

Serial

Getting Started with Your PXI Serial Hardware and Software for Windows 2000

Worldwide Technical Support and Product Information

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Compliance

FCC/Canada Radio Frequency Interference Compliance*

Determining FCC Class

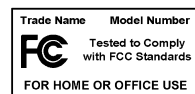
The Federal Communications Commission (FCC) has rules to protect wireless communications from interference. The FCC places digital electronics into two classes. These classes are known as Class A (for use in industrial-commercial locations only) or Class B (for use in residential or commercial locations). Depending on where it is operated, this product could be subject to restrictions in the FCC rules. (In Canada, the Department of Communications (DOC), of Industry Canada, regulates wireless interference in much the same way.)

Digital electronics emit weak signals during normal operation that can affect radio, television, or other wireless products. By examining the product you purchased, you can determine the FCC Class and therefore which of the two FCC/DOC Warnings apply in the following sections. (Some products may not be labeled at all for FCC; if so, the reader should then assume these are Class A devices.)

FCC Class A products only display a simple warning statement of one paragraph in length regarding interference and undesired operation. Most of our products are FCC Class A. The FCC rules have restrictions regarding the locations where FCC Class A products can be operated.

FCC Class B products display either a FCC ID code, starting with the letters **EXN**, or the FCC Class B compliance mark that appears as shown here on the right.

Consult the FCC web site <http://www.fcc.gov> for more information.



FCC/DOC Warnings

This equipment generates and uses radio frequency energy and, if not installed and used in strict accordance with the instructions in this manual and the CE Mark Declaration of Conformity**, may cause interference to radio and television reception. Classification requirements are the same for the Federal Communications Commission (FCC) and the Canadian Department of Communications (DOC).

Changes or modifications not expressly approved by National Instruments could void the user's authority to operate the equipment under the FCC Rules.

Class A

Federal Communications Commission

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

Canadian Department of Communications

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Cet appareil numérique de la classe A respecte toutes les exigences du Règlement sur le matériel brouilleur du Canada.

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Federal Communications Commission

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.

- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

Canadian Department of Communications

This Class B digital apparatus meets all requirements of the Canadian Interference-Causing Equipment Regulations.

Cet appareil numérique de la classe B respecte toutes les exigences du Règlement sur le matériel brouilleur du Canada.

European Union - Compliance to EEC Directives

Readers in the EU/EEC/EEA must refer to the Manufacturer's Declaration of Conformity (DoC) for information** pertaining to the CE Mark compliance scheme. The Manufacturer includes a DoC for most every hardware product except for those bought for OEMs, if also available from an original manufacturer that also markets in the EU, or where compliance is not required as for electrically benign apparatus or cables.

* Certain exemptions may apply in the USA, see FCC Rules §15.103 **Exempted devices**, and §15.105(c). Also available in sections of CFR 47.

** The CE Mark Declaration of Conformity will contain important supplementary information and instructions for the user or installer.

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About This Manual

This manual contains instructions to help you install and configure the National Instruments serial hardware and the NI-Serial software for Windows 2000. This manual includes information about the RS-232 boards (PXI-8420 two, four, and eight-port, and PXI-8422 two and four-port) and the RS-485 boards (PXI-8421 two, four, and eight-port, and PXI-8423 two and four-port).

This manual assumes that you are already familiar with Windows 2000.

Conventions

The following conventions appear in this manual:

»

The » symbol leads you through nested menu items and dialog box options to a final action. The sequence **File»Page Setup»Options** directs you to pull down the **File** menu, select the **Page Setup** item, and select **Options** from the last dialog box.



This icon denotes a note, which alerts you to important information.



This icon denotes a caution, which advises you of precautions to take to avoid injury, data loss, or a system crash.

bold

Bold text denotes items that you must select or click on in the software, such as menu items and dialog box options. Bold text also denotes parameter names.

DTR

Signal names with an overscore, such as DTR, indicate that the signal is active low.

italic

Italic text denotes variables, emphasis, a cross reference, or an introduction to a key concept. This font also denotes text that is a placeholder for a word or value that you must supply.

monospace

Text in this font denotes text or characters that you should enter from the keyboard, sections of code, programming examples, and syntax examples. This font is also used for the proper names of disk drives, paths, directories, programs, subprograms, subroutines, device names, functions, operations, variables, filenames and extensions, and code excerpts.

monospace bold Bold text in this font denotes the messages and responses that the computer automatically prints to the screen. This font also emphasizes lines of code that are different from the other examples.

PXI serial boards *PXI serial boards* refers to all port versions of the PXI serial boards.

Related Documentation

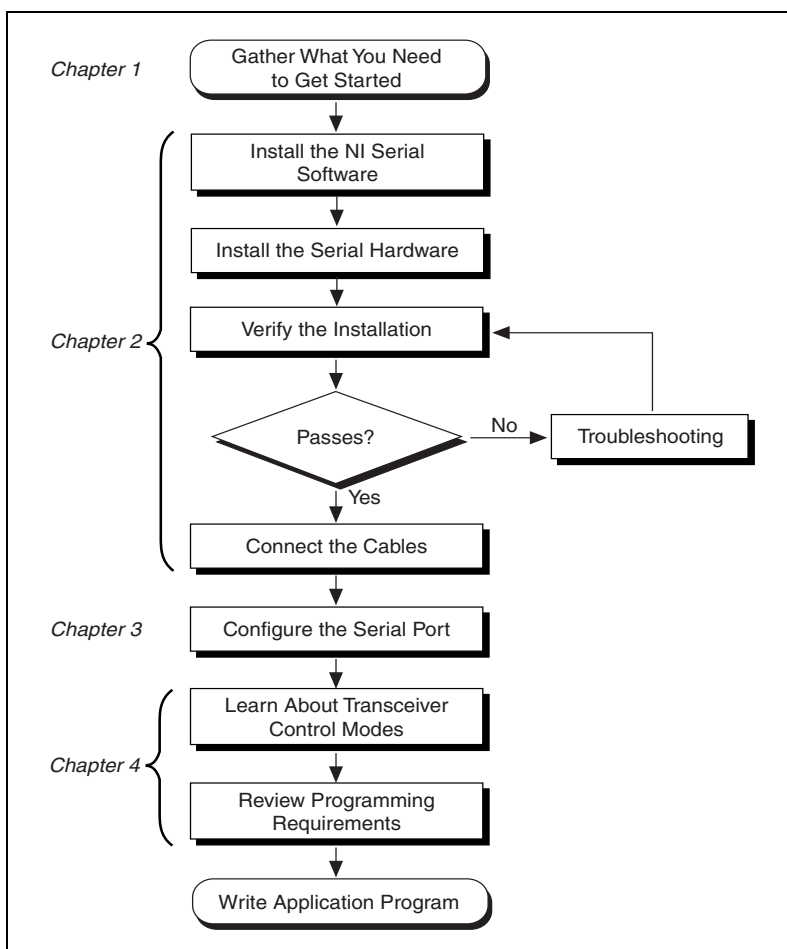
The following documents contain information that you might find helpful as you read this manual:

- ANSI/EIA-232-D Standard, *Interface Between Data Terminal Equipment and Data Circuit-Terminating Equipment Employing Serial Binary Data Interchange*
- EIA/RS-422-A Standard, *Electrical Characteristics of Balanced Voltage Digital Interface Circuits*
- EIA-485 Standard, *Standard for Electrical Characteristics of Generators and Receivers for Use in Balanced Digital Multipoint Systems*
- *Microsoft Win32 Software Developer Kit*, Online Documentation for *Win32 Overviews*, *Win32 Reference*, and *Microsoft Windows NT System Guide*, Microsoft Corporation
- *NS16550AF Universal Asynchronous Receiver/Transmitter with FIFOs*, National Semiconductor
- *ST16C654 Asynchronous Receiver/Transmitter with FIFOs*, EXAR Corporation

Introduction

This chapter explains how to use this manual, lists what you need to get started and optional equipment you can order, and briefly describes the serial hardware and the NI-Serial software.

How to Use This Manual



What You Need to Get Started

Before you install your serial hardware and the NI-Serial software, make sure you have all of the following items:

- Windows 2000 installed on your computer
- One of the following serial boards, which is included in your kit:
 - PXI-8420 (two, four, or eight port)
 - PXI-8421 (two, four, or eight port)
 - PXI-8422 (two or four port)
 - PXI-8423 (two or four port)
- CD, *NI-Serial Software for Windows 2000/NT/Me/9x*, which is included in your kit

Optional Equipment

For more information about ordering the following optional equipment, contact National Instruments:

- DB-9 RS-485 termination connector (RS-485 (PXI-8421 and PXI-8423 only))
- 10-position modular jack to DB-9 cable (four-port boards only)
- 10-position modular jack to DB-25 cable (four-port boards only)
- 68-pin to DB-9 adapter cable (eight-port boards only)
- RS-232 9-pin to 9-pin null modem cable
- RS-232 9-pin to 25-pin null modem cable
- RS-485 9-pin to 9-pin null modem cable

Serial Hardware Overview

The serial hardware gives you a variety of solutions for serial communication. The RS-232 boards (PXI-8420 and PXI-8422) work with the RS-232 protocols. The RS-485 boards (PXI-8421 and PXI-8423) work with the RS-422 and RS-485 protocols. You can use the RS-232 boards for serial communication up to distances of 50 ft. You can connect the RS-485 boards to up to 31 devices using serial cable lengths up to 4,000 ft.

Additionally, the PXI serial boards are available in a two-port version, a four-port version, and an eight-port version (PXI-8420 and PXI-8421 only). The two-port versions use DB-9 connectors. The four-port versions use 10-position modular jacks to provide all four connections on a single front panel. Optional cable accessories convert the 10-position modular jacks to either DB-9 or DB-25 connectors with standard pinouts. The eight-port versions use two different adapter cables to convert the 68-pin connector on the board to eight DB-9 connectors. Throughout this manual, *PXI serial boards* refers to all versions of the PXI serial boards.

The isolated PXI boards are designed for applications in harsh environments. Isolated ports provide reliable communication in situations involving ground loops from different ground levels or high common mode voltage induced on the lines in noisy environments. Non-isolated ports may not provide reliable communication in those situations. The isolation between each communication port and the host PC ensures the safe operation of the PC and the devices connected to other ports on the same board, in case of accidental high voltages on communication lines.

The RS-485 boards (PXI-8421 and PXI-8423) support four hardware transceiver control modes for reliable communication with two- and four-wire devices. For more information about transceiver control modes, refer to Chapter 4, *Using Your Serial Hardware*.

All serial hardware uses standard 16550-compatible UARTs (Universal Asynchronous Receiver/Transmitters) for complete compatibility with standard PC COM ports. The serial hardware contains FIFOs (First-In-First-Out) buffers to reduce susceptibility to interrupt latency for faster transmission rates. Full Plug and Play compatibility allows switchless configuration and installation. For more information about the serial hardware specifications and operating conditions, refer to Appendix D, *Specifications*.

