USER GUIDE AND SPECIFICATIONS

MID-7604/7602 Stepper Power Motor Drive

This user guide describes the electrical and mechanical aspects of the MID-7604/7602 stepper power motor drive and how to use the MID-7604/7602 with your motion controller.

Contents

Conventions

The following conventions are used in this manual:

» The » symbol leads you through nested menu items and dialog box options to a final action. The sequence **Options»Settings»General** directs you to pull down the **Options** menu, select the **Settings** item, and select **General** from the last dialog box.

This icon denotes a note, which alerts you to important information.

NATIONAL INSTRUMENTS

	This icon denotes a caution, which advises you of precautions to take to avoid injury, data loss, or a system crash. When this symbol is marked on a product, refer to the *Specifications* section of this guide for information about precautions to take.
	When this symbol is marked on a product, it denotes a component that may be hot. Touching this component may result in bodily injury.
bold	Bold text denotes items that you must select or click in the software, such as menu items and dialog box options. Bold text also denotes parameter names.
italic	Italic text denotes variables, emphasis, a cross-reference, or an introduction to a key concept. Italic text also denotes text that is a placeholder for a word or value that you must supply.
`monospace`	Text in this font denotes text or characters that you should enter from the keyboard, sections of code, programming examples, and syntax examples. This font is also used for the proper names of disk drives, paths, directories, programs, subprograms, subroutines, device names, functions, operations, variables, filenames, and extensions.
overline	Indicates the signal is active low.

Introduction

The National Instruments MID-7604/7602 power drive is a complete power amplifier and system interface for use with four or two axes of simultaneous stepper motion control. Ideally suited to industrial and laboratory applications, the MID-7604/7602 has everything you need to connect motors, encoders, limit switches, I/O, and other motion hardware to National Instruments motion controllers.

The MID-7604/7602 can drive a broad range of stepper motors with its rugged microstepping bipolar chopper driver and user-selectable current-per-phase settings. In all configurations, power supplies are built-in and use standard 230/115 VAC for operation. Electronics are fan-cooled to assure reliable operation.

The MID-7604/7602 simplifies field wiring through separate encoder, limit switch, and motor power removable screw terminal connector blocks for each axis. The terminal blocks do not require special wiring tools for installation. The MID-7604/7602 connects to National Instruments motion controllers using a 68-pin, high-density interconnect cable.

The MID-7604/7602 has four levels of amplifier inhibit/disable protection for motion system shutdown. The front panel contains both enable and power switches for direct motor inhibiting and system power-down operations. The MID-7604/7602 also has a host bus power interlock that activates an internal driver inhibit signal if the host computer is shut down or the motion controller interface cable is disconnected. The inhibit input from the back panel connectors also inhibits the stepper drives when activated.

The MID-7604/7602 is packaged in a rugged, lightweight enclosure that can be used as a benchtop unit, panel mounted using a panel-mount kit, or rack mounted using a 19-inch standard rack kit.

What You Need to Get Started

To set up and use your MID-7604/7602 accessory, you must have the following items:

- ❑ MID-7604/7602 power drive
- ❑ Power cord (IEC type)

- ❑ Panel-mount kit, NI part number 187243-01 (included)
- ❑ One of the following shielded cable assemblies, as applicable:
  - SH68-C68-S, NI part number 186381-02 (not included)
  - SHC68-C68-S, NI part number 186380-02 (not included)

Refer to the *Specifications* section of this document for detailed specifications for the MID-7604/7602.

Safety Information

The following section contains important safety information that you must follow when installing and using the hardware.

Do not operate the hardware in a manner not specified in this document and in the user documentation. Misuse of the hardware can result in a hazard. You can compromise the safety protection if the hardware is damaged in any way. If the hardware is damaged, return it to National Instruments for repair.

Clean the hardware with a soft, nonmetallic brush. Make sure that the hardware is completely dry and free from contaminants before returning it to service.

Do not substitute parts or modify the hardware except as described in this document. Use the hardware only with the chassis, modules, accessories, and cables specified in the installation instructions or specifications. You must have all covers and filler panels installed during operation of the hardware.

Do not operate the hardware in an explosive atmosphere or where there may be flammable gases or fumes unless the hardware is UL (U.S.) or Ex (EU) Certified and marked for hazardous locations. The hardware must be in a suitably rated IP 54 minimum enclosure for hazardous locations.

You must insulate signal connections for the maximum voltage for which the hardware is rated. Do not exceed the maximum ratings for the hardware. Do not install wiring while the hardware is live with electrical signals. Do not remove or add connector blocks when power is connected to the system. Avoid contact between your body and the connector block signal when hot swapping hardware. Remove power from signal lines before connecting them to or disconnecting them from the hardware.

Caution The MID-7604/7602 does not provide overload protection for motor loads. Overload protection *must* be provided externally by the system designer.

Caution The MID-7604/7602 does not provide motor overtemperature sensing. External temperature sensing *must* be provided externally by the system designer. Temperature sensing is required for monitoring the motor temperature and disabling the drive.

Caution The stepper motor connectors on this drive are energized when the unit is powered on. Disconnect the MID-7604/7602 unit from the power outlet *before* connecting wires to or disconnecting wires from the stepper connectors. Strip back the insulation of the stepper wires to the stepper connectors no more than 7 mm. ***Failure to do so could result in electric shock leading to serious bodily injury or death.***

Hot Surface The bottom surface of the MID-7604/7602 can get very hot to the touch under certain conditions. To avoid a burn hazard, refer to *Output Current Settings* in the *Front Panel DIP Switch Settings* section of this guide for the appropriate current setting and safety hazards.

Operate the hardware only at or below Pollution Degree 2. Pollution is foreign matter in a solid, liquid, or gaseous state that can reduce dielectric strength or surface resistivity. The following is a description of pollution degrees:

- Pollution Degree 1 means no pollution or only dry, nonconductive pollution occurs. The pollution has no influence. Typical level for sealed components or coated PCBs.
- Pollution Degree 2 means that only nonconductive pollution occurs in most cases. Occasionally, however, a temporary conductivity caused by condensation must be expected. Typical level for most products.
- Pollution Degree 3 means that conductive pollution occurs, or dry, nonconductive pollution occurs that becomes conductive due to condensation.

Note The MID-7604/7602 is intended for indoor use only.

Operate the hardware at or below the measurement category[1] marked on the hardware label. Measurement circuits are subjected to working voltages[2] and transient stresses (overvoltage) from the circuit to which they are connected during measurement or test. Measurement categories establish standard impulse withstand voltage levels that commonly occur in electrical distribution systems. The following is a description of measurement categories:

- Measurement Category I is for measurements performed on circuits not directly connected to the electrical distribution system referred to as MAINS[3] voltage. This category is for measurements of voltages from specially protected secondary circuits. Such voltage measurements include signal levels, special hardware, limited-energy parts of hardware, circuits powered by regulated low-voltage sources, and electronics.
- Measurement Category II is for measurements performed on circuits directly connected to the electrical distribution system (MAINS[3]). This category refers to local-level electrical distribution, such as that provided by a standard wall outlet (for example, 115 AC voltage for U.S. or 230 AC voltage for Europe). Examples of Measurement Category II are measurements performed on household appliances, portable tools, and similar hardware.
- Measurement Category III is for measurements performed in the building installation at the distribution level. This category refers to measurements on hard-wired hardware such as hardware in fixed installations, distribution boards, and circuit breakers. Other examples are wiring, including cables, bus bars, junction boxes, switches, socket outlets in the fixed installation, and stationary motors with permanent connections to fixed installations.
- Measurement Category IV is for measurements performed at the primary electrical supply installation typically outside buildings. Examples include electricity meters and measurements on primary overcurrent protection devices and on ripple control units.

To obtain the safety certification(s) for this product, visit `ni.com/certification`, search by model number or product line, and click the appropriate link in the Certification column.

