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FP-1600

Lookout™

Lookout Object Reference Manual

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About This Manual

This manual describes Lookout object classes, listed in alphabetical order, in two sections.

Conventions

The following conventions appear in this manual:

»

The » symbol leads you through nested menu items and dialog box options to a final action. The sequence **File»Page Setup»Options** directs you to pull down the **File** menu, select the **Page Setup** item, and select **Options** from the last dialog box.



This icon denotes a tip, which alerts you to advisory information.



This icon denotes a note, which alerts you to important information.



This icon denotes a caution, which advises you of precautions to take to avoid injury, data loss, or a system crash.

bold

Bold text denotes items that you must select or click on in the software, such as menu items and dialog box options. Bold text also denotes parameter names.

italic

Italic text denotes variables, emphasis, a cross reference, or an introduction to a key concept. This font also denotes text that is a placeholder for a word or value that you must supply.

`monospace`

Text in this font denotes text or characters that you should enter from the keyboard, sections of code, programming examples, and syntax examples. This font is also used for the proper names of disk drives, paths, directories, programs, subprograms, subroutines, device names, functions, operations, variables, filenames and extensions, and code excerpts.

`monospace bold`

Bold text in this font denotes the messages and responses that the computer automatically prints to the screen. This font also emphasizes lines of code that are different from the other examples.

`monospace italic`

Italic text in this font denotes text that is a placeholder for a word or value that you must supply.

Related Documentation

The following documents contain information that you might find helpful as you read this manual:

- *Getting Started With Lookout*
- *Lookout Developer's Manual*
- *Lookout Operator's Manual*
- *Lookout Object Developer's Toolkit Reference*

Introduction to the Lookout Object Class Reference

This manual describes Lookout object classes, listed in alphabetical order, in two chapters.

Chapter 2, *Lookout System Objects*, covers the Lookout System object classes, native to Lookout. You use objects made from these classes as controls and for data analysis and display.

Chapter 3, *Lookout Driver and Protocol Objects*, contains Lookout driver and protocol objects that you use to connect to PLCs, RTUs, and other hardware that is a part of your industrial automation and control system.

Input parameter syntax and data members are documented for each object class, along with a description of the functionality of each object class.



Note Lookout assists you in building graphical screen displays when possible. When you place a displayable object (like Pots or Switches) on a control panel, the appropriate **Display Parameter** dialog box appears, prompting you to select a display type. If the object is not displayable but supports an implicit signal (like Counters, LatchGates, and OneShots), Lookout inserts an expression on the control panel.

You can elect not to display an object or its signal by clicking on the **Cancel** button at any time. If you change your mind later, you can display the object or its signal using the **Insert»Displayable Object** or **Insert»Expression** commands, respectively.

Some object classes have neither a display member nor an implicit signal—instead they have multiple data members. If you want to display the result of a logical or numeric data member on a control panel, you can use the **Insert»Expression** command and choose the appropriate name and data member, or drag and drop the data member from the Lookout Object Explorer.

See the *Getting Started with Lookout* manual for more information on creating objects, modifying their databases, and linking them together.

Lookout System Objects

This chapter describes Lookout System object classes, listed in alphabetical order. Input parameter syntax and data members are documented for each object class, along with a description of the functionality of each object class.

Accumulator

Accumulator is a numeric totalizer. It samples the numeric **Input** any time the **Sample** value transitions from off to on, adding each new sample to the previous running total. It resets the totalized value to zero when **Reset** transitions from off to on.

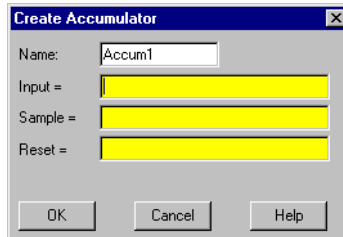
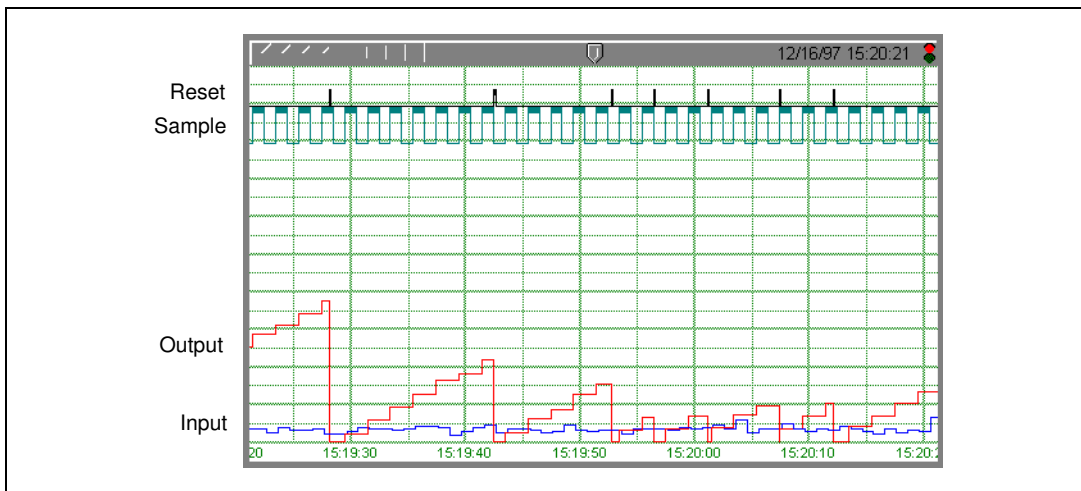


Figure 2-1. Accumulator Definition Parameters Dialog Box

Input is a numeric expression while **Sample** and **Reset** are logical expressions.

The following HyperTrend demonstrates the relationship between **Input**, **Sample**, and **Reset**.



Accumulator Data Members

Table 2-1. Accumulator Data Members

| Data Members | Type | Read | Write | Description |
|---------------------|-------------|-------------|--------------|--|
| (implicit) | numeric | yes | no | Current totalized value, totalized since the most recent Reset signal. Updated at the defined Sample rate. |

Comments **Reset** could be a regular pulse interval created by a Pulse timer, as shown in the dialog box in Figure 2-1.

The Counter object class totalizes a number of logical events and the Integral object class totalizes rates. Use Accumulator to totalize numeric variables.

Related Objects *Average, Minimum, Maximum, Sample*

Alarm

Alarm is a flexible and powerful object class you use to create various logical- and numeric-triggered alarms that are displayed in the alarm window.



Note You should first read about the Lookout alarm system in Chapter 9, *Alarms*, in the *Lookout Developer's Manual* to aid you in designing the most efficient alarming scheme for your application.

The screenshot shows the 'Create Alarm' dialog box with the following settings:

- Name:** LogicalAlarm
- Alarm_area:** Plant
- Message:** "Relief valve failed to open after 30 seconds"
- Condition:** PLC1.reliefVlv AND DelayOnTimer
- Logical alarm:** Selected
- Priority (1-10):** 8
- Wave file:** c:\
- Numeric alarm:** Not selected
- Buttons:** OK, Cancel, Help

Figure 2-2. Typical Settings for a Logical Style Alarm

There are two basic alarm types: Logical and Numeric. **When Logical alarm** is selected, Lookout prompts you to enter a logical expression in the **Condition** field. It then uses the logical **Condition** to trigger and reset the alarm. If the alarm **Condition** is true, the alarm is active, and if the condition is false, the alarm goes inactive. You can also connect an audio **Wave file** to individual logical alarms. See [Playwave](#) for additional information.

Lookout queues alarm .wav files, with up to 100 files in the queue. Each alarm .wav file plays completely before the next file plays. If more than 100 alarms fill the queue, new alarms cancel the currently playing files and begin playing instead.

When you pick the **Numeric** alarm selection, the name of the Condition field changes to **Signal**. This prompts you to enter a numeric expression in the field against which your various alarm setpoints are measured. **Hi-Hi**, **Hi**, **Lo**, and **Lo-Lo** are all numeric expressions. **Rate of change** generates an alarm when the signal is actively changing by the set amount for the period of time between any two **Sample** pulses. The **Unit time** setting determines the time units for the rate of change.

The screenshot shows the 'Create Alarm' dialog box with the following settings:

- Name:** Alarm1
- Alarm area:** (empty)
- Message =** (empty)
- Signal =** (empty)
- Logical alarm:** (unchecked)
- Numeric alarm:** (checked)
 - Priority (1-10):** 4
 - Wave file:** (empty)
 - Hi-Hi level =** HiHiSetpoint (Priority: 9)
 - Hi level =** (empty) (Priority:)
 - Lo level =** (empty) (Priority:)
 - Lo-Lo level =** LoLoSetpoint (Priority: 6)
 - Rate of change =** 2.5 (Priority: 4)
 - Unit time:** 00:01:00.0 (Example: 1:00 for per minute)
 - Sample =** Pulse (true, 0.0:1.0, 0.0)

Figure 2-3. Typical Settings for a Numeric Style Alarm

Alarm area specifies the group name associated with the alarm object. All previously defined groups appear in the list box and may be selected with the mouse.

Priority ranges from 1 to 10 where 10 is the most important.

Message is a text expression whose result is displayed in the alarm window when this object generates an alarm. If alarm style is numeric, the relevant alarm trigger prefixes your message (for example, HiHi level: *Alarm message*). See Chapter 9, *Alarms*, in the *Lookout Developer's Manual* for additional information.

Alarm Data Members

Table 2-2. Alarm Data Members

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|---|
| active | logical | yes | no | Result of logical alarm status. True if alarm is active and false if alarm is inactive. |
| hi | logical | yes | no | Result of numeric alarm hi data member status. |
| hihi | logical | yes | no | Result of numeric alarm hihi data member status. |
| lo | logical | yes | no | Result of numeric alarm lo data member status. |
| lolo | logical | yes | no | Result of numeric alarm lolo data member status. |
| rate | logical | yes | no | Result of numeric alarm rate data member status. |

Comments A common alarm condition is caused by a measured value going out of an acceptable range. For example, a storage tank whose level is too low or too high can generate several alarms: Hihi: Tank level is out of range, or Lo: Tank level is out of range. If you use a numeric style alarm to trigger the alarm and if the tank level fluctuates or “jitters” around the alarm level settings, a new alarm record is generated in the alarm window each time the tank level fluctuates above or below the level settings. To alleviate this condition, you could use the Neutralzone object to filter out minor tank fluctuations.



Note Alarms can also be defined through parameter settings on object data members. Many times, this is the most efficient method of defining and creating alarm conditions. See *Database-Generated Alarms* in Chapter 9, *Alarms*, in the *Lookout Developer’s Manual*, and *Editing Object Databases* in Chapter 4, *Using Lookout*, in the *Getting Started with Lookout* manual.

\$Alarm

\$Alarm is a global object. It makes available global alarm data such as the number of currently active alarms.

You can use \$Alarm data members just like other data members. By inserting an expression you can display the number of active alarms in any particular group. Or, by connecting a pushbutton to an acknowledge data member, operators can acknowledge alarms through pushbutton selection.

Assume, for example, that you want to create a pushbutton that acknowledges all alarms. First create a pushbutton object. Next, use the **Object»Edit Connections...** command to connect the pushbutton (Pb1) to the .ack data member of \$Alarm. Such a connection is shown in the following illustration.

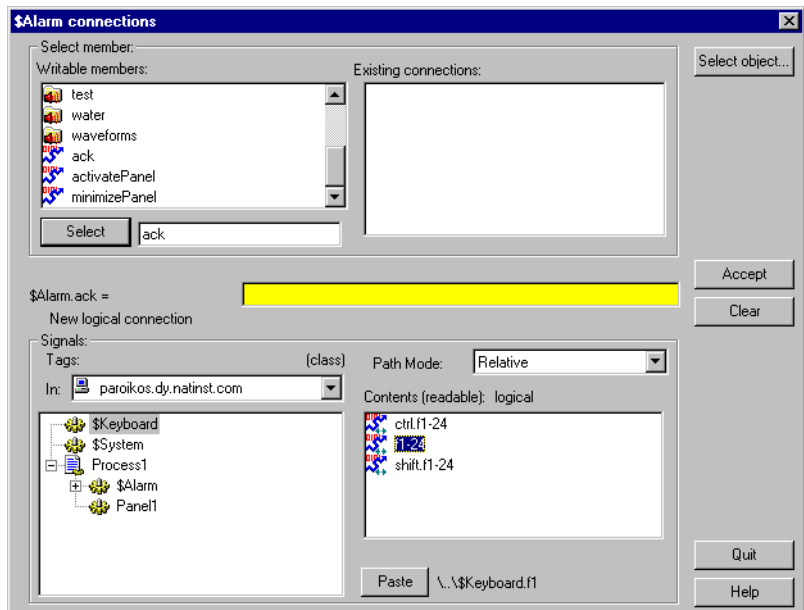


Figure 2-4. Edit Connections Dialog Box for using \$Alarm

The expression (Pb1) acknowledges all active alarms any time the pushbutton is depressed. You could make similar connections to acknowledge individual alarm areas.

You can define new alarm areas through Alarm objects and by modifying object database parameters. As you create each new alarm area, Lookout adds new readable and writable data members to the \$Alarm object. \$Alarm data members are described in the following table.

\$Alarm Data Members

Table 2-3. \$Alarm Data Members

| Data Member | Type | Read | Write | Description |
|--------------------------|-------------|-------------|--------------|---|
| ack | logical | no | yes | Upon transition from FALSE to TRUE, acknowledges all alarms. |
| Ackselected | logical | no | yes | Upon transition from FALSE to TRUE, acknowledges all selected alarms. |
| ActivatePanel | logical | no | yes | Calls Alarm Window upon transition from FALSE to TRUE, making it visible on the screen. |
| Active | numeric | yes | no | Total number of currently active alarms (that is, alarm conditions that still exist). |
| Groupname | text | yes | no | Alarm area name associated with the most recent alarm. |
| <i>Groupname.ack</i> | logical | no | yes | Upon transition from FALSE to TRUE, acknowledges all alarms within the specified group. |
| <i>Groupname.active</i> | numeric | yes | no | Number of currently active alarms within the specified group. |
| <i>Groupname.unacked</i> | numeric | yes | no | Number of unacknowledged alarms within the specified group. |
| Message | text | yes | no | Text of the message of the most recent alarm |
| MinimizePanel | logical | no | yes | Closes Alarm Window upon transition from FALSE to TRUE, changing it to an icon. |
| Priority | numeric | yes | no | Alarm priority associated with the most recent alarm. |

Table 2-3. \$Alarm Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|---|---------|------|-------|--|
| Priority01.active – Priority10.active | numeric | yes | no | Number of currently active alarms of the specified priority. |
| Priority01.unacked – Priority10.unacked | numeric | yes | no | Number of unacknowledged alarms of the specified priority. |
| Silence | logical | no | yes | Turns off alarm sounds when set to TRUE. |
| Name | text | yes | no | Object name associated with the most recent alarm. |
| Unacked | numeric | yes | no | Total number of unacknowledged alarms (that is, alarm conditions that have not yet been acknowledged). |
| Update | logical | yes | no | Pulses high every time there is a new alarm. |

Comments Groupname in the preceding table represents the name of any specified alarm area. The \$Alarm object contains an `.active`, `.unacked`, and `.ack` data member for every alarm area.

Using \$Alarm with Other Objects

Every time a new alarm appears in Lookout, `$Alarm.Message`, `$Alarm.Name`, `$Alarm.Groupname`, and `$Alarm.Priority` are updated with the appropriate information for the new alarm. Then `$Alarm.Update` pulses high to alert you that those four data members contain fresh values.

These data members can serve many purposes, but they are specifically designed to work with the Pager object class. In a typical application, you could use `$Alarm.Update` to initiate a page, possibly including the other four data members in the text of the page. With this system you can also filter which alarms you want to page, and which alarms the pager ignores.

Alternator

Alternator is an object class Lookout uses to control a series of devices with various commands. Typically this means rotating the usage of the devices at specified times.

Figure 2-5. Alternator Definition Parameters Dialog Box

Devices determines the maximum number of devices that can be controlled by the alternator.

Maximum run time is the maximum amount of time that any one device is allowed to run continuously. This function can be disabled by entering 0.

Delay between device starts is the minimum amount of time between device starts that are initiated by the alternator object. This function can be disabled by entering 0.

Device failure alarm priority determines the priority level of alarms generated by the alternator. This defaults to 5.

Device response time is the amount of time the alternator waits for a response from a device before activating an alarm. This function can be disabled for individual devices by not connecting anything to the Response data member.

Device name is a string describing the type of device that is being controlled by the alternator. This is used to create the alarm messages and is also the name of the group to which the alarms belong.

Timer update specifies the resolution of the timers used by the alternator to decide which devices to turn on and off. This also specifies how often the alternator updates the ElapsedTime and RunTime data members.

Alternator Data Members

Table 2-4. Alternator Data Members

| Data Member | Type | Read | Write | Description |
|-----------------------------------|-------------|-------------|--------------|--|
| Advance | logical | no | yes | Turns on the next device in the sequence and turns off the last device in the sequence |
| Command | numeric | no | yes | How many devices the alternator is to have running |
| DeviceConnect1 - DeviceConnect100 | logical | yes | no | States whether device is in the active sequence considered by the alternator |
| DeviceOn1 - DeviceOn100 | logical | yes | no | Confirmation of the actual device state |
| DeviceRequest1 - DeviceRequest100 | logical | yes | no | Output to whatever drives the device |
| ElapsedTime1 - ElapsedTime100 | numeric | yes | no | Elapsed time device has been on since last reset |
| HOAmode1 - HOAmode100 | numeric | no | yes | States whether device is in Hand, Off, or Auto mode |
| Reset1 - Reset100 | logical | no | yes | Used to reset the ElapsedTime data member |
| Response1 - Response100 | logical | no | yes | Response bit from device |
| RunTime1 - RunTime100 | numeric | yes | no | Elapsed time device has been on continuously |

Connecting the Alternator

The **DeviceRequest** data members should be connected to whatever drivers are controlling your devices. Notice that when you connect the **DeviceRequest** data member to anything, the **DeviceConnect** data member goes high. This connection is the only one required for the alternator to consider your device connected. The **RunTime**, **ElapsedTime**, **DeviceConnect**, and **DeviceOn** data members can be connected to or not depending on whether you want that information.

The **Command** data member is the essential writable data member to connect to. The connection to **Command** can be any numeric expression, but a pot is probably most convenient, especially for testing and demonstration purposes. It only accepts values in the integer range from zero to the number of **Device connections** specified as a parameter. To the **Response** data members should be connected a response bit from each device. If no connection is made to **Response** the alternator does not require any response from the device. The **Advance**, **Reset**, and **HOAMode** data members are not essential either; You need only make connections to them if you want their functionality. **Advance** and **Reset** typically are connected to pushbuttons, and **HOAMode** typically connects to a pot. The **HOAMode** data member only accepts values in the integer range from one to three.

Command and Advance

The **Command** data member is the number of devices that the alternator is to have running at one time. When you send the alternator its first command, it requests a corresponding number of devices to turn on. The **DeviceRequest** data member for each of these devices goes high to signify this. When the devices respond that they are in fact on via the **Response** data member, (if it is connected) the alternator recognizes that the device is on and the **DeviceOn** data member goes high. Conversely, if the **Command** data member specifies that devices are to be turned off, the **DeviceRequest** data members for the corresponding number of devices goes low. The devices should then respond accordingly via the **Response** data member.

When you give the alternator a numeric command, it takes into account the number of devices currently running, and makes its requests accordingly. Because of this, it is important to know how the alternator counts the number of devices running. Devices running as a result of a **Hand** command from the **HOAMode** data member are **NOT** counted. All other running devices (including those with active alarms) are.

When the alternator is asked to turn on a new device it chooses the device that has been off the longest. When asked to turn off a device it chooses the device that has been on the longest.

The **Advance** command turns on one device and turns off another device.

Maximum Run Time and Delay Operation

The **Maximum run time** parameter specifies how long any one device can be running. Each device has its own timer to ensure that this is enforced. When one of these timers informs the alternator that its device has been on for the maximum allowed time, the alternator executes a command identical to the **Advance** command. Notice that there are two cases where the maximum time limit is not enforced strictly. One of them is when you have turned on a device via the HOAmode data member. (Its operation is discussed in the next section.) The other is when it conflicts with the operation of the **Delay between device starts** feature.

Delay between device starts is specified as a parameter, and limits how often the alternator can turn on devices. An example of the operation of the **Delay between device starts** would be beginning with a new alternator that has none of the devices on. You issue a command using the Command data member of 3. If the delay feature is in use, the alternator sends three ON requests separated by the amount of time specified by **Delay between device starts**.

Hand-Off-Auto Modes

The **HOAmode** data member gives the user direct control over each device. The integer value of this numeric data member corresponds to an operating mode. (See Table 2-5.) When the **HOAmode** data member is in Auto mode (as it is by default if you never connect anything to this data member) it is subject to the commands of the alternator. Its **DeviceConnect** data member will be high to signify that the alternator recognizes it. When you select Hand mode, two things happen: The device is disconnected and is sent an on request. Similarly in Off mode the device is disconnected and requested off. In these two modes, the alternator does not recognize or request anything of these devices. If you select Auto mode again, the device is reconnected.

Table 2-5. HOA Modes

| HOA mode | Integer |
|----------|---------|
| Hand | 1 |
| Off | 2 |
| Auto | 3 |

Elapsed Time, Run Time, and Reset

The **ElapsedTime** data member keeps track of how long a particular device has been on since its last reset (or since it was created). Its value is in days, so by viewing it through a numeric expression you may select any time format.

The **RunTime** data member keeps track of how long a particular device has been on continuously. Its value is in days, so by viewing it through a numeric expression you may select any time format.

The **Reset** data member is used to reset **ElapsedTime**.

Alternator Status Messages

Not responding to on request

A device that was sent an ON request via the **DeviceRequest** data member did not respond that it had in fact turned on. The alternator attempts to turn it on again when its turn comes and the alarm remains active until the device responds properly to an alternator command.

Not responding to off request

A device that was sent an OFF request via the **DeviceRequest** data member did not respond that it had in fact turned off. The alternator attempts to turn it off again when its turn comes and the alarm remains active until the device responds properly to an alternator command.

Turned on unexpectedly

A device that was previously off and that the alternator expected to remain off turned on without reason. The alternator attempts to turn it off when its turn comes, and the alarm remains active until the device responds properly to an alternator command.

Turned off unexpectedly

A device that was previously on and that the alternator expected to remain on turned off without reason. The alternator attempts to turn it on when its turn comes, and the alarm remains active until the device responds properly to an alternator command.

Not responding to HOA command

A device did not respond properly to a command from the HOAmode data member. The alternator attempts to request it when its turn comes, and the alarm remains active until the device responds properly to an alternator command.

Animator

The Animator object class provides full graphical animation including horizontal and vertical motion, dynamic resizing and visibility, dynamic symbol sequencing and programmable color changes.

When you first create an animator object, the **Select graphic** dialog box appears.



Figure 2-6. Select Graphic Dialog Box

Select the graphic you want to animate. To animate colors, you must select a Windows Metafile (.wmf). A moving animation must have the series of images you want to animate arranged in a single bitmap so that each cell of the animation can be defined by a grid of rows and columns.

Animations

To create a moving animation, select the Animation name.

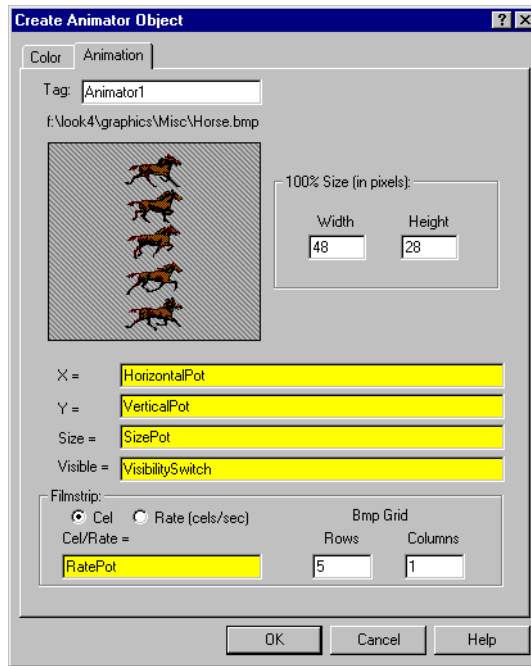


Figure 2-7. Animator Definition Parameters Dialog Box, Animation Tab

The graphic file you select determines what images appear on the screen. You delineate the images in a bitmap graphic by dividing it into a grid of **Rows** and **Columns**. In the preceding illustration, the single column is 48 pixels **Wide** and each row is 28 pixels **High**. Conceivably, the grid *could* consist of 32,000 cells. 100 cells would be more practical.

Each grid cell is a filmstrip image. Internally, the Animator assigns a cell number to each image. It normally plays the filmstrip by progressing from left to right and top to bottom, from the lowest cell number to the highest cell number.

The **Rate (cells/sec)** selection you use to specify a frequency at which the Animator progresses from one cell image to the next. The rate value can be positive or negative and can range from 0.0000005 (one frame every 23.148 days) to 100 frames per second.

If the rate value is negative, the Animator plays the filmstrip backwards, starting at the last cell.

You can use the **Cell** selection in the definition dialog box to identify a particular cell number to display. For example, you might use this selection to display a specific image when a PLC register is equal to a particular value. This is similar to the multistate object, but can provide many more states, depending on the number of cells in the bitmap.

The **X** and **Y** parameters specify the horizontal and vertical position of the image, respectively. These numeric parameters range from 0 to 100, and together provide the X-Y position of the image as a percent of the Animator dimension on a control panel.

Size is a numeric parameter that ranges from 0 to 100 percent, where 100 percent is the full size of a single cell as specified by **W** and **H**.

Visible is a logical parameter that causes the image to appear when it goes true and disappear when it goes false.

Color Animation

To create color changes programmatically, select the **Color** tab.

With this option, you can set the color map on a `.wmf` graphic using a series of five logical conditions and a default state. If no condition is true, the default state (or color map) is imposed.

You can choose a custom color map by clicking on the color sample associated with each logical condition. You can then select any color from the palette available on your computer.

Select the **Show Original Colors** box if you want the original color map of the .wmf file to be imposed for that condition.

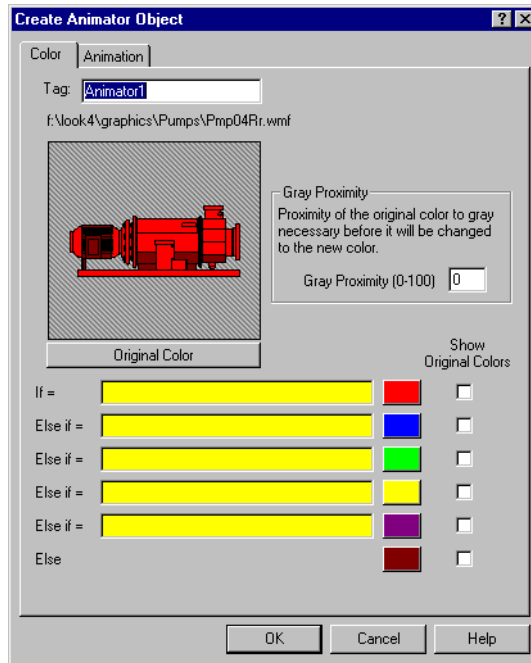


Figure 2-8. Animator Definition Parameters Dialog Box, Color Tab

Gray Proximity determines the color saturation point at which the selected color replaces an original color. When this parameter is set to 0, most colors change. When this parameter is set to 100, most colors will not change. You can test the effects of this setting by putting your cursor over the color button and observing the change in the graphic displayed in the dialog box window.

Notice that the if and else if statements are evaluated in sequence. If several conditional expressions are true at once, Multistate displays the graphic associated with the first true expression.

For instance, if your **If** parameters use less-than comparisons, such as `PumpSpeed<50`, the following **Else if** parameter must have a larger comparison value, such as `PumpSpeed<75`. If you use a smaller comparison value, such as `PumpSpeed<25`, the color change will not take place. In other words, the comparison values must be used from smallest to largest.

In the same way, if you are using greater-than comparisons, such as `PumpSpeed>50`, you must list your comparison values from largest to smallest, so that the next **Else If** parameter would have to be something like `PumpSpeed>25`.

Put **If** parameters using equality, such as `PumpSpeed=50`, before parameters using inequalities.

A few minutes experimentation should help you understand the interactions of the color choice conditions.

Animator Data Members

Table 2-6. Animator Data Members

| Data Member | Type | Read | Write | Description |
|-------------|------|------|-------|---|
| none | — | — | — | Animator objects do not have data members |

Comments Consider using an Integral object instead of a Counter/Pulse combination when trying to achieve smooth animation.

Related Objects [DialGauge](#), [Gauge](#), [Multistate](#), [Pipe](#), [Spinner](#)

Average

Average actively calculates the average value of **Data** over time. Average is only active when the **Enable** expression is true and resets to zero when the **Reset** expression transitions from off to on. Average also maintains an array of up to 35 previous averaged values. If **Enable** is left blank, the object always actively calculates the average.

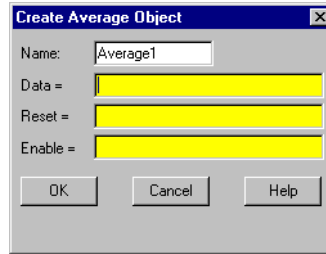


Figure 2-9. Average Definition Parameters Dialog Box

Data is a numeric expression while **Reset** and **Enable** are logical expressions.

Average Data Members

Table 2-7. Average Data Members

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|--|
| (implicit) | numeric | yes | no | Current average calculated since the most recent Reset signal. Updated approximately once per second. |
| 1 – 35 | numeric | yes | no | Previous average values. Signal 1 is the most recent prior average since the Reset signal went high. |
| DataReset | logical | no | yes | Upon transition from FALSE to TRUE, resets to zero all data members—including the current average and all previous averages. |

Comments The **Reset** expression could be a regular pulse interval created by a TimeOfxxxx timer, so that the pulse is synchronized to the top of the hour or day. For example, if you want to calculate the daily average flow rate, use the output signal from a TimeOfDay timer or a daily Spreadsheet object to reset the average calculation at the beginning of each day. If you want to calculate the average flow rate only when a pump is running, use the input signal from the pump motor relay in the **Enable** parameter.

Related Objects [Minimum](#), [Maximum](#), [Sample](#)

Counter

Counter counts the number of times that the **Count** expression transitions from off to on. The digital display shows the number of pulses counted so far, and is updated approximately once per second—however, it can receive and count multiple pulses within a given second. The counter can count to just under 4,503,600,000,000 or 142,710 years worth of pulses at one pulse per second. When the **Reset** expression transitions from off to on, the counter resets to zero.

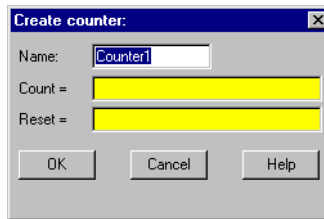


Figure 2-10. Counter Definition Parameters Dialog Box

Both **Count** and **Reset** are logical expressions.

Counter Data Members

Table 2-8. Counter Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|------------------------------|
| (implicit) | numeric | yes | no | numeric total of pulse count |

Comments You should not use Counters to count external pulse signals that cycle more often than about once per second. For higher counting speeds, use the accumulator capabilities built into your PLC.

Related Objects [Accumulator](#), [Integral](#)

DataTable

DataTables are used in the following applications:

- Multiplexing various data sources into a single display template.
- Importing or exporting large quantities of data to other applications using DDE. (Unlike the DdeTable, the DataTable provides bidirectional DDE communications. See [DdeTable](#).)
- Networking multiple Lookout nodes (see Chapter 5, *Networking*, in the *Lookout Developer's Manual*).

A DataTable contains a matrix of rows and columns, much like a spreadsheet. Each column is represented by a letter (A – IV). Each row is represented by a number (1 – 1,000). Letter-number combinations represent intersections of rows and columns. Such intersections are called cells. Any given cell contains a value. A cell value can be numeric, logical, or textual.



Note DataTables are advanced tools that require a mastery of Lookout object databases. Make sure you understand editing, connecting to, and using object databases and aliases before creating a DataTable object. See Chapter 4, *Using Lookout*, and Chapter 5, *Developer Tour*, in the *Getting Started with Lookout* manual for more information on object databases.

The following dialog box appears when you create a DataTable:

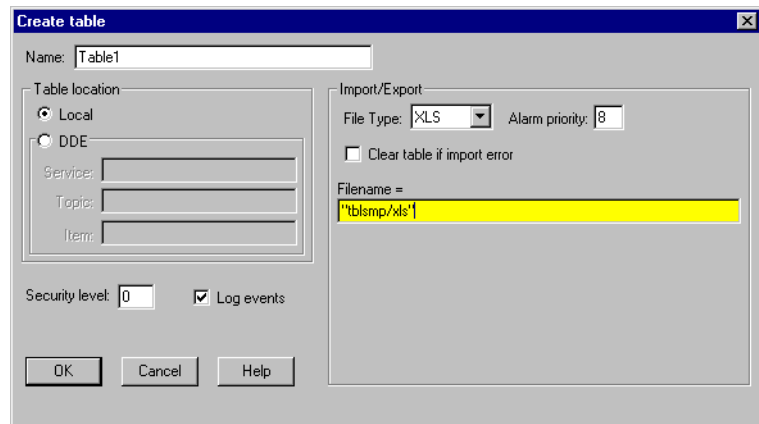


Figure 2-11. DataTable Definition Parameters Dialog Box

Specify **DDE** parameters if you want to use the DataTable to exchange large quantities of data from an external source (such as Excel) continuously, with both Lookout and the other program running. See Chapter 6, *Dynamic Data Exchange*, of the *Lookout Developer's Manual* for more information on DDE connections to other programs.

Specify **Local** if you are using the DataTable to import or export data from Lookout into or out of a static file. Also specify **Local** if you are using the DataTable to multiplex various signals into a single display or graphic template.

To exchange data with another DataTable running in another Lookout process, you can use ordinary Lookout connections.

The export and import data members control the transfer of data between Lookout and a Microsoft Excel spreadsheet. The spreadsheet filename must be entered in the **Import/Export** section of the **Create table** dialog box.



Note The data table import and export data members only work with Microsoft Excel Version 4 at this time. This feature does not work with Excel Version 5 or greater.

Instead of entering a file name in the **Import/Export** dialog box, you can enter a Lookout expression in the **Filename** field. You can then import and export different files using a switch setting, a text entry box, or some other expression input. If something goes wrong with the transfer of data, including data corruption, Lookout reports an alarm.

Click on the **Clear table if import error** checkbox to clear the DataTable before importing either from a spreadsheet or an ODBC database. This only affects what happens if there is an error during the import. If there are no errors during the import, the imported data always replaces the old data in the table. However, if the checkbox is selected, the DataTable is always cleared before starting an import, so that, if an error occurs, the DataTable is left empty. If the checkbox is not checked and an error occurs, the old data is left in the table.

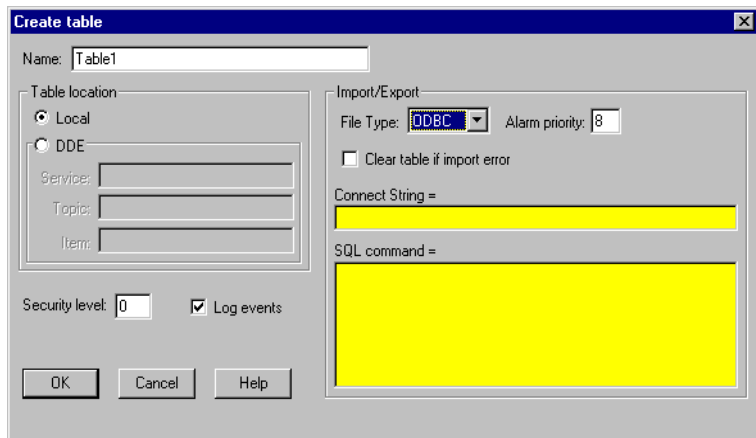


Figure 2-12. DataTable Definition Parameters Dialog Box; Import from ODBC Database

The **Connect String=** field specifies the DataSource Name (DSN) as well as any other parameters needed by the ODBC driver to make the connection to your chosen data source.

The **SQL command=** field is where you enter the SQL string you want to pass to the ODBC driver. See the [SqlExec](#) object for more information about using SQL queries in Lookout.

Use the **Clear table if import error** checkbox to clear the DataTable before importing either from an ODBC database or a spreadsheet. This only affects what happens if there is an error during the import. If there are no errors during the import, the imported data always replaces the old data in the table. However, if the checkbox is selected, the DataTable is always cleared before starting an import, so that, if an error occurs, the DataTables left empty. If the checkbox is not checked and an error occurs, the old data is left in the table.

Multiplexing Displays and Graphics

You can use DataTables to multiplex signals into a single control panel, used as a template. For instance, assume you have nine identical pump stations. At each site you have a single PLC monitoring the pressure, flow rate, and status of two pumps. You are also controlling an analog output with an operator setpoint from Lookout. Instead of developing nine identical control panels in Lookout, you can build just one panel and multiplex the signals from the nine sites into a single set of graphics.

The following figure is a graphical representation of the connections for a possible DataTable.

| | A | B | C | D | E | F |
|---|-------|------------|-----------|--------------------------|-----------|-----------|
| 1 | Site1 | PLC1.press | PLC1.flow | Setpoint Value Column | PLC1.pmp1 | PLC1.pmp2 |
| 2 | Site2 | PLC2.press | PLC2.flow | | PLC2.pmp1 | PLC2.pmp2 |
| 3 | Site3 | PLC3.press | PLC3.flow | | PLC3.pmp1 | PLC3.pmp2 |
| 4 | Site4 | PLC4.press | PLC4.flow | | PLC4.pmp1 | PLC4.pmp2 |
| 5 | Site5 | PLC5.press | PLC5.flow | | PLC5.pmp1 | PLC5.pmp2 |
| 6 | Site6 | PLC6.press | PLC6.flow | | PLC6.pmp1 | PLC6.pmp2 |
| 7 | Site7 | PLC7.press | PLC7.flow | | PLC7.pmp1 | PLC7.pmp2 |
| 8 | Site8 | PLC8.press | PLC8.flow | | PLC8.pmp1 | PLC8.pmp2 |
| 9 | Site9 | PLC9.press | PLC9.flow | | PLC9.pmp1 | PLC9.pmp2 |

Figure 2-13. Graphical Representation of a DataTable Showing Connections



Note At this time there is no actual view in Lookout for you to see this table. It is a representation, not a screen capture of a Lookout dialog box or display element.

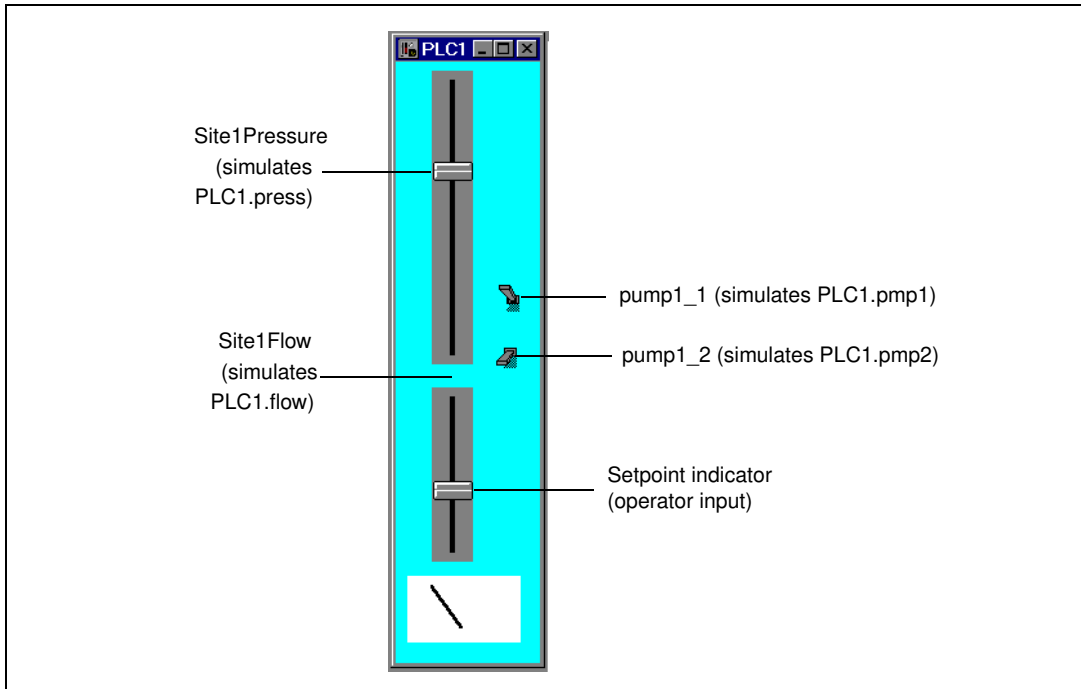
Each row of the table is connected to the site name, the data you want to keep track of from the PLC at that site, and a place for the operator setpoint data for that site.

Notice the names of the nine PLCs (PLC1, PLC2...). Each value has an alias (press, flow, pmp1, pmp2). Each cell represents a connection made from that PLC output to the that cell of the DataTable.

The open column D represents the connection of a single Pot object called *Setpoint* to the column—not to individual cells. This way Lookout only changes the value of a cell in column D when that particular row has been made active. You connect the individual cells in column D (D1 through D9) to the correct holding registers (outputs) on the respective PLCs. For example, `Table1.D1` would be connected to the appropriate data member of PLC1 – `Table1.D2` to the appropriate data member of PLC2, and so on. In other words, when you intend to multiplex signals to a panel through a data table connect inputs from a PLC or RTU to individual cells. Connect operator setpoints (outputs) to columns.

DataTable Example

To practice using a DataTable, you can create a PLC simulator as shown in the following illustration. You can use a separate control panel for each PLC output simulator, or place all the objects you make on one panel.



Use two slider pots as your pressure and flow outputs, and two switches as the on/off indicators for pumps one and two. You can use the dial gauge at the bottom to check the operator input, `Setpoint`. Instead of connecting the cells of your data table to PLC outputs, you connect directly to the Lookout objects, named after the outputs for clarity.

You should create at least three sets of PLC input/output simulators. The following example refers to the 9 PLCs mentioned in the [Multiplexing Displays and Graphics](#) section, but you can explore using a data table using 2 or 3 simulators.

Connect specific DataTable cells from the `D` column to the Setpoint indicator for each PLC simulator.

After you have built your simulators, open a new Control Panel to use as your display and create a DataTable. You will create the rest of the display in a later step.



When it first appears, the DataTable contains the number 0. This indicates the contents of cell A1. You can increase the size of the display window, but you cannot show the entire array of data in the table. You can view the contents of any cell in column A by clicking on the window when you are in run mode. Selecting the contents of that cell activates that row of the data table.

Enter text expressions into the cells of column A to act as your table index. For example, enter the string "Site 1" as the connection to your DataTable A1.txt data member. Connect the outputs of your PLC simulators to the cells in the B, C, E, and F columns shown in the following figure. You will connect an operator input to the entire column D, and then later connect individual cells in the D column to your PLC simulators.

| | A | B | C | D | E | F |
|---|--------|---------------|-----------|---|---------|---------|
| 1 | Site 1 | Site1Pressure | Site1Flow | | pump1_1 | pump1_2 |
| 2 | Site 2 | Site2Pressure | Site2Flow | | pump2_1 | pump2_2 |
| 3 | Site 3 | Site3Pressure | Site3Flow | | pump3_1 | pump3_2 |
| 4 | Site 4 | Site4Pressure | Site4Flow | | pump4_1 | pump4_2 |
| 5 | Site 5 | Site5Pressure | Site5Flow | | pump5_1 | pump5_2 |
| 6 | Site 6 | Site6Pressure | Site6Flow | | pump6_1 | pump6_2 |
| 7 | Site 7 | Site7Pressure | Site7Flow | | pump7_1 | pump7_2 |
| 8 | Site 8 | Site8Pressure | Site8Flow | | pump8_1 | pump8_2 |
| 9 | Site 9 | Site9Pressure | Site9Flow | | pump9_1 | pump9_2 |

Connecting Signals to DataTables

To connect a value to a particular cell or column within a DataTable, use the **Object»Edit Connections...** command. Select the specific data member of the DataTable to be written, and identify the data member of the source object.

Connecting to Cells

The value from `Site1Pressure` is numeric. To write the value of `Site1Pressure` into cell B1, connect the simulated output to B1—not `B1.logical` or `B1.txt`. The **Edit connection** dialog box is shown in the following illustration.

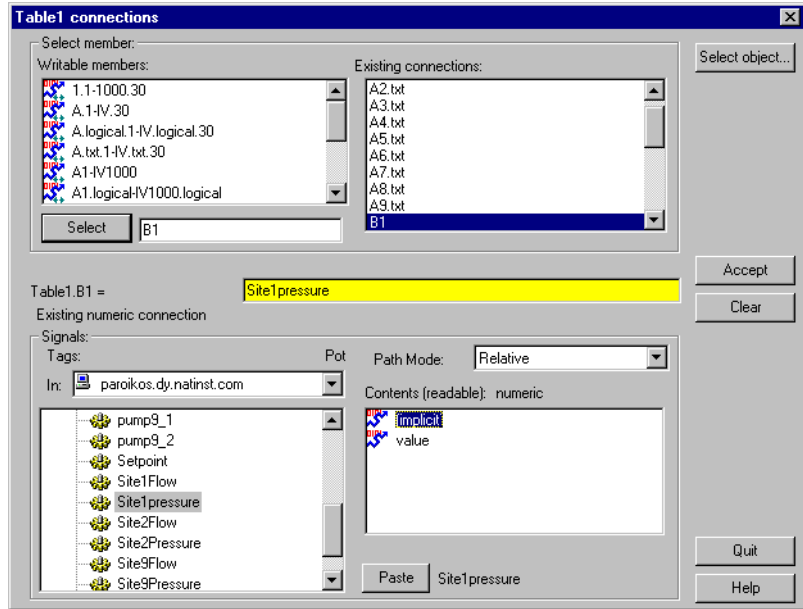


Figure 2-14. Edit Connections Dialog Box

After you establish a connection to a cell, the value within the cell changes any time the expression changes. Any time the value of `Site1Pressure` changes, the value within cell B1 changes.

Connecting to Columns

To connect the value of the `Setpoint` potentiometer to column D, select `D`—not `D.logical` or `D.txt`—as shown in the following illustration. As with the previous value, you use `D` because you are using a numerical value. There is no number following the `D` because you are connecting to a column, not a cell.

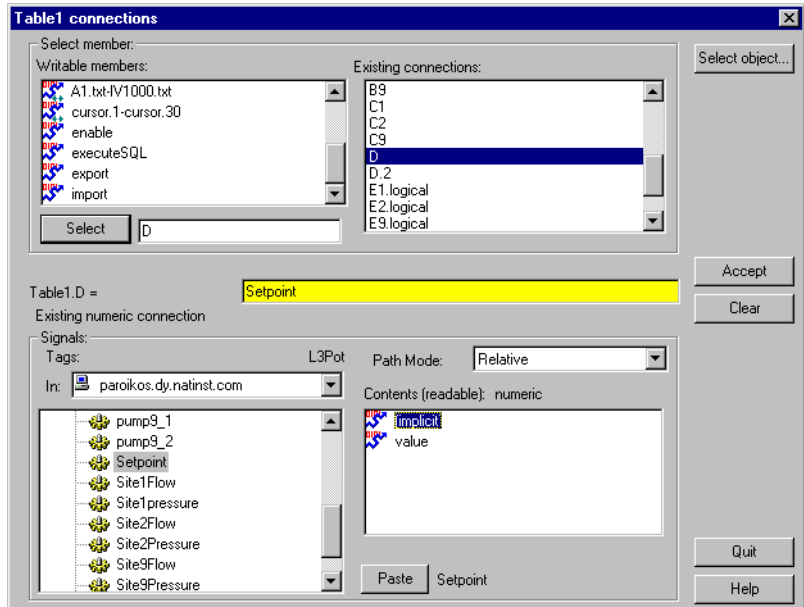
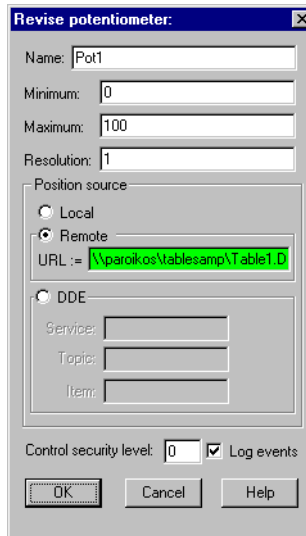


Figure 2-15. Edit Connections Dialog Box

Once a connection to a column is established, the value within the cell *at the currently selected row* changes when the expression changes. So, if you activate row 4 and change the value of `Setpoint` changes, the value within cell `D4` changes. No other cells are affected until you move the cursor to activate another row and the operator adjusts the pot.

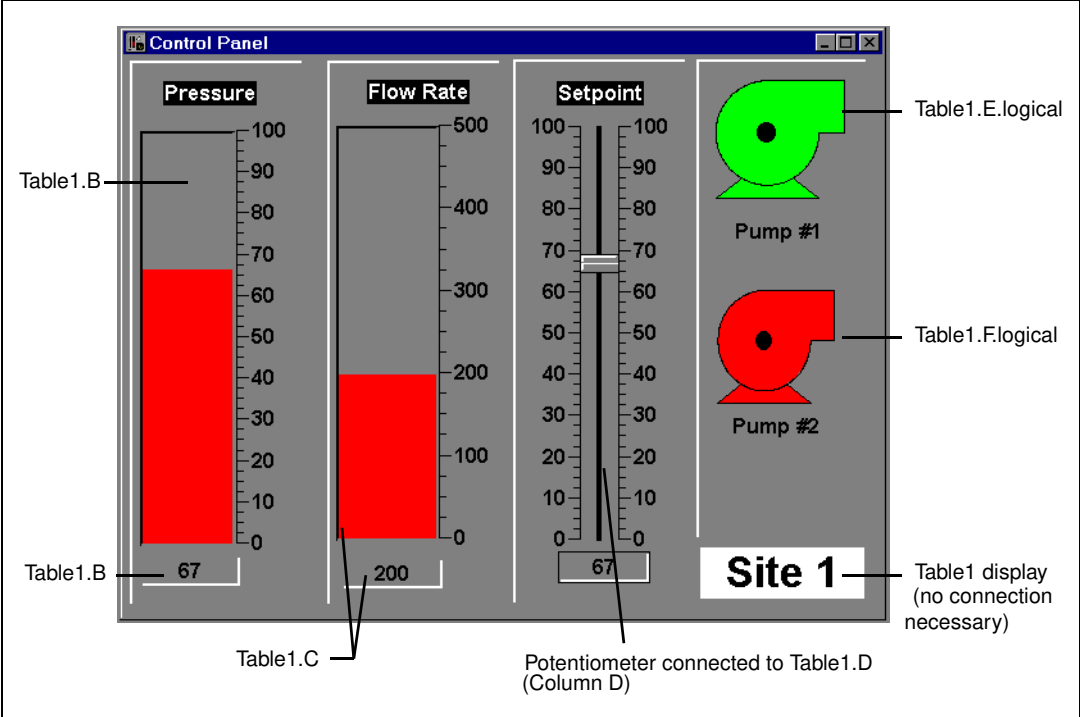
Reading a Cell Value Back to a Lookout Object

When you connect the display panel potentiometer called `Setpoint` to `Table1.D`, you should configure your pot with the appropriate **Remote** parameter to ensure that it automatically adjusts to track the value in any cell (within the specified column) when the cursor moves to a new row.



The Display Panel

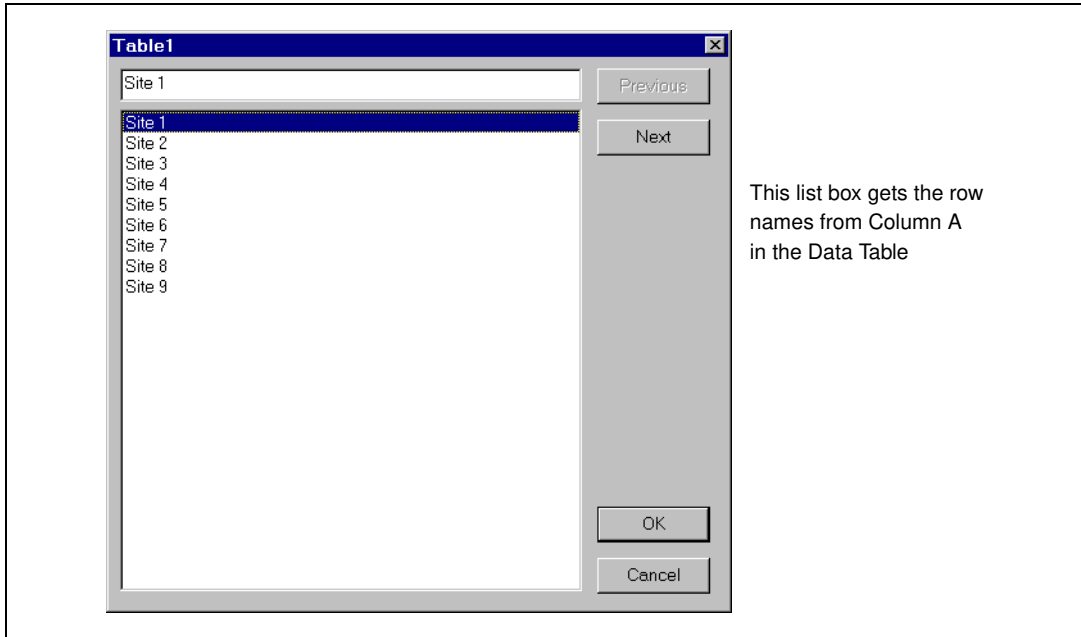
Now that your DataTable (called `Table1`) is complete, you can return to your display panel (where you placed the DataTable object initially) and begin to build a single control panel that allows you to multiplex the data from your PLCs. A sample panel is shown in the following illustration.



Instead of using expressions that reference the actual values from your driver objects to display values, use the column names from `Table1`. For instance, the bar graph and numeric readout for Pressure both represent the expression `Table1.B`. The actual value for `Table1.B` depends on what row is currently active in the DataTable. In the illustration row 1 is active, so all the expressions return the value in their respective columns at row 4. The callouts in the picture indicate how the control panel was developed. All are Lookout expressions except the Pot and the DataTable, which are displayable objects.

Operating Your Multiplexed Panel

The plate in bottom right corner of the control panel is the DataTable object (Table1). To view a different site with the control panel (that is, to activate a different row, thereby selecting a different PLC), click on Table1 and the following dialog box should appear.



By selecting a site, you connect your control panel to the PLC at that site. This is referred to as moving the cursor to that row.

DataTable Cursors

The cursor is a DataTable pointer that you can move from row to row to activate the values in the cells of that row. There are several methods for controlling the location of the cursor:

- Connect a numeric expression to the `cursor` data member. A typical example would be to connect a potentiometer (minimum = 1, maximum = the number of rows in table, resolution = 1) to the cursor.
- Connect logical expressions to appropriate row numbers. A typical example would be to create a pushbutton for every row and then connect them to their respective row numbers.

- Use the display (list box) built into the DataTable object. A typical example was described previously where you connected text values to cells in column A and then displayed the table as a plate.

The following example provides a graphical representation of a DataTable (called Table1) showing typical values within its many cells. You can create a multiplex effect in Lookout by referencing column names and then selecting the row with the information you want to use. If you reference column names (instead of individual cells), the DataTable outputs only the values within the currently selected row. If you reference individual cells, the DataTable outputs the current value within the cell—no matter where the cursor is.

| | A | B | C | D | E | F |
|---|--------|------|-----|----|---|---|
| 1 | Site 1 | 67.8 | 540 | 56 | 0 | 1 |
| 2 | Site 2 | 77.9 | 460 | 43 | 0 | 1 |
| 3 | Site 3 | 57.3 | 480 | 78 | 0 | 1 |
| 4 | Site 4 | 57.8 | 410 | 51 | 1 | 1 |
| 5 | Site 5 | 51.8 | 560 | 92 | 1 | 0 |
| 6 | Site 6 | 88.3 | 490 | 40 | 0 | 1 |
| 7 | Site 7 | 79.4 | 530 | 63 | 1 | 0 |
| 8 | Site 8 | 92.1 | 520 | 71 | 1 | 0 |
| 9 | Site 9 | 59.9 | 550 | 62 | 0 | 1 |

| | | | | | | |
|------------------|--------------|-------------|------------|-----------|----------|----------|
| Outputs = | Site2 | 77.9 | 460 | 78 | 0 | 1 |
|------------------|--------------|-------------|------------|-----------|----------|----------|

Figure 2-16. DataTable with Cursor at Row 2 and Corresponding Outputs

The value of cell B2 is currently 77.9. Therefore, the `Table1.B` data member is also 77.9. If you move the cursor to row 9, the value of `Table1.B` changes to 59.9, as shown.

| | A | B | C | D | E | F |
|---|--------|------|-----|----|---|---|
| 1 | Site 1 | 67.8 | 540 | 56 | 0 | 1 |
| 2 | Site 2 | 77.9 | 460 | 43 | 0 | 1 |
| 3 | Site 3 | 57.3 | 480 | 78 | 0 | 1 |
| 4 | Site 4 | 57.8 | 410 | 51 | 1 | 1 |
| 5 | Site 5 | 51.8 | 560 | 92 | 1 | 0 |
| 6 | Site 6 | 88.3 | 490 | 40 | 0 | 1 |
| 7 | Site 7 | 79.4 | 530 | 63 | 1 | 0 |
| 8 | Site 8 | 92.1 | 520 | 71 | 1 | 0 |
| 9 | Site 9 | 59.9 | 550 | 62 | 0 | 1 |

| | | | | | | |
|------------------|--------------|-------------|------------|-----------|----------|----------|
| Outputs = | Site9 | 59.9 | 550 | 62 | 0 | 1 |
|------------------|--------------|-------------|------------|-----------|----------|----------|

Figure 2-17. DataTable with Cursor at Row 9 and Corresponding Outputs

Using Multiple Cursors

The previous description assumes you are using just one cursor. But a `DataTable` can have up to 20 cursors. Multiple cursors allow you to select multiple rows at the same time. When using multiple cursors, you also use multiple names for each column. For a given column, each name is associated with a given cursor. If you are using two cursors in the previous example (`cursor` and `cursor.2`), you can reference the column name of a given column as follows:

Table 2-9. Column Names

| | A | B | C | D | E | F |
|----------|---------|-----|-----|-----|-------------|-------------|
| cursor | A.txt | B | C | D | E.logical | F.logical |
| cursor.2 | A.txt.2 | B.2 | C.2 | D.2 | E.logical.2 | F.logical.2 |

Earlier, when you were using just one cursor, you connected the value of a potentiometer called `Setpoint` to column D. Subsequently the value of `Setpoint` was written to the cell at the row selected by the cursor. But when there are multiple cursors, you have to select which cursor you are writing to. Thus, depending on how you want your table to work, you might connect the potentiometer to both `Table1.D` and `Table1.D.2`.

DataTable Data Members

Table 2-10. DataTable Data Members

| Data Members | Type | Read | Write | Description |
|--------------|----------|------|-------|--|
| executeSQL | logical | no | yes | Imports data from an ODBC database into the DataTable when value goes high, using the connect string and SQL command you enter in the Create/modify DataTable dialog box. |
| (implicit) | DdeTable | no | no | Not displayable in Lookout, but it can be referenced by a DDE link from another application. |
| 1.1–1000.20 | logical | no | yes | Specifies row (1, 2, 3, ...1000) or specifies row.cursor (for example, 24.2 is the selector for row 24, cursor 2). Upon transition from false to true, the specified cursor moves to specified row. |
| A.1–IV.20 | numeric | yes | yes | Specifies column names (for example, A, B, C...IV) or specifies column names and associated cursor numbers (such as, A.1, B.1, A.2, B.2, and so on.) <i>Read</i> —returns a numeric value from the cell specified by the column and currently selected row of the indicated cursor. <i>Write</i> —writes a numeric value into the cell specified by the column and currently selected row of the indicated cursor. |

Table 2-10. DataTable Data Members (Continued)

| Data Members | Type | Read | Write | Description |
|-----------------------------|-------------|-------------|--------------|---|
| A.logical.1 – IV.logical.20 | logical | yes | yes | <p>Specifies column names (for example, A.logical, B.logical, C.logical, ...IV.logical) or specifies column names and associated cursor numbers (such as, A.logical.1, B.logical.1, A.logical.2, B.logical.2, and so on.)</p> <p><i>Read</i>—returns a logical value from the cell specified by the column and currently selected row of the indicated cursor.</p> <p><i>Write</i>—writes a logical value into the cell specified by the column and currently selected row of the indicated cursor.</p> |
| A.txt.1 – IV.txt.20 | text | yes | yes | <p>Specifies column names (for example, A.txt, B. txt, C. txt, ...IV.txt) or specifies column names and associated cursor numbers (such as, A. txt.1, B. txt.1, A. txt.2, B. txt.2, and so on.)</p> <p><i>Read</i>—returns a text value from the cell specified by the column and currently selected row of the indicated cursor.</p> <p><i>Write</i>—writes a text value into the cell specified by the column and currently selected row of the indicated cursor.</p> |
| A1 – IV16384 | numeric | yes | yes | Specified cell interpreted as numeric value |
| A1.logical –IV16384.logical | logical | yes | yes | Specified cell interpreted as logical value |
| A1.txt –IV16384.txt | text | yes | yes | Specified cell interpreted as text value |

Table 2-10. DataTable Data Members (Continued)

| Data Members | Type | Read | Write | Description |
|----------------------|-------------|-------------|--------------|--|
| Cursor.1 – Cursor.20 | numeric | yes | yes | Specifies the currently selected row of the indicated cursor. |
| enable | logical | yes | yes | If TRUE (the default), enables DDE. If FALSE, disables DDE. The default value is on. The input is ignored for non-DDE TextEntry objects. |
| export | logical | no | yes | When this input transitions from false to true, the Lookout data table is exported to the designated spreadsheet file. |
| import | logical | no | yes | When this input transitions from false to true, the Lookout data table imports data from the designated spreadsheet. |
| Modified | logical | yes | no | Pulses TRUE when any cell value in the DataTable changes. |
| Update | logical | yes | no | Pulses each time the cursor changes rows. Often used to “call up” a control panel. |

Related Objects [DdeTable](#), [DdeLink](#)

DdeLink

DdeLink creates a unidirectional Dynamic Data Exchange (DDE) link to another application. The other application could be running on the same computer or on another computer over a network. DdeLink objects provide an easy way to *import* remote values into Lookout. See Chapter 5, *Dynamic Data Exchange*, in the *Lookout Developer's Manual* for more information on DDE. For each DdeLink object you define, Lookout creates a separate link to the other application. If you need to import large quantities of data, you should use the DdeTable or DataTable object. See [DdeTable](#) and [DataTable](#) for more information.

DdeLinks on Same Computer

If you are importing values from another application running on the same computer, your DDE parameters will look similar to the ones in the following illustration.



Figure 2-18. DdeLink Definition Parameters Dialog Box (Same Computer)

Service specifies the application name, **Topic** specifies the file, and **Item** points to the individual value (r1c1 refers to the cell at row1, column1. Unfortunately, Excel does not support the more convenient A1 cell references with DDE).

DdeLinks to Remote Computer

If you are importing values from another application running on a remote computer, your DDE parameters will look similar to the ones in the following illustration.

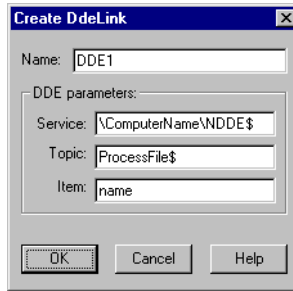


Figure 2-19. DdeLink Definition Parameters Dialog Box (Remote Computer)

Notice the differences in the **Service**, **Topic**, and **Item** parameters. The backslashes (\\) and dollar signs (\$) are standard requirements for making network connections in Microsoft Windows. `ComputerName` specifies the network name of the computer you are connecting to. If you are connecting to a value in another Lookout application, `ProcessFile` is the Lookout file name running on the remote computer, and `Name` refers to the name you are linking to.

DdeLink Data Members

Table 2-11. DdeLink Data Members

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|--|
| (implicit) | numeric | yes | no | DDE link interpreted as numeric value. |
| enable | logical | yes | yes | If TRUE (the default), enables DDE. If FALSE, disables DDE. This input is ignored for non-DDE TextEntry objects. |
| hot | logical | yes | no | Status of DDE link. |
| logical | logical | yes | no | DDE link interpreted as logical value. |
| txt | text | yes | no | DDE link interpreted as text value. |

Related Objects [DdeTable](#), [DataTable](#)

DdeTable

DdeTable creates a unidirectional Dynamic Data Exchange (DDE) link to another application. The other application could be running on the same computer or on another computer over a network. See Chapter 5, *Dynamic Data Exchange*, in the *Lookout Developer's Manual* for more information on DDE. You can use DdeTable to *import* large quantities of data from other applications. The table format is much more efficient at transferring data than the Link format because a table can contain hundreds or even thousands of data points that all share a single link. On the other hand, the link format can only transfer a single value per link—and every link requires a certain amount of CPU overhead. If you are only importing a relatively small amount of data, you may find the DdeLink technique easier to implement.

DdeTable on Same Computer

If you are importing values from another application running on the same computer, your DDE parameters will look similar to the ones in the following figure.



Figure 2-20. DdeTable Definition Parameters Dialog Box (Same Computer)

Service specifies the application name, **Topic** typically specifies the file, and **Item** specifies the particular data item name.

The following example shows an Excel spreadsheet with the highlighted range named Data.

| | Data | | Pressures | |
|---|-----------|----------|-----------|---------|
| | A | B | C | D |
| 1 | Pressures | Temps | Flows | Times |
| 2 | 99 | 574.9 | 12 | 1:23:04 |
| 3 | 11 | 442 | 21 | 0:30:13 |
| 4 | 98.51 | 602.4 | 34 | 0:57:45 |
| 5 | | | | |
| 6 | Ammonia | Chlorine | Alum | Status |
| 7 | 0.076 | 1.34 | 27.87 | ON |

You can now display any value in the range Data with this Lookout DdeTable object.

Select **Insert>Expression...** and then choose the DdeTable data member corresponding to the Excel spreadsheet cell containing the value you want to display. Make sure that the type of data member you select matches the type data in the spreadsheet cell.

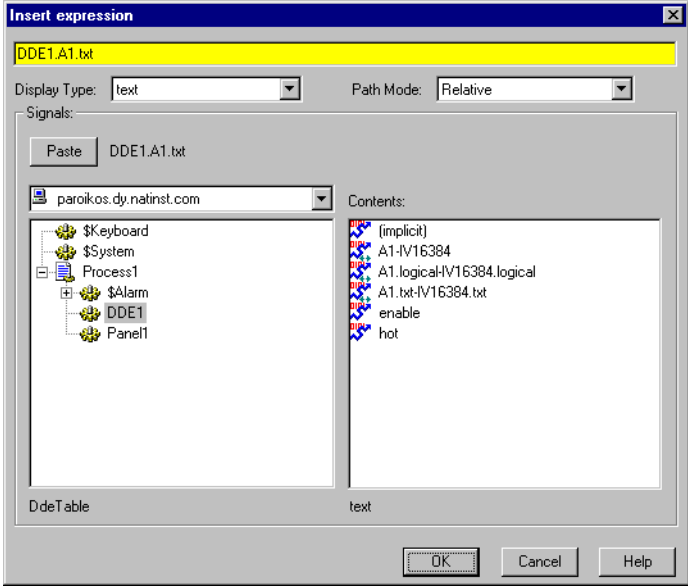
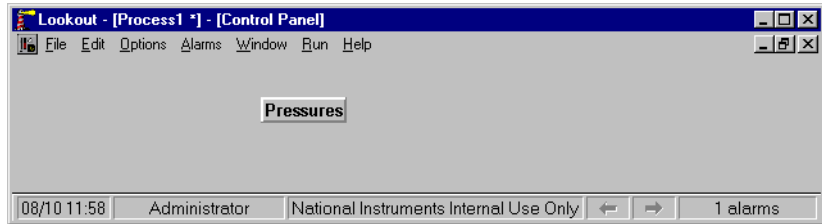


Figure 2-21. Inserting a DdeTable Expression

Notice the reference for the displayed item in the Lookout status bar.



DdeTable to Remote Computer

Using the DdeTable object over a network is somewhat different from the previous example.

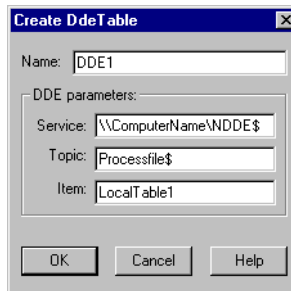


Figure 2-22. DdeTable Definition Parameters Dialog Box (Remote Computer)

Notice the differences in the **Service**, **Topic**, and **Item** parameters. The backslashes (\\) and dollar signs (\$) are standard requirements for making network connections in Windows. `ComputerName` specifies the network name of the computer you are connecting to. If you are connecting to a DdeTable or DataTable in another Lookout application, `ProcessFile` is the Lookout file name running on the remote computer, and `LocalTable1` refers to the DdeTable or DataTable object you are linking to.

DDETable Data Members

Table 2-12. DdeTable Data Members

| Data Members | Type | Read | Write | Description |
|------------------------------|-------------|-------------|--------------|--|
| (implicit) | numeric | yes | no | Cell A1 interpreted as a numeric value |
| A1 – IV16384 | numeric | yes | no | Specified cell interpreted as a numeric value |
| A1.logical – IV16384.logical | logical | yes | no | Specified cell interpreted as a logical value |
| A1.txt – IV16384.txt | text | yes | no | Specified cell interpreted as a text value |
| enable | logical | yes | yes | If TRUE (the default), enables DDE. If FALSE, disables DDE. This input is ignored for non-DDE TextEntry objects. |
| hot | logical | yes | no | Status of DDE link |

Related Objects [DataTable](#), [DdeLink](#)

DelayOff

DelayOff is an adjustable delay timer. When **On/off signal** transitions to off, the **Timer delay** begins to count down. At the end of the delay countdown, the output signal turns off. **On/off signal** must remain off during the time delay period for the output signal to turn off. The output immediately turns on when the **On/off signal** turns on.

Timer delay can range from 0.0 seconds to several years, and the effective resolution is 0.1 seconds over the entire range. The timer display digitally shows the time delay remaining, and is updated approximately once per second. If the **On/off signal** is high, the timer display shows `on`. If the **Timer delay** period has expired, the display shows `off`.

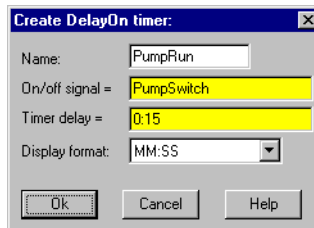


Figure 2-23. DelayOff Definition Parameters Dialog Box

The **On/off signal** is a logical expression while **Timer delay** is a numeric expression. Normally, this is a simple time constant such as 0:20—twenty seconds. See *Numeric Data Members* in Chapter 2, *Introduction*, of the *Getting Started with Lookout* manual for information on entering time constants.

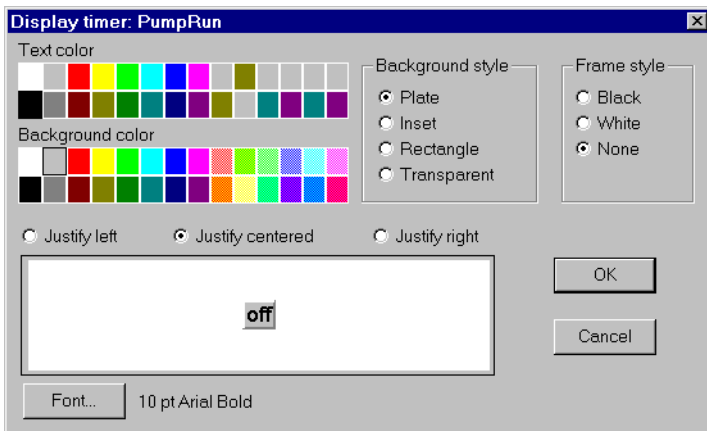


Figure 2-24. DelayOff Display Parameters Dialog Box

DelayOff Data Members

Table 2-13. DelayOff Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|---------------------|
| (implicit) | logical | yes | no | Logical timer value |

Comments The DelayOff timer can prevent a pump from short-cycling.

Related Objects [DelayOn](#), [Interval](#), [OneShot](#), [Pot](#), [TextEntry](#)

DelayOn

DelayOn is an adjustable delay timer. When **On/off signal** transitions to on, the **Timer delay** begins to count down. At the end of the delay countdown, the output signal turns on. **On/off signal** must remain on during the time delay period for the output signal to turn on. The output immediately turns off when the **On/off signal** turns off.

Timer delay can range from 0.0 seconds to several years, and the effective resolution is 0.1 seconds over the entire range. The timer display digitally shows the time delay remaining and is updated approximately once per second. The timer display shows `off` when the **On/off signal** is low. If the **Timer delay** period has expired, the display shows `on`.

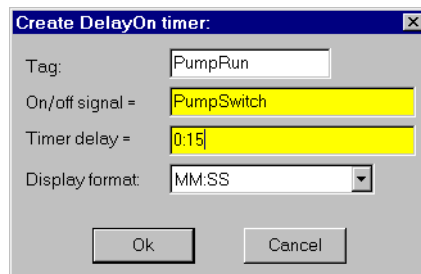


Figure 2-25. DelayOn Definition Parameters Dialog Box

The **On/off signal** is a logical expression while **Timer delay** is a numeric expression. Normally, this is a simple time constant such as 0:20—twenty seconds. See *Numeric Data Members* in Chapter 2, *Introduction*, of the *Getting Started with Lookout* manual for information on entering time constants.

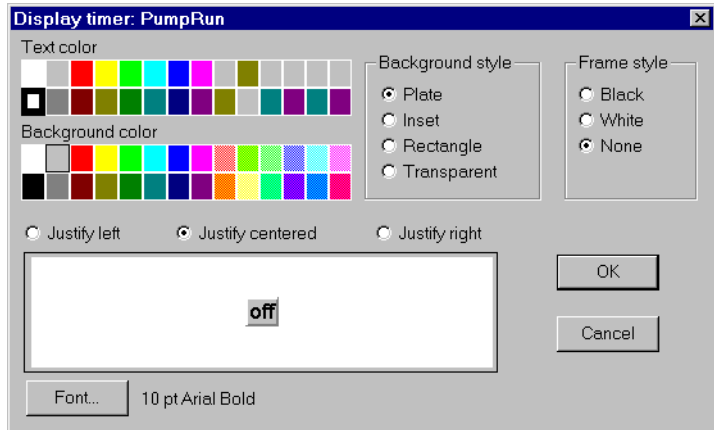


Figure 2-26. DelayOn Display Parameters Dialog Box

DelayOn Data Members

Table 2-14. DelayOn Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|---------------------|
| (implicit) | logical | yes | no | Logical timer value |

Comments The DelayOn timer can be used to prevent pumps from cycling too often, to allow one operation to complete before another begins, or to require a condition to exist for a period of time before an alarm is activated.

Related Objects [DelayOff](#), [Interval](#), [OneShot](#), [Pot](#), [TextEntry](#)

Derivative

Derivative can also be called a rate of change object—it calculates the rate of change of the incoming numeric input signal. You can use this class to calculate the rate at which a tank is filling or draining, or to convert a changing totalized flow value into a flow rate. The output units are in Input Units/Time Unit.

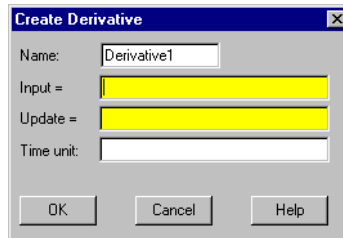


Figure 2-27. Derivative Definition Parameters Dialog Box

The previous example calculates the rate of change in the water level of a tank. Lookout polls the RTU connected to the tank level transmitter every 5 minutes, so this example uses the RTU update data member as the Update pulse for the Derivative object. Tanklevel is in feet and Time unit is 1 minute, so the output result is in feet per minute.

Input is the numeric expression you are monitoring for rate of change.

Update can be a logical expression or numeric constant. If you specify **Update** as a numeric constant, it creates an internal pulse timer with a pulse period of the specified time and a pulse duration of zero. See *Numeric Data Members* in Chapter 2, *Introduction*, of the *Getting Started with Lookout* manual for information on entering time constants. If you specify **Update** as a logical variable, the variable should pulse at the frequency you want to use.

The **Update** expression triggers the calculation of a new rate-of-change based on the **Input** value at the prior **Update**, and the current **Input** value. The current **Input** value is then stored as the prior **Input** value for the next calculation. The **Update** period should be greater than the refresh rate of the incoming signal; or if the Input is generated directly by external I/O, the update data member generated by the PLC object should be used. If the **Update** period is less than the **Input** refresh rate, the rate of change calculation fluctuates erratically between zero and a high value.

Time unit is a numeric expression used as the basis for unit time on the Input signal. For instance, if the rate of change should be in feet per minute, the Input signal would be feet, and **Time unit** would be one minute (entered as 1:00). Typically the **Time unit** is one second (0:01), one minute (1:00), one hour (1:00:00), or one day (1:00:00:00). However, you can specify any unit, such as 5:23 (a rate of change in Input units per five minutes and 23 seconds).

Derivative Data Members

Table 2-15. Derivative Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|----------------|
| (implicit) | numeric | yes | no | Rate of change |

Comments Derivative performs the inverse function of Integral—you can theoretically run a signal through an Integral object and then a Derivative object (or vice versa) and you would end up with the original signal. (Discretization of the time calculations by the computer may cause the final and original signals to differ somewhat).

It is important to consider the resolution of the process variable measured by the PLC when determining the Update period for this object. For instance, if a pressure transmitter connected to a PLC only has a resolution of 0.5 psi and you want to measure rates down to 1 psi/minute, the Update pulse must be greater than 30 seconds even if the PLC is polled once per second (i.e., 0.5 psi/1 psi/min. = 30 sec.). For this application, the Update pulse should probably be about two minutes.

Related Objects [Integral](#)

DialGauge

The DialGauge object class displays a numeric signal as a sweeping needle on an analog gauge or dial.

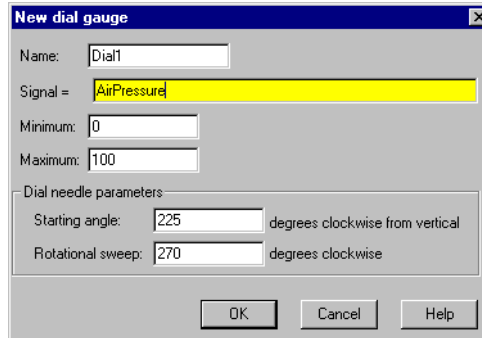
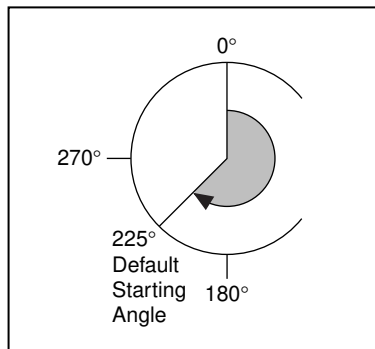


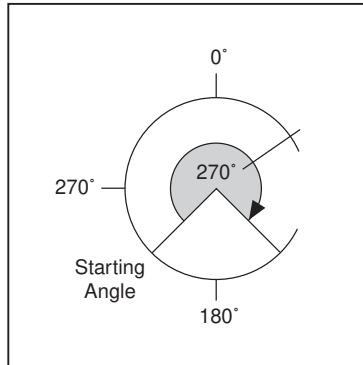
Figure 2-28. DialGauge Definition Parameters Dialog Box

Signal is a numeric expression.

Starting angle indicates the position of the needle when the **Signal** is at its **Minimum** value. As shown here, you specify the starting needle position by counting the degrees clockwise from vertical.



Rotational sweep specifies the number of degrees clockwise that the needle will rotate as the **Signal** approaches the **Maximum** value. As shown in the diagram here, you count the **Rotational sweep** in degrees clockwise from the **Starting angle**.



After you specify the DialGauge definition parameters, Lookout presents a display parameters dialog box, as shown here. You use this dialog box to specify needle color, thickness, and length.

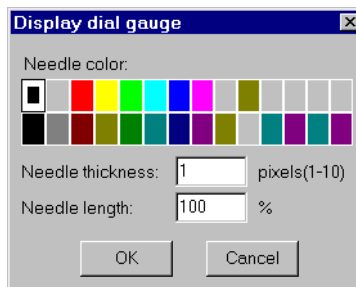
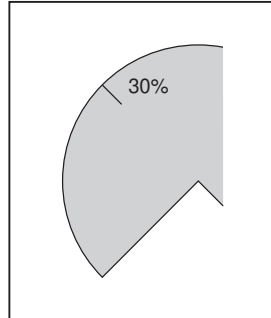


Figure 2-29. DialGauge Display Parameters Dialog Box

Needle thickness defines how wide your needle will be. Thickness can range from one pixel (hairline) to 10 pixels wide.

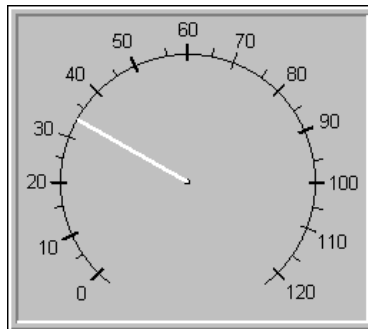
Needle length specifies the length of the needle as a percent of the radius. At 30 percent, for example, only the outer tip of the needle is visible—you cannot see the part of the needle closest to the origin. At 100 percent, the needle extends the full radius of the circle.



DialGauge Data Members

Table 2-16. DialGauge Data Members

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|-----------------------------------|
| (implicit) | numeric | yes | no | Current value of signal parameter |



Comments The DialGauge object class only displays a needle. You may wish to enhance it with a corresponding scale or dial face as shown. You can create a scale or dial face by importing one from a graphics package. See *Creating Custom Graphics* in Chapter 2, *Graphics*, in the *Lookout Developer’s Manual* for more information.



Note If you choose to import a scale or dial face from an external package, you should use a bitmap instead of a metafile. This makes the display refresh cleaner when the needle changes position.

Related Objects (*expression*), *Gauge*

ElapsedTime

ElapsedTime is an elapsed time meter or “hour meter” that totals the amount of time the **Enable** expression is on. If **Enable** is the logical constant ON, the meter reflects the time since the process was started. If a **Reset** expression is specified, the meter resets to zero the moment **Reset** transitions from off to on. The display always shows the elapsed time, and is updated approximately once per second.

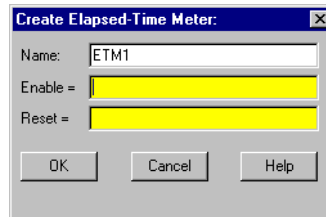


Figure 2-30. ElapsedTime Definition Parameters Dialog Box

ElapsedTime Data Members

Table 2-17. ElapsedTime Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|--|
| (implicit) | numeric | yes | no | Total elapsed time—updated once per second, while meter is running |

Comments ElapsedTime meters are used primarily to record the amount of time that individual pieces of equipment have been running. It is also straightforward to set up an alarm that sounds when a particular device has been operating for a certain time and needs routine servicing. The plant operator could then perform the service and reset the ElapsedTime meter with a pushbutton.

ElapsedTime can also record the amount of time a particular device is operated each day and you can record the resulting time to a daily Spreadsheet which you can then use to automatically reset the meter after the data is permanently recorded.

Event

Event is a flexible and powerful object class you can use to define event messages that are triggered based on a user-defined logical expression. Lookout logs such events to the Citadel database and you can subsequently print and archive them. See Chapter 7, *Logging Data and Events*, in the *Lookout Developer's Manual* for more information on logging events.

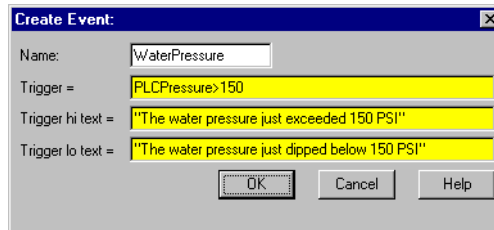


Figure 2-31. Typical Settings for an Event

When the result of the **Trigger** logical expression transitions from FALSE to TRUE, it logs the result of the **Trigger hi text** expression as an event in the EVENT.DAT file. When the results of the **Trigger** expression transitions from TRUE to FALSE, it logs the results of the **Trigger lo text** expression as an event.

Event Data Members

Table 2-18. Event Data Members

| Data Member | Type | Read | Write | Description |
|-------------|------|------|-------|--|
| none | — | — | — | Event objects do not have data members |

Comments For each event logged, Lookout records the date and time, the name of the user currently logged on, and the expression text.

Although event messages are shown for both **Trigger hi text** and **Trigger lo text**, you do not have to include text in both fields.

(expression)

Named expressions, shown as (expression)s, are flexible, powerful real-time calculators. They create and calculate the result of spreadsheet-style formulas that include a mixture of constants and signals from other objects. There are over fifty built-in functions that you use in expressions, including logical, mathematical, statistical, text and trigonometric functions. See Chapter 2, *Expressions*, in the *Lookout Developer's Manual* for more information on expressions and expression functions.

Named expressions can be short and simple, or extremely complex with several signal inputs, function calls, and multiple levels of parentheses. A single expression may incorporate text, logical, and numeric calculations. The variable type returned by the outermost function or operator in the expression determines the signal type generated by the expression.

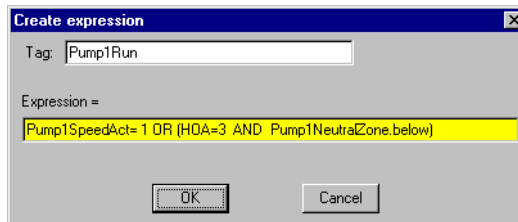


Figure 2-32. Create Expression Dialog Box



Note You typically use (expression) objects when you need to define a unique condition that is used multiple times throughout your application.

When you define an (expression) object (as opposed to inserting an intrinsic expression), you create a unique name for your expression and can therefore reference the output signal generated from the expression in other expressions or objects. Instead of defining the same expression in many places, you create it one time and use its name any time you need this expression.



Note The expression may not express a **condition**.