Table 1-1 lists the PXI serial board numbers and corresponding board descriptions.

Table 1-1. PXI Board Names and Descriptions

| PXI Board Name | Description |
|----------------|--|
| PXI-8420 | RS-232 2-port RS-232 4-port RS-232 8-port |
| PXI-8421 | RS-485 2-port RS-485 4-port RS-485 8-port |
| PXI-8422 | RS-232 2-port isolated RS-232 4-port isolated |
| PXI-8423 | RS-485 2-port isolated RS-485 4-port isolated |

NI-Serial Software Overview

The NI-Serial software for Windows 2000 includes a native Windows device driver that provides full interrupt-driven, buffered I/O for multiple COM ports. You can obtain a maximum baud rate of 460.8 KBaud. You can also use up to 256 serial ports under Windows 2000. The NI-Serial software also includes a configuration utility, which is fully integrated into the Windows 2000 Device Manager. For more information about software specifications, refer to Appendix D, *Specifications*.

The NI-Serial software includes the following components:

- Device driver
- Diagnostic utility
- Configuration utility
- Product manuals

The NI-Serial software supports all National Instruments serial hardware, including the AT, PCI, PXI/CompactPCI, and PCMCIA versions.

Time-Saving Development Tools

Your kit includes the NI-Serial software for Windows 2000. In addition, you can order the LabWindows/CVI or LabVIEW software from National Instruments to speed your application development time and make it easier to communicate with your instruments.

LabVIEW is an easy-to-use, graphical programming environment you can use to acquire data from thousands of different instruments, including IEEE 488.2 devices, VXI devices, serial devices, PLCs, and plug-in data acquisition boards. After you have acquired raw data, you can convert it into meaningful results using the powerful data analysis routines in LabVIEW. LabVIEW also comes with hundreds of instrument drivers, which dramatically reduce software development time, because you do not have to spend time programming the low-level control of each instrument.

LabWindows/CVI is similar to LabVIEW, except that it combines an interactive, easy-to-use development approach with the programming power and flexibility of compiled ANSI C code.

For ordering information, or to request free demonstration software, contact National Instruments.

Using Your Serial Hardware with LabVIEW and LabWindows/CVI

After you install your serial hardware and the NI-Serial software, you can use standard serial I/O functions in LabVIEW and LabWindows/CVI with your serial interface. If you already have LabVIEW or LabWindows/CVI and want to use it with your serial hardware, refer to your LabVIEW or LabWindows/CVI documentation for information about serial I/O functions.

Installation and Verification

This chapter describes how to install the NI-Serial software, serial hardware, and cables, and how to verify the installation.

Install the Software

Before you install your serial hardware, complete the following steps to install the NI-Serial software for Windows 2000:

1. Select **Start»Settings»Control Panel**.
2. Double-click on the **Add/Remove Programs** icon. A dialog box similar to the one shown in Figure 2-1 appears.

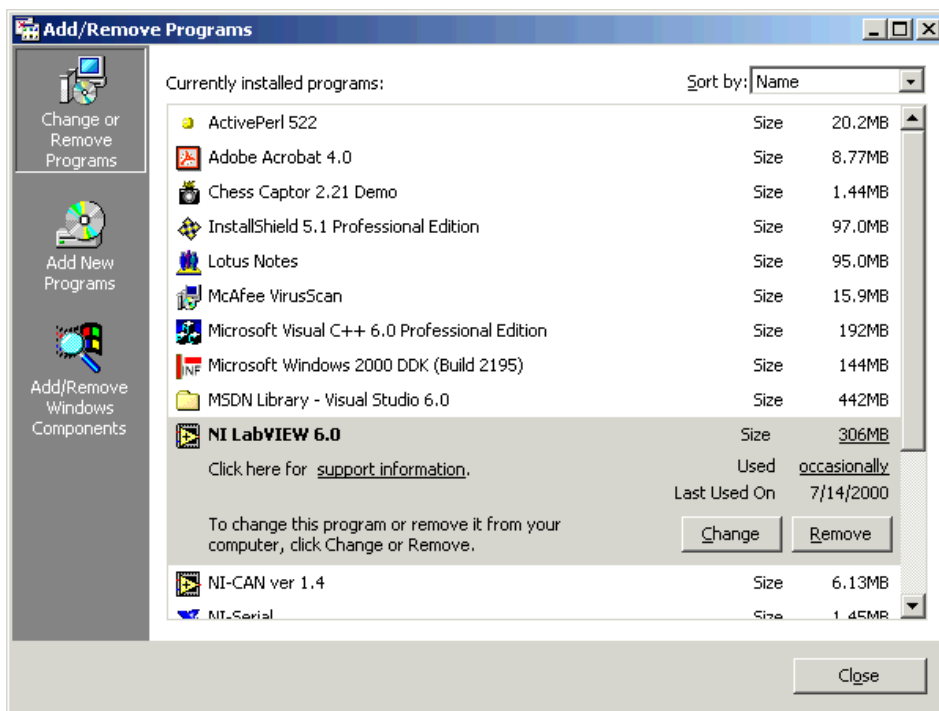


Figure 2-1. Add/Remove Programs Dialog Box

3. Click on the **Add New Programs** button and then the **CD or Floppy** button.
4. When prompted, insert the *NI-Serial Software for Windows 2000/NT/Me/9x* CD and click on the **Next** button.
5. When prompted, click on the **Finish** button to install the program files from the CD.
6. The setup wizard begins with the screen shown in Figure 2-2.

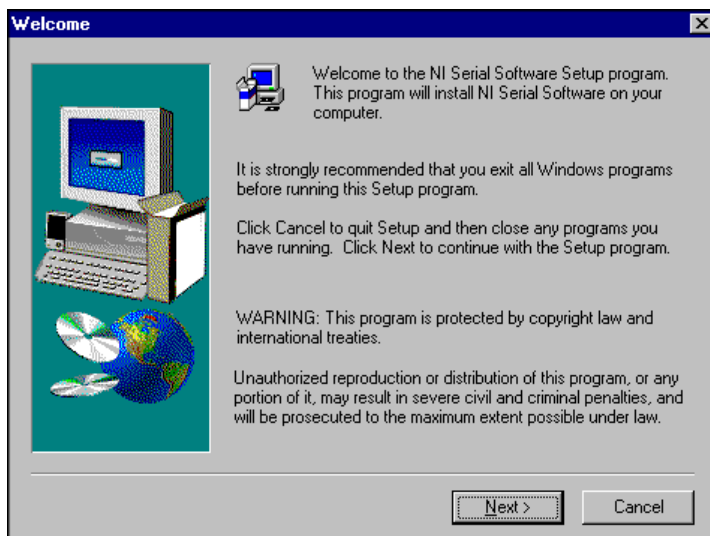


Figure 2-2. NI-Serial Setup Screen

The setup wizard guides you through the necessary steps to install the NI-Serial software. To exit the setup wizard at any time, click on the **Cancel** button.

7. If you need to install your hardware, or if this is your first time to install the NI-Serial software for Windows 2000, skip to the next section, [Install the Hardware](#). Otherwise, continue to step 8.
8. If your hardware is already installed, restart Windows 2000.
9. Windows 2000 should automatically detect your hardware and display the Found New Hardware Wizard. Complete the wizard by clicking **Next** in each window and then **Finish**. When you complete the wizard, continue to the [Verify the Installation](#) section.

If the Found New Hardware Wizard does not appear, refer to the [Forcing Windows to Detect Your Hardware](#) section in Appendix C, [Troubleshooting and Common Questions](#).

Install the Hardware



Caution Before you remove your board from the package, touch the antistatic plastic package to a metal part of your system chassis to discharge electrostatic energy, which can damage several components on your serial board.

To install your PXI serial board, complete the following steps:

1. Turn off your PXI or CompactPCI chassis. Keep the chassis plugged in so that it remains grounded while you install the PXI serial board.
2. Find an unused PXI or CompactPCI 5 V peripheral slot.
3. Remove the corresponding filler panel.
4. Touch a metal part on your chassis to discharge any static electricity.
5. Insert the PXI serial board into the 5 V slot. Use the injector/ejector handle to fully inject the device into place. Figure 2-3 shows how to install the PXI serial board into a PXI or CompactPCI chassis.

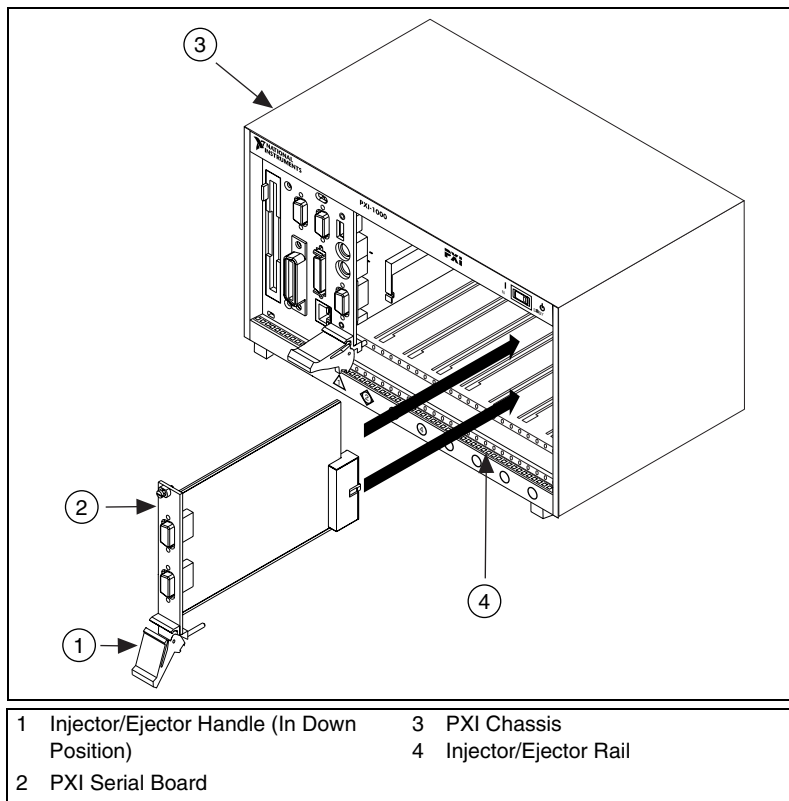


Figure 2-3. Installing the PXI Serial Board

6. Screw the PXI serial board front panel to the front panel mounting rail of the PXI or CompactPCI chassis.
7. Turn on your PXI or CompactPCI chassis and start Windows 2000.
8. Windows 2000 should automatically detect your hardware and display the Found New Hardware Wizard. Complete the wizard by clicking **Next** in each window and then **Finish**.