[1] Measurement categories, also referred to as overvoltage or installation categories, are defined in electrical safety standard IEC 61010-1 and IEC 60664-1.

[2] Working voltage is the highest rms value of an AC or DC voltage that can occur across any particular insulation.

[3] MAINS is defined as a hazardous live electrical supply system that powers hardware. Suitably rated measuring circuits may be connected to the MAINS for measuring purposes.

Electromagnetic Compatibility Information

This hardware has been tested and found to comply with the applicable regulatory requirements and limits for electromagnetic compatibility (EMC) as indicated in the hardware's Declaration of Conformity (DoC)[1]. These requirements and limits are designed to provide reasonable protection against harmful interference when the hardware is operated in the intended electromagnetic environment. In special cases, for example when either highly sensitive or noisy hardware is being used in close proximity, additional mitigation measures may have to be employed to minimize the potential for electromagnetic interference.

While this hardware is compliant with the applicable regulatory EMC requirements, there is no guarantee that interference will not occur in a particular installation. To minimize the potential for the hardware to cause interference to radio and television reception or to experience unacceptable performance degradation, install and use this hardware in strict accordance with the instructions in the hardware documentation and the DoC[1].

If this hardware does cause interference with licensed radio communications services or other nearby electronics, which can be determined by turning the hardware off and on, you are encouraged to try to correct the interference by one or more of the following measures:

- Reorient the antenna of the receiver (the device suffering interference).
- Relocate the transmitter (the device generating interference) with respect to the receiver.
- Plug the transmitter into a different outlet so that the transmitter and the receiver are on different branch circuits.

Some hardware may require the use of a metal, shielded enclosure (windowless version) to meet the EMC requirements for special EMC environments such as, for marine use or in heavy industrial areas. Refer to the hardware's user documentation and the DoC[1] for product installation requirements.

When the hardware is connected to a test object or to test leads, the system may become more sensitive to disturbances or may cause interference in the local electromagnetic environment.

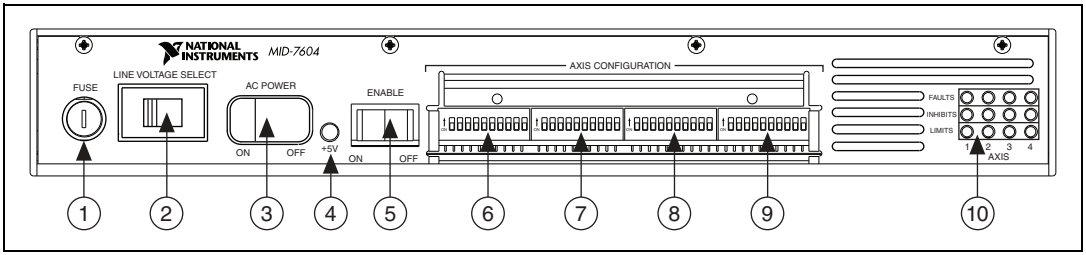
Operation of this hardware in a residential area is likely to cause harmful interference. Users are required to correct the interference at their own expense or cease operation of the hardware.

Changes or modifications not expressly approved by National Instruments could void the user's right to operate the hardware under the local regulatory rules.

[1] The Declaration of Conformity (DoC) contains important EMC compliance information and instructions for the user or installer. To obtain the DoC for this product, visit `ni.com/certification`, search by model number or product line, and click the appropriate link in the Certification column.

Front Panel Switches

Figure 1 shows the front panel of your MID-7604/7602. The DIP switches are shown with the detachable metal cover plate removed.



1	Main Input Fuse	5	Enable Switch	8	Axis 3 DIP Switch Bank*
2	Line Voltage Select Switch	6	Axis 1 DIP Switch Bank	9	Axis 4 DIP Switch Bank*
3	Power Switch	7	Axis 2 DIP Switch Bank	10	LED Status Array
4	Green Power LED				

Figure 1. MID-7604/7602 Front Panel

Note Items followed by an asterisk (*) are available on the MID-7604 only.

The two rocker switches on the MID-7604/7602 front panel are the AC POWER and ENABLE. Figure 1 shows the location of these switches.

The AC POWER switch energizes the motor bus (+24 V) and the logic (+5 V) power supplies. When switched on, the green power LED labeled **+5 V** illuminates. If this LED fails to illuminate, check the power cord and main input fuse on the front panel.

The ENABLE switch enables or inhibits the stepper drivers. If the ENABLE switch is in the inhibit position (off), the stepper drivers are inhibited, and the yellow LEDs (the middle row of the LED status array) and red LEDs (the top row of the LED status array) illuminate for all axes. Refer to the *Front Panel LEDs* section of this guide for more information.

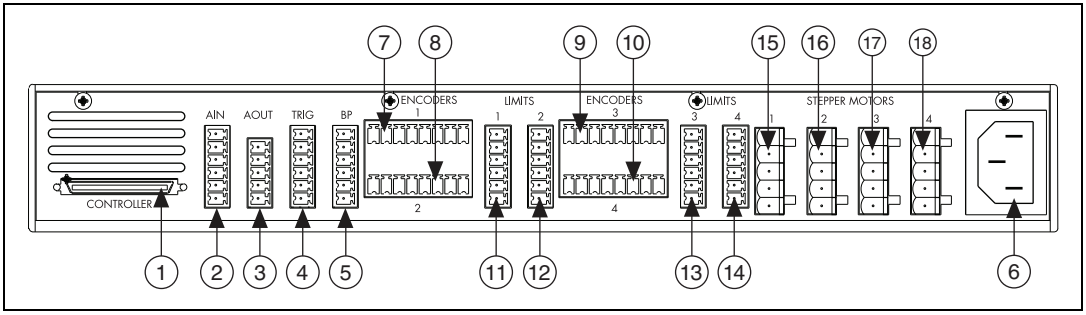
Note In older versions of the MID-7604/7602, the red status LEDs do not illuminate when the yellow status LEDs illuminate. This behavior only occurs in newer versions of the MID-7604/7602.

Both the AC POWER and ENABLE switches can inhibit the stepper drivers. However, as long as the AC POWER switch is on, only the stepper driver output stages are disabled. The remaining circuitry remains active, including the quadrature encoder circuit.

Caution You *must* change the MID-7604/7602 main input fuse on the front panel if you change the line voltage from the factory setting. Refer to the *Specifications* section of this guide for fuse specifications.

Back Panel Connector Wiring

Figure 2 shows the connectors located on the back panel of your MID-7604/7602.



1	Motion Controller Connector	**Encoder Connectors**		**Limit Connectors**		**Motor Connectors**	
2	Analog Input Connector	7	Axis 1	11	Axis 1	15	Axis 1
3	Analog Output Connector	8	Axis 2	12	Axis 2	16	Axis 2
4	Trigger Connector	9	Axis 3*	13	Axis 3*	17	Axis 3*
5	Breakpoint Connector	10	Axis 4*	14	Axis 4*	18	Axis 4*
6	AC Power						

Figure 2. MID-7604/7602 Back Panel Connectors

Note Items followed by an asterisk (*) are available on the MID-7604 only.

Caution Be sure to turn off the ENABLE switch and the main AC power to your MID-7604/7602 and host computer *before* connecting the accessory to your motion controller.

Caution The stepper motor connectors on this drive are energized when the unit is powered on. Disconnect the MID-7604/7602 unit from the power outlet *before* connecting wires to or disconnecting wires from the stepper connectors. Strip back the insulation of the stepper wires to the stepper connectors no more than 7 mm. ***Failure to do so could result in electric shock leading to serious bodily injury or death.***

1. Use the interface cable to connect the motion controller to the MID-7604/7602. Wire the motor power, limit switch, encoder, and I/O terminal blocks as described in this guide and to your specific system requirements.

Caution You *must* change the MID-7604/7602 main input fuse on the front panel if you change the line voltage from the factory setting. Refer to the *Specifications* section of this guide for fuse specifications.