Table 2-19. Expression Data Members

| Data Member | Type | Read | Write | Description |
|--------------------|---------------------------------|-------------|--------------|---|
| (implicit) | numeric, logical, or text | yes | no | Value of expression. The variable type returned by the outermost function or operator in the expression determines the signal type generated by the expression. |

Flipflop

Flipflop changes its logical output signal from on to off, or from off to on when the **Input** signal goes high. The output signal does not change when the signal goes low. **Input** is a logical expression.

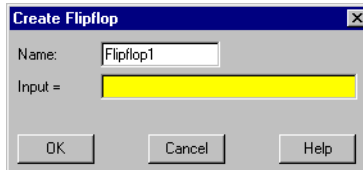


Figure 2-33. Flipflop Definition Parameters Dialog Box

Flipflop Data Member

Table 2-20. Flipflop Data Member

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|---------------|
| (implicit) | logical | yes | no | Current state |

Comments Flipflop can be used to alternate the operation of two pumps, or when connected to a pushbutton, provides a pushbutton on/off control device.

Related Objects [LatchGate](#)

Gauge

Gauge displays the **Signal** expression in digital or bar graph format. Gauge display parameters change depending on the values of the **Conditional expressions**. Gauge determines which colors to display based on the order and current status of your conditional expressions. For instance, if several conditional expressions are true at once, Gauge displays the color associated with the first true expression.

You can use the **Transparent** background style with numeric expressions and gauges displayed as bar graphs. This means you can have bar graphs with transparent backgrounds.

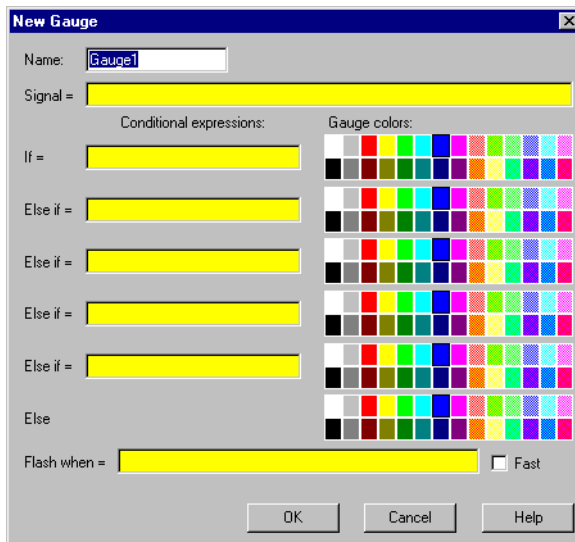


Figure 2-34. Gauge Definition Parameters Dialog Box

Conditional expressions and **Flash when** are logical expressions while **Signal** is a numeric expression. The **Fast** option instructs the Gauge to flash faster when enabled than when disabled.

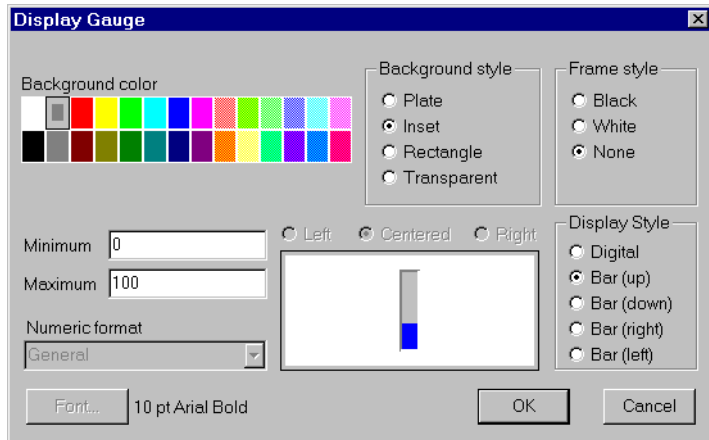


Figure 2-35. Gauge Display Parameters Dialog Box

Gauge Data Members

Table 2-21. Gauge Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|------------------------|
| (implicit) | numeric | yes | no | Numeric value of Gauge |

Comments You should use a Gauge object when you need a bar graph or digital display to change colors and/or flash upon certain conditions. If you do not need either of these capabilities, you should display a bar graph or digital value with the **Insert»Expression...** command.

Histogram

The Histogram object class is one of the Lookout Statistical Process Control (SPC) tools and can play an important role in a Total Quality Management (TQM) program. This object class displays the distribution and/or relative distribution of a signal value. It shows the central tendency and variability of the sampled data. It also calculates process capability ratio (PCR), PCR confidence interval, mean, variance and standard deviation.

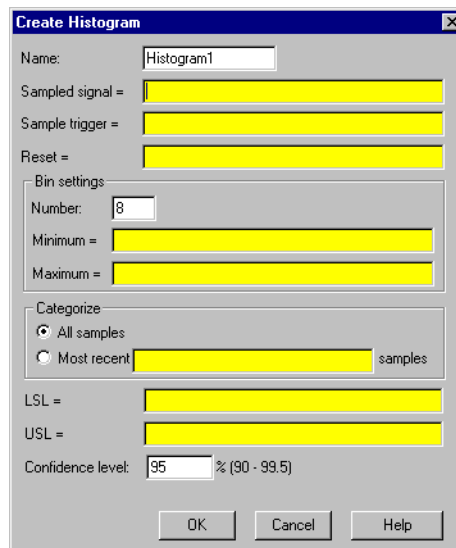


Figure 2-36. Histogram Definition Parameters Dialog Box

Sampled signal identifies the value that you are statistically monitoring. Histogram reads and categorizes the **Sampled signal** any time **Sample trigger** transitions from off to on.

You can either **Categorize** all samples since **Reset** last transitioned from off to on, or you can **Categorize** a sliding window of the most recent 2 – 1000 samples.

Bin Settings define the **Number** of desired categories. The difference between **Minimum** and **Maximum** determines the width of each bin or category.

The settings for the following Histogram graph call for eight bins. Because the difference between **Minimum** and **Maximum** is 80 and because there

are eight bins, each class interval has a range of 10 ($80/8 \text{ bins} = 10$). So bin_1 contains sample values ranging from zero to less than 10; bin_2 contains sample values ranging from 10 to less than 20, and so on.

This object always allocates two more bins than you request. These bins are used for accumulating samples less than the **Minimum** and greater than the **Maximum**. The lower bin is always data member f_0 . The upper bin is f_{n+1} , where $n = \text{Number in Bin Settings}$.

In the following example, Bin_0 (data member f_0) contains all sample values less than **Minimum** and bin_9 contains all sample values greater than or equal to **Maximum**.

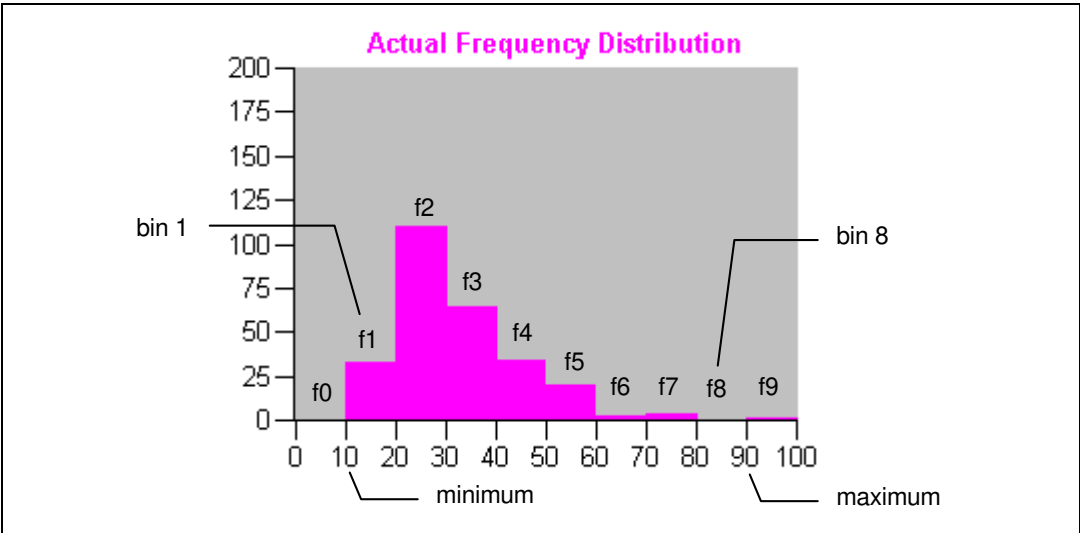


Figure 2-37. Graph from Inserting Ten Numeric Expression Barcharts (Data Members f_0 through f_9 as Shown) and Two Scales

LSL and **USL** identify the lower and upper specification limits. These limits generally define the range of acceptable sample values. Histogram uses **LSL** and **USL** to calculate the process capability ratios (**PCR** and **PCRk**).

The **Confidence level** expresses the degree of certainty or probability that the actual value of **PCR** (the process capability ratio) falls within the confidence interval (that is, between **PCRL** and **PCRU**). A typical value is 95 percent. The lower the confidence level, the tighter the interval.



Note Histogram does not have a display parameters dialog box. However, you can easily display the results of its output signals by referencing them in expressions.

Histogram Data Members

Table 2-22. Histogram Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|--|
| f0 – f201 | numeric | yes | no | Frequency of sampled signal values falling within the identified bin |
| LSL | numeric | yes | no | Lower specification limit |
| mean | numeric | yes | no | Average of sampled values, where $\bar{x} = \frac{\sum_{i=1}^n x_i}{n}$ |
| PCR | numeric | yes | no | Process capability ratio measuring the uniformity or variability of the sampled signal using upper and lower specification limits. This ratio measures <i>potential</i> capability. If standard deviation = 0, PCR = 0. Otherwise $PCR = \frac{USL - LSL}{6\sigma}$ |
| PCRk | numeric | yes | no | One-sided process capability ratio for an off-center process. This ratio takes process centering into account, measuring <i>actual</i> capability. $PCR_k = \min\left(\frac{\bar{x} - LSL}{3\sigma}, \frac{USL - \bar{x}}{3\sigma}\right)$ |
| PCRL | numeric | yes | no | Lower limit of the confidence interval |
| PCRU | numeric | yes | no | Upper limit of the confidence interval |
| rf0 – rf201 | numeric | yes | no | Relative frequency (percent) of sampled signal values falling within the identified bin |

Table 2-22. Histogram Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|--|
| samples | numeric | yes | no | Number of sampled signal values |
| sdev | numeric | yes | no | Sample standard deviation, where $\sigma = \sqrt{\frac{\sum_{i=1}^n (x_i - \bar{x})^2}{n-1}}$ |
| USL | numeric | yes | no | Upper specification limit |
| variance | numeric | yes | no | Sample variance, where $\sigma^2 = \frac{\sum_{i=1}^n (x_i - \bar{x})^2}{n-1}$ |

Comments The confidence interval is the range of values determined by the limits PCRL and PCRU.

Related Objects *Average, Maximum, Minimum, Sample, XBarR*

Related Functions Avg, Max, Min, Stdev, Stdevp, Sum, Var, Varp
 See Chapter 1, *Expressions*, of the *Lookout Developer's Manual* for more information on these functions.

HyperTrend

A HyperTrend object displays a trend graph on a control panel. It plots any number of logical and numeric trend lines.

HyperTrends provide instant access to both real-time and historical data in a single graph. For each plot line, they combine both real-time and historical data into a seamless, contiguous trace of data. See *Citadel Historical Database* in Chapter 7, *Logging Data and Events*, in the *Lookout Developer's Manual*.



Note There has been an important change in the way Lookout logs data to the Citadel database to be displayed on the HyperTrend object.

In Lookout 3.xx, creating a trend line in a HyperTrend object automatically logged the requested data to the database.

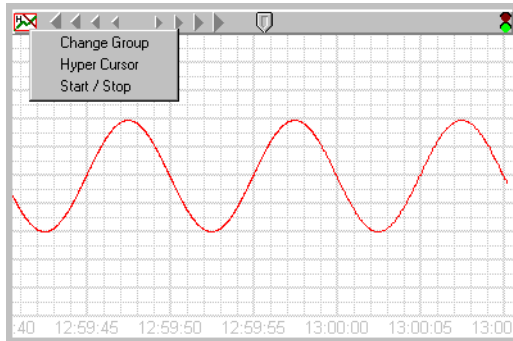
In Lookout 4, you must select the Log to historical database option in the Edit Database dialog box for any data you want to display in a HyperTrend object before you can display the data. This is because logging must be configured in a Lookout Server process, while trending is typically done in a separate Lookout client process.

You can log information by connecting to a symbolic link, but only if the data source the symbolic link represents has had the Log to historical database option selected.

You can use HyperTrends to pan and zoom both the X axis and the Y axis, enabling dynamic adjustment of the vertical and horizontal resolutions of each plot line on the graph. Using this feature, you can, for example, zoom into a particular area of focus on the trend.

The graph scrolls from right to left, plotting current, real-time signals at the right end of the graph.

The icon in the upper left of the display accesses a menu you can use to change the group of traces being plotted, activate the cursor, and start or stop scrolling. The arrow-shaped buttons make it easy for you to scroll the trend graph forward and back in time. It provides instant access to data that has scrolled off the left end of the graph (that is, historical data stored in the Citadel database).



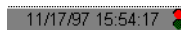
The button bar includes scroll arrows, a cursor button, date, time, and a stop and go light. Use the scroll arrows to move back and forth through time—the bigger the arrow button you select, the further the trend jumps in time. The scroll arrows also function much like a horizontal slider. Click on them and slide the mouse left and right while holding down the mouse button. The further you slide the cursor from dead center, the faster the trend scrolls in that direction.

Use the date and time indicators to choose a specific month, day, year, hour, minute, or second. If you click on the lower part of the hour, for example, it jumps back in time by one hour.

If you click on the upper part of the hour, it jumps ahead by one hour.



It works the same way for month, day, year, minute and second.



The stop & go light on the button bar is either red or green. If the light is green, it indicates the far right edge of the trend window displays the current time.

When you scroll back in time or if you click on the light when it is green, it changes to red, indicating that the trend is temporarily frozen in time. The date and time appears in the button bar indicating the exact time at the far right edge of the trend window. As you scroll back and forth through time, the data and time changes accordingly.

If you click on the light when it is red, the trend jumps back to current time and starts scrolling while plotting real-time values.



Note The Citadel database continues to log data no matter what state the HyperTrend is in. You do not lose any data when it is in "historical" mode (that is, when the HyperTrend is not scrolling in real-time).

When you click on the cursor button, a vertical cursor bar appears in the center of the graph along with an associated cursor dialog box. The dialog box indicates the value of each trend line at the current location of the cursor. As you drag the cursor bar left and right on the trend graph, the values in the pop-up change to reflect the new cursor location.

You can select how the trend line values are shown by choosing a format through the cursor control menu.

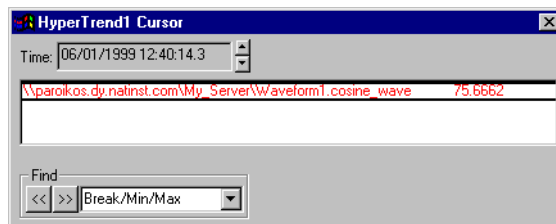
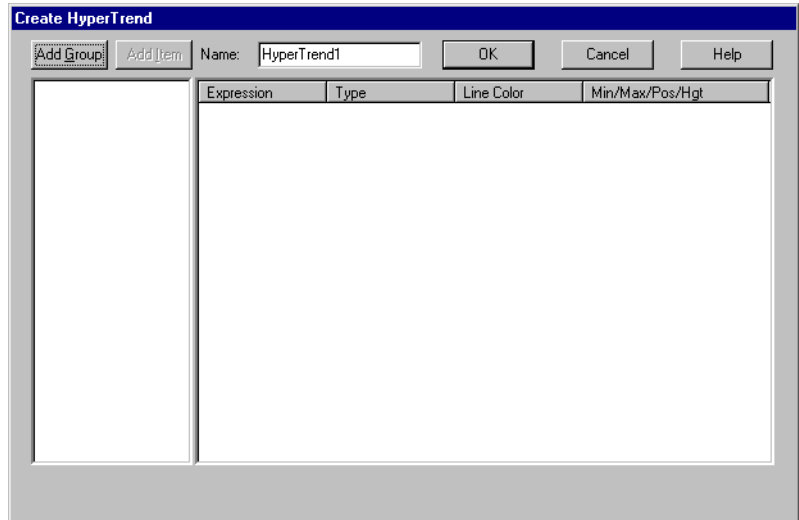


Figure 2-38. HyperTrend Cursor Dialog Box

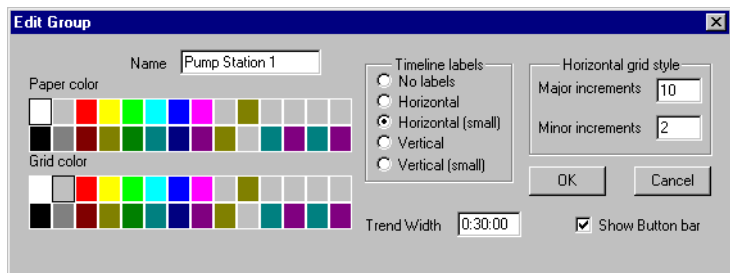
Time indicates the current location of the cursor bar. The increment and decrement buttons beside the field move the cursor left and right in the trend graph. Choose the size of the incremental move by clicking on the desired portion of the date/time. The hour portion is selected in the previous example, so each time you click on the increment or decrement button, the cursor bar jumps ahead or back by an hour. It works the same way for any portion of the date and time.

Use the **Find** combo box to search for a break in the trend line, a signal peak or valley, or a specific value. For example, you can find the last instance in which a process control limit value was exceeded. To find the last time a trend line crossed a specific value, choose the desired trend line by clicking on it in the list box, select **Value** in the **Find** combo box, enter the desired value, and click on the scroll back button.

To create a hypertrend object, choose **Object»Create** or right-click on a process in the object explorer and select **New Object**. Select **HyperTrend**. The following dialog box appears.



First you must create a group of trends. Double-click on the **AddGroup** button. The following dialog box appears.



Configuring the group sets the appearance of the HyperTrend object when it displays traces from that group. You can set different paper and grid colors for different groups to help operators distinguish between them.

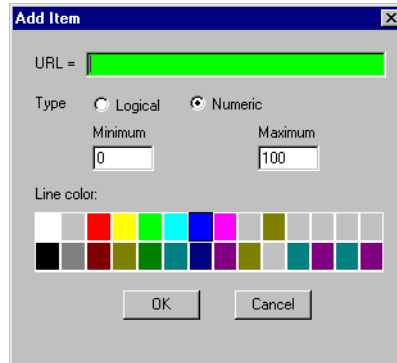
Give your group a name that clearly identifies it. Be sure to set the **Trend Width** for the period of time you want under observation for that group. Graphs may have a default width, or time span, of anywhere from two seconds to four years. The default **Trend Width** in the example dialog box indicates a time span of 1:00:00 or one hour. See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout*

manual for more information on entering time constants. After creating the HyperTrend object, you can make the trend width adjustable by connecting a numeric signal to the TrendWidth data member.

Major increments specifies the number of heavy horizontal grid lines on a trend graph. This value is independent of the range of any trend expressions.

Minor increments specifies the number of light horizontal grid lines between the major increment grid lines on a trend graph. This value is independent of the range of any trend expressions.

After you create a group, you must add individual items. Right-click on the group you want to add a trace to. Select **Add Item** (or click on the **Add Item** button). The following dialog box appears.

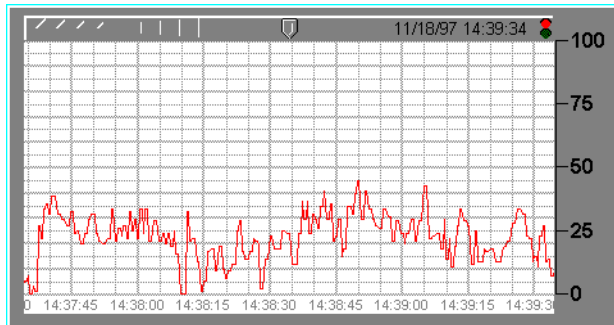


Right-clicking in the URL field displays the object selection dialog box covering all the registered computers running Lookout on your network. Select the computer and process generating the value you want to display on your HyperTrend chart. See the URLs section for more information on this type of Lookout connection.

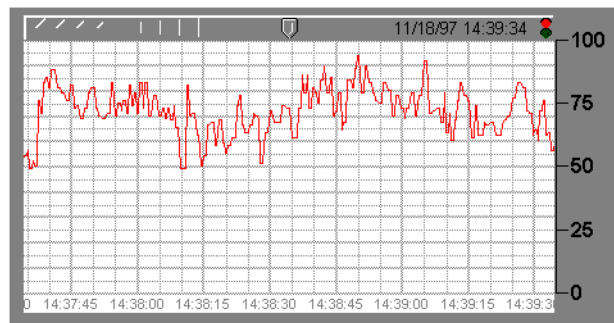
Minimum and **Maximum** set the scale for the trace on your display. If you are charting a logical data member, position and height set the base display line and the height of the trace from that point when your signal goes TRUE. **Minimum** is the bottom of the graph while **Maximum** is the top of the graph, regardless of the range of the expression. These settings create an imaginary vertical scale and affect each expression independently.

For example, take two numeric expressions, both of which range from 0 to 50. Set the **Minimum** and **Maximum** to 0 and 100 on the first expression, and -50 and 50 on the second. The first expression plots in the bottom half

of the chart while the second expression plots in the top half of the chart, even though they both fluctuate between 0 and 50.

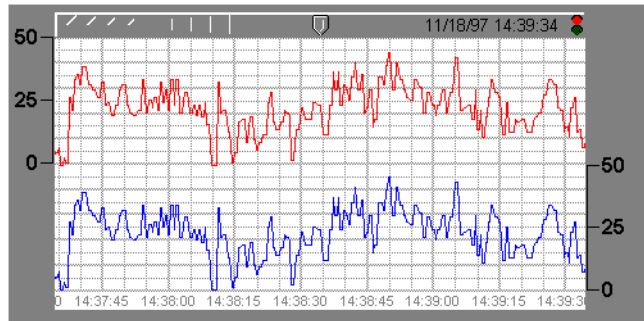


This figure shows the imaginary scale of the first expression (where min. = 0 and max. = 100). Because the expression ranges from 0 to 50, it is plotted in the bottom half of the graph.

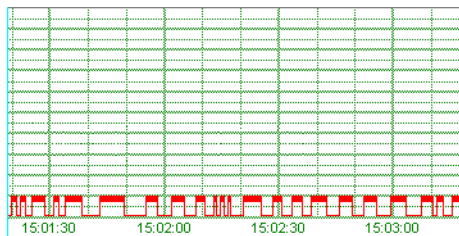


This figure shows the imaginary scale of the second expression (where min. = -50 and max. = 50). Because the expression ranges from 0 to 50, it is plotted in the top half of the graph.

When both expressions are entered on a single trend graph, you get the following effect. Notice the custom scales at either end of the graph.



If you select Logical for the expression type, the minimum and maximum settings changes to **Position** and **Height**. These two values now represent a number between 0% and 100%, and determine the baseline location of the trend line and its unit height when the expression goes TRUE.



Use **Insert>Scale** to label the values being charted according to your minimum and maximum settings.

Comments HyperTrend objects access data from the Citadel database. Think of them as windows into your historical database. See Chapter 5, *Developer Tour* in the *Getting Started with Lookout* manual, and Chapter 7, *Logging Data and Events*, in the *Lookout Developer's Manual*, for more information on specifying a point to be logged to the Citadel database.

HyperTrends are updated as quickly as once per second, depending on screen resolution, the size of the graph, and the trend width setting. Computers with slow display adapters may slow down considerably when you display a large trend graph. On slower computers with slow display cards (no graphics coprocessor), consider limiting the size of your HyperTrends to less than one fourth the screen size.

HyperTrend Data Members

Table 2-23. HyperTrend Data Members

| Data Members | Type | Read | Write | Description |
|---------------------|---------|------|-------|--|
| ActiveGroup | numeric | yes | yes | Sets which of the HyperTrend trace groups is active. |
| Enable1– Enable 999 | logical | yes | yes | When TRUE, the identified trend line is visible. When FALSE, the trend line hidden. The default value is TRUE. Trend lines are identified by the group number followed by the item number, so Enable1.2 would refer to item 2 in group 1. |
| Height1 – Height999 | numeric | yes | yes | Specifies the amplitude or height of the identified trend line (distance from baseline) when the logical expression goes TRUE. Height should be between 2 and (100 minus position). Trend lines are identified by the group number followed by the item number, so Height1.2 would refer to item 2 in group 1. |
| Max1 – Max999 | numeric | yes | yes | Specifies the top of the graph for the identified numeric trend line (the value of the trended line when it is at 100 percent of the Y axis). Trend lines are identified by the group number followed by the item number, so Max1.2 would refer to item 2 in group 1. |
| Min1 – Min999 | numeric | yes | yes | Specifies the bottom of the graph for the identified numeric trend line (the value of the trended line when it is at zero percent of the Y axis). Trend lines are identified by the group number followed by the item number, so Min1.2 would refer to item 2 in group 1. |

Table 2-23. HyperTrend Data Members (Continued)

| Data Members | Type | Read | Write | Description |
|---------------------|-------------|-------------|--------------|---|
| Pos1 – Pos999 | numeric | yes | yes | Specifies the baseline location of the identified logical trend line. Baseline position should range should be 1–98. (pos1 is associated with trend line 1) Trend lines are identified by the group number followed by the item number, so Pos1.2 would refer to item 2 in group 1. |
| TrendWidth | numeric | yes | yes | Specifies the span of time that the X axis covers. |
| UseButtonBar | logical | yes | yes | When TRUE, the HyperTrend button bar becomes visible on the control panel. When FALSE, it is invisible. The default value is TRUE. |
| Visible | logical | yes | yes | When TRUE, the HyperTrend becomes visible on the control panel. When FALSE, it is invisible. The default value is TRUE. |

Converting Lookout 3.xx HyperTrends to Lookout 4

If you convert a process created in a version of Lookout earlier than 4.0 which contains a HyperTrend object that is displaying a complex expression, Lookout automatically creates a named (expression) for the converted HyperTrend to chart. To maintain your legacy HyperTrend objects you must use or replace these (expression) objects.

Integral

Integral is a totalizer—it totals the numeric **Input** signal. This class is typically used to total a measured flow rate.

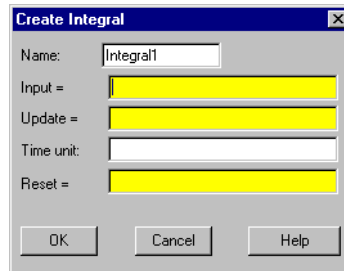


Figure 2-39. Integral Definition Parameters Dialog Box

Input is the numeric expression that you want to totalize or integrate.

Update can be a logical expression or numeric constant. If you specify **Update** as a numeric constant, it creates an internal Pulse timer with a pulse period of the specified time and a pulse duration of zero. See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants. If you specify **Update** as a logical variable, the variable should pulse at the desired frequency.

The **Update** expression extrapolates an interim total based on the current total and the most recent **Input** value. The interim total is then sent out as the output. The total is calculated using the trapezoidal numeric integration technique, and the total is corrected any time the incoming signal is refreshed.

Time unit is a numeric expression used as the basis for unit time on the **Input** signal. For instance, if the **Input** rate is in units of gallons per minute, the **Time unit** should be entered as one minute (1:00) so the totalized flow is in gallons. Typically the **Time unit** is one second (0:01), one minute (1:00), one hour (1:00:00), or one day (1:00:00:00). However, you can specify any unit, such as 5:23 (a rate of change in **Input** units per five minutes and 23 seconds).

Reset is a logical expression that resets the totalizer value to zero upon transition from OFF to ON.



Note Integral does not have a display parameters dialog box. You can easily display the result of the Integral output signal by referencing its data member in an expression.

Integral Data Members

Table 2-24. Integral Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|-----------------|
| (implicit) | numeric | yes | no | Totalized value |

Comments The **Update** pulse forces the calculated total to continue changing between Input signal updates. For example, if a remote RTU that is monitoring a flow rate is polled every ten minutes, the **Update** pulse could be set at five seconds so the operator can watch the totalized flow continue to change on the screen as an extrapolated value. The corrected totalized value is calculated any time the **Input** signal refreshes—in this case, every ten minutes.

If totalized values are logged to a spreadsheet on a daily basis, for example, and the total should be reset at the end of every day, use the update pulse generated by the Spreadsheet object to reset the total—this guarantees that the total is recorded before the totalizer is reset. The example on the previous page totalizes the hourly flow for permanent data logging by a spreadsheet object named HourlySheet. Notice that the spreadsheet update pulse `HourlySheet.logged` is used to reset the totalizer.

Related Objects [Accumulator](#), [Counter](#), [Derivative](#)

Interpolate

The Interpolate object class performs a linear interpolation between a set of X,Y coordinate pairs to determine a corresponding output for any given input. A single Interpolate object can have up to 1,000 coordinate pairs. Although this object class can be used for any calculation requiring linear interpolation, it is especially useful for tank strapping applications.

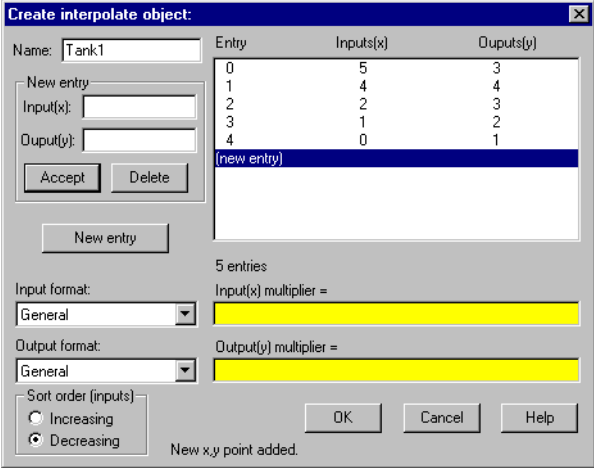
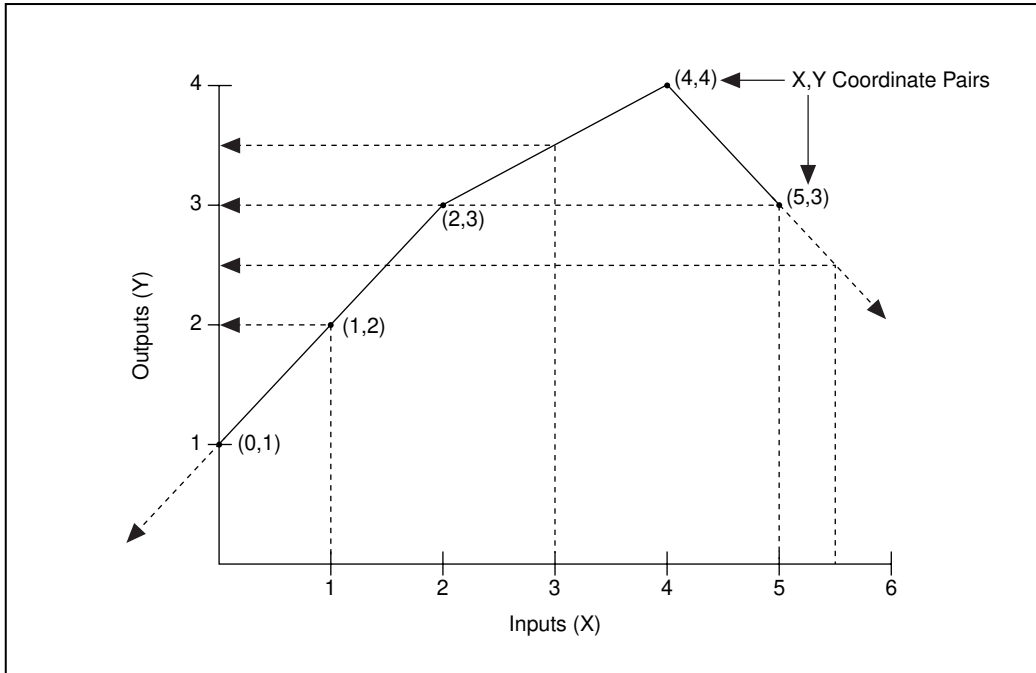


Figure 2-40. Interpolate Definition Parameters Dialog Box

The following diagram visually depicts the basic functionality of the Interpolate object, and the set of coordinate pairs as entered.

Based on this graphical representation of the object, you can readily see how different X inputs give corresponding Y outputs. Also notice that an X input of 5.5 yields a Y output of 2.5—even though the last coordinate pair was (5,3). Lookout uses straight line extrapolation at both end points with a slope determined by the last two coordinate pairs.



The **New entry** parameter fields enable adding, modifying and deleting **Input(x)** and **Output(y)** coordinate pairs. **Input(x)** and **Output(y)** are numeric parameters.

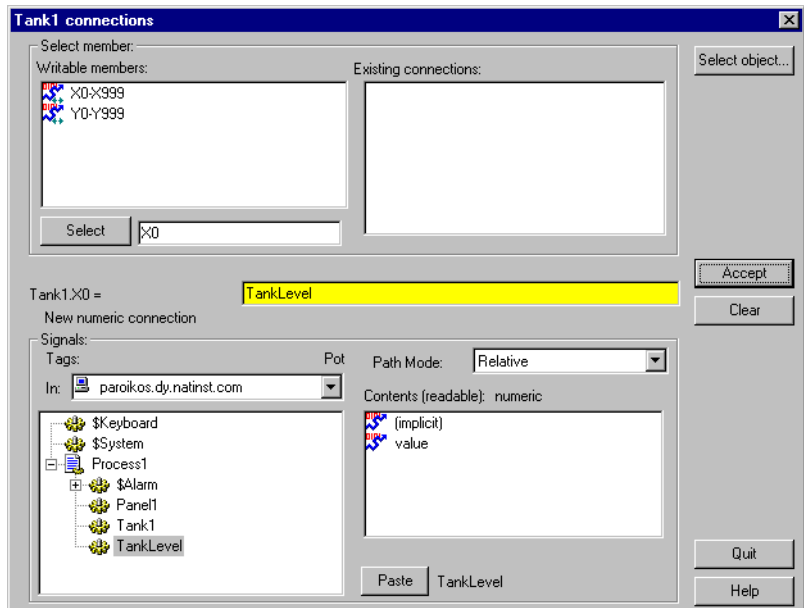
Input format and **Output format** define the numeric format of the **Input(x)** and **Output(y)** coordinate pairs displayed in the definition dialog box.

Sort order (inputs) specifies whether the dialog box lists X,Y coordinate pairs in **Increasing** or **Decreasing** order. The sort order has no bearing on output calculations or the values of the readable data members.

The **Input(x) multiplier** and the **Output(y) multiplier** are numeric expressions. These two parameters are useful for the more advanced calculations often found in tank strapping applications. They can be used for such things as temperature, pressure, density, and product correction factors. As their names imply, Lookout multiplies the corresponding Input/Output by the respective multiplier. If you specify an **Input(x) multiplier**, the object multiplies the input by the appropriate multiplier *before* calculating an interpolated output. If you specify an **Output(y) multiplier**, the object multiplies an interim output by the appropriate multiplier *before* calculating the final output value.

Step through a simple example using the preceding diagram to clarify this concept. Use an **Input(x) multiplier** of 1.5, and a **Output(y) multiplier** of 2. Assume the variable input is currently 2. The object first multiplies 2 by 1.5 to produce 3. It then uses the coordinate pairs to find the appropriate output value for an input of 3. As you can see, the interim output would be 3.5. Because you specified an output multiplier, it must first multiply 3.5 by 2 to give a final output of 7.

Situations may arise where you want multiple inputs going through a single Interpolate object, giving multiple respective outputs. Instead of creating an Interpolate object for each input, Lookout can connect multiple inputs to a single object and read their corresponding outputs. The inputs are writable data members (X0 – X999). For each input, there is a corresponding readable output (Y0 – Y999 respectively). The following diagram shows a numeric signal called TankLevel connected to an input, X0.



The Interpolate object now multiplies the X0 input by the **Input(x) multiplier**, find the two coordinate pair parameters that X0 falls between, interpolate, and multiply the interim output by the **Output(y) multiplier**, then send the resulting value to the Y0 readable data member.



Note The Interpolate object class does not have a display parameters dialog box. However, you can easily display the result of its output signals by referencing its data members in expressions.

Interpolate Data Members

Table 2-25. Interpolate Data Members

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|---|
| X0 – X999 | numeric | yes | yes | Input value |
| Y0 – Y999 | numeric | yes | yes | Output value. For a given input, X_n , the object outputs the result of the interpolation as a corresponding Y_n value. |

Comments If you want to interpolate another input using the same coordinate pair parameters and multipliers (that is, the same Interpolate object), connect to another input like X23, and read its corresponding output, Y23.

Because X_n and Y_n data members are both readable and writable, the object can also act as a bi-directional interpolator. For example, you can connect a numeric signal to a Y_n data member, and read the corresponding interpolated X_n data member. A real-world example of this could be a typical tank strapping problem. Normally, you would use a tank level as an input to X0, and read the interpolated output Y0 as the corresponding tank volume. Hence you begin with a level and end up with a volume. However, you might also be monitoring the volume and would like to use that value to calculate a corresponding level. In that case, you might want the Interpolate object to be bi-directional, which it is. If Y0 ever changes, the object *divides* Y0 by the **Output(y) multiplier**, interpolate between the two closest **Output(y)** parameters, calculate a corresponding input value based on the two closest **Input(x)** parameters, divide it by the **Input(x) multiplier**, and send the resulting value to the X0 data member.

Interval

Interval is an adjustable delay timer. When **On/off signal** transitions to on, its output turns on and the **Timer delay** begins to count down. At the end of the delay countdown, the output signal turns OFF. If **On/off signal** is dropped at any time, the output signal turns OFF, and the timer is reset.

Timer delay can range from 0.0 seconds to several years, and the effective resolution is 0.1 seconds over the entire range. The timer display digitally shows the time delay remaining. It is updated approximately once per second. If the **On/off signal** is low, or the time delay period has expired, the timer display shows OFF.

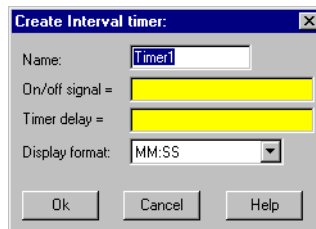


Figure 2-41. Interval Definition Parameters Dialog Box

The **On/off signal** is a logical expression while **Timer delay** is a numeric expression. Normally, this is a simple time constant such as 0:20 (twenty seconds). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

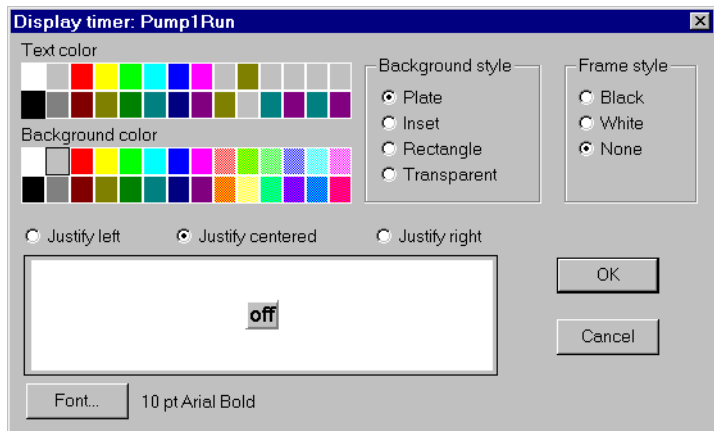


Figure 2-42. Interval Display Parameters Dialog Box

Interval Data Members

Table 2-26. Interval Data Members

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---------------------|
| (implicit) | logical | yes | no | Logical timer value |

Comments The Interval timer can be used to enforce a maximum run time for a pump.

Related Objects [DelayOff](#), [DelayOn](#), [OneShot](#), [Pot](#), [TextEntry](#)

Junction

Junction receives up to nine numeric values, each of which could be the result of a complex numeric expression. It outputs the value of the last **Additional input** that changed (event driven). Notice, however, that it will not output a value until the **Initializing input** has changed. After that, any change in any input is immediately output.

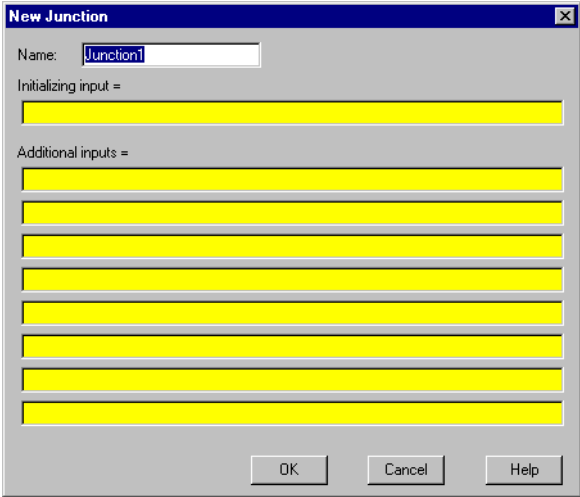


Figure 2-43. Junction Definition Parameters Dialog Box

Junction Data Members

Table 2-27. Junction Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|---|
| (implicit) | numeric | yes | no | The value of the input that most recently changed |

Comments Junction is a unique class that should be used only in rare circumstances.

\$Keyboard

\$Keyboard is a global object. Its data members represent the keyboard function keys. Unlike other object classes in which you can create several objects of the same class, you cannot create or delete \$Keyboard objects, but you can use the one supplied.

You can use the \$Keyboard global object to perform such functions as calling a particular control panel, activating a batch sequence, or acknowledging alarms by pressing a key.

Think of \$Keyboard data members (which represent function keys on the keyboard) as Lookout pushbuttons. Just as you can connect a pushbutton to the activate data member of a panel, you can also connect a \$Keyboard data member to the activate data member of a panel. Such a connection is shown in the following illustration.

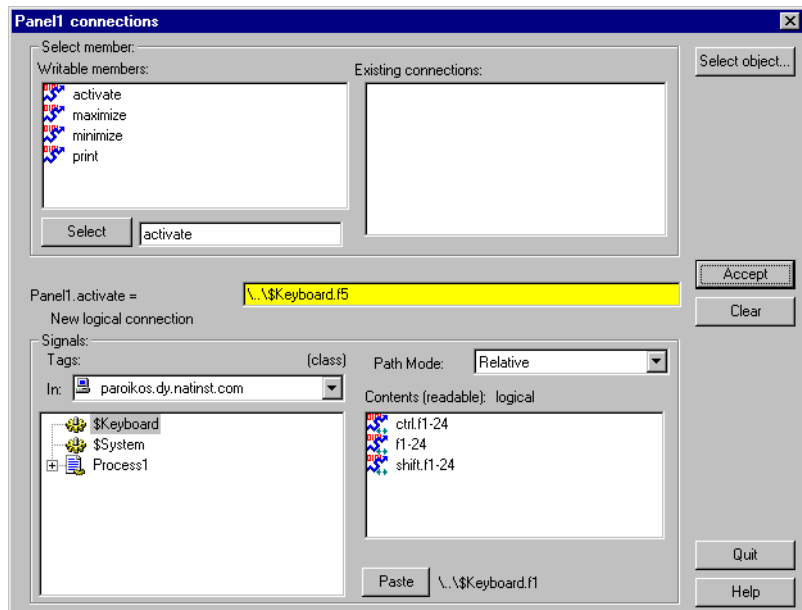


Figure 2-44. Edit Connections Dialog Box

The logical expression, `$Keyboard.F1` calls up Panel1 any time a user presses the F1 key on the keyboard. Similar connections could be made to other panels. You can easily connect a different panel to each function key.

Just as easily, you can connect a function key to a batch process trigger. When the key is pressed, (that is, when the `$Keyboard` data member goes TRUE) the batch is activated—reading batch ingredients from a recipe object, opening and closing valves, starting mixers, bottling finished material, and so on.

You might also connect a function key to `$Alarm.ack`. This would enable users to acknowledge alarms through a single keystroke.

\$Keyboard Data Members

`$Keyboard` has 72 readable data members. Each data member represents a unique key sequence, described in the following table.

Table 2-28. \$Keyboard Data Members

| Data Member | Type | Read | Write | Description |
|----------------------|---------|------|-------|--|
| Ctrl-F1 - Ctrl-F24 | logical | yes | no | Each of these 24 data members represent a function key, F1 – F24—when pressed in conjunction with the Ctrl key. A given data member returns logical TRUE when the Ctrl key and function key are pressed together and FALSE when the keys are released. |
| F1 - F24 | logical | yes | no | Each of these 24 data members represent a function key, F1 – F24. A given data member returns a logical TRUE when its associated function key is pressed and FALSE when the key is released. |
| Shift-F1 - Shift-F24 | logical | yes | no | Each of these 24 data members represent a function key, F1 – F24—when pressed in conjunction with the Shift key. A given data member returns logical TRUE when the Shift key and function key are pressed together and FALSE when the keys are released. |

Comments \$Keyboard function keys are global in nature. Any time F1 is pressed, the `$keyboard.F1` signal goes TRUE—regardless of what panel the user is looking at. If you want a function key to be unique from one control panel to the next, use the Panel object class function key data member. See [Panel](#) object class definition for more information.

Related Objects [L3Pushbutton](#), [Pushbutton](#)

L3Pot

L3Pot is a potentiometer that you use to change numeric setpoint values. You can display pots on a control panel as a knob, vertical slider, horizontal slider, increment/decrement pushbuttons, or digital entry. You can also use pots as multiple-position switches.

If you change the background color of a panel and add a Pot object displayed as a slider, its color is always gray. To change the background color of a Pot to match your panel, select the Pot object, then pick **Change»Background Color** from the menu.

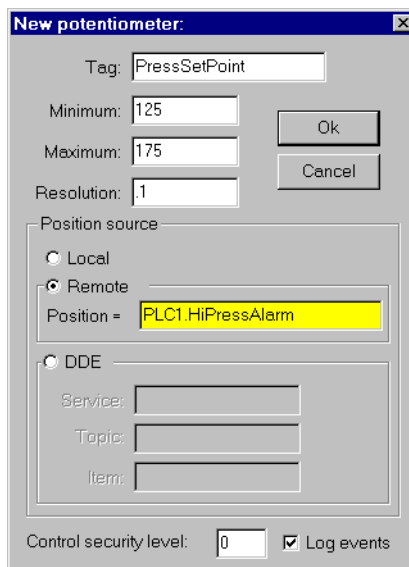


Figure 2-45. L3Pot Definitions Parameters Dialog Box

Minimum is the lowest value signal the Pot will generate.

Maximum is the highest value signal the Pot will generate.

Resolution is the smallest increment of change, or detent spacing the Pot supports.

Position source determines where the value of the Pot resides. **Local** indicates the value of the Pot lies within the object itself—on the control panel.

Remote pots get their values from a remote source, often the register on a controller they are connected to. Adjusting the Pot changes the value in the register, and changing the value in the register adjusts the Pot. In effect, the Pot is tracking a remote value. This is especially useful when you want to prevent Lookout from changing the value of setpoints or registers upon initial startup, or reconnection of lost communication. When you use this style Pot you are creating a kind of looped signal. Half the loop is formed when you connect the controller register to the Pot with the **Position** expression, while the second half is formed when you connect the Pot output signal to the controller register. **Position** is a numeric expression. Do not forget to complete the second half of the loop with the **Object»Edit Connections...** command.

Much like Remote Pots, **DDE** (Dynamic Data Exchange) Pots get their values from a remote source. This could be a cell in a spreadsheet, another DDE aware application, or a second copy of Lookout running on the network. The last DDE parameters used on any object automatically become the default values for any new DDE object. See Chapter 5, *Dynamic Data Exchange*, of the *Lookout Developer's Manual* for more information on Service, Topic, and Item parameters.

Control security level specifies the minimum security level operators must have to gain access to this individual object, and thus control it.

The **Log events** option creates a permanent audit trail for the object—who did what and when. All adjustments of the Pot are logged to disk, including the time of the adjustment, the operator account name, and what adjustment was made. See Chapter 7, *Logging Data and Events*, in the *Lookout Developer's Manual* for more information on event logging.

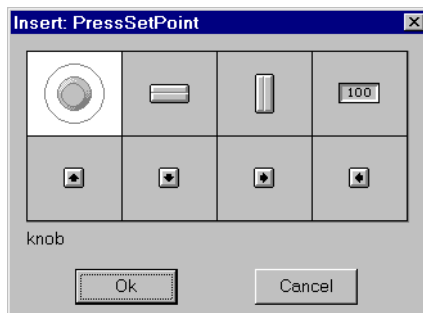


Figure 2-46. L3Pot Display Parameters Dialog Box



Note You can modify the background color on vertical and horizontal sliders with the **Change»Background color...** menu command. You can modify the font and font color of digital pots using **C**hange commands.

L3Pot Data Members

Table 2-29. L3Pot Data Members

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---|
| (implicit) | numeric | yes | no | Current value |
| decrement | logical | no | yes | When this data member value transitions from FALSE to TRUE, the implicit value of the Pot object decreases by the Pot Resolution amount. |
| enable | logical | no | yes | If TRUE (the default), enables DDE. If FALSE, disables DDE. The default value is on. This input is ignored for non-DDE TextEntry objects. |
| enterValue | logical | no | yes | <p>Under specific circumstances, when this value transitions from FALSE to TRUE, pops up a Enter new value dialog box for an operator to use in entering a value for the pot. See the note following the table for more detailed information.</p> <p>The enterValue data member is designed for use under unusual circumstances, in particular when pointing devices are not available on a computer running Lookout. Because of its unusual operation, this data member should not be used unless it is necessary for hardware reasons.</p> |

Table 2-29. L3Pot Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---|
| increment | logical | no | yes | When this data member value transitions from FALSE to TRUE, the implicit value of the Pot object increases by the Resolution amount. |
| visible | logical | no | yes | When FALSE, the Pot object cannot be seen on the display panel. When TRUE, the Pot can be seen and controlled. |



Note When the **enterValue** input transitions from **FALSE** to **TRUE**, and
 if the Pot is visible,
 if Lookout is not in edit mode, and
 if the Pot has at least one digital display,

The **Enter new value** dialog box pops up so an operator can input a value, just as if he had clicked on the digital display.

The numeric format and position used for the dialog box are based on the digital display for a pot.

Even if the panel containing the Pot digital display is inactive, the **Enter new value** dialog box will pop up. You can prevent this by predicating the **enterValue** input on the panel's **active** data member.

Comments Potentiometers are one of the most common control objects used in process controls. Using Pots, a plant operator can make setpoint changes with the mouse. L3Pots also work well as HOA switches. To create an HOA switch with a Pot, specify the minimum as 1, the maximum as 3, and the resolution as 1.

The increment and decrement data members enable quick connection of pot objects to \$Keyboard and Panel function keys, and screen Pushbuttons. These are often used to control Pot objects when Lookout is running on an industrial PC platform that has restricted or no mouse functionality.

L3Pushbutton

L3Pushbutton generates a logical signal for receipt by other objects. A pushbutton changes state when you position the cursor over it and press the mouse button, trackball, touchscreen, or space bar. The pushbutton remains depressed and the output signal remains high until you release the button. If a **Verify on** message is defined, the operator must first acknowledge the message, then the output signal goes high, *but only momentarily*.

Figure 2-47. L3Pushbutton Definitions Parameters Dialog Box

Button text displays the specified text on the pushbutton.

Use **Verify on** to create a dynamic text expression to be displayed in a message dialog box. See Chapter 6, *Security*, in the *Lookout Developer's Manual* for more information on security.

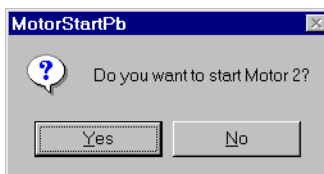


Figure 2-48. Verification Message Dialog Box

Position source determines where the value of the pushbutton resides. **Local** indicates the value of the pushbutton lies within the pushbutton itself—on the control panel. If the pushbutton is not depressed its signal is OFF, if depressed its signal is ON.

Remote pushbuttons get their values from a remote source, often the register in a controller they are connected to. Depressing the pushbutton changes the status of the register, and changing the status of the register depresses the pushbutton.

The **Remote** option is especially useful when you want to prevent Lookout from changing the value of setpoints or registers upon initial startup, or reconnection of lost communication. When you use this style of pushbutton you are creating a sort of looped signal. Half the loop is formed when you connect the controller register to the pushbutton with the Position expression, while the second half is formed when you connect the pushbutton output signal to the controller register. Position is a logical expression. Do not forget to complete the second half of the loop with the **Object»Edit Connections...** command.

When you select the **Remote** option, you can choose whether or not the pushbutton latches its output. The **Latch output** check box configures Lookout for controlling a latching-relay.

When a user clicks on a pushbutton that has latching selected, the pushbutton remains depressed, sending an ON signal (TRUE or high) until the Remote Position signal turns ON. Assume for example that an operator clicks on `MotorStartPb`, configured previously. The pushbutton remains pushed in, sending a TRUE signal, until `PLC.C101` goes TRUE. As soon as `PLC.C101` goes TRUE, the pushbutton releases.

Much like Remote pushbuttons, **DDE** (Dynamic Data Exchange) pushbuttons get their values from a remote source. This could be a cell in a spreadsheet, another DDE aware application, or a second copy of Lookout running on the network. See Chapter 5, *Dynamic Data Exchange*, in the *Lookout Developer's Manual* for information on **Service**, **Topic**, and **Item** parameters.

Control security level specifies the minimum security level operators must have to gain access to this individual object, and thus control it. See Chapter 6, *Security*, in the *Lookout Developer's Manual* for more information on security.

The **Log events** option creates a permanent audit trail for the object—who did what and when. Any depression of the pushbutton is recorded to disk, including the time the button was depressed, and the operator's account name. See Chapter 7, *Logging Data and Events*, in the *Lookout Developer's Manual* for more information on logging events.

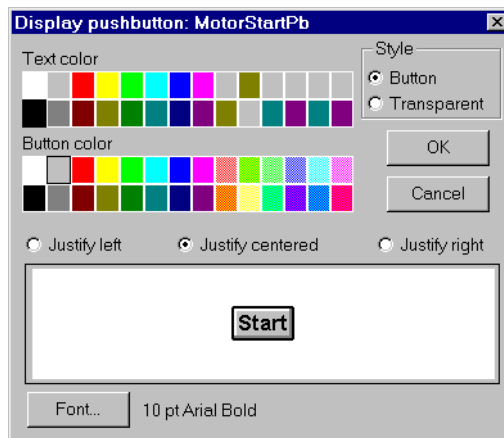


Figure 2-49. L3Pushbutton Display Parameters Dialog Box

L3Pushbutton Data Members

Table 2-30. L3Pushbutton Data Members

| Data Members | Type | Read | Write | Description |
|---------------------|-------------|-------------|--------------|---|
| (implicit) | logical | yes | no | Value of object (TRUE when button is depressed) |
| enable | logical | no | yes | If TRUE (the default), enables DDE. If FALSE, disables DDE. The default value is on. This input is ignored for non-DDE TextEntry objects. |
| visible | logical | no | yes | When FALSE, the pushbutton cannot be seen on the display panel. When TRUE, the button can be seen and controlled. |

L3Switch

L3Switch generates a logical signal for receipt by other objects. Switches change state when you click on them with a mouse button, trackball, touchscreen, or space bar on your keyboard.

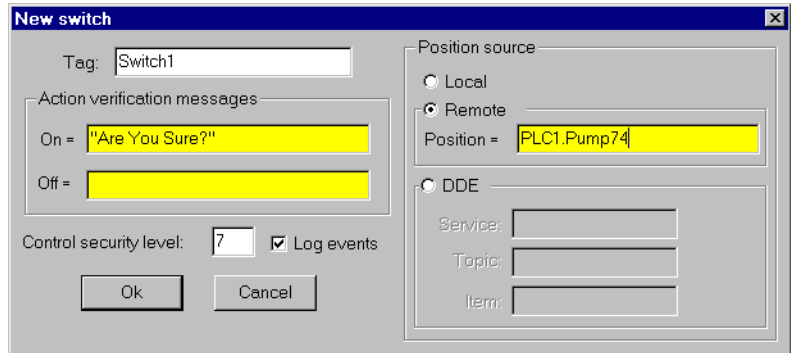


Figure 2-50. L3Switch Definition Parameters Dialog Box

Use **Action verification messages** to create dynamic text expressions to be displayed in message dialog boxes. See Chapter 6, *Security*, in the *Lookout Developer's Manual* for more information on security.

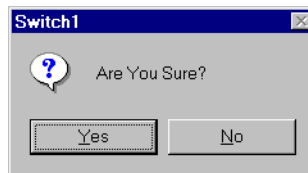


Figure 2-51. Verification Message Dialog Box

Position source determines where the value of the switch resides. **Local** indicates the value of the switch lies within the object itself—on the control panel. If the switch is up the signal is ON, if down the signal is OFF.

Remote switches get their values from a remote source, often the register on a controller they are connected to. Flipping the switch changes the status of the register, and changing the status of the register flips the switch.

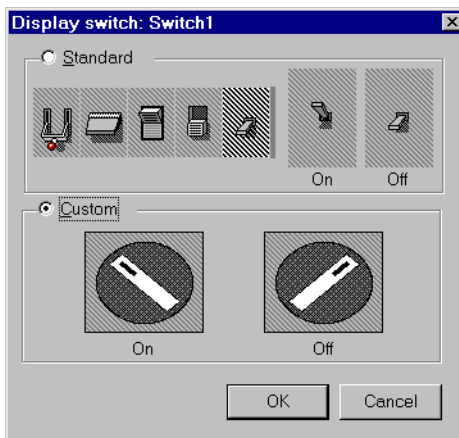
The **Remote** option is especially useful when you want to prevent Lookout from changing the value of setpoints or registers upon initial startup, or reconnection of lost communication. When you use this style switch, you are creating a sort of looped signal. Half the loop is formed when you

connect the controller register to the switch with the **Position** expression, while the second half is formed when you connect the switch output signal to the controller register. Notice **Position** is a logical expression. Do not forget to complete the second half of the loop with the **Object»Edit Connections...** command.

Much like Remote switches, **DDE** (Dynamic Data Exchange) switches get their values from a remote source. This could be a cell in a spreadsheet, another DDE aware application, or a second copy of Lookout running on the network. See Chapter 5, *Dynamic Data Exchange*, in the *Lookout Developer's Manual* for more information on **Service**, **Topic**, and **Item** parameters.

Control security level specifies the minimum security level operators must have to gain access to this individual object, and thus control it.

The **Log events** option creates a permanent audit trail for the object—who did what and when. All adjustments of the switch are logged to disk, including the time the switch was flipped, the operator's account name, and the direction the switch was flipped. See Chapter 7, *Logging Data and Events*, in the *Lookout Developer's Manual* for more information on event logging.



You can replace the standard switch types with custom graphic symbols. If you decide to use custom graphics, you must specify both symbol parameters, **On** and **Off**. See Chapter 2, *Graphics*, in the *Lookout Developer's Manual* for more information on creating custom graphic symbols and the use of Transparent pixels.

L3Switch Data Members

Table 2-31. L3Switch Data Members

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|---|
| (implicit) | logical | yes | no | L3Switch Position |
| enable | logical | no | yes | If TRUE (the default), enables DDE. If FALSE, disables DDE. The default value is ON. This input is ignored for non-DDE L3TextEntry objects. |
| visible | logical | no | yes | When FALSE, the switch object cannot be seen on the display panel. When TRUE, the switch can be seen and controlled. |

Comments If a switch with more than two positions is needed, use a Radiobutton object instead.

Related Objects [L3Pushbutton](#), [L3Pot](#), [Pushbutton](#), [Pot](#)

L3TextEntry

With L3TextEntry you can manually enter textual notes with the keyboard. These notes may contain any combination of numeric and alphanumeric characters; however, the result of your entry is converted to a text value. Just like any other text expression in Lookout, your note can be logged to disk, connected to other data members that accept text signals, and so on. The note is saved and displayed as a single line entry—you cannot embed carriage returns into the message.

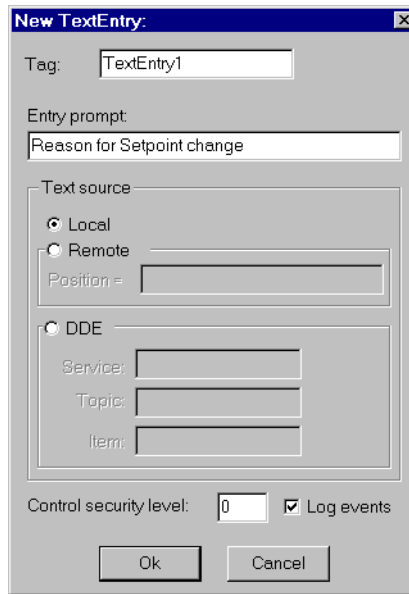


Figure 2-52. TextEntry Parameters Dialog Box

Entry prompt is the text that appears at the top of the text entry dialog box when an operator selects the text entry pushbutton.

Text source determines where the user-entered text resides. **Local** indicates the user-entered text lies within the object itself—on the control panel.

Remote indicates that the user-entered text resides in a remote source, such as a text expression or another TextEntry object.

Much like **Remote** TextEntry objects, **DDE** TextEntry objects get their values from a remote source. This is the option you use to tie the text to a cell in a spreadsheet, a database lookup table, or any DDE aware

application—including a second copy of Lookout running on the network. See Chapter 5, *Dynamic Data Exchange*, in the *Lookout Developer's Manual* for more detailed information on **Service**, **Topic** and **Item**.



Note The last DDE parameters used on any object automatically become the default values for any new DDE object.

Control security level specifies the minimum security level operators must have to gain access to this individual object, and thus control it.

The **Log events** option creates a permanent audit trail for the object—who did what and when. When selected, all text entries in this object are logged to disk. Each entry includes the time of the entry, the operator's account name, and what entry was made. See Chapter 7, *Logging Data and Events*, in the *Lookout Developer's Manual* for more information on event logging.

Lookout presents the following display parameters dialog box after you define the object. It lets you define the text font and presentation style.

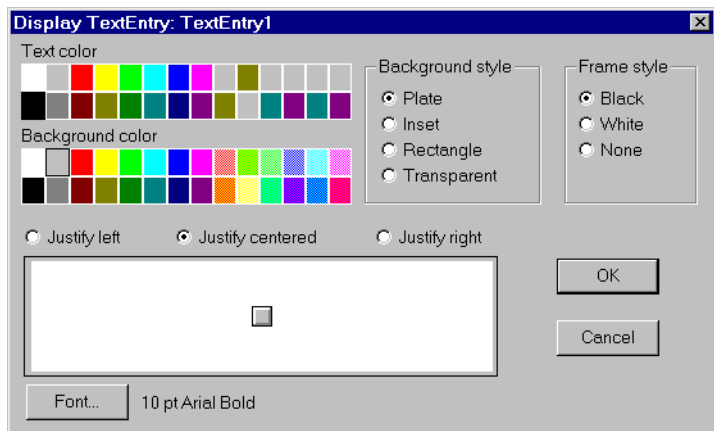


Figure 2-53. TextEntry Display Parameters Dialog Box

L3TextEntry Data Members

Table 2-32. L3TextEntry Data Members

| Data Members | Type | Read | Write | Description |
|---------------------|-------------|-------------|--------------|---|
| (implicit) | text | yes | no | Current, user-entered text |
| enable | logical | no | yes | If TRUE (the default), enables DDE. If FALSE, disables DDE. The default value is ON. This input is ignored for non-DDE TextEntry objects. |

LatchGate

LatchGate is latched on and off by two incoming signals. It retains the state of the signal that most recently went high, regardless of the state of the other signal. When the **Turn Off** signal transitions from OFF to ON, the LatchGate output goes OFF until the **Turn On** signal transitions from OFF to ON. The output signal does not change when either incoming signal transitions from ON to OFF. Both **Turn Off** and **Turn On** are logical expressions.

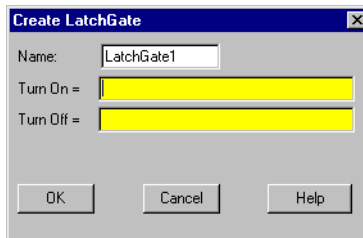


Figure 2-54. LatchGate Definition Parameters Dialog Box

LatchGate Data Members

Table 2-33. LatchGate Data Members

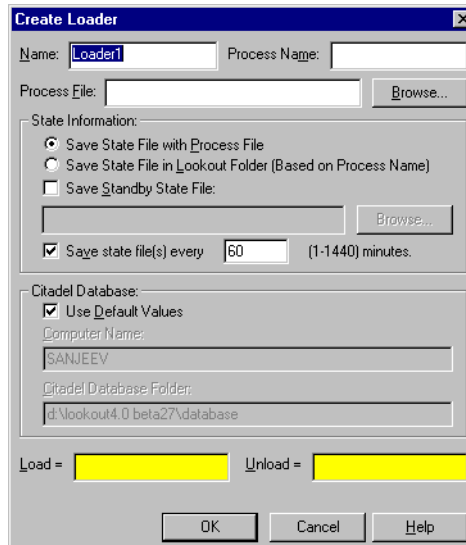
| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|-----------------------------|
| (implicit) | logical | yes | no | Logical output signal value |

Comments Two pushbuttons connected to the **Turn On** and **Turn Off** expressions of a LatchGate create pushbutton start/stop controls for a pump or other device.

Related Objects [Flipflop](#)

Loader

Use the Lookout Loader to load or unload a Lookout process in response to a logical trigger. Using a Loader object in conjunction with a Monitor object is how you create failover redundancy with Lookout. See Chapter 10, *Redundancy*, in the *Lookout Developer's Manual* for more information on redundancy.



You may notice that the information in the **State Information** and **Citadel Database** sections of this dialog box are the same as those areas in the **Create Process** dialog box and, in the case of the **Citadel Database** section, the **System Options** dialog box. Just as the **Citadel Database** section of the **Create Process** dialog box overrides the system database location settings for a particular process, any settings you make in the Loader object for database location or saving of state files override both system defaults and whatever settings you may have made when you created the process being loaded.

Process Name is the name that the process runs under when you open the **Process File**. You can use a process name other than the one used when the process file loaded was created.

Process File is the name of the file this Loader object will load when activated. You must enter a complete path to the file. You can specify a file

from another computer on your network, but you must map the location on the remote computer as a network drive on your own computer first.

The **State Information** section of this dialog box lets you set where Lookout saves state files for the process just loaded, and under what name the files are saved.

Select **Save State File with Process File** to save the state file in the location where the process file was opened.

Select **Save State File in Lookout Folder** to save the state file in the Lookout folder of the copy of Lookout you are currently running. The state file name is the same as the process name.

Select the **Save Standby State File** checkbox to save one or more extra copies of the state file in a location of your choosing. Enter a complete path, including state file name, to each location you want to save a state file. If you are saving the state file to more than one backup or alternative location, separate the paths with the vertical bar (|) operator symbol.

Check the **Save State File(s) every *NNNN* (1-1440) minutes** option to set the frequency with which Lookout saves the state file. The Lookout default is 60 minutes.

The **Citadel Database** section sets the location of the Citadel database that Lookout logs data to for the process you load. If you check the **Use Default Values** checkbox, Lookout uses the default location set in the **System Options** dialog box of any instance of Lookout running the process.

If you enter a computer name and a path on that computer to a specific folder, Lookout logs data to that location on that computer, no matter what computer is running the process.

To designate a specific computer and path for your process to log data to, enter the fully qualified network name for the target computer in the **Computer Name** field, and the complete path to the target database directory in the **Citadel Database Folder** field.

Load is the logical signal you use to activate the Loader and load the process.

Unload is the logical signal you use to activate the Loader and unload the process you loaded earlier.

The Loader can only load one process at a time, and can only load a process to run inside the instance of Lookout currently running the process that contains the Loader.

To load multiple processes with one trigger, you must use multiple Loader objects.

Loader Data Members

Table 2-34. Loader Data Members

| Data Member | Type | Read | Write | Description |
|------------------|---------|------|-------|--|
| SaveWithProcess | logical | yes | no | When TRUE, Lookout saves a state file in the same location as the process file it contains the state for. |
| DatabaseComputer | text | yes | no | Sets the computer on which Lookout saves Citadel database files. |
| DatabaseFolder | text | yes | no | Sets the folder in which Lookout saves Citadel database files. |
| Failure | logical | yes | no | Monitor this data member to be alerted if a load attempt fails. |
| Failuretext | text | yes | no | Returns the reason for a failure to load the process designated by the loader. |
| Load | logical | yes | yes | Triggers the loader to load the designated process file. |
| ProcessFile | text | yes | no | Name of the process the loader loads when activated. |
| ProcessName | text | yes | no | Specifies the process name a loaded process runs under. |
| SavePeriod | numeric | yes | no | Sets how often, in minutes, that Lookout saves the state file for the loaded process. |
| SaveWithLookout | logical | yes | no | When TRUE, Lookout saves the state file in the Lookout directory, using <code>ProcessName</code> as the name for the state file as well. |

Table 2-34. Loader Data Members

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---|
| StandbyFile | text | yes | no | Complete path to the location in which you want Lookout to save copies of the state file. |
| Unload | logical | yes | yes | Triggers the loader to unload the designated process. |

Loader Error Messages

Load: No process file specified

Specify a process file in the **ProcessFile** field.

Load: No process name specified

Name your process in the **ProcessName** field.

Load: Process already exists: *loadername.processname*

The process specified by your Loader object is already running under that name in this instance of Lookout. Only one process may run under each process name.

Load: No state file specified

You must specify state file information for any process you load with a Loader object.

Load: Invalid process name

You have chosen an invalid process name. See the *Object Names* section in Chapter 4, *Using Lookout*, of your *Getting Started With Lookout* manual for detailed information on valid Lookout process and object names.

Load: Invalid database computer name

The computer name you have entered in the **ComputerName** field is not registered as being a part of your Lookout network. Check the spelling of the name or register the computer through the Lookout Object Explorer or the Lookout Connection Browser.

Load: Invalid database folder

Check the path you have entered in the **Citadel Database Folder** field to make sure the path you entered does exist on the computer specified in the **ComputerName** field.

Load: Can't open process file *processfilename*

Lookout was unable to open the file *processfilename*. Check to see that the file exists in the specified location and has not been corrupted.

Unload: No process name specified

Enter the name of the process you want to unload in the **Process Name** field.

Unload: Process not found

Lookout must be running a process with the name specified in the **Process Name** field for the Loader to unload a process. If no process with the specified name is running when the Loader attempts to unload a process, Lookout returns this error message.

Maximum

Maximum actively calculates the maximum value of **Data** over time. Maximum is only active when the **Enable** expression is TRUE. It resets to zero when the **Reset** expression transitions from OFF to ON. Maximum also maintains an array of up to 35 previous maximum values. If **Enable** is left blank, the object always actively calculates the maximum. **Data** is a numeric expression while **Reset** and **Enable** are logical expressions.

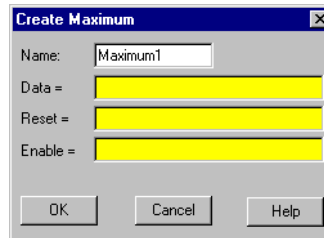


Figure 2-55. Maximum Configuration Parameters Dialog Box



Note Maximum does not have a display parameters dialog box. However, you can easily display Maximum by referencing it in an expression.

Maximum Data Members

Table 2-35. Maximum Data Members

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|--|
| (implicit) | numeric | yes | no | Current maximum value |
| 1 – 35 | numeric | yes | no | Previous maximum values. Signal 1 is the most recent prior maximum since the Reset expression went high. |
| DataReset | logical | no | yes | Upon transition from FALSE to TRUE, resets to zero all data members—including the current maximum value and all previous maximum values. |

Comments The **Reset** interval could be a regular pulse interval created by a TimeOfxxxx timer, so that the pulse is synchronized to the top of the hour or day. For example, if you want to calculate the daily maximum flow rate, use the output signal from a TimeOfDay timer or a daily Spreadsheet object to reset the maximum calculation at the beginning of each day.

Related Objects *Average, Minimum, Sample, SampleText*

Minimum

Minimum actively calculates the minimum level of **Data** over time. Minimum is only active when the **Enable** expression is TRUE. It resets to zero when the **Reset** expression transitions from OFF to ON. Minimum also maintains an array of up to 35 previous minimum values. If **Enable** is left blank, the object is always actively calculating the minimum. **Data** is a numeric expression while **Reset** and **Enable** are logical expressions.

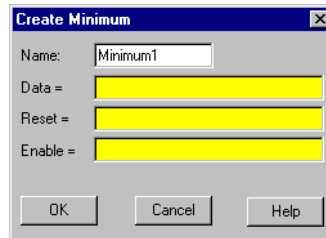


Figure 2-56. Minimum Configuration Parameters Dialog Box



Note Minimum does not have a display parameters dialog box. You can easily display the Minimum value referencing it as an expression.

Minimum Data Members

Table 2-36. Minimum Data Members

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|--|
| (implicit) | numeric | yes | no | Current minimum value |
| 1 – 35 | numeric | yes | no | Previous minimum values. Signal 1 is the most recent prior minimum since the Reset expression went high. |
| DataReset | logical | no | yes | Upon transition from FALSE to TRUE, resets to zero all data members—including the current minimum value and all previous minimum values. |

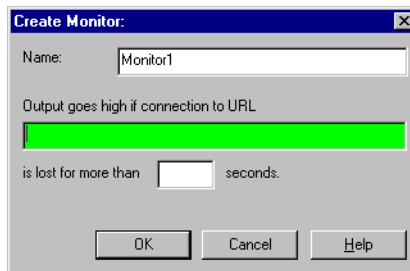
Comments The **Reset** interval could be a regular pulse interval created by a TimeOfxxxx timer, so that the pulse is synchronized to the top of the hour or day. For example, if you want to calculate the daily minimum flow rate, use the output signal from a TimeOfDay timer or a daily Spreadsheet object to reset the minimum calculation at the beginning of each day.

Related Objects *Average, Maximum, Sample, SampleText*

Monitor

The Lookout Monitor object is integral to Lookout redundancy. The Monitor object maintains a connection with a data member in any process you want to watch from another computer or process. If the data flow from that source stops, the Monitor signals the halt, allowing you to respond.

Using a Monitor object in conjunction with a Loader object is how you create failover redundancy with Lookout. See Chapter 10, *Redundancy*, in the *Lookout Developer's Manual* for more information on redundancy.



In the **Output goes high** field enter a data member in the process you want to monitor. If the data quality of that expression goes bad for more than the number you enter in the **seconds** field, the monitor goes high (TRUE), letting you know there is a problem with the process.

Monitor Data Members

Table 2-37. Monitor Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|--|
| (implicit) | logical | yes | no | Goes TRUE when the data member the Monitor is watching cannot be accessed after a specified length of time. |
| timeout | numeric | yes | no | The length of time in seconds that the data member being monitored must be unavailable before the Monitor goes TRUE. |

Multistate

Multistate displays different graphics on a control panel as dictated by the values of **Conditional expressions**. You can use up to six **Graphic files**, but at least one is required. Multistate determines which graphic to display based on the order and current status of your **Conditional expressions**. If several **Conditional expressions** are true at once, Multistate displays the graphic associated with the first true expression.

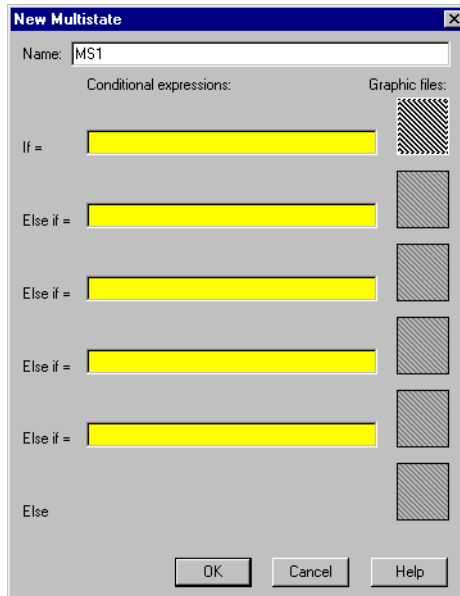


Figure 2-57. Multistate Configuration Parameters Dialog Box

Conditional expressions must result in logical values (TRUE or FALSE). See the *Animator* section for more information about constructing logical statements. Double-click in a **Graphic file** box to select the graphic you want to use.

Multistate Data Members

Table 2-38. Multistate Data Members

| Data members | Type | Read | Write | Description |
|--------------|------|------|-------|---|
| none | — | — | — | Multistate objects do not have data members |

Comments By creating several graphic images that depict a sequence of events, Multistate can be used to create animation sequences on control panels such as hydraulic pistons moving back and forth. A more typical use of Multistate is for three-color pilot lights, where green represents running, red represents stopped, and yellow represents failed, for example.

For smooth, high speed animations, use the Animator object.

Related Objects [*Animator*](#)

Neutralzone

Neutralzone is an ON/OFF Controller. It functions the way a home air conditioning thermostat does; if the temperature rises above a certain level, the `above` data member goes TRUE (turning the A/C on). When it drops below a lower temperature, the `below` data member goes TRUE (turning the A/C off).

When the incoming **Signal** value rises above both **Low limit** and **High limit**, the data member `above` turns on, and the data member `below` turns off. When the incoming **Signal** value drops below both **Low limit** and **High limit**, `above` turns off, and `below` turns on. The `above` and `below` data members do not change state when the signal value falls back within the two limits (within the neutral zone). **Signal**, **High limit**, and **Low limit** are all numeric expressions.

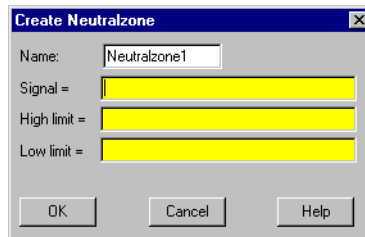


Figure 2-58. Neutralzone Definition Parameters Dialog Box

The previous discussion assumes numeric constants for both limits. However, you could use variable setpoint signals from Pot objects so an operator could dynamically adjust Neutralzone behavior.



Note Neutralzone does not have a display parameters dialog box. You can easily display the result of Neutralzone output signals by referencing its data members in an expression.

Neutralzone Data Members

Table 2-39. Neutralzone Data Members

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|--|
| above | logical | yes | no | ON if signal is greater than both limits, OFF if signal is less than both limits, and does not change if signal is between both limits |
| below | logical | yes | no | ON if signal is less than both limits, OFF if signal is greater than both limits, and does not change if signal is between both limits |

Comments You can use this object to turn pumps on and off or open and close valves based on line pressures or tank levels. Neutralzone objects prevent pumps from cycling on and off around a single setpoint, just as an air conditioning thermostat prevents your home air conditioner from incessantly starting and stopping.

Often the term deadband is mistakenly used to describe a neutral zone. However, deadbands refer to the amount of change a numeric value must travel in the reverse direction before the output numeric value begins to change.

OneShot

OneShot is an adjustable delay timer. When **On/off signal** transitions to on, the output signal goes TRUE and the **Timer delay** begins to count down. At the end of the delay countdown, the output signal goes FALSE.

Unlike the Interval timer, the OneShot timer output remains on for the **Time delay** period even if **On/off signal** goes FALSE. So a OneShot timer requires only a momentary signal to begin the **Timer delay** period. Pulsing the **On/off signal** during the time delay period does not extend the time delay period of a OneShot timer.

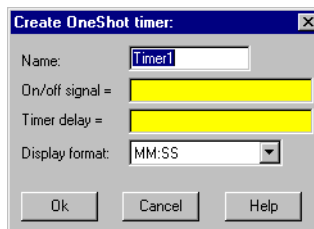


Figure 2-59. OneShot Definition Parameters Dialog Box

The **On/off signal** is a logical expression while Timer delay is a numeric expression. Normally, this is a simple time constant such as 0:20 (twenty seconds). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on time constants.

Timer delay can range from 0.0 seconds to several years. The effective resolution is 0.1 seconds over the entire range.

The object is represented on a control panel by showing the time delay remaining in the format defined by the **Display format** parameter. It is updated approximately once per second. If the delay period has expired, it shows **OFF**.

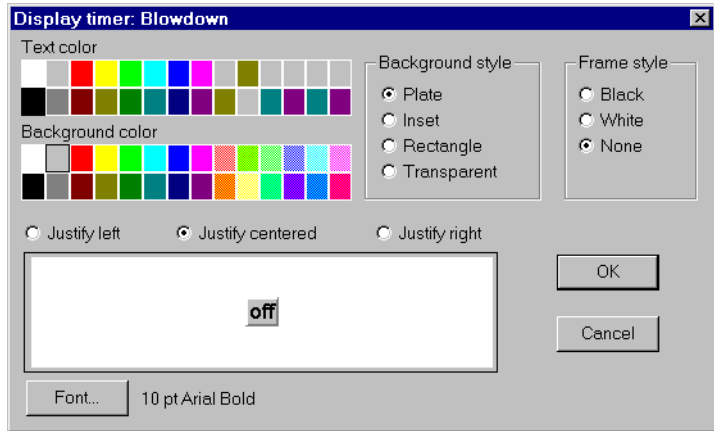


Figure 2-60. OneShot Display Parameters Dialog Box

OneShot Data Members

Table 2-40. OneShot Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|---------------------|
| (implicit) | logical | yes | no | Logical timer value |

Comments You can use the OneShot timer to hold a valve open for a set period of time after a pushbutton is pressed, or to prevent pump starts from occurring too rapidly in succession.

Related Objects [DelayOff](#), [DelayOn](#), [Interval](#), [Pot](#), [TextEntry](#)

Pager

Pager is an object class Lookout uses to contact a numeric or alphanumeric pager through a modem, sending a message to the pager.

The screenshot shows the 'Create Pager' dialog box with the following settings:

- Name: Pager1
- Pager type: Numeric Only
- Pager number = "555-5555"
- Message = "Lookout numeric Page 123-4567"
- Numeric Only parameters:
 - Delay: 12 seconds
- Baud rate: 1200
- Serial port: COM1
- Communication alarm priority: 8

Figure 2-61. Numeric Only Pager Definition Parameters Dialog Box

The screenshot shows the 'Create Pager' dialog box with the following settings:

- Name: Pager1
- Pager type: Alphanumeric
- Pager number = "555-5555"
- Message = "Lookout numeric Page 123-4567"
- Alphanumeric parameters:
 - Terminal number: 89226068
 - Retry attempts: 4
 - Receive timeout: 2000 msec
- Baud rate: 1200
- Serial port: COM1
- Communication alarm priority: 8

Figure 2-62. Alphanumeric Pager Definition Parameters Dialog Box

Pager type determines whether the Pager object operates in numeric only or alphanumeric mode. A detailed description of the operation of these two modes follows.

Pager number is the phone number of the pager you want to contact. When the Pager object is in **Alphanumeric** mode, this number corresponds to the pager ID number.

Message is the message you want to send to the pager. Notice that in **Numeric Only** mode only numeric characters are sent.

Delay is how long the Pager object waits after dialing the pager number before it dials the message number. This parameter is valid in **Numeric Only** mode only.

Terminal number is the phone number of the remote paging terminal you want to contact. This parameter is valid in **Alphanumeric** mode only.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the Pager object generates an alarm and releases the COM port. Refer to Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information. This parameter is valid in **Alphanumeric** mode only.

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request. This parameter is valid in **Alphanumeric** mode only.

Baud rate indicates the baud rate Lookout uses to communicate with the modem and paging terminal.

Serial port specifies which COM port Lookout uses to communicate with your modem. You must have this COM port configured as dial-up under **Options»Serial Ports**.

Communication alarm priority determines the priority level of alarms generated by the Pager object. You can relate such alarms to communications with the modem or with the remote paging terminal.

Pager Data Members

Table 2-41. Pager Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|--|
| Message | text | no | yes | Pager message |
| Phone | text | no | yes | Individual pager phone number or Page ID number |
| Send | logical | no | yes | Sends the message on transition from FALSE to TRUE |

Pager Object Modes

Numeric Only

In **Numeric Only** mode, the Pager object establishes a connection with your local modem. Once this connection has been established and the pager number dialed, the Pager object waits for the time specified by **Delay**, then dials the number that is the message. Because the `Message` data member is a text value, the Pager object in **Numeric Only** mode omits any non-numeric characters from the message when it is sent.

Alphanumeric Mode

In **Alphanumeric** mode, the Pager object actually establishes a connection with a remote paging terminal, then transmits an alphanumeric message using Telocator Alphanumeric Protocol (TAP) version 1.8. TAP is an industry standard protocol for paging terminals that accept alphanumeric pages. Alphanumeric messages are limited to 250 characters. The text value in the `Message` data member will be truncated to this length if it is longer.

Pager Serial Port Settings

Notice that there are two different retry settings that affect the operation of the Pager object in **Alphanumeric** mode. The retry settings in the Pager object dialog box govern serial communications with the remote paging terminal. This means that after the two modems have connected and finished handshaking, and the serial transaction is underway, each individual frame is timed by the **Receive timeout** setting, and retried the number of times specified by **Retry attempts**.

These retry settings will not dial the phone number again if the remote paging terminal for some reason does not answer or is busy, which happens occasionally. This setting and other important modem settings (including the AT initialization string that the Pager object must use on your modem) can be found in **Option»Serial Ports**, and should be chosen carefully. These settings are important in both Pager object modes.



Note You may have to increase your **Receive Gap** setting from its default of 5 to something closer to 20 or 25. You must also have your COM port configured as dial-up.

Pager Queueing

The Pager object queues up to 10 messages in either mode. If the object is in the process of sending out a page and the `Send` data member goes high again, the current value of the `Message` data member will be queued and sent out when the Pager object has time. Messages that are already in the queue will not be duplicated.

Pager Status Messages

Paging terminal refused logon

Alphanumeric only error code

Paging terminal forced disconnect

Alphanumeric only error code

Paging terminal NAKed block transmission

Alphanumeric only error code

Paging terminal abandoned block transmission

Alphanumeric only error code

No response within timeout period

This means that the modem is not responding to Lookout requests.

Queue full

The paging queue currently has 10 pages in it, and will not accept any more until at least one of those pages is successfully sent.

Garbled response

A response from the modem was corrupted or in an unrecognizable form.

Panel

Panel is a unique object class that accepts display members of other objects. Panels (Control panels) are a window into your process you can use to monitor and control your system by flipping switches, depressing pushbuttons, and turning knobs.

There is no limit as to the number of control panels you can create in Lookout or the number of objects or graphics that you can display on a given panel. Control panels can be any size, and you can display them within the Lookout workspace in various states (maximized, normal, minimized).

Create control panels with the **Object>Create...** command or with the **Insert>Control panel...** command. Both commands deliver the same result.