If the Found New Hardware Wizard does not appear, refer to the [Forcing Windows to Detect Your Hardware](#) section in Appendix C, *Troubleshooting and Common Questions*.

The serial hardware installation is complete. Continue to the next section, [Verify the Installation](#).

Verify the Installation

To verify the hardware and software installation, complete the following steps:

1. Select **Start»Settings»Control Panel** and double-click on the **System** icon.
2. Click on the **Hardware** tab and click on the **Device Manager** button.
3. Double-click on the **Ports (COM & LPT)** icon to display all of the ports.
4. Double-click on the **Multi-function adapters** icon.

The PXI serial boards are configured as devices belonging to the *multi-function adapters* class. The multi-function parent device is listed under the **Multi-function adapters** icon, and each child device is listed as a port under the **Ports (COM & LPT)** icon.

Figure 2-4 shows the Device Manager tab for serial hardware that is installed properly.

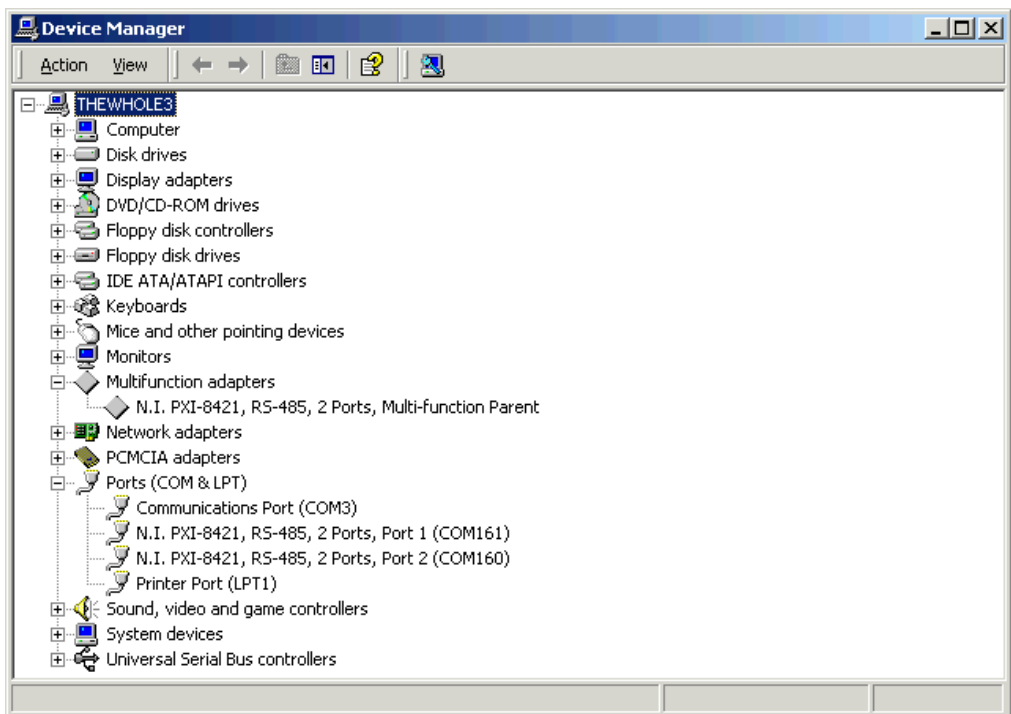


Figure 2-4. Device Manager for PXI Serial Board Ports

5. Verify the hardware resources, as follows:
 - a. In the Device Manager under **Multi-function adapters**, double-click on a serial board.
 - b. Click on the **Resources** tab. If the resources were assigned properly, the **Resources** tab shows which resources are assigned to your serial ports.
 - c. Repeat steps 5a and 5b until you have verified the resources for each board.
6. (Optional) To determine which physical port is associated with COMx, note the Port 1, Port 2, etc. entries next to the COM numbers. For all serial hardware, PORT1 refers to the top port, PORT2 refers to the next port down, and so on.
7. Run the diagnostic utility, as follows: select **Start»Programs»National Instruments»NI-Serial»Diagnostics**.

The diagnostic utility verifies that your serial driver is installed properly, that the configuration of your hardware does not conflict with anything else in your system, and that the serial driver can communicate with your hardware correctly.

If the test is successful, your serial hardware and software are installed properly. If the test fails, refer to Appendix C, *Troubleshooting and Common Questions*, to troubleshoot the problem.

After you verify the hardware and software installation, continue to the next section, *Connect the Cables*.

Connect the Cables

For the two-port PXI serial boards, you can use the standard DB-9 connector found on most serial cables. To use the DB-9 connector with the four-port PXI serial boards, you need the 10-position modular jack to DB-9 cable, which is available from National Instruments. You can also use a DB-25 connector with the four-port PXI serial boards by ordering the 10-position modular jack to DB-25 converter cable from National Instruments. The eight-port PXI serial boards include a pig tail cable adapter, providing eight standard DB-9 connectors.

DB-9 Connector

Figure 2-5 and Table 2-1 give the pin locations and descriptions of the DB-9 connector, which is on the two-port PXI serial board, the 10-position modular jack to DB-9 cable, and the cable adapter for the eight-port board.

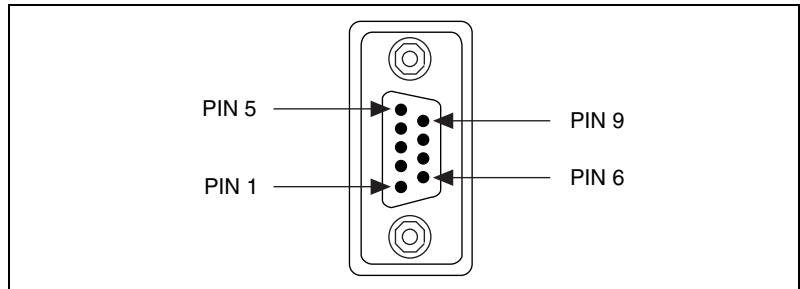


Figure 2-5. DB-9 Connector Pin Locations

Table 2-1. DB-9 Pin Descriptions

| DB-9 Pin | 232 Signal | 485 Signal |
|----------|-------------------------|-------------|
| 1 | DCD* | GND |
| 2 | $\overline{\text{RXD}}$ | CTS+ (HSI+) |
| 3 | $\overline{\text{TXD}}$ | RTS+ (HSO+) |
| 4 | DTR* | RXD+ |
| 5 | GND | RXD- |
| 6 | DSR* | CTS- (HSI-) |
| 7 | RTS | RTS- (HSO-) |
| 8 | CTS | TXD+ |
| 9 | RI* | TXD- |

* These signals are not supported by the isolated 232 boards or ports 9-16 of the RS-232 sixteen-port board.

Modular Jack Connector

Figure 2-6 and Table 2-2 give the pin locations and descriptions of the 10-position modular jack, which is on the four-port PXI serial board.

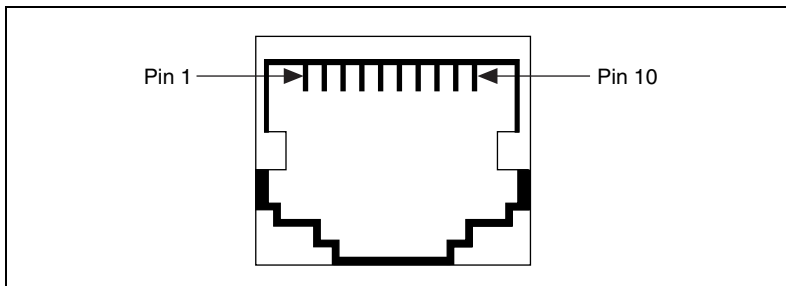


Figure 2-6. 10-Position Modular Jack Pin Locations

Table 2-2. 10-Position Modular Jack Pin Descriptions

| 10-Position Modular Jack Pin | 232 Signal | 485 Signal |
|------------------------------|-------------------------|-------------|
| 10 | DCD* | GND |
| 9 | $\overline{\text{RXD}}$ | CTS+ (HSI+) |
| 8 | $\overline{\text{TXD}}$ | RTS+ (HSO+) |
| 7 | DTR* | RXD+ |
| 6 | GND | RXD- |
| 5 | DSR* | CTS- (HSI-) |
| 4 | RTS | RTS- (HSO-) |
| 3 | CTS | TXD+ |
| 2 | RI* | TXD- |
| 1 | No Connect | No Connect |

* These signals are not supported by the isolated 232 ports.

DB-25 Connector

Figure 2-7 and Table 2-3 give the pin locations and descriptions of the DB-25 connector, which is on the optional 10-position modular jack to DB-25 cable.

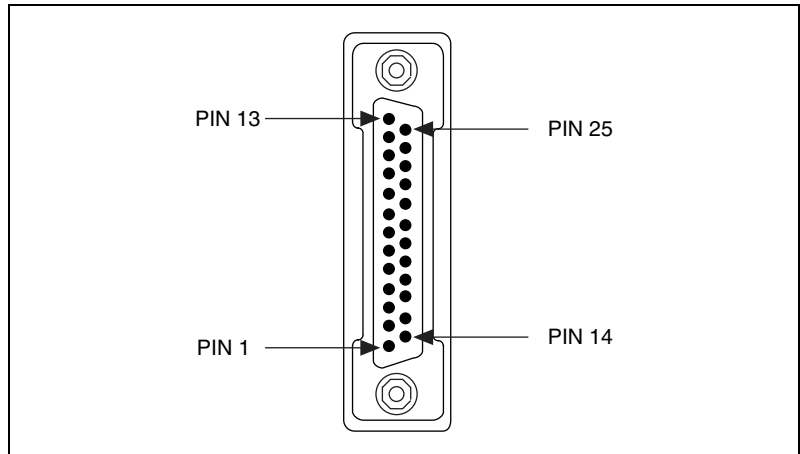


Figure 2-7. DB-25 Connector Pin Locations

Table 2-3. DB-25 Pin Descriptions

| DB-25 Pin | 232 Signal | 485 Signal |
|-----------|-------------------------|-------------|
| 2 | $\overline{\text{TXD}}$ | RTS+ (HSO+) |
| 3 | $\overline{\text{RXD}}$ | CTS+ (HSI+) |
| 4 | RTS | RTS- (HSO-) |
| 5 | CTS | TXD+ |
| 6 | DSR* | CTS- (HSI-) |
| 7 | GND | RXD- |
| 8 | DCD* | GND |
| 20 | DTR* | RXD+ |
| 22 | RI* | TXD- |

Pins not listed in this table are No Connect.
 * These signals are not supported by the isolated 232 ports.

Figure 2-8 shows how to connect the cables when you install a four-port PXI serial board.

