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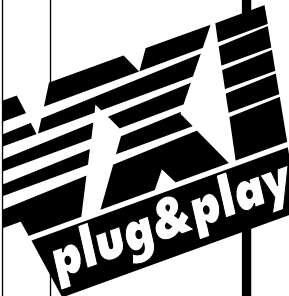
**VME-MXI-2**



**MXI**

# Getting Started with Your VXI/VME-AT4000 Series and the NI-VXI™ Software

January 1997 Edition  
Part Number 371698A-01





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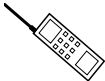
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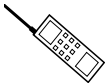
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This manual contains instructions for installing and configuring the National Instruments VXI-AT4000 or VME-AT4000 Series interface kit. The VXI-AT4000 kit includes a VXI-MXI-2 module, which plugs into a VXI mainframe and links your PC AT or compatible computer to the VXIbus. The VME-AT4000 kit comes with a VME-MXI-2 that plugs into a VME chassis and links your PC AT to the VMEbus. Both kits include the AT-MXI-2 interface board, which links your computer to the MXIbus, and the NI-VXI bus interface software. The NI-VXI software is fully *VXIplug&play* compliant.

This manual uses the term *VXI/VME-AT4000* when information applies to either kit and the term *VXI/VME-MXI-2* when information applies to either the VXI-MXI-2 or the VME-MXI-2.

## Organization of This Manual

---

This manual is organized as follows:

- Chapter 1, *Introduction and Quick Start*, describes the VXI/VME-AT4000 interface kits, lists what you need to get started, introduces the concepts of MXI-2, and includes a brief description of the hardware and software. This chapter also contains a *Quick Start* section, which has the basic information you need to install the VXI/VME-AT4000 interface kit with a simple configuration along with a list of the hardware and software default settings for easy reference.
- Chapter 2, *AT-MXI-2 Configuration and Installation*, contains the instructions to configure and install the AT-MXI-2 module.
- Chapter 3, *VXI-MXI-2 Configuration and Installation*, contains the instructions to configure and install the VXI-MXI-2 module. This chapter applies only if you ordered the VXI-AT4000 interface kit.
- Chapter 4, *VME-MXI-2 Configuration and Installation*, contains the instructions to configure and install the VME-MXI-2 module. This chapter applies only if you ordered the VME-AT4000 interface kit.

- Chapter 5, *NI-VXI Software Installation*, contains the instructions to install the NI-VXI software.
- Chapter 6, *NI-VXI Configuration Utility*, contains instructions for using the VXI Resource Editor utility of the NI-VXI software to configure the AT-MXI-2 and the VXI-MXI-2 or VME-MXI-2.
- Chapter 7, *Using the NI-VXI Software*, discusses programming information for you to consider when developing applications that use the NI-VXI driver.
- Appendix A, *Specifications*, lists various module specifications of the AT-MXI-2, VXI-MXI-2, and VME-MXI-2 such as physical dimensions and power requirements.
- Appendix B, *NI-VXI Software Overview*, lists and describes the main programs and files that make up the NI-VXI software.
- Appendix C, *EEPROM Configuration*, describes how to control the operation of the AT-MXI-2 onboard EEPROM and how to fix an invalid EEPROM setting.
- Appendix D, *Common Questions*, addresses common questions you may have about using the NI-VXI bus interface software on the AT-MXI-2 platform.
- Appendix E, *Customer Communication*, contains forms you can use to request help from National Instruments or to comment on our products and manuals.
- The *Glossary* contains an alphabetical list and description of terms used in this manual, including abbreviations, acronyms, metric prefixes, mnemonics, and symbols.
- The *Index* contains an alphabetical list of key terms and topics used in this manual, including the page where you can find each one.

# Conventions Used in This Manual

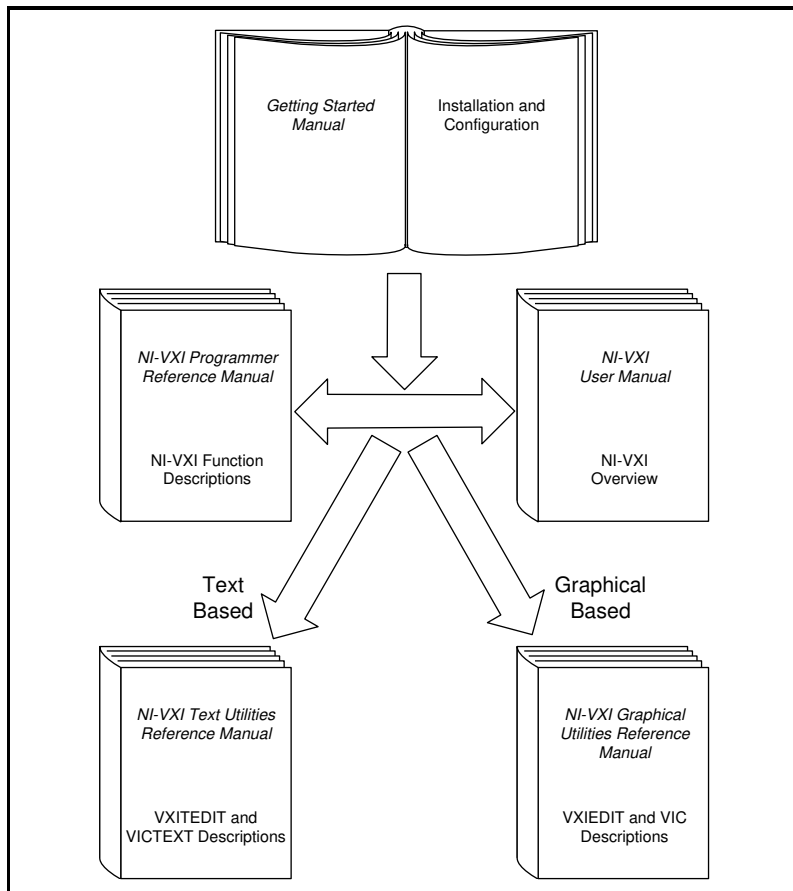
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The following conventions are used in this manual:

<b>bold</b>	Bold text denotes menus, menu items, or dialog box buttons or options.
<b><i>bold italic</i></b>	Bold italic text denotes a note, caution, or warning.
<b>bold</b>	Bold text in this font denotes the messages and responses that the computer automatically prints to the screen.
<b>monospace</b>	
<i>italic</i>	Italic text denotes emphasis, a cross reference, or an introduction to a key concept.
monospace	Text in this font denotes text or characters that are to be literally input from the keyboard, sections of code, programming examples, and syntax examples. This font is also used for the proper names of disk drives, paths, directories, programs, subprograms, subroutines, device names, functions, variables, filenames, and extensions, and for statements and comments taken from program code.
◆	The ◆ symbol indicates that the text following it applies only to a specific product, a specific operating system, or a specific software version.
< >	Angle brackets enclose the name of a key on the keyboard—for example, <PageDown>.
-	A hyphen between two or more key names enclosed in angle brackets denotes that you should simultaneously press the named keys—for example, <Control-Alt-Delete>.
	Abbreviations, acronyms, metric prefixes, mnemonics, symbols, and terms are listed in the <i>Glossary</i> .

# How to Use This Documentation Set

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Begin by reading this getting started manual to guide you through the installation and configuration of the hardware and software. You should install and configure the components of the VXI/VME-AT4000 kit in the order in which this manual describes them. Be sure to review the *Quick Start* and *Default Settings* sections in Chapter 1. The material in those sections may be all you need to get up and running with your VXI/VME-AT4000 kit.

When you are familiar with the material in this getting started manual, you can begin to use the *NI-VXI User Manual*. This manual presents the concepts of VXI and prepares you for detailed explanations of the

NI-VXI functions. Study the descriptions of each function given in the *NI-VXI Programmer Reference Manual* to fully understand the purpose and syntax of each function.

Refer to the *NI-VXI Graphical Utilities Reference Manual* and the *NI-VXI Text Utilities Reference Manual* to learn more about the NI-VXI utilities.

## Related Documentation

---

The following documents contain information that you may find helpful as you read this manual:

- ANSI/IEEE Standard 1014-1987, *IEEE Standard for a Versatile Backplane Bus: VMEbus*
- ANSI/IEEE Standard 1155-1993, *IEEE VMEbus Extensions for Instrumentation: VXIbus*
- ANSI/VITA 1-1994, *VME64*
- *Multisystem Extension Interface Bus Specification*, Version 2.0, National Instruments Corporation
- *VXI-MXI-2 User Manual*, National Instruments Corporation
- *VME-MXI-2 User Manual*, National Instruments Corporation
- *VXI-6, VXIbus Mainframe Extender Specification*, Rev. 1.0, VXIbus Consortium

## Customer Communication

---

National Instruments wants to receive your comments on our products and manuals. We are interested in the applications you develop with our products, and we want to help if you have problems with them. To make it easy for you to contact us, this manual contains comment and configuration forms for you to complete. These forms are in Appendix E, *Customer Communication*, at the end of this manual.



# Introduction and Quick Start

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Chapter

1

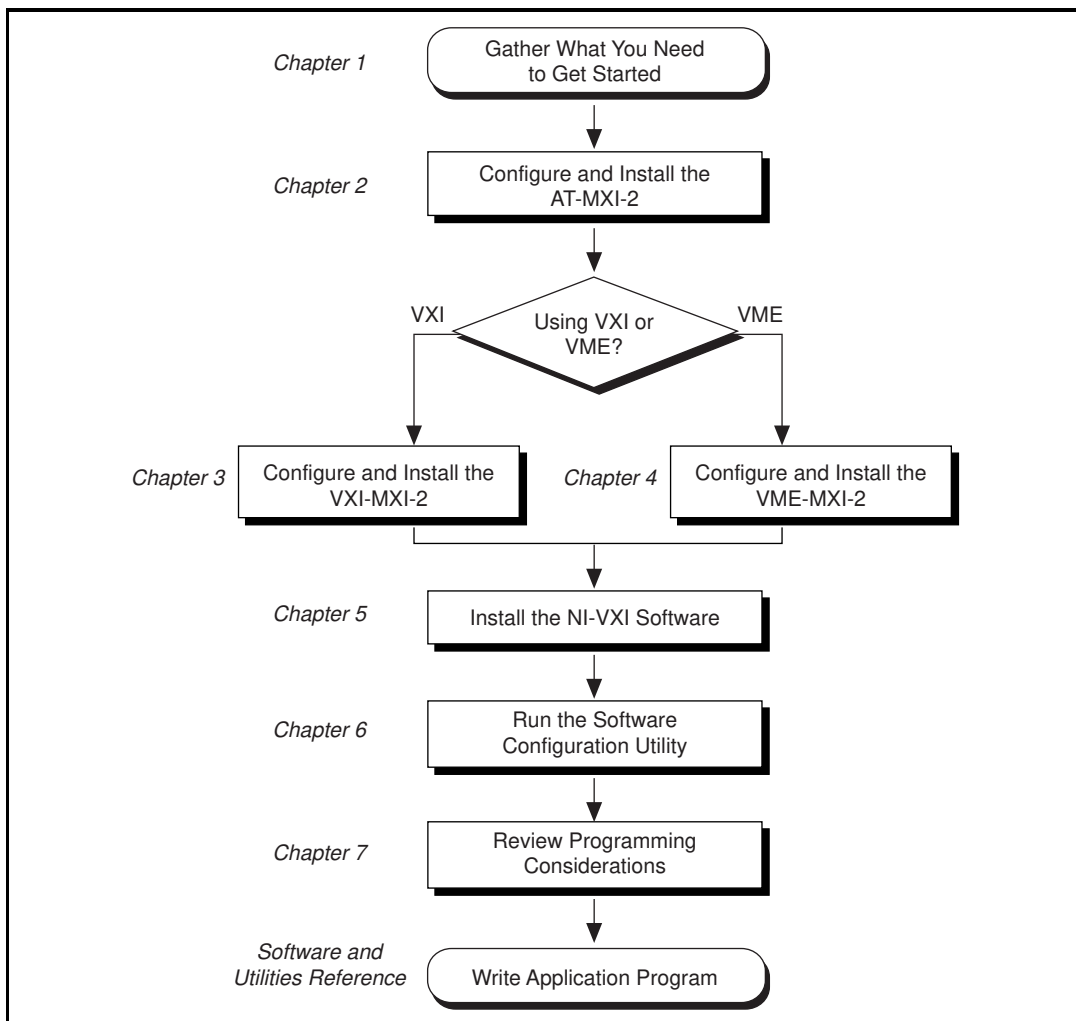
This chapter describes the VXI/VME-AT4000 interface kits, lists what you need to get started, introduces the concepts of MXI-2, and includes a brief description of the hardware and software.

This chapter also contains a *Quick Start* section, which has the basic information you need to install the VXI/VME-AT4000 interface kit with a simple configuration, along with a *Default Settings* section, which lists the hardware and software default settings for easy reference. You may find that these sections contain as much information as you need to get started with your VXI/VME-AT4000 interface kit.

This manual uses the term *VXI/VME-AT4000* when information applies to either the VXI-AT4000 kit, which contains a VXI-MXI-2 module, or the VME-AT4000 kit, which contains a VME-MXI-2 module. Similarly, the term *VXI/VME-MXI-2* means that information applies to either the VXI-MXI-2 or the VME-MXI-2.

The following flowchart shows where to turn in this manual for more details on configuring and using the hardware and software.

# How to Use This Manual



## VXI/VME-AT4000 Kit Overview

---

The VXI/VME-AT4000 interface kits link any PC AT or compatible computer (hereafter referred to as a PC AT) directly to the VXIbus or VMEbus using the high-speed Multisystem eXtension Interface bus (MXI-2).

A PC AT equipped with a VXI-AT4000 interface can function as a VXI Commander and Resource Manager. A PC AT equipped with a VME-AT4000 can function as a VMEbus master and/or slave device. The VXI/VME-AT4000 makes your PC AT behave as though it were plugged directly into the VXI/VME backplane as an embedded CPU VXI/VME module.

The software included with the kits is for x86/Pentium-based computers.

## What You Need to Get Started

---

- A PC AT
- VXIbus or VMEbus mainframe
- AT-MXI-2 interface board
- VXI-MXI-2 or VME-MXI-2 interface module
- MXI-2 cable
- NI-VXI software media for the AT-MXI-2

## MXI-2 Description

---

MXI-2 is the second generation of the National Instruments MXIbus product line. The MXIbus is a general-purpose, 32-bit, multimaster system bus on a cable. MXI-2 expands the number of signals on a standard MXI cable by including VXI triggers, all VXI interrupts, CLK10, and all of the utility bus signals (SYSFAIL\*, SYSRESET\*, and ACFAIL\*).

Because MXI-2 incorporates all of these new signals into a single connector, the triggers, interrupts, and utility signals can be extended not only to other mainframes but also to the local CPU in all MXI-2

products using a single cable. Thus, MXI-2 lets CPU interface boards such as the AT-MXI-2 perform as though they were plugged directly into the VXI/VME backplane.

In addition, MXI-2 boosts data throughput performance past previous-generation MXIbus products by defining new high-performance protocols. MXI-2 is a superset of MXI. All accesses initiated by MXI devices will work with MXI-2 devices. However, MXI-2 defines synchronous MXI block data transfers which surpass previous block data throughput benchmarks. The new synchronous MXI block protocol increases MXI-2 throughput to a maximum of 33 MB/s between two MXI-2 devices. All National Instruments MXI-2 boards are capable of initiating and responding to synchronous MXI block cycles.



**Note:** *In the remainder of this manual, the term MXIbus refers to MXI-2.*

## Hardware Description

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The AT-MXI-2 is a full-size, AT-compatible Plug and Play circuit board that plugs into one of the expansion slots in your PC AT. It links your computer directly to the MXIbus and vice versa. Because the AT-MXI-2 uses the same communication register set that other VXIbus message-based devices use, other MXIbus devices view the AT-MXI-2 as a VXIbus device. The AT-MXI-2 can also function as the MXIbus System Controller and can terminate the MXIbus signals directly on the AT-MXI-2. In addition, you can have up to 16 MB of onboard DRAM on the AT-MXI-2 that can be shared with the MXIbus and VXI/VMEbus and used as a dedicated data buffer.

The VXI-MXI-2 module is an extended-class, register-based VXIbus device with optional VXIbus Slot 0 capability so that it can reside in any slot in a C-size or D-size chassis.



**Note:** *D-size VXI mainframes have connections for a P3 connector. The VXI-MXI-2, however, does not have this connector and, if configured as a Slot 0 controller, cannot provide the necessary control for VXI devices that need P3 support.*

The VXI-MXI-2 uses address mapping to convert MXIbus cycles into VXIbus cycles and vice versa. By connecting to the AT-MXI-2 board, the VXI-MXI-2 links the AT bus to the VXIbus. The VXI-MXI-2 can

automatically determine whether it is located in VXI Slot 0 and/or if it is the MXIbus System Controller.

The VME-MXI-2 module is a single-slot, double-height VMEbus device with optional VMEbus System Controller functions. It uses address mapping to convert MXIbus cycles into VMEbus cycles and vice versa, just like the VXI-MXI-2. By connecting to the AT-MXI-2 board, it links the AT bus to the VMEbus. The VME-MXI-2 can automatically determine if it is located in the first slot of a VMEbus chassis and if it is the MXIbus System Controller.

Also, the VXI-MXI-2 and VME-MXI-2 automatically terminate the MXIbus if installed as the first or last device in the MXIbus. If installed in the middle of the MXIbus, both the VXI-MXI-2 and VME-MXI-2 automatically disable MXIbus termination. In addition, you can have up to 64 MB of onboard DRAM on the VXI-MXI-2 and VME-MXI-2 modules that can either be shared with the VXI/VMEbus and MXIbus or used as a dedicated data buffer.

The AT-MXI-2, VXI-MXI-2, and VME-MXI-2 products achieve high-performance block transfer rates by integrating the MITE custom ASIC, a sophisticated dual-channel DMA controller with standard interfaces for VXI, VME, MXI, and AT. By using MITE DMA to transfer data and commands to and from devices, the MITE frees up a computer's microprocessor to perform other tasks such as data analysis and presentation. In addition to DMA, the MITE incorporates both the new Synchronous MXI protocol and VME64 MBLT (8-byte block transfers in which both the address bus and data bus are used to transfer data) directly into the ASIC to perform the fastest transfer operation to instruments.

## Software Description

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The NI-VXI bus interface software for the AT-MXI-2 includes a Resource Manager, graphical and text-based versions of an interactive VXI resource editor program, a comprehensive library of software routines for VXI/VME programming, and an interactive control program for interacting with VXI/VME. You can use this software to seamlessly program multiple-mainframe configurations and have software compatibility across a variety of VXI/VME controller platforms.

## Optional Software

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Your VXI/VME-AT4000 kit includes the NI-VXI bus interface software. In addition, you can use the National Instruments LabVIEW and LabWindows®/CVI application programs and instrument drivers to ease your programming task. These standardized programs match the modular virtual instrument capability of VXI and can reduce your VXI/VMEbus software development time. These programs are fully *VXIplug&play* compliant and feature extensive libraries of VXI instrument drivers written to take full advantage of direct VXI control.

LabVIEW is a complete programming environment that departs from the sequential nature of traditional programming languages and features a graphical programming environment.

LabWindows/CVI is an interactive C development environment for building test and measurement and instrument control systems. It includes interactive code-generation tools and a graphical editor for building custom user interfaces.

LabVIEW and LabWindows/CVI include all the tools needed for instrument control, data acquisition, analysis, and presentation. When you order the LabVIEW VXI Development System for Windows or the LabWindows/CVI VXI Development System for Windows, you also get more than 500 complete instrument drivers, which are modular, source-code programs that handle the communication with your instrument to speed your application development.

## Quick Start

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You can use this *Quick Start* section as a guide to quickly configure and operate your VXI or VME system using the AT-MXI-2 and the VXI-MXI-2 or VME-MXI-2. The *Quick Start* summary assumes that you intend to perform a basic configuration as follows:

- You have one AT-MXI-2 interface module, which you will install in your PC AT as the Resource Manager (logical address 0).
- You have either one C-size VXI-MXI-2 or one 6U, B-size VME-MXI-2, which you will install in a VXI or VME chassis, respectively, and connect to the AT-MXI-2.
- You will be using the NI-VXI software for initialization, configuration, and device interaction.

- You will use the default hardware and software settings.
  - The AT-MXI-2 is the main controller, the VXI/VME Resource Manager, and a message-based device.
  - The AT-MXI-2 is software configured to use IRQ level 11, DMA channel 6, I/O ports 340h to 34Fh, and memory region C800h to DFFFh. See the *Resolving a Resource Conflict* section in Chapter 5, *NI-VXI Software Installation*, if your system already uses any of these resources.
  - Your system contains only one VXI or VME chassis.
  - There is no shared memory used on the PC AT, the AT-MXI-2, or the VXI/VME-MXI-2.

Refer to the end of this chapter for a complete listing of the hardware and software default settings. If you need more information, or if you want to try a different configuration, please refer to the subsequent chapters in this manual, which describe the installation and configuration steps in greater detail.

The VXI/VME-AT4000 kit works with either DOS or Windows, but the two operating systems have different installation and configuration requirements. Be sure to observe any specific instructions for DOS or Windows in the following information.

## Hardware Installation

To guard against electrostatic discharge, touch the antistatic plastic package to a metal part of your computer before removing the AT-MXI-2 from the package. Install the AT-MXI-2 in an available expansion slot in your PC AT.

By default, the AT-MXI-2 automatically detects whether it should be the system controller on the MXIbus. Verify that the correct cable end labeled *Connect This End To Device Closest To MXIbus Controller In This Daisy Chain* is attached securely to the AT-MXI-2. The cable must be connected in this manner so that the AT-MXI-2 can correctly detect whether it should be the system controller on the MXIbus. For more information, refer to Chapter 2, *AT-MXI-2 Configuration and Installation*.

You received either a VXI-MXI-2 or a VME-MXI-2 in your VXI/VME-AT4000 kit. To guard against electrostatic discharge, touch the antistatic plastic package to a metal part of your computer before removing the VXI-MXI-2 or VME-MXI-2 from the package. Install

the VXI-MXI-2 in the first slot of a VXI chassis, or install the VME-MXI-2 in the first slot of a VME chassis.

The VXI/VME-MXI-2 default configuration automatically detects whether it should be the VXI/VMEbus system controller. The VXI/VMEbus system controllers operate certain VXI/VMEbus lines as required for VXI/VME systems. Verify that any other VXI/VME devices with system controller capability that are located in the same chassis are not configured as system controller. Having more than one device configured as system controller will damage the VXI/VME system.

For VXI systems that include VME devices, ensure that the VME devices are not configured in the upper 16 KB (starting from 0xC000) of the A16 address space. This region is reserved for VXI device configuration registers, which are used for initializing, configuring, and interacting with VXI devices. The AT-MXI-2 and VME-MXI-2 also use this region for this purpose.

Also ensure that no VXI devices in your system are configured for either logical addresses 0 or 1. These are the default configurations for the AT-MXI-2 and the VXI-MXI-2, respectively.

For more details on the VXI-MXI-2 or VME-MXI-2 hardware, refer to either Chapter 3, *VXI-MXI-2 Configuration and Installation*, or Chapter 4, *VME-MXI-2 Configuration and Installation*.



**Note:** *If you are a DOS user, proceed to the DOS Users section. If you are a Windows user, continue with the following section and then skip the DOS Users section.*

## Windows Users

1. Insert the NI-VXI disk labeled *Disk 1* into the floppy drive and run the Setup program to install the software.



**Note:** *At the end of the installation, you can select the Launch VXIedit to configure the system button. If you decide to run this configuration utility, you cannot enter the VXI/VME-MXI-2 Configuration Editor. The `VXIinit` and `RESMAN` utilities must be executed before you can enter this editor. In addition, if you made any changes within the AT-MXI-2 Configuration Editor, you must exit Windows, reboot the computer, and then proceed with steps 2 and 3.*



2. **Windows 3.x users only**—Locate the NI-VXI group in the Program Manager and run the **VXIinit** item. This utility initializes the AT-MXI-2 hardware.
3. Execute the **Resman** item, which is located within the same NI-VXI group.

## DOS Users

Follow these instructions to install the NI-VXI software for DOS.

1. Insert the NI-VXI disk labeled *Disk 1* into the floppy drive and run the `INSTALL` program to install the software.
2. Execute `VXIinit` from the DOS prompt. This utility initializes the AT-MXI-2 hardware. `VXIinit` also shows where the AT Configuration Manager has placed your AT-MXI-2. If this region conflicts with another board in your system, or if you experience any problems with your system, refer to the *User Window and Driver Window* section in Chapter 6, *NI-VXI Configuration Utility*. Notice that if you are using a memory manager (such as `EMM386.EXE`), you must exclude the region assigned to your AT-MXI-2. This region may shift if you insert additional boards into your PC AT or move your AT-MXI-2 to another slot.
3. Execute `RESMAN` to configure your VXI/VME system.

## VME Users

When used with a VXI-MXI-2, `RESMAN` identifies and configures the VXI devices, including the VXI-MXI-2. When used with a VME-MXI-2, `RESMAN` configures the VME-MXI-2 to allow the AT-MXI-2 to access devices in the VME chassis. `RESMAN` does not configure VME devices. The VME specification does not specify the initialization and configuration procedures that the VXI specification requires.

However, it is recommended that you enter the information about your VME devices into the `VXIedit` or `VXItdedit` utility. `RESMAN` can then properly configure the various device-specific VME address spaces and VME interrupt lines. For more information on configuring non-VXI devices in your VXI system, refer to the description of the **Non-VXI Device Configuration Editor** in Chapter 3, *VXI Resource Editor: VXIedit*, in the *NI-VXI Graphical Utilities Reference Manual*. For more details about installing the NI-VXI software, refer to Chapter 5, *NI-VXI Software Installation*, in this manual.

## Device Interaction

After RESMAN has detected and configured all VXI/VME devices, you can view specific information on each device in your system by using the `VXIedit` or `VXItext` utilities. These utilities include a **Resource Manager Display**, which contains a description for each device, including each VXI device's logical address.

You can interact with your VXI/VME devices by using the `VIC` or `VICtext` utilities. These utilities let you interactively control your VXI/VME devices without having to use a conventional programming language, LabVIEW for Windows, or LabWindows/CVI.

Try the following in `VIC` or `VICtext`:

At the prompt, type:

```
help vxiiinreg
```

This help file shows you the syntax for this command, which reads VXI device configuration registers. The first argument is a logical address, and the second is the offset of the VXI device configuration register to be read.

Now type:

```
vxiiinreg 1,0
```

This should return a value, such as:

```
Return Status (0): SUCCESS.
```

```
value = 0x4ff6
```

If the value ends with `ff6`, you have successfully read the National Instruments manufacturer ID from the ID register for the VXI/VME-MXI-2.

You may now want to read the configuration registers from other VXI devices in your system using the command `vxiiinreg`. This command accesses only the upper 16 KB of A16 space. Try reading the registers from one of the devices listed in the **Resource Manager Display** of either `VXIedit` or `VXItext`. In this way, you can verify that your AT-MXI-2 can access each of the devices in your VXI system successfully.

You can also access VXI and VME devices that are configured in A16, A24, and A32 address space by using the `vxiiin` or `vxiiout` commands.

For more information regarding VIC operation and commands, refer to the *NI-VXI Graphical Utilities Reference Manual*. For more information regarding VIC<sub>text</sub> operation and commands, refer to the *NI-VXI Text Utilities Reference Manual*.

## Default Settings

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This section summarizes the hardware and software default settings for the VXI/VME-AT4000 kit. If you need more information about a particular setting, or if you want to try a different configuration, please refer to the appropriate hardware or software chapters in this manual. The manual flowchart at the beginning of this chapter directs you to where to find the information you need.

### AT-MXI-2

This section summarizes the hardware and software default settings for the AT-MXI-2.

**Table 1-1.** AT-MXI-2 Hardware Default Settings

Hardware Component	Default Setting
U15 Switch 1 (FOV)	OFF: AT-MXI-2 boots off the user-configured half of the EEPROM
U15 Switch 2 (FOV)	OFF: Factory configuration of the EEPROM is protected
U15 Switch 3 (FOV)	OFF: Do not alter this setting
U15 Switch 4 (FOV)	ON: Do not alter this setting
DRAM SIMM Installed	Per customer order

**Table 1-2.** AT-MXI-2 Logical Address Configuration Editor Default Settings

<b>Editor Field</b>	<b>Default Setting</b>
<b>Logical Address</b>	0
<b>Device Type</b>	MBD
<b>Address Space</b>	A16
<b>VXI Shared RAM Size</b>	0 KB
<b>Shared RAM Pool</b>	0 KB
<b>Lower Half Window Byte Swapping</b>	Disabled
<b>Lower Half Window Memory Select</b>	System RAM
<b>Upper Half Window Byte Swapping</b>	Disabled
<b>Upper Half Window Memory Select</b>	System RAM
<b>Map Upper and Lower Halves to Same Address</b>	Disabled
<b>Resource Manager Delay</b>	5 s

**Table 1-3.** AT-MXI-2 Device Configuration Editor Default Settings

<b>Editor Field</b>	<b>Default Setting</b>
<b>Default Controller (LA-1)</b>	First Remote Controller
<b>System IRQ Level</b>	1
<b>Servant Area Size</b>	0
<b>Number of Handlers</b>	1
<b>Number of Interrupters</b>	0
<b>Protocol Register</b>	0xFF0
<b>Read Protocol Response</b>	0x8448

**Table 1-4.** AT-MXI-2 Bus Configuration Editor Default Settings

<b>Editor Field</b>	<b>Default Setting</b>
<b>MXI System Controller</b>	Auto
<b>MXI Bus Timeout Value</b>	1 ms
<b>MXI CLK10</b>	Receive
<b>MXI Transfer Limit</b>	Unlimited
<b>Synchronous MXI</b>	Enabled
<b>MXI-2 Auto Retry</b>	Enabled
<b>A24/A32 Write Posting</b>	Disabled
<b>IRQ Level</b>	11 *
<b>DMA Channel</b>	6 *
<b>I/O Base Address</b>	340 (hex) *
<b>Driver Window Base</b>	C800
<b>Driver Window Size</b>	32 KB
<b>User Window Base</b>	D000
<b>User Window Size</b>	64 KB *
<b>Slave Timeout</b>	2.5 $\mu$ s
<p>* These are values you might need to change to resolve possible conflicts with other resources in your system. Refer to the <i>Resolving a Resource Conflict</i> section in Chapter 5, <i>NI-VXI Software Installation</i>, if your system already uses any of these resources.</p>	

## VXI/VME-MXI-2

This section summarizes the hardware and software default settings for the VXI-MXI-2 and VME-MXI-2.