2. Use the **LINE VOLTAGE SELECT** switch to configure the MID-7604/7602 for 115 VAC, 60 Hz or 230 VAC, 50 Hz operation. For proper operation, you must set this switch to match your power source.
3. Finally, install the power cord into the back panel AC connector and plug it in to a correctly rated power source.

Host Bus Interlock Circuit

The MID-7604/7602 has a host bus interlock circuit that monitors the presence of +5 V from the host computer and disables the MID-7604/7602 when the voltage is not present or falls out of tolerance. This circuit shuts down the stepper drives for all axes by activating the inhibit when the host computer is disconnected from the MID-7604/7602 or inadvertently shut down. Activation of the host bus interlock circuitry illuminates the yellow LEDs (middle row) and red LEDs (top row) of the LED status array for all axes. Refer to the *Front Panel LEDs* section of this guide for more information.

Note In older versions of the MID-7604/7602, the red status LEDs do not illuminate when the yellow status LEDs illuminate. This behavior only occurs in newer versions of the MID-7604/7602.

Front Panel LEDs

The front panel LEDs consist of a single green LED to indicate if the main power is active and an LED status array of 3 rows by 4 columns that provides a variety of status information. Refer to Figure 1 for the location of the front panel LEDs.

If the DC power supplies are active, the green power LED illuminates. If this LED fails to illuminate, check the power cord and the main input fuse on the front panel.

The LED status array is arranged by motor axes. Each of the four columns represents an axis, and each of the three rows represents a particular status. Table 1 summarizes the axis and corresponding status for each LED in the 3 × 4 array.

Table 1. Front Panel LED Indicators

Status	Motor Axis			
Driver Fault Output (red)	1	2	3	4
Driver Inhibit (yellow)	1	2	3	4
Limit Status (green)	1	2	3	4

Driver Fault Output LEDs

The top row of LEDs indicates the status of the stepper drivers. An LED illuminates red when an overcurrent condition or a problem with the motor bus voltage on that axis occurs. The LEDs also illuminate red when the axis is inhibited. Refer to the *Driver Inhibit LEDs* section of this guide for more information about inhibit conditions.

Note In older versions of the MID-7604/7602, the red status LEDs do not illuminate when the yellow status LEDs illuminate. This behavior only occurs in newer versions of the MID-7604/7602.

Driver Inhibit LEDs

The middle row of LEDs indicates whether or not a motor axis is inhibited. An axis is inhibited and the LED illuminates yellow in the following instances:

- if the host bus interlock circuitry is activated
- if the **ENABLE** switch on the front panel is in the inhibit (off) position
- if the motion controller's inhibit signal is low
- if the per-axis inhibit input is actively driven

The polarity of the per-axis inhibit input is selectable from the front panel DIP switches. Refer to the *Front Panel DIP Switch Settings* section of this guide for more information.

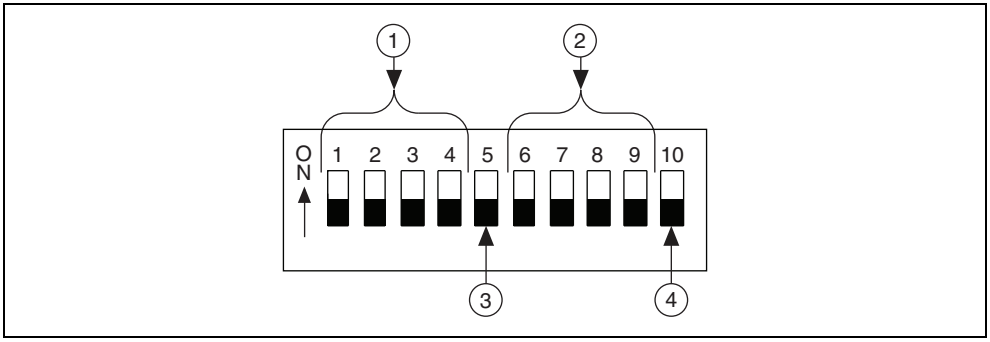
Limit Status LEDs

The bottom row of LEDs indicates whether or not a limit switch is currently active. The LED illuminates green if either the forward or reverse limit switch is active for each axis. You can select the polarity for the limit status LEDs from the front panel DIP switches. Refer to the *Front Panel DIP Switch Settings* section of this guide for more information.

Front Panel DIP Switch Settings

The MID-7604/7602 front panel has a detachable metal plate that when removed provides access to four 10-position DIP switch banks. Refer to Figure 1 for the location of these switches.

Use the first nine DIP switches on each 10-position DIP switch bank to configure the microstep rate, peak output current, and current reduction for each axis. The DIP switch banks for axes 1 and 2 contain a global DIP switch, switch 10, which sets the polarity of the inhibit input and the polarity of the limit status LED, respectively. Figure 3 shows the DIP switch bank layout.



1	Peak Current Output Switches	4	Global Polarity Switch (unused on axes 3 and 4 DIP switch banks)
2	Microstep Rate Switches		
3	Current Reduction Switch		

Figure 3. DIP Switch Bank Layout

Microstepping Selection

The MID-7604/7602 uses bipolar chopper, two-phase microstepping drivers with a broad range of microstep rates. The factory default setting is 10-times microstepping (2,000 steps/rev with standard 1.8º stepper motors). Table 2 shows the DIP switch settings for all possible microstep settings. DIP switches 6 through 9 control the microstep rate on a per-axis basis.

Table 2. Microstep Rate DIP Switch Setting

Binary Selections	
Switch	**Microsteps/Step**
	2 (half step)
	4
	8
	16
	32
	64
	128
	256

Decimal Selections	
Switch	**Microsteps/Step**
	5
	10 (factory default)
	25
	50
	125
	250
	Do not use
	Do not use

Output Current Settings

The MID-7604/7602 can provide 0.20 to 1.4 A peak (0.14 to 1 A RMS), depending on the peak output current DIP switch settings for each axis. DIP switches 1 through 4 control the peak output current. Table 3 shows the DIP switch settings for all possible peak output current settings.

Table 3. Peak Output Current DIP Switch Setting

Switch	Peak Output (A)	Switch	Peak Output (A)
	1.40		0.35
	1.20		0.30
	1.00		0.28
	0.85		0.27
	0.70		0.25
	0.60		0.24
	0.55		0.23
	0.50 (factory default)		0.20

If you are connecting multiple motors to your MID-7604/7602, verify that the total power dissipated by the motors at any given time is less than the total power the drive can provide. If the total power requirement exceeds the capability of the drive at any point, the drive will provide less power to the motors than desired until the total power requirement drops back down. The MID-7604/7602 may overheat under continuous operation with loads that exceed specified limits.

Caution A fire safety hazard exists when the total power dissipated by the motors exceeds 80 W continuous for a sustained period of time.

To determine the maximum total power dissipation of all of the motors combined, add up the maximum power each motor can dissipate. If this value is less than or equal to 80 W continuous, you will not exceed the capabilities of the MID-7604/7602.

If the value is greater than 80 W continuous, you may still be within the operating capabilities of the MID-7604/7602, since it is unlikely you will run all of your motors simultaneously at their maximum levels. Make a reasonable estimation of the maximum power your motors will require at any given time and verify that this value is less than 80 W continuous.

You can configure the MID-7604/7602 stepper drivers in a current reduction mode on a per-axis basis. This configuration is useful to minimize motor heating when you are not stepping. With current reduction enabled, the current decreases by 50% when no stepping has occurred for approximately 500 ms. DIP switch 5 controls current reduction on a per-axis basis. When this DIP switch is on, current reduction is enabled. When this DIP switch is off, current reduction is disabled. The factory default setting is current reduction enabled.

Table 4 shows the available settings for DIP switch 5.

