
variant	VARIANT	Variant to which CA_VariantSetVariantPtr assigns variantPtr.

Name	Туре	Description
status	HRESULT	Refer to Table 11-19 for error codes or to cvi\sdk\winerror.h for Windows SDK error codes.

CA_VariantShort

VARIANT variant = CA_VariantShort (short shortValue);

Purpose

Converts a short integer value to a variant that contains the short integer value. Use CA_VariantShort to pass a short integer value as a VARIANT parameter.

Parameter

Input

Name	Туре	Description
shortValue	short integer	Value to store in the variant.

Name	Туре	Description
variant	VARIANT	Variant that contains the value in shortValue .

CA_VariantUChar

VARIANT variant = CA_VariantUChar (unsigned char uCharValue);

Purpose

Converts an unsigned character value to a variant that contains the unsigned character value. Use CA_VariantUChar to pass an unsigned character value as a VARIANT parameter.

Parameter

Input

Name	Туре	Description
uCharValue	unsigned character	Value to store in the variant.

Name	Туре	Description
variant	VARIANT	Variant that contains the value in uCharValue .

Error Conditions

Most of the functions in the ActiveX Automation Library return error codes, which are defined in cvi\include\cviauto.h or in cvi\sdk\include\winerror.h. Table 11-19 lists error codes defined in cviauto.h or winerror.h that the ActiveX Automation Library returns explicitly. Occasionally, an ActiveX Automation Library function returns an error code because an internal call to a Windows function returns it. Table 11-19 does not list such error codes, but winerror.h does.

You can use CA_GetAutomationErrorString to get the description of an error code. You can use CA_DisplayErrorInfo to display the description of an error code.

Defined Constant	Value	Description
E_CVIAUTO_NO_ERROR	0	No error.
E_CVIAUTO_INVALID_TYPE_DESC	0X80040201	Type you passed is an invalid Automation data type.
E_CVIAUTO_INVALID_RETURN_TYPE	0X80040202	Type you passed is an invalid return type.
E_CVIAUTO_USE_CAVT_TYPE_DESC	0X80040203	Use CAVT_ constants for data types instead of VT_ constants.
E_CVIAUTO_INVALID_NUM_DIM	0X80040204	Number of dimensions in the safe array does not match the number this function requires.
E_CVIAUTO_DIFF_SAFEARRAY_TYPE	0X80040205	Safe array type does not match the type you request.
E_CVIAUTO_VARIANT_NOT_SAFEARRAY	0X80040206	Variant does not contain a safe array.
E_CVIAUTO_NULL_RET_VAL_PARAM	0X80040207	Return value parameter must not be NULL.
E_CVIAUTO_DLL_LOAD_FAILED	0X80040208	Could not load the Automation Support DLL.

 Table 11-19.
 ActiveX Automation Library Error Codes

Defined Constant	Value	Description
E_CVIAUTO_BAD_DLL_VERSION	0X80040209	Automation Support DLL version does not match the import library.
E_CVIAUTO_COULD_NOT_CREATE_MUTEX	0X8004020A	Unable to create a required mutex.
DISP_E_TYPEMISMATCH	0X80020005	Variant type does not match the type this function requires.
DISP_E_BADVARTYPE	0X80020008	Variant type is invalid for the operation you request.
DISP_E_EXCEPTION	0X80020009	Exception occurred in server; refer to ERRORINFO structure for details or call CA_DisplayError Info.
E_HANDLE	0X80070006	Invalid object handle.
E_OUTOFMEMORY	0X8007000E	Out of memory.
E_INVALIDARG	0X80070057	Invalid argument, such as NULL pointer.
ERROR_INSUFFICIENT_BUFFER	0X8007007A	Array buffer is not large enough to receive the contents of the safe array.

Table 11-19.	ActiveX Automation	Librarv E	rror Codes	(Continued)
	/ totil o/ t / tatolilation	LIDIALY L		(continuou)

Note Refer to cvi\sdk\winerror.h for more Windows SDK error codes.



Customer Communication

For your convenience, this appendix contains forms to help you gather the information necessary to help us solve your technical problems and a form you can use to comment on the product documentation. When you contact us, we need the information on the Technical Support Form and the configuration form, if your manual contains one, about your system configuration to answer your questions as quickly as possible.

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Finland	09 725 725 11	09 725 725 55
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Italy	02 413091	02 41309215
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Mexico	5 520 2635	5 520 3282
Netherlands	0348 433466	0348 430673
Norway	32 84 84 00	32 84 86 00
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Hard disk capacityMB Brand	
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National Instruments hardware product model	Revision
Configuration	
	Version
Configuration	
The problem is:	
List any error messages:	
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Prefix	Meanings	Value
n-	nano-	10 ⁻⁹
μ-	micro-	10 ⁻⁶
m-	milli-	10 ⁻³
k-	kilo-	10 ³
M-	mega-	106

Numbers/Symbols

1D	One-dimensional.
2D	Two-dimensional.
A	
A/D	Analog-to-digital.
AI	Analog input.
analog trigger	A trigger that occurs at a user-selected point on an incoming analog signal. You can set triggering to occur at a specific level on an increasing or a decreasing signal, that is, a positive or negative slope. You can implement analog triggering in software or in hardware. When you implement it in software, all data is collected, transferred into system memory, and analyzed for the trigger condition. When you implement it in hardware, no data is transferred to system memory until the trigger condition has occurred.
ANSI	American National Standards Institute.
AO	Analog output.