**Table 1-5.** VXI-MXI-2 Hardware Default Settings

<b>Hardware Component</b>	<b>Default Setting</b>
Logical Address (U43)	1
VXIbus Slot 0/Non-Slot 0 (W2)	Automatic detection
VXIbus Local Bus (S8, S9)	Both OFF: Single VXI-MXI-2
VXIbus CLK10 Routing (W3)	From onboard oscillator
External Trigger Termination (S2)	OFF: Unterminated
SMB CLK10 Direction (S3)	OUT: Drive CLK10 signal
SMB CLK10 Termination (S4)	Ignored; effective only when S3 is set to IN
Polarity of External SMB CLK10 (S5)	Inverted
MXIbus Termination (U35 switches 1 and 2)	Automatic MXIbus termination: switch 2 set to NO; switch 1 ignored
Configuration EEPROM (U35 switches 3 and 4)	User-modifiable; factory settings protected: both switches set to NO
DRAM SIMMs Installed	Per customer order
SIMM Size Configuration	OFF if SIMMs are 4 M x 32 or larger; ON if smaller than 4 M x 32

**Table 1-6.** VME-MXI-2 Hardware Default Settings

<b>Hardware Component</b>	<b>Default Setting</b>
A16 Base Address (U20)	Hex C040
VME-MXI-2 Intermodule Signaling (W2)	No user-defined pin selected
MXIbus Termination (U21 switches 3 and 4)	Automatic MXIbus termination: switch 3 OFF; switch 4 ignored
Configuration EEPROM (U21 switches 1 and 2)	User-modifiable; factory settings protected: both switches OFF
DRAM SIMMs Installed	Per customer order
SIMM Size Configuration (S2)	OFF if SIMMs are 4 M x 32 or larger; ON if smaller than 4 M x 32

**Table 1-7.** VXI/VME-MXI-2 Configuration Editor Default Settings

<b>Editor Field</b>	<b>Default Setting</b>
<b>Logical Address</b>	1 (set by hardware switch)
<b>LA Selection</b>	Set by hardware switch
<b>Address Space</b>	A24*
<b>Requested Memory</b>	16 KB*
<b>A16 Write Posting</b>	Disabled
<b>A24/A32 Write Posting</b>	Disabled
<b>Interlocked Mode</b>	Disabled
<b>VXIVME System Controller</b>	Auto
<b>VXI/VME Bus Timeout Value</b>	125 $\mu$ s
<b>VXI/VME Auto Retry</b>	Disabled

**Table 1-7.** VXI/VME-MXI-2 Configuration Editor Default Settings (Continued)

<b>Editor Field</b>	<b>Default Setting</b>
<b>VXI/VME Transfer Limit</b>	256
<b>VXI/VME Arbiter Type</b>	Priority
<b>VXI/VME Request Level</b>	3
<b>VXI/VME Fair Requester</b>	Enabled
<b>VXI/VME Arbiter Timeout</b>	Enabled
<b>MXI System Controller</b>	Auto
<b>MXI Bus Timeout Value</b>	1 ms
<b>MXI Auto Retry</b>	Disabled
<b>MXI Transfer Limit</b>	Unlimited
<b>MXI Parity Checking</b>	Enabled
<b>MXI Fair Requester</b>	Disabled
<b>MXI CLK10 Signal Direction</b>	Set by hardware switch (VXI-MXI-2 only)
* Assumes no DRAM is installed. If DRAM is installed, the <b>Address Space</b> would be A32, and <b>Requested Memory</b> would match the amount of DRAM.	



# AT-MXI-2 Configuration and Installation

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Chapter

2

This chapter contains the instructions to configure and install the AT-MXI-2 module.



**Warning:** *Electrostatic discharge can damage several components on your AT-MXI-2 module. To avoid such damage in handling the module, touch the antistatic plastic package to a metal part of your computer chassis before removing the AT-MXI-2 from the package.*

## Configure the AT-MXI-2

---

This section describes how to configure the following options on the AT-MXI-2:

- AT Bus configuration
- Onboard DRAM

Figure 2-1 shows the AT-MXI-2. The drawing shows the location and factory-default settings on the module.

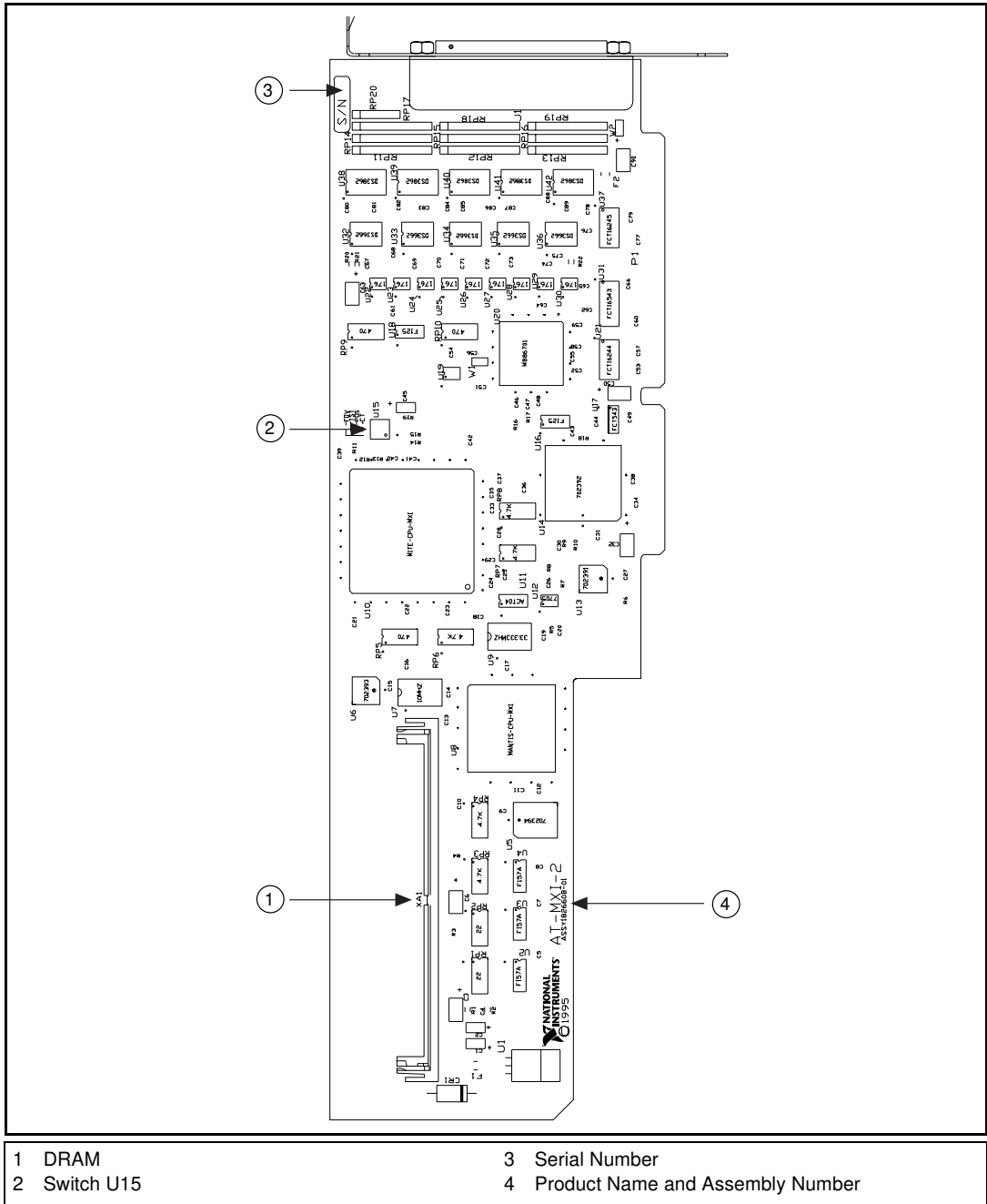


Figure 2-1. AT-MXI-2 Parts Locator Diagram

## AT Bus Configuration

Due to the Plug and Play functionality of the board, the AT-MXI-2 is completely software configurable. Two types of configuration must be performed on the AT-MXI-2: AT Bus configuration and VXI/VME configuration. AT Bus-related configuration includes setting the I/O address, DMA channel, interrupt channel, and memory base address and size.

The AT-MXI-2 board works in either a Plug and Play mode or a switchless mode. The modes dictate how the I/O address, memory base address and size, DMA channel, and interrupt channel are determined and assigned to the board.

The AT-MXI-2 board is fully compatible with the industry-standard Intel/Microsoft Plug and Play specification version 1.0a. A Plug and Play system arbitrates and assigns resources through software, freeing you from manually setting switches and jumpers. These resources include the I/O address, memory base address and size, DMA channel, and interrupt channel. Each AT-MXI-2 is factory configured to request these resources from the Plug and Play Configuration Manager.

The Configuration Manager receives all of the resource requests at startup, compares the available resources to those requested, and assigns the available resources as efficiently as possible to the Plug and Play boards. Application software can query the Configuration Manager to determine the resources assigned to each board without your involvement. The Plug and Play software is installed as a device driver or as an integral component of the computer BIOS.

You can use the AT-MXI-2 board in a non-Plug and Play system as a switchless board. A non-Plug and Play system is a system in which the Configuration Manager has not been installed and which does not contain any non-National Instruments Plug and Play products. You use `VXIedit`, an NI-VXI software configuration utility, to enter the I/O base address, memory base address and size, DMA and interrupt selections, and the application software assigns them to the board.



**Note:** *Avoid resource conflicts with other boards. For example, do not configure two boards for the same I/O base address.*

Use the **Bus Configuration Editor** in `VXIedit` to configure the AT bus configuration for the AT-MXI-2. `VXIedit` is described in Chapter 6, *NI-VXI Configuration Utility*.

## Configuration EEPROM

The AT-MXI-2 has an onboard EEPROM, which stores default register values that are loaded at power-on. The EEPROM is divided into two halves—a factory-configuration half, and a user-configuration half—so you can modify the user-configurable half, while the factory-configured half stores a back-up of the default user settings. The factory configuration is a minimal configuration that allows you to boot your AT-MXI-2 regardless of the changes made to the user configuration.

For information on configuring the onboard EEPROM, refer to Appendix C, *EEPROM Configuration*.

## Onboard DRAM

The AT-MXI-2 can accommodate one DRAM SIMM. Table 2-1 lists the SIMMs you can use. You can use 32-bit or 36-bit SIMMs since DRAM parity is not required. The AT-MXI-2 can hold up to 16 MB of onboard memory. The AT-MXI-2 supports DRAM speeds of 80 ns or faster.

**Table 2-1.** AT-MXI-2 DRAM Configurations

<b>SIMMs</b>	<b>Total DRAM</b>	<b>National Instruments Option?</b>
—	0	—
256 K x 32 or 256 K x 36	1 MB	—
1 M x 32 or 1 M x 36	4 MB	YES
4 M x 32 or 4 M x 36	16 MB	YES

## Install the AT-MXI-2

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This section contains general installation instructions for the AT-MXI-2. Consult your computer user manual or technical reference manual for specific instructions and warnings.

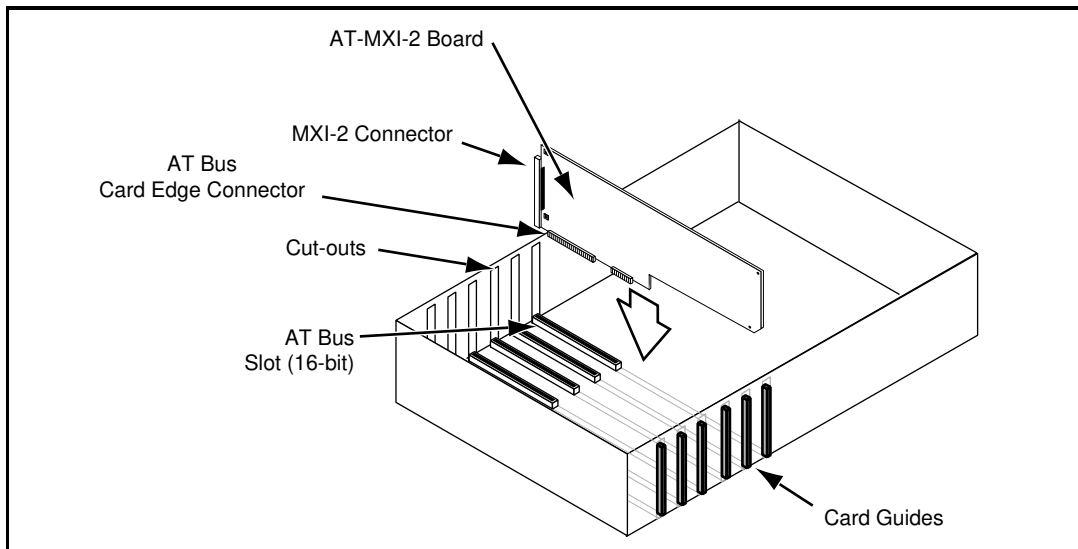
1. Plug in your PC AT or compatible computer before installing the AT-MXI-2. The power cord grounds the computer and protects it from electrical damage while you are installing the module.



**Warning:** *To protect both yourself and the computer from electrical hazards, the computer should remain off until you are finished installing the AT-MXI-2 module.*

2. Remove the top cover or access port to the AT bus.
3. Select any available PC AT expansion slot.
4. Locate the metal bracket that covers the cut-out in the back panel of the chassis for the slot you have selected. Remove and save the bracket-retaining screw and the bracket cover.
5. Touch the metal part of the power supply case inside the computer to discharge any static electricity that might be on your clothes or body.
6. Line up the AT-MXI-2 with the MXI-2 connector near the cut-out on the back panel. Slowly push down on the top of the AT-MXI-2 until its card-edge connector is resting on the expansion slot receptacle. Using slow, evenly distributed pressure, press the AT-MXI-2 straight down until it seats in the expansion slot.
7. Reinstall the bracket-retaining screw to secure the AT-MXI-2 to the back panel rail.
8. Check the installation.
9. Replace the computer cover.

Figure 2-2 shows how to install the AT-MXI-2.



**Figure 2-2.** AT-MXI-2 Installed in a Computer

# VXI-MXI-2 Configuration and Installation

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Chapter

3

This chapter contains the instructions to configure and install the VXI-MXI-2 module. This chapter applies only if you ordered the VXI-AT4000 interface kit. If you ordered the VME-AT4000 kit, skip this chapter and refer to Chapter 4, *VME-MXI-2 Configuration and Installation*.



**Warning:** *Electrostatic discharge can damage several components on your VXI-MXI-2 module. To avoid such damage in handling the module, touch the antistatic plastic package to a metal part of your VXI chassis before removing the VXI-MXI-2 from the package.*

## Configure the VXI-MXI-2

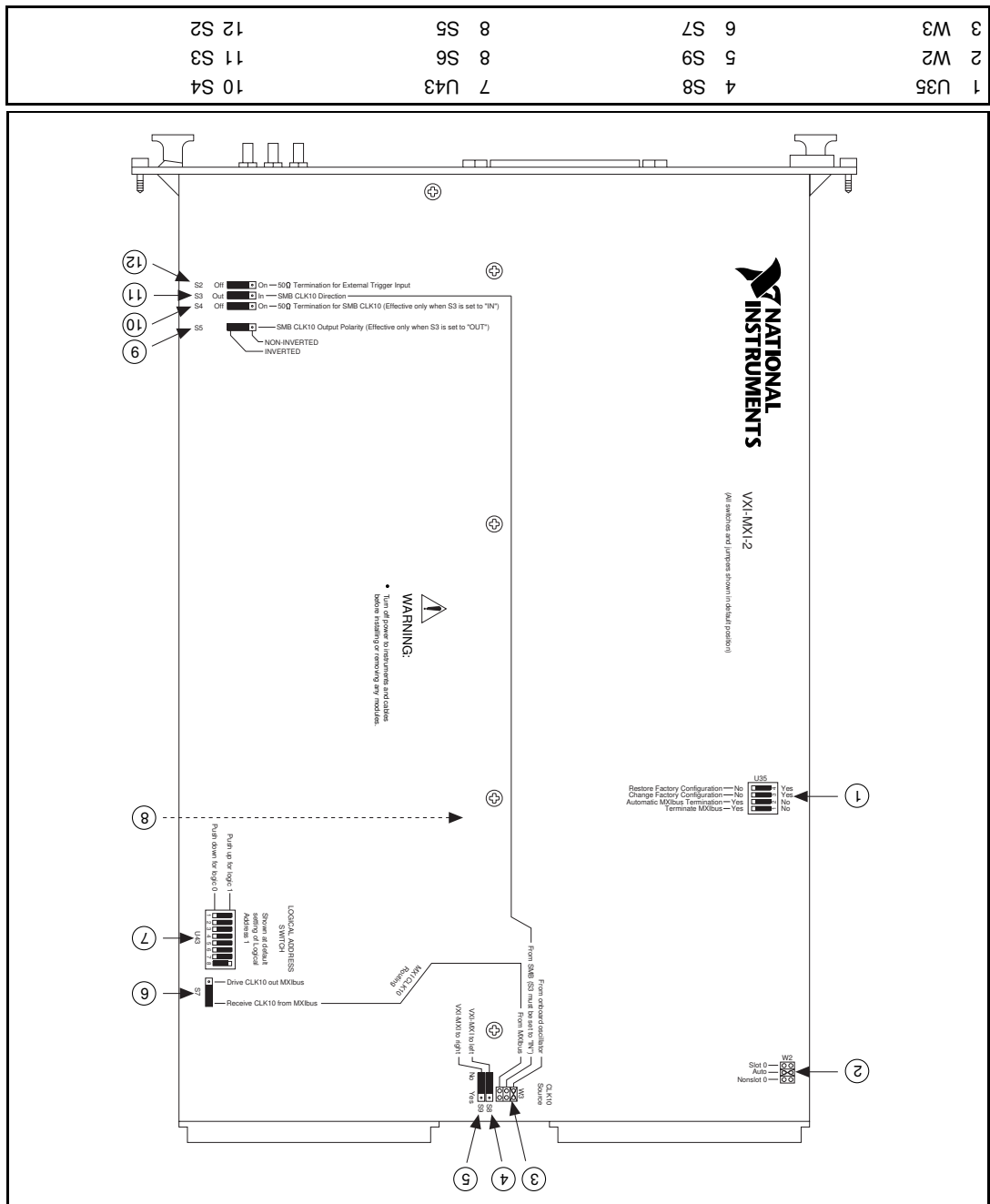
---

This section describes how to configure the following options on the VXI-MXI-2.

- VXIbus logical address
- VXIbus Slot 0/Non-Slot 0
- VXIbus local bus
- VXIbus CLK10 routing
- Trigger input termination
- MXIbus termination
- Configuration EEPROM
- Onboard DRAM

Figure 3-1 shows the VXI-MXI-2 as it would appear when facing the right side cover. The drawing shows the location and factory-default settings of most of the configuration switches and jumpers on the module. Notice that switch S6 (called out as number 8 in the figure) is accessible only by removing the front cover.

Figure 3-1. VXI-MXI-2 Right-Side Cover





## Front Panel Features

The VXI-MXI-2 has the following front panel features.

- Three front panel LEDs
  - **SYSFAIL** LED indicates that the VMEbus SYSFAIL line is asserted.
  - **MXI** LED indicates when the VXI-MXI-2 is accessed from the MXIbus.
  - **VXI** LED indicates when the VXI-MXI-2 is accessed from the VXIbus.
- MXIbus connector
- Three SMB connectors
  - External clock
  - Trigger output
  - Trigger input
- System reset push-button

## Removing the Metal Enclosure

The VXI-MXI-2 is housed in a metal enclosure to improve EMC performance and to provide easy handling. Because the enclosure includes cutouts to facilitate changes to the switch and jumper settings, it should not be necessary to remove it under normal circumstances.

However, it is necessary to remove the enclosure if you want to change the amount of DRAM installed on the VXI-MXI-2. Switch S6, which is directly related to the amount of DRAM you want to install, is also accessible only by removing the enclosure. If you will be making this change, remove the four screws on the top, the four screws on the bottom, and the five screws on the right side cover of the enclosure. Refer to the *Onboard DRAM* section later in this chapter for details about changing DRAM.

## VXibus Logical Address

Each device in a VXibus/MXibus system is assigned a unique number between 0 and 254. This 8-bit number, called the *logical address*, defines the base address for the VXI configuration registers located on the device. With unique logical addresses, each VXibus device in the system is assigned 64 bytes of configuration space in the upper 16 KB of A16 space.

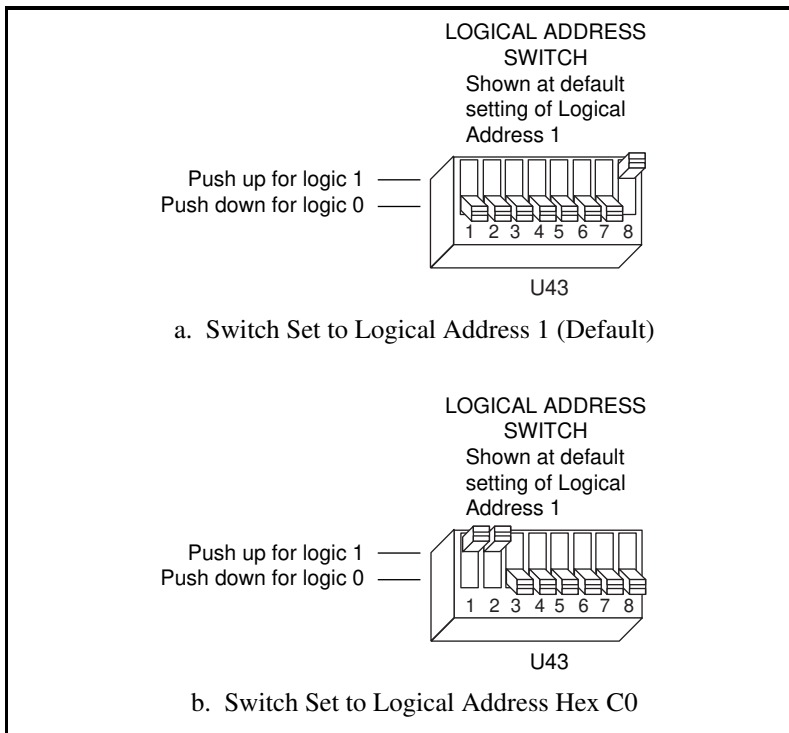
Logical address 0 is reserved for the Resource Manager in the VXibus system. Because the VXI-MXI-2 cannot act as a Resource Manager, do not configure the VXI-MXI-2 with a logical address of 0.

Some VXibus devices have *dynamically configurable* logical addresses. These devices have an initial logical address of hex FF or 255, which indicates that they can be dynamically configured. While the VXI-MXI-2 does support dynamic configuration of VXI devices within its mainframe, it is itself a *statically configured* device and is preset at the factory with a VXI logical address of 1.

Ensure that no other statically configurable VXibus devices have a logical address of 1. If they do, change the logical address setting of either the VXI-MXI-2 or the other device so that every device in the system has a unique associated logical address.

You can change the logical address of the VXI-MXI-2 by changing the setting of the 8-bit DIP switch labeled *LOGICAL ADDRESS SWITCH* (location designator U43) on the panel. The down position of the DIP switch corresponds to a logic value of 0 and the up position corresponds to a logic value of 1. Verify that the VXI-MXI-2 does not have the same logical address as any other statically configured VXibus device in your system. Remember that logical addresses hex 0 and FF are not allowed for the VXI-MXI-2. Also, when setting logical addresses, keep in mind the grouping requirements set by the system hierarchy. See VXI-6, *VXibus Mainframe Extender Specification*, for more information on setting logical addresses on a multimainframe hierarchy.

Figure 3-2 shows switch settings for logical address hex 1 and C0.



**Figure 3-2.** Logical Address Selection

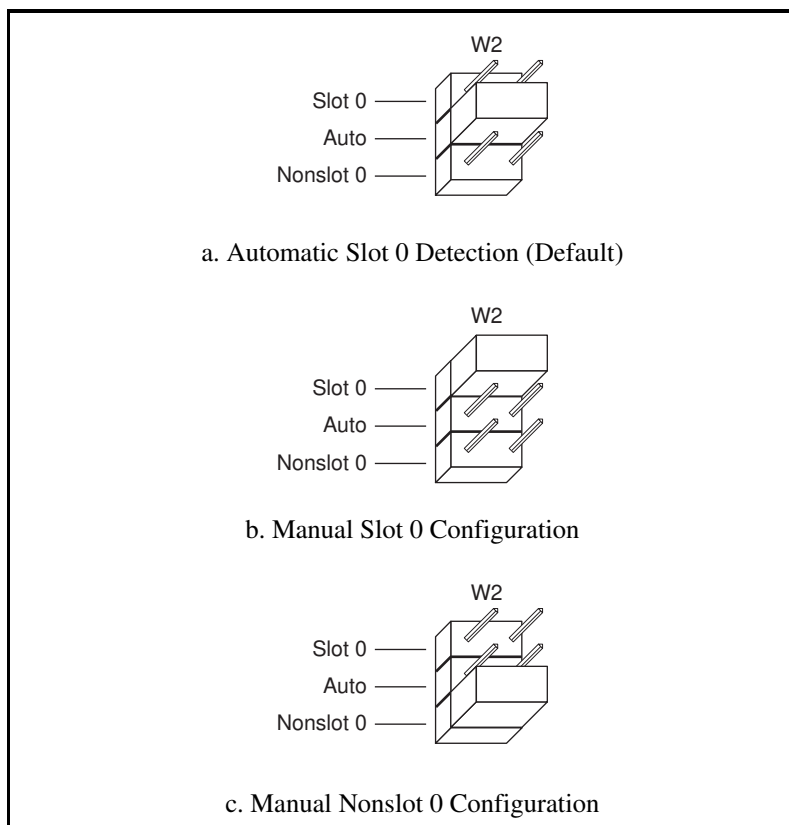
## VXIbus Slot 0/Non-Slot 0

The VXI-MXI-2 is configured at the factory to automatically detect if it is installed in Slot 0 of a VXIbus mainframe. With automatic Slot 0 detection, you can install the VXI-MXI-2 into any VXIbus slot.

You can manually configure the VXI-MXI-2 for either Slot 0 or Non-Slot 0 operation by defeating the automatic-detection circuitry. Use the three-position jumper W2 to select automatic Slot 0 detection, Slot 0, or Non-Slot 0 operation. Figure 3-3 shows these three settings.



**Warning:** *Do not install a device configured for Slot 0 into another slot without first reconfiguring it to either Non-Slot 0 or automatic configuration. Neglecting to do this could damage the device, the VXIbus backplane, or both.*



**Figure 3-3.** VXIbus Slot Configuration

When the VXI-MXI-2 is installed in Slot 0, it becomes the VMEbus System Controller. In this role, it has VMEbus Data Transfer Bus Arbiter circuitry that accepts bus requests on all four VMEbus request levels, prioritizes the requests, and grants the bus to the highest priority requester. As VMEbus System Controller, the VXI-MXI-2 also drives the 16 MHz VMEbus system clock by an onboard 16 MHz oscillator.

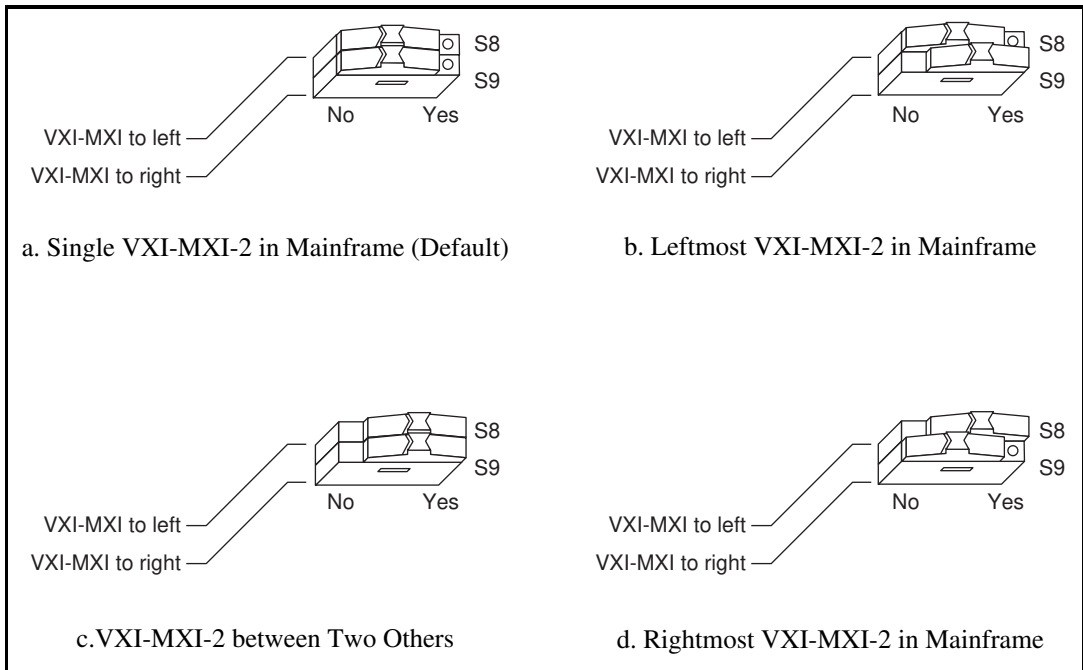
As required by the VXIbus specification, the VXI-MXI-2 drives the 10 MHz signal CLK10 on a differential ECL output when installed in Slot 0. When not installed in Slot 0, the VXI-MXI-2 only receives the CLK10 signal.

## VXIbus Local Bus

If you will be installing more than one VXI-MXI-2 in a single VXIbus mainframe, you must configure the boards to use the local bus. The VXI-MXI-2 uses the local bus to pass a signal to the other VXI-MXI-2 modules in the mainframe to disable the VMEbus bus timeout unit (BTO) during cycles that map to the MXIbus. Because the local bus is used, you need to install all VXI-MXI-2 modules for a single mainframe in adjacent slots.

You will use two switches on the VXI-MXI-2 to select its position in relation to any other VXI-MXI-2 module in the mainframe. Use switch S9 when there is a VXI-MXI-2 to the right (higher numbered slot). Use S8 when there is a VXI-MXI-2 to the left (lower numbered slot).

Figure 3-4 shows four configuration settings for a VXI-MXI-2. Figure 3-4a illustrates the default setting, which is for a single VXI-MXI-2 in a mainframe. Use the setting in Figure 3-4b for the VXI-MXI-2 located to the left of all others. Figure 3-4c shows the setting to use if the VXI-MXI-2 is between two others. Use the setting of Figure 3-4d for the VXI-MXI-2 located to the right of all others.