Table 4. Current Reduction DIP Switch Settings

Switch Setting	Operation
	Current reduction enabled (factory default)
	Current reduction disabled

Inhibit Input Polarity Setting

The MID-7604/7602 has a DIP switch that globally sets the polarity for the inhibit input for all axes. DIP switch 10 on the axis 1 DIP switch bank controls this setting. Refer to Figures 1 and 3 for the location of this switch.

The factory default setting of DIP switch 10 is active low. If the inhibit input is active, the axis is inhibited and the yellow status LED (middle row) and red status LED (top row) illuminates for the axis.

Note In older versions of the MID-7604/7602, the red status LEDs do not illuminate when the yellow status LEDs illuminate. This behavior only occurs in newer versions of the MID-7604/7602.

Table 5 shows the DIP switch setting for the inhibit input polarity selection.

Table 5. Inhibit Input Polarity DIP Switch Settings

Axis 1 Switch Setting	Operation
	Active high
	Active low (factory default)

Limit Status LED Polarity Setting

The MID-7604/7602 has a DIP switch that globally sets the polarity for the Limit Status LED. DIP switch 10 on the axis 2 DIP switch bank controls this setting. Refer to Figures 1 and 3 for the location of this switch.

The factory default setting is active low. Typically, you set the switch to match your controller's polarity setting, so that if either the reverse or forward limits for an axis are active, the green status LED (on the bottom row) for the axis illuminates. This DIP switch alters only the polarity for the LEDs, and not the actual limit to the motion controller. Table 6 shows the DIP switch setting for the Limit Status LED polarity selection.

Table 6. Limit Status LED DIP Switch Settings

Axis 2 Switch Setting	Operation
	Active high
	Active low (factory default)

Back Panel Connector Wiring

Motor Power Terminal Blocks

Each axis on the MID-7604/7602 has a separate 5-position removable screw terminal block for motor power wiring. Figure 4 shows a typical stepper motor configuration pin assignment.

Note The dotted loop indicates a shielded cable. A line above a signal indicates that the signal is active low.

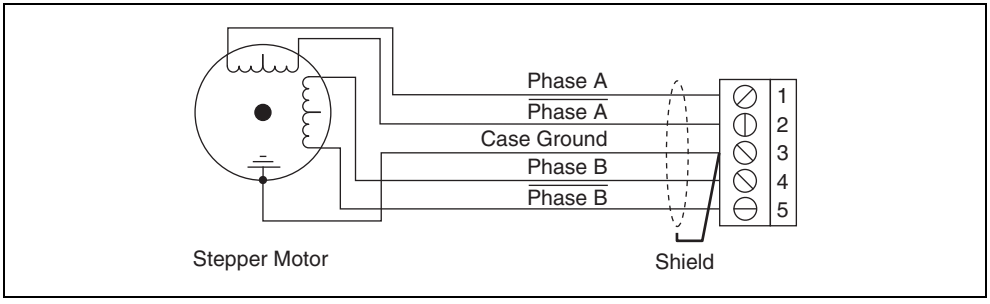


Figure 4. Typical Full-Coil Stepper Motor (2-Phase Type) Terminal Block Pin Assignment

Caution The stepper motor connectors on this drive are energized when the unit is powered on. Disconnect the MID-7604/7602 unit from the power outlet *before* connecting wires to or disconnecting wires from the stepper connectors. Strip back the insulation of the stepper wires to the stepper connectors no more than 7 mm. ***Failure to do so could result in electric shock leading to serious bodily injury or death.***

Use shielded, 20 AWG wire or larger for the motor power cable. If available, you should connect a case ground wire to pin 3 (Ground/Shield) to avoid ground loops and signal noise problems. Case ground connects to the motor housing, not to the motor power terminals.

The MID-7604/7602 contains bipolar chopper drivers. You must wire the stepper motors in a 4-wire configuration as shown in Figure 4. You must isolate unused lead wires and leave them disconnected. Refer to the *Stepper Motor Configurations* section of this guide for additional information on connecting 6- and 8-wire motors and on the alternate half-coil configuration.

Caution Never connect unused center taps or winding terminals to pin 3 (ground) or to each other.

Encoder Terminal Blocks

For quadrature incremental encoder signals, each MID-7604/7602 axis has a separate 8-position removable screw terminal block. Where applicable, the MID-7604/7602 accepts two types of encoder signal inputs: single-ended (TTL) or differential line driver. You can accommodate open-collector output encoders by using 2.2 kΩ pullup resistors to +5 VDC.

Figure 5 shows the typical encoder wiring pin assignment for single-ended signal input.

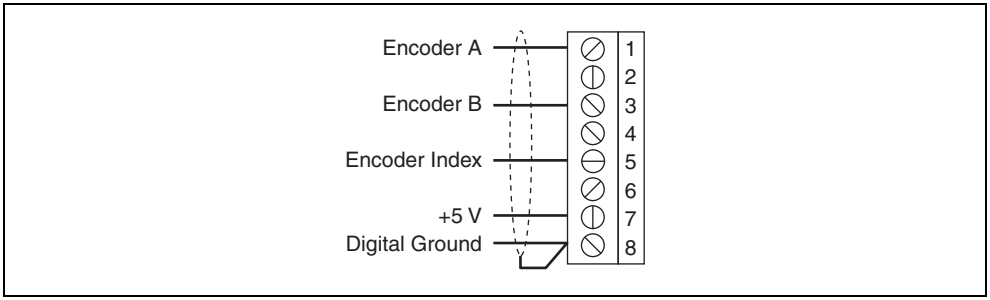


Figure 5. Typical Single-Ended Encoder Wiring Pin Assignment

Figure 6 shows the typical encoder wiring pin assignment for differential line driver signal inputs.

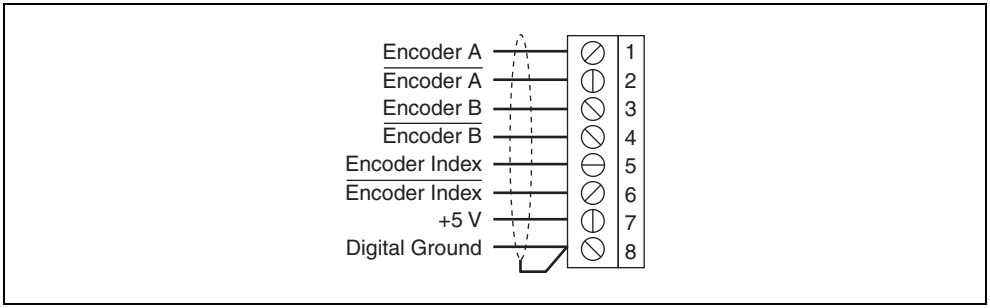


Figure 6. Typical Differential Line Driver Encoder Wiring Pin Assignment

If the encoder cable length is greater than 3.05 m (10 ft), use encoders with line driver outputs for your applications. Power for a +5 V encoder—generated by a power supply inside the MID-7604/7602—is available on pin 7.

Note If you require other encoder power voltages, reference an external power supply to the Digital Ground signal on the 8-pin encoder terminal block.

The MID-7604/7602 supports differential inputs for Phase A, Phase B, and Index signals. You can easily accommodate encoders with various phase relationships by swapping the signals and/or connecting them to the inverting inputs as specific applications require. The Index signal must occur when both Phase A and Phase B signals are low, as shown in Figure 7. If the Index polarity is inverted, try reversing the Index and $\overline{\text{Index}}$ signals on differential encoders or using the $\overline{\text{Index}}$ input on single-ended encoders.

Figure 7 shows the proper encoder phasing for CW (forward) motor rotation.