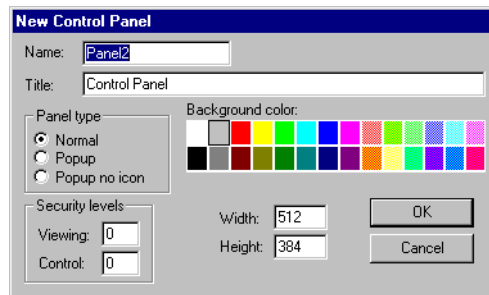


Figure 2-63. Panel Definition and Display Parameters Dialog Box

There are three distinct panel types: **Normal**, **Popup**, and **Popup no icon**.

A **Normal** control panel can be maximized, normal size, or minimized within the Lookout workspace. When you activate a **Normal** panel it appears at the size defined by its **Height** and **Width**. When you maximize a **Normal** panel, it fills the Lookout workspace. When you minimize a **Normal** panel it appears as an icon. The **Normal** option is typically selected for full-sized control panels.

Popup control panels can either be in a popup state or minimized (they cannot be maximized). When you activate a **Popup** panel it appears at the size defined by its **Height** and **Width**. When a Popup control panel is activated, it remains on top of all other panels until it is minimized. When you minimize a **Popup** panel it appears as a bar at the bottom of the Lookout screen.

Popup no icon control panels are identical to **Popup** panels except they are not represented by icons when minimized. When you minimize a **Popup no icon** panel it disappears from the Lookout workspace.

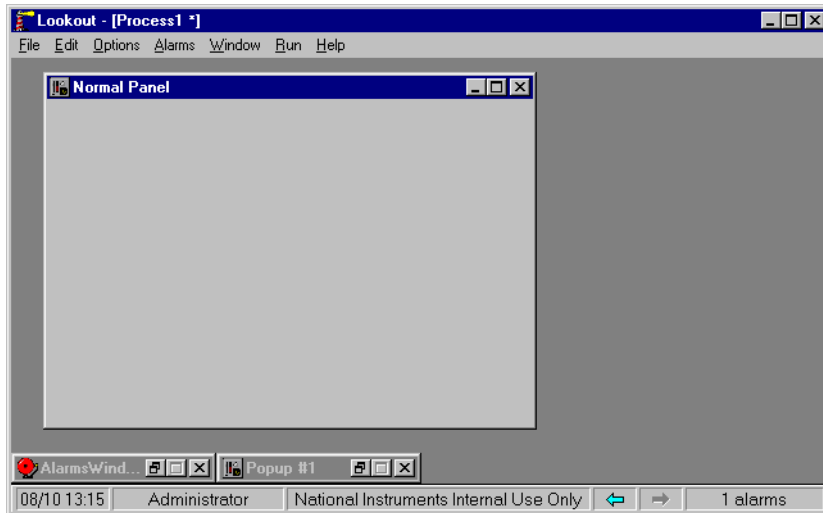


Note Because **Popup no icon** control panels are not represented by icons, they use less memory. (Microsoft Windows allocates a fixed amount of memory to each icon.) If you are experiencing memory problems when running a Lookout application that has many control panels, consider converting your **Popup** panels to **Popup no icon**.

Normal panels and Popup panels can be chosen by selecting their icon, using the **Window** menu command. **Popup no icon** control panels cannot; they can only be accessed by triggering their `activate` data member.

The **Security levels** settings are globally applied to a given control panel. The **Control** security level works in conjunction with all individual object security levels on that panel. The higher security level of the two is used to determine if an operator has control over the object. For example, consider a single Switch object with a security level of 4 that is displayed on two panels. The first panel has a control level of 6 and the second panel has a control level of 2. Only level 6 and higher operators are able to flip the switch on the first panel; however, level 4 and higher operators have control over the same switch on the second panel.

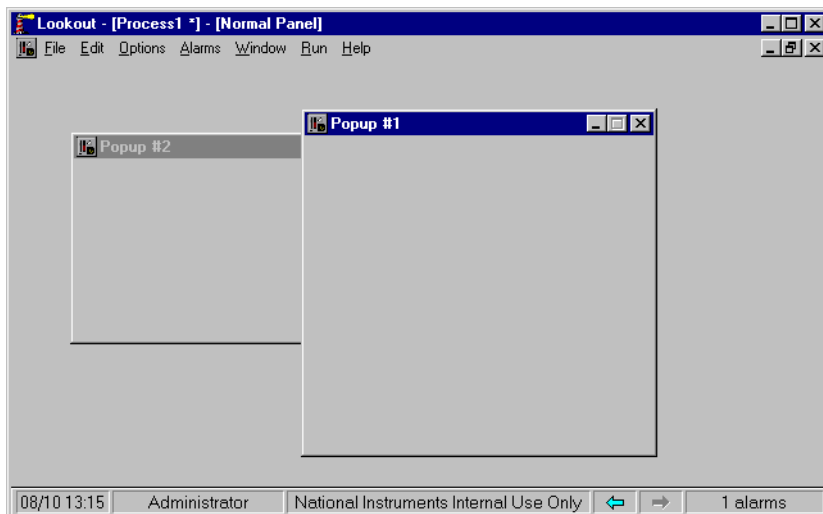
Viewing security can hide entire control panels from low level operators. This parameter affects the entire control panel. As an example take a control panel with a viewing security level of 6. If a level 5 (or lower) operator logs on, he is unable to see the control panel. In fact, he does not even know it exists because it is not listed in the **Window** menu and it is not shown as an icon. If a level 6 (or higher) operator logs on, the control panel instantly becomes available for display. This feature is useful for hiding panels that are rarely used or that contain sensitive information.



This example shows a **Normal** control panel in a normal state and a **Popup** control panel in a minimized state. The **Normal** panel could easily be minimized or maximized by hitting the appropriate arrow button.

The following example is a typical scenario involving full screen control panels with multiple popup panels displayed at once.

This configuration maximizes the amount of information that you can display at once; and it allows you to have any number of different combinations of control panels displayed on your monitor.



This example displays a **Normal** control panel in a maximized state and two **Popup** control panels in a “popped up” state.

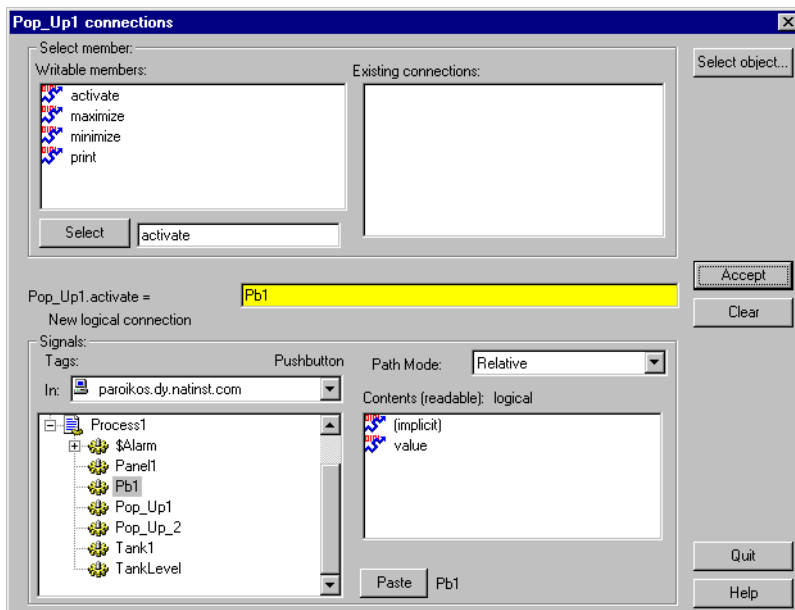
Manipulating Panels

Lookout control panels utilize the Microsoft standard Multiple Document Interface (MDI) techniques. You manipulate Lookout windows the same way you do other windows in the Microsoft Windows environment.

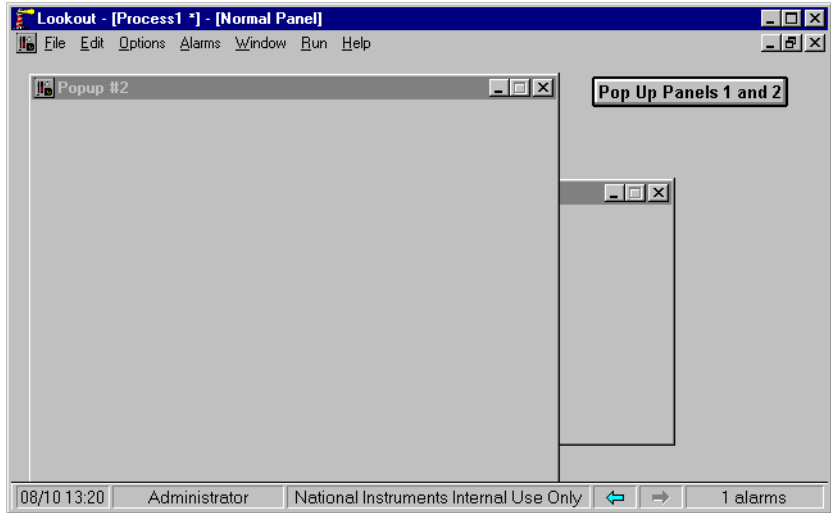
Panel Switching

It is common to have several or even dozens of control panels. Creating a methodology for moving between your panels can be as simple or as elaborate as you want. One effective method utilizes pushbuttons that invoke other control panels. You connect the pushbutton output signal to the activate or maximize data member of the control panel(s) you want to affect. When the button signal goes high the respective panel(s) appear.

The following example shows a single pushbutton and X with its output signal connected to two **Popup** control panels. The pushbutton is inserted on a third maximized panel.

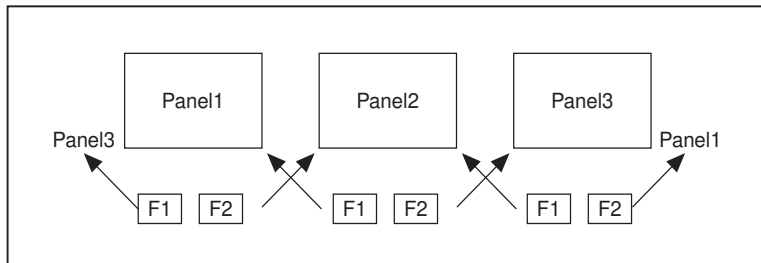


When you toggle out of Edit Mode and depress the button, both **Popup** control panels instantly appear, as shown in the following illustration. Of course you could have connected the pushbutton to another **Normal** panel instead, and it would have appeared as the new maximized panel.



As you can imagine, there is no limit to the number of connections between various signals and control panels. In fact, you can create complex expressions/alarms that automatically call up specific control panels.

Another way to move between panels is through the use of function keys. Like the \$Keyboard object, each panel has its own set of data members representing the function keys F1 – F24. The following example shows the F2 data member of Panel1 connected to the activate data member of Panel2. The F2 data member of Panel2 is also connected to the activate data member of Panel3. This way an operator can depress F2 to page forward through several panels.



In similar fashion, the F1 data member of Panel3 is connected to the activate data member of Panel2 and the F1 data member of Panel2 is connected to the activate data member of Panel1. So now, `Panel2.activate = Panel1.F2 OR Panel3.F1`. An operator can depress F2 to page forward through the control panels and F1 to page back through the control panels.

Special Considerations for “Home Panel”

To ensure users do not get lost when switching between panels, you might define one panel as your master control panel, or home panel or computer main menu. You could connect the activate data member of your home panel to `$Keyboard.Shift.F1`, or perhaps to a pushbutton object. If connected to the function key, any time the user presses <SHIFT-F1> (no matter what panel he or she is looking at), the home panel is called, returning the operator to a familiar control panel.

You might also want the home panel to maximize upon startup. If you have already created a pushbutton to call the home panel, you can connect it to the `maximize` data member.

The exclamation point (!) instructs Lookout to use the opposite of the pushbutton value. At startup, the pushbutton is not depressed so its value is FALSE. But because you are using the opposite of the pushbutton value, `Panel1.maximize` is TRUE at startup. Any time a user depresses `CallHomePb` after this connection is made, nothing happens until the pushbutton is released—at which time the panel is called.

Panel Print

You can easily print a control panel using the **Print Panel** command. This function works equally well for both Normal and Popup panel types.

Print the contents of a panel by clicking on the panel control menu and then on **Print Panel**, or by connecting a logical expression to the `Print` data member of the desired control panel. A panel does not have to be visible to be printed.



Note Certain metafiles look different on the printed page than they do on the display screen. This means that parts of layered objects sometimes appear opaque on the screen, but translucent when drawn on paper.



Note When you print a **Normal** panel, it is printed at its defined **Height** and **Width** parameters. If you define a panel whose **Height** and **Width** are at the default 400×300 pixel setting, maximize the panel, and then add graphic elements to the full panel, those elements outside of the default 400×300 pixel range are not shown when the panel is printed. To print all the elements on a maximized panel, modify the **Width** and **Height** of the panel to match the full-screen dimension of the panel.

You can modify an existing control panel by toggling into edit mode and right-mouse clicking on its title bar. You can also modify a panel with the **Object»Modify...** menu command just like any other object.

Screen Resolution and Lookout Graphics

Lookout graphics and control panels appear different, depending on the PC you are using and the resolution of your screen driver. When you position a graphic (or any other display element) onto a control panel, Lookout identifies the position you selected by recording the specific pixel position of the graphic. (A pixel is the smallest possible dot on the screen.) Lookout actually counts the number of pixels that the graphic is from the upper left-hand corner of the screen. When you subsequently recall a panel, Lookout knows the exact location to place the graphic.

The reason to bring this up is because different computer screen drivers have different screen resolutions. VGA screens are 640×480 pixels. Super VGA screens typically range from 800×600 pixels to 1024×768 pixels. A panel created at 640×480 pixel resolution does not fill the screen of a 1024×768 super VGA monitor. A panel created at 1024×768 pixel resolution will overflow the screen of a 640×480 VGA monitor.

It is best to create your panels using the display driver resolution of the computer on which you intend to run Lookout. If you are creating panels for use on multiple computers, consider developing panels using the display driver resolution of the most common resolution monitor (if you have a dozen Super VGA computers and one VGA computer, develop your panels in Super VGA, not VGA). You will then have to modify the panels slightly to fit on the less common resolution computer(s).

You can usually change the resolution of your screen from VGA to Super VGA by changing System Settings in Windows Setup. Refer to your *Microsoft Windows* manual for more information.

Panel Data Members

Table 2-42. Panel Data Members

| Data Members | Type | Read | Write | Description |
|-----------------------------------|---------|------|-------|--|
| <CTRL-F1> – <CTRL-F24> | logical | yes | no | Each of these 24 data members represent a function key, <F1> – <F24>—when pressed in conjunction with the <CTRL> key. Returns TRUE when the panel is active and its associated function key is pressed in conjunction with the <CTRL> key. |
| <F1> – <F24> | logical | yes | no | Each of these 24 data members represent a function key, <F1> – <F24>. Returns TRUE when the panel is active and its associated function key is pressed. |
| <SHIFT-F1> through <SHIFT-F24> | logical | yes | no | Each of these 24 data members represent a function key, <F1> – <F24>—when pressed in conjunction with the <SHIFT> key. Returns TRUE when the panel is active and its associated function key is pressed in conjunction with the <SHIFT> key. |
| activate | logical | no | yes | Upon transition from FALSE to TRUE, calls control panel to focus or pop up. |
| active | logical | yes | no | Returns TRUE when the panel is the currently selected panel (i.e., it is active). |
| maximize | logical | no | yes | Upon transition from FALSE to TRUE, maximizes control panel, replacing existing maximized control panel. |

Table 2-42. Panel Data Members (Continued)

| Data Members | Type | Read | Write | Description |
|---------------------|-------------|-------------|--------------|---|
| minimize | logical | no | yes | Upon transition from FALSE to TRUE, minimizes control panel to icon state. |
| print | logical | no | yes | Upon transition from FALSE to TRUE, sends the control panel to the Windows Print Manager. |

Pareto

The Pareto object class is one of the Lookout Statistical Process Control (SPC) tools and can play an important role in your Total Quality Management (TQM) program. This object class displays a frequency distribution of occurrences sorted by category so that you can identify the most frequently occurring anomalies or defects in your process.

The Pareto object class displays weighted and/or unweighted Pareto charts. The charts can be interactive, automatic, or a combination of both. An optional percentage line, showing cumulative percentage of factors, may be displayed. The number of factors to display, which may be less than the total number of factors defined, is user selectable. The chart background color, as well as the label, weight, and color of each factor, can be defined by the user.

The Pareto chart object definition dialog box is shown in the following illustration.

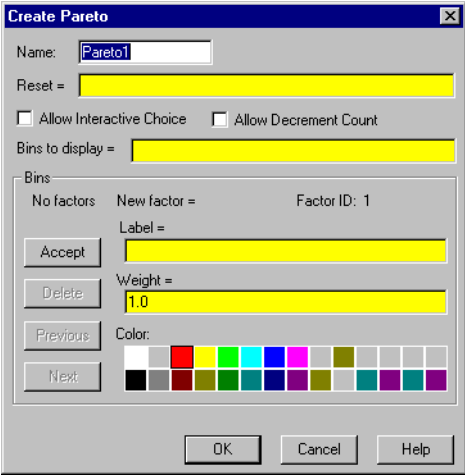


Figure 2-64. Pareto Definition Parameters Dialog Box

Reset is a logical expression that, on transition from FALSE to TRUE, resets all of the factor counts to zero.

Use **Allow Interactive Choice** to indicate whether the operator can increment (and possibly decrement) factor counts by clicking the mouse cursor on the Pareto chart object.

Allow Decrement Count indicates whether the operator can decrement the factor counts if you enable interactive choice.

Bins to display is the number of factor bins to display in the Pareto chart. This can be a numeric expression or a constant.

Bins parameters enable adding, modifying, or deleting factors to and from the Pareto chart. **Label** is the descriptive title for the factor. It can be a text constant or expression. **Weight** is the bias you can apply for a factor if you are going to display a weighted Pareto chart. It can be a numeric constant or expression. **Color** is the color of the bar for the factor. **Factor ID** is a number generated by the object to uniquely identify the current factor count when it is being saved to or restored from the Lookout state file. It is a visual indication to the user that a factor count is associated with a particular Factor ID, and not with the Label.

The Pareto display dialog box is shown in the following illustration.

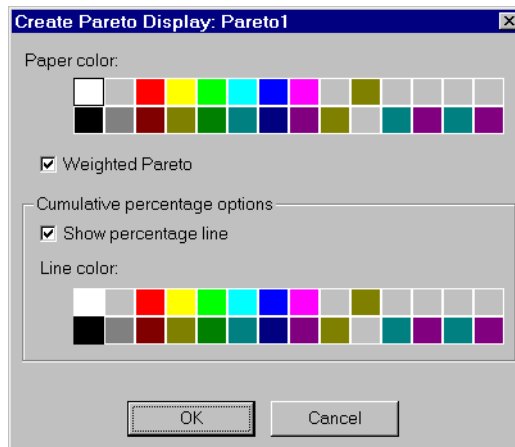


Figure 2-65. Pareto Display Parameters Dialog Box

Show percentage line determines whether a cumulative percentage line will be displayed in the color selected by **Line color**.

Weighted Pareto determines whether the Pareto is displayed as a weighted chart or an unweighted chart.

Weighted or Unweighted Charts

Using the same Pareto object, you can display weighted or unweighted Pareto charts. An unweighted Pareto chart shows which factors occur most frequently. If the factors are of approximately equal importance, an unweighted chart is a good indication of trouble spots.

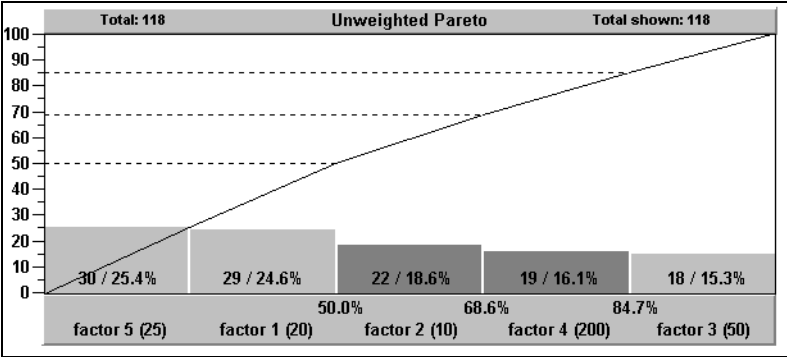


Figure 2-66. Unweighted Pareto Chart

If some factors are much more serious than others, using a weighted Pareto chart to ascertain the cost or exposure of a factor is a much more effective tool for identifying problem areas. For example, in the unweighted Pareto chart in Figure 2-66, factor 1 and factor 5 together account for 50 percent of the defect occurrences. However, as you can see on the weighted Pareto chart in Figure 2-67, factor 4 alone accounts for 60.8 percent of the total expense of all defects.

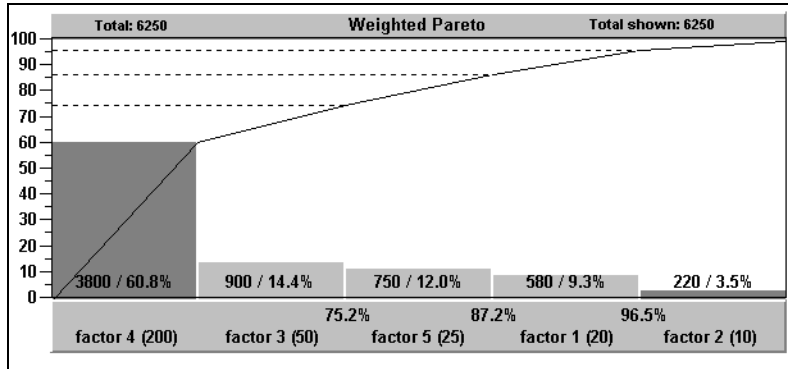
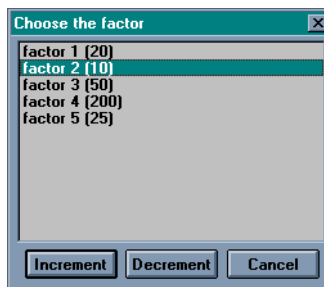


Figure 2-67. Weighted Pareto Chart

Incrementing Factor Counts

You can use a Pareto chart to interactively or automatically increment factor counts. In fact, the object can accept any combination of automatic and interactive inputs.

If you select the **Allow Interactive Choice** option in the object definition dialog box, the operator can manually increment factor counts. To do this, the operator clicks the mouse cursor on the Pareto chart object. This pops up box that lists all the possible factors you can choose. The factor that the cursor is on when the operator clicks on the chart determines which factor is highlighted when the dialog box pops up. In this example, the mouse cursor was over the factor 2 bin.



If you select the **Allow Decrement Count** option in the object definition dialog box, the Decrement button is displayed in the pop-up, allowing the operator to decrement a factor count. Operators with a high enough security level can correct errors if necessary.

Pareto Data Members

The Pareto object can use external connections to trigger the factor counts automatically. You can connect a pushbutton, an alarm, an expression, a PLC output, and so on, to a factor trigger to increment a factor count on a transition from FALSE to TRUE. The following table lists data members of the Pareto object class.

Table 2-43. Pareto Data Members

| Data Members | Type | Read | Write | Description |
|-------------------------------------|---------|------|-------|--|
| count.sorted1 – 1000 | numeric | yes | no | The count in the respective sorted-by-count factor bin. |
| count.weighted.sorted 1 – 1000 | numeric | yes | no | The weighted count in the respective sorted-by-weighted-count factor bin. |
| count.weighted1 – 1000 | numeric | yes | no | The weighted count in the respective unsorted factor bin. |
| count1 – 1000 | numeric | yes | no | The count in the respective unsorted factor bin. |
| factor1 – 1000 | logical | no | yes | On transition from FALSE to TRUE, increment the respective factor count by 1. |
| label.sorted1 – 1000 | text | yes | no | The label of the respective sorted-by-count factor bin. |
| label.weighted.sorted 1 – 1000 | text | yes | no | The label of the respective sorted-by-weighted-count factor bin. |
| label1 – 1000 | text | yes | no | The label of the respective unsorted factor bin. |
| percent.sorted1 – 1000 | numeric | yes | no | The percent of the total count in the respective sorted-by-count factor bin. |
| percent.weighted.sorted 1 – 1000 | numeric | yes | no | The percent of the total weighted count in the respective sorted-by-weighted-count factor bin. |
| percent.weighted 1 – 1000 | numeric | yes | no | The percent of the total weighted count in the respective unsorted factor bin. |

Table 2-43. Pareto Data Members (Continued)

| Data Members | Type | Read | Write | Description |
|----------------------|-------------|-------------|--------------|---|
| percent1 – 1000 | numeric | yes | no | The percent of the total count in the respective unsorted factor bin. |
| total | numeric | yes | no | The total of all unweighted factor counts in all defined factors. |
| total.shown | numeric | yes | no | The total of all unweighted factor counts in all currently displayed factors. |
| total.shown.weighted | numeric | yes | no | The total of all weighted factor counts in all currently displayed factors. |
| total.weighted | numeric | yes | no | The total of all weighted factor counts in all defined factors. |
| visible | logical | yes | yes | When TRUE, the Pareto chart becomes visible on the control panel. When FALSE, it is invisible. The default value is TRUE. |

PID

The PID object compares a **Process Variable** to a **Setpoint**. If there is a difference, it calculates the error and adjusts its output to compensate until the **Process Variable** is equal to the **Setpoint**.

PID stands for Proportional-Integral-Derivative. These are three factors in the equation that can be applied against the calculated error. You specify **Gain** which is the proportional factor, **Reset** (the integral factor), and **Rate** (the derivative factor) to define how the object responds to the error.



Note The way in which the PID object responds to your process can vary greatly according to the parameters you enter and the process you are controlling. Any discussion regarding tuning of a PID loop falls outside of the topics addressed in this manual.

Figure 2-68. PID Definition Parameters Dialog Box

Type selects either positional control or velocity control. Detailed descriptions of both control modes are provided in the following sections.

Process Variable (PV) is typically the numeric signal from the field that you want to control. The PID loop equation does not expect this value to be normalized; rather the PID object performs the scaling of loop input and output values from engineering units.

Setpoint (SP) is typically the value of a Pot object, a constant numeric value, or the output signal from another PID object in a cascaded loop. Like the process variable, the setpoint is also scaled internally by the PID object.

Setpoint Min and Max are numeric constants that specify the range of *SP* and *PV* in engineering units.

Manual Output is a numeric parameter that specifies the output of the object when it is in manual mode; that is, when the **Automatic Enable** expression is **FALSE**. Users typically enter either a constant, or the name of a Pot object in this field.

Output Min and Max are numeric constants that specify the range of the object output signal. The output is often referred to as the *manipulated variable (MV)*.

Sample Pulse indicates the frequency at which the PID object executes. This parameter field can contain either a numeric constant or a logical variable. If you use a numeric constant (like 0:01 for one second), the object calculates a new output value at the defined frequency. If you use a logical variable, then the variable should pulse at some desired frequency. Any time the pulse transitions from **FALSE** to **TRUE**, the object calculates a new output value. It is very important not to over-sample your data. Start with a slow sample rate.

Gain (K_c) is a numeric parameter that determines the overall sensitivity of the PID loop to changes in error. A gain value of 1.00 changes the proportional increment of the PID equation by 50 percent when there is a 50 percent change in error. A gain value of 0.25 changes the proportional increment by 12.5 percent with a 50 percent change in error.

Reset (T_i) also referred to as integral time, is a numeric parameter that specifies the amount of time it takes for the integral sum increment of the PID loop equation to react to a given change in error. For example, if the error suddenly changes by 20% and reset = 0:10 (10 seconds), the integral increment of the PID loop increases at a rate of 0.5 percent per second until it has changed by 20 percent after 40 seconds. This 20 percent contribution is multiplied by the gain, so if the gain is 2.0, the integral term contributes 40% to the loop output in this example. In other words, the shorter the reset time, the faster the object output responds to a change in either *PV* or *SP*.

Rate (T_d) also referred to as derivative time, is a numeric parameter that dampens loop response. It is calculated based upon the rate of change of *PV* and adds an increment to the output that attempts to anticipate and slow the change in *PV*. As an example, if *PV* is increasing by 10 percent per minute, and rate is 0:30 (0.5 minutes), the derivative increment is calculated as $-(10\%/min. \times 0.5\ minutes) = -5\%$ (or -0.05). So the derivative term would contribute -5% to the output if the gain is 1.0.

Automatic Enable specifies whether the loop controller is operating in automatic mode or manual mode. When it is ON, controller is operating in automatic mode and the output signal is being calculated using the PID algorithm. In manual mode, the output signal is equal to the **Manual Output** input signal.

The PID object provides bumpless transfer from manual to automatic operation—when the controller is switched from manual to automatic, its output begins changing from the current manual output setting. Contrast this with a loop controller without bumpless transfer. When such a controller is in manual, the integral term continues to accumulate. When the controller is switched to automatic, the loop controller would immediately go to a high or low output.

Add proportional increment specifies whether the loop equation adds the proportional increment of the PID equation to *MV*. This value is typically ON.

Freeze Enable specifies whether the loop bias should be frozen or actively back-calculated when the controller output signal goes out of range. In either case, the loop controller is protected from integral wind-up, but if Freeze Enable is OFF (recommended setting), the bias is actively back-calculated to prevent controller overshoot when *PV* comes back into range.

The PID object protects against integral windup in one of two selectable ways: It either freezes the bias term when the controller output goes out of range, or it actively back-calculates the bias so the controller responds smoothly with less chance of overshoot when its output returns to range.

Output Time is a numeric constant that specifies the time domain of the controller output when operating in velocity mode. For example, if the object output controls a value with dimensions of inches per minute, output time would be 1:00 (one minute).

Low Limit Enable is used in velocity control mode. It is an optional logical signal that clips the PID output to a value greater than or equal to zero when TRUE. This input can be used to signal the controller that the low limit switch on the controlled device has been activated.

High Limit Enable is used in velocity control mode. It is an optional logical signal that clips the PID output to a value less than or equal to zero when TRUE. This input can be used to signal the controller that the high limit switch on the controlled device has been activated.

PID Positional Control

When you select `Position`, the PID object calculates the output as follows:

$$MV = K_c(e_n + \text{integral sum}_n - T_d/dT(Pv_n - Pv_{n-1}))$$

where:

dT = time increment between current and previous calc.

MV = controller output (manipulated variable)

K_c = controller gain (units: % output / % error)

e_n = error at sample n (error = $SP - Pv_n$)

$\text{integral sum}_n = \text{integral sum}_{n-1} + dT / T_i (e_n - e_{n-1})$ also called bias

T_d = rate, or derivative time

$Pv_n - Pv_{n-1}$ = change in PV from previous to current calculation

PID Velocity Control

The output of the velocity form of the PID equation is the velocity or rate of change of the output signal. The velocity form of the PID equation is the first derivative of the position form of the PID equation with respect to time, so the result is the rate of change of the controller position.

When you select `Velocity`, the object calculates the output as follows:

$$dMV = MV_n - MV_{n-1} = K_c((e_n - e_{n-1}) + T_s e_n / T_i + T_d / T_s (Pv_n - 2Pv_{n-1} + Pv_{n-2}))$$

where:

MV = controller output position (manipulated variable)

dMV = controller output velocity

K_c = controller gain (units: % output / % error)

e_n = error at sample n (error = $SP - Pv_n$)

T_d = rate, or derivative time

PV = process variable

PID Data Members

Table 2-44. PID Data Members

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|--|
| Error | numeric | yes | no | This is the difference between the Setpoint (SP) and the Process Variable (PV) . |
| Output | numeric | yes | no | This is the PID controller output value, also called <i>MV</i> , or the manipulated variable. This value is either the result of the PID loop equation or the Manual Output , depending on the state of Automatic Enable . |

Comments The proportional term of the PID equation contributes an amount to the output equal to the error multiplied by the **Gain**. This provides an immediate output compensation when the error value changes.

The integral term of the PID equation calculates a running total of the error summed (or integrated) over time—think of this increment as adding the area under the curve of a plot of error versus time. While *SP* is greater than *PV*, the integral term is increasing, and while *PV* is greater than *SP*, the integral term is decreasing. The sensitivity of the integral output is set by the gain and the reset variables. Integral action can be eliminated by setting **Reset** to a higher number. At least some Integral action is required, however, for the loop controller to operate properly with bias adjustment. If you do not use any Integral, you may experience offset, a condition in which the output is adjusted to compensate for the error, but not enough to correct the error.

The derivative term of the PID equation acts to dampen the change in *PV* by adding a negative value for a positive-going *PV* and a positive value for a negative-going *PV*. Because *PV* is subject to sudden small changes and signal noise in many process loops, derivative action can cause a loop to respond erratically. **Rate** can be set to 0, especially when initially tuning the loop, to eliminate derivative action. Derivative action dampens process loops that tend to oscillate around the setpoint and thus provide better loop response. Rapidly changing loops such as liquid flow control in a pipe may not benefit from derivative action, but more sluggish loops that tend to build momentum, such as temperature control, benefit from derivative action by preventing overshoot and dampening oscillatory action.

Pipe

Pipe displays different color rectangles (pipes) on a control panel as defined by the values of **Conditional expressions**. Pipe determines which color rectangle to display based on the order and current status of your **Conditional expressions**. If several **Conditional expressions** are TRUE at once, Pipe displays the color associated with the first TRUE expression. **Conditional expressions** must result in logical values.

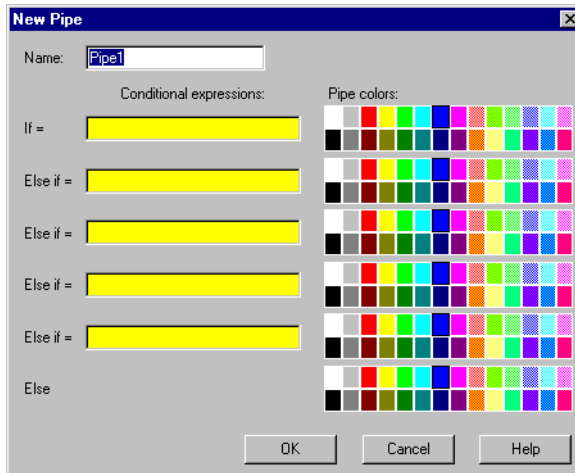


Figure 2-69. Pipe Definition Parameters Dialog Box

Pipe Data Members

Table 2-45. Pipe Data Members

| Data Members | Type | Read | Write | Description |
|--------------|------|------|-------|----------------------------------|
| none | — | — | — | Pipe does not have data members. |

Comments You can easily create a complex piping network scheme (including changing colors) with a single Pipe object. Display the object on a control panel and copy the pipe display with the shift-drag method to create additional pipes with the same parameters. You can then move, resize, and group the pipes as you choose.

Playwave

Playwave connects Microsoft standard wave form files (.wav) to events in Lookout. Playwave plays the audio file specified by **Wave file** when **Play when** transitions from off to on. **Play when** is a logical expression and might range from a simple pushbutton, to a digital input from a PLC, to an alarm generated in Lookout. You can also create your own custom audio files with various software products. Therefore, you can connect individual alarms to custom wave files to be played each time an alarm goes TRUE.

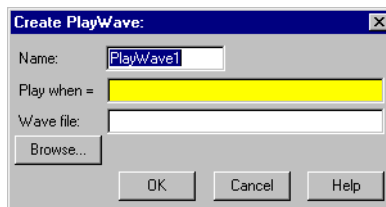


Figure 2-70. Playwave Definitions Parameters Dialog Box

Playwave Data Members

Table 2-46. Playwave Data Members

| Data Members | Type | Read | Write | Description |
|--------------|------|------|-------|---|
| none | — | — | — | Playwave does not have any data members |

Comments Many computers do not come equipped with quality speakers built in. If this is the case, your wave files may sound distorted or may even be inaudible. If you want to take advantage of the Playwave feature, you may need to buy additional hardware, in particular a Microsoft Windows compatible sound board (with Windows driver) and external speakers.

Pot

Pot is a potentiometer that you use to change numeric setpoint values. You can display Pots on a control panel as a knob, vertical slider, horizontal slider, increment/decrement pushbuttons, or digital entry. You can also use Pots as multiple-position switches.

If you change the background color of a panel and add a Pot object displayed as a slider, its color is always gray. To change the background color of a Pot to match your panel, select the Pot object, then pick **Change»Background Color** from the menu.

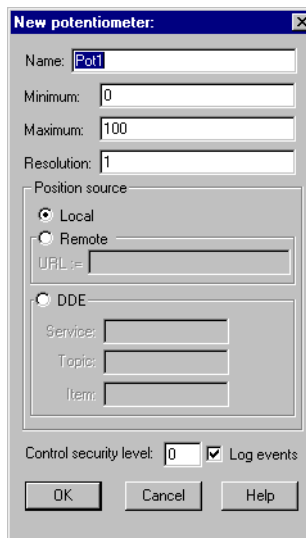


Figure 2-71. Pot Definitions Parameters Dialog Box

Minimum is the lowest value signal the pot will generate.

Maximum is the highest value signal the pot will generate.

Resolution is the smallest increment of change, or detent spacing the Pot supports.

Position source determines where the value of the Pot resides. **Local** indicates the value of the Pot lies within the object itself—on the control panel.

Remote Pots get their values from a remote source, often the register on a controller they are connected to. Adjusting the Pot changes the value in

the register, and changing the value in the register adjusts the Pot. In effect, the Pot is tracking a remote value. This is especially useful when you want to prevent Lookout from changing the value of setpoints or registers upon initial startup, or reconnection of lost communication.

The **Remote** option calls for a URL to locate the data member you want to connect to. The URL field is green, and you cannot use a complex expression as a URL. If you need to use one RadioButton for several purposes, you can use a Symbolic Link to make a more complex connection than that possible with a URL.

You can right-click in the **URL** field and use the **URL Editor** dialog box to assemble the URL, in the same way you use the Lookout expression editor.

A remote position source connection is completely reciprocal. A change in your Lookout control changes the data member that control is remoted to. Any change in that data member also changes the control. It is not necessary, and is incorrect, to use the **Edit Connections** dialog box to connect a control object to its controlled data member.

Because the remote connection is reciprocal, you can only make such a connection to a data member that is either writable, or readable and writable.

When a process with remoted controls first opens, those controls take their initial values by following the URL to read the data members they are remoted to. The control will be covered by a red X to indicate that the remote connection is not functioning.



Note You should use **Remote** to connect a control in a client process to a data member in a server process. Connections inside a single process can be made using **Object>Edit Connections**.

Because complex expressions are read-only values, you cannot remote directly to them. For the same reason, you cannot remote one control to another control's (intrinsic) data member (though you can remote a control to another control's value data member).

Much like Remote Pots, **DDE** (Dynamic Data Exchange) Pots get their values from a remote source. This could be a cell in a spreadsheet, another DDE aware application, or a second copy of Lookout running on the network. The last DDE parameters used on any object automatically become the default values for any new DDE object.

Control security level specifies the minimum security level operators must have to gain access to this individual object, and thus control it.

The **Log events** option creates a permanent audit trail for the object—who did what and when. All adjustments of the Pot are logged to disk, including the time of the adjustment, the operator account name, and what adjustment was made.

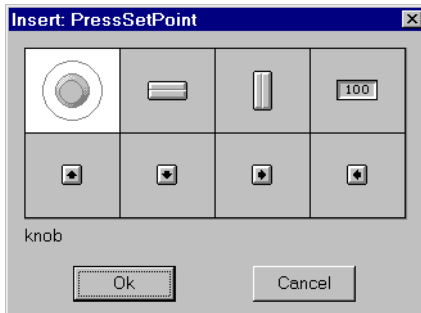


Figure 2-72. Pot Display Parameters Dialog Box



Note You can modify the background color on vertical and horizontal sliders with the **Change»Background color...** menu command. You can modify the font and font color of digital Pots using Change commands.

Pot Data Members

Table 2-47. Pot Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|---|
| (implicit) | numeric | yes | no | Current value |
| decrement | logical | no | yes | When this data member value transitions from FALSE to TRUE, the implicit value of the Pot object decreases by the Pot Resolution amount. |
| enable | logical | no | yes | If TRUE (the default), enables DDE. If FALSE, disables DDE. The default value is on. This input is ignored for non-DDE TextEntry objects. |

Table 2-47. Pot Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|---|
| enterValue | logical | no | yes | <p>Under specific circumstances, when this value transitions from FALSE to TRUE, pops up a Enter new value dialog box for an operator to use in entering a value for the Pot. See the note following the table for more detailed information.</p> <p>The enterValue data member is designed for use under unusual circumstances, in particular when pointing devices are not available on a computer running Lookout. Because of its unusual operation, this data member should not be used unless it is necessary for hardware reasons.</p> |
| increment | logical | no | yes | When this data member value transitions from FALSE to TRUE, the implicit value of the pot object increases by the Resolution amount. |
| reset | logical | no | yes | While this value equals TRUE, the control will be set to the value in <code>resetvalue</code> . |
| resetvalue | numeric | no | yes | Sets the value a control will take when the reset data member transitions from FALSE to TRUE. |
| value | numeric | yes | yes | The current value of the control. If you have remoted this control, then <code>value</code> is the current value of the position source. |
| visible | logical | no | yes | When FALSE, the Pot object cannot be seen on the display panel. When TRUE, the Pot can be seen and controlled. |



Note When the `enterValue` input transitions from **FALSE** to **TRUE**, and if the Pot is visible, if Lookout is not in edit mode, and if the Pot has at least one digital display, the **Enter new value** dialog box pops up so an operator can input a value, just as if the operator had clicked on the digital display.

The numeric format and position used for the dialog box are based on the digital display for a Pot. Even if the panel containing the Pot digital display is inactive, the **Enter new value** dialog box will pop up. You can prevent this by predicating the `enterValue` input on the panel's `active` data member.

Comments Potentiometers are one of the most common control objects used in process controls. Using Pots, a plant operator can make setpoint changes with the mouse. Pots also work well as H-O-A switches. To create an HOA switch with a Pot, specify the minimum as 1, the maximum as 3, and the resolution as 1.

The increment and decrement data members enable quick connection of Pot objects to \$Keyboard and Panel function keys, and screen Pushbuttons. These are often used to control Pot objects when Lookout is running on an industrial PC platform that has restricted or no mouse functionality.

Pulse

Pulse is a timer that generates a periodic pulse of a specified duration. When **On/off signal** transitions to ON, the output signal turns on for the pulse duration time and then turns off for the remainder of the period. The output signal immediately turns off when the **On/Off signal** goes low.

Timer period is the time interval for the full pulse cycle, and **Timer duration** is the width of each pulse. These parameters can range from 0.0 seconds to several years, with an effective resolution of 0.1 seconds over the entire range. **Timer duration** should always be less than **Timer period**.

The object is represented on a control panel by showing the time remaining before the output changes state. It is depicted in the format defined by the **Display format** parameter. It is updated approximately once per second. If the **On/Off signal** is FALSE, it shows OFF.

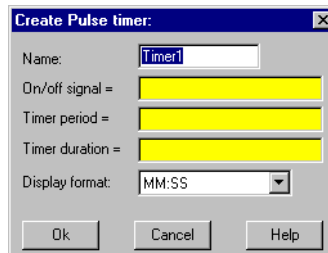


Figure 2-73. Pulse Definition Parameters Dialog Box

The **On/off signal** is a logical expression while **Timer period** and **Timer duration** are numeric expressions. Normally, these are simple time constants such as 0:20 (twenty seconds). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

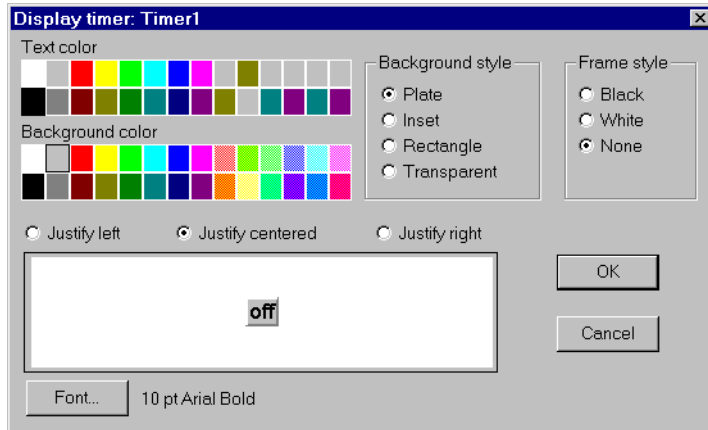


Figure 2-74. Pulse Display Parameters Dialog Box

Pulse Data Members

Table 2-48. Pulse Data Members

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|---------------------|
| (implicit) | logical | yes | no | Logical timer value |

Comments Pulse can be used to periodically open a valve for a specified time duration. It can also act as a flasher to turn text and graphic signals on and off for display purposes.

Related Objects [DelayOff](#), [DelayOn](#), [Interval](#), [OneShot](#), [TextEntry](#)

Pushbutton

Pushbutton generates a logical signal for receipt by other objects. A pushbutton changes state when you position the cursor over it and press the mouse button, trackball, touchscreen, or space bar. The pushbutton remains depressed and the output signal remains high until you release the button. If a **Verify on** message is defined, the operator must first acknowledge the message, then the output signal goes high, *but only momentarily*.

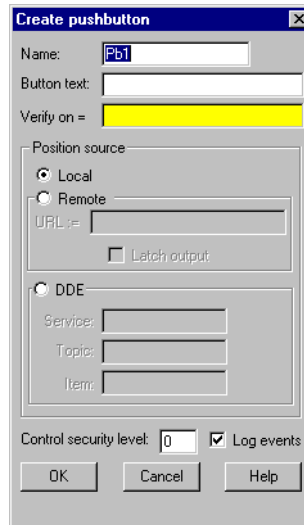


Figure 2-75. Pushbutton Definitions Parameters Dialog Box

Button text displays the specified text on the pushbutton.

Use **Verify on** to create a dynamic text expression to be displayed in a message dialog box. See Chapter 6, *Security*, in the *Lookout Developer's Manual* for more information on security.

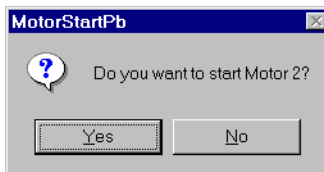


Figure 2-76. Verification Message Dialog Box

Position source determines where the value of the Pushbutton resides. **Local** indicates the value of the Pushbutton lies within the Pushbutton itself—on the control panel. If the pushbutton is not depressed its signal is OFF, if depressed its signal is ON.

Remote Pushbuttons get their values from a remote source, often the register in a controller they are connected to. Depressing the pushbutton changes the status of the register, and changing the status of the register depresses the pushbutton.

The **Remote** option calls for a URL to locate the data member you want to connect to. The URL field is green, and you cannot use a complex expression as a URL. If you need to use one RadioButton for several purposes, you can use a Symbolic Link to make a more complex connection than that possible with a URL.

You can right-click in the **URL** field and use the **URL Editor** dialog box to assemble the URL, in the same way you use the Lookout expression editor.

A remote position source connection is completely reciprocal. A change in your Lookout control changes the data member that control is remoted to. Any change in that data member also changes the control. It is not necessary, and is incorrect, to use the **Edit Connections** dialog box to connect a control object to its controlled data member.

Because the remote connection is reciprocal, you can only make such a connection to a data member that is either writable, or readable and writable.

When a process with remoted controls first opens, those controls take their initial values by following the URL to read the data members they are remoted to. The control will be covered by a red X to indicate that the remote connection is not functioning.



Note You should use **Remote** to connect a control in a client process to a data member in a server process. Connections inside a single process can be made using **Object»Edit Connections**.

Because complex expressions are read-only values, you cannot remote directly to them. For the same reason, you cannot remote one control to another control's (*intrinsic*) data member (though you can remote a control to another control's value data member).

When you select the **Remote** option, you can choose whether or not the Pushbutton latches its output. The **Latch output** check box configures Lookout for controlling a latching-relay.

When a user clicks on a Pushbutton that has latching selected, the pushbutton remains depressed, sending an ON signal (TRUE or high) until the Remote Position signal turns ON. Assume for example that an operator clicks on `MotorStartPb`, configured above. The pushbutton remains pushed in, sending a TRUE signal, until `PLC.C101` goes TRUE. As soon as `PLC.C101` goes TRUE, the pushbutton releases.

Much like Remote Pushbuttons, **DDE** (Dynamic Data Exchange) Pushbuttons get their values from a remote source. This could be a cell in a spreadsheet, another DDE aware application, or a second copy of Lookout running on the network. See Chapter 5, *Dynamic Data Exchange*, in the *Lookout Developer's Manual* for information on **Service**, **Topic**, and **Item** parameters.

Control security level specifies the minimum security level operators must have to gain access to this individual object, and thus control it. See Chapter 6, *Security*, in the *Lookout Developer's Manual* for more information on security.

The **Log events** option creates a permanent audit trail for the object—who did what and when. Any depression of the Pushbutton is recorded to disk, including the time the button was depressed, and the operator’s account name. See Chapter 7, *Logging Data and Events*, in the *Lookout Developer’s Manual* for more information on logging events.

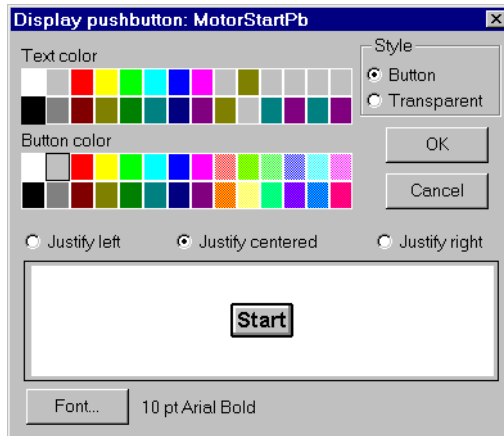


Figure 2-77. Pushbutton Display Parameters Dialog Box

Pushbutton Data Members

Table 2-49. Pushbutton Data Members

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|---|
| (implicit) | logical | yes | no | Value of object (TRUE when button is depressed) |
| enable | logical | no | yes | If TRUE (the default), enables DDE. If FALSE, disables DDE. The default value is on. This input is ignored for non-DDE TextEntry objects. |
| reset | logical | no | yes | While this value equals TRUE, the control will be set to the value in resetvalue. |
| resetvalue | numeric | no | yes | Sets the value a control will take when the reset data member transitions from FALSE to TRUE. |

Table 2-49. Pushbutton Data Members (Continued)

| Data Members | Type | Read | Write | Description |
|---------------------|-------------|-------------|--------------|--|
| value | numeric | yes | yes | The current value of the control. If you have removed this control, then <code>value</code> is the current value of the position source. |
| visible | logical | no | yes | When FALSE, the Pushbutton cannot be seen on the display panel. When TRUE, the button can be seen and controlled. |

RadioButton

The RadioButton object creates a set of radio buttons on your panel. You can have from 2 to 40 buttons in a set. Only one button at a time can be activated in each radio button group.

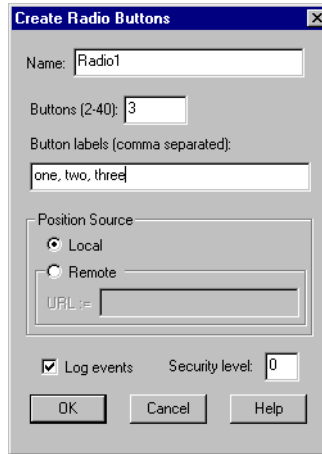


Figure 2-78. RadioButton Definition Parameters Dialog Box

Set the **Buttons (2-40)** in each set. You can have as many as 40 buttons in each group, but you must have at least 2.

Position source determines where the value of the RadioButton resides. **Local** indicates the value of the RadioButton lies within the object itself—on the control panel.

The **Remote** option tells Lookout to initialize the RadioButton value from a remote source. Adjusting the RadioButton changes the value in the register, and changing the value in the register adjusts the RadioButton. In effect, the RadioButton is tracking a remote value. This is especially useful when you want to prevent Lookout from changing the value of setpoints or registers upon initial startup, or reconnection of lost communication.

The **Remote** option calls for a URL to locate the data member you want to connect to. The URL field is green, and you cannot use a complex expression as a URL. If you need to use one RadioButton for several purposes, you can use a Symbolic Link to make a more complex connection than that possible with a URL.

You can right-click in the **URL** field and use the **URL Editor** dialog box to assemble the URL, in the same way you use the Lookout expression editor.

A remote position source connection is completely reciprocal. A change in your Lookout control changes the data member that control is remoted to. Any change in that data member also changes the control. It is not necessary, and is incorrect, to use the **Edit Connections** dialog box to connect a control object to its controlled data member.

Because the remote connection is reciprocal, you can only make such a connection to a data member that is either writable, or readable and writable.

When a process with remoted controls first opens, those controls take their initial values by following the URL to read the data members they are remoted to. The control will be covered by a red X to indicate that the remote connection is not functioning.



Note You should use **Remote** to connect a control in a client process to a data member in a server process. Connections inside a single process can be made using **Object»Edit Connections**.

Because complex expressions are read-only values, you cannot remote directly to them. For the same reason, you cannot remote one control to another control's (intrinsic) data member (though you can remote a control to another control's value data member).



Note You cannot break a group of radio buttons into multiple rows.

Enter any text for the buttons in the **Button labels** field. Separate each button label with a comma. If you need to include a comma or a backslash in any button text, precede that character with a backslash(\). If you want to leave a button blank, you can enter two commas without any text or numbers between the commas. You do not have to enter a label for every button. Lookout will leave each button after your last label entry blank. If you enter more labels than you have set buttons, your labels will be preserved but not displayed.

To log changes in button state, check the **Log Events** checkbox.

Security level sets the minimum security level an operator must have to change the radio buttons.

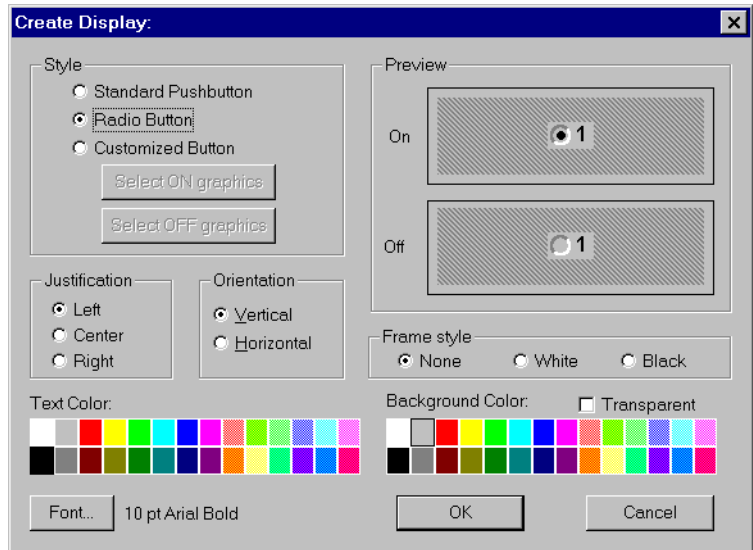


Figure 2-79. RadioButton Display Parameters Dialog Box

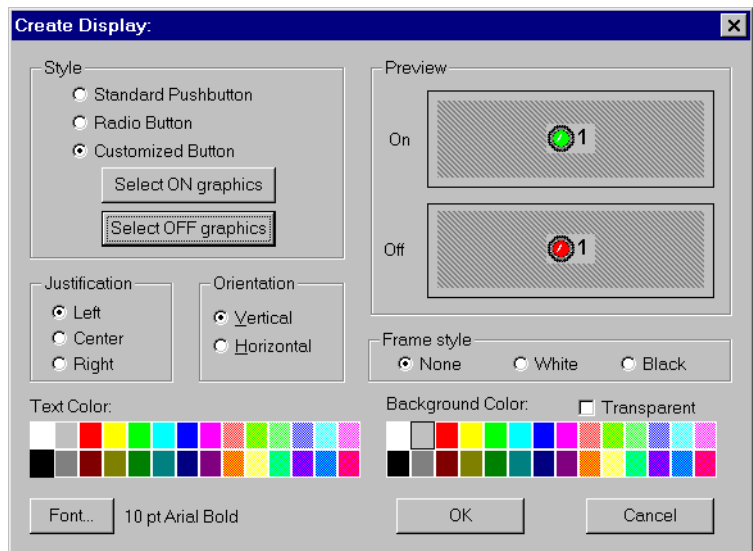


Figure 2-80. RadioButton Display Parameters Dialog Box with Custom Graphics Chosen

You can use a standard Lookout pushbutton, standardized radio buttons, or custom graphics for your radio button groups.

Notice that you cannot enter text in the **Create Display** dialog box. You must enter any text you intend to use in the **RadioButton Definition Parameters** dialog box. You can change font and text size in the **Create Display** dialog box. The first text label you entered for your radio button is displayed in the **Preview** field so you see the effect of font changes.

The default display uses a standard **Radio Button** display. You can adjust text and background color for any of your display choices.

Selecting **Standard Pushbutton** displays standard on/off buttons in your radio button array.

Select **Customized Button** for a free range of choices from the Lookout graphics library, or create your own ON/OFF indicators for a radio button array. See the *Creating Custom Graphics* section of Chapter 2, *Graphics*, in the *Lookout Developer's Manual* for detailed information on creating your own graphics for use on a Lookout control panel.

Set the **Orientation** of the radio button array to horizontal or vertical by checking the appropriate checkbox. Set label text **Justification** and button **Frame style** in the appropriate fields.

Related Objects [L3Pot](#), [L3Pushbutton](#), [L3Switch](#), [Pot](#), [Pushbutton](#), [Switch](#)

RadioButton Data Members

Table 2-50. RadioButton Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|---|
| 1-40 | logical | yes | no | Reports ON/OFF status of each button in a radio button set. |
| current | numeric | yes | no | Reports which radio button is active in a set. |
| (implicit) | numeric | yes | yes | Radiobutton value. |
| value | numeric | yes | yes | Number of the correctly active radiobutton. |
| visible | logical | yes | yes | Controls visibility of a radio button set. Default=TRUE. |

Recipe

Recipe objects are an efficient means of importing large arrays of data (namely recipes and their ingredients) into Lookout using an Excel (.xls) spreadsheet. Once created and implemented, the operator can easily and quickly change the current recipe with the click of the mouse, thus selecting a new set of ingredients.

The best way to describe how the Recipe class works is to step through a typical example, in this case involving cookie manufacture.

There are two steps to creating and implementing a recipe object. First, you define your recipes with their respective ingredients in a spreadsheet program such as Excel (anything that creates an .xls file will work—including Lotus 123). You can define up to 1,000 recipes in a single .xls file. Each recipe can have up to 255 ingredients. Three cookie recipes are defined in this spreadsheet.

The screenshot shows a Microsoft Excel spreadsheet titled "Cookies.xls". The spreadsheet has columns labeled A through O. Column A is reserved for recipe names, and columns B through O contain ingredient names and their quantities for three recipes: Chocolate Chip, Oatmeal, and Ginger Snap. Row 1 is the header row for ingredients. Row 2 is the first recipe, Row 3 is the second, and Row 4 is the third. Row 5 is empty. The status bar at the bottom shows "Ready" and "Sum=0".

| | A | B | C | D | E | F | G | H | I | J | K | L | M | N | O |
|---|----------------|-------|------|--------|-------------|-------------|----------------|---------|------|-------------|----------|------|--------|-----------|------------|
| 1 | | Flour | Eggs | Butter | White Sugar | Brown Sugar | Powdered Sugar | Vanilla | Salt | Baking Soda | Cinnamon | Oats | Ginger | Chocolate | Shortening |
| 2 | Chocolate Chip | 100 | 50 | 60 | 10 | 8 | 5 | 6 | 3 | 8 | 7 | 0 | 0 | 60 | 43 |
| 3 | Oatmeal | 120 | 45 | 50 | 15 | 14 | 3 | 5 | 4 | 7 | 5 | 50 | 0 | 0 | 51 |
| 4 | Ginger Snap | 110 | 40 | 40 | 8 | 11 | 4 | 4 | 5 | 9 | 8 | 0 | 57 | 0 | 68 |
| 5 | | | | | | | | | | | | | | | |

The first row of the spreadsheet is reserved for ingredient names. They begin in column B. These ingredient names later become alias data members of the Recipe object. Therefore, ingredient names must be unique. They cannot have the same name as a native data member (see the Recipe Data Member table for data member names). Also, you cannot name an ingredient `missing`; this is a reserved word. Valid characters in

an ingredient name include A – Z, 0 – 9, the dollar sign (\$), and a period (.). If you enter `Hi_@#!There` as an ingredient name, Lookout names the alias `HiThere`. Alias names are case sensitive.

Beginning in Row 2, Column A lists the names of the various recipes. Recipes follow the same naming convention as ingredients. Each recipe is followed by its unique ingredient values.

Ingredient values can represent process inputs, parameters, and outputs. Process inputs typically represent raw materials and other inputs consumed in the batch process. Examples include the number of eggs consumed, amount of flour used, amount of energy consumed, possibly even work hours required or amount of traceable fixed costs consumed.

Another type of ingredient value is a process parameter. Process parameters identify operational settings such as furnace cooling time, an air pressure setpoint, or a Low pH alarm limit. Process parameters might also include identifications of specific equipment to be used during the batch process.

The third type of ingredient value is a process output. Such an ingredient value might represent the number of finished cookies expected from the batch, amount of byproduct expected, or a cost variance calculation based on the selected recipe.

Ingredient value quantities may be specified as constants or as equations based on other formula parameters such as batch size.

The second part of defining a recipe involves defining a recipe object in Lookout.

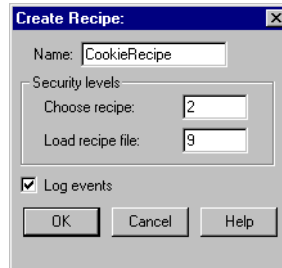


Figure 2-81. Recipe Definition Parameters Dialog Box

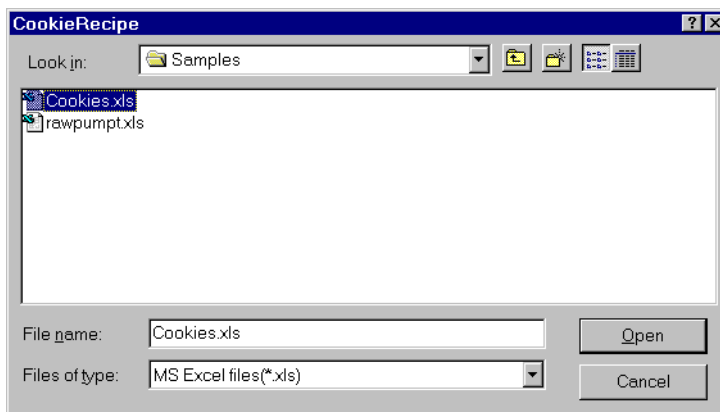
The first recipe dialog box defines security and event data logging.

Choose recipe security level specifies the minimum security level an operator must have to be able to select a recipe from all the recipes listed in the currently selected spreadsheet file.

Load recipe file security level specifies the minimum security level an operator must have to be able to select a different spreadsheet file.

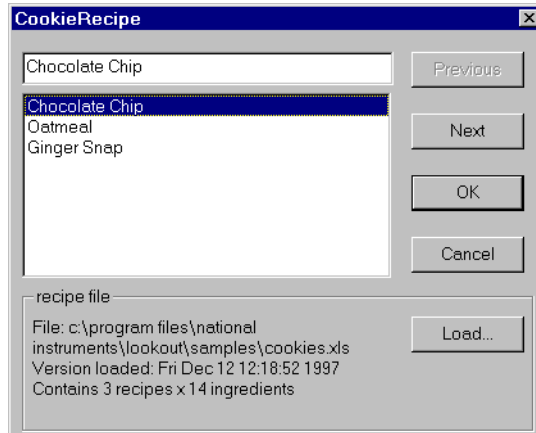
The **Log events** option creates a permanent audit trail for the object—who did what and when. Any selection of a different recipe or recipe file is logged to disk, including the time the action occurred and the operator’s account name. See Chapter 7, *Logging Data and Events*, in the *Lookout Developer’s Manual* for more information on logging events.

After defining security and event data logging, Lookout presents you with a file selection dialog box.



Select the `cookies.xls` spreadsheet file because it has the three batch recipes in it.

Once a file is selected, Lookout presents a list of recipes.



As you can see, the recipe names come from column A of the spreadsheet. You can use the **Previous** and **Next** buttons to identify a recipe from among the list, or type the name in the data entry field above the list. (This same dialog box appears later when an operator clicks on the pushbutton representing this object.) Click on **OK** to choose the recipe you want to use. Select the recipe for oatmeal cookies.

The recipe file **Load** button invokes the file list dialog box, described previously. Click on this button to select a new `.xls` file.



Note If the recipe is changed in the spreadsheet, the change is noted in the recipe file dialog box—but the values currently resident in the object data members remain intact. The operator must load the spreadsheet again to update the copy of the recipe file in Lookout. If you select a new `.xls` file to load but click on the Cancel button, it does *not* update! You must select **OK** for the recipe to actually be loaded.

After loading the spreadsheet, Lookout presents the display parameters box.

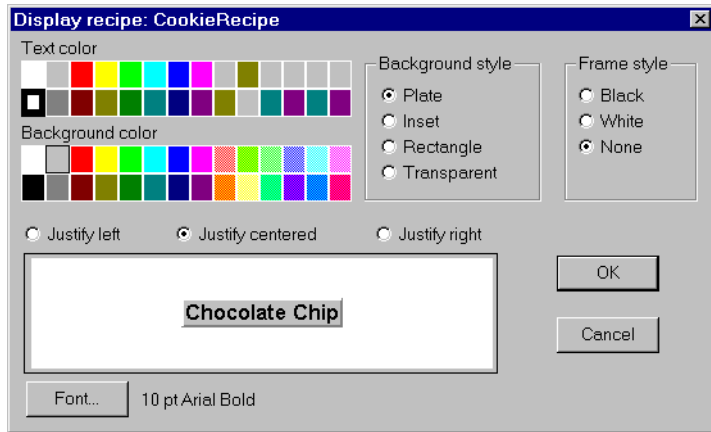
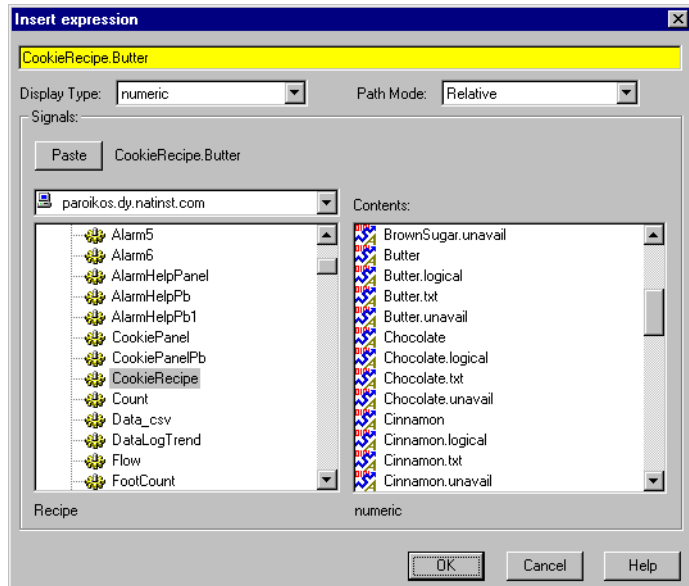


Figure 2-82. Recipe Object Display Parameters Box

After you choose the object display parameters, you can paste it into the panel.

When you select a new recipe, Lookout writes the ingredient values for the selected recipe into the corresponding data members of the object.

The actual number of data members that a recipe object has is based on the number of ingredients within it. This is best demonstrated by looking at the Insert Expression dialog box.



Notice that there are four data members for each defined ingredient. Actual data member names vary from object to object, depending upon your recipe ingredients. However, the four readable data member types for each ingredient are consistent.

Recipe Data Members

Table 2-51. Recipe Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|--|
| (implicit) | text | yes | no | Name of currently selected recipe |
| B – IV | numeric | yes | no | Each letter, B through IV, represents a column in the spreadsheet. The value of the data member is the numeric amount of the ingredient for the currently selected recipe. |

Table 2-51. Recipe Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|------------------------------|-------------|-------------|--------------|---|
| B.logical through IV.logical | logical | yes | no | Each letter, B through IV represents a column in the spreadsheet. Returns TRUE (ON) if the amount of the ingredient in the spreadsheet cell for the selected recipe is greater than zero. Returns FALSE if the specified amount for the ingredient is zero. |
| B.txt – IV.txt | text | yes | no | Each letter, B through IV represents a column in the spreadsheet. The value of the data member is the textual amount of the ingredient for the currently selected recipe. |
| B.unavail through IV.unavail | logical | yes | no | Each letter, B through IV represents a column in the spreadsheet. Returns TRUE if the spreadsheet cell is empty. Returns FALSE if the cell contains data. |
| pick1 through pick1000 | logical | no | yes | Upon transition from FALSE to TRUE, chooses the respective recipe within the spreadsheet. When used with pushbutton objects, these data members can eliminate the need for operators to use the recipe list dialog box. |

Comments The recipe object reads a block of continuous columns. Therefore, the ingredient names should be a contiguous list in Row 1. If a recipe does not use a particular ingredient, just leave the respective cell blank.

When Lookout encounters a blank cell in Column A, it ignores the entire row. Thus, you can easily annotate your recipes by leaving a cell in Column A blank and adding text to the cell in Column B of the same row.

Run

You can use Run objects to start an external program file from within Lookout. When the result of the **Run when** logical expression goes TRUE, the object executes the **Command line**.

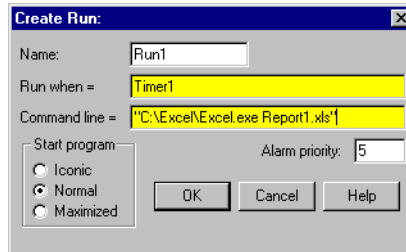


Figure 2-83. Run Definition Parameters Dialog Box

In this example, Lookout runs an Excel macro called `REPORT1.XLM` when the logical value returned by `Timer1` goes TRUE. `Timer1` is a `TimeOfDay` object that triggers the report to run every day at 8:00 a.m.

The **Command line** text expression must be enclosed in quotation marks as shown. Notice that the example includes the full path name of the executable file. Ensure that your command line meets DOS syntax requirements. Because this is an expression data field, the command could be the result of a text expression.

Passing arguments in the Run Object in Lookout requires proper use of double quotes depending on how many arguments you are passing and whether or not those arguments have spaces in the path.

If your argument has no spaces in the path, you need only insert double quotes before and after the argument.

If your argument has spaces in the path, you must insert two double quotes at the beginning and the end of that argument to define it as a single argument. These two double quotes are in addition to the double quotes you must use in passing any argument.

For example, when passing a single argument the following examples demonstrate the correct use of double quotes (spaces are exaggerated for effect):

```
""c:\my excel\autoexec.xls""
"c:\excel\excel.exe"
```

When passing two or more arguments, you follow the same rules for each argument, as illustrated in the following examples:

```
""c:\program files\msoffice\excel\excel.exe" c:\autoexec.xls"
""c:\program files\excel\excel.exe" ""c:\my excel\autoexec.xls""
"c:\excel\excel.exe c:\working\autoexec.xls"
```

You can specify how an application presents itself when you activate it with the **Start program** selections. If you select **Normal**, the application window appears in front of the open Lookout window when it is activated. If you want to reduce the application to an icon each time you start it, select **Iconic**. If you select **Maximized**, the application window replaces the Lookout window on the screen. (Lookout is still running; you just cannot see it. Press <Alt+Tab> to switch between applications.)

Table 2-52. Run Data Members

| Data Member | Type | Read | Write | Description |
|-------------|------|------|-------|------------------------------------|
| none | — | — | — | Run does not have any data members |

Comments If the application does not automatically shut down, multiple instances of the program may be running because of previous starts. Over time, this can snowball to the point where Windows performance is severely hampered.

If you want to execute DOS commands from within Lookout, put the commands in a DOS batch file (.bat) and then identify the batch file in the Command Line.

Sample

The Sample object samples and holds data. Any time the **Sample** expression transitions from OFF to ON and the **Enable** expression is TRUE, the Sample object samples and stores a **Data** expression. Sample maintains an array of up to 35 previous samples. If **Enable** is left blank it is assumed to be TRUE. **Data** is a numeric expression while **Sample** and **Enable** are logical.

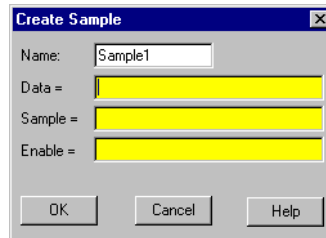


Figure 2-84. Sample Configuration Parameters Dialog Box



Note Sample does not have a display parameters dialog box. You can display the result of a Sample output signal by using its data member in an expression.

Sample Data Members

Table 2-53. Sample Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|--|
| (implicit) | numeric | yes | no | Current Data value—tracks Data input value. |
| 1 – 35 | numeric | yes | no | Previous samples. Signal 1 is the most recent sample since Sample went high. If you display Sample, you display the current and active value for the object—that is, the (implicit) value. If you display Sample.1, you display the least complete value. |
| DataReset | logical | no | yes | Upon transition from FALSE to TRUE, resets to zero all data members—including the current value and all previous samples. |

Comments The **Reset** expression can be a regular pulse interval created by a TimeOfxxxx timer. For example, if you want to sample the temperature every hour of the day, use the output signal from a TimeOfHour timer in the **Reset** expression to sample the temperature at the beginning of each hour.

Related Objects [Average](#), [Maximum](#), [Minimum](#), [SampleText](#)

SampleText

SampleText samples and stores the result of the **Data** expression any time the **Sample** expression transitions from OFF to ON and the **Enable** expression is TRUE. SampleText maintains an array of up to 35 previous samples. If **Enable** is left blank it is assumed to be TRUE.

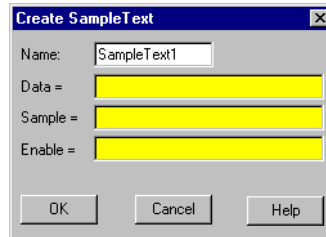


Figure 2-85. SampleText Definition Parameters Dialog Box

Data is a text expression while **Sample** and **Enable** are logical expressions.



Note SampleText does not have a display parameters dialog box. You can display the result of a Sample object output signal by using its data member in an expression.

SampleText Data Members

Table 2-54. SampleText Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|---|
| (implicit) | text | yes | no | Current Data value. Tracks Data input value. |
| 1 – 35 | text | yes | no | Previous samples. Signal 1 is the most recent sample since Sample went high. |
| DataReset | logical | no | yes | Upon transition from FALSE to TRUE, resets all data members—including the current value and all previous samples. |

Related Objects [Sample](#), [L3TextEntry](#), [TextEntry](#)

Scale

You can use the Scale object to create dynamic scales—that is, scales whose ranges and divisions can change based on numeric parameter expressions.



Note If you want to create a simple scale that does not change dynamically (which is normally the case), use the **Insert»Scale** command.

Figure 2-86. Scale Definition Parameters Dialog Box

Absolute Minimum and **Absolute Maximum** are numeric constants. They define the fullest possible range that the scale can show. These values act as clamps, restricting **Minimum** and **Maximum**.

Minimum and **Maximum** are numeric expressions you can use to change the minimum and maximum values on the scale. In the preceding example, the highest value of the scale (**Maximum**) is 400 if `Pot1` is less than 400, 1600 if `Pot1` is greater than 1600 (because of the **Absolute Maximum**), or equal to the value of `Pot1`.

Major unit specifies the number of units between major tick marks. **Minor unit** specifies the number of units between minor tick marks.

When you click on **OK**, the Display Scale dialog box appears.

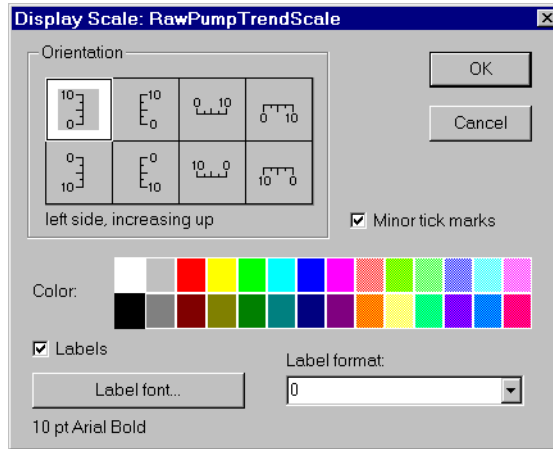


Figure 2-87. Scale Display Parameters Dialog Box

Specify **Orientation**, **Color**, **Label format**, and **Label font** as you choose.

You can remove minor tick marks by deselecting the **Minor tick marks** check box and you can remove label numbers from your scale altogether by deselecting the **Labels** check box. (Only major units have numeric labels.)

Scale Data Members

Table 2-55. Scale Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|--|
| visible | logical | no | yes | When TRUE, the Scale becomes visible on the control panel. When FALSE, it is invisible. The default value is TRUE. |

Comments Many people use this object class in conjunction with HyperTrends that are configured for a variable Y axis. They configure the **Minimum** and **Maximum** parameters of the Scale object to follow the same values as the **Max** and **Min** data members of the HyperTrend Object.

Sequencer

The Sequencer object is a method for cycling through a collection of up to 100 differently configured ON/OFF states for your process.

Each Sequencer state has 26 logical outputs. Outputs left blank are considered OFF.

You set each output to ON or OFF for each state. You can also create jumps to skip from one state to another, or activate immediate jumps to a designated state.

| State No. | Label | Time Limit (HH:MM:SS) | Outputs | | | | | | | | | | | | | | | | | | | | | | | | | |
|-----------|-------|-----------------------|---------|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| | | | A | B | C | D | E | F | G | H | I | J | K | L | M | N | O | P | Q | R | S | T | U | V | W | X | Y | Z |
| 1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

Figure 2-88. Sequencer Definition Parameters Dialog Box

The **States** field activates the states you want in your sequence loop. If you set **States** to 5, the sequence object will pass through states 1 through 5 and then return to state 1 to repeat the cycle.

Notice that unused states can still be configured. In this way you can preconfigure special states, create subroutines, and so on. See the [Programming the Sequencer](#) section for further information on using this object.

Use **Label** to label each state.

The **Time Limit** parameter determines how long the Sequencer holds each state. If you leave this parameter blank, the Sequencer halts on that state until a **Goto** or **Jump** is activated, or the **Time Limit** parameter is changed.



Note When you set the Time Limit expression to reference a Lookout control, you must make sure the output of that control is either in HH:MM:SS format, or in days.

Outputs are the ON/OFF settings for each state.

Programming the Sequencer

Left unmodified, the Sequencer cycles through the states selected in the **States** field of the **Sequencer parameter configuration** dialog box, beginning with state 1. If you enter 4 in the **States** field, the Sequencer will cycle through states 1—4 continuously, spending the amount of time in each state set by the **Time limit**.

Use the `Goto` data members to jump to a given state of the Sequencer immediately. Use the `Jump` data member to skip automatically from one state to a target state.

There is a tiny lag in state transition when you use the `Jump` data member. For instance, if you have a sequence cycling through states 1—8, and under some circumstances you want to skip states 5 and 6, moving directly from state 4 to state 7, set the `jump5.7` data member to `TRUE`. When the Sequencer reaches the end of the state 4 **Time limit**, it switches to state 5, and then immediately jumps to state 7. State 5 will be active for a brief period (about 10 ms), however, which you should take into account in designing your sequences.

You can use sequential jumps if you choose. When you activate a jump from state 1 to state 5, for example, and also a jump from state 5 to state 9, the Sequencer skips from state 1 to state 9 with a 10 ms delay at state 5.

If you use a `Jump` or `Goto` data member to activate a state outside the number you selected in your **States** field, the Sequencer will continue to cycle through any states following the target state, until it either reaches a state with no set **Time limit**, or state 100.

If the Sequencer reaches a state with no set **Time limit**, it remains in that state until a `Goto` or `Jump` is activated, or until the **Time Limit** parameter is changed.

If the Sequencer reaches state 100, and if state 100 has a **Time Limit** set, the Sequencer cycles to state 1 at the end of that time, resuming its cycle inside the states defined by the **States** parameter.

If you use a `Goto` or `Jump` data member to activate a state outside the ordinary cycle of a Sequencer object, you must use the `Jump` or `Goto` data members to return the sequence to its automatic cycle.

Sequencer Data Members

See the *Programming the Sequencer* section for detailed information on using Sequencer data members.

Table 2-56. Sequencer Data Members

| Data Member | Type | Read | Write | Description |
|-----------------------|---------|------|-------|--|
| A – Z | logical | yes | no | Sequencer outputs |
| Goto1 – Goto100 | logical | no | yes | When activated, forces Sequencer to go to the indicated state |
| Jump1.1 – Jump100.100 | logical | no | yes | When activated, jumps from the state indicated by the first number to the state indicated by the second number |
| StateName | text | yes | no | Reports the currently active state name (Label) |
| StateNumber | text | yes | no | Reports the sequence number (State No.) of the current state |
| Time | numeric | yes | no | Reports the current length of time the Sequencer has been in the current state |
| TimeLimit | numeric | yes | no | Reports the length of time set for the Sequencer to hold the current state |

Spinner

Spinner is a small, rotating disk. Its rotation speed can be variable, to represent the magnitude of a numeric **Signal**, or its rotation can be turned on or off based on the logical signal, **Spin**.

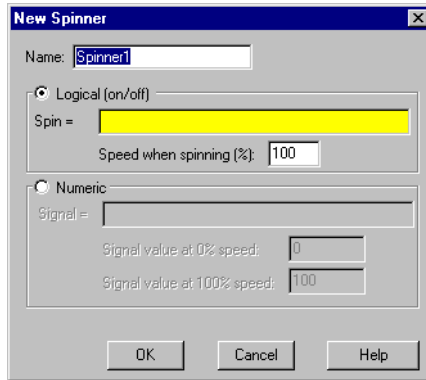


Figure 2-89. Spinner Definition Parameters Dialog Box

Logical (on/off) and **Numeric** choose whether the spinner responds to a logical signal or a numeric signal. Choose **Logical** if you want to be able to turn the spinner on and off. Choose **Numeric** if you want the speed and direction of the spinner to change depending on a numeric variable.

Spin is a logical expression. When the result of the logical expression is TRUE, the spinner rotates at the rate defined by the **Speed when spinning (%)** field. **Speed when spinning (%)** is a numeric constant, ranging from -100 to 100.

Connecting the spinner to a positive value rotates the spinner in a counterclockwise direction. A negative value rotates the spinner in a clockwise direction.

Signal is a numeric expression. The result of this expression dictates the spin speed based on the linear range defined by **Signal value at 0% speed** and **Signal value at 100% speed**.

Table 2-57. Spinner Data Members

| Data Members | Type | Read | Write | Description |
|--------------|------|------|-------|--|
| none | — | — | — | Spinner does not have any data members |

Comments Spinners are typically used to represent flow through a line or to show a motor running.



Spreadsheet

Spreadsheet permanently stores data to disk in spreadsheet files. You can log data on even and uneven intervals, when a data value changes, when an event occurs, or when any one of these things happen. Hence, you can implement complex logging criteria to meet almost any data storage need.

After each log, a new row is automatically added to the spreadsheet file. Lookout can log a new row of data approximately 10 times per second; however, the time stamps associated with each row are rounded to the nearest second.

Each spreadsheet file may store any number of data signals. Each data signal is assigned a spreadsheet column, beginning with column number two. The first column contains the date and time. The first row contains the expressions associated with the data in each column. You may create any number of Spreadsheet objects for a given process.

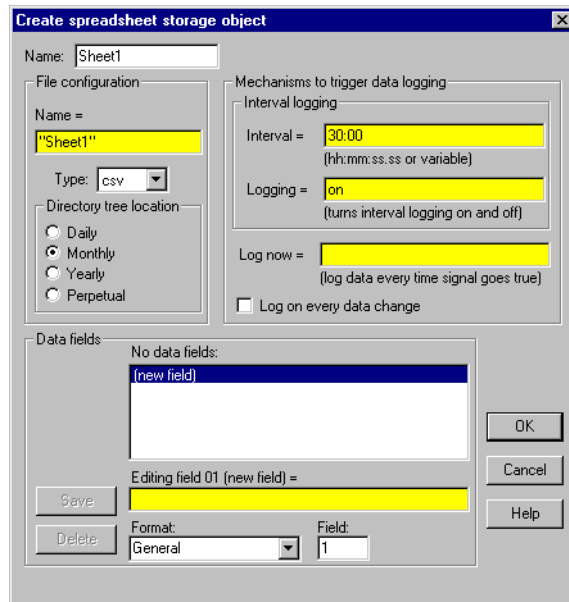


Figure 2-90. Spreadsheet Configuration Parameters Dialog Box

Name is the filename used to create a spreadsheet file. Lookout assigns a DOS filename to each spreadsheet file by adding the **Type** extension to the **Name**. Currently, Lookout supports only one **Type**: comma separated

value format (.csv). Most database and spreadsheet programs including Microsoft Excel directly read the .csv file format.

Because the **Name** parameter is a text expression field, you can create new .csv files with unique names dynamically. This is especially useful for recording batch processing data. The definition dialog box Figure 2-86 is configured so that an operator can enter a batch name using a TextEntry object before the batch is started. The text expression appends the filename to the specified path, C:\BATLOG\. So if the operator enters a file name like BATCH71, then the full path name would be C:\BATLOG\BATCH71.CSV. When the BatchRun logical signal goes TRUE, Lookout creates the new .csv file and begins writing to it. When BatchRun goes FALSE, logging ends, leaving a comprehensive log of all data associated with the batch.

This example forces Lookout to store the .csv file in a particular directory because it specifies a full path name. If you enter a relative pathname like "\BATLOG\" & TextEntry1, the file is located in that subdirectory of the identified **Directory tree location**. So, for example, the full path name of the file might be C:\LOOKOUT\1995\SEP\BATLOG\BATCH71.CSV.

If you enter just a filename such as "DATA", the file location is based on the Lookout directory. For example, the full path name of the file might be C:\LOOKOUT\1995\SEP\DATA.CSV.

If you select **Daily**, Lookout creates a new file and subdirectory every day in which to store the data. If you select **Monthly**, Lookout creates a new file and subdirectory every month in which to store the data. If you select **Yearly**, Lookout creates a new file and subdirectory every year. **Perpetual** files are stored in the root directory as specified by your **Data files location** parameter.