Glossary

asynchronous	(1) Hardware—A property of an event that occurs at an arbitrary time, without synchronization to a reference clock.
	(2) Software—A property of a function that begins an operation and returns before the completion or termination of the operation.
automatic serial	A feature in which the GPIB polling driver automatically executes serial polls whenever a device asserts the SRQ line.
В	
В	Bytes.
C	
C locale	The minimal environment for compiling a C program.
counter/timer	A circuit that counts external pulses or clock pulses (timing).
coupling	The manner in which a signal is connected from one location to another.
D	
Data acquisition	(1) Collecting and measuring electrical signals from sensors, transducers, and test probes or fixtures and inputting them to a computer for processing.
	(2) Collecting and measuring the same kinds of electrical signals with A/D and/or DIO boards plugged into a PC and possibly generating control signals with D/A and/or DIO boards in the same PC.
device	Refers to a DAQ device inside your computer or attached directly to your computer through a parallel port. Plug-in boards, PCMCIA cards, and devices such as the DAQPad-1200, which connects to your computer parallel port, are all examples of DAQ devices. SCXI modules are distinct from devices with the exception of the SCXI-1200, which is a hybrid.
differential input	An analog input that consists of two terminals, both of which are isolated from computer ground, whose difference is measured.
di =: (= 1 == == +	
digital port	Refer to port.

F

FIFO	A first-in first-out memory buffer; the first data stored is the first data sent to the acceptor.
format string	A mini-program that instructs the formatting and scanning functions how to transform the input arguments to the output arguments. For conciseness, format strings are constructed using single-character codes.
G	
gender	Refers to cable connector types. A male connector is one with protruding pins, like a lamp plug. A female connector has holes, like an outlet.
gender changer	A small device you can attach to serial cable connectors or PC sockets, among others, to convert a female connector into a male or a male connector into a female.
GPIB	General Purpose Interface Bus is the common name for the communications interface system defined in ANSI/IEEE Standards 488.1-1987 and 488.2-1992.
group	A collection of digital ports, combined to form a larger entity for digital input and/or output.
Н	
handshaking	Prevents overflow of the input queue that occurs when the receiver is unable to empty its input queue as quickly as the sender is able to fill it. The RS-232 Library has two types of handshaking: software handshaking and hardware handshaking. You should enable one or the other if you want to ensure that your application program synchronizes its data transfers with other serial devices that perform handshaking.
Hz	Hertz.

I

ID	Identification.
IEEE	Institute of Electrical and Electronics Engineers.
Instrument Library	A LabWindows/CVI library that contains instrument drivers.
interrupt	A computer signal that indicates the CPU should suspend its current task to service a designated activity.
I/O	Input/output.
К	
KB	Kilobytes of memory.
М	
MB	Megabytes of memory.
MIO	Multifunction I/O.
ms	Milliseconds.
Ν	
NI-488 functions	National Instruments functions you use to communicate with GPIB devices built according to the ANSI/IEEE Standards 488.1-1987 and 488.2-1992.
NI-488.2 routines	National Instruments routines you use to communicate with GPIB devices built according to the ANSI/IEEE Standard 488.2-1992.
Р	
port	A digital port that consists of four or eight lines of digital input and/or output.

R

resolution	The smallest signal increment a measurement system can detect. Resolution can be expressed in bits, in proportions, or in percent of full scale. For example, a system has 12-bit resolution, one part in 4,096 resolution, and 0.0244 percent of full scale.
S	
SCXI	Signal Conditioning eXtensions for Instrumentation; the National Instruments product line for conditioning low-level signals within an external chassis near sensors so only high-level signals are sent to DAQ boards in the noisy PC environment.
software trigger	A programmed event that triggers an event such as data acquisition.
standard libraries	The LabWindows/CVI Analysis, ANSI C, DDE, Formatting and I/O, GPIB and GPIB-488.2, RS-232, TCP, and Utility libraries.
synchronous	(1) Hardware—Property of an event that is synchronized to a reference clock.
	(2) Software—Property of a function that begins an operation and returns only when the operation is complete.
т	
ТС	Terminal count.
TTL	Transistor-Transistor Logic.
X	
Xmodem functions	Allow you to transfer files that use a data transfer protocol. The protocol uses a generally accepted technique to perform serial file transfers with error-checking. Files are sent in packets that contain data from the files plus error-checking and synchronization information.

Numbers and Special Characters

- 1D array functions. *See* one-dimensional array operation functions.
- 1D complex operation functions. *See* one-dimensional complex operation functions.
- 2D array functions. *See* two-dimensional array operation functions.
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