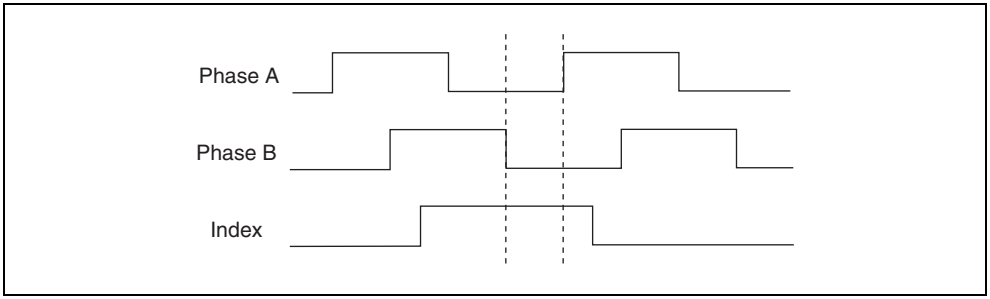


Figure 7. Encoder Signal Phasing, CW Rotation

Closed-loop stepper applications require consistent directional polarity between the motor and encoder for correct operation. The National Instruments motion control standard directional polarity is as follows:

- Positive = forward = clockwise (CW) facing motor shaft
- Negative = reverse = counter-clockwise (CCW) facing motor shaft

Figure 8 shows clockwise and counter-clockwise motor rotation.

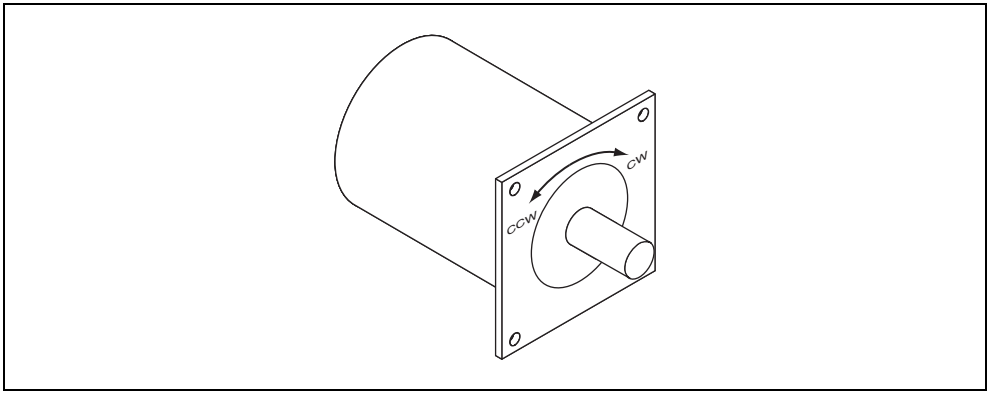


Figure 8. Clockwise and Counter-Clockwise Motor Rotation

When connecting the encoder wiring to your MID-7604/7602, use shielded wire of at least 24 AWG. Analog noise filters filter the encoder inputs in the MID-7604/7602. You must use cables with twisted pairs and an overall shield for improved noise immunity and enhanced encoder signal integrity. Figure 9 shows twisted pairs in a shielded cable.

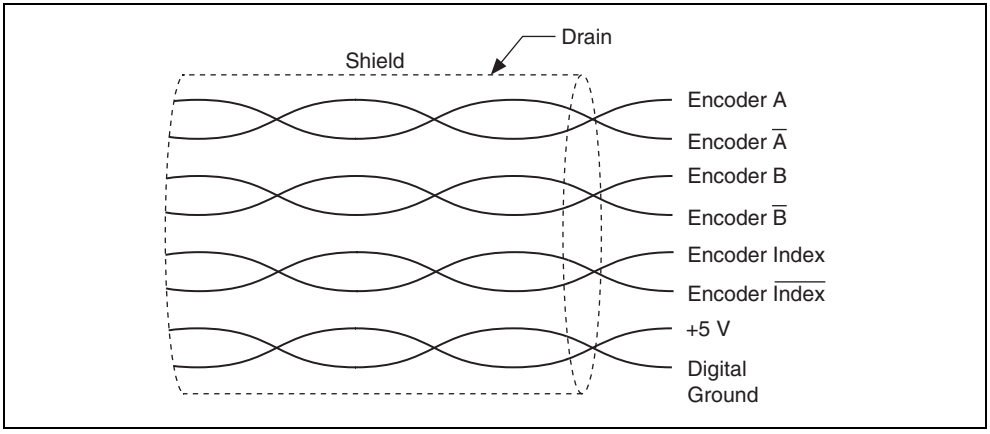


Figure 9. Shielded Twisted Pairs

Note If you use an unshielded cable, noise can corrupt the encoder signals, resulting in lost counts, reduced accuracy, and other erroneous encoder and controller operation.

Limit Switch Terminal Blocks

For end-of-travel limit, home, inhibit input, and inhibit output connections, MID-7604/7602 axes have a separate, 6-position removable screw terminal connector block. Figure 10 shows the limit switch terminal block pin assignments.

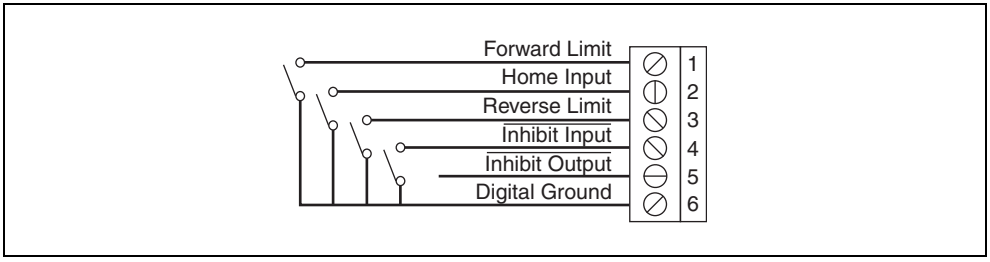


Figure 10. Limit Switch Terminal Block Pin Assignment
(Passive Limit Switch Connection Example)

The inhibit output signal is asserted low from the MID-7604/7602 when an axis is inhibited. This signal can be useful for actuating mechanical brakes or for monitoring an axis status. An axis is inhibited if the host bus interlock circuitry is activated, if the ENABLE switch on the front panel is in the inhibit position, if the motion controller's inhibit signal is low, or if the per-axis inhibit input is actively driven.

The MID-7604/7602 stepper drive remains in a reset state for 500 ms after the inhibit is deasserted. Therefore, you can lose steps if you attempt to issue a start motion command within 500 ms from the deassertion of the stepper drive inhibit. A Kill command asserts the inhibit signal from the controller and a Halt command deasserts the inhibit signal from the controller. The yellow LEDs (middle row) and red LEDs (top row) on the front panel illuminate if an axis is currently inhibited (killed state).

Note In older versions of the MID-7604/7602, the red status LEDs do not illuminate when the yellow status LEDs illuminate. This behavior only occurs in newer versions of the MID-7604/7602.

Execute a halt stop to de-assert the inhibit signal from the controller, after which you must wait at least 500 ms before executing a start.

Breakpoint and Trigger Terminal Blocks

Both the breakpoint and trigger connectors use a 6-pin removable terminal block.

The trigger terminal block provides access to the trigger input lines, shutdown input line, and digital ground. The breakpoint terminal block provides access to the breakpoint output lines, +5 V supplied by the MID-7604/7602, and digital ground. Figures 11 and 12 show the breakpoint and trigger 6-position terminal block assignments.