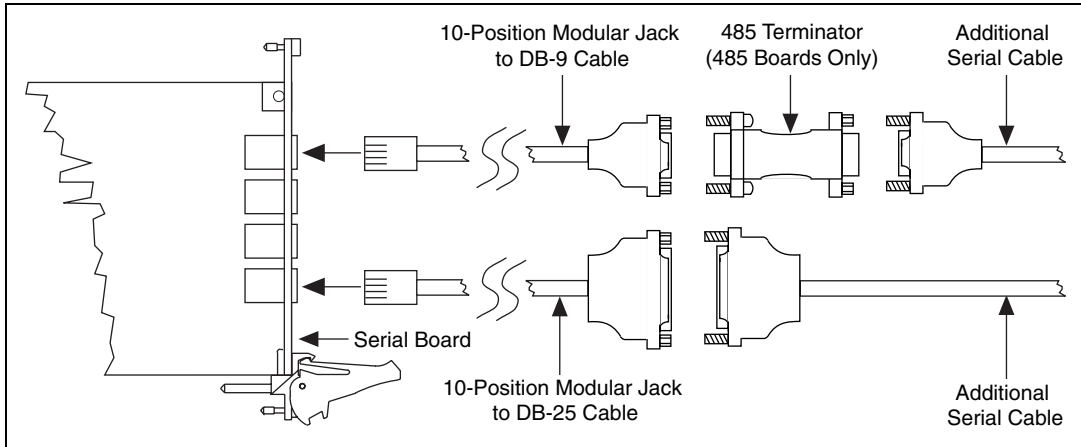


Figure 2-8. Connecting the Cables to Your Four-Port PXI Serial Board

68-Pin Connector

Figure 2-9 and Table 2-4 give the pin locations and descriptions of the 68-pin connector, which is on the eight-port PXI serial board.

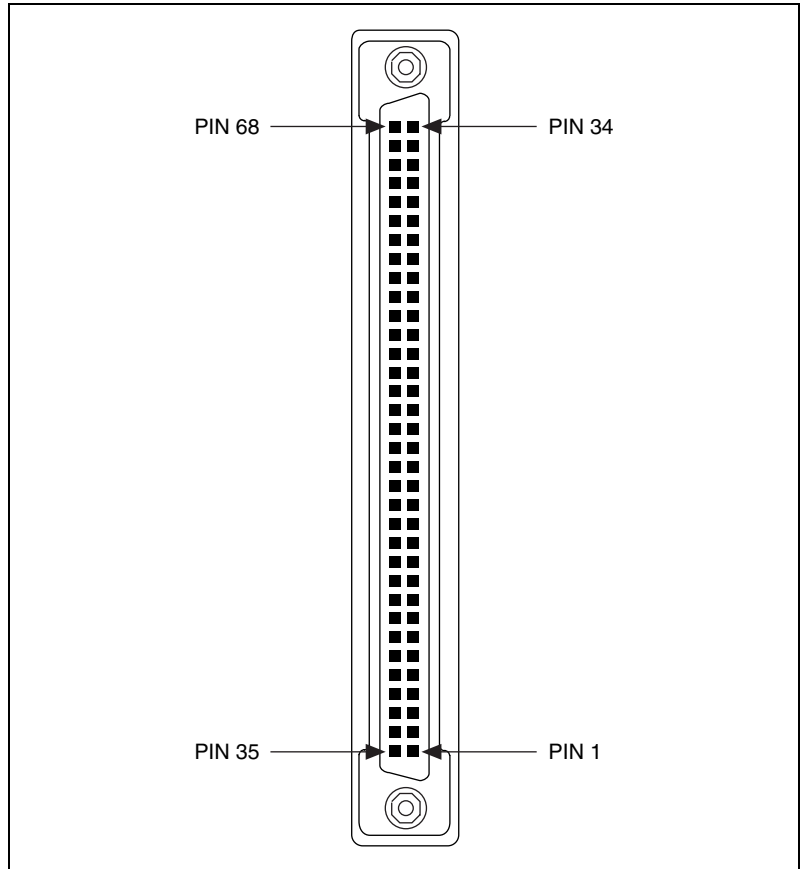


Figure 2-9. 68-Pin Connector Pin Locations

Table 2-4. 68-Pin Connector Pin Descriptions

| 68-Pin Connector Port | | | | | | | | 485 Signal | 485 D-Sub 9 Connector | 232 Signal | 232 D-Sub 9 Connector |
|-----------------------|----|----|----|----|----|----|---|---------------|-----------------------------|-------------------------|-----------------------------|
| 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | | | | |
| 66 | 57 | 49 | 40 | 32 | 23 | 15 | 6 | RXD- | 5 | DCD | 1 |
| 68 | 59 | 51 | 42 | 34 | 25 | 17 | 8 | CTS+ | 2 | $\overline{\text{RXD}}$ | 2 |
| 65 | 56 | 48 | 39 | 31 | 22 | 14 | 5 | RTS+ | 3 | $\overline{\text{TXD}}$ | 3 |
| 64 | 55 | 47 | 38 | 30 | 21 | 13 | 4 | RXD+ | 4 | DTR | 4 |
| 60 | 60 | 43 | 43 | 26 | 26 | 9 | 9 | GND | 1 | GND | 5 |
| 63 | 54 | 46 | 37 | 29 | 20 | 12 | 3 | CTS- | 6 | DSR | 6 |
| 62 | 53 | 45 | 36 | 28 | 19 | 11 | 2 | RTS- | 7 | RTS | 7 |
| 61 | 52 | 44 | 35 | 27 | 18 | 10 | 1 | TXD+ | 8 | CTS | 8 |
| 67 | 58 | 50 | 41 | 33 | 24 | 16 | 7 | TXD- | 9 | RI | 9 |

Connecting Two-Wire Devices

The RS-485 boards (PXI-8421 and PXI-8423) are designed to work with either two- or four-wire devices. If you are using a two-wire device, refer to the device documentation for specific wiring instructions.

In general, half-duplex networks use a single twisted pair of wires for communication in both directions, so you must connect both the transmitter and the receiver at each end of the same pair of wires. For example, to connect an RS-485 data acquisition device to a port on your RS-485 board using half-duplex communication, you need a single twisted pair of wires. At the RS-485 board, connect the TXD+ and RXD+ signals (pins 8 and 4 on a DB-9 connector, pins 5 and 20 on a DB-25 connector) together and to one wire. Connect the other end of this wire to both the TXD+ and RXD+ signals on the data acquisition device. Use the same method to connect the TXD- and RXD- signals (pins 9 and 5 on a DB-9 connector, pins 22 and 7 on a DB-25 connector) to the second wire.

For information about setting the transceiver mode for two-wire communication, refer to Chapter 4, *Using Your Serial Hardware*. For more information about duplex architectures, refer to Appendix A, *Serial Port Information*.

Configuration

This chapter describes how to view or change the communication port settings.

View or Change Communication Port Settings

The serial configuration utility is fully integrated into the Windows 2000 Device Manager. You can use it to view or change the configuration of your serial ports.

To configure a serial port, complete the following steps:

1. Select **Start»Settings»Control Panel** and double-click on the **System** icon.
2. Click on the **Hardware** tab and click on the **Device Manager** button.
3. Double-click on the **Ports (COM & LPT)** icon.
4. Double-click on the port you want to configure and refer to the following instructions:
 - To view the hardware resources assigned to the serial port, click on the **Resources** tab.
 - To view or change the port settings, click on the **Port Settings** tab. For more information about the settings, refer to the next section, *Port Settings Tab*.
 - To change the RS-485 transceiver mode, or to enable or disable the FIFOs on the serial hardware, in the **Port Settings** tab, click on the **Advanced** button. For more information about the settings, refer to the next section, *Port Settings Tab*.



Note Transceiver modes apply to RS-485 interfaces only. For more information about transceiver modes, refer to Chapter 4, *Using Your Serial Hardware*.

5. To save your changes, click on the **OK** button. To exit without saving the changes, click on the **Cancel** button.

Port Settings Tab

In the **Port Settings** tab, you can change any of the settings by clicking on the arrow button to the right of a field. When you click on the arrow button, a list of valid values for that field appears and you can select the desired setting from the list. Figure 3-1 shows the **Port Settings** tab.

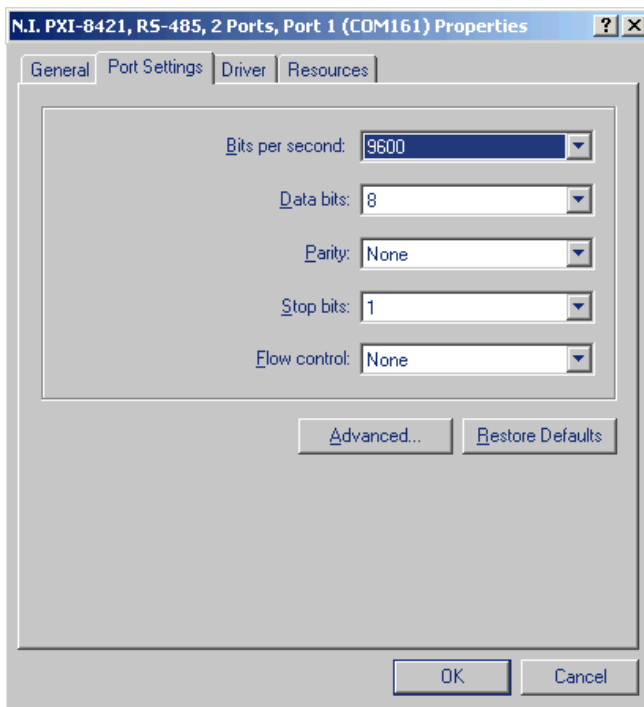


Figure 3-1. Port Settings Tab

The following sections describe the options you can set in the Device Manager **Port Settings** tab.

Bits per Second

Bits per second, or baud rate, is the speed for a serial port.

Data Bits

Data bits is the number of data bits in a single serial byte.

Parity

Parity is the specification for even, odd, or no parity bits in each transmitted byte.

Stop Bits

Stop bits is the number of terminating bits on the end of each transmitted serial byte.

Flow Control

Flow control is a method for temporarily halting the stream of serial bytes to prevent overflow.

Advanced Settings

To view or change the advanced settings, click on the **Advanced** button. Figure 3-2 shows the **Advanced Settings** dialog box.