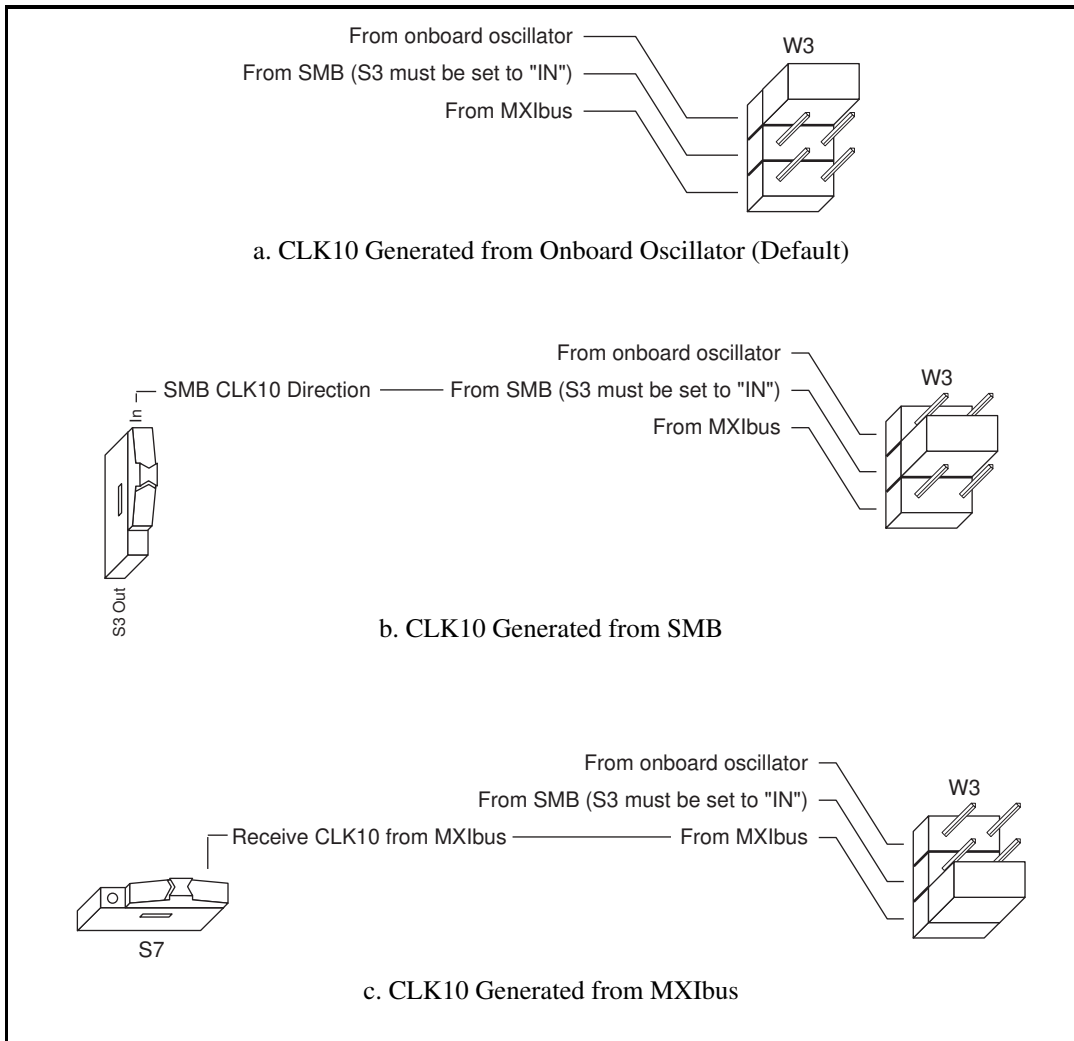


**Figure 3-4.** VXIbus Local Bus Configuration

## VXIbus CLK10 Routing

When the VXI-MXI-2 is installed in Slot 0 of your mainframe, it supplies the VXIbus CLK10 signal. The VXI-MXI-2 can use three different sources to generate this signal: an onboard oscillator, the external CLK SMB connector, and the MXIbus CLK10 signal. Use the three-position jumper W3 to select these options, as shown in Figure 3-5.

Notice that Figures 3-5b and 3-5c also show switches S3 and S7, respectively. You must configure these switches as shown when using the corresponding CLK10 source setting of W3.



**Figure 3-5.** VXIbus CLK10 Routing

The VXI-MXI-2 can also be configured to drive the external CLK SMB signal from the VXIbus CLK10 signal. Switch S3 controls whether the VXI-MXI-2 drives or receives the external CLK SMB signal. If you change the S3 setting to drive CLK10 out the external CLK10 SMB connector, do not set the W3 jumper to receive the SMB CLK10 signal; instead use the settings shown in either Figure 3-5a or Figure 3-5c as appropriate.

When switch S3 is set so that the VXI-MXI-2 receives the SMB CLK10 signal, you have the option to add a 50  $\Omega$  termination to the signal by setting switch S4. S4 is unused—its setting does not matter—when S3 is configured to drive the external CLK SMB signal.

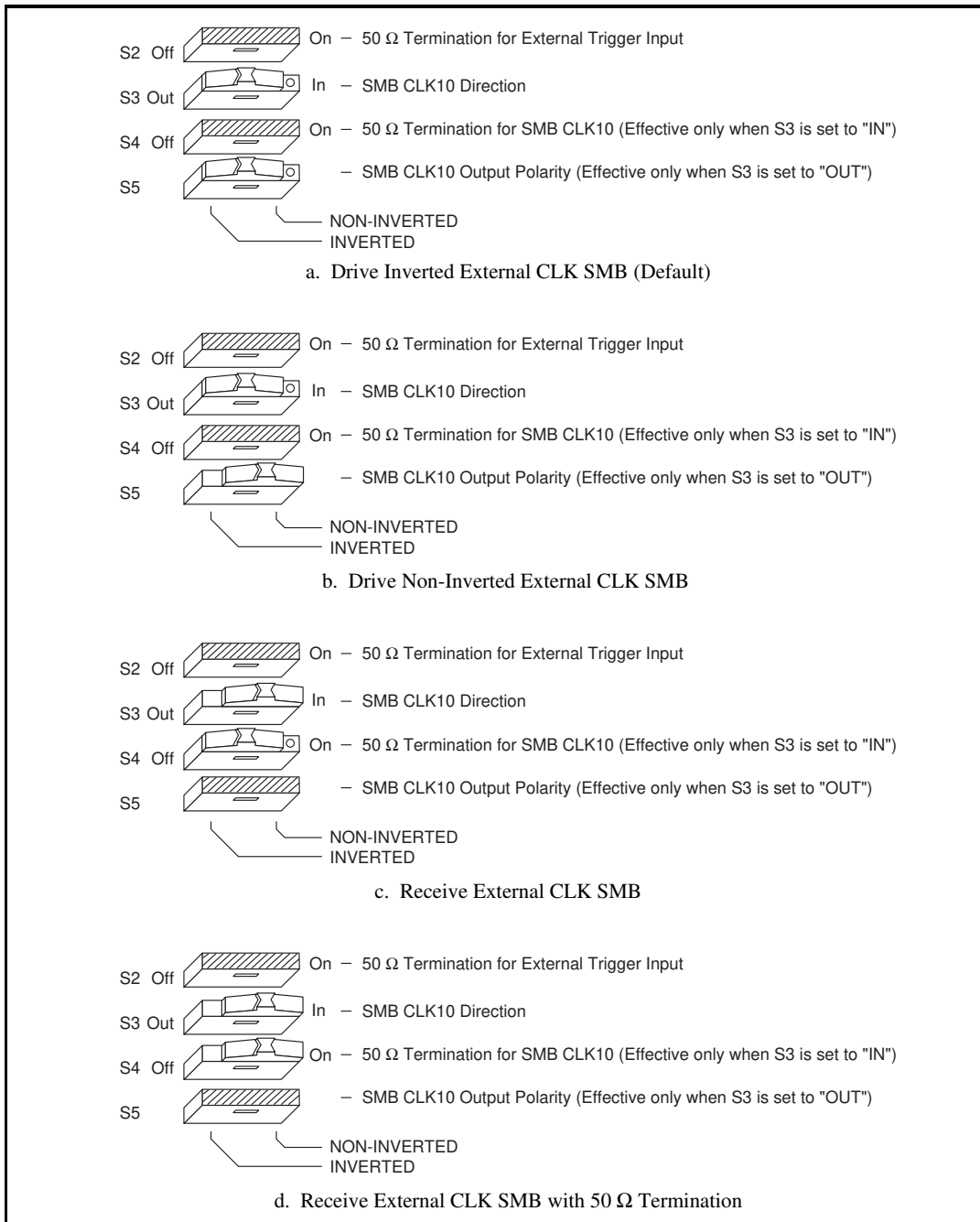
You can use an additional switch, S5, to control the polarity of the external CLK SMB signal when S3 is configured to drive it. S5 is unused—its setting does not matter—when S3 is configured to receive the external CLK SMB signal.

Figure 3-6 shows four configuration settings for the VXI-MXI-2. Figure 3-6a shows the default configuration, which is for driving the inverted external CLK SMB. Use the settings of Figure 3-6b to drive the noninverted external CLK SMB signal. Figure 3-6c illustrates the setting for receiving the external CLK SMB signal. Finally, you can configure the switches as shown in Figure 3-6d to receive the external CLK SMB signal with a 50  $\Omega$  termination.



**Note:** *The settings of any switches shown with this pattern (▣) have no bearing on the configuration described in any of the following figures.*





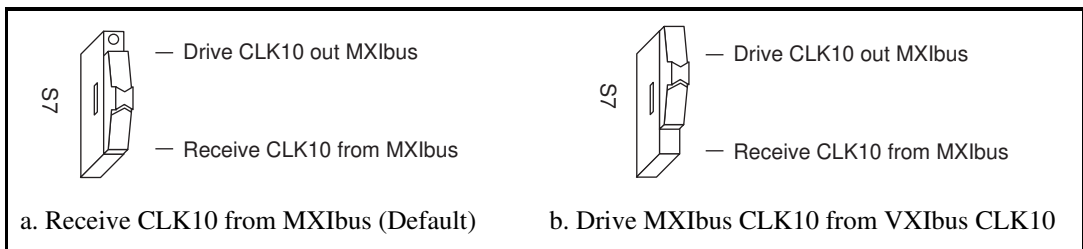
**Figure 3-6.** SMB CLK10 Settings

The VXI-MXI-2 can also drive or receive the MXIbus CLK10 signal. Switch S7 controls whether the VXI-MXI-2 drives MXIbus CLK10 from the VXIbus CLK10 or receives MXIbus CLK10. As shown earlier in Figure 3-5c, if W3 is configured to use the MXIbus CLK10 to generate the VXIbus CLK10 signal, switch S7 must be configured to receive MXIbus CLK10. This is shown again in Figure 3-7a below. If you change the S7 setting to drive CLK10 out the MXIbus, do not set the W3 jumper to receive the MXIbus CLK10; instead use the settings shown in Figure 3-5a or 3-5b as appropriate.



**Warning:** *Do not configure more than one MXIbus device to drive the MXIbus CLK10. Having a second device driving MXIbus CLK10 could damage the device.*

Figure 3-7 shows the configuration settings for receiving and driving MXIbus CLK10, respectively.



**Figure 3-7.** Receiving or Driving MXIbus CLK10

## Trigger Input Termination

You can use switch S2 to terminate the external trigger input SMB with 50 Ω. Figure 3-8a shows the default setting for a nonterminated trigger input SMB. Use the setting of Figure 3-8b to terminate the trigger input SMB. Switch S2 is located above switches S3, S4, and S5, which have no effect on this configuration.

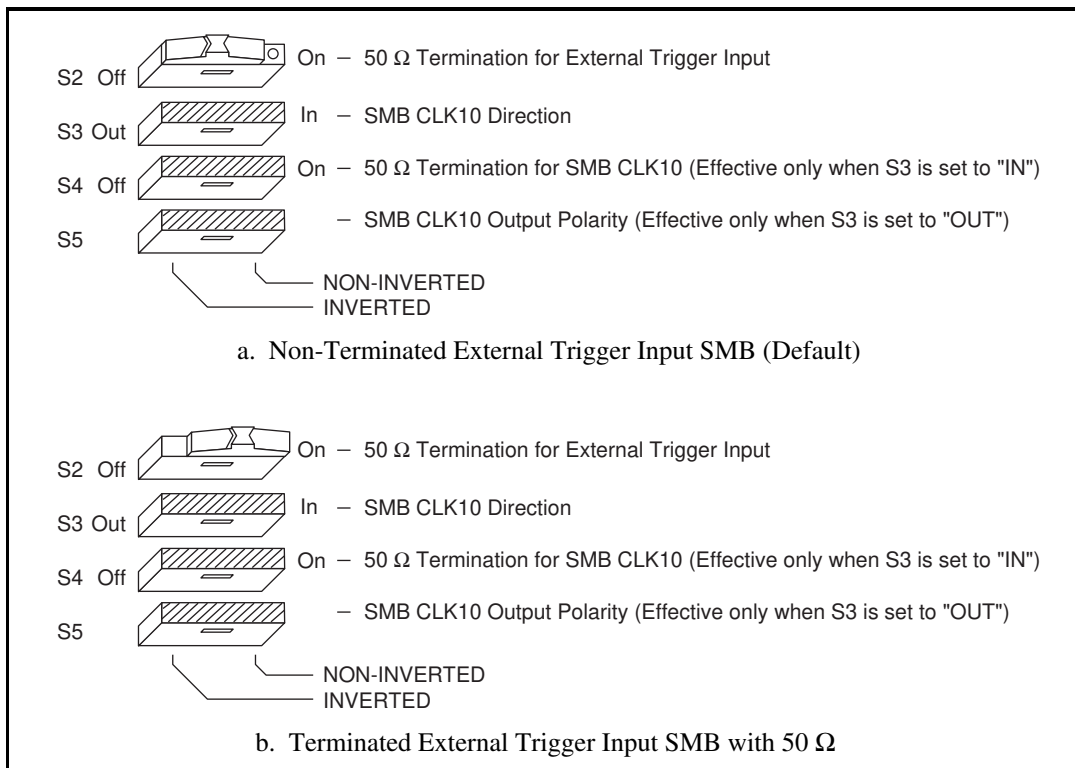


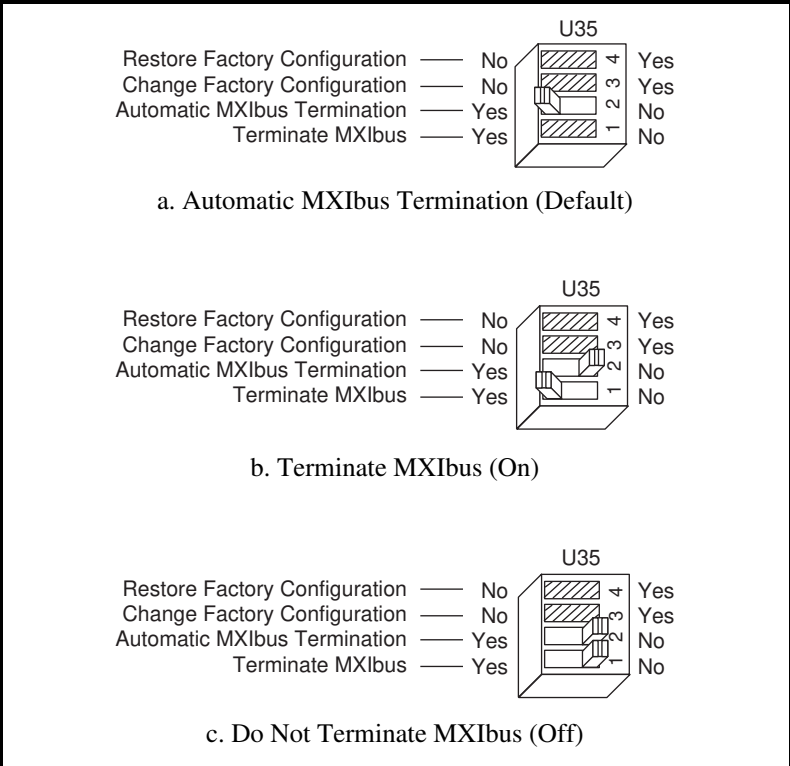
Figure 3-8. SMB Trigger Input Termination

## MXIbus Termination

The first and last MXIbus devices connected to the MXIbus—whether it is a single MXI-2 cable or daisy-chained MXI-2 cables—must terminate the MXIbus. Any MXIbus devices in the middle of a MXIbus daisy chain must *not* terminate the MXIbus.

The VXI-MXI-2 automatically senses whether it is at either end of the MXIbus cable to terminate the MXIbus. You can manually control MXIbus termination by defeating the automatic circuitry. Use switches 1 and 2 of the four-position switch at location U35 to control whether MXIbus termination is automatic (Figure 3-9a), on (Figure 3-9b), or off (Figure 3-9c). The settings of switches 3 and 4 have no effect on MXIbus termination.

Use switch 2 of U35 to select whether you want the VXI-MXI-2 to automatically control termination of the MXIbus. Switch 1 of U35 lets you manually control whether to terminate the MXIbus when automatic termination is turned off. Switch 1 has no effect when switch 2 is set for automatic MXIbus termination; you must turn off automatic termination if you want to manually control termination.



**Figure 3-9.** MXIbus Termination

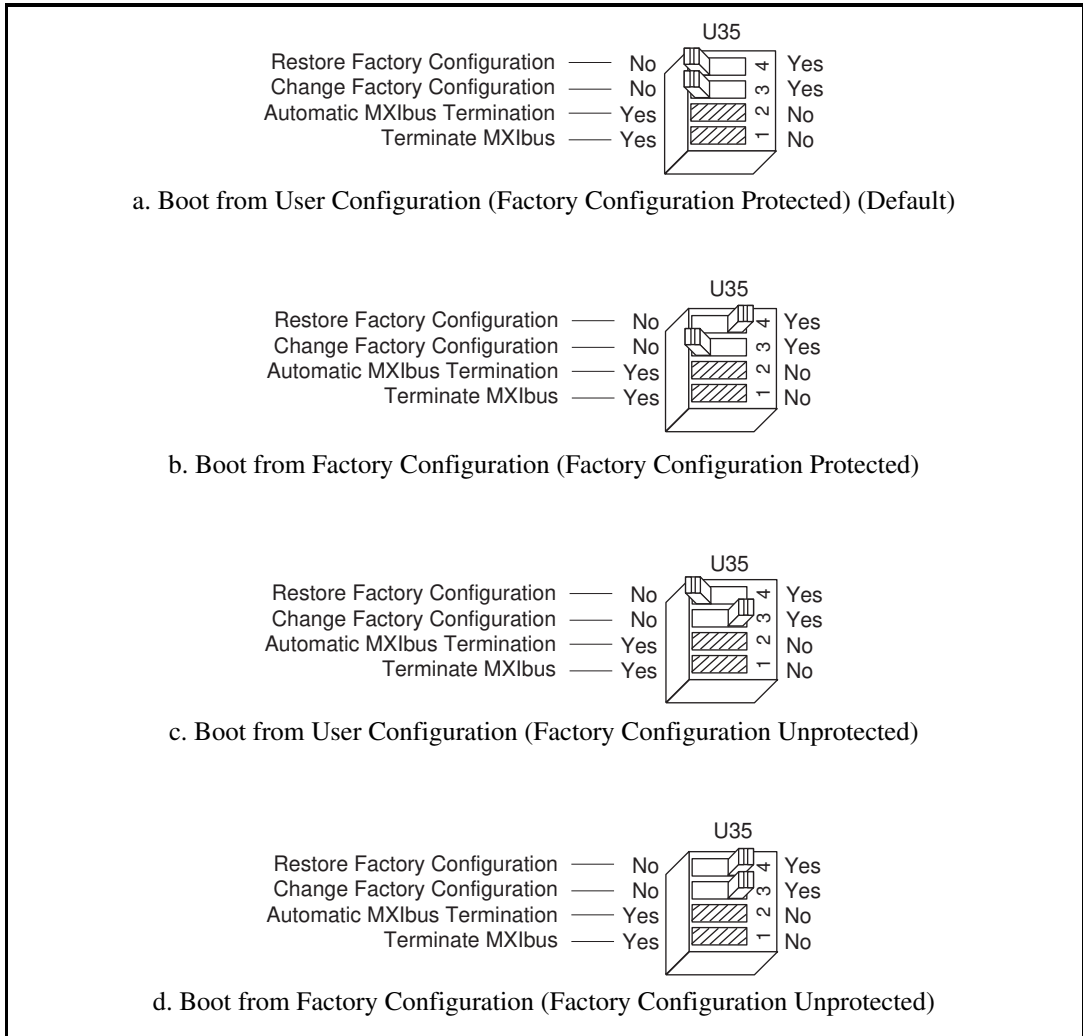
## Configuration EEPROM

The VXI-MXI-2 has an onboard EEPROM, which stores default register values that are loaded at power-on. The EEPROM is divided into two halves—a factory-configuration half, and a user-configuration half. Both halves were factory configured with the same configuration values so you can modify the user-configurable half, while the factory-configured half stores a back-up of the default user settings.

Use switches 3 and 4 of the four-position switch at location U35 to control the operation of the EEPROM. The Restore Factory Configuration switch (switch 4) causes the VXI-MXI-2 to boot off the factory-configured half instead of the user-modified settings. This is useful in the event that the user-configured half of the EEPROM becomes corrupted in such a way that the VXI-MXI-2 boots to an unusable state.

The Change Factory Configuration switch (switch 3 of U35) lets you change the factory-default configuration settings by permitting writes to the factory settings section of the EEPROM. This switch serves as a safety measure and should not be needed under normal circumstances. When this switch is off (its default setting) the factory configuration of the EEPROM is protected, so any writes to the factory area will be ignored. The factory area is protected regardless of the setting of switch 4 of U35.

Figure 3-10 shows the configuration settings for EEPROM operation. The settings of switches 1 and 2 have no effect on EEPROM configuration.

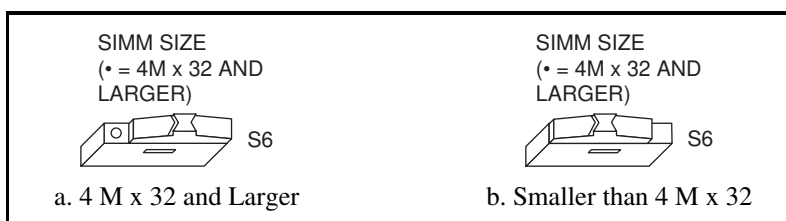


**Figure 3-10.** EEPROM Operation

## Onboard DRAM

The VXI-MXI-2 can accommodate up to two 1.35 in. DRAM SIMMs. Table 3-1 lists the SIMMs you can use. You can use 32-bit or 36-bit SIMMs since DRAM parity is not required. Because the VXI-MXI-2 supports only one organization at a time, all installed SIMMs must be of the same type. Use Bank 0 first when installing the SIMMs. This allows you to install up to 64 MB. The VXI-MXI-2 supports DRAM speeds of 80 ns or faster.

Switch S6 is used to select the size of each SIMM. The SIMM sockets and S6 are accessible only by removing the right-side cover. To access these components, remove the four screws on the top, the four screws on the bottom, and the five screws on the right-side cover of the metal enclosure. If the SIMMs are 4 M x 32 or larger, S6 should be in the OFF setting as shown in Figure 3-11 a. For SIMMs *smaller* than 4 M x 32, use the ON setting as shown in Figure 3-11 b.



**Figure 3-11.** SIMM Size Configuration

Refer to Table 3-1 for how to adjust the switch (ON or OFF) for all supported DRAM configurations. Many of the DRAM options are available from National Instruments.

**Table 3-1.** VXI-MXI-2 DRAM Configurations

<b>Bank 0</b>	<b>Bank 1</b>	<b>Total DRAM</b>	<b>National Instruments Option?</b>	<b>Switch Setting of S6</b>
—	—	0	—	—
256 K x 32 or 256 K x 36	—	1 MB	—	ON
256 K x 32 or 256 K x 36	256 K x 32 or 256 K x 36	2 MB	—	ON
512 K x 32 or 512 K x 36	—	2 MB	—	ON
512 K x 32 or 512 K x 36	512 K x 32 or 512 K x 36	4 MB	—	ON
1 M x 32 or 1 M x 36	—	4 MB	YES	ON
1 M x 32 or 1 M x 36	1 M x 32 or 1 M x 36	8 MB	—	ON
2 M x 32 or 2 M x 36	—	8 MB	YES	ON
2 M x 32 or 2 M x 36	2 M x 32 or 2 M x 36	16 MB	—	ON
4 M x 32 or 4 M x 36	—	16 MB	YES	OFF
4 M x 32 or 4 M x 36	4 M x 32 or 4 M x 36	32 MB	—	OFF
8 M x 32 or 8 M x 36	—	32 MB	YES	OFF
8 M x 32 or 8 M x 36	8 M x 32 or 8 M x 36	64 MB	YES	OFF



## Install the VXI-MXI-2

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This section contains general installation instructions for the VXI-MXI-2. Consult your VXIbus mainframe user manual or technical reference manual for specific instructions and warnings.

1. Plug in your mainframe before installing the VXI-MXI-2. The power cord grounds the mainframe and protects it from electrical damage while you are installing the module.



**Warning:** *To protect both yourself and the mainframe from electrical hazards, the mainframe should remain off until you are finished installing the VXI-MXI-2 module.*

2. Remove or open any doors or covers blocking access to the mainframe slots.
3. If you are installing the VXI-MXI-2 into a D-size mainframe, install a support designed for installing C-size boards in D-size mainframes. The VXI-MXI-2 has no P3 connector and cannot provide P3 Slot 0 control to VXI devices requiring this capability.



**Warning:** *If the VXI-MXI-2 is not configured for automatic Slot 0 detection, be certain that the slot you select in your VXIbus mainframe matches the VXI-MXI-2 configuration as either a Slot 0 device or a Non-Slot 0 device. If you install your VXI-MXI-2 into a slot that does not correspond with the jumper setting, you risk damage to the VXI-MXI-2, the VXIbus backplane, or both.*

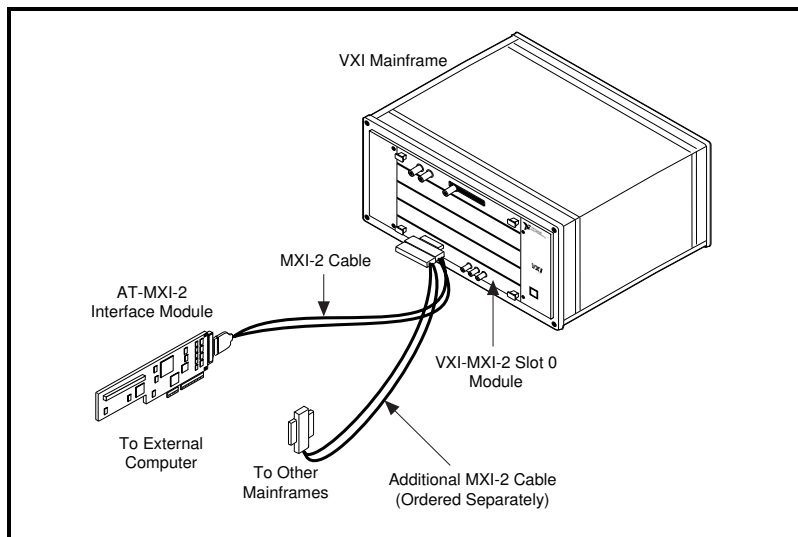
4. Insert the VXI-MXI-2 in the slot you have selected by aligning the top and bottom of the board with the card-edge guides inside the mainframe. Slowly push the VXI-MXI-2 straight into the slot until its plug connectors are resting on the backplane receptacle connectors. Using slow, evenly distributed pressure, press the VXI-MXI-2 straight in until it seats in the expansion slot. The front panel of the VXI-MXI-2 should be even with the front panel of the mainframe.
5. Tighten the retaining screws on the top and bottom edges of the front panel.
6. Check the installation.
7. Connect the cables as described in the following section before restoring power.
8. Replace or close any doors or covers to the mainframe.

## Connect the MXIbus Cable

There are two basic types of MXI-2 cables. MXI-2 cables can have either a single connector on each end or a single connector on one end and a double connector on the other end.

Connect the labeled end of the cable to the MXI-2 device that will be the MXIbus System Controller. Connect the other end of the cable to the other device. Be sure to tighten the screw locks to ensure proper pin connection.

Figure 3-12 shows the correct cabling for a VXI system containing a AT-MXI-2 board in a PC AT cabled to a VXI-MXI-2 module residing in Slot 0 of a VXIbus mainframe. Notice that you can expand your system to include other devices by using an additional MXI-2 cable. However, in such a case the first cable needs to have a double connector on one end. You can use a cable with a single connector on each end to connect the last device on the MXIbus.



**Figure 3-12.** MXI-2 Cable Configuration Using an AT-MXI-2 and a VXI-MXI-2

When you have properly connected the MXI-2 cable, power on the VXIbus mainframe and then the computer.



**Note:** *Always turn on the mainframe first. Doing so makes it possible for your external computer to access the VXI boards in the mainframe upon startup.*

# VME-MXI-2 Configuration and Installation

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Chapter

4

This chapter contains the instructions to configure and install the VME-MXI-2 module. This chapter applies only if you ordered the VME-AT4000 interface kit. If you ordered the VXI-AT4000 kit, you should refer to Chapter 3, *VXI-MXI-2 Configuration and Installation*.



**Warning:** *Electrostatic discharge can damage several components on your VME-MXI-2 module. To avoid such damage in handling the module, touch the antistatic plastic package to a metal part of your VMEbus chassis before removing the VME-MXI-2 from the package.*

## Configure the VME-MXI-2

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This section describes how to configure the following options on the VME-MXI-2.

- VMEbus A16 base address
- VME-MXI-2 intermodule signaling
- MXIbus termination
- Configuration EEPROM
- Onboard DRAM

The VME-MXI-2 automatically detects if it is located in the first slot of the chassis to perform the VMEbus System Controller functions. It is not necessary to configure the VME-MXI-2 System Controller option. The module can be installed in any slot of a VMEbus chassis.

Figure 4-1 shows the VME-MXI-2. The drawing shows the location and factory-default settings of the configuration switches and jumpers on the module.

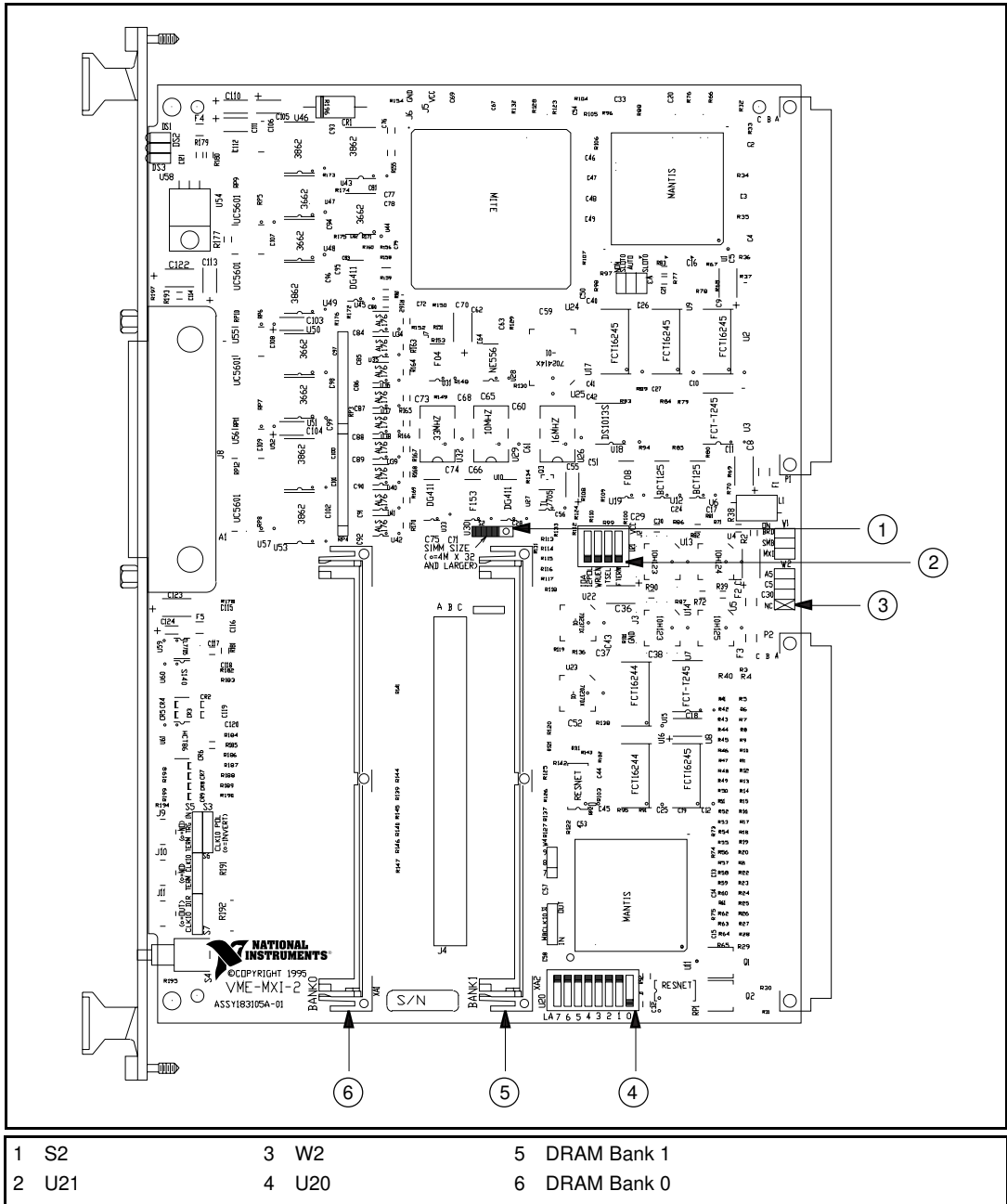


Figure 4-1. VME-MXI-2 Parts Locator Diagram

## Front Panel Features

The VME-MXI-2 has the following front panel features.