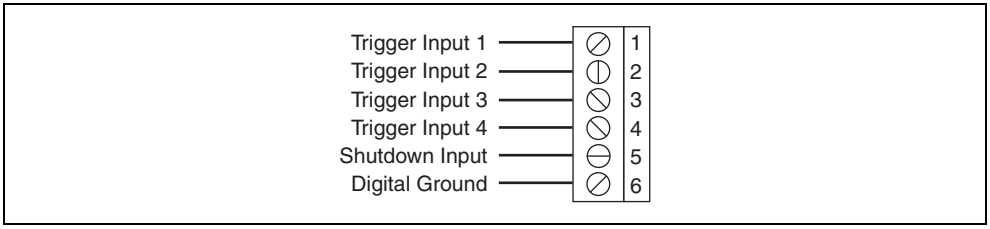


Figure 11. Trigger Terminal Block Pin Assignment

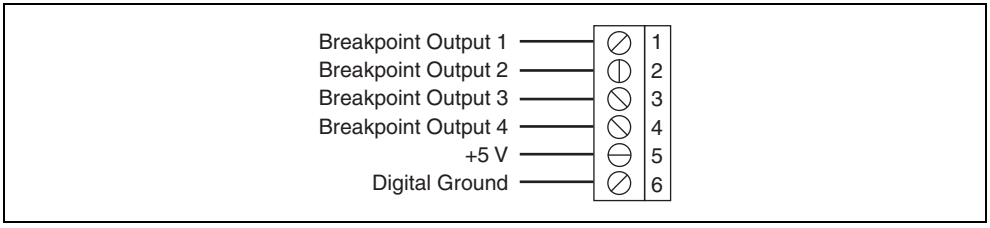


Figure 12. Breakpoint Terminal Block Pin Assignment

Analog I/O Terminal Blocks

The MID-7604/7602 has two analog I/O connectors. The analog input connector uses a 6-pin removable terminal block, and the analog output connector uses a 5-pin removable terminal block.

The analog input terminal block provides access to four analog-to-digital converter channels, an analog reference voltage from the converter circuit, and an analog input ground signal. The analog output terminal block provides access to four digital-to-analog converter channels with ±10 V output range and analog output ground. Refer to Figures 13 and 14 for terminal block pin assignments.

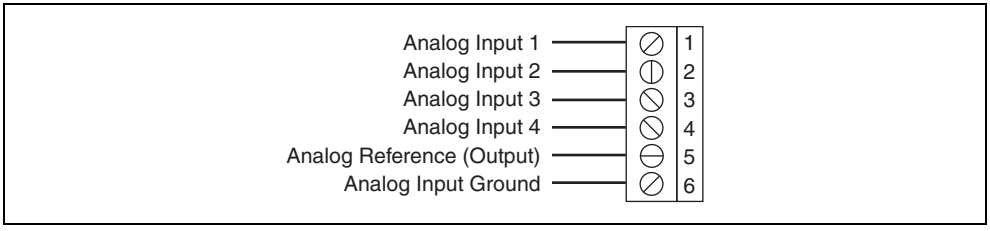


Figure 13. Analog Input Terminal Block Pin Assignment

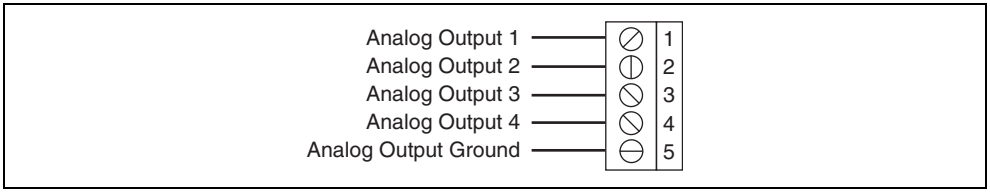


Figure 14. Analog Output Terminal Block Pin Assignment

Accessories for Optional Use

Strain-Relief Bar

The strain-relief bar provides strain relief for wiring to the back panel terminals of the MID-7604/7602.

The arms of the strain-relief bar attach to the sides of the MID-7604/7602 with the thumb nuts facing upward, as shown in Figure 15.

Using the provided screws, attach the strain-relief bar to the rear set of screwholes on the side panels of the MID-7604/7602.

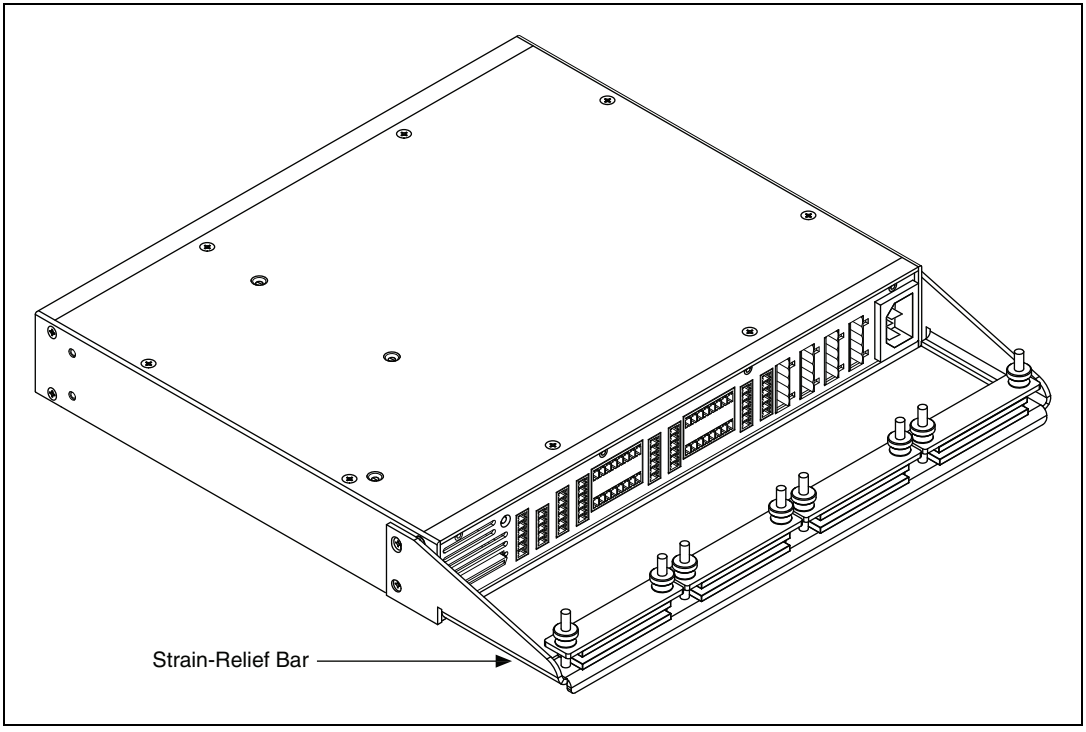


Figure 15. MID-7604/7602 with the Strain-Relief Bar Installed

Panel-Mount Kit (Included)

The panel-mount kit allows you to mount the MID-7604/7602 inside a cabinet or enclosure. Using the provided screws, attach the panel-mount kit to the rear and front set of screw holes on the side panels of the MID-7604/7602, as shown in Figure 16.