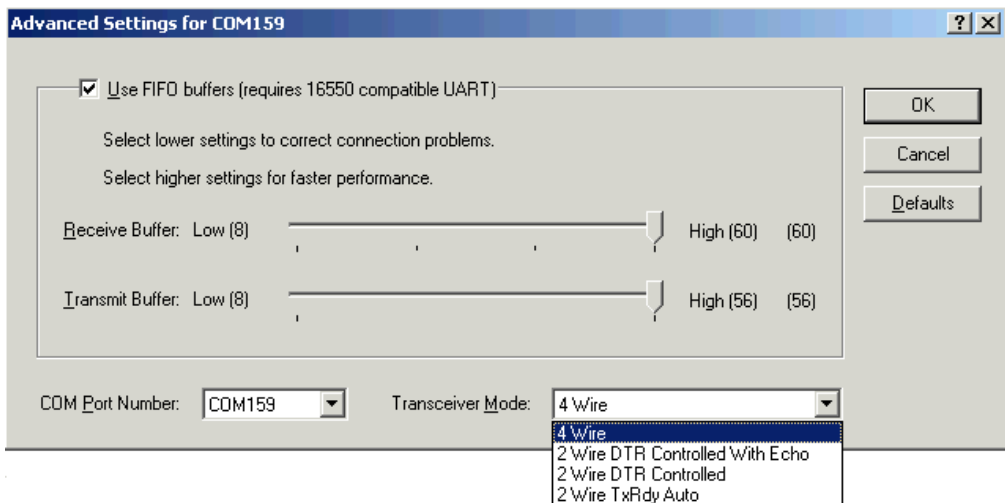


Figure 3-2. Advanced Settings Dialog Box

The following sections describe the advanced settings options.

Transceiver Mode

This field shows the transceiver mode in use, and applies only to RS-485 boards. For more information about transceiver modes, refer to Chapter 4, [Using Your Serial Hardware](#).

Use FIFO Buffers

FIFO buffers are present on the 16550-compatible UARTs—one for the transmitter and one for the receiver. The **Receive Buffer** control sets the number of characters received in the FIFO before the PC is interrupted to read the data. The **Transmit Buffer** control sets the maximum number of bytes written to the FIFO in a block when the PC is interrupted to write the data. When you configure FIFO settings, consider the following points:

- You can select larger FIFO buffer sizes to reduce the number of interrupts your PC receives and therefore minimize system overhead.
- If transfer rates are high, you can lower the **Receive Buffer** value to prevent overrun errors due to interrupt latency.
- If your data transfer sizes are small and your **Receive Buffer** value is above your data sizes, your system is less efficient. Therefore, set the **Receive Buffer** value below your data sizes.

Restore Defaults

To reset the fields to their default values at any time, click on the **Restore Defaults** button.

Using Your Serial Hardware

This chapter describes how to set the hardware transceiver control mode for your RS-485 interfaces and lists some general programming requirements.

General Programming Requirements

The NI-Serial software is fully integrated into the standard Windows 2000 communications software. NI serial ports are used like any other Windows 2000 communications (COM) port. Windows 2000 has standard communication functions for use within either Win16 or Win32 applications.

When you develop your application, remember that you must use the standard Microsoft Windows serial communication functions. For information about Microsoft Windows serial communication functions, refer to the *Win32 Software Development Kit* and to the *Win32 Overviews and Win32 Reference* online help.

If you have LabVIEW or LabWindows/CVI and want to use it with your serial hardware, refer to your LabVIEW or LabWindows/CVI documentation for information about serial I/O functions.

Advanced Transceiver Control for the RS-485 Boards



Note Transceiver modes apply only to the RS-485 boards.

The RS-485 boards support four modes of hardware transceiver control. You can use hardware flow control to enable and disable your transmitters and receivers so that they function on different bus topologies. Table 4-1 lists the status of the transmitters and receivers under each of the transceiver control modes.

Table 4-1. Transceiver Control Modes

| Mode | Transmitter | Receiver |
|--|--|--|
| Four-wire mode | Always enabled | Always enabled |
| Two-wire mode: $\overline{\text{DTR}}$ with echo | Enabled with $\overline{\text{DTR}}$ unasserted | Always enabled |
| Two-wire mode: $\overline{\text{DTR}}$ controlled | Enabled with $\overline{\text{DTR}}$ unasserted | Enabled with $\overline{\text{DTR}}$ asserted |
| Two-wire mode: $\overline{\text{TXRDY}}$ auto control | Enabled with $\overline{\text{TXRDY}}$ asserted | Enabled with $\overline{\text{TXRDY}}$ unasserted |



Note Signal names with an overscore, such as $\overline{\text{DTR}}$, indicate that the signal is active low.

Four-Wire Mode

Use the four-wire mode for most full-duplex systems. In this mode, the transmitter and receiver are always enabled. This mode is the default.

Two-Wire Mode: $\overline{\text{DTR}}$ with Echo

Use this mode in half-duplex systems where the $\overline{\text{DTR}}$ (Data Terminal Ready) line must control the transmitter. In the $\overline{\text{DTR}}$ -with-echo mode, the transmitter is tri-stated when the $\overline{\text{DTR}}$ signal of the UART (Universal Asynchronous Receiver/Transmitter) is asserted. To transmit, your application must first clear the $\overline{\text{DTR}}$ bit to enable the transmitter. After the data is fully transmitted, your application once again sets the $\overline{\text{DTR}}$ bit to disable the transmitter. Because the receiver is always enabled in this mode, you not only receive packets from other devices, you also receive the packets sent from your transmitter.

Two-Wire Mode: $\overline{\text{DTR}}$ Controlled

This mode is similar to the two-wire, $\overline{\text{DTR}}$ -with-echo mode. Use this mode in half-duplex systems where the $\overline{\text{DTR}}$ line must control the transmitter. Although this mode uses the same method as the $\overline{\text{DTR}}$ -with-echo mode to control the transmitter, the hardware automatically disables the receiver whenever the transmitter is enabled. Thus, you do not receive the packets sent from your transmitter.

Two-Wire Mode: $\overline{\text{TXRDY}}$ Auto Control

In this mode, the serial hardware transparently enables the transmitter and receiver in a two-wire system. Use this mode to remove the burden of flow control from your application. By connecting the transmitter to the $\overline{\text{TXRDY}}$ (Transmit Ready) line, the hardware enables the transmitter for each byte to be transmitted. Also, the hardware disables the receiver whenever the transmitter is enabled, so you do not receive the packets sent from your transmitter.



Note When you are communicating with a two-wire device, National Instruments recommends that you use the two-wire $\overline{\text{TXRDY}}$ auto control mode. Because this mode handles the transmitter/receiver enabling for a two-wire connection in your hardware, it reduces the software overhead required to perform this operation in your application program.

For more information about serial communication in two- or four-wire modes, refer to the [Serial Communication Issues](#) section in Appendix A, [Serial Port Information](#).

Setting the Transceiver Control Mode

To set the transceiver control mode, use the Windows 2000 Device Manager. For instructions on how to use the Device Manager, refer to Chapter 3, [Configuration](#). The mode you select in the Device Manager is automatically configured when you open a port on a serial interface.

Setting the Transceiver Mode with DeviceIoControl

The NI-Serial software extends the `DeviceIoControl` Windows function for programming the transceiver control mode. To program the transceiver control mode using `DeviceIoControl`, complete the following steps:

1. Add the following lines to your source code:

```
#include <winioctl.h>

#define IOCTL_SERIAL_SET_TRANSCEIVER_MODE
CTL_CODE(FILE_DEVICE_SERIAL_PORT, 37,
METHOD_BUFFERED, FILE_ANY_ACCESS)
```

2. Use the Win32 function `DeviceIoControl`, as follows:
 - a. Use the defined control code value listed in step 1 to set the transceiver mode.
 - b. Use the input buffer values (unsigned long) listed in Table 4-3 for programming different transceiver modes.

Table 4-2. DeviceIoControl Function Input Values

| Transceiver Mode | DeviceIoControl Function Input Value |
|---|---|
| Four-wire mode | 128 |
| Two-wire mode: $\overline{\text{DTR}}$ with echo | 129 |
| Two-wire mode: $\overline{\text{DTR}}$ controlled | 130 |
| Two-wire mode: $\overline{\text{TXRDY}}$ auto control | 131 |

For example, to set $\overline{\text{TXRDY}}$ two-wire auto control mode, use the following code:

```

ULONG TranceiverMode = 131;
ULONG dummy;
DeviceIoControl(hDevice,
IOCTL_SERIAL_SET_TRANSCEIVER_MODE, (PVOID)
&TranceiverMode, sizeof(ULONG), NULL, 0, &dummy, NULL);

```

Serial Port Information

This appendix describes the RS-232, RS-422, and RS-485 standards and explains some of the issues involved with these types of serial communication.

Table A-1 lists the features of the RS-232, RS-422, and RS-485 standards.

Table A-1. RS-232, RS-422, and RS-485 Features

| Feature | RS-232 | RS-422 | RS-485 |
|-----------------------------|------------------|--------------|---------------|
| Type of transmission lines | Single ended | Differential | Differential |
| Maximum number of drivers | 1 | 1 | 32 |
| Maximum number of receivers | 1 | 10 | 32 |
| Maximum cable length | 50 ft | 4,000 ft | 4,000 ft |
| Maximum data rate | 20 kbytes/s | 10 Mbytes/s | 10 Mbytes/s |
| Maximum CMV | ± 25 V | ± 7 V | +12 to -7 V |
| Driver output | 5 to 25 V | 2 to 6 V | 1.5 to 6 V |
| Driver load | > 3 k Ω | 100 Ω | 60 Ω |

RS-232

As specified in the ANSI/EIA-232-D Standard, *Interface Between Data Terminal Equipment and Data Circuit-Terminating Equipment Employing Serial Binary Data Interchange*, RS-232 standardizes serial communication between computers, and between computer terminals and modems. Most applications use the RS-232 standard to interface peripherals to personal computers. RS-232 uses transmission lines in which the state of each signal is represented by referencing the voltage level of a single line to ground. RS-232 was designed for serial communication up to

distances of 50 ft and with data rates up to 20 kbytes/s. However, because of improvements in line drivers and cabling, you can usually increase the actual performance of the bus past the limitations on speed and distance recommended in the specification.

RS-422

As specified in the EIA/RS-422-A Standard, *Electrical Characteristics of Balanced Voltage Digital Interface Circuits*, RS-422 defines a serial interface much like RS-232. However, RS-422 uses balanced (or differential) transmission lines. Balanced transmission lines use two transmission lines for each signal. The state of each signal is represented, not by a voltage level on one line referenced to ground as in RS-232, but rather by the relative voltage of the two lines to each other. For example, the TX signal is carried on two wires, wire A and wire B. A logical 1 is represented by the voltage on line A being greater than the voltage on line B. A logical 0 is represented by the voltage on line A being less than the voltage on line B. Differential voltage transmission creates a signal that is more immune to noise as well as voltage loss due to transmission line effects. Thus, you can use RS-422 for longer distances (up to 4,000 ft) and greater transmission speeds (up to 10 Mbytes/s) than RS-232.

RS-485

As specified in the EIA-485 Standard, *Standard for Electrical Characteristics of Generators and Receivers for Use in Balanced Digital Multipoint Systems*, RS-485 expands on the RS-422 standard by increasing the number of devices you can use from 10 to 32 and by working with half-duplex bus architectures. Unlike the RS-422 standard, RS-485 addresses the issue of using multiple transmitters on the same line. RS-485 defines the electrical characteristics necessary to ensure adequate signal voltages under maximum load, short-circuit protection. RS-485 can also withstand multiple drivers driving conflicting signals at the same time.