- Three front panel LEDs
  - **SYSFAIL** LED indicates that the VMEbus SYSFAIL line is asserted.
  - **MXI** LED indicates when the VME-MXI-2 is accessed from the MXIbus.
  - **VME** LED indicates when the VME-MXI-2 is accessed from the VMEbus.
- MXIbus connector
- System reset push-button

## VMEbus A16 Base Address

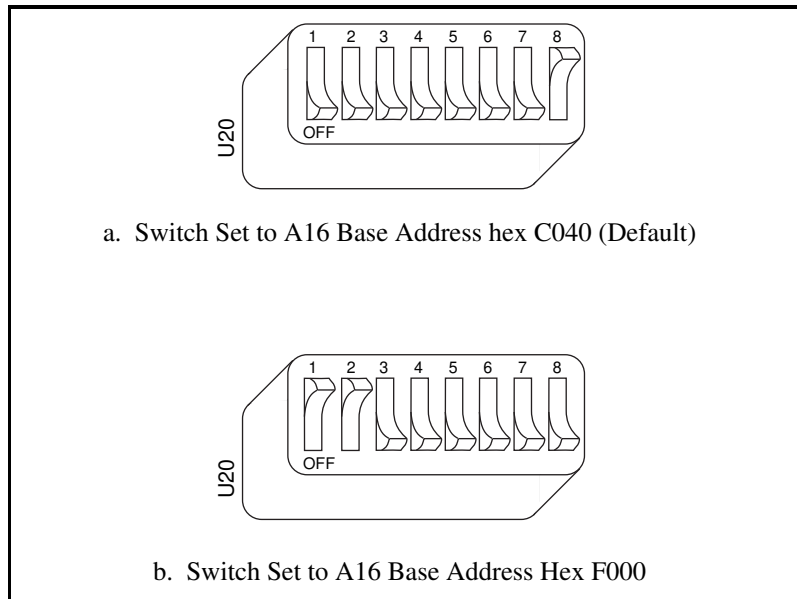
The VME-MXI-2 requires 64 bytes of A16 space for its configuration registers. It uses the *logical address* scheme of the VXIbus specification, in which each device is assigned an 8-bit value called the logical address. This logical address allocates 64 bytes of space to the device within the upper quarter of A16 space. The VME-MXI-2 cannot be configured to locate its registers in the lower three quarters of A16 space. The A16 base address of the VME-MXI-2 will be address lines 15 and 14 high with address lines 13 through 6 matching the logical address of the VME-MXI-2, and address lines 5 through 0 low. In other words, the A16 base address of the VME-MXI-2 module's 64 B register set is as calculated below:

$$\text{base address} = \text{C000 hex} + (\text{logical address}) * 40 \text{ hex}$$

The factory-default logical address for the VME-MXI-2 is 1, which locates the registers in the range C040 hex to C07F hex. You can change the logical address of the VME-MXI-2 by changing the setting of the 8-bit DIP switch at location designator U20. The ON position of the DIP switch corresponds to a logic value of 0, and the OFF position corresponds to a logic value of 1. Allowable logical addresses for the VME-MXI-2 range from 1 to 254 (hex FE). Verify that no other devices in your system use the A16 address space for the VME-MXI-2. If possible, configure all other VMEbus A16 devices to be located within the lower three quarters of A16 space. Also, when setting base addresses, keep in mind the grouping requirements set by the system hierarchy. See VXI-6, *VXIbus Mainframe Extender Specification*, for

more information on setting base addresses on a multiframe hierarchy.

Figure 4-2 shows switch settings for A16 base address hex C040 and F000.



**Figure 4-2.** Base Address Selection

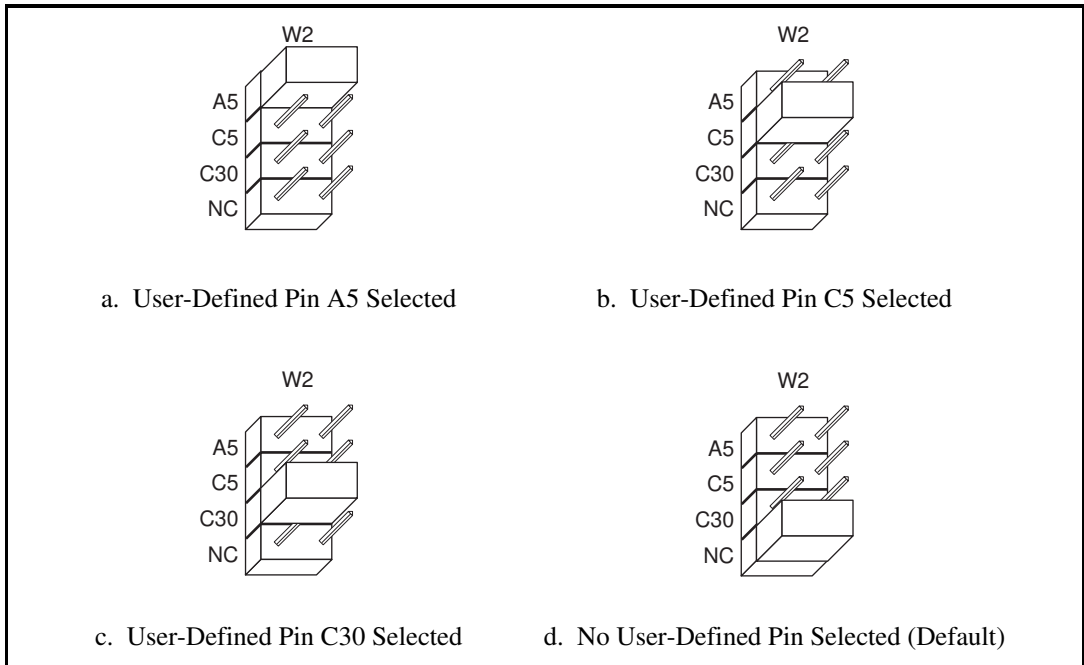
## VME-MXI-2 Intermodule Signaling

If you will be installing more than one VME-MXI-2 in a single VMEbus chassis, you must select a user-defined pin for use by the VME-MXI-2. The VME-MXI-2 modules use this signal to disable the bus timeout unit(s) on the other VME-MXI-2 modules during VMEbus accesses that map to the MXIbus. This is done because the MXIbus bus timeout unit should be the sole timer of any MXIbus access. Since bus timeout units on other VMEbus modules cannot monitor this signal, they should be permanently disabled. If it is not possible to disable a module's bus timeout unit, it should be configured to the highest setting to give MXIbus accesses as much time as possible.

You can choose from three user-defined pins on J2/P2. The pin you select must be based on the VMEbus backplane between all slots that will have a VME-MXI-2 installed. Use jumper W2 to select pin A5, C5, or C30 of J2/P2, as shown in Figure 4-3.

Notice that a fourth position is also available on the jumper. This is the factory-default setting, which does not connect the VME-MXI-2 to any user-defined pin. You would use this option only if you are installing a single VME-MXI-2 in a chassis.

Figure 4-3 shows the four intermodule signaling settings.



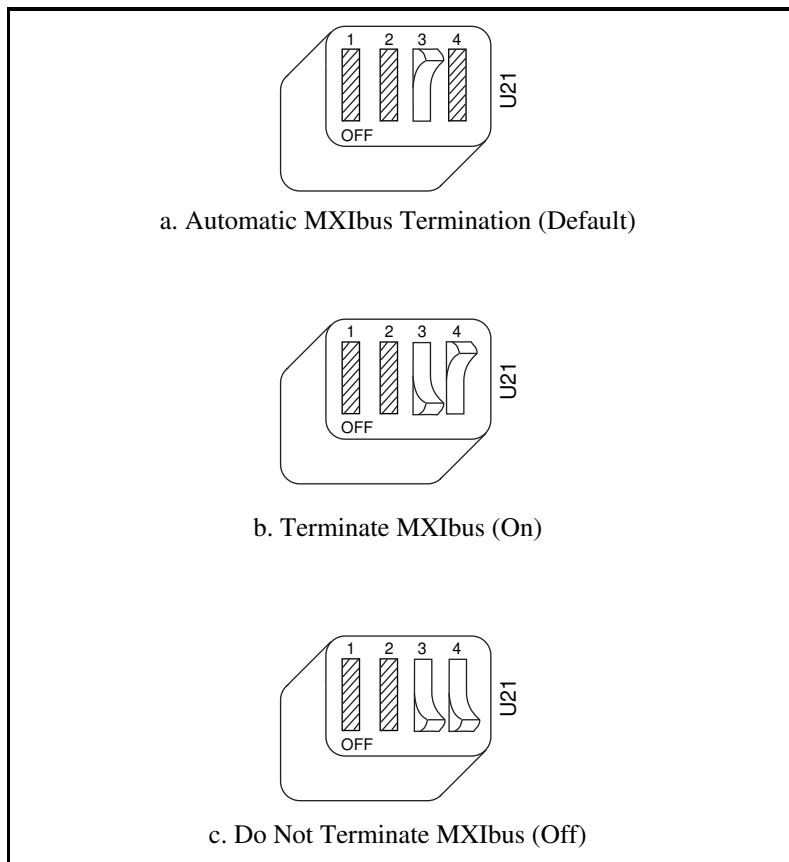
**Figure 4-3.** VME-MXI-2 Intermodule Signaling Settings

## MXIbus Termination

The first and last MXIbus devices connected to the MXIbus—whether it is a single MXI-2 cable or daisy-chained MXI-2 cables—must terminate the MXIbus. Any MXIbus devices in the middle of a MXIbus daisy chain must *not* terminate the MXIbus.

The VME-MXI-2 automatically senses if it is at either end of the MXIbus cable to terminate the MXIbus. You can manually control MXIbus termination by defeating the automatic circuitry. Use switches 3 and 4 of the four-position switch at location U21 to control whether MXIbus termination is automatic (Figure 4-4a), on (Figure 4-4b), or off (Figure 4-4c). The settings of switches 1 and 2 have no effect on MXIbus termination.

Use switch 3 to select whether you want the VME-MXI-2 to automatically control termination of the MXIbus. Switch 4 lets you manually control whether to terminate the MXIbus when automatic termination is turned off. Switch 4 has no effect when switch 3 is set for automatic MXIbus termination; you must turn off automatic termination if you want to manually control termination.



**Figure 4-4.** MXIbus Termination



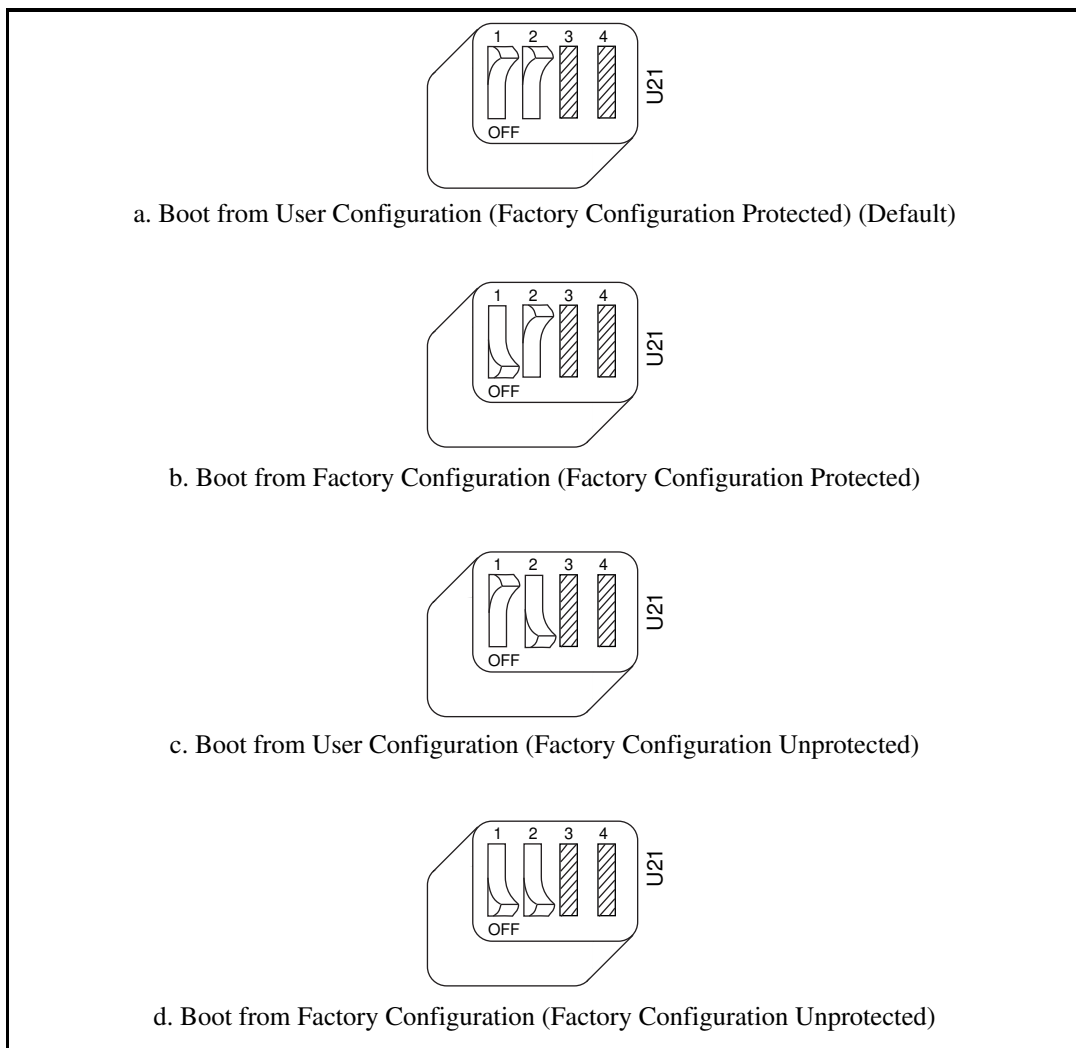
## Configuration EEPROM

The VME-MXI-2 has an onboard EEPROM, which stores default register values that are loaded at power-on. The EEPROM is divided into two halves—a factory-configuration half, and a user-configuration half. Both halves were factory configured with the same configuration values so you can modify the user-configurable half, while the factory-configured half stores a back-up of the default user settings.

Use switches 1 and 2 of the four-position switch at location U21 to control the operation of the EEPROM. The Restore Factory Configuration switch (switch 1) causes the VME-MXI-2 to boot off the factory-configured half instead of the user-modified settings. This is useful in the event that the user-configured half of the EEPROM becomes corrupted in such a way that the VME-MXI-2 boots to an unusable state.

The Change Factory Configuration switch (switch 2 of U21) lets you change the factory-default configuration settings by permitting writes to the factory settings section of the EEPROM. This switch serves as a safety measure and should not be needed under normal circumstances. When this switch is off (its default setting) the factory configuration of the EEPROM is protected so any writes to the factory area will be ignored. The factory area is protected regardless of the setting of switch 1 of U21.

Figure 4-5 shows the configuration settings for EEPROM operation. The settings of switches 3 and 4 have no effect on EEPROM configuration.



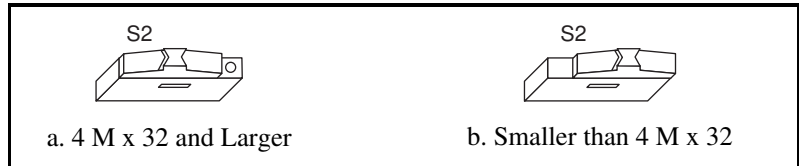
**Figure 4-5.** EEPROM Operation

## Onboard DRAM

The VME-MXI-2 can accommodate up to two 1.35 in. DRAM SIMMs. Table 4-1 lists the SIMMs you can use. You can use 32-bit or 36-bit SIMMs since DRAM parity is not required. Because the VME-MXI-2 supports only one organization at a time, all SIMMs installed must be

of the same type. Use Bank 0 first when installing SIMMs. This allows you to install up to 64 MB. The VME-MXI-2 supports DRAM speeds of 80 ns or faster.

Switch S2 is used to select the size of each SIMM. If the SIMMs are 4 M x 32 or larger, S2 should be in the OFF setting as shown in Figure 4-6a. For SIMMs *smaller* than 4 M x 32, use the ON setting as shown in Figure 4-6b.



**Figure 4-6.** SIMM Size Configuration

Refer to Table 4-1 for how to adjust the switch (ON or OFF) for all supported DRAM configurations. Many of the DRAM options are available from National Instruments.

**Table 4-1.** VXI-MXI-2 DRAM Configurations

Bank 0	Bank 1	Total DRAM	National Instruments Option?	Switch Setting of S6
—	—	0	—	—
256 K x 32 or 256 K x 36	—	1 MB	—	ON
256 K x 32 or 256 K x 36	256 K x 32 or 256 K x 36	2 MB	—	ON
512 K x 32 or 512 K x 36	—	2 MB	—	ON
512 K x 32 or 512 K x 36	512 K x 32 or 512 K x 36	4 MB	—	ON
1 M x 32 or 1 M x 36	—	4 MB	YES	ON

**Table 4-1.** VXI-MXI-2 DRAM Configurations (Continued)

<b>Bank 0</b>	<b>Bank 1</b>	<b>Total DRAM</b>	<b>National Instruments Option?</b>	<b>Switch Setting of S6</b>
1 M x 32 or 1 M x 36	1 M x 32 or 1 M x 36	8 MB	—	ON
2 M x 32 or 2 M x 36	—	8 MB	YES	ON
2 M x 32 or 2 M x 36	2 M x 32 or 2 M x 36	16 MB	—	ON
4 M x 32 or 4 M x 36	—	16 MB	YES	OFF
4 M x 32 or 4 M x 36	4 M x 32 or 4 M x 36	32 MB	—	OFF
8 M x 32 or 8 M x 36	—	32 MB	YES	OFF
8 M x 32 or 8 M x 36	8 M x 32 or 8 M x 36	64 MB	YES	OFF

## Install the VME-MXI-2

This section contains general installation instructions for the VME-MXI-2. Consult your VMEbus mainframe user manual or technical reference manual for specific instructions and warnings.

1. Plug in your mainframe before installing the VME-MXI-2. The power cord grounds the mainframe and protects it from electrical damage while you are installing the module.



**Warning:** *To protect both yourself and the mainframe from electrical hazards, the mainframe should remain off until you are finished installing the VME-MXI-2 module.*

2. Remove or open any doors or covers blocking access to the mainframe slots.

3. Insert the VME-MXI-2 in the slot you have selected by aligning the top and bottom of the board with the card-edge guides inside the mainframe. Slowly push the VME-MXI-2 straight into the slot until its plug connectors are resting on the backplane receptacle connectors. Using slow, evenly distributed pressure, press the VME-MXI-2 straight in until it seats in the expansion slot. The front panel of the VME-MXI-2 should be even with the front panel of the mainframe.
4. Tighten the retaining screws on the top and bottom edges of the front panel.
5. Check the installation.
6. Connect the cables as described in the following section before restoring power.
7. Replace or close any doors or covers to the mainframe.

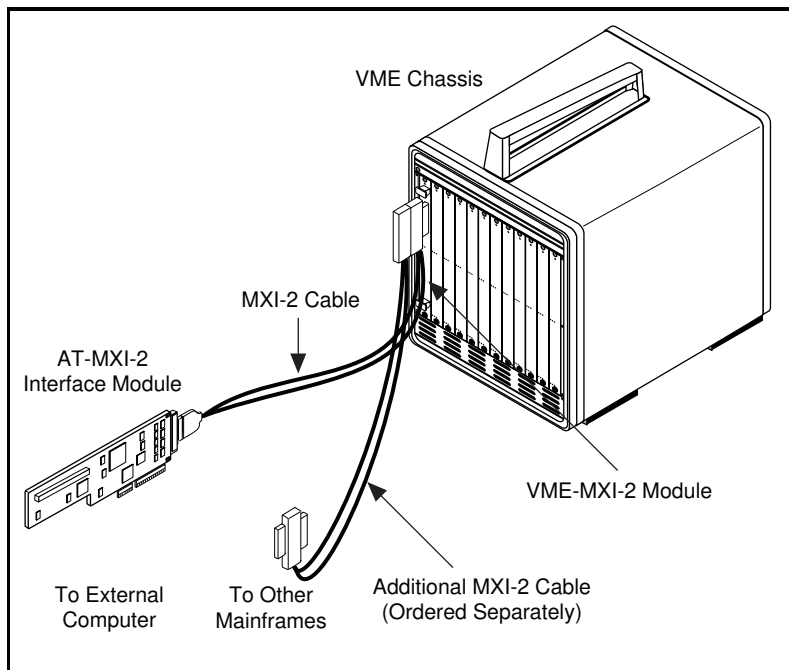
## Connect the MXIbus Cable

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There are two basic types of MXI-2 cables. MXI-2 cables can have either a single connector on each end or a single connector on one end and a double connector on the other end.

Connect the labeled end of the cable to the MXI-2 device that will be the MXIbus System Controller. Connect the other end of the cable to the other device. Be sure to tighten the screw locks to ensure proper pin connection.

Figure 4-7 shows the correct cabling for a VME system containing a AT-MXI-2 board in a PC AT cabled to a VME-MXI-2 module residing in Slot 1 of a VMEbus mainframe. Notice that you can expand your system to include other devices by using an additional MXI-2 cable. However, in such a case the first cable needs to have a double connector on one end. You can then use a cable with a single connector on each end to connect the last device on the MXIbus.



**Figure 4-7.** MXI-2 Cable Configuration Using an AT-MXI-2 and a VME-MXI-2

When you have properly connected the MXI-2 cable, power on the VMEbus mainframe and then the computer.



**Note:**

*Always turn on the mainframe first. Doing so makes it possible for your external computer to access the VME boards in the mainframe upon startup.*

# NI-VXI Software Installation

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Chapter

5

This chapter contains the instructions to install the NI-VXI software.

There are two methods for installing your NI-VXI software: the Windows Setup program, and a DOS INSTALL program. You can use the Windows Setup program to install NI-VXI for both Windows and DOS. The DOS INSTALL program can install only the NI-VXI software for DOS.

Some of the new utilities rely on the LabWindows/CVI Run-Time Engine. This software is installed, if necessary, during the NI-VXI installation.

## Using the Windows Setup Program

---

You can use the Setup program that came with your NI-VXI software to install the entire NI-VXI software package, a software update, or to reinstall software in the event that your files were accidentally erased. You can use these procedures to install all or part of the NI-VXI software.

### Installing the NI-VXI Software

This section describes how to install the NI-VXI software for the AT-MXI-2 and Windows. Please carefully read these directions along with any messages on the screen before making your selections.

You can quit the Setup program at any time by pressing the **Cancel** button. If you do not have a mouse, pressing the <Esc> key performs the same action.



**Note:** *The NI-VXI software requires up to 4 MB of free space on your hard disk, depending on the options you select.*

Setup is an interactive, self-guiding program that installs the NI-VXI software and configures your system to use the NI-VXI software with the AT-MXI-2. Follow these steps to perform the installation.

1. Insert the disk labeled *NI-VXI Software for AT-MXI-2*.
2. Select **Run...** from the Windows Program Manager's **File** menu and enter the following code, where x is your floppy drive (usually A or B).

X:\setup.exe

3. Click on the **Next** option at the **Welcome** screen to start the installation.
4. Select the target directory for your installation. Although Setup prompts you to accept a default directory, you can select a different location by clicking on **Browse...**
  - If you do not already have NI-VXI on your computer, Setup prompts you to select the default directory of C:\NIVXI.
  - Setup detects if you already have a previous installation of NI-VXI on your computer, and prompts you to either overwrite the previous version or install the new version in a different directory. Only one copy of NI-VXI can be active on your computer at any time. If you install the new version of NI-VXI into a different directory, the old installation is disabled.



**Caution:** *If you have a previous version of the NI-VXI software installed, Setup does not automatically create a backup of the software files. If there are files you want to preserve, you should exit the installation program now and make a backup before continuing.*

5. Select the type of installation you want.
  - **Typical** installation includes Windows and DOS drivers, utilities, and development files for all supported compilers.
  - **Compact** installation includes only the driver and utilities necessary to run applications written with NI-VXI.
  - **Custom** installation lets you select the target operating system and development environments according to your needs.



**Note:** *If you install the driver files, you must include the Common Windows/DOS Driver Files. Similarly, when installing development files, include Common Development Files in your custom installation.*

6. Select the name of the Program Manager folder that will contain icons for the NI-VXI software for AT-MXI-2.

At this point Setup copies the necessary files to your hard drive and creates Program Manager icons.



7. Your `AUTOEXEC.BAT` file needs to be modified to use NI-VXI. You can either let Setup modify the file, create a different file, or do nothing. If you decide to not let Setup modify your `AUTOEXEC.BAT` file, you should make the necessary changes manually. Refer to the following section, *Modifying the AUTOEXEC.BAT File*, for complete details.
8. When the installation process completes, run `VXIedit` to configure your system. If you want the Setup program to automatically start `VXIedit`, select the checkbox **Launch VXIedit to configure the system** in the last screen. Click on **Finish** to end the installation.



**Note:** *For your configuration settings to take effect, you must exit Windows and reboot your computer.*

9. You can now use `VXIedit` to configure the hardware in your VXI system. Continue with Chapter 6, *NI-VXI Configuration Utility*, for instructions on using the configuration editors in `VXIedit`.

## Modifying the AUTOEXEC.BAT File

If you choose to let Setup modify your `AUTOEXEC.BAT` file, it updates the setting of environment variables `PATH`, `LIB`, and `INCLUDE` to include the relevant subdirectories of the NI-VXI directory. When Setup modifies the file, it saves the old file as `AUTOEXEC.OLD` in the NI-VXI directory. The previously specified directories in `PATH`, `LIB`, and `INCLUDE` remain unchanged. Setup also adds a new environment variable `NIVXIPATH`, and appends a command line to execute `NI-PNP.EXE` and `VXIINIT.EXE` automatically.

If you choose not to let Setup modify your `AUTOEXEC.BAT` file, it creates a file called `AUTOEXEC.VXI` in the NI-VXI directory. Refer to the `AUTOEXEC.VXI` file for suggestions on how to change the following lines manually.

- The `PATH` variable should include the full path to the subdirectory where the NI-VXI utilities and `NIVXI.DLL` are located, in addition to whatever other directories you have already specified in `PATH`. The path must be specified so that Windows can locate the executable code when the library needs to be loaded. Normally, these files reside in the root of the NI-VXI directory, and also the `WIN` subdirectory.
- The `LIB` variable should include the full path to the subdirectories that contain the C libraries for the compiler you choose to install.

- The `INCLUDE` variable should include the full path to the subdirectory that contains the NI-VXI include files. By default, the include files reside in the `INCLUDE` subdirectory of the NI-VXI directory.
- The `NIVXIPATH` variable should contain the full path to the NI-VXI directory.
- `NI-PNP` should be executed before any other NI-VXI program.

## Using the DOS INSTALL Program

---

If you do not have Windows installed on your machine, you can install the NI-VXI software for DOS with the `INSTALL` program. The `INSTALL` program functions similarly to the Windows Setup program.

### Running INSTALL

Run `INSTALL.EXE`. This program copies the necessary files to your hard disk and performs the necessary steps to install the NI-VXI software for DOS to your system. Follow the directions as prompted.

## Resolving a Resource Conflict

---

The AT-MXI-2 is software configured for the following settings:

- IRQ level 11
- DMA Channel 6
- I/O ports 340h to 34Fh
- Memory region C800h to DFFFh

If these settings conflict with the settings of other devices in your system, you need to run `VXIedit` to change these settings. If `VXIedit` cannot run because of a conflict, follow these steps to resolve the conflict.

1. Remove `NI-PNP.EXE` from the `AUTOEXEC.BAT` file.
2. Reboot the computer.
3. Run `VXIedit` and reconfigure the board with new settings.
4. Replace the `NI-PNP.EXE` command in `AUTOEXEC.BAT`.

# NI-VXI Configuration Utility

---

Chapter

6

This chapter contains instructions for using the VXI Resource Editor utility of the NI-VXI software to configure the AT-MXI-2 and the VXI-MXI-2 or VME-MXI-2.

VXIedit is the VXI resource editor program that you use to configure the system and to edit the manufacturer name and ID numbers, the model names of VXI and non-VXI devices in the system, and the system interrupt configuration information. This program also displays the system configuration information generated by the Resource Manager.

The displays shown in this section are from the Windows version of VXIedit. The DOS version of VXIedit has the same organization and functionality as the Windows version although the displays look slightly different. The descriptions and instructions in this chapter apply to both versions of VXIedit.

You can use VXIedit even if the board is not present, but the program will lack some functionality. In the **AT-MXI-2 Configuration Editor**, all MXI/VXI-related fields will be grayed out.