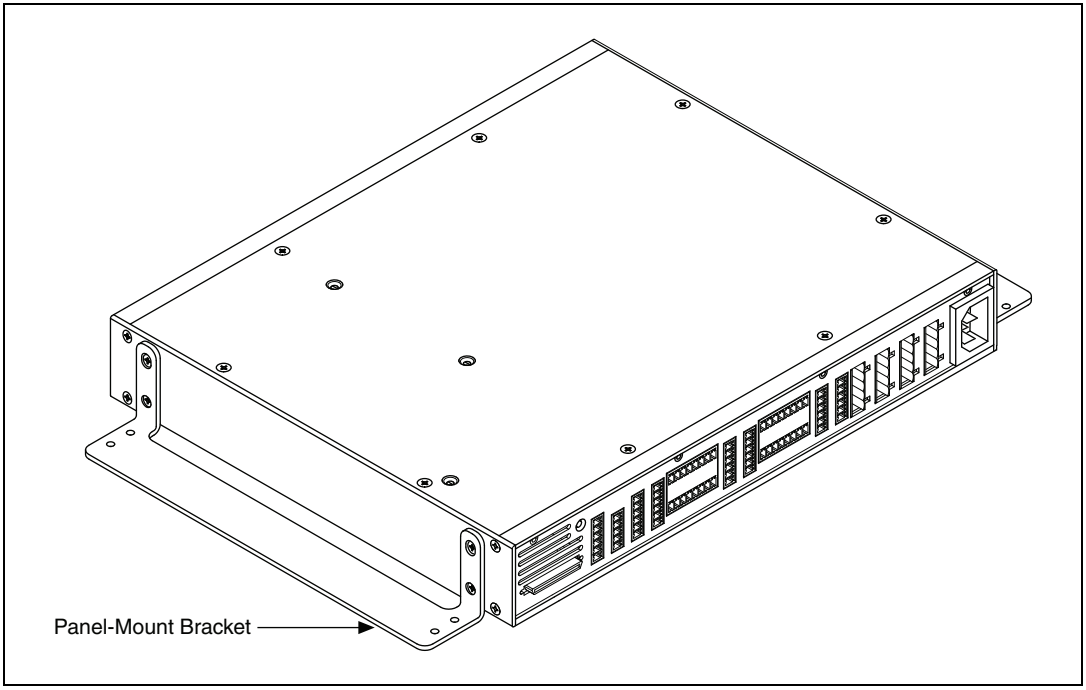


Figure 16. MID-7604/7602 with the Panel-Mount Kit Installed

Note The strain-relief bar and panel-mount kit cannot be installed at the same time.

Amplifier/Driver Command Signals

For stepper drivers, the two industry standards for command signals are as follows:

- Step and Direction signals (MID-7604/7602 standard)
- Independent CW and CCW pulses

The MID-7604/7602 uses stepper drivers that have active high step and direction inputs. You must configure the stepper outputs of your motion controller for Step and Direction signals with active high polarity.

Note You can use National Instruments Measurement & Automation Explorer (MAX) to configure the stepper polarity for your NI motion controller.

Stepper Motor Configurations

This section describes the various industry-standard winding configurations for stepper motors and shows how to connect them to a MID-7604/7602. The MID-7604/7602 is compatible with all configurations of two-phase stepper motors.

Note The MID-7604/7602 is *not* compatible with five-lead unipolar stepper motors or five-phase stepper motors.

Two-phase stepper motors come in 4-, 6-, and 8-wire variations. Figure 17 shows a 6-wire and an 8-wire stepper motor. A 4-wire motor is the same as a 6-wire motor except that the center taps (CT) are not brought out.

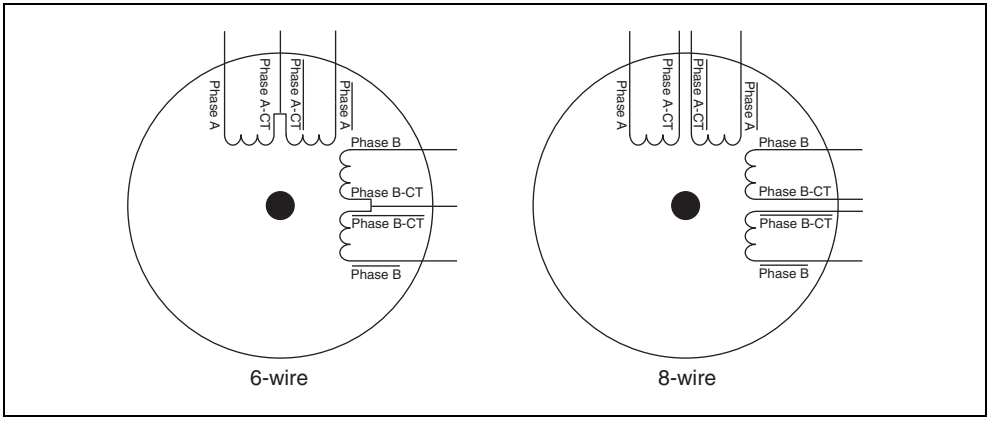


Figure 17. 6-Wire and 8-Wire Stepper Motors

For maximum flexibility, you can connect 8-wire stepper motors in either a series or parallel configuration. Connecting the windings in a series, as shown in Figure 18, produces the most torque per amp but has the disadvantage of higher inductance and poorer high-speed performance.

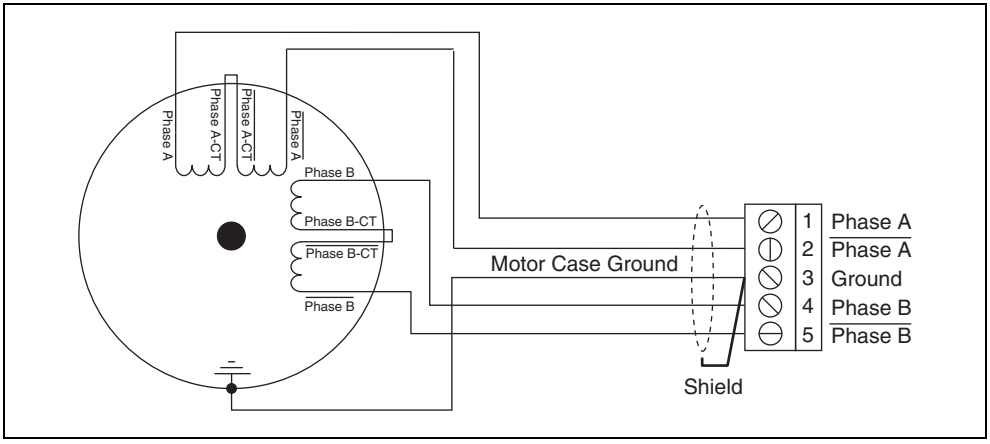


Figure 18. Series Stepper Motor Wiring (Higher Torque, Lower Speed)

Alternatively, you can wire 8-wire stepper motors in parallel as shown in Figure 19. This configuration produces better high-speed performance but requires more current to produce rated torque.

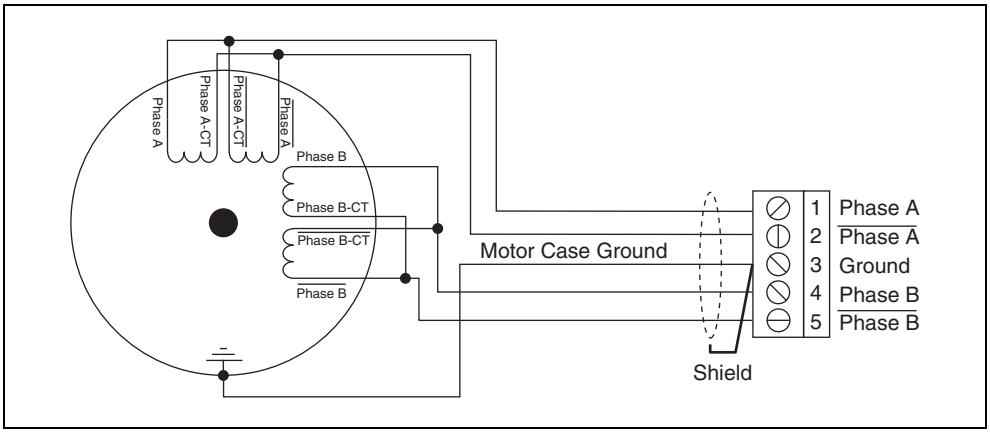


Figure 19. Parallel Stepper Motor Wiring (Higher Speed, Lower Torque)

Notice that an 8-wire motor wired in series is virtually identical to a 6-wire motor and typically has the same high-torque but low-speed characteristics. While a parallel configuration is not possible with a 6-wire motor, you can usually obtain high-speed performance with the half-coil connection shown in Figure 20. This configuration sacrifices low-speed torque for better high-speed performance. With this configuration, it is typically not possible to produce the rated torque of the motor without the risk of the motor overheating because only half of the windings are being used.