The following examples are the DOS filenames and directory trees created by Lookout for a spreadsheet file named, DATA.

| Daily | Yearly |
|---|--|
| c:\lookout\1993\sep\09\data.csv \sep\10\data.csv \sep\11\data.csv | c:\lookout\1993\data.csv \1994\data.csv \1995\data.csv |
| Monthly | Perpetual |
| c:\lookout\1993\sep\data.csv \oct\data.csv \nov\data.csv | c:\lookout\data.csv |

The **Mechanisms to trigger data logging** are a set of tools used to create a simple or complex logging scheme, as desired. Use these parameters to log data based on a timer, event, or any combination of the two. When the spreadsheet is triggered, all data in the Data fields is logged to disk.

Interval is a numeric expression used to create a Pulse timer with a pulse period of the specified time period and a pulse duration of zero. Normally this is a time formatted constant value such as 15:00 (fifteen minutes), for example.

Logging is a logical expression that turns the **Interval** parameter on and off. It could be a switch on a control panel, a logical input from an external device, or a more complex expression. Normally this is a constant value, ON or OFF.

Log now is a logical expression. When **Log now** transitions from OFF to ON, Lookout logs the data. A transition from ON to OFF has no effect. This expression could be a pushbutton on a control panel, a logical signal from a device, or a more complex expression.

The **Log on every data change** option should be used with care. When turned on, it triggers the logging of data any time any one of the data fields experiences a change. This is normally used to log the starting and stopping of pumps, opening and closing of valves, or other similar events. If your data fields contain even a single analog value that changes often, you could end up triggering the logger thousands of times. Or if they contain a logical value that changes frequently, you could have the same problem.

The **Data fields** window lists all expressions that have been entered for logging in the order of their field number.

The **Save** button saves your new or modified expression in the **Data fields** window along with a new field number if any. Normally, **Data fields** contain simple expressions like `PLC1.TankLevel`.

The **Delete** button deletes the currently selected expression from the data fields list.

The **Format** option specifies the numeric format assigned to the currently selected numeric expression when it is logged to disk. This has no effect on logical or text expressions.

Field indicates the number of the currently selected data field.



Note Field numbers should not be modified after data has been stored or the data will not appear under correct headers until a new file is created.

Spreadsheet Data Members

Table 2-58. Spreadsheet Data Members

| Data Members | Type | Read | Write | Description |
|---------------------|-------------|-------------|--------------|---|
| logged | logical | yes | no | Spreadsheet file update pulse. The Spreadsheet object generates this logical pulse with a pulse duration of zero after each successful log. |

SqlExec

SqlExec is an object Lookout uses to communicate with the ODBC driver. ODBC allows Lookout to connect to any database that supports ODBC.

SqlExec connects to ODBC using the standard ODBC calls, and queries the database using SQL statements. The data, if any, is returned in the object data members.

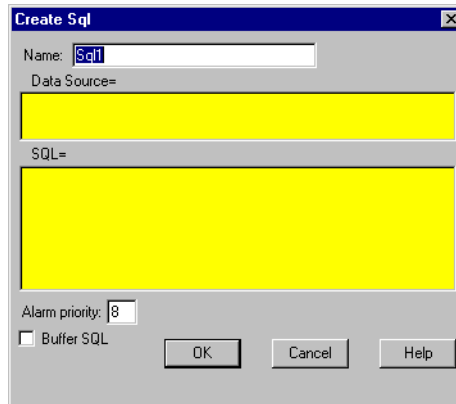


Figure 2-91. SqlExec Configuration Parameters Dialog Box

Data Source specifies the Data Source Name (DSN) as well as any other parameters needed by the ODBC driver to make the connection to the data source. For example if you want to connect to Excel 4.0, use:

```
"DSN=Excel Files; DBQ=C:\pathname;"
```

SQL is the SQL string you want to pass to the ODBC driver.

Alarm Priority determines the priority level of object-generated alarms.

Buffer SQL tells the SqlExec object to buffer any entries that fail for that object. An entry consists of the Data Source string and the SQL string. While Lookout does install a Lookout ODBC driver, you must manually create your own data source in order to access the Citadel database using ODBC. Consult Chapter 8, *Structured Query Language*, of the *Lookout Developer's Manual* for information on how to create your Lookout data source.



Note Some applications are not completely ODBC compliant. If you plan to use Microsoft Query, Microsoft Access, or Microsoft Visual Basic, ensure that the maximum column name length does not exceed 62 characters. These applications cannot handle longer names. Applications that are completely ODBC-compliant can handle names up to 126 characters long. All traces whose names exceed the maximum column name length are excluded from queries.

Because Lookout objects may include network path information in their names, and because you can arrange Lookout objects in hierarchies inside your processes, you may find it easy to exceed the 62 and 126 character limitations of ODBC. Consideration given to naming and organizing objects can minimize the risk of encountering this difficulty.

SqlExec Data Members

Table 2-59. SqlExec Data Members

| Data Member | Type | Read | Write | Description |
|-----------------------------|-------------|-------------|--------------|--|
| c1 – c65535 | numeric | yes | no | Value of the <i>n</i> th column in the row returned by ODBC. |
| c1.logical – c65535.logical | logical | yes | no | Value of the <i>n</i> th column in the row returned by ODBC. |
| c1.txt – c65535.txt | text | yes | no | Value of the <i>n</i> th column in the row returned by ODBC. |
| Execute | logical | no | yes | Executes the submitted SQL statement when it receives a change from low to high. |
| Failure | logical | yes | no | High if the last submitted query failed. |
| ReadOnly | logical | yes | yes | If TRUE, opens the file in read only mode. If FALSE, opens the file in read write mode. |
| Status | logical | yes | no | High when the object is processing a query. |

SqlExec Comments

The placement of the data in the data members is determined by the SQL string. If you submit the SQL string

```
"select Album, Artist, NumTracks from cdTable
where NumTracks>5"
```

the return value for Album is contained in the data member `c1.txt`, Artist in `c2.txt`, and NumTracks in `c3`. This value is displayed according to the data member you choose—Text, Logical, or Numeric. If you connect both to `c1` and `c1.txt`, you are connecting to the same value twice. In these circumstances, the value is represented in a different form.

A select statement only returns the first row that it encounters with the matching criteria. An update statement updates all the rows it encounters with the matching criteria.

If you connect your SqlExec object to a timer that pulses faster than several times per second, Lookout may become so busy handling SQL queries that it becomes unresponsive to user input from the mouse or keyboard.

Comma Separated Value (CSV) files are supported in ODBC. You can append data to them using the SQL insert command, but you cannot update records using the SQL update command. This is a limitation of the CSV file format.

- Excel files are accessible through ODBC, but they do have some unusual properties.
- If you use SqlExec to update an Excel 5.0 or greater workbook, the workbook must be closed and have multi-user editing turned off.
- If you are just trying to read from a workbook using a select query, then multi-user editing can be on, and the file can be opened or closed.
- If you try to access an Excel 5.0 or greater workbook while it is open and multi-user editing is off, Lookout locks up until the Excel file is closed. This is caused by a problem in the Excel ODBC driver.
- If you are using Excel 4.0 you can update or read from the worksheet only when it is closed. If you try to access an Excel 4.0 worksheet while it is open, you will receive an alarm in Lookout.

Citadel is also accessible through ODBC, but is opened exclusively in read-only mode to protect the integrity of the data.

The following table lists a few sample DSN and SQL strings for connecting to different types of databases through ODBC. Notice that they differ

slightly from database to database. Remember that **Data Source** and **SQL** are expressions. If you enter a string into the expression box, the string must be properly set off by quotes. The strings in the following table appear exactly as you would type them into Lookout.

| Database Type | Data Source String | SQL String |
|---------------|---|---|
| CSV | DSN=Text Files; DBQ= c:\ldev\ald2csv; | "select Priority, "Date & Time," "Description from alarm.csv where Priority = 4" |
| Excel 4.0 | DSN=Excel Files; DBQ= c:\ldev\ald2csv; | select Priority, "Date & Time," "Alarm Codes (Set:Reset:Acknowledge", "Description from alarm.xls alarm where Priority = 4" |
| Excel 5.0 | DSN=Excel Files; | "select Priority, "Date & Time," "Alarm Code (Set:Reset:Acknowledged), "Description from Table1 where Priority = 4" |
| MS Access | DSN=MS Access 7.0 Database; DBQ=c:\My Documents\compact.mdb; | "select Title, AlbumID, Length from tracks where TrackID = 7" |
| Citadel | DSN=Citadel 32-bit; | "select Interval, LocalTime, "Waves.Square" from Traces where Interval = 0:1 and LocalTime >" 2/14/97 14:34:30" |

SQL Command Buffering

The `SqlExec` object can create a buffer for SQL commands so that commands are not lost if the connection to the database is temporarily lost. Buffering stores failed commands in a file so that they can be resubmitted once the connection to the database is reestablished.

If you check the **Buffer SQL** checkbox in the Create SQL dialog box, the object buffers entries that fail for the following reasons.

- Unable to connect to data source: error code 08001.
- Connection in use: error code 08002.
- Communication link failure: error code 08S01.
- Drivers `SQLAllocEnv` failed: error code IM004.
- Drivers `SQLAllocConnect` Failed: error code IM005.
- Unable to load translation DLL: error code IM009.

Entries are not buffered for any other error codes. This is to prevent entries that always cause an error from being buffered, such as a syntax error in an SQL string.

You should only enable buffering for `SqlExec` objects that are inserting new data into a database, such as an SQL insert command.

When entries are being buffered, they are buffered according to the data source with which they are trying to connect. This prevents an `SqlExec` object being buffered for an Excel data source from blocking an `SqlExec` object connected to an MS Access data source.

Separating the buffers by data source also keeps entries from different `SqlExec` objects trying to connect to the same data source in their proper chronological order.

If an `SqlExec` object has to buffer data, it keeps the data in a directory called `dsndata` in your Lookout data directory. The data is kept in a `.csv` file, you can view in Excel. Do not try to view these files while Lookout is running.

Once an object starts buffering, it buffers all subsequent entries to that data source for all objects that have buffering turned on. Because of this, an entry with a syntax or other error that should not be buffered, can be buffered. If this occurs, the buffering system discards that entry after the entry is passed to ODBC and ODBC returns an error. You are not notified when the entry is discarded.

If an object has buffering turned off, and that data source is currently being buffered, then that entry bypasses the buffer entirely. It then either succeeds or fails according to the state of the connection to the data source.

If a data source has buffered data, the buffering system automatically tries to reconnect to the data source periodically. Once it connects, it clears the buffer by periodically de-queuing the first few entries and sending them to ODBC.

During buffering, the **Failure** data member has a slightly different meaning. If it is high, then the first entry in the buffer failed and was kept in the buffer. If it is low it means that the first entry in the buffer was successfully submitted to ODBC, and objects are still being buffered until the buffer can be cleared.

If you are creating and testing a process file, you may accumulate a large amount of buffered data in the `dsndata` directory. You can safely delete this directory when Lookout is *not* running. You will lose all the buffered data, but the SqlExec objects then loads with no errors or alarms.

SqlExec Status Messages

ODBC Environment not allocated. No buffering will occur

Indicates that memory could not be allocated for the connection to ODBC. This only occurs if your system is about to run out of memory. No buffering occurs if this alarm is set. Data that has already been buffered is not lost.

ODBC(32).DLL Not loaded

Indicates that the DLL could not be loaded. No buffering can occur if this alarm is set. Data that has already been buffered, is not lost.

Data Source Name: Objects are being buffered for this data source

This indicates which data sources are being buffered. Once the buffered entries have been cleared, the alarm ceases.

Incorrect data source string, check syntax

This means that the Data Source string is missing the `DSN=driver name;` pair.

SqlExec displays any error messages that it receives from ODBC as an alarm. If the error is an error that should cause buffering, the status message indicates whether the entry was buffered or not buffered. Each message

returned by ODBC belongs to the ODBC group. Some of the more common ODBC error messages are:

[Not Buffered] 37000/-3100: [Microsoft][*Driver Name*] Syntax error in query expression ‘...’

The SQL string has a syntax error in it.

[Not Buffered] S1000/-1811 [Microsoft][*Driver Name*] Couldn't find file '(unknown)'

This usually means that your data source expression is incorrect, or you have ODBC configured incorrectly for that data source expression, such as trying to connect to an Excel 5.0 workbook your ODBC Excel driver set up for Excel 4.0 worksheets. Check the data source expression and the configuration of the ODBC driver.

[Not Buffered] 42000/-1809 [Microsoft][*Driver Name*] can't update. Database or object is read-only.

The file has been opened in read-only mode, but you are trying to write to it. If you have the data member **ReadOnly** set to TRUE, set it to FALSE. For some drivers, you can specify in the ODBC administration tool that all files opened by that driver should be opened in read-only mode. Check the ODBC configuration if you have **ReadOnly** set to FALSE and are still getting this error. For some ODBC drivers (such as Citadel) the file is always opened in read-only mode to protect the integrity of the files.

Switch

Switch generates a logical signal for receipt by other objects. Switches change state when you click on them with a mouse button, trackball, touchscreen, or space bar on your keyboard.

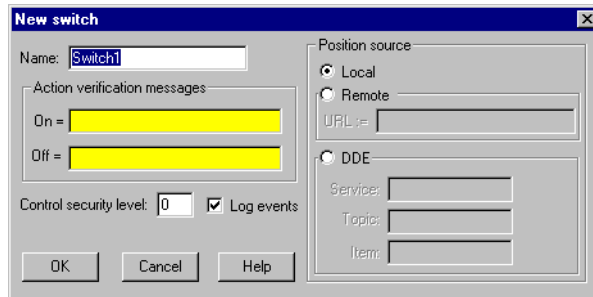


Figure 2-92. Switch Definition Parameters Dialog Box

Use **Action verification messages** to create dynamic text expressions to be displayed in message dialog boxes. See Chapter 6, *Security*, in the *Lookout Developer's Manual* for more information on security.

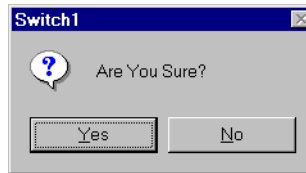


Figure 2-93. Verification Message Dialog Box

Position source determines where the value of the Switch resides. **Local** indicates the value of the Switch lies within the object itself—on the control panel. If the switch is up the signal is ON, if down the signal is OFF.

Remote Switches get their values from a remote source, often the register on a controller they are connected to. Flipping the Switch changes the status of the register, and changing the status of the register flips the switch.

The **Remote** option is especially useful when you want to prevent Lookout from changing the value of setpoints or registers upon initial startup, or reconnection of lost communication.

The **Remote** option calls for a URL to locate the data member you want to connect to. The URL field is green, and you cannot use a complex

expression as a URL. If you need to use one `RadioButton` for several purposes, you can use a Symbolic Link to make a more complex connection than that possible with a URL.

You can right-click in the **URL** field and use the **URL Editor** dialog box to assemble the URL, in the same way you use the Lookout expression editor.

A remote position source connection is completely reciprocal. A change in your Lookout control changes the data member that control is remoted to. Any change in that data member also changes the control. It is not necessary, and is incorrect, to use the **Edit Connections** dialog box to connect a control object to its controlled data member.

Because the remote connection is reciprocal, you can only make such a connection to a data member that is either writable, or readable and writable.

When a process with remoted controls first opens, those controls take their initial values by following the URL to read the data members they are remoted to. The control will be covered by a red X to indicate that the remote connection is not functioning.



Note You should use **Remote** to connect a control in a client process to a data member in a server process. Connections inside a single process can be made using **Object»Edit Connections**.

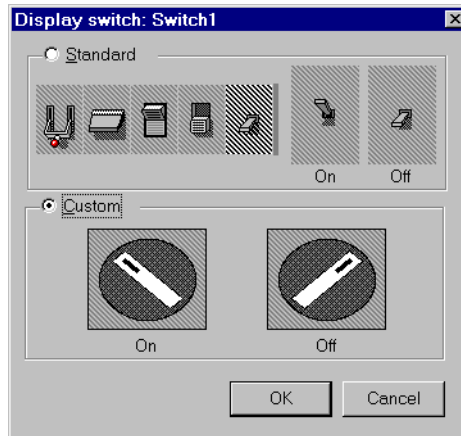
Because complex expressions are read-only values, you cannot remote directly to them. For the same reason, you cannot remote one control to another control's (`intrinsic`) data member (though you can remote a control to another control's value data member).

Much like Remote Switches, **DDE** (Dynamic Data Exchange) Switches get their values from a remote source. This could be a cell in a spreadsheet, another DDE aware application, or a second copy of Lookout running on the network. See Chapter 5, *Dynamic Data Exchange*, in the *Lookout Developer's Manual* for more information on **Service**, **Topic**, and **Item** parameters.

Control security level specifies the minimum security level operators must have to gain access to this individual object, and thus control it.

The **Log events** option creates a permanent audit trail for the object—who did what and when. All adjustments of the Switch are logged to disk, including the time the Switch was flipped, the operator's account name,

and the direction the Switch was flipped. See Chapter 7, *Logging Data and Events*, in the *Lookout Developer's Manual* for more information on event logging.



You can replace the standard switch types with custom graphic symbols. If you decide to use custom graphics, you must specify both symbol parameters, **On** and **Off**. See Chapter 2, *Graphics*, in the *Lookout Developer's Manual* for more information on creating custom graphic symbols and the use of transparent pixels.

Switch Data Members

Table 2-60. Switch Data Members

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|---|
| (implicit) | logical | yes | no | Switch Position |
| enable | logical | no | yes | If TRUE (the default), enables DDE. If FALSE, disables DDE. The default value is ON. This input is ignored for non-DDE TextEntry objects. |
| reset | logical | no | yes | While this value equals TRUE, the control will be set to the value in <code>resetvalue</code> . |
| resetvalue | numeric | no | yes | Sets the value a control will take when the reset data member transitions from FALSE to TRUE. |

Table 2-60. Switch Data Members (Continued)

| Data Members | Type | Read | Write | Description |
|---------------------|-------------|-------------|--------------|--|
| value | numeric | yes | yes | The current value of the control. If you have removed this control, then <code>value</code> is the current value of the position source. |
| visible | logical | no | yes | When FALSE, the switch object cannot be seen on the display panel. When TRUE, the Switch can be seen and controlled. |

Comments If a switch with more than two positions is needed, use a Pot object instead.

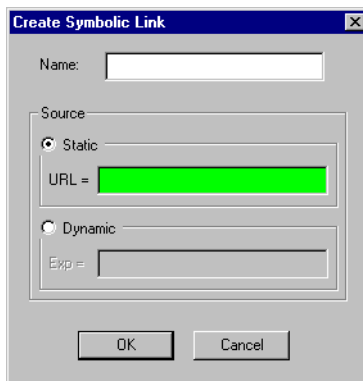
Related Objects [Pushbutton](#), [Pot](#)

Symbolic Links

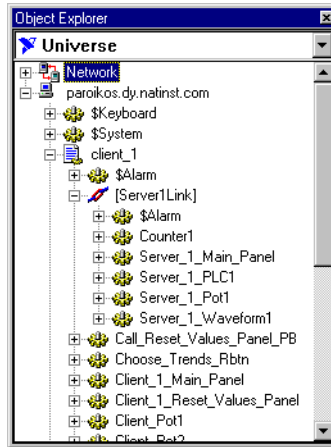
A Symbolic Link is a Lookout object you use to make certain kinds of remote connections easier and more efficient. This object can also be used to manage failover redundancy in Lookout 4. (Redundancy is not implemented in the Lookout 4 Preview.)

The Symbolic Link serves as a flexible intermediary between separate processes whether they are running on one computer or on different computers.

Create a Symbolic Link using the Lookout object browser. Right-click on the process or folder into which you want to insert the new Symbolic Link. The following dialog box appears.



The Symbolic Link can represent either a static or a dynamic source. The **Static** source is a URL pointing to a computer, process, folder, or object running in some instance of Lookout on your network. A typical Symbolic Link set to a process appears in the following illustration.



As you can see, all the objects in the `Server_1` process are represented in the Symbolic Link `[Link_to_Server1]`. You can drag and drop any of the objects or data members onto a panel in the process containing the Symbolic Link, where they will appear as expressions.

The **Dynamic** source must always be an expression that evaluates as a text string. When you select this option, you can use text strings and text variables to prepare the Symbolic Link to be used by a control for remote connections that cannot be made directly.

For example, you cannot use a complex expression in a Pot control remote source URL. You can, however, construct a complex expression as the dynamic source in a Symbolic Link, and then set the URL to connect to that Symbolic Link.

For instance, the following expression evaluates as two different URLs depending on the position of `Switch1` (line breaks inserted for clarity).

```
tif(Switch1,
    "\\.\server_1\Server_1_Waveform1.sinewave",
    "\\.\Server2\Server2_Waveform.sinewave")
```

If you connect a HyperTrend item to the Symbolic Link containing this dynamic source, changing the switch changes which server provides the wave form being plotted on the HyperTrend graph.

As another example, because Lookout data is now polymorphic, you can construct strings using both text and numeric inputs.

For example, if you create Pot1 with a **minimum** of 0, a **maximum** of 9, and an **interval** of 1, you can use the expression

```
"Modbus1.4001" & Pot1
```

as the entry for the **Dynamic** option in a Symbolic Link.

You can then use the Symbolic Link to connect a control to Modbus data members 40010–40019, depending on the setting of Pot1.

While you could not directly remote your control to that range of Modbus data members, you can make a remote connection from that control to the Symbolic Link using that dynamic expression.

If you connect the **Dynamic** expression to a data table, you have a nearly unlimited ability to have one object control a large number of data members, either through a cursor control or a radio button control.

\$System

\$System is a global object. It makes global Lookout data such as the currently logged in user name and security level available for use in your process. You can use \$System data members just like other object data members.

The **seclevel** data member is always an integer value between 1 and 10. This number represents the Lookout security level of the user currently logged in. For more information about Lookout security levels, see Chapter 6, *Security*, in the *Lookout Developer's Manual*.

The **time** data member represents the current date and time of the system. Like all time values in Lookout, this is a floating point number in which the integer represents the date and the fraction represents the time of day. You can use the various Lookout date and time numeric formats to view this value in the most convenient format. This data member updates itself every minute, on the minute. It also updates itself immediately after it is created or when its process is opened.

The **username** data member is the account name of the user currently logged in. For more information about Lookout security accounts, see Chapter 6, *Security*, in the *Lookout Developer's Manual*.

\$System Data Members

Table 2-61. \$System Data Members

| Data Member | Type | Read | Write | Description |
|---------------|---------|------|-------|--|
| NetworkStatus | text | yes | no | Reports the status of the last network transaction of your computer. You may need to use this data member in conjunction with a Sample object to keep track of high levels of network activity with many I/O points. |
| seclevel | numeric | yes | no | Security level of the user currently logged in |
| time | numeric | yes | no | Current operating system time |
| username | text | yes | no | Name of the user currently logged in |

TextEntry

With TextEntry you can manually enter textual notes with the keyboard. These notes may contain any combination of numeric and alphanumeric characters; however, the result of your entry is converted to a text value. Just like any other text expression in Lookout, your note can be logged to disk, connected to other data members that accept text signals, and so on. The note is saved and displayed as a single line entry—you cannot embed carriage returns into the message.

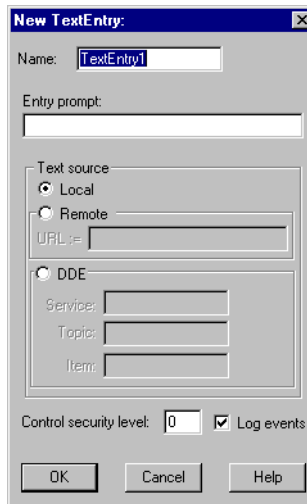


Figure 2-94. TextEntry Parameters Dialog Box

Entry prompt is the text that appears at the top of the text entry dialog box when an operator selects the text entry pushbutton.

Text source determines where the user-entered text resides. **Local** indicates the user-entered text lies within the object itself—on the control panel.

Remote indicates that the user-entered text resides in a remote source, such as a text expression or another TextEntry object.

The **Remote** option calls for a URL to locate the data member you want to connect to. The URL field is green, and you cannot use a complex expression as a URL. If you need to use one RadioButton for several purposes, you can use a Symbolic Link to make a more complex connection than that possible with a URL.

You can right-click in the **URL** field and use the **URL Editor** dialog box to assemble the URL, in the same way you use the Lookout expression editor.

A remote position source connection is completely reciprocal. A change in your Lookout control changes the data member that control is remoted to. Any change in that data member also changes the control. It is not necessary, and is incorrect, to use the **Edit Connections** dialog box to connect a control object to its controlled data member.

Because the remote connection is reciprocal, you can only make such a connection to a data member that is either writable, or readable and writable.

When a process with remoted controls first opens, those controls take their initial values by following the URL to read the data members they are remoted to. The control will be covered by a red X to indicate that the remote connection is not functioning.



Note You should use **Remote** to connect a control in a client process to a data member in a server process. Connections inside a single process can be made using **Object»Edit Connections**.

Because complex expressions are read-only values, you cannot remote directly to them. For the same reason, you cannot remote one control to another control's (intrinsic) data member (though you can remote a control to another control's value data member).

Much like **Remote** TextEntry objects, **DDE** TextEntry objects get their values from a remote source. This is the option you use to tie the text to a cell in a spreadsheet, a database lookup table, or any DDE aware application—including a second copy of Lookout running on the network. See Chapter 5, *Dynamic Data Exchange*, in the *Lookout Developer's Manual* for more detailed information on **Service**, **Topic** and **Item**.



Note The last DDE parameters used on any object automatically become the default values for any new DDE object.

Control security level specifies the minimum security level operators must have to gain access to this individual object, and thus control it.

The **Log events** option creates a permanent audit trail for the object—who did what and when. When selected, all text entries in this object are logged to disk. Each entry includes the time of the entry, the operator's account

name, and what entry was made. See Chapter 7, *Logging Data and Events*, in the *Lookout Developer's Manual* for more information on event logging.

Lookout presents the following display parameters dialog box after you define the object. It lets you define the text font and presentation style.

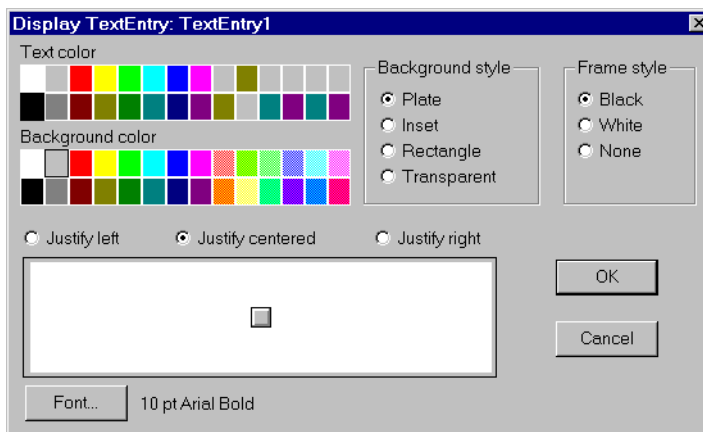


Figure 2-95. TextEntry Display Parameters Dialog Box

TextEntry Data Members

Table 2-62. TextEntry Data Members

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|---|
| (implicit) | text | yes | no | Current, user-entered text |
| enable | logical | no | yes | If TRUE (the default), enables DDE. If FALSE, disables DDE. The default value is ON. This input is ignored for non-DDE TextEntry objects. |
| reset | logical | no | yes | While this value equals TRUE, the control will be set to the value in resetvalue. |

Table 2-62. TextEntry Data Members

| | | | | |
|------------|---------|-----|-----|--|
| resetvalue | numeric | no | yes | Sets the value a control will take when the reset data member transitions from FALSE to TRUE. |
| value | numeric | yes | yes | The current value of the control. If you have removed this control, then <code>value</code> is the current value of the position source. |

TimeOfxxxx

TimeOfxxxx are timers that generate a periodic pulse of a specified duration. The timers are turned on and off by **On/off signal**. The time period is defined by the type of timer used—a TimeOfMinute timer has a one-minute period, a TimeOfYear timer has a one-year time period, and so on. The output of these timers goes high after the specified **Timer offset** has elapsed in the current period and remains high for the specified **Timer duration**.

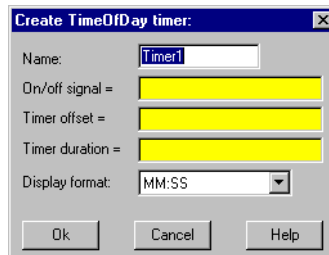


Figure 2-96. TimeOfDay Definition Parameters Dialog Box

The **Timer offset** and **Timer duration** can range from 0.0 seconds to a year, and the effective resolution is 0.01 seconds over the entire range. The **Timer offset** plus the **Timer duration** should always be less than or equal to the time period.

The object display shows the time remaining before the output changes state and is updated approximately once per second. It is shown in the selected **Display format**. If the **On/off signal** is OFF, the display shows OFF.

The **On/off signal** is a logical expression while **Timer offset** and **Timer duration** are numeric expressions. Normally, these are simple time constants such as 6:10:20 (six hours:ten minutes:twenty seconds). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, in the *Getting Started with Lookout* manual for more information on entering time constants.

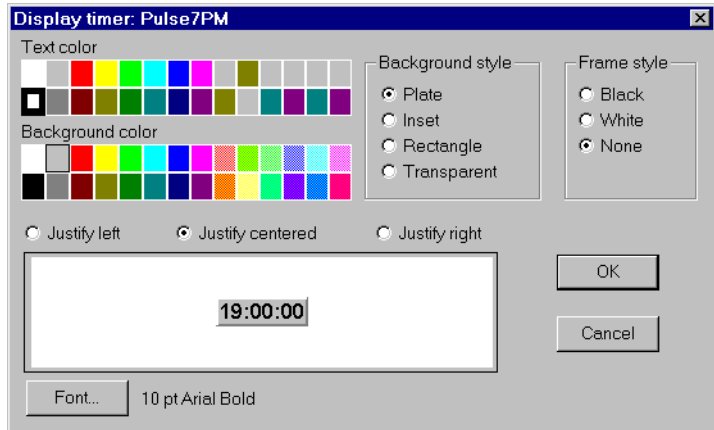


Figure 2-97. TimeOfDay Display Parameters Dialog Box

Timeofxxxx Data Members

Table 2-63. TimeOfxxxx Data Members

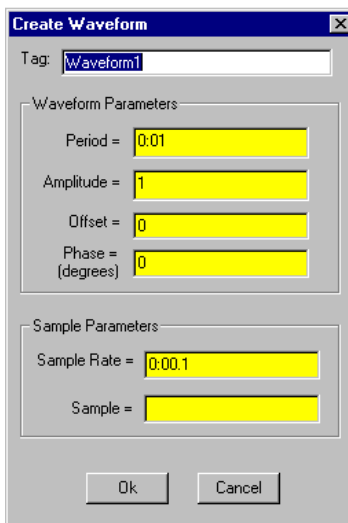
| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|---------------------|
| (implicit) | logical | yes | no | Logical timer value |

Comments TimeOfxxxx can be used in place of Pulse objects when the pulse needs to be synchronized with the clock—if a pump should only be allowed to run between the hours of 8:00 and 17:00 each day, the TimeOfDay timer should be used.

Related Objects [DelayOff](#), [DelayOn](#), [Interval](#), [OneShot](#), [Pot](#)

Waveform

The Waveform object generates cosine, sine, square, sawtooth, triangle, and random waveforms.



The Waveform object produces output by sampling the desired waveform at the specified **Sample Rate**. The **Period** (in days), **Amplitude**, **Offset** (level shift), and **Phase** (in degrees) of the generated waveforms can be set to any numerical expression. A single Waveform object can be used to generate multiple waveforms of varying relative phases, all with the same **Period**, **Amplitude**, **Offset** and absolute **Phase**.

Lookout samples a waveform when the logical expression **Sample** transitions from FALSE to TRUE. This can be a simple expression like the signal from a pushbutton, or it can be a complex algorithm.

Sample Rate is a numeric expression that determines how often to sample the waveform. Lookout converts the numeric value of **Sample Rate** into a time signal that represents days and fractions of a day. The Waveform object then samples the waveforms at the specified time interval. Normally, this will be a simple time constant such as 0:01 (one second).

When the **Period** of the waveform is changed, the waveform must be phase shifted so that there is a smooth transition to the new frequency. This is handled internally by the Waveform object and does not effect the **Phase** parameter.

As a result, multiple waveform objects will not be in phase with each other if one or more have had their **Periods** changed. To reset a waveform so that it will again be in phase with other waveforms, use the **Reset** connection. See *Waveform Comments* for a more detailed discussion of phase.

Each waveform output (except random) has 361 separate data members for generating waveforms of different relative phase shifts. For example, cosine0 (or just cosine) is a cosine wave of 0-degree relative phase shift, cosine90 is a cosine wave with +90 degrees relative phase shift, and cosine_90 is a cosine wave with -90 degrees relative phase shift.

Waveform Data Members

Table 2-64. Waveform Data Members

| Data Members | Type | Read | Write | Description |
|----------------------------|---------|------|-------|--|
| cosine_180 — cosine180 | numeric | yes | no | Cosine waveform output. |
| random | numeric | yes | no | Random waveform output. |
| Reset | logical | no | yes | Resets the phase shift to zero when transitioned from OFF to ON. (See comments on phase in Waveform Comments.) |
| Sample | logical | no | yes | When this transitions from false to true, the waveform is sampled. |
| SampleRate | numeric | no | yes | Specifies the rate at which the waveform will be automatically sampled. |
| saw_180 — saw180 | numeric | yes | no | Sawtooth waveform output. |
| sine_180 — sine180 | numeric | yes | no | Sine waveform output. |
| square_180 — square180 | numeric | yes | no | Square waveform output. |
| triangle_180 — triangle180 | numeric | yes | no | Triangle waveform output. |

Waveform Comments

A waveform is a function of time whose values repeat every period. The total phase shift of the waveform determines where, in its cycle, the waveform starts at time $t = 0$ (midnight on the morning of the January 1, 1900 for Lookout). Two waveforms that start at the same place in their

cycle at $t = 0$ (that is, same total phase shift) are said to be “in phase” with each other.

For a waveform generated by a Waveform object, the total phase shift is equal to the absolute phase shift as specified by the **Phase** parameter, and by the relative phase shift specified by the selection of a particular data member (for example, cosine 90). Because the phase is defined in terms of absolute time, two waveform objects with the same **Period** and **Phase** will generate waveforms that are in phase with each other.

However, if the **Period** of one of the waveforms is variable (for example, if it is connected to a Pot object) and changes, the absolute phase of the waveform will be changed. This additional phase shift is handled internally by the Waveform object, and is only noticeable by the fact that it can produce an undesirable phase shift between two Waveform objects that have the same **Period**. For this reason, you may want to use the **Reset** data member to reset this internal phase shift.



Note The **Phase** parameter is in degrees. A **Phase** of 180 degrees will shift the waveforms one half period ahead. For example if the **Period** is 1 day and the **Phase** is 180 degrees, then the shift will be one-half day.

$$\frac{\mathbf{Phase}}{360^\circ} \times \mathbf{Period} = \frac{180^\circ}{360^\circ} \times 1 \text{ day} = \frac{1}{2} \text{ day}$$

XBarR

The XBarR object class is one of the Lookout Statistical Process Control (SPC) tools and can play an important role in your Total Quality Management (TQM) program. This object class graphically displays an *X-Bar chart* and/or an *R chart* for a given signal. These control charts (also called mean and range charts, respectively) enable you to track your process to determine if it is about to go out of control and needs corrective attention.

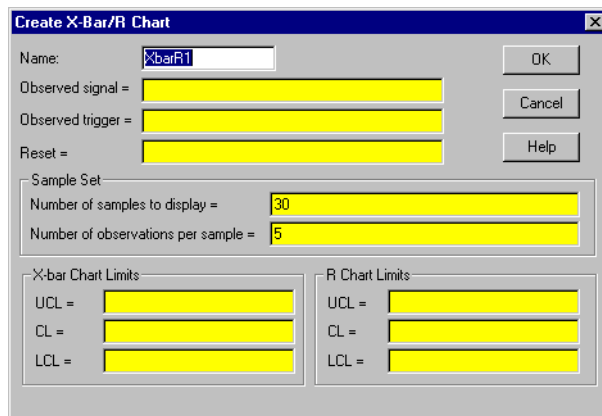


Figure 2-98. XBarR Definition Parameters Dialog Box

The XBarR object reads the **Observed signal** value any time the **Observed trigger** transitions from OFF to ON. When the object collects the specified **Number of observations per sample** (2 – 25), it calculates the mean and range and plots them on their respective charts. Each chart plots the specified **Number of samples to display**.

X-bar Chart limits and **R Chart limits** can be specified or calculated, as you choose. The object continually calculates chart limits based on new samples as they are accumulated. These calculated limits enable you to track your process for a time to determine limit settings that your process is capable of operating within. Once you know what limits your process can normally handle, you can specify the chart limit parameters by entering them directly.

LCL and **UCL** chart limits identify the lower and upper control limits. These outer limits generally define the range of process acceptability. **CL** identifies the *centerline*. For the X-bar chart, the centerline is the mean

of sample means. For the R chart, the centerline is the average of the sample ranges.

You can display X-bar charts and R charts in various colors with different label styles and grid spacing.

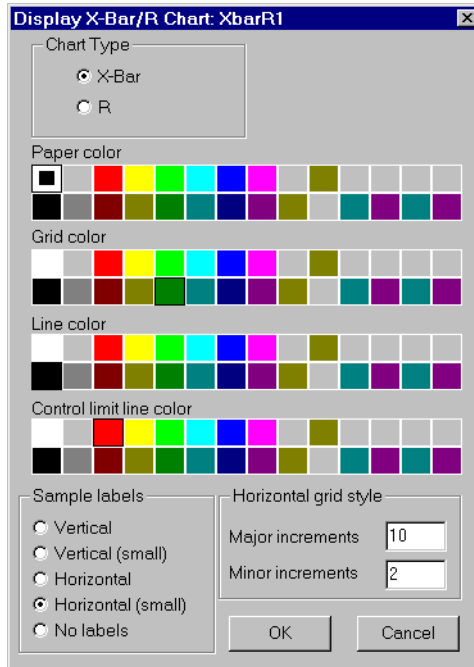


Figure 2-99. XBarR Display Parameters Dialog Box

When you enter the **LCL**, **UCL** and **CL** chart limit parameters for a chart, the entered values represent the limits shown on the chart. The following X-Bar Chart shows upper control limit, center line, and lower control limit entered as constants. The chart shows that the majority of the last 30 samples are running a bit under the centerline, suggesting that the process may need to be adjusted. The calculated control limits, shown below the graph, indicate new limits that might be used based on the current plotted samples.

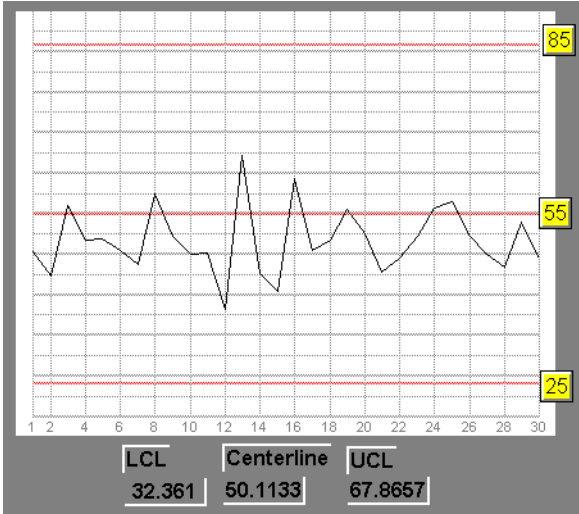


Figure 2-100. X-Bar Chart Showing Upper Control Limit, Center Line, and Lower Control Limits

If you leave one or more of the limit parameters blank for a chart in the definition parameters dialog box, the chart shows its *calculated* limits. As you can see in the following R chart, the calculated limits and the plotted limits are the same.

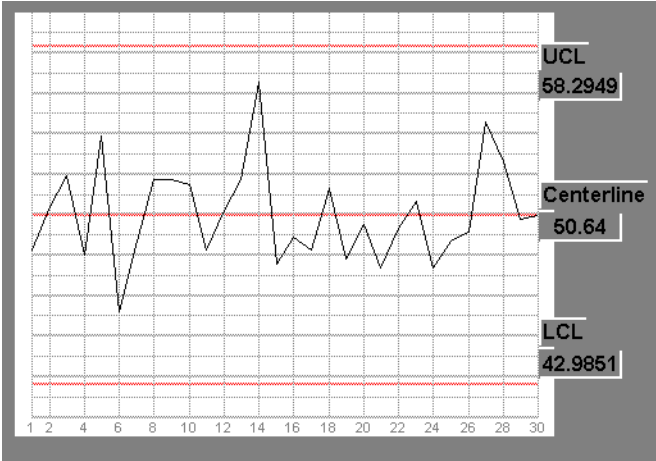


Figure 2-101. R Chart Showing Upper Control Limit, Center Line, and Lower Control Limits as Calculated Based on Plotted Samples

XBarR Data Members

Table 2-65. XBarR Data Members

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|--|
| R_ChartMax | numeric | yes | no | Identifies the top of the Range chart graph (the value of the plotted line when it is at 100 percent of the Y axis). The object recalculates this value as each new sample is read to ensure that the plotted line is always visible on the graph. |
| R_ChartMin | numeric | yes | no | Identifies the bottom of the Range chart graph (the value of the plotted line when it is at zero percent of the Y axis). The object recalculates this value as each new sample is read to ensure that the plotted line is always visible on the graph. |
| R_CL | numeric | yes | no | Centerline of range chart showing average of sample ranges calculated as follows: $\bar{R} = \frac{\sum_{i=1}^n R_i}{n}$ |
| R_LCL | numeric | yes | no | Lower control limit of Range chart, calculated using the sampled data as follows: $LCL = D_3 \bar{R}$ <p>where D_3 is from any standard 3-sigma control factors table</p> |
| R_Sample | numeric | yes | no | Calculated range, R , of the last completed sample of observations, defined as the difference between the maximum and minimum observations in the sample. |

Table 2-65. XBarR Data Members (Continued)

| Data Members | Type | Read | Write | Description |
|---------------|---------|------|-------|--|
| R_UCL | numeric | yes | no | Upper control limit of Range chart, calculated using the sampled data as follows: $UCL = D_4 \bar{R}$ where D_4 is from any standard 3-sigma control factors table |
| Visible | logical | yes | yes | When TRUE, the X-bar and R charts become visible on the control panel. When FALSE, they are invisible. The default value is TRUE. |
| Xbar_ChartMax | numeric | yes | no | Identifies the top of the X-bar chart graph (the value of the plotted line if it is at 100 percent of the Y axis). The object recalculates this value as each new sample is read to ensure that the plotted line is always visible on the graph. |
| Xbar_ChartMin | numeric | yes | no | Identifies the bottom of the X-bar chart graph (the value of the plotted line if it is at zero percent of the Y axis). The object recalculates this value as each new sample is read to ensure that the plotted line is always visible on the graph. |
| Xbar_CL | numeric | yes | no | Centerline of X-bar chart showing the mean of sample means, calculated as follows: $\bar{\bar{x}} = \frac{\sum_{i=1}^n \bar{x}_i}{n}$ |

Table 2-65. XBarR Data Members (Continued)

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|--|
| Xbar_LCL | numeric | yes | no | Lower control limit of X-bar chart, calculated as follows: $LCL = \bar{\bar{x}} - A_2 \bar{R}$ where A_2 is from any standard 3-sigma control factors table |
| Xbar_Sample | numeric | yes | no | Calculated mean of the last completed sample of observations, where $\bar{x} = \frac{\sum_{i=1}^n x_i}{n}$ |
| Xbar_UCL | numeric | yes | no | Upper control limit of X-bar chart, calculated as follows: $UCL = \bar{\bar{x}} + A_2 \bar{R}$ where A_2 is from any standard 3-sigma control factors table |

Related Objects *Average, Histogram, Maximum, Minimum, Sample*

Related Functions Avg, Max, Min, Stdev, Stdevp, Sum, Var, Varp
 Refer to the *Lookout Developer's Manual* for more information.

XChart

The XChart object class graphically plots the value of an observed signal on a chart in response to a trigger signal.

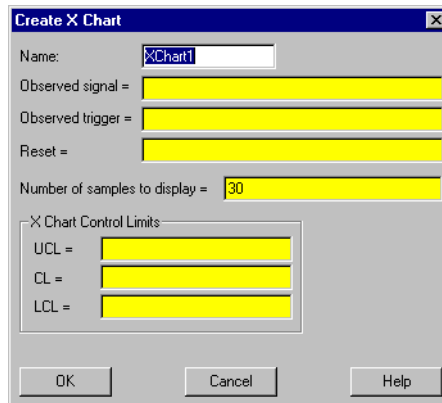


Figure 2-102. XChart Definition Parameters Dialog Box

The XChart object reads the value of the **Observed signal** any time the **Observed Trigger** transitions from OFF to ON.

Xchart plots the specified **Number of samples to display**. When it reaches the limit set by that parameter, it removes the oldest point before plotting the newest one. **Number of samples to display** must be between 2-4000. All the points on the chart are cleared any time **Reset** transitions from OFF to ON.

XChart Control Limits can be specified or calculated as you choose. If you leave the values in this section of the dialog box open, the object continually calculates chart limits based on new values as they are accumulated. You can watch your process for a time with XChart calculating limits to determine the ranges of normal operation, and then you can set the chart limits directly. Once set, XChart displays limit lines at the specified settings.

UCL and **LCL** identify the upper and lower control limit lines. **CL** defines the centerline.

You can display Xcharts in various colors and styles with different vertical and horizontal grid spacing.



Figure 2-103. XChart Display Parameters Dialog Box

XChart Data Members

Table 2-66. XChart Data Members

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|---|
| ChartMax | numeric | yes | no | Identifies the top of the chart graph (the value of the plotted line when it is at 100 percent of the Y axis) |
| ChartMin | numeric | yes | no | Identifies the bottom of the chart graph (the value of the plotted line when it is at zero percent of the Y axis) |

Table 2-66. XChart Data Members (Continued)

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|--|
| CL | numeric | yes | no | Centerline of the chart, showing the mean of the sample, calculated by the formula: $CL = \frac{\sum_{i=1}^n x_i}{n}$ |
| LCL | numeric | yes | no | Lower control limit of the chart (3 standard deviations below CL), calculated by the formula: $LCL = CL - 3 \sqrt{\frac{\sum_{i=1}^n (x_i)^2 - \frac{\left(\sum_{i=1}^n x_i\right)^2}{n}}{n-1}}$ |
| Sample | numeric | yes | no | Value of the last sample recorded |

Table 2-66. XChart Data Members (Continued)

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|--|
| UCL | numeric | yes | no | <p>Upper control limit of chart. When calculated, is drawn 3 standard deviations above CL, using the following formula:</p> $UCL = CL + 3 \sqrt{\frac{\sum_{i=1}^n (x_i)^2 - \frac{\left(\sum_{i=1}^n x_i\right)^2}{n}}{n-1}}$ |
| Visible | logical | yes | yes | <p>When TRUE, XChart become visible on the control panel. When FALSE, XChart is invisible. The default value is TRUE.</p> |

XYChart

The XYChart object class graphically plots X and Y points on a chart in response to a trigger signal.

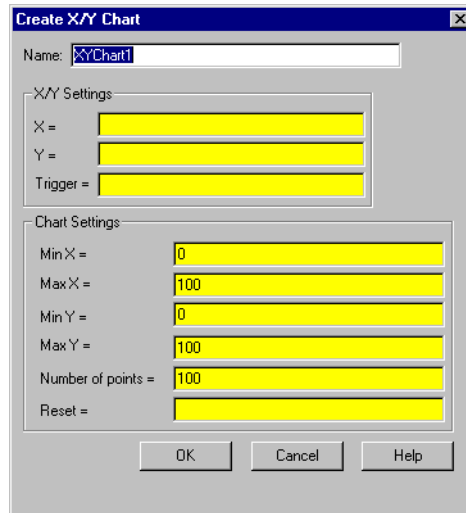


Figure 2-104. XYChart Definition Parameters Dialog Box

The XYChart object reads the value of the **X** and **Y** signals any time **Trigger** transitions from OFF to ON and plots the corresponding X/Y point on the chart in relation to the chart ranges **Min X**, **Max X**, **Min Y**, and **Max Y**.

XYChart plots the specified **Number of points**. When it reaches that limit, it removes the oldest point before plotting the newest one. **Number of points** must be between 2-4000. All the points on the chart are cleared any time **Reset** transitions from OFF to ON.

You can display X/Y charts in various colors and styles with different vertical and horizontal grid spacing.

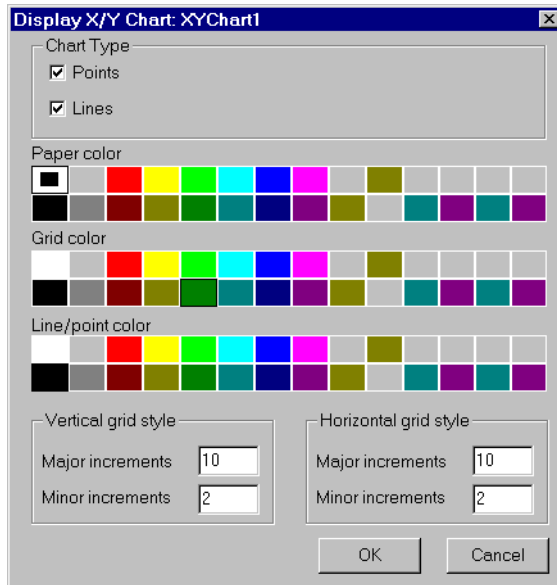


Figure 2-105. XYChart Display Parameters Dialog Box

XYChart Data Members

Table 2-67. XYChart Data Members

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|---|
| ChartXMax | numeric | yes | no | Identifies the right most point of the chart graph (the value of the plotted line when it is at 100 percent of the X axis). |
| ChartXMin | numeric | yes | no | Identifies the left most point of the chart graph (the value of the plotted line when it is at zero percent of the X axis). |
| ChartYMax | numeric | yes | no | Identifies the top of the chart graph (the value of the plotted line when it is at 100 percent of the Y axis). |

Table 2-67. XYChart Data Members (Continued)

| Data Members | Type | Read | Write | Description |
|---------------------|-------------|-------------|--------------|--|
| ChartYMin | numeric | yes | no | Identifies the bottom of the chart graph (the value of the plotted line when it is at zero percent of the Y axis). |
| Visible | logical | yes | yes | When TRUE, X/Y chart become visible on the control panel. When FALSE, it is invisible. The default value is TRUE. |

Lookout Driver and Protocol Objects

This chapter describes Lookout Driver and protocol object classes, listed in alphabetical order. Input parameter syntax and data members are documented for each object class, along with a description of the functionality of each object class.

AB_PLC2, AB_PLC5, AB_SLC500

Lookout uses the AB object classes to communicate with the Allen-Bradley family of PLC controllers using a variety of interfaces.

Lookout can communicate with a member of the PLC-2 family in the following ways:

- Through a Data Highway Plus (DH+) connection to an Allen-Bradley 1785-KA3 PLC-2 adapter module using an Allen-Bradley 1784-KT, 1784-KTx, or 1784-PCMK card, or an S-S Technologies 5136-SD direct-link interface card installed in the computer,
- Through the serial port using an Allen-Bradley KF2 module (which converts serial DF1 to DH+) to an Allen-Bradley 1785-KA3 PLC-2 adapter module, or
- Through a direct DF1 serial connection to the PLC programming port.

Lookout can communicate with a member of the PLC-5 family in the following ways:

- Through a direct Ethernet connection to the PLC AUI port,
- Through a direct DH+ connection using a 1784-KT, 1784-KTx, 1784-PCMK, or 5136-SD card installed in the computer,
- Through the serial port via a KF2 module which converts serial DF1 to DH+, or
- Through a direct DF1 serial connection to the PLC programming port.

Lookout can communicate with a member of the SLC-500 family in the following ways:

- Through a direct DH+ connection using a 1784-KT, 1784-KTx, 1784-PCMK, or 5136-SD card installed in the computer,
- Through the serial port via a KF2 module which converts serial DF1 to DH+,
- Through the serial port using an Allen-Bradley 1747-KE card (which plugs into the SLC chassis and converts DF1 to DH 485),
- Through the serial port using a stand-alone Allen-Bradley 1770-KF3 communication interface module which converts DF1 to DH 485,

- Through a direct DF1 serial connection to a SLC 5/03 or SLC 5/04 programming port, or
- Through a direct DH485 connection using a 1784-PCMk card in conjunction with either a 1747-AIC or 1761-NET-AIC module.

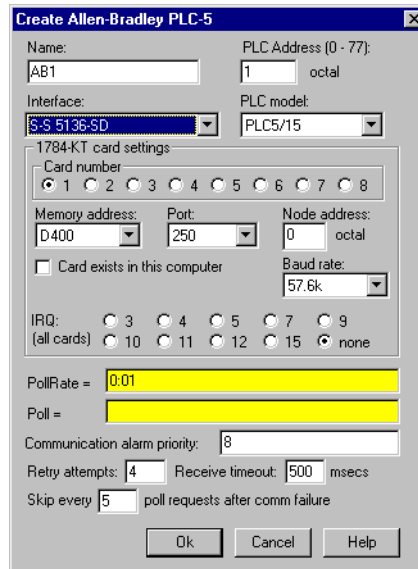


Figure 3-1. Allen-Bradley Parameter Dialog Box

PLC Address refers to the PLC network node address setting as configured on the physical device. If devices share a common **Interface**, they require unique addresses. When using DF1 protocol (serial communications), valid addresses range from 0 to 254 decimal. When using DH+, valid addresses range from 0 to 77 octal.

PLC Model specifies the particular type of PLC or SLC you are representing with this object. The **PLC Model** you select determines what native data members comprise the object.

PollRate is a numeric expression that determines how often to poll the device. Lookout polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Poll is a logical expression. When this expression changes from false to true, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of the alarms generated by the AB object.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the object generates an alarm and begins to **Skip every *n* poll requests after comm failure**. Once Lookout reestablishes communications, it polls the device on its regular cycle, as defined by **PollRate**.

Receive timeout is the time delay Lookout waits for a response from a device before retrying the poll request.

Interface identifies the type of communication hardware you are using. The selection you make here determines what protocol parameters you have to specify. The paragraphs that follow describe interface-specific protocol parameters.

Allen-Bradley Serial Port Interface Parameters

The `KE/KF/Serial` **Interface** selection enables serial port communication via a KE card, a KF3 module or KF2 module. When using your serial port, Lookout employs the Allen-Bradley full-duplex (peer-to-peer) DF1 protocol. Figure 3-1 shows an Allen Bradley object configured for serial communications.

Serial port specifies which RS-232C port the object uses for communication to the physical device.

Data rate, Parity, and Error detection reference the settings on the hardware device. The AB object classes support both *BCC* (block check character) and *CRC* (cyclic redundancy check) error detection. *BCC* provides a medium level of data security. *CRC* ensures a higher level of data security. Choose the settings as configured on your PLC or SLC.

Phone number specifies the number to be dialed if the serial port setting is configured for dial-up. This number only applies to the individual object.

Allen-Bradley DH+ Interface Parameters



Note When you configure an AB_PLC2, AB_PLC5, or AB_SLC500 for DH+, Lookout creates a file called ALLBRAD.INI. This file contains the configuration settings that you enter for your KT card(s). If you plan to run the process file on a Lookout Runtime System, be sure to copy the INI file along with your process (.1kp) file to the target computer.

The 1784-KT, 1784-KTx, 1784-PCMK, and S-S 5136-SD **Interface** selections enable direct connection of your computer to a DH+ network. The following illustration shows an AB_SLC500 configured for DH+ communications using a 1784-KTx card.

Figure 3-2. AB_SLC-500 Definition Parameters Dialog Box Configured for DH+ Communications

Card number selects which network interface card that the PLC is connected to in case your computer has multiple KT or S-S cards.

Card DH+ node address identifies the address of the interface card in the DH+ network. Valid addresses range from 0 to 77 octal. The node address of the card must be unique—that is, it must not be the same as the address of any other device on the DH+ network.

Memory address specifies the base address location of the selected interface card memory. Your selection should match the settings on the card. If you are using multiple interface cards, be sure each card has a unique address. The network interface cards use dual-ported memory. For this reason, if you are using a memory manager such as EMM386 it is important to add a memory exclusion statement to your `CONFIG.SYS` file. The table on the following page lists base memory address selections and corresponding exclusions for all legal memory addresses for the 1784-KT card.

Use **Max node address** to maximize the performance of a DH485 network by assigning addresses to nodes on the network using consecutive numbers starting with zero. Set the **Max node address** to the maximum of the assigned node addresses. By default, the value of this variable is 31, which is the largest legal address for any node on a DH485 network.

The 1784-KT interface card has on-board network termination resistors. If you are using such a card and if your computer is the last node on the network and if the cable does not already have a terminating resistor on it, then select the **Enable link termination resistor** check box.

Use the **Card exists in this computer** check box to instruct Lookout whether or not to look for the interface card in the computer. *Be sure to check this box when you are ready to start polling your PLCs.* When you check this box and select **OK**, Lookout initializes the card, activates its self-test, and downloads its driver firmware. Then polling begins. Leave the **Card exists in this computer** check box deselected (this is the default setting) if the card is not in your computer (for example, if you are developing a process on a computer different from the one that will be running the process) or if you do not want to poll any PLC connected to the card.

If you deselect the **Card exists in this computer** check box, you are disabling communications using this interface card with all PLCs connected to it.

Table 3-1. Allen-Bradley DH+ Interface Memory Addresses

| Memory Address | AB 1784-KT Exclude | AB 1784-KTx 1784-PCMk Exclude | SS-5136-SD Exclude* | Recommendation |
|--|--------------------|-------------------------------------|------------------------|---|
| A000 | A300-A3FF | A000-A0FF | A000-A3FF | Typically used by VGA drivers. Use if no other option is available. |
| A400 | A700-A7FF | A400-A4FF | A400-A7FF | |
| A800 | AB00-ABFF | A800-A8FF | A800-ABFF | |
| AC00 | AF00-AFFF | AC00-ACFF | AC00-AFFF | |
| B000 | B300-B3FF | B000-B0FF | B000-B3FF | Used by MDA & CGA drivers. Use if no Dxxx option is available. |
| B400 | B700-B7FF | B400-B4FF | B400-B7FF | |
| B800 | BB00-BBFF | B800-B8FF | B800-BBFF | |
| BC00 | BF00-BFFF | BC00-BCFF | BC00-BFFF | |
| C000 | C300-C3FF | C000-C0FF | C000-C3FF | Typically used by BIOS. Use if no Dxxx option is available. |
| C400 | C700-C7FF | C400-C4FF | C400-C7FF | |
| C800 | CB00-CBFF | C800-C8FF | C800-CBFF | |
| CC00 | CF00-CFFF | CC00-CCFF | CC00-CFFF | |
| D000 | D300-D3FF | D000-D0FF | D000-D3FF | Normally available. Try to use one of these first. |
| D400 | D700-D7FF | D400-D4FF | D400-D7FF | |
| D800 | DB00-DBFF | D800-D8FF | D800-DBFF | |
| DC00 | DF00-DFFF | DC00-DCFF | DC00-DFFF | |
| * The 5136-SD memory exclusions recommended here are based on 16K memory mapping. Because you are using the SS card to emulate the KT card, there is no advantage to using its 32K memory access capability. | | | | |

Baud rate (1784-KTx, 1784-PCMk, 5136-SD only) selects the baud rate of the DH+ network. The default is 57.6k baud. Before selecting a higher baud rate, be aware of that only a few PLCs (such as the SLC5/04) support higher baud rates; that every node on a DH+ network must support the baud rate used on that network; that the maximum network cable length is smaller for higher baud rates; and that the correct values for the termination resistors at the ends of the network cable are different for higher baud rates. Consult the manuals that came with your hardware for more detailed information.

IRQ (all cards) identifies the interrupt setting of all DH+ interface cards installed in the computer. This selection should match the IRQ settings on *all* of the interface cards.

Assigning an interrupt to the interface card(s) improves overall computer performance somewhat. Any time one of the cards receives an input, it generates an interrupt recognized by Lookout.



Caution Be sure to verify that no other drivers or cards are mapped to the selected memory address or use the same interrupt.

Allen-Bradley Ethernet Interface Parameters

The Ethernet **Interface** selection enables direct communication between your computer and a PLC using a standard Ethernet network. The following diagram shows an AB_PLC5 configured for Ethernet communications.

Figure 3-3. AB_PLC5 Definition Parameters Dialog Box Configured for Ethernet Communications

IP address specifies the Internet protocol address of the PLC. An Internet protocol address consists of four numbers, separated by periods. Each number ranges from zero to 255 decimal. Thus, a typical Internet address might be 128.7.9.231. Ensure that the **IP address** you enter matches the

Internet protocol address of the PLC your object represents. You can also enter the IP address by name.

Using the 5136-SD card from S-S Technologies, Inc.

To use the 5136-SD card, select the S-S 5136-SD interface in the **Create Object** dialog box. It is not necessary to run the `sdinst.exe` program that ships with the card because Lookout downloads the KT-emulation module automatically as part of the initialization process. It is, however, necessary to tell Lookout the port address specified by the switch settings on the card.

Figure 3-4. AB_PLC5 Definition Parameters Dialog Box Configured for the 5136-SD card

Allen-Bradley Register Addressing

Lookout has adopted a sequential, flat addressing scheme for the Allen-Bradley PLCs. The addresses are sequential by data type, having nothing to do with the actual slot number. For example, consider the following slot configuration:

| PLC slot Location | Type of Module in PLC Slot | Channel Address in Lookout |
|-------------------|-----------------------------------|----------------------------|
| slot 1 | 16 channel analog input | I:0-I:16 |
| slot 2 | 16 channel analog output | O:0-O:16 |
| slot 3 | 8 channel input, 8 channel output | I:17-I:24, O:17-O:24 |
| slot 4 | 16 channel analog input | I:25-I:32 |

You can see from the example, the slot number of the module is irrelevant to Lookout, and the input channels follow consecutive numbers as the output channels follow their own consecutive numbers.

Allen-Bradley Data Members

Each AB object contains a great deal of data. All readable and writable members (inputs/outputs) are bundled with the object. As soon as you create an AB object you immediately have access to all the object data members.

The AB object classes automatically generate an efficient read/write blocking scheme based on the inputs and outputs you are using in your process file. You are not required to build your own I/O blocking table. However, you can ensure peak performance by organizing your PLC data into contiguous groups.

Table 3-2. AB_PLC2 Data Members

| Data Member | Type | Read | Write | Description |
|---------------|---------|------|-------|---|
| 0 - 7777 | numeric | yes | yes | 16-bit signed binary word ranging from -32,768 to +32,767 |
| 0_0 - 7777_17 | logical | yes | no | One bit within a 16-bit binary word |
| CommFail | logical | yes | no | Object-generated signal that is ON if, for any reason, Lookout cannot communicate with the PLC. |

Table 3-2. AB_PLC2 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|---|
| OffHook | logical | no | yes | When true, instructs the PLC to retain exclusive use of its assigned communication port. This prevents Lookout from hanging up between polls, saving the redial overhead. This also prevents other blocks from communicating over the same channel. |
| Poll | logical | no | yes | When transitioned from false to true, the Lookout object polls the PLC device |
| PollRate | numeric | no | yes | Specifies the frequency at which the Lookout object polls the PLC device |
| Update | logical | yes | no | Object-generated signal that pulses each time the object polls the device |

Table 3-3. AB_SLC500 Data Members

| Data Member | Type | Read | Write | Description |
|------------------------|---------|------|-------|--|
| B:0 - B255:255 | numeric | yes | yes | 16-bit signed binary word ranging from -32,768 to +32,767 |
| B:0_0-B255:255_15 | logical | yes | yes | One bit within a 16-bit binary word |
| B_0 - B255_4095 | logical | yes | yes | One bit within the specified datafile. For example, B3_32 specifies datafile 3, word 2, bit 1. |
| C:0.ACC - C255:255.ACC | numeric | yes | yes | Counter accumulated value. Two-byte signed word ranging from -32,768 to +32,767 |
| C:0.PRE - C255:255.PRE | numeric | yes | yes | Preset counter value. Two-byte signed word ranging from -32,768 to +32,767 |
| C:0_CU - C255:255_CU | logical | yes | yes | Counter up-enable bit. |
| C:0_DN - C:255:255_DN | logical | yes | yes | Counter done bit. |

Table 3-3. AB_SLC500 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|----------------------|-------------|-------------|--------------|---|
| C:0_OV - C255:255_OV | logical | yes | yes | Counter overflow bit. |
| C:0_UA - C255:255_UA | logical | yes | yes | Counter update accumulation bit (HSC in fixed controller only) |
| C:0_UN - C255:255_UN | logical | yes | yes | Counter underflow bit. |
| C:0_CD -C255:255_CD | logical | yes | yes | Counter down-enable bit. |
| CommFail | logical | yes | no | Object-generated signal that is ON if, for any reason, Lookout cannot communicate with the SLC. |
| F:0-F255:255 | numeric | yes | yes | Floating point value |
| I:0 - I:30 | numeric | yes | yes | Unsigned 16-bit input value ranging from 0 to 65,535 |
| I:0_0 - I:30_15 | logical | yes | yes | One bit within a 16-bit input word |
| N:0 - N255:255 | numeric | yes | yes | 16-bit signed integer value ranging from -32,768 to +32,767. |
| N:0_0 - N255:255_15 | logical | yes | yes | One bit within a 16-bit signed integer word |
| O:0 - O:30 | numeric | yes | yes | Unsigned 16-bit output value ranging from 0 to 65,535 |
| O:0_0 - O:30_15 | logical | yes | yes | One bit within a 16-bit output word |
| OffHook | logical | no | yes | When true, instructs the PLC to retain exclusive use of its assigned communication port. This prevents Lookout from hanging up between polls, saving the radial overhead. This also prevents other blocks from communicating over the same channel. |
| Poll | logical | no | yes | When transitioned from false to true, the Lookout object polls the SLC device |

Table 3-3. AB_SLC500 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|------------------------|-------------|-------------|--------------|---|
| PollRate | numeric | no | yes | Specifies the frequency at which the Lookout object polls the SLC device |
| R:0_FD - R255:255_FD | logical | yes | yes | Control “found” single-bit logical indicator |
| R:0.LEN - R255:255.LEN | numeric | yes | yes | Control “length” signed integer ranging from –32,768 to +32,767 |
| R:0.POS - R255:255.POS | numeric | yes | yes | Control “position” signed integer ranging from –32,768 to +32,767 |
| R:0_DN - R255:255_DN | logical | yes | yes | Control “done” single-bit logical indicator |
| R:0_EM - R255:255_EM | logical | yes | yes | Control “empty” single-bit logical indicator |
| R:0_EN - R255:255_EN | logical | yes | yes | Control “enable” single-bit logical indicator |
| R:0_ER - R255:255.ER | logical | yes | yes | Control “error” single-bit logical indicator |
| R:0_EU - R255:255_EU | logical | yes | yes | Control “enable unloading” single-bit |
| R:0_IN - R255:255.IN | logical | yes | yes | Control “inhibit comparison” flag single-bit logical indicator |
| R:0_UL - R255:255_UL | logical | yes | yes | Control “unload” single-bit logical indicator |
| S:0 - S:96 | numeric | yes | yes | SLC status file containing a signed integer ranging from –32,768 to +32,767 (see Allen-Bradley documentation) |
| S:0_0 -S:96_15 | logical | yes | yes | Individual SLC status bits (see Allen-Bradley documentation) |
| ST9:0 - ST255:255 | text | yes | yes | String, limited to 83 characters in length. See the note on Allen-Bradley string data members at the end of this table. |

Table 3-3. AB_SLC500 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|------------------------|---------|------|-------|---|
| T:0.ACC - T255:255.ACC | numeric | yes | yes | Accumulated timer value ranging from -32,768 to +32,767 |
| T:0.PRE - T255:255.PRE | numeric | yes | yes | Preset timer value ranging from -32,768 to +32,767 |
| T:0_DN - T255:255_DN | logical | yes | yes | Timer “done” single-bit logical indicator |
| T:0_EN - T255:255_EN | logical | yes | yes | Timer “enabled” single-bit logical indicator |
| T:0_TT - T255:255_TT | logical | yes | yes | Timer “timing” single-bit logical indicator |
| Update | logical | yes | no | Object-generated signal that pulses each time the object polls the device |



Note There is no Allen-Bradley default file type associated with strings. You must configure your Allen-Bradley device to have a string file. See your Allen-Bradley documentation for details on this configuration procedure.

The string data member only works with the SLC 500 Enhanced series of PLCs, including the SLC 5/03; OS301 and SLC 5/04., and with the PLC 5 Enhanced series, PLC 5/11, PLC 5/20, PLC 5/30, PLC 5/40, PLC 5/60, PLC 5/80.

Table 3-4. AB_PLC5 Data Members

| Data Member | Type | Read | Write | Description |
|------------------------|---------|------|-------|--|
| B:0 - B999:999 | numeric | yes | yes | 16-bit signed binary word ranging from -32,768 to +32,767 |
| B:0_0-B999:999_15 | logical | yes | yes | One bit within a 16-bit binary word. |
| B_0 - For B999_15999 | logical | yes | yes | One bit within the specified datafile; for example, B3_32 specifies datafile 3, word 2, bit 1. |
| C:0.ACC - C999:999.ACC | numeric | yes | yes | Counter accumulated value. Two-byte signed word ranging from -32,768 to +32,767 |

Table 3-4. AB_PLC5 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|------------------------|-------------|-------------|--------------|--|
| C:0.PRE - C999:999.PRE | numeric | yes | yes | Preset counter value ranging from -32,768 to +32,767. |
| C:0_CD - C999:999_CD | logical | yes | yes | Counter down-enable bit. |
| C:0_CU - C999:999_CU | logical | yes | yes | Counter up-enable bit. |
| C:0_DN - C:999:999_DN | logical | yes | yes | Counter done bit. |
| C:0_OV - C999:999_OV | logical | yes | yes | Counter overflow bit. |
| C:0_UA - C999:999_UA | logical | yes | yes | Counter update accumulation bit (HSC in fixed controller only). |
| C:0_UN - C999:999_UN | logical | yes | yes | Counter underflow bit. |
| CommFail | logical | yes | no | Object-generated signal that is ON if, for whatever reason, Lookout cannot communicate with the PLC. |
| F:0-F999:999 | numeric | yes | yes | Floating point value. |
| I:0 - I:277 | numeric | yes | yes | Unsigned 16-bit input value ranging from 0 to 65,535. |
| I:0_0 - I:277_17 | logical | yes | yes | One bit within a 16-bit input word (octal). |
| N:0 - N999:999 | numeric | yes | yes | 16-bit signed integer value ranging from -32,768 to +32,767. |
| N:0_0 - N999:999_15 | logical | yes | yes | One bit within a 16-bit signed integer word. |
| O:0 - O:277 | numeric | yes | yes | Unsigned 16-bit output value ranging from 0 to 65,535. |
| O:0_0 - O:277_17 | logical | yes | yes | One bit within a 16-bit output word (octal). |

Table 3-4. AB_PLC5 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|------------------------|-------------|-------------|--------------|---|
| OffHook | logical | no | yes | When true, instructs the PLC to retain exclusive use of its assigned communication port. This prevents Lookout from hanging up between polls, saving the redial overhead. This also prevents other blocks from communicating over the same channel. |
| Poll | logical | no | yes | When transitioned from false to true, the Lookout object polls the PLC device. |
| PollRate | numeric | no | yes | Specifies the frequency at which the Lookout object polls the PLC device. |
| R:0.LEN - R999:999.LEN | numeric | yes | yes | Control “length” signed integer ranging from –32,768 to +32,767. |
| R:0.POS - R999:999.POS | numeric | yes | yes | Control “position” signed integer ranging from –32,768 to +32,767. |
| R:0_DN - R999:999_DN | logical | yes | yes | Control “done” single-bit logical indicator. |
| R:0_EM - R999:999_EM | logical | yes | yes | Control “empty” single-bit logical indicator. |
| R:0_EN - R999:999_EN | logical | yes | yes | Control “enable” single-bit logical indicator. |
| R:0_ER - R999:999.ER | logical | yes | yes | Control “error” single-bit logical indicator. |
| R:0_EU - R999:999_EU | logical | yes | yes | Control “enable unloading” single-bit logical indicator. |
| R:0_FD - R999:999_FD | logical | yes | yes | Control “found” single-bit logical indicator. |
| R:0_IN - R999:999.IN | logical | yes | yes | Control “inhibit comparison” flag logical indicator. |
| R:0_UL - R999:999_UL | logical | yes | yes | Control “unload” single-bit logical indicator. |

Table 3-4. AB_PLCC5 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|------------------------|-------------|-------------|--------------|---|
| S:0 - S:127 | numeric | yes | yes | PLC status file containing a signed integer ranging from -32,768 to +32,767 (see Allen-Bradley documentation). |
| S:0_0 - S:127_15 | logical | yes | yes | Individual PLC status bits (see Allen-Bradley documentation). |
| ST9:0 - ST255:255 | text | yes | yes | String, limited to 83 characters in length. See the note on Allen-Bradley string data members at the end of this table. |
| T:0.ACC - T999:999.ACC | numeric | yes | yes | Accumulated timer value ranging from -32,768 to +32,767. |
| T:0.PRE - T999:999.PRE | numeric | yes | yes | Preset timer value ranging from -32,768 to +32,767. |
| T:0_DN - T999:999_DN | logical | yes | yes | Timer “done” single-bit logical indicator. |
| T:0_EN - T999:999_EN | logical | yes | yes | Timer “enabled” single-bit logical indicator. |
| T:0_TT - T999:999_TT | logical | yes | yes | Timer “timing” single-bit logical indicator. |
| Update | logical | yes | no | Object-generated signal that pulses each time the object polls the PLC device. |



Note There is no Allen-Bradley default file type associated with strings. You must configure your Allen-Bradley device to have a string file. See your Allen-Bradley documentation for details on this configuration procedure.

The string data member only works with the SLC 500 Enhanced series of PLCs, including the SLC 5/03; OS301 and SLC 5/04., and with the PLC 5 Enhanced series, PLC 5/11, PLC 5/20, PLC 5/30, PLC 5/40, PLC 5/60, PLC 5/80.

Allen-Bradley Error Messages

AB objects report the statuses of commands they issue to AB devices. When Lookout receives a response from an AB device, it reads the status (STS) byte and, if necessary, the extended status (EXT STS) byte to verify the device executed the Lookout command properly. If the command was not executed properly, Lookout reports the failure as an alarm containing the status code and its meaning. The following is an example of such an alarm:

```
EXT STS = 0F: not enough levels in address
```

AB object classes can also generate alarms internally. The following is a list of AB alarms generated by Lookout, their descriptions, and possible responses. In the messages, *KT* is used to refer to any of the DH+ interface cards (1784-KT, 1784-KTx, 1784-PCMK, or 5136-SD) and *SS* is used to refer to the 5136-SD card.

Cannot resolve ip address: *address*

The AB object failed to find any node on the network that corresponds to the given IP address. Confirm that the IP address entered in the **Modify Object** dialog box is correct.

Cannot get session id from plc

The AB object sent a message to the PLC requesting a TCP/IP session and failed to receive a satisfactory response.

Cannot communicate with device (code=*dd*)

The AB object timed out while waiting for a response (via TCP/IP) from the PLC. If the code is 0, the object timed out while trying to establish the TCP/IP connection; if the code is 1, the object timed out while waiting for a session id from the PLC; if the code is 2, the object timed out while waiting for a response to a poll request. Confirm that the IP address of the PLC has been entered correctly and that the PLC is reachable over the TCP/IP network.

Download of file sdipds.ss1 failed

Lookout was unable to write the KT-emulation program file to the 5136-SD card physical memory. This could be due to either an invalid port or memory address or to a faulty or improperly seated card.

Invalid memory address for card: 0xAAAA

The memory address specified for the card (for example, D400) is not valid for this model of card. The address must be a multiple of 0x0100 and lie in the range 0xA000 to 0xDF00. Moreover, the KT, KT_x, PCMK, and 5136-SD cards support different sets of valid memory addresses. See the documentation that shipped with the card for details.

Invalid node address for card: xx

Node addresses must be between 0 and 63 decimal.

Invalid port number for SS card: 0xPPP

The port number specified for the 5136-SD card is invalid. See the documentation that shipped with the card for the list of valid port addresses.

Invalid port or memory address

Lookout was unable to write to the 5136-SD card physical memory. This could be due to either an invalid port or memory address or to a faulty or improperly seated card.

KT card failed to find resources**KT card receive mailbox is in an invalid state****KT card send mailbox is in an invalid state**

You will probably never see one of these alarms. If you do, call National Instruments and ask for technical support.

KT card dual-ported memory test failed at location xxxx

The interface card failed a memory test when it was first powered on. The memory test reads, writes and rereads the dual-ported memory to ensure memory access by the card. Verify that the card is configured for the memory address that you specified. Verify that your memory manager (like EMM386) excludes the appropriate portion of memory. Verify that your card is not trying to use the same memory location as another card. You may need to restart the card by calling up the AB object definition dialog box and selecting **OK**. If that does not work try rebooting the computer. Other causes can include memory conflicts, a bad interface card, or a misbehaving driver.

KT card CTC test timed out

KT card CTC test failed with status code xx

The interface card failed the Counter Timer Circuit test when it was first powered on. This test verifies proper functionality of the card timer and counter modes over all CTC channels. You may need to restart, reseal, or replace the interface card.

KT card timed out while loading protocol code

KT card failed with status code xx while loading protocol

Lookout was not able to transfer a loader file to the card and subsequently download the card protocol firmware. Try to restart the interface card by calling up the AB object definition dialog box and selecting **OK**. If that does not work try rebooting the computer.

KT card is no longer responding

The Lookout AB object did not receive the interface card heartbeat within the last second. Normally, the card generates a heartbeat any time it receives the DH+ network token. If the alarm does not deactivate after 30 seconds, try to restart the card by calling up the AB object definition dialog box and selecting **OK**. If that does not work try restarting Lookout or rebooting the computer.

KT card memory address conflicts with card n

Lookout found another interface card with the same memory address. Be sure that the memory address on each interface card is different and that the corresponding **Memory address** in the Lookout object matches the card address.

KT card not present in this computer

The **Card exists in this computer** check box is deselected (this is the default setting). Select **Object»Modify** to retrieve the PLC definition parameters dialog box and select the **Card exists in this computer** check box and **OK** to initialize the card.

KT card RAM test timed out

KT card RAM test failed with status code xx

The interface card failed a memory test when it was first powered on. The memory test writes a pattern to on-board RAM and reads its content to verify the card memory is working. Confirm that the memory address specified in the **Object»Modify** dialog box is correct. You may need to restart, reseal, or replace the card.

KT card signature test failed

The AB object does not recognize the card. Make sure that the interface card is actually installed in the PC and that you indicated the correct memory address in Lookout. You may need to reseat the card, or the card may require repair. Also ensure that you did not identify more **Card Numbers** than actual physical cards.

KT card SIO test timed out**KT card SIO test failed with status code xx**

The interface card failed the Serial Input Output test when it was first powered on. You may need to restart, reseat, or replace the interface card.

KT card send mailbox timed out

The AB object timed out while waiting for the KT card to signal that it is ready to be given a new message to send. This is most likely due to a communication problem between the computer and the PLC. Confirm that the network cable is properly installed and that the PLC is turned on.

NAK response received

The AB object received a NAK (not acknowledged) response when it polled the device. The device received a command from Lookout but it did not accept the message. The command that the device received may be incomplete or contain irregularities due to poor network performance. If your Serial Port is configured for radio, you may need to adjust the **RTS delay off** setting. Also consider increasing the number of **Retry attempts**.

No response — no ACK for our transmission

Lookout is not getting any response from the device. This could be caused by just about anything. Verify that the **Data rate**, **Parity**, and **Error detection** settings are the same as the settings on the device. Make sure you are using the proper **Serial port** on your computer. Verify that the device interface module and other network equipment is connected and working properly. If you are using a modem, verify that your object **Phone number** and the serial port **Dial-up** settings are correct. This may also be caused by low level noise or reflections on the highway, or marginal circuitry on a card.

No response within timeout period

No response received after receiving ENQ

The AB object received an acknowledgment of its poll from the device. The device accepted the command from Lookout. However, the device did not appear to send anything else back in response. You may have to increase **Receive timeout** to make sure Lookout allows enough time to receive the message.

EOT response received

The AB object received an EOT (end of transmission) response when it polled the device indicating that the device did not have a message ready to give in response to the Lookout poll request. It is unlikely that you will ever see this error message.

Received TSN does not match

Response message garbled -- bad CRC or bad BCC

Response message garbled -- no DLE EXT

Response message garbled -- bad DLE follower

The AB object is receiving messages from the device. However, the messages may be failing the selected data integrity test. Verify that the object **Error detection** setting is the same as the settings on the device. Another cause may be that the last part of the message is actually getting clipped off before it is completed. You may have to increase the **Receive gap** Serial Port setting to ensure Lookout is receiving the entire message. If your Serial Port is configured for radio this could be caused by an audible squelch tail occurring at the end of a radio transmission. You may need to adjust the **RTS delay off** or the **CTS timeout** settings. Also consider increasing the number of **Retry attempts**.

Socket communications error *dd: msg*

The AB object has encountered a problem while attempting to communicate using TCP/IP. The error number *dd* and corresponding error message *msg* give further information. Confirm that the IP address of the PLC has been entered correctly and that the PLC is reachable over the TCP/IP network.

SS card failed

This message is suffixed with an error message read from the card itself. You may need to contact the vendor of your card for technical support.

SS card failed while performing diagnostics

Lookout successfully wrote the KT-emulation program to the 5136-SD card, but the program failed to terminate. Try running the `sdinst.exe` program that ships with the 5136-SD card, using the `CHK` option to confirm that the card is working properly.

Unable to access physical memory at segment 0xAAAA

Lookout was unable to access the memory at the given segment address. The memory may already be in use by the operating system or by another application. Either change the object memory address (which may involve changing switch settings on the card itself) or, if you are using a memory manager, make sure that it is excluding the correct portion of memory.

Unable to open port 0xPPP for SS card

Lookout was unable to open the port number specified for the 5136-SD card. Make sure that you have specified the port that is selected by the jumper settings on the card. Make sure that port and the following two ports (for example, 250, 251, and 252) are not in use by any other devices in your computer.

Unexpected data response length**Unexpected response****Unhandled error**

You will probably never see one of these alarms. If you do, call National Instruments and ask for technical support.

AdvantechPCL

The AdvantechPCL object class enables Lookout to communicate with the Advantech PC-MultiLab Card, model PCL-711B. The MultiLab Card installs in your computer and provides one analog output, eight analog inputs, 16 digital inputs and 16 digital outputs.

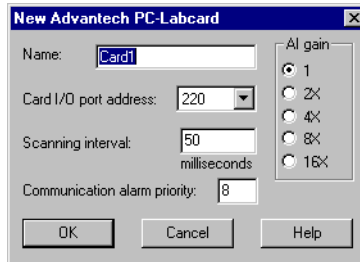


Figure 3-5. AdvantechPCL Definition Parameters Dialog Box

Card I/O port address indicates the base I/O port address you chose using DIP switch settings on the card. The Advantech card uses 16 consecutive I/O port address locations in your computer. So if you identify base address 220 (hex), it uses addresses 220 to 22F. Valid base addresses range from 000 to 3F0. If your computer does not have an Advantech card installed, be sure to select `no card`.



Note I/O ports identify to the CPU the location of basic system components such as serial ports, video cards, and disk controllers. Check your computer hardware manual and add-on board configurations to be sure you are assigning a unique I/O port address to the Advantech card.

Scanning interval is a numeric parameter that determines how often Lookout scans the card for changed values. Valid intervals range from 10 to 1000 milliseconds.

AI gain specifies the input amplification gains of all analog input signals (AI0 – AI7). For the highest possible resolution, you should amplify the input signals so that their maximum voltage swing equals their maximum input range. The following table lists recommended settings.

| If your maximum voltage range is... | use A1 gain... |
|-------------------------------------|----------------|
| ±5V | 1 |
| ±2.5V | 2X |

| If your maximum voltage range is... | use A1 gain... |
|-------------------------------------|----------------|
| $\pm 1.25\text{V}$ | 4X |
| $\pm 0.625\text{V}$ | 8X |
| $\pm 0.3125\text{V}$ | 16X |

Communication alarm priority determines the priority level of the alarms generated by the AdvantechPCL object class.

AdvantechPCL Data Members

The table that follows lists data members supported by the AdvantechPCL object class.

Table 3-5. AdvantechPCL Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|---|
| AI0 – AI7 | Analog | yes | no | Analog input where AI0 represents A/D 0 (pin 1 on CN1) and AI7 represents A/D 7 (pin 15 on CN1). Each input is a 12-bit integer, ranging from 0 to 4095. |
| AO0 | Analog | no | yes | Analog output where AO0 represents D/A (pin 17 on CN1). This output is a 12-bit integer, ranging from 0 – 4095 (+5V or +10V, depending on jumper JP1). |
| CommFail | logical | yes | no | Object-generated signal that is on if, for whatever reason, Lookout cannot communicate with the card. |
| DI0 – DI15 | logical | yes | no | Digital input where DI0 represents pin 1 and DI15 represents pin 16 on CN4. Returns False when a monitored signal is open ($>2.0\text{V}$), True when the signal is shorted ($<0.8\text{V}$). |
| DO0 – DO15 | logical | no | yes | Digital output where DO0 represents pin 1 and DO15 represents pin 16 on CN3. |
| Update | logical | yes | no | Object-generated signal that pulses each time the object scans the device. |

Applicom

Applicom is a set of object classes Lookout uses to communicate with a series of devices and protocols, including the Applicom on-board database (Local mode), April 1000, Klockner-Moeller, Otic Fischer & Porter, Profibus DP, Profibus FMS, Profibus L2, SAIA-SBus, Siemens S7MPI, Siemens H1, Siemens S5 AS511, and Telemecanique.

The following illustration on the left is the dialog box for creating an Applicom Local object. At right is the dialog box for creating an Applicom Telemecanique object. The Telemecanique object has the same parameters as all the other Applicom objects except for Applicom Local, and makes a good representative sample for the group.