**Note:**

*A text-based version, VXIedit, is also available as an alternative. You can run VXIedit in either Windows or DOS. Although this chapter focuses only on the graphical VXIedit program, the two programs are functionally equivalent. For information on VXIedit, refer to the NI-VXI Text Utilities Reference Manual.*

## Running the VXIedit Configuration Utility

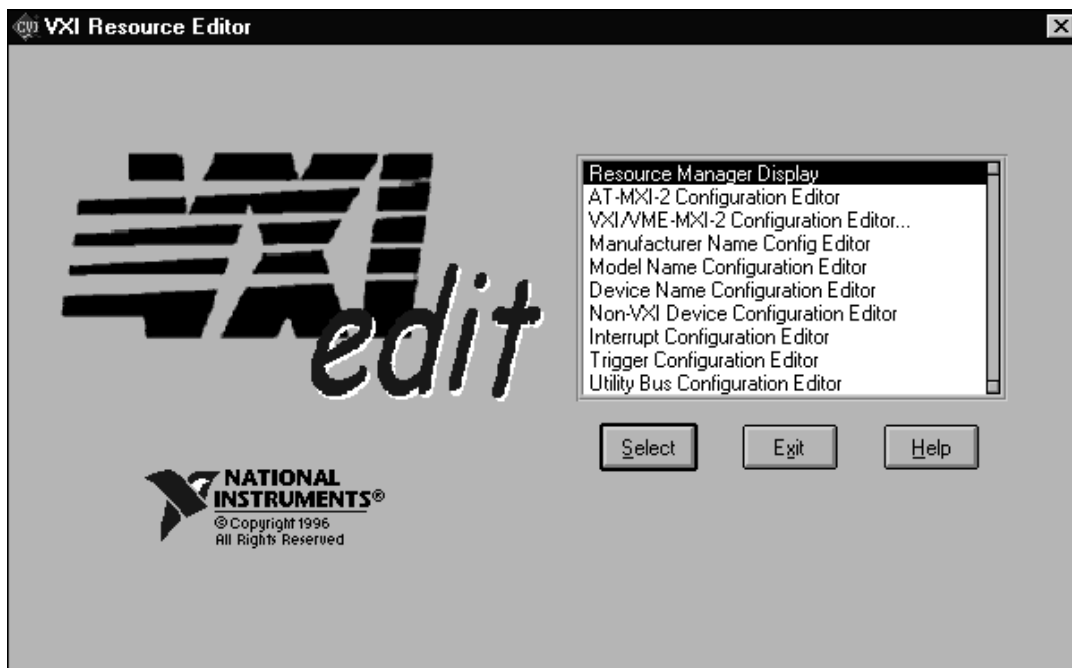
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To run VXIedit in Windows, double click the **VXIEDIT** (Windows) icon in the NI-VXI group. To run VXIedit in DOS, type **VXIEDIT** at the DOS command prompt. In DOS, you can run VXIedit from any directory, but make sure that both the **PATH** and **NIVXIPATH** environment variables have the destination directory of the NI-VXI software added to it. **PATH** is used to find the application itself, while **NIVXIPATH** is used by the application to find the different configuration

files (\*.CFG), table files (\*.TBL), and help files (\*.HLP) during its execution. The default pathname used by the program if NIVXIPATH is not set is C:\NIVXI.

The features on the AT-MXI-2 are configurable through software, using `VXIedit`, rather than through hardware switches or jumpers on the board itself. The same applies for several features on the VXI-MXI-2 and VME-MXI-2 modules. In addition, the `VXIedit` utility can override some of the hardware settings.

Figure 6-1 shows the main menu of the `VXIedit` resource editor.

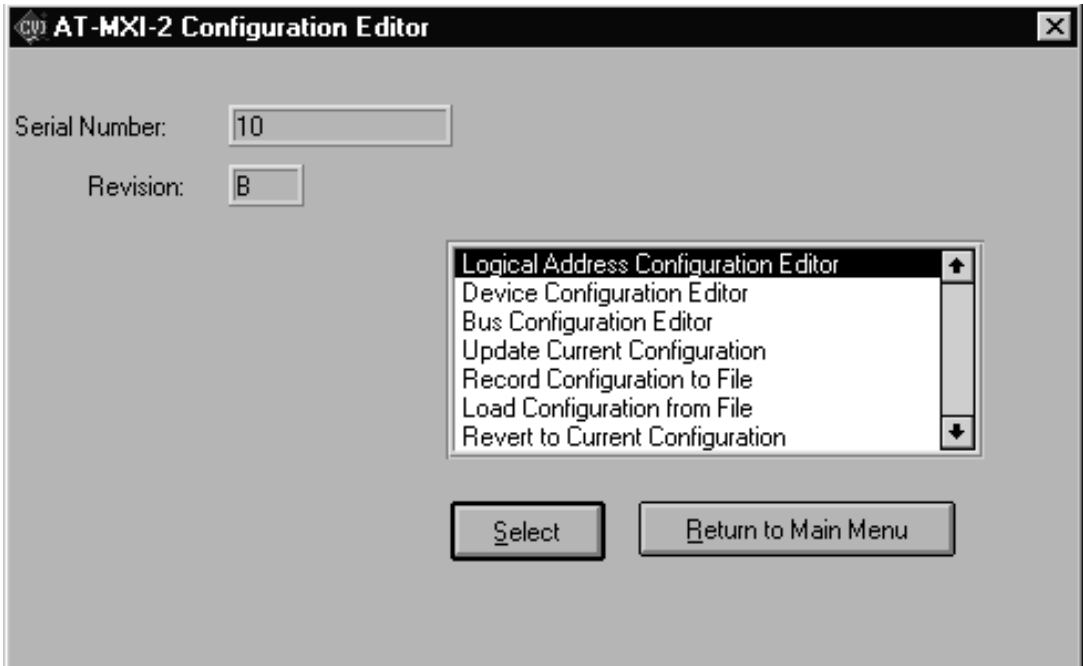


**Figure 6-1.** VXIedit Main Screen

The rest of this chapter describes only the features of the **AT-MXI-2 Configuration Editor** and the **VXI/VME-MXI-2 Configuration Editor**. For instructions on using the other editors, refer to your software utility reference manual, either the *NI-VXI Graphical Utilities Reference Manual* or the *NI-VXI Text Utilities Reference Manual*.

## AT-MXI-2 Configuration Editor

Figure 6-2 shows the opening screen of the **AT-MXI-2 Configuration Editor**. Notice that the screen displays the serial number and hardware revision of the AT-MXI-2 board in addition to several configuration options.



**Figure 6-2.** AT-MXI-2 Configuration Editor

The first three options under the **AT-MXI-2 Configuration Editor** are:

- **Logical Address Configuration Editor**
- **Device Configuration Editor**
- **Bus Configuration Editor**

When making changes to the AT-MXI-2 through these editors, remember that the changes do not take effect until you commit them by selecting the **Update Current Configuration** option.

The remaining four options of the **AT-MXI-2 Configuration Editor** directly relate to how you can use the changes you make using the configuration editors, which are described after the options.

## Update Current Configuration

Use this option to write the configuration settings to the AT-MXI-2 EEPROM and files used by NI-VXI. It configures the AT-MXI-2 to be consistent with the configuration EEPROM. Notice that some of the configuration settings cannot take effect until you reset the machine, either by using the reset button or by turning the power off and on again.



**Note:** *You will not be able to use the <Control-Alt-Del> keystroke combination to perform this reset. Instead you must perform a hardware reset as described above.*

## Record Configuration to File

With this option you can save your configuration settings to a file. Notice that this option does *not* write the configuration settings to the AT-MXI-2 configuration EEPROM.

If you want to update the AT-MXI-2 configuration settings, use the **Update Current Configuration** option instead.

## Load Configuration from File

You can use this option to load your configuration settings from a file. This action only updates the configuration settings in your editor. This does *not* write the configuration settings to the AT-MXI-2 configuration EEPROM. To update the configuration use the **Update Current Configuration** option for the changes to take effect.

## Revert to Current Configuration

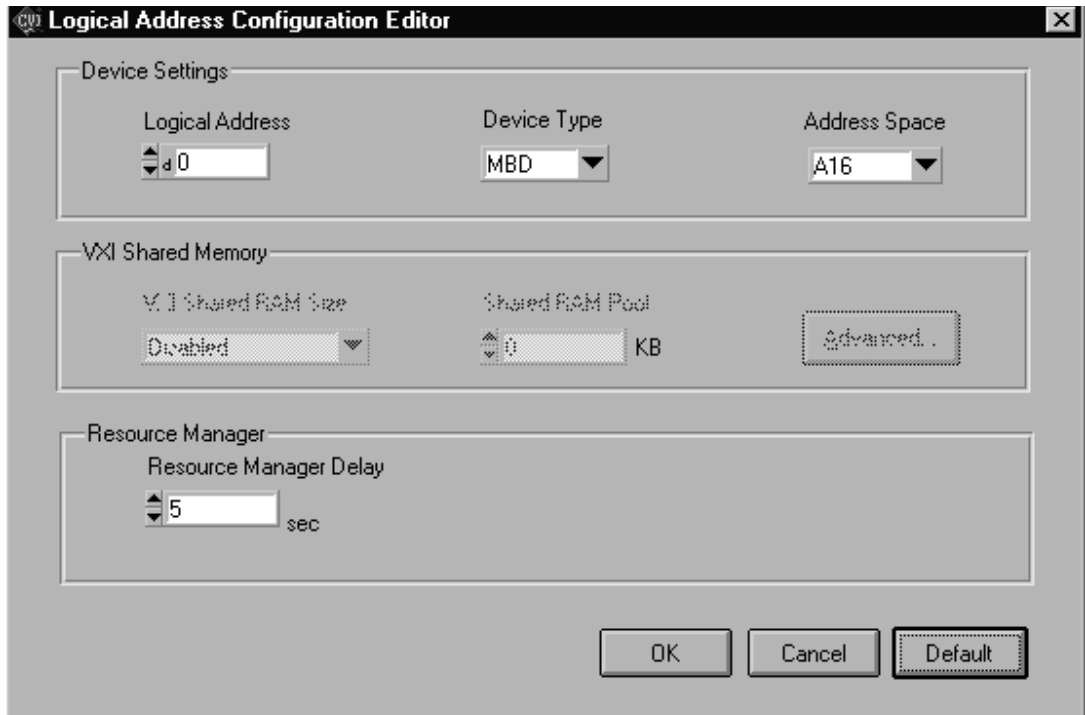
If you made changes to the configuration settings without committing those changes (writing to configuration EEPROM), you can revert the configuration settings to the values they had before you made the changes.



**Note:** *You can successfully revert only if you have **NOT** yet selected the **Update Current Configuration** option.*

## Logical Address Configuration Editor

Figure 6-3 shows the **Logical Address Configuration Editor**. Notice that the options are arranged into three groups—**Device Settings**, **VXI Shared Memory**, and **Resource Manager**. The following paragraphs describe the options you can select for each of the fields.



**Figure 6-3.** AT-MXI-2 Logical Address Configuration Editor

### Device Settings

The Device Settings group contains the controls to set the logical address, device type, and address space of the AT-MXI-2.

## Logical Address

This parameter sets the MXI logical address of the AT-MXI-2. The following table shows the allowable range of values and the default value.

Logical Address Range	Default Value
0 to 254	0

## Device Type

This field indicates the classification of the AT-MXI-2. The default value is **MBD**, designating a message-based device. The following table shows the available options.

Classification	Setting
Extended Device	<b>EXT</b>
Message-Based Device	<b>MBD</b>
Register-Based Device	<b>RBD</b>

The device type affects only the contents of the **Device Class** field in the Device Type register. The functionality of the other registers does not change.

## Address Space

This field indicates the addressing mode(s) of the device's operational registers. The AT-MXI-2 can be configured in one of three ways. The default addressing mode is for **A16** space only. Your other options are **A16/A24** and **A16/A32**.

Notice that several other controls on the configuration editor panel are disabled when the addressing mode is A16, as shown in Figure 6-3. Only if you select **A16/A24** or **A16/A32** are the following controls relevant:

- **VXI Shared RAM Size**
- **Shared RAM Pool**
- **Advanced**



- **Byte Swapping**
- **Memory Select**
- **Mapping**

## VXI Shared Memory

The **VXI Shared Memory** group contains the controls to set the VXI shared RAM size and the shared RAM pool. The **Advanced** button leads to additional options that configure the upper and lower half of the shared RAM area.



**Note:** *When the Address Space field is in the default setting of A16 only, all of the options in this group are disabled because they are irrelevant.*

## VXI Shared RAM Size

This field indicates the amount of RAM (in bytes) that are shared in either A24 or A32 space. This determines the *total* shared RAM size, which is then divided into two equal halves that you can set up independently of one another.



**Note:** *When the Address Space field is in the default setting of A16 only, this field is ignored.*

## Shared RAM Pool

This field indicates the size of memory (in kilobytes) that is allocated on Windows startup. This memory is used by the lower/upper half windows when the **Memory Select** control (accessible through the **Advanced** popup field) is set to **System memory**.

If you make a change to this setting, you must restart Windows to enable the change.

Memory Range	Default Value
0 to 65535 KB	0 KB

The following table indicates how the **Shared RAM Pool** relates to the **VXI Shared RAM Size** depending on the setting of the **Memory Select** control for the upper and lower half windows.

Lower Half Window	Upper Half Window	Shared RAM Pool (Window)
System memory	System memory	Equal to VXI Shared RAM Size
System memory	Onboard memory	Half the VXI Shared RAM Size
Onboard memory	System memory	Half the VXI Shared RAM Size
Onboard memory	Onboard memory	0

The shared RAM pool is used by `VXIMemAlloc()` function calls from both Windows applications and DOS applications running under Windows. For information on the `VXIMemAlloc()` function, refer to the *NI-VXI User Manual* and the *NI-VXI Programmer Reference Manual*.



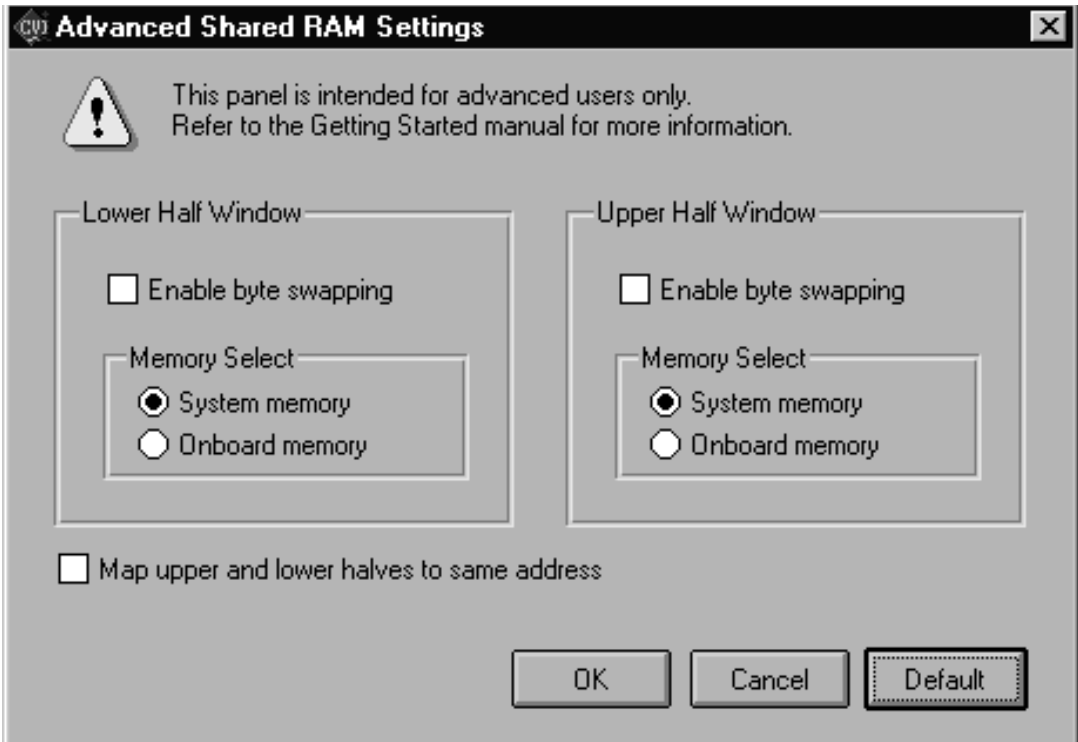
**Note:** *When the Address Space field is in the default setting of A16 only, this field is ignored. This field is also ignored if the Memory Select fields for both the lower and upper half windows are set to Onboard memory.*



**Caution:** *This memory pool is allocated at Windows startup, and will not be available for Windows. Take into account the memory requirements of Windows and your applications and the amount of memory in your system before setting this option.*

### Advanced Shared RAM Settings

Clicking on the **Advanced** button displays a dialog box to configure the destination of MXIbus cycles that map into the AT-MXI-2 through the A24/A32 shared RAM.



**Figure 6-4.** Advanced Shared RAM Settings



**Note:** *When the Address Space field is in the default setting of A16 only, these fields are ignored and cannot be accessed.*

The VXI shared RAM is divided into two halves, or *windows*. You can select the byte order for each half independently. You can map each half of the VXI shared RAM independently into system RAM on the motherboard or into onboard RAM on the AT-MXI-2.

Because each half is independent of the other, you can choose from any of these mapping options:

- Half the VXI shared RAM mapped to system RAM; the other half mapped to AT-MXI-2 onboard RAM
- Both halves mapped to AT-MXI-2 onboard RAM
- Both halves mapped to system RAM

### Enable Byte Swapping

This checkbox indicates whether byte swapping should be performed for slave accesses to this half of the VXI shared RAM space. For example, if the native byte order of the shared RAM is Intel (Little Endian), and you want to present data to the VXI/VMEbus in Motorola (Big Endian) byte order, you will need to enable byte swapping. The default value is non-swapped. Click on the checkbox if you want to enable byte swapping.

This field is ignored if the **Memory Select** field is set to **Onboard memory**.

Figure 6-5 shows four possible configurations of the VXI shared RAM, where the VXI shared RAM size is 16 MB and the VXI offset is 20000000 (hex). Notice that you can set up the byte order and memory select independently for the upper half and lower half window.

### Memory Select

This option determines where this half of the VXI shared RAM is mapped. By default, the shared RAM is mapped to **System memory**. If you want to use the RAM on the AT-MXI-2, choose the **Onboard memory** option.

### Window Mapping

When both halves of the inward window are mapped to the same destination with the same byte order, the windows essentially form one continuous window. If the windows are mapped to different destinations, the base of each inward window maps to the base of each destination.

If the windows both map to the shared RAM destination but the byte order is different, the base of each inward window maps to the base of the shared RAM destination. This results in one half of the window accessing the system RAM in Little Endian byte order and the other half accessing it in Big Endian byte order.

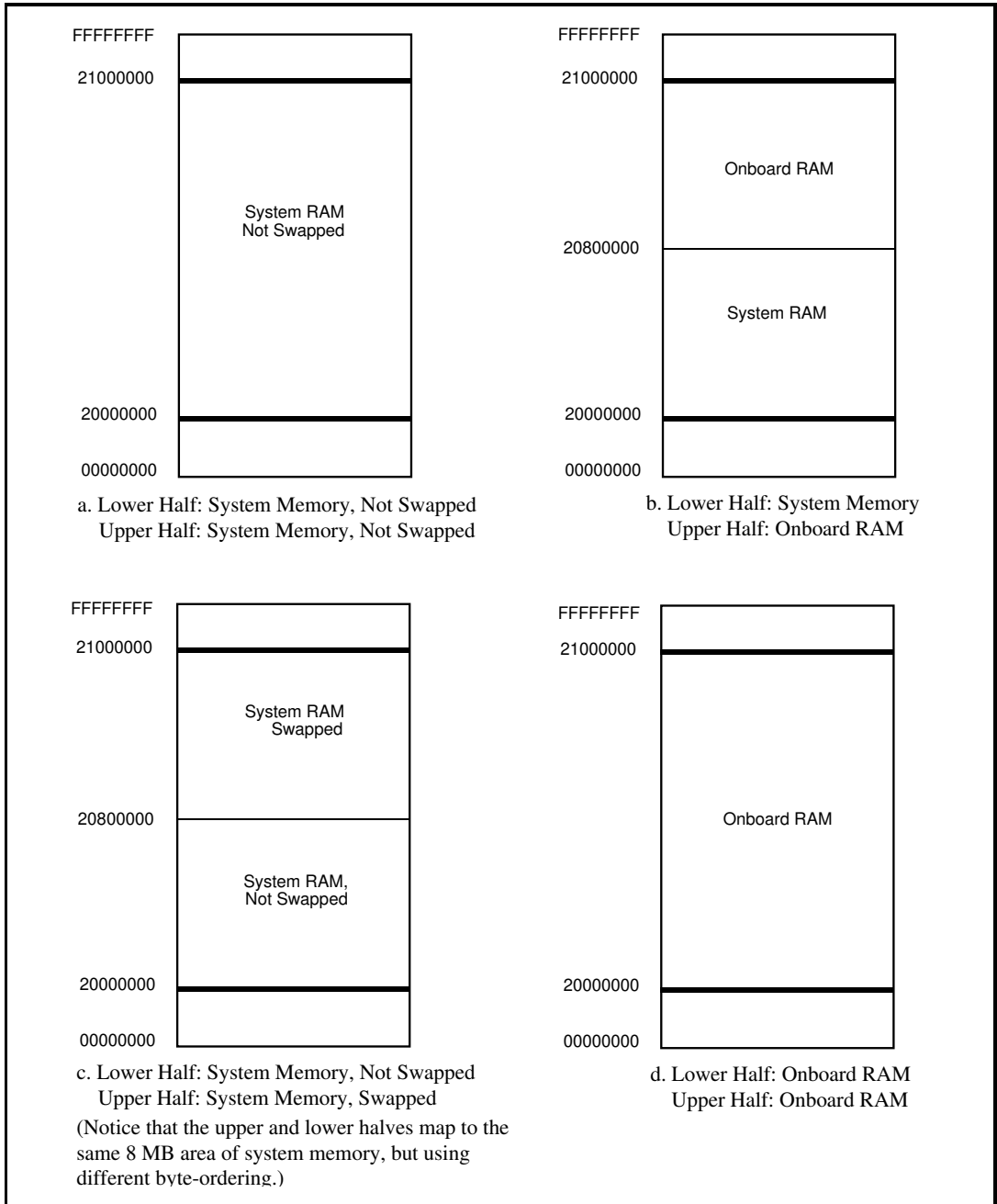


Figure 6-5. VXI Shared RAM Configurations

## Resource Manager

The only option under the **Resource Manager** portion of the **Logical Address Configuration Editor** is the **Resource Manager Delay** control.

### Resource Manager Delay

**Note:**

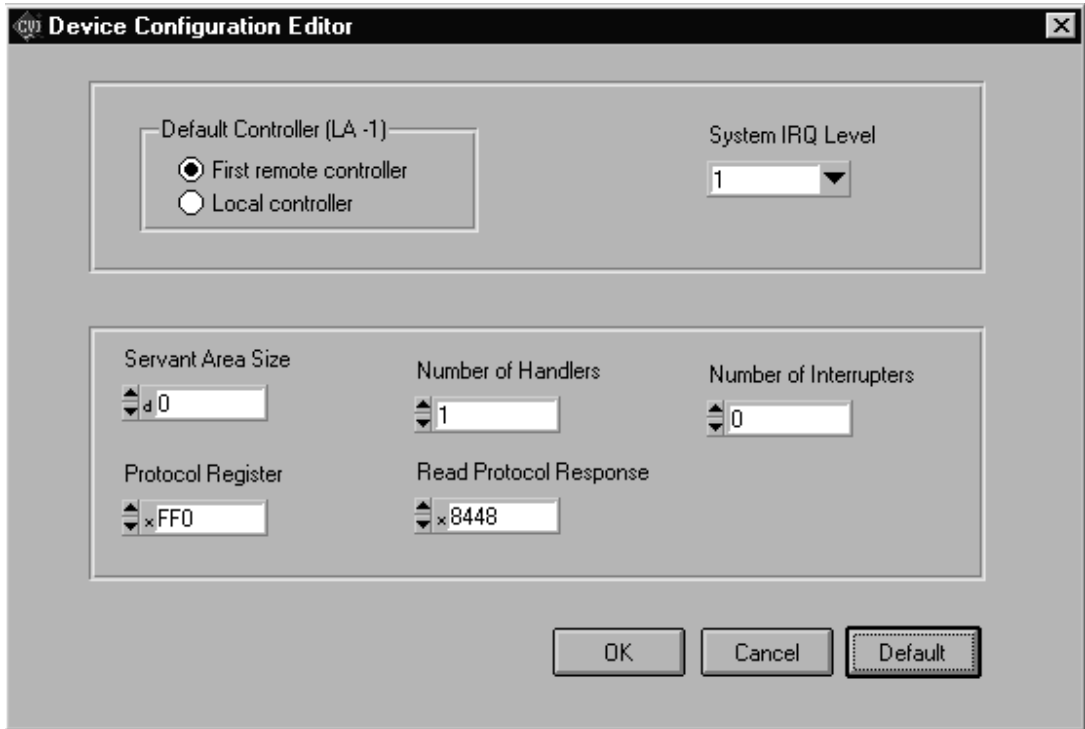
*This field is effective only when the AT-MXI-2 is at its default logical address of 0. The AT-MXI-2 is the Resource Manager only if its logical address is 0.*

This field specifies the time in seconds that the Resource Manager (RM) waits before accessing any other VXI/VMEbus device's A16 configuration registers.

RM Delay Range	Default Value
0 to 65535 s	5

## Device Configuration Editor

Figure 6-6 shows the **Device Configuration Editor**. The following paragraphs describe the options you can select for each of the fields.



**Figure 6-6.** AT-MXI-2 Device Configuration Editor

### Default Controller (LA -1)

Many NI-VXI functions use **controller** as a parameter with -1 accepted as a valid value. You use this selection to determine which controller you are referring to when you use -1 in these NI-VXI functions. Review the descriptions of the NI-VXI functions to determine which are applicable for this control.

By default, the **Default Controller (LA -1)** option is set to **First remote controller**, so that any NI-VXI functions that are passed the value of -1 for the **controller** parameter will be executed on the first VXI/VME-MXI-2 in the MXI-2 chain. If you select the **Local controller** option, the NI-VXI functions execute on the AT-MXI-2.

## System IRQ Level

The remote controllers—in this case the VXI/VME-MXI-2—can report events such as triggers and DMA to the AT-MXI-2 through a VXI IRQ line. This field selects which VXI IRQ level the remote controllers should use to report events to the AT-MXI-2.

Interrupt Request Levels	Default Value
1 to 7	1

## Servant Area Size

This field designates the servant area size, which is supplied to the Resource Manager in response to the *Read Servant Area* command (if the AT-MXI-2 is *not* the Resource Manager in your system). The servant area size is an 8-bit value (0 through 255) that indicates the servant area. The servant area begins at the logical address following the AT-MXI-2 logical address, and includes  $N$  contiguous logical addresses, where  $N$  is the value of the servant area size. This field is meaningful only when the AT-MXI-2 is configured as a message-based device.

Servant Area Range	Default Value
0 to 255	0



### Note:

*If the AT-MXI-2 is the Resource Manager (Logical Address 0), this setting is irrelevant.*

## Number of Handlers

This field gives the number of interrupt handlers that the AT-MXI-2 supports.

Interrupt Handlers	Default Value
0 to 7	1



## Number of Interrupters

This field gives the number of interrupters that the AT-MXI-2 supports.

Interrupters	Default Value
0 to 7	0

## Protocol Register

This field specifies the contents of the Protocol register, indicating which protocols the device supports. This field is meaningful only when the AT-MXI-2 is configured as a message-based device. The default value is 0x0ff0 (Commander, Signal Register, Master).

## Read Protocol Response

This field specifies the response value to a *Read Protocol* command received by the AT-MXI-2 from the Resource Manager (if the AT-MXI-2 is *not* the Resource Manager in your system). This field is meaningful only when the AT-MXI-2 is configured as a message-based device. The default value is 0x8448 (Response Generation, Event Generation, Programmable Handler, Word Serial Trigger, Instrument, Extended Longword Serial, Longword Serial).

## Bus Configuration Editor

Figure 6-7 shows the **Bus Configuration Editor**. The following paragraphs describe the options you can select for each of the fields.

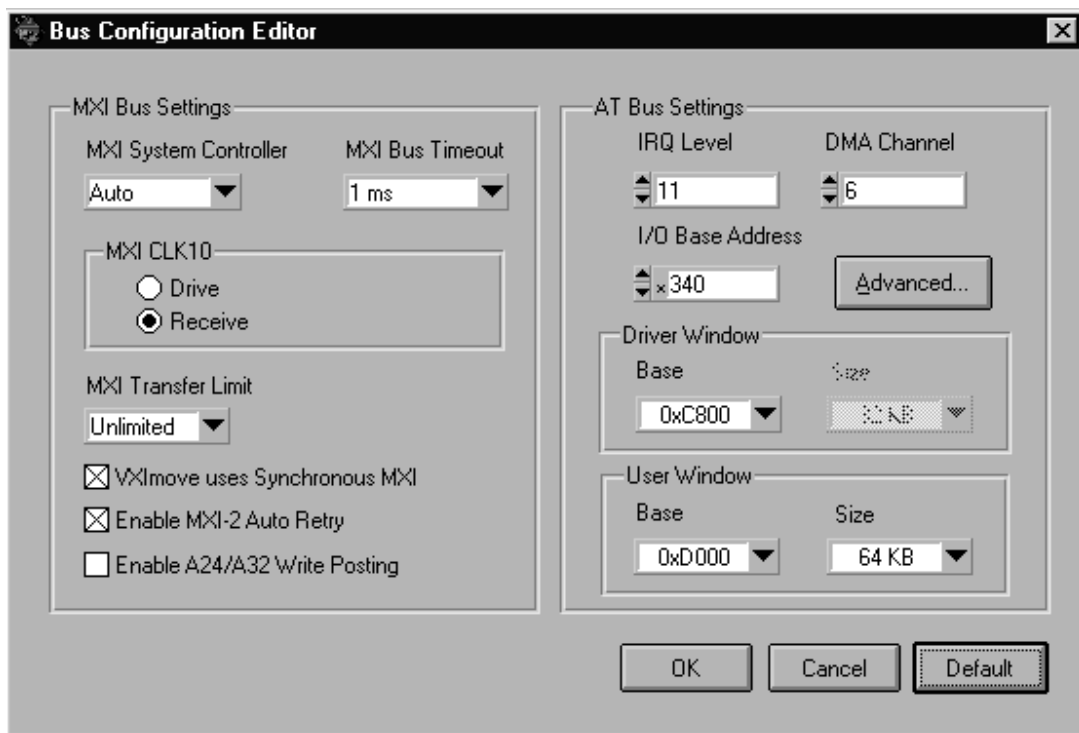


Figure 6-7. AT-MXI-2 Bus Configuration Editor

### MXI Bus Settings

The following paragraphs describe the options for the **MXI Bus** portion of this editor.

#### MXI System Controller

You can use the **MXI System Controller** control to determine whether the AT-MXI-2 acts as the MXIbus System Controller. The three options are **Auto**, **Yes**, and **No**.

When the **Auto** setting is active (the default setting), the AT-MXI-2 automatically can sense from the MXIbus cable whether it should be the controller. This setting requires that the cable is attached properly

before making any NI-VXI function calls or attempting to use the **VXI/VME-MXI-2 Configuration Editor**. Refer to the *Connect the MXIbus Cable* section at the end of either Chapter 3 or Chapter 4 of this manual.

You can use the **Yes** or **No** options to manually determine whether the AT-MXI-2 should be the MXIbus System Controller. You must still be certain to cable the MXIbus system appropriately when you make either of these selections.



**Note:** *Make sure the MXI-2 cable is connected to the AT-MXI-2 when you power on or reboot the computer. This is required for the AT-MXI-2 to automatically detect whether it will be the MXIbus System Controller.*

## MXI Bus Timeout

The MXIbus Bus Timeout (BTO) is a watchdog timer for transfers on the MXIbus. The MXIbus BTO operates only when the AT-MXI-2 is acting as the MXIbus System Controller.

After the specified amount of time has elapsed, the BTO circuitry terminates a MXIbus cycle if no slave has responded. The BTO is also disabled when the current MXIbus cycle maps to the VXI/VMEbus through a VXI/VME-MXI-2.

The default timeout value is 1 ms. If the **Enable MXI-2 Auto Retry** checkbox option is checked, you should use a **MXI Bus Timeout** of 1 ms or greater.

## MXI CLK10

The AT-MXI-2 is capable of either receiving or driving the MXIbus CLK10 signal.