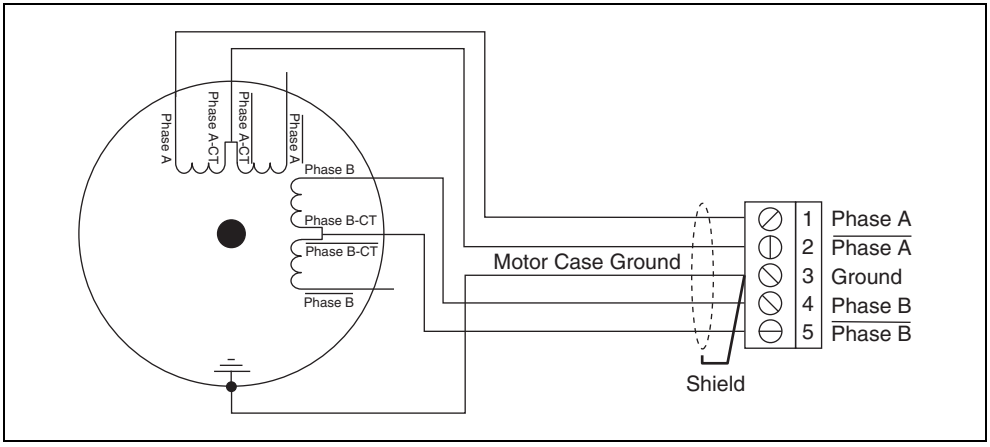


Figure 20. Half-Coil Stepper Motor Wiring

Figure 21 shows the wiring for a typical 4-wire motor.

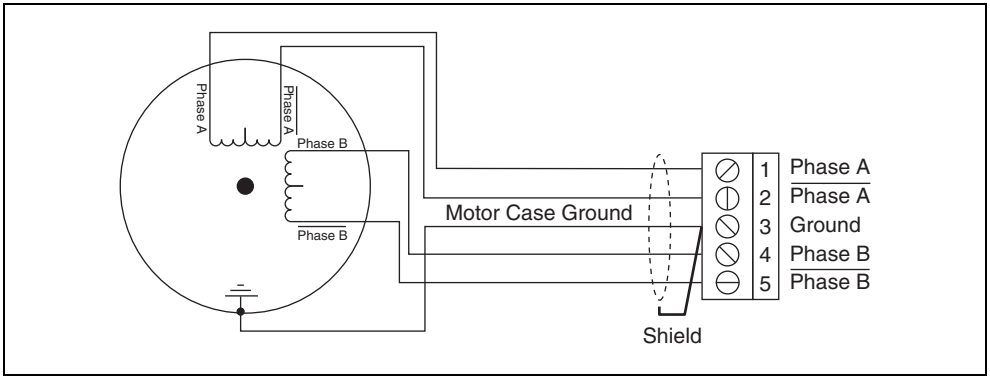


Figure 21. 4-Wire Motor Wiring

Specifications

The following specifications apply only to the MID-7604/7602. To obtain a complete system specification, you must account for your motion controller. Refer to your controller specifications to determine overall system specifications.

Some signals have compatibility defined as signal pass-through, which means the MID-7604/7602 may have passive filtering on these signals but will not affect the voltage range or current handling capability. Consult your motion controller specifications to determine the allowable voltage range and logic level compatibility of the signal.

Stepper Amplifiers

Type.....IM481H modular hybrid, bipolar chopper

Chopping frequency.....20 kHz

DC-bus motor.....24 VDC nominal

Current per phase.....0.20 to 1.4 A peak
(0.14 to 1 A RMS)
(factory setting is 0.50 A peak)

Microstepping selections.....×2, 4, 8, 16, 32, 64, 128, 256
×5, 10, 25, 50, 125, 250
(factory default is ×10 microsteps/step)

Continuous power output rating
(all axes combined).....80 W continuous

Motion I/O

Encoder inputs.....Quadrature, incremental

- Voltage range.....0 to 5 VDC
- Differential input threshold.....± 0.3 V (typical)
- Single ended input threshold.....TTL/CMOS
- Noise filter (RC time constant).....100 ns
- Maximum quadrature frequency.....1 MHz

Limit and home switch inputs compatibility .....Signal pass-through

Inhibit inputs
- Voltage range .....0 to 12 VDC
  - Inhibit low voltage .....0.8 V
  - Inhibit high voltage .....2 V

Inhibit output
- Voltage range .....0 to 5 VDC
  - Output low voltage.....0.5 V at 64 mA
  - Output high voltage.....2.4 V at 32 mA

Trigger input compatibility .....Signal pass-through
- Noise filter (RC time constant) .....100 ns

Breakpoint output compatibility .....Signal pass-through

Analog input compatibility .....Signal pass-through
- Noise filter (RC time constant) .....10 µs

Analog output compatibility .....Signal pass-through

Shutdown input compatibility.....Signal pass-through

+5 V output .....1 A

Included Connectors

Encoders.....8-position mini-combicon 3.81 mm plug (1 per axis)

Limits .....6-position mini-combicon 3.81 mm plug (1 per axis)

Motors .....5-position combicon 5.08 mm plug (1 per axis)

Breakpoints .....6-position mini-combicon 3.81 mm plug (1 total)

Triggers .....6-position mini-combicon 3.81 mm plug (1 total)

Analog input .....6-position mini-combicon 3.81 mm plug (1 total)

Analog output .....5-position mini-combicon 3.81 mm plug (1 total)

AC power .....Detachable AC power cord (IEC standard type)

Motion I/O .....68-pin female high density VHDCI type

Power Supply

Input voltage .....115/230 VAC, 2/1 A, 60/50 Hz

Measurement category II

Fuse
- 115 VAC input (factory default) .....F3A 250V (Bussmann #GMA-3)
- 230 VAC input .....F1.5A 250V (Bussmann #GMA-1.5)
- Dimensions .....5 mm × 20 mm

Host Bus Voltage Interlock

Undervoltage threshold.....4 VDC

Physical Characteristics

Dimensions (W × H × L) .....25.4 cm × 4.3 cm × 30.7 cm
(10 in. × 1.7 in. × 12.1 in.)

Weight .....4.5 kg (10 lb.)

Environment

Operating temperature .....0 ºC to 40 ºC

Storage temperature .....–20 ºC to 70 ºC

Humidity .....10% to 90% RH, noncondensing

Maximum altitude.....2,000 m

Pollution Degree 2

Safety

This product is designed to meet the requirements of the following standards of safety for electrical equipment for measurement, control, and laboratory use:

- EN 61010-1, IEC 61010-1
- UL 508C, UL 61010-1
- CAN/CSA C22.2 No. 61010-1

UL Listed to UL 508C, power conversion equipment.

Note For UL and other safety certifications, refer to the product label or the *Online Product Certification* section.

Electromagnetic Compatibility

This product meets the requirements of the following EMC standards for electrical equipment for measurement, control, and laboratory use:

- Emissions: EN 55011 Class A at 10 m FCC Part 15A above 1 GHz
- Immunity: EN 61326:1997 + A2:2001, Table 1
- CE, C-Tick, and FCC Part 15 (Class A) Compliant

Note For the standards applied to assess the EMC of this product, refer to the *Online Product Certification* section.

Note For EMC compliance, operate this device according to the documentation.

CE Compliance CE

This product meets the essential requirements of applicable European Directives as follows:

- 73/23/EEC; Low-Voltage Directive (safety)
- 89/336/EEC; Electromagnetic Compatibility Directive (EMC)

Online Product Certification

Refer to the product Declaration of Conformity (DoC) for additional regulatory compliance information. To obtain product certifications and the DoC for this product, visit `ni.com/certification`, search by module number or product line, and click the appropriate link in the Certification column.

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Waste Electrical and Electronic Equipment (WEEE)

EU Customers At the end of the product life cycle, all products *must* be sent to a WEEE recycling center. For more information about WEEE recycling centers, National Instruments WEEE initiatives, and compliance with WEEE Directive 2002/96/EC on Waste and Electronic Equipment, visit `ni.com/environment/weee`.

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Where to Go for Support

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