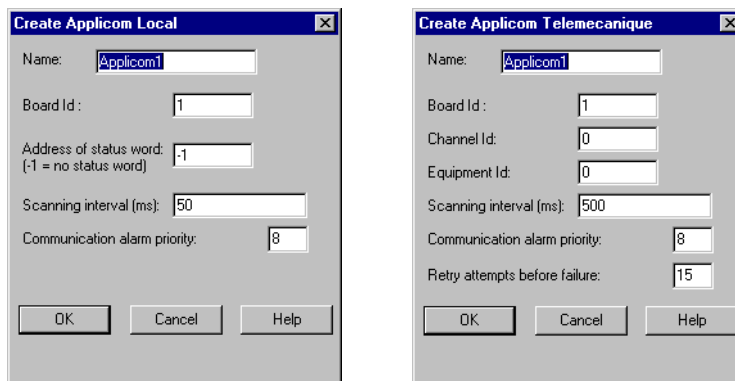


Figure 3-6. Applicom Definition Parameters Dialog Boxes

Board ID identifies the board you are trying to address.

Address of status word is the address of the specific cyclic function of your Applicom board that you want to interact with using this Applicom Local object.

Channel ID identifies the Applicom channel your device is communicating on.

Equipment ID is the Applicom equipment ID for the device you are connecting to.

Scanning interval is the time period between polls. Valid range is 10 - 65535 (expressed in msec).

Communication alarm priority determines the priority level of the alarms generated by the object.

Retry attempts before failure specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the Applicom object generates an alarm and releases the communication port back to the communications service which then moves on to the next device in the polling queue (if any). Refer to Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more detailed information.

Table 3-6. Lookout Applicom Object Classes and the Corresponding Protocols/Devices

| Object Class | Device/protocol |
|-----------------------|---|
| Applicom Local | Any device or protocol supported by Applicom cards. See the <i>Special Instructions on Using the Applicom Local Object Class</i> section, for more detailed information on using this object. |
| Applicom JBUS | Devices using Jbus protocol (mostly those made by April). |
| April 1000 | April 1000 PLC using Ethway or Fipway protocols. |
| Klockner-Moeller | Klockner-Moeller SUCOS PS32 and PS316 PLC using the Sucoma link. |
| Otic Fischer & Porter | Otic Fischer & Porter controllers of series 2000, 5000, and 2000 supervisor using the DATALINK protocol. |
| Profibus DP | Profibus DP with any I/O module or PLC that communicates on a Profibus network using the Decentralized Periphery protocol (includes some Siemens S5 PLCs). |
| Profibus FMS | Profibus FMS protocol with any master or slave FMS device on a Profibus network (includes most Siemens PLCs). |
| Profibus L2 | Profibus L2 protocol with Siemens S5 PLC using Siemens France messaging system. (The PLC must be running a program also distributed with the Applicom hardware.) |
| SAIA-SBus | SAIA SBus master protocol. |
| Siemens S7MPI | Siemens MPI protocol with Siemens S7 PLCs. |
| Siemens H1 | Sinec H1 protocol with various Siemens PLCs. |

Table 3-6. Lookout Applicom Object Classes and the Corresponding Protocols/Devices (Continued)

| Object Class | Device/protocol |
|------------------|--|
| Siemens S5 AS511 | AS511 (programming port) protocol with Siemens S5 PLCs. |
| Telemecanique | Uni-Telway, Ethway and Fipway protocols with all Telemecanique PLCs. |

Applicom Data Members

Table 3-7. Applicom Local Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|---|
| B0-B31999 | logical | yes | yes | Output bits |
| CommFail | logical | yes | no | Object-generated signal that is ON if Lookout cannot communicate with the device(s) |
| D0-D31998 | numeric | yes | yes | Internal double words |
| DS0-DS31998 | numeric | yes | yes | Signed internal double words |
| F0-F31998 | numeric | yes | yes | Internal floating words |
| O0-O13999 | numeric | yes | yes | Internal bytes |
| OS0-OS13999 | numeric | yes | yes | Signed internal bytes |
| Update | logical | yes | no | Goes FALSE when a poll starts and TRUE when a poll completes |
| W0-W31999 | numeric | yes | yes | Output words |
| WS0-WS31999 | numeric | yes | yes | Signed output words |

Table 3-8. Applicom JBUS Data Members

| Data Member | Type | Read | Write | Description |
|------------------|---------|------|-------|---------------|
| B0-B4294967295 | logical | yes | yes | Internal bits |
| BI0-BI4294967295 | logical | yes | no | Input bits |
| BO0-BO4294967295 | logical | yes | yes | Output bits |

Table 3-8. Applicom JBUS Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|---------------------|-------------|-------------|--------------|---|
| CommFail | logical | yes | no | Object-generated signal that is ON if Lookout cannot communicate with the device(s) |
| D0-D4294967295 | numeric | yes | yes | Internal double words |
| F0-F4294967295 | numeric | yes | yes | Internal floating words |
| O0-O4294967295 | numeric | yes | yes | Internal bytes |
| O0.0-O4294967295.7 | logical | yes | yes | Bit in internal bytes |
| O0.0-O4294967295.7 | logical | yes | yes | Bit in internal bytes |
| OI0-OI4294967295 | numeric | yes | no | Input bytes |
| OIS0-OIS4294967295 | numeric | yes | no | Signed input bytes |
| OO0-OO4294967295 | numeric | yes | yes | Output bytes |
| OOS0-OOS4294967295 | numeric | yes | yes | Signed output bytes |
| OS0-OS4294967295 | numeric | yes | yes | Signed internal bytes |
| Update | logical | yes | no | Goes FALSE when a poll starts and TRUE when a poll completes |
| W0-W4294967295 | numeric | yes | yes | Internal words |
| W0.0-W4294967295.15 | logical | yes | yes | Bits in internal words |
| WI0-WI4294967295 | numeric | yes | no | Input words |
| WIS0-WIS4294967295 | numeric | yes | no | Signed input words |
| WO0-WO4294967295 | numeric | yes | yes | Output words |
| WOS0-WOS4294967295 | numeric | yes | yes | Signed output words |
| WS0-WS4294967295 | numeric | yes | yes | Signed internal words |

Table 3-9. Applicom April 1000 Data Members

| Data Member | Type | Read | Write | Description |
|-----------------|---------|------|-------|---|
| CommFail | logical | yes | no | Object-generated signal that is ON if Lookout cannot communicate with the device(s) |
| FD0-FD409598 | numeric | yes | yes | Floating words in the data words |
| IX00000-IX96931 | logical | yes | no | Input bits |
| MD0-MD409598 | numeric | yes | yes | Double words in the data words |
| MDS0-MDS409598 | numeric | yes | yes | Signed double words in the data words |
| MW0-MW409599 | numeric | yes | yes | Data words |
| MWS0-MWS409599 | numeric | yes | yes | Signed data words |
| MX0-MX16383 | logical | yes | yes | Not safeguarded internal bits |
| QX00000-QX96931 | logical | yes | yes | Output bits |
| RX0-RX8191 | logical | yes | yes | Safeguarded internal bits |
| Update | logical | yes | no | Goes FALSE when a poll starts and TRUE when a poll completes |

Table 3-10. Applicom Klockner-Moeller Data Members

| Data Member | Type | Read | Write | Description |
|------------------|---------|------|-------|---|
| B0-B4294967295 | logical | yes | yes | Internal bits |
| BI0-BI4294967295 | logical | yes | no | Input bits |
| BO0-BO4294967295 | logical | yes | yes | Output bits |
| CommFail | logical | yes | no | Object-generated signal that is ON if Lookout cannot communicate with the device(s) |
| D0-D4294967295 | numeric | yes | yes | Internal double words |
| DS0-DS4294967295 | numeric | yes | yes | Signed internal double words |
| F0-F4294967295 | numeric | yes | yes | Internal floating words |
| O0-O4294967295 | numeric | yes | yes | Internal bytes |

Table 3-10. Applicom Klockner-Moeller Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|---------------------|-------------|-------------|--------------|--|
| O0.0-O4294967295.7 | logical | yes | yes | Bit in internal bytes |
| OI0-OI4294967295 | numeric | yes | no | Input bytes |
| OIS0-OIS4294967295 | numeric | yes | no | Signed input bytes |
| OO0-OO4294967295 | numeric | yes | yes | Output bytes |
| OOS0-OOS4294967295 | numeric | yes | yes | Signed output bytes |
| OS0-OS4294967295 | numeric | yes | yes | Signed internal bytes |
| Update | logical | yes | no | Goes FALSE when a poll starts and TRUE when a poll completes |
| W0-W4294967295 | numeric | yes | yes | Internal words |
| W0.0-W4294967295.15 | logical | yes | yes | Bits in internal words |
| WI0-WI4294967295 | numeric | yes | no | Input words |
| WIS0-WIS4294967295 | numeric | yes | no | Signed input words |
| WO0-WO4294967295 | numeric | yes | yes | Output words |
| WOS0-WOS4294967295 | numeric | yes | yes | Signed output words |
| WS0-WS4294967295 | numeric | yes | yes | Signed internal words |

Table 3-11. Applicom Otic Fischer & Porter Data Members

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---|
| B0-B65535 | numeric | yes | yes | Bytes |
| B0.0-B65535.7 | logical | yes | yes | Bits in bytes |
| BS0-BS65535 | numeric | yes | yes | Signed Bytes |
| C0-C65535 | numeric | yes | yes | Floating word on three bytes |
| CommFail | logical | yes | no | Object-generated signal that is ON if Lookout cannot communicate with the device(s) |
| H0-H65535 | numeric | yes | yes | Floating word on five bytes |

Table 3-11. Applicom Otic Fischer & Porter Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|--|
| L0-L65535 | logical | yes | yes | Bits |
| Update | logical | yes | no | Goes FALSE when a poll starts and TRUE when a poll completes |

Table 3-12. Applicom Profibus DP Data Members

| Data Member | Type | Read | Write | Description |
|---------------------|---------|------|-------|---|
| B0-B4294967295 | logical | yes | yes | Internal bits |
| BI0-BI4294967295 | logical | yes | no | Input bits |
| BO0-BO4294967295 | logical | yes | yes | Output bits |
| CommFail | logical | yes | no | Object-generated signal that is ON if Lookout cannot communicate with the device(s) |
| D0-D4294967295 | numeric | yes | yes | Internal double words |
| DS0-DS4294967295 | numeric | yes | yes | Signed internal double words |
| F0-F4294967295 | numeric | yes | yes | Internal floating words |
| O0-O4294967295 | numeric | yes | yes | Internal bytes |
| O0.0-O4294967295.7 | logical | yes | yes | Bit in internal bytes |
| OI0-OI4294967295 | numeric | yes | no | Input bytes |
| OIS0-OIS4294967295 | numeric | yes | no | Signed input bytes |
| OO0-OO4294967295 | numeric | yes | yes | Output bytes |
| OOS0-OOS4294967295 | numeric | yes | yes | Signed output bytes |
| OS0-OS4294967295 | numeric | yes | yes | Signed internal bytes |
| Update | logical | yes | no | Goes FALSE when a poll starts and TRUE when a poll completes |
| W0-W4294967295 | numeric | yes | yes | Internal words |
| W0.0-W4294967295.15 | logical | yes | yes | Bits in internal words |
| WI0-WI4294967295 | numeric | yes | no | Input words |

Table 3-12. Applicom Profibus DP Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|-----------------------|
| WIS0-WIS4294967295 | numeric | yes | no | Signed input words |
| WO0-WO4294967295 | numeric | yes | yes | Output words |
| WOS0-WOS4294967295 | numeric | yes | yes | Signed output words |
| WS0-WS4294967295 | numeric | yes | yes | Signed internal words |

Table 3-13. Applicom Profibus FMS Data Members

| Data Member | Type | Read | Write | Description |
|-------------------------------|-------------|-------------|--------------|---|
| BID0-BID65535 | logical | yes | yes | Bits (simple variables) |
| BID0SUB0-BID65535S UB240 | logical | yes | yes | Bits |
| CommFail | logical | yes | no | Object-generated signal that is ON if Lookout cannot communicate with the device(s) |
| DID0-DID65535 | numeric | yes | yes | Doubles words (simple variables) |
| DID0SUB0-DID65535 SUB60 | numeric | yes | yes | Doubles words |
| FID0-FID65535 | numeric | yes | yes | Floating words (simple variables) |
| FID0SUB0-FID65535S UB60 | numeric | yes | yes | Floating words |
| OID0-OID65535 | numeric | yes | yes | Bytes (simple variables) |
| OID0SUB0-OID65535 SUB240 | numeric | yes | yes | Bytes |
| OID0SUBS0-OID6553 5SUBS240 | numeric | yes | yes | Signed bytes |
| IDS0-IDS65535 | numeric | yes | yes | Signed bytes (simple variables) |
| Update | logical | yes | no | Goes FALSE when a poll starts and TRUE when a poll completes |
| WID0-WID65535 | numeric | yes | yes | Words (simple variables) |

Table 3-13. Applicom Profibus FMS Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|-------------------------------|-------------|-------------|--------------|---------------------------------|
| WID0SUB0-WID65535 SUB120 | numeric | yes | yes | Words |
| WID0SUBS0-WID6553 5SUBS120 | numeric | yes | yes | Signed words |
| WIDS0-WIDS65535 | numeric | yes | yes | Signed words (simple variables) |

Table 3-14. Applicom Profibus L2 Data Members

| Data Member | Type | Read | Write | Description |
|---------------------------|-------------|-------------|--------------|---|
| CommFail | logical | yes | no | Object-generated signal that is ON if Lookout cannot communicate with the device(s) |
| DB1D0.0-DB255D255.15 | logical | yes | yes | Bits of DB word |
| DB1DD0-DB255DD254 | numeric | yes | yes | Double words in DB |
| DB1DD0KG- DB255DD254KG | numeric | yes | yes | Floating words in DB |
| DB1DDS0- DB255DDS254 | numeric | yes | yes | Signed double words in DB |
| DB1DW0-DB255DW255 | numeric | yes | yes | Update pulse: words in DB |
| DB1DWS0-DB255DWS255 | numeric | yes | yes | Signed words in DB |
| DX0D0.0-DX255D255.15 | logical | yes | yes | Bits of DX word |
| DX0DD0-DX255DD254 | numeric | yes | yes | Double words in DX |
| DX0DD0KG- DX255DD254KG | numeric | yes | yes | Floating words in DX |
| DX0DDS0- DX255DDS254 | numeric | yes | yes | Signed double words in DX |
| DX0DW0- DX255DW255 | numeric | yes | yes | Update pulse: words in DX |
| DX0DWS0- DX255DWS255 | numeric | yes | yes | Signed words in DX |

Table 3-14. Applicom Profibus L2 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---|
| F0.0-F255.7 | logical | yes | yes | Bits in flag bytes |
| FD0-FD255 | numeric | yes | yes | Double words in flag bytes |
| FD0KG-FD252KG | numeric | yes | yes | Floating words in flag bytes |
| FDS0-FDS255 | numeric | yes | yes | Signed double words in flag bytes |
| FW0-FW254 | numeric | yes | yes | Words in flag bytes |
| FWS0-FWS254 | numeric | yes | yes | Signed words in flag bytes |
| FY0-FY255 | numeric | yes | yes | Flag bytes |
| FYS0-FYS255 | numeric | yes | yes | Signed flag bytes |
| I0.0-I127.7 | logical | yes | no | Input bits |
| IB0-IB127 | numeric | yes | no | Input bytes |
| IBS0-IBS127 | numeric | yes | no | Signed input bytes |
| IW0-IW126 | numeric | yes | no | Input words |
| IWS0-IWS126 | numeric | yes | no | Signed input words |
| Q0.0-Q127.7 | logical | yes | yes | Output bits |
| QW0-QW126 | numeric | yes | yes | Output words |
| QWS0-QWS126 | numeric | yes | yes | Signed output words |
| QY0-QY127 | numeric | yes | yes | Output bytes |
| QYS0-QYS127 | numeric | yes | yes | Signed output bytes |
| S0.0-S4095.7 | logical | yes | yes | Bits in Sflags (internal bytes) |
| SD0-SD4095 | numeric | yes | yes | Floating words in Sflags |
| SD0KG-SD4092KG | numeric | yes | yes | Floating words in Sflags |
| SDS0-SDS4095 | numeric | yes | yes | Signed double words in Sflags |
| SW0-SW4094 | numeric | yes | yes | Words in Sflags (internal bytes) |
| SWS0-SWS4094 | numeric | yes | yes | Signed words in Sflags (internal bytes) |
| SY0-SY4095 | numeric | yes | yes | Sflags (internal bytes) |

Table 3-14. Applicom Profibus L2 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|--|
| SYS0-SYS4095 | numeric | yes | yes | Signed Sflags (internal bytes) |
| Update | logical | yes | no | Goes FALSE when a poll starts and TRUE when a poll completes |

Table 3-15. Applicom Siemens S5 H1 Data Members

| Data Member | Type | Read | Write | Description |
|-------------------------|-------------|-------------|--------------|---|
| CommFail | logical | yes | no | Object-generated signal that is on if Lookout cannot communicate with the device(s) |
| DB1D0.0 - DB255D255.15 | logical | yes | yes | Bits of DB word |
| DB1DD0 - DB255DD254 | numeric | yes | yes | Double words in DB |
| DB1DD0KG - DB255DD254KG | numeric | yes | yes | Floating words in DB |
| DB1DDS0 - DB255DDS254 | numeric | yes | yes | Signed double words in DB |
| DB1DW0 - DB255DW255 | numeric | yes | yes | Update pulse: words in DB |
| DB1DWS0 - DB255DWS255 | numeric | yes | yes | Signed words in DB |
| DX0D0.0 - DX255D255.15 | logical | yes | yes | Bits of DX word |
| DX0DD0 - DX255DD254 | numeric | yes | yes | Double words in DX |
| DX0DD0KG - DX255DD254KG | numeric | yes | yes | Floating words in DX |
| DX0DDS0 - DX255DDS254 | numeric | yes | yes | Signed double words in DX |
| DX0DW0 - DX255DW255 | numeric | yes | yes | Update pulse: words in DX |

Table 3-15. Applicom Siemens S5 H1 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|-----------------------|-------------|-------------|--------------|---|
| DX0DWS0 - DX255DWS255 | numeric | yes | yes | Signed words in DX |
| FD0 - FD255 | numeric | yes | yes | Double words in flag bytes |
| FD0KG - FD252KG | numeric | yes | yes | Floating words in flag bytes |
| FDS0 - FDS255 | numeric | yes | yes | Signed double words in flag bytes |
| FW0 - FW254 | numeric | yes | yes | Words in flag bytes |
| FWS0 - FWS254 | numeric | yes | yes | Signed words in flag bytes |
| FY0 - FY255 | numeric | yes | yes | Flag bytes |
| FYS0 - FYS255 | numeric | yes | yes | Signed flag bytes |
| I0.0 - I127.7 | logical | yes | no | Input bits |
| IB0 - IB127 | numeric | yes | no | Input bytes |
| IBS0 - IBS127 | numeric | yes | no | Signed input bytes |
| IW0 - IW126 | numeric | yes | no | Input words |
| IWS0 - IWS126 | numeric | yes | no | Signed input words |
| Q0.0 - Q127.7 | logical | yes | yes | Output bits |
| QW0 - QW126 | numeric | yes | yes | Output words |
| QWS0 - QWS126 | numeric | yes | yes | Signed output words |
| QY0 - QY127 | numeric | yes | yes | Output bytes |
| QYS0 - QYS127 | numeric | yes | yes | Signed output bytes |
| S0.0 - S4095.7 | logical | yes | yes | Bits in Sflags (internal bytes) |
| SD0 - SD4095 | numeric | yes | yes | Floating words in Sflags |
| SD0KG - SD4092KG | numeric | yes | yes | Floating words in Sflags |
| SDS0 - SDS4095 | numeric | yes | yes | Signed double words in Sflags |
| SW0 - SW4094 | numeric | yes | yes | Words in Sflags (internal bytes) |
| SWS0 - SWS4094 | numeric | yes | yes | Signed words in Sflags (internal bytes) |

Table 3-15. Applicom Siemens S5 H1 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|--------------------------------|
| SY0 - SY4095 | numeric | yes | yes | Sflags (internal bytes) |
| SYS0 - SYS4095 | numeric | yes | yes | Signed Sflags (internal bytes) |
| Update | logical | yes | no | False during Polling sequence |

Table 3-16. Applicom SAIA SBus Data Members

| Data Member | Type | Read | Write | Description |
|------------------------|-------------|-------------|--------------|---|
| CommFail | logical | yes | no | Object-generated signal that is ON if Lookout cannot communicate with the device(s) |
| DB0Q0-DB7999Q7999 | numeric | yes | yes | Floating data block |
| DB0R0-DB7999R7999 | numeric | yes | yes | Binary data block |
| DB0R0.0-DB7999R7999.31 | logical | yes | yes | Bits in binary data block |
| DB0R0.0-DB7999R7999.31 | logical | yes | yes | Bits in binary data block |
| F0-F8091 | logical | yes | yes | Flags |
| I0-I8091 | logical | yes | no | Input |
| O0-O8091 | logical | yes | yes | Output |
| Q0-Q4095 | numeric | yes | yes | Floating registers |
| R0-R4095 | numeric | yes | yes | Binary registers |
| R0.0-R4095.31 | logical | yes | yes | Bits in binary registers |
| RS0-RS4095 | numeric | yes | yes | Signed binary registers |
| Update | logical | yes | no | Goes FALSE when a poll starts and TRUE when a poll completes |

Table 3-17. Applicom Siemens S5 AS511 Data Members

| Data Member | Type | Read | Write | Description |
|-----------------------|-------------|-------------|--------------|---|
| CommFail | logical | yes | no | Object-generated signal that is ON if Lookout cannot communicate with the device(s) |
| DB1D0.0-DB255D255.15 | logical | yes | yes | Bits of DB word |
| DB1DD0-DB255DD254 | numeric | yes | yes | Double words in DB |
| DB1DD0KG-DB255DD254KG | numeric | yes | yes | Floating words in DB |
| DB1DDS0-DB255DDS254 | numeric | yes | yes | Signed double words in DB |
| DB1DW0-DB255DW255 | numeric | yes | yes | Update pulse: words in DB |
| DB1DWS0-DB255DWS255 | numeric | yes | yes | Signed words in DB |
| DX0D0.0-DX255D255.15 | logical | yes | yes | Bits of DX word |
| DX0DD0-DX255DD254 | numeric | yes | yes | Double words in DX |
| DX0DD0KG-DX255DD254KG | numeric | yes | yes | Floating words in DX |
| DX0DDS0-DX255DDS254 | numeric | yes | yes | Signed double words in DX |
| DX0DW0-DX255DW255 | numeric | yes | yes | Update pulse: words in DX |
| DX0DWS0-DX255DWS255 | numeric | yes | yes | Signed words in DX |
| F0.0-F255.7 | logical | yes | yes | Bits in flag bytes |
| FD0-FD255 | numeric | yes | yes | Double words in flag bytes |
| FD0KG-FD252KG | numeric | yes | yes | Floating words in flag bytes |
| FDS0-FDS255 | numeric | yes | yes | Signed double words in flag bytes |
| FW0-FW254 | numeric | yes | yes | Words in flag bytes |
| FWS0-FWS254 | numeric | yes | yes | Signed words in flag bytes |
| FY0-FY255 | numeric | yes | yes | Flag bytes |
| FYS0-FYS255 | numeric | yes | yes | Signed flag bytes |
| I0.0-I127.7 | logical | yes | no | Input bits |
| IB0-IB127 | numeric | yes | no | Input bytes |

Table 3-17. Applicom Siemens S5 AS511 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|--|
| IBS0-IBS127 | numeric | yes | no | Signed input bytes |
| IW0-IW126 | numeric | yes | no | Input words |
| IWS0-IWS126 | numeric | yes | no | Signed input words |
| Q0.0-Q127.7 | logical | yes | yes | Output bits |
| QW0-QW126 | numeric | yes | yes | Output words |
| QWS0-QWS126 | numeric | yes | yes | Signed output words |
| QY0-QY127 | numeric | yes | yes | Output bytes |
| QYS0-QYS127 | numeric | yes | yes | Signed output bytes |
| S0.0-S4095.7 | logical | yes | yes | Bits in Sflags (internal bytes) |
| SD0-SD4095 | numeric | yes | yes | Floating words in Sflags |
| SD0KG-SD4092KG | numeric | yes | yes | Floating words in Sflags |
| SDS0-SDS4095 | numeric | yes | yes | Signed double words in Sflags |
| SW0-SW4094 | numeric | yes | yes | Words in Sflags (internal bytes) |
| SWS0-SWS4094 | numeric | yes | yes | Signed words in Sflags (internal bytes) |
| SY0-SY4095 | numeric | yes | yes | Sflags (internal bytes) |
| SYS0-SYS4095 | numeric | yes | yes | Signed Sflags (internal bytes) |
| Update | logical | yes | no | Goes FALSE when a poll starts and TRUE when a poll completes |

Table 3-18. Applicom Siemens S7 MPI Data Members

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---------------------|
| A0.0-A65535.7 | logical | yes | yes | Output bits |
| AB0-AB65535 | numeric | yes | yes | Output bytes |
| ABS0-ABS65535 | numeric | yes | yes | Signed output bytes |

Table 3-18. Applicom Siemens S7 MPI Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|---------------------------------|-------------|-------------|--------------|---|
| AW0-AW65534 | numeric | yes | yes | Output words |
| AWS0-AWS65534 | numeric | yes | yes | Signed output words |
| CommFail | logical | yes | no | Object-generated signal that is ON if Lookout cannot communicate with the device(s) |
| DB0.DBD0-DB32767. DBD65532 | numeric | yes | yes | Double words in DB |
| DB0.DBD0F-DB32767. DBD65532F | numeric | yes | yes | Floating words in DB |
| DB0.DBDS0-DB32767. DBDS65532 | numeric | yes | yes | Signed double words in DB |
| DB0.DBW0-DB32767. DBW65534 | numeric | yes | yes | Words in DB |
| DB0.DBWS0-DB32767. DBWS65534 | numeric | yes | yes | Signed words in DB |
| DB0DBB0-DB32767. DBB65535 | numeric | yes | yes | Bytes in DB |
| DB0DBBS0-DB32767. DBBS65535 | numeric | yes | yes | Signed bytes in DB |
| DB1.DBX0.0-DB8191. DB65535.7 | logical | yes | yes | Bits in DB byte |
| E0.0-E65535.7 | logical | yes | no | Input bits |
| EB0-EB65535 | numeric | yes | no | Input bytes |
| EBS0-EBS65535 | numeric | yes | no | Signed input bytes |
| EW0-EW65534 | numeric | yes | no | Input words |
| EWS0-EWS65534 | numeric | yes | no | Signed input words |
| M0.0-M65535.7 | logical | yes | yes | Bits in flag bytes |
| MB0-MB65535 | numeric | yes | yes | Flag bytes |
| MBS0-MBS65535 | numeric | yes | yes | Signed flag bytes |

Table 3-18. Applicom Siemens S7 MPI Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|--|
| MD0-MD65532 | numeric | yes | yes | Double words in flag bytes |
| MD0F-MD65532F | numeric | yes | yes | Floating words in flag bytes |
| MDS0-MDS65532 | numeric | yes | yes | Signed double words in flag bytes |
| MW0-MW65534 | numeric | yes | yes | Words in flag bytes |
| MWS0-MWS65534 | numeric | yes | yes | Signed words in flag bytes |
| Update | logical | yes | no | Goes FALSE when a poll starts and TRUE when a poll completes |

Table 3-19. Applicom Siemens S7 PPI Data Members

| Data Member | Type | Read | Write | Description |
|---------------------------------|-------------|-------------|--------------|---|
| A0.0-A65535.7 | logical | yes | yes | Output bits |
| AB0-AB65535 | numeric | yes | yes | Output bytes |
| ABS0-ABS65535 | numeric | yes | yes | Signed output bytes |
| AW0-AW65534 | numeric | yes | yes | Output words |
| AWS0-AWS65534 | numeric | yes | yes | Signed output words |
| CommFail | logical | yes | no | Object-generated signal that is ON if Lookout cannot communicate with the device(s) |
| DB0.DBD0-DB32767. DBD65532 | numeric | yes | yes | Double words in DB |
| DB0.DBD0F-DB32767. DBD65532F | numeric | yes | yes | Floating words in DB |
| DB0.DBDS0-DB32767. DBDS65532 | numeric | yes | yes | Signed double words in DB |
| DB0.DBW0-DB32767. DBW65534 | numeric | yes | yes | Words in DB |
| DB0.DBWS0-DB32767. DBWS65534 | numeric | yes | yes | Signed words in DB |

Table 3-19. Applicom Siemens S7 PPI Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|---------------------------------|-------------|-------------|--------------|--|
| DB0DBB0-DB32767. DBB65535 | numeric | yes | yes | Bytes in DB |
| DB0DBBS0-DB32767. DBBS65535 | numeric | yes | yes | Signed bytes in DB |
| DB1.DBX0.0-DB8191. DB65535.7 | logical | yes | yes | Bits in DB byte |
| E0.0-E65535.7 | logical | yes | no | Input bits |
| EB0-EB65535 | numeric | yes | no | Input bytes |
| EBS0-EBS65535 | numeric | yes | no | Signed input bytes |
| EW0-EW65534 | numeric | yes | no | Input words |
| EWS0-EWS65534 | numeric | yes | no | Signed input words |
| M0.0-M65535.7 | logical | yes | yes | Bits in flag bytes |
| MB0-MB65535 | numeric | yes | yes | Flag bytes |
| MBS0-MBS65535 | numeric | yes | yes | Signed flag bytes |
| MD0-MD65532 | numeric | yes | yes | Double words in flag bytes |
| MD0F-MD65532F | numeric | yes | yes | Floating words in flag bytes |
| MDS0-MDS65532 | numeric | yes | yes | Signed double words in flag bytes |
| MW0-MW65534 | numeric | yes | yes | Words in flag bytes |
| MWS0-MWS65534 | numeric | yes | yes | Signed words in flag bytes |
| Update | logical | yes | no | Goes FALSE when a poll starts and TRUE when a poll completes |

Table 3-20. Applicom Siemens H1 Data Members

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---|
| C1-C2097152 | logical | yes | yes | Bits |
| CommFail | logical | yes | no | Object-generated signal that is ON if Lookout cannot communicate with the device(s) |

Table 3-20. Applicom Siemens H1 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|--|
| DCP1-DCP65536 | numeric | yes | yes | Drum count preset |
| DSC1-DSC65536 | numeric | yes | yes | Drum step current |
| DSP1-DSP65536 | numeric | yes | yes | Drum step preset |
| K1-K2097152 | numeric | yes | yes | Constant words |
| K1.0-K2097152.15 | logical | yes | yes | Bits in constant words |
| KF1-KF2097151 | numeric | yes | yes | Floating constant words |
| KS1-KS2097152 | numeric | yes | yes | Signed constant words |
| STW1-STW65536 | numeric | yes | yes | System status words |
| TCC1-TCC65536 | numeric | yes | yes | Timer/counter current |
| TCP1-TCP65536 | numeric | yes | yes | Timer/counter preset |
| Update | logical | yes | no | Goes FALSE when a poll starts and TRUE when a poll completes |
| V1-V2097152 | numeric | yes | yes | Internal words |
| V1.0-V2097152.15 | logical | yes | yes | Bits in internal words |
| VD1-VD2097151 | numeric | yes | yes | Internal double words |
| VDS1-VDS2097151 | numeric | yes | yes | Signed internal double words |
| VF1-VF2097151 | numeric | yes | yes | Floating words |
| VS1-VS2097152 | numeric | yes | yes | Signed internal words |
| WSY1-WYS2097152 | numeric | yes | yes | Signed output words |
| WX1-WX2097152 | numeric | yes | yes | Input words |
| WXS1-WXS2097152 | numeric | yes | yes | Signed input words |
| WY1-WY2097152 | numeric | yes | yes | Output words |
| X1-X2097152 | logical | yes | no | Input bits |
| Y1-Y2097152 | logical | yes | yes | Output bits |

Table 3-21. Applicom Telemecanique Data Members

| Data Member | Type | Read | Write | Description |
|----------------------------|---------|------|-------|---|
| B0-B4095 | logical | yes | yes | Internal bits |
| CommFail | logical | yes | no | Object-generated signal that is ON if Lookout cannot communicate with the device(s) |
| DW0-DW32766 | numeric | yes | yes | Internal double words |
| DWS0-DWS32766 | numeric | yes | yes | Signed internal double words |
| FW0-FW32766 | numeric | yes | yes | Internal floating words |
| I00.0-IF7.F | logical | yes | no | Input bits |
| IW00.0-IWF7.7 | numeric | yes | no | Words in input registers |
| IWS00.0-IWSF7.7 | numeric | yes | no | Signed words in input registers |
| O00.0-OF7.F | logical | yes | yes | Output bits |
| OW00.0-OWF7.7 Special | numeric | yes | yes | Words in output registers |
| OWS00.0-OWSF7.7 Special | numeric | yes | yes | Signed words in output registers |
| Update | logical | yes | no | Goes FALSE when a poll starts and TRUE when a poll completes |
| W0-W32767 | numeric | yes | yes | Internal words |
| WS0-WS32767 | numeric | yes | yes | Signed internal words |

General Information on Using the Applicom drivers for Lookout

The Applicom drivers for Lookout are all contained in `APPLICOM.CBX` (16- or 32-bit) which is designed to work with the Applicom server software distributed with every Applicom card. These drivers assume that you have version 2.9 or later of the Applicom software installed on the same computer under the same operating system as your copy of Lookout. The `APPLICOM.CBX` file presently supports 12 different object classes corresponding to 12 different protocols or object types.

Before you start using Lookout with Applicom, you must follow certain configuration and testing procedures to ensure that Lookout can

communicate with your devices. The steps include configuration, loading, testing, and if you choose, cyclic function configuration.

First, however, take special notice of the two different modes for using the Lookout Applicom driver—Image and Local. The distinction between these two modes is crucial to using the Lookout Applicom object classes.

Applicom Local and Image Modes

You can configure the Applicom server software to constantly poll a remote device and store data in a database onboard your Applicom card. You use *Local* mode to access that data.

In Lookout, you address the data using a generic addressing scheme (as a bit number, or word number, and so on.). The Applicom card takes care of polling the device and writing out new values to registers on the device. If there are any problems in communicating with the device, an error code may be generated and stored in a specified database location. The Lookout driver can then use the data at that location to generate alarms.

In *Image* mode you address data on the remote device according to the addressing scheme commonly used with the particular class of devices. In this mode, Lookout asks for data directly from a remote device and is notified of communication errors when they arise. The Lookout Applicom driver then retries the particular data transfer repeatedly, generating alarms when the data transfer continues to fail.

You use the Applicom Local object class for local mode functionality, and the other device- or protocol-specific object classes for image mode functionality. You can use Applicom Local concurrently with any of the other Applicom classes.

The Image mode classes are the typical way to use the Applicom driver for most applications. However, the Local mode provides a convenient way to achieve two goals: providing access to data from multiple applications (because any application may use the Applicom functions to access the local mode database); and allowing inputs from one device connected to a card to be written to outputs on another device connected to the same card without the interference of the Windows operating system or the client application (for example, Lookout).

Configuration of the Applicom Server

After you install the Applicom server software, you must first configure it using the `PCConf` utility provided as part of the Applicom software. Refer to the *Software Installation* section of your Applicom documentation for details on using Applicom software. You use the `PCConf` utility to set the basic types of devices connected to the Applicom card and the protocols used to connect to them. You also set all the communication parameters with this program.

While configuring your system with `PCConf`, make note of the **Channel** number and **Equipment** number for the device(s) you are using Lookout to communicate with. You will need these values as parameters when you create Lookout objects in Image mode.

Loading of the Applicom Server

After you configure the Applicom Server, you must download the appropriate firmware module to the card and then configure it. You do this by running the Applicom program `PCInit`. The configuration software notifies you at this time if there is any physical problem with the installation of the card.

You must run `PCInit` every time you restart the computer if you plan to communicate with the Applicom card and connected devices during that session. Because of this, you may consider putting a shortcut to this program in the Startup program group.

At this point, the Applicom server should be ready to communicate with Lookout and with the remote devices connected to the card. Before starting Lookout and attempting to communicate, you should first test the connections using some of the Applicom programs.

Testing the Applicom Server

The `ReadWait` program in the Applicom server group is a good example of a program that can be used to test the connectivity of the Applicom card with a remote device. You can also use `WritWait`, `Essai`, and `Essaigb`. Try performing read or write operations using these programs to test whether you can perform basic data transfer operations between the card and the devices. If these tests fail, Lookout will not be able to communicate with the devices either.

If your tests succeed and Lookout fails to communicate with the Applicom devices, it is likely that the problem is in the Lookout object configuration. Because the Applicom programs require you to use the channel and equipment numbers from the `PCConf` program, testing helps you verify that you have the correct numbers.

Creating the Cyclic Functions

There is only one more step before you start using the Lookout drivers, and it is required only if you are planning to use the Applicom Local object class. In that case, you must first configure the cyclic functions that exchange data between the onboard database of the Applicom card and the remote devices.

You do this by using either the Applicom `CreateCyc` or `PCCyc` utility programs. These programs require that you enter a channel number, an equipment number, and whether the required operation is a read or a write. You also enter the address of the data on the remote device and the requested address of the data in the database. Once you have created and saved the cyclic functions, you can test them using the `GetDB` and `SetDB` programs in the Applicom server.

After you verify that the card can communicate with the remote device, you can start using Lookout. Create a Lookout object of the appropriate class, enter the required parameters, and start communicating with the remote device.

Special Instructions on Using the Applicom Local Object Class

The Applicom Local object class behaves very differently from the Image mode object classes. To use it, you must have configured cyclic functions on your Applicom card using the Applicom `PCCyc` or `CreateCyc` programs.

After you configure these functions, you can create one or more Applicom Local objects in Lookout to read from or write to the Applicom database directly. The syntax is a generic syntax which does not correspond with the syntax you use with the PLC. The address you specify in Lookout must be the address of the data on the Applicom board, not the address on the remote device.

You can also specify a status word in the `PCCYC` program for each cyclic function you create. You can then specify a single status address in the object creation/modification dialog box for Applicom Local to get Lookout alarms any time the corresponding cyclic function is unable to exchange data successfully.

The Applicom Local object class is compatible with the other object classes so that you can create multiple Applicom object classes of any type and use them all at the same time.

Applicom Status Messages

The requested address is incorrect

You have requested data for an invalid address. Check the address and try again. For further details check the Applicom documentation for an explanation of error code 2.

Incorrect data type

The type of the data on the device is not compatible with the requested type. This may occur for different reasons in different protocols. For further details check the Applicom documentation for an explanation of error code 3.

Irretrievable data

The data you are trying to access is irretrievable. Please check that the device is connected and has all the appropriate models. For further details check the Applicom documentation for an explanation of error code 4.

Response timed out

The device did not respond to a message within the time-out period. Check that the device is connected. For further details, check the Applicom documentation for an explanation of error code 33.

Check word or parity fault

Check the channel and target equipment configuration and the wiring to the equipment. For further details, check the Applicom documentation for an explanation of error code 34.

Data not available in cyclic read

There was an error in reading from the card. Contact National Instruments technical support if this error occurs.

Equipment not configured

Configure the equipment with PCCConf. If you have already done so, check that you are using the correct (logical) equipment ID, as configured in PCCConf.

Deferred read or write request when deferred request register is full

There was an error in writing to the card. Contact National Instruments technical support if this error occurs.

Deferred request transfer attempt with transdif when request register is empty

There was an error in writing to the card. Contact National Instruments technical support if this error occurs.

Communication software not initialized

The Applicom board was not initialized using the PCInit software. Close Lookout, run PCInit and try running Lookout again.

Board number not configured

The board number you are attempting to use is not one that has been configured. Please check the configuration using PCCConf.

No Applicom interface

There is no Applicom interface present. Check that PCInit executed correctly.

Timeout elapsed. Message lost

A communication problem occurred that may be related to the configuration of the remote equipment or the bus that the equipment is on. For further details, check the Applicom documentation for an explanation of error code 55.

Negative acknowledgment (NAK) from equipment

A message was received by the destination equipment but not processed due to lack of resources. For further details, check the Applicom documentation for an explanation of error code 56.

Communication refused by the equipment.

The equipment is not responding to communication requests. This may be caused by a misconfigured device or by a bad connection with the Applicom card. Check the device configuration, check the Applicom configuration and use the Applicom utilities to check that there is communication between the two.

Bad frame received

The remote device is not behaving correctly. Check the configuration of the device.

Errorcode ID: refer to Applicom documentation

Your application has returned an error specific to your Applicom device. Consult your Applicom documentation for further information.

Aquatrol

Aquatrol is a protocol driver class Lookout uses to communicate with Aquatrol W1500 controllers.

Figure 3-7. Aquatrol Definition Parameters Dialog Box

Address is the address of the RTU as configured on the device. The address can be in the range of 100 to 999 inclusive.

Model is W1500 only at this time.

Serial port specifies which port the object uses for communication to the external device. This does not specify the communication type. Communication type is determined by the **Options»Serial Ports...** command.

Data rate, Parity, Data bits, and Stop bits reference the settings on the hardware device.

Phone specifies the number to be dialed if the serial port setting is configured for dial-up. This number only applies to the individual protocol object.

PollRate is a numeric expression that determines how often to poll the device. Lookout converts the numeric value of **PollRate** into a time signal that represents days and fractions of a day. Aquatrol then polls the device at the specified time interval. Normally, this is a time constant such as

0:01 (one second). See the *Numeric Data Members* section in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Poll is a logical expression. When this expression changes from false to true, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of object-generated alarms (0 – 10).

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the Aquatrol object generates an alarm and releases the communication port back to the communications service which then moves on to the next device in the polling queue (if any).

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

The **Skip every...** setting instructs Lookout not to poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle accordingly. Once communications have been reestablished, the device is polled on its regular cycle.

RTU Configuration Dialog Box

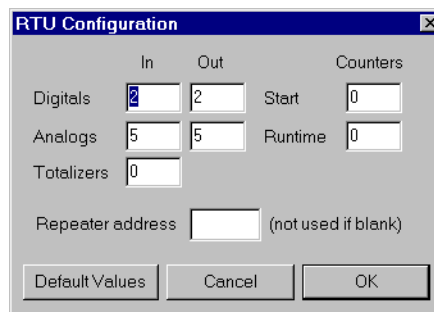


Figure 3-8. RTU Configuration Dialog Box

You must configure Lookout to match the configuration in your Aquatrol device.

Digital (In/Out) specifies configuration for the number of discrete I/O.

Analogs (In/Out) specifies configuration for the number of analog I/O.

Totalizers specifies configuration for the number of totalizers.

Start specifies configuration for the number of start counters.

Runtime specifies configuration for the number of runtime counters.

Repeater Address is the final destination address if a repeater is being used.



Note The Aquatrol must be configured with all I/O grouped together by kind. Digital inputs must be the first physical inputs on the device, followed by digital outputs. Analog inputs are next, followed by analog outputs. If you do not configure the I/O this way, you can receive invalid data.

Aquatrol Data Members

All readable and writable members (inputs/outputs), polling instructions, read/write blocking, serial port usage, and so on, are bundled with the object. Therefore, as soon as you create an Aquatrol object you immediately have access to all the object data members (see data member list in Table 3-22).



Note Lookout protocol driver objects automatically generate an efficient read/write blocking scheme based on the inputs and outputs being used in your process file. You are not required to build your own I/O blocking table.

Table 3-22. Aquatrol Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|---|
| AI1-AI48 | numeric | yes | no | Analog Input, 16 bit. |
| AO1-AO48 | numeric | no | yes | Analog Output, 16 bit. |
| ColdRestart | logical | yes | no | True if the device power has cycled on/off or the reset button has been pushed. |
| CommFail | logical | yes | no | True if serial communications have failed. |

Table 3-22. Aquatrol Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|--|
| ConfigError | logical | yes | no | True if the configuration of the device does not match the configuration set in the configuration dialog of the Aquatrol device. |
| DataFail | logical | yes | no | True if the device has had a data failure. |
| DI1-DI48 | logical | yes | no | Discrete Input, 1 bit. |
| DO1-DO48 | logical | no | yes | Discrete Output, 1 bit. |
| EEPROMerror | logical | yes | no | True if the device has an EEPROM error. |
| LowBattery | logical | yes | no | True if the device has a low battery. |
| Poll | logical | no | yes | True initiates a Poll sequence. |
| PollRate | numeric | no | yes | Time interval of Polling sequence. |
| PowerFail | logical | yes | no | True if there is no power to the device. |
| R1-R48 | numeric | yes | no | Runtimes, 16 bit. |
| S1-S48 | numeric | yes | no | Starts, 16 bit. |
| T1-T48 | numeric | yes | no | Totalizers, 16 bit. |
| Update | logical | yes | no | False during Polling sequence. |
| WarmRestart | logical | yes | no | True if the device has been reset locally. |

Aquatrol Status Messages

No response within timeout period

No response within timeout period for repeated message. Lookout did not receive the expected response within the **Receive timeout** period. The object sent an inquiry and received an acknowledgment, but the device did not send an expected response to the request. This might happen if the response was interrupted. You may have to increase **Receive timeout**.

Frame Error (garbled): Invalid destination address

Lookout has received a frame with an invalid return address. Make sure that no duplicate addresses exist on the Aquatrol network.

Frame Error (garbled): Invalid source address

Lookout has received a frame from a device that you are not actively polling. Make sure that there is only one outstanding master request at a time.

Frame Error (garbled): Invalid message length for configuration

Lookout has received a frame whose length conflicts with the length expected based on the configuration settings in the Aquatrol device configuration dialog box.

Frame Error (garbled): Invalid CRC

Lookout has received a frame with an invalid CRC (cyclic redundancy check). Check for signal noise on Aquatrol network.

Invalid discrete address #: Check configuration settings

Invalid analog address #: Check configuration settings

Invalid runtime address #: Check configuration settings

Invalid start address #: Check configuration settings

Invalid totalizer address #: Check configuration settings

All these errors mean that a I/O point being either read or written is out of range with respect to the configuration set in the Aquatrol device configuration dialog box.

ASCII

ASCII is a protocol driver class Lookout uses to communicate with any serial device that accepts ASCII characters. This object is only available with 32-bit versions of Lookout.

An ASCII object contains no predefined data points. When you create an ASCII object, you must define your data request strings as well as the template Lookout uses to parse the response frame.



Figure 3-9. ASCII Definition Parameters Dialog Box

Serial port specifies which COM port the object uses for communicating to the external device. This does not specify the communication type. Communication type is determined by the **Options»Serial Ports...** command.

Baud rate indicates the rate that Lookout uses to communicate with the hardware device.

Data bits indicates the number of data bits that Lookout uses to communicate with the hardware. This setting should match the selection made on the physical device.

Stop bits indicates the number of stop bits that Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Parity indicates the parity that Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Phone number specifies the number to be dialed if the selected serial port is configured for dial-up. This number only applies to the individual protocol object.

Monitor Serial Port specifies whether you can receive unsolicited frames.

Communication alarm priority determines the priority level of alarms generated by the ASCII object. Such alarms are typically related to communications with the physical device.

Retry attempts specifies the number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the ASCII object generates an alarm and releases the communication port back to the communications service which then moves on to the next device in the polling queue (if any). Refer to Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

Receive timeout is the amount of time Lookout waits for a response from a device before retrying the request.

The **Skip every N poll requests after comm failure** setting instructs Lookout not to poll a device it has lost communication with on every scheduled poll. Instead, Lookout polls the device only once in the specified number of poll cycles. Once communication has been reestablished, the device is polled on its regular cycle.

ASCII Data Members

Table 3-23. ASCII Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|--|
| CommFail | logical | yes | no | Object-generated signal that is on if Lookout cannot communicate with the device(s). |
| OffHook | logical | no | yes | Keeps the driver from releasing the serial port. |
| Request | text | yes | no | Exact request frame sent. |

Table 3-23. ASCII Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--|-------------|-------------|--------------|--|
| RequestFormat | text | no | yes | Format used to create request frame. |
| Response | text | yes | no | Exact response frame received. |
| ResponseFormat | text | no | yes | Format used to parse response frame. |
| RQSum:1:1 - RQSum255:255 | numeric | yes | no | Request byte sum |
| RQV1, RQV512 | numeric | no | yes | Variable list used to populate request frame with numeric values. |
| RQV1.logical, RQV512.logical | logical | no | yes | Variable list used to populate request frame with logical values. |
| RQV1.txt, RQV512.txt | text | no | yes | Variable list used to populate request frame with text values. |
| RSFilter | text | no | yes | All characters in this string will be filtered out of the incoming response before processing. |
| RSSum1:1 - RSSum255:255 | numeric | yes | no | Response byte sum |
| RSV1, RSV512 | numeric | yes | no | Variable list used to store values retrieved from response frame. |
| RSV1.logical, RSV512.logical | logical | yes | no | Variable list used to store values retrieved from response frame. |
| RSV1.txt, RSV512.txt | text | yes | no | Variable list used to store values retrieved from response frame. |
| Send | logical | no | yes | Sends request frame. |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device. |
| RSVn, RSVn.txt and RSVn.logical all represent the same value in different forms RQVn, RQVn.txt and RQVn.logical all represent the same value in different forms | | | | |

Request and Response Format Strings

The request and response format strings consist of static characters and markers that control how the request and response frames respectively are formatted or decoded. The request format string is used to *create* the request frame, which is sent to the device, while the response format string is used to *decode* the response frame, which comes from the device.

Static characters in the format strings are reproduced exactly in the request or response frame. Markers specify the location within the frame and type of data which should be found there, such as five characters read as an unsigned integer, for example. The ASCII object constructs a request frame by processing the sequence of static characters and markers in the request format string, and including data from RQV data members.

The response format string decodes a response frame using an analogous process, storing the results in RSV data members.

To construct a request frame, the ASCII object parses the request format string character by character. Static characters are copied directly to the request frame. When a marker is encountered the ASCII object reads a value from the appropriate RQV variable and places it into the request frame.

There are 512 RQV and RSV values provided for in the ASCII object data member collection. The first marker in a format string uses the value from RQV1 (or RQV1.txt or RQV1.logical), the next marker uses the value RQV2, and so on. Values taken from Response strings are stored in RSV data members in the same way.

Keep in mind that writing into RQV1 changes the value both for RQV1.txt and RQV1.logical. Their only difference is the format in which they are represented. The same principle applies to the RSV data members.



Note There is no precedence to the order in which multiple objects connected to the same variable number initialize upon opening the process file. Consider, for example, the case in which a Pot object is connected to RQV1 while a TextEntry object is connected to RQV1.txt. You should take care to initialize such variables to the proper value after opening a process file.

To decode a response frame, the ASCII object compares the response frame to the response format string character by character. The static characters in the response frame must match those in the response format string or the decoding process terminates. Static characters are, in effect, discarded

by the ASCII object as they are matched between the response format string and the response frame.

When the ASCII object encounters a marker, it places the data indicated by the marker into the appropriate RSV data member.

The conversion of a portion of the response frame to a data type specified by a marker in the response format string must be valid, or the process will terminate.

If nothing halts the process, decoding terminates when the end of the response frame string is reached.

There are examples of both request frames and response frames at the end of this section, but for the examples to make sense, you must first understand the ASCII object markers.

ASCII Object Markers

The general format for a marker is:

$$\%[\text{width}][\text{type}]$$

Each field in the marker format is a single character or a number signifying a particular format option.

The % sign denotes the beginning of the marker. For example, to specify that a percent-sign character is a static character part of the frame, use %%.

Width is a positive decimal integer specifying the number of characters that particular value occupies in the frame. By default ASCII pads the value with blank spaces if the value takes up fewer characters than the value specified by width. Including a 0 before the width value forces the ASCII object to pad with zeroes instead of blank spaces.

Type determines whether the field is interpreted as a character, a string, or a number.

Table 3-24. Data Types Allowed by ASCII

| Character | Data Type |
|-----------|-----------------|
| c | Character |
| d | Decimal integer |
| O, o | Octal |

Table 3-24. Data Types Allowed by ASCII

| | |
|--|--------------------------|
| x, X | Hexadecimal integer |
| u | Unsigned decimal integer |
| e, f | Floating-point |
| s | String |
| b* | Byte (binary) |
| <p>*For the %b data type:</p> <ul style="list-style-type: none"> – Number of bytes can be specified, for example %3b, %2b. – Response format can read as either signed or unsigned, for example %^b and %3^b are signed and %b is unsigned. – Endian order can be specified, for example %3~b is big endian and %3b is little endian. %5~^b and %2^~b forms are also valid. | |

The simplest format specification contains only the percent sign and a type character (for example, %s). That would place the value in the response frame in the RSV1.txt data member.

| Request Format String | RQV1 | Request Frame |
|-----------------------|------|---------------|
| >%5d | 34 | > 34 |
| >%05d | 34 | >00034 |

The request format string also has a precision value in the form %**[width].[precision][type]**. This specifies the number of digits to the right of the decimal point, if any, in the request frame. If you use a float (%f) and do not specify a precision value, the ASCII object assumes a default of 6.

Characters are converted and stored in RSV data members from response frames in the order they are encountered in the response format. However, fewer than **[width]** characters may be read if a white-space character (space, tab, or newline) or a character that cannot be converted according to the given format occurs before **[width]** is reached.

Values needed for request frames come from the RQV data members, and are also used in the order in which they occur in the request format.

To read strings not delimited by space characters, or that contain spaces, you can substitute a set of characters in brackets ([]) s (string) type

character. The corresponding input field is read up to the first character that does not appear in the bracketed character set. Using a caret (^) as the first character in the set reverses this effect: the ASCII object reads input field up to the first character that does appear in the rest of the character set.

| Response Format String | RSV1.txt | Response Frame |
|------------------------------------|-----------|----------------------------|
| <code>\$\$[A – Z,a – z,]\$</code> | Natl Inst | <code>\$Natl Inst\$</code> |
| <code>>^[^,s]</code> | days | <code>>day</code> |

Notice that `%[a – z]` and `%[z – a]` are interpreted as equivalent to `%[abcde...z]`, and that the character set is case sensitive. Valid control characters accepted include `\a`, `\A`, `\b`, `\B`, `\f`, `\F`, `\n`, `\N`, `\r`, `\R`, `\t`, `\T`, `\v`, `\V`, `\l`, `\’`, and `\?`.

Any ASCII character can be specified in the format string using `\xbb` or `\nnn` masks. `\xbb` is a hexadecimal byte with each `b` representing a valid hex character in the range (0...9, a...F), for example `\xff` or `\x1a`.

`\nnn` is an octal byte with each `n` being a valid octal character in the range 0 to 7, for example `\123` or `\347`. This value may not exceed 255 as it is meant to represent a single byte of data. These two features can be used to create and compare static characters. These can also be specified in the regular expression, for example `%[\xff, \123, \a, \b]` is a valid frame.



Note The brackets only work in response format strings. They have no effect in the request format string.

The ASCII object scans each field in the response frame character by character. It may stop reading a particular field before it reaches a character for a variety of reasons:

- The specified width has been reached.
- The next character cannot be converted as specified.
- The next character conflicts with a character in the response format string that it is supposed to match.
- The next character fails to appear in a given character set.

No matter what the reason, when the ASCII object stops reading a field, the next field is considered to begin at the first unread character. The conflicting character, if there is one, is considered unread and is the first character of the next field.

Entering ASCII Object Format String

For a static connection to one of the format data members, enter your format string in the yellow field box in the Edit Connections dialog box. Remember to begin and end the format strings with quotation marks so that Lookout accepts the string input.

You can also connect any valid text data member, such as a text entry object, to the format data members.

Request Frame Construction Examples

| Request Format String | RQV | Request Frame |
|-----------------------|-----------------------------|---------------|
| <01%4u%s | RQV1=1234 RQV2.txt=Steph | <011234Steph |
| <01%04u%s | RQV1=34 RQV2.txt=Steph | <010034Steph |
| <01% 4u%s | RQV1=34 RQV2.txt=Steph | <01 34Steph |

A zero in front of the four pads with zeroes; a space pads with spaces.

Response Format Examples

| Response Frame | Response Format String | RSV |
|----------------|------------------------|------------|
| *(16.38: | *(%52f: | RSV1=16.38 |



Note The decimal point counts as a character when decoding floats (%f). Also, decimal points denoting precision are not allowed when decoding a float in the response frame.

| Response Frame | Response Format String | RSV |
|----------------|------------------------|---------------|
| >>Test Text<< | >>%s<< | RSV1.txt=Test |

The space between the words terminates the conversion. See the preceding bracketed character example in order to span a space or other special characters.

| Response Frame | Response Format String | RSV |
|----------------|------------------------|--------------------------------|
| >>Test Text<< | >>%s%s<< | RSV1.txt=Test RSV2.txt=Text |
| >>DogCat<< | >>%3s%3s<< | RSV1.txt=Dog RSV2.txt=Cat |

The response format uses a space as a delimiter.

Using Sum Data Members

The ASCII object includes summing data members you can use to calculate checksum characters. This can be a checksum you want to write into an outgoing request frame or a checksum you want to verify in an incoming response frame.

For example, if you want to calculate a checksum for the request A00B, you would use an RQSum (request sum) data member. In the case of A00B, you would use RQSum1 : 4, which would give you a sum of the ASCII byte values of characters 1 through 4. Once you have this sum, you can manipulate it mathematically any way necessary for the checksum value you need. You can then insert this value at the end of your frame as a byte (%b) or a series of bytes.

The same technique works in reverse for RSSum (response sum) data members.

For example, consider the response Z00A@. You know that you are expecting 4 bytes plus a checksum. Assuming that this checksum calculation involves the first four characters, use RSSum1 : 4 to get the byte sum of characters 1 through 4. After performing the appropriate mathematical manipulation, you can compare this value with the actual byte read from the frame, and determine when there is a checksum failure.



Note There are many different methods for calculating checksums, and these data members cannot support all of them. Before attempting to use them for checksum calculation, make sure your checksum can be calculated from a simple byte sum of characters in the frame.

ASCII Error Messages

No response from device within timeout period

Lookout received no response from the device within the **Receive timeout** period. The ASCII object was able to establish a socket, but when it sent a message to the device, the device did not respond—as if it were not there. You may have to significantly increase **Receive timeout** (and **Poll Rate**) to ensure Lookout is allowing enough time to receive the expected response. Also, verify your cable connections, power, configuration settings, and IP settings.

Not enough data to send a valid frame

This means that the ASCII object has not received enough data to fill in all the variables in the Request Format frame. This could mean that you do not have connections made to all of the RQVs that the ASCII object is expecting.

Frame Error (garbled)

ASCII got a response frame, but static characters in the response did not match up to the response format string.

Data type or length does not match format string

ASCII got a response frame, but certain characters in the response were not in the format stated by the markers in the response format string.

Illegal control character

The request frame had a % modifier followed by an invalid control code.

Related Objects [*IPASCII*](#)

Cutler-Hammer

Cutler-Hammer is a protocol driver class Lookout uses to communicate with Cutler-Hammer devices using serial communications.

It supports reading and writing of all predefined data points allowed by the particular Cutler-Hammer model. When you create a Cutler-Hammer object, you have immediate access to all the object data members. See the [Cutler-Hammer Data Member Set](#) table for more information on data members for this object.

The screenshot shows a dialog box titled "Create Cutler-Hammer Secondary (BETA)". It has the following fields and controls:

- Name:
- Address: PLC Model:
- Communication Settings:
 - Serial port: Data bits:
 - Baud Rate: Stop bits:
 - Parity:
 - Phone number:
- PollRate = (highlighted in yellow)
- Poll = (highlighted in yellow)
- Communication alarm priority:
- Retry attempts: Receive timeout: msecs
- Skip every poll requests after comm failure
- Buttons: OK, Cancel, Help

Figure 3-10. Cutler-Hammer Definition Parameters Dialog Box

Address specifies which Cutler-Hammer device you are communicating with using this object. This number is between 0 and 191, and is set on the device. (An address number of 255 broadcasts to all devices connected to the network.)

PLC Model specifies what model of Cutler-Hammer device you are using. The only model supported now is the Cutler-Hammer D50.

Serial port specifies which comm port the object uses for communicating to the external device. This does not specify the communication type. Communication type is determined by the **Options»Serial Ports** command.



Note For Lookout to communicate correctly with the Cutler-Hammer D50, you must configure your COM port as `radio` using the **Options»Serial Ports** command.

Data rate indicates the baud rate that Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Data bits indicates the number of data bits that Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Stop bits indicates the number of stop bits that Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Parity indicates the parity that Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Phone number specifies the number to be dialed if the selected serial port is configured for dial-up. This number only applies to the individual protocol object.

PollRate is a numeric expression that determines how often to poll the device. Lookout converts the numeric value of **PollRate** into a time signal that represents days and fractions of a day. The object then polls the device at the specified time interval. Normally, this is a time constant such as 0:01 (one second). See the *Numeric Data Members* section in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Poll is a logical expression. When this expression changes from false to true, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of alarms generated by the Cutler-Hammer object. Such alarms are typically related to communications with the physical device.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the Cutler-Hammer object generates an alarm and releases the comm port. See Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

The **Skip every N poll requests after comm failure** setting instructs Lookout to not poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle accordingly. Once communications have been reestablished, the device is polled on its regular cycle.

Cutler-Hammer Data Members

As with all Lookout drivers, you can access I/O points and other data through data members. The following is a table of data members currently supported by the Cutler-Hammer object class.

Table 3-25. Cutler-Hammer Data Member Set

| Data Member | Type | Read | Write | Description |
|---------------------------------|---------|------|-------|---|
| CommFail | logical | yes | no | Goes high if Lookout cannot communicate with the device |
| K0000 - K0015 | numeric | yes | yes | Keep relay |
| K00000.logical - K01515.logical | logical | yes | yes | Keep relay |
| M0000 - M0031 | numeric | yes | yes | Internal relay |
| M00000.logical - M03115.logical | logical | yes | yes | Internal relay |
| Poll | logical | no | yes | When transitioned from low to high, Lookout begins a poll cycle on the device |
| PollRate | numeric | no | yes | Specifies the frequency at which Lookout polls the device |
| R00000.logical - R02915.logical | logical | yes | yes | External inputs and outputs, and special function registers |

Table 3-25. Cutler-Hammer Data Member Set (Continued)

| Data Member | Type | Read | Write | Description |
|---|-------------|-------------|--------------|--|
| Update | logical | yes | no | Goes high when Lookout begins a poll cycle on the device |
| W0000 - W2815 | numeric | yes | yes | Timers, counters, and word registers |
| For a more complete definition of the function of these data members, see Cutler-Hammer documentation. Not all of these data members are valid for every Cutler-Hammer device. See Cutler-Hammer documentation to see which data members are valid for your particular model number. | | | | |

Cutler-Hammer Status Messages

No response within timeout period

Lookout received no response from a device within the **Receive timeout** period. The Cutler-Hammer object is able to use the comm port, but when it polls the device, it does not respond—as if it is not even there. If you have daisy-chained several devices, you may have introduced an inherent delay. You may have to significantly increase **Receive timeout** (and **Poll Rate**) to ensure Lookout is allowing enough time to receive the expected response. This increase has nothing to do with the processing capabilities of Lookout. Rather it is based solely on **Data rate** and the number of devices on the chain. Also, verify your baud rate settings, cable connections, power, configuration settings, comm port settings, and polling addresses.

Invalid query acknowledge frame

This means that the query acknowledge frame sent from the PLC in response to the command sent by Lookout out was invalid.

Invalid PLC address in response frame

This means that the address within the response frame from the PLC does not match exactly the address in the command sent out by Lookout. You may possibly be requesting an address that is outside the valid range from Cutler-Hammer devices.

Invalid CRC in response

This means the checksum (CRC in this case) failed in a frame received by Lookout. Check cabling or for two or more devices with the same address.

Garbled or invalid frame

Frame received without format characters in their proper positions. Check the **Receive gap** setting.

Invalid response frame

This means that the response frame from the PLC did not have the expected number of bytes in it.

Invalid function code in response frame

This means that the function code within the response frame from the PLC does not match the function code in the command sent out by Lookout.

Wrong query, length, or designation

This is an error returned as an error code frame from the Cutler-Hammer device. This means that the device could not successfully interpret the query you just sent it.

Designated range exceeded

This is an error returned as an error code frame from the Cutler-Hammer device. It means you have requested an address beyond the valid range of addresses.

Command too long in length

This is an error returned as an error code frame from the Cutler-Hammer device. This means that the frame just sent has exceeded the maximum amount information that can be transported in a single frame (256 bytes).

Abnormal communications command

This is an error returned as an error code frame from the Cutler-Hammer device.

Cutler-Hammer models supported:

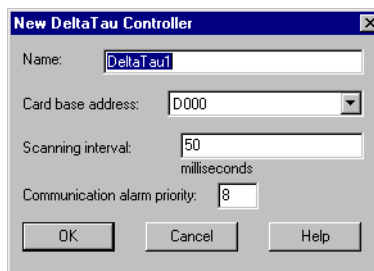
D50

DeltaTau

DeltaTau is a protocol driver object class Lookout uses to communicate with Delta Tau Data Systems PMAC Motion Controllers. Create a DeltaTau object for each card installed in the computer.

This object class communicates with Delta Tau PMAC cards through dual-ported memory, so be sure that your PMAC hardware includes the dual-ported RAM option.

The following figure shows a Delta Tau card configured to use PC memory beginning at address D000.



Card base address specifies the beginning memory location of the dual ported RAM address. It should match card settings.

Scanning Interval identifies the frequency that the DeltaTau object in Lookout polls the PMAC Motion Controller. Intervals can range from 10 ms to 1,000 ms.

Communication alarm priority specifies the priority level of alarms generated by the object.

DeltaTau Data members

Like other protocol driver objects, DeltaTau objects contain a great deal of data. All readable and writable members (inputs/outputs), polling instructions, and so on, are bundled with the object. Therefore, as soon as you create a DeltaTau object you immediately have access to all the object data members. The following table lists data members for the DeltaTau object.

Table 3-26. DeltaTau Data Members

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---|
| DS0 – DS8190 | numeric | yes | yes | Signed 32-bit word ranging from –2,147,483,648 to 2,147,483,647 |
| DW0 – DW8190 | numeric | yes | yes | 32-Bit double-precision word ranging from 0 to 4,294,967,295 |
| F0 – F8188 | numeric | yes | yes | 32-bit IEEE floating point word |
| S0 – S8190 | numeric | yes | yes | Signed 16-bit word ranging from –32,768 to 32,767 |
| Update | logical | yes | no | Driver-generated signal that pulses each time Lookout scans the PMAC Motion Controller card |
| W0 – W8190 | numeric | yes | yes | 16-Bit word ranging from 0 to 65,535 |
| W0.0 – W8190.15 | logical | yes | yes | 1 Bit in a 16-Bit word |

DL205, DL405

DL205 and DL405 are protocol driver object classes Lookout uses to communicate with Koyo 205 and 405 PLCs, and other devices that use the CCM protocol.

Koyo sells the 205 and 405 models under private brand labels. PLCDirect offers the units as the DirectLOGIC 205 and 405 PLCs, and Siemens offers the 405 unit as the TI405 series.

The DL205 and DL405 object classes support the Koyos native protocol, CCM, which is also called DirectNET by PLCDirect and HostLink by Siemens. This documentation refers to this protocol as CCM.

The DL205 and DL405 object classes support both point-to-point and multidrop configurations. You can connect Lookout to a PLC programming port, built-in DirectNET/HostLink port, or to the PLC DCM (data communication module). These PLC communication ports use two different versions of the CCM protocol: K-sequence and N-sequence. Lookout supports both.

The screenshot shows the 'Create DL205' dialog box with the following settings:

- Name: DL1
- PLC Address: (empty)
- Model: DL240
- Protocol: Lower port (n)
- Serial Settings:
 - Serial port: COM1
 - Parity: Odd
 - Data bits: 8
 - Stop bits: 1
 - Data rate: 19200
- Phone number: (empty)
- PollRate = 0.01
- Poll = (empty)
- Communication alarm priority: 8
- Retry attempts: 4
- Receive timeout: 500 msec
- Skip every 5 poll requests after comm failure

Figure 3-11. DL205 Parameters Configured for one PLC in a Multidropped Configuration

Protocol identifies the CCM port you use to communicate with the device. If you are planning to connect Lookout to a single PLC in a point-to-point configuration, choose the `UPPER PORT (k)` **Protocol** and use the PLC programming port. It supports K-sequence CCM. With this version of the CCM protocol you can write directly to logical outputs.

If you are planning to network multiple PLCs in a multidrop configuration where Lookout is the host computer, you must use the built-in PLC DirectNET/HostLink port, or its DCM. Choose the `LOWER PORT (n)` or `DCM (n) Protocol` as appropriate. These ports support N-sequence CCM. The N-sequence CCM protocol does not permit writes directly to logical data members.



Note Although you can connect logical signals to data members such as Y0 in Lookout, any time you attempt to write to such a data member using the N-sequence CCM protocol, the write request is ignored. (This is due to the limitations of N-sequence CCM protocol.) If you have to write out a logical value using N-sequence, consider parsing the corresponding VU address into a binary number and setting the bit you want to use by writing a corresponding decimal integer. If you write a zero or 65535 to the corresponding VU-memory location, you will write all zeros or ones to every bit in the register.

PLC Address is a slave address and refers to the address setting as set on the physical device. If you are connecting to the PLC programming port, set **PLC Address** to 1. If multiple devices share a common line, enter the unique addresses of the device (1 to 255).

Use **Model** to choose the PLC model you want to use. If you are using a model not listed, select a model whose data set most closely fits the model you are using.

Serial port specifies which COM port on your computer that the object uses for communicating to the PLC. This does not specify the communication type. Communication type is determined by the **Options»Serial Ports...** command.

Data rate, Parity, Data bits, and Stop bits should match the PLC settings.

Phone number specifies the number to be dialed if the selected serial port is configured for dial-up. This number only applies to the individual protocol object.

PollRate is a numeric expression that determines how often to poll the device. The object then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second).

See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Poll is a logical expression. When this expression changes from false to true, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of alarms generated by the object. Such alarms are typically related to communications with the physical device.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device it does not get a valid response from. After the object retries communications the specified number of times, it generates a communication alarm and Lookout moves on to the next device in the polling queue (if any). Refer to Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

The **Skip every...** setting instructs Lookout to not poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle accordingly. Once communications have been reestablished, the device is polled on its regular cycle.

DL205 and DL405 Data Members

Protocol driver objects contain a great deal of data. V-memory addresses, registers, inputs and outputs are all bundled with the object. Therefore, as soon as you create a DL205 object you have immediate access to the entire data member set of the object (see data member list in Table 3-27).

As with all Lookout drivers, you can access I/O points and other data through data members. The DL205 and DL405 object classes automatically generate an efficient read/write blocking scheme based on the inputs and outputs you are using in your process file. So, you do not have to build your own I/O blocking table. When Lookout polls a device, it optimizes frame exchange according to the data length required and overhead needed. The maximum data frame size that these drivers request is 256 data bytes. The drivers use LRC and parity error checking to validate data.

The following is a table of data members currently supported by the DL205 and DL405 object class.

Table 3-27. DL205 and DL405 Data Members

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|--|
| C0 – C3777 | logical | yes | yes | Control Relays—addressed in octal and mapped to V40600 – V40700. |
| CommFail | logical | yes | no | Object-generated signal that is on if, for whatever reason, Lookout cannot communicate with the device. |
| CT0 – CT377 | logical | yes | yes | Counter status bits—addressed in octal and mapped to V41140 – V41147. |
| OffHook | logical | no | yes | When TRUE, this flag instructs the DL object to retain exclusive use of its assigned communication port. |
| Poll | logical | no | yes | When this value transitions from FALSE to TRUE, Lookout polls the device. |
| PollRate | numeric | no | yes | Lookout expression that determines the device polling frequency. |
| S0 – S1777 | logical | yes | yes | Stages—addressed in octal and mapped to V41000 – V41037. |
| SPA0 – SPA177 | logical | yes | yes | Lower special relays—addressed in octal. |
| SPB320 – SPB717 | logical | yes | yes | Upper special relays—addressed in octal. |
| T0 – T377 | logical | yes | yes | Timer status bits—addressed in octal and mapped to V41100 – V41107. |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device. |
| V0 – V41230 | numeric | yes | yes | Signed V-memory register containing 16-bit integer ranging from –32768 to 32767 dec. |

Table 3-27. DL205 and DL405 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|---|-------------|-------------|--------------|---|
| V0.0 – V41230.17 | logical | yes | no | Individual bits within V-memory registers—the least significant bit is 0, the most significant bit is 17 (octal). |
| VBCD0-VBDC41230 | numeric | yes | yes | V-memory as BCD. |
| VD0 – VD41227 | numeric | yes | yes | Double—reads two adjacent V-memory registers as a single 32-bit integer ranging from 0 to 4,294,967,296. |
| VDBCD0-VDBCD41227 | numeric | yes | yes | V-memory double as BCD. |
| VF0 – VF41227 | numeric | yes | yes | Float—reads two adjacent V-memory registers as a single 32-bit floating point value. |
| VU0 – VU41230 | numeric | yes | yes | Unsigned—V-memory register holding 16-bit unsigned integer ranging from 0 to 65535. |
| X0 – X1777* | logical | yes | yes | Discrete input points—addressed in octal and mapped to V40400 – V40407. |
| Y0 – Y1777* | logical | yes | yes | Discrete output points—addressed in octal and mapped to V40500 – V40507. |
| * 205 series PLCs are limited to 128 input and output points total . You can mix these addresses as necessary, but understand that Y17 and X17 refer to the same memory location on DL205. | | | | |

DL205 and DL405 Status Messages

No response within timeout period

Lookout did not receive the expected response within the **Receive timeout** period. The object sent an inquiry and received an acknowledgment, but the device did not send an expected response to the request. This might happen if the response was interrupted. You may have to increase **Receive timeout**.

No return inquiry response from secondary unit

Lookout received no response from the device within the **Receive timeout** period. The driver object is able to use the COM port, but when it polls

the device, it does not respond—as if it is not even there. You may have to increase **Receive timeout** to ensure Lookout is allowing enough time to receive the expected response. Also, verify your baud rate settings, cable connections, power, configuration settings, COM port settings, and polling addresses.

Bad LRC

The object is receiving a poll response from the device, but it could not decipher the response because it is garbled. Verify that all devices connected to the COM port have unique addresses. The last part of the message may actually be getting clipped off before it is completed. Consider increasing the number of **Retry attempts**. You may have to increase the **Receive gap** Serial Port setting to ensure Lookout is receiving the entire message. If your Serial Port is configured for radio, this could be caused by an audible squelch tail occurring at the end of a radio transmission. Try adjusting **RTS delay off** and **CTS timeout**.

No acknowledgment for header frame

You sent an inquiry and some kind of data write or read, but the device has not responded. The object was expecting an acknowledgment for an instruction frame and did not receive it. You may be asking for an invalid memory address. Recheck your PLC memory address configuration. Also verify that the PLC communication port supports the **CCM Protocol** that you selected.

Invalid request frame

You are probably trying to use an invalid memory address. Recheck your PLC address configuration.

DNP

Use the DNP driver to connect to specific devices using the Distributed Network Protocol version 3.0.

The screenshot shows a dialog box titled "Create DNP Secondary (BETA1)". It contains the following fields and controls:

- Name: DNP1
- Address: 0
- Source Address: 255
- Communication Settings:
 - Serial port: COM1
 - Data bits: 8
 - Baud Rate: 9600
 - Stop bits: 1
 - Parity: None
 - Phone number: (empty)
- PollRate = 0.01
- Poll = (empty)
- Communication alarm priority: 8
- Retry attempts: 4
- Receive timeout: 250 msecs
- Skip every 5 poll requests after comm failure
- Buttons: Ok, Cancel, Help

Address specifies which device you are communicating with using this object. This number is between 0 and 255, and is set on the device.

Source Address specifies the DNP address of the computer running Lookout.

Serial port specifies which port the object uses for communication to the external device. This does not specify the communication type. You set communication type in the **Serial Ports** dialog box. Select **Options»Serial Ports** to access this dialog box.

Baud Rate, Parity, Data bits, and Stop bits reference the settings on the hardware device.

Phone number specifies the number to be dialed if the serial port setting is configured for dial-up. This number only applies to the individual protocol object.

PollRate is a numeric expression that determines how often to poll your DNP device. The object then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second).

See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for more information.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls your DNP device for data from the specified device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

The **Skip *N* poll requests after COM failure** setting instructs Lookout to not poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle. Once communications have been reestablished, the device is polled on its regular cycle.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the DNP object generates an alarm and releases the communication port back to the communications service which then moves on to the next device in the polling queue (if any).

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

Communication alarm priority determines the priority level of alarms generated by the object. Such alarms are typically related to communications with the physical device.

DNP Data Members

Table 3-28. DNP Data Members

| Data Member | Type | Read | Write | Description |
|---------------------|---------|------|-------|--|
| AINDW0-AINDW65535 | numeric | yes | no | 32-bit analog input (object 30, variation 3) |
| AINFDW0-AINFDW65535 | numeric | yes | no | 32-bit analog input with flag (object 30, variation 1) |
| AINFW0-AINFW65535 | numeric | yes | no | 16-bit analog input with flag (object 30, variation 2) |
| AINW0-AINW65535 | numeric | yes | no | 16-bit analog input (object 30, variation 4) |

Table 3-28. DNP Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|-----------------------|-------------|-------------|--------------|--|
| AOUTFDW0-AOUTFDW65535 | numeric | yes | yes | 32-bit analog output with flag (object 40, variation 1) |
| AOUTFW0-AOUTFW65535 | numeric | yes | yes | 16-bit analog output with flag (object 40, variation 2) |
| BIN0-BIN65535 | logical | yes | no | Binary input (object 1, variation 1) |
| BINS0-BINS65535 | logical | yes | no | Binary input with status (object 1, variation 2) |
| BOUT0-BOUT65535 | logical | yes | yes | Binary output (object 10, variation 1) |
| BOUTS0-BOUTS65535 | logical | yes | yes | Binary output with status (object 10, variation 2) |
| CNTDW0-CNTDW65535 | numeric | yes | no | 32-bit counter (object 20, variation 5) |
| CNTFDW0-CNTFDW65535 | numeric | yes | no | 32-bit counter with flag (object 20, variation 1) |
| CNTFW0-CNTFW65535 | numeric | yes | no | 16-bit counter with flag (object 20, variation 2) |
| CNTW0-CNTW65535 | numeric | yes | no | 16-bit counter (object 20, variation 6) |
| CommFail | logical | yes | no | Object-generated signal that is on if, for whatever reason, Lookout cannot communicate with your DNP device. |
| DCNTDW0-DCNTDW65535 | numeric | yes | no | 32-bit delta counter (object 20, variation 7) |
| DCNTFDW0-DCNTFDW65535 | numeric | yes | no | 32-bit delta counter with flag (object 20, variation 3) |
| DCNTFW0-DCNTFW65535 | numeric | yes | no | 16-bit delta counter with flag (object 20, variation 4) |
| DCNTW0-DCNTW65535 | numeric | yes | no | 16-bit delta counter (object 20, variation 8) |
| FL0-FL65535 | numeric | yes | yes | 64-bit float (object 100, variation 2) |
| FS0-FS65535 | numeric | yes | yes | 32-bit float (object 100, variation 1) |

Table 3-28. DNP Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|---|
| Poll | logical | no | yes | When this value transitions from FALSE to TRUE, Lookout polls the device. |
| PollRate | numeric | no | yes | Lookout expression that determines the device polling frequency. |
| TIMEDATE | numeric | yes | no | Device time and date (in Lookout time format) (object 50, variation 1) |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device. |

Error Messages

No response within timeout period

Lookout received no response from a device within the **Receive timeout** period. The DNP object is able to use the COM port, but when it polls the device, it doesn't respond—as if it is not there. If you have daisy-chained several devices, you have introduced an inherent delay. You may have to significantly increase **Receive timeout** (and **Poll Rate**) to ensure Lookout is allowing enough time to receive the expected response. This increase has nothing to do with the processing capabilities of Lookout. It is based solely on **Baud rate** and the number of devices on the chain. Also, verify your baud rate settings, cable connections, power, configuration settings, COM port settings, and polling addresses.

FT3 Error: No start bytes

The driver could not find the bytes that signify the beginning of a DNP frame in a response received from the device. This kind of garbled frame might be caused by bad communications settings.

FT3 Error: FCB fail

The Frame Count Bit (FCB) in the received frame was wrong. This bit helps to ensure that messages are sent and received in the right order. If you are consistently seeing this error you may have a lot of quiescent traffic on the network that is disrupting the driver.

FT3 Error: Bad destination byte

The DNP driver received a message that was not addressed to it.

FT3 Error: Bad source bytes

The DNP driver received a message that was not from the device that this object is monitoring.

FT3 Error: CRC fail

One of the FT3 level checksums failed. If this happens consistently, verify your communications link and settings.

FT3 Error: Bad transport header sequence number

The sequence number in the transport header in the received frame was wrong. This number helps to ensure that messages are sent and received in the right order. If you are consistently seeing this error you may have a lot of quiescent traffic on the network that is disrupting the driver.

FT3 Error: Bad application control sequence number

The sequence number in the application control byte in the received frame was wrong. This number helps to ensure that messages are sent and received in the right order. If you are consistently seeing this error you may have a lot of quiescent traffic on the network that is disrupting the driver.

FT3 Error: Bad DIR

The DIR bit identifies a message as from the master or from a slave. If you get this error you may have multiple masters set up on your network.

FT3 Error: Bad PRM

The PRM bit identifies a message as from an initiating station or from a secondary station. If you get this error you may have multiple masters set up on your network.

Dynamic

Dynamic is a protocol driver class Lookout uses to communicate with equipment such as programmable logic controllers (PLCs), remote terminal units (RTUs), or any other piece of equipment that uses Dynamic as its communication protocol.

Protocol driver objects contain a great deal of data. All readable and writable members (inputs/outputs), polling instructions, read/write blocking, serial port usage, etc. are bundled with the object. Therefore, as soon as you create a Dynamic object you immediately have access to all the object data members (see data member list in this section).

The driver currently supports reading and writing of all predefined data point types including analog input, state input, pulse count input, pulse duration input, pulse period input, high speed accumulator inputs, state outputs, pulse outputs, analog outputs, and AGA data.

The driver automatically configures the RTU database to match the data points referenced in the Lookout process file and verifies that the points specified in the process file actually exist on the RTU. If you reference undefined or unavailable points, the driver posts an alarm message to the Lookout alarm system.

The Dynamic protocol driver automatically takes advantage of the RTU exception reporting capabilities to maximize communication efficiency. The driver requires that the RTU be set for physical point addressing—refer to the RTU hardware technical reference manual for the dipswitch locations that set this parameter.



Note Lookout protocol driver objects automatically generate an efficient read/write blocking scheme based on the inputs and outputs being used in your process file. You are not required to build your own I/O blocking table.

The Dynamic protocol driver was written for Texas Instruments Model 8635, 8640 and 8641 RTUs (Remote Terminal Units) with RTX 5.41 EPROMs—earlier releases of RTX have significant bugs and do not operate correctly with the Lookout Dynamic driver.

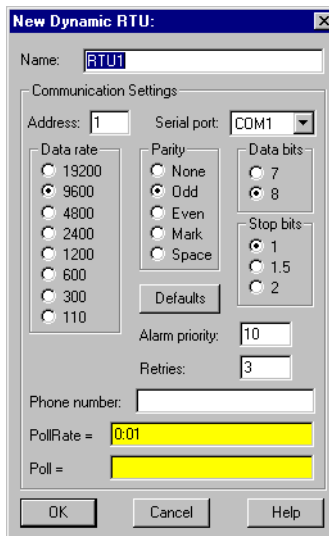


Figure 3-12. Dynamic Parameter Configuration Dialog Box

In this example Lookout is connected to a Dynamic-speaking RTU with an address of 7. Lookout is using serial port1 (which was previously configured for Dial-up communications), and calling the specified phone number. Each poll occurs every 1 hour or when the operator depresses Pushbutton7.

Address refers to the PLC or RTU address setting as set on the device dipswitches. If devices share a common line, they require unique addresses (1 to 255).

Serial port specifies which port the object uses for communication to the external device. This does not specify the communication type. Communication type is determined by the **Options»Serial Ports...** command.

Data rate, Parity, Data bits, and Stop bits reference the settings on the hardware device.

The **Defaults** button replaces the current settings with default values.

Alarm priority determines the priority level of Dynamic-generated alarms.

Phone number specifies the number to be dialed if the serial port setting is configured for dial-up. This number only applies to the individual protocol object.

PollRate is a numeric expression that determines how often to poll the device. Dynamic then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Poll is a logical expression. When this expression changes from false to true, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

As with all Lookout drivers, you can access I/O points and other data through data members. The following is a table of data members currently supported by the Dynamic object class.