Serial Communication Issues

This section explains some serial communication issues, including duplex architectures, termination methods, bias resistors, and types of connecting equipment.

Duplex Architectures

Duplex refers to the means of bandwidth usage in a serial system. The two common means of bi-directional serial communication are full duplex and half duplex. Half-duplex communication involves a transmitter and a receiver connected to each end of the same wire or pair of wires. Because the same transmission line both sends and receives data, devices cannot send data in both directions at the same time. First, one device transmits over the wire(s) to the receiver of the second device. When the first device finishes transmitting, both devices switch the connections from their transmitter to their receiver, or vice versa. The device that was receiving data can then transmit over the line.

In full-duplex communication, the devices use a separate wire (or pair of wires) for simultaneous transmission in each direction. Thus, the devices do not switch between transmitting and receiving.

In a differential serial bus (such as RS-422 or RS-485), a half-duplex system transmits and receives over the same twisted pair of wires. Thus, half-duplex communication is often referred to as *two-wire* communications. Likewise, full-duplex communication is often referred to as *four-wire* communications, because the full-duplex system uses a separate pair of wires for communication in each direction.

Full Duplex

A typical full-duplex multidrop bus architecture involves a master-slave protocol. Only one device, the master, can control access to the bus. All other devices are slaves. Slave devices must wait for the master to give them access to the bus. In a typical full-duplex system, one transmission line connects the bus master transmitter to all of the slave receivers. A second transmission line connects all of the slave transmitters to the bus master receiver. Because each transmission line has two separate wires, a full-duplex system is often referred to as a four-wire system. Figure A-1 shows a typical full-duplex system.

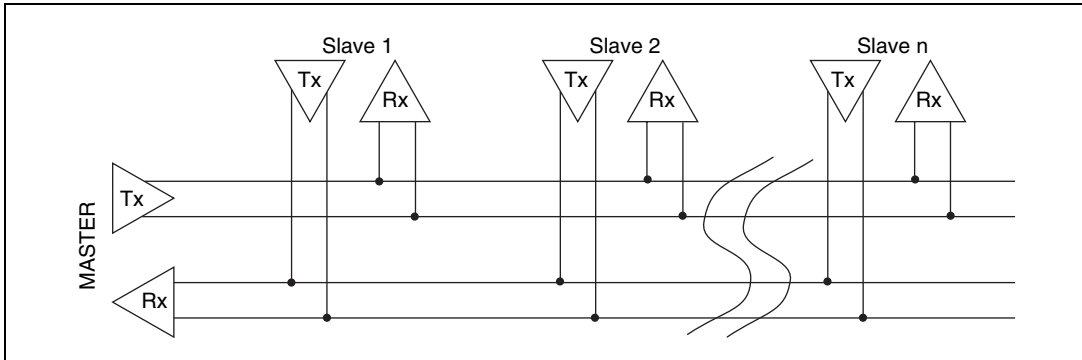


Figure A-1. Typical Full-Duplex System

Half Duplex

A typical half-duplex multidrop bus architecture also involves a master-slave protocol. However, in a half-duplex system, all transmitters and receivers are connected to the same transmission line. A half-duplex system is often referred to as a two-wire system. Figure A-2 shows a typical half-duplex system.

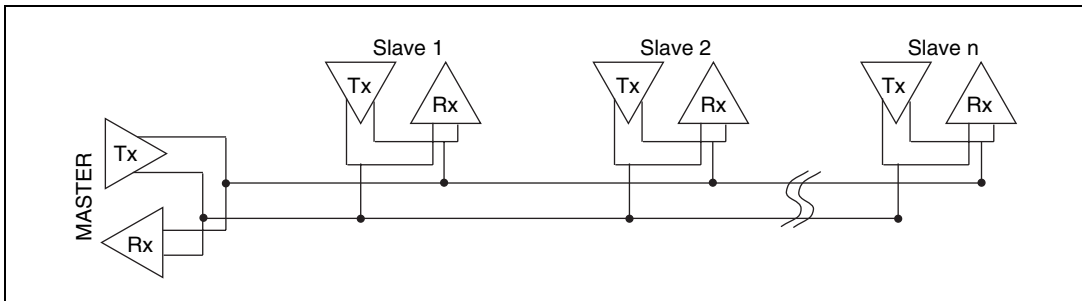


Figure A-2. Typical Half-Duplex System

Termination

Because each differential pair of wires is a transmission line, you must properly terminate the line to prevent reflections. A common method of terminating a two-wire multidrop RS-485 network is to install terminating resistors at each end of the multidrop network. If you daisy-chained multiple instruments together, you need a terminating resistor at only the first and last instruments. The terminating resistor should match the characteristic impedance of the transmission line (typically 100 to 120 Ω). You can order an optional DB-9 RS-485 termination connector that contains embedded terminating resistors for easy termination from National Instruments. For ordering information, contact National Instruments.

Figure A-3 shows a multidrop network using terminating resistors.

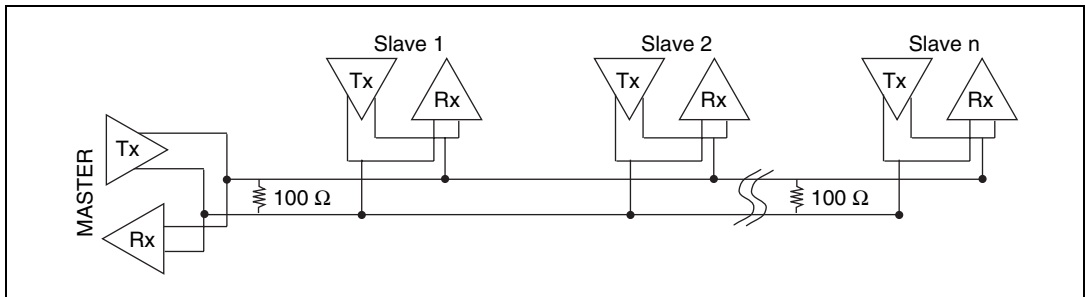


Figure A-3. Multidrop Network Using Terminating Resistors

Bias Resistors

A transmission line enters an indeterminate state if no nodes are transmitting on it. This indeterminate state can cause the receivers to receive invalid data bits from noise picked up on the cable. To prevent a line from receiving these data bits, force the transmission line into a known state. To do so, install two 620 Ω bias resistors at one node on the transmission line; doing so creates a voltage divider that forces the voltage between the differential pair to be greater than 200 mV, the threshold voltage for the receiver. You should install these resistors on only one node.



Note Bias resistors are not available on the eight-port PXI-8421.

Figure A-4 shows a transmission line using bias resistors.

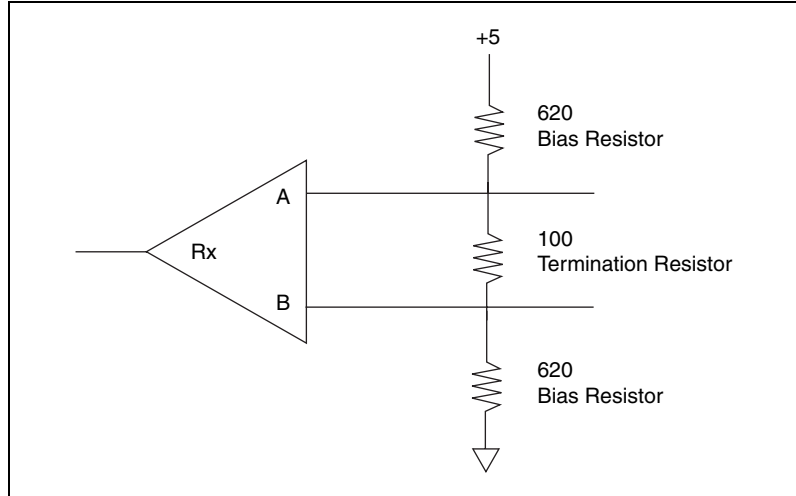


Figure A-4. Transmission Line Using Bias Resistors

Rather than using two 620 Ω resistors at one node, you can increase the value of the resistors and put them at every node. For instance, if there are eight nodes in a system, you can use 4.7 k Ω resistors at each node to effectively achieve the same result.

DTE vs. DCE

In the RS-232 specification, DTE (Data Terminal Equipment) and DCE (Data Communications Equipment)¹ refer to the types of equipment on either end of a serial connection. In general, DTE and DCE refer to computer equipment and modems, respectively. Because the RS-232 specification mainly involves connecting a DTE directly to a DCE and vice versa, the pinouts are defined so that cabling is simple. That is, a cable connected a computer to a modem by wiring pin 1 to pin 1, pin 2 to pin 2, and so on. This method is known as *straight-through* cabling.

¹ In Revision D of the RS-232 specification, a DCE is a Data Circuit-Terminating Equipment.

Figure A-5 shows straight-through cabling in a DTE-to-DCE interface.

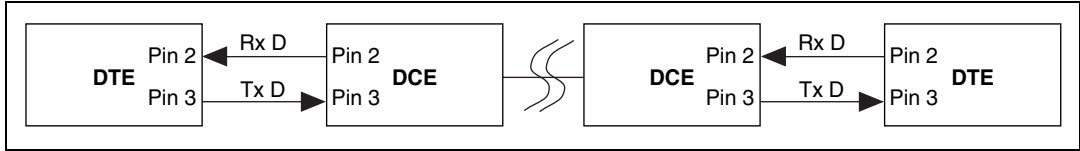


Figure A-5. Straight-Through Cabling in a DTE-to-DCE Interface

Straight-through cabling is still the standard method to connect a modem to your PC. However, because many applications use serial communication to connect two or more DTEs without modems, the cabling becomes more complicated. If two DTEs are wired together using a straight-through cable, one transmitter is connected to the other transmitter, and one receiver is connected to the other receiver. In this setup, no transmissions can occur. Thus, these applications must use a cabling scheme that connects the transmitter on one device to the receiver on the other device and vice versa. This method is known as *null-modem* cabling, because it replaces the two modems that traditional RS-232 applications would require between the two DTEs. To communicate from one serial port to another, use a null-modem cable.

Figure A-6 shows null-modem cabling in a DTE-to-DTE interface.

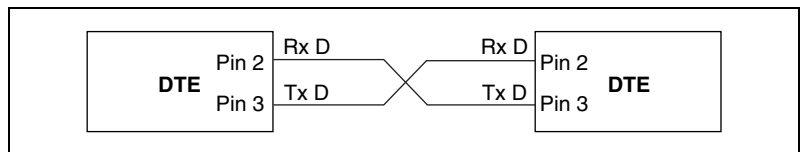


Figure A-6. Null-Modem Cabling in a DTE-to-DTE Interface

Uninstalling the Hardware and Software

This appendix describes how to uninstall your serial hardware and the NI-Serial software.