You can use the **Drive** or **Receive** options of the **MXI CLK10** feature to control the direction of the MXIbus CLK10 signal. By default all MXI-2 boards receive MXI CLK10 (the **Receive** option is active); therefore, you must choose one board on your MXI-2 bus to drive CLK10 by changing the value of the control to **Drive**. For most configurations, it is recommended to choose the System Controller as the CLK10 source for simplicity. The only exception you may want to make is if you want your triggers synchronous to the VXI 10 MHz clock.



**Warning:** *Do not configure more than one MXIbus device to drive MXI CLK10. Having a second device driving MXI CLK10 could damage the device.*

## MXI Transfer Limit

Use this feature to control how many data transfers the AT-MXI-2 will perform on the MXIbus before releasing it to another master device that is requesting use of the bus. The default setting holds the MXIbus for an unlimited period of time.

The other options you can choose from are 256, 64, and 16 transfers. If you do not want the AT-MXI-2 to hold the MXIbus for an unlimited period of time, you can use this control to select one of these values.

## Synchronous MXI

The MXIbus has a special high-speed block protocol for transferring large blocks of data. This protocol, *SYNC-MXI*, locks the MXIbus during the transfer, which prevents anyone else from using the bus. `VXImove()` uses this protocol to transfer data. By default this option is enabled—the **VXImove uses Synchronous MXI** checkbox is checked.

If a VXI interrupt or signal comes in while a synchronous MXI move is underway, there can be a problem. You can disable SYNC-MXI programmatically in `VXImove()`. If you have an older NI-VXI application that does not disable SYNC-MXI programmatically, you can deselect the checkbox to force your application to not use SYNC-MXI, if necessary.

## MXI-2 Auto Retry

The AT-MXI-2 has an automatic retry feature for cycles that map from the MXI bus to the AT bus. By default this option is enabled—the **Enable MXI-2 Auto Retry** checkbox is checked.

Normally, when a cycle maps from the MXI bus to the AT bus, any retry response received on the AT bus is passed to the MXI bus. When the MXI-2 auto retry feature is enabled, the AT-MXI-2 automatically retries any AT cycle when the AT host responds to a cycle with a retry. The AT-MXI-2 automatically continues to retry the AT cycle until it receives either a *DTACK* or *BERR* response, which it then passes to the MXIbus. This is the default situation because many external masters do not support VXI/MXI retries. If the external master does support retries,

it may be beneficial to disable the MXI-2 auto retry feature. With this feature disabled, you can lower the **MXI Bus Timeout** value because there will be no delay due to the inward cycles being retried.



**Note:** *The AT-MXI-2 has a limit on the number of automatic retries it will perform on any one cycle. If the limit is exceeded and the AT-MXI-2 receives another retry, it will pass a retry back to the MXIbus even though the **Enable MXI-2 Auto Retry** checkbox is checked.*

## A24/A32 Write Posting

This field determines whether to enable write posting for incoming slave accesses to A24/A32 VXI shared RAM. By default this option is disabled—the **Enable A24/A32 Write Posting** checkbox is cleared.

Enabling write posting will increase the throughput of your inward cycles. However, you should not enable write posting unless the destination of your inward A24/A32 cycles is onboard RAM, because cycles to onboard RAM will always complete successfully.

## AT Bus Settings

The following paragraphs describe the options for the **AT Bus** portion of this editor.



**Note:** *If you are using ISA Configuration Manager software, this portion of the panel will be grayed out. You must use the ISA Configuration Utility (ICU) to change these settings. Please refer to your ICU documentation for further information.*

You will need to change these settings from their default settings if your system already uses any of these resources. Refer to the *Resolving a Resource Conflict* section at the end of Chapter 5 for more information.

## IRQ Level

Use this control to select an interrupt level that the AT-MXI-2 will use to interrupt the processor. The default interrupt level is 11. Other valid values you can select are 3, 4, 5, 6, 7, 9, 10, 12, 14, and 15.

## DMA Channel

Use this control to select an AT DMA channel that the AT-MXI-2 will use in all accesses to system RAM. The AT-MXI-2 will access system RAM when a MXI-2 cycle maps to shared memory in your computer,

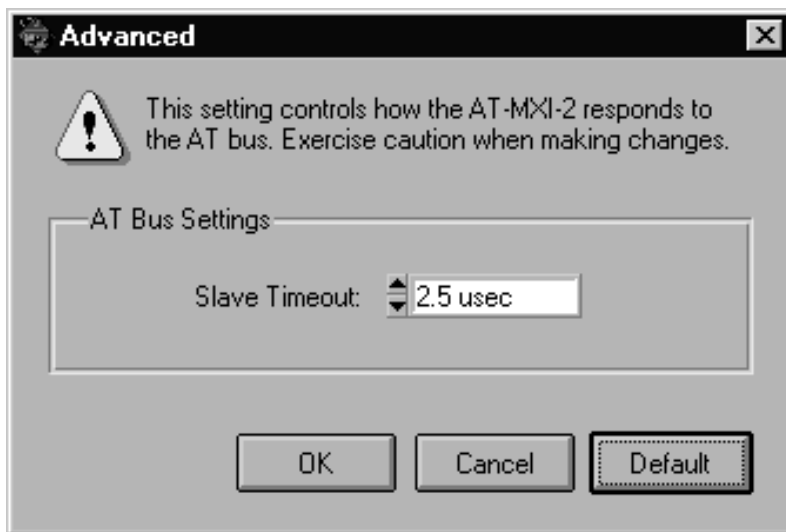
or when a MITE DMA channel is used to perform a block move using the `VXImove()` function. The default DMA channel is 6. Other valid values you can select are 1, 3, 5, and 7.

## I/O Base Address

Use this control to select the I/O address of the AT-MXI-2 configuration registers. The default address is 340 (hex). Each AT-MXI-2 board occupies 16 bytes of I/O address space. You can select another address in the range of 20 (hex) to FFE0 in increments of 10 (hex).

## Advanced Bus Configuration Settings

Clicking on the Advanced button displays a dialog box to configure the slave timeout setting. This option is intended for more advanced users.



**Figure 6-8.** Advanced AT Bus Settings

### Slave Timeout

Slave timeout determines how long the AT-MXI-2 can hold the AT bus when it is acting as a slave. By default, this value is set to 2.5  $\mu$ s, which is the maximum allowed by the AT specification. However, in many cases this value can be increased up to 10  $\mu$ s without causing any problems. Increasing the slave timeout will increase your system performance.

## User Window and Driver Window

The AT-MXI-2 driver requires at least one memory window of 32 KB. NI-VXI uses the driver window to perform high-level functions such as `VXIin()` and `VXIout()`, and to access registers on the AT-MXI-2 and VXI/VME-MXI-2. If you plan to use low-level access functions, such as `MapVXIAddress()`, `VXIpeek()`, and `VXIpoke()`, you will also need a user window. Calling the `MapVXIAddress()` function allocates regions of the user window to your application. `VXIpeek()` and `VXIpoke()` accesses are performed through this window.

### Window Base

Valid values are C800 up to E800, in increments of 16, 32, or 64 KB, depending on the size of the window. The default values are C800 for the driver window, and D000 for the user window.

### Window Size

The amount of space you can allocate for the user window is system dependent. You can use the **Size** control to select the size of the user window (16, 32, or 64 KB). The more you increase the size of the user window, the larger the window you can map in `MapVXIAddress()`.

You can also disable this option. Disabling the user window causes the AT-MXI-2 to request the minimum amount of address space on the AT bus. With the window disabled, you will be unable to perform any low-level function calls such as `VXIpeek()`, `VXIpoke()`, and `MapVXIAddress()`. For example, on DOS systems, you may not be able to request more than the 32 KB driver window if the address space between 640 KB and 1 MB is being used by other devices in your computer.

It is recommended to have a user window of at least 32 KB. The default setting for the user window is set at 64 KB. If you are going to be initiating transfers to a wide variety of addresses in both A24 and A32, you should increase the size of the user window.

The size of the driver window, however, is system defined and is not user configurable.

## VXI/VME-MXI-2 Configuration Editor

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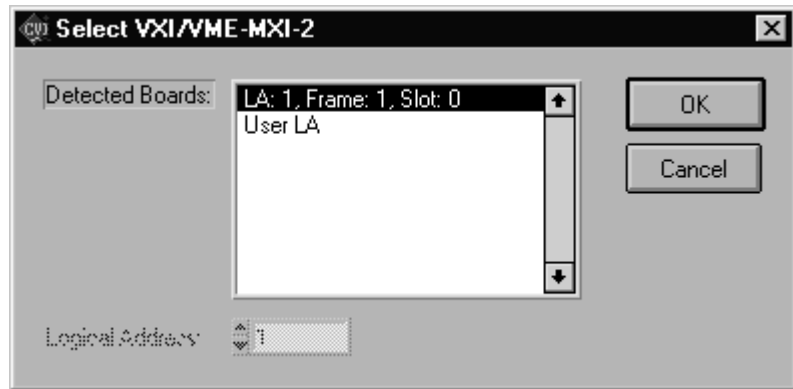
Before running the **VXI/VME-MXI-2 Configuration Editor**, you must run `VXIinit` and `RESMAN`. Upon entering this editor,

the program prompts you to enter the logical address of the VXI/VME-MXI-2 that you are configuring.



**Note:** *Throughout this section, the term VXI/VME-MXI-2 denotes that the information applies equally to the VXI-MXI-2 or the VME-MXI-2.*

Upon entering the **VXI/VME-MXI-2 Configuration Editor**, the program displays a list of VXI/VME-MXI-2 boards that RESMAN detected in your system, as shown in Figure 6-9.



**Figure 6-9.** VXI/VME-MXI-2 Selection Dialog Box

Select the device you want to configure from the **Detected Boards** list, or you can select the **User LA** control and type in the device's logical address in the **Logical Address** field. Click **OK** to enter the editor or **Cancel** to return to the main menu.

After finding a VXI/VME-MXI-2, the **VXI/VME-MXI-2 Configuration Editor** displays a panel, as shown in Figure 6-10, that you can use to modify the configuration settings of that VXI/VME-MXI-2. The panel displays the current settings of the module. Notice that it also shows the hardware revision and serial number of the VXI/VME-MXI-2.

The title of the screen will reflect the model of the device you have. For instance, if you have a VXI-MXI-2, the title will read **VXI-MXI-2 Configuration Editor** as shown in the following screen.



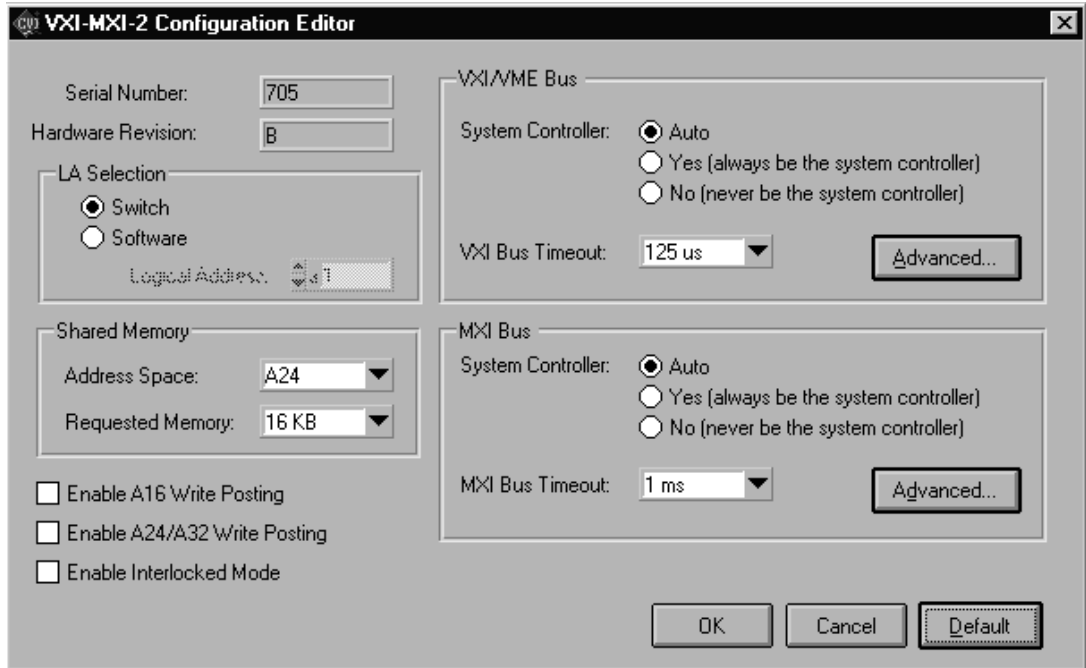


Figure 6-10. VXI/VME-MXI-2 Configuration Editor

## LA Selection and Logical Address

You can set or modify the logical address of the VXI/VME-MXI-2 either within the **VXI/VME-MXI-2 Configuration Editor** itself or with the onboard 8-position DIP switch. To select the configuration method you prefer, use the **LA Selection** control.

The default selection is the **Switch** option. Notice that the **Logical Address** control is inaccessible, since it would have no effect. In this option you need to change the hardware switch setting on the VXI/VME-MXI-2 itself if you want to change the logical address.

If you select **Software** for this option, you can then use the **Logical Address** control to select a logical address within the range of 1 to 254. If you use this option, the hardware switch setting has no effect and you must use the **VXI/VME-MXI-2 Configuration Editor** to change the logical address.

## Address Space and Requested Memory

The VXI/VME-MXI-2 requires at least 16 KB of address space in A24 space or at least 64 KB in A32 space. Use the **Address Space** control to select whether you want to use A24 space or A32 space. Use the **Requested Memory** control to set the amount of memory space that the VXI/VME-MXI-2 will request. You can select up to 8 MB in A24 space and up to 2 GB in A32 space. The default setting uses the minimum requirement of 16 KB in A24 space.

These controls are necessary if you change the amount of DRAM installed on the VXI/VME-MXI-2. The amount of memory you set with the **Requested Memory** control should match the amount of DRAM installed on the VXI/VME-MXI-2. If no DRAM is installed, keep the default setting of 16 KB. Notice that the smallest valid amount in A32 space is 64 KB.



**Caution:** *If you install DRAM into the VXI/VME-MXI-2, do not attempt to use the first 4 KB of memory space. This 4 KB space maps to the registers on the VXI/VME-MXI-2 and does not access onboard DRAM. Accessing this region will cause your VXI/VME-MXI-2 to behave incorrectly.*

If you do not want to lose 4 KB of DRAM you can get around this limitation by setting the **Requested Memory** control to double the amount that is installed on the VXI/VME-MXI-2, because the DRAM is aliased throughout the remainder of the requested memory space. The DRAM should then be accessed in the upper half of the requested memory space.

## A16 and A24/A32 Write Posting

The VXI/VME-MXI-2 can increase performance with its capability to post write cycles from both the MXIbus and the VXI/VMEbus. Write cycles should be posted only to devices that cannot return a *BERR* signal, because the *BERR* will not be reported to the originating master.

Click on the checkbox control(s) if you want to use either A16 or A24/A32 write posting. By default, both options are disabled.

The A16 write posting control affects only write cycles that map through the A16 window from the VXI/VMEbus to the MXIbus and vice-versa. A16 write cycles in VXI configuration space are never posted regardless of the setting of this control.

The A24/A32 write posting control affects write cycles that map through the A24 window and A32 window from the VXI/VMEbus to the MXIbus and vice-versa. This control also affects write cycles to the VXI/VME-MXI-2 itself via its requested memory space from both the VXI/VMEbus and the MXIbus. For more information on the A16, A24, and A32 windows, refer to VXI-6, the *VXIbus Mainframe Extender Specification*.

## Interlocked Mode

Interlocked arbitration mode is an optional mode of operation in which at any given moment the system can perform as if it were one large VXI/VMEbus mainframe with only one master of the entire system—VXI/VMEbus and MXIbus. This mode of operation prevents deadlocks by interlocking all arbitration in the VXI/VMEbus/MXIbus system. By default, this option is disabled, which puts the VXI/VME-MXI-2 in normal operating mode.

In normal operating mode (non-interlocked), multiple masters can operate simultaneously in the VXI/VMEbus/MXIbus system. A deadlock occurs when a MXIbus master requests use of a VXI/VMEbus resource in another VXI/VMEbus mainframe while a VXI/VMEbus master in that mainframe is in the process of requesting a resource across the MXIbus. When this situation occurs, the VXI/VMEbus master must give up its bus ownership to resolve the conflict. The *RETRY* signal is used to terminate the transfer on the VMEbus; however, devices in the VXI/VMEbus mainframe must be able to detect a *RETRY* caused by a deadlock condition so that they can retry the operation. Any master device that cannot detect the *RETRY* protocol will interpret the response as a *BERR* signal instead.

The VXI/VME-MXI-2 is shipped from the factory configured for normal operating mode (non-interlocked). If MXIbus transfers will be occurring both into and out of the mainframe and the VXI/VMEbus modules in your system do not have the capability for handling retry conditions, you may want to configure the VXI/VME-MXI-2 for interlocked arbitration mode by clicking on the Enable checkbox. In this mode, no software provisions for deadlock conditions are required. However, parallel accesses in separate VXI/VMEbus mainframes are no longer possible, and system performance may be lower than in normal operating mode.

In a VXI/VMEbus/MXIbus system, you can configure some VXI/VME-MXI-2 modules for normal operating mode and others for interlocked arbitration mode. The VXI/VMEbus mainframes configured in interlocked arbitration mode will be interlocked with each other and the mainframes configured for normal operating mode can perform transfers in parallel.

This type of system configuration is recommended if you have one of the following situations:

- A VXI/VMEbus mainframe with only slave devices and no masters. Without bus masters, there is no chance for deadlock. You can configure the VXI/VME-MXI-2 devices in this mainframe for normal operating mode.
- A VXI/VMEbus mainframe with both masters and slaves, but the masters communicate only with the slaves in their mainframe. The masters never attempt transfers across the MXIbus, so there is no chance for deadlock when a MXIbus master attempts a transfer into the VXI/VMEbus mainframe. You can configure the VXI/VME-MXI-2 devices in this mainframe for normal operating mode.
- A VXI/VMEbus mainframe in which all masters that perform cycles across the MXIbus support the VME64 RETRY protocol. You can configure the VXI/VME-MXI-2 devices in this mainframe for normal operating mode because all masters that could cause a deadlock will automatically retry the operation.

## VXI/VME Bus Options

Use the options in this group to control features of the VXI/VMEbus interface on the VXI/VME-MXI-2.

### VMEbus System Controller

You can use the **System Controller** control to override the jumper setting on the VXI-MXI-2. The VME-MXI-2 does not have an onboard jumper setting for this option. When the **Auto** setting (the default setting) is active, the onboard jumper setting determines if the VXI-MXI-2 is the VXI Slot 0 device. For more information, refer to the *VXIbus Slot 0/Non-Slot 0* section in Chapter 3, *VXI-MXI-2 Configuration and Installation*.

Otherwise, choose either the **Yes** or **No** option. Notice that selecting either of these options overrides the onboard jumper setting on the VXI-MXI-2, so it will not matter how the jumper is set. You would need to run the **VXI/VME-MXI-2 Configuration Editor** again if you decide to change the VMEbus System Controller (VXI Slot 0) setting at a later time.



**Warning:** *Do not install a VXI/VME-MXI-2 configured for VMEbus System Controller (VXI Slot 0) into another slot without first reconfiguring it to either Non-Slot 0 or automatic configuration. Neglecting to do this could damage the VXI/VME-MXI-2, the VXI/VMEbus backplane, or both.*

*This means that you should use either the No option or the Auto option of this control. For the VXI-MXI-2, you also have the option of changing the hardware jumper setting.*

## VXI/VME Bus Timeout Value

The VXI/VMEbus Bus Timeout (BTO) is a watchdog timer for transfers on the VMEbus Data Transfer bus. After the specified amount of time has elapsed, the BTO circuitry terminates a VMEbus cycle if no slave has responded. The VXI/VME-MXI-2 must provide the VXI/VMEbus BTO for proper operation because when a MXIbus cycle is involved, the VXI/VMEbus timeout must be disabled and the MXIbus BTO enabled. You should disable the BTO of any other BTO module residing in the mainframe. If this is not possible, set its **VXI Bus Timeout** control to its maximum setting to give the MXIbus cycles as much time as possible to complete.

The lowest value in the allowable range is 15  $\mu$ s and the highest is 256 ms. The default value is 125  $\mu$ s.

## Advanced VXI Settings

Click on the **Advanced** button to reach additional configuration options for the VXI/VME Bus portion of this editor, as shown in Figure 6-11. These options are intended for more advanced users.

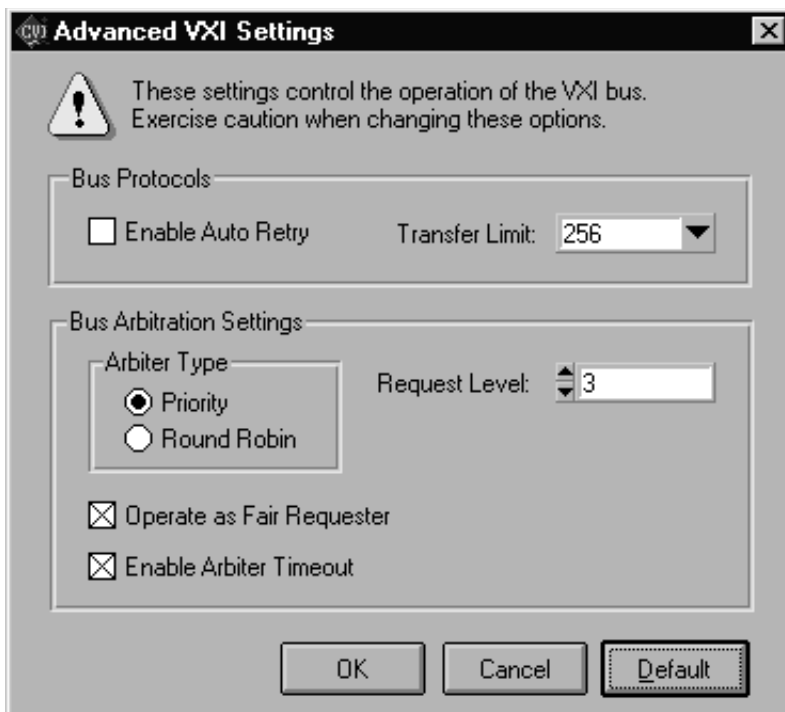


Figure 6-11. Advanced VXI Settings

## VXI/VME Auto Retry

The VXI/VME-MXI-2 has an automatic retry feature for cycles that map from the VXI/VMEbus to the MXIbus. By default this option is disabled.

Normally, when a cycle maps from the VXI/VMEbus to the MXIbus, any retry response received on the MXIbus is passed to the VXI/VMEbus. If you enable the **Auto Retry** feature, the VXI/VME-MXI-2 automatically retries any MXI cycle that receives a retry response instead of passing a retry response back to the VXI/VMEbus. The VXI/VME-MXI-2 automatically continues to retry the MXI cycle until it receives either a *DTACK* or *BERR* response, which it then passes to the VXI/VMEbus.

Notice that the VXI/VME-MXI-2 has a limit on the number of automatic retries it will perform on any one cycle. If the limit is exceeded and the VXI/VME-MXI-2 receives another retry, it will pass a retry back to the VXI/VMEbus even though **Auto Retry** is enabled.

## Transfer Limit

You can use this feature to control how many data transfers the VXI/VME-MXI-2 will perform on the VXI/VMEbus before releasing it to another master device that is requesting use of the bus.

The available options you can choose from are 16, 64, and 256 transfers. If you do not want the VXI/VME-MXI-2 to hold the VXI/VMEbus long enough to perform 256 transfers (the default value), you can use this control to select a smaller value.

## Arbiter Type

You can use the **Arbiter Type** feature to configure the VXI/VME-MXI-2 as either a Priority or Round Robin VMEbus arbiter. This control is applicable only if the VXI/VME-MXI-2 you are configuring is a VMEbus System Controller (VXI Slot 0) device. The default value is **Priority**.

When configured for **Priority** arbitration, the VXI/VME-MXI-2 grants the bus to the highest pending bus request level. In **Round Robin** arbitration mode, the VXI/VME-MXI-2 grants the bus to the next highest bus request level after the level of the previous bus owner. This effectively gives the same priority to each bus request level. Refer to the VMEbus specification for more information on the different types of arbiters.

## Request Level

The VXI/VME-MXI-2 uses one of the four VMEbus request levels (0 to 3) to request use of the VME Data Transfer Bus (DTB). The VXI/VME-MXI-2 requests use of the DTB whenever an external MXIbus device, such as a PC AT with an AT-MXI-2 interface, attempts a transfer that maps into the VXI/VMEbus mainframe.

The VXI/VME-MXI-2 uses VMEbus request level 3 in its factory-default setting, as required by the VXIbus specification. This is suitable for most VXIbus systems. However, you can change the VXI/VME-MXI-2 to use any of the other three request levels (0, 1, or 2) by changing the setting of the **Request Level** control. You may want to change request levels to change the priority of the VXI/VME-MXI-2 request signal. For more information, refer to the VMEbus specification.

## VXI/VME Fair Requester

The VXI/VME-MXI-2 is always a Release On Request requester. However, you can configure whether the VXI/VME-MXI-2 acts as either a fair or unfair requester on the VXI/VMEbus. By default the **Operate as Fair Requester** checkbox is enabled, signifying a fair requester. For more information on the different types of requesters, refer to the VMEbus specification.

## Arbiter Timeout

An arbitration timeout feature is available on the VXI/VME-MXI-2 when it is acting as the VMEbus arbiter. This feature applies only to a VXI Slot 0 (VMEbus System Controller) VXI/VME-MXI-2. By default this option is enabled.

The timer begins when the arbiter circuit on the VXI/VME-MXI-2 drives one of the *BGOUT* lines on the backplane. If no device takes over the bus within the timeout limit, the *BGOUT* is removed and the bus is either idle or granted to another requester.

## MXI Bus Options

Use the options in this group to control features of the MXIbus interface on the VXI/VME-MXI-2 module.

### MXIbus System Controller

You can use the **System Controller** control to determine whether the VXI/VME-MXI-2 acts as the MXIbus System Controller. When the **Auto** setting (the default setting) is active, the VXI/VME-MXI-2 automatically can sense from the MXIbus cable whether it should be the controller.

You can select either **Yes** or **No** to manually determine if the VXI/VME-MXI-2 should be the MXIbus System Controller. You must still be certain to cable the MXIbus system appropriately when you make either of these selections.

### MXI Bus Timeout Value

The MXIbus Bus Timeout (BTO) is a watchdog timer for transfers on the MXIbus. The MXIbus BTO unit operates only when the VXI/VME-MXI-2 is acting as the MXIbus System Controller. The

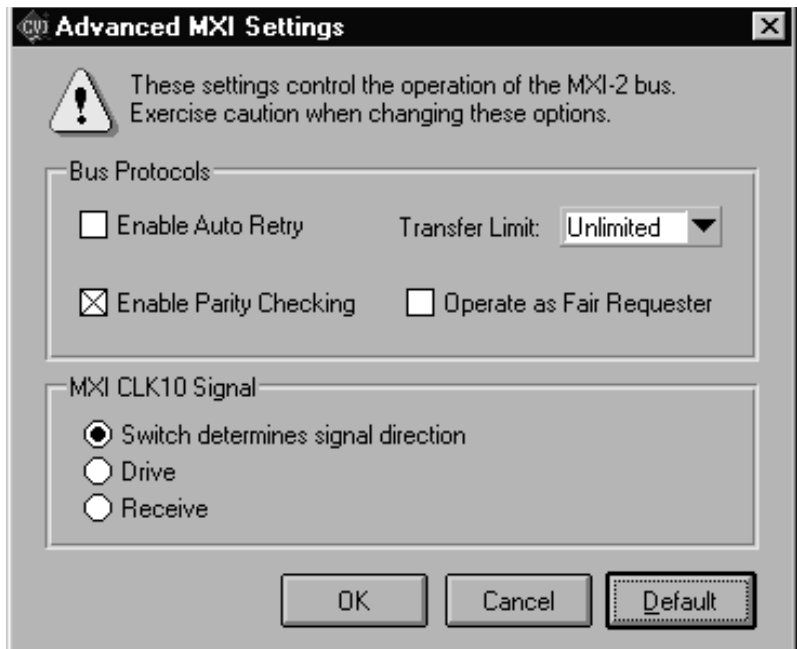


functionality of this control is similar to that of the **VXI Bus Timeout** control described previously under the *VXI/VME Bus Options* section. The options range from 8  $\mu$ s to 128 ms, with a default value of 1 ms.

After the specified amount of time has elapsed, the BTO circuitry terminates a MXIbus cycle if no slave has responded. The BTO circuitry is automatically deactivated when the VXI/VME-MXI-2 is not acting as the MXIbus System Controller. The BTO is also disabled when the current MXIbus cycle maps to the VXI/VMEbus through a VXI/VME-MXI-2.

## Advanced MXI Settings

Click on the **Advanced** button to reach additional configuration options for the MXI Bus portion of this editor, as shown in Figure 6-12. These options are intended for more advanced users.



**Figure 6-12.** Advanced MXI Settings

## MXI Auto Retry

The VXI/VME-MXI-2 has an automatic retry feature for cycles that map from the MXIbus to the VXI/VMEbus. This feature works in the same manner as the **Auto Retry** control described previously under the *VXI/VME Bus Options* section. By default, this option is disabled.

Normally, when a cycle maps from the MXIbus to the VXI/VMEbus, any retry response received on the VXI/VMEbus is passed to the MXIbus. If you enable the **Auto Retry** feature, the VXI/VME-MXI-2 automatically retries any VXI/VME cycle that receives a retry response instead of passing a retry response on to the MXIbus. The VXI/VME-MXI-2 automatically continues to retry the VXI/VME cycle until it receives either a *DTACK* or *BERR* response, which it then passes to the MXIbus.

Notice that the VXI/VME-MXI-2 has a limit on the number of automatic retries it will perform on any one cycle. If the limit is exceeded and the VXI/VME-MXI-2 receives another retry, it will pass a retry back to the MXIbus even though **Auto Retry** is enabled.

## Transfer Limit

You can use this feature to control how many data transfers the VXI/VME-MXI-2 will perform on the MXIbus before releasing it to another master device that is requesting use of the bus. The default setting holds the MXIbus for an unlimited period of time.

The other options you can choose from are 16, 64, and 256 transfers. If you do not want the VXI/VME-MXI-2 to hold the MXIbus for an unlimited period of time, you can use this control to select one of these values.

## Parity Checking

By default, MXIbus parity checking is enabled and should not be disabled under normal circumstances. MXIbus parity is always generated regardless if checking is enabled or disabled.

## MXI Fair Requester

You can use the **Operate as Fair Requester** checkbox control to configure the VXI/VME-MXI-2 as either a fair or unfair requester on the MXIbus. In its default setting (disabled), the VXI/VME-MXI-2 will request the bus at any time. If you enable this option, the

VXI/VME-MXI-2 will request the MXIbus only when there are no requests pending from other MXIbus masters. This prevents other MXIbus masters from being starved of bandwidth.

## MXI CLK10 Signal

The VXI-MXI-2 can either receive or drive the MXIbus CLK10 signal. In its default setting, the VXI-MXI-2 uses the switch setting of S7 to determine the signal direction.

- ◆ **VME users**—This option is not applicable to the VME-MXI-2.

You can use the **Drive** or **Receive** options to override the setting of S7 and control the direction of the MXIbus CLK10 signal. When receiving the MXIbus CLK10 signal, configure the W3 jumper setting to use the MXIbus as the source for generating the VXIbus CLK10 (applicable only if the VXI-MXI-2 is a Slot 0 device). When driving the MXIbus CLK10, the VXIbus CLK10 is used as the source. In this case, change the jumper setting so that it does *not* use the MXIbus CLK10 as the source for the VXIbus CLK10.