Dynamic Data Members

Table 3-29. Dynamic Data Members

| Data Members | Type | Read | Write | Description |
|---------------|---------|------|-------|---|
| AI0 – AI239 | numeric | yes | no | Analog inputs—returns a normalized numeric value that ranges from 0 to 32000 and spans the full input analog range. |
| AO0 – AO239 | numeric | no | yes | Analog outputs—sets voltage level of analog outputs, and accepts a normalized number from 0 to 32000. |
| btu1 – btu4 | numeric | yes | no | AGA data |
| dp1 – dp4 | numeric | yes | no | Differential pressure (psi). 1 – 4 specifies meter run being referenced. |
| HSA0 – HSA127 | numeric | yes | no | High-speed accumulator inputs—counts the number of digital pulses on an HSA input. Rollover is detected automatically by driver, so maximum pulse count is 4.5×10^{15} . |

Table 3-29. Dynamic Data Members (Continued)

| Data Members | Type | Read | Write | Description |
|-------------------------|-------------|-------------|--------------|--|
| MeterCode1 – MeterCode4 | text | no | yes | First 8 characters of this text string are used to create a filename with a .csv extension. Entire text string is used as a field within the .csv file. 1 – 4 specifies meter run being referenced. |
| NoComm | logical | yes | no | Driver-generated signal that is on if Lookout cannot communicate with the device for whatever reason. |
| PCI0 – PCI239 | numeric | yes | no | Digital pulse count inputs—counts the number of times a digital state input has transitioned from <i>off</i> to <i>on</i> . Rollover is detected automatically by driver, so maximum pulse count is about 4.5×10^{15} . |
| PDI0 – PDI239 | numeric | yes | no | Digital pulse duration inputs—measures a periodic pulse on time with a 10 msec resolution. Pulse period should be 15 seconds or less. Returned time is in standard Lookout time units of fraction of a day. |
| Poll | logical | no | yes | When this value transitions from FALSE to TRUE Lookout polls the device. |
| PollRate | numeric | no | yes | Lookout expression that determines the frequency at which the device is to be polled. |
| PPI0 – PPI239 | numeric | yes | no | Digital pulse period inputs—measures a pulse period with a 10 msec resolution. Pulse period should be 15.1 seconds or less. Returned time is in standard Lookout time units of fraction of a day. |
| Qe1 – Qe4 | numeric | yes | no | Energy rate 1 – 4 specifies meter run being referenced. |

Table 3-29. Dynamic Data Members (Continued)

| Data Members | Type | Read | Write | Description |
|----------------------------------|-------------|-------------|--------------|---|
| Qsum1 – Qsum4 | numeric | yes | no | Accumulated flow over the last 60 minutes (cubic feet – CF). 1 – 4 specifies meter run being referenced. |
| Qsum_month1 – Qsum_month4 | numeric | yes | no | Accumulated flow over the last 30 days (cubic feet – CF). 1 – 4 specifies meter run being referenced. |
| Qsum_yesterday1– Qsum_yesterday4 | numeric | yes | no | Accumulated flow over the last 24 hours (cubic feet – CF). 1 – 4 specifies meter run being referenced. |
| Qv1 – Qv4 | numeric | yes | no | Instantaneous flow rate (cubic feet/hour – CFH). 1 – 4 specifies meter run being referenced. |
| ReadHistory | logical | no | yes | When this value transitions from TRUE to FALSE, Lookout polls the device and reads the historical AGA from the RTU, storing to disk. |
| SI0 – SI239 | logical | yes | no | Digital state inputs |
| SO0 – SO239 | logical | no | yes | Digital state outputs. On the 8635, state outputs and pulse outputs are mapped to programmable I/O (PIO) points and range from SO8 to SO15. |
| sp1 – sp4 | numeric | yes | no | Static pressure (psi). 1 – 4 specifies meter run being referenced. |
| tf1 – tf4 | numeric | yes | no | Flowing temperature (deg. F). 1 – 4 specifies meter run being referenced. |
| Update | logical | yes | no | Driver-generated signal that pulses each time the driver polls the device |
| VB0-VB65535 | logical | yes | yes | Bit in V register read as logical. |
| VF0-VF2047 | numeric | yes | yes | V register read as float on 4-byte boundary. |
| VFN0-VFN2047 | numeric | yes | yes | V register read as float, no boundary. |

Table 3-29. Dynamic Data Members (Continued)

| Data Members | Type | Read | Write | Description |
|---------------------|-------------|-------------|--------------|---|
| VW0-VW4095 | numeric | yes | yes | V register read as a word on 2-byte boundary. |
| VWN0-VWN4095 | numeric | yes | yes | V register read as a word, no boundary. |

FisherROC

FisherROC is a protocol driver class Lookout uses to communicate with a ROC364 (Remote Operations Controller) made by Fisher Controls. To communicate with the ROC364, connect directly to its COM1 or COM2 port. Depending on the device configuration, these ports may be configured for RS-232, RS-422/485 or Bell 202 modem communications.

Create one FisherROC object for each ROC364. This object class contains a great deal of data. All point types including inputs, outputs, PID, AGA, Tank, and their configuration signals are bundled with the object. Therefore, as soon as you create a FisherROC object you immediately have access to the object data member set.

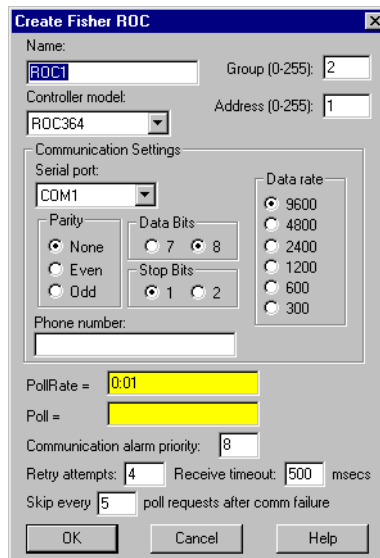


Figure 3-13. FisherROC Definition Parameters Dialog Box

Group is the group code to which the ROC station is assigned. This is typically set to 2, but is configurable through the GV101 Configuration software.

Address is the unit code (address setting) of the ROC station as defined using the GV101 Configuration software. If multiple ROCs are members of the same group, then they must have unique addresses (0 to 255). As the host station, the Lookout computer is assigned Group 0, Address 1.

Controller model identifies the type of Fisher remote operations controller that the object represents. This object class supports **ROC364**.

Serial port specifies which COM port on the host computer that Lookout object uses for communicating to the external device. This does not specify the communication type. Communication type is determined by the **Options»Serial Ports...** command.

Data rate, Parity, Data bits, and Stop bits reference the settings on the hardware device.

Phone number specifies the number to be dialed if the selected serial port is configured for dial-up. This number only applies to the individual protocol object.

PollRate is a numeric expression that determines how often to poll the device. The object then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of alarms generated by the object. Such alarms are typically related to communications with the physical device.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the object generates an alarm and releases the communication port back to the communications service which then moves on to the next device in the polling queue (if any). Refer to Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

The **Skip every...** setting instructs Lookout to not poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle accordingly. Once communications have been reestablished, the device is polled on its regular cycle.

FisherROC Data Members

Table 3-30. FisherROC Data Members

| Data Member | Type | Read | Write | Description |
|-------------------------|---------|------|-------|------------------------------------|
| AGA1.la – AGA5.la | numeric | yes | yes | AGA low alarm EU value |
| AGF1.btud – AGF5.btud | numeric | yes | no | AGA Flow in units of MMBTU/Day |
| AGF1.btut – AGF5.btut | numeric | yes | no | MMBTUs of AGA Flow today |
| AGF1.btuy – AGF5.btuy | numeric | yes | no | MMBTUs of AGA Flow yesterday |
| AGF1.mcfcd – AGF5.mcfcd | numeric | yes | no | AGA Flow in units of MCF/Day |
| AGF1.mcft – AGF5.mcft | numeric | yes | no | MCFs of AGA Flow today |
| AGF1.mcfy – AGF5.mcfy | numeric | yes | no | MCFs of AGA Flow yesterday |
| AI:A1.adh – AI:D16.adh | numeric | yes | yes | Analog input adjusted A/D 100% |
| AI:A1.adl – AI:D16.adl | numeric | yes | yes | Analog input adjusted A/D 0% |
| AI:A1.dla – AI:D16.dla | numeric | yes | yes | Analog input Delta Alarm EU |
| AI:A1.euh – AI:D16.euh | numeric | yes | yes | Analog input High Reading EU |
| AI:A1.eul – AI:D16.eul | numeric | yes | yes | Analog input Low Reading EU |
| AI:A1.feu – AI:D16.feu | numeric | yes | yes | Analog input Filtered EU value |
| AI:A1.flt – AI:D16.flt | numeric | yes | yes | Analog input Filter |
| AI:A1.ha – AI:D16.ha | numeric | yes | yes | Analog input High alarm limit |
| AI:A1.hha – AI:D16.hha | numeric | yes | yes | Analog input High-High alarm limit |
| AI:A1.la – AI:D16.la | numeric | yes | yes | Analog input Low alarm limit |
| AI:A1.lla – AI:D16.lla | numeric | yes | yes | Analog input Low-Low alarm limit |
| AI:A1.raw – AI:D16.raw | numeric | yes | no | Analog input Raw A/D input value |
| AO:A1.adh – AO:D16.adh | numeric | yes | yes | Analog output Adjusted A/D 100% |
| AO:A1.adl – AO:D16.adl | numeric | yes | yes | Analog output Adjusted A/D 0% |
| AO:A1.eu – AO:D16.eu | numeric | yes | yes | Analog output EU output value |
| AO:A1.euh – AO:D16.euh | numeric | yes | yes | Analog output High Reading EU |
| AO:A1.eul – AO:D16.eul | numeric | yes | yes | Analog output Low Reading EU |

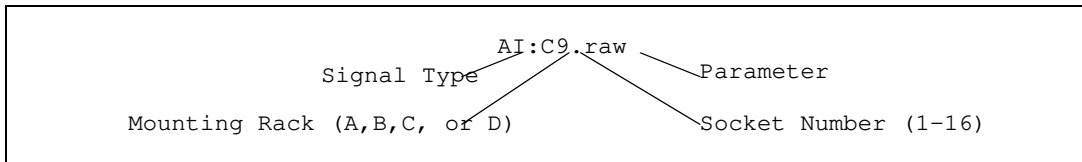
Table 3-30. FisherROC Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|------------------------|-------------|-------------|--------------|---|
| CommFail | logical | yes | no | Object-generated signal that is on if, for whatever reason, Lookout cannot communicate with the ROC |
| DI:A1.acc – DI:D16.acc | numeric | yes | yes | Discrete input accumulated value |
| DI:A1.flt – DI:D16.flt | logical | yes | yes | Discrete input filter |
| DI:A1.ha – DI:D16.ha | numeric | yes | yes | Discrete input high alarm |
| DI:A1.hha – DI:D16.hha | numeric | yes | yes | Discrete input high-high alarm |
| DI:A1.la – DI:D16.la | numeric | yes | yes | Discrete input low alarm |
| DI:A1.lla – DI:D16.lla | numeric | yes | yes | Discrete input low-low alarm |
| DI:A1.sts – DI:D16.sts | logical | yes | no | Discrete input status (value) |
| DO:A1.acc – DO:D16.acc | numeric | yes | yes | Discrete output accumulated value |
| DO:A1.cth – DO:D16.cth | numeric | yes | yes | Discrete output 100% count |
| DO:A1.ctl – DO:D16.ctl | numeric | yes | yes | Discrete output 0% count |
| DO:A1.ctm – DO:D16.ctm | numeric | yes | yes | Discrete output cycle time |
| DO:A1.eu – DO:D16.eu | numeric | yes | yes | Discrete output EU value |
| DO:A1.rdh – DO:D16.rdh | numeric | yes | yes | Discrete output high reading EU |
| DO:A1.rdl – DO:D16.rdl | numeric | yes | yes | Discrete output low reading EU |
| DO:A1.sts – DO:D16.sts | logical | yes | yes | Discrete output status (value) |
| DO:A1.to – DO:D16.to | numeric | yes | yes | Discrete output time on |
| FST1.rg1 – FST8.rg10 | numeric | yes | yes | Function seq. table register value |
| FST1.rrg – FST8.rrg | numeric | yes | yes | Function seq. table result register |
| FST1.tm1 – FST8.tm4 | numeric | yes | yes | Function seq. table timer value |
| PID1.eu – PID16.eu | numeric | yes | yes | PID output EU value |
| PID1.ost – PID16.ost | numeric | yes | yes | PID OVR sw setpoint |
| PID1.pst – PID16.pst | numeric | yes | yes | PID PRI sw setpoint |
| PID1.set – PID16.set | numeric | yes | yes | PID setpoint value |

Table 3-30. FisherROC Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|------------------------|-------------|-------------|--------------|---|
| PL:A1.acc – PL:D16.acc | numeric | yes | yes | Pulse input accumulated value |
| PL:A1.crt – PL:D16.crt | numeric | yes | no | Pulse input current rate |
| PL:A1.dla – PL:D16.dla | numeric | yes | yes | Pulse input delta alarm EU |
| PL:A1.eu – PL:D16.eu | numeric | yes | yes | Pulse input value in engineering units |
| PL:A1.ha – PL:D16.ha | numeric | yes | yes | Pulse input high alarm EU value |
| PL:A1.hha – PL:D16.hha | numeric | yes | yes | Pulse input high-high alarm EU value |
| PL:A1.la – PL:D16.la | numeric | yes | yes | Pulse input low alarm EU value |
| PL:A1.lla – PL:D16.lla | numeric | yes | yes | Pulse input low-low alarm EU value |
| PL:A1.rpd – PL:D16.rpd | numeric | yes | yes | Pulse input rate period |
| Poll | logical | no | yes | When this value transitions from FALSE to TRUE, Lookout polls the device. |
| PollRate | numeric | no | yes | Lookout expression that determines the device polling frequency. |
| SPT1.d1 – SPT32.d20 | numeric | yes | yes | Soft point parameter data number |
| TNK1.cfl – TNK8.cfl | numeric | yes | no | Tank current fluid level |
| TNK1.dis – TNK8.dis | numeric | yes | no | Tank barrels discharged |
| TNK1.dla – TNK8.dla | numeric | yes | yes | Tank delta alarm EU |
| TNK1.lsl – TNK8.lsl | numeric | yes | no | Tank last scan level |
| TNK1.man – TNK8.man | numeric | yes | yes | Tank manual entry—barrels |
| TNK1.ttl – TNK8.ttl | numeric | yes | no | Tank total barrels hauled |
| TNK1.tvl – TNK8.tvl | numeric | yes | no | Today's tank volume |
| TNK1.yvl – TNK8.yvl | numeric | yes | no | Yesterday's tank volume |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device |

Comments To read the raw value of an analog input located at I/O module socket 9 on the third mounting rack, you would enter `NAME.AI:C9.raw`, where



FisherROC Status Messages

No response within timeout period

Lookout received no response from the ROC device within the **Receive timeout** period. The driver object is able to use the COM port, but when it polls the device, it does not respond—as if it is not even there. You may have to increase **Receive timeout** to ensure Lookout is allowing enough time to receive the expected response. Also, verify your baud rate settings, cable connections, power, configuration settings, COM port settings, and polling addresses.

Message Garbled—Bad CRC

The object is receiving a poll response from the device, but it cannot decipher the response. Verify that all devices assigned to the device group have unique unit codes. The last part of the message may actually be getting clipped off before it is completed. Consider increasing the number of **Retry attempts**. You may have to increase the **Receive gap** Serial Port setting to ensure Lookout is receiving the entire message. If your Serial Port is configured for radio, this could be caused by an audible squelch tail occurring at the end of a radio transmission. Try adjusting **RTS delay off** and **CTS timeout**.

Unexpected data response length

The object is receiving a poll response from the device, but the response is too long. Verify that all devices connected to the COM port and assigned to the same device group have unique unit codes. Devices with identical addresses may be trying to respond at the same time. Also verify device protocol settings.

Response too short

The object is receiving data of a length that does not meet the minimum frame length requirements. Verify device protocol settings. You may have to increase **Receive timeout**.

Return unit address incorrect**Return group address incorrect**

The object sent a data write or data read request, but the ROC did not respond. You may be asking for an invalid memory address. Recheck your ROC address configuration.

Invalid module or point requested

You attempted a data type mismatch. For example, you may have tried to write or read an *analog* value to or from a rack I/O socket that has a *discrete* module installed, or visa versa. This is an addressing problem. Verify that the type of I/O at the desired socket matches the signal type of the address identified in the data member you are writing to.

Unexpected opcode in response: xx

The object is receiving a poll response from the device, but the response was not expected. This might happen if the object receives a poll response after the **Receive timeout** period expires. You may have to increase **Receive timeout**. Another possibility is that the ROC is attempting an unsolicited communication. The FisherROC object class currently does not support unsolicited report-by-exception.

GE_Series90

GE_Series90 is a protocol driver class Lookout uses to communicate with GE Series 90-30 and GE Series 90-70 programmable logic controllers (PLCs) using SNPX, a Series Ninety Protocol.

Figure 3-14. GE_Series90 Definition Parameters Dialog Box

PLC Address is a slave address and refers to the PLC address setting as configured on the device. The address can be up to eight ASCII characters.

Model chooses either 90-30 or 90-70.

Interface selects the protocol. You can choose between SNPX and Ethernet.

Serial port specifies which port the object uses for communication to the external device. This does not specify the communication type. Communication type is determined by the **Options»Serial Ports...** command.

Data rate, Parity, Data bits, and Stop bits reference the settings on the hardware device.

Phone number specifies the number to be dialed if the serial port setting is configured for dial-up. This number only applies to the individual protocol object.

PollRate is a numeric expression that determines how often to poll the device. GE_Series90 then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of object-generated alarms (0 – 10).

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the GE_Series90 object generates an alarm and releases the communication port back to the communications service which then moves on to the next device in the polling queue (if any). Refer to Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

The **Skip every...** setting instructs Lookout to not poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle accordingly. Once communications have been reestablished, the device is polled on its regular cycle.

GE_Series90 Data Members

This protocol driver object contains a great deal of data. All readable and writable members (inputs/outputs), polling instructions, read/write blocking, serial port usage, and so on, are bundled with the object. Therefore, as soon as you create a GE_Series90 object you immediately have access to all the object data members (see data member list in Table 3-31).



Note Lookout protocol driver objects automatically generate an efficient read/write blocking scheme based on the inputs and outputs being used in your process file. You are not required to build your own I/O blocking table.

Table 3-31. GE_Series90 Data Members

| Data Member | Type | Read | Write | Description |
|--------------|---------|------|-------|--|
| AI1 – AI64 | numeric | yes | yes | 16-bit analog inputs encoded as unsigned binary integers ranging from 0 to 65535 |
| AID1 – AID64 | numeric | yes | yes | 32-bit analog inputs encoded as unsigned binary integers ranging from 0 to 65535 |
| AQ1 – AQ64 | numeric | yes | yes | 16-bit analog outputs encoded as unsigned binary integers ranging from 0 to 65535 |
| AQD1 – AQD64 | numeric | yes | yes | 32-bit analog outputs encoded as unsigned binary integers ranging from 0 to 65535 |
| CommFail | logical | yes | no | Object-generated signal that is on if, for whatever reason, Lookout cannot communicate with the PLC. |
| I1 – I512 | logical | yes | no | Single bit discrete inputs |
| M1 – M4096 | logical | yes | yes | Single bit discrete (Internal coil) |
| OffHook | logical | no | yes | When TRUE, this flag instructs the GE object to retain exclusive use of its assigned communication port. |
| Poll | logical | no | yes | When this value transitions from FALSE to TRUE, Lookout polls the device. |
| PollRate | numeric | no | yes | Lookout expression that determines the device polling frequency. |
| Q1 – Q512 | logical | yes | yes | Single bit discrete outputs |
| R1 – R9999 | numeric | yes | yes | 16-bit holding registers encoded as unsigned binary integers ranging from 0 to 65535 |

Table 3-31. GE_Series90 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|--|
| RD1 – RD9998 | numeric | yes | yes | 32-bit holding registers encoded as unsigned binary integers ranging from 0 to 65535 |
| S1 – S32 | logical | yes | no | System fault |
| SA1 – SA32 | logical | yes | no | Special Contacts A |
| SB1 – SB32 | logical | yes | no | Special Contacts B |
| SC1 – SC32 | logical | yes | no | Special Contacts C |
| Update | logical | yes | no | Object-generated signal that pulses each time the driver polls the device |

GE_Series90 Status Messages

No response within timeout period

Lookout did not received the expected response within the **Receive timeout** period. The object sent an inquiry and received an acknowledgment, but the device did not send an expected response to the request. This might happen if the response was interrupted. You may have to increase **Receive timeout**.

No return inquiry response from secondary unit

Lookout received no response from the device within the **Receive timeout** period. The driver object is able to use the COM port, but when it polls the device, it does not respond—as if it is not even there. You may have to increase **Receive timeout** to ensure Lookout is allowing enough time to receive the expected response. Also, verify your baud rate settings, cable connections, power, configuration settings, COM port settings, and polling addresses.

Bad LRC or BCC

The object is receiving a poll response from the device, but it could not decipher the response because it is garbled. Verify that all devices connected to the COM port have unique addresses. The last part of the message may actually be getting clipped off before it is completed. Consider increasing the number of **Retry attempts**. You may have to increase the **Receive gap** Serial Port setting to ensure Lookout is receiving the entire message. If your Serial Port is configured for radio, this could be

caused by an audible squelch tail occurring at the end of a radio transmission. Try adjusting **RTS delay off** and **CTS timeout**.

No attach response within timeout period

An attempt was made to establish communications with the PLC without any response. Check your cabling and COM port selections, power, configuration settings, and polling addresses.

Invalid response [x]

An error in the structure of a response frame was detected. You may have two PLCs with the same address.

Incorrect response length [x]

A response was received with an unexpected length. You may have to increase the **Receive gap** Serial Port setting to ensure Lookout is receiving the entire message.

Incorrect response Address

A response was received with an address not matching the objects address. You may have two master devices on the network.

SNPX ERROR—Major code: x Minor code: x

The response message contained an SNPX error code. Refer to your GE documentation for the meaning of this particular error.

Hitachi

Hitachi is a protocol driver class Lookout uses to communicate with Hitachi devices using the H series serial communication protocol.

Figure 3-15. Hitachi Definition Parameters Dialog Box

Serial port specifies which comm. port the object uses for communicating to the external device. This does not specify the communication type. Communication type is determined by the **Options»Serial Ports...** command.

Data rate indicates the baud rate that Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Data bits indicates the number of data bits that Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Stop bits indicates the number of stop bits that Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Parity indicates the parity that Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Phone number specifies the number to be dialed if the selected serial port is configured for dial-up. This number only applies to the individual protocol object.

PollRate is a numeric expression that determines how often to poll the device. The object then polls the device at the specified time interval. Normally, this will be a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

When the logical value **Poll** transitions from FALSE to TRUE, Lookout polls the device. This can be a simple expression like the signal from a pushbutton, or it can be a complex algorithm.

Communication alarm priority determines the priority level of alarms generated by the Hitachi object. Such alarms are typically related to communications with the physical device.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the Hitachi object generates an alarm and releases the communication port back to the communications subsystem, which then moves on to the next device in the polling queue (if any). Refer to Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

The **Skip every...** setting instructs Lookout to not poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle. Once communications have been reestablished, the device is polled on its regular cycle.

Hitachi Data Members

An Hitachi object contains a great deal of data. It supports reading and writing of all predefined data points. When you create an Hitachi object, you have immediate access to all the object data members.

As with all Lookout drivers, you can access I/O points and other data through data members. The following is a table of data members currently supported by the Hitachi object class.

Table 3-32. Hitachi Data Members (Address Ranges in Hexadecimal)

| Data Member | Type | Read | Write | Description |
|--------------|---------|------|-------|--|
| CommFail | logical | yes | no | Object-generated signal that is ON if Lookout cannot communicate with the device(s). |
| CU0 – CU512 | numeric | yes | yes | Up Counter |
| DL0 – DL1000 | numeric | yes | yes | Double-word CPU link area |
| DM0 – DM1000 | numeric | yes | yes | Double-word data area |
| DR0 – DR3E | numeric | yes | yes | Internal double-word output |
| DX0 – DX10 | numeric | yes | yes | External double-word output |
| DY0 – DY10 | numeric | yes | no | External double-word output |
| L0 – L4000 | logical | yes | yes | Bit CPU link area |
| M0 – M4000 | logical | yes | yes | Bit data area |
| Poll | logical | no | yes | When this expression transitions from FALSE to TRUE, Lookout polls the device. |
| PollRate | numeric | no | yes | Lookout expression that determines the device polling frequency. |
| R0 – R7C0 | logical | yes | yes | Internal bit output |
| TC0 – TC512 | numeric | yes | yes | Timer counter elapsed time |
| TD0 – TD512 | logical | yes | yes | On-Delay timer |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device. |
| WL0 – WL2000 | numeric | yes | yes | Word CPU link area |

Table 3-32. Hitachi Data Members (Address Ranges in Hexadecimal) (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|----------------------|
| WM0 – WM2000 | numeric | yes | yes | Word data area |
| WR0 – WR7C | numeric | yes | yes | Internal word output |
| WX0 – WX20 | numeric | yes | yes | External word output |
| WY0 – WY20 | numeric | yes | no | External word output |
| X0 – X200 | logical | yes | yes | External bit input |
| Y0 – Y200 | logical | yes | no | External bit output |

Hitachi Status Messages

no acknowledgment for data request

no within timeout period

PLC response frame timeout

The PLC is not responding to data requests. Check communications settings, cables, and power.

Frame Error (Garbled): [Hitachi error code string]

Response frame was garbled. Check cabling and cable environment.

Hitachi frame error (RTC): [RTC error code string]

PLC received an invalid frame. Check communications settings.

Hitachi error message: [Hitachi error code string]

PLC received an invalid request. Check for a data member that is out of range for the model of PLC configuration.

IPASCII

IPASCII is a protocol driver class Lookout uses to communicate with any IP device that runs standard TCP or UDP services.

An IPASCII object contains no predefined data points. When you create a IPASCII object, you must define your data request strings as well as the template Lookout uses to parse the response frame.

Local port specifies which local Ethernet I/O port the object uses for communicating to the external device.

Mode indicates whether the object will use a TCP socket or a UDP socket.

IP address indicates the address of the device you wish to communicate with.

Port indicates the Ethernet I/O port number on the remote device where the object will try to establish a socket.

Accept Unsolicited Messages indicates whether or not the object will report packets from the device that are not in response to a request that the IPASCII object has sent it. This does *not* mean that the IPASCII object can act as a server. It means that once the IPASCII object has established a socket as a client, it reports unexpected data it receives from that point on.

Communication alarm priority determines the priority level of alarms generated by the IPASCII object. Such alarms are typically related to communications with the physical device.

Retry attempts specifies the number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the IPASCII object generates an alarm and releases the socket.

Receive timeout is the amount of time Lookout waits for a response from a device before retrying the request.

The **Skip every ___ poll requests after comm failure** setting instructs Lookout not to poll a device it has lost communication with on every scheduled poll. Instead, Lookout polls the device only once in the specified number of poll cycles. Once communication has been reestablished, the device is polled on its regular cycle. In the context of the IPASCII object, this means that this number of Send commands will be ignored until communication has been reestablished.

IPASCII Data Members

Table 3-33. IPASCII Data Members

| Data Member | Type | Read | Write | Description |
|----------------------------------|---------|------|-------|--|
| CommFail | logical | yes | no | Object-generated signal that is on if Lookout cannot communicate with the device(s). |
| Request | text | yes | no | Exact request frame sent. |
| RequestFormat | text | no | yes | Format used to create request frame. |
| Response | text | yes | no | Exact response frame received. |
| ResponseFormat | text | no | yes | Format used to parse response frame. |
| RQV1.logical— RQV100.logical— | logical | no | yes | Variable list used to populate request frame with logical values. |
| RQV1.txt—RQV100.txt | text | no | yes | Variable list used to populate request frame with text values. |
| RQV1—RQV100 | numeric | no | yes | Variable list used to populate request frame with numeric values. |
| RSV1.logical—RSV100 .logical | logical | yes | no | Variable list used to store values retrieved from response frame. |
| RSV1.txt— RSV100.txt | text | yes | no | Variable list used to store values retrieved from response frame. |

Table 3-33. IPASCII Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--|---------|------|-------|--|
| RSV1—RSV100 | numeric | yes | no | Variable list used to store values retrieved from response frame. |
| Send | logical | no | yes | Sends request frame. |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device. |
| * RQVn, RQVn.txt and RQVn.logical all represent the same value in different forms. * RSVn, RSVn.txt and RSVn.logical all represent the same value in different forms. | | | | |

Request and Response Format Strings

The request and response format strings consist of static characters and markers that control how the request and response frames respectively are formatted or decoded. The request format string is used to *create* the request frame, which is sent to the device, while the response format string is used to *decode* the response frame, which comes from the device.

Static characters in the format strings are reproduced exactly in the request or response frame. Markers specify the location within the frame and type of data which should be found there, such as five characters read as an unsigned integer, for example. The IPASCII object constructs a request frame by processing the sequence of static characters and markers in the request format string, and including data from RQV data members.

The response format string decodes a response frame using an analogous process, storing the results in RSV data members.

To construct a request frame, the IPASCII object parses the request format string character by character. Static characters are copied directly to the request frame. When a marker is encountered the IPASCII object reads a value from the appropriate RQV variable and places it into the request frame.

There are 100 RQV and RSV values provided for in the IPASCII object data member collection. The first marker in a format string uses the value from RQV1 (or RQV1.txt or RQV1.logical), the next marker uses the value RQV2, and so on. Values taken from Response strings are stored in RSV data members in the same way.

Keep in mind that writing into `RQV1` changes the value both for `RQV1.txt` and `RQV1.logical`. Their only difference is the format in which they are represented. The same principle applies to the RSV data members.



Note There is no precedence to the order in which multiple objects connected to the same variable number will initialize upon opening the process file, such as the case in which a Pot object is connected to `RQV1` while a TextEntry object is connected to `RQV1.txt`. You should take care to initialize such variables to the proper value after opening a process file.

To decode a response frame, the IPASCII object compares the response frame to the response format string character by character. The static characters in the response frame must match those in the response format string or the decoding process terminates. Static characters are, in effect, discarded by the IPASCII object as they are matched between the response format string and the response frame.

When the IPASCII object encounters a marker, it places the data indicated by the marker into the appropriate RSV data member.

The conversion of a portion of the response frame to a data type specified by a marker in the response format string must be valid, or the process will terminate.

If nothing halts the process, decoding terminates when the end of the response frame string is reached.

There are examples of both request frames and response frames at the end of this section, but for the examples to make sense, you must first understand the IPASCII object markers.

Markers

The general format for a marker is:

$$\%[\text{width}][\text{type}]$$

Each field in the marker format is a single character or a number signifying a particular format option.

The `%` sign denotes the beginning of the marker. If the percent sign is followed by a character that has no meaning as a format-control character, that character and the following characters (up to the next percent sign) are treated as static characters, that is, a sequence of characters that must match the frame exactly. For example, to specify that a percent-sign character is a static character part of the frame, use `%%`.

Width is a positive decimal integer specifying the number of characters that particular value occupies in the frame. By default IPASCII will pad the value with blank spaces if the value takes up fewer characters than the value specified by width. Including a 0 before the width value forces the IPASCII object to pad with zeroes instead of blank spaces.

Type determines whether the field is interpreted as a character, a string, or a number.

Table 3-34. Data Types Allowed by IPASCII

| Character | Data Type |
|-----------|--------------------------|
| d | Decimal integer |
| x, X | Hexadecimal integer |
| u | Unsigned decimal integer |
| f | Floating-point |
| s | String |
| b | Byte (binary) |

The simplest format specification contains only the percent sign and a type character (for example, %s). That would place the value in the response frame in the RSV1.txt data member.

| Request Format String | RQV1 | Request Frame |
|-----------------------|------|---------------|
| >%5d | 34 | > 34 |
| >%05d | 34 | >00034 |

The request format string also has a precision value in the form **%[width].[precision][type]**. This specifies the number of digits to the right of the decimal point, if any, in the request frame. If you use a float (%f) and do not specify a precision value, the IPASCII object assumes a default of 6.

Characters are converted and stored in RSV data members from response frames in the order they are encountered in the response format. However, fewer than **[width]** characters may be read if a white-space character (space, tab, or newline) or a character that cannot be converted according to the given format occurs before **[width]** is reached.

Values needed for request frames come from the RQV data members, and are also used in the order in which they occur in the request format.

To read strings not delimited by space characters, or that contain spaces, you can substitute a set of characters in brackets ([]) s (string) type character. The corresponding input field is read up to the first character that does not appear in the bracketed character set. Using a caret (^) as the first character in the set reverses this effect: the IPASCII object reads input field up to the first character that does appear in the rest of the character set.

| Response Format String | RSV1.txt | Response Frame |
|------------------------------|-----------|----------------------------|
| <code>[\$A-Z,a-z,]\$</code> | Natl Inst | <code>\$Natl Inst\$</code> |
| <code>>[^,s]</code> | days | <code>>day</code> |

Notice that `%[a-z]` and `%[z-a]` are interpreted as equivalent to `%[abcde...z]`, and that the character set is case sensitive.



Note The brackets only work in response format strings. They have no effect in the request format string.

The IPASCII object scans each field in the response frame character by character. It may stop reading a particular field before it reaches a character for a variety of reasons:

- The specified width has been reached.
- The next character cannot be converted as specified.
- The next character conflicts with a character in the response format string that it is supposed to match.
- The next character fails to appear in a given character set.

No matter what the reason, when the IPASCII object stops reading an field, the next field is considered to begin at the first unread character. The conflicting character, if there is one, is considered unread and is the first character of the next field.

Entering the Format String

For a static connection to one of the format data members, enter your format string in the yellow field box in the Edit Connections dialog box. Remember to begin and end the format strings with quotation marks so that Lookout will accept the string input.

You can also connect any valid text data member, such as a text entry object, to the format data members.

Request Frame Construction Examples

| Request Format String | RQV | Request Frame |
|-----------------------|----------------------------|---------------|
| <01%4u%s | RQV1=1234 RQV2.txt=Ross | <011234Ross |
| <01%04u%s | RQV1=34 RQV2.txt=Ross | <010034Ross |
| <01% 4u%s | RQV1=34 RQV2.txt=Ross | <01 34Ross |

A zero in front of the four pads with zeroes; a space pads with spaces.

Response Format Examples

| Response Frame | Response Format String | RSV |
|----------------|------------------------|------------|
| *(16.38: | *(%5.2f: | RSV1=16.38 |



Note The decimal point counts as a character when decoding floats (%f). Also, decimal points denoting precision are not allowed when decoding a float in the response frame.

| Response Frame | Response Format String | RSV |
|----------------|------------------------|---------------|
| >>Test Text<< | >>%s<< | RSV1.txt=Test |

The space between the words terminates the conversion. See the preceding bracketed character example in order to span a space or other special characters. The response format uses a space as a delimiter.

| Response Frame | Response Format String | RSV |
|-----------------------|-------------------------------|--------------------------------|
| >>Test Text<< | >>%s%s<< | RSV1.txt=Test RSV2.txt=Text |
| >>DogCat<< | >>%3s%3s<< | RSV1.txt=Dog RSV2.txt=Cat |

IPASCI Error Messages

No response from device within timeout period

Lookout received no response from the device within the **Receive timeout** period. The IPASCI object was able to establish a socket, but when it sends its message to the device, it does not respond—as if it is not even there. You may have to significantly increase **Receive timeout** (and **Poll Rate**) to ensure Lookout is allowing enough time to receive the expected response. Also, verify your cable connections, power, configuration settings, and IP settings.

Not enough data to send a valid frame

This means that the IPASCI object has not received enough data to fill in all the variables in the Request Format frame. This could mean that you do not have connections made to all of the RQVs that the IPASCI object is expecting.

Socket communications error

This alarm message will be followed by a Windows standard socket error message. The most common reason you might see one of these errors is if an error has occurred on the socket after a valid socket has already been established.

Cannot communicate with device

This means that the IPASCI object was not able to establish a valid socket with the remote device, and in fact did not get any kind of response from the device.

Cannot resolve IP address

Check to make sure you have given IPASCI a valid IP address.

Cannot resolve port

Check to make sure you have given IPASCII a valid port number on the remote device.

Garbled or unexpected response

IPASCII got a response frame, but static characters in the response did not match up to the response format string.

Illegally formatted string received

IPASCII got a response frame, but certain characters in the response were not in the format stated by the markers in the response format string.

Related Objects [*ASCII*](#)

Mitsubishi

MitsubishiFX

Mitsubishi is a protocol driver class Lookout uses to communicate with Mitsubishi devices using the serial communication protocol.

A Mitsubishi object contains a great deal of data. It supports reading and writing of all predefined data points. When you create a Mitsubishi object, you have immediate access to all the data members for that object.

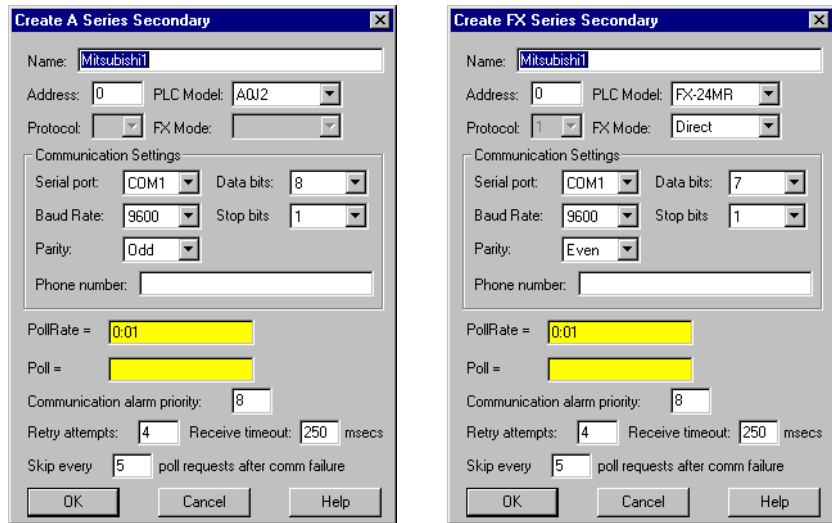


Figure 3-16. Mitsubishi Configuration Parameters Dialog Box

Serial port specifies which COM port the object uses for communicating to the external device. This does not specify the communication type. Communication type is determined by the **Options»Serial Ports...** command.

Data rate indicates the baud rate that Lookout uses to communicate with the hardware device. This **Data rate** setting should match the selection made on the physical device.

Data bits indicates the number of data bits that Lookout uses to communicate with the hardware device. This **Data bits** setting should match the selection made on the physical device.

Stop bits indicates the number of stop bits that Lookout uses to communicate with the hardware device. This **Stop bits** setting should match the selection made on the physical device.

Parity indicates the parity that Lookout uses to communicate with the hardware device. This **Parity** setting should match the selection made on the physical device.

Phone number specifies the number to be dialed if the selected serial port is configured for dial-up. This **Phone number** only applies to the individual protocol object.

PollRate is a numeric expression that determines how often to poll the device. The object then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for more information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of alarms generated by the Mitsubishi object. Such alarms are typically related to communications with the physical device.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device when it is not getting a valid response. After it tries the number of **Retry attempts** specified, the Mitsubishi object generates an alarm and releases the communication port back to the communications subsystem. The subsystem then moves on to the next device in the polling queue (if any). See Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

The **Skip every...** setting instructs Lookout not to poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle. Once communications have been reestablished, the device is polled on its regular cycle.

Mitsubishi Data Members

As with all Lookout drivers, you can access I/O points and other data through data members. The following is a table of data members currently supported by the Mitsubishi object class.

Table 3-35. Mitsubishi Data Members (A Series)

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|--|
| C0–C1023 | numeric | yes | yes | Counter, 16-bit word. |
| CommFail | logical | yes | no | Object-generated signal, ON if Lookout cannot communicate with the device(s). |
| D0–D1023 | numeric | yes | yes | Data register, 16-bit word. |
| M0–M2047 | logical | yes | yes | Discrete coil, 1-bit. |
| Poll | logical | no | yes | When this expression transitions from FALSE to TRUE, Lookout polls the device. |
| PollRate | numeric | no | yes | Lookout expression that determines the device polling frequency. |
| T0–T1023 | numeric | yes | yes | Timer, 16-bit word. |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device. |
| W0–W1023 | numeric | yes | yes | Data register, 16-bit word. |
| X0–X2047 | logical | yes | no | Discrete input, 1-bit. |
| Y0–Y2047 | logical | yes | yes | Discrete output, 1-bit. |

Table 3-36. MitsubishiFX Data Members (FX Series)

| Data member | Type | Read | Write | Description |
|-------------|---------|------|-------|--|
| C0–C1023 | numeric | yes | yes | Counter, 16-bit word. |
| CommFail | logical | yes | no | Object-generated signal that is ON if Lookout cannot communicate with the device(s). |
| D0–D1023 | numeric | yes | yes | Data register, 16-bit word. |

Table 3-36. MitsubishiFX Data Members (FX Series) (Continued)

| Data member | Type | Read | Write | Description |
|---------------|---------|------|-------|--|
| M0–M1023 | logical | yes | yes | Discrete coil, 1-bit. |
| Poll | logical | no | yes | When this expression transitions from FALSE to TRUE, Lookout polls the device. |
| PollRate | numeric | no | yes | Lookout expression that determines the device polling frequency. |
| S0–S1023 | logical | yes | yes | State, 1-bit. |
| sD8000–sD8255 | numeric | yes | yes | Special data register, 16-bit word. |
| sM0–sM1023 | logical | yes | yes | Special discrete coil, 1-bit. |
| T0–T1023 | numeric | yes | yes | Timer, 16-bit word. |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device. |
| X0–X1023 | logical | yes | no | Discrete input, 1-bit. |
| Y0–Y1023 | logical | yes | yes | Discrete output, 1-bit. |

Mitsubishi Status Messages

No response within timeout period

Lookout received no response from a device within the **Receive timeout** period. The Mitsubishi object is able to use the COM port, but when it polls the device, it does not respond—as if it is not even there. If you have daisy-chained several devices, you have introduced an inherent delay. You may need to significantly increase **Receive timeout** (and **PollRate**) to ensure Lookout is allowing enough time to receive the expected response. This increase has nothing to do with the processing capabilities of Lookout, but is based solely on **Data rate** and the number of devices on the chain. Also, verify your Baud rate settings, cable connections, power, configuration settings, COM port settings, and polling addresses.

Incorrect frame check sum (FCS)

The frame was received with an invalid frame check sum. Check for two or more devices with the same address.

Incorrect PC number in response

The frame received had an incorrect source address. Check for two or more devices with the same address.

Incorrect command in response

The frame received had an incorrect command. Check for two or more devices with the same address.

Garbled or Invalid frame

The frame was received without proper termination character (ETX). Check the Lookout **Receive Gap** setting.

No acknowledgment for write frame

The write frame was not acknowledged by the PC. Check the address of Mitsubishi object or the address range of the PC.

Mitsubishi errors reported in the response

These errors are reported by the Mitsubishi device, and are in turn reported to the user in text form.

Mitsubishi Models Supported

A series:

A0J2, A0J2H, A1, A1S, A1N, A1E, A2, A2n, A2C, A2E, A3, A3N, A3E, A3H, A3M.

FX series:

All models through March, 1997.

Modbus

ModbusMOSCAD

Modbus and ModbusMOSCAD are protocol driver classes Lookout uses to communicate with equipment such as programmable logic controllers (PLCs), remote terminal units (RTUs), or any other piece of equipment using Modbus Serial (ASCII or RTU) or Modbus Plus communication protocol.

The Modbus object class has general-purpose addresses, such as holding register 40001, and is suitable for communicating with nearly all Modbus devices, including the Control Microsystems TeleSAFE RTU.

The ModbusMOSCAD object class works with Motorola MOSCAD PLCs and RTUs. It also uses the Modbus Serial (ASCII or RTU) or Modbus Plus communication protocol, but its data members reflect the address of Motorola MOSCAD devices.

You can limit the number of channels Lookout uses on the SA-85 card by creating a `modbus.ini` file in the Lookout directory, as shown in the following example.

```
[ALL]
MaxChannels=channel
```

where `channel` is a number between 1 and 8, inclusive (default = 8).

These protocol driver objects contain a great deal of data. All readable and writable members (inputs/outputs), polling instructions, read/write blocking, serial port usage, and so on are bundled with the object.

Therefore, as soon as you create a Modbus or ModbusMOSCAD object you immediately have access to all the object data members (see data member list in Table 3-38).



Note Lookout protocol driver objects automatically generate an efficient read/write blocking scheme based on the inputs and outputs being used in your process file. You are not required to build your own I/O blocking table.

As protocol drivers, both object classes conform to the specifications in the Modicon Modbus Protocol Reference Guide PI-MBUS-300 Rev. C. The drivers support ASCII and RTU transmission modes, as well as Modbus Plus.

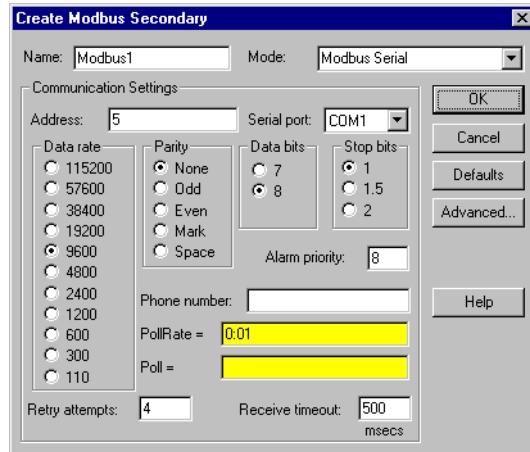


Figure 3-17. Modbus Configuration Parameters Dialog Box

In this example, Lookout is connected to a Modbus-speaking PLC with an address of 5 using serial port 1 (which was previously configured for hardwired communications), and polling the device every second.

Modbus Serial indicates that the slave device talks either Modbus ASCII or Modbus RTU. When you select this option, Lookout first tries to communicate using the RTU format. If unsuccessful, it then tries the ASCII format (a little slower). If your network is susceptible to repeated communication problems, and if these problems slow scanning considerably, you may want to disable Lookout from retrying both formats. This can speed communication retries by Lookout; however, it will not fix your communication problems. Call National Instruments technical support to for information on how to prohibit Lookout from trying to communicate using both formats.

Modbus Plus Network indicates that the slave device is connected to the Lookout computer via a Modbus Plus network card.



Note NetBIOS-based networking software typically uses software interrupt 5C. This is also the default software interrupt used by the Modbus Plus Network card driver. Change the Modbus Plus software interrupt from 5C to 5D, 5E, or 5F. Refer to your Modicon documentation for instructions on changing the software interrupt setting.

Modbus Ethernet indicates you are communicating with the Modbus slave device using an Ethernet connection.

If you select **Modbus Serial**, you must specify **Address**, **Serial Port**, **Data Rate**, **Parity**, **Data Bits**, and **Stop Bits**. And if you are using a Dial-up modem connected to your communication port, you must also specify a **Phone Number**.

If you select **Modbus Plus Network**, you need only specify the remote device **Address**.

If you select **Modbus Ethernet** you must specify the **IP address** in addition to **Alarm Priority**, **Poll Rate**, **Poll Retry attempts**, and **Receive timeout**.

Address is a slave address and refers to the PLC or RTU address setting as set on the device dip switches. If devices share a common line, they require unique addresses (1 to 255).

IP address is the Internet Protocol address for the Modbus slave object you are communicating with.

Serial port specifies which port the object uses for communication to the external device. This does not specify the communication type. Communication type is determined by the **Options»Serial Ports...** command.

Data rate, **Parity**, **Data bits**, and **Stop bits** reference the settings on the hardware device.

The **Defaults** button replaces the current settings with default values.

Alarm priority determines the priority level of Modbus-generated alarms.

Phone number specifies the number to be dialed if the serial port setting is configured for dial-up. This number only applies to the individual protocol object.

PollRate is a numeric expression that determines how often to poll the device. Modbus then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the Modbus object generates an alarm and releases the communication port back to the communications subsystem which then moves on to the next device in the polling queue (if any). Refer to Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

Advanced Modbus Parameters

The Modbus driver attempts to block the reads and writes of coils, input registers and holding registers into groups to maximize communication efficiency. Through the **Advanced Modbus Options** dialog box, you can control the maximum block sizes that the driver uses. In fact, if your device does not support the default block sizes, you may have to specify smaller blocks.

The **Advanced...** button invokes the **Advanced Modbus Options** dialog box you can use to customize specific options within the Modbus protocol.

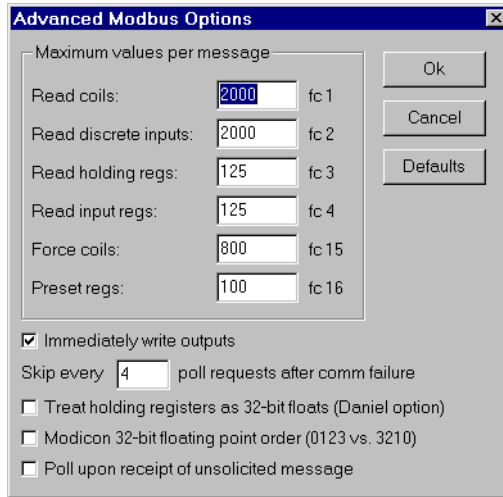


Figure 3-18. Advanced Modbus Parameters Dialog Box

The Modbus object class uses Modbus Function Codes 01, 02, 03, 04, 05, 06, 15, and 16; and expects the remote I/O device to support these codes as specified by Modbus. The driver can communicate with up to 247 Modbus slave devices on each serial port.

The **Maximum values per message** settings specify the maximum number of elements Lookout attempts to read (fc 1 – fc 4), or write (fc 15 and fc 16), in a single Modbus message. The default values represent the maximum number of elements that the protocol can transmit in a single message, and provides optimal speed. However, some devices are not capable of handling the maximum number of elements, so you should set the values according to the documentation for those devices.

If the **Immediately write outputs** option is ON, Lookout immediately polls the device any time a value changes that is being written out to the device. If it is OFF, Lookout waits until the next scheduled poll to write out changed values.

The **Skip every...** setting instructs Lookout to not poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle accordingly. Once communications have been reestablished, the device is polled on its regular cycle.

The **Daniel option** is device-dependent and instructs Lookout to treat holding registers as 32-bit IEEE floating values instead of 16-bit values. If you set this flag, you must also set your hardware device to treat holding

registers as 32-bit floats—most devices do not support this option, but Bristol-Babcock RTUs and Daniel flow meters do.



Note Activating the Daniel option deactivates all Modbus holding register members (on that device) except for 40001 – 49999 and 4000001 – 465000. If you attempt to read D40001, for example, the returned value is 0, and Lookout will not attempt to write D40001 to the RTU. Of course, in devices that do not support this option, you can still read and write two adjacent holding registers as a floating point value with the Modbus data members F40001 – F4999. In fact, this is a more general purpose solution than the Daniel option, because you can still read bits and word values out of the holding registers, too.

Some Modbus PLCs reverse byte order in a floating point data member. If your process is returning garbled or senseless floating point values, select the **Modicon 32-bit floating point order (0123 vs. 3210)** option in the **Advanced Modbus Options** dialog box. This option chooses whether the characters within the floating point registers (data members F40001 – F49999 and F400001 – F465000) are in little endian or big endian format.

On occasion a Modbus PLC will direct a message to your process. To poll for all data member values following receipt of such a poll, select the **Poll on receipt of unsolicited message** option in the **Advanced Modbus Options** dialog box. Using this option is a way to force a poll of a Modbus device based on an event, without reference to the configured poll intervals and somewhat outside the usual Lookout event-driven action.



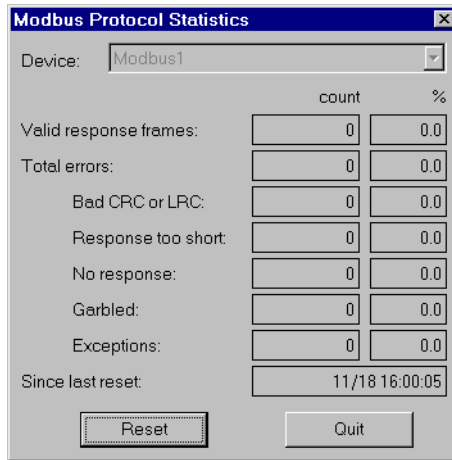
Caution Notice that the D and F data members read two adjacent registers as single, 32-bit numbers. One consequence of this is that if you connect to two adjacent registers, such as **D40010** and **D40011**, you will get incorrect values because of overlapping. Make sure that you do not connect to adjacent registers with the D or F data members.

Modbus Protocol Statistics

The driver monitors Modbus Protocol Statistics. This data is held within readable data members of the Modbus object and you can see them in the Modbus Protocol Statistics dialog box. To view the dialog box, select **Options»Modbus...** and click on **Statistics...**



Note The **Options»Modbus...** option is only visible in the **Options** menu if a Modbus object was previously created in your Lookout application.



The dialog box, titled "Modbus Protocol Statistics", features a "Device:" dropdown menu set to "Modbus1". Below this is a table with two columns: "count" and "%". The table lists several categories with their respective counts and percentages, all currently at 0 and 0.0. At the bottom, there is a "Since last reset:" field showing the date and time "11/18 16:00:05", and two buttons: "Reset" and "Quit".

| | count | % |
|------------------------|----------------|-----|
| Valid response frames: | 0 | 0.0 |
| Total errors: | 0 | 0.0 |
| Bad CRC or LRC: | 0 | 0.0 |
| Response too short: | 0 | 0.0 |
| No response: | 0 | 0.0 |
| Garbled: | 0 | 0.0 |
| Exceptions: | 0 | 0.0 |
| Since last reset: | 11/18 16:00:05 | |

Figure 3-19. Modbus Protocol Statistics Dialog Box

The **Count** column contains the accumulated number of messages received from the selected **Device** that fall into each respective category since the last time the **Reset** button was pressed. The percent column (**%**) indicates the percentage of messages received that fall into each respective category since the last time the **Reset** button was pressed.

When you depress the **Reset** button, the **ResetCounts** data member is set **TRUE**, setting all statistical values to zero. Lookout records the date and time that the reset was last performed in the **Since last reset** data field.

Modbus Data Members

The Modbus object class supports both 5-digit and 6-digit addressing. When you use a 6 digit address, the left-most digit represents the address *type* as follows:

Table 3-37. 6-Digit Address Coding

| First Digit | Address Type |
|-------------|-------------------|
| 0 | Single-bit coils |
| 1 | Discrete inputs |
| 3 | Input registers |
| 4 | Holding registers |

The remaining 5 digits represent the actual address of the coil, input or holding register.



Note When you reference address 000001 and address 1, you are referring to the same point, but 40001 and 040001 do not refer to the same point. Because zero is the left-most digit in the 6-digit address, 040001 points to the 40001st single-bit coil and 40001 refers to the first holding register.

Table 3-38. Modbus Data Members

| Data Member | Type | Read | Write | Description |
|-----------------|---------|------|-------|---|
| 000001 – 065000 | logical | yes | yes | 6-digit addresses of single-bit coils |
| 1 – 9999 | logical | yes | yes | Single-bit coils |
| 100001 – 165000 | logical | yes | no | 6-digit addresses of single-bit discrete inputs |
| 10001 – 19999 | logical | yes | no | Single bit discrete inputs |
| 300001 – 365000 | numeric | yes | no | 6-digit addresses of 16-bit input registers encoded as unsigned binary integers ranging from 0 to 65535 |
| 30001 – 39999 | numeric | yes | no | 16-bit input registers encoded as unsigned binary integers ranging from 0 to 65535 |

Table 3-38. Modbus Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|-----------------------|-------------|-------------|--------------|---|
| 400001 – 465000 | numeric | yes | yes | 6-digit addresses of 16-bit input registers encoded as unsigned binary integers ranging from 0 to 65535 |
| 400001.1 – 465000.16 | logical | yes | yes | 6-digit address used to access individual bits out of holding registers and read them as logical ON/OFF values. The least significant bit is 1; the most significant, 16. |
| 40001 – 49999 | numeric | yes | yes | 16-bit holding registers encoded as unsigned binary integers ranging from 0 to 65535 |
| 40001.1 – 49999.16 | logical | yes | yes | Access individual bits out of holding registers and read them as logical ON/OFF values. The least significant bit is 1; the most significant, 16. |
| BadCRC | numeric | yes | no | Number of responses from device whose message failed the cyclic redundancy check (CRC) or the longitudinal redundancy check (LRC) |
| BCD300001 – BCD365000 | numeric | yes | no | 6-digit addresses of 16-bit input registers encoded as binary-coded decimal integers ranging from 0 to 9999 |
| BCD30001 – BCD39999 | numeric | yes | no | 16-bit input registers encoded as binary-coded decimal integers ranging from 0 to 9999 |
| BCD400001 – BCD465000 | numeric | yes | yes | 6-digit addresses of 16-bit holding registers encoded as binary-coded decimal integers ranging from 0 to 9999 |
| BCD40001 – BCD49999 | numeric | yes | yes | 16-bit holding registers encoded as binary-coded decimal integers ranging from 0 to 9999 |

Table 3-38. Modbus Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---|
| CommFail | logical | yes | no | Driver-generated signal that is ON if Lookout cannot communicate with the device for whatever reason |
| D400001 – D465000 | numeric | yes | yes | 6-digit addresses of 32-bit unsigned holding register—reads two adjacent holding registers as a single 32-bit number ranging from 0 to 4,294,967,296. |
| D40001 – D49999 | numeric | yes | yes | 32-bit unsigned holding register—reads two adjacent holding registers as a single 32-bit number ranging from 0 to 4,294,967,296. |
| Exceptions | numeric | yes | no | Number of responses from device whose message was understandable to the driver but included an error code indication from the device |
| F400001 – F465000 | numeric | yes | yes | 6-digit addresses of 32-bit IEEE floating point register—reads two adjacent holding registers as a single 32-bit floating point value |
| F40001 – F49999 | numeric | yes | yes | 32-bit IEEE floating point register—reads two adjacent holding registers as a single 32-bit floating point value |
| Garbled | numeric | yes | no | Number of responses from device whose message was unintelligible to the driver |
| NoResponse | numeric | yes | no | Number of polls generated by driver not responded to by device |
| OffHook | logical | no | yes | When TRUE, this flag instructs the Modbus object to retain exclusive use of its assigned communication port |
| Poll | logical | no | yes | When this expression transitions from FALSE to TRUE, Lookout polls the device. |

Table 3-38. Modbus Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|--|
| PollRate | numeric | no | yes | Lookout expression that determines the device polling frequency. |
| ProtocolErrors | numeric | yes | no | Total number of bad messages received from polled device |
| ResetCounts | logical | no | yes | Resets number to zero in the following data members: ValidFrame, NoResponse, TooShort, BadCRC, Garbled, Exceptions, & ProtocolErrors |
| S400001 – S465000 | numeric | yes | yes | 6-digit addresses of 16-bit holding registers encoded as signed binary integers ranging from –32767 to +32768. |
| S40001 – S49999 | numeric | yes | yes | 16-bit holding registers encoded as signed binary integers ranging from –32767 to +32768. |
| TooShort | numeric | yes | no | Number of responses from device whose message length was too short |
| Update | logical | yes | no | Driver-generated signal that pulses each time the driver polls the device |
| ValidFrame | numeric | yes | no | Number of good messages received from polled device |

Comments You can use the OffHook data member to enhance communications when using the Modbus object class with dial-up modems. When OffHook is TRUE and the serial port is connected to a dial-up modem, the Modbus object does not hang up the modem when the poll is complete. Rather, it keeps the phone off the hook, retaining exclusive use of the serial port. As long as OffHook is TRUE, the Modbus object continues to poll the same PLC without hanging up the modem.

As soon as OffHook goes FALSE, the object releases the serial port to the communications subsystem, which goes to the next poll request in the queue, if any. The object also releases the port if data communications are lost for any reason—such as if the PLC modem breaks the connection.

When using OffHook, consider defining the driver object **PollRate** to poll fast when OffHook is TRUE, and poll at its normal rate when OffHook is FALSE. You might tie a Switch object to the OffHook writable data member for this very purpose.

ModbusMOSCAD Data Members

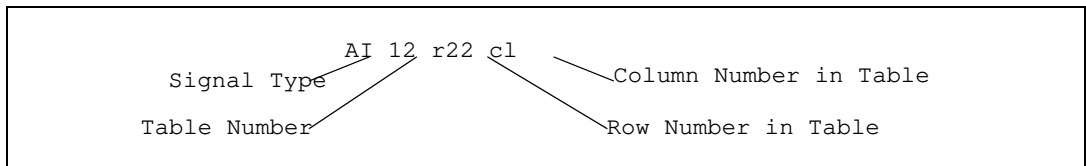
Table 3-39. ModbusMOSCAD Data Members

| Data Member | Type | Read | Write | Description |
|---------------------------|---------|------|-------|---|
| AI0r0c0 – AI30r255c7 | numeric | yes | no | Each address represents a 16-bit analog input encoded as an unsigned integer ranging from 0 to 65535 |
| AO0r0c0 – AO30r255c7 | numeric | yes | yes | Each address represents a 16-bit analog output encoded as an unsigned integer ranging from 0 to 65535 |
| BadCRC | numeric | yes | no | Number of responses from device whose message failed the cyclic redundancy check (CRC) or the longitudinal redundancy check (LRC) |
| CommFail | logical | yes | no | Driver-generated signal that is ON if Lookout cannot communicate with the device for whatever reason |
| DI0r0c0.0 – DI30r255c7.15 | logical | yes | no | Each address represents an individual discrete input read as a logical ON/OFF value. The least significant bit is 0; the most significant, 15. |
| DO0r0c0.0 – DO30r255c7.15 | logical | no | yes | Each address represents an individual discrete output read as a logical ON/OFF value. The least significant bit is 0; the most significant, 15. |
| Exceptions | numeric | yes | no | Number of responses from device whose message was understandable to the driver but included an error code indication from the device |
| Garbled | numeric | yes | no | Number of responses from device whose message was unintelligible to the driver |

Table 3-39. ModbusMOSCAD Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|----------------|---------|------|-------|--|
| NoResponse | numeric | yes | no | Number of polls generated by driver not responded to by device |
| Poll | logical | no | yes | When this expression transitions from FALSE to TRUE, Lookout polls the device. |
| PollRate | numeric | no | yes | Lookout expression that determines the device polling frequency. |
| ProtocolErrors | numeric | yes | no | Total number of bad messages received from polled device |
| ResetCounts | logical | no | yes | Resets number to zero in the following data members: ValidFrame, NoResponse, TooShort, BadCRC, Garbled, Exceptions, & ProtocolErrors |
| TooShort | numeric | yes | no | Number of responses from device whose message length was too short |
| Update | logical | yes | no | Driver-generated signal that pulses each time the driver polls the device |
| ValidFrame | numeric | yes | no | Number of good messages received from polled device |

Comments To specify the address of an analog input located in row 22, column 1 of Table 12, you would enter AI12r22c1, where



ModbusSlave

ModbusSlave is an object class Lookout uses to act as a slave to equipment such as PLCs, distributed control systems (DCSs), or any other device that can act as a Modbus master. The ModbusSlave object enables Lookout to respond to unsolicited messages generated by other devices on a Modbus protocol network.

Applications include:

- PLCs and/or RTUs dial up a Lookout application over a non-dedicated phone line when there is an alarm or event that must be reported (unsolicited report-by-exception).
- Two Lookout packages communicate with each other over radio. One uses a Modbus object and the other uses a ModbusSlave object.
- Lookout, directly connected to a Modbus network, responds to polls from a DCS as a Modbus slave.

Think of the ModbusSlave object as representing a virtual PLC within Lookout. It can receive reads and writes over a Modbus protocol-based network. Like the Modbus object, the ModbusSlave object has a collection of readable and writable data members, all created when you define the ModbusSlave object.

You can create a unique ModbusSlave object for every master PLC, or you can create a single ModbusSlave object for multiple master PLCs. In the latter case, one master might write to one group of registers within the ModbusSlave object and another master might write to another group of registers within the ModbusSlave object.

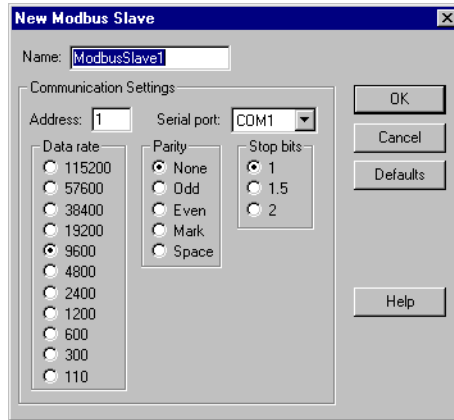


Figure 3-20. Modbus Slave Configuration Parameters Dialog Box

Address is a number (1 to 255) that refers to the address that this ModbusSlave object will assume. Even though this object exists only in software, other physical devices do not know that. They communicate with this object using a physical communication line and need to know the slave address.

Serial port identifies which communication port on the PC that the Modbus master uses to communicate with the ModbusSlave in Lookout.

Data rate, Parity, Data bits, and Stop bits reference the settings utilized by the master hardware device.

The **Defaults** button replaces the current settings with default values.

Modbus Slave Data Members

Table 3-40. ModbusSlave Data Members

| Data Member | Type | Read | Write | Description |
|---------------|---------|------|-------|--|
| 1 – 9999 | logical | yes | yes | Single-bit coils |
| 10001 – 19999 | logical | yes | yes | Single bit discrete inputs |
| 30001 – 39999 | numeric | yes | yes | 16-bit input registers encoded as unsigned binary integers ranging from 0 to 65535 |

Table 3-40. ModbusSlave Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|------------------------|-------------|-------------|--------------|--|
| 40001 – 49999 | numeric | yes | yes | 16-bit holding registers encoded as unsigned binary integers ranging from 0 to 65535 |
| BCD30001 – BCD39999 | numeric | yes | yes | 16-bit input registers encoded as binary-coded decimal integers ranging from 0 to 9999 |
| BCD40001 – BCD49999 | numeric | yes | yes | 16-bit holding registers encoded as binary-coded decimal integers ranging from 0 to 9999 |
| D30001 – D39999 | numeric | yes | yes | 32-bit input register |
| D40001 – D49999 | numeric | yes | yes | 32-bit unsigned holding register—reads two adjacent holding registers as a single 32-bit number ranging from 0 to 4,294,967,296. |
| F30001 – F39999 | numeric | yes | yes | 32-bit input register |
| F40001 – F49999 | numeric | yes | yes | 32-bit IEEE floating point register—reads two adjacent holding registers as a single 32-bit floating point value |
| H40001.f1 – H49999.f16 | logical | yes | yes | Access individual bits out of holding registers and read them as logical ON/OFF values. The least significant bit is F1 and the most significant bit is F16. |
| S40001 – S49999 | numeric | yes | yes | 16-bit holding registers encoded as signed binary integers ranging from –32767 to +32768. |

National Instruments Fieldbus

Lookout can communicate with Fieldbus devices using the National Instruments NI-FBUS AT card.

The Lookout Fieldbus objects contain no inherent physical data members. All physical data members are obtained by reading Device Descriptions (DD). A default DD is provided when you install the National Instruments Fieldbus card which contains all the standard Fieldbus blocks. Lookout creates a Fieldbus object class dynamically for every uniquely named block found in any of the DDs. If a block is defined more than once by name, then the user is able select which DD block definition to apply to the Lookout object in the object creation dialog box. The National Instruments supplied DD is selected by default.

In order to add or remove a Fieldbus block type to the Lookout object class list, delete the `Lookout.dat` file in the `\Lookout` directory and restart Lookout. This forces Lookout to re-index all of its subordinate object classes. The name of Fieldbus object classes is the name of the block preceded by `FF_`. For example, the Lookout class name for an Analog Input block would be `FF_Analog_Input`.

Lookout also supports manufacturer supplied DDs. These DDs must be placed in the appropriate directory structure as defined by the Fieldbus Foundation. You can configure the base directory for manufacturer supplied DDs with the National Instruments `NI-FBUS Config` software. After selecting **DD Info** in the main dialog box of the `NI-FBUS Config` software, enter the path for your base directory. The DD should be placed, along with its symbol file, two folders below this base directory. Conventions for naming these directories are outlined by Fieldbus Foundation but the names are not used by Lookout.

When re-indexing occurs, Lookout looks into every DD in the directory system for Fieldbus blocks. Lookout also requires a symbol file (`*.sym`) for every DD (`*.ffo`).



Note DD must be made with tokenizer version 4.2 or greater.

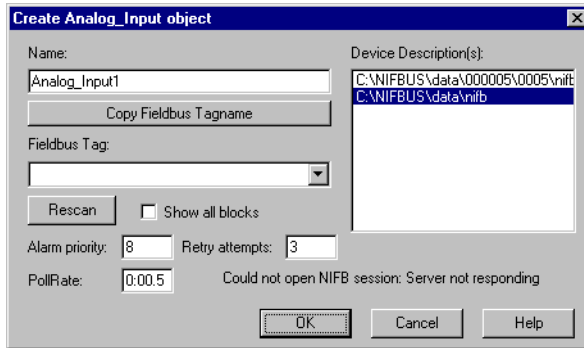


Figure 3-21. Fieldbus Configuration Parameters Dialog Box

Name is the Lookout name and is used to reference this object in Lookout.

Copy Fieldbus Name replaces invalid characters in the Fieldbus Name with underscores while copying the Fieldbus Name into the Lookout Name edit box.

Fieldbus Name shows a list of all Fieldbus blocks, of the appropriate type, available on your network. This list comes from comparing the DD_Item_Type of the block on the networks with the type of object that the user has selected to create. If there are no devices in this listbox, you can click the **Show all blocks** checkbox and select the **Rescan** button to show Fieldbus blocks of all types on the network.



Note Lookout treats the block selected as the type of block the user was trying to make. If an incorrect block is selected, the wrong parameter list appears for that block and invalid data request may occur.

Device Description contains a list of Device Descriptions that have definitions for the block the user is about create. The parameter list for each definition may vary. Care should be taken in selecting the proper DD for the block this Lookout object will represent.

PollRate is a numeric expression that determines how often to poll the device. The object then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Retry is the number of Fieldbus communication alarms to ignore before reporting an alarm.

Alarm priority determines the priority level of alarms generated by the National Instruments Fieldbus object. Such alarms are typically related to communications with the physical device.

Fieldbus Alarms

The Fieldbus Alarms dialog box lets you acknowledge Fieldbus Alarms.

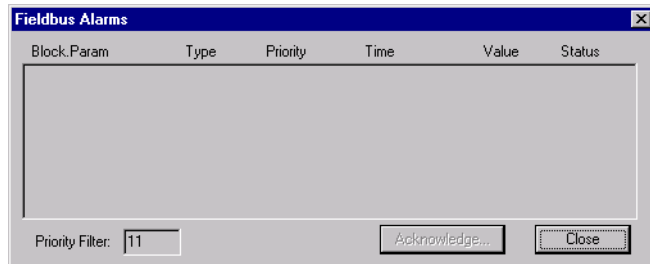


Figure 3-22. Fieldbus Alarms Dialog Box

Priority Filter filters alarms by priority. If you **Acknowledge** an alarm, it is removed from the list if successful.

Fieldbus Data Members

As with all Lookout drivers, you can access I/O points and other data through data members. The following is a table of built-in data members currently supported by the National Instruments Fieldbus object class. All other data members are obtained from device descriptions.

Table 3-41. National Instruments Fieldbus Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|--|
| Alarms | numeric | yes | no | Expression that shows number of active Fieldbus alarms. |
| CommFail | logical | yes | no | Object-generated signal that is on if Lookout cannot communicate with the device(s). |
| Poll | logical | no | yes | When this value transitions from FALSE to TRUE, Lookout polls the device. |

Table 3-41. National Instruments Fieldbus Data Members

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|--|
| ShowAlarms | logical | no | yes | When this value transitions from FALSE to TRUE, Lookout shows the Fieldbus alarm window. |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device. |

Fieldbus Status Messages

No response within timeout period

Lookout did not receive a response from a device within the **Receive timeout** period. Check the device's connection. Check to see if the device can be polled using NI-FBUS Dialog.

Cannot find nifb.dll

Lookout could not find a component needed to communicate with the Fieldbus devices. This component is placed during the installation of the NI-FBUS software. Make sure the installation was successful.

Could not open NIFB session [: optional error message]

Lookout could not open a Fieldbus communications session. If available, specific error text is shown providing specific information. Make sure that the `nifb` driver in **Settings»Control Panels»Devices** is started. Also make sure that `nifb.exe` is running.

Block name could not be found on network

Lookout could not find the block name specified on the Fieldbus network. Check name spelling or the device/network connections.

I/O error: [error message]

Lookout encountered an error during the read/write process. The error message, provided by the Fieldbus communication interface, contains specific information regarding the cause of the failure.

Fieldbus Troubleshooting

If after deleting the lookout.dat file and restarting Lookout there are no FF_(Fieldbus Object) classes listed in Lookout; check the following:

- Is the path to the data directory in your `nifbus` installation directory specified correctly in NI-FBUS config software under **DD Info**?
- Is the path to the base directory for manufacturer supplied DDs specified correctly?
- Does the `NI-FBUS Dialog` application work correctly?

Lookout cannot establish a fieldbus session with the card.

- Is `NIFB.EXE` running?
- Has the device driver `nifb` in your device control panel been started?
- Does the `NI-FBUS Dialog` application work correctly?

National Instruments FieldPoint

FieldPoint is a protocol driver class Lookout uses to communicate with FieldPoint devices using an enhanced version of the Optomux communication protocol. This object works with the FieldPoint models FP-1000, FP-1001, FP-AI-110, FP-AO-200, FP-DI-330, and FP-DO-400.

This protocol uses no parity, eight data bits and one stop bit. In Lookout, a single FieldPoint object represents all devices connected to the same COM port.

The Lookout FieldPoint object can read and write to all predefined data points allowed by the particular FieldPoint module. When you create a FieldPoint object, you have immediate access to all the object data members. See the [FieldPoint Data Members](#) section for more information on object data members.

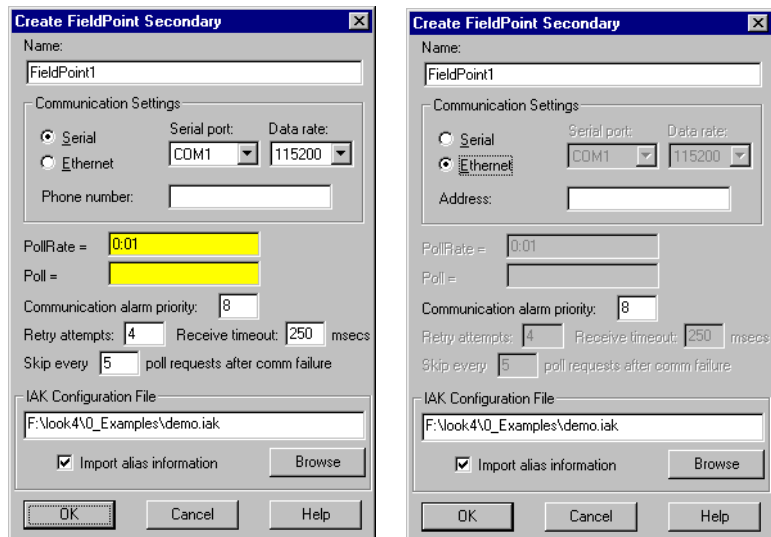


Figure 3-23. National Instruments FieldPoint Configuration Parameters Dialog Box

When you select the **Ethernet** option, the serial port configuration options are disabled.

Enter the IP address in the **Address** field. You could also enter the FieldPoint network name instead.



Note If you replace a FieldPoint FP-1000 module (serial communications) with a FieldPoint FP-1600 module (Ethernet communications) or replace an FP-1600 module with an FP-1000 module, you must re-import your .IAK file. First, you must use FieldPoint Explorer to update your .IAK file. If necessary, consult your FieldPoint online help for detailed instructions on using FieldPoint Explorer. To re-import the .IAK file, unselect the **Import alias information** checkbox and click on **OK**. Reopen the FieldPoint object dialog box and select the **Import alias information** checkbox again. When you click on **OK**, Lookout re-imports the new .IAK file information.

Serial port specifies which COM port the object uses for communicating to the external device. This does not specify the communication type. Communication type is determined by the **Options»Serial Ports...** menu command.

Data rate indicates the baud rate that Lookout uses to communicate with the hardware device. This setting should match the selection made on each of your network modules.

Phone number specifies the number to be dialed if the selected serial port is configured for dial-up. This number only applies to the individual protocol object.

PollRate is a numeric expression that determines how often to poll the device. The object then polls the device at the specified time interval. Ordinarily, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Poll is a logical expression. When transitioned from FALSE to TRUE, Lookout polls the device. This can be a simple expression, like the signal from a pushbutton, or it can be a complex algorithm.

Communication alarm priority determines the priority level of alarms generated by the FieldPoint object. Such alarms are typically related to communications with the physical device.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the FieldPoint object generates an alarm and releases the COM port. Refer to Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

The **Skip every n** setting instructs Lookout to not poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle. Once communications have been reestablished, the device is polled on its regular cycle.

IAK configuration file is a dialog for selecting an IAK configuration file. The IAK file contains alias and scaling information which is extracted for use in Lookout. Choose the configuration file you want to use by entering the path directly, or use the **Browse** button. Check **Import alias information** if you want to extract information from the selected file.

FieldPoint Data Members

As with all Lookout drivers, you can access I/O points and other data through data members. The following is a table of data members currently supported by the FieldPoint object class.

Table 3-42. National Instruments FieldPoint Data Members

| Data Member | Type | Read | Write | Description |
|---------------------|---------|------|-------|--|
| AI000.00 - AI255.15 | numeric | yes | no | Analog input channels. |
| AO000.00 - AO255.15 | numeric | yes | yes | Analog output channels. |
| CA000.00 - CA255.15 | numeric | yes | no | Use to connect to count inputs on a FieldPoint counter module. |
| CD000.00 - CD255.15 | logical | yes | no | Use to connect to digital inputs on a FieldPoint counter module. |
| CI000.00 - CI255.15 | logical | no | yes | Counter increment. |
| CO000.00 - CO255.15 | logical | yes | yes | Use to connect to digital outputs in a FieldPoint Counter module. |
| CommFail | logical | yes | no | Goes high if Lookout cannot communicate with the device. |
| CR000.00 - CR255.15 | logical | no | yes | Counter reset. |
| DI000.00 - DI255.15 | logical | yes | no | Discrete input channels. |
| DO000.00 - DO255.15 | logical | yes | yes | Discrete output channels. |
| PF000.00 - PF255.15 | numeric | yes | yes | Pulse width modulator period setting. Period is the entire on/off time of the pulse in milliseconds. |

Table 3-42. National Instruments FieldPoint Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|---------------------|---------|------|-------|---|
| Poll | logical | no | yes | When transitioned from low to high, Lookout begins a poll cycle on the device. |
| PollRate | numeric | no | yes | Specifies the frequency at which Lookout polls the device. |
| PW000.00 - PW255.15 | numeric | yes | yes | Sets the FieldPoint pulse module duty cycle on/off ratio. A setting of 10.00 means the pulse is on for 10% of the pulse period and off for 90%. |
| RL000.00 - RL255.15 | logical | yes | yes | Use to connect to digital output channels on a FieldPoint relay module. |
| RT000.00 - RT255.15 | numeric | yes | no | RTD temperature measurement module analog input; returns a value in degrees Centigrade. |
| TC000.00 - TC255.15 | numeric | yes | no | Use to connect to analog input channels on a FieldPoint thermocouple module. |
| Update | logical | yes | no | Goes high when Lookout begins a poll cycle on the device. |



Note When you use the CA, CD, CI, CO, CR, PW, RL, RT, and TC data members with FieldPoint serial modules, they are synonyms for analog or digital inputs or outputs as follows:

CI, CD—Digital Input

CR, CA, RL—Digital Output

PF, PP, RT, TC—Analog Input

PW—Analog Output

With FieldPoint Ethernet, these data members represent different FieldPoint modules.



Note The first two characters of the I/O data members represent the kind of module being accessed. The next three digits represent the device address of the module. This is the address of the I/O module itself, not the network module that governs it. Following the period are two digits representing the channel number within the module.

Not all of these data members are valid for every FieldPoint module. For all the device

types you are able to select the full range of device addresses and channels. So if you select DO123.03, you need to be certain that the device at address 123 is in fact a discrete output module.

For a more complete definition of the function of these data members, see FieldPoint documentation.



Note In the event of a power cycle to the FieldPoint device during use, the configuration of the device reverts to some default state, which is configurable. You should keep in mind that if the ranges you configured into the IAK file differ from those in the power-up configuration, the scaling information imported from the IAK file and used as a Lookout alias might become outdated and incorrect after a power loss. To avoid this, make certain your power-up configuration ranges and your IAK configuration ranges are identical.

FieldPoint Multiple Discrete Data Members

Table 3-43. Multiple Discrete Data Members

| Data Member | Type | Read | Write | Description |
|---------------------------|---------|------|-------|-----------------------------------|
| MDI000.0000 - MDI255.FFFF | numeric | yes | no | Multiple discrete input channels |
| MDO000.0000 - MDO255.FFFF | numeric | yes | yes | Multiple discrete output channels |

These special purpose data members are for reading or writing a numeric integer value to a set of discrete channels.

For instance, when you are configuring your modules with FieldPoint Explorer, you have the option of selecting more than one discrete channel for a data item that you are defining. If you do this and import the resulting .IAK file into Lookout for use as aliases, the aliases created will correspond to this set of data members. You can then read and write to all the discrete channels with a single numeric data member. The data member names are in the form `MTTAAA.CCCC`, where:

| | |
|------|--|
| M | Indicates multiple as opposed to single |
| TT | Two characters specifying module type (Discrete Out, Discrete In) |
| AAA | Three numeric characters specifying module address |
| CCCC | Four hexadecimal characters specifying which of the 16 channels are included in this data member |



Note These data members will not enumerate. You may use them either by importing configurations from FieldPoint Explorer or by entering the data member name explicitly.

FieldPoint Error Messages

No response within timeout period

Lookout received no response from a device within the **Receive timeout** period. The FieldPoint object is able to use the COM port, but when it polls the device, the device does not respond. If you have daisy-chained several devices, you have introduced an inherent delay. You may have to significantly increase **Receive timeout** (and **Poll Rate**) to ensure Lookout is allowing enough time to receive the expected response. This increase has nothing to do with the processing capabilities of Lookout. Rather it is based solely on **Data rate** and the number of devices on the chain. Also, verify your baud rate settings, cable connections, power, configuration settings, COM port settings, and polling addresses.

Module returning ?? checksum

This means that the frame sent from the PLC in response to the command sent by Lookout out returned ?? instead of a valid checksum. Check FieldPoint configuration.

Message Garbled - Bad CRC

This means the checksum (CRC in this case) failed in a frame received by Lookout. Check cabling or for two or more devices with the same address.

Unexpected data response length

The frame received was of an unexpected length. Check the Lookout **receive gap** setting.

Error loading IAK configuration file

Lookout was not able to successfully extract data from the .IAK configuration file. Try running the FieldPoint Explorer again and reconfigure your hardware.

FP error: Power-up clear expected

A command other than power-up clear was attempted after power-up or power failure. The command sent is ignored and normal operations should resume.

FP error: Undefined command

The addressed module does not support this command. (for example, trying to write to an input module) Check to see if you are sending a command appropriate to the module.

FP error: Checksum error

This means the checksum (CRC in this case) failed in a frame sent by Lookout. Check the Lookout **receive gap** setting.

FP error: Input buffer overrun

The command sent to the FieldPoint module was too long. Check the Lookout **receive gap** setting.

FP error: Non-printable ASCII character received

Only characters from ASCII value 33 to 127 are permitted in FieldPoint commands. The command is ignored.

FP error: Data field error

An insufficient or incorrect number of characters were received by the FieldPoint module for the specified command. Check the Lookout **receive gap** setting.

FP error: Communications link network watchdog timed out

There has been no network traffic in the amount of time specified by your watchdog configuration settings, and the system has reverted to its watchdog defaults.

FP error: Specified limits invalid for the command

This includes the case where an invalid digit (hex or decimal) was received. Check the Lookout **receive gap** setting.

FP error: ASCII to binary conversion error

One or more ASCII characters could not be converted to binary on the FieldPoint module. Check the Lookout **receive gap** setting.

FP error: Invalid device address

The command is valid, but the addressed module does not support the command received. Check to see if you are sending a command appropriate to the module.

FP error: Serial framing error

An improperly framed command was received by the FieldPoint module. Check the Lookout **receive gap** setting.

FP error: Addressed module does not exist

Make sure that you are addressing a valid module address.

FP error: Invalid channel

One or more channels specified in the command either do not exist or do not support the operation specified.

FP error: Invalid range setting

Check to see that the range information on the module has not changed, possibly due to a loss of power.

FP error: Invalid operation for the module

One or more module-specific operations specified in the command either do not exist or do not support the operation specified. Make sure that you are not requesting a discrete operation for an analog module, and vice versa.

FP error: Module has been hotswapped since last command

The alarm should deactivate immediately after it appears. Its appearance is only to acknowledge that a hot swap has occurred.

FP error: Irrecoverable hardware fault

A malfunction in the FieldPoint firmware or hardware has made communications from Lookout impossible.

Channel specific error: dev:##,ch:##,err:##

These are error codes returned from the FieldPoint I/O modules. The alarm message specifies a device address, channel number, and error code. See FieldPoint documentation for a description of the error condition.

National Instruments Lookout OPC Client

Lookout uses the National Instruments Lookout OPC client to read data from and write data to any OPC server. It supports numeric, logical (boolean), and text I/O. The Lookout 4 OPC client normally reads from the cache. You can connect a switch or pushbutton to the `PollDevice` data member to trigger a device update.

For your convenience, you can create `OPCFieldPoint` and `OPCNIDAQ` versions of the `OPCClient` object class by selecting these two special cases from the **Select Object Class** dialog box.



Note If you are using the National Instruments OPC IATest server, there is no device to poll. Triggering the `PollDevice` data member returns a zero (0). Simulated data will be restored shortly after such a poll.

The **Server Name** box enumerates all of the OPC servers registered on the local computer. Select the appropriate server.



Note The Server Name listbox contains only local servers. It has no effect on what you find when you browse remote servers.

You can then select one of the **In-Process Server**, **Local Server**, and **Remote Server** options. These options specify the type of server the OPC

client will attempt to launch. If it cannot successfully connect to the selected server, the OPC client generates an alarm.

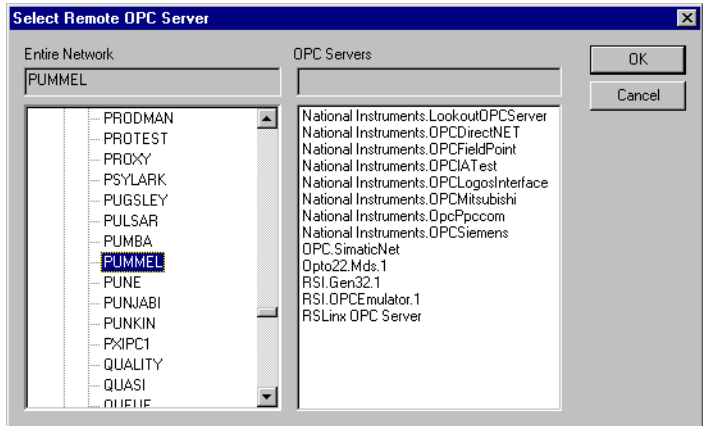
Select **Remote Server** to enable **Computer Name**, which specifies the name of the computer on which the remote server is to be launched. If you know the computer name you want, enter it preceded with two backslashes, as in \\PUMMEL.



Caution In-process servers should only be used if Lookout is the only program communicating with the server. If other programs address the same server, use the Local Server option.

The **Browsing** options include **Disabled**, **Flat**, and **Hierarchical**. If your OPC servers permit browsing, select either **Flat** or **Hierarchical**. If you enable flat browsing all data members appear in any Lookout windows displaying OPC client data members. If you select **Hierarchical**, the data members are arranged in hierarchical folders.

To browse remote servers, click on the browsing button next to the **Remote Server** field. The following dialog box appears.



Browse for the computer you want, and select the OPC server running on the computer that you want to access.