Uninstall the Hardware

Before you physically remove the serial hardware from your system, you must remove the hardware information. To do so, complete the following steps:

1. Select **Start»Settings»Control Panel** and double-click on the **System** icon.
2. Select the **Hardware** tab and click on the **Device Manager** button.
3. Double-click on the **Multi-function adapters** icon.
4. From the **Multi-function adapters** list, right-click on the National Instruments interface that you want to uninstall, as shown in Figure B-1.

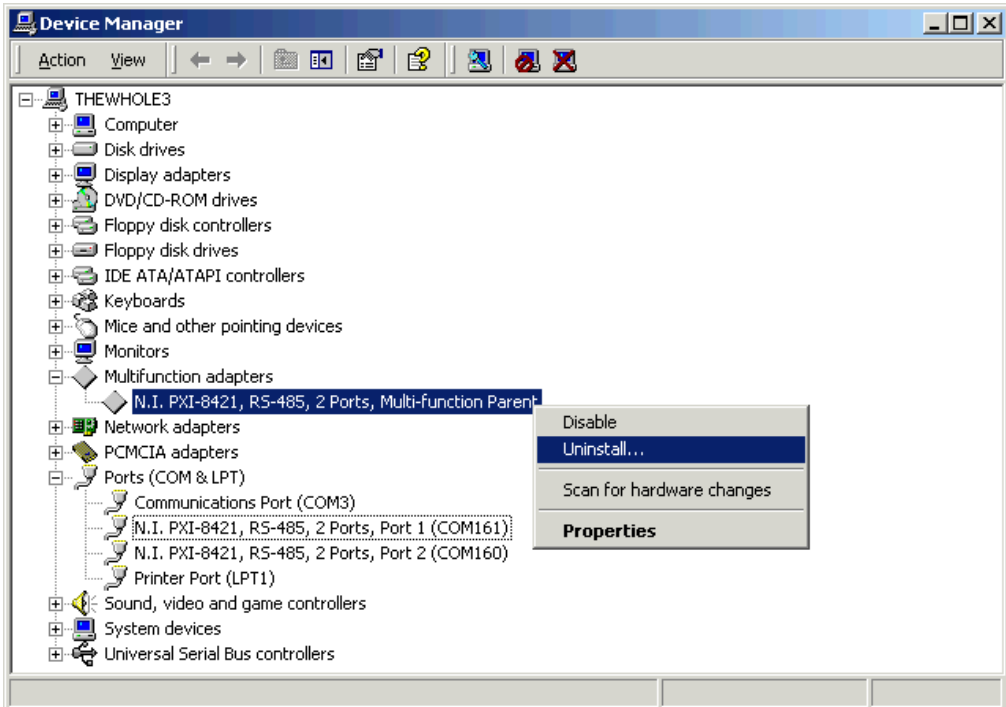


Figure B-1. Selecting an Interface to Uninstall

5. Choose the **Uninstall...** option.
6. In the **Confirm Device Removal** dialog box, click on the **OK** button to remove the hardware information, or click on the **Cancel** button to cancel your request.

Uninstall the Software

Before you uninstall the NI-Serial software, you must remove the hardware information from your system, as described in the previous section.

To uninstall the NI-Serial software, complete the following steps:

1. Select **Start»Settings»Control Panel**.
2. Double-click on the **Add/Remove Programs** icon. A dialog box similar to the one shown in Figure B-2 appears. This dialog box lists the software that you can uninstall.

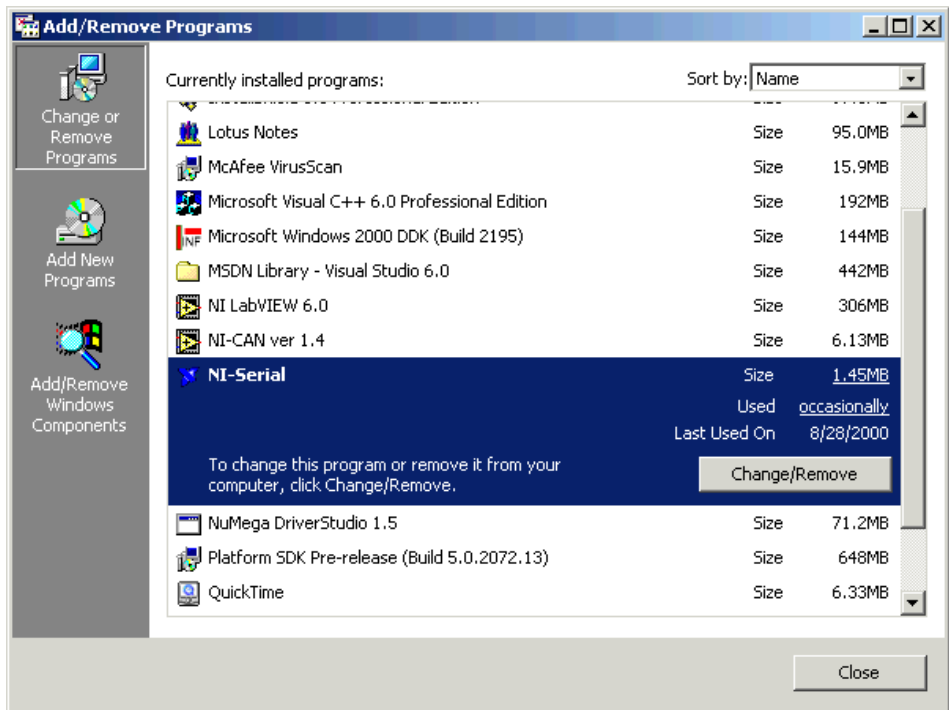


Figure B-2. Add/Remove Programs Dialog Box

3. Select **NI-Serial** and click on the **Change/Remove** button. The uninstallation program removes all folders, utilities, and registry entries associated with the NI-Serial software. Figure B-3 shows the results of a successful uninstallation.

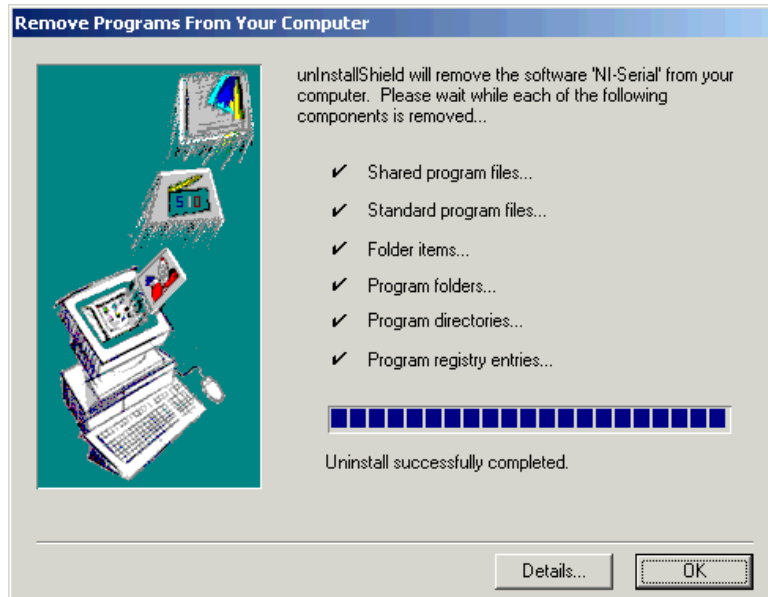


Figure B-3. Successful Uninstallation

4. Shut down Windows 2000, turn off your computer, and physically remove the serial interfaces from your system.

The uninstallation program only removes items that the setup wizard installed. If you added anything to a directory that the setup wizard created, the uninstallation program does not delete that directory. You must remove any remaining components yourself.

If you want to reinstall the hardware and software, refer to Chapter 2, [Installation and Verification](#).



Troubleshooting and Common Questions

This appendix describes how to troubleshoot problems and answers some common questions.

Forcing Windows to Detect Your Hardware

If Windows 2000 did not display the Found New Hardware Wizard, it did not detect your hardware. To solve this problem, complete the following steps:

1. Select **Start»Settings»Control Panel** and double-click on the **System** icon.
2. Select the **Hardware** tab and click on the **Device Manager** button.
3. Double-click on the **Multi-function adapters** icon.
4. From the **Multi-function adapters** list, right-click on the National Instruments interface that you want to uninstall, as shown in Figure C-1.

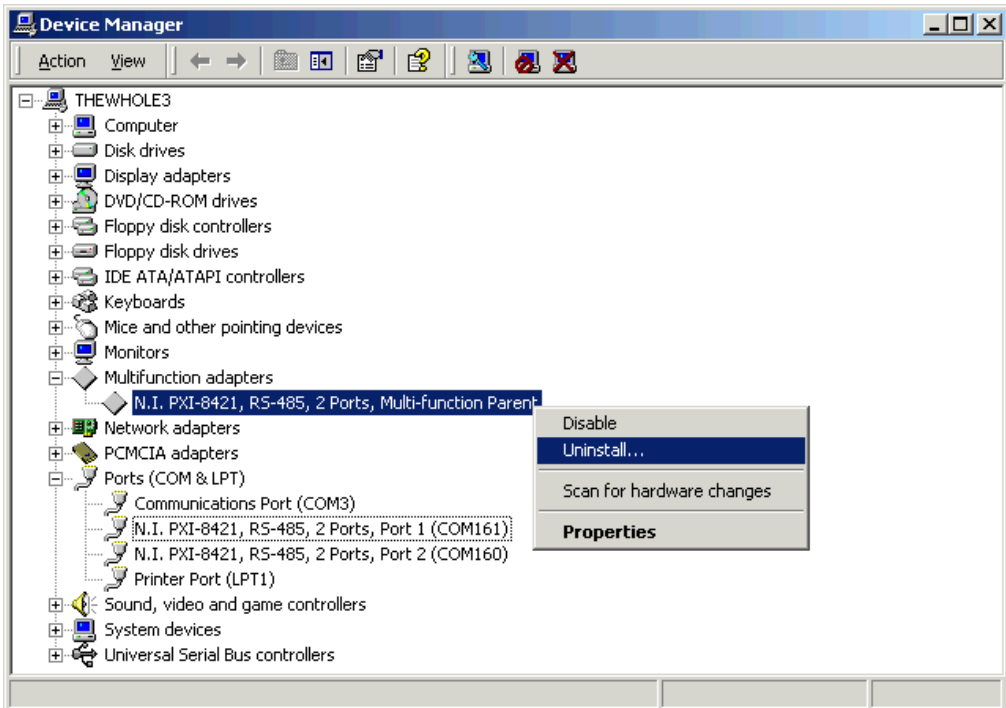


Figure C-1. Selecting an Interface to Uninstall

5. Choose the **Uninstall...** option.
6. In the **Confirm Device Removal** dialog box, click on the **OK** button to remove the hardware information, or click on the **Cancel** button to cancel your request.
7. Click on the **Scan for Hardware Changes** icon at the top of the Device Manager window.
8. Windows 2000 should automatically detect your hardware and display the Found New Hardware Wizard. Complete the wizard by clicking **Next** in each window and then **Finish**.