**Warning:** *Do not configure more than one MXIbus device to drive MXI CLK10. Setting up a second device to drive MXI CLK10 could damage the device.*

# Using the NI-VXI Software

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Chapter

7

This chapter discusses programming information for you to consider when developing applications that use the NI-VXI driver.

After installing the driver software, you can begin to develop your VXI application software. Be sure to check the `README.DOC` file for the latest application development notes. Remember that you must run the `VXIinit` initialization program before performing any VXI operations and after each computer reset. You must also run `RESMAN` each time the chassis power is cycled so that your application can access devices in the VXI chassis.

The NI-VXI software was designed for use in VXI systems. Because VXI is a superset of VME, you can also use the NI-VXI functions as a comprehensive set of programming tools for VME systems. Refer to the *NI-VXI User Manual* and the *NI-VXI Programmer Reference Manual* for an overview of NI-VXI and detailed descriptions of the NI-VXI functions. Notice that the following function classes apply only to VXI systems:

- Commander Word Serial Protocol functions
- Servant Word Serial Protocol functions
- VXI Signal functions
- VXI Trigger functions

## Interactive Control of NI-VXI

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The easiest way to learn how to communicate with your instruments is by controlling them interactively. Use the VXI interactive control program (`VIC` from DOS or `VICtext` from Windows) to write to and read from your instruments. Both programs display the status of your VXI transactions and inform you of any errors that occur. Refer to the *NI-VXI Graphical Utilities Reference Manual* for instructions on how to use `VIC` from DOS and to learn about its features. If you are using `VICtext` from Windows refer to the *NI-VXI Text Utilities Reference Manual* for information.



**Warning:** *If NIVXI.DLL is loaded in memory, do not attempt to execute VIC or any DOS program that uses the NI-VXI library in a DOS shell. Conflicts occur if both the DOS and Windows NI-VXI drivers are active at the same time, and may cause a system failure. To guard against this conflict, the safest approach is to always exit Windows before attempting to execute any DOS program that uses the NI-VXI Library, including VIC. You can execute VIC from a Windows DOS shell, however, if you ensure that no other Windows application that uses the NIVXI.DLL file is executing.*



**Note:** *When compiling NI-VXI applications, you must define the macro VXIWIN (if you are developing a Windows application) or the macro VXIDOS (if you are developing a DOS application) in your makefile/project. Refer to the example programs on your software diskettes for details.*

## Example Programs

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The EXAMPLES subdirectory contains various example programs along with a makefile that show how to use various functions in the NI-VXI software and how to develop application programs using these functions. Make certain that the environment variables LIB and INCLUDE are set correctly as described in Chapter 5, *NI-VXI Software Installation*. Also refer to the *NI-VXI User Manual* and the *NI-VXI Programmer Reference Manual* for additional examples.

## Programming Considerations

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The following paragraphs contain information for you to consider when developing DOS or Windows applications that use the NI-VXI bus interface software.

### Memory Model

The NI-VXI libraries were compiled using the large memory model. All DOS applications must also be compiled for the large memory model. However, Windows application programs that link with the NI-VXI library can also use the medium, compact, or small memory models. Because of this ability to use different memory models for your application, you not only can take advantage of the efficiency inherent in small memory model programs, but also run multiple instances of the application as well. (Normally, you cannot run multiple instances of an application if it is a large memory model application.)

## Multiple Applications Using the NI-VXI Library

Multiple-application support is another feature in the NI-VXI library. You can have several applications that use the NI-VXI library running simultaneously in Windows. In addition, you can have multiple instances of the same application that uses the NI-VXI library running simultaneously. The NI-VXI functions perform in the same manner whether you have only one application that uses the NI-VXI library or several applications (or several instances of an application) all using the NI-VXI library.

However, you do need to be careful in cases when you have multiple applications using low-level VXIbus/VMEbus access functions or setting user handlers.

## Low-Level Access Functions

The memory windows used to access the VXIbus are a limited resource. You should follow the protocol of calling the `MapVXIAddress()` function with Access Only mode first before attempting to perform low-level VXIbus access with `VXIpeek()` or `VXIpoke()`. Your application should always call the `UnMapVXIAddress()` function immediately after the accesses are complete so that you free up the memory window for other applications.

The function `MapVXIAddress()` returns a pointer for use with low-level access functions. It is strongly recommended to use the `VXIpeek()` and `VXIpoke()` macros to access the memory.

## Setting User Handlers

You can set a user handler that will be invoked when certain conditions occur, such as VXI signals and triggers, by using functions such as `SetSignalHandler()` in the NI-VXI library. However, setting a new user handler replaces the existing handler, meaning that the existing handler will no longer be invoked when the condition occurs. The following example illustrates the point.

```
SetSignalHandler(5, mySignalHandler1)

/* mySignalHandler1 is now the handler for VXI
signals from logical address 5. */

SetSignalHandler(5, mySignalHandler2)

/* mySignalHandler1 is replaced by mySignalHandler2
as the new handler for VXI signals from logical
address 5. */
```



**Caution:** *Avoid running multiple applications that indiscriminately change user handlers, or try to make sure that when the applications do change the user handlers, they do so in a coordinated manner. Setting new handlers while using multiple applications runs the risk of one application inadvertently overwriting the handler that another application had set up, causing disruptions and incorrect behavior.*

## Local Resource Access Functions

By using `VXIedit` or `VXItdedit`, you can set up the AT-MXI-2 to share either the system memory on the motherboard or the onboard memory on the AT-MXI-2 with the VXI/VME system. Refer to the *NI-VXI Graphical Utilities Reference Manual* or the *NI-VXI Text Utilities Reference Manual* for more information on setting these parameters.

Notice that sharing the system memory with the VXI/VME system does not mean that the entire range of shared system memory is available to be used for VXI transfers. You need to be cautious in specifying the portion of memory you want to share, as some areas are already used for other purposes.



**Warning:** *Use `VXImemAlloc()` to allocate a buffer in the system memory that is reserved for your use only. Using any range of addresses that was not returned from `VXImemAlloc()` to receive data may cause your computer to crash or behave incorrectly.*

Another factor to consider is that although you may have selected to share 8 MB, you must also inform Windows how much memory to set aside for possible `VXImemAlloc()` calls. You can use the **Shared Memory Pool** option in `VXIedit` and `VXItdedit` for this purpose. But remember that the memory you put into this pool is no longer available to Windows. If this setting is too large, you may experience memory limitation problems when you run Windows. Also remember that changes in the size of the pool do not take effect until the next time you start Windows.

The onboard memory on your AT-MXI-2, on the other hand, is entirely available to you. You can obtain the VXI address of your onboard memory using the `GetDevInfo()` function. Once you have the VXI address, you can access that memory using high-level or low-level VXIbus access functions.

## System Configuration Functions

The System Configuration functions provide the lowest-level initialization of your NI-VXI software and VXI controller. You must use the `InitVXIlibrary()` function at the start of each application and the `CloseVXIlibrary()` function at the end of each application.

## Compiling Your C Program

---

You can use the sample programs included with the NI-VXI software as a starting point to develop your own C program that uses NI-VXI functions. First, look over and compile the sample program using the makefile provided to get familiar with how the functions operate. The example program is broken into multiple files, and each file shows how to use different groups of functions. You can then modify the sample program to try out different aspects of the NI-VXI software.

The sample Windows program for the Microsoft C compiler is in the `\nivxi\win\msc\examples` directory and the sample Windows program for the Borland C compiler is in the `\nivxi\win\borlandc\examples` directory.

The sample DOS program for the Microsoft C compiler is in the `\nivxi\dos\msc\examples` directory and the sample DOS program for the Borland C compiler is in the `\nivxi\dos\borlandc\examples` directory.

The easiest way to compile the sample program is to use the makefile included with the NI-VXI software. If you are using the Microsoft C compiler, go to the Microsoft C sample directory and type `nmake` to compile that program. If you are using the Borland C compiler, go to the Borland C sample directory and type `make -f example.mak`.

## Symbols

You may need to define some symbols so that the NI-VXI library can work properly with your program. You can define the symbols using `#define` statements in the source code or you can use either the `/D` or the `-D` option in your compiler (both the Microsoft and Borland compilers support the `/D` and `-D` options). If you use `#define` statements, you must define the symbols before including the NI-VXI header file `nivxi.h`. If you use the makefiles to compile the sample program, the makefile already defined the necessary symbols.



The following symbols are usually required. You must define them when using the Microsoft C or Borland C compiler.

- `VXIWIN` designates the application as a Windows application. You can use the same NI-VXI header files to compile DOS programs by defining `VXIDOS` instead.



**Note:**

***Because LabWindows/CVI cannot be used to compile DOS programs, the correct symbol is automatically defined. You should not define `VXIWIN` when using LabWindows/CVI.***

- `__PROTOTYPES__` designates that you are using an ANSI C-compliant compiler. If you are using a C++ compiler or if your compiler defines the `__STDC__` symbol, this symbol is automatically defined.

The following symbol is optional.

- `BINARY_COMPATIBLE` makes the application binary compatible with embedded VXI controllers, such as the National Instruments VXIpc series of embedded controllers. Using this option may cause a slight performance degradation when using low-level VXIbus access functions.

If you define these symbols in your source code, your source code should look something like the following sample code:

```
#define VXIWIN
#define __PROTOTYPES__
#define BINARY_COMPATIBLE
.
.
.
#include <nivxi.h>
```

If you define these symbols using the `/D` or `-D` compiler options, you should specify the following when invoking the compiler.

For the Microsoft C compiler:

```
/DVXIWIN /D__PROTOTYPES__ /DBINARY_COMPATIBLE
```

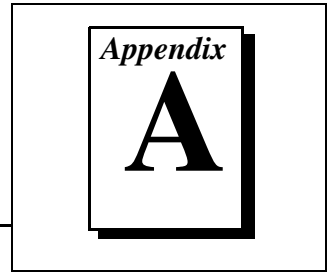
For the Borland C compiler:

```
-DVXIWIN;__PROTOTYPES__;BINARY_COMPATIBLE;
```

Refer to the documentation that came with your compiler package for detailed instructions about using the compiler and the various tools (linker, debugger, and so on). Your compiler documentation is an important and useful source of information for writing, compiling, and debugging C programs.

# Specifications

---



This appendix lists various module specifications of the AT-MXI-2, VXI-MXI-2, and VME-MXI-2 such as physical dimensions and power requirements.

## AT-MXI-2

---

The following pages list the specifications for the AT-MXI-2 module.

### MXIbus Capability Descriptions

- Master-mode A32, A24, and A16 addressing
- Master-mode block transfers and synchronous block transfers
- Slave-mode A32, A24, and A16 addressing
- Slave-mode block transfers and synchronous block transfers
- Master-mode D32, D16, and D08 data sizes
- Slave-mode D32, D16, and D08 data sizes
- Optional MXIbus System Controller
- Can be a fair MXIbus requester
- Can lock the MXIbus for indivisible transfers
- Can terminate the MXIbus
- MXIbus master retry support
- MXIbus slave retry support
- Interrupt handler for levels 7 to 1
- Interrupt requester for levels 7 to 1
- MXIbus D32, D16, D08(O) interrupt handler
- MXIbus D32, D16, D08(O) interrupter
- Release on Acknowledge or Register Access interrupter
- MXIbus bus timer (programmable limit)
- Automatic MXIbus System Controller detection

## AT Functionality

Characteristic	Specification
AT Alternate Master Capability	Supported
AT Slave Capability	Supported
Data Path	16 or 8 bits
Card Voltage/Type	5 V only; full-size XT card
AT I/O Window	One 10 (hex) window
DMA Request Level	1, 3, 5, 6, or 7
Interrupts	3, 4, 5, 6, 7, 9, 10, 11, 12, 14, or 15
AT Memory Window (0)	32 KB window under 1 MB
AT Memory Window (1)	Optional 64 KB window
AT Master Performance (Ideal Maximum)	4 MB/s
AT Slave Performance (Ideal Maximum)	4 MB/s

## Requirements

Characteristic	Specification
Memory Space	64 KB minimum (programmable)
I/O Space	16 B

## Environmental

Characteristic	Specification
Temperature	0° to 55° C operating; -40° to 85° C storage
Relative Humidity	0% to 95% noncondensing, operating; 0% to 95% noncondensing, storage
EMI	FCC Class A Verified

## Physical

Characteristic	Specification
Board Dimensions	337.56 by 106.68 mm (13.29 by 4.2 in.)
Connectors	Single fully implemented MXI-2 connector
Slot Requirements	Single AT (ISA) slot
MTBF	Contact Factory
Weight	0.225 Kg (0.5 lb) typical (no DRAM installed)

## Electrical

Source	Typical	Direct Current (Max)
+5 VDC	1.6 A	3.4 A

## Performance

MXI Transfer Rate	
Peak	33 MB/s
Sustained	23 MB/s

## VXI-MXI-2

---

The following pages list the specifications for the VXI-MXI-2 module.

### MXIbus Capability Descriptions

- Master-mode A32, A24, and A16 addressing
- Master-mode block transfers and synchronous block transfers
- Slave-mode A32, A24, and A16 addressing
- Slave-mode block transfers and synchronous block transfers
- Master-mode D32, D16, and D08 data sizes
- Slave-mode D32, D16, and D08 data sizes
- Optional MXIbus System Controller
- Can be a fair MXIbus requester
- Can lock the MXIbus for indivisible transfers
- Can terminate the MXIbus
- MXIbus master retry support
- MXIbus slave retry support
- Interrupt handler for levels 7 to 1
- Interrupt requester for levels 7 to 1
- MXIbus D32, D16, D08(O) interrupt handler
- MXIbus D32, D16, D08(O) interrupter
- Release on Acknowledge or Register Access interrupter
- MXIbus bus timer (programmable limit)
- Automatic MXIbus System Controller detection
- Automatic MXIbus termination detection

## VMEbus Capability Codes

Capability code	Description
A32, A24, A16 (master)	VMEbus master A32, A24, and A16 addressing
A32, A24, A16 (slave)	VMEbus slave A32, A24, and A16 addressing
D32, D16, D08(EO) (master)	VMEbus master D32, D16, and D08 data sizes
D32, D16, D08(EO) (slave)	VMEbus slave D32, D16, and D08 data sizes
BLT, MBLT (master)	VMEbus master block and D64 transfers
BLT, MBLT (slave)	VMEbus slave block and D64 transfers
RMW (master)	VMEbus master read/modify/write transfers
RMW (slave)	VMEbus slave read/modify/write transfers
RETRY (master)	VMEbus master retry support
RETRY (slave)	VMEbus slave retry support
FSD	First slot detector
SCON	VMEbus System Controller
PRI, RRS	Prioritized or Round Robin Select arbiter
ROR, FAIR	Release on Request and FAIR bus requester
IH(7-1)	Interrupt handler for levels 7-1
I(7-1)	Interrupt requester for levels 7-1
D32, D16, D08(O) (Interrupt Handler)	VMEbus D32, D16, D08(O) interrupt handler
D32, D16, D08(O) (Interrupter)	VMEbus D32, D16, D08(O) interrupter
ROAK, RORA	Release on Acknowledge or Register Access interrupter
BTO(x)	VMEbus bus timer (programmable limit)

## Requirements

Characteristic	Specification
VXIbus Configuration Space	64 B
A24 or A32 Space	16 KB minimum (programmable)

## Environmental

Characteristic	Specification
Temperature	0° to 55° C operating; -40° to 85° C storage
Relative Humidity	0% to 95% noncondensing, operating; 0% to 95% noncondensing, storage
EMI	FCC Class A Verified

## Physical

Characteristic	Specification
Board Dimensions	Fully enclosed, shielded VXI C-size board 233.35 by 340 mm (9.187 by 13.386 in.)
Connectors	Single fully implemented MXI-2 connector and three SMB connectors
Slot Requirements	Single VXI C-size slot
Compatibility	Fully compatible with VXI specification
VXI Keying Class	Class 1 TTL
MTBF	Contact factory



Characteristic	Specification
Weight	1.027 Kg (2.26 lb) typical (no DRAM installed)

## Electrical

Source	DC Current Ratings	
	Typical	Maximum
+5 VDC	2.5 A	3.4 A
-5.2 VDC	180 mA	225 mA
-2 VDC	80 mA	100 mA

## Performance

VME Transfer Rate	
Peak	33 MB/s
Sustained	23 MB/s

## VME-MXI-2

---

The following pages list the specifications for the VME-MXI-2 module.

### MXIbus Capability Descriptions

- Master-mode A32, A24 and A16 addressing
- Master-mode block transfers and synchronous block transfers
- Slave-mode A32, A24, and A16 addressing
- Slave-mode block transfers and synchronous block transfers
- Master-mode D32, D16, and D08 data sizes
- Slave-mode D32, D16, and D08 data sizes
- Optional MXIbus System Controller
- Can be a fair MXIbus requester
- Can lock the MXIbus for indivisible transfers
- Can terminate the MXIbus
- MXIbus master retry support
- MXIbus slave retry support
- Interrupt handler for levels 7 to 1
- Interrupt requester for levels 7 to 1
- MXIbus D32, D16, D08(O) interrupt handler
- MXIbus D32, D16, D08(O) interrupter
- Release on Acknowledge or Register Access interrupter
- MXIbus bus timer (programmable limit)
- Automatic MXIbus System Controller detection
- Automatic MXIbus termination detection

## VMEbus Capability Codes

Capability Code	Description
A32, A24, A16 (master)	VMEbus master A32, A24, and A16 addressing
A32, A24, A16 (slave)	VMEbus slave A32, A24, and A16 addressing
D32, D16, D08(EO) (master)	VMEbus master D32, D16, and D08 data sizes
D32, D16, D08(EO) (slave)	VMEbus slave D32, D16, and D08 data sizes
BLT, MBLT (master)	VMEbus master block and D64 transfers
BLT, MBLT (slave)	VMEbus slave block and D64 transfers
RMW (master)	VMEbus master read/modify/write transfers
RMW (slave)	VMEbus slave read/modify/write transfers
RETRY (master)	VMEbus master retry support
RETRY (slave)	VMEbus slave retry support
FSD	First slot detector
SCON	VMEbus System Controller
PRI, RRS	Prioritized or Round Robin Select arbiter
ROR, FAIR	Release on Request and FAIR bus requester
IH(7-1)	Interrupt handler for levels 7-1
I(7-1)	Interrupt requester for levels 7-1
D32, D16, D08(O) (Interrupt Handler)	VMEbus D32, D16, D08(O) interrupt handler
D32, D16, D08(O) (Interrupter)	VMEbus D32, D16, D08(O) interrupter
ROAK, RORA	Release on Acknowledge or Register Access interrupter
BTO(x)	VMEbus bus timer (programmable limit)

## Requirements

Characteristic	Specification
A16 Space	64 B
A24 or A32 Space	16 KB minimum (programmable)

## Environmental

Characteristic	Specification
Temperature	0° to 55° C operating; -40° to 85° C storage
Relative Humidity	0% to 95% noncondensing, operating; 0% to 95% noncondensing, storage
EMI	FCC Class A Verified

## Physical

Characteristic	Specification
Board Dimensions	VMEbus double-height board 233 by 160 mm (9.187 by 6.2999 in.)
Connectors	Single fully implemented MXI-2 connector
Slot Requirements	Single VMEbus double-height slot
Compatibility	Fully compatible with VMEbus specification
MTBF	Contact factory
Weight	0.33 Kg (0.73 lb) typical (no DRAM installed)

## Electrical

Source	DC Current Ratings	
	Typical	Maximum
+5 VDC	2.2 A	3.2 A

## Performance

VME Transfer Rate	
Peak	33 MB/s
Sustained	23 MB/s

# NI-VXI Software Overview

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Appendix

**B**

This appendix lists and describes the main programs and files that make up the NI-VXI software.

## Main Programs and Files

---

This section lists the main programs and files that you can use for controlling your VXI/VME interface.



**Note:** *Any executable not listed in this section is used by the driver and should not be executed by the user directly.*

- `VXIINIT.EXE` is the AT-MXI-2 initialization program. You can execute `VXIinit` from DOS, Windows, or the Windows DOS shell, although the latter is not recommended. This program initializes the AT-MXI-2. It may be included in the DOS batch file `AUTOEXEC.BAT` so that the AT-MXI-2 is automatically initialized at startup. The configuration settings can be modified using the `VXIEDIT.EXE` or `VXITEDIT.EXE` program.
- `RESMAN.EXE` is the National Instruments multiple-mainframe Resource Manager. You can execute `RESMAN` from DOS, Windows, or the Windows DOS shell, although the latter is not recommended. `RESMAN.EXE` may be executed only after `VXIINIT.EXE` has been run.
- `VIC.EXE` is an interactive control program that executes functions you enter from the keyboard. `VIC` helps you learn the functions, program your VXI devices, and develop and debug your application program. You can execute `VIC` from DOS or the Windows DOS shell, although the latter is not recommended. If you do use `VIC` from the Windows DOS shell, you must ensure that no other Windows application that uses NI-VXI functions is executing. This program is described in detail in the *NI-VXI Graphical Utilities Reference Manual*.
- `VICTEXT.EXE` is a text-based interactive control program that is functionally equivalent to `VIC.EXE`. You can execute `VICtext` from DOS, Windows, or the Windows DOS shell, although the

latter is not recommended. If you run `VICtext` as a Windows application, you can use it at the same time that other Windows applications that use NI-VXI functions are executing. This program is described in detail in the *NI-VXI Text Utilities Reference Manual*.

- `VXIEDIT.EXE` is the VXI resource editor program that runs in DOS or Windows. You use the **Non-VXI Device Editor** in `VXIedit` to identify details about VME devices installed in your system. You must use this editor to instruct your system about the addresses your VME devices occupy. The Resource Manager can then use this configuration information to automatically open the hardware windows so that your PC AT can access the VMEbus. This program also displays the system configuration information generated by the Resource Manager after it configures the link to the VMEbus. In VXI systems, you also use `VXIedit` to edit the model names of VXI devices and the manufacturer name and ID numbers. This program is described in detail in the *NI-VXI Graphical Utilities Reference Manual*.
- `VXITEDIT.EXE` is the text-based VXI resource editor program that is functionally equivalent to `VXIEDIT.EXE`. You can execute `VXITedit` from DOS, Windows, or the Windows DOS shell. This program is described in detail in the *NI-VXI Text Utilities Reference Manual*.
- `README.DOC` contains the latest updates and corrections to the manual when appropriate.
- `NI-PNP.EXE` is a program that configures National Instruments hardware (including the AT-MXI-2) to use hardware resources, such as IRQ lines and DMA channels, as designated in the `NI-PNP.INI` file. `NI-PNP.EXE` is automatically added to `AUTOEXEC.BAT` by the Setup program. This program must be run before `VXIinit`.
- `NI-PNP.INI` is a data file used by `NI-PNP.EXE` to assign hardware resources, such as IRQ lines and DMA channels, to National Instruments hardware.

## Header Files

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The `C:\NIVXI\INCLUDE` directory contains the following include files for the Microsoft C and Borland C language interfaces.

- `NIVXI.H` is the main header file containing the C prototypes for the NI-VXI functions.

- `DATASIZE.H` contains data size specifications.
- `BUSACC.H` contains parameter and return values for the bus access functions.
- `DEVINFO.H` contains parameter and return values for the device information and system configuration functions.
- `VXIINT.H` contains parameter and return values for the interrupt and signal functions.
- `SYSINT.H` contains parameter and return values for the system interrupt functions.
- `TRIG.H` contains parameter and return values for the trigger functions. This file is useful in VXI systems but is not applicable for VME systems.
- `WS.H` contains parameter and return values for the Commander and Servant Word Serial functions. This file is useful in VXI systems but is not applicable for VME systems.
- `NIVXI.INC` is the include file for the Visual Basic for DOS language interface.



# EEPROM Configuration

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Appendix

C

This appendix describes how to control the operation of the AT-MXI-2 onboard EEPROM and how to fix an invalid EEPROM setting.

The EEPROM stores default registers values that are loaded at power-on. The EEPROM is divided into two halves so that you can modify one half, while the factory-configured half retains a back-up of the default user settings.

## Controlling the EEPROM Operation

---

Use switch 1 (FOV) of the four-position switch at location U15 to control the operation of the EEPROM. Switch 1 determines whether the AT-MXI-2 boots off the factory-configured half or the user-configurable half. In its default setting, the AT-MXI-2 boots off the user-configurable half. This switch is useful in the event that the configuration becomes corrupted in such a way that the AT-MXI-2 boots to an unusable state.

The TST switch (switch 2 of U15) lets you change the default factory configuration settings by permitting writes to the factory settings section of the EEPROM. This switch serves as a safety measure and should not be needed under normal circumstances. When this switch is off (its default setting) the factory configuration of the EEPROM is protected so any writes to the factory area will be ignored. The factory area is protected regardless of the setting of switch 1 of U15.

Figure C-1 shows the default settings for EEPROM operation.



**Caution:** *Do not alter the settings of switches 3 and 4 of U15. Leave these switches as shown in Figure C-1 unless specifically directed by National Instruments.*

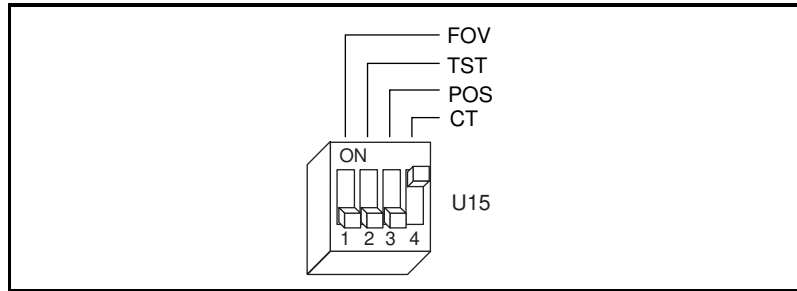


Figure C-1. EEPROM Operation

## Fixing an Invalid EEPROM Configuration

Certain EEPROM configurations can cause your PC AT to lock up while in its boot process. If this situation occurs after changing the configuration on the AT-MXI-2, follow these steps to reconfigure the AT-MXI-2.

1. Turn your computer off.



**Warning:** *To protect both yourself and the computer from electrical hazards, the computer should remain off while changing the settings on the AT-MXI-2 module.*

2. Remove the top cover or access port to the ISA bus.
3. Change switch 1 (FOV) on U15 to the ON position as shown in Figure C-2 to restore the factory configuration.

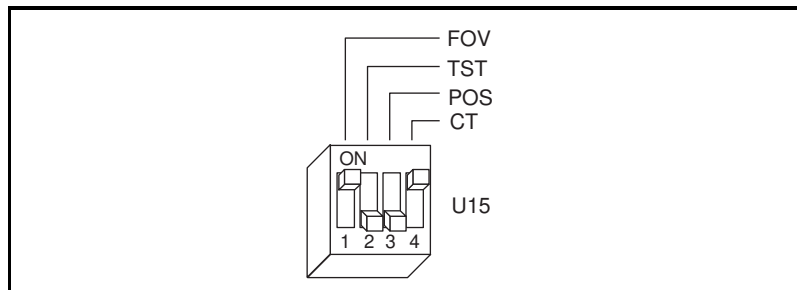


Figure C-2. Restoring the Factory Configuration



**Note:** *If you have to remove the AT-MXI-2 module to access switch 1, follow the installation instructions given in Chapter 2, AT-MXI-2 Configuration and Installation, to re-install the AT-MXI-2 module.*

4. Replace the computer cover.
5. Turn on the computer. The computer should boot this time because the factory-default configuration is being used to initialize the AT-MXI-2 module.
6. Run `VXIedit` to re-adjust the AT-MXI-2 configuration. Refer to Chapter 6, *NI-VXI Configuration Utility*, for instructions on using this utility.
7. After saving the configuration, exit Windows and turn off the computer.
8. Remove the top cover or access port to the ISA bus.
9. Change switch 1 (FOV) on U15 to the OFF position.
10. Replace the computer cover.
11. Turn on the computer. If the computer does not boot with this configuration, you will have to repeat these steps, modifying your configuration until a final configuration is reached.

# Common Questions

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Appendix

D

This appendix addresses common questions you may have about using the NI-VXI bus interface software on the AT-MXI-2 platform.

## **How can I determine which version of the NI-VXI software I have installed?**

Run the NI-VXI utility program `VIC` or `VICtext`. At the prompt type `ver`, and the utility will display the versions of `VIC/VICtext` and NI-VXI, and the latest AT-MXI-2 board revision that this NI-VXI driver supports.

## **How can I determine the revision of the AT-MXI-2 board that my NI-VXI software supports?**

Running the NI-VXI utility program `VICtext` as described above will display the versions of `VICtext` and NI-VXI, and the hardware revision of the AT-MXI-2 that the NI-VXI software supports.

## **How can I determine the serial number and hardware revision of the AT-MXI-2 board?**

Run the NI-VXI utility program `VXIedit`. Choose the **AT-MXI-2 Configuration Editor**. The opening screen displays the serial number and hardware revision of the AT-MXI-2 board.

## **How can I determine the serial number and hardware revision of the VXI-MXI-2 or VME-MXI-2?**

Run the NI-VXI utility program `VXIedit`. Choose the **VXI/VME-MXI-2 Configuration Editor**. The opening screen displays the serial number and hardware revision of the VXI-MXI-2 or VME-MXI-2.

## **Which NI-VXI utility program must I use to configure the AT-MXI-2?**

Use the VXI Resource Editor program, either `VXIedit` or `VXIedit`, to configure the AT-MXI-2. It is located in the `NIVXI` directory.

### **Which NI-VXI utility program must I use to initialize the AT-MXI-2?**

Use `NI-PNP.EXE`, located in the root directory of your boot drive, followed by the hardware initialization program, `VXInit`, to initialize the AT-MXI-2. It is located in the `NIVXI` directory.

### **What does `vxiinit` do?**

The `VXInit` program configures the components of the AT-MXI-2 interface that are not configured by the EEPROM, such as resetting the DMA channels and setting up the MITE windows for direct access. In other words, it initializes the AT-MXI-2. It also reads the current configuration and displays that to the user.

### **Which NI-VXI utility program must I use to perform startup Resource Manager operations?**

Use the `RESMAN` program to perform startup Resource Manager operations. It is located in the `NIVXI` directory. `RESMAN` uses the settings in the Configuration Editor of `VXIedit` or `VXItextedit`. It initializes your VXI/VMEbus system and stores the information that it collects to the `RESMAN.TBL` file in the `TBL` subdirectory of the `NIVXI` directory.

### **What can I do to make sure that my system is up and running?**

The fastest method for testing the system is to run `RESMAN`. This program attempts to access memory in the upper A16 address space of each device in the system. If `RESMAN` does not report any problems, the VXI/MXI communication system is operational.

To test individual devices, you can use the `VIC` or `VICtext` program to interactively issue NI-VXI functions. You can use the `VXIin()` and `VXIout()` functions or the `VXIinReg()` and `VXIoutReg()` functions to test register-based devices by programming their registers. If you have any message-based devices, you can send and receive messages with the `WSwrT()` and `WSrd()` functions. Notice that `VXIinReg()` and `VXIoutReg()` are for VXI devices only.

Finally, if you are using LabVIEW or LabWindows/CVI and you have instrument drivers for the devices in your chassis, you can use the interactive features of these programs to quickly test the functionality of the devices.