Note You must have the Microsoft Remote Registry service installed for remote OPC browsing to work on a computer running Windows 98/95. To install, select **Start»Settings»Control Panel** and then select **Network**. Check the Configuration tab to see if Microsoft Remote Registry is installed. If it is not, click on the **Add** button, and select **Service** in the **Select Network Component Type** dialog box. Choose Microsoft as the

manufacturer. If the Remote Registry service is not visible, you will need your Windows 98/95 CD-ROM. You may have to browse through the disk to find the correct service. Once you have installed this service, you can successfully use remote OPC browsing in the Lookout OPCClient object.

Select **Use Asynchronous I/O** if you want to use asynchronous communications with your OPC server. This is the preferred communications mode, and should be used when possible.

The **Force Refresh after Write** option is only available if you select the **Use Asynchronous I/O** option. This option forces the OPC server to return the current status of all data members every time you write to one.



Note Selecting **Force Refresh after Write** can sometimes impair performance of your Lookout process, depending on the number of data members in your OPC server and other system variables, including communications speed and what other tasks are being performed at any particular moment.

Update Rate is a numeric expression that determines how often the OPC server updates the client. Enter this time interval in milliseconds.

Deadband sets the percentage change that must take place in a data member before the OPC server reports a change in value to Lookout.

Poll Device is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the OPC server for all values. You can use a simple expression like the signal from a pushbutton, or a complex algorithm. In most applications there is no need to do device reads, so this parameter is often left blank.

Enter a **Default Access Path** if you want to simplify entering paths to various data members.

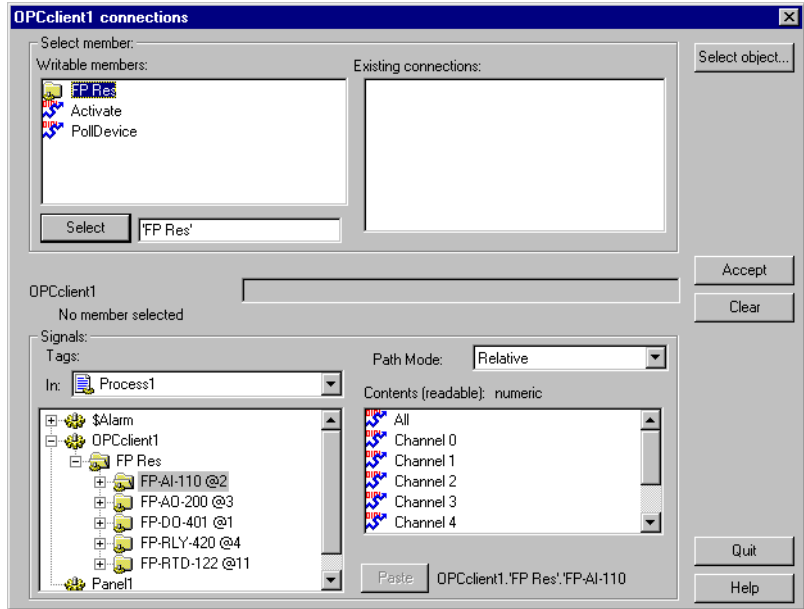
Communication Alarm Priority specifies the priority of alarms generated by this OPC client object.

OPC Client Data Members

As with all Lookout drivers, you can access I/O points and other data through data members.

Unlike other Lookout driver objects, however, the OPCClient data member set changes depending on the OPC servers you have running on your computer.

If you selected hierarchical browsing when you created the OPCClient, the data members for the OPC server you have connected your OPC client to appear as data members inside a folder in your OPCClient list of data members in the Lookout Object Explorer, connection editor, and other windows as shown in the following illustration.



If you selected flat browsing, you will see a long list of available data members without hierarchical organization into folders.

If you did not enable browsing, or your computer cannot browse certain OPC servers, you will only see the data members built into the Lookout OPCClient.

The Lookout OPCClient object class currently contains the built-in data members contained in the following table.

Table 3-44. OPCClient Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|--|
| Activate | logical | no | yes | When TRUE, the OPC client is active and receives data. When FALSE, the OPC client does not update. |
| CommFail | logical | yes | no | Goes high if Lookout cannot communicate with the server. |
| DataError | logical | yes | no | Goes high if the object cannot properly process the data returned by the server. |
| PollDevice | logical | no | yes | When transitioned from FALSE to TRUE, the object polls the server. |
| Update | logical | yes | no | Pulses high and low when the OPC server updates Lookout or Lookout successfully polls the server. |

The data members for the OPC Client depend on your OPC server. To use one of the data members from your server, enter the data member directly into an expression or URL field.

If the OPC server permits browsing, you can use data members as you would with any other Lookout driver object. If you cannot browse your OPC server, enter the item manually in the form acceptable to your OPC server, as in the following example:

```
OPCclient1.'device\folder\itemName'
```



Note Notice the use of single quotes. Using a single quote around a component of a path allows the use of any character in that path, not just the normally allowed characters.

If all your items use the same access path, use the **Default Access Path** option. If you need to specify a different access path, use a period and tilde (.) to denote the first element of the path, as in the following example:

```
OPCclient1.'device\itemN'.'~accesspath'
```

Notice that the access path must be a separate component. Single quotes denote a string as being a single component.

If an item name or access path already contains a tilde, you must enter one additional tilde to act as an escape character for that tilde, and a second additional tilde to denote an access path (for example, if the access path is ~COM1, enter ~~~COM1).

Examples

```
OPCclient1.'4:0'. '~Modbus Demo Box'
```

The access path is Modbus Demo Box and the OPC item ID is 4:0.

```
OPCclient1.'4:0'
```

The access path is Null and the OPC item ID is 4:0.



Note You cannot browse access paths for an item. You must enter access paths manually.

NIDAQDevice

Lookout uses the NIDAQDevice object class to communicate with National Instruments data acquisition devices, including data acquisition devices connected in parallel mode to SCXI hardware. Refer to the NISCXI object class for more information concerning configurations using SCXI hardware connected in multiplexed mode.

To use this object, you should have NI-DAQ 5.0 or better software installed. While the NIDAQDevice object works with some earlier versions of NI-DAQ software, it does not perform well with these earlier versions, and has not been extensively tested.

Consult your NI-DAQ hardware and software manuals for information on installing and configuring National Instruments data acquisition software and hardware.

When you create an NIDAQDevice object for the first time, or when you launch Lookout and run an application using the NIDAQDevice object, Lookout automatically loads the NI-DAQ software. This can take a few moments, during which the screen is frozen. Once the NI-DAQ software has loaded, Lookout returns to its former speed.



Note This object class is available on 32-bit versions of Lookout 3.7 and later. It is not backward compatible with earlier versions of Lookout, and does not run on the 16-bit version of Lookout.



Figure 3-24. NIDAQ Device Configuration Parameters Dialog Box

Device is the NI-DAQ device number. The DAQ configuration utility (WDAQConf.exe) assigns this number to an installed device. Valid device numbers range is from 1 to 16.

Scanning interval is the time period between analog and digital input polls. The valid range is 20 msec to 1 day (expressed in msec). You should also keep in mind that some National Instruments DAQ cards need time to stabilize, and so that a scanning rate that is faster than the stabilization rate of the card returns suspect values.

Communication alarm priority determines the priority level of the alarms generated by the NIDAQDevice object.

NIDAQDevice Data Members

Table 3-45. NIDAQDevice Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|--|
| AI0, AI63 | numeric | yes | no | Analog input channel in volts. |
| AO0, AO63 | numeric | no | yes | Analog output channel in volts. |
| CommFail | logical | yes | no | Object-generated signal that is on if, for whatever reason, Lookout cannot communicate with or control the device without error. |
| DI0, DI31 | logical | yes | no | Digital input line. |
| DO0, DO31 | logical | no | yes | Digital output line. |
| Update | logical | yes | no | Object-generated signal that pulses low each time the object polls the device. |

NIDAQ.INI

You may configure individual channel attributes by editing the NIDAQ.INI file in your Lookout directory.

To specify a channel, use the following format: [DEV1.AI5]

This specifies analog input channel 5 on device number 1.

UPPERLIMIT specifies the upper input limit in volts (for example, UPPERLIMIT=2.5). Usually used in conjunction with **LOWERLIMIT**.

LOWERLIMIT specifies the lower input limit in volts (for example, `LOWERLIMIT=-3.7`). Usually used in conjunction with **UPPERLIMIT**.

INPUTMODE specifies the analog input connection mode to use for this channel. Valid choices are 1 for differential, 2 for referenced single-ended, and 3 for non-referenced single-ended.

NIDAQDevice Error Messages

Error loading NI-DAQ driver

Lookout was not able to communicate to the NI-DAQ driver. Be sure that NI-DAQ has been installed properly, and the NI-DAQ Configuration Utility has been used to configure the your hardware devices.

NIDAQ: Analog Input: Invalid Data Member(s)

NIDAQ: Analog Output: Invalid Data Member(s)

NIDAQ: Digital Input: Invalid Data Member(s)

NIDAQ: Digital Output: Invalid Data Member(s)

At least one channels you have specified is not valid for your current hardware configuration. Be sure your hardware is configured properly using the NI-DAQ Configuration Utility.

NIDAQ: Error code: NNNNN

NIDAQ: Analog Input: Error code: NNNNN

NIDAQ: Analog Output: Error code: NNNNN

NIDAQ: Digital Input: Error code: NNNNN

NIDAQ: Digital Output: Error code: NNNNN

NI-DAQ has detected an error condition. Please refer to your *NI-DAQ Function Reference Manual* to determine the meaning of the error code.

Table 3-46. National Instruments Data Acquisition Devices Supported by Lookout

| Device | AI | AO | DIO |
|--------------------|-----------|-----------|------------|
| AT-AO-6 | — | yes | yes |
| AT-AO-10 | — | yes | yes |
| AT-MIO-16E-1 | yes | yes | yes |
| AT-MIO-16E-2 | yes | yes | yes |
| AT-MIO-16E-3 | yes | yes | yes |
| AT-MIO-16DE-10 | yes | yes | yes |
| AT-MIO-16XE-50 | yes | yes | yes |
| AT-MIO-16X | yes | yes | yes |
| AT-MIO-16F-5 | yes | yes | yes |
| AT-MIO-64E-3 | yes | yes | yes |
| CS-2017 | CJC | — | — |
| DAQCard-1200 | yes | yes | yes |
| DAQCard-700 | yes | — | yes |
| DAQCard-5XX | yes | — | yes |
| DAQPad-MIO-16XE-50 | yes | yes | yes |
| DAQPad-1200 | yes | yes | yes |
| Lab-PC+ | yes | yes | yes |
| PC-LP-16 | yes | — | yes |
| SC-2070 | CJC | — | — |
| SCB-68 | CJC | — | — |
| SCB-100 | CJC | — | — |

NISCXI

Lookout uses the NISCXI object class to communicate with National Instruments data acquisition devices connected in multiplex mode to SCXI hardware. Refer to the NIDAQDevice object class for more information concerning parallel SCXI configurations, and data acquisition configurations without SCXI.

To use this object, you should have NI-DAQ 5.0 or better software installed. While the NIDAQDevice object works with some earlier versions of NI-DAQ software, it does not perform well with these earlier versions, and has not been extensively tested.

Consult your NI-DAQ and NI-SCXI hardware, and NI-DAQ software manuals for information on installing and configuring National Instruments data acquisition software and hardware.

When you create an NISCXI object for the first time, or when you launch Lookout and run an application using the NISCXI object, Lookout automatically loads the NI-DAQ software. This can take a few moments, during which the screen is frozen. Once the NI-DAQ software has loaded, Lookout returns to its former speed.



Note This object class is available on 32-bit versions of Lookout 3.7 and later. It is not backward compatible with earlier versions of Lookout, and does not run on the 16-bit version of Lookout.

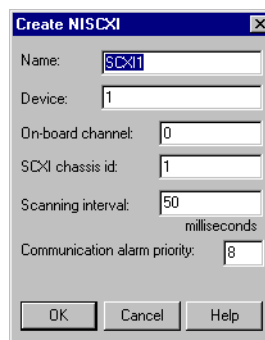


Figure 3-25. NISCXI Definition Parameters Dialog Box

Device is the NI-DAQ device number of the controlling device. The DAQ configuration utility (`WDAQConf.exe`) assigns this number to an installed device. Valid device numbers range is from 1 to 16.

On-board channel specifies the analog input channel of the controlling device used to address this SCXI chassis. When only one chassis is being controlled by the controlling board, this value should be 0. When this chassis in a multi-chassis configuration, this value should reflect the order of this chassis. For instance, the first chassis should be 0, the next chassis should be 1, and so on. Valid range is 0 to 7. If there are no analog input channels in this chassis, use the value 0.

SCXI chassis id is the chassis Id number assigned to this chassis by the DAQ configuration utility.

Scanning interval is the time period between analog and digital input polls. Valid range is 20 msec to 1 day (expressed in msec).

Communication alarm priority determines the priority level of the alarms generated by the NISCXI object.

NISCXI Data Members

Table 3-47. NISCXI Device Data Members

| Data Member | Type | Read | Write | Description |
|------------------------|---------|------|-------|--|
| CommFail | logical | yes | no | Object-generated signal that is on if, for whatever reason, Lookout cannot communicate with or control the device without error. |
| MD1.AI0–MD12.AI63 | numeric | yes | no | Analog input channel in volts. |
| MD1.AO0–MD12.AO63 | numeric | no | yes | Analog output channel in volts. |
| MD1.cjtemp–MD12.cjtemp | numeric | yes | no | Built-in cold-junction sensor on analog input terminal blocks. |
| MD1.DI0–MD12.DI31 | logical | yes | no | Digital input line. |
| MD1.DO0–MD12.DO31 | logical | no | yes | Digital output line. |
| MD1.Etc0–MD12Etc31 | numeric | yes | no | Analog input channel with built-in polynomial conversion for an E type thermocouple. |

Table 3-47. NISCXI Device Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|----------------------|---------|------|-------|--|
| MD1.Jtc0 – MD12Jtc31 | numeric | yes | no | Analog input channel with built-in polynomial conversion for a J type thermocouple. |
| MD1.Ktc0 – MD12Ktc31 | numeric | yes | no | Analog input channel with built-in polynomial conversion for a K type thermocouple. |
| MD1.Rtc0 – MD12Rtc31 | numeric | yes | no | Analog input channel with built-in polynomial conversion for an R type thermocouple. |
| MD1.Stc0 – MD12Stc31 | numeric | yes | no | Analog input channel with built-in polynomial conversion for an S type thermocouple. |
| MD1.Ttc0 – MD12Ttc31 | numeric | yes | no | Analog input channel with built-in polynomial conversion for a T type thermocouple. |
| Update | logical | yes | no | Object-generated signal that pulses low each time the object polls the device. |

Configuring NIDAQ.INI for NISCXI

You may configure individual channel attributes by editing the `NIDAQ.INI` file in your Lookout directory.

Channel Attributes

To specify a channel, use the following format: `[DEV3.SC1.MD2.AI5]`

This specifies analog input channel 5 on module 2 of SCXI chassis 1 controlled by device 3.

UPPERLIMIT specifies the upper input limit in volts (for example, `UPPERLIMIT=2.5`). Usually used in conjunction with **LOWERLIMIT**.

LOWERLIMIT specifies the lower input limit in volts (for example, `LOWERLIMIT=-3.7`). Usually used in conjunction with **UPPERLIMIT**.

Cold-Junction Sensor Attributes

To specify a cold-junction sensor, use the following format:

```
[DEV3 . SC1 . MD2 . CJC]
```

This specifies the cold-junction sensor on module 2 of SCXI chassis 1 controlled by device 3.

SENSORTYPE specifies the type of temperature sensor on the terminal block. Valid choices are `IC` and `THERMISTOR`. Check your SCXI terminal block documentation to determine the correct sensor type.

RESAMPLE specifies the number of minutes between resampling the cold-junction sensor. Valid range is 1 to 10080, and 0. Use 0 to only check the cold-junction sensor once at the start, and do not resample the sensor later.

NISCXI Error Messages

Error loading NI-DAQ driver

Lookout was not able to communicate to the NI-DAQ driver. Be sure that NI-DAQ has been installed properly, and that you used the NI-DAQ Configuration Utility to configure the your hardware devices.

NIDAQ: Analog Input: Invalid Data Member(s)

NIDAQ: Analog Output: Invalid Data Member(s)

NIDAQ: Digital Input: Invalid Data Member(s)

NIDAQ: Digital Output: Invalid Data Member(s)

At least one channels you have specified is not valid for your current hardware configuration. Be sure your hardware is configured properly using the NI-DAQ Configuration Utility.

NIDAQ: Error code: NNNNN

NIDAQ: Analog Input: Error code: NNNNN

NIDAQ: Analog Output: Error code: NNNNN

NIDAQ: Digital Input: Error code: NNNNN

NIDAQ: Digital Output: Error code: NNNNN

NI-DAQ has detected an error condition. Please refer to your *NI-DAQ Function Reference Manual* to determine the meaning of the error code.

SCXI Devices

You can use the following National Instruments data acquisition devices with Lookout.

| Device | AI | AO | DIO |
|------------|-----|-----|-----|
| SCXI-1000 | — | — | — |
| SCXI-1001 | — | — | — |
| SCXI-1100 | yes | — | — |
| SCXI-1102 | yes | — | — |
| SCXI-1120 | yes | — | — |
| SCXI-1121 | yes | — | — |
| SCXI-1124 | — | yes | — |
| SCXI-1160 | — | — | yes |
| SCXI-1161 | — | — | yes |
| SCXI-1162 | — | — | yes |
| SCXI-1163 | — | — | yes |
| SCXI-1163R | — | — | yes |
| SCXI-1200 | yes | yes | yes |
| SCXI-1300 | CJC | — | — |
| SCXI-1303 | CJC | — | — |
| SCXI-1320 | CJC | — | — |
| SCXI-1328 | CJC | — | — |
| SCXI-2000 | yes | yes | yes |
| SCXI-2400 | yes | yes | yes |

Omron

Omron is a protocol driver class Lookout uses to communicate with Omron devices using the Host Link serial communication protocol.

An Omron object contains a great deal of data. It supports reading and writing of all predefined data points. When you create an Omron object, you have immediate access to all the data members for that object (see *Omron Data Members* list in Table 3-48).

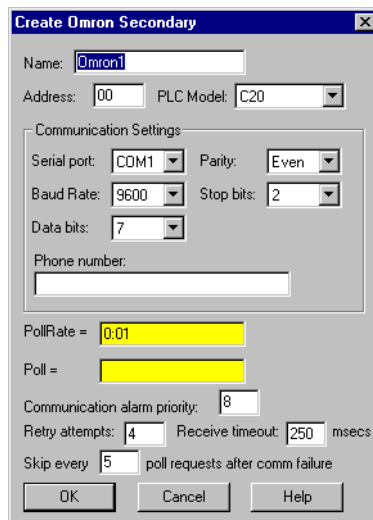


Figure 3-26. Omron Definition Parameters Dialog Box

Serial port specifies which COM port the object uses for communicating to the external device. This does not specify the communication type. Communication type is determined by the **Options»Serial Ports...** command.

Data rate indicates the baud rate that Lookout uses to communicate with the hardware device. This **Data rate** setting should match the selection made on the physical device.

Data bits indicates the number of data bits that Lookout uses to communicate with the hardware device. This **Data bits** setting should match the selection made on the physical device.

Stop bits indicates the number of stop bits that Lookout uses to communicate with the hardware device. This **Stop bits** setting should match the selection made on the physical device.

Parity indicates the parity that Lookout uses to communicate with the hardware device. This **Parity** setting should match the selection made on the physical device.

Phone number specifies the number to be dialed if the selected serial port is configured for dial-up. This **Phone number** only applies to the individual protocol object.

PollRate is a numeric expression that determines how often to poll the device. The object then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for more information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of alarms generated by the Omron object. Such alarms are typically related to communications with the physical device.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device when it is not getting a valid response. After it tries the number of **Retry attempts** specified, the Omron object generates an alarm and releases the communication port back to the communications subsystem. The subsystem then moves on to the next device in the polling queue (if any). See Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

The **Skip every...** setting instructs Lookout not to poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle. Once communications have been reestablished, the device is polled on its regular cycle.

Omron Data Members

As with all Lookout drivers, you can access I/O points and other data through data members. The following is a table of data members currently supported by the Omron object class.

Table 3-48. Omron Data Members

| Data Member | Type | Read | Write | Description |
|----------------|---------|------|-------|---|
| AR0–AR27 | numeric | yes | yes | Auxiliary relay area, read as 16-bit word. |
| AR0.0–AR27.15 | logical | yes | yes | Auxiliary relay area, read as 1-bit discrete. |
| DM0–DM9999 | numeric | yes | yes | Data memory area, 16-bit word. |
| CommFail | logical | yes | no | Object-generated signal that is on if, for any reason, Lookout cannot communicate with the device(s). |
| HR0–HR99 | numeric | yes | yes | Holding relay area, read as 16-bit word. |
| HR0.0–HR99.15 | logical | yes | yes | Holding relay area, read as 1-bit discrete. |
| IR0–IR511 | numeric | yes | yes | I/O area, read as 16-bit word. |
| IR0.0–IR511.15 | logical | yes | yes | I/O area, read as 1-bit discrete. |
| LR0–LR63 | numeric | yes | yes | Link relay area, read as 16-bit word of information. |
| LR0.0–LR63.15 | logical | yes | yes | Link relay area, read as 1-bit discrete. |
| TC0–TC999 | numeric | yes | no | Timer/Counter, read as 16-bit word. |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device. |



Note The Omron requires a special cable configuration in order to work properly. See your Omron hardware documentation for the correct configuration.

Omron Status Messages

No response within timeout period

Lookout received no response from a device within the **Receive timeout** period. The Omron object is able to use the COM port, but when it polls the device, it does not respond—as if it is not even there.

Cannot set PLC to MONITOR mode

The Omron object is trying to set the PLC in MONITOR mode in order to communicate with the PLC correctly, but cannot perform the operation.

Incorrect address in response

The frame received had an incorrect source address. Check for two or more devices with the same address.

Incorrect command in response

The frame received had an incorrect command. Check for two or more devices with the same address.

Incorrect data type in response

The frame received had an incorrect data type marker.

Incorrect frame check sum (FCS)

The frame received had an incorrect check sum.

Omron errors reported in the response

These errors are reported by the Omron device, and are in turn reported to you in text form.

Omron Models Supported

C20, C200, C500, C1000, C2000, CQM, CPM1

OptoHostWords

OptoHostWords is a protocol driver class Lookout uses to communicate with Opto22 controllers using HostWords protocol.

Unlike other Lookout driver objects, OptoHostWords does not give you direct access to the Opto22 I/O. Opto22 I/O is handled through the controller, which you program with the OptoControl software.

You also have access to string and numerical variables of your own definition when working with the Opto22 controller.

You must furnish the Lookout HostWords data members with the variable names you assign when you program the Opto22 controller. The Lookout data members are documented as having a *.name* suffix. When you make connections with the OptoHostWords object, you must use the name from the program running on your Opto22 controller.



Note HostWords names are case sensitive.

Figure 3-27. OptoHost Definition Parameters Dialog Box: Serial

Medium selects whether to use Ethernet or serial communications.

Serial port specifies which port the object uses for communication to the PLC.

Baud Rate specifies the speed at which the object communicates with the PLC.

Phone number specifies the number to be dialed if the serial port setting is configured for dial-up. This number only applies to the individual protocol object.

PollRate is a numeric expression that determines how often to poll the device. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of object-generated alarms (0 – 10).

Receive timeout is the time the object waits for a response from a device before retrying a request.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the object generates an alarm and releases the COM port. See Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

The **Skip every** setting instructs the object to skip the next specified number of polls to the PLC in the event of a communications failure, before attempting to re-establish communications. Once communications have been re-established, the device is polled on its regular cycle.

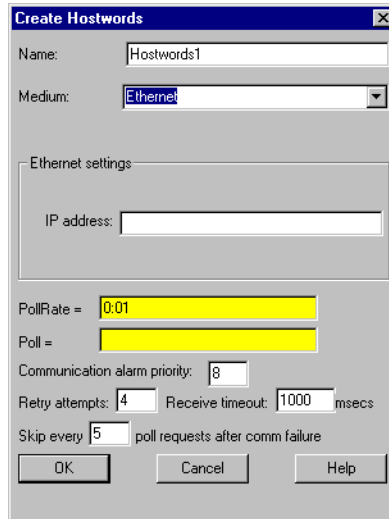


Figure 3-28. OptoHostWords Definition Parameters Dialog Box: Ethernet

IP Address specifies the IP address of the Opto22 controller.

Configuring the Hostwords Controller

Any time you download your OptoControl strategy onto the controller, you can choose to send library files along with it. One of these library files, `HOSTWORDS.CTL`, is necessary for the controller to interpret and send HostWords commands.

To make sure you have your system properly configured, use the following steps:

1. Open OptoControl, and bring up the strategy you want to download to the controller.
2. Select the **Controllers** command from the **Configure** menu.
3. Select the controller you are downloading *to* and click on the **Download Options** button.
4. In the **After Run File** section, add a file called `HOSTWORDS.CTL`. This file ships on the OptoControl CD.
5. Click on **OK** to finish in all open dialog boxes.
6. Download to the controller from OptoControl.

OptoHostWords Data Members

The suffix for the OptoHostWords data members in Table 3-49 is *name*. You provide the name yourself when you program the Opto22 controller with the OptoControl software.

Table 3-49. OptoHostWords Data Members

| Data Member | Type | Read | Write | Description |
|----------------------|---------|------|-------|---|
| <i>APT.name</i> | numeric | yes | yes | Analog point |
| <i>APTFILTC.name</i> | logical | no | yes | Analog point filter clear |
| <i>APTFILTW.name</i> | numeric | no | yes | Analog point filter weight |
| <i>APTMAX.name</i> | numeric | yes | no | Analog point maximum |
| <i>APTMAXC.name</i> | logical | yes | no | Analog point maximum clear |
| <i>APTMIN.name</i> | numeric | yes | no | Analog point minimum |
| <i>APTMINC.name</i> | logical | no | yes | Analog point minimum clear |
| <i>APTTOT.name</i> | numeric | yes | yes | Read analog point totalizer |
| <i>APTTOTC.name</i> | logical | no | yes | Analog point totalizer clear |
| <i>APTTOTR.name</i> | numeric | no | yes | Analog point totalizer rate |
| <i>Chart.name</i> | logical | no | yes | Opto22 flowchart. This data member runs an Opto22 flowchart you previously created. |
| CommFail | logical | yes | no | Object-generated signal that is ON if the object cannot communicate with the PLC. |
| Date | text | yes | no | date read from controller |
| DateSynch | logical | no | yes | When TRUE, Lookout writes current date from system clock to controller |
| <i>DPT.name</i> | logical | yes | yes | Digital point |
| <i>DPTCNT.name</i> | numeric | yes | yes | Digital point counter |
| <i>DPTCNTC.name</i> | logical | no | yes | Digital point counter clear |
| <i>DPTCNTEN.name</i> | logical | no | yes | Digital point counter enable |

Table 3-49. OptoHostWords Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|------------------------|-------------|-------------|--------------|---|
| <i>DTPOFFLAT.name</i> | logical | yes | no | Digital point latch off |
| <i>DTPOFFLATC.name</i> | logical | no | yes | Digital point clear latch off |
| <i>DTPONLAT.name</i> | logical | yes | no | Digital point latch on |
| <i>DTPONLATC.name</i> | logical | no | yes | Digital point clear latch on |
| <i>PIDACTIVE.name</i> | logical | no | yes | Proportional/ Differential/Integral control active and performing calculations |
| <i>PIDAUTO.name</i> | logical | no | yes | Output is affected by the Proportional/ Differential/Integral control calculations |
| <i>PIDD.name</i> | numeric | yes | yes | Proportional/ Differential/Integral control differential term |
| <i>PIDI.name</i> | numeric | yes | yes | Proportional/ Differential/Integral control integral term |
| <i>PIDINPUT.name</i> | numeric | yes | no | Proportional/ Differential/Integral control input |
| <i>PIDOUTPUT.name</i> | numeric | yes | no | Proportional/ Differential/Integral control output |
| <i>PIDP.name</i> | numeric | yes | yes | Proportional/ Differential/Integral control proportional |
| <i>PIDSET.name</i> | numeric | yes | yes | Proportional/ Differential/Integral control setpoint |
| Poll | logical | no | yes | When this expression transitions from FALSE to TRUE, Lookout polls the device. |

Table 3-49. OptoHostWords Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|----------------------|-------------|-------------|--------------|--|
| PollRate | numeric | no | yes | Lookout expression that determines the device polling frequency. |
| STR. <i>name</i> | text | yes | yes | String |
| STRT. <i>name.0</i> | text | yes | yes | String table |
| Time | text | yes | no | Time read from the device |
| TimeSynch | logical | no | yes | When TRUE, Lookout writes current time from system clock to controller |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device |
| VARF. <i>name</i> | numeric | yes | yes | Variable floating point |
| VARFT. <i>name.0</i> | numeric | yes | yes | Variable floating point table |
| VARI. <i>name</i> | numeric | yes | yes | Variable integer |
| VARIT. <i>name.0</i> | numeric | yes | yes | Variable integer table |

OptoHostWords Status Messages

There are three categories of error messages you may receive when using OptoHostWords

- Windows TCP/IP Errors
- Lookout Driver Errors
- HostWords Error Codes

One of the most common errors is the Host port device error:

Controller received an undefined command: *name*

This error informs you that the name listed is incorrect. To fix this error, make sure the name you attempted to use matches the name you used in your OptoControl program.

OptoHostwords TCP/IP Errors

Socket Communications error

This error message returns one of the standard Windows socket errors:

Socket timed out while attempting to connect

No Response from socket

Unknown socket error

Cannot resolve IP address

Cannot resolve port

Lookout Driver Errors with OptoHostWords

Garbled or unexpected response

This error can happen in Ethernet or serial communications. This error means the driver received a message it could not make sense of.

No response

This error means that a serial device has not responded at all.

HostWords Errors

The following General, Host Port Device, Ethernet, and HostWords errors are the most common error codes encountered when using the Lookout OptoHostWords driver. For a complete list of HostWords errors, or more detailed explanations, consult your HostWords documentation.

One of the most common errors is the Host port device error:

Controller received an undefined command: *name*

This error informs you that the name listed is incorrect. To fix this error, make sure the name you attempted to use matches the name you configured under HostWords

Invalid port number

This indicates your have sent a peer message to the same controller, or have encountered a firmware error.

Send timeout

You may have to increase your port timeout delay. This error can also result from lending long strings to a serial port, CTS low on a host port, or a firmware error.

Bad table index

You may have a negative table index value, or an index value greater than the table length.

Numeric overflow

The result of the calculation is larger than the numeric type used.

Not a number

A math operation has resulted in a complex or imaginary number.

Divide by zero

A math operation has tried to divide by zero.

Bus fault

This indicates either a failure in the controller hardware, or an attempt to access invalid memory area.

Port already in use

This indicates an attempt to have more than one port open in a chart.

Invalid event/reaction hold buffer

This indicates an attempt to read an event/reaction data hold buffer for an event/reaction that was not configured with a read and hold reaction.

Host port relock

An error occurring after an unlock command.

String too short to hold data

You may have had a string variable too short for the data specified, or attempted to put the date or time in a string with a length of less than eight.

Wrong object type

You may have passed the wrong data type to the ENABLE and DISABLE commands.

Controller received an undefined command

Check your use of the name returned by the error message. Names must match those you configured in your OptoControl configuration.

Controller received a message with a bad CRC

This indicates a problem in communication between your PC and the controller. See the HostWords documentation for a more detailed explanation.

Controller power up clear

Controller has lost power since the last communication. See the HostWords documentation for a more detailed explanation.

Controller received insufficient data

There may be an error in your command syntax.

I/O unit not configured

See the HostWords documentation for a more detailed explanation.

Controller host port is busy

The command that returned this message is not executed. See the HostWords documentation for a more detailed explanation.

Controller stack is empty

See the HostWords documentation for a more detailed explanation.

Controller Stack is full

See the HostWords documentation for a more detailed explanation.

Unknown response

An Ethernet communication may have been stopped by a bus error, or there may have been a firmware error.

Invalid Port

You have attempted to acquire a port that does not exist. See the HostWords documentation for a more detailed explanation.

No more sessions

An attempt has been made to open too many Ethernet sessions. See the HostWords documentation for a more detailed explanation.

Open session timeout

An attempt to open a session exceeded the timeout interval. See the HostWords documentation for a more detailed explanation.

Close session timeout

An attempt to close a session exceeded the timeout interval. See the HostWords documentation for a more detailed explanation.

Session not open

See the HostWords documentation for a more detailed explanation.

Invalid Session number

See the HostWords documentation for a more detailed explanation.

No session selected

There is no active session for the specified port.

Wrong LC type

A command has been used that is the wrong type for the current controller.

Bad Address

See the HostWords documentation for a more detailed explanation.

Operation failed

Could not gain access to the PC bus. See the HostWords documentation for a more detailed explanation.

Character not found

The **Find Character in String** command could not find the specified character.

Substring not found

The **Find Substring in String** command could not find the specified substring.

OptoMistic

Lookout uses the OptoMistic driver to communicate directly with Opto Model 200 I/O modules.

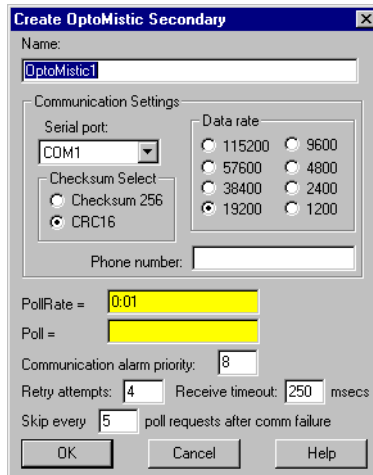


Figure 3-29. OptoMistic Parameter Definition Dialog Box.

Serial port specifies which port the object uses for communication to the external device. This does not specify the communication type. Communication type is determined by the **Options»Serial Ports...** command.

Checksum Select chooses which checksum method to use.

PollRate is a numeric expression that determines how often to poll the device. The object then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of alarms generated by the object. Such alarms are typically related to communications with the physical device.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the object generates an alarm and releases the communication port back to the communications service which then moves on to the next device in the polling queue (if any). Refer to Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

The **Skip every...** setting instructs Lookout to not poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle accordingly. Once communications have been reestablished, the device is polled on its regular cycle.

OptoMistic Data Members

Table 3-50. OptoMistic Data Members

| Data Member | Type | Read | Write | Description |
|------------------------|---------|------|-------|---|
| AI0.09—AI255.15 | numeric | yes | no | Analog input |
| AO0.0—AO255.15 | numeric | yes | yes | Analog output |
| CommFail | logical | yes | no | Object-generated signal that is on if, for whatever reason, Lookout cannot communicate with the ROC |
| DI0.0—DI255.15 | logical | yes | no | Digital input |
| DICNT0.0—DICNT255.15 | numeric | yes | no | Digital input counter |
| DICNTC0.0—DICNTC255.15 | logical | no | yes | Digital input counter clear |
| DICNTE0.0—DICNTE255.15 | logical | no | yes | Digital input counter enable |
| DIFRQ0.0—DIFRQ255.15 | numeric | yes | no | Digital input frequency |
| DILN0.0—DILN255.15 | logical | yes | no | Digital input latch negative (read only) |
| DILNC0.0—DILNC255.15 | logical | no | yes | Digital input latch negative (write only) |

Table 3-50. OptoMistic Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------------|-------------|-------------|--------------|---|
| DILP0.0—DILP255.15 | logical | yes | no | Digital input latch positive (read only) |
| DILPC0.0—DILPC255.15 | logical | no | yes | Digital input latch positive (write only) |
| DIOFFP0.0—DIOFFP255.15 | numeric | yes | no | Digital input OFF pulse totalizer |
| DIOFFPC0.0—DIOFFPC255.15 | logical | no | yes | Digital input OFF pulse totalizer clear |
| DIONP0.0—DIONP255.15 | numeric | yes | no | Digital input ON pulse totalizer |
| DIONPC0.0—DIONPC255.15 | logical | no | yes | Digital input ON pulse totalizer clear |
| DIPRD0.0—DIPRD255.15 | numeric | yes | no | Digital input period |
| DIPRDC0.0—DIPRDC255.15 | logical | no | yes | Digital Input period clear |
| DO0.0—DO255.15 | logical | yes | yes | Digital Output |
| Offhook | logical | no | yes | When TRUE, this flag instructs the object to retain exclusive use of its assigned communication port. |
| Poll | logical | no | yes | When this value transitions from FALSE to TRUE, Lookout polls the device. |
| PollRate | numeric | no | yes | Lookout expression that determines the device polling frequency |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device |

OptoMistic Error Messages

No Response within timeout period

Message Garbled

Unexpected data response length

Response too short

No response (configuring)

Each of these messages indicates a communications error. See your OptoMistic documentation for more detailed information.

Mistic Error: Undefined command

Recheck your OptoMistic address. See your OptoMistic documentation for more detailed information.

Mistic Error: Checksum or CRC error

This message indicates a general COM error. See your OptoMistic documentation for more detailed information.

Mistic Error: Power-up clear error

This error message may include a code detailing more specific information. See your OptoMistic documentation for more detailed information.

Mistic Error: Communications link watchdog timeout error

This message may indicate an address problem. See your OptoMistic documentation for more detailed information.

Mistic Error: Busy error

The system was busy and did not return data.

Mistic Error: Invalid module type error

The driver has attempted to read a module of a type different than the module located at the address.

Optomux

Optomux is a protocol driver class Lookout uses to communicate with Opto 22 I/O devices and other equipment using the Optomux communication protocol.

This protocol driver uses Optomux 2-pass protocol with no parity, eight data bits, and one stop bit. You can choose between CRC16 and BCC error correction modes, and select a data rate.

Several physical Optomux devices can be daisy-chained or multidropped on one ASCII network. In Lookout, you create a single Optomux object to represent all devices connected to the same COM port.

An Optomux object contains a great deal of data. It represents all devices and their associated channels. It supports reading and writing of all predefined data point types including analog input, discrete input, analog output, discrete output, counter, latch, latch clear, and temperature. When you create an Optomux object, you have immediate access to all the object data members (see data member list in Table 3-51).

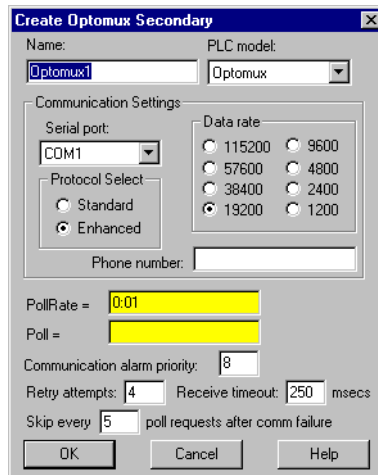


Figure 3-30. Optomux Definition Parameters Dialog Box

Serial port specifies which COM port the object uses for communicating to the external device. This does not specify the communication type. Communication type is determined by the **Options»Serial Ports...** command.

Protocol Select specifies the type of error correction mode used by the RTU. **Enhanced** mode uses CRC16 error checking. **Standard** mode uses BCC (horizontal parity). **Enhanced** mode is the default and is recommended.

Data rate indicates the baud rate that Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Phone number specifies the number to be dialed if the selected serial port is configured for dial-up. This number only applies to the individual protocol object.

PollRate is a numeric expression that determines how often to poll the device. The object then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of alarms generated by the Optomux object. Such alarms are typically related to communications with the physical device.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the Optomux object generates an alarm and releases the communication port back to the communications subsystem, which then moves on to the next device in the polling queue (if any). Refer to Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

The **Skip every...** setting instructs Lookout to not poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle accordingly. Once communications have been reestablished, the device is polled on its regular cycle.

Optomux Watchdog Capability

The Optomux protocol has a built in watchdog capability. The device monitors communications at all times. If the device receives no communications within the amount of time specified by `WDTime`, the device goes into *watchdog state*. This state makes sure all your devices are in a fail-safe condition if there is any kind of COM failure.

The DWD and AWD data members write to the device the values that device will use if it enters the watchdog state. They are write only.

Notice that the DWD data members are not logical values, as you might expect them to be. They also do not have channel numbers. This is because you set the watchdog data of an entire discrete module with one command and one value. Because there may be 16 channels possible, the single value sent may be as large as 16-bit.

For example, if you want to set the watchdog data for the discrete output module (DWD) at address 3, perform the following steps:

1. Connect a numeric value, such as 10 seconds, to `WDTime`. There has to be something connected to data member or you cannot set watchdog data. `WDTime` reads the numeric input as milliseconds; to set the watchdog time to 10 seconds, the numeric input must be 10000.
2. If you want Channels 1, 2, and 16 to be ON when the device goes into watchdog state, and all other channels to be OFF, send the hex value `0x8003` to `DWD3`. This expands to 1000 0000 0000 0011 in binary (Optomux arranges channels from left to right in the binary sequence). You can use the **Change»Numeric Format...** option to create a hexadecimal numeric in Lookout.

AWD data members work the same way, except that you have a separate data member for each channel, and you give it a numeric value. To set channel 3 of the analog output module at address 10, you would connect the numeric value to `AWD10.3`.

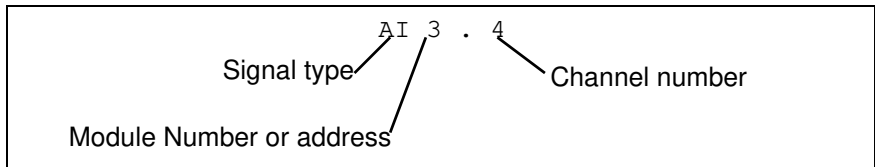
Optomux Data Members

As with all Lookout drivers, you can access I/O points and other data through data members. The following is a table of data members currently supported by the Optomux object class.

Table 3-51. Optomux Data Members

| Data Member | Type | Read | Write | Description |
|--------------------|---------|------|-------|---|
| AI0.1 – AI255.16 | numeric | yes | no | Analog input. 12 bit word containing an unsigned integer ranging from 0 to 4095 |
| AO0.1 – AO255.16 | numeric | yes | yes | Analog output. 12 bit word containing an unsigned integer ranging from 0 to 4095 |
| AWD0.1 – AWD255.16 | numeric | no | yes | Analog watchdog data |
| CNT0.1 – CNT255.16 | numeric | yes | no | Counter. Returns accumulated count for specified inputs |
| CommFail | logical | yes | no | Object-generated signal that is on if, for whatever reason, Lookout cannot communicate with the device(s) |
| DI0.1 – DI255.16 | logical | yes | no | Discrete input |
| DO0.1 – DO255.16 | logical | yes | yes | Discrete output |
| DWD0 – DWD255 | numeric | no | yes | Discrete watchdog data |
| LAT0.1 – LAT255.16 | logical | yes | no | Returns ON status for inputs which are latched |
| LTC0.1 – LTC255.16 | logical | yes | no | Returns ON status for latched input and clears the latch |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device |
| WDtime | numeric | no | yes | Watchdog time (in ms) |

Comments To specify the address of an analog input located on channel 4 of module 3, you would enter AI3.4, where



Note The Optomux protocol may perform limited value-type verifications depending upon the hardware you use. In other words, trying to read analog input data from a discrete module may be allowed but the data returned may be arbitrary (or zero).

Optomux Status Messages

No response within timeout period

Lookout received no response from a device within the **Receive timeout** period. The Optomux object is able to use the COM port, but when it polls the device, it does not respond—as if it is not even there. If you have daisy-chained several devices, you have introduced an inherent delay. You may have to significantly increase **Receive timeout** (and **Poll Rate**) to ensure Lookout is allowing enough time to receive the expected response. This increase has nothing to do with the processing capabilities of Lookout. Rather it is based solely on **Data rate** and the number of devices on the chain. Also, verify your baud rate settings, cable connections, power, configuration settings, COM port settings, and polling addresses.

Invalid data request from module

Either you tried to read from a module that is missing, or you attempted a data type mismatch. For example, you may have tried to read a discrete value from an analog module. This data type mismatch is seen on a data analyzer as a frame containing question marks. This may be an addressing problem. Verify that the type of I/O at the desired channel matches the signal type of the address identified in the data member you are writing to.

Message garbled – Bad CRC or BCC

The Optomux object is receiving a poll response from the device(s), but it could not decipher the response. Verify that the error correction scheme you selected in **Protocol Select** is the same as that of all of the physical devices. Also verify that all devices connected to the COM port have unique addresses. It may also be that the last part of the message is getting clipped off before it is completed. Consider increasing the number of **Retry**

attempts. You may have to increase the **Receive gap** Serial Port setting to ensure Lookout is receiving the entire message. If your Serial Port is configured for radio this could be caused by an audible squelch tail occurring at the end of a radio transmission. You may need to adjust the **RTS delay off** or the **CTS timeout** settings.

Unexpected data response length

The Optomux object is receiving a poll response from the device(s), but the response is too long. Verify that all devices connected to the COM port have unique addresses. Devices with identical addresses may be trying to respond at the same time.

Response too short

The Optomux object is receiving data that does not meet the minimum frame length requirements. This could happen if you configured a device for 4-pass instead of 2-pass protocol. Lookout uses 2-pass protocol. Verify device protocol settings.

Philips

Philips is a protocol driver class Lookout uses to communicate with Philips devices using the PPCCOMM communication protocol.

A Philips object contains a great deal of data. It supports reading and writing of all predefined data points. When you create a Philips object, you have immediate access to all the object data members (see [Philips Data Members](#) list in this section).

Figure 3-31. Philips Configuration Parameters Dialog Box

Serial port specifies which communications port the object uses for communicating to the external device. This does not specify the communication type. Communication type is determined by the **Options»Serial Ports...** command.

Baud rate indicates the baud rate that Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Data bits indicates the number of data bits that Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Stop bits indicates the number of stop bits that Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Parity indicates the parity that Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Phone number specifies the number to be dialed if the selected serial port is configured for dial-up. This number only applies to the individual protocol object.

PollRate is a numeric expression that determines how often to poll the device. The object then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of alarms generated by the Philips object. Such alarms are typically related to communications with the physical device.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the Philips object generates an alarm and releases the communication port back to the communications service which then moves on to the next device in the polling queue (if any). Refer to Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

The **Skip every...** setting instructs Lookout not to poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle accordingly. Once communications have been reestablished, the device is polled on its regular cycle.

Philips Data Members

As with all Lookout drivers, you can access I/O points and other data through data members. The following is a table of data members currently supported by the Philips object class.

Table 3-52. Philips Data Members

| Data Member | Type | Read | Write | Description |
|--------------------|---------|------|-------|---|
| CommFail | logical | yes | no | Object-generated signal that is on if Lookout cannot communicate with the device(s) |
| IB0.0 – IB1023.1 | numeric | yes | yes | Discrete inputs, 8 bits |
| ID0 – ID1023 | numeric | yes | yes | Discrete inputs, 32 bits |
| IW0 – IW1023 | numeric | yes | yes | Discrete inputs, 16 bits |
| IX0.0 – IX123.15 | logical | yes | no | Discrete input, 1 bit |
| MB0.0 – M14335.1 | numeric | yes | yes | Data register, 8 bits |
| MD0 – MD14335 | numeric | yes | yes | Data register, 32 bits |
| MW0 – MW14335 | numeric | yes | yes | Data register, 16 bits |
| MX0.0 – MX14335.15 | logical | yes | no | Data register, 1 bit |
| Poll | logical | no | yes | When this value transitions from FALSE to TRUE, Lookout polls the device. |
| PollRate | numeric | no | yes | Lookout expression that determines the device polling frequency. |
| QB0.0 – QB1023.1 | numeric | yes | yes | Discrete outputs, 8 bits |
| QD0 – QD1023 | numeric | yes | yes | Discrete outputs, 32 bits |
| QW0 – QW1023 | numeric | yes | yes | Discrete outputs, 16 bits |
| QX0.0 – QX1023.15 | logical | yes | no | Discrete output, 1 bit |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device. |

Philips Status Messages

Invalid frame format

Bad Checksum

Invalid frame length

These messages indicate garbled communications. Check cabling for signal noise or multiple devices with the same address.

Philips Alarms

These are messages returned to Lookout in a response frame. See your Philips documentation for meanings and solutions.

Profibus DP

Profibus DP is a protocol driver class for communicating with PLCs and remote I/O units using the Decentralized Periphery protocol in the Profibus standard. The Lookout driver currently supports the S-S Technologies card 5136-PFB PC card only.

Configuring the Profibus DP Network

In order to use the Lookout Profibus DP driver for the S-S card, you must first configure your DP network using the Siemens COM ET-200 software. This software is not included in the Lookout release and must be purchased separately. The S-S card is the master device on the Profibus network. Because the COM ET-200 software does not know about this device, you must select some other device as the master. You may leave all of its parameters as the defaults because the S-S card ignores the parameters of this master system.

You must, however, enter a master station number and configure the bus parameters. These parameters are used by the SS card to configure the DP network.

Next, you must configure the parameters for each of the slave devices. Refer to the online documentation for the COM ET200 software for instructions on how to do this. Once all the slave devices are configured, save the file to an `.et2` format and export the file to a binary file `.2bf` format. This last step is done using the Export selection in the File menu. Place the binary file in a location accessible to Lookout.

Profibus DP Requirements

To run the 32-bit version of this object, you must be running Windows NT 3.51 or greater or Windows 95, with an S-S Technologies 5136-PFB card installed in the computer. Lookout automatically loads the firmware module when an object is created.

You must place the configuration file in COM ET 200 binary format in a directory accessible to Lookout.

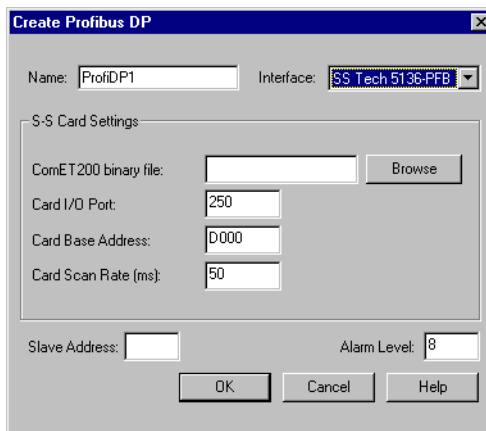


Figure 3-32. Profibus DP Configuration Parameters Dialog Box

Interface is the type of card to be used to communicate with the DP network. At present, this driver only supports the S-S card interface.

Slave Address is the Profibus address for the particular slave device that this object is to communicate with.

Alarm Level determines the priority level of object-generated alarms (0 – 10).

PFB Card Settings

COM ET200 Binary File is the path to the binary configuration file produced by the Siemens COM ET200 software. This file must match the network that the S-S card is actually connected to.

Card I/O Port specifies the base port address for the card. The jumpers on the card must be preset to the port address selected.

Card Base Address specifies the base address location of the card memory. At present, only one 5136-PFB card in a computer is supported. The default is D000. In Lookout, the Profibus DP object itself sets this on the card when it is loading the firmware.

Network Init Timeout specifies the number of milliseconds the card should wait while attempting to initialize the network before generating an alarm. The default is 1000 ms or one second.

Card Scan Rate is the rate at which the 5136-PFB card is scanned to look for fresh data. The default is 50 milliseconds.

Profibus DP Data Members

All readable and writable members—inputs/outputs—are bundled with the object. Therefore, as soon as you create a Profibus DP object you immediately have access to all the object data members.

Data can be addressed either as bytes or words within slots, or as bits within these bytes or words. However, you cannot address a slot configured for digital input or output (as bytes) using word numbers. Similarly you cannot address a slot configured for analog input or output (as words) using byte numbers.

Table 3-53. Profibus DP Data Members

| Data Member | Type | Read | Write | Description |
|---------------------------|---------|------|-------|---|
| CommFail | logical | yes | no | Object-generated signal that is on if, for any reason, Lookout cannot communicate with the Profibus card. |
| Slot0B0 – Slot127B63 | numeric | yes | yes | This addresses data in a slot as a sequence of bytes. |
| Slot0B0.0 – Slot127B63.7 | logical | yes | yes | This addresses individual bits while looking at a slot as a sequence of bytes. |
| Slot0W0 – Slot127W63 | numeric | yes | yes | This addresses data in a slot as a sequence of words. |
| Slot0W0.0 – Slot127W63.15 | logical | yes | yes | This addresses individual bits while looking at a slot as a sequence of words. |

Profibus DP Status Messages

Profibus SS Card not found

The SS card was not found at the specified port and card base address. Check that the jumper settings on your card match the port address that you specified in the object creation dialog box. Also, check that the card is properly seated in the slot.

Profibus init failed

The initialization of the Profibus SS card failed. This alarm is usually followed by an explanation of the reason for this failure.

Error accessing COM ET 200 binary file

A file error occurred while attempting to open the COM ET 200 binary file.

Unconfigured Read Error

A read was attempted on a data member that is not valid in the current Profibus DP network configuration.

Unconfigured Write Error

A write was attempted on a data member that is not valid in the current Profibus DP network configuration.

Slave Error

There was a problem with the particular slave device you are trying to access. This alarm is followed by a description of the problem with that slave device.

ProfibusL2

ProfibusL2 is a protocol driver class for communicating with PLCs using Profibus Sinec-L2.

One of the problems with communicating with PLCs using Profibus Sinec-L2 is that there is no standard messaging system for transferring data. The Sinec L2 interface has a variety of message types available that you can use with applications as well as PLCs on a network. Lookout uses its own messaging system for transferring data and provides help for you to implement the PLC end of the messaging system.

Lookout Messaging System

You should read the Siemens manual *Sinec-L2 Interface of the S5-95U Programmable Controller*, or some similar document that details a Sinec-L2 interface and how to write programs for your particular Sinec-L2 interface device.

Lookout uses two message types to receive and send all the data it needs. It uses the message type SRDh (Send and Request Data, high priority) to receive data from the PLC. To send data to the PLC, Lookout uses the message type SDAh (Send Data with Acknowledge, high priority).

All messages in Sinec-L2 are directed at specified SAPs (Service Access Points). You must program SAPs on each PLC to provide or accept the data you want to exchange with Lookout. You can use a given SAP only for reading or writing. Each poll request for a configured SAP reads *all* the data in that SAP. In the same way, if you are writing to a particular SAP, each write transfers all the data for that SAP to the PLC.

Sample Program

Included in your copy of Lookout is a sample Siemens STEP5 program file, `LKTPFBST.S5D`. This file is placed in the `\sinec12` directory under your Lookout directory during installation. This program contains an example of the logic necessary to create the Service Access Points (SAPs) for communications from a Simatic S5-95U to Lookout software using the Profibus protocol.

The program consists of one program block, three function blocks, three data blocks, and the modifications needed in OB1 and DB1 to successfully configure the Profibus communication link. This sample establishes two SAPs to the Profibus Layer 2 services of the PLC. Lookout uses the first

SAP, 34, to write values to the PLC. Lookout uses the second SAP, 35, when reading values from the PLC. You can read or write data in byte, word, or double word formats.

In order to install the example Profibus program, follow these steps:

1. **TRANSFER ALL BLOCKS TO THE CPU MEMORY**

This must include all PBs, FBs, and DBs.

2. **PROFIBUS CONFIGURATION**

The example configures SAP 34 and SAP 35. However, you may modify the program, if necessary, to customize your application.

3. **PROFIBUS EXECUTION**

Jump to PB 223 is required from OB1. An example of this jump is included in OB1 in the program.

4. **PROFIBUS DATA HANDLING**

The sample program uses DB 234, DB 235, and DB 236 to move data from the PLC to Lookout and from Lookout to the PLC. All data must be mapped to and from data blocks for Profibus communications. These data blocks also contain 8-byte headers used as a part of the Profibus configuration parameters. Again, you may modify these blocks if necessary. In addition, flag bytes above 200 are used by the example program, so you should avoid using them.

Detailed Explanation of the Profibus Example Program

The example program employs the Layer 2 services of the Siemens Simatic S5-95U for the Profibus communications to Lookout. In particular, the program uses SRD and RUP_MULTIPLE. The configuration of these services is described in detail in Chapter 8, *Data Transmission by Accessing Layer 2 Services*, of the *Sinec-L2 Interface of the S5-95U Programmable Controller Manual*.

DB1 Configuration

The first step in configuring the S5-95U is to insert the correct Profibus parameters in DB1 of the PLC. You should employ the COM_DB1 software, available from Siemens, when setting these parameters.

First, you must enter the SINEC L2 basic parameters. These parameters include the station address, baud rate, target rotation time, and more. The parameters must exactly match those used in configuring your SinecL2 object. You can find the defaults for these parameters in the example program where they are used.

Next you must configure the SINEC L2 layer 2 service. Here, you define the individual SAPs and designate a status byte for each SAP. SAPs used for writing data to the PLC must have a status byte allocated in the **Receive** area. SAPs used for reading data from the PLC must have a status byte allocated in both the **Send** and **Receive** areas.

You can define up to 23 SAPs, numbering from 33 to 54 and also including 64. The example program uses SAP 34 for writing data, and FW 204 as its status and length bytes. The program uses SAP 35 for reading data, with FW 200 and FW 202 used for the status and length bytes in the **Send** and **Receive** areas.

Function Block Explanation

The example program contains three function blocks to handle the data transfer between the Profibus SAPs and the CPU internal memory. These blocks evaluate the status bits associated with each SAP, and send or receive the data when allowable.

Function Block FB 224 coordinates the data written from Lookout to the PLC. The CPU looks for an *indication* from the SAP that new data exists. If the receive is viable, the block performs a jump to FB 253, which is the integrated L2-REC function block. The block takes the data and writes it to the area specified by DBNR. The example uses DB 234, starting at DW 0 and continuing for an unknown wildcard length. The first 8 bytes of DB 234, DW 0 through DW 3, contain the header for the message. You must include this header in the data block for proper operation.

Function Blocks FB 223 and FB 225 handle the data Lookout is attempting to read from the PLC. FB 225 acts in the same way as FB 224, looking for an indication that the SAP has received a new request for data. FB 223 actually writes the data to the SAP using a jump to FB 252, the integrated L2-SEND function block. The data is taken from the area designated by DBNR. In this case, DB 235 is used by FB 223 and DB 236 is used by FB 225. The first 8 bytes act as a header to the message to follow, and must be set with specific parameters. In DB 235, DW 1 through DW 4 are used for the Send, and DW 128 through DW 131 are used for the Indication. In DB 236, DW 1 through DW 4 are used for the Indication. The parameters required in the data blocks are discussed in the *Sinec-L2 Interface of the S5-95U Programmable Controller Manual*.

Program Block PB 223 initiates the jumps to all the function blocks for the Profibus communications. You must add a jump to PB 223 in your OB 1 in order to start the communications.

Finally, all the program blocks and function blocks use bits of the **Send** and **Receive** status bytes in their logic. If you change these bytes in DB 1, the you must also change the associated logic accordingly.

ProfibusL2 Requirements

To run the 32-bit version of this object, you must have Windows NT 3.51 or better, or Windows 95 loaded, and an S-S Technologies 5136-PFB card installed in the computer. Lookout automatically loads the firmware module when an object is created.

Figure 3-33. ProfibusL2 Configuration Parameters Dialog Box

PollRate is a numeric expression that determines how often to poll the device. Lookout then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for further information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of object-generated alarms (0 – 10).

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the Profibus L2 object generates an alarm.

Card Memory Address specifies the base address location of the card memory. At present, only one 5136-PFB card in a computer is supported. The default is D000. In Lookout, the Profibus object itself sets this on the card when it is loading the firmware.

Base Port Address specifies the base port address for the card. The jumpers on the card must be preset to the port address selected.

PFB Card Settings

Card Network Address specifies the Profibus address for the card on the bus. The valid range is 0 to 126.

PLC Network Address specifies the Profibus address for the PLC on the bus. The valid range is 0 to 126.

Network High Address specifies the highest possible Profibus address possible on the bus. The valid range is 0 to 126.

Token Rotation Time specifies the target maximum token rotation time for the network in Tbits (bit times). The valid range is 256 to 16,777,215.

Network Baud Rate specifies the baud rate to be used on the network. The valid selections are shown in the selection box.

Slot Time specifies how long the card waits for a reply to a message, in Tbits. The valid range is 37 to 16,383.

Idle Time1 specifies the time in Tbits that the card waits after it receives a reply, an acknowledge or a token message before sending a message. Range: 35 to 1023

Idle Time2 specifies the time in Tbits that the card waits after sending an SDN (Send Data with no acknowledge) message before it sends again. Range: 35 to 1023

Ready Time specifies the time in Tbits that the card, after it sends a command, is ready to receive the ACK or response. It is also the time the card waits after receiving a command. The valid values range from 11 to 1023.

ProfibusL2 Data Members

All readable and writable members (inputs/outputs), polling instructions, and so on, are bundled with the object. Therefore, as soon as you create a Profibus object you immediately have access to all the object data members (see data member list in Table 3-54).

Data is addressed using SAP numbers and, within a SAP, the byte, word or Dword number. For example, if SAP 33 is configured for reading, SAP33B200 refers to the 201st byte of that SAP. Similarly, SAP42DW10.20 refers to the 21st bit of the 11th Dword of SAP 42.

The legal SAPs used by the Lookout Profil2 driver range from 0 to 255. Each SAP may provide up to 242 bytes of data (0 – 241) which you can address either as bytes, 121 words, or 60 Dwords. The actual range of valid SAPs varies according to the device being addressed. You can address bits by appending a period and bit number after the byte number, word number, or Dword number.



Note Lookout protocol driver objects automatically generate an efficient read/write blocking scheme based on the inputs and outputs being used in your process file. You are not required to build your own I/O blocking table.

Table 3-54. ProfibusL2 Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|---|
| CommFail | logical | yes | no | Object-generated signal that is on if, for any reason, Lookout cannot communicate with the Profibus card. |
| Poll | logical | no | yes | When this value transitions from FALSE to TRUE Lookout polls the device. |

Table 3-54. ProfibusL2 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|---------------------------|-------------|-------------|--------------|---|
| PollRate | numeric | no | yes | Lookout expression that determines the device polling frequency. |
| SAP0B0 – SAP255B241 | numeric | yes | yes | This addresses all the data in the SAP as a sequence of bytes. |
| SAP0B0.0 – SAP255B241.7 | logical | yes | yes | This addresses individual bits while looking at an SAP as a sequence of bytes. |
| SAP0DW0 – SAP255DW60 | numeric | yes | yes | This addresses all the data in the SAP as a sequence of double words. |
| SAP0DW0.0 – SAP255DW60.31 | logical | yes | yes | This addresses individual bits while looking at an SAP as a sequence of double words. |
| SAP0W0 – SAP255W120 | numeric | yes | yes | This addresses all the data in the SAP as a sequence of words. |
| SAP0W0.0 – SAP0255W120.15 | logical | yes | yes | This addresses individual bits while looking at an SAP as a sequence of words. |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device. |

ProfibusL2 Status Messages

Profibus SS Card not found

The SS card was not found at the specified port and card base address. Check that the jumper settings on your card match the port address that you specified in the object creation dialog box. Also, check that the card is properly seated in the slot.

Profibus SS Card timed out on message

The SS card did not respond within a reasonable time to the message sent by Lookout. This may mean that you have lost communication with the card. Try restarting Lookout to see if this fixes the problem. If the problem persists, call National Instruments for assistance.

Reliance

Reliance is a protocol driver class Lookout uses for communicating with Reliance AutoMate controllers.

Figure 3-34. Reliance Definition Parameters Dialog Box



Note If you are developing your application without a PC-Link card installed in your computer, and do not know the settings in the target system, you can enter 250 for Port Address, 0 for Node ID, and 3 for Max Nodes. You can then create the Reliance object and correct the parameter values for the actual system later, if necessary.

Interface is the method the object uses to communicate with the Reliance PLCs. Currently, only the Reliance R-Net is supported, using the Reliance PC-Link card.

PollRate is a numeric expression that determines how often to poll the device. Reliance then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of object-generated alarms (0 – 10).

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the object generates an alarm. See Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

The **Skip every...** setting instructs Lookout not to poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle accordingly. Once communications have been reestablished, the device is polled on its regular cycle.

PC-Link Card Settings

Port Address is the I/O port address used to access the software module on the card. See your PC-Link card documentation for specific settings.

Interrupt identifies the interrupt (IRQ) setting of your PC-Link card. The card generates an interrupt recognized by Lookout any time it receives an response from the device.

Node ID is the node ID setting of the PC-Link card on the R-Net.

Max Nodes is the maximum number of nodes on the R-Net.

Destination Settings

Node ID is the node ID on the R-Net setting of the AutoMate processor that controls the target AutoMate PLC.

Slot ID is the ID of the PLC rack slot in which the target AutoMate resides.

Reliance Data Members

All readable and writable members (inputs/outputs), polling instructions, read/write blocking, serial port usage, and so on, are bundled with the object. Therefore, as soon as you create an Reliance object you immediately have access to all the object data members (see data member list).



Note Lookout protocol driver objects automatically generate an efficient read/write blocking scheme based on the inputs and outputs being used in your process file. You are not required to build your own I/O blocking table.

Reliance Data Members

Table 3-55. Reliance Data Members (all addresses are in octal)

| Data Member | Type | Read | Write | Description |
|----------------|---------|------|-------|---|
| 0 – 157775 | numeric | yes | yes | 16-bit input registers encoded as unsigned binary integers ranging from 0 to 65,535. |
| 0.0 – 15775.17 | logical | yes | yes | Access individual bits in holding registers and read them as logical ON/OFF values. The least significant bit is 1; the most significant bit is 17. |
| CommFail | logical | yes | no | Driver-generated signal that is ON if Lookout cannot communicate with the device. |
| D0 – D157774 | numeric | yes | yes | Wide data format ranges from –99,999,999 to +99,999,999. |
| Poll | logical | no | yes | When this expression transitions from FALSE to TRUE, Lookout polls the device. |
| PollRate | numeric | no | yes | Lookout expression that determines the polling frequency of the device. |
| Update | logical | yes | no | Driver-generated signal that pulses each time the driver polls the device. |

Reliance Status Messages

See your Reliance or PC-Link documentation for details of Reliance device generated messages.

RKC F Series

RKC is a protocol driver class Lookout uses to communicate with RKC F Series devices using 7-bit ASCII serial communications.

With this driver you can read and write to all predefined data points allowed by a particular F Series model. When you create an RKC object, you have immediate access to all the object data members. See the data member tables for more information on data members for this object.

Address specifies which RKC F Series device you are communicating with. This number is between 0 and 31, and is set on the F Series device.

PLC Model specifies what model of RKC F Series device you are using. This driver supports the following models: REX-F400, REX-F700, and REX-F900.

Serial port specifies which COM port the object uses to communicate with the external device. This does not specify the communication type. Communication type is determined by the **Options»Serial Ports...** command.

Data rate indicates the baud rate Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Data bits indicates the number of data bits Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Stop bits indicates the number of stop bits Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Parity indicates the parity that Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Phone number specifies the number to be dialed if the selected serial port is configured for dial-up.

PollRate is a numeric expression that determines how often to poll the device. The object then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of alarms generated by the RKC object. Such alarms are typically related to communications with the physical device.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the RKC object generates an alarm and releases the COM port. See Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

The **Skip every...** setting instructs Lookout to not poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle. Once communications have been reestablished, the device is polled on its regular cycle.

RKC Data Members

As with all Lookout drivers, you can access I/O points and other data through data members. The Lookout RKC object class currently supports the data members contained in the following tables, which are divided into groups according to their functionality.

Table 3-56. RKC Data Member Group

| Parameter Group | Description |
|---------------------------------|---|
| Measured Value Group | measured inputs and alarm status |
| Operation Mode Group | operation mode status |
| Memory Area and Set Value Group | set value (SV) |
| Parameter Group 10 | measured input parameters |
| Parameter Group 11 | remote setting input parameters |
| Parameter Group 12 | output parameters |
| Parameter Group 13 | auto-tuning bias parameters |
| Parameter Group 14 | alarm 1 parameters |
| Parameter Group 15 | analog output parameters |
| Parameter Group 16 | positioning, proportioning, PID action parameters |
| Parameter Group 17 | bar graph parameters |
| Parameter Group 20 | input selection parameters |
| Parameter Group 21 | setting parameters |
| Parameter Group 22 | output action parameters |
| Parameter Group 23 | alarm 2 parameters |
| Parameter Group 40 | data lock parameters |
| Lookout data members | standard Lookout data members |



Note For a more complete definition of the function of these data members, see your RKC F Series documentation.

Not all data members are valid for every F Series device. See your RKC documentation for which data members are valid for particular model numbers.

Table 3-57. Measured Value Group

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---|
| AA | logical | yes | no | First alarm status |
| AB | logical | yes | no | Second alarm status |
| AC | logical | yes | no | Heater break alarm status |
| B1 | logical | yes | no | Burnout status |
| B2 | logical | yes | no | Burnout status of feedback resistance input |
| M1 | numeric | yes | no | Measured value input |
| M2 | numeric | yes | no | Feedback resistance input |
| M3 | numeric | yes | no | Current transformer input |
| MS | numeric | yes | no | Set value |
| O1 | numeric | yes | no | Manipulated output |
| O2 | numeric | yes | no | Cooling-side manipulated output |
| S2 | numeric | yes | no | Remote set value |

Table 3-58. Operation Mode Group

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|-------------------------------------|
| C1 | logical | yes | yes | Local/remote mode |
| E1 | logical | yes | yes | Local/external memory area transfer |
| G1 | logical | yes | yes | PID control/autotuning |
| J1 | logical | yes | yes | Auto/manual mode |
| ON | numeric | yes | no | Manipulated output |
| RA | logical | yes | no | Local/computer mode |
| SR | logical | yes | yes | RUN/STOP mode |
| ZA | numeric | yes | yes | Control area |

Table 3-59. Memory Area and Set Value Group

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|--|
| A1:1 - A1:8 | numeric | yes | yes | First alarm setting |
| A2:1 - A2:8 | numeric | yes | yes | Second alarm setting |
| CA:1 - CA:8 | numeric | yes | yes | Control response designation parameter |
| D1:1 - D1:8 | numeric | yes | yes | Derivative constant |
| HH:1 - HH:8 | numeric | yes | yes | Setting change rate limit |
| I1:1 - I1:8 | numeric | yes | yes | Integral constant |
| P1:1 - P1:8 | numeric | yes | yes | Proportional constant |
| P2:1 - P2:8 | numeric | yes | yes | Cooling-side proportional band |
| S1:1 - S1:8 | numeric | yes | yes | Set value |
| V1:1 - V1:8 | numeric | yes | yes | Deadband |

Table 3-60. Parameter Group 10 (Measured Input Parameters)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---------------------------------------|
| DP | numeric | yes | yes | Low input cut-off |
| F1 | numeric | yes | yes | Measured value first order lag filter |
| PB | numeric | yes | yes | Measured value bias |

Table 3-61. Parameter Group 11 (Remote Setting Input Parameters)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---|
| F2 | numeric | yes | yes | Remote set value first order lag filter |
| RB | numeric | yes | yes | Remote set value bias |
| RR | numeric | yes | yes | Remote set value ratio |

Table 3-62. Parameter Group 12 (Output Parameters)

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|--------------------------------------|
| IV | numeric | yes | yes | Upper ON/OFF differential gap |
| IW | numeric | yes | yes | Lower ON/OFF differential gap |
| OE | numeric | yes | yes | Manual output at abnormality |
| OH | numeric | yes | yes | Manipulated output high limit |
| OL | numeric | yes | yes | Manipulated output low limit |
| OQ | numeric | yes | yes | Shortest cooling output on time |
| PH | numeric | yes | yes | Increase in output change rate limit |
| PL | numeric | yes | yes | Decrease in output change rate limit |

Table 3-63. Parameter Group 13 (Auto-Tuning Bias Parameters)

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|---|
| GB | numeric | yes | yes | Set value bias when autotuning is performed |

Table 3-64. Parameter Group 14 (Alarm 1 Parameters)

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|-------------------------------|
| A3 | numeric | yes | yes | Heater break alarm value |
| HA | numeric | yes | yes | First alarm differential gap |
| HB | numeric | yes | yes | Second alarm differential gap |
| TD | numeric | yes | yes | First alarm timer setting |
| TG | numeric | yes | yes | Second alarm timer setting |

Table 3-65. Parameter Group 15 (Analog Output Parameters)

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|-----------------------------------|
| HV | numeric | yes | yes | High limit of analog output range |
| HW | numeric | yes | yes | Low limit of analog output range |
| LA | numeric | yes | yes | Analog output type |

Table 3-66. Parameter Group 16 (Positioning, Proportioning, PID Action Parameters)

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|---|
| SY | numeric | yes | yes | Action selection at feedback resistance input break |
| V2 | numeric | yes | yes | Neutral zone |
| VH | numeric | yes | yes | Open/close output differential gap |

Table 3-67. Parameter Group 17 (Bar Graph Parameter)

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|-----------------------------|
| DA | logical | yes | yes | Bar graph display selection |

Table 3-68. Parameter Group 20 (Input Selection Parameters)

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|--|
| AV | numeric | yes | yes | High limit of abnormality |
| AW | numeric | yes | yes | Low limit of abnormality |
| WH | logical | yes | yes | High limit of abnormality action selection |
| WL | logical | yes | yes | Low limit of abnormality action selection |
| XH | logical | yes | yes | Square root extraction |
| XI | numeric | yes | yes | Measured value input type |
| XU | numeric | yes | yes | Decimal point position selection |

Table 3-68. Parameter Group 20 (Input Selection Parameters) (Continued)

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|--|
| XV | numeric | yes | yes | High limit of input programmable range |
| XW | numeric | yes | yes | Low limit of input programmable range |

Table 3-69. Parameter Group 21 (Setting Parameters)

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|-----------------------------|
| SH | numeric | yes | yes | High limit of setting range |
| SL | numeric | yes | yes | Low limit of setting range |
| XL | logical | yes | yes | SV tracking selection |
| XR | numeric | yes | yes | Remote setting input type |

Table 3-70. Parameter Group 22 (Output Action Parameters)

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|-------------------------------------|
| SX | numeric | yes | yes | Start determination point |
| T0 | numeric | yes | yes | Control output cycle setting |
| T1 | numeric | yes | yes | Cooling-side output cycle setting |
| XE | logical | yes | yes | Direct/reverse action |
| XN | numeric | yes | yes | Action after power recovery setting |

Table 3-71. Parameter Group 23 (Alarm 2 Parameters)

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|--|
| XA | numeric | yes | yes | First alarm action |
| NA | logical | yes | yes | First alarm energized/de-energized |
| OA | numeric | yes | yes | First alarm action when measured value exceeds abnormality |
| WA | numeric | yes | yes | First alarm hold action |

Table 3-71. Parameter Group 23 (Alarm 2 Parameters) (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---|
| XB | numeric | yes | yes | Second alarm action |
| NB | logical | yes | yes | Second alarm energized/de-energized |
| OB | numeric | yes | yes | Second alarm action when measured value exceeds abnormality |
| WB | numeric | yes | yes | Second alarm hold action |

Table 3-72. Parameter Group 40 (Data Lock Parameters)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---------------------------------|
| DH | logical | yes | yes | Operation RUN/STOP display lock |
| LK | numeric | yes | yes | Data lock level setting |
| LL | logical | yes | yes | Memory area lock |

Table 3-73. Lookout Data Members

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|--|
| CommFail | logical | yes | no | Object-generated signal that is ON if Lookout cannot communicate with the device(s). |
| Poll | logical | no | yes | When this value transitions from FALSE to TRUE, Lookout polls the device. |
| PollRate | numeric | no | yes | Lookout expression that determines the device polling frequency. |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device. |

RKC Status Messages

No response within timeout period

Lookout received no response from a device within the **Receive timeout** period. The RKC object is able to use the COM port, but when it polls the device, it does not respond—as if it is not even there. If you have daisy-chained several devices, you have introduced an inherent delay. You may have to significantly increase **Receive timeout** (and **Poll Rate**) to ensure Lookout is allowing enough time to receive the expected response. This increase has nothing to do with the processing capabilities of Lookout. Rather it is based solely on **Data rate** and the number of devices on the chain. Also, verify your baud rate settings, cable connections, power, configuration settings, COM port settings, and polling addresses.

Invalid BCC in response

Lookout has received a frame with an invalid block check character (BCC). Check the cabling or look for two or more devices with the same address.

Invalid identifier in request

The request frame sent had an invalid identifier. This could possibly mean that you have requested an identifier that is not valid for your particular model in the RKC F Series. Check your model number carefully and read your RKC documentation to determine which identifiers are valid for which models.

Garbled or invalid frame

Lookout has received a frame without format characters in their proper positions. Check the **Receive gap** setting.

Numeric conversion failed

Lookout was unable to successfully convert ASCII data sent back from RKC into a number. Check the **Receive gap** setting.

No acknowledgment for write frame

There was no response to the write frame just sent. This could possibly mean that you have requested an identifier that is not valid for your particular model in the RKC F Series. Check your model number carefully and read RKC documentation to determine which identifiers are valid for which models.

RKC F Series models supported:

REX-F400, REX-F700, REX-F900

S5_3964

S5_3964 is a protocol driver class Lookout uses to communicate with Siemens Simatic S5 PLCs using the 3964 or 3964R protocols.

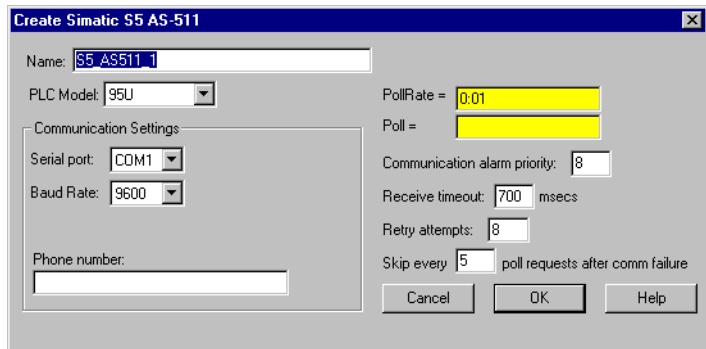


Figure 3-35. S5_3964 Definition Parameters Dialog Box

PLC Model specifies the model of Simatic S5 CPU the object communicates with.

Protocol specifies the protocol used to communicate with the PLC, 3964 or 3964R.

Serial port specifies which port the object uses for communication to the PLC.

Baud Rate specifies the speed at which the object communicates with the PLC.

Phone number specifies the number to be dialed if the serial port setting is configured for dial-up. This number only applies to the individual protocol object.

PollRate is a numeric expression that determines how often to poll the device. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of object-generated alarms (0 – 10).

Receive timeout is the time the object waits for a response from a device before retrying a request.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the object generates an alarm and releases the COM port. See Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

The **Skip every...** setting instructs the object that, in the event of a communications failure, to skip the next specified number of polls to the PLC before attempting to re-establish communications. Once communications have been re-established, the device is polled on its regular cycle.

S5_3964 Data Members

This protocol driver object contains a great deal of data. All readable and writable members (inputs/outputs), polling instructions, read/write blocking, serial port usage, and so on, are bundled with the object. As soon as you create a S5_3964 object, you immediately have access to all the data members of that object.



Note Lookout protocol driver objects automatically generate an efficient read/write blocking scheme based on the inputs and outputs being used in your process file. You are not required to build your own I/O blocking table.

The suffixes for the PLC data members in Table 3-74 (KC, KF, and so on) follow the Siemens format for data suffixes. That is, KC for Counter format, KT for Timer format, KB for byte format, KF for fixed-point format, KG for floating-point format, and no suffix for those data members for which only one format is possible, such as bit fields, counters, and timers.

Table 3-74. S5_3964 Data Members

| Data Member | Type | Read | Write | Description |
|-------------------------|-------------|-------------|--------------|---|
| A0KC – A65535KC | numeric | yes | no | Absolute address interpreted as a counter. |
| A0KF – A65535KF | numeric | yes | no | Absolute address interpreted as a signed fixed-point. |
| A0KF – A65535KT | numeric | yes | no | Absolute address interpreted as a timer. |
| C0 – C255 | numeric | yes | no | Counter. |
| CommFail | logical | yes | no | Object-generated signal that is ON if the object cannot communicate with the PLC. |
| DB1D0.0 – DB255D255.15 | logical | yes | no | A bit in a Data Block word. |
| DB1DD0KF – DB255DD254KF | numeric | yes | yes | A double-word in an extended Data Block, interpreted as signed fixed-point. |
| DB1DD0KG – DB255DD254KG | numeric | yes | yes | A double-word in a Data Block interpreted as a Siemens floating point format. |
| DB1DL0KB – DB255DL255KB | numeric | yes | no | The unsigned left byte in a Data Block word. |
| DB1DR0KB – DB255DR255KB | numeric | yes | no | The unsigned right byte in a Data Block word. |
| DB1DW0KC – DB255DW255KC | numeric | yes | yes | Word in a Data Block interpreted as a counter. |
| DB1DW0KF – DB255DW255KF | numeric | yes | yes | Word in a Data Block interpreted as a signed fixed-point. |
| DB1DW0KT – DB255DW255KT | numeric | yes | yes | Word in a Data Block interpreted as a timer. |
| DX1D0.0 – DX255D255.15 | logical | yes | no | A bit in an Extended Data Block word. |

Table 3-74. S5_3964 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|-------------------------|-------------|-------------|--------------|--|
| DX1DD0KG – DX255DD254KG | numeric | yes | yes | A double-word in an Extended Data Block interpreted as a Siemens floating point format. |
| DX1DL0KB – DX255DL255KB | numeric | yes | no | The unsigned left byte in an Extended Data Block word. |
| DX1DR0KB – DX255DR255KB | numeric | yes | no | The unsigned right byte in an Extended Data Block word. |
| DX1DW0KC – DX255DW255KC | numeric | yes | yes | Word in an Extended Data Block interpreted as a counter. |
| DX1DW0KF – DX255DW255KF | numeric | yes | yes | Word in an Extended Data Block signed fixed-point. |
| DX1DW0KT – DX255DW255KT | numeric | yes | yes | Word in an Extended Data Block interpreted as a timer. |
| F0.0 – F255.7 | logical | yes | no | A bit in Flag byte. |
| FD0KG – FD252KG | numeric | yes | no | A Flag double-word interpreted as a Siemens floating point format. |
| FW0KF – FW254KF | numeric | yes | no | A Flag word interpreted as a signed fixed-point. |
| FY0KB – FY255KB | numeric | yes | no | An unsigned Flag byte. |
| I0.0 – I127.7 | logical | yes | no | A bit in a byte of the Input (PII) data area. |
| IB0KB – IB127KB | numeric | yes | no | A unsigned byte of the Input (PII) data area. |
| ID0KG – ID124KG | numeric | yes | no | A double-word of the Input (PII) data area interpreted as a Siemens floating point format. |
| IW0KF – IW126KF | numeric | yes | no | Word in of the Input (PII) data area interpreted as a signed fixed-point. |
| Poll | logical | no | yes | When this expression transitions from FALSE to TRUE, Lookout polls the device. |

Table 3-74. S5_3964 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---|
| PollRate | numeric | no | yes | Lookout expression that determines the device polling frequency. |
| Q0.0 – Q127.7 | logical | yes | no | A bit in a byte of the Output (PIO) data area. |
| QB0KB – QB127KB | numeric | yes | no | An unsigned byte of the Output (PIO) data area. |
| QD0KG – QD124KG | numeric | yes | no | A double-word of the Output (PIO) data area interpreted as a Siemens floating point format. |
| QW0KF – QW126KF | numeric | yes | no | Word in of the Output (PIO) data area interpreted as a signed fixed-point. |
| RS0KC – RS511KC | numeric | yes | no | Word in the System data area interpreted as a signed fixed-point. |
| RS0KF – RS511KF | numeric | yes | no | Word in the System data area interpreted as a timer. |
| RS0KT – RS511KT | numeric | yes | no | Word in the System data area. |
| T0 – T255 | numeric | yes | no | Timer. |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device |

S5_3964 Alarms

Object Alarms

The following alarms originate in the object, and are only generated after the object has retried the request the number of times specified by the **Retry attempts** parameter.

No response from PLC

Lookout did not receive a response from the device within the **Receive timeout** period. The driver object is able to use the COM port, but when it polls the device, the device does not respond. You may have to increase **Receive timeout** to ensure Lookout is allowing enough time to receive the expected response. Also, verify your baud rate settings, cable connections, power, configuration settings, COM port settings, and polling addresses.

Unexpected response from PLC

A response was received from the PLC, but not the response expected according to the protocol.

Bad frame

A response frame was received from the PLC, but the frame is not valid according to the protocol. This is usually caused by a truncated frame. You may need to increase the **Receive Gap** setting in the **Options»Serial Ports...** dialog.

Bad BCC

The BCC computed by the object for a received frame did not match the BCC in the frame.

PLC Alarms

The following alarms originate in the PLC, and are generated immediately by the object. There are no retry attempts.

Illegal DB/DX number

The Data Block (DB) or Extended Data Block (DX) number in a read/write request to a PLC was not valid for the PLC.

Synchronization error

The PLC and S5_3964 object are not synchronized within the protocol. This usually happens after the object is modified and a read/write request was interrupted. After generating the alarm, the S5_3964 object attempts to resynchronize the protocol in the PLC.

S5_AS511

S5_AS511 is a protocol driver class Lookout uses to communicate with Siemens Simatic S5 PLCs using the AS511 protocol.

Figure 3-36. S5_AS511 Definition Parameters Dialog Box

PLC Model specifies the model of Simatic S5 CPU the object communicates with.

Protocol specifies the protocol used to communicate with the PLC, 3964 or 3964R.

Serial port specifies which port the object uses for communication to the PLC.

Baud Rate specifies the speed at which the object communicates with the PLC.

Phone number specifies the number to be dialed if the serial port setting is configured for dial-up. This number only applies to the individual protocol object.

PollRate is a numeric expression that determines how often to poll the device. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of object-generated alarms (0 – 10).

Receive timeout is the time the object waits for a response from a device before retrying a request.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the object generates an alarm and releases the COM port. See Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

The **Skip every** setting instructs the object that, in the event of a communications failure, to skip the next specified number of polls to the PLC before attempting to re-establish communications. Once communications have been re-established, the device is polled on its regular cycle.

S5_AS511 Data Members

For the PLC data members in Table 3-75, all of the suffixes that start with K (KC, KF, and so on) follow the Siemens format for data suffixes. That is, KC for Counter format, KT for Timer format, KB for byte format, KF for fixed-point format, KG for floating-point format, and no suffix for those data members for which only one format is possible, such as bit fields, counters, and timers. The other three suffixes, F, D, and T have been added to allow reading and writing IEEE 32-bit floating point (F), IEEE 64-bit floating point (D), and Lookout time (T). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on Lookout time format.