Troubleshooting Diagnostic Messages

This section lists possible error messages returned by the diagnostic utility, along with solutions.

No National Instruments Serial Port Found or Diagnostic Utility Does Not Show All Installed Ports

If the **No National Instruments serial port found** error message appears or the diagnostic utility does not show all the ports you installed, follow all the steps in the [Forcing Windows to Detect Your Hardware](#) section above.

Address Test Failed

If the **address test failed, Interrupt test cannot be performed** error message appears, you might have an address conflict with legacy boards in your system. To solve this problem, change the base addresses assigned to your legacy boards and refer to the [Resolving Resource Conflicts with Legacy Boards](#) section later in this appendix.

Interrupt Test Failed

If the **Interrupt test failed** error message appears, you might have an IRQ conflict with legacy boards in your system. To solve this problem, change the IRQ level assigned to your legacy boards and refer to the next section, [Resolving Resource Conflicts with Legacy Boards](#).

Resolving Resource Conflicts with Legacy Boards

Resource conflicts typically occur if your system contains legacy boards that use resources that are not reserved properly. If a resource conflict exists, write down the resource that caused the conflict and refer to the Microsoft Windows 2000 user's guide for instructions on how to use the Device Manager to reserve I/O and IRQ resources for legacy boards.

Common Questions

How can I determine which type of serial hardware I have installed?

1. Select **Start»Settings»Control Panel** and double-click on the **System** icon.
2. Click on the **Hardware** tab and click on the **Device Manager** button.
3. Double-click on the **Ports (COM & LPT)** icon to display a list of installed ports.

How can I determine which version of the NI-Serial software I have installed?

The **Read Me** file gives the version of the software. To open the file, select **Start»Programs»National Instruments»NI-Serial»Read Me**.

What do I do if the diagnostic test fails with an error?

Refer to the [Troubleshooting Diagnostic Messages](#) section earlier in this appendix.

How can I determine which port is associated with COMx?

To determine which physical port is associated with COM x , complete the following steps:

1. In the **Device Manager**, under **Ports (COM & LPT)**, double-click on a serial port.
2. Note the Port 1, Port 2, etc. entries next to the COM numbers. For all serial hardware, PORT1 refers to the top port, PORT2 refers to the next port down, and so on.

How can I change the COM number of my National Instruments serial ports?

1. Select **Start»Settings»Control Panel** and double-click on the **System** icon.
2. Click on the **Hardware** tab and click on the **Device Manager** button.
3. Double-click on the **Ports (COM & LPT)** icon.
4. Double-click on the port you want to configure.
5. Click on the **Port Settings** tab.

6. Click on the **Advanced** button. The Advanced Settings dialog box should pop up.
7. Change the COM number in the **COM Port Number** field. (You can use a COM number that is designated as in use, as long as no hardware is actually using that COM number.)

How do I remove information about serial boards from the Device Manager?

Refer to the [Uninstall the Hardware](#) section in Appendix B, [Uninstalling the Hardware and Software](#).

What is the maximum baud rate supported and how can I set it?

The maximum baud rate supported is 460.8 Kbaud for RS-485 and 115.2 Kbaud for RS-232. To set the baud rate, use the **SetCommState** Win32 function and pass the actual value of the baud rate in the **BaudRate** field of the **DCB** structure.

Specifications

This appendix describes the characteristics of the serial hardware, the NI-Serial software, along with the recommended operating conditions.

Two-Port Boards

| | |
|--------------------------------------|-------------------------------------|
| Dimensions..... | 100 by 160 mm (3.94 by 6.30 in.) |
| I/O connector..... | DB-9 |
| Power requirement (from PXI channel) | |
| PXI-8420/2 | |
| +5 VDC..... | 100 mA typical 150 mA maximum |
| ±12 VDC..... | 20 mA typical 200 mA maximum |
| PXI-8421/2 | |
| +5 VDC..... | 350 mA typical 750 mA maximum |
| PXI-8422/2 | |
| +5 VDC..... | 400 mA typical 650 mA maximum |
| PXI-8423/2 | |
| +5 VDC..... | 800 mA typical 1300 mA maximum |

Four-Port Boards

| | |
|----------------------------------|-------------------------------------|
| Dimensions..... | 100 by 160 mm (3.94 by 6.30 in.) |
| I/O connector ¹ | 10-position modular jack |

¹ The four-port PXI serial boards require a cable to convert the 10-position modular jack to either DB-9 or DB-25 connectors.

Power requirement (from PXI channel)

PXI-8420/4

| | |
|---------------|----------------------------------|
| +5 VDC | 125 mA typical 200 mA maximum |
| ±12 VDC | 40 mA typical 400 mA maximum |

PXI-8421/4

| | |
|--------------|----------------------------------|
| +5 VDC | 350 mA typical 750 mA maximum |
|--------------|----------------------------------|

PXI-8422/4

| | |
|--------------|----------------------------------|
| +5 VDC | 500 mA typical 750 mA maximum |
|--------------|----------------------------------|

PXI-8423/4

| | |
|--------------|------------------------------------|
| +5 VDC | 1000 mA typical 1500 mA maximum |
|--------------|------------------------------------|

Eight-Port Boards

| | |
|------------------|-------------------------------------|
| Dimensions | 100 by 160 mm (3.94 by 6.30 in.) |
|------------------|-------------------------------------|

| | |
|----------------------------------|----------------------------------|
| I/O connector ¹ | 68-position, SCSI type connector |
|----------------------------------|----------------------------------|

Power requirement (from PXI channel)

PXI-8420/8

| | |
|---------------|----------------------------------|
| +5 VDC | 150 mA typical 250 mA maximum |
| ±12 VDC | 80 mA typical 800 mA maximum |

PXI-8421/8

| | |
|--------------|------------------------------------|
| +5 VDC | 1100 mA typical 2000 mA maximum |
|--------------|------------------------------------|

¹ The eight-port PXI serial boards require cables, which are included in your kit, to convert the 68-position connector to eight DB-9 connectors.

Environmental Characteristics

Operating environment

Component temperature..... 0 to 70 °C

Relative humidity..... 10 to 90%, noncondensing

Storage environment

Temperature –40 to 120 °C

Relative humidity..... 5 to 90%, noncondensing

EMI FCC Class A Verified

Software Characteristics

Maximum serial transfer rate¹

RS-485 460,800 bps

RS-232 115,200 bps

¹ Actual speed may vary considerably from speed shown due to system and instrumentation capabilities.

Technical Support Resources

Web Support

National Instruments Web support is your first stop for help in solving installation, configuration, and application problems and questions. Online problem-solving and diagnostic resources include frequently asked questions, knowledge bases, product-specific troubleshooting wizards, manuals, drivers, software updates, and more. Web support is available through the Technical Support section of ni.com

NI Developer Zone

The NI Developer Zone at ni.com/zone is the essential resource for building measurement and automation systems. At the NI Developer Zone, you can easily access the latest example programs, system configurators, tutorials, technical news, as well as a community of developers ready to share their own techniques.

Customer Education

National Instruments provides a number of alternatives to satisfy your training needs, from self-paced tutorials, videos, and interactive CDs to instructor-led hands-on courses at locations around the world. Visit the Customer Education section of ni.com for online course schedules, syllabi, training centers, and class registration.

System Integration

If you have time constraints, limited in-house technical resources, or other dilemmas, you may prefer to employ consulting or system integration services. You can rely on the expertise available through our worldwide network of Alliance Program members. To find out more about our Alliance system integration solutions, visit the System Integration section of ni.com

Worldwide Support

National Instruments has offices located around the world to help address your support needs. You can access our branch office Web sites from the Worldwide Offices section of ni.com. Branch office Web sites provide up-to-date contact information, support phone numbers, e-mail addresses, and current events.

If you have searched the technical support resources on our Web site and still cannot find the answers you need, contact your local office or National Instruments corporate. Phone numbers for our worldwide offices are listed at the front of this manual.

Glossary

| Prefix | Meaning | Value |
|---------|---------|------------|
| p- | pico- | 10^{-12} |
| n- | nano- | 10^{-9} |
| μ - | micro- | 10^{-6} |
| m- | milli- | 10^{-3} |
| k- | kilo- | 10^3 |
| M- | mega- | 10^6 |
| G- | giga- | 10^9 |
| t- | tera- | 10^{12} |

° degrees

Ω ohms

% percent

A amperes

ANSI American National Standards Institute

b bits

B bytes

baud bits per second

bps bits per second

C Celsius

COM Computer Output Microform; used in reference to a communication port

CTS clear to send

DB-xx subminiature D connector, where xx is the number of pins

Glossary

| | |
|-------------------------|---|
| DCD | data carrier detect |
| DCE | data communications equipment or data circuit-terminating equipment |
| DLL | dynamic link library |
| DMA | direct memory access |
| DSR | data set ready |
| DTE | data terminal equipment |
| $\overline{\text{DTR}}$ | data terminal ready—the overscore denotes that the signal is active low |
| duplex | the means of bandwidth usage in a serial system |
| EIA | Electronic Industries Association |
| EMI | electromagnetic interference |
| FCC | Federal Communications Commission |
| FIFO | First-In-First-Out |
| ft | feet |
| GND | ground |
| HSI | handshake input |
| HSO | handshake output |
| Hz | Hertz |
| IEEE | Institute of Electrical and Electronic Engineers |
| in. | inches |
| I/O | input/output |
| IRQ | interrupt request |
| ISA | Industry Standard Architecture |
| Kbaud | kilobits per second |
| m | meters |

| | |
|---------------------------|--|
| MB | megabytes of memory |
| PC | personal computer |
| PCI | Peripheral Components Interconnect |
| RAM | random-access memory |
| RI | ring indicator |
| RTS | request to send |
| RX | receive |
| $\overline{\text{RXD}}$ | receive data—the overscore denotes that the signal is active low |
| s | seconds |
| SCSI | Small Computer Systems Interface |
| TX | transmit |
| $\overline{\text{TXD}}$ | transmit data—the overscore denotes that the signal is active low |
| $\overline{\text{TXRDY}}$ | transmit ready—the overscore denotes that the signal is active low |
| UART | Universal Asynchronous Receiver/Transmitter |
| V | volts |
| VDC | volts direct current |
| VXI | VME eXtensions for Instrumentation |
| Win16 | describes a 16-bit Windows application |
| Win32 | describes a 32-bit Windows application |

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