### How can I determine the IRQ level, I/O base address, DMA channel, or memory used by the AT-MXI-2?

Run `VXIedit`. Select the **AT-MXI-2 Configuration Editor** and then the **Bus Configuration Editor**.

### What should I do if `vxiinit` reports that it cannot access the EEPROM?

You probably have a memory conflict. The EEPROM is probably fine. You need to run these applications successfully in this order:

1. `NI-PNP.EXE`
2. `VXIINIT.EXE`
3. `RESMAN.EXE`

`NI-PNP` must return assigned resources. If `NI-PNP` reports that no resources are assigned, you probably have a memory conflict. If you are using Windows 95 with a Plug and Play (PNP) BIOS, follow the rest of the instructions in this topic. Otherwise, proceed to the next topic about resolving memory conflicts.

If you are unsure whether you have a PNP BIOS, `NI-PNP` can determine this for you. Check the `\NI-PNP.INI` file. If the following line appears, `NI-PNP` has detected a PNP BIOS.

```
IsaPnpSystemType = PnpBios
```

If this is the case and you are running Windows 95, you need to modify the `\NI-PNP.INI` file. The original [System Info] section contains the line:

```
IsaPnpIsolationMethod = IsolationSequence
```

Edit this line as shown below:

```
IsaPnpIsolationMethod = ReadPortSearch
```

Then add this line immediately after the [System Info] line:

```
IsaPnpSystemOverride = Yes
```

Save these changes and restart the computer. Your `AUTOEXEC.BAT` file should contain the `NI-PNP.EXE` as the first line.

### How do I resolve a memory conflict?

Typically, the problem is a conflict with the computer's upper (adapter space) memory. The procedures in this topic should resolve the most common causes of the conflicts.

If you are using Windows 3.x, do all your work in DOS instead of Windows 3.x. In fact, conflicting drivers could be loading in your `WINDOWS\SYSTEM.INI` file when you run Windows, which is a situation you will need to resolve later.

If you are using Windows 95, you can use the information in the Device Manager to find a valid memory space for the driver window.

1. Because the user window is needed only if you intend to use the `VXIpeek` or `VXIpoke` functions, you do not need this window for initial configuration. Run `VXIedit` and, in the **AT-MXI-2 Bus Configuration Editor**, disable the user window. Reboot the computer after saving this change. If you need to use `VXIpeek` or `VXIpoke` at a later time, you can re-enable the user window, but be aware that you may again experience memory conflicts.
2. If problems persist, the most likely problem is a conflict with the computer's upper (adapter space) memory. NI-VXI requires a 32 KB driver window in upper memory. If you have a Plug and Play (PNP) BIOS, the BIOS will try to place this window at the location specified in `VXIedit` in the **Bus Configuration Editor**. If you do not have a PNP BIOS, NI-PNP will try to place this window at the specified location. However, this memory assignment may conflict with the resources in your computer. You must resolve these conflicts. Continue with the following steps to find and resolve the most common causes of the conflicts.
3. The easiest test to determine if you have a software conflict is to rename `AUTOEXEC.BAT` and `CONFIG.SYS` to `AUTOEXEC.OLD` and `CONFIG.OLD`, respectively, and reboot the computer. Does NI-PNP run properly now? If not, proceed to step 4. If NI-PNP does run properly now, you need to look at the following paragraphs for corrective action.

Usually SCSI and network adapters need the upper memory and can conflict with the AT-MXI-2. Determine the memory regions used by these devices and configure the AT-MXI-2 to use a different region.

Often the memory conflict is not with another device, but rather with the memory management software such as EMM386, QEMM, or 386MAX. These products enable your computer to use parts of

the upper memory, typically reserved for hardware adapters, to load device drivers and TSR. Because the AT-MXI-2 needs that memory to operate, you must instruct your memory management software to exclude the regions used by the board. You can either omit the line that loads the memory manager or add a flag that prohibits the memory manager from using the requested range of upper memory. The most common memory manager is EMM386 because it ships standard with Microsoft DOS and Windows 3.x. In many cases, EMM386 is not needed for your configuration and can be omitted by adding `REM` to the beginning of that line. If any of your applications do need it, you can add the following flag to the end of the line that loads EMM386:

```
x=start-end
```

where *start* is the base address of the window and *end* is the base plus the size minus 1. Notice that both the base and the size are in paragraphs (16-byte units). For example, if your driver window is located at 0xC8000 and your 64 KB user window is at 0xE0000, you should specify the following flags at the end of the EMM386 line:

```
x=0xC800-0xCFFF x=0xE000-0xEFFF
```

4. Otherwise, your BIOS is probably shadowing BIOS functions to your RAM. You can usually check your BIOS settings and find a parameter to disable Shadow RAM. If this resolves the conflict, you can later re-enable Shadow RAM by either moving the driver window or by changing the location that the BIOS uses to Shadow BIOS functions.
5. If the preceding steps have not solved the conflicts, it is possible that the interrupt level for the AT-MXI-2 is conflicting with those used by your computer and by other plug-in boards. Remove all other plug-in boards. Some Ethernet boards that use adapter memory space as well as other boards may use the same interrupt level. If this is the case, resolve the conflict either by changing the interrupt level of the AT-MXI-2 through `VXIedit`, or by changing the interrupt level on the conflicting plug-in board. Mouse drivers could also be a problem. If `RESMAN` conflicts persist, try omitting the mouse driver in `AUTOEXEC.BAT` and in Windows Setup, and physically disconnecting the mouse from your computer.

### What should I do if `RESMAN` hangs?

1. If you are using MXI-2, ensure that the MXI-2 cable is plugged in and that the end labeled *Connect this end to the device closest to the*



*MXIbus System Controller* is connected to the MXIbus system controller (by default the AT-MXI-2). Because the MXI-2 cables are polarized, it matters which end is connected to which device.

2. Check for bent or broken pins on the MXI-2 connectors.
3. Make sure `VXIinit` and `VXIedit` work correctly. If not, refer to the previous question and answer topics that deal with incorrect driver window base and memory conflict problems.
4. If problems persist, run `RESMAN` with the VXI/VME-MXI-2 located in the leftmost slot of your chassis and no other instruments installed. If this works, try adding instruments until the problem occurs again. Contact National Instruments for further assistance.

### **What do the LEDs on the front of the VXI-MXI-2 or VME-MXI-2 mean?**

The **SYSFAIL** LED shows the state of the VXIbus/VMEbus **SYSFAIL** line. This line is asserted whenever any device in the chassis has not yet passed its self test, if it has failed its self test, or if it has detected a failure after originally passing its self test. The **MXI ACCESS** LED indicates that the VXI-MXI-2 or VME-MXI-2 is acting as a slave to another device on the MXIbus, such as when the AT-MXI-2 communicates to either the VXI-MXI or VME-MXI or another device in the chassis. The **VXI (VME) ACCESS** LED, when lit, indicates that the VXI-MXI or VME-MXI is acting as a slave to another device in the VXI (VME) chassis, such as when a bus master inside the chassis wants to talk to either the VXI-MXI or VME-MXI or another device outside the chassis.

### **Are the AT-MXI-2 and the VXI-MXI-2 two devices or one with respect to the VXIbus?**

Both the AT-MXI-2 and the VXI-MXI-2 are unique VXIbus devices with their own logical addresses. However, the MXIbus allows the PC AT computer to behave as if it is inside the chassis with the VXI-MXI-2 by transparently converting AT bus cycles to MXIbus cycles to VXIbus cycles, and vice versa.

### **I have a system that requires rugged chassis and bulkhead cables. Can I still use MXIbus?**

Yes, National Instruments sells MXIbus bulkhead cables. Contact National Instruments for further information.

**What kind of signal is CLK10 and what kind of signal do I need for an external CLK10?**

CLK10 is a differential ECL signal on the VXIbus backplane. However, the oscillator for the VXI-MXI-2 and the EXTCLK input from the front panel use TTL. Therefore, you need to supply a TTL level signal for EXTCLK and our voltage converters will convert the signal to differential ECL.

CLK10 is not applicable to VME.

**What is the accuracy of the CLK10 signal?**

The CLK10 generated by the VXI-MXI-2 is  $\pm 100$  ppm (0.01%) as per the VXIbus specification. If you need a more accurate CLK10 signal, you can use the EXTCLK input at the front of the VXI-MXI-2.

CLK10 is not applicable to VME.

# Customer Communication

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Appendix

E

For your convenience, this appendix contains forms to help you gather the information necessary to help us solve your technical problems and a form you can use to comment on the product documentation. When you contact us, we need the information on the Technical Support Form and the configuration form, if your manual contains one, about your system configuration to answer your questions as quickly as possible.

National Instruments has technical assistance through electronic, fax, and telephone systems to quickly provide the information you need. Our electronic services include a bulletin board service, an FTP site, a Fax-on-Demand system, and e-mail support. If you have a hardware or software problem, first try the electronic support systems. If the information available on these systems does not answer your questions, we offer fax and telephone support through our technical support centers, which are staffed by applications engineers.

## Electronic Services



### Bulletin Board Support

National Instruments has BBS and FTP sites dedicated for 24-hour support with a collection of files and documents to answer most common customer questions. From these sites, you can also download the latest instrument drivers, updates, and example programs. For recorded instructions on how to use the bulletin board and FTP services and for BBS automated information, call (512) 795-6990. You can access these services at:

United States: (512) 794-5422

Up to 14,400 baud, 8 data bits, 1 stop bit, no parity

United Kingdom: 01635 551422

Up to 9,600 baud, 8 data bits, 1 stop bit, no parity

France: 01 48 65 15 59

Up to 9,600 baud, 8 data bits, 1 stop bit, no parity



### FTP Support

To access our FTP site, log on to our Internet host, `ftp.natinst.com`, as anonymous and use your Internet address, such as `joesmith@anywhere.com`, as your password. The support files and documents are located in the `/support` directories.



## Fax-on-Demand Support

Fax-on-Demand is a 24-hour information retrieval system containing a library of documents on a wide range of technical information. You can access Fax-on-Demand from a touch-tone telephone at (512) 418-1111.



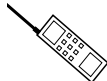
## E-Mail Support (currently U.S. only)

You can submit technical support questions to the applications engineering team through e-mail at the Internet address listed below. Remember to include your name, address, and phone number so we can contact you with solutions and suggestions.

[support@natinst.com](mailto:support@natinst.com)

## Telephone and Fax Support

National Instruments has branch offices all over the world. Use the list below to find the technical support number for your country. If there is no National Instruments office in your country, contact the source from which you purchased your software to obtain support.



### Telephone



### Fax

Australia	03 9879 5166	03 9879 6277
Austria	0662 45 79 90 0	0662 45 79 90 19
Belgium	02 757 00 20	02 757 03 11
Canada (Ontario)	905 785 0085	905 785 0086
Canada (Quebec)	514 694 8521	514 694 4399
Denmark	45 76 26 00	45 76 26 02
Finland	09 527 2321	09 502 2930
France	01 48 14 24 24	01 48 14 24 14
Germany	089 741 31 30	089 714 60 35
Hong Kong	2645 3186	2686 8505
Israel	03 5734815	03 5734816
Italy	02 413091	02 41309215
Japan	03 5472 2970	03 5472 2977
Korea	02 596 7456	02 596 7455
Mexico	5 520 2635	5 520 3282
Netherlands	0348 433466	0348 430673
Norway	32 84 84 00	32 84 86 00
Singapore	2265886	2265887
Spain	91 640 0085	91 640 0533
Sweden	08 730 49 70	08 730 43 70
Switzerland	056 200 51 51	056 200 51 55
Taiwan	02 377 1200	02 737 4644
U.K.	01635 523545	01635 523154

# Technical Support Form

Photocopy this form and update it each time you make changes to your software or hardware, and use the completed copy of this form as a reference for your current configuration. Completing this form accurately before contacting National Instruments for technical support helps our applications engineers answer your questions more efficiently.

If you are using any National Instruments hardware or software products related to this problem, include the configuration forms from their user manuals. Include additional pages if necessary.

Name \_\_\_\_\_

Company \_\_\_\_\_

Address \_\_\_\_\_

\_\_\_\_\_

Fax (\_\_\_\_) \_\_\_\_\_ Phone (\_\_\_\_) \_\_\_\_\_

Computer brand \_\_\_\_\_ Model \_\_\_\_\_ Processor \_\_\_\_\_

Operating system (include version number) \_\_\_\_\_

Clock speed \_\_\_\_\_ MHz RAM \_\_\_\_\_ MB Display adapter \_\_\_\_\_

Mouse \_\_\_yes \_\_\_no Other adapters installed \_\_\_\_\_

Hard disk capacity \_\_\_\_\_ MB Brand \_\_\_\_\_

Instruments used \_\_\_\_\_

\_\_\_\_\_

National Instruments hardware product model \_\_\_\_\_ Revision \_\_\_\_\_

Configuration \_\_\_\_\_

National Instruments software product \_\_\_\_\_ Version \_\_\_\_\_

Configuration \_\_\_\_\_

The problem is: \_\_\_\_\_

\_\_\_\_\_

\_\_\_\_\_

\_\_\_\_\_

List any error messages: \_\_\_\_\_

\_\_\_\_\_

\_\_\_\_\_

The following steps reproduce the problem: \_\_\_\_\_

\_\_\_\_\_

\_\_\_\_\_

\_\_\_\_\_

\_\_\_\_\_

\_\_\_\_\_

# Hardware and Software Configuration Form

Record the settings and revisions of your hardware and software on the line to the right of each item. Complete a new copy of this form each time you revise your software or hardware configuration, and use this form as a reference for your current configuration. Completing this form accurately before contacting National Instruments for technical support helps our applications engineers answer your questions more efficiently.

## National Instruments Products

NI-VXI Software Version Number \_\_\_\_\_

Using VXIedit or VXIedit? \_\_\_\_\_

## AT-MXI-2

Hardware Revision Number \_\_\_\_\_

Switch U15 Settings \_\_\_\_\_

DRAM SIMMs Installed \_\_\_\_\_

## AT-MXI-2 Configuration Editor Settings (VXIedit)

Logical Address \_\_\_\_\_

Device Type \_\_\_\_\_

Address Space \_\_\_\_\_

VXI Shared RAM Size \_\_\_\_\_

Shared RAM Pool \_\_\_\_\_

Byte Swapping for Lower Half Window \_\_\_\_\_

Memory Select for Lower Half Window \_\_\_\_\_

Byte Swapping for Upper Half Window \_\_\_\_\_

Memory Select for Upper Half Window \_\_\_\_\_

Mapping Scheme for Lower and Upper Half Windows of VXI Shared RAM \_\_\_\_\_

Resource Manager Delay \_\_\_\_\_

Default Controller (LA-1) \_\_\_\_\_

System IRQ Level \_\_\_\_\_

Servant Area Size \_\_\_\_\_

Number of Handlers \_\_\_\_\_

Number of Interrupters \_\_\_\_\_

Protocol Register \_\_\_\_\_

Read Protocol Response \_\_\_\_\_

MXI System Controller \_\_\_\_\_  
MXI Bus Timeout Value \_\_\_\_\_  
MXI CLK10 \_\_\_\_\_  
MXI Transfer Limit \_\_\_\_\_  
Synchronous MXI \_\_\_\_\_  
MXI-2 Auto Retry \_\_\_\_\_  
A24/A32 Write Posting \_\_\_\_\_  
IRQ Level \_\_\_\_\_  
DMA Channel \_\_\_\_\_  
I/O Base Address \_\_\_\_\_  
Slave Timeout \_\_\_\_\_  
Driver Window Base \_\_\_\_\_  
Driver Window Size \_\_\_\_\_  
User Window Base \_\_\_\_\_  
User Window Size \_\_\_\_\_

## **VXI/VME-MXI-2**

Using VXI-MXI-2 or VME-MXI-2? \_\_\_\_\_  
Hardware Revision Number \_\_\_\_\_

## **VXI-MXI-2 Hardware Configuration**

Slot Location \_\_\_\_\_  
VXIbus Logical Address Switch Setting (U43) \_\_\_\_\_  
VXIbus slot 0/Non-Slot 0 (W2) \_\_\_\_\_  
VXIbus Local Bus (S8, S9) \_\_\_\_\_  
VXIbus CLK10 Routing (W3) \_\_\_\_\_  
SMB CLK10 (S3, S4, S5) \_\_\_\_\_  
Receiving or Driving MXIbus CLK10 (s7) \_\_\_\_\_  
Trigger Input Termination (S2) \_\_\_\_\_  
MXIbus Termination (U35 switches 1 and 2) \_\_\_\_\_  
EEPROM Operation (U35 switches 3 and 4) \_\_\_\_\_  
Onboard DRAM SIMM Size (S6) \_\_\_\_\_  
DRAM SIMMs Installed \_\_\_\_\_

## VME-MXI-2 Hardware Configuration

Slot Location \_\_\_\_\_

VMEbus A16 Base Address (U20) \_\_\_\_\_

VME-MXI-2 Intermodule Signaling (w2) \_\_\_\_\_

MXIbus Termination (U21 switches 3 and 4) \_\_\_\_\_

EEPROM Operation (U21 switches 1 and 2) \_\_\_\_\_

Onboard DRAM SIMM Size (S2) \_\_\_\_\_

DRAM SIMMs Installed \_\_\_\_\_

## VXI/VME-MXI-2 Configuration Editor Settings (VXIedit)

Logical Address \_\_\_\_\_

LA Selection \_\_\_\_\_

Address Space \_\_\_\_\_

Requested Memory \_\_\_\_\_

A16 Write Posting \_\_\_\_\_

A24/A32 Write Posting \_\_\_\_\_

Interlocked or Normal Mode \_\_\_\_\_

VXI/VME System Controller \_\_\_\_\_

VXI/VME Bus Timeout Value \_\_\_\_\_

Auto Retry for Cycles from VXI/VMEbus to MXIbus \_\_\_\_\_

Transfer Limit on VXI/VMEbus \_\_\_\_\_

VXI/VME Arbiter Type \_\_\_\_\_

VXI/VME Request Level \_\_\_\_\_

VXI/VME Arbiter Timeout \_\_\_\_\_

VXI/VME Fair Requester \_\_\_\_\_

MXI System Controller \_\_\_\_\_

MXI Bus Timeout Value \_\_\_\_\_

Auto Retry for Cycles from MXIbus to VXI/VMEbus \_\_\_\_\_

MXI Transfer Limit \_\_\_\_\_

MXI Parity Checking \_\_\_\_\_

MXI Fair Requester \_\_\_\_\_

MXI CLK10 Direction (VXI-MXI-2 only) \_\_\_\_\_



## Other Products

Computer Make and Model \_\_\_\_\_

Mainframe Make and Model \_\_\_\_\_

Microprocessor \_\_\_\_\_

Clock Frequency or Speed \_\_\_\_\_

Type of Video Board Installed \_\_\_\_\_

Operating System \_\_\_\_\_

Operating System Version \_\_\_\_\_

Operating System Mode \_\_\_\_\_

Programming Language \_\_\_\_\_

Programming Language Version \_\_\_\_\_

Other Boards in System \_\_\_\_\_

Base I/O Address of Other Boards \_\_\_\_\_

DMA Channels of Other Boards \_\_\_\_\_

Interrupt Level of Other Boards \_\_\_\_\_

# Documentation Comment Form

National Instruments encourages you to comment on the documentation supplied with our products. This information helps us provide quality products to meet your needs.

**Title:** *Getting Started with Your VXI/VME-AT4000 Series and the NI-VXI™ Software*

**Edition Date:** January 1997

**Part Number:** 371698A-01

Please comment on the completeness, clarity, and organization of the manual.

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If you find errors in the manual, please record the page numbers and describe the errors.

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Thank you for your help.

Name \_\_\_\_\_

Title \_\_\_\_\_

Company \_\_\_\_\_

Address \_\_\_\_\_

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Phone (\_\_\_\_) \_\_\_\_\_ Fax (\_\_\_\_) \_\_\_\_\_

**Mail to:** Technical Publications  
National Instruments Corporation  
6504 Bridge Point Parkway  
Austin, TX 78730-5039

**Fax to:** Technical Publications  
National Instruments Corporation  
(512) 794-5678

Prefix	Meaning	Value
n-	nano-	$10^{-9}$
$\mu$ -	micro-	$10^{-6}$
m-	milli-	$10^{-3}$
K-	kilo-	$10^3$
M	Mega	$10^6$
G-	giga-	$10^9$

## Numbers/Symbols

° degrees

$\Omega$  ohms

% percent

## A

A amperes

A16 space VXIbus address space equivalent to the VME 64 KB short address space. In VXI, the upper 16 KB of A16 space is allocated for use by VXI devices configuration registers. This 16 KB region is referred to as VXI configuration space.

A24 space VXIbus address space equivalent to the VME 16 MB *standard* address space.

A32 space	VXIbus address space equivalent to the VME 4 GB <i>extended</i> address space.
ACFAIL	A VMEbus backplane signal that is asserted when a power failure has occurred (either AC line source or power supply malfunction), or if it is necessary to disable the power supply (such as for a high temperature condition).
address	Character code that identifies a specific location (or series of locations) in memory.
address modifier	One of six signals in the VMEbus specification used by VMEbus masters to indicate the address space in which a data transfer is to take place.
address space	A set of $2^n$ memory locations differentiated from other such sets in VXI/VMEbus systems by six addressing lines known as address modifiers. $n$ is the number of address lines required to uniquely specify a byte location in a given space. Valid numbers for $n$ are 16, 24, and 32. In VME/VXI, because there are six address modifiers, there are 64 possible address spaces.
address window	A portion of address space that can be accessed from the application program.
ANSI	American National Standards Institute
arbitration	A process in which a potential bus master gains control over a particular bus.
asynchronous	Not synchronized; not controlled by time signals.
<b>B</b>	
B	bytes
backplane	An assembly, typically a printed circuit board, with 96-pin connectors and signal paths that bus the connector pins. A C-size VXIbus system will have two sets of bused connectors called J1 and J2. A D-size VXIbus system will have three sets of bused connectors called J1, J2, and J3.
BERR*	Bus error signal

binary	A numbering system with a base of 2.
BIOS	Basic Input/Output System. BIOS functions are the fundamental level of any PC or compatible computer. BIOS functions embody the basic operations needed for successful use of the computer's hardware resources.
block-mode transfer	An uninterrupted transfer of data elements in which the master sources only the first address at the beginning of the cycle. The slave is then responsible for incrementing the address on subsequent transfers so that the next element is transferred to or from the proper storage location. In VME, the data transfer may have no more than 256 elements; MXI does not have this restriction.
BTO unit	Bus Timeout Unit; a functional module that times the duration of each data transfer and terminates the cycle if the duration is excessive. Without the termination capability of this module, a bus master attempt to access a nonexistent slave could result in an indefinitely long wait for a slave response.
bus master	A device that is capable of requesting the Data Transfer Bus (DTB) for the purpose of accessing a slave device.
<b>C</b>	
C	Celsius
CLK10	A 10 MHz, $\pm 100$ ppm, individually buffered (to each module slot), differential ECL system clock that is sourced from Slot 0 of a VXIbus mainframe and distributed to Slots 1 through 12 on P2. It is distributed to each slot as a single-source, single-destination signal with a matched delay of under 8 ns.
CMOS	Complementary Metal Oxide Semiconductor; a process used in making chips.
Commander	A message-based device which is also a bus master and can control one or more Servants.
configuration registers	A set of registers through which the system can identify a module device type, model, manufacturer, address space, and memory requirements. In order to support automatic system and memory

configuration, the VXIbus specification requires that all VXIbus devices have a set of such registers.

## D

daisy-chain	A method of propagating signals along a bus, in which the devices are prioritized on the basis of their position on the bus.
Data Transfer Bus	DTB; one of four buses on the VMEbus backplane. The DTB is used by a bus master to transfer binary data between itself and a slave device.
DIP	Dual Inline Package
DMA	Direct Memory Access; a method by which data is transferred between devices and internal memory without intervention of the central processing unit.
DRAM	Dynamic RAM
driver window	A region of AT address space that is decoded by the AT-MXI-2 for use by the NI-VXI software.
DTACK*	Data Acknowledge signal
DTB	See <i>Data Transfer Bus</i> .
dynamic configuration	A method of automatically assigning logical addresses to VXIbus devices at system startup or other configuration times.
dynamically configured device	A device that has its logical address assigned by the Resource Manager. A VXI device initially responds at Logical Address 255 when its MODID line is asserted. A MXIbus device responds at Logical Address 255 during a priority select cycle. The Resource Manager subsequently assigns it a new logical address, which the device responds to until powered down.

## E

ECL	Emitter-Coupled Logic
EEPROM	Electrically Erasable Programmable Read Only Memory

embedded controller	An intelligent CPU (controller) interface plugged directly into the VXI backplane, giving it direct access to the VXIbus. It must have all of its required VXI interface capabilities built in.
EMC	Electromechanical Compliance
EMI	Electromagnetic Interference
expansion ROM	An onboard EEPROM that may contain device-specific initialization and system boot functionality.
external controller	In this configuration, a plug-in interface board in a computer is connected to the VXI mainframe via one or more VXIbus extended controllers. The computer then exerts overall control over VXIbus system operations.

## F

fair requester	A MXIbus master that will not arbitrate for the MXIbus after releasing it until it detects the bus request signal inactive. This ensures that all requesting devices will be granted use of the bus.
----------------	--

## H

hex	Hexadecimal; the numbering system with base 16, using the digits 0 to 9 and letters A to F.
Hz	hertz; cycles per second.

## I

IC	Integrated Circuit
IEEE	Institute of Electrical and Electronics Engineers
in.	inches
I/O	input/output; the techniques, media, and devices used to achieve communication between machines and users.
interrupt	A means for a device to request service from another device.

interrupt handler	A VMEbus functional module that detects interrupt requests generated by Interrupters and responds to those requests by requesting status and identify information.
interrupt level	The relative priority at which a device can interrupt.
IRQ*	Interrupt signal
<b>K</b>	
KB	Kilobytes of memory
<b>L</b>	
LED	Light Emitting Diode
logical address	An 8-bit number that uniquely identifies each VXIbus device in a system. It defines the A16 register address of a device, and indicates Commander and Servant relationships.
<b>M</b>	
m	meters
master	A functional part of a MXI/VME/VXIbus device that initiates data transfers on the backplane. A transfer can be either a read or a write.
master-mode operation	A device is in master mode if it is performing a bus cycle which it initiated.
MB	Megabytes of memory
MBLT	Eight-byte block transfers in which both the Address bus and the Data bus are used to transfer data.
message-based device	An intelligent device that implements the defined VXIbus registers and communication protocols. These devices are able to use Word Serial Protocol to communicate with one another through communication registers.



MITE	A National Instruments custom ASIC, a sophisticated dual-channel DMA controller that incorporates the Synchronous MXI and VME64 protocols to achieve high-performance block transfer rates.
MODID	Module Identification lines
MTBF	Mean Time Between Failure
MXI-2	The second generation of the National Instruments MXIbus product line. MXI-2 expands the number of signals on a standard MXIbus cable by including VXI triggers, all VXI interrupts, CLK10, SYSFAIL*, SYSRESET*, and ACFAIL*.
MXIbus	Multisystem eXtension Interface Bus; a high-performance communication link that interconnects devices using round, flexible cables.
MXIbus System Controller	A functional module that has arbiter, daisy-chain driver, and MXIbus cycle timeout responsibility. Always the first device in the MXIbus daisy-chain.

## N

NI-VXI	The National Instruments bus interface software for VME/VXIbus systems.
Non-Slot 0 device	A device configured for installation in any slot in a VXIbus mainframe other than Slot 0. Installing such a device into Slot 0 can damage the device, the VXIbus backplane, or both.

## O

Onboard RAM	The optional RAM installed into the SIMM slots of the AT-MXI-2 board or VXI/VME-MXI-2 module.
-------------	---

## P

propagation	The transmission of signal through a computer system.
-------------	---

## R

register-based device	A Servant-only device that supports VXIbus configuration registers. Register-based devices are typically controlled by message-based devices via device-dependent register reads and writes.
RESMAN	The name of the National Instruments Resource Manager in NI-VXI bus interface software. See <i>Resource Manager</i> .
Resource Manager	A message-based Commander located at Logical Address 0, which provides configuration management services such as address map configuration, Commander and Servant mappings, and self-test and diagnostic management.
retry	An acknowledge by a destination that signifies that the cycle did not complete and should be repeated.

## S

s	seconds
Servant	A device controlled by a Commander; there are message-based and register-based Servants.
Shared Memory Protocol	A communication protocol that uses a block of memory that is accessible to both a client and a server. The memory block operates as a message buffer for communications.
SIMM	Single In-line Memory Module
slave	A functional part of a MXI/VME/VXIbus device that detects data transfer cycles initiated by a VMEbus master and responds to the transfers when the address specifies one of the device's registers.
slave-mode operation	A device is in slave mode if it is responding to a bus cycle.
Slot 0 device	A device configured for installation in Slot 0 of a VXIbus mainframe. This device is unique in the VXIbus system in that it performs the VMEbus System Controller functions, including clock sourcing and arbitration for data transfers across the backplane. Installing such a device into any other slot can damage the device, the VXIbus backplane, or both.

statically configured device	A device whose logical address cannot be set through software; that is, it is not dynamically configurable.
SYSFAIL	A VMEbus signal that is used by a device to indicate an internal failure. A failed device asserts this line. In VXI, a device that fails also clears its PASSEd bit in its Status register.
SYSRESET	A VMEbus signal that is used by a device to indicate a system reset or power-up condition.
System RAM	RAM installed on your personal computer and used by the operating system, as contrasted with onboard RAM, which is installed on the AT-MXI-2 or VXI/VME-MXI-2.

## T

trigger	Either TTL or ECL lines used for intermodule communication.
TTL	Transistor-Transistor Logic

## U

user window	A region of AT address space reserved by the AT-MXI-2 for use via the NI-VXI low-level function calls. <code>MapVXIAddress()</code> uses this address space to allocate regions for use by the <code>VXIpeek()</code> and <code>VXIpoke()</code> macros.
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## V

V	volts
VDC	volts direct current
VIC or VICTEXT	VXI Interactive Control Program, a part of the NI-VXI bus interface software package. Used to program VXI devices, and develop and debug VXI application programs.
VME	Versa Module Eurocard or IEEE 1014
VMEbus System Controller	A device configured for installation in Slot 0 of a VXIbus mainframe or Slot 1 of a VMEbus chassis. This device is unique in the VMEbus system in that it performs the VMEbus System

Controller functions, including clock sourcing and arbitration for data transfers across the backplane. Installing such a device into any other slot can damage the device, the VMEbus/VXIbus backplane, or both.

VXIbus

VMEbus Extensions for Instrumentation

VXIINIT

A program in the NI-VXI bus interface software package that initializes the board interrupts, shared RAM, VXI register configurations, and bus configurations.

VXIedit or VXItdedit

VXI Resource Editor program, a part of the NI-VXI bus interface software package. Used to configure the system, edit the manufacturer name and ID numbers, edit the model names of VXI and non-VXI devices in the system, as well as the system interrupt configuration information, and display the system configuration information generated by the Resource Manager.

## W

Word Serial Protocol

The simplest required communication protocol supported by message-based devices in a VXIbus system. It utilizes the A16 communication registers to transfer data using a simple polling handshake method.

write posting

A mechanism that signifies that a device will immediately give a successful acknowledge to a write transfer and place the transfer in a local buffer. The device can then independently complete the write cycle to the destination.

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