Table 3-75. S5_AS511 Data Members

| Data Member | Type | Read | Write | Description |
|---------------|---------|------|-------|--|
| A0KB -A6535KB | numeric | yes | yes | Absolute address unsigned left byte in a data block word. |
| A0KC -A6535KC | numeric | yes | yes | Absolute address of a word in a data block interpreted as a counter. |

Table 3-75. S5_AS511 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|----------------------------|-------------|-------------|--------------|---|
| A0KF -A6535KF | numeric | yes | yes | Absolute address of a word in a data block interpreted as a signed fixed-point. |
| A0KG -A6535KG | numeric | yes | yes | Absolute address of a word in a data block interpreted as a Siemens floating-point. |
| A0KT -A6535KT | numeric | yes | yes | Absolute address of a word in a data block interpreted as a Siemens time format. |
| CommFail | Logical | yes | no | Object-generated signal that is ON if the object cannot communicate with the PLC. |
| DB1D0.0 – DB255D255.15 | Logical | yes | no | A bit in a Data Block word. |
| DB1DD0D – DB255DD254D | Numeric | yes | yes | 64-bit in a Data Block interpreted as IEEE floating point format. |
| DB1DD0F – DB255DD254F | Numeric | yes | yes | 32-bit in a Data Block interpreted as IEEE floating point format. |
| DB1DD0KF – DB255DD254KF | Numeric | yes | yes | Single-word in a Data Block interpreted as signed fixed-point. |
| DB1DD0KG – DB255DD254KG | Numeric | yes | yes | Double-word in a Data Block interpreted as Siemens floating point format. |
| DB1DL0KB – DB255DL255KB | Numeric | yes | no | The unsigned left byte in a Data Block word. |
| DB1DR0KB – DB255DR255KB | Numeric | yes | no | The unsigned right byte in a Data Block word. |
| DB1DW0KC – DB255DW255KC | Numeric | yes | yes | Word in a Data Block interpreted as a counter. |
| DB1DW0KF – DB255DW255KF | Numeric | yes | yes | Word in a Data Block interpreted as signed fixed-point. |
| DB1DW0KT – DB255DW255KT | Numeric | yes | yes | Word in a Data Block interpreted as Siemens time format. |

Table 3-75. S5_AS511 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------------|-------------|-------------|--------------|--|
| DB1DW0T – DB255DW255T | Numeric | yes | yes | Word in a Data Block interpreted as Lookout time format. |
| Poll | Logical | no | yes | When this expression transitions from FALSE to TRUE, Lookout polls the device. |
| PollRate | Numeric | no | yes | Lookout expression that determines the device polling frequency. |
| Update | Logical | yes | no | Object-generated signal that pulses low each time it polls the device |

S5_AS511 Alarms

Object Alarms

The following alarms originate in the object, and are only generated after the object has retried the request the number of times specified by the Retry attempts parameter.

No response from PLC

Lookout did not receive a response from the device within the Receive timeout period. The driver object is able to use the COM port, but when it polls the device, the device does not respond. You may have to increase Receive timeout to ensure Lookout is allowing enough time to receive the expected response. Also, verify your baud rate settings, cable connections, power, configuration settings, COM port settings, and polling addresses.

Unexpected response from PLC

A response was received from the PLC, but not the response expected according to the protocol.

The BCC computed by the object for a received frame did not match the BCC in the frame.

PLC Alarms

The following alarms originate in the PLC, and are generated immediately by the object. There are no retry attempts.

Illegal DB/DX number

The Data Block (DB) number in a read/write request to a PLC was not valid for the PLC.

Invalid datablock word number

The word number in a read/write request to a PLC was not valid for the specified Data Block (DB).

SiemensTI505

SiemensTI505 is an Ethernet protocol driver object class Lookout uses to communicate with Siemens SIMATIC TI505 PLCs that are equipped with CP1431 NIMs. This driver is often referred to as Siemens H1.

Designed using the SINEC TF software library, this object class uses the SINEC H1 protocol and fully conforms to the application layer of the Siemens SINEC H1-TF protocol stack.

Your PC must be equipped with a Siemens CP 1413 Ethernet communications card and Siemens TF-NET 1413 software. See [Configuring HI-TF](#) in this section for instructions on setting up your H1 driver.

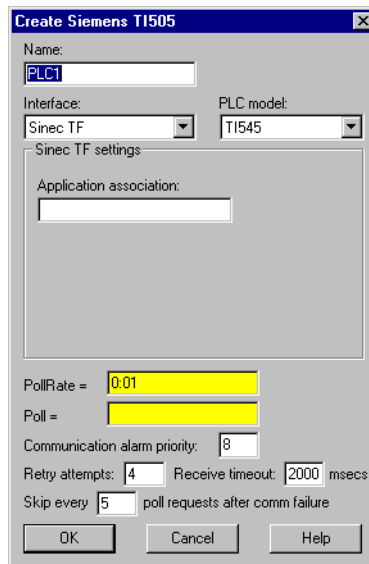


Figure 3-37. SiemensTI505 Definition Dialog Box

PLC Model specifies the PLC model number for the requested device. The list includes SIMATIC TI545, TI555 and TI565 PLCs.

Application association identifies an application name that you define using the SINEC Com1413t.exe program. This name identifies the physical device that your object represents. See [Configuring HI-TF](#) in this section for more information.

PollRate is a numeric expression that determines how often to poll the device. SiemensTI505 then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for more information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the object generates an alarm and releases the COM port. See Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

Communication alarm priority determines the priority level of alarms generated by the SiemensTI505 object.

The **Skip every ___ polls** setting instructs Lookout not to poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle accordingly. Once communications have been reestablished, the device is polled on its regular cycle.

Configuring HI-TF

Install the Siemens TF-NET1413 MSDOS/Windows driver configuration software, including the COML 1413 TF configuration tool.

Configure the CP1413 Ethernet MAC address, memory map, and other settings by executing the following program from DOS (not Windows):

```
c:\sinec\bin\netinst.exe.
```

This creates a text file called `C:\SINEC\DATA\DOS_conf.dat` that stores the configuration parameters. You can later edit this file to change card settings in lieu of executing the install program.

If you are using a memory manager such as EMM386, add a memory exclude statement to your computer `CONFIG.SYS` file. For example, enter:

```
DEVICE=C:\WINDOWS\EMM386.EXE X=D000-DFFF
```

The CP 1413 Ethernet card uses 64 Kb of dual-ported RAM. Possible start addresses are D0000 and E0000.



Note Be sure to verify that no other drivers are mapped to the selected memory location.

From Windows, run `C:\SINEC\COM\Com1413t.exe` (the three-pawn icon) and configure the PLC name/address database that you download later to the CP 1413 card during system startup. Create a database file called `STARTUP`, and save it in the `C:\SINEC\DATA` directory.

This program creates two files, with your database represented by `startup.ldb` and `startup.txt`. These files contain the application association names that you need for each PLC.



Note There is a line of text in `DOS_CONF.DAT` that points to `STARTUP.LDB`. To use a different path or filename for your `.ldb` file, modify `DOS_CONF.DAT` to point to the file you create.

From Windows, activate `C:\SINEC\H1\H1.exe` (the single pawn icon) to create an H1 configuration file. Then, using the serial port on the NIM, download the configuration file to the H1 NIM in the PLC.

You must enter a unique Ethernet address and application association that matches one stored in the `.LDB` file. Also be sure that the Local TSAP and Remote TSAP values match exactly with the `.LDB` settings, except the Local TSAP and Remote TSAP values are swapped.

Create one H1 configuration file for each NIM in each PLC.



Note Application Association, Local TSAP, Remote TSAP, and just about everything else in the Siemens software is case sensitive.

Download the configuration to each NIM through the serial port on the NIM.

Edit your `AUTOEXEC.BAT` file and add the following command to the end of the file—but prior to any `WIN` command):

```
CALL C:\SINEC\BIN\STARTCP.BAT
```

Reboot your computer.

Within Lookout, create a SIEMENSTI505 object for each PLC using the appropriate Application Association. You are now ready to access PLC variables in Lookout.

SiemensTI505 Data Members

Protocol driver objects contain a great deal of data. All readable and writable members (inputs/outputs), polling instructions, read/write blocking, serial port usage, and so on, are bundled with the object. Therefore, as soon as you create a SiemensTI505 object you immediately have access to all the object data members (see data member list in Table 3-76).



Note Lookout protocol driver objects automatically generate an efficient read/write blocking scheme based on the inputs and outputs being used in your process file. You are not required to build your own I/O blocking table.

Table 3-76. SiemensTI505 Data Members

| Data Member | Type | Read | Write | Description |
|-------------------|---------|------|-------|---|
| AACK1 – AACK32000 | numeric | yes | yes | (Analog Alarm) Alarm acknowledge flags |
| AADB1 – AADB32000 | numeric | yes | yes | (Analog Alarm) Deadband |
| ACF1 – ACF32000 | numeric | yes | yes | (Analog Alarm) Alarm C-flags |
| ACFH1 – ACFH32000 | numeric | yes | yes | (Analog Alarm) Alarm C-flags most significant word |
| ACFL1 – ACFL32000 | numeric | yes | yes | (Analog Alarm) Alarm C-flags least significant word |
| AERR1 – AERR32000 | numeric | yes | yes | (Analog Alarm) Alarm error |
| AHA1 – AHA32000 | numeric | yes | yes | (Analog Alarm) High alarm limit |
| AHHA1 – AHHA32000 | numeric | yes | yes | (Analog Alarm) High high alarm limit |
| ALA1 – ALA32000 | numeric | yes | yes | (Analog Alarm) Low alarm limit |
| ALLA1 – ALLA32000 | numeric | yes | yes | (Analog Alarm) Low low alarm limit |
| AODA1 – AODA32000 | numeric | yes | yes | (Analog Alarm) Orange deviation limit |

Table 3-76. SiemensTI505 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|--|
| APV1 – APV32000 | numeric | yes | yes | (Analog Alarm) Process variable |
| APVH1 – APVH32000 | numeric | yes | yes | (Analog Alarm) Process variable high limit |
| APVL1 – APVL32000 | numeric | yes | yes | (Analog Alarm) Process variable low limit |
| ARCA1 – ARCA32000 | numeric | yes | yes | (Analog Alarm) Rate of change limit |
| ASP1 – ASP32000 | numeric | yes | yes | (Analog Alarm) Setpoint |
| ASPH1 – ASPH32000 | numeric | yes | yes | (Analog Alarm) Setpoint high limit |
| ASPL1 – ASPL32000 | numeric | yes | yes | (Analog Alarm) Setpoint low limit |
| ATS1 – ATS32000 | numeric | yes | yes | (Analog Alarm) Sample rate |
| AVF1 – AVF32000 | numeric | yes | yes | (Analog Alarm) Alarm flags |
| AYDA1 – AYDA32000 | numeric | yes | yes | (Analog Alarm) Yellow deviation limit |
| C1 – C32000 | logical | yes | yes | Control Registers |
| CommFail | logical | yes | no | Driver-generated signal that is ON if Lookout cannot communicate with the device for whatever reason |
| DCC1 – DCC32000 | numeric | yes | no | Drum current count |
| DSC1 – DSC32000 | numeric | yes | yes | Drum step current |
| DSP1 – DSP32000 | numeric | yes | yes | Drum step preset |
| K1 – K32000 | numeric | yes | yes | K-memory unsigned 16-bit integer value ranging from 0 to 65535 |
| K1. – K32000. | numeric | yes | yes | K-memory 32-bit IEEE floating point value |
| K1D – K32000D | numeric | yes | yes | K-memory 32-bit unsigned integer value |
| K1S – K32000S | numeric | yes | yes | K-memory signed 16-bit integer value ranging from –32768 to 32767 |
| LACK1 – LACK32000 | numeric | yes | yes | (Loop) Alarm Acknowledge Flags |

Table 3-76. SiemensTI505 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---------------------------------------|
| LADB1 – LADB32000 | numeric | yes | yes | (Loop) Deadband |
| LCF1 – LCF32000 | numeric | yes | yes | (Loop) C-flags |
| LCFH1 – LCFH32000 | numeric | yes | yes | (Loop) C-flags most significant word |
| LCFL1 – LCFL32000 | numeric | yes | yes | (Loop) C-flags least significant word |
| LERR1 – LERR32000 | numeric | yes | no | (Loop) Error |
| LHA1 – LHA32000 | numeric | yes | yes | (Loop) High alarm limit |
| LHHA1 – LHHA32000 | numeric | yes | yes | (Loop) High high alarm limit |
| LKC1 – LKC32000 | numeric | yes | yes | (Loop) Gain |
| LKD1 – LKD32000 | numeric | yes | yes | (Loop) Derivative gain |
| LLA1 – LLA32000 | numeric | yes | yes | (Loop) Low alarm limit |
| LLLA1 – LLLA32000 | numeric | yes | yes | (Loop) Low low alarm limit |
| LM1 – LM32000 | numeric | yes | yes | (Loop) Mode |
| LMN1 – LMN32000 | numeric | yes | yes | (Loop) Output |
| LMX1 – LMX32000 | numeric | yes | yes | (Loop) Bias |
| LODA1 – LODA32000 | numeric | yes | yes | (Loop) Orange deviation limit |
| LPV1 – LPV32000 | numeric | yes | yes | (Loop) Process variable |
| LPVH1 – LPVH32000 | numeric | yes | yes | (Loop) Process variable high limit |
| LPVL1 – LPVL32000 | numeric | yes | yes | (Loop) Process variable low limit |
| LRCA1 – LRCA32000 | numeric | yes | yes | (Loop) Rate of change limit |
| LRSF1 – LRSF32000 | numeric | yes | yes | (Loop) Ramp/Soak status flags |
| LS1 – LS32000 | numeric | yes | no | (Loop) Status |
| LSP1 – LSP32000 | numeric | yes | yes | (Loop) Setpoint |
| LSPH1 – LSPH32000 | numeric | yes | yes | (Loop) Setpoint high limit |
| LSPL1 – LSPL32000 | numeric | yes | yes | (Loop) Setpoint low limit |
| LTD1 – LTD32000 | numeric | yes | yes | (Loop) Rate |
| LTI1 – LTI32000 | numeric | yes | yes | (Loop) Reset |

Table 3-76. SiemensTI505 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|--|
| LTS1 – LTS32000 | numeric | yes | yes | (Loop) Sample rate |
| LVF1 – LVF32000 | numeric | yes | yes | (Loop) V-flags |
| LYDA1 – LYDA32000 | numeric | yes | yes | (Loop) Yellow deviation limit |
| Poll | logical | no | yes | When this value transitions from FALSE to TRUE, the Lookout object polls the device |
| PollRate | numeric | no | yes | Specifies the frequency at which the Lookout object polls the device |
| TCC1 – TCC32000 | numeric | yes | yes | (Analog Alarm) Timer/counter current |
| TCP1 – TCP32000 | numeric | yes | yes | (Analog Alarm) Timer/counter preset |
| Update | logical | yes | no | Driver-generated signal that pulses each time the driver polls the device |
| V1 – V32000 | numeric | yes | yes | V-memory unsigned 16-bit integer value ranging from 0 to 65535 |
| V1. – V32000. | numeric | yes | yes | V-memory 32-bit IEEE floating point value |
| V1D – V32000D | numeric | yes | yes | V-memory 32-bit unsigned integer value |
| V1S – V32000S | numeric | yes | yes | V-memory signed 16-bit integer value ranging from –32768 to 32767 |
| WX1 – WX32000 | numeric | yes | no | Word Image Inputs—16-bit values that typically range from 6400 – 32000 for 4 – 20 mA signals, and 0 – 32000 for 0 – 5V signals. |
| WY1 – WY32000 | numeric | yes | yes | Word Image Outputs—16-bit values that typically range from 6400 – 32000 for 4 – 20 mA signals, and 0 – 32000 for 0 – 5V signals. |

Table 3-76. SiemensTI505 Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|--|
| X1 – X32000 | logical | yes | no | Discrete Inputs—unassigned Xs may be used as control registers |
| Y1 – Y32000 | logical | yes | yes | Discrete Outputs—same memory space as Discrete Inputs, so X37 references the same point as Y37. Unassigned Ys may be used as control registers |

SiemensTI505 Status Messages

The following alarms are SINEC error codes returned by the Siemens software. For more detailed information, consult the Siemens SINEC TF documentation.

- **cannot initialize Sinec TF service**
- **hardware error**
- **invalid address**
- **invalid app. assoc. name: xxxx**
- **more than one object using same app. assoc.**
- **no more space in PDU**
- **no response**
- **no response (reconnecting)**
- **not available at times**
- **object access not allowed**
- **object attribute inconsistent**
- **object does not exist**
- **object not defined**
- **object now invalid**
- **type not supported**
- **type/alt acc. not consistent**

Sixnet

Sixnet is a protocol driver object class Lookout uses to communicate with Sixnet IOMUX RTUs (remote terminal units), Versamux RTUs, and DIN rail-mounted Sixtrak I/O modules.

The Lookout Sixnet object class establishes an interface to the Sixnet Control Room software using direct DLL calls (not DDE). Using this seamless connection between programs, Lookout can communicate with Sixnet devices through your serial port (RS-232 or RS-422/485), through Ethernet, or RTUnet.



Note This protocol driver object class requires Version 1.0 or later of Sixnet Control Room I/O Map software, and Version 3.5 build 15 (or later) of Lookout.

Create one Lookout Sixnet object for each station you define in the Control Room software. In order to make Sixtags names correspond as closely as possible to Lookout alias names, you should name the Lookout objects using the eight-letter prefixes of the Sixnet stations.

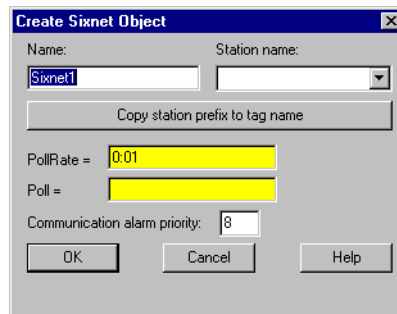


Figure 3-38. Sixnet Configuration Parameters Dialog Box

Station name is a pull-down list box of all stations defined in the Control Room software. Select the station that you want the object to represent.

PollRate is a numeric expression that specifies how often Lookout polls the Control Room software. Normally, this is a simple time constant such as 0:01 (one second), but you may choose to make this a complex expression, making the **PollRate** change dynamically based on criteria that you specify. See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants and variables.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of alarms generated by the Lookout Sixnet object. Such alarms are typically related to DLL handshaking with the Control Room software.

Sixnet Data Members

A Sixnet object represents all values within a given station; therefore, it can contain a great deal of data. The object can read and write all possible data point types, including predefined and user-defined I/O types. When you create a Sixnet object, you have immediate access to all data within the assigned station (see *Sixnet Data Members* in Table 3-77).

Each register in the Sixnet I/O Map corresponds to a data member within the Lookout Sixnet object. The register I/O type number and address are encoded into the name of the data member. Predefined I/O type numbers correspond with Lookout data member prefixes as follows.

| I/O Type Number | Data Member Prefix |
|-----------------|--------------------|
| 0 | AI (Analog In) |
| 1 | AO (Analog Out) |
| 10 | DI (Discrete In) |
| 11 | DO (Discrete Out) |
| 20 | LongIn |
| 21 | LongOut |
| 22 | FloatIn |
| 23 | FloatOut |

For user-defined I/O types, the Sixnet I/O type number is specified by the name of the Lookout data member which takes the following form:

<DataType><ioTypeNumber>:<Address>

where <DataType> is Bit, Byte, Short, Word, Long, Float, or Double; <ioTypeNumber> is a number between 0 and 126 inclusive; and <Address> is a number whose legal range depends on the data type. Thus the Lookout point `Sixnet1.Word33:99` corresponds to the hundredth register with

I/O type number 33 for the station with name `Sixnet1.Station`. The register is read as a word (that is, an unsigned 16-bit number).

You can use any data type with any I/O type number in Lookout. This means that you can read a long (32-bit signed number) from two consecutive analog registers. This makes it very easy to get the value of a 32-bit counter that is stored in consecutive 16-bit registers in a PLC. For example, the data member `Long0:7` would correspond to analog inputs `AI7` and `AI8` and it would be interpreted as a signed, 32-bit register. This capability also means that you have the choice of reading an analog value as either a signed value (using `AI0` or `Short0:0`) or as an unsigned value (using `Word0:0`).



Note Writing a bit to an analog register sets that analog value to 0 or 1. It does not set just one of the bits to 0 or 1.

Table 3-77. Sixnet Data Members

| Data Member | Type | Read | Write | Description |
|----------------------------|---------|------|-------|---|
| AI0 – AI32499 | numeric | yes | yes | Analog input encoded as a 16-bit signed integer ranging from –32768 to +32767 |
| AO0 – AO32499 | numeric | yes | yes | Analog output encoded as a 16-bit signed integer ranging from –32768 to +32767 |
| Bit0:0 – Bit126:64999 | logical | yes | yes | User-defined discrete I/O (TRUE or FALSE) |
| Byte0:0 – Byte126:64999 | numeric | yes | yes | User-defined register encoded as an 8-bit unsigned integer ranging from zero to 255 |
| CommFail | logical | yes | no | Driver-generated signal that is ON if Lookout cannot communicate with the device for whatever reason |
| DI0 – DI64999 | logical | yes | yes | Discrete input (TRUE or FALSE) |
| DO0 – DO64999 | logical | yes | yes | Discrete output (TRUE or FALSE) |
| Double0:0 – Double126:8124 | numeric | yes | yes | User-defined I/O referring to 4 consecutive registers encoded as a single 64-bit floating point value |

Table 3-77. Sixnet Data Members (Continued)

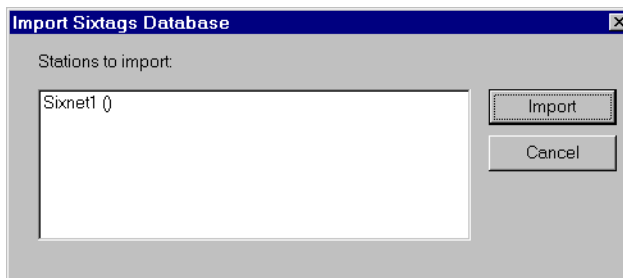
| Data Member | Type | Read | Write | Description |
|------------------------------|-------------|-------------|--------------|---|
| Float0:0 – Float126:16299 | numeric | yes | yes | User-defined register pair encoded as a 32-bit IEEE floating point value |
| FloatIn0 – FloatIn16299 | numeric | yes | yes | 32-bit IEEE floating point value —reads two adjacent registers as a single 32-bit floating point value |
| FloatOut0 – FloatOut16299 | numeric | yes | yes | 32-bit IEEE floating point value —writes two adjacent registers as a single 32-bit floating point value |
| Long0:0 – Long126:16299 | numeric | yes | yes | User-defined register pair encoded as a signed 32-bit long integer. Lookout reads two adjacent registers as a single 32-bit number ranging from –2147483648 to +2147483647. |
| LongIn0 – LongIn16299 | numeric | yes | yes | Long input encoded as a signed 32-bit long integer. Lookout reads two adjacent registers as a single 32-bit number ranging from –2147483648 to +2147483647. |
| LongOut0 – LongOut16299 | numeric | yes | yes | Long output encoded as a signed 32-bit long integer. Lookout writes two adjacent registers as a single 32-bit number ranging from –2147483648 to +2147483647. |
| Poll | logical | no | yes | When this value transitions from FALSE to TRUE, Lookout polls the device. |
| PollRate | numeric | no | yes | Lookout expression that determines the device polling frequency. |
| Short0:0 – Short126:32499 | numeric | yes | yes | User-defined register encoded as 16-bit signed integer ranging from –32767 to +32768 |
| Station | text | yes | no | Station name (such as, Local Computer) |

Table 3-77. Sixnet Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|----------------------------|---------|------|-------|--|
| Update | logical | yes | no | Driver-generated signal that pulses each time the driver polls the device |
| Word0:0 – Word126:32499 | numeric | yes | no | User-defined register encoded as 16-bit unsigned integer ranging from 0 to 65535 |

Importing Sixtags Database

With the Sixnet Lookout object you can take advantage of Sixnet's Sixtags database. After you create at least one Sixnet object, the Sixnet class adds a menu selection (**Import Sixtags database**) to the Lookout **Options** menu. Use this menu command to import a set of aliases for one or more stations.



When you select the menu command, a dialog box appears, listing all of the Lookout Sixnet objects—giving their names and corresponding station names. From the dialog box, select one or more station names and click on Import. Notice that spaces in the Sixtags names are replaced by underscores. You can re-import name files as your Sixtags data is modified, and Lookout readjusts the aliased tag names automatically, in real time.

Sixnet Status Messages

Unable to load Sixnet IOMAP library: iodbase.dll

The Sixnet software is not installed—Lookout cannot find the `iodbase.dll` library. Make sure that you have installed the Control Room software properly. This should put the `iodbase.dll` library into the `\WINDOWS\SYSTEM` directory.

No Sixnet configuration currently loaded

The Sixnet I/O Map software is not running yet. Use the Sixnet I/O Map program to open and run a project file. According to the Sixnet I/O Map help file, your DLL must be loaded and scanning before Lookout can control I/O. The easiest way to load the DLL and start scanning is to run the Control Room Power Switch. You could also select the **Run** command from the **Control** menu in the Sixnet I/O Map.

Station <name> is not on line

Sixnet reports that the named station is not on line. Lookout might still be able to read from and write to registers for that station, but the updates will not be propagated to the remote device.

Read error (<station name>, type <type number>, address <address>)

Write error (<station name>, type <type number>, address <address>)

One of the following reasons will be given:

- Address out of range
- Bad station, address, or type number
- Bad type number

SquareD

Lookout uses the SquareD object class to communicate with the SquareD family of SCP PLCs. These include the SCP-1xx, 3xx, 4xx, 5xx, 6xx, and 7xx series. Lookout can interface to Square D PLCs through either a serial interface or a SY/MAX interface. The SY/MAX interface supports both SY/MAX and net-to-net communication modes.

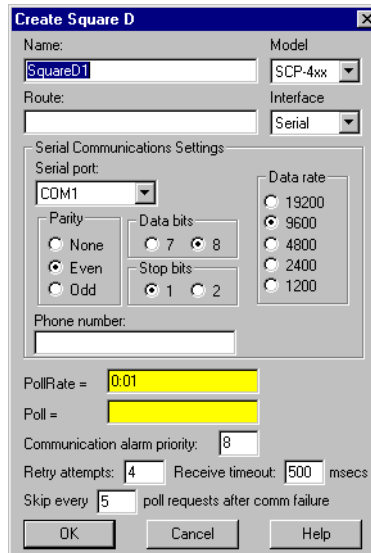


Figure 3-39. SquareD Definition Parameters Dialog Box Configured for Serial Communications

Route refers to a unique path through any network devices that leads to the PLC port. Remember, when using the SY/MAX card, the first route must be a zero followed by the address of the card. This is because the SY/MAX card edge is considered to be port zero. The RS422 port on the SY/MAX card is considered to be port one.

Model specifies the particular type of PLC you are representing with this object. The **Model** you select determines what native data members comprise the object.

PollRate is a numeric expression that determines how often to poll the device. Lookout polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of the alarms generated by the SquareD object.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device if it is not getting a valid response. After it tries the number of **Retry attempts** specified, the object generates an alarm and begins to **Skip every n poll requests after comm failure**. Once Lookout reestablishes communications, it polls the device on its regular cycle, as defined by **PollRate**.

Receive timeout is the time Lookout waits for a response from a device before retrying the poll request.

Serial Port Interface Parameters

The **Serial Interface** selection enables serial port communication from your computer to the programming port on your PLC. The previous diagram shows a Square D PLC configured for serial communications.

Serial port specifies which RS-232C port on your computer the object uses for communication to the physical device.

Data rate, Parity, Data Bits, and Stop bits reference the settings of the hardware device. Choose the settings as configured on you PLC.

Phone number specifies the number to be dialed if the serial port setting is configured for dial-up. This number only applies to the individual object. See **Options»Serial Ports** for more information.

SY/LINK Interface Parameters

The **SY/LINK Interface** selection enables direct connection of your computer to a Square D network using a SY/MAX card. The following diagram shows a SquareD object configured for SY/MAX communications.

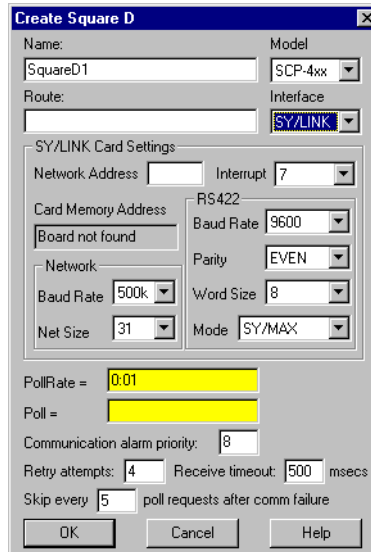


Figure 3-40. SquareD Definition Dialog Box Configured for SY/LINK Communications

Network address identifies the address of your computer interface card in the SY/MAX network. Valid addresses range from 0 to 99. The card node address must be unique—that is, it must not be the same as the address of any other device on the network.

Interrupt identifies the interrupt (IRQ) setting of your SY/MAX interface card in your PC. Assigning an interrupt to the interface card improves overall computer performance. Any time the card receives a response, it generates an interrupt recognized by Lookout.

Card memory address specifies the base address location of the card memory. This is selected for you automatically. At present, only one SY/MAX card in a computer is supported. Lookout looks for the card and fills this box with its address. If the card is not found, this is indicated here as well.

Network settings include net size and baud rate. **Net size** identifies the number of devices on the network. The *SY/MAX* card and all of the **PLCs** or **NIMs** must have the same settings for successful communications to occur. A net size of 31 should promote a faster response time. **Baud rate** selects the baud rate at which the *SY/LINK* card tries to communicate on the *SY/NET* network.

The **RS-422** settings include **baud rate**, **parity**, and **word size**. These parameters reference the settings of the hardware device. Choose the settings as configured on you PLC.

RS-422 mode chooses either *SY/MAX* or *Net-to-net*. Choosing *SY/MAX* allows normal network operations. Choosing *Net-to-net* allows extended distributed networks, large capacity networks (more than 200 devices), or network redundancy (more than one path between two devices). The default is *SY/MAX*.

SY/ENET Interface Parameters

The *SY/ENET* **Interface** selection enables direct connection of your computer to an Ethernet network using an Ethernet card. *SY/ENET* is only available on computers running Windows NT. You cannot use SquareD ENET under Windows 95.

To use SquareD with the ENET protocol, you must install the Lookout Ethernet driver as a protocol in the Windows Network Control Panel. Lookout installs the files *LKETHER.SYS* and *OEMSETUP.INF* when you install Lookout. To install the Lookout Ethernet Driver, select **Settings»Control Panel»Network** and click on the **Protocols** tab. Click **Add**, and then click **Have Disk**, changing the default path from *A:* to your main Lookout directory. Follow the onscreen instructions to complete installation of the driver.

The following diagram shows a SquareD object configured for SY/ENET communications.

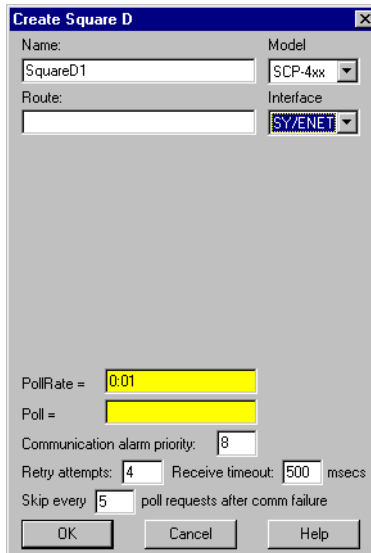


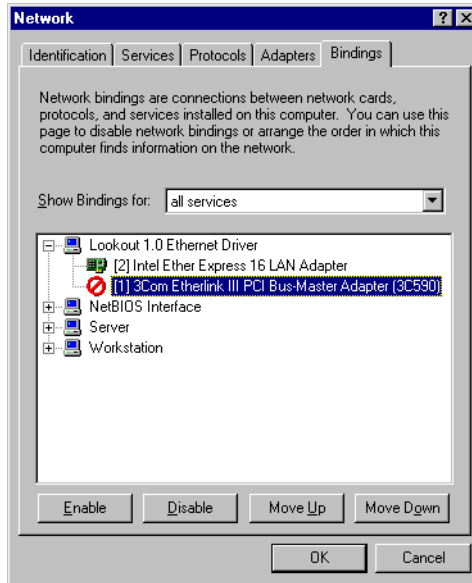
Figure 3-41. SquareD Definition Dialog Box Configured for SY/ENET Communications

Route refers to a unique path through any network devices that leads to the PLC port.

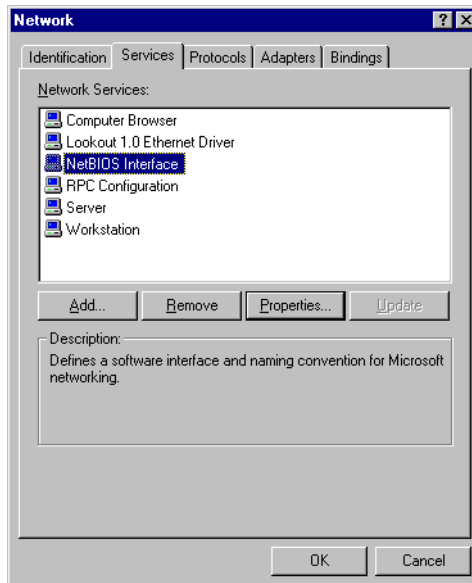
Using SY/ENET with More Than One Ethernet Board in Your System

If you have more than one Ethernet board installed in your computer, you must configure your system properly to use the SquareD driver object.

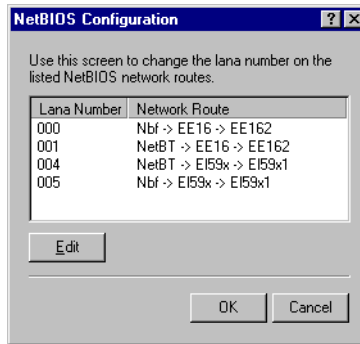
Open the **Network** Dialog Box from **Settings»Control Panel»Network** and select the **Bindings** name. Under the Lookout Ethernet Driver Heading, highlight all ethernet boards *except* the one connected to your SquareD network, and click on the **Disable** button. For instance, in the following illustration, the Intel Ether Express 16 LAN adapter is connected to the SquareD network.



Next select the **Services** tab.



Highlight **NetBios Interface** and click on **Properties**. The **NetBIOS Configuration** dialog box appears.



Make sure that the Square D Ethernet card is **LANA Number** 000 and the **Network Route** is Nbf.

SquareD Data Members

Each SquareD object contains a great deal of data. All readable and writable members (inputs/outputs) are bundled with the object. As soon as you create an object you immediately have access to all the object data members.



Note The SquareD object class automatically generates an efficient read/write blocking scheme based on the inputs and outputs you are using in your process file. You are not required to build your own I/O blocking table. However, you can ensure peak performance by organizing your PLCs data into contiguous groups.

Table 3-78. SquareD Data Members

| Data Member | Type | Read | Write | Description |
|-------------|---------|------|-------|---|
| 1 – 8176 | numeric | yes | yes | 16-bit unsigned integer ranging from 0 to 65535 |
| 1. – 8176. | logical | yes | yes | Logical I/O that reads and writes the entire register. When you write to the register, all bits in the word go TRUE or FALSE. |

Table 3-78. SquareD Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------------|-------------|-------------|--------------|--|
| 1.0 – 8176.15 | logical | yes | yes | Individual bits in a register read as logical ON/OFF values. The least significant bit is 0; the most significant, 15. |
| CommFail | logical | yes | no | Object-generated signal that is on if, for whatever reason, Lookout cannot communicate with the PLC. |
| F1 – F8175 (odd only) | numeric | yes | yes | 32-bit IEEE floating point register—reads two adjacent holding registers as a single 32-bit floating point value |
| Poll | logical | no | yes | When this value transitions from FALSE to TRUE, the Lookout object polls the PLC device |
| PollRate | numeric | no | yes | Specifies the frequency at which the Lookout object polls the PLC device |
| S1 – S8176 | numeric | yes | yes | 16-bit signed word ranging from –32,768 to +32,768 |
| Update | logical | yes | no | Object-generated signal that pulses each time the object polls the device |

SquareD Error Messages

The SquareD object class reports the status of commands it issues to the PLC. When Lookout receives an error response from a PLC, it reports the failure as an alarm containing the status code and its meaning. The following are a few examples of such alarms:

SY/MAX initialization error:(0)Cannot initialize SY/LINK board
SY/MAX polling error:(3)Illegal address attempted
Response error:(3) Received NAK in response

Tesco

Tesco is a protocol driver object class Lookout uses to communicate with Liquitronic LIQ programmable controllers using the **LIQ4** (Data Express) and **LIQ5** (Data Express Plus) messaging protocols. Create one Tesco object for each controller.

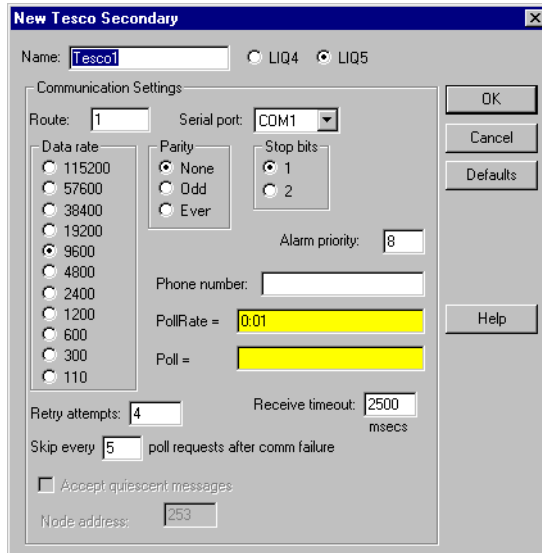


Figure 3-42. Tesco Configuration Parameters Dialog Box

Route refers to the PLC address setting as specified in its Configuration Table. When using **LIQ4**, it is a simple node address (1 to 255). When using **LIQ5**, Route contains both the network address and the node address in the format `network.node`, as shown in the diagram.

Serial port specifies which port the object uses for communication to the external device. This does not specify the communication topology (such as, radio, dial-up, hard wired). Communication type is determined by the **Options»Serial Ports...** command.

Data rate, **Parity**, and **Stop bits** reference the settings on the hardware device.

The **Defaults** button replaces the current settings with default values.

Alarm priority determines the priority level of Tesco communication alarms.

Phone number specifies the number to be dialed if the serial port setting is configured for dial-up. This number only applies to the individual driver object.

PollRate is a numeric expression that determines how often to poll the device. The Tesco object then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for more information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device it does not get a valid response from. After **Retry attempts** times, the object generates a communication alarm and Lookout moves on to the next device in the polling queue (if any).

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

The **Skip every N poll requests after comm failure** setting instructs Lookout not to poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle accordingly. Once communications are reestablished, the device is polled on its regular cycle.

Selecting the **Accept quiescent messages** checkbox enables Lookout to accept unsolicited, unpolled messages from the PLC. This parameter applies to LIQ IV only.

Node Address denotes the address of the computer you are running Lookout on in the TESCO device route. The default value is 253. This parameter applies to LIQ IV only.

Tesco Data Members

Like other protocol driver objects, Tesco objects can contain a great deal of data. All readable and writable members (inputs/outputs), polling instructions, and so on, are bundled with the object. As soon as you create a Tesco object you immediately have access to all the object data members (see the data member list in Table 3-79).

Table 3-79. Tesco Data Members

| Data Members | Type | Read | Write | Description |
|--------------|---------|------|-------|---|
| AO0 – AO1023 | numeric | yes | yes | Analog Output register capable of holding a 32-bit IEEE floating point value for use in internal Tescode programming, or a physical AO signal value as a 12-bit whole number ranging from 0 to 4095. |
| CommFail | logical | yes | no | Driver-generated signal that is ON if Lookout cannot communicate with the device for whatever reason. |
| IR0 – IR1023 | numeric | yes | yes | Index register containing a 32-bit unsigned integer ranging from 0 to 4,294,967,295. |
| L0 – L1023 | numeric | yes | yes | Level (Analog Input) register capable of holding a 32-bit IEEE floating point value for use in internal Tescode programming, or a physical AI signal as a 12-bit whole number ranging from 0 to 4095. |
| P0 – P1023 | logical | yes | yes | Pump (Discrete Output) register associated with a physical output channel. |
| Poll | logical | no | yes | When this value transitions from FALSE to TRUE, Lookout polls the device. |
| PollRate | numeric | no | yes | Specifies the frequency at which the device is to be polled. |

Table 3-79. Tesco Data Members (Continued)

| Data Members | Type | Read | Write | Description |
|---------------------|-------------|-------------|--------------|--|
| S0 – S1023 | logical | yes | yes | Status (Digital Input) register that can represent either a physical input channel or an internal Tescode programming flag. |
| SP0 – SP1023 | numeric | yes | yes | Setpoint register that holds a 32-bit IEEE floating point value with a range of $\pm 3.37 \times 1038$ |
| T0 – T1023 | numeric | yes | yes | Timer/Counter register containing Pulse counters, Hours timers, HMS timers, Event counters, and Seconds timers as documented in the TESCO LIQ 5 Programmable Control Operations Manual |
| Update | logical | yes | no | Driver-generated signal that pulses each time the driver polls the device |

Tiway

Tiway is a protocol driver object Lookout uses to communicate with series 5xx PLCs manufactured by Siemens, formerly made by Texas Instruments.

Protocol driver objects contain a great deal of data. All readable and writable members (inputs/outputs), polling instructions, read/write blocking, serial port usage, and so on are bundled with the object. As soon as you create a Tiway object you immediately have access to all the object data members (see data member list in this section).



Note Lookout protocol driver objects automatically generate an efficient read/write blocking scheme based on the inputs and outputs being used in your process file. You are not required to build your own I/O blocking table.

Figure 3-43. Tiway Configuration Parameters Dialog Box

PLC Model specifies the PLC model number for the requested device.

PollRate is a numeric expression that determines how often to poll the device. Tiway then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for more information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device it does not get a valid response from. After Retry attempts times, Tiway generates a communication alarm and Lookout moves on to the next device in the polling queue (if any).

Alarm priority determines the priority level of Tiway generated alarms.

Phone number specifies the number to be dialed if the serial port setting is configured for dial-up. This number only applies to the individual protocol object.

The **Skip every ___ polls** setting instructs Lookout not to poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle accordingly. Once communications have been reestablished, the device is polled on its regular cycle.

Update Write Settings

The Lookout default for the Tiway driver object is for the object to perform an update write to the PLC registers every 100 polls. Notice that this can be problematic if the PLC has been changing its own register values. To change this default operation, you must create an entry in the `Lookout.INI` file. Create a Tiway group with the key `UpdateOutputs`.

Setting the `UpdateOutputs` key equal to 0 means the Tiway object will not perform update writes. Setting the key equal to some positive integer N will set the Tiway object to perform update writes once every N polls.

See Appendix C, *The Lookout .INI File*, in the *Lookout Developer's Manual* for more information on using the `Lookout.INI` file. You can also refer to the `Lookout.INI` file topic in Lookout Help for additional information.

Communication Techniques

Lookout communicates with Siemens PLCs in several ways: direct serial connection to the **Local port**, serial connection to an **external Unilink**

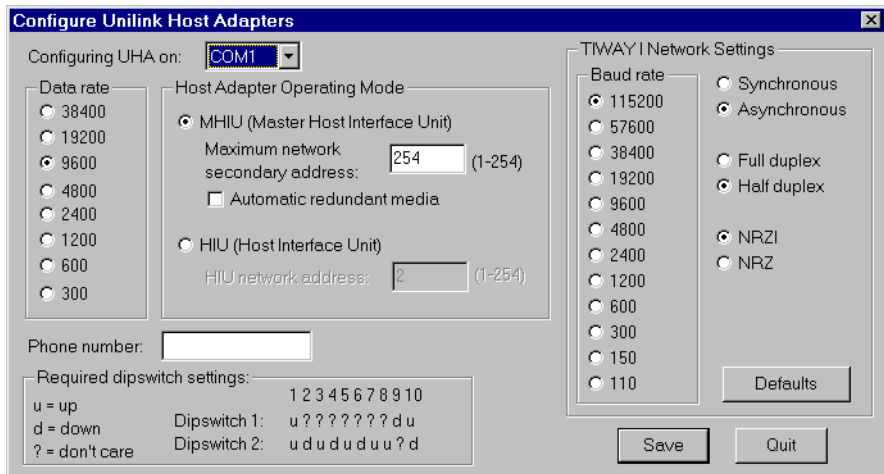
Host Adapter, through an internal **Unilink PC Adapter** card, or through an internal **CTI TCP/IP** card.

Local Port

The **Local port** settings determine the **serial port**, **data rate**, and **phone number** (if any) to be used in a direct connect setup. Because the **Local port** protocol does not include address information, this option is limited to only one (1) PLC per serial port.

Unilink Host Adapter

If **Unilink Host Adapter** is selected, you must specify the **Serial port** to be used and the **NIM** (Network Interface Module) **address** as set at the PLC. You also should configure several settings on the Unilink Host Adapter by selecting the **Configure UHA...** button.



The settings in this dialog box are globally applied to all PLCs on the specified TIWAY network (each network requires a separate serial port). Therefore, it is only necessary to configure each Unilink Host Adapter one time—you need not repeat this step every time you create a new Tiway object.

Data rate specifies the communication speed between the computer and the Unilink Host Adapter. It also determines the required dip switch settings on the UHA for the selected baud rate.

The **Host Adapter Operating Mode** determines if the Unilink Host Adapter is the network manager (**Master Host Interface Unit**) or just

another network secondary (**Host Interface Unit**). There must be exactly one MHIU per TIWAY network.

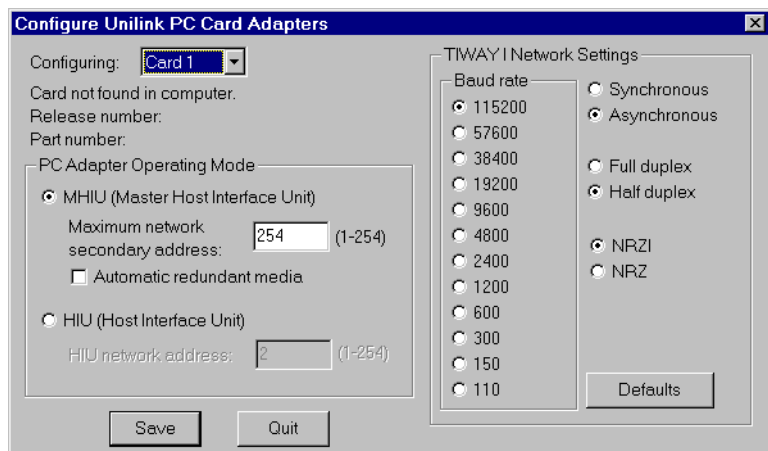
Enabling **Automatic redundant media** instructs the Unilink Host Adapter to attempt communications over a redundant TIWAY network to any secondary it loses communications with.

The **TIWAY I Network Settings** configure the communication parameters for the TIWAY network. This network runs between the Unilink Host Adapter and its secondaries. The Lookout default network settings correspond to the default NIM settings as shipped from Siemens. See your TIWAY documentation to modify any of these parameters.

Unilink PC Adapter

Because the **Unilink PC Adapter** is an internal card, it eliminates the 19200 baud serial bottleneck and replaces it with the 8 MHz PC ISA bus speed. Therefore, the performance gains over the **Unilink Host Adapter** and **Local port** settings can be substantial.

If **Unilink PC Adapter** is selected, you must specify the **Card** to be used and the **NIM (Network Interface Module) address** as set at the PLC. You should also configure several settings on the Unilink PC Adapter by selecting the **Configure PCA...** button.



The settings in this dialog box are globally applied to all PLCs on the specified TIWAY network (each network requires a separate card). Therefore, it is only necessary to configure each Unilink PC Adapter one

time—this step need not be repeated every time a new Tiway object is created.

The **PC Adapter Operating Mode** determines if the Unilink PC Adapter is the network manager (**Master Host Interface Unit**) or just another network secondary (**Host Interface Unit**). There must be exactly one MHIU per TIWAY network.

Enabling **Automatic redundant media** has no effect with the PC Adapter card because it has only one port. If Siemens adds a second port, Lookout automatically supports this option.

The **TIWAY I Network Settings** configure the communication parameters for the TIWAY network. This network runs between the Unilink PC Adapter card and its secondaries. Lookout default network settings correspond to the default NIM settings as shipped from Siemens. See your TIWAY documentation to modify any of these parameters.

CTI TCP/IP

Lookout supports the Control Technology Incorporated (CTI) Ethernet TCP/IP adapter cards that can be installed in SIMATIC TI545 PLCs. In order to work with such cards, your PC must be equipped with an Ethernet network card and a Windows Sockets-Compliant TCP/IP software package. Such packages are available from Microsoft, FTP Software, and NetManage, Inc.

The Lookout **CTI TCP/IP** protocol option is Windows Sockets Compliant. It uses connectionless UDP sockets in software, an industry standard for TCP/IP protocols. In this protocol, a FIFO (first-in, first-out) stack is used to temporarily store communication messages if the data highway is busy or if multiple poll request are generated by several Tiway objects.

Because **CTI TCP/IP** utilizes sockets to momentarily store poll requests, this protocol eliminates bottlenecks imposed by multiple Tiway objects trying to access the data highway at the same time. Performance gains over **Local port**, **Unilink Host Adapter** and **Unilink PC Adapter** settings can be substantial when you are configuring a system that has several PLCs on the same network.

If **CTI TCP/IP** is selected, you need to specify the **IP address** (Internet protocol address) of the PLC. An Internet protocol address consists of four numbers, separated by periods. Each number ranges from zero to 255 decimal. Thus, a typical Internet address might be 128.7.9.231. Ensure that

the **IP address** you enter matches the Internet protocol address of the PLC as specified in its EEPROM or as programmed using PCL.

You can add a secondary IP address to the **CTI TCP/IP** parameter. Lookout now toggles between the primary and secondary IP address after a COM failure (assuming a secondary address exists). Enter the secondary ID after the first, preceded by a space or a comma. For example:

207.68.156.61, 1.2.3.4

Tiway Data Members

Table 3-80. Tiway Data Members

| Data Members | Type | Read | Write | Description |
|-------------------|---------|------|-------|--|
| AERR1 – AERR32000 | numeric | yes | yes | (Analog Alarm) Error |
| AHA1 – AHA32000 | numeric | yes | yes | (Analog Alarm) High alarm limit |
| AHHA1 – AHHA32000 | numeric | yes | yes | (Analog Alarm) High high alarm limit |
| ALA1 – ALA32000 | numeric | yes | yes | (Analog Alarm) Low alarm limit |
| ALLA1 – ALLA32000 | numeric | yes | yes | (Analog Alarm) Low low alarm limit |
| AODA1 – AODA32000 | numeric | yes | yes | (Analog Alarm) Orange deviation limit |
| APVH1 – APVH32000 | numeric | yes | yes | (Analog Alarm) Process variable high limit |
| APVL1 – APVL32000 | numeric | yes | yes | (Analog Alarm) Process variable low limit |
| ARCA1 – ARCA32000 | numeric | yes | yes | (Analog Alarm) Rate of change limit |
| ASP1 – ASP32000 | numeric | yes | yes | (Analog Alarm) Setpoint |
| ASPH1 – ASPH128 | numeric | yes | yes | (Analog Alarm) Setpoint high limit |
| ASPL1 – ASPL128 | numeric | yes | yes | (Analog Alarm) Setpoint low limit |
| ATS1 – ATS32000 | numeric | yes | yes | (Analog Alarm) Sample rate |
| AVF1 – AVF128 | numeric | yes | yes | (Analog Alarm) Alarm flags |
| C1 – C32000 | logical | yes | yes | Control Registers |

Table 3-80. Tiway Data Members (Continued)

| Data Members | Type | Read | Write | Description |
|---------------------|-------------|-------------|--------------|--|
| CommFail | logical | yes | no | Driver-generated signal that is ON if Lookout cannot communicate with the device for whatever reason |
| K1 – K32000 | numeric | yes | yes | K-memory unsigned 16-bit integer value ranging from 0 to 65535 |
| K1. – K32000. | numeric | yes | yes | K-memory 32-bit IEEE floating point value |
| K1D – K32000D | numeric | yes | yes | K-memory 32-bit unsigned integer value |
| K1S – K32000S | numeric | yes | yes | K-memory signed 16-bit integer value ranging from –32768 to 32767 |
| LADB1 – LADB64 | numeric | yes | yes | (Analog Alarm) Deadband |
| LADB1 – LADB64 | numeric | yes | yes | (Loop) Deadband |
| LER1 – LER64 | numeric | yes | no | (Loop) Error |
| LHA1 – LHA64 | numeric | yes | yes | (Loop) High alarm limit |
| LHHA1 – LHHA64 | numeric | yes | yes | (Loop) High high alarm limit |
| LKC1 – LKC64 | numeric | yes | yes | (Loop) Gain |
| LKD1 – LKD64 | numeric | yes | yes | (Loop) Derivative gain |
| LLA1 – LLA64 | numeric | yes | yes | (Loop) Low alarm limit |
| LLLA1 – LLLA64 | numeric | yes | yes | (Loop) Low low alarm limit |
| LMN1 – LMN64 | numeric | yes | yes | (Loop) Output |
| LMX1 – LMX64 | numeric | yes | yes | (Loop) Bias |
| LODA1 – LODA64 | numeric | yes | yes | (Loop) Orange deviation limit |
| LPV1 – LPV64 | numeric | yes | yes | (Loop) Process variable |
| LPVH1 – LPVH64 | numeric | yes | yes | (Loop) Process variable high limit |
| LPVL1 – LPVL64 | numeric | yes | yes | (Loop) Process variable low limit |
| LRCA1 – LRCA64 | numeric | yes | yes | (Loop) Rate of change limit |
| LSP1 – LSP64 | numeric | yes | yes | (Loop) Setpoint |

Table 3-80. Tiway Data Members (Continued)

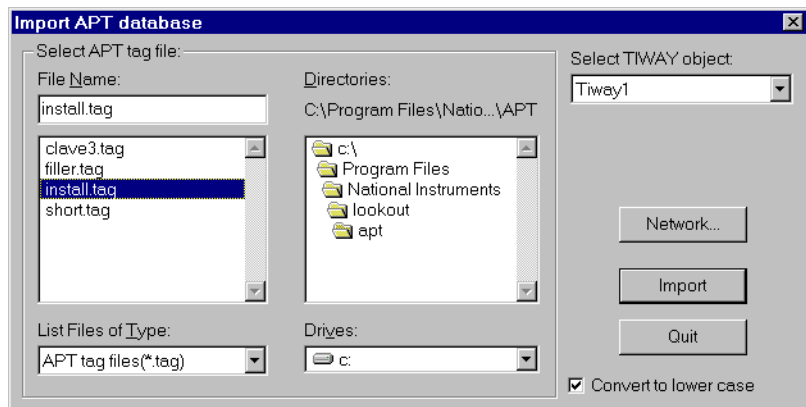
| Data Members | Type | Read | Write | Description |
|---------------------|-------------|-------------|--------------|---|
| LSPH1 – LSPH64 | numeric | yes | yes | (Loop) Setpoint high limit |
| LSPL1 – LSPL64 | numeric | yes | yes | (Loop) Setpoint low limit |
| LTD1 – LTD64 | numeric | yes | yes | (Loop) Rate |
| LTI1 – LTI64 | numeric | yes | yes | (Loop) Reset |
| LTS1 – LTS64 | numeric | yes | yes | (Loop) Sample rate |
| LYDA1 – LYDA64 | numeric | yes | yes | (Analog Alarm) Yellow deviation limit |
| LYDA1 – LYDA64 | numeric | yes | yes | (Loop) Yellow deviation limit |
| Poll | logical | no | yes | When this value transitions from FALSE to TRUE, Lookout polls the device |
| PollRate | numeric | no | yes | Specifies the frequency at which the Lookout object polls the device |
| STW1 – STW32000 | numeric | yes | no | Status Words |
| TCC1 – TCC32000 | numeric | yes | yes | (Analog Alarm) Timer/counter current |
| TCP1 – TCP32000 | numeric | yes | yes | (Analog Alarm) Timer/counter preset |
| Update | logical | yes | no | Driver-generated signal that pulses each time the driver polls the device |
| V1 – V32000 | numeric | yes | yes | V-memory unsigned 16-bit integer value ranging from 0 to 65535 |
| V1. – V32000. | numeric | yes | yes | V-memory 32-bit IEEE floating point value |
| V1B1 – V32000B16 | logical | yes | yes | One bit of a word written out as a whole word |
| V1D – V32000D | numeric | yes | yes | V-memory 32-bit unsigned integer value |
| V1S – V32000S | numeric | yes | yes | V-memory signed 16-bit integer value ranging from –32768 to 32767 |
| V1T – V32000T | text | yes | yes | Two characters of text |

Table 3-80. Tiway Data Members (Continued)

| Data Members | Type | Read | Write | Description |
|---------------|---------|------|-------|--|
| WX1 – WX32000 | numeric | yes | no | Word Image Inputs—16-bit values that typically range from 6400 – 32000 for 4 – 20 mA signals, and 0 – 32000 for 0 – 5V signals. |
| WY1 – WY32000 | numeric | yes | yes | Word Image Outputs—16-bit values that typically range from 6400 – 32000 for 4 –20 mA signals, and 0 – 32000 for 0 – 5V signals. |
| X1 – X32000 | logical | yes | no | Discrete Inputs—unassigned Xs may be used as control registers |
| Y1 – Y32000 | logical | yes | yes | Discrete Outputs—same memory space as Discrete Inputs, so X37 references the same point as Y37. Unassigned Ys may be used as control registers |

Importing APT Name Files

After you have created at least one Tiway object, the Tiway class adds a menu selection to the Lookout **Options** menu you can use to import an APT name file database for each Tiway object created. You can re-import name files as your APT programs are modified, and Lookout readjusts the aliased name names automatically, in real time.



Toshiba Mseries/Toshiba Tseries

Toshiba is a protocol driver class Lookout uses to communicate with Toshiba M Series Ex100, M20, M49 and T Series T1, T2, and T3 devices using the Host Link serial communication protocol.

The dialog box is titled "Create Toshiba Secondary". It contains the following fields and controls:

- Name: Toshiba1
- Address: 00
- PLC Model: EX100
- Communication Settings:
 - Serial port: COM1
 - Data bits: 8
 - Baud Rate: 9600
 - Stop bits: 1
 - Parity: None
 - Phone number: (empty)
- PollRate = 0.01
- Poll = (empty)
- Communication alarm priority: 8
- Retry attempts: 4
- Receive timeout: 250 msec
- Skip every 5 poll requests after comm failure
- Buttons: OK, Cancel, Help

Figure 3-44. Toshiba M Series Configuration Parameters Dialog Box

The dialog box is titled "Create Toshiba Secondary". It contains the following fields and controls:

- Name: Ttoshiba1
- Address: 00
- PLC Model: T1
- Communication Settings:
 - Serial port: COM1
 - Data bits: 8
 - Baud Rate: 9600
 - Stop bits: 1
 - Parity: None
 - Phone number: (empty)
- PollRate = 0.01
- Poll = (empty)
- Communication alarm priority: 8
- Retry attempts: 4
- Receive timeout: 250 msec
- Skip every 5 poll requests after comm failure
- Buttons: OK, Cancel, Help

Figure 3-45. Toshiba T Series Configuration Parameters Dialog Box

Address specifies the address of the PLC. The maximum address for a T Series PLC is 32 and for an M Series PLC, 15.

Serial port specifies which COM port the object uses for communicating to the external device. This does not specify the communication type. Communication type is determined by the **Options»Serial Ports...** command.

Data rate indicates the baud rate that Lookout uses to communicate with the hardware device. The **Data rate** setting should match the selection made on the physical device.

Data bits indicates the number of data bits that Lookout uses to communicate with the hardware device. The **Data bits** setting should match the selection made on the physical device.

Stop bits indicates the number of stop bits that Lookout uses to communicate with the hardware device. This setting should match the selection made on the physical device.

Parity indicates the parity that Lookout uses to communicate with the hardware device. This **Parity** setting should match the selection made on the physical device.

Phone number specifies the number to be dialed if the selected serial port is configured for dial-up. This **Phone number** only applies to the individual protocol object.

PollRate is a numeric expression that determines how often to poll the device. The object then polls the device at the specified time interval. Normally, this is a simple time constant such as 0:01 (one second). See *Numeric Data Members* in Chapter 2, *How Lookout Works*, of the *Getting Started with Lookout* manual for more information on entering time constants.

Poll is a logical expression. When this expression changes from FALSE to TRUE, Lookout polls the device. You can use a simple expression like the signal from a pushbutton, or a complex algorithm.

Communication alarm priority determines the priority level of alarms generated by the Toshiba object. Such alarms are typically related to communications with the physical device.

Retry attempts specifies the consecutive number of times Lookout attempts to establish communications with a device when it is not getting a valid response. After it tries the number of **Retry attempts** specified, the Toshiba object generates an alarm and releases the communication port back to the communications subsystem. The subsystem then moves on to the next device in the polling queue (if any). See Chapter 3, *Serial Communications*, in the *Lookout Developer's Manual* for more information.

Receive timeout is the time delay Lookout uses in waiting for a response from a device before retrying the request.

The **Skip every...** setting instructs Lookout not to poll a device it has lost communication with on every scheduled poll. Instead, Lookout skips the device in the polling cycle. Once communications have been reestablished, the device is polled on its regular cycle.

Toshiba Data Members

A Toshiba object contains a great deal of data. You can read and write to all predefined data points. When you create a Toshiba object, you have immediate access to all the data members for that object.

As with all Lookout drivers, you can access I/O points and other data through data members. The following is a table of data members currently available in the Toshiba object class.

Table 3-81. Toshiba M Series Data Members

| Data Member | Type | Read | Write | Description |
|--------------|---------|------|-------|---|
| C:0 – C:1536 | numeric | yes | no | Counter. |
| CommFail | logical | yes | no | Object-generated signal that is ON if, for any reason, Lookout cannot communicate with the device(s). |
| D:0, D:1536 | numeric | yes | yes | Data register. |
| Poll | logical | no | yes | When this value transitions from FALSE to TRUE Lookout polls the device. |
| PollRate | numeric | no | yes | Lookout expression that determines the device polling frequency. |
| R:0, R:1024 | logical | yes | yes | Auxiliary relay device. |

Table 3-81. Toshiba M Series Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|--|
| RW:0, RW:64 | numeric | yes | yes | Auxiliary relay register. |
| T:0, T:128 | numeric | yes | yes | Timer register. |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device. |
| Y:0, Y:512 | logical | yes | yes | External output device. |
| YW:0, YW:64 | numeric | yes | yes | External output register. |
| Z:0, Z:512 | logical | yes | yes | Link device. |
| ZW:0, ZW:64 | numeric | yes | yes | Link register. |

Table 3-82. Toshiba T Series Data Members

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---|
| CommFail | logical | yes | no | Object-generated signal that is ON if, for any reason, Lookout cannot communicate with the device(s). |
| D:0, D:1536 | numeric | yes | yes | Data register. |
| Poll | logical | no | yes | When this value transitions from FALSE to TRUE Lookout polls the device. |
| PollRate | numeric | no | yes | Lookout expression that determines the device polling frequency. |
| R:0, R:1024 | logical | yes | yes | Auxiliary relay device. |
| RW:0, RW:64 | numeric | yes | yes | Auxiliary relay register. |
| S:0 – S:1024 | logical | yes | yes | Binary timer register. |
| SW:0 – SW:62 | numeric | yes | yes | Data register. |
| T:0, T:128 | numeric | yes | no | Timer register. |
| Update | logical | yes | no | Object-generated signal that pulses low each time it polls the device. |
| X:0, X:512 | logical | yes | no | External input device. |

Table 3-82. Toshiba T Series Data Members (Continued)

| Data Member | Type | Read | Write | Description |
|--------------------|-------------|-------------|--------------|---------------------------|
| XW:0, XW:64 | numeric | yes | no | External input register. |
| Y:0, Y:512 | logical | yes | yes | External output device. |
| YW:0, YW:64 | numeric | yes | yes | External output register. |

Toshiba Status Messages

No response within timeout period

Lookout received no response from a device within the **Receive timeout** period. The Toshiba object is able to use the COM port, but when it polls the device, it does not respond—as if it is not even there.

Toshiba errors reported in the response

These errors are reported by the Toshiba device and are in turn reported to the user in text form.

Missing address marker in frame.

Invalid address in response.

Invalid command in response.

Missing BCC marker in frame.

Invalid BCC.

Missing end of frame marker.

All these alarms indicate a garbled response frame. Check the receive gap or the retry setting in Lookout.

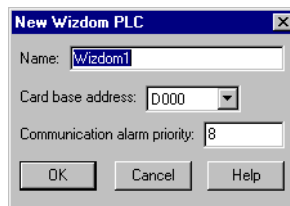
Wizdom

Wizdom is an object class that Lookout uses to communicate with the Wizdom Coprocessor Card. Create one Wizdom object for each Wizdom card installed in the computer.

The Wizdom object scans configured data members for changes 10 times per second.

Wizdom cards are single-board computers. They communicate with the PC through dual-ported memory (that is, RAM accessed by both the PC processor and the Wizdom card processor).

In this example, as shown in the following figure, jumper settings on the card are configured to use hardware interrupt 7 and beginning memory address D000.



Card base address specifies the beginning memory location of the dual ported RAM address. It should match jumper settings on the card. The card uses 8K of physical memory.

When the Wizdom card writes an input value into a memory location, the card generates an interrupt (if so configured), causing the Lookout Wizdom object to immediately scan. This ensures faster responses to field changes.



Note Be sure to verify that no other drivers are mapped to the selected memory location and interrupt.



Note Because the EMM386 memory manager only recognizes the first 4K of mapped memory, it is important to add a memory exclude statement to your computer `CONFIG.SYS` file as instructed in the card documentation.

Wizdom Data Members

Like other object classes designed to communicate with external I/O, Wizdom objects can contain a great deal of data. All readable and writable members (inputs/outputs), polling instructions, and so on are bundled with the object. As soon as you create a Wizdom object you immediately have access to all the object data members.

Table 3-83. Wizdom Data Members

| Data Members | Type | Read | Write | Description |
|---------------------|---------|------|-------|--|
| B0 – B1903 | numeric | yes | yes | 8-Bit word ranging from 0 to 255 |
| B0.0 – B1903.7 | logical | yes | yes | 1 Bit in an 8-Bit word |
| BCD0.2 – BCD1900.16 | numeric | yes | yes | Reserved for future binary coded decimal implementation |
| BS0 – BS1903 | numeric | yes | yes | Signed 8-bit word ranging from –128 to 127 |
| BS0.0 – BS1903.7 | logical | yes | yes | 1 Bit in a signed 8-bit word |
| DF0 – DF1896 | numeric | yes | yes | 64-bit IEEE floating point double precision word |
| DS0 – DS1900 | numeric | yes | yes | Signed 32-bit double-precision word ranging from –2,147,483,648 to 2,147,483,648 |
| DS0.0 – DS1900.31 | logical | yes | yes | 1 Bit in a signed 32-bit word |
| DW0 – DW1900 | numeric | yes | yes | 32-Bit double-precision word ranging from 0 to 4,294,967,295 |
| DW0.0 – DW1900.31 | logical | yes | yes | 1 Bit in a 32-bit word |
| F0 – F1900 | numeric | yes | yes | 32-bit IEEE floating point word |
| S0 – S1902 | numeric | yes | yes | Signed 16-bit word ranging from –32,768 to 32,767 |
| S0.0 – S2047.15 | logical | yes | yes | 1 Bit in a signed 16-bit word |
| STR0 – STR1900 | text | yes | yes | Reserved for future character string implementation |
| W0 – W1902 | numeric | yes | yes | 16-Bit word ranging from 0 to 65,535 |
| W0.0 – W1902.15 | logical | yes | yes | 1 Bit in a 16-Bit word |

Comments The data member addresses listed in the data member table all share the same 4K of memory. For this reason, the following are all the same bit:

$$B391.5 = W391.5 = DS391.5$$

Technical Support Resources

This appendix describes the comprehensive resources available to you in the Technical Support section of the National Instruments Web site and provides technical support telephone numbers for you to use if you have trouble connecting to our Web site or if you do not have internet access.

NI Web Support

To provide you with immediate answers and solutions 24 hours a day, 365 days a year, National Instruments maintains extensive online technical support resources. They are available to you at no cost, are updated daily, and can be found in the Technical Support section of our Web site at www.natinst.com/support.

Online Problem-Solving and Diagnostic Resources

- **KnowledgeBase**—A searchable database containing thousands of frequently asked questions (FAQs) and their corresponding answers or solutions, including special sections devoted to our newest products. The database is updated daily in response to new customer experiences and feedback.
- **Troubleshooting Wizards**—Step-by-step guides lead you through common problems and answer questions about our entire product line. Wizards include screen shots that illustrate the steps being described and provide detailed information ranging from simple getting started instructions to advanced topics.
- **Product Manuals**—A comprehensive, searchable library of the latest editions of National Instruments hardware and software product manuals.
- **Hardware Reference Database**—A searchable database containing brief hardware descriptions, mechanical drawings, and helpful images of jumper settings and connector pinouts.
- **Application Notes**—A library with more than 100 short papers addressing specific topics such as creating and calling DLLs, developing your own instrument driver software, and porting applications between platforms and operating systems.

Software-Related Resources

- **Instrument Driver Network**—A library with hundreds of instrument drivers for control of standalone instruments via GPIB, VXI, or serial interfaces. You also can submit a request for a particular instrument driver if it does not already appear in the library.
- **Example Programs Database**—A database with numerous, non-shipping example programs for National Instruments programming environments. You can use them to complement the example programs that are already included with National Instruments products.
- **Software Library**—A library with updates and patches to application software, links to the latest versions of driver software for National Instruments hardware products, and utility routines.

Worldwide Support

National Instruments has offices located around the globe. Many branch offices maintain a Web site to provide information on local services. You can access these Web sites from www.natinst.com/worldwide.

If you have trouble connecting to our Web site, please contact your local National Instruments office or the source from which you purchased your National Instruments product(s) to obtain support.

For telephone support in the United States, dial 512 795 8248. For telephone support outside the United States, contact your local branch office:

Australia 03 9879 5166, Austria 0662 45 79 90 0, Belgium 02 757 00 20,
Brazil 011 284 5011, Canada (Calgary) 403 274 9391,
Canada (Ontario) 905 785 0085, Canada (Québec) 514 694 8521,
China 0755 3904939, Denmark 45 76 26 00, Finland 09 725 725 11,
France 01 48 14 24 24, Germany 089 741 31 30, Greece 30 1 42 96 427
Hong Kong 2645 3186, India 91805275406, Israel 03 6120092,
Italy 02 413091, Japan 03 5472 2970, Korea 02 596 7456,
Mexico (D.F.) 5 280 7625, Mexico (Monterrey) 8 357 7695,
Netherlands 0348 433466, Norway 32 27 73 00, Singapore 2265886,
Spain (Barcelona) 93 582 0251, Spain (Madrid) 91 640 0085,
Sweden 08 587 895 00, Switzerland 056 200 51 51,
Taiwan 02 2377 1200, United Kingdom 01635 523545

Glossary

| Prefix | Meanings | Value |
|--------|----------|-----------|
| μ- | micro- | 10^{-6} |
| m- | milli- | 10^{-3} |
| k- | kilo- | 10^3 |
| M- | mega- | 10^6 |

A

absolute date
absolute time

Numeric system Lookout uses for keeping track of dates and times, in which midnight (0 hours), January 1, 1900 is represented by 1, midnight of January 2, 1900 is represented by 2, and so on. The absolute date/time number 36234.47222250 represents 11:20 AM, March 15, 1999.

The numeric value for 1 second in Lookout is .000011574, the numeric value for 1 minute is .000694444, and the numeric value for 1 hour is .041666667.

ACK

Acknowledge (an alarm or event).

active notification

A feature of event-driven software systems in which the application is alerted of value changes when they occur instead of through continuous, loop-driven queries.

address space

An OPC term for the area you browse to find what items are available on an OPC server. Part of the standard OPC interface, this space may arrange items hierarchically.

alarm

Software notification of a condition in a process. This alarm may call attention of a value that has exceeded or fallen below certain levels, set in the object database or in an Alarm object.

alias Name given to a data member using the **Edit Database** dialog box. This name can be descriptive or mnemonic, and may be associated with other data member configurations such as scaling, logging, and alarming. A data member can have more than one alias, each with different associated configurations.

B

baud rate Measurement of data transmission speed, formally defined as the number of electronic state changes per second. Because most modems transmit four bits of data per change of state, is sometimes misused or misunderstood—a 300 baud modem is moving 1200 bits per second. See [BPS](#).

.bmp files Graphic files in bitmap format. If you are using a .bmp file in Lookout, you cannot resize it on screen. See [Windows metafile](#).

BPS Bits per second—measure of the rate of transfer of data.

C

CBL compiler Lookout uses the CBL (Control Block Language) compiler to compile a Lookout source file (.lks) into a binary file (.l4p).

.cbx file A Lookout file containing a Lookout object class. A .cbx (Control Block Extension) file may have one or more object classes in it.

checksum A method of verifying that the number of bits received is the same as the number of bits transmitted. Used by TCP/IP and serial protocols.

Citadel The Lookout historical database that stores your data for access later.

classes See [object classes](#).

client A Lookout process that monitors a Lookout server process. Lookout clients should be computer independent so that they can be run from any computer on your network. Lookout server processes run on computers actually connected to your control hardware.

comm port Term sometimes used for a serial port.

connection Input to a Lookout object's writable data members. For more information, refer to Chapter 4, *Using Lookout*.

| | |
|----------------------|--|
| control objects | Lookout objects you use to control a process, change a data value, adjust a register, and so on. |
| controllable objects | Lookout objects you can control with a Lookout control object. |
| .csv files | Comma Separated Value file, a format widely accepted by spreadsheet and other data handling programs. |
| CTS | Clear to Send. Part of a handshaking protocol for certain devices that connect the serial port of a computer. See the <i>RTS/CTS Handshaking Settings</i> section of Chapter 3, <i>Serial Port Communications</i> , in the <i>Lookout Developer's Manual</i> for detailed information. |
| cursor (data table) | The Lookout data table can activate one row of data at a time using the data table cursor. See the data table reference in the Lookout online help or the <i>Lookout Object Reference Manual</i> . |

D

| | |
|-------------|--|
| DAQ | Short for Data AcQuisition. |
| data member | Data source or sink associated with a Lookout object. A readable data member, or source, may be used in expressions or as inputs to other objects. A writable data member, or sink, may have at most one connection into it, created using the Object»Edit Connections dialog box. A data member may be both readable and writable. See also native data member and alias . |
| data type | Kind of value (numeric, logical, or text) that a parameter or data member can hold. |
| database | Collection of data stored for later retrieval, display, or analysis. |
| datagram | Message sent between objects in Lookout. A datagram contains a route and a value. |
| DCOM/COM | Distributed Component Object Model, a Microsoft standard in which client program objects request services from server program objects. The Component Object Model (COM) is a set of interfaces, clients, and servers used to communicate within the same computer (running Windows 98/95 or Windows NT). |

| | |
|----------------------|--|
| DDE | Dynamic Data Exchange, currently used in Lookout to exchange data with other programs (such as Microsoft Excel) running on your network. |
| deadband | A value that must be exceeded for an alarm to sound or a change in state to be recorded. For instance, if you have a low-level alarm set at 5 with a deadband of 2, the alarm will not trigger until the value being monitored drops to 5. The alarm will then stay active until the value being monitored moves above 7. A deadband keeps small oscillations of value from triggering an alarm and then canceling it too rapidly. |
| deviation | Set a deviation to filter out small changes in value when logging data. Before being logged to a database, a value must change by at least the deviation amount of the last logged value. |
| dialing prefix | Part of the Hayes AT command set for use with modems. See the Dial-Up Modem Settings section of Chapter 3, <i>Serial Port Communications</i> , in the <i>Lookout Developer's Manual</i> for detailed information. |
| displayable objects | A Lookout object class that has a displayable component, such as a Pot, a Switch, or a Pushbutton. |
| DLL | A Dynamic Link Library, which is a collection of small, special purpose programs which can be called by a larger program running on the computer. Sometimes called Dynamically Linked Library. |
| driver objects | Lookout objects used to communicate with PLCs, RTUs, and other I/O devices. |
| E | |
| edit mode | Lookout mode in which you can alter and create objects within a process. Switch in and out of edit mode by pressing <Ctrl-space> or by selecting Edit»Edit Mode . |
| engineering unit | In Lookout, used to refer to scaled or converted data. Thermocouple data, for instance, arrives in volts as the raw unit, and must be converted to degrees, an engineering unit. |
| environment services | Tasks Lookout performs as a part of making your SCADA/HMI work easier. Lookout environment services include serial communications, database and logging, security, networking, alarming, and so on. |

| | |
|----------------------|---|
| Ethernet | A widely used, standardized local area networking technology, specified in the IEEE 802.3 standard. |
| event | Anything that happens can be an event. In Lookout, events include such things as adjusting a control value, entering or exiting edit mode, opening or closing a control panel, and logging in or logging out of the system. |
| expression functions | Mathematical, logical, and other functions used by Lookout expressions. |
| expressions | Lookout expressions are often paths to a data member. They can also function like variables that, using a spreadsheet cell type formula, become capable of performing flexible, real-time math operations, condition testing, and other complex operations functions. See Chapter 1, <i>Expressions</i> , in the <i>Lookout Developer's Manual</i> for more information on expressions. |
| F | |
| failover | A failover is the takeover of a process by a standby computer when the primary computer fails for any reason. |
| FieldBus | An all digital communication network used to connect process instrumentation and control systems. |
| FieldPoint | A National Instruments hardware product line for industrial automation, control, monitoring, and reporting. |
| frame | Sequence of bytes sent from a computer to a device or vice versa. The syntax of the frame depends on the protocol being used. A read frame contains enough information to specify a set of variables whose values the device should return. A write frame specifies a variable in the device and a new value to write into that variable. Some protocols support the writing of multiple variables in a single frame. A response frame is returned from the device to the computer, indicating whether the frame just sent to it was received successfully. If the frame just received was a read frame, the response frame contains a set of requested values. |
| functionality | The way an object works, operates, or performs a task. Functionality is a general concept that applies in the same way to all objects in a given object class. Parameters define the specific functionality of an individual object. |
| functions | <i>See</i> expression functions . |

G

gray proximity A term used in Lookout color animation. This sets what percentage of gray will be replaced by a given color as conditions change in a monitored value or set of values.

H

Hi and HiHi Alarm settings. Both warn that a value has gone above some setpoint. Generally a Hi alarm is used to alert an operator of a need for intervention. A hihi alarm is usually used to alert an operator that the value has been exceeded by an even greater margin than a hi alarm indicates, and is usually used to indicate an urgent need for action.

historical logging The process of storing data in a database for use at another time, or from another location.

HOA Hand-Off-Auto control, used to set whether a value must be changed manually, is completely turned off, or functions automatically. You can use a Pot object and a complex expression to create this sort of control in Lookout, or you can use a RadioButton object, depending on the particular requirements of the task you need to accomplish.

I

I/O point Every read-only, write-only, or read-write connection Lookout makes to external hardware is counted as an I/O point. Lookout is licensed for use with a set number of I/O points. If you exceed the number you are licensed to use with your copy of Lookout, a warning message appears on your computer screen warning you to shut down one of your processes within a specified time before Lookout cuts back on I/O usage.

(implicit) data member A Lookout data member containing the fundamental data for certain object classes. When you make a connection to an (implicit) data member, you only use the name of the object, not the name of the object followed by the data member name.

L

| | |
|---------------------|--|
| .14p files | File extension for Lookout process files. These are the compiled files Lookout runs when it runs a process. |
| .14t files | File extension for a Lookout state file, which stores the values for Lookout controls and other objects with state information. |
| .1ka files | File extension for Lookout security files. |
| .1kp files | File extension for Lookout process files in versions of Lookout earlier than Lookout 4. |
| .1ks files | File extension for a Lookout source file, which Lookout compiles to make a Lookout process file that Lookout can run. This is the file you should make sure you keep backed up in case you need to recreate a corrupted process file, or in case some future version of Lookout cannot run a process file compiled in an earlier version of Lookout. |
| logging | The process of storing data in a computer database file. See Chapter 7, <i>Logging Data and Events</i> , in the <i>Lookout Developer's Manual</i> for more information on logging data in Lookout. |
| logical data member | A Lookout data member of the logical data type. |
| .1st files | Extension for the Lookout state file in versions of Lookout earlier than Lookout 4. |

M

| | |
|-----------|---|
| multiplex | A method of working with more than one data stream using only one communications channel. There are a number of different methods of multiplexing, depending on the hardware and software being used. A number of Lookout driver objects support multiplexing hardware. |
|-----------|---|

N

- native data member Data members built into a Lookout object class, as opposed to data members you create by using aliases.
- NetDDE A way of networking using DDE (dynamic data exchange), retained in Lookout 4 and later for compatibility with earlier versions of Lookout.
- numeric data member A Lookout data member of the numeric data type.

O

- object A specific instance created from an object class.
- object classes Software modules you use to create individual objects to perform tasks in Lookout.
- object connections Software links between objects used to transmit data and commands from one object to another.
- ODBC Open DataBase Connectivity, a standard application programming interface (API) for accessing a database. You can use ODBC statements to access files in a number of different databases, including Access, dBase, DB2, and Excel.
- ODBC is compatible with the Structured Query Language (SQL) Call-Level Interface. ODBC handles SQL requests by converting them into requests an ODBC database can use.
- OPC OLE for Process Control, an industry standard interface providing interoperability between disparate field devices, automation/control systems, and business systems. Based on ActiveX, OLE, Component Object Model (COM), and Distributed COM (DCOM) technologies.

P

- parameter Input to an object, similar to a writable data member, whose value is specified in the object parameter list in a Lookout source (.lks) file. Typically, parameter values are set in the object **Object»Create** or **Object»Modify** dialog box.

| | |
|--------------|---|
| ping | A small utility program in Windows and DOS that checks to see if a computer can be reached across a network. Also used to indicate the running of that program. |
| pixel | Picture Element, the smallest bit of a picture. Has one color or shade of grey. The number of pixels per inch determine the resolution of an image. |
| PLC | Programmable Logic Controller. |
| poll | A software event in which a computer checks some value in a device or register. In Lookout, a logical command that forces a device poll to check data member values. |
| poll rate | How often a device is polled. |
| pop-up panel | One variety of Lookout control panel that can only be displayed at the size set by the process developer, and which cannot be maximized. When open, a popup panel remains on top of other panels until minimized. |
| process | In Lookout, process refers to a Lookout “program,” used for industrial automation, control, monitoring, or reporting. |
| process file | The Lookout binary file Lookout executes when running a process. Carries the .14p extension. |

R

| | |
|-------------|--|
| raw unit | Data as it arrives in your process, such as voltage or amperage. Thermocouple data, for instance, arrives in volts as the raw unit, and must be converted to degrees, an engineering unit. |
| receive gap | A serial communications setting that determines the number of empty bytes (or amount of time) a driver receives before recognizing the end of a message frame and requesting another message. See the <i>Setting Receive Gap</i> section of Chapter 3, <i>Serial Communications</i> , in the <i>Lookout Developer's Manual</i> for more information about the receive gap. |
| redundancy | A system for making sure that a computer can come online and run a Lookout process if the computer currently running that process fails for some reason. |

| | |
|-------------------|---|
| remote | In the context of Lookout, remote is a position source location for a control. See the <i>Remote Position Source Connections</i> section of Chapter 4, <i>Using Lookout</i> , for detailed information on the Lookout remote position source. |
| resolution | The smallest signal increment that can be detected by a measurement system. Also, the number of pixels per inch on a computer monitor screen or dots per inch in printer output. |
| RTS | Request to Send, part of a handshaking protocol for certain devices that connect the serial port of a computer. See the <i>RTS/CTS Handshaking Settings</i> section of Chapter 3, <i>Serial Communications</i> , in the <i>Lookout Developer's Manual</i> for detailed information. |
| RTU | Remote Terminal Unit, a device similar to a PLC for use at a remote location, communicating with a host system through radio or telephonic connections. |
| run mode | Lookout mode in which processes run but no editing changes can be made. Switch in and out of run mode by pressing <Ctrl-space> or selecting Edit»Edit Mode . |
| S | |
| SCXI | Signal Conditioning eXtensions for Instrumentation, a National Instruments product line for conditioning low-level signals. |
| security accounts | Also called user and group accounts, Lookout uses security accounts to define what users or group of users have different operation privileges in Lookout. See Chapter 6, <i>Security</i> , in the <i>Lookout Developer's Manual</i> for detailed information on Lookout security. |
| server | A process that provides data (services) to client processes. In Lookout, server processes are intended to be run on one computer only, with direct connections to field hardware. Client processes interact with field hardware through server processes. |
| source file | Lookout file that can be compiled to produce a binary Lookout process file that runs a process. Uses a <code>.lks</code> file extension. |
| SQL | Structured Query Language, used to get information from and update information in a database. |

| | |
|----------------|---|
| standby | A computer standing by to take over running a process if the primary computer fails or falls offline. |
| startup file | A Lookout process file (.14p) you designate in the System Options dialog box that Lookout will open and run any time Lookout is opened. |
| state file | The Lookout file that stores the value of all Lookout control parameters and object data members in use in a process. Uses the file extension .14t. |
| system objects | Lookout objects used to control other objects or process and analyze data. |

T

| | |
|------------------|---|
| TCP TCP/IP | Transmission Control Protocol, a method (protocol) for sending data between computers. Used with IP, the Internet Protocol. TCP/IP sends data as packets, with IP handling the delivery of data and TCP keeping track of the individual packets. |
| text data member | Lookout data member used for text data. |
| trace | A term for data from a single source over some period of time, stored in an ODBC-compliant database. |
| traces table | ODBC databases present data in the form of traces tables. A traces table contains a field or column of data for each data member being logged, along with a field you can use to query the database. |
| trend | Historical data showing the change in a value over time. Often used in connection with graphing the data for display. |

W

| | |
|------------------|---|
| .wav files | File extension given to sound files. You can play a .wav file in Lookout to add sounds or speech to alarms or events. |
| Windows metafile | A standard graphics file type for use in the Microsoft Windows operating environment. If you use a metafile graphic in Lookout, you can enlarge or reduce it on the screen, use them as masks without specifying transparent pixels, and use the Lookout Animator to animate the colors of the graphic. |
| .wmf file | File extension given to Windows Metafile graphic files. |

X

`.xls` file

File extension given to Microsoft Excel